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MO-SHW: Hierarchy-Aware Multi-Objective Optimization for Open-World Segmentation

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Abstract

The exploitation of hierarchical information by vision models has shown significant benefits in various segmentation tasks. However, this remains largely unexplored in open-world scenarios, where models must cope with unknown, evolving, and underrepresented labeled class spaces. Most existing hierarchy-aware segmentation approaches are not readily applicable to open-world settings. This is primarily because they rely on architectural modifications that are incompatible with the design constraints of open-world models. Moreover, hierarchy-aware losses are challenging to integrate into such pipelines, as they often conflict with task-specific objectives and exacerbate optimization complexity in already multi-objective training environments. In this work, we demonstrate that hierarchy-aware losses can be effectively leveraged in open-world models when optimized under a multi-objective learning framework. Specifically, we show that gradient-based multi-objective optimization methods, such as multi-objective gradient descent (MOGD), are well-suited for jointly optimizing hierarchical and task-specific objectives, leading to better overall performance. To support this, we propose SHW, a novel hierarchy-aware loss function based on the Wasserstein distance. SHW is lightweight, model-agnostic, and encourages intra-class compactness and inter-class separation across multiple semantic levels. The integration of SHW with MOGD yields a general, model-agnostic framework that enables the effective exploitation of semantic hierarchies in open-world segmentation tasks, improving the performance of several recent methods.

1 Introduction

In computer vision tasks, the ability to understand and interpret a scene goes beyond recognizing individual objects. True visual understanding involves identifying the semantic relationships between the objects present in the scene. These relationships encompass several aspects, such as spatial positioning (how objects are arranged or oriented relative to each other), functional interactions (the roles or actions that entities perform or are capable of performing), and categorical associations (how objects are grouped based on similar or

shared attributes). Such relationships provide context, enabling a more refined and accurate interpretation of visual data. They often appear as hierarchies, which are structures that gradually connect broad, generic categories to increasingly detailed and specific concepts. Understanding the context of hierarchical relationships is fundamental in semantic segmentation tasks, where images are partitioned into regions labeled with different object classes. As the system learns typical spatial arrangements and inter-object relationships, it becomes capable of producing more precise segmentation boundaries, with more accurate and less uncertain label assignments.

In open-world tasks [24, 66], systems must adapt to an unpredictable and constantly changing environment. In such scenarios, models must simultaneously address the following challenges: handling imbalanced data distributions (imbalanced learning [46]), effectively learning underrepresented classes (few-shot learning [51]), detecting samples from unknown classes (open-set recognition [42, 59]), identifying what those unknown classes are (novel class discovery [53]), and incrementally learning new classes without forgetting previously acquired knowledge (class-incremental learning [64]). By exploring how classes are hierarchically related, it becomes possible to share knowledge among them, allowing models to leverage previously learned patterns from other classes to make more informed predictions under limited data conditions. This knowledge transfer benefits the learning of minority and few-shot classes, since the model can exploit common features of a broader category to infer about a specific class, as well as the learning of incremental classes, as the previously acquired general knowledge can assist in assimilating new related concepts. Furthermore, the understanding how classes relate to each other enables the model to construct embeddings that are coherent with semantic relationships, bringing semantically related classes closer together and pushing unrelated ones apart, thus facilitating the recognition of pixels belonging to unknown labels and the identification of novel classes.

Although some works in the semantic segmentation literature have explored semantic hierarchies [27, 28, 32], most of these methods are designed for closed-world problems, in which all classes are previously known and well-represented, limiting their applicability in real-world scenarios. Consequently, such approaches struggle to address open-world challenges, which involve the presence of unknown or underrepresented classes and the need for incrementally learning new classes. Existing open-world methods either overlook hierarchical structures or address only isolated challenges. To the best of our knowledge, the exploitation of class hierarchies remains unexplored in comprehensive open-world scenarios.

According to some of the most effective approaches [30, 31, 40] of hierarchical learning in closed-world settings, one of the most common and effective ways to exploit semantic hierarchies is through the use of hierarchy-aware losses. However, incorporating them into existing open-world pipelines presents several challenges: I) Typically, open-world models already include several loss terms. Adding another one increases training complexity and makes it more difficult to achieve consistent results, both in terms of maintaining strong performance on the main task and in effectively acquiring the knowledge provided by the hierarchical loss. II) The hierarchical losses proposed for semantic segmentation are incompatible with most open-world models, as they require specific modifications in the model architecture that are prohibitive of being made in most open-world pipelines [27], such as changing the meaning or structure of their output, or are conflicting with their main loss objectives [40].

