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1	A Mixture Coupling Theory based model for solute transport in
2	deformable dual-porosity media
3	Kai Wang ¹ ; Wenjie Tan ² ; Yanxiao Si ² ; Yue Ma ³ ; Xiao-Hui Chen ³ ; Aizhong
4	Ding ^{1*}
5	¹ College of Water Sciences, Beijing Normal University, Beijing, 100875, CHINA
6	² Surface engineering division, Sinopec Petroleum exploration and production research
7	institute, Beijing, 102206, CHINA
8	³ School of Civil Engineering, University of Leeds, Leeds, LS2 9JT, UK
9	* Corresponding author: Aizhong Ding. E-mail address: <u>ading@bnu.edu.cn</u>
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13 Abstract

14 Rock, soil and many porous-like materials are often fractured or structured media, 15 which can exhibit dual-porosity behaviour. Studies on solute transport in deformable 16 dual-porosity media remain challenging due to the multi-physics coupled effects and 17 the complex interaction between fracture (or macropore) and porous matrix. Though 18 several studies exist on constitutive modelling of coupled behaviour in deformable 19 dual-porosity, the previously developed models are not systematic in thermodynamical 20 frameworks. This paper proposes a Mixture Coupling Theory approach based on 21 nonequilibrium thermodynamics to develop the solute transport model with 22 consideration of hydro-mechanical coupling in dual-porosity media (referred to as the 23 ST-HM model). This paper derives the constitutive equations of fully hydro-24 mechanical coupled behaviour in dual-porosity media and considers the pore and 25 fracture porosity evolution influenced by both hydro and mechanical fields. Therefore, 26 the governing equations of ST-HM are capable of predicting non-reactive solute 27 transport with a fully hydro-mechanical coupled effect in dual-porosity media. Then, 28 the model was verified against existing models and validated by relevant experimental 29 results. Further, a numerical example shows that the presented model significantly 30 improves the accuracy of the prediction of porosity, fluid pressure, and solute 31 concentration compared with previous models, which ignore the fully hydro-32 mechanical coupled effects on solute transport.

- 33 Keywords: Solute transport; Deformable dual-porosity media; Coupled model;
- 34 Nonequilibrium thermodynamics; Mixture Coupling Theory

35

36	List of notations
37	<i>B</i> material coefficient
38	$c_{\alpha c}$ solute mass fraction
39	<i>C</i> solute volumetric concentration
40	d displacement vector
41	d_i displacement in <i>i</i> axis
42	D^{α} dispersion - diffusion coefficient for solute
43	E Green strain
44	F deformation gradient
45	<i>G</i> shear modulus
46	H_{ij} material-dependent parameter
47	$\mathbf{I}^{lphaeta}$ mass flux
48	J Jacobian of F
49	$\mathbf{J}^{lphaeta}$ diffusion flux
50	k_0^{α} initial permeability
51	k^{α} permeability
52	K bulk modulus of total geomaterial
53	K_s bulk modulus of solid grain
54	K_w bulk modulus of water
55	K_{pb} bulk modulus of the porous matrix block
56	<i>L</i> fracture spacing

57	L_{ijkl} material-dependent parameter
58	$m^{\alpha\beta}$ mass density in the reference configuration
59	M_{ij} material-dependent parameter
60	n outward unit normal vector
61	N dimension of porous matrix block ($N=1,2,3$)
62	$p^{\alpha l}$ fluid pressure
63	Q material coefficient
64	r_{ex}^{β} exchange flux between the pore and fracture
65	S_{ij} material-dependent parameter
66	<i>S</i> boundary of an arbitrary region
67	t Time
68	T second Piola-Kirchhoff stress
69	<i>T</i> temperature.
70	v^{α} porosity in the reference configuration
71	v_0^{α} initial porosity in the reference configuration
72	$\mathbf{u}^{\alpha l}$ Darcy velocity of fluid
73	<i>v</i> Poisson's ratio
74	\mathbf{v}_s velocity of a solid.
75	V an arbitrary region in the current configuration
76	V_0 an arbitrary region in the reference configuration
77	W deformation energy (dual potential)

70		· · 1	• • • •		1	•	1 .		~ · ·
/X	v	material	point for	one	nhase	in an	arbifrary	current	configuration
10	л	material	point ioi	one	phase	III uII	aronary	Carrent	Comparation

- 79 X material point for one phase in an arbitrary reference configuration
- 80 Z material coefficients

81 Greek symbols

 γ entropy production per unit volume

 ε_{ii} strain tensor

 ζ^{α} Biot constant

- μ_w dynamic viscosity of water
- $\mu^{\alpha\beta}$ chemical potential
- $\nabla \mu_{ex}^{\beta}$ gradient of the chemical potential of exchange water or solute
- $\rho^{\alpha\beta}$ mixture density
- $\rho_l^{\alpha\beta}$ In-phase density (true density)
- σ Cauchy stress
- ϕ^{α} porosity in current configuration
- ϕ^s volume fraction of the solid part
- ψ Helmholtz free energy density
- ψ_{α} Helmholtz free energy density of the bulk fluid

 χ shape factor

- τ diffusion transfer parameter
- Ψ Helmholtz free energy density in the reference configuration
- $\mathcal{G}_{\alpha l}$ entropy production of fluid flow

 \mathcal{G}_{ex} entropy production of fluid exchange between pore and fracture

100 Subscripts and superscripts

- $\alpha = M$ For pore
- $\alpha = F$ For fracture
- $\beta = w$ For water
- $\beta = c$ For solute
- $\beta = l$ For liquid (solution)

106 Introduction

107 Rock, soil, and many porous-like materials are fractured or structured in reality and 108 exhibit very different characteristics than ideal porous media (Duguid and Lee, 1977, 109 Berre et al., 2019). For fractured and structured porous media, which contains both 110 macropores and porous matrix, the most distinctive properties compared to single 111 porosity media are the very heterogeneous distribution of porosity, permeability, and 112 the interaction between fracture (or macropore) and porous matrix. Here, fractured 113 porous media represents both fractured and structured media. Understanding the fluid 114 flow and solute transport in fractured porous media is very important in groundwater 115 remediation, agriculture engineering, and underground construction (Rutqvist and 116 Stephansson, 2003, Molson et al., 2012, Ray, 1994). Also, the exploitation of naturally 117 fractured reservoirs needs to study the fluid and solute flow in the fractured rock (Liu 118 et al., 2019, Savatorova et al., 2016). Geological carbon storage (GCS) technology often 119 experiences chemo-hydro-mechanical coupled processes in fractured rocks during 120 carbon sequestration (Akono et al., 2019).

