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Bionics and dynamic interface wetting intensely appeal to many research communities due to their unique practical implications. The rose petals had a highly robust dynamic water-retaining capacity under heavy precipitation. We predicted that the roses became more "hydrophilic" at higher Weber numbers.

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Fresh rose petals were directly impacted by droplets, and facile artificial petal-like substrates and superhydrophobic substrates were used in the comparative analysis. The wetting dynamics of the droplet (e.g., topography, bounce dynamics, contact time, three-phase contact lines, and oscillations) were investigated when interacting with four selected target substrates.

Findings

The present work first time investigated the dynamic wetting rule of the sticky superhydrophobic substrates (SSHS). Simulated and experimental investigations confirmed that the unique coupling synergy between the pinning effect and the inhomogeneous micropapillae resulted in lopsided contact line velocities, which remarkably suppressed the lateral oscillation and rebounding. This may be a new strategy when designing dynamic water-repellent surfaces and open a promising avenue for emerging areas such as super-efficiency energy conversion and harvesting.

Robust adhesion of droplets via heterogeneous dynamic petal effects

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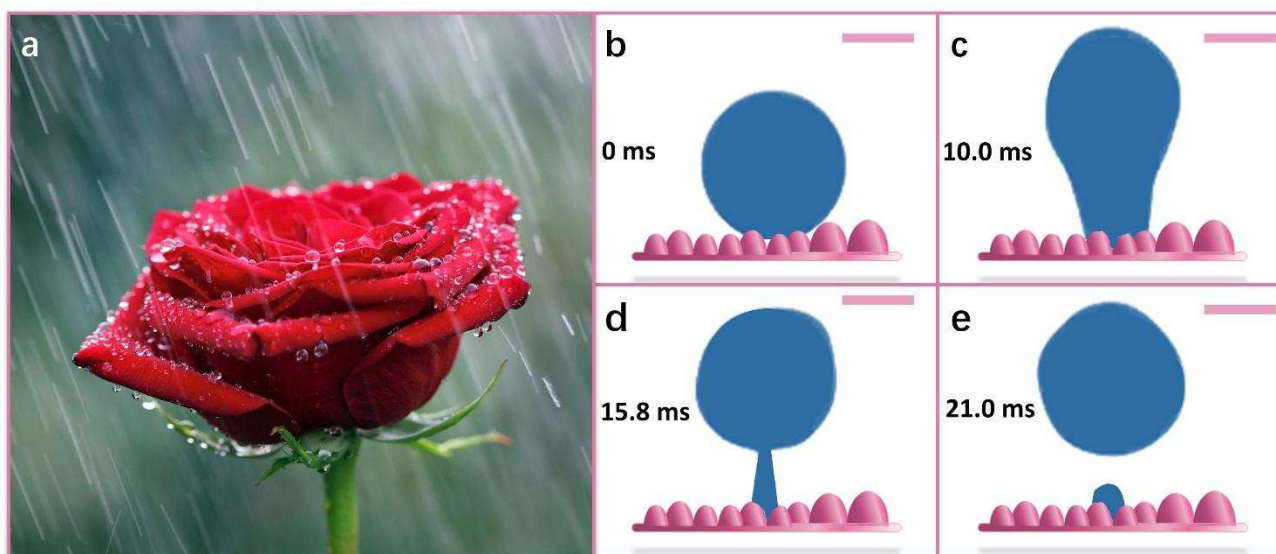
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28 **Keywords:** dynamic petal effect, droplet impact, asymmetric wetting, sticky superhydrophobic

29 **1. Introduction**

30 Rain droplets on lotus leaves may be less striking than rain droplets on rose petals. Water droplets
31 can attach to rose petals without rolling off, even at great tilt angles. However, water droplets cannot
32 remain on lotus leaves after a rain. The “lotus effect” is synonymous with superhydrophobicity, and a
33 superhydrophobic surface(SHS) exhibits a static **apparent contact angle** (CA, θ) of greater than 150°
34 with a very low contact angle hysteresis (CAH, θ_{CAH})[1–4]. Interestingly, rose petals can exhibit an
35 extremely high CA similar to that of the “lotus effect”, but with high CAH (Fig. 1a)[5]. This "sticky
36 superhydrophobic" substrate (SSHS) phenomenon known as the "petal effect" was first proposed by
37 Jiang et al.[6] and has since drawn much research attention due to its widespread use in emerging fields
38 such as self-cleaning[7], droplet transfer, transportation[8], biochemical separation, and energy
39 harvesting[9,10]. In addition, studying the dynamic wetting mechanism of an SSHS provides
40 information for enhancing functional surface designs.

41



42 Fig. 1 Dynamic wetting phenomenon on rose petals. (a) Retention of spherelike droplets on rose
43 petals in the rain. (b-e) Schematic diagram of the interfacial process of a droplet impacting a rose petal
44 at low-impact velocities. The scale bar=1 mm.

45 Generally, the static-wetting state of rough surfaces can be explained by the classical wetting
46 theory of Cassie-Baxter[11] and Wenzel[12]. In the Cassie-Baxter model, the rough solid surface is
47 completely filled with liquid, resulting in high water adhesion. However, entrapped air is observed in

48 the Wenzel model, which is attributed to hydrophobicity[13]. The superhydrophobicity exhibited on
49 the lotus leaf results from the combination of convex epidermal cells and extremely low-density
50 biowax layers[14]. The lotus effect should be governed by the idealized Cassie-Baxter model. For the
51 lotus effect, research on fabricating and characterizing biomimetic surfaces is trending, both
52 theoretically and experimentally[15–21]. In contrast, few in-depth studies have examined the petal
53 effect; thus, the accurate mechanism of the petal effect wetting behavior remains unclear[22].
54 Nonetheless, the Cassie-Baxter and Wenzel models are used by most scientists to explain wettability at
55 the interface. Adhesion of water droplets to rose petals has been attributed to the Wenzel state based on
56 the geometric parameters of the rose petal surface determined for both biological and artificial samples.
57 These parameters include the diameter, spacing and secondary nanostructure of the
58 micropapillae[23](Fig. 1b-e). In contrast, the opposite conclusion has also been suggested, in that the
59 petal’s microstructure is considered to benefit adhesion, but this conclusion cannot be explained by the
60 classic Cassie-Baxter wetting theory[24]. Thus, the rose petal wetting mechanism seems puzzling. S.
61 Yang et al.[25] observed that the interaction between droplets and rose petals was completely in
62 accordance with the Wenzel state, and these authors found no air cushion using micro computed
63 tomography. Visualization technology has been developed, which has facilitated analyzing this
64 mechanism. Optical microscopy observations using micron-scale resolution have recently shown that
65 the wetting behavior of droplets on rose petals is unstable because gas moves slowly from the space
66 over the liquid, thus altering the wetting state. This is a mutual transformation from the Cassie and
67 Wenzel states[26]. This contradictory conclusion was likely reached because dynamic observations
68 were applied to the latter; that is, the movable air cushion disappeared after connecting to the
69 atmosphere, resulting in continuous wetting at the three-phase contact line (TCL).

70 Thus, the static-wetting mechanism of the petal effect remains unclear, and determining its
71 precise dynamic wetting process is challenging. Experiments and simulations in which droplets
72 impact the substrate have long been used to investigate the dynamic wettability of natural, artificial
73 and chemically heterogeneous surfaces[27]. To our knowledge, previous investigations of the
74 substrate’s configuration after being impacted by the droplet mainly included liquid film[28],
75 superhydrophilicity[29], hydrophobicity[30], superhydrophobicity[31], elastic

76 superhydrophobicity[32,33], and vibrating superhydrophobicity[34]; however, no reports regarding
77 droplet impact on SSH surfaces (the petal effect) have been published. Li et al.[35] reported the
78 dynamic wetting characteristics of water droplets on various substrate configurations at $CA = 160^\circ$,
79 154° , 153° , 122° , 124° , and 119° . Shen et al.[36] verified that a relationship exists between the
80 trapped air and the interface adhesion when a droplet impacts a sticky hydrophobic substrate. In the
81 two aforementioned studies, the droplets were released from the same height as that impacting the
82 substrate, which was insufficient to summarize the rules of dynamic wetting on sticky
83 superhydrophobic surfaces.

84 This paper describes the dynamic wetting rule on a SSHS (i.e., the petal effect) by comparing
85 the wetting state on a superhydrophobic surface. The quantitative (experiments) and qualitative
86 (simulations) investigation confirm that the dynamic unbalance wetting mechanism of the petal effect
87 is due to the coupling of the lateral interaction of the droplets with the pinning effect, thus providing
88 novel insights into why rose petals can retain water droplets and new rational guidelines for wetting
89 functional surface design.

90 **2. Experimental materials and methods**

91 **2.1 Surface fabrication and characterization**

92 To capture the commonality of droplet dynamics on the SSHS, three target substrates were
93 fabricated, including the rose petal surface (RPS) and engineering sticky superhydrophobic surfaces
94 (SSHS-1 and SSHS-2). Besides, the superhydrophobic surface (SHS) is used for comparative
95 verification.

96 **2.1.1 Rose petal surface (RPS)**

97 A fresh red rose was purchased from a flower market (Changchun, China), and a piece of the
98 rose petal ($15\text{ mm} \times 1.5\text{ mm}$) was fixed to a glass sheet which was neither cleaned nor altered.

99 **2.1.2 Sticky superhydrophobic surface (SSHS)**

100 We replicated the surface (SSHS-1) invented by Chen et al.[37], with some modifications to the
101 chemical reactions. One-millimeter-thick zinc foil was ultrasonically cleaned in acetone and
102 deionized water. The zinc foil was etched in hydrochloric acid for 15 seconds, then washed
103 thoroughly in deionized water. Next, the zinc foil was etched in hydrochloric acid for 15 s, then

104 immersed in 0.01 mol/L $\text{CuSO}_4 \cdot \text{H}_2\text{O}$ for 12 minutes, thoroughly washed again in deionized water,
105 and immersed in 0.005 mol/L $\text{CH}_3(\text{CH}_2)_{16}\text{COOH}$ for 30 minutes. We also established a micron-scale
106 with arrays on paraffin with low surface energies (SSHS-2) for comparison. (S1.2, Supplementary
107 Information).

108 2.1.3 Superhydrophobic surface (SHS)

109 The 2-mm-thick square copper plate was etched in hydrochloric and sanding with sandpaper then
110 treated with 1H,1H,2H,2H-perfluorodecyl trichlorosilane (Aladdin, Inc., China) via chemical vapour
111 deposition.

112 2.1.4 Surface characterization

113 All characterization tests were performed indoors at 25°C. The surface morphology was
114 characterized by scanning electron microscopy (SEM; EVO MA 25/LS, ZEISS, Inc., Germany) with
115 20-kV accelerating voltage and a three-position ultra-depth microscope (Smartzoom 5, ZEISS, Inc.,
116 Germany). The **apparent contact angles** were measured using a contact angle meter (DSA 22 KRUSS,
117 Germany), wherein the water droplet volume was 4 μL .

118 2.1.5 Experimental apparatus and image analysis

119 To analyze the dynamic wetting behavior of the droplets, an experimental system was
120 established to observe and record the droplet impacting the substrate (Fig. S1 in Supplementary
121 Information). This system generates the water droplets (2.14 ± 0.01 mm) using a 0.24-mm metal
122 needle and a syringe driven by a microstepping motor. Using another microstepper motor, the
123 droplet-to-substrate distance (H) can be varied, resulting in speeds of $v=0.308\text{--}1.128$ m/s. The
124 resulting corresponding dimensionless numbers are the Weber number $W_e = \rho v^2 D_0 / \gamma = 4\text{--}50$, **capillary**
125 **number** $C_a = \mu v / \gamma = (4\text{--}16) \times 10^{-3}$, **Reynolds number** $R_e = \rho v D_0 / \mu = 866\text{--}3120$, and **Ohnesorge number**
126 $O_h = \mu / (\rho \gamma D_0)^{1/2} = 2 \times 10^{-3}$, with a density of $\rho = 997$ $\text{Kg} \cdot \text{m}^{-3}$, surface tension of $\gamma = 72 \times 10^{-3}$ N/m, and
127 dynamic viscosity of $\mu = 0.89 \times 10^{-3}$ Pa·s, which are the water's physical parameters.

128 2.1.6 Simulations

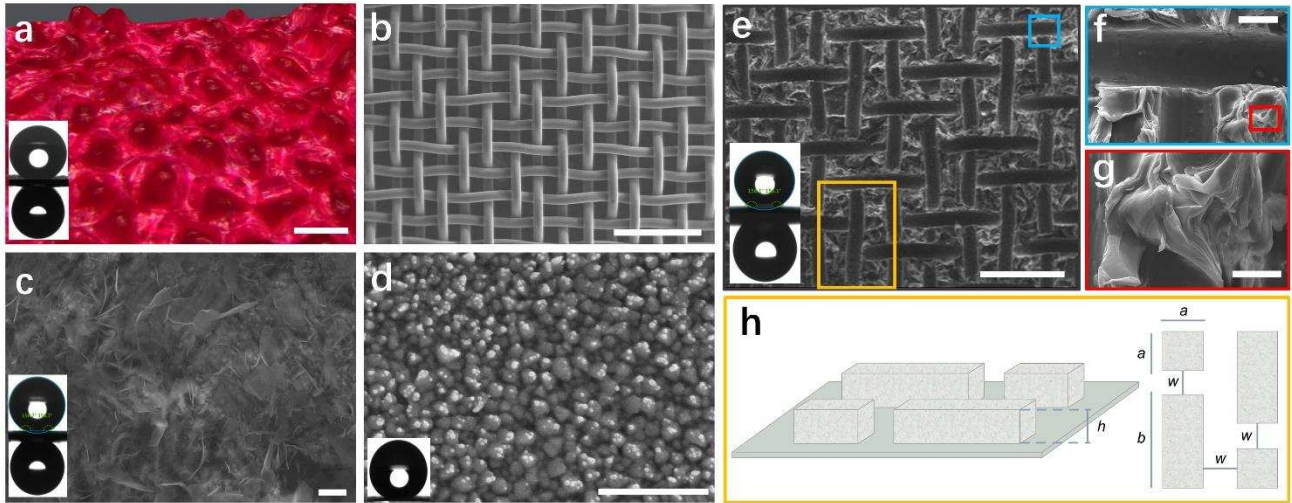
129 Qualitative simulation analysis was performed via the lattice Boltzmann method (the D3Q9 grid)
130 [38,39].

