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- 1 Abstract
- 2

Background: Cemented polished taper fit (PTF) stems are the femoral implant of choice for total hip replacement (THR) in many locations worldwide. There is increasing evidence that peri-prosthetic fracture may be the single major contributor to reoperation with these stems. The aim of this study was to demonstrate how mismatches at the implant-cement interface may occur and the subsequent effect of these incongruities on the contacting area and the forces transmitted to the cement mantle.

8

9 *Methods:* A parametric equation-based model was developed to determine the contact mismatch 10 relative to axial stem rotations. This model was also used to calculate the restoration of contact 11 surface area with stem subsidence for both a dual-taper and triple-taper geometry. A finite element 12 analysis (FEA) was used to compare the effects of reduced contact area due to the incongruent hip 13 implant-cement interface.

14

15 Results: The contact model showed a large decrease in surface contact area with even only a small 16 rotation going from 100% at 0° to 50.00% at 2.5° for the dual-taper geometry and from 100% at 0° 17 to 50.20% at 2.5° for the triple-taper geometry. There was a gradual but small ongoing decrease in 18 contact surface with increasing rotation for both the dual-taper and triple-taper geometries. For both 19 taper designs, there was an increase in contact surface area with an increase in subsidence resulting 20 in contact for up to a 5° mismatch being restored with 2mm subsidence. FEA showed that with 21 increasing mismatches and consequent contact area reduction there was an increase in von Mises 22 stress in the implant-cement interface of up to 235%.

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Conclusion: With increasing mismatch there was an increase in maximum stresses, total strain, and
 subsidence in the cement mantle highlighting the importance of achieving an optimal implant-cement
 interface at the time of implantation of cemented PTF femoral stems.

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1 **1. Introduction**

2

3 Implant choice and surgical technique are two key aspects of total hip replacement (THR) which 4 are within the control of the surgeon to affect a satisfactory clinical outcome for their patients(1). 5 Cemented polished taper fit (PTF) stems are the stem of choice in many locations worldwide(2,3). 6 There is growing evidence around an increased risk of periprosthetic fracture (PPF) with PTF stems 7 over composite beam or uncemented stems(4-10). However, a clear explanation for these 8 observations has yet to be established. Whether this increased risk of PPF can be attributed to the 9 taper fit philosophy as a whole or only certain stem designs within this group is unclear. Significant 10 differences in the incidence of PPF have been noted when comparing current designs. Differences 11 in material properties, surface finish, cement viscosity, and implant geometry have been suggested 12 as possible causes(11-14).

13

14 PTF stems are designed for even distribution of forces to bone using an even cement mantle. Taper 15 fit relies on a large contact surface area to distribute forces, maintained over time by controlled stem 16 subsidence(15). It follows that reducing this contact area or interruptions to its uniformity leads to 17 both increased contact pressure as well as less optimal force distribution which in turn increases the 18 risk of fracture. The implant-cement interface plays a crucial role in the function of PTF stems. 19 Contact mismatch at the cement implant interface potentially occurs either early on related to 20 improper surgical technique or later on in the life span of the implant with cement creep damage and 21 plastic deformation of the cement mantle(16–18).

22

23 During cementation the PTF stem is inserted into the cement mantle to the desired position. While 24 the cement is curing, for a period, it is in a plastic (pre-cured) state meaning that changes / 25 adjustments or movement when detaching the stem introducer and/or leg movement from the 26 assistant during this period will create permanent shape changes in the surface which could risk 27 compromising the fit of the cement mantle. PTF stems utilize an interference fit to secure the stem 28 within the cement mantle through creating a large contact area for the transfer of forces(19). The 29 "load-transfer" (load transfer from stem to bone via cement mantle) generates stresses in the 30 materials and at their interfaces with the likelihood of mechanical failure depending on the stress 31 levels relative to the material strengths(20). A non-conforming cement mantle and reduction in 32 contact area is potentially introduced at the time of stem insertion before the cement has cured. 33 We hypothesize that a mismatch at the stem/cement interface leads to an uneven distribution of 34 pressure on the cement mantle leading to regions of the cement mantle transferring increased load 35 subsequently resulting in these areas being more likely to reach the point of failure.