So far, several methods have been considered to study the fluid and solute transport in fractured porous media, including laboratory experiments (<u>Leij et al., 2012</u>), numerical studies (<u>Kodešova et al., 2006</u>) and mathematical models (<u>Berre et al., 2019</u>). In the previous studies, continuum models (<u>Shu, 1999</u>, <u>Li et al., 2020</u>, <u>Saevik et al., 2013</u>, <u>Dykhuizen, 1990</u>) were used, this includes research on permeability tensor by Oda (<u>Oda,</u> <u>1985</u>), one of the earliest studies, and other damage mechanics studies in fractured 127 media (De Bellis et al., 2017, De Bellis et al., 2016, Arson and Pereira, 2013). Also, 128 many researchers used discrete fracture models (Lee et al., 2001, Jiang and Younis, 129 2017) to represent fractured porous media. The dual-porosity model (also called the 130 double porosity model), one of the multi-continuum models, was firstly presented by 131 Barenblatt in 1960 s (Barenblatt et al., 1960). This theory assumes that fractured porous 132 media can be viewed as two overlapping domains, porous matrix and fracture (shown 133 in Figure 1); they are both continua but with different characteristics such as 134 permeability, porosity, bulk modulus and so on. In addition, the water and solute 135 exchange happens between fracture and porous matrix. However, the dual-porosity 136 model cannot present a geometric distinction between porous matrix and fracture, as it 137 employs a continuum to simplify the fracture network.



138

139

Figure 1. Conceptual description of the dual-porosity theory

A more realistic understanding of solute transport needs a further understanding of the coupled model because, natural rocks always exist in a multi-physics coupled environment. Biot (<u>Biot, 1941</u>) and Terzaghi (<u>Terzaghi, 1943</u>) are the pioneers of hydromechanical coupled consolidation theory. Based on these theories, Khalili et al. studied the Hydro-Mechanical and Thermo-Hydro-Mechanical coupling in deformable dual145 porosity media (Khalili, 2003, Gelet et al., 2012b, Khalili, 2008a). In addition, several solute transport models (Murad and Moyne, 2008, Revil, 2017) and Hydro-Mechanical-146 147 Chemical coupled models (Li et al., 2020, Musso et al., 2013, Vecchia and Musso, 2016) 148 in dual-porosity media were developed recently. However, these studies often ignore 149 the fully hydro-mechanical coupling (especially the porosity evolution induced by fluid 150 pressure), which may strongly influence solute transport. These models can be termed 151 as mechanics approach (most widely used by researchers since Terzhagi developed 1D 152 consolidation theory) models as their derivation is mainly based on mechanics and 153 momentum balance. Mechanics approach can easily develop new coupled models in by 154 introducing equations from other disciplines (e.g. adding chemical reaction equations 155 into solute transport equation), while lacking a systemic framework that covers 156 different fields (Chen et al., 2016). 157 On the other hand, the Mixture Theory, which adopts a different approach, was 158 developed from the study of biological tissues at the early stage (Bowen, 1976) but,

gained more and more attention from geological and environmental researchers in
recent years. In the Mixture Theory, each point in the mixture is assumed to contain
every component (for example, solid and fluid) (Bedford and Drumheller, 1983).
Several works have been carried out on coupled fluid transport and porous media
deformation (Drumheller, 1978, Bowen, 1984, Rajagopal and K., 2007, Hutter et al.,
2015).

165 Mixture Coupling Theory (originally named Modified Mixture Theory) is an emerging

10

166 approach developed by Heidug and Wong (Heidug and Wong, 1996). This theory is 167 based on nonequilibrium thermodynamics and Mixture Theory, which makes it a 168 energy-based theory. Mixture Coupling Theory has been used to derive the Hydro-169 Mechanical model (Chen and Hicks, 2011, Chen, 2013), Hydro-Mechanical-Chemical 170 and Thermo-Hydro-Mechanical-Chemical model (Chen and Hicks, 2013, Ma et al., 171 <u>2021</u>) in porous media. The Mixture Coupling Theory links different physical fields 172 using Helmholtz free energy and obtains the coupling relationships of stress, porosity 173 and other variables by deformation energy analysis. 174 Mixture theory uses the internal frictional interaction force to study information on the 175 interaction between different components, which is hard to obtain (Laloui et al., 2003). 176 In comparison, Mixture Coupling Theory uses entropy production to study the 177 interaction between each component, which makes it easier to consider molecule-scale 178 friction or other chemical-induced dissipative processes. 179 The presented paper used the Mixture Coupling Theory to derive a systematic solute 180 transport model with consideration of hydro-mechanical coupling in dual-porosity 181 media (referred to as the ST-HM model) based on nonequilibrium thermodynamics. 182 This model successfully determines the non-reactive solute transport behaviour with 183 fully hydro-mechanical coupling effects, and considers porosity and permeability 184 evolution influenced by solid deformation, porous/fracture fluid pressure, and the 185 coupled interaction between porous and fracture fluid flow. The new model is compared 186 with previous models derived by the mechanics approach and validated against

11

- 187 experimental data. A numerical simulation is further performed to investigate the
- 188 potential application of the proposed model in groundwater contamination research.

189 **Constitutive equation development**

190 Balance equation of Helmholtz free energy and entropy production

191 An arbitrary region V with a boundary S is selected for this to study the dual-porosity 192 medium. Water and solute fluxes can pass through the boundary while the solid phase 193 cannot; and only one solute is considered in this study. The local version balance 194 equation of Helmholtz free energy for the open system can be obtained in a dual-195 porosity media as

196
$$\dot{\psi} + \psi \nabla \cdot \mathbf{v}^{s} - \nabla \cdot (\boldsymbol{\sigma} \mathbf{v}^{s}) + \nabla \cdot (\mu^{Mw} \mathbf{I}^{Mw} + \mu^{Mc} \mathbf{I}^{Mc}) + \nabla \cdot (\mu^{Fw} \mathbf{I}^{Fw} + \mu^{Fc} \mathbf{I}^{Fc}) = -T\gamma \leq 0$$
197 (1)

198 where ψ is the Helmholtz free energy density, σ is the Cauchy stress tensor, \mathbf{v}^s is 199 the velocity of a solid, μ^{Mw} , μ^{Fw} , μ^{Mc} , μ^{Fc} are the chemical potential of pore water, 200 fracture water, solute in porous flow, solute in fracture flow, respectively. \mathbf{I}^{Mw} , \mathbf{I}^{Mc} , 201 \mathbf{I}^{Fw} , \mathbf{I}^{Fc} are the flux of pore water, porous solute, fracture water, and fracture solute, 202 respectively. T is the constant temperature and γ is the entropy production per unit 203 volume.