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132 3. Results and discussion

133 3.1 Morphology and wettability of the target substrates

134 Fig. 2 illustrates the morphology and adhesive states of the selected substrates (RPS, SSHS-1,
135 SSHS-2 and SHS). The RPS could be visually characterized by a three-position ultra-depth
136 microscope at 1000 \times magnification (Fig. 2a). The irregular array consisted of micropapillae
137 averaging 9 ± 2 μm high and 19 ± 2 μm in diameter (similar to previous studies[6,40]), which were
138 semiautomatically obtained from the written code in MATLAB and the open-source software ImageJ
139 by analyzing the selected images. The inset plots in Fig. 2a illustrate that the CA of the RPS was 154°
140 $\pm 2^\circ$, and a 4- μL droplet could adhere to the surface with a tilt angle of 180° . Similar wetting states
141 also occur on sticky superhydrophobic zinc foils fabricated by chemical etching. The insets in Fig. 2c
142 show that the CA of the SSHS-1 is $157^\circ\pm 2^\circ$, and it exhibited high adhesion. Fig. 2d shows the SHS
143 with $\text{CA}=153^\circ\pm 2^\circ$ and $\theta_{\text{CAH}}=3^\circ\pm 1^\circ$, indicating a typical lotus effect phenomenon, which is consistent
144 with previous studies[41,42].The microstructures in Fig. 2e–g are SSHS-2, which are manufactured
145 by rapidly peeling off the copper mesh that was tightly attached to the solidified paraffin and the
146 colored box indicates the corresponding selected area. The inset plot in Fig. 2e likewise shows a
147 similar petal effect phenomenon, indicating $\text{CA}=156^\circ\pm 2^\circ$ with a large adhesive force. We established
148 a diagrammatic sketch of a typical SSHS-2 microstructure (Fig. 2h), in which the corresponding
149 statistical geometric parameters of the typical microstructures were short-side length: $a=85\pm 2$ μm ,
150 long-side length: $b=220\pm 2$ μm , width: $w=50\pm 2$ μm , and height: $h=50\pm 2$ μm .



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Fig. 2 Characterization of the static wettabilities of (a) RPS, (b) 200-mesh copper mesh, (c) SSHS-1, (d) SHS and (e–h) SSHS-2. (a) Image of a fresh rose petal captured by a 3D super depth-of-field microscope at 1000 \times magnification (scale bar=25 μ m). The darker red indicates the top of the mastoid, while the relatively low area is shown in light red. The RPS exhibited a petal effect phenomenon with $CA=154^{\circ}\pm 2^{\circ}$ and high adhesion, as illustrated in the insets. (b) SEM image of the 200-mesh copper mesh (scale bar=500 μ m). (c) SEM image of SSHS-1 (scale bar=4 μ m). The insets indicate that the $CA=156^{\circ}\pm 2^{\circ}$ with the high adhesive phenomenon. (d) SEM image of a superhydrophobic surface with $CA=153^{\circ}\pm 2^{\circ}$ (see inset). The scale bar=500 nm. (e) Regular array of paraffin cubes with the same spacing and height. The insets indicate that $CA=157^{\circ}\pm 2^{\circ}$ with markedly high adhesive behavior (scale bar=300 μ m). (f) T-shaped paraffin microstructure (blue boxes). Compared with the top of the raised paraffin square column, the trace of the single copper wire was almost smooth at the same magnification factor. (scale bar=40 μ m) (g) The top of the raised paraffin square column is shown in red boxes. (h) Schematic diagram of a typical microstructure model (orange boxes). The microstructure dimensional parameters were $a=85\pm 2$ μ m, $b=220\pm 2$ μ m, $w=50\pm 2$ μ m, and $h=50\pm 2$ μ m (scale bar =20 μ m).

3.2 Qualitative and quantitative analysis of Non-uniform lateral interaction on the SSHS

Simulations are performed to qualitatively explain the effect of the unbalanced Young's force dF_t on the wettability of the interface. The micropapillae and droplets are of the same order of magnitude to facilitate intuitive analysis (Fig. 3a). Two-phase fluid dynamics equations are solved

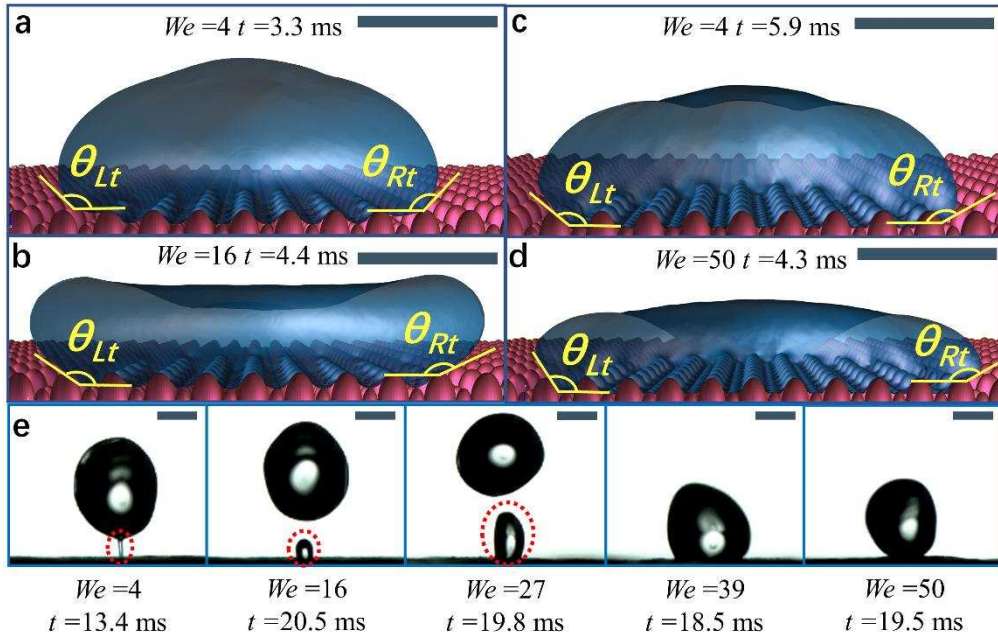
171 using the D3Q19 grid based on a lattice Boltzmann algorithm[38,39]. The micropapillae of the RPS
 172 are arranged in regular arrays during a simulation. In addition, the larger micropapillae (height =0.4
 173 mm with diameter =0.4 mm) are configured with a CA of 150° to counteract the superhydrophobicity,
 174 whereas the CA of the secondary micropapillae (height =0.2 mm with diameter =0.2 mm) is
 175 configured for 110°. The high-impact velocity droplets oscillated randomly and finally adhered to the
 176 rose petals; otherwise, the droplets have bounced at a low-impact speed. **The droplets tend to adhere**
 177 **to the petals with the increasing Weber numbers, as reflected in the residual droplets (red dotted**
 178 **circle in Fig. 3e).** The additional viscous dissipation during the droplet-petal interaction in the high
 179 Weber number state is attributed to cooperation between the irregular morphology[43]
 180 (micropapillae, Fig. 2a) and the sticky superhydrophobicity of the rose petals. Anomalous droplet
 181 formation was initialized during the spreading phase; however, the asymmetrical speed of the
 182 moving contact line was evident in the receding phase from a two-dimensional perspective in the
 183 schematic (Fig. 3 a-d). The lateral rebounding of a droplet can be manipulated because of the uneven
 184 gradient on the textured surface[44] and the unbalanced Young's force expressed as

$$185 \quad dF = \sigma |\cos \theta_{Rt} - \cos \theta_{Lt}| ds, \quad (1)$$

186 where $\cos \theta_{Rt}$ and $\cos \theta_{Lt}$ are the apparent contact angles of the right and left sides(Fig. 3 a-d),
 187 respectively, which were evaluated instantaneously by image analysis. d_s is the differential of the
 188 moving contact line, and dF is the transient unbalanced Young's force, which resists the inertia of the
 189 droplet. Thus, as $|\cos \theta_{Rt} - \cos \theta_{Lt}|$ increases (the droplet is more distorted), F_t also increases,
 190 resulting in a more "hydrophilic" substrate, which is consistent with that shown in Fig. 3e. Here, the
 191 effective unbalanced Young's force (F_e) can be simplified as

$$192 \quad \Delta \propto |\cos \theta_{Rt} - \cos \theta_{Lt}| \propto \frac{1}{5} (\lg |\theta_{Rt} - \theta_{Lt}|) \quad (2)$$

193 via analyzing the simulations. Δ contains a constant $\frac{1}{5}$, so that Δ is in the same order of
 194 magnitude as the quantitative result, which is advantageous for comparison verification.



195

196 **Fig. 3** Simulated and experimental analysis and verification of the unbalanced Young's force
 197 caused by the SSHS. **(a)-(d)** Simulation analysis of droplets are observed to be in the most laterally
 198 unbalanced. Unbalanced droplet morphology due to irregular micropapillae in the receding phase.
 199 Consequently, the Young's force increases, causing additional energy dissipation. The results of the
 200 simulation show that the difference between $\cos\theta_{Lt}$ and $\cos\theta_{Rt}$ is more significant as the Weber
 201 number increases, so higher F_e eventually lead to droplets adhesion. **The scale bar= 1.8 mm.** **(e)** The
 202 quantitative similarity of various morphologies of pingting tiny droplets (red dotted circle) on a rose
 203 petal as the Weber number increased. The rose petals became more "hydrophilic". **The scale bar= 1**
 204 **mm.**

205 However, the aforementioned effective unbalanced Young's force F_e is transient and difficult to
 206 quantify via experiments. Thus, the dimensionless size of the residual droplets, $\lambda = D_r / D_0$, is used
 207 to investigate the extent of the dynamic petal effect due to the intuitive result of the dynamic petal
 208 effect is reflected in the residual moisture on the RPS, as shown in Fig. 3e. These retained liquids on
 209 the RPS are essentially caused by varying degrees of the Cassie-to-Wenzel transition[11,12] which
 210 can be regarded as the partial wetting state. This partial wetting state is mainly governed by the
 211 effective water hammer pressure verified by Tao et al[45],

$$212 \quad P_{EWH} = k\rho C v, \quad (3)$$

213 where C is the speed of sound in water, and k is the fitting parameter of the corresponding
 214 experiment. Herein, $v \propto We^{0.5}$ and then $P_{EWH} \propto \alpha We^{0.5}$, where $\alpha = k\rho C$. In this case, we assumed
 215 that that dF_t is in a two-dimensional environment, thus dF_t and λ are in the same dimension and
 216 related. Together with Eq. (1-3), the quantitative estimation of dynamic petal effect of RPS would
 217 yield $dF_t \propto (\zeta = \alpha We^{\beta\lambda}) \propto \Delta \propto \alpha We^\gamma$. Thereby,

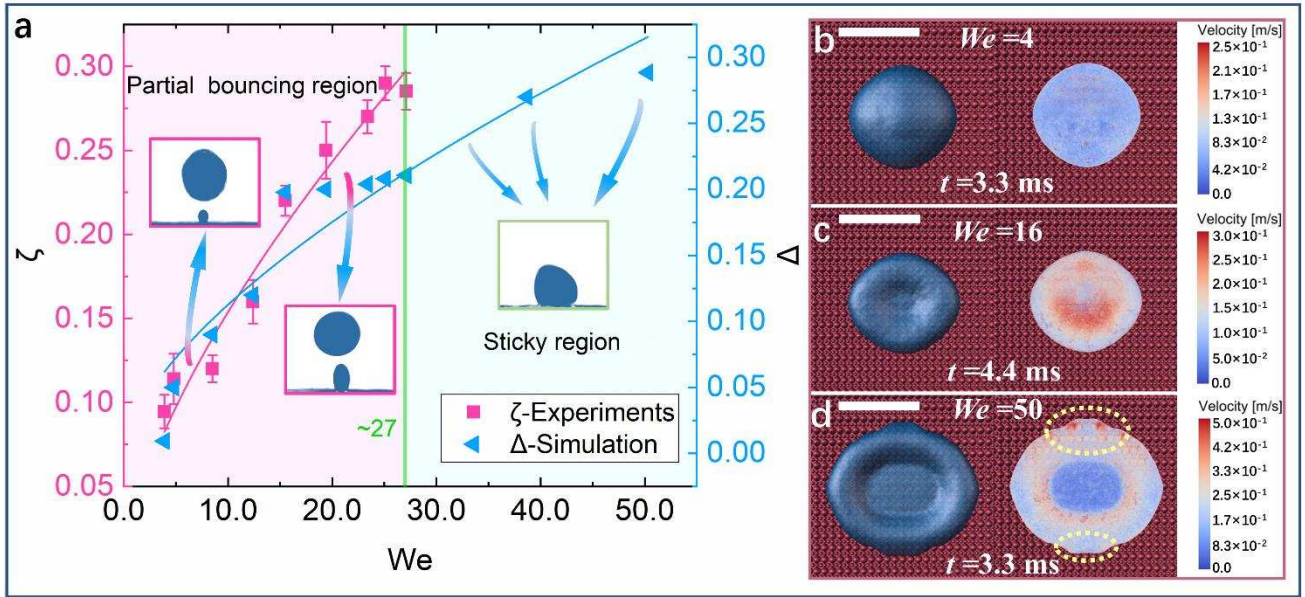
$$218 \quad \zeta = 0.0366 \left(\frac{\rho v^2 D_0}{\gamma} \right)^{0.633}, \quad (3)$$

219 where $4 < We_e = \frac{\rho v^2 D_0}{\gamma} < 27$. Eq. (3) are satisfied in our experiments (Fig. 3e and Fig. 4a): the
 220 dynamic water-repellency of the SSHS is only closely related to the impact velocity of the droplets
 221 (v). The limit ($We_e < 4$) was considered as the inconspicuous dynamic petal effect regime, while the
 222 critical total wetting state occurs when $We_e > 27$. Furthermore, the simulation results (Fig. 3 a-d and Fig.
 223 4b-d) qualitatively reveal the adhesion water caused by the lateral effect of the droplets of the SSHS
 224 in this study. Thus, the aforementioned effective unbalanced Young's force F_t would yield

$$225 \quad \Delta = 0.0259 \left(\frac{\rho v^2 D_0}{\gamma} \right)^{0.638}. \quad (4)$$

226 Herein, $4 < We_e = \frac{\rho v^2 D_0}{\gamma} < 50$. The results of the simulation (the blue line in Fig. 4a)
 227 satisfactorily confirm the positive effect of the lateral effect on droplet adhesion. The RPS—with its
 228 unique asymmetric natural sticky superhydrophobic, resulting in solid edges with discontinuous
 229 physical properties (e.g. wettability) that directly affect the receding speed of the three-phase contact
 230 line, which is striking at higher at high Weber numbers. As shown in yellow dotted circles in Fig. 4d,
 231 significant asymmetric receding line velocities and morphology are observed on both sides of the
 232 droplet, in contrast, symmetrical edge velocities occur at low Weber numbers (Fig. 4 b-c).
 233 Qualitatively, the synergy of the multiple lateral asymmetric effects and sticky will make the SSHS
 234 more sticky and "hydrophilic" at high droplet impinging velocities regime (see the insets in Fig. 4).