36

37 The impact of reduction in contact surface area at the implant-cement interface, under stem rotation,

1 has not been previously investigated. This study aims to demonstrate the reduction in contact 2 surface area at the implant-cement interface with stem rotation using two methods: 1) an analytical 3 cross-sectional model which assumes perfect plastic behaviour and 2) finite element analysis (FEA) 4 which includes elastic response. In addition, the ability of cemented PTF stems to compensate for a 5 reduction in implant-cement mantle surface area under loading conditions was also explored. The 6 degree to which stem subsidence can restore the contact surface area was explored using the same 7 two models. The effect of implant-cement interface mismatch on the contacting area and the forces 8 transmitted to the cement mantle was quantified using the FEA model.

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11 **2. Methods**

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2.1. Cross-sectional contact model

15 To demonstrate the reduction in implant-cement contact area due to the degree of incongruity 16 between the implant and cement mantle geometry, a cross-sectional model was used. The cross-17 sectional geometry of a stem was described using a parametric function (Equation 1) to define eight 18 shape components consisting of four radii and four edges. The shape components were defined by 19 parameter 't' which was varied from 0 to 8 in the equations resulting in points describing the outline 20 of the stem in a single axial cross section. In this model, w represents half the width (medial-lateral) of the stem, d_1 and d_2 are the thicknesses (anterior-posterior) of the stem medially and laterally, 21 22 respectively, and $r_1 - r_4$ are the radii at the cross-sectional corners of the stem (*Figure 1*).

23

24 Equation 1 was used to generate point clouds (t was varied at increments of 0.01 resulting in 800 25 points describing the stem cross-section) iteratively through rotational positions of the stem. To 26 determine the points remaining in contact with the cement mantle a second copy of the point cloud 27 at 0 degrees was used to describe the cement mantle. At 0 degrees the point clouds were coincident 28 representing perfect contact. With rotation of the point clouds representing the femur remaining 29 contact points could be calculated by subtracting the points which are within the bounds of the 30 original cement mantle and previous stem positions (figure 1).Rotational and translational 31 mismatches were simulated with variations in origin relative to the stem to mimic mismatches during 32 cementation (to account for designs where the stem introducer is not mounted along the ais of the 33 taper) or cement fatigue with torsional forces pivoting around the medial calcar/cement mantle.