204 The detailed derivation of equation (1) is presented in Supplementary information.

It is assumed that only the friction generated at the solid-fluid (water and solute) interface contributes to the energy dissipation in the mixture. By using the equation of entropy production of water and solute flow (Katachalsky and Curran, 1965) and the equation for fluid exchange between porous and fracture space (Gelet et al., 2012b, 209 <u>Coussy</u>, 2004), the entropy production of the dual-porosity media can be obtained as

210
$$0 \leq T\gamma = -\mathbf{I}^{Mw} \cdot \nabla \mu^{Mw} - \mathbf{I}^{Mc} \cdot \nabla \mu^{Mc} - \mathbf{I}^{Fw} \cdot \nabla \mu^{Fw} - \mathbf{I}^{Fc} \cdot \nabla \mu^{Fc} + r_{ex}^{w} \left(\mu^{Mw} - \mu^{Fw}\right) + r_{ex}^{c} \left(\mu^{Mc} - \mu^{Fc}\right)$$

(2)

212 where r_{ex}^{w} and r_{ex}^{c} are the exchange water and solute flux between the pore and 213 fracture. The chemical potential of exchange water changes from $\mu^{M_{w}}$ to $\mu^{F_{w}}$ when 214 the exchange is to fracture, from $\mu^{F_{w}}$ to $\mu^{M_{w}}$ vice versa.

215 Basic equations of water and solute flow in dual-porosity media

In this manuscript, both mixture density and In-phase (also called true density) density are used. The mixture density can be obtained by the In-phase density of pore water ρ_l^{Mw} , fracture water ρ_l^{Fw} , porous solute ρ_l^{Mc} and fracture solute ρ_l^{Fc} as

219
$$\rho^{Mw} = \phi^{M} \rho_{l}^{Mw}, \rho^{Fw} = \phi^{F} \rho_{l}^{Fw}, \rho^{Mc} = \phi^{M} \rho_{l}^{Mc}, \rho^{Fc} = \phi^{F} \rho_{l}^{Fc}$$
(3)

220 where ϕ^M , ϕ^F are the porosity of porous matrix and fracture, and they obey

$$\phi^M + \phi^F + \phi^S = 1 \tag{4}$$

222 where ϕ^s is the volume fraction of the solid phase.

In-phase density refers to the mass of a specified component per unit phase volume (for example, the mass of solute per unit liquid volume). Here, using In-phase density instead of true density avoids confusion since true density can easily be misunderstood with the intrinsic density of one component, such as solid salt.

227 The In-phase density of the solution in the porous matrix and fracture is defined as

228
$$\rho_{l}^{Ml} = \rho_{l}^{Mc} + \rho_{l}^{Mw}, \rho_{l}^{Fl} = \rho_{l}^{Fc} + \rho_{l}^{Fc}$$
(5)

229 The balance equation of fluid writes

230
$$(\boldsymbol{\upsilon}^{M}\boldsymbol{\rho}_{l}^{Ml})^{\cdot} + \nabla \cdot (\boldsymbol{\rho}_{l}^{Ml}\mathbf{u}^{Ml}) + \boldsymbol{r}_{ex}^{l} = 0$$
(6)

231
$$(\boldsymbol{\upsilon}^{F}\boldsymbol{\rho}_{l}^{Fl})^{\cdot} + \nabla \cdot (\boldsymbol{\rho}_{l}^{Fl}\mathbf{u}^{Fl}) - r_{ex}^{l} = 0$$
(7)

where $v^{M} = J\phi^{M}$ and $v^{F} = J\phi^{F}$ are pore volume per unit referential volume and fracture volume per unit referential volume, and $r_{ex}^{l} = r_{ex}^{w} + r_{ex}^{c}$ is the fluid mass exchange between pore and fracture, \mathbf{u}^{Ml} and \mathbf{u}^{Fl} are the Darcy velocity of the porous fluid and fracture fluid, *J* is the Jacobian of the deformation gradient **F**.

Also, the balance equation of solute in porous matrix and fracture can be derived as

237
$$(\boldsymbol{\upsilon}^{M} \boldsymbol{\rho}_{l}^{Ml}) \dot{\boldsymbol{c}}_{Mc} + \boldsymbol{\rho}_{l}^{Ml} \mathbf{u}^{Ml} \nabla \boldsymbol{c}_{Mc} + \boldsymbol{r}_{ex}^{c} + \nabla \cdot \mathbf{J}^{Mc} = 0$$
(8)

238
$$(\boldsymbol{\upsilon}^{F}\boldsymbol{\rho}_{l}^{Fl})\dot{\boldsymbol{c}}_{Fc} + \boldsymbol{\rho}_{l}^{Fl}\mathbf{u}^{Fl}\nabla\boldsymbol{c}_{Fc} - \boldsymbol{r}_{ex}^{c} + \nabla\cdot\mathbf{J}^{Fc} = 0$$
(9)

239 where $c_{Mc} = \frac{\rho_l^{Mc}}{\rho_l^{Ml}}$, $c_{Fc} = \frac{\rho_l^{Fc}}{\rho_l^{Fl}}$ are the solute mass fraction, \mathbf{J}^{Mc} , and \mathbf{J}^{Fc} are the

The detailed derivation of the balance equation is presented in Supplementaryinformation.

243 Basic equation of state

244 Based on the assumption that the dual-porosity media maintain mechanical equilibrium

and without volume force, so
$$\nabla \cdot \mathbf{\sigma} = \mathbf{0}$$
. By using equation (1) and (2), it leads to

246
$$\frac{\dot{\psi} + \psi \nabla \cdot \mathbf{v}^{s} - \nabla \cdot (\mathbf{\sigma} \mathbf{v}^{s}) + (\mu^{Mw} \nabla \cdot \mathbf{I}^{Mw} + \mu^{Mc} \nabla \cdot \mathbf{I}^{Mc}) + (\mu^{Fw} \nabla \cdot \mathbf{I}^{Fw} + \mu^{Fc} \nabla \cdot \mathbf{I}^{Fc}) + r_{ex}^{w} \left(\mu^{Mw} - \mu^{Fw}\right) + r_{ex}^{w} \left(\mu^{Mc} - \mu^{Fc}\right) = 0$$

Based on the mass balance equation and using equation (10), using finite strain theory
in continuum mechanics, the free energy in the reference configuration can be obtained
as

251
$$\dot{\Psi} = tr(\mathbf{T}\dot{\mathbf{E}}) + \mu^{Mw}\dot{m}^{Mw} + \mu^{Fw}\dot{m}^{Fw} + \mu^{Mc}\dot{m}^{Mc} + \mu^{Fc}\dot{m}^{Fc}$$
(11)

where $\Psi = J\psi$, **E** represents Green strain, **T** is the second Piola-Kirchhoff stress, $m^{Mw} = J\rho^{Mw}$, $m^{Fw} = J\rho^{Fw}$, $m^{Mc} = J\rho^{Mc}$, $m^{Fc} = J\rho^{Fc}$ are the mass density of pore water, fracture water, porous solute, and fracture solute in the reference configuration. The detailed derivation of equation (11) is presented in Supplementary information.

