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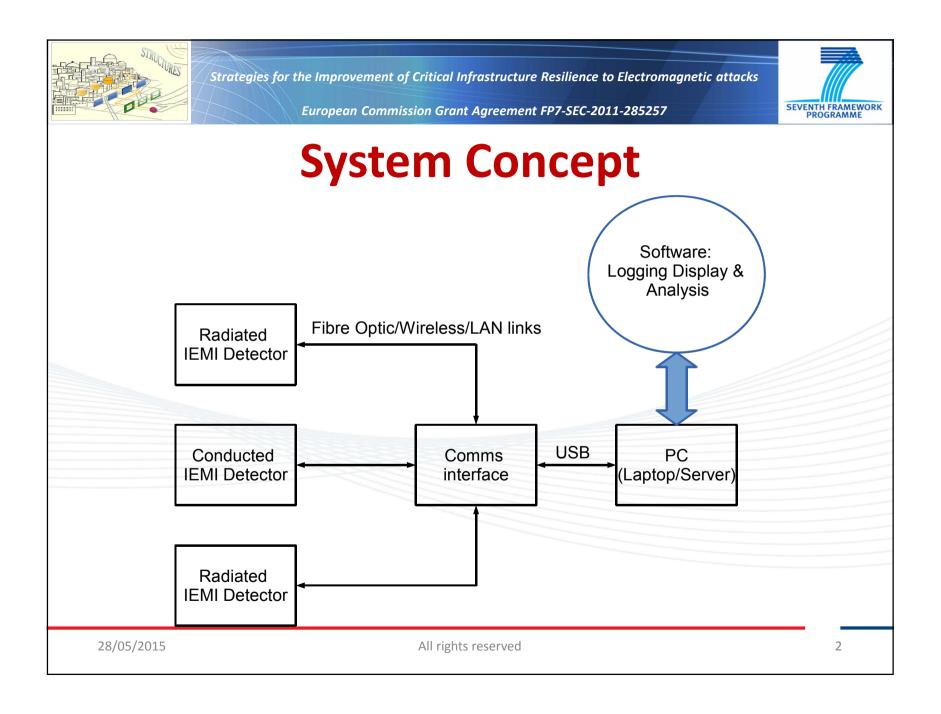


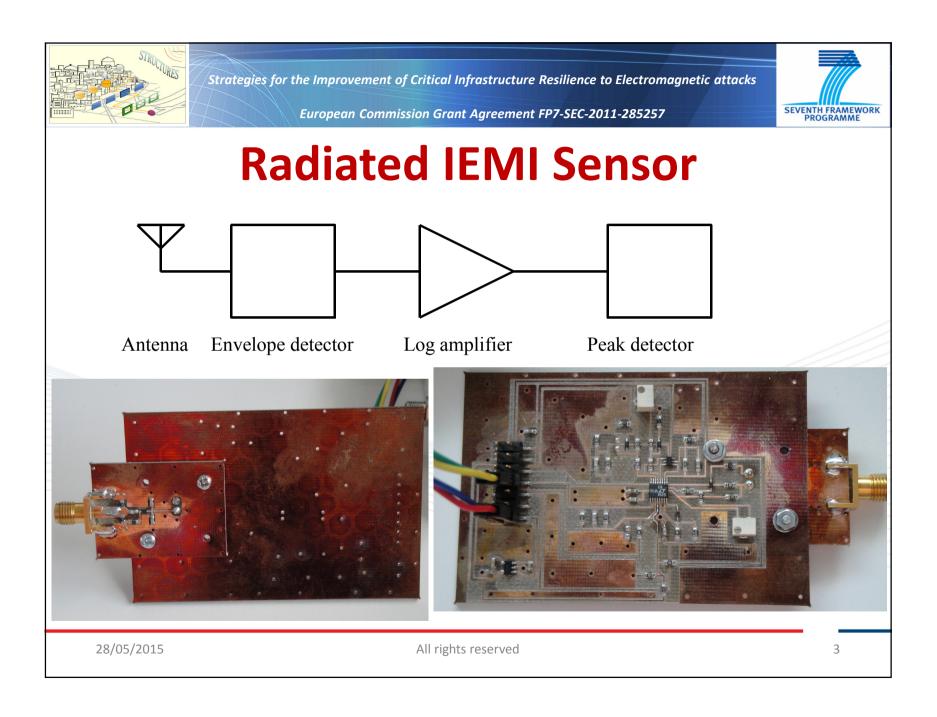
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IEMI Detection Systems: A low cost IEMI detector