Toward overcoming challenge I, we investigate the idea of handling the several loss terms of the open-world model as different objectives and employ model optimization through multi-objective gradient descent, instead of aggregating them in a single objective (a.k.a.

scalarization technique [22, 26]) as done by most works of the deep learning literature. Our motivation is grounded in insights from the multi-objective optimization literature [11, 21, 45], which demonstrate that jointly optimizing multiple objectives enables a more effective exploration of the solution space, leading to outcomes that better satisfy each objective individually. Based on this, we hypothesize that adopting a multi-objective framework can enhance the optimization of hierarchical-aware losses without hindering, but also improving the optimization of the primary objectives already present in open-world models.

To address challenge II, we introduce SHW (Semantic Hierarchy-Aware Wasserstein), a novel loss function designed to enhance the hierarchical structure of learned feature representations. SHW explicitly enforces inter-class separation and intra-class compactness across multiple semantic levels, encouraging a structured embedding space where pixel representations align with the underlying class hierarchy. By operating directly on the output of the feature extractor, SHW remains agnostic to the model architecture, requiring no alterations to the model architecture. This design ensures seamless integration into existing open-world learning pipelines, regardless of the task-specific loss functions already in use, thereby preserving compatibility. Furthermore, SHW leverages the Wasserstein distance [41, 58] to compare class distributions. Unlike traditional distance metrics, the Wasserstein formulation captures both the magnitude and the structural geometry of differences in the feature space. This is particularly beneficial in open-world scenarios, where data distributions are non-stationary, imbalanced, and subject to the emergence of previously unseen classes. The use of Wasserstein distance allows SHW to be sensitive to these complexities, providing more stable gradients, improved generalization to underrepresented or novel classes, and better robustness to distributional shifts [35, 37], all of which are critical for scalable and adaptive open-world systems.

Through the integration of our solutions for challenges I and II, we construct a unified framework (MO-SHW) that enables open-world models to effectively leverage semantic class hierarchies. Empirical results show that our framework effectively improves closed-world segmentation and consistently enhances the performance of open-world models yielding significant improvements for state-of-the-art methods in the sub-tasks of open-set semantic segmentation and few-shot class-incremental semantic segmentation.

Summary of contributions:

- i We are the first to enable the effective exploitation of class hierarchies in comprehensive open-world semantic segmentation, resulting in consistent improvements in performance across multiple sub-tasks.
- ii We introduce a model-agnostic hierarchy-aware representation learning framework that augments open-world semantic segmentation pipelines with awareness of semantic hierarchy. The framework offers seamless *plug-and-play* integration, requires no modifications to the model architecture, ensures ease of adoption, and introduces only minor computational and memory overhead.
- iii We show that employing gradient-based multi-objective optimization significantly improves training outcomes when using hierarchy-aware loss functions, by better balancing competing objectives.
- iv We propose **SHW**, a novel Wasserstein-based hierarchy-aware loss function that enforces hierarchical consistency among pixel embeddings in open-world models.

2 Background and Related Work

2.1 Open-World Semantic Segmentation

In real-world scenarios, systems usually operate in open long-tailed data scenarios [38], where they have to continuously adapt and learn from limited and unseen data. When these challenges are simultaneously encountered in the same scenario, they are studied under the umbrella of Open World Recognition [38, 66] - a paradigm in machine learning that aims to overcome the limitations of closed-world models by enabling them to recognize when faced with something unknown and incorporate this new information into their learning process. Ideally, open-world models must deal with several subtasks, such as imbalanced learning [7], few-shot learning [10], open-set recognition [42], novel class discovery [63] and class-incremental learning [60]. However, in the context of semantic segmentation, only a few methods have been proposed to jointly handle more than one subtask. Some methods [8, 16] separate the open-world problem in three sequential steps: (1) Open-Set Semantic Segmentation (6.1.1), to classify pixels from known classes and recognize unknown; (2) Manual labeling of unknown pixels (with human supervision), to group them in novel classes; and (3) Few-Shot Class-Incremental Semantic Segmentation (6.1.2), to learn these novel classes. Some other works [50, 54] replace step (2) with the use of automatic learning strategies to identify novel classes, a.k.a. Novel Class Discovery. **Open-World methods exploiting class hierarchies.** While some existing methods leverage hierarchical relationships among classes to address open-world challenges, they are tailored to tackle only specific subtasks in isolation. For example, certain incremental learning approaches [20, 25] utilize class hierarchy information to facilitate knowledge expansion. However, these methods are generally evaluated on closed-world benchmarks and do not address key open-world challenges such as the handling of underrepresented or unknown classes. Our proposed methodology is task-agnostic and seamlessly integrates into existing open-world pipelines providing plug-and-play exploitation of semantic class hierarchies to a wide range of models and subtasks. To the best of our knowledge, our work is the first to provide hierarchy-aware learning across a broader spectrum of subtasks in the open world.