256 Helmholtz free energy density of the fluid and solid skeleton

257 The derivation of the Helmholtz free energy density of the bulk fluid in porous matrix 258 and fracture requires some of the following assumptions to be made. The fluid flow is 259 isothermal, the equilibrium is transient (i.e. porosity can be viewed as a constant), and the chemical is non-reactive. The fluid is non-sorptive, and this is necessitated as 260 261 Brochard and Honório points out that the Gibbs-Duhem equation does not hold well, in general, for an adsorbed fluid (Brochard and Honório, 2020). Based on the above 262 263 assumptions, water/fluid in the pores and fractures is not strongly influenced by 264 intermolecular and surface forces. So the Helmholtz free energy density of the bulk 265 fluid in porous matrix and fracture can be derived as

266
$$\Psi_{M} = -p^{Ml} + \left(\mu^{Mw}\rho_{l}^{Mw} + \mu^{Mc}\rho_{l}^{Mc}\right)$$
(12)

267
$$\psi_{F} = -p^{Fl} + \left(\mu^{Fw}\rho_{l}^{Fw} + \mu^{Fc}\rho_{l}^{Fc}\right)$$
(13)

268 where p^{Ml} is the porous fluid pressure and p^{Fl} is the fracture fluid pressure. Using 269 Gibbs–Duhem equation, there are

270
$$\dot{\psi}_{M} = \dot{\rho}_{l}^{Mw} \mu^{Mw} + \dot{\rho}_{l}^{Mc} \mu^{Mc}$$
(14)

271
$$\dot{\psi}_F = \dot{\rho}_l^{Fw} \mu^{Fw} + \dot{\rho}_l^{Fc} \mu^{Fc}$$
(15)

Using equation (11), (12), (13), (14), (15) and equation (3), the free energy of the solid skeleton (including solid phase and water molecules attached to the solid's surface) can be described as:

275
$$\left(\Psi - J\phi^{M}\psi_{M} - J\phi^{F}\psi_{F}\right) = tr(\mathbf{T}\dot{\mathbf{E}}) + \dot{\upsilon}^{M}p^{M} + \dot{\upsilon}^{F}p^{Fl}$$
(16)

276 Constitutive equations

Subtracting the contribution of porous fluid pressure and fracture fluid pressure from
Helmholtz free energy density of the solid skeleton, the deformation energy (also called
dual potential) can be obtained

280
$$W = \left(\Psi - J\phi^{M}\psi_{M} - J\phi^{F}\psi_{F}\right) - \upsilon^{M}p^{M} - \upsilon^{F}p^{F}$$
(17)

The time derivative of deformation energy can be obtained using equation (16) and (17) as

283
$$\dot{W} = tr(\mathbf{T}\dot{\mathbf{E}}) - \upsilon^M \dot{p}^{M} - \upsilon^F \dot{p}^{Fl}$$
(18)

284 Equation (18) shows that W is a function of **E**, p^{Ml} and p^{Fl} .

285 From equation (18), the expression of **T**, v^M and v^F can be obtained as

286
$$T_{ij} = \left(\frac{\partial W}{\partial E_{ij}}\right)_{p^{Ml}, p^{Fl}}, \quad v^{M} = -\left(\frac{\partial W}{\partial p^{Ml}}\right)_{E_{ij}, p^{Fl}}, \quad v^{F} = -\left(\frac{\partial W}{\partial p^{Fl}}\right)_{E_{ij}, p^{Ml}}$$
(19)

287 So that

288
$$\dot{W}(\mathbf{E}, p^{Ml}, p^{Fl}) = \left(\frac{\partial W}{\partial E_{ij}}\right)_{p^{Ml}, p^{Fl}} \dot{E}_{ij} + \left(\frac{\partial W}{\partial p^{Ml}}\right)_{E_{ij}, p^{Fl}} \dot{p}^{Ml} + \left(\frac{\partial W}{\partial p^{Fl}}\right)_{E_{ij}, p^{Ml}} \dot{p}^{Fl}$$

289

By differentiating equation (19), and using equation (20), the basic constitutive equation for the evolution of stress, pore porosity and fracture porosity can be obtained as

(20)

293
$$\dot{T}_{ij} = L_{ijkl} \dot{E}_{kl} - M_{ij} \dot{p}^{Ml} - S_{ij} \dot{p}^{Fl}$$
(21)

294
$$\dot{\upsilon}^{M} = M_{ij}\dot{E}_{ij} + Q\dot{p}^{M} + B\dot{p}^{Fl}$$
 (22)

295
$$\dot{\upsilon}^F = S_{ij}\dot{E}_{ij} + B\dot{p}^{Ml} + Z\dot{p}^{Fl}$$
(23)

where the parameters L_{ijkl} , M_{ij} , S_{ij} , H_{ij} , B, Q, Z, defined by the following equations

298 Coupled field equations

299 Assumptions in dual-porosity media

300 Some simplifications and assumptions are made to simplify the further discussion.

301 1. Small strain condition is adopted in this paper, so the Green Strain tensor E_{ij} and

302 Piola-Kirchhoff stress T_{ij} can be replaced by strain tensor ε_{ij} and Cauchy stress σ_{ij} .

- 303 2. The parameters L_{ijkl} , M_{ij} , S_{ij} , Z, B, Q are all material-dependent constants.
- 304 3. The rock is assumed to be isotropic, so that

305
$$M_{ij} = \zeta^M \delta_{ij} , \quad S_{ij} = \zeta^F \delta_{ij} , \quad L_{ijkl} = G(\delta_{ik} \delta_{jl} + \delta_{il} \delta_{jk}) + (K - \frac{2G}{3}) \delta_{ij} \delta_{kl}$$
(24)

306 where G and K are the shear modulus and bulk modulus of the rock.

307 Similarly, the pore and fracture porosity equation (22) and (23) become

$$\dot{\upsilon}^{M} = \zeta^{M} \dot{\varepsilon}_{ii} + Q \dot{p}^{Ml} + B \dot{p}^{Fl}$$
(25)

$$\dot{\upsilon}^F = \zeta^F \dot{\varepsilon}_{ii} + B \dot{p}^{Ml} + Z \dot{p}^{Fl}$$
(26)

310 The evolution of pore and fracture permeability can be obtained using the Kozeny-

311 Carman function(Bitzer, 1996)

312
$$k^{M} = k_{0}^{M} \left(\frac{\nu^{M}}{\nu_{0}^{M}}\right)^{3} \left(\frac{1-\nu_{0}^{M}}{1-\nu^{M}}\right)^{2}$$
(27)

313
$$k^{F} = k_{0}^{F} \left(\frac{\nu^{F}}{\nu_{0}^{F}}\right)^{3} \left(\frac{1-\nu_{0}^{F}}{1-\nu^{F}}\right)^{2}$$
(28)

314 where k_0^M and k_0^F are the initial pore and fracture permeability, υ_0^M and υ_0^F are the 315 initial pore and fracture porosity.