34

$$f(t) = \begin{cases} \{w, -(d1 - r4)(2t - 1)\} \\ \{w, -(d1 - r1)(2t - 1)\} \\ \{w, -(d1 - r1)(2t - 1)\} \\ \{w - r1 + r1.\cos\left(\frac{1}{2}\pi(t - 1)\right), -d1 + r1 - r1.\sin\left(\frac{1}{2}\pi(t - 1)\right)\} \\ \{w - r1 + r1.\cos\left(\frac{1}{2}\pi(t - 1)\right), -d1 + r1 - r1.\sin\left(\frac{1}{2}\pi(t - 1)\right)\} \\ \{w - r1 + r1.\cos\left(\frac{1}{2}\pi(t - 1)\right), -d1 + r1 - r1.\sin\left(\frac{1}{2}\pi(t - 1)\right)\} \\ \{w - r1 + r1.\cos\left(\frac{1}{2}\pi(t - 1)\right), -d1 + r1 - r1.\sin\left(\frac{1}{2}\pi(t - 1)\right)\} \\ \{-(w - r1)(2t - 5), -(d1 + (t - 2)(d2 - d1))\} \\ \{-(w - r2)(2t - 5), -(d1 + (t - 2)(d2 - d1))\} \\ \{-w + r - r2.\sin\left(\frac{1}{2}\pi(t - 3)\right), -d2 + r2 - r2.\cos\left(\frac{1}{2}\pi(t - 3)\right)\} \\ \{-w + r2 - r2.\sin\left(\frac{1}{2}\pi(t - 3)\right), -d2 + r2 - r2.\cos\left(\frac{1}{2}\pi(t - 3)\right)\} \\ \{-w, (d2 - r2)(2t - 9)\} \\ \{-w, (d2 - r3)(2t - 9)\} \\ \{w - r4 + r3 - r3.\cos\left(\frac{1}{2}\pi(t - 5)\right), d2 - r3 + r3.\sin\left(\frac{1}{2}\pi(t - 5)\right)\} \\ \{w - r4)(2t - 13), (d2 - (t - 6)(d2 - d1))\} \\ \{(w - r3)(2t - 13), (d2 - (t - 6)(d2 - d1))\} \\ \{w - r4 + r4.\sin\left(\frac{1}{2}\pi(t - 7)\right), d2 - r4 + r4.\cos\left(\frac{1}{2}\pi(t - 7)\right)\} \\ \{w - r4 + r4.\sin\left(\frac{1}{2}\pi(t - 7)\right), d2 - r4 + r4.\cos\left(\frac{1}{2}\pi(t - 7)\right)\} \\ \{w - r4 + r4.\sin\left(\frac{1}{2}\pi(t - 7)\right), d2 - r4 + r4.\cos\left(\frac{1}{2}\pi(t - 7)\right)\} \\ \{w - r4 + r4.\sin\left(\frac{1}{2}\pi(t - 7)\right), d2 - r4 + r4.\cos\left(\frac{1}{2}\pi(t - 7)\right)\} \\ \{w - r4 + r4.\sin\left(\frac{1}{2}\pi(t - 7)\right), d2 - r4 + r4.\cos\left(\frac{1}{2}\pi(t - 7)\right)\} \\ \{w - r4 + r4.\sin\left(\frac{1}{2}\pi(t - 7)\right), d2 - r4 + r4.\cos\left(\frac{1}{2}\pi(t - 7)\right)\} \\ \{w - r4 + r4.\sin\left(\frac{1}{2}\pi(t - 7)\right), d2 - r4 + r4.\cos\left(\frac{1}{2}\pi(t - 7)\right)\} \\ \{w - r4 + r4.\sin\left(\frac{1}{2}\pi(t - 7)\right), d2 - r4 + r4.\cos\left(\frac{1}{2}\pi(t - 7)\right)\} \\ \{w - r4 + r4.\sin\left(\frac{1}{2}\pi(t - 7)\right), d2 - r4 + r4.\cos\left(\frac{1}{2}\pi(t - 7)\right)\} \\ \{w - r4 + r4.\sin\left(\frac{1}{2}\pi(t - 7)\right), d2 - r4 + r4.\cos\left(\frac{1}{2}\pi(t - 7)\right)\} \\ \{w - r4 + r4.\sin\left(\frac{1}{2}\pi(t - 7)\right), d2 - r4 + r4.\cos\left(\frac{1}{2}\pi(t - 7)\right)\} \\ \{w - r4 + r4.\sin\left(\frac{1}{2}\pi(t - 7)\right), d2 - r4 + r4.\cos\left(\frac{1}{2}\pi(t - 7)\right)\} \\ \{w - r4 + r4.\sin\left(\frac{1}{2}\pi(t - 7)\right), d2 - r4 + r4.\cos\left(\frac{1}{2}\pi(t - 7)\right)\} \\ \{w - r4 + r4.\sin\left(\frac{1}{2}\pi(t - 7)\right), d2 - r4 + r4.\cos\left(\frac{1}{2}\pi(t - 7)\right)\} \\ \{w - r4 + r4.\sin\left(\frac{1}{2}\pi(t - 7)\right), d2 - r4 + r4.\cos\left(\frac{1}{2}\pi(t - 7)\right)\} \\ \{w - r4 + r4.\sin\left(\frac{1}{2}\pi(t - 7)\right), d2 - r4 + r4.\cos\left(\frac{1}{2}\pi(t - 7)\right)\} \\ \{w - r4 + r4.\sin\left(\frac{1}{2}\pi(t - 7)\right), d2 - r4 + r4.$$

Equation 1: Parametric equation used to describe cross-sectional geometry as a function of the parameter t, where w is the width (medial-lateral) of the stem, d_1 and d_2 are the thickness (anterior-posterior) of the stem medially and laterally respectively, and r_1, r_2, r_3 and r_4 the radii at the cross-sectional corners of the stem taper. These parameters correspond to those illustrated in Figure 1.

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2.2. Effect of subsidence on contact area

9 An advantage of the cemented PTS stem is that it can compensate for an amount of implant-cement 10 mantle mismatch through subsidence. This occurs with deformation of the contact areas meaning 11 that a broader section of the stem taper will increase contact the cement mantle (*Figure 2*). The 12 change in cross-sectional geometry (δ) with subsidence can derived from the implant taper (θ) and 13 the subsidence (*s*): $\delta = s. tan\theta$.

14

15 To model this the stem was moved by a set amount such that the area in contact for a particular 16 rotation was a consequence of the taper. The model calculated the implant's cross-sectional 17 geometry at the cement mantle level when including subsidence by adding the change in 18 profile (δ) to w, d_1 and d_2 as well as to the r_1 , r_2 , r_3 and r_4 parameters (see figure 2). Using these 19 new parameters, the contact points were recalculated with the retained cement mantle. To model 20 the effect of this compensation, subsidence ranges, including 0.5mm, 1.0mm, 1.5mm and 2.0mm, 21 were modelled, based on Baryeh et al.(21) who in their meta-analysis reported a mean subsidence 22 of cemented PTF stems at one, two, five and ten years of 0.97mm, 1.07mm, 1.47mm and 1.61mm 23 respectively.

