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# Modelling 3D magnetic networks in a realistic solar atmosphere

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## ABSTRACT

The magnetic network extending from the photosphere (solar radius  $\simeq R_{\odot}$ ) to lower corona ( $R_{\odot} + 10$  Mm) plays an important role in the heating mechanisms of the solar atmosphere. Here we further develop the models with realistic open magnetic flux tubes of Gent et al. (2013, 2014) in order to model more complicated configurations. Closed magnetic loops, and combinations of closed and open magnetic flux tubes are modelled. These are embedded within a realistic stratified atmosphere, subject to solar gravity and including the Interface Region. Constructing a magnetic field comprising self-similar magnetic flux tubes, an analytic solution for the kinetic pressure and plasma density is derived following Gent et al. (2014).

Combining flux tubes of opposite polarity it is possible to create a steady background magnetic field configuration modelling realistic solar atmosphere. The result can be applied to SOHO/MDI and SDO/HMI and other magnetograms from the solar surface, upon which realistic photospheric motions can be simulated to explore the mechanism of energy transport. We demonstrate this powerful and versatile method with an application to Helioseismic and Magnetic Imager data.

**Key words:** MHD — Sun:atmosphere — chromosphere — photosphere — magnetic fields

## 1 INTRODUCTION

Since discovery that the solar corona was significantly hotter than the photosphere, following the 1932 solar eclipse (Cillié & Menzel 1935) and subsequent confirmation (Redman 1942), how so has posed a major challenge. Across the solar atmosphere temperatures vary by orders of magnitude. Typical photospheric temperatures are about 6500 K (solar radius  $R_{\odot} \simeq 696$  Mm), and above  $10^6$  K in the corona (out to about  $2R_{\odot}$ ) (Priest 1987, 2014; Aschwanden 2005; Erdélyi 2008, and references therein). The solar surface and atmosphere are extremely dynamic. Frequent and powerful events such as coronal mass ejections release high energy, localised heating within the atmosphere, and yet the corona everywhere is hot. Jets, flares, prominences, and flux emergence, among others, carry mass and energy from the surface into the atmosphere. However, it remains unclear how energy is dissipated through the chromosphere and subsequently to the coronal plasma (Zirker 1993; Aschwanden 2005; Klimchuk 2006; De Pontieu et al. 2011; van Ballegoijen et al. 2011; Priest et al. 2018; Zank et al. 2018). Persistent and ubiquitous small-scale processes would appear to be candidates for this effect. Some advocate small-scale reconnections of magnetic field lines (Peter et al. 2004; Bourdin et al. 2013). Such

reconnections occur on physical scales well below the resolution and cadence currently available for observational validation. An alternative view may be that solar magnetic field lines, in the form of magnetic *flux tubes*, act as guides for magnetohydrodynamic (MHD) waves that may carry the missing energy to heat the atmosphere to observed temperatures. These occur at scales, which are increasingly available to observational comparison (Jess et al. 2007; Morton et al. 2012; Wedemeyer-Böhm et al. 2012). This article is motivated by the latter, but may nevertheless be useful more generally.

Models of magnetic field configuration dealing with coronal heating often set the flux-tube footpoints just above the Transition Region (TR), or leave it unresolved. The