2.2 Hierarchy-Aware Semantic Segmentation

Several works in the semantic segmentation literature have been designed with the purpose of exploring the information of class hierarchies. They usually exploit hierarchical information through modifications in the network architecture, specific loss objectives, or learning embeddings with hierarchical coherence. As they were typically designed for closed-world problems, they are not properly equipped to effectively operate in more realistic data scenarios. **Hierarchy-Aware Architectures** [32, 33, 39, 56] encode the class hierarchy directly into the network structure. They typically construct structured neural modules, which replicate the hierarchy semantics, to replace the class-agnostic segmentation head of existing standard segmentation models, producing a hierarchy-aligned architecture. This often causes significant architectural modifications, hindering generality as the model becomes more specific and complex, and leading to scalability issues, as the number of parameters usually increases with the size of the hierarchy. **Hierarchy-Aware Losses** [40] are designed to incorporate the class hierarchy into the learning process by directly penalizing predictions that violate hierarchical relationships. These objectives are parameterized by the class hierarchy, ensuring that the model's predictions respect the structured relationships between

classes. However, incorporating hierarchical losses can introduce additional complexity to already intricate pipelines, such as those designed for open-world problems, burdening models that already feature multiple loss terms, complicating the training process, and consequently hindering performance improvements. **Hierarchy-Aware Embeddings** [27, 30, 31] aim to capture multiple levels of class abstraction within a single embedding representation, ensuring that similar or related classes are positioned closer together in the embedding space, thus reflecting their hierarchical relationships. Specifically, some approaches [27] parameterize the hierarchical embedding space using hierarchical models, which intuitively organize embeddings to mirror the structure of the class hierarchy. These models are often computationally intensive and require adjustments in the network architecture to accommodate different hierarchies. This leads to increased complexity and resource demands, making them less practical for large-scale applications. **Employing Hierarchy-Aware Approaches in Open-World Pipelines.** Although the closed-world literature offers a variety of hierarchy-aware methods (*e.g.* loss functions) that are relatively easy to integrate and have shown promising result, these approaches are generally unsuitable for open-world segmentation models. For instance, HSSN* [30, 31] introduces the Focal Tree-Min Loss, which enforces hierarchy-consistent predictions, and the Tree-Triplet Loss, which imposes hierarchical separation margins on pixel embeddings across distinct semantic classes. However, both rely on a multi-label classification paradigm that requires architectural changes incompatible with most open-world segmentation frameworks. Likewise, HCE [40] proposes a hierarchy-aware cross-entropy formulation to account for inter-class hierarchical relations. However, in open-world settings, where label spaces may be incomplete, dynamic, or unknown, such objectives often conflict with the primary task losses, limiting their applicability. To the best of our knowledge, no current hierarchy-aware semantic segmentation method is directly compatible with open-world models without imposing significant constraints or introducing incompatibilities.

3 Methodology

With the goal of enabling the effective exploitation of semantic hierarchies in open-world segmentation models, we propose MO-SHW (Fig. 1) - a unified model optimization framework that integrates two complementary components: the SHW loss (Section 3.2) and a gradient-based multi-objective optimization (Section 3.1). This integration combines the structural benefits of SHW, which enforces hierarchical organization in pixel embeddings with seamless adaptability, with the broader exploratory capacity of multi-objective optimization, which allows for a more balanced and principled trade-off among competing objectives. By employing gradient-balancing methods, our approach ensures the simultaneous and efficient optimization of both task-specific and auxiliary hierarchy-aware losses. The final framework is model-agnostic, lightweight, and easily integrable into existing open-world pipelines. As demonstrated in our experiments, this joint formulation improves segmentation performance across several open-world methods and different subtasks.