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Fig. 4 Quantitative and qualitative comparisons of the effects of multiple lateral pinning on the

RPS's wetting characteristics. **(a)** Investigations of the correlation between lateral effects and sticky

adhesion on the SSHS. The insets show the extent of the dynamic petal effect, from pinning tiny

droplets (partial rebound, lilac region) to no bouncing sticky region (light green area) as the Weber

number increases. Satisfactory qualitative similarities are revealed in experimental and numerical

results (purple and blue fitted line). The critical of the partial bouncing region and sticky region is $We =$

27 (green line). **(b)-(d)** The simulated velocity field as the droplets develop to their most asymmetrical

morphology. Axisymmetric droplet morphology occurs under the low Weber number regime ($We = 4$),

but note that the higher impinging velocities (corresponding to $We = 50$) result in remarkable

unbalanced receding velocities (yellow dotted circle). Both versions of the investigation confirmed the

same characteristic that asymmetric interactions caused by high weber number reduce the possibility

of droplet bouncing. **The scale bar=4 mm.**

248 3.3 Droplet bounce dynamics

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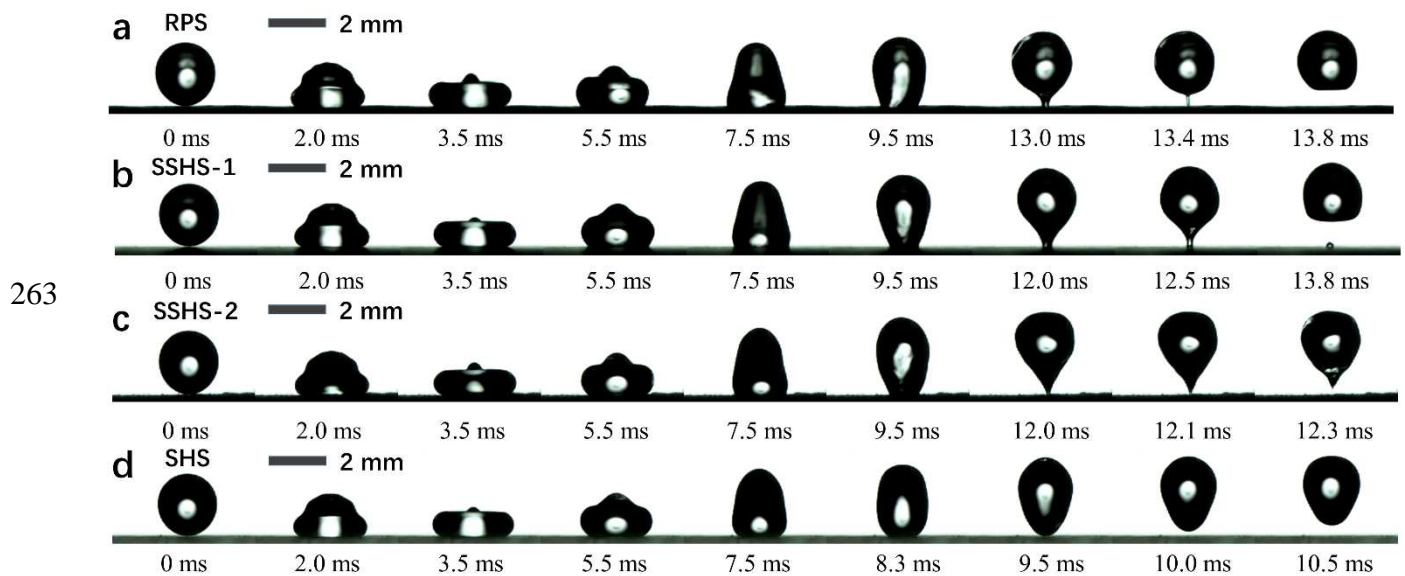
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In order to verify the above-mentioned theory, three SSHSs (the RPS, SSHS-1 and SSHS-2) and a SHS were selected as the target substrates. When a droplet hits a rough solid surface, it may bounce or stick, after undergoing the spreading and receding stages. The interfacial behavior of the droplets corresponds to the hydrophobicity (e.g., CA and CAH) of the substrate and is significantly affected by the wettability (e.g., high adhesion) of the interface[27]. We examined the droplet impact on the four

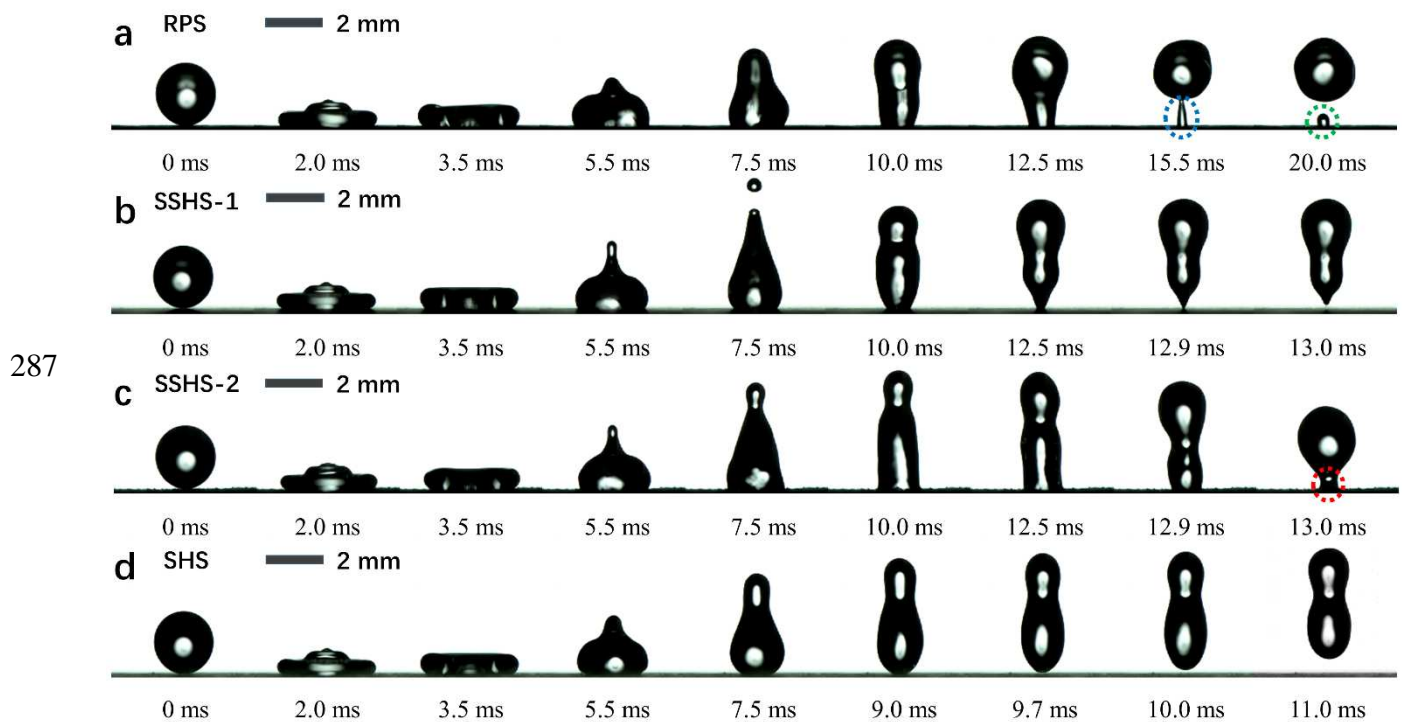
254 aforementioned surfaces. For droplets, the low-impact velocity resulted in a low kinetic energy level.
 255 **Fig. 5** illustrates the dynamic wetting process of the droplets on RPS, SSHS-1, SSHS-2 and SHS at a
 256 very low Weber number ($W_e=4$, corresponding to $v=0.362\pm 0.001$ m/s; see also Supplementary Movie
 257 S1). Droplets with sufficient kinetic energy can generally bounce off sticky superhydrophobic
 258 substrates at a very low Weber number, $W_e=4$ (**Fig. 5** a–c). Partial pinning occurred at the bottom of
 259 the droplet resulting in a slightly longer contact time than that on the SHS (see S3 in Supplementary
 260 Information for more details). The bounce of the drop was partially inhibited when the droplet
 261 impacted the sticky superhydrophobic substrate compared with that on the superhydrophobic
 262 substrate under the corresponding impacting velocity.



264 **Fig. 5** Snapshots of the droplets' dynamic behavior on RPS, SSHS-1, SSHS-2 and SHS ($W_e=4$,
 265 corresponding to $v=0.362\pm 0.001$ m/s). **(a–c)** Time evolution of an impacting droplet on RPS, SSHS-1,
 266 SSHS-2, respectively. The droplet morphology becomes asymmetrical during the receding phase.
 267 Droplets can still rebound, but the substrates exhibit some viscosity. **(d)** Impact phase diagram of a
 268 droplet impacting the SHS. The droplet lifts off the substrate with less contact time and remains more
 269 symmetric compared with that on the aforementioned substrates. Supplementary Movie S1 provides
 270 more details. **The scale bar=2 mm.**

271 As the Weber number increases slightly ($W_e=16$, corresponding to $v=0.723\pm 0.001$ m/s), the
 272 SSHS plays a more vital role in the droplets' dynamic behavior than does the SSH. Detaching the

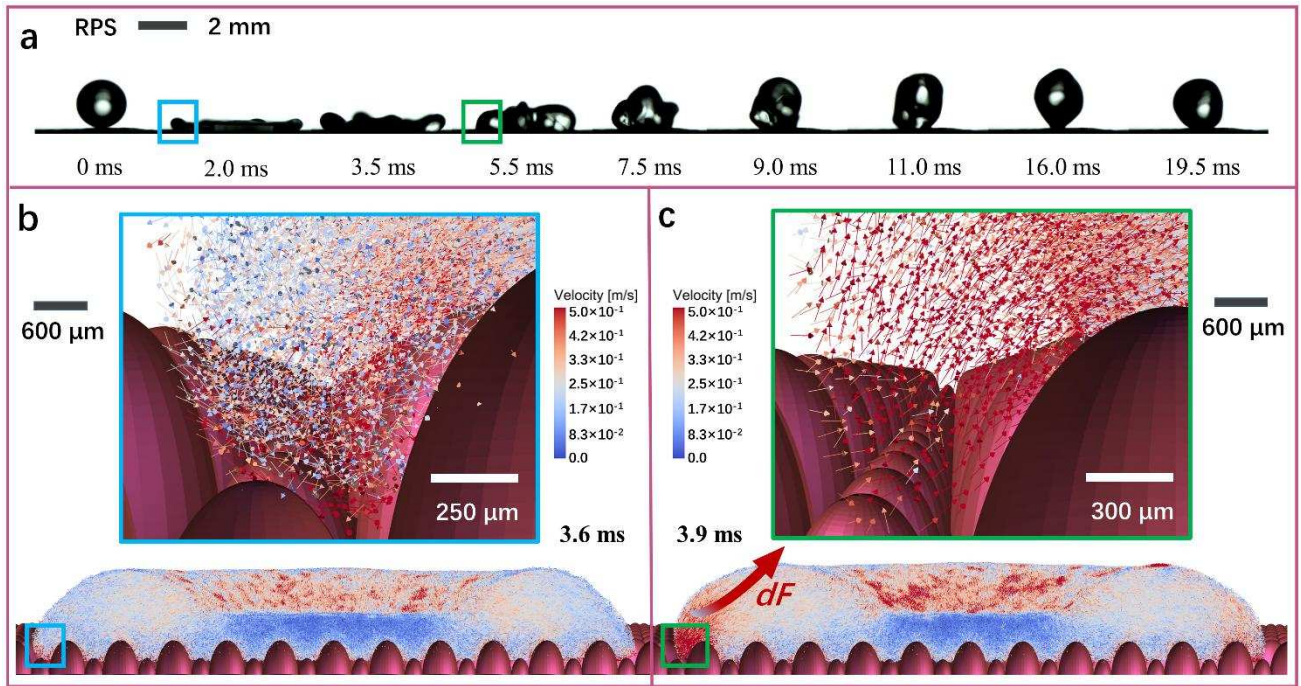
273 droplet from the SSHS was more difficult and differed greatly from its interaction on the SHS (Fig. 6;
 274 Supplementary Movie S2). The droplet morphology on all target substrates was almost synchronous
 275 during the spreading phase ($0 \text{ ms} < t < 3.5 \text{ ms}$) and was independent of the target substrate's
 276 wettability and impact velocity, which is consistent with previous studies[33,36,46]. For the RPS, the
 277 geometric center of the droplet changed and gradually moved away from the axis of symmetry,
 278 indicating more sensitivity to the impact velocity of the droplet after 3.5 ms than at the We of 4 (Fig.
 279 5 a and Fig. 6a). Thus, the droplet exhibited difficulty in rebounding completely, even with a higher
 280 initial kinetic energy, as illustrated by the residual secondary droplets on the sticky substrate (blue
 281 and green dotted circles in Fig. 6a, see also S4 in Supplementary Information). Interestingly, similar
 282 wetting phenomena were observed on both SSHS-1 and SSHS-2 (Fig. 6b–c). One droplet was
 283 difficult to lift off and was even pinned to the substrate (red dotted circle in Fig. 6c). Instead, the
 284 droplet lifted off from the SHS quickly after undergoing a spreading and retracting phase similar to
 285 that of the above corresponding testing condition. We confirmed that the dynamic response of the
 286 droplets is critical to wetting the SSHS interface during the receding phase when $4 \leq We \leq 16$.



