

Supplementary material for mobile sensors for hydraulic calibration of pipe network models

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Table S1. Candidate pipe roughness values used in the optimisation

No.	Water supply network roughness height (Ks)	Sewer network (Manning's n)
	(mm)	(dimensionless)
1	0.045	0.0060
2	0.104	0.0087
3	0.155	0.0095
4	0.184	0.0101
5	0.212	0.0108
6	0.239	0.0115
7	0.277	0.0121
8	0.316	0.0128
9	0.320	0.0132
10	0.331	0.0138
11	0.435	0.0147
12	0.659	0.0157
13	1.121	0.0165
14	2.074	0.0182
15	3.164	0.0202
16	6.769	0.0260

Table S2. Summary of key simulation and optimisation parameters used in the study

Category	Parameter name	Value	Sensing type	Applicable scenario	Rational for selection
Simulation parameters	Demand profile resolution	15 minutes	Both	Water supply	Defined in the water supply case study network.
	Rainfall data resolution	1 minute	Both	Sewer	Defined in the sewer case study network.
	Sampling interval	3 minutes	Both	Water supply	For mobile sensing, ensuring the possibility of collecting at least one measurement per pipe. Static sensing uses the same rate for consistency.
		10 seconds	Both	Sewer	
	Sensor speed	0.25 m/s	Mobile	Both	For the mobile sensor to traverse the entire network twice in the 24 hours.
	Data collection duration	24 hours	Both	Both	Matches 24-hour extended-period simulation for full daily demand cycle coverage.
	Number of sensor paths	4	Mobile	Both	To evaluate calibration robustness under different spatial sampling patterns.
Optimisation parameters (NSGA II)	Population size	400	Both	Water supply	To maintain population diversity for complex optimisation.
		200	Both	Sewer	
	Number of generations	5,000	Both	Both	To ensure convergence of both objective functions.
	Function evaluations	2,000,000	Both	Water supply	
		1,000,000	Both	Sewer	For exploitation of good solutions for faster convergence
	Crossover probability	1	Both	Both	
	Mutation probability	0.005	Both	Both	To maintain population diversity and avoid premature convergence.
	Number of optimisations runs	5	Static	Both	To account for NSGA-II randomness and to verify consistency of the results.
		5 per path (20 total)	Mobile	Both	
	Convergence generation criterion	10^{-4}	Both	Both	Defined as the earliest generation at which the absolute change in objective values remains below 10^{-4} over a 50-generation window.

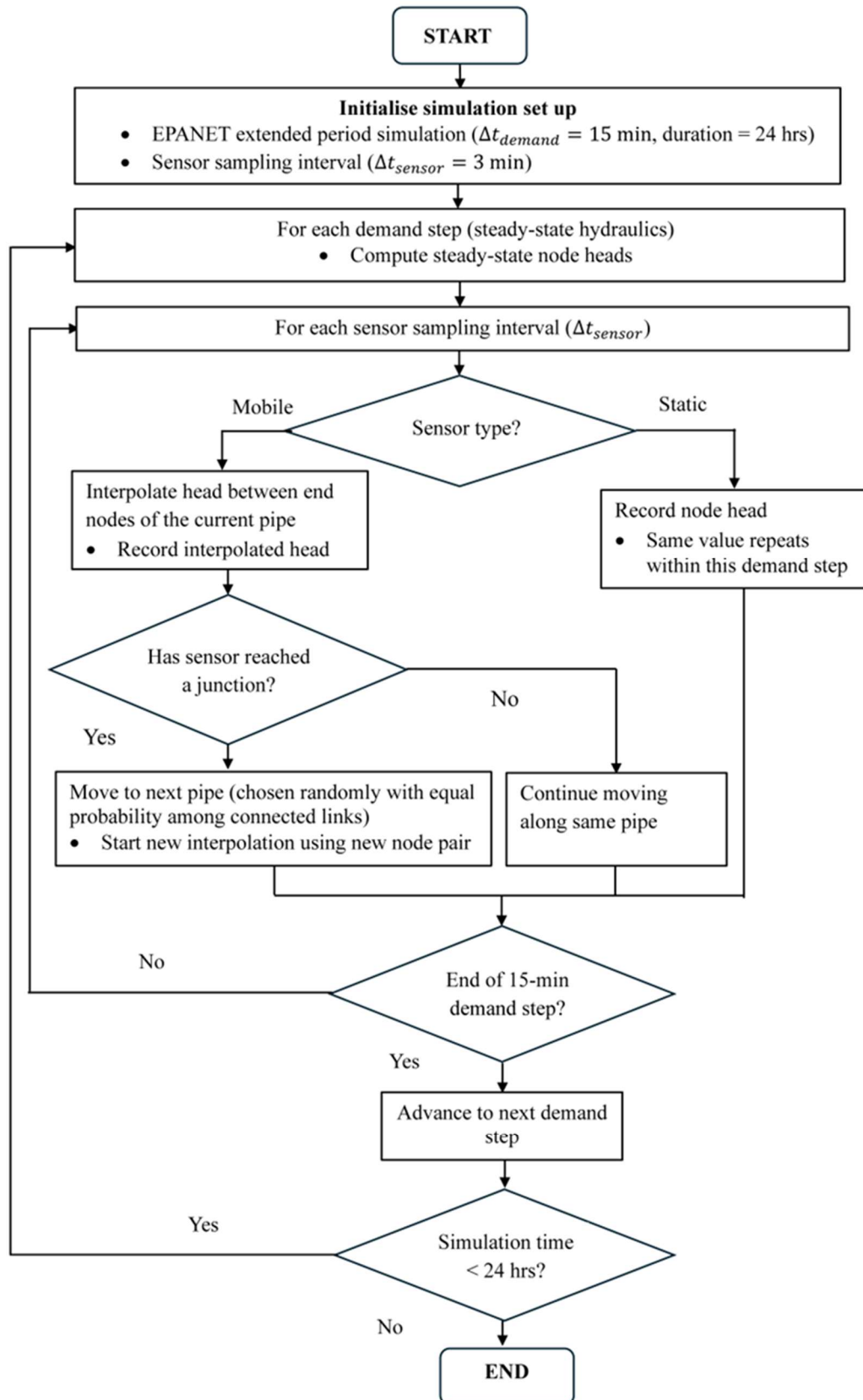


Figure S1. Flowchart illustrating how static and mobile sensors record data within EPANET's extended-period simulation.