3.1 Multi-Objective Optimization for Hierarchy-Aware Open-World Models

Deep learning models are traditionally trained using single-objective loss functions that aggregate multiple objectives into a single scalar value through weighted sums - a method

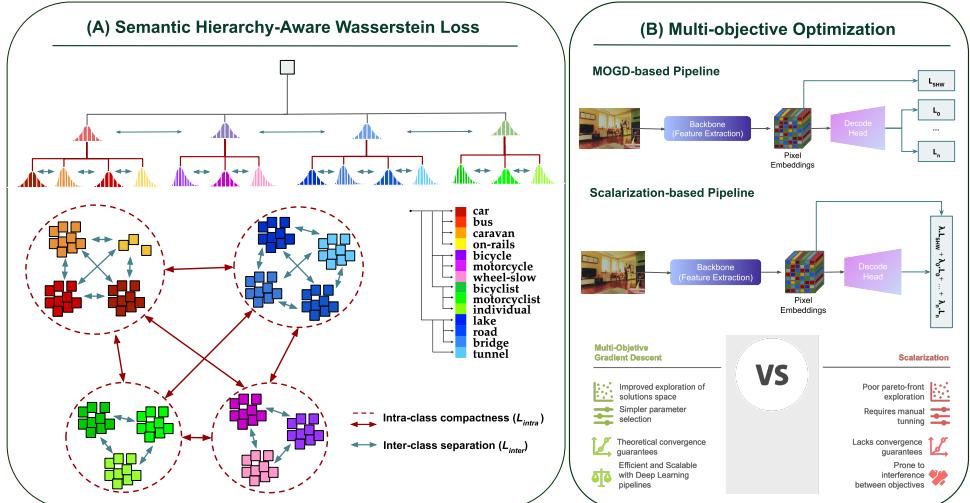


Figure 1: Overview of the proposed MO-SHW methodology. It comprises two key components: (A) the Semantic Hierarchical Wasserstein (SHW) loss (Sec.3.2), which operates directly on pixel class distributions explicitly enforcing inter-class separation and intra-class compactness across multiple semantic levels to encourage a structured embedding space where pixel representations are aligned with the underlying class hierarchy; and (B) a multi-objective optimization strategy (Sec. 3.1) based on Gradient Descent (MOGD). Unlike scalarization, which aggregates multiple objectives into a single weighted loss, MOGD treats each objective independently, offering several advantages in terms of solution-space exploration, parameter tuning, and convergence guarantees.

known as Scalarization [22, 26]. However, this approach has several limitations that can hinder effective model training in complex, multi-objective optimization scenarios. Scalarization often requires manual tuning of loss term weights, lacks convergence guarantees to Pareto-optimal solutions, and is prone to suboptimal trade-offs - especially in non-convex or conflicting objective settings [22]. It also struggles to identify "unsupported" yet valuable solutions and is susceptible to gradient interference between tasks, which can destabilize training and reduce optimization efficiency [14].

These limitations are especially critical in open-world scenarios, where models are required to simultaneously optimize a diverse set of objectives (*e.g.* segmentation accuracy, novelty detection, and semantic consistency). The challenge is further exacerbated when integrating additional objectives, such as hierarchy-aware losses, alongside task-specific losses. In such complex multi-objective settings, scalarization tends to oversimplify the optimization landscape, often leading to suboptimal solutions or unstable training dynamics.

To address these limitations, we reformulate model training as a multiobjective optimization (MOO) problem. Our hypothesis is that treating each objective as a distinct optimization target allows for a more principled and balanced training process. Rather than collapsing all objectives into a single function, a MOO formulation enables simultaneous optimization of multiple loss functions, which we expect to improve model optimization across both standard and hierarchy-informed evaluation metrics alongside with its overall segmentation performance.