J F Dawson, L Dawson, I D Flintoft, L Rebers, Michael Camp, Juergen Schmitz, Markus Jung

EMC Europe 2015, Dresden Workshop 26, Paper 6a



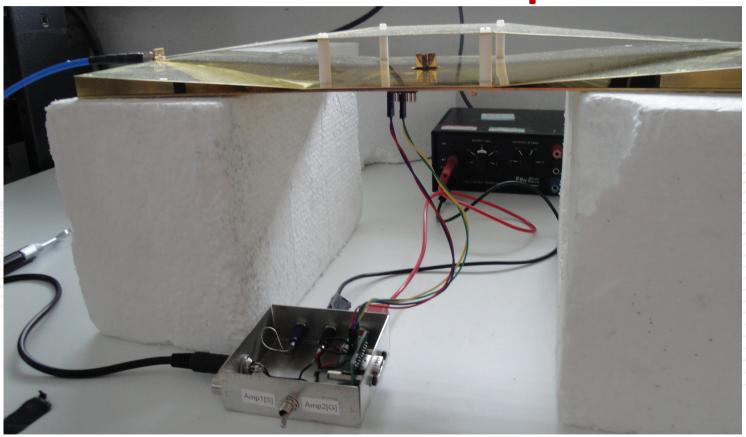


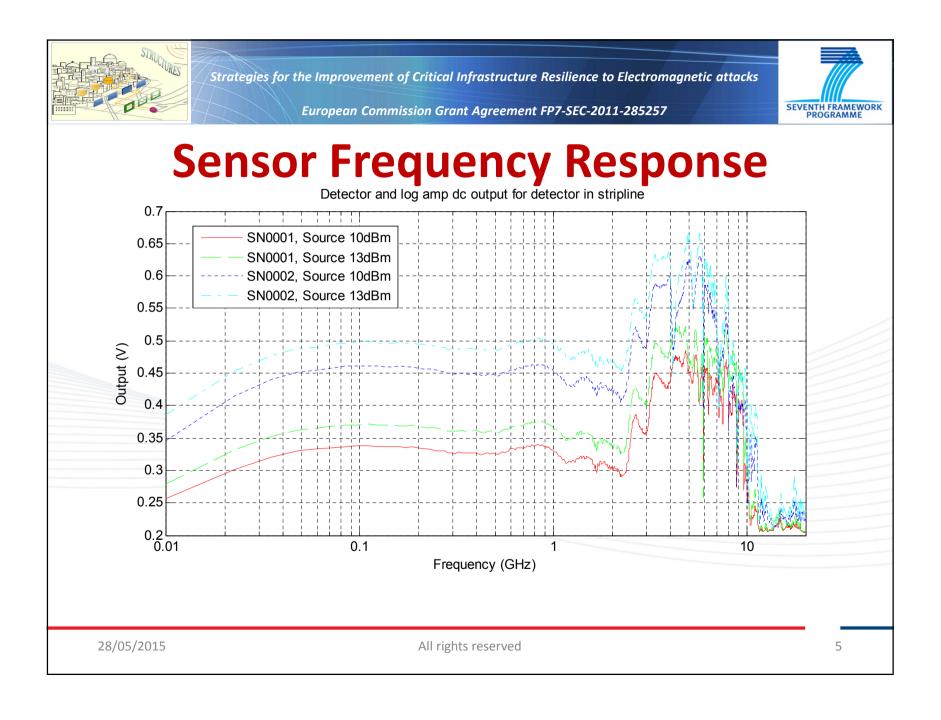


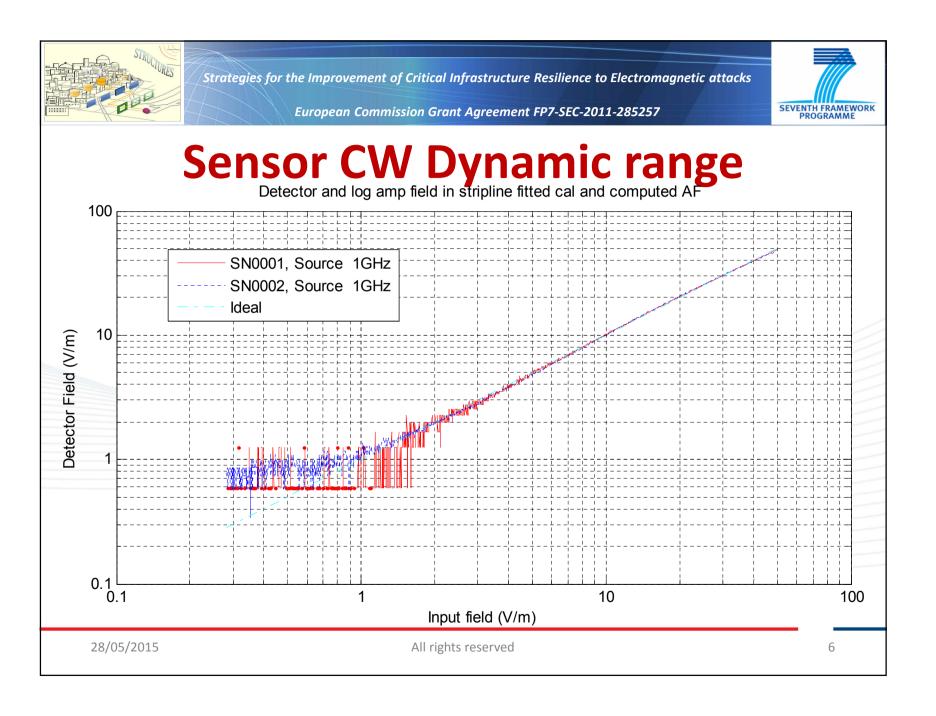