316 Multi-physics governing equations of solute transport in dual-porosity media

317 Mechanical static equilibrium is assumed here, so
$$\partial \sigma_{ij} / \partial x_j = 0$$
, using displacement

318 variables
$$d_i (i = 1, 2, 3)$$
 through $\varepsilon_{ij} = \frac{1}{2} (d_{i,j} + d_{j,i})$ and $\dot{\varepsilon}_{ii} = \nabla \cdot \dot{\mathbf{d}}$, the mechanical

319 governing equation can be described as

320
$$G\nabla^{2}\dot{\mathbf{d}} + \left(\frac{G}{1-2\nu}\right)\nabla(\nabla\cdot\dot{\mathbf{d}}) - \zeta^{M}\nabla\dot{p}^{M} - \zeta^{F}\nabla\dot{p}^{Fl} = 0$$
(29)

321 where v is Poisson's ratio.

322 If the influence of solute on fluid pressure is neglected, the variation of the In-phase

323 density of the porous fluid is

324
$$\dot{\rho}_{l}^{Ml} = \rho_{l}^{Ml} \left(\frac{1}{\rho_{l}^{Ml}} \frac{\partial \rho_{l}^{Ml}}{\partial p^{Ml}} \right) \frac{\partial p^{Ml}}{\partial t} = \rho_{l}^{Ml} \frac{1}{K_{w}} \dot{p}^{Ml}$$
(30)

325 where K_w is the bulk modulus of water.

Using the pore porosity equation (25), Darcy's law, and displacement d, substituting
equation (30) into equation (6), the balance equation of porous fluid (equation
(6))becomes

329
$$\zeta^{M} \nabla \cdot \dot{\mathbf{d}} + (Q + \upsilon^{M} \frac{1}{K_{w}}) \dot{p}^{Ml} + B \dot{p}^{Fl} + \frac{r_{ex}^{l}}{\rho_{l}^{Ml}} - \frac{k^{M}}{\mu_{w}} \nabla^{2} p^{Ml} = 0$$
(31)

where k^{M} is the permeability for the porous matrix, μ_{w} the water dynamic viscosity (normally related to water temperature), p^{Ml} the fluid pressure in the porous matrix. Similar to the above steps of porous fluid, the governing equation for fracture fluid transport can be obtained as

334
$$\zeta^{F} \nabla \cdot \dot{\mathbf{d}} + (Z + \upsilon^{F} \frac{1}{K_{w}}) \dot{p}^{Fl} + B \dot{p}^{Ml} - \frac{r_{ex}^{l}}{\rho_{l}^{Fl}} - \frac{k^{F}}{\mu_{w}} \nabla^{2} p^{Fl} = 0$$
(32)

335 where k^{F} is the permeability for fracture, p^{Fl} is the fluid pressure in fracture.

336 Using Darcy's law and Fick's law in the balance equation of porous solute transport,

the governing equation for porous solute transport is

338
$$(\upsilon^{M} \rho_{l}^{Ml}) \dot{c}_{Mc} - \rho_{l}^{Ml} \frac{k^{M}}{\mu_{w}} \nabla p^{Ml} \nabla c_{Mc} + r_{ex}^{c} + \nabla \cdot (\rho_{l}^{Ml} D^{M} \nabla c_{Mc}) = 0$$
(33)

339 Similarly, the governing equation for fracture solute transport can be obtained as

340
$$(\upsilon^{F} \rho_{l}^{Fl}) \dot{c}_{Fc} - \rho_{l}^{Fl} \frac{k^{F}}{\mu_{w}} \nabla p^{Fl} \nabla c_{Fc} - r_{ex}^{c} + \nabla \cdot (\rho_{l}^{Fl} D^{F} \nabla c_{Fc}) = 0$$
(34)

341 where D^M , D^F are the dispersion -diffusion coefficient for the solute in porous matrix

342 and fracture.

343 The transfer term has been studied for a long time since 1960 s (Barenblatt et al., 1960,

344 <u>Khalili, 2003</u>). Here a linear transfer equation is adopted, which can be described as:

$$\frac{r_{ex}^{l}}{\rho_{l}^{\alpha l}} = \frac{\chi k^{M}}{\mu_{w}} \left(p^{Ml} - p^{Fl} \right)$$
(35)

346 where the χ means shape factor, $\rho_l^{\alpha l}$ is the In-phase density of porous or fracture 347 fluid. χ can be calculated as (Warren and Root, 1963)

348
$$\chi = \frac{4N(N+2)}{L^2}$$
 (36)

349 where N denotes the dimension of porous matrix block (N = 1,2,3), L is the fracture 350 spacing.

351 The transfer term of the solute can be divided into two parts, convection and diffusion

353
$$\frac{r_{ex}^{c}}{\rho_{l}^{\alpha l}} = \frac{\chi k^{M}}{\mu_{w}} \left(p^{Ml} - p^{Fl} \right) \left(c_{Mc} - c_{Fc} \right) + \tau \left(c_{Mc} - c_{Fc} \right)$$
(37)

354 where τ is the diffusion transfer parameter.

355 Parameter identification

356 The parameters in the governing equations were identified by <u>MA et al. (2023)</u>. Below

are the expressions of these parameters

$$\zeta^F = 1 - \frac{K}{K_{pb}} \tag{38}$$

359 where K_{pb} denotes the bulk modulus of the porous matrix block (Valliappan and

360 Khalili-Naghadeh, 1990).

$$\zeta^{M} = \frac{K}{K_{pb}} - \frac{K}{K_{s}}$$
(39)

362 where K_s is the bulk modulus of solid grain.

363
$$Z = \frac{1}{K_{pb}} \left(1 - \phi^F - \frac{K}{K_{pb}} \right)$$
(40)

364
$$B = \left(1 - \phi^F - \frac{K}{K_{pb}}\right) \left(\frac{1}{K_s} - \frac{1}{K_{pb}}\right)$$
(41)

365
$$Q = \left(\frac{1}{K_{pb}} - \frac{1}{K_s}\right) \left(1 - \phi^F - \frac{K}{K_{pb}} + \frac{K}{K_s}\right) - \frac{\phi^M}{K_s}$$
(42)

366 These parameters can be determined directly in the laboratory test.

367 Theoretical verification

368 The mathematical model in the present paper (from equation (29) to (34)), obtains the 369 effects of mechanical deformation and fluid flow on solute transport in dual-porosity 370 media. The constitutive equation of hydro-mechanical coupling is the same as research 371 from the mechanics approach (Khalili, 2003, Khalili, 2008b), which mainly focus on 372 the coupling between fluid flow (including multiphase flow) and solid deformation, 373 without exploration of the influence of hydro-mechanical coupling on solute transport. 374 Equation (25) and (26) obtain the porosity evolution in dual-porosity media; which is 375 determined by solid deformation, both pore and fracture pressure change. If Equation 376 (25) and (26) are ignored, as well as the mechanical part (equation (29)), the ST-HM 377 model can degenerate to the classical Dual-Permeability Model proposed by (Simunek

and van Genuchten, 2008).