Among the available MOO strategies (detailed in Appendix 6.1.3), we adopt a gradient-balancing algorithm due to its ability to effectively balance theoretical robustness with computational efficiency. Unlike Pareto-based algorithms, which are computationally intensive, or loss-weighting heuristics, which lack formal convergence guarantees, gradient-based approaches scale well with modern deep learning pipelines while providing theoretically grounded convergence to Pareto-stationary solutions [11]. Specifically, we adopt Aligned-MTL [47] as our gradient-balancing multi-objective optimization algorithm due to its strong empirical performance in recent comparative studies [34].

3.2 SHW: Semantic Hierarchy-aware Wasserstein Loss

Our goal is to design a loss function that encourages the model to learn feature representations aligned with the semantic structure of the class hierarchy, bringing embeddings of semantically similar classes closer together while pushing apart those of semantically distant classes. To ensure compatibility with a wide range of model architectures, the proposed loss should not depend directly on the model’s output (e.g., predicted labels) or require any modifications to the architecture itself. To this end, we propose leveraging the Wasserstein distance D_w (Appendix 6.1.4), approximated via DbTSW [52], to act directly on pixel embeddings, reorganizing their structure in the feature space by comparing the distances between their associated class distributions. The use of this distance is particularly advantageous for open-world learning, as it enables the model to better capture semantic relationships [35, 36], handle uncertainty, and deal more effectively with novel or out-of-distribution inputs [13].

We introduce a contrastive learning objective, L_{SHW} (Eq. 3), designed to compare class distributions across multiple levels of a class hierarchy \mathcal{H} , guided by two core principles: promoting intra-class proximity (Eq. 1) and enforcing inter-class separation (Eq. 2). The first component, L_{intra} , encourages each class node v to move closer to its parent class v_p , while simultaneously pushing it away from all other non-parent classes $u \in \Gamma(v)$ at the same higher hierarchical level. The second component, L_{inter} , aims to increase the separation between v and its immediate siblings $s \in S(v)$, that is, the other child nodes sharing the same parent. The overall loss is defined as:

$$L_{intra}(v) = -\log \frac{\exp(-D_w(v, v_p))}{\sum_{u \in \Gamma(v)} \exp(-D_w(v, u))} \quad L_{inter}(v) = -\log \frac{1}{\sum_{s \in S(v)} \exp(-D_w(v, s))} \quad (1) \quad (2)$$

$$L_{SHW} = \sum_{v \in V} \lambda_l(v) \left(\frac{1}{|\Gamma(v)|} L_{intra}(v) + \frac{1}{|S(v)|} L_{inter}(v) \right) \quad (3)$$

where λ_l is a scaling parameter that imposes a fixed penalty based on a node’s position in the class hierarchy. This is grounded in the intuition that distances in the feature space should reflect the degree of semantic similarity: pairs of similar classes at deeper (more specific) levels of the hierarchy should be pulled closer together, while pairs at higher (more general) levels may tolerate greater separation. Accordingly, we apply stronger penalties to classes at lower levels of the hierarchy and weaker penalties to those at higher levels. In this sense, we define $\lambda_l(v) = \exp(1/(|L| - level(v)))$, where L is set of hierarchical levels, following the formulation shown to outperform alternative penalty schemes in prior work [61].

4 Experimental Evaluation

4.1 Multi-Objective Optimization for Hierarchy-Aware Losses

Table 1: Quantitative results of the comparison between model optimization strategies employing hierarchical-aware losses in the Cityscapes [12] dataset. Values in green indicate MOGD gains against Scalarization.

Objective Functions	Scalarization			Multi-objective GD		
	CE loss ↓	HA loss ↓	mIoU% ↑	CE loss ↓	HA loss ↓	mIoU% ↑
CE (flat model)	0.1891	—	80.97	—	—	—
CE + HCE [40] [VISIGRAPP’20]	0.1830	0.1957	81.09	0.1697 (-0.0133)	0.1763 (-0.0194)	81.88 (+0.81)
CE + HSSN* [31] [TAPMI’23]	0.1755	0.3364	81.62	0.1659 (-0.0095)	0.3105 (-0.0259)	82.09 (+0.47)
CE + SHW (Section 3.2)	0.1673	-2.1563	82.03	0.1431 (-0.0242)	-2.4216 (-0.2653)	83.19 (+1.16)