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Sensor in 25mm Stripline





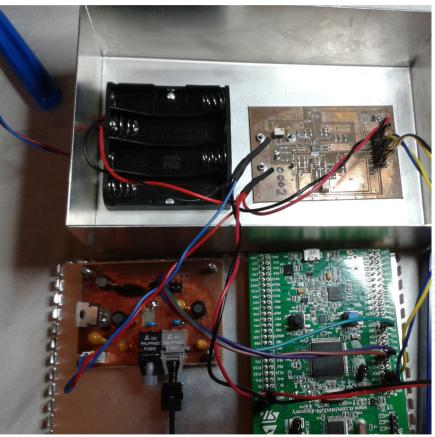






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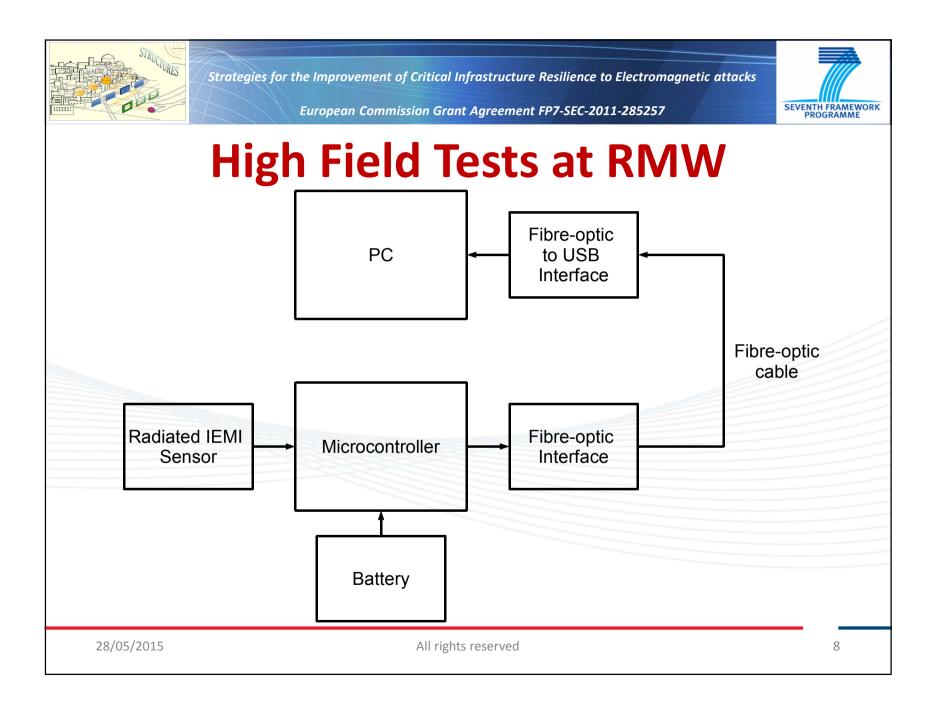
Detector Assembly



Prototype detector, microcontroller, optical link, and batteries in shielded enclosure