288 Fig. 6 Sequential snapshots of the droplets' dynamic behaviors on the RPS, SSHS-1, SSHS-2 and
 289 SHS ($We=16$, corresponding to $v=0.723\pm 0.001 \text{ m/s}$). (a) Impact phase diagram of a droplet impacting
 290 the RPS. Note that this droplet was observed to be extremely asymmetric at $t=5.5 \text{ ms}$. During the

291 rebound phase, the liquid bridge (blue circle) is captured between the ejecting droplet and the
292 substrate. A residual secondary droplet is shown in the green circle. **(b)** Drop impacting the SSHS-1
293 with a tiny droplet ejecting at $t=7.5$ ms. **(c)** A droplet is completely trapped on the SSHS-2. A larger
294 liquid bridge is observed at the interface and is circled in red. **(d)** Sequential phase diagram of a
295 droplet impacting the SHS. Almost no adhesion was observed (Supplementary Movie S2). The scale
296 bar=4 mm.

297 Interestingly, as we predicted, the spreading phase of the droplets was also affected by the
298 substrate configuration, such as in the receding phase when the impact velocity was high ($We=50$,
299 corresponding to $v=1.304\pm 0.001$ m/s), which appears to be inconsistent with previous studies. In the
300 present study, the surface tension and viscosity of the water were constant and were factors that
301 inhibited the droplet from receding[47]. Fig. 7 shows the dynamic process of the droplet impacting
302 the RPS and SSHS-2 (Supplementary Movie S3). The droplet morphology is extremely
303 asynchronized during the spreading phase after $t=2$ ms. In addition, the droplet showed a maximum
304 twist compared with all previous test conditions and exhibited a surprisingly dF and could not to lift
305 off the substrate (Fig. 7a). Previously, we confirmed that droplets are more likely to adhere at high
306 Weber numbers, but did not qualitatively clarify the droplets' reciprocating oscillation on the RPS.
307 Once the de-pinning effect is initialized (red box in Fig. 7a), the de-pinning force for the moment,
308 including the inward and upward forces, will be activated (green box in Fig. 7a). The mechanism of the
309 corresponding state can be qualitatively explained by the blue box in Fig. 7b and the green box in Fig.
310 7c, respectively. Note that dF, with both upward and inward vectors, drives the leftmost liquid to hit
311 those adjacent portions with lower receding velocities, instead, the de-pinning does not occur on the
312 rightmost, thus the droplet exhibits unbalanced and eventually cause reciprocating oscillation of a
313 droplet on a rose petal. The free liquid-gas interface adjacent to the petal is pinned again, causing
314 multiple viscous energy dissipation, and the petal eventually becomes more "hydrophilic".



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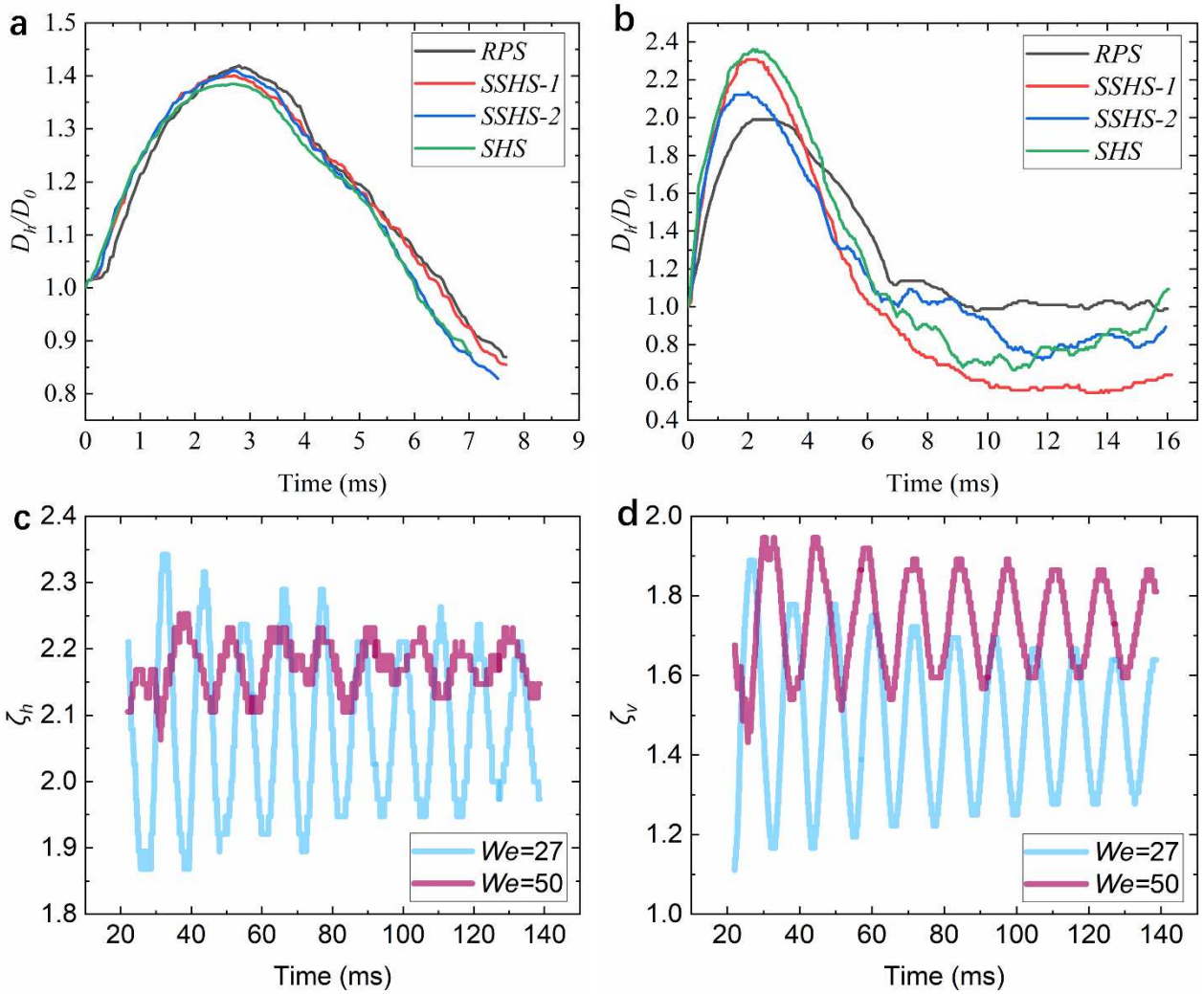
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Fig. 7 Impact of droplets on the RPS at high velocities ($We=50$, corresponding to $v=1.304\pm 0.001$ m/s). (a) A droplet impacts the RPS, exhibiting a sharp anisotropic vibration that prevents it from bouncing off the substrate. As we predicted, the non-negligible unbalanced Young's force increases with higher Weber number regime due to the strong asymmetrical solid-liquid interaction (See Supplementary Movie S3 for more details). **The scale bar=2 mm.** (b)-(c) Side-view snapshots of force analysis of the de-pinning procedure (3.6-3.9 ms). The velocity vectors of the particles are represented by arrows, and the zoomed area (blue box, **the scale bar=250 μm**) indicates that the high inward velocities vector only occurs at the wall before de-pinning. Subsequently, the leftmost particles have both inward and upward velocity vectors, which then impact adjacent low-velocity portions, causing unbalanced oscillations and additional energy dissipation, ultimately depleting the energy of the upward impact of the droplets(**green box, the scale bar=300 μm**).

3.4 Unique mechanism for suppressing oscillation

The TCL is always accompanied by the whole process of solid-liquid interaction, which does not merely increase the effective interfacial friction but also suppresses the bouncing droplets[48]. The size of the annular TCL can be quantified by the length of the horizontally overlapping lines (D_h). As a function of the time scale, D_h was normalized by the initial diameter D_0 (Fig. 8). A droplet

332 can bounce from both a sticky superhydrophobic substrate and a superhydrophobic substrate, which
333 was reflected in the similarity of the TCL when the droplet underwent a symmetrically evolved
334 interaction with the substrate ($W_e=4$, Fig. 8 a). The TCL evolved as a function of time scales, and the
335 peaks of these curves correspond to the droplet's maximum spreading diameter (D_{max}) when it
336 impacted the four selected substrates. The maximum spreading factor $\beta_{max} = (D_{max}/D_0) \sim W_e^{0.25} = 1.405$
337 is a critical parameter for evaluating inertia-dominated wetting kinetics based on mass conservation,
338 which is consistent with the conclusions drawn by Clanet et al.[49]. This also indicates that the
339 droplet's dynamic response is independent of the substrate configuration and remains dominated by
340 inertia within a low Weber number regimen. For the higher $W_e=50$, the effect of the substrate
341 configuration on the impact dynamics of the droplets was more effective. All droplets accomplished
342 the spreading process in 3 ms, then experienced a more time-consuming receding phase (Fig. 8b).
343 The distinguishable curves indicate that the droplet morphology was more sensitive to the substrate
344 configuration than that within the high Weber number regimen. We also noticed that the rose petals
345 exhibited the strongest robust liquid viscous effect[48] compared with the other three target
346 substrates during the solid-liquid interaction process. In addition, the comparative analysis indicated
347 that the droplet spreading was strongly suppressed at the liquid-petal interface, and the excess
348 restoring force (reflected in the viscosity of the droplets) was transformed into the surface energy of
349 the irregular twisting droplet ($t = 7.5$ ms in Fig. 7a). The irregular droplet twist caused the surface
350 energy to be consumed by both the viscosity of the droplet and the partial pinning effect of the petals
351 based on the energy conservation argument, eventually leading to droplet adhesion. Conversely, the
352 spreading and retraction of the droplets were maximized because the SHS exhibited the lowest contact
353 angle hysteresis among all selected substrates[2,3]. Analysis of the contact line showed that this twist
354 was relatively stable, while the other three selected substrates exhibited larger fluctuations.



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Fig. 8 Transient contact diameter of the droplet impacting the four substrates at **(a)** $We_c=4$ and **(b)** $We_c=50$. The difference was not significant under the low Weber number regimen. Nevertheless, the substrate configuration dominated the droplet topography at $We_c=50$. **(c)** Comparative analysis of the horizontal flatness factor, ζ_h , under moderate ($We_c=27$) and high ($We_c=50$) Weber numbers. The lateral droplet response was consistent in the latter case. **(d)** Comparative analysis of the vertical flatness factor, ζ_v , under moderate ($We_c=27$) and high ($We_c=50$) Weber numbers. Unexpectedly, the high-impact velocity of a droplet led to a lower amplitude.

Attenuation of the droplet oscillation is similar to the underdamped harmonic oscillator, which has the characteristics of a vibration system composed of a spring, damping, and mass with a certain degree of freedom[33]. To quantify this oscillation, the oscillation frequencies were analyzed in the horizontal ($f_h=1/T_h=\omega_h/2\pi$) and vertical ($f_v=1/T_v=\omega_v/2\pi$) directions using the fast Fourier transform

367 algorithm[50,51] in MATLAB. Under the high Weber numbers, the droplet oscillation frequency was
368 lower than that under the moderate-impact velocity condition, where $f_{h50} = 80 \text{ Hz} < f_{h27} = 93 \text{ Hz}$ and
369 $f_{v50} = 76 \text{ Hz} < f_{v27} = 90 \text{ Hz}$ (the frequency of a free-oscillating droplet: $f=109 \text{ Hz}$ [52]). Thus, the
370 lower frequency and smaller amplitude of the droplet oscillations reveal that more energy is
371 dissipated by the viscous force at high-impact velocities. Additionally, mutations in the degree of
372 freedom of the droplet-spring system due to pinning/depinning can severely inhibit lateral but not
373 vertical droplet oscillations during the retraction process; thus, the lower part of the droplet will again
374 collide with the petal, causing multiple surface energy dissipation as demonstrated in Fig. 7.
375 Artificial SSHSs (e.g., SSHS-1, SSHS-2) are more isotropic with respect to the rose petals but can
376 also become more "hydrophilic" under high Weber numbers. In addition, the underdamped harmonic
377 oscillator, especially in the horizontal direction (Fig. 8a), are highly efficient on the RPS. The
378 pinning effect of the high regimen experienced random oscillation in an underdamped manner on the
379 rose petals. The flatness factor, $\zeta_h = D_h/D_0$, and the dimensionless vertical dimension of the droplet, ζ_v
380 $= D_v/D_0$, were defined to investigate the degree of oscillation. Furthermore, we analyzed the
381 oscillation phenomenon of the depositional droplet under moderate ($W_e = 27$) and high ($W_e = 50$)
382 Weber numbers as denoted in Fig. 8, resulting in greater damping and droplet stiffness at $W_e = 50$. The
383 increased velocity appeared to attenuate the oscillation amplitude faster than did the collision of a
384 lower velocity droplet on the same petal, indicating a higher effective damping coefficient.

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386 4. Conclusions

387 There seems to be no consensus on the static petal effects[22–24,26] and a large amount of the
388 previous studies have mainly focused on the wettability of superhydrophobic
389 surfaces[15–21,42]. These all determine that the dynamic petal effects are still far from being fully
390 understood yet. We systematically investigated the impact dynamics of droplets on the interfaces of
391 rose petals, imitation rose petals and SHS. Spherical droplet retention is attributed to the
392 sophisticated energy-consuming system at the droplet-petal interface—the ingenious combination of
393 a sticky superhydrophobic texture and an irregular texture. The pinning effect significantly modified
394 the droplets' dynamic wettability. The sticky superhydrophobic surface is a type of superhydrophobic

395 surface with various defects; thus, the above combination effect should be avoided when designing
396 water-repellent surfaces. As we mentioned, the roses may reveal more "hydrophilic" at heavier
397 precipitation. These findings may offer possibilities for designing high-efficiency energy conversion
398 and harvesting[9,10,27].

399 **Conflicts of interest**

400 There are no conflicts of interest to declare.

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407 **Author contributions**

408 C.Z. and Y.Z. conceived the study. Y.Z. and J.W. performed the experiments. J.Y., C.S. and Y.L.
409 performed the simulations. Y.Z. wrote the paper. All the authors analyzed the data, proofread the
410 paper, made comments.