2 Assumptions made in this model were:

- The cement underwent perfect plastic deformation where there was contact on rotation of the stem. Time-dependent viscous behaviour of cement potentially allowing it to fill gaps created by stem rotation were not modelled.
- The cross-sectional geometry was based on estimated measurements and did not
 represent true dimensions of actual implants
- The cross-sectional geometry was assumed to be proportional with the taper along the
 length of the stem and as such the contact percentage could be applied along the length of
 the stem.
- 11

13

12 2.3. Finite element model

14 CAD models of the cross sections (dual-taper and triple-taper) of 100mm in length and a taper angle 15 of 7° within a cylindrical bone cement mantle were created using SolidWorks 2022 SP3.1 version 16 (Dassault Systèmes, France). The distance between the proximal aspect of the cement restrictor 17 was assumed to be 10mm distal to the tip of the stem. A 2mm void was modelled distal to the tip of 18 the stem to simulate the use of a stem centralizer.

19

To simulate the effect of mismatches between implant and cement mantle, the hip stems were modelled at a rotation of 2.5° and 5°, representing geometrical mismatches, and compared to 0° (neutral) representing fully conforming interface (*see Figure 3*). The stem model was assembled and rotated within the solid cement model using SolidWorks, and the cement was cut by the stem geometry through a subtract feature before finite element meshing. This approach aimed to replicate the perfectly plastic deformation (pre-curing) of the model.

26

FEA was used to compare the effects of reduced contact area due to the incongruent hip stemcement mantle interface. An overview of the material properties used is given in *Table 1*. Static structural module in Ansys Workbench software version 2022 (Ansys, USA) was used in this study for the purposes of FEA modelling. The contacting surface between the bone cement and the hip stem was defined as 'frictional', with a coefficient of friction 0.4 applied between surfaces(12).

32

The components were meshed using quadratic elements with a size of 0.2mm at the contacting surfaces. The mesh size was selected based on mesh independence test showing that the von Mises stress did not vary significantly when the mesh size was further refined further than 0.2mm at the contacting surfaces of both geometrical components; with total number of nodes 1,225,526 and elements of 715,312. A simulated axial force of 6,900N in the -Z direction was applied at the proximal

1 stem taper, with fixed supports employed at the distal end and outer shell of the cement mantle 2 surface. This was chosen to represent stumbling force conditions is estimated to be three times the 3 standard loading condition(22), and the maximum cyclic loading test is 2,300N as per ISO standard 4 for hip implants(23). Simulation outputs included the von Mises stress (MPa) to observe stress 5 distribution on the loaded components and indicate potential material yielding, maximum shear 6 stress (MPa), equivalent total strain (calculated from strain components/tensors along the X, Y, and 7 Z directions) and directional deformations (mm) to assess subsidence in both the stem and cement 8 models(24,25). These results were used to compare the effect of varying contact areas (mm²) from 9 different mismatch positions. Additionally, the effect of subsidence on contact area for dual and tripletaper stems (at neutral 0° and mismatched at 2.5° and 5° rotations) in both pre- and post-subsidence 10 11 conditions were compared.

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14 **3. Results**

15 16

3.1. Contact area model output

The relationship of surface area percentage in contact to the amount of rotation is illustrated in *Figure* 2 and *Figure 3* for dual and triple-tapers, respectively. The contact model showed that there was a large decrease in surface contact area with even only a small rotation going from 100% at 0° to 50.00% at 2.5° for the dual-taper geometry and from 100% at 0° to 50.20% at 2.5° for the triple-taper geometry. There was a gradual but small ongoing decrease in contact surface with increasing rotation for both the dual-taper and triple-taper geometries.

23

24

3.2. Effect of subsidence on contact area

25 The compensatory effect of subsidence is shown in Figure 6 for the dual-taper and Figure 7 for the 26 triple-taper geometry. For both taper designs, there was an increase in contact surface area with an 27 increase in subsidence. Similarly, the amount of contact surface area restored was also dependent 28 on the taper angle, with larger taper angles restoring greater surface areas than smaller angles. The 29 initial contact areas prior to any subsidence or load conditions for all variants of taper angles and 30 mismatch rotational degrees were plotted as a baseline, generally around 50% of the full contact 31 surface or slightly lower. In both taper geometry designs, the more the stems subsided into the 32 cement mantle under loading, the more the contact surface was restored. Additionally, increasing 33 the taper angle of the stem design increased the compensatory contact surface between the stem-34 cement interface under loading.