Antenna close up



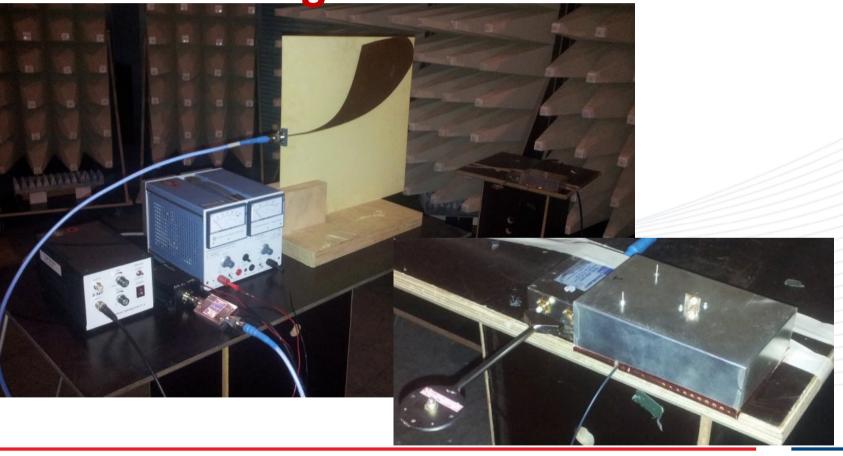






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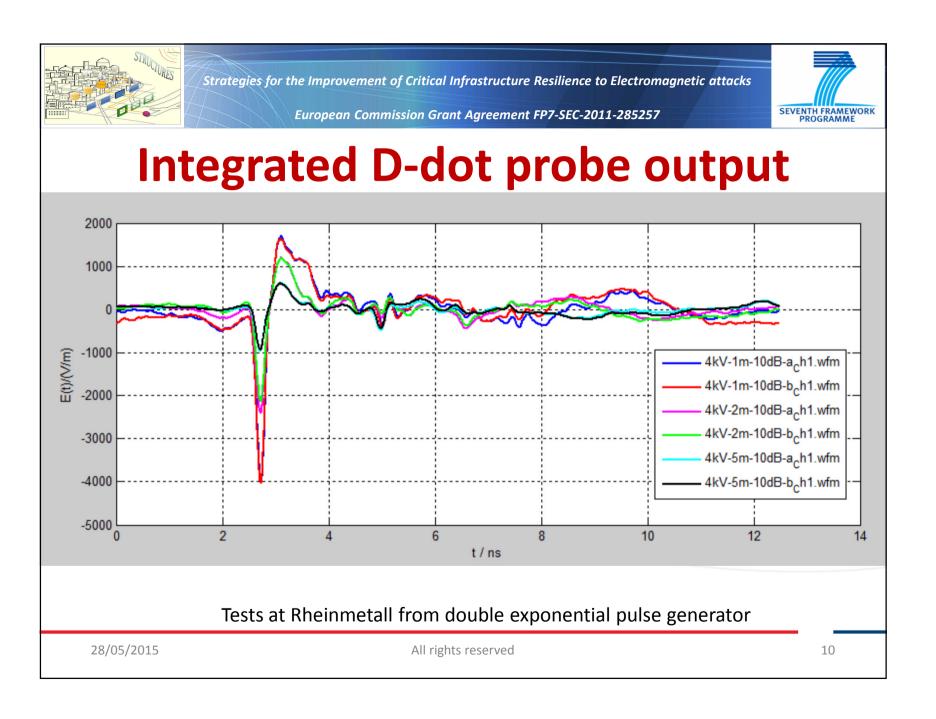
High Field Tests

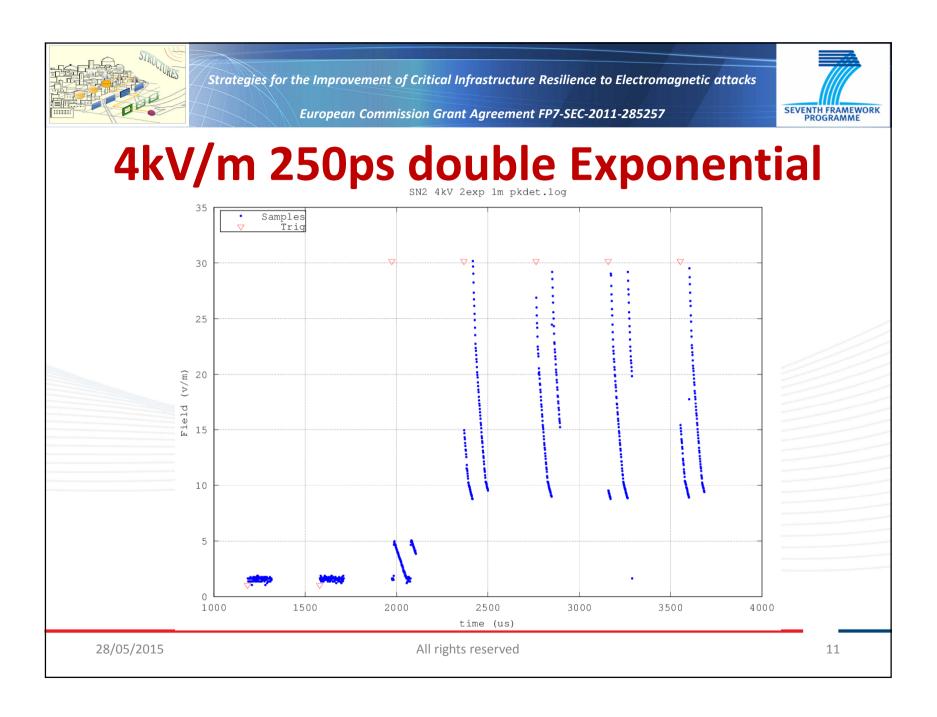


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Low cost detector Status

- Useable Radiated detector up to 6~GHz
- Frequency response flat to 2GHz
 - Sensitive 2V/m to > 4kV/m
- Partial response to short pulses
 - Sensitive 200V/m to > 4kV/m for 250ps pulse
- Potential for low power operation
 - could be solar powered
- A conducted IEMI detector has also been designed using the same hardware