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Robust adhesion of droplets via heterogeneous dynamic petal effects

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Abstract

Hypothesis

Bionics and dynamic interface wetting intensely appeal to many research communities due to their unique practical implications. The rose petals had a highly robust dynamic water-retaining capacity under heavy precipitation. We predicted that the roses became more "hydrophilic" at higher Weber numbers.

Experiments

Fresh rose petals were directly impacted by droplets, and facile artificial petal-like substrates and superhydrophobic substrates were used in the comparative analysis. The wetting dynamics of the droplet (e.g., topography, bounce dynamics, contact time, three-phase contact lines, and oscillations) were investigated when interacting with four selected target substrates.

Findings

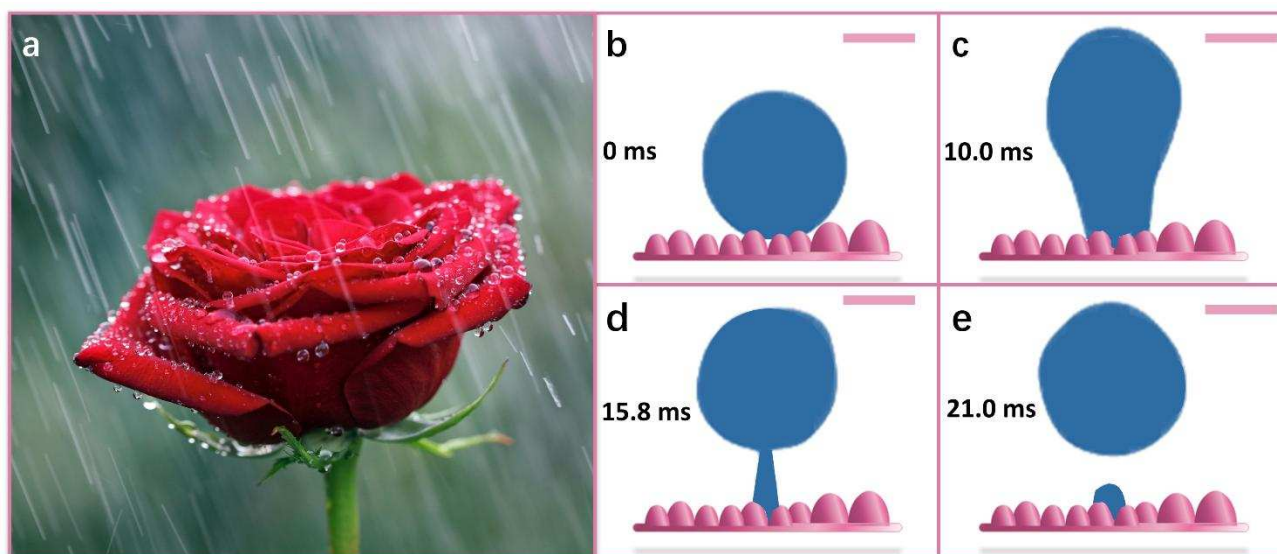
The present work first time investigated the dynamic wetting rule of the sticky superhydrophobic substrates (SSHS). Simulated and experimental investigations confirmed that the unique coupling synergy between the pinning effect and the inhomogeneous micropapillae resulted in lopsided contact line velocities, which remarkably suppressed the lateral oscillation and rebounding. This may be a new strategy when designing dynamic water-repellent surfaces and open a promising avenue for emerging areas such as super-efficiency energy conversion and harvesting.

28 **Keywords:** dynamic petal effect, droplet impact, asymmetric wetting, sticky superhydrophobic

29 **1. Introduction**

30 Rain droplets on lotus leaves may be less striking than rain droplets on rose petals. Water droplets
31 can attach to rose petals without rolling off, even at great tilt angles. However, water droplets cannot
32 remain on lotus leaves after a rain. The “lotus effect” is synonymous with superhydrophobicity, and a
33 superhydrophobic surface(SHS) exhibits a static apparent contact angle (CA, θ) of greater than 150°
34 with a very low contact angle hysteresis (CAH, θ_{CAH})[1–4]. Interestingly, rose petals can exhibit an
35 extremely high CA similar to that of the “lotus effect”, but with high CAH (Fig. 1a)[5]. This "sticky
36 superhydrophobic" substrate (SSHS) phenomenon known as the "petal effect" was first proposed by
37 Jiang et al.[6] and has since drawn much research attention due to its widespread use in emerging fields
38 such as self-cleaning[7], droplet transfer, transportation[8], biochemical separation, and energy
39 harvesting[9,10]. In addition, studying the dynamic wetting mechanism of an SSHS provides
40 information for enhancing functional surface designs.

41



42 Fig. 1 Dynamic wetting phenomenon on rose petals. (a) Retention of spherelike droplets on rose
43 petals in the rain. (b-e) Schematic diagram of the interfacial process of a droplet impacting a rose petal
44 at low-impact velocities. The scale bar=1 mm.

45 Generally, the static-wetting state of rough surfaces can be explained by the classical wetting
46 theory of Cassie-Baxter[11] and Wenzel[12]. In the Cassie-Baxter model, the rough solid surface is
47 completely filled with liquid, resulting in high water adhesion. However, entrapped air is observed in

48 the Wenzel model, which is attributed to hydrophobicity[13]. The superhydrophobicity exhibited on
49 the lotus leaf results from the combination of convex epidermal cells and extremely low-density
50 biowax layers[14]. The lotus effect should be governed by the idealized Cassie-Baxter model. For the
51 lotus effect, research on fabricating and characterizing biomimetic surfaces is trending, both
52 theoretically and experimentally[15–21]. In contrast, few in-depth studies have examined the petal
53 effect; thus, the accurate mechanism of the petal effect wetting behavior remains unclear[22].
54 Nonetheless, the Cassie-Baxter and Wenzel models are used by most scientists to explain wettability at
55 the interface. Adhesion of water droplets to rose petals has been attributed to the Wenzel state based on
56 the geometric parameters of the rose petal surface determined for both biological and artificial samples.
57 These parameters include the diameter, spacing and secondary nanostructure of the
58 micropapillae[23](Fig. 1 b-e). In contrast, the opposite conclusion has also been suggested, in that the
59 petal’s microstructure is considered to benefit adhesion, but this conclusion cannot be explained by the
60 classic Cassie-Baxter wetting theory[24]. Thus, the rose petal wetting mechanism seems puzzling. S.
61 Yang et al.[25] observed that the interaction between droplets and rose petals was completely in
62 accordance with the Wenzel state, and these authors found no air cushion using micro computed
63 tomography. Visualization technology has been developed, which has facilitated analyzing this
64 mechanism. Optical microscopy observations using micron-scale resolution have recently shown that
65 the wetting behavior of droplets on rose petals is unstable because gas moves slowly from the space
66 over the liquid, thus altering the wetting state. This is a mutual transformation from the Cassie and
67 Wenzel states[26]. This contradictory conclusion was likely reached because dynamic observations
68 were applied to the latter; that is, the movable air cushion disappeared after connecting to the
69 atmosphere, resulting in continuous wetting at the three-phase contact line (TCL).

70 Thus, the static-wetting mechanism of the petal effect remains unclear, and determining its
71 precise dynamic wetting process is challenging. Experiments and simulations in which droplets
72 impact the substrate have long been used to investigate the dynamic wettability of natural, artificial
73 and chemically heterogeneous surfaces[27]. To our knowledge, previous investigations of the
74 substrate’s configuration after being impacted by the droplet mainly included liquid film[28],
75 superhydrophilicity[29], hydrophobicity[30], superhydrophobicity[31], elastic

76 superhydrophobicity[32,33], and vibrating superhydrophobicity[34]; however, no reports regarding
77 droplet impact on SSH surfaces (the petal effect) have been published. Li et al.[35] reported the
78 dynamic wetting characteristics of water droplets on various substrate configurations at CA = 160°,
79 154°, 153°, 122°, 124°, and 119°. Shen et al.[36] verified that a relationship exists between the
80 trapped air and the interface adhesion when a droplet impacts a sticky hydrophobic substrate. In the
81 two aforementioned studies, the droplets were released from the same height as that impacting the
82 substrate, which was insufficient to summarize the rules of dynamic wetting on sticky
83 superhydrophobic surfaces.

84 This paper describes the dynamic wetting rule on a SSHS (i.e., the petal effect) by comparing
85 the wetting state on a superhydrophobic surface. The quantitative (experiments) and qualitative
86 (simulations) investigation confirm that the dynamic unbalance wetting mechanism of the petal effect
87 is due to the coupling of the lateral interaction of the droplets with the pinning effect, thus providing
88 novel insights into why rose petals can retain water droplets and new rational guidelines for wetting
89 functional surface design.

90 **2. Experimental materials and methods**

91 **2.1 Surface fabrication and characterization**

92 To capture the commonality of droplet dynamics on the SSHS, three target substrates were
93 fabricated, including the rose petal surface (RPS) and engineering sticky superhydrophobic surfaces
94 (SSHS-1 and SSHS-2). Besides, the superhydrophobic surface (SHS) is used for comparative
95 verification.

96 **2.1.1 Rose petal surface (RPS)**

97 A fresh red rose was purchased from a flower market (Changchun, China), and a piece of the
98 rose petal (15 mm × 1.5 mm) was fixed to a glass sheet which was neither cleaned nor altered.

99 **2.1.2 Sticky superhydrophobic surface (SSHS)**

100 We replicated the surface (SSHS-1) invented by Chen et al.[37], with some modifications to the
101 chemical reactions. One-millimeter-thick zinc foil was ultrasonically cleaned in acetone and
102 deionized water. The zinc foil was etched in hydrochloric acid for 15 seconds, then washed
103 thoroughly in deionized water. Next, the zinc foil was etched in hydrochloric acid for 15 s, then

104 immersed in 0.01 mol/L $\text{CuSO}_4 \cdot \text{H}_2\text{O}$ for 12 minutes, thoroughly washed again in deionized water,
105 and immersed in 0.005 mol/L $\text{CH}_3(\text{CH}_2)_{16}\text{COOH}$ for 30 minutes. We also established a micron-scale
106 with arrays on paraffin with low surface energies (SSHS-2) for comparison. (S1.2, Supplementary
107 Information).

108 **2.1.3 Superhydrophobic surface (SHS)**

109 The 2-mm-thick square copper plate was etched in hydrochloric and sanding with sandpaper then
110 treated with 1H,1H,2H,2H-perfluorodecyl trichlorosilane (Aladdin, Inc., China) via chemical vapour
111 deposition.

112 **2.1.4 Surface characterization**

113 All characterization tests were performed indoors at 25°C. The surface morphology was
114 characterized by scanning electron microscopy (SEM; EVO MA 25/LS, ZEISS, Inc., Germany) with
115 20-kV accelerating voltage and a three-position ultra-depth microscope (Smartzoom 5, ZEISS, Inc.,
116 Germany). The apparent contact angles were measured using a contact angle meter (DSA 22 KRUSS,
117 Germany), wherein the water droplet volume was 4 μL .

118 **2.1.5 Experimental apparatus and image analysis**

119 To analyze the dynamic wetting behavior of the droplets, an experimental system was
120 established to observe and record the droplet impacting the substrate (Fig. S1 in Supplementary
121 Information). This system generates the water droplets (2.14 ± 0.01 mm) using a 0.24-mm metal
122 needle and a syringe driven by a microstepping motor. Using another microstepper motor, the
123 droplet-to-substrate distance (H) can be varied, resulting in speeds of $v=0.308\text{--}1.128$ m/s. The
124 resulting corresponding dimensionless numbers are the Weber number $W_e = \rho v^2 D_0 / \gamma = 4\text{--}50$, capillary
125 number $C_a = \mu v / \gamma = (4\text{--}16) \times 10^{-3}$, Reynolds number $Re = \rho v D_0 / \mu = 866\text{--}3120$, and Ohnesorge number
126 $Oh = \mu / (\rho \gamma D_0)^{1/2} = 2 \times 10^{-3}$, with a density of $\rho = 997$ $\text{Kg} \cdot \text{m}^{-3}$, surface tension of $\gamma = 72 \times 10^{-3}$ N/m, and
127 dynamic viscosity of $\mu = 0.89 \times 10^{-3}$ Pa·s, which are the water's physical parameters.

128 **2.1.6 Simulations**

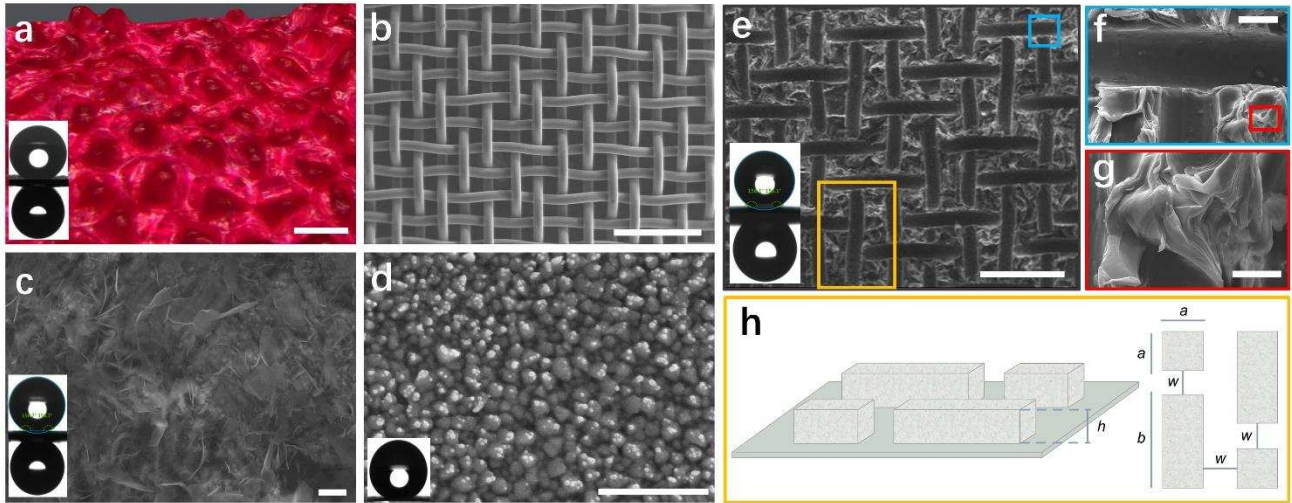
129 Qualitative simulation analysis was performed via the lattice Boltzmann method (the D3Q9 grid)
130 [38,39].