35

36 3.3. Finite element model

The maximum output values resulting from the FEA simulations are shown in *Table 2*, comparing the effect of reduced contact area at the stem-cement interface. In the 0° position, the triple-taper had a

1 lower initial contact area than the dual-taper. Under mismatch conditions, the contact areas reduced, 2 with the rotational 2.5° in dual and triple-taper stems dropping to 51.0% and 50.5%, respectively, of 3 the full contact area. The contact areas further reduced when rotated by 5°, though the change was 4 minimal (49.8% and 49.8% respectively). This trend was similar to the outputs of the contact model 5 (Figure 2 & 5). The contact areas in the contact model reduced under mismatch with the rotational 6 2.5° in dual and triple-taper stems decreasing to 49.1% and 49.4% of the full contact area, 7 respectively. The contact areas also further dropped when rotated by 5° with minimal changes to 8 47.7% and 48.6%, respectively.

9

With increasing mismatches and consequent contact area reduction there was an increase in maximum stresses and total strain in the cement mantle. All triple-taper variants exhibited higher stresses and strains compared to the dual-tapers. An incremental stress of 51.4% was observed in the dual-taper's cement mantle when rotated by 2.5°, with only a slight further increase to 54.5% in with a rotational mismatch of 5°. However, the incremental stress in the triple-taper's cement mantle was higher, with around 100.6% increase at 2.5° and 135.1% at 5°.

16

17 Figure 8 shows von Mises stress distribution (MPa) in the cement mantle. The von Mises stresses 18 intensified at the distal section and the edges with smaller fillet radii, *i.e.* the lateral edges in the dual-19 taper and medial edge in triple-taper. Stress concentrations increased at the contact areas after the 20 stems rotated, indicated by stress lines extending from the distal tip to each fillet corner and towards 21 the midpoint of the broad surfaces. There was an increased stress region at the medial curved 22 surface of the triple-taper's cement mantle under mismatch conditions, indicating higher von Mises 23 stress. The highest maximum values of von Mises stress on the cement mantle were with a 5° 24 rotation in both taper designs, reaching 68.29 MPa for dual-taper and 165.32 MPa for triple-taper.

25

The corresponding stress in the stems, as shown in *Figure 9*. After mismatch, stress areas were observed at six contact points in dual-tapers, with higher stress at the smaller radii. The medial surface of the triple-taper geometry showed increased stress. As with the cement mantles the highest maximum values of von Mises stress on the stems were seen at 5° rotation, reaching 173.61 MPa for the dual-taper and 261.93 MPa for triple-taper geometries.

31

32 Shear stresses in the cement mantle were higher with triple-taper geometry compared to dual-taper 33 stems (*Figure 10*). As seen in the cross-sectional anterior view, shear stresses were concentrated 34 mostly at the distal end of the taper, extending proximally through the contacting areas of the implant-35 cement interface. The trend in shear stress distribution was consistent with the von Mises stress 36 distribution in the cement component for all stem taper variants. As with the von Mises stress', the 37 highest maximum values of shear stress on the cement mantle were observed with a 5° rotation, 1 reaching 37.85 MPa for dual-taper and 92.09 MPa for the triple-taper.

2

3 Implant cement mantle mismatch approximately doubled the depth of subsidence for both dual and triple-tapers in the 5° mismatch position, reaching 0.199mm and 0.310mm, respectively, compared 4 5 to the 0° neutral stem position (0.096mm for dual-taper and 0.146mm for triple-taper stems) see 6 Table 3. As with subsidence, at 5° rotation, cement deformations doubled compared to the neutral 7 position. The triple-taper geometry exhibited higher subsidence and cement mantle deformation 8 compared to dual-taper stems. Cement deformation was greater on the medial aspect of the stem 9 in triple-taper, corresponding to the increased stress in the cement mantle highlighting the influence 10 of the cross-sectional geometry.

11

A comparison of the analytical and FEA models with reference to contact surface are with subsidence is shown in *Table 4*. The FEA results showed a consistent trend with the results from the analytical model; however, the FEA results showed a more conservative increase in contact surface area with subsidence.

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18 4. Discussion

19

20 The primary objective of this study was to investigate the hypothesis that a mismatch at the stem-21 cement interface contributes to increased pressure within the cement mantle of polished taper-fit 22 femoral stems, thereby potentially elevating the risk of periprosthetic fractures post total hip 23 replacement. A cross-sectional model was utilized to demonstrate the reduction in implant-cement 24 contact area resulting from geometrical incongruity between the implant stem and the cement mantle. 25 Subsequently a finite element model was used to demonstrate the effects of reduced contact area 26 due to implant-cement mismatch on stress distributions within the cement mantle under simulated 27 loading conditions.