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IEMI Detection Systems: A system for sensing, localization and identification of IEMI attacks

Werner Hirschi, Mirjana Stojilović, Marcos Rubenstein, Benjamin Menssen, Heyno Garbe

EMC Europe 2015, Dresden Workshop 26, Paper 6b

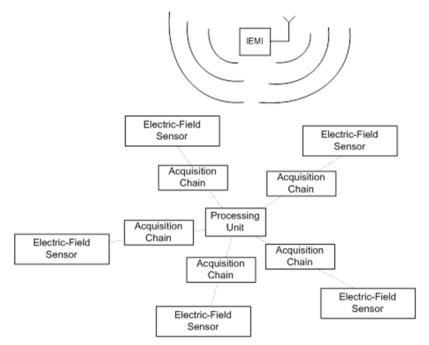




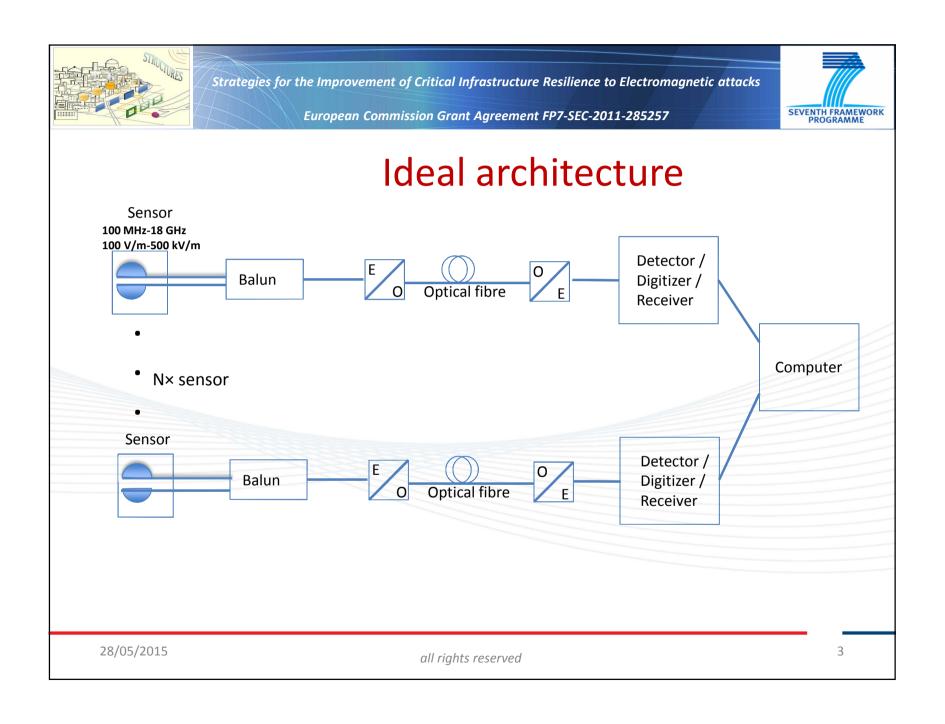
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Overall Architecture

- Localization by the time difference of arrival method
- Identification of IEMI sources by analysis of the received waveforms



Overall architecture for identification and localization system for IEMI sources





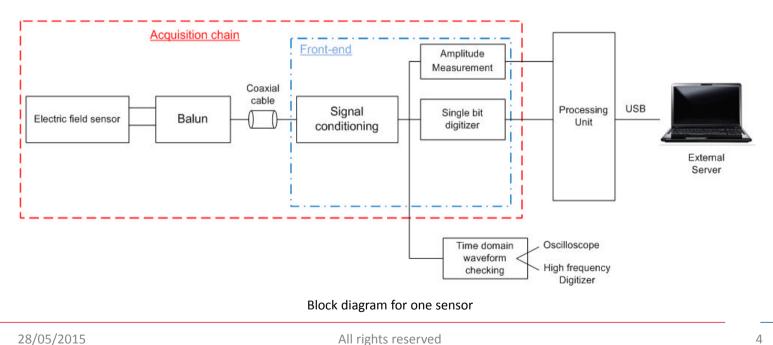


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Block Diagram for one sensor