379 The fluid transfer term is consistent with previous research (Khalili, 2003, Zhao and

- 380 <u>Chen, 2006</u>). The solute transfer term is consistent with solute transport research in
- dual-porosity media (Dykhuizen, 1987, Li et al., 2020, Gerke and Vangenuchten, 1993).
- 382 If it ignores the solute diffusion between pore and fracture, it converts to a pure
- 383 convection term (Sharma et al., 2021). It converts to a pure concentration-depended
- term (Leij et al., 2012) if it ignores the convection between pore and fracture.
- 385 Musso and Li (Musso et al., 2013, Li et al., 2020) studied HMC coupling in swelling
- 386 clay. Compared with the solute transport part in their model (i.e. ignoring swelling), the
- 387 ST-HM model considers the fully coupled effects between pore and fracture fluid flow

388 (equation (31) and (32)).

389 Experimental validation of the coupled model

390 Validation strategy

391 The presented model is validated by two existing laboratory tests. The first simulation 392 is used to validate the solute transport behaviour in dual-porosity media, while the 393 second one is used to validate the dual porosity Hydro-Mechanical coupling part.

The numerical models based on the equations proposed in this paper were used to simulate the experiments. The initial parameter's value was adopted by the experimental research, the simulated results were compared with experimental data for model validation. During the optimization, the parameters were changed to different values, and the final optimized parameter values were obtained when the modelling resultsfitted well with the experimental data.

400 Validation of the solute transport behaviour

The experimental information is detailed in (Leij et al., 2012)). The details of this experiment and how the model was calibrated are provided in the supplementary material. At first, the soil column which contains both macropore and pore was saturated, and a steady flow rate of 1397.5 cm/d was established. The solute concentration (CaCl₂) of the inflow fluid C_i was 60 mol/m³. Then the concentration (CaCl₂) of inflow fluid C_i was changed from 60 mol/m³ to 90 mol/m³, and the concentration at each probe was measured. The relative concentration ratio $\frac{C}{C_0}$ was

408 calculated, C means the relative concentration (measured concentration minus the 409 initial concentration 60 mol/m³) and C_0 the concentration step (30 mol/m³).

410 Note that the soil is dual-porosity media. So, the measured concentration was the 411 average volumetric concentration, which was calculated as

412
$$C_{av} = \frac{C_{Mc} \times \upsilon^M + C_{Fc} \times \upsilon^F}{\upsilon^M + \upsilon^F}$$
(43)

413 A numerical model was set up in COMSOL MultiphysicsTM software (<u>AB</u>) based on 414 the experiment. Mechanical deformation was ignored in this simulation, and no 415 adsorption was considered (details of the numerical model setting are provided in the 416 supplementary materials). All simulation parameters are listed in **Table 1**. 417 The modelled and experimental BTC data are plotted together in Figure 2. The 418 calculation error between the model results and experimental data is presented in



419 Supplementary information.

Figure 2. Experimental and modelled BTC at depths of 7.7, 10.0, 14.1, and 16.9 cm
in (a). Modelled BTC for volume average, pore and macropore concentration at a
depth of 16.9 cm in (b).

Figure 2a shows that the modelled results are in very close agreement with the experimental data. Figure 2b shows the modelled BTC of volume average, pore and macropore concentration at 16.9 cm. The peak of macropore BTC appears at about 12 h, much ahead of the peak of pore BTC (about 35 h), which leads to bimodal transport.

428 Validation of hydro-mechanical coupling behaviour

429 The experimental information is detailed in Callari's research (Callari and Federico,

430 <u>2000</u>). A artificial dual porosity media experienced a 1D consolidation process.

- 431 Drainage of water during the consolidation was allowed through the upper boundary.
- 432 The preliminary compaction was conducted under an initial effective pressure of 50
- 433 kPa; three successive load increments were applied. Here the third load increment (from

434 200 KPa to 400 KPa) is considered.

435 The details of the numerical model and how the model was calibrated are provided in 436 the supplementary materials. All simulation parameters are listed in Table 2. The 437 modelled and experimental excess fluid pressure data are plotted together in Figure 3. 438 The modelled results fit well with the experimental one, except in the very early stage 439 (less than 2 minutes). The measurement of pressure in the geotextile is quite difficult 440 due to the high rate of pressure dissipation in the geotextile (Callari and Federico, 2000). Both modelled and experimental results show that the fluid pressures in clayey block 441 442 (porous space) and geotextile (fracture space) are quite different.



444 Figure 3. Experimental and modelled excess fluid pressure at the base of the cell
445 versus time

446 Numerical case setup

443

447 Two numerical models were set up to further illustrate the solute transport behaviour in 448 deformable dual-porosity. The first model used the ST-HM equations, and the second 449 used the equations in the research of Zhenze Li (<u>Li et al., 2020</u>), hereinafter referred to 450 as the Zhenze model. Zhenze model deals with coupled hydro-mechanical-chemical

(HMC) behaviour in dual-porosity media, considering osmosis flow and swelling, which can interpret the swelling behaviour of MX-80 when infiltrated with brine. Osmosis flow and swelling were ignored in the presented paper, so only the nonreactive solute transport part in Zhenze model is compared with ST-HM. This comparison investigates the fully coupling effects between micropore and macropore flow on the solute transport and porosity evolution, which is not considered in Zhenze model.

As shown in **Figure 4**, the initial fluid pressure was 3×10^6 Pa, and the initial solute 458 concentration was $10 \text{ mol}/\text{m}^3$. The bottom boundary was a fixed constraint and no flow 459 boundary. The overburden applies a constant vertical load of 4×10^6 Pa on the rock, 460 with no flow crossing this boundary. The left boundary was constant horizontal load 461 2×10^6 Pa, and the right boundary was fixed in the X direction. In the simulation, the 462 fluid pressure on the left boundary remained 3×10^6 Pa while the fluid pressure on the 463 right boundary decreased to 1.5×10^6 Pa due to external human activity. The solute 464 concentration on the left boundary changed to $60 \text{ mol}/\text{m}^3$ while the concentration on 465 the right remained at $10 \text{ mol}/\text{m}^3$. The boundary conditions are referenced from 466 467 (Nguyen, 2010).





469 Figure 4. Model description and boundary conditions for an assumed aquifer
470 The parameters adopted in these two simulations are the same and are listed in Table 3.

471 Parameters are from the research of (Gelet et al., 2012a) and (Abousleiman and Nguyen,

472 <u>2005</u>).