28

29 The effect of stem rotation on contact area showed that even minimal rotational movements resulted 30 in a substantial loss of surface contact between the implant and the cement, as demonstrated 31 through both numerical and FEA methods. This was the case for both the dual-taper and triple-taper 32 geometries with contact at the implant-cement interface approximately halved with minimal rotation. Once rotated further increase in rotation only resulted in small changes in the contact surfaces 33 34 (Figures 4&5). There were relatively minor discrepancies between the two modeling approaches in 35 the contact surface reduction results, only less than 1.4% for the dual taper and less than 0.7% for 36 the triple taper models. However, these reductions in contact area validated a consistent trend of 37 diminished interface integrity as rotational mismatch increases observed in both the contact model and the FEA. However, increased rotation did reduce the percentage contact restored through
 subsidence with up to 5 degrees rotational mismatch being compensated for with 2mm of subsidence
 (*Figures 6&7*) although this effect was less pronounced when elastic deformation was taken into
 account in the FEA model (*Table 4*).

5

6 FEA simulations showed that the stress in the cement mantle increased with decreased contact at 7 the implant-cement interface. The reduction in contact to 50.8% at 2.5° rotation resulted in an 8 increase in von Mises' stress to 151.4% for the dual-taper and 200.6% for the triple-taper cross-9 section. Under this extreme condition, which applied three times the standard load, the maximum 10 von Mises stresses on the cement component, as shown in Table 2, exceeded the yield strength of 11 the PMMA cement material (29 MPa), indicating plastic deformation at the contacting surface of the 12 cement (26,27). In contrast, the maximum von Mises stresses on the stem component were lower 13 than the yield strength of the Co-Cr alloy material (270 MPa). Similarly substantial increases in shear 14 stress and total strains were also noted with decreased contact.

15

16 The substantial increase in stress and strain within the cement mantle with decreased contact 17 highlights the importance of achieving an optimal implant-cement mantle interface. Although these 18 findings do not directly link to the occurrence of PPFs they suggest that this mechanism could 19 potentially play a contributory role to cement mantle failure and periprosthetic fracture among others. 20 Optimizing the cement mantle at implantation should be a primary focus of the surgeon aiming to 21 minimize relative movement of the implant while the cement is setting.

22

23 The compensatory mechanism of stem when there was incongruity was demonstrated. The 24 numerical model illustrated that subsidence could restore contact area in the event of a rotational 25 mismatch. There was increased restoration of contact with increased subsidence with 1° of rotational 26 mismatch contact was restored with 0.5mm subsidence increasing to contact for a 5° mismatch being 27 restored with 2mm subsidence. Similarly, the FEA simulations showed that under loading conditions, 28 subsidence partially restored contact surface area at the implant-cement interface (Table 4). The 29 absolute values for contact restoration were less for the FEA model which is likely due to the fact 30 that the FEA model more realistically took into account the material properties and contact friction 31 as opposed to the ideal frictionless conditions simulated in the numerical model. These findings 32 illustrate the strength of the PTF design philosophy to compensate for implant-cement incongruency 33 and resistance to loosening. The lower rates of loosening of PTF stems to other cemented designs 34 has been documented previously(3,28,29). However, this ability to maintain stem stability with 35 subsidence does come with increased forces and increased peak stress and strain within the cement 36 mantle.

1 The simulation presented in this paper is focused on the effect of an implant-cement interface 2 mismatch occurring during cementation with unintended movement of the stem resulting in plastic 3 deformation within curing cement. However, the mechanism of mismatch at the implant-cement 4 interface potentially may also occur later on in the life cycle of an implant. Cement has been shown 5 to fatigue and undergo plastic deformation with time(16–18,30). With repeated rotational/torsional 6 force and plastic deformation a mismatch between cement mantle and implant will develop. The 7 polished taper fit mechanism compensates for this mismatch with subsidence of the stem can lead 8 to significant increases in stresses and strains within the cement mantle meaning it becomes 9 increasingly susceptible to failure. An observed increase in the incidence of PPFs over time has 10 recently been reported by Lynch et al(7). However, to validate this theory fatigue indued mismatch 11 further modelling and experimental studies would be required.