- Electric-field sensor
- Signal Conditioning
- Amplitude Measurement
- Single bit digitizer

- Time domain waveform checking
- Processing unit
- External server



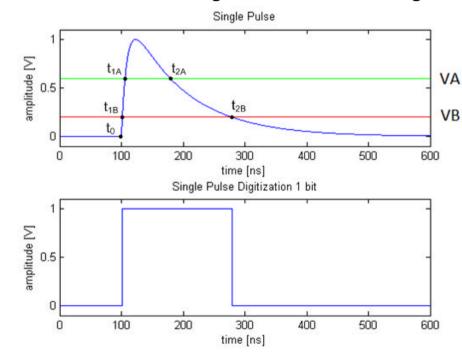




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Estimations of waveform parameters Single pulse double exponential

- Estimating time constants
 - From timing two threshold crossings we can obtain the two time constants



$$V_{\rm A} \cong V_{\rm 0} e^{-t_{\rm 2A}'/ au_{
m 1}} \qquad V_{
m B} \cong V_{
m 0} e^{-t_{\rm 2B}'/ au_{
m 1}}$$
 $V_{
m A}/V_{
m B} \cong e^{(-t_{\rm 2A}'+t_{\rm 2B}')/ au_{
m 1}}$

$$\tau_1 \cong (t'_{2B} - t'_{2A}) / \ln(V_A / V_B)$$

$$V_0 \cong \frac{V_{\rm A}}{e^{-t_{\rm 2A}' \ln \left(\frac{V_{\rm A}}{V_{\rm B}}\right) / (t_{\rm 2B}' - t_{\rm 2A}')}}$$

$$\tau_2 = -t'_{1A}/\ln(e^{-t'_{1A}/\tau_1} - V_A/V_0)$$

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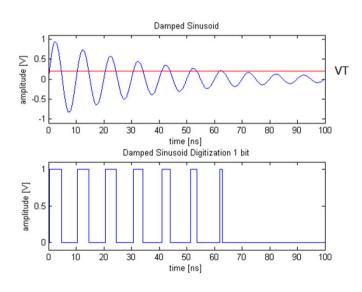




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Estimations of waveform parameters Damped sinusoid

Estimating decay time constant and fundamental frequency



$$t_{End, m} = (2m - 1)/2f$$

$$e^{-t/\tau} \ge V_{T}$$

$$t \le -\tau \ln(V_{T})$$

$$\frac{2m - 1}{2f} \le -\tau \ln(V_{T})$$

$$\tau \ge -\frac{2m - 1}{2f \ln(V_{T})}$$

 $t_{Start, m} = m / f$

$$x(t) = \sin(2\pi f t)e^{-t/\tau}$$

$$\sin(2\pi f t)e^{-t/\tau} = V_{T}$$

$$f = \frac{n-1}{2\Delta t} \quad \text{if} \quad n > 1$$

Damped sinusoid

$$f \approx \frac{p-1}{2\Delta t_{n,V_{\rm T} \neq 0}}$$

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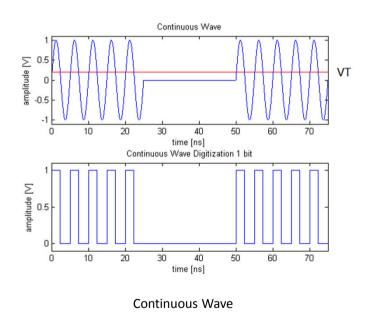




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Estimations of waveform parameters Continuous wave