473 Numerical case results

474 Mechanical deformation in dual-porosity media

475 The effects of fluid pressure change on solid deformation are well predicted by the ST-476 HM model. As shown in Figure 5, the rock consolidates in the simulation. The 477 displacement of the ST-HM model increases with time, finally reaching almost a steady 478 value at about 100 d. In contrast, the displacement of Zhenze model does not change 479 during the simulation. The reason is that fluid pressure does not influence solid 480 deformation in Zhenze model. As the fluid pressure decreases in the rock, it leads to 481 further consolidation until the fluid pressure reaches an equilibrium stage. Deformation 482 is related to the evolution of fluid pressure (equation (29)), so the increased deformation rates slow with time (as the decreased rates of fluid pressure become slow). 483



485

Figure 5. Horizontal and vertical displacement in X direction of rock

486 Fluid flow coupling in dual-porosity media

487 Figure 6 shows the pressure evolution in the pore and fracture of the rock. The fluid 488 pressure in both pores and fractures decreases gradually from the right side. Fluid 489 pressure in fracture changes much faster than in pore due to the much higher 490 permeability of fracture. Comparing the results of these two models, the fluid pressure 491 of the Zhenze model in both pore and fracture decreases faster than the fluid pressure 492 of the ST-HM model. It can be attributed to the coupled effect between pore and fracture 493 flow which is not considered in the Zhenze model. In equation (31) and (32), the coupling term $Q\dot{p}^{Ml} + B\dot{p}^{Fl}$ in the porous fluid equation and $Z\dot{p}^{Fl} + B\dot{p}^{Ml}$ in fracture 494 495 fluid equation is one of the novelties of ST-HM model. Since pore and fracture pressure 496 decrease in the simulation domain, these two coupling terms contribute to a lower value 497 of fluid pressure gradient (means lower water flow rates and slower decreased rates of 498 fluid pressure) than the Zhenze model.





Figure 6. Pore and fracture fluid pressure evolution on X direction of rock

501

Porosity evolution in dual-porosity media

502 Figure 7 shows the porosity evolution in pore and fracture in the X direction of rock. The pore porosity and fracture porosity all decrease in the consolidation process. 503 504 However, the ST-HM model and the Zhenze model give different predictions for the 505 evolution trend. In the the Zhenze model, porosity decreases from the initial value 506 instantaneously and remains constant throughout the simulation because this model 507 does not consider the influence of fluid pressure on porosity. According to equation (25) 508 and (26), the ST-HM model considers the influence of both pore pressure and fracture 509 pressure on porosity, so the porosity decreases gradually from the right side to the left 510 side (as the pressure change from the right side to the left side). Compared with the 511 Zhenze model, ST-HM model can better predict the long-term porosity change induced 512 by fluid pressure change.



514 Figure 7. Pore and fracture porosity evolution on X direction of rock Note that the fracture porosity at the right part reaches the lowest value in the early 515 516 stage (less than 100 d) and subsequently increases to a higher value, while the left part 517 shows the opposite trend. This can be explained based on the effects of pore pressure 518 and fracture pressure on fracture porosity. According to equation (26), the fracture 519 porosity is determined by solid strain, both pore and fracture pressure. In this simulation, $B = -6.65 \times 10^{-11}$ and $Z = 6.95 \times 10^{-11}$, which means that pore pressure change and 520 521 fracture pressure change affect fracture porosity oppositely in this case. Between 5 to 100 days \dot{p}^{M} is much lower than \dot{p}^{Fl} at the right part of the simulation domain 522 523 (because the response of fracture pressure is much quicker than pore pressure), which leads to an increase of fracture porosity at the right. While at the left part of the 524 simulation domain, the difference of \dot{p}^{Ml} and \dot{p}^{Fl} is not so high to overcome the 525 526 total decreased trend of fracture porosity.

527 The porosity change is induced by solid deformation, pore and fracture pressure. As 528 shown in **Figure 8**, the maximum pore porosity change is about -0.0022 (accounts for 529 1.46% of the initial pore porosity). In comparison, the maximum fracture porosity

change is about -0.00025 (accounts for 1.67% of the initial fracture porosity). The main 530 contribution of porosity change comes from solid deformation. Remarkably, in dual-531 porosity media, with the decrease of fluid pressure in both pore and fracture, the 532 533 porosity responds to both pore and fracture pressure. For pore porosity, the decrease of 534 pore pressure induces consolidation and the decrease of pore porosity. At the same time, 535 the decrease of fracture pressure induces the expansion of pore water which increase 536 the pore porosity. Similarly, the decrease of pore pressure induces fracture water 537 expansion for fracture porosity, while the decrease of fracture pressure induces 538 consolidation. As the permeability of fracture is much higher than pore, the fracture 539 pressure reaches its equilibrium much earlier, so the influence of the pore pressure on pore and fracture porosity last longer than fracture pressure. 540





544 *Effects of hydro-mechanical coupling on solute transport*

545 The solute concentration evolution in the X direction of rock is illustrated in Figure 9.

546 The solute transport is quite slow due to the low permeability of the rock. The transport

547 rates in the fracture are much higher than in the pore. That is, the transport in fracture 548 dominates the transport phenomenon in this simulation. For the ST-HM model, it gives 549 a prediction that the solute transport front reached approx. 180 m after 1000 days, while 550 for Zhenze model this value is approx. 210 m. This difference is due to the 551 overestimation of porosity in the Zhenze model, which also overestimates permeability 552 and diffusivity. Hence, in most parts of the simulation domain, the concentration values 553 predicted by Zhenze model are higher than the ST-HM model. The ST-HM model reduces about 16.67 % error for the prediction of solute transport front after 1000 days, 554 555 considering the influence of fluid pressure on porosity and the coupled effect between pore and fracture flow. After 1000 days, the overestimation of fracture solute 556 consideration is 0.41 mol/m³ (accounting for 0.73 %) at 50 m, 2.85 mol/m³ (accounting 557 558 for 9.71 %) at 85 m, 2.26 mol/m³ (accounting for 12.39 %) at 103 m. The increased rate 559 of the difference in solute transport font location between ST-HM and Zhenze model 560 becomes slow with time (because the pressure gradient and concentration gradient 561 decrease throughout the simulation).





Figure 9. Solute concentration evolution on the X direction of rock (fracture

564

concentration, pore concentration and average volumetric concentration)

565 Discussion of advantages and limitations

566 This study presents a novel method based on nonequilibrium thermodynamics rather

than the traditional mechanics approach. Since it is an energy-based approach, it is easy

568 to bridge different behaviour and extendable for other processes such as thermo-hydro-

569 mechanical-chemical and bio-hydro-mechanical-chemical coupling.