12

13 Although this work focused specifically on the implant-cement interface mismatch and the effect on 14 the cement mantle, the effect of implant design in relation to the incidence of periprosthetic fracture 15 is the subject of extensive debate(4,31–33). Palan et al. using registry data from England and Wales 16 reported that among the three most commonly used PTF designs a triple-taper design had a lower 17 risk of periprosthetic fracture requiring revision in comparison to two dual-taper designs(4). Windell 18 et al. tested two dual-taper and a triple-taper design in composite sawbone models and found 19 significant differences in torque to failure between designs where the triple-taper result was between 20 the two dual-taper designs. Our findings showed increased stresses and subsidence with the triple-21 taper cross-section which does not correspond with the clinical findings presented by Palan et al(4). 22 This is likely to be due to our use of estimated cross-sectional geometries for the two stem designs. 23 In the models the overall surface area for the triple taper was less than the dual taper which would 24 be reflected by an increase in contact pressures which is observed in our results. Additionally, our 25 model did not take into account changes in length of the stem which has been shown to influence 26 the risk of PPF(32). What can be taken from our findings is that it is clear that smaller radii surfaces 27 lead to increased contact forces and result in more rapid increases in contact force with implant-28 cement mantle mismatches. This aspect needs to be weighed against the need for smaller radii 29 edges to provide torsional stability.

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31 It is important to recognize the limitations of this study. This study used simplified models. The cross-32 sectional geometries, although representative of existing stems, were not the exact geometry of 33 these stems. The model of the taper was simplified where many implants make use of a complex 34 taper. Furthermore, there can be significant variation in stem designs. Although the model used here did not make use of exact stem geometry the geometries used were representative of the PTS 35 36 principles. A linear load on the taper was used which did not consider the more complex physiological 37 loads seen in-vivo. The point cloud numerical method used to determine contact surfaces potentially 38 introduce errors, however these were marginal for small rotations (larger rotations were not modelled

1 as it is assumed that the occurrences of gross mismatches would be noticed and corrected by the 2 surgeon) and felt not to impact the interpretation of the outcomes. The FEA model implemented was 3 a static calculation of a high impact stumble which did not account for the time dependent material 4 behaviour of the cement. Additionally, this geometric analysis did not consider the cyclical nature of 5 loading with everyday activities. Indeed in vivo, the cement may undergo time dependent change in 6 its shape and structure after the stem is implanted and this may alter the implant-cement interface 7 including the extent of voids created. As such this model is limited as it only modelled a single 8 scenario (stumble) and did not account for fatigue of the implant or cement mantle with time under 9 physiological conditions.

10 11

12 Overall, this study provides valuable insights into the mechanics of load transfer within the cement 13 mantle and underscores the importance of interface integrity in the longevity and performance of 14 PTF stems. Future research should continue to explore the interplay between stem design, 15 cementing technique, and long-term clinical outcomes to develop more effective strategies for 16 reducing PPF risk in THR procedures. Additionally, more in-depth modeling studies of stems in 17 cement should be conducted to account for creep and plastic deformation, as well as rotational 18 forces, to assess the impact of implant-cement interface mismatch secondary mismatch due to 19 cement fatigue. In-vitro testing would be the next step to be carried out to practically validate the 20 surface contact mechanism by conducting load tests with controlled stem-cement positions inside 21 femur samples.

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23 In conclusion, this study highlights the importance of achieving an optimal implant-cement interface 24 at the time of implantation. This places the onus on the surgeon to control factors that can potentially 25 lead to stem movement within the setting cement mantle such as stem introducer removal, 26 experienced assistant, and avoidance of last-minute adjustments. The mechanism of polished taper 27 fit stems compensates well for smaller mismatches; however, this comes with the trade-off of 28 increased stresses in areas of the cement mantle which may compromise the long-term survival of 29 the implant. Furthermore, although not the focus of this study it is likely that rotational mismatches 30 occur with cement fatigue due to torsional loads on the stem resulting in a similar mechanism of 31 compromise to the cement-mantle interface resulting in a potential increased risk of periprosthetic 32 fracture.

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1 5. Figures

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Figure 1: a) Examples of a dual-taper and triple-taper stem cross-sectional geometry models with respective parameters where w is the width (medial-lateral) of the stem, d_1 and d_2 are the thickness (anterior-posterior) of the stem medially and laterally respectively, and r_1 and r_2 the radii at the cross-sectional corners of the stem 7 taper. b) illustration of the effect of rotation on cross-sectional contact with the solid line representing the cement mantle, θ the angle of rotation, the bold lines the regions of the stem still in contact with cement, and the dashed lines the areas that are no longer in contact due to rotation.