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132 3. Results and discussion

133 3.1 Morphology and wettability of the target substrates

134 Fig. 2 illustrates the morphology and adhesive states of the selected substrates (RPS, SSHS-1,
135 SSHS-2 and SHS). The RPS could be visually characterized by a three-position ultra-depth
136 microscope at 1000 \times magnification (Fig. 2a). The irregular array consisted of micropapillae
137 averaging 9 ± 2 μm high and 19 ± 2 μm in diameter (similar to previous studies[6,40]), which were
138 semiautomatically obtained from the written code in MATLAB and the open-source software ImageJ
139 by analyzing the selected images. The inset plots in Fig. 2a illustrate that the CA of the RPS was 154°
140 $\pm 2^\circ$, and a 4- μL droplet could adhere to the surface with a tilt angle of 180° . Similar wetting states
141 also occur on sticky superhydrophobic zinc foils fabricated by chemical etching. The insets in Fig. 2c
142 show that the CA of the SSHS-1 is $157^\circ\pm 2^\circ$, and it exhibited high adhesion. Fig. 2d shows the SHS
143 with $\text{CA}=153^\circ\pm 2^\circ$ and $\theta_{\text{CAH}}=3^\circ\pm 1^\circ$, indicating a typical lotus effect phenomenon, which is consistent
144 with previous studies[41,42].The microstructures in Fig. 2e–g are SSHS-2, which are manufactured
145 by rapidly peeling off the copper mesh that was tightly attached to the solidified paraffin and the
146 colored box indicates the corresponding selected area. The inset plot in Fig. 2e likewise shows a
147 similar petal effect phenomenon, indicating $\text{CA}=156^\circ\pm 2^\circ$ with a large adhesive force. We established
148 a diagrammatic sketch of a typical SSHS-2 microstructure (Fig. 2h), in which the corresponding
149 statistical geometric parameters of the typical microstructures were short-side length: $a=85\pm 2$ μm ,
150 long-side length: $b=220\pm 2$ μm , width: $w=50\pm 2$ μm , and height: $h=50\pm 2$ μm .



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Fig. 2 Characterization of the static wettabilities of (a) RPS, (b) 200-mesh copper mesh, (c) SSHS-1, (d) SHS and (e–h) SSHS-2. (a) Image of a fresh rose petal captured by a 3D super depth-of-field microscope at 1000 \times magnification (scale bar=25 μ m). The darker red indicates the top of the mastoid, while the relatively low area is shown in light red. The RPS exhibited a petal effect phenomenon with $CA=154^{\circ}\pm 2^{\circ}$ and high adhesion, as illustrated in the insets. (b) SEM image of the 200-mesh copper mesh (scale bar=500 μ m). (c) SEM image of SSHS-1 (scale bar=4 μ m). The insets indicate that the $CA=156^{\circ}\pm 2^{\circ}$ with the high adhesive phenomenon. (d) SEM image of a superhydrophobic surface with $CA=153^{\circ}\pm 2^{\circ}$ (see inset). The scale bar=500 nm. (e) Regular array of paraffin cubes with the same spacing and height. The insets indicate that $CA=157^{\circ}\pm 2^{\circ}$ with markedly high adhesive behavior (scale bar=300 μ m). (f) T-shaped paraffin microstructure (blue boxes). Compared with the top of the raised paraffin square column, the trace of the single copper wire was almost smooth at the same magnification factor. (scale bar=40 μ m) (g) The top of the raised paraffin square column is shown in red boxes. (h) Schematic diagram of a typical microstructure model (orange boxes). The microstructure dimensional parameters were $a=85\pm 2$ μ m, $b=220\pm 2$ μ m, $w=50\pm 2$ μ m, and $h=50\pm 2$ μ m (scale bar =20 μ m).

3.2 Qualitative and quantitative analysis of Non-uniform lateral interaction on the SSHS

Simulations are performed to qualitatively explain the effect of the unbalanced Young's force dF_t on the wettability of the interface. The micropapillae and droplets are of the same order of magnitude to facilitate intuitive analysis (Fig. 3a). Two-phase fluid dynamics equations are solved

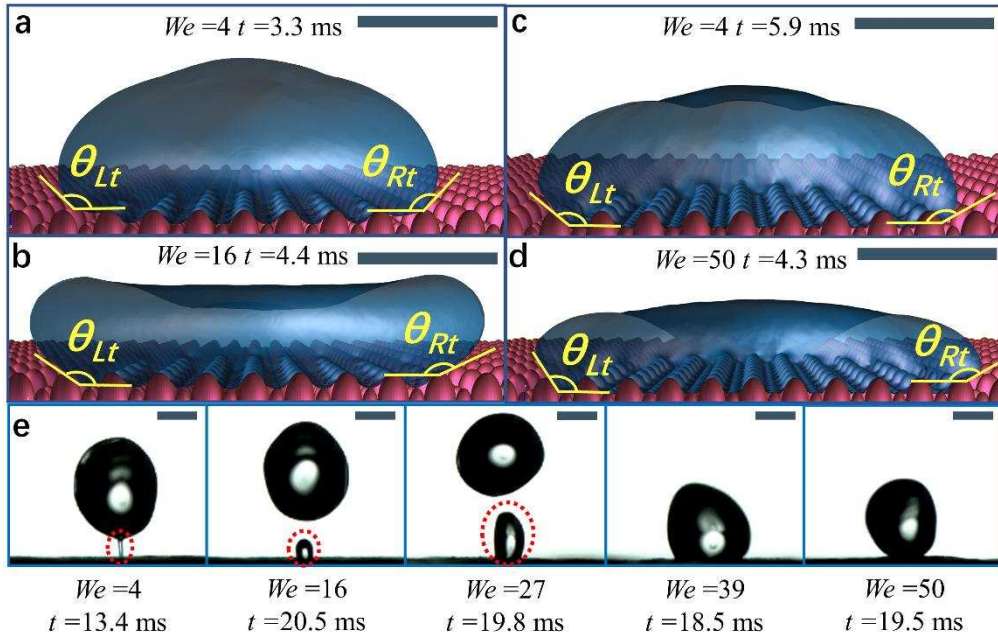
171 using the D3Q19 grid based on a lattice Boltzmann algorithm[38,39]. The micropapillae of the RPS
 172 are arranged in regular arrays during a simulation. In addition, the larger micropapillae (height =0.4
 173 mm with diameter =0.4 mm) are configured with a CA of 150° to counteract the superhydrophobicity,
 174 whereas the CA of the secondary micropapillae (height =0.2 mm with diameter =0.2 mm) is
 175 configured for 110°. The high-impact velocity droplets oscillated randomly and finally adhered to the
 176 rose petals; otherwise, the droplets have bounced at a low-impact speed. The droplets tend to adhere
 177 to the petals with the increasing Weber numbers, as reflected in the residual droplets (red dotted
 178 circle in Fig. 3e). The additional viscous dissipation during the droplet-petal interaction in the high
 179 Weber number state is attributed to cooperation between the irregular morphology[43]
 180 (micropapillae, Fig. 2a) and the sticky superhydrophobicity of the rose petals. Anomalous droplet
 181 formation was initialized during the spreading phase; however, the asymmetrical speed of the
 182 moving contact line was evident in the receding phase from a two-dimensional perspective in the
 183 schematic (Fig. 3 a-d). The lateral rebounding of a droplet can be manipulated because of the uneven
 184 gradient on the textured surface[44] and the unbalanced Young's force expressed as

$$185 \quad dF = \sigma |\cos \theta_{Rt} - \cos \theta_{Lt}| ds, \quad (1)$$

186 where $\cos \theta_{Rt}$ and $\cos \theta_{Lt}$ are the apparent contact angles of the right and left sides(Fig. 3 a-d),
 187 respectively, which were evaluated instantaneously by image analysis. d_s is the differential of the
 188 moving contact line, and dF is the transient unbalanced Young's force, which resists the inertia of the
 189 droplet. Thus, as $|\cos \theta_{Rt} - \cos \theta_{Lt}|$ increases (the droplet is more distorted), F_t also increases,
 190 resulting in a more "hydrophilic" substrate, which is consistent with that shown in Fig. 3e. Here, the
 191 effective unbalanced Young's force (F_e) can be simplified as

$$192 \quad \Delta \propto |\cos \theta_{Rt} - \cos \theta_{Lt}| \propto \frac{1}{5} (\lg |\theta_{Rt} - \theta_{Lt}|) \quad (2)$$

193 via analyzing the simulations. Δ contains a constant $\frac{1}{5}$, so that Δ is in the same order of
 194 magnitude as the quantitative result, which is advantageous for comparison verification.



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196 Fig. 3 Simulated and experimental analysis and verification of the unbalanced Young's force
 197 caused by the SSHS. (a)-(d) Simulation analysis of droplets are observed to be in the most laterally
 198 unbalanced. Unbalanced droplet morphology due to irregular micropapillae in the receding phase.
 199 Consequently, the Young's force increases, causing additional energy dissipation. The results of the
 200 simulation show that the difference between $\cos\theta_{Lt}$ and $\cos\theta_{Rt}$ is more significant as the Weber
 201 number increases, so higher F_e eventually lead to droplets adhesion. The scale bar= 1.8 mm. (e) The
 202 quantitative similarity of various morphologies of ping-pong tiny droplets (red dotted circle) on a rose
 203 petal as the Weber number increased. The rose petals became more "hydrophilic". The scale bar= 1
 204 mm.

205 However, the aforementioned effective unbalanced Young's force F_e is transient and difficult to
 206 quantify via experiments. Thus, the dimensionless size of the residual droplets, $\lambda = D_r / D_0$, is used
 207 to investigate the extent of the dynamic petal effect due to the intuitive result of the dynamic petal
 208 effect is reflected in the residual moisture on the RPS, as shown in Fig. 3e. These retained liquids on
 209 the RPS are essentially caused by varying degrees of the Cassie-to-Wenzel transition[11,12] which
 210 can be regarded as the partial wetting state. This partial wetting state is mainly governed by the
 211 effective water hammer pressure verified by Tao et al[45],

$$212 \quad P_{EWH} = k\rho C v, \quad (3)$$

213 where C is the speed of sound in water, and k is the fitting parameter of the corresponding
 214 experiment. Herein, $v \propto We^{0.5}$ and then $P_{EWH} \propto \alpha We^{0.5}$, where $\alpha = k\rho C$. In this case, we assumed
 215 that that dF_t is in a two-dimensional environment, thus dF_t and λ are in the same dimension and
 216 related. Together with Eq. (1-3), the quantitative estimation of dynamic petal effect of RPS would
 217 yield $dF_t \propto (\zeta = \alpha We^{\beta\lambda}) \propto \Delta \propto \alpha We^\gamma$. Thereby,

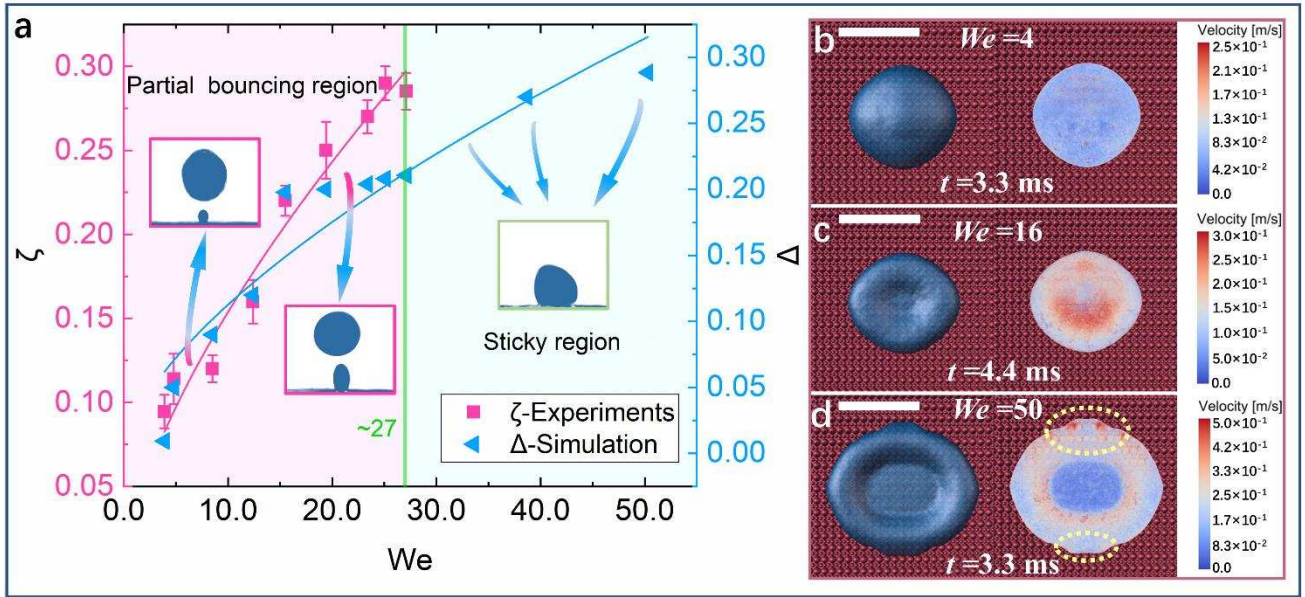
$$218 \quad \zeta = 0.0366 \left(\frac{\rho v^2 D_0}{\gamma} \right)^{0.633}, \quad (3)$$

219 where $4 < We_e = \frac{\rho v^2 D_0}{\gamma} < 27$. Eq. (3) are satisfied in our experiments (Fig. 3e and Fig. 4a): the
 220 dynamic water-repellency of the SSHS is only closely related to the impact velocity of the droplets
 221 (v). The limit ($We_e < 4$) was considered as the inconspicuous dynamic petal effect regime, while the
 222 critical total wetting state occurs when $We_e > 27$. Furthermore, the simulation results (Fig. 3 a-d and Fig.
 223 4b-d) qualitatively reveal the adhesion water caused by the lateral effect of the droplets of the SSHS
 224 in this study. Thus, the aforementioned effective unbalanced Young's force F_t would yield

$$225 \quad \Delta = 0.0259 \left(\frac{\rho v^2 D_0}{\gamma} \right)^{0.638}. \quad (4)$$

226 Herein, $4 < We_e = \frac{\rho v^2 D_0}{\gamma} < 50$. The results of the simulation (the blue line in Fig. 4a)
 227 satisfactorily confirm the positive effect of the lateral effect on droplet adhesion. The RPS—with its
 228 unique asymmetric natural sticky superhydrophobic, resulting in solid edges with discontinuous
 229 physical properties (e.g. wettability) that directly affect the receding speed of the three-phase contact
 230 line, which is striking at higher at high Weber numbers. As shown in yellow dotted circles in Fig. 4d,
 231 significant asymmetric receding line velocities and morphology are observed on both sides of the
 232 droplet, in contrast, symmetrical edge velocities occur at low Weber numbers (Fig. 4 b-c).
 233 Qualitatively, the synergy of the multiple lateral asymmetric effects and sticky will make the SSHS
 234 more sticky and "hydrophilic" at high droplet impinging velocities regime (see the insets in Fig. 4).