The governing equation in this paper is based on the assumption of small deformation and isotropic, these equations for hydro and mechanical fields are similar to research from the mechanics approach (<u>Khalili, 2003</u>, <u>Khalili, 2008b</u>). If these assumptions are released, more general governing equations are likely to be obtained, which shows an advantage of mixture-coupling theory over the classical mechanics approach on deriving complicated multi-physics in a systematic way.

576 The consideration of hydro-mechanical coupling on solute transport in dual-porosity 577 media is an advancement to the classical Dual-Permeability Model proposed by 578 Simunek and van Genuchten (2008). This model captures the fully coupling effects of 579 pore and fracture flow with mechanical deformation. By engaging this effect, the solid 580 stress and the porosity change can be better predicted than the classical model. Since 581 ignoring the fully coupling effects of pore and fracture fluid can induce significant error, 582 especially for long-term prediction, the ST-HM model can significantly reduce the error 583 for the prediction of the solute transport front compared with the equations by Li et al. 584 (2020).

There are also some limitations existed in this model. The potential effects of exchange on the transport phenomenon in pore and fracture were not studied. In addition, highvelocity flow would affect the dissipation process in porous media (<u>Takhanov, 2011</u>). So, the modification of general Darcy's law in dual-porosity media is needed to implement these limitations.

590 Finally, the basic assumption of the dual-porosity theory is that the different spaces in 591 the media and the exchange phenomenon between those spaces can be captured by the 592 equivalent continuous parameters and variables (<u>Berre et al., 2019</u>). The proposed 593 model is not capable to solve solute transport in some fractured or structured media 594 with insignificant dual porosity characteristics.

595 Conclusion

596 This research extends the Mixture Coupling Theory and derives the constitutive 597 equations for non-reactive solute transport in deformable dual-porosity media (ST-HM), 598 based on nonequilibrium thermodynamics. The final governing equations of ST-HM 599 enable the prediction of non-reactive solute transport considering fully hydro-600 mechanical coupling, which was often ignored by existing research.

A conceptual case was simulated to illustrate the major improvement of the presented model. Simulated results show that the presented model provides a better prediction than a previous model on the porosity evolution, fluid pressure and solute concentration due to the consideration of fully coupling effects between pore and fracture flow. The ST-HM model reduces about 16.67 % error for the prediction of solute transport front

35

after 1000 days and reduces up to 12.39 % error for the prediction of fractureconcentration.

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Parameter	Value	Meaning
ρ	$8.5 \times 10^2 \text{ kg} \cdot \text{m}^{-3}$	bulk density of Andisol
$\mu_{_{w}}$	8×10^{-4} Pa·s	Viscosity of water
$oldsymbol{ u}^M$	0.41	Initial pore porosity
$v^{\scriptscriptstyle F}$	0.16	Initial macro pore porosity
$k^{\scriptscriptstyle M}$	$2.75 \times 10^{-9} \text{ m}^2$	Initial pore permeability
$k^{\scriptscriptstyle F}$	8.5×10 ⁻⁹ m ²	Initial macro pore permeability
$K_{ m w}$	4.3 GPa	Compressibility of water
L	1×10 ⁻² m	Macro pore spacing
$D^{\scriptscriptstyle M}$	$7 \times 10^{-5} m^2 \cdot s^{-1}$	Pore Hydrodynamic dispersion coefficient
D^F	$2.5 \times 10^{-4} \text{ m}^2 \cdot \text{s}^{-1}$	Macro pore Hydrodynamic dispersion
		coefficient
τ	1×10 ⁻⁸ s ⁻¹	Coefficient of diffusive transfer
Т	70 min	Calculation period
Step	0.1 min	Timestep

Table 1 Parameters used in the numerical model against solute transport experiment

Table 2 *Parameters used in the numerical model against hydro-mechanical coupling*

experiment

Parameter	Value	Meaning
ho	$2.5 \times 10^3 \text{ kg} \cdot \text{m}^{-3}$	bulk density of soil
$\mu_{_W}$	8×10 ⁻⁴ Pa·s	Viscosity of water
v	0.3	Poisson's ratio
K	3.2 MPa	Bulk modulus of total rock
K_{Pb}	6.6 MPa	Bulk modulus of porous block
K _s	27.5 GPa	Bulk modulus of solid grain
$\boldsymbol{\upsilon}^{\scriptscriptstyle M}$	0.55	Initial pore porosity
$v^{\scriptscriptstyle F}$	0.008	Initial fracture porosity

k^{M}	$4.8 \times 10^{-18} m^2$	Initial pore permeability
$k^{\scriptscriptstyle F}$	$4 \times 10^{-11} m^2$	Initial fracture permeability
$K_{ m w}$	4.3 GPa	Compressibility of water
L	6×10^{-3} m	Fracture spacing
Т	10 ⁴ min	Calculation period
Step	0.01 min	Timestep
T Step	6×10^{-4} min 0.01 min	Calculation period Timestep

Table 3 Parameters used in the numerical simulation for discussion of solute

transport behaviour in deformable dual-porosity

Parameter	Value	Meaning
K	1.103 GPa	Bulk modulus of rock
K_{Pb}	1.226 GPa	Bulk modulus of porous block
$K_{\rm s}$	27.5 GPa	Bulk modulus of solid grain
V	0.22	Poisson's ratio
$\mu_{\scriptscriptstyle w}$	8×10 ⁻⁴ Pa·s	Viscosity of water
$oldsymbol{ u}^M$	0.15	Initial pore porosity
$oldsymbol{ u}^F$	0.015	Initial fracture porosity
$k^{\scriptscriptstyle M}$	$5 \times 10^{-18} m^2$	Initial pore permeability
$k^{\scriptscriptstyle F}$	$5 \times 10^{-15} m^2$	Initial fracture permeability
$K_{ m w}$	4.3 GPa	Compressibility of water
$D^{\scriptscriptstyle M}$	$9 \times 10^{-12} m^2 \cdot s^{-1}$	Pore Hydrodynamic dispersion coefficient
\mathbf{D}^F	7 10-11 2 -1	Fracture Hydrodynamic dispersion
D^{*}	1×10 m ² ·s ²	coefficient
τ	1×10 ⁻¹¹ s ⁻¹	Coefficient of diffusive transfer
L	2 m	Fracture spacing
Т	1000 d	Calculation period
Step	0.1 d	Timestep





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Figure 3. Experimental and modelled excess fluid pressure at the base of the cell

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versus time





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Figure 4. Model description and boundary conditions for an assumed aquifer





Figure 5. Horizontal and vertical displacement on X direction of rock





Figure 6. Pore and fracture fluid pressure evolution on X direction of rock





Figure 7. Pore and fracture porosity evolution on X direction of rock





Figure 8. Pore and fracture porosity evolution at centre of the rock (X=250, Y=5)



Figure 9. Solute concentration evolution on the X direction of rock (fracture
concentration, pore concentration and average volumetric concentration)