This experiment aims to evaluate the effectiveness of our proposed multi-objective optimization strategy (described in Section 3.1) for training models with additional hierarchy-aware losses, compared to the conventional single-objective scalarization approach. We evaluate these optimization strategies using three distinct loss functions: HCE [40], a widely adopted formulation of hierarchy-aware loss in computer vision; HSSN* [31], currently one of the best-performing methods for hierarchy-aware semantic segmentation in closed-world settings; and our proposed SHW loss (see Section 3.2). **Experimental Setup:** Given that HCE and HSSN* are not readily adaptable to open-world models (as discussed in Section 2.2), this evaluation is conducted within a standard closed-world setting using the Cityscapes dataset and the DeepLabV3+ architecture with a ResNet-101 backbone trained for 90K iterations. See Appendix 6.2 for other details. **Quantitative Results:** As shown in Table 1, the multi-objective optimization strategy led to consistent and substantial improvements across all evaluated loss functions. These results demonstrate that the proposed approach can identify solutions that more effectively optimize the targeted objectives, all within the same training budget. The observed improvements in individual loss metrics align with insights from the multi-objective optimization literature [22], which suggest that simultaneously optimizing multiple objectives enables a more thorough exploration of the solution space, allowing superior trade-offs and better fulfillment of each objective. These findings provide strong empirical support for our hypothesis that multi-objective optimization not only enables the seamless incorporation of hierarchy-aware losses into open-world segmentation models, but also improves overall performance by jointly enhancing both auxiliary (hierarchical) and primary (task-specific) learning objectives. *SHW in closed-world:* Although the primary objective of the proposed SHW loss is its employment in open-world tasks (Section 4.2), experimental results also reveal strong performance in closed-world settings. Specifically, SHW achieves a notable improvement of nearly 2% in mIoU under the multi-objective optimization framework when compared to standard flat segmentation. **Qualitative Results:** please see Appendix 6.3.2.

4.2 Evaluating the Proposed Framework in Open-World Pipelines

The following experiments are designed to evaluate the impact of our proposed framework (MO-SHW), which combines the SHW loss with a multi-objective optimization strategy using a gradient-balancing algorithm, on open-world semantic segmentation pipelines. To ensure a comprehensive evaluation, we adopt a standard protocol in the open-world semantic

segmentation literature and conduct independent assessments for each of the key subtasks: open-set semantic segmentation and few-shot class-incremental semantic segmentation. A more detailed description of the experimental setups is provided in Appendix 6.2.

Table 2: Quantitative evaluation of open-set semantic segmentation on the Street-Harzards [19] dataset.

Method	Anomaly Segmentation		mIoU↑	Open-Set Segmentation		
	AuPRC↑	FPR ₉₅ ↓		O-IoU ₁₅ ↑	O-IoU ₁₆ ↑	O-IoU↑
DML [8] [ICCV'21]	14.7	17.3	53.9	-	-	-
MSP [ICLR'17]	7.5	27.9	65.0	32.7	40.2	35.1
ODIN [ICLR'18]	7.0	28.7	65.0	26.4	33.9	28.8
OE [ICLR'19]	14.6	17.7	61.7	43.7	44.1	43.8
OOD-H [GCPR'19]	19.7	56.2	66.6	33.7	34.3	33.9
Energy [NurIPS'20]	12.9	18.2	63.3	41.7	44.9	42.7
ReAct [NurIPS'21]	10.9	21.2	62.7	33.0	36.2	34.0
OH*MSP [CoRR'21]	18.8	30.9	66.6	43.3	44.2	43.6
ML [ICML'22]	11.6	22.5	65.0	39.6	44.5	41.2
AEM [CVPRw'23]	30.7	99.7	71.3	35.3	54.6	41.4
Rba [ICCV'23]	50.1	96.9	73.2	10.4	12.1	10.9
DH [17] [ECCV'22]	30.2	13.0	63.0	46.1	45.3	45.8
DH + MO-SHW (ours)	35.9	12.1	66.3	47.2	46.6	46.9
M2A [44] [CVPR'23]	58.1	14.9	72.3	59.9	59.7	59.8
M2A + MO-SHW (ours)	58.7	15.3	74.1	60.7	60.2	60.3