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Fig. 4 Quantitative and qualitative comparisons of the effects of multiple lateral pinning on the RPS's wetting characteristics. (a) Investigations of the correlation between lateral effects and sticky adhesion on the SSHS. The insets show the extent of the dynamic petal effect, from pinning tiny droplets (partial rebound, lilac region) to no bouncing sticky region (light green area) as the Weber number increases. Satisfactory qualitative similarities are revealed in experimental and numerical results (purple and blue fitted line). The critical of the partial bouncing region and sticky region is $We = 27$ (green line). (b)-(d) The simulated velocity field as the droplets develop to their most asymmetrical morphology. Axisymmetric droplet morphology occurs under the low Weber number regime ($We = 4$), but note that the higher impinging velocities (corresponding to $We = 50$) result in remarkable unbalanced receding velocities (yellow dotted circle). Both versions of the investigation confirmed the same characteristic that asymmetric interactions caused by high weber number reduce the possibility of droplet bouncing. The scale bar=4 mm.

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3.3 Droplet bounce dynamics

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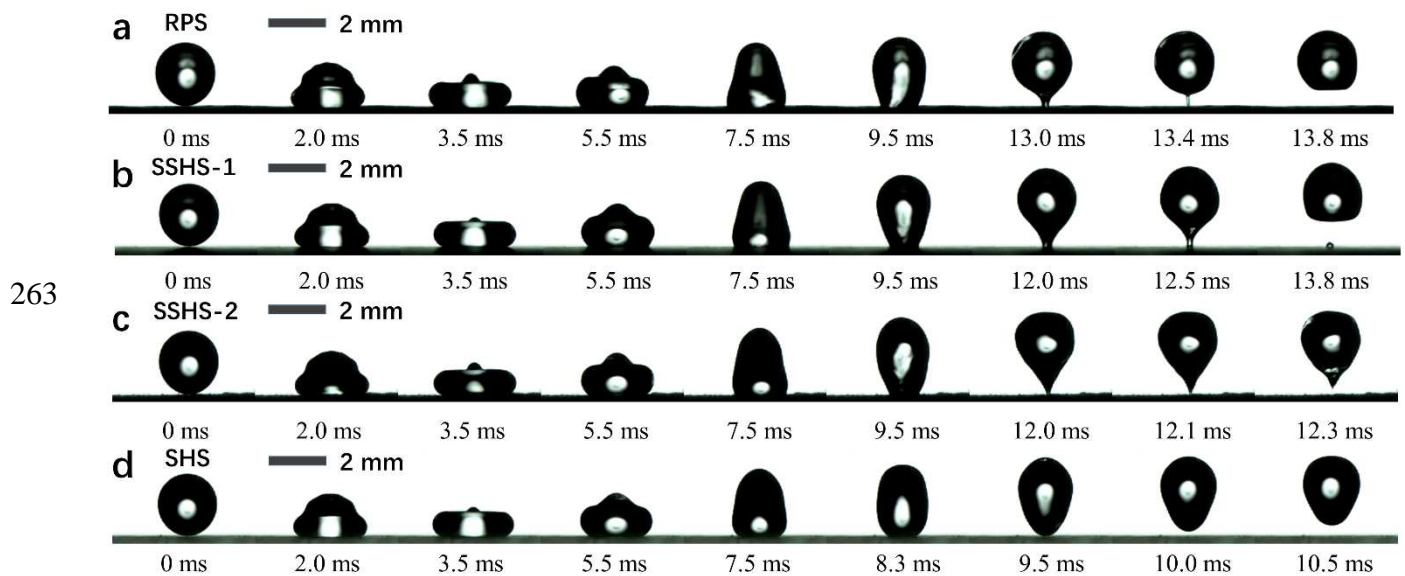
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In order to verify the above-mentioned theory, three SSHSs (the RPS, SSHS-1 and SSHS-2) and a SHS were selected as the target substrates. When a droplet hits a rough solid surface, it may bounce or stick, after undergoing the spreading and receding stages. The interfacial behavior of the droplets corresponds to the hydrophobicity (e.g., CA and CAH) of the substrate and is significantly affected by the wettability (e.g., high adhesion) of the interface[27]. We examined the droplet impact on the four

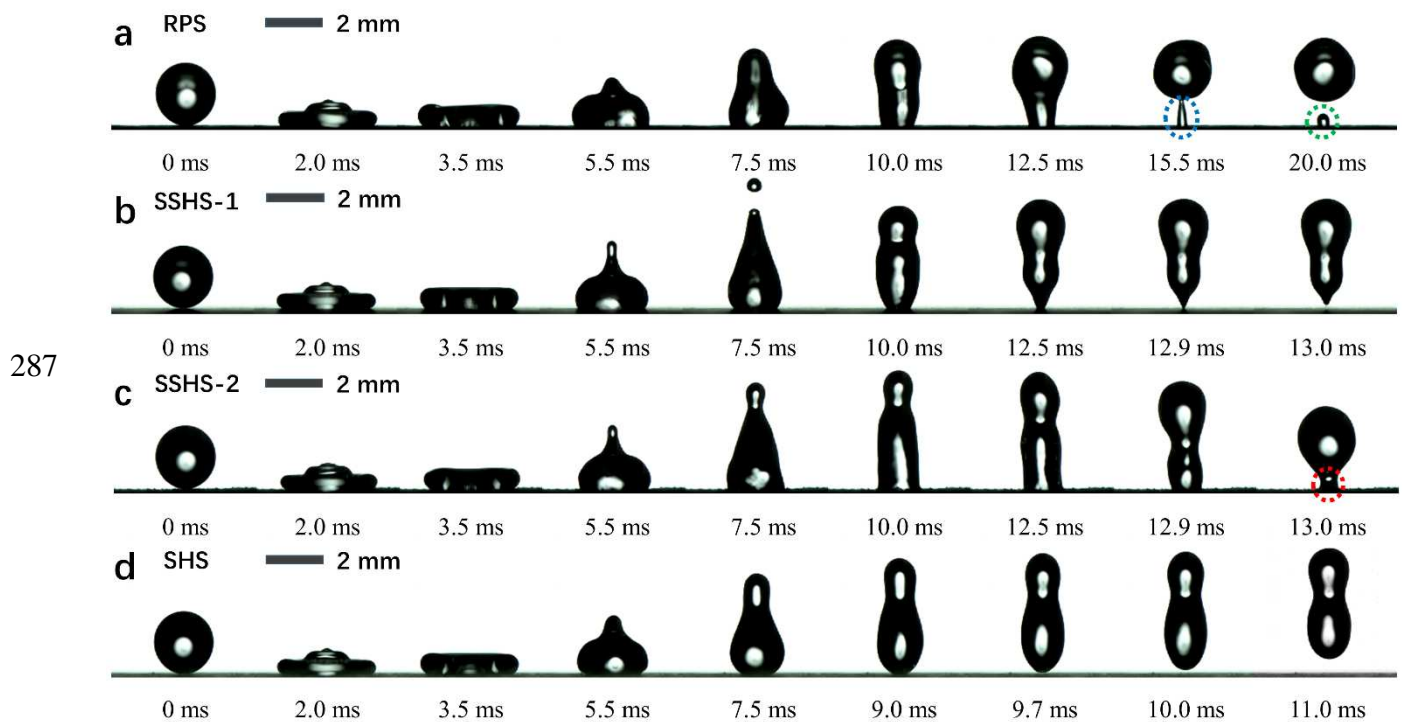
254 aforementioned surfaces. For droplets, the low-impact velocity resulted in a low kinetic energy level.
 255 Fig. 5 illustrates the dynamic wetting process of the droplets on RPS, SSHS-1, SSHS-2 and SHS at a
 256 very low Weber number ($W_e=4$, corresponding to $v=0.362\pm 0.001$ m/s; see also Supplementary Movie
 257 S1). Droplets with sufficient kinetic energy can generally bounce off sticky superhydrophobic
 258 substrates at a very low Weber number, $W_e=4$ (Fig. 5 a–c). Partial pinning occurred at the bottom of
 259 the droplet resulting in a slightly longer contact time than that on the SHS (see S3 in Supplementary
 260 Information for more details). The bounce of the drop was partially inhibited when the droplet
 261 impacted the sticky superhydrophobic substrate compared with that on the superhydrophobic
 262 substrate under the corresponding impacting velocity.



264 Fig. 5 Snapshots of the droplets' dynamic behavior on RPS, SSHS-1, SSHS-2 and SHS ($W_e=4$,
 265 corresponding to $v=0.362\pm 0.001$ m/s). (a–c) Time evolution of an impacting droplet on RPS, SSHS-1,
 266 SSHS-2, respectively. The droplet morphology becomes asymmetrical during the receding phase.
 267 Droplets can still rebound, but the substrates exhibit some viscosity. (d) Impact phase diagram of a
 268 droplet impacting the SHS. The droplet lifts off the substrate with less contact time and remains more
 269 symmetric compared with that on the aforementioned substrates. Supplementary Movie S1 provides
 270 more details. The scale bar=2 mm.

271 As the Weber number increases slightly ($W_e=16$, corresponding to $v=0.723\pm 0.001$ m/s), the
 272 SSHS plays a more vital role in the droplets' dynamic behavior than does the SSH. Detaching the

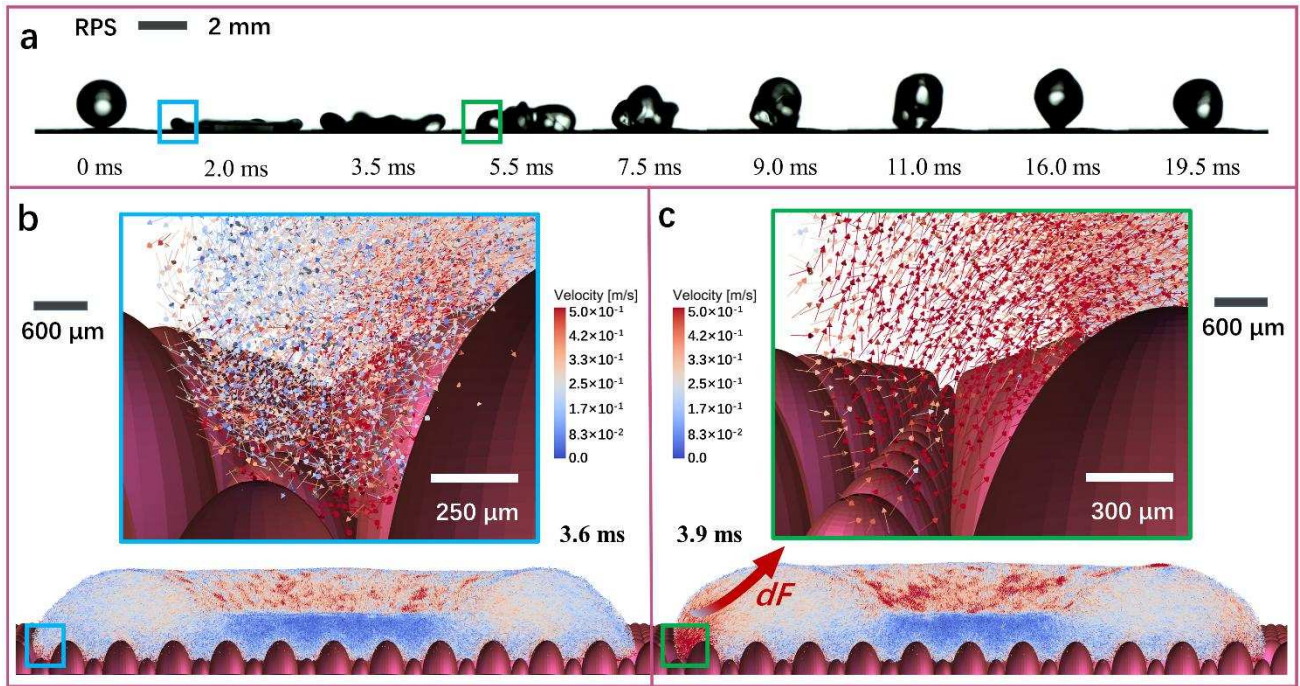
273 droplet from the SSHS was more difficult and differed greatly from its interaction on the SHS (Fig. 6;
 274 Supplementary Movie S2). The droplet morphology on all target substrates was almost synchronous
 275 during the spreading phase ($0 \text{ ms} < t < 3.5 \text{ ms}$) and was independent of the target substrate's
 276 wettability and impact velocity, which is consistent with previous studies[33,36,46]. For the RPS, the
 277 geometric center of the droplet changed and gradually moved away from the axis of symmetry,
 278 indicating more sensitivity to the impact velocity of the droplet after 3.5 ms than at the We of 4 (Fig.
 279 5 a and Fig. 6a). Thus, the droplet exhibited difficulty in rebounding completely, even with a higher
 280 initial kinetic energy, as illustrated by the residual secondary droplets on the sticky substrate (blue
 281 and green dotted circles in Fig. 6a, see also S4 in Supplementary Information). Interestingly, similar
 282 wetting phenomena were observed on both SSHS-1 and SSHS-2 (Fig. 6b–c). One droplet was
 283 difficult to lift off and was even pinned to the substrate (red dotted circle in Fig. 6c). Instead, the
 284 droplet lifted off from the SHS quickly after undergoing a spreading and retracting phase similar to
 285 that of the above corresponding testing condition. We confirmed that the dynamic response of the
 286 droplets is critical to wetting the SSHS interface during the receding phase when $4 \leq We \leq 16$.