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- 11



12 13 **Figure 2:** Illustration to show relationship change in cross-sectional geometry (δ) with subsidence (*s*). The 14 anterior-posterior view (inset) shows how with subsidence the cross-sectional profile will change with an 15 increasing taper. With the solid line representing the cement mantle, the bold lines the regions of the stem 16 still in contact with cement, and the dashed lines the areas that are no longer in contact due to rotation prior 17 to subsidence. The dotted line represents the cross-section of the stem post subsidence illustrating how this 18 can increase the contact region.







Figure 2: The contact area percentages with rotation from 0.25° to 5° (0° to 5° see inset top right) and change in point of rotation in the x-axis from -5mm to +5mm (see inset bottom left) from center for the dualtaper geometry.



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Figure 7: The contact area percentage with rotation from 0 - 10 degrees with series reflecting variation in both subsidence and taper for a triple-taper geometry.



Figure 8: FEA visualization from superior view on von Mises stress distribution (MPa) comparing cement mantles in neutral (0°) and mismatch positions (2.5° and 5°) for dual and triple-taper stems.



Figure 9: FEA visualization from superior view on von Mises stress distribution (MPa) comparing crosssectional stems in neutral (0°) and mismatch positions (2.5° and 5°) for dual and triple-taper stems.



comparing cement mantles in neutral and mismatch positions for dual and triple-taper stems.

- 1 6. Tables
- 2

Components Material		Young's Modulus (GPa)	Poisson's Ratio	
Cement mantle	PMMA	2	0.3	
Hip stem taper	Co-Cr alloy	220	0.3	

Table 1: overview of the material properties used for each component of the FEA model (26,27).

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Hip Stem Taper	Contacting Area – mm ²	Max von Mises Stress - MPa (Cement)	Max von Mises Stress - MPa (Stem)	Max Shear Stress - MPa (Cement)	Max Total Strain (Cement)
DT 0°	4161.9 mm² (100%)	44.206 MPa (100%)	106.17 MPa (100%)	25.031 MPa (100%)	0.030368 (100%)
DT 2.5°	51.0%	151.4%	151.3%	140.8%	111.5%
DT 5°	49.8%	154.5%	163.5%	151.2%	131.3%
TT 0°	3732.85 mm ² (100%)	70.328 MPa (100%)	60.125 MPa (100%)	39.657 MPa (100%)	0.038142 (100%)
TT 2.5°	50.5%	200.6%	405.6%	209.1%	195.3%
TT 5°	49.8%	235.1%	435.6%	232.2%	229.8%

5 **Table 2**: FEA results on maximum stresses (MPa) and total strain following contact area changes of stem-

6 cement interface in mismatches (2.5° and 5°) from the neutral position (0°). The percentage (%) represents

7 the ratio between the output values under each contact condition and the neutral condition (0°) for both dual

8 and triple-taper stems.

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Stem taper	<i>s</i> -Z Stem subsidence (mm)	δ_a -X Cement lateral deformation (mm)	δ_b +X Cement medial deformation (mm)
DT 0°	0.096	0.013	0.010
DT 2.5°	0.191	0.018	0.019
DT 5°	0.199	0.019	0.020
TT 0°	0.146	0.009	0.021
TT 2.5°	0.324	0.022	0.045
TT 5°	0.310	0.027	0.048

10 **Table 3:** FEA results on directional deformations (mm) of stem taper subsidence in -Z axis orientation and

11 deformed cement mantle towards -/+X axis orientation for both lateral and medial taken from all converged

12 stem taper simulations.

13

	Contact Area via N	Contact Area via Numerical Model		Contact Area via FEA	
Stem Taper	Unloaded	Subsided (<i>s</i> = -0.5mm)	Unloaded	Subsided (<i>s</i> = -0.5mm)	
DT 0°	100%	100.0%	100%	100.0%	
DT 2.5°	50.7%	82.4%	51.0%	67.7%	
DT 5°	51.2%	67.7%	49.8%	57.2%	
TT 0°	100%	100.0%	100%	100.0%	
TT 2.5°	50.8%	78.3%	50.5%	58.0%	
TT 5°	51.3%	67.9%	49.8%	51.6%	

14 **Table 4:** Contact area percentage of stem-cement interface when unloaded (s = 0mm) vs. post-subsided (s =

15 -0.5mm) resulted from cross-sectional contact model and FEA methods. Calculations for both geometries with

16 a taper angle of 7°, and 0.5mm subsidence.

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