Open-Set Semantic Segmentation (OSSS). For this subtask, we selected DenseHybrid [17] and Mask2-Anomaly [44], two of the most recent and best-performing methods in the literature, as base models. We integrated our framework into their respective pipelines and compared the resulting models against their original versions as well as other prominent baselines from the open-set segmentation literature. *Quantitative Results:* Table 2 presents the comparative results. Overall, the MO+SHW-augmented models consistently outperform their original counterparts and competing baselines, with pronounced improvements observed for the DenseHybrid variant. The anomaly segmentation metrics reveal that incorporating MO-SHW enhances the models’ ability to detect out-of-distribution pixels. Specifically, DenseHybrid benefited from a notable reduction in false positives, while Mask2Anomaly experienced a marginal increase. In line with the observations of Section 4.1, the proposed framework substantially improved performance in closed-world sem. segmentation, suggesting improved dense prediction capabilities. Furthermore, the open-set recognition metrics indicate that MO-SHW introduces modest but meaningful gains in the models’ ability to identify unknown classes. These findings confirm that MO-SHW effectively boosts the general predictive performance of models in open-set semantic segmentation tasks, by simultaneously enhancing the recognition of both known (closed-set) and unknown (open-set) categories.

Few-Shot Class-Incremental Semantic Segmentation (FSCISS). We integrated the our framework into the pipelines of two traditional methods for this task: PIFS [9] and GAPS [43]. The performance of the resulting MO-SHW-augmented models was then compared against their original versions as well as other notable approaches from the FSCILSS literature. *Quantitative Results:* As reported in Table 3, the MO-SHW-extended models consistently outperform their respective baselines across all evaluation metrics. Notably, improvements in mIoU_{new} demonstrate that our approach enhances the models’ capacity to learn novel

Table 3: Quantitative evaluation for few-shot class-incremental semantic segmentation in the PASCAL-5ⁱ [1] dataset.

Method	1-shot			5-shot		
	mIoU _{base} ↑	mIoU _{new} ↑	HM↑	mIoU _{base} ↑	mIoU _{new} ↑	HM↑
Fine-Tunning	47.2	3.9	7.2	58.7	7.7	13.6
EHNet [49] [ACM-MM'22]	68.4	18.8	29.1	67.9	31.3	43.5
CaLNet [48] [ACM-MM'23]	74.2	17.4	28.2	74.7	30.1	42.9
SRAA [65] [MMM'24]	66.4	18.8	29.3	64.3	28.7	39.7
MBCL [62] [ISCAS'24]	65.0	19.2	29.6	66.1	28.5	40.0
PIFS [9] [BMVC'21]	64.1	16.9	26.7	64.5	27.5	38.6
PIFS + MO-SHW (ours)	65.9	18.5	28.8	65.3	29.2	39.9
PIFS + GAPS [43] [CVPRw'23]	66.8	23.6	34.7	68.2	43.9	53.4
PIFS + GAPS + MO-SHW (ours)	68.5	25.6	37.2	68.9	46.4	55.4

classes with limited supervision. Concurrently, gains in mIoU_{base} indicate improved retention of previously acquired knowledge, suggesting that MO-SHW not only facilitates the acquisition of new concepts but also mitigates the effects of catastrophic forgetting. These results highlight the effectiveness of the MO-SHW framework in supporting continual learning under few-shot constraints, thereby improving both adaptability to novel information and stability of prior knowledge in open-world segmentation scenarios.

5 Conclusion

In this paper, we address the challenge of incorporating hierarchical understanding into open-world semantic segmentation. We proposed a novel framework that enables supervised open-world models to effectively leverage semantic class hierarchies, thereby improving both the robustness and generalization of their predictions. Our framework introduces two key contributions: (i) a novel and adaptable Wasserstein-based hierarchy-aware loss function (SHW) which enforces hierarchical consistency by promoting intra-class similarity and inter-class separation across multiple levels of abstraction without architecture modifications; and (ii) the integration of this loss into a multi-objective optimization paradigm using gradient-balancing methods, allowing simultaneous and balanced optimization of hierarchical and task-specific objectives. Our approach has several advantages: it is model-agnostic, seamlessly integrates into existing pipelines, introduces minimal computational overhead, and maintains compatibility with the training dynamics of open-world segmentation tasks. Through experiments on several benchmarks, we empirically demonstrated that our framework consistently enhances the performance of leading open-world segmentation models, including recent methods for open-set segmentation and few-shot class-incremental learning. These results show that semantic hierarchies offer a valuable source of structural prior knowledge, which, when properly integrated, can significantly improve open-world reasoning in visual scene understanding.

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