288 Fig. 6 Sequential snapshots of the droplets' dynamic behaviors on the RPS, SSHS-1, SSHS-2 and
 289 SHS ($We=16$, corresponding to $v=0.723\pm 0.001 \text{ m/s}$). (a) Impact phase diagram of a droplet impacting
 290 the RPS. Note that this droplet was observed to be extremely asymmetric at $t=5.5 \text{ ms}$. During the

291 rebound phase, the liquid bridge (blue circle) is captured between the ejecting droplet and the
292 substrate. A residual secondary droplet is shown in the green circle. **(b)** Drop impacting the SSHS-1
293 with a tiny droplet ejecting at $t=7.5$ ms. **(c)** A droplet is completely trapped on the SSHS-2. A larger
294 liquid bridge is observed at the interface and is circled in red. **(d)** Sequential phase diagram of a
295 droplet impacting the SHS. Almost no adhesion was observed (Supplementary Movie S2). The scale
296 bar=4 mm.

297 Interestingly, as we predicted, the spreading phase of the droplets was also affected by the
298 substrate configuration, such as in the receding phase when the impact velocity was high ($We=50$,
299 corresponding to $v=1.304\pm 0.001$ m/s), which appears to be inconsistent with previous studies. In the
300 present study, the surface tension and viscosity of the water were constant and were factors that
301 inhibited the droplet from receding[47]. Fig. 7 shows the dynamic process of the droplet impacting
302 the RPS and SSHS-2 (Supplementary Movie S3). The droplet morphology is extremely
303 asynchronized during the spreading phase after $t=2$ ms. In addition, the droplet showed a maximum
304 twist compared with all previous test conditions and exhibited a surprisingly dF and could not to lift
305 off the substrate (Fig. 7a). Previously, we confirmed that droplets are more likely to adhere at high
306 Weber numbers, but did not qualitatively clarify the droplets' reciprocating oscillation on the RPS.
307 Once the de-pinning effect is initialized (red box in Fig. 7a), the de-pinning force for the moment,
308 including the inward and upward forces, will be activated (green box in Fig. 7a). The mechanism of the
309 corresponding state can be qualitatively explained by the blue box in Fig. 7b and the green box in Fig.
310 7c, respectively. Note that dF, with both upward and inward vectors, drives the leftmost liquid to hit
311 those adjacent portions with lower receding velocities, instead, the de-pinning does not occur on the
312 rightmost, thus the droplet exhibits unbalanced and eventually cause reciprocating oscillation of a
313 droplet on a rose petal. The free liquid-gas interface adjacent to the petal is pinned again, causing
314 multiple viscous energy dissipation, and the petal eventually becomes more "hydrophilic".



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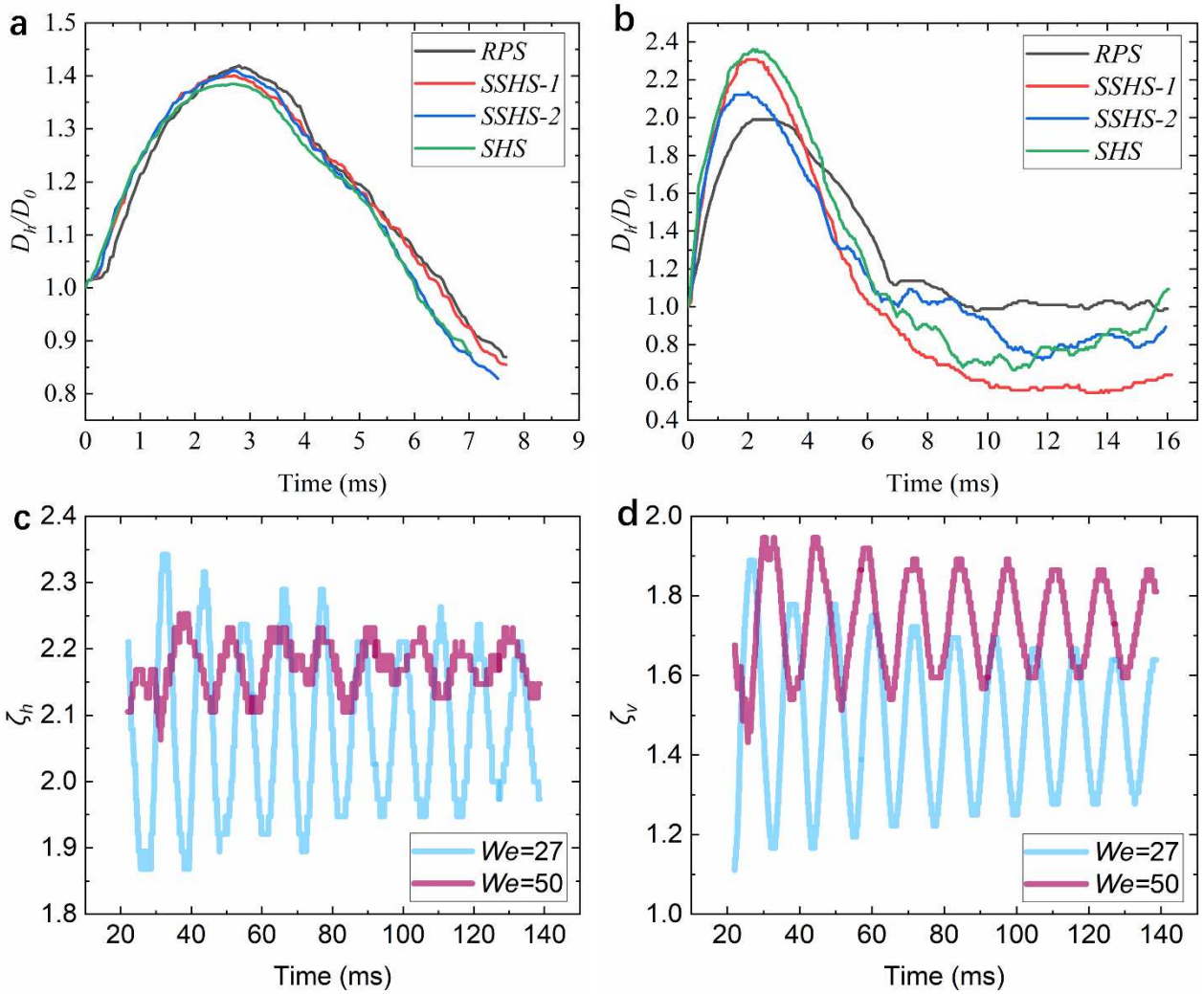
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Fig. 7 Impact of droplets on the RPS at high velocities ($We=50$, corresponding to $v=1.304 \pm 0.001$ m/s). (a) A droplet impacts the RPS, exhibiting a sharp anisotropic vibration that prevents it from bouncing off the substrate. As we predicted, the non-negligible unbalanced Young's force increases with higher Weber number regime due to the strong asymmetrical solid-liquid interaction (See Supplementary Movie S3 for more details). The scale bar=2 mm. (b)-(c) Side-view snapshots of force analysis of the de-pinning procedure (3.6-3.9 ms). The velocity vectors of the particles are represented by arrows, and the zoomed area (blue box, the scale bar=250 μm) indicates that the high inward velocities vector only occurs at the wall before de-pinning. Subsequently, the leftmost particles have both inward and upward velocity vectors, which then impact adjacent low-velocity portions, causing unbalanced oscillations and additional energy dissipation, ultimately depleting the energy of the upward impact of the droplets (green box, the scale bar=300 μm).

3.4 Unique mechanism for suppressing oscillation

The TCL is always accompanied by the whole process of solid-liquid interaction, which does not merely increase the effective interfacial friction but also suppresses the bouncing droplets[48]. The size of the annular TCL can be quantified by the length of the horizontally overlapping lines (D_h). As a function of the time scale, D_h was normalized by the initial diameter D_0 (Fig. 8). A droplet

332 can bounce from both a sticky superhydrophobic substrate and a superhydrophobic substrate, which
333 was reflected in the similarity of the TCL when the droplet underwent a symmetrically evolved
334 interaction with the substrate ($W_e=4$, Fig. 8 a). The TCL evolved as a function of time scales, and the
335 peaks of these curves correspond to the droplet's maximum spreading diameter (D_{max}) when it
336 impacted the four selected substrates. The maximum spreading factor $\beta_{max} = (D_{max}/D_0) \sim W_e^{0.25} = 1.405$
337 is a critical parameter for evaluating inertia-dominated wetting kinetics based on mass conservation,
338 which is consistent with the conclusions drawn by Clanet et al.[49]. This also indicates that the
339 droplet's dynamic response is independent of the substrate configuration and remains dominated by
340 inertia within a low Weber number regimen. For the higher $W_e=50$, the effect of the substrate
341 configuration on the impact dynamics of the droplets was more effective. All droplets accomplished
342 the spreading process in 3 ms, then experienced a more time-consuming receding phase (Fig. 8b).
343 The distinguishable curves indicate that the droplet morphology was more sensitive to the substrate
344 configuration than that within the high Weber number regimen. We also noticed that the rose petals
345 exhibited the strongest robust liquid viscous effect[48] compared with the other three target
346 substrates during the solid-liquid interaction process. In addition, the comparative analysis indicated
347 that the droplet spreading was strongly suppressed at the liquid-petal interface, and the excess
348 restoring force (reflected in the viscosity of the droplets) was transformed into the surface energy of
349 the irregular twisting droplet ($t = 7.5$ ms in Fig. 7a). The irregular droplet twist caused the surface
350 energy to be consumed by both the viscosity of the droplet and the partial pinning effect of the petals
351 based on the energy conservation argument, eventually leading to droplet adhesion. Conversely, the
352 spreading and retraction of the droplets were maximized because the SHS exhibited the lowest contact
353 angle hysteresis among all selected substrates[2,3]. Analysis of the contact line showed that this twist
354 was relatively stable, while the other three selected substrates exhibited larger fluctuations.



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Fig. 8 Transient contact diameter of the droplet impacting the four substrates at (a) $We=4$ and (b) $We=50$. The difference was not significant under the low Weber number regimen. Nevertheless, the substrate configuration dominated the droplet topography at $We=50$. (c) Comparative analysis of the horizontal flatness factor, ζ_h , under moderate ($We=27$) and high ($We=50$) Weber numbers. The lateral droplet response was consistent in the latter case. (d) Comparative analysis of the vertical flatness factor, ζ_v , under moderate ($We=27$) and high ($We=50$) Weber numbers. Unexpectedly, the high-impact velocity of a droplet led to a lower amplitude.

Attenuation of the droplet oscillation is similar to the underdamped harmonic oscillator, which has the characteristics of a vibration system composed of a spring, damping, and mass with a certain degree of freedom[33]. To quantify this oscillation, the oscillation frequencies were analyzed in the horizontal ($f_h=1/T_h=\omega_h/2\pi$) and vertical ($f_v=1/T_v=\omega_v/2\pi$) directions using the fast Fourier transform

367 algorithm[50,51] in MATLAB. Under the high Weber numbers, the droplet oscillation frequency was
368 lower than that under the moderate-impact velocity condition, where $f_{h50} = 80 \text{ Hz} < f_{h27} = 93 \text{ Hz}$ and
369 $f_{v50} = 76 \text{ Hz} < f_{v27} = 90 \text{ Hz}$ (the frequency of a free-oscillating droplet: $f=109 \text{ Hz}$ [52]). Thus, the
370 lower frequency and smaller amplitude of the droplet oscillations reveal that more energy is
371 dissipated by the viscous force at high-impact velocities. Additionally, mutations in the degree of
372 freedom of the droplet-spring system due to pinning/depinning can severely inhibit lateral but not
373 vertical droplet oscillations during the retraction process; thus, the lower part of the droplet will again
374 collide with the petal, causing multiple surface energy dissipation as demonstrated in Fig. 7.
375 Artificial SSHSs (e.g., SSHS-1, SSHS-2) are more isotropic with respect to the rose petals but can
376 also become more "hydrophilic" under high Weber numbers. In addition, the underdamped harmonic
377 oscillator, especially in the horizontal direction (Fig. 8a), are highly efficient on the RPS. The
378 pinning effect of the high regimen experienced random oscillation in an underdamped manner on the
379 rose petals. The flatness factor, $\zeta_h = D_h/D_0$, and the dimensionless vertical dimension of the droplet, ζ_v
380 $= D_v/D_0$, were defined to investigate the degree of oscillation. Furthermore, we analyzed the
381 oscillation phenomenon of the depositional droplet under moderate ($W_e = 27$) and high ($W_e = 50$)
382 Weber numbers as denoted in Fig. 8, resulting in greater damping and droplet stiffness at $W_e = 50$. The
383 increased velocity appeared to attenuate the oscillation amplitude faster than did the collision of a
384 lower velocity droplet on the same petal, indicating a higher effective damping coefficient.

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386 4. Conclusions

387 There seems to be no consensus on the static petal effects[22–24,26] and a large amount of the
388 previous studies have mainly focused on the wettability of superhydrophobic
389 surfaces[15–21,42]. These all determine that the dynamic petal effects are still far from being fully
390 understood yet. We systematically investigated the impact dynamics of droplets on the interfaces of
391 rose petals, imitation rose petals and SHS. Spherical droplet retention is attributed to the
392 sophisticated energy-consuming system at the droplet-petal interface—the ingenious combination of
393 a sticky superhydrophobic texture and an irregular texture. The pinning effect significantly modified
394 the droplets' dynamic wettability. The sticky superhydrophobic surface is a type of superhydrophobic

395 surface with various defects; thus, the above combination effect should be avoided when designing
396 water-repellent surfaces. As we mentioned, the roses may reveal more "hydrophilic" at heavier
397 precipitation. These findings may offer possibilities for designing high-efficiency energy conversion
398 and harvesting[9,10,27].

399 **Conflicts of interest**

400 There are no conflicts of interest to declare.

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407 **Author contributions**

408 C.Z. and Y.Z. conceived the study. Y.Z. and J.W. performed the experiments. J.Y., C.S. and Y.L.
409 performed the simulations. Y.Z. wrote the paper. All the authors analyzed the data, proofread the
410 paper, made comments.

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