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Jimenez Varon, Cristian Felipe and KNIGHT, MARINA IULIANA (2026) Contribution to the Discussion of 'New tools for network time series with an application to COVID-19 hospitalisations' by Nason et al. *Journal of the Royal Statistical Society: Series A (Statistics in Society)*. pp. 172-173. ISSN: 1467-985X

<https://doi.org/10.1093/jrsssa/qnaf162>

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**Cristian F. Jimenez-Varon and Marina I. Knight's
contribution to the Discussion of
New tools for network time series with an application to
COVID-19 hospitalisations by Guy Nason, Daniel Salnikov
and Mario Cortina-Borja**

Journal:	<i>Journal of the Royal Statistical Society: Series A</i>
Manuscript ID	JRSSA-May-2025-0206
Manuscript Type:	Discussion Paper Contribution
Date Submitted by the Author:	28-May-2025
Complete List of Authors:	Jiménez Varón, Cristian Felipe; University of York, Knight, Marina Iuliana; University of York, Mathematics & Statistics;
Keywords:	

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Manuscripts

Cristian F. Jiménez-Varón and Marina I. Knight's contribution to
the Discussion of "New tools for network time series with an
application to COVID-19 hospitalisations" by Guy Nason, Daniel
Salnikov and Mario Cortina-Borja

Cristian F. Jiménez-Varón¹, Marina I. Knight¹

May 28, 2025

Discussion

First of all, we would like to congratulate the authors on their insightful paper (Nason et al., 2025) and valuable contribution to the analysis of network time series by developing new tools for studying such stochastic processes. At the heart of these developments sits the generalized network autoregressive (GNAR) model, originally proposed by Knight et al. (2020) and extended to e.g., incorporate covariates (Nason and Wei, 2022), model edge-based time series (Mantziou et al., 2023), forecast (Nason and Palasciano, 2025).

Through this work, [Nason et al. \(2025\)](#) not only introduce novel time-domain tools, namely the network and partial network autocorrelation functions and associated Corbit (correlation–orbit) visualisation plots, but the authors also build on graphical models for time series by theoretically connecting the GNAR formulation to a latent graphical process. Their Theorem 2 identifies two important structural properties. First, the connection to partial correlation graphs generalises earlier edge-based notions of dependence ([Dahlhaus, 2000](#)), where dependence is now captured via active (r -stage) neighbourhoods instead of direct connections. Second, the assignment of an r -stage GNAR adjacency is connected to a cross-spectral hierarchy, under the intuition that nodal dependence is strongest between first-stage neighbours and it weakens as r increases.

Regarding the first point, a key implication is that zeroes in the inverse spectral matrix no longer imply a direct node pair disconnection, but rather the absence of a path of length at most $2r^*$ between them, where r^* denotes the largest active r -stage neighbourhood regression of a particular GNAR model. With the increase of active neighbourhood regressions, the GNAR-induced adjacency becomes denser, thus potentially reducing interpretability in the [Dahlhaus \(2000\)](#) sense. When r^* exceeds the network diameter, the structural advantages of GNAR over standard VAR models may no longer be exploited via the adjacency sparsity. These observations raise a crucial question: can we still recover interpretable network structures from data when sparsity in the estimated inverse GNAR spectrum no longer directly maps to edge absence?

In the second part of Theorem 2, [Nason et al. \(2025\)](#) establish the existence of a cross-spectral hierarchy connected to the active neighbourhood regressions. The authors define an r -stage dependent inverse GNAR spectrum using a complex soft threshold operator (*sft*) underpinned by the property that the strength of nodal dependence decays with increasing r . Whilst insightful, this approach relies heavily on the set threshold levels, hence raising questions about their practical estimation and interpretation.

¹Department of Mathematics, University of York, UK. E-mail: cristian.jimenezvaron@york.ac.uk; marina.knight@york.ac.uk

1 Finally, connecting these two points, the r -dependent inverse GNAR spectrum gives rise to an r -stage
2 partial correlation graph $\mathcal{G}^{(r)} = (\mathcal{K}, \mathcal{E}^{(r)})$. Notably, once a pair of nodes becomes conditionally independent,
3 the *sft* operator maps the corresponding entry to zero for all larger thresholds, allowing the latent graph
4 to be pruned based on conditional cross-spectrum strength. This structure links edges in the underlying
5 network to the intersection of r -dependent edge sets and the active node set (\mathcal{P}_r). Could the hierarchical
6 structure that you defined for the second part of Theorem 2 provide a pathway for inferring underlying
7 network structures when the network is unknown?
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