Estimating fundamental frequency



$$\Delta t_n = \frac{(n-1)\pi}{2\pi f}$$
 If n is odd

$$\Delta t_{_{n}} = \frac{\pi - 2\arcsin(V_{_{\mathrm{T}}}) + (n-2)\pi}{2\pi f}$$
 If n is even

$$f = \frac{n-1}{2\Delta t_n}$$
 If n is odd

$$f = \frac{\pi - 2\arcsin(V_{\rm T}) + (n-2)\pi}{2\pi\Delta t_n}$$
 If n is even

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Specifications of the demonstrator

- System able to accept large dynamic in amplitude & frequency
 - Amplitude dynamic range : min 100 V/m; max 20 kV/m
 - Frequency dynamic range : a few hundred Hz -> 1 GHz
- Amplitude measurement with fast transition and rise time in case of the pulse signal
 - lowest rise time = 300 ps
 - lowest duration 50% = 1 ns

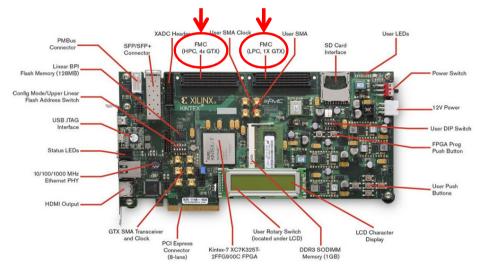




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KC705 Evaluation Board for the Kintex-7 FPGA

Main reason for the choice



- High-performance transceivers capable of up to 12.5 Gb/s; the demonstrator of the Structures project runs at 8 Gb/s
- Extremely cheap multi channel high speed digitizing system



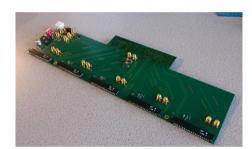


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System assembly



Sensor board



Interface Board



FPGA



Integrated equipment

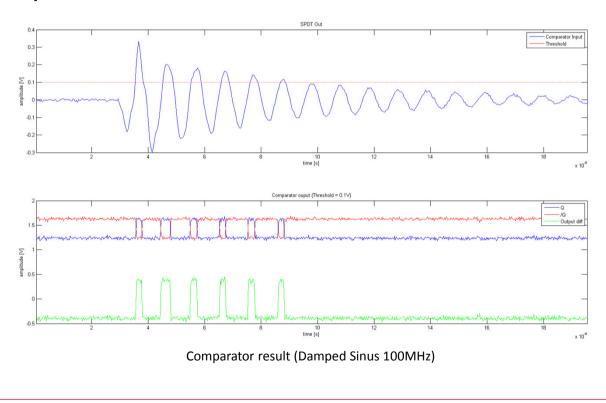




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Hardware results & measurement

Comparator measurement



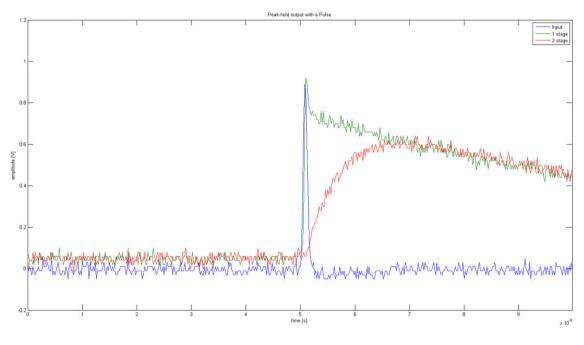




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Hardware results & measurement

Peak-hold measurement



Peak-hold with pulse signal





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Algorithm: Localization

Time Difference of Arrival (TDoA)

- Calculating the time difference between the received signals at the different sensor locations using the cross correlation algorithm
- 5 sensors are used of which one is considered as reference
- Using 5 sensors, the set of equations can be linearized
- Solving the source location by linear algebra methods

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Localization and identification system Status

Prototype detection and identification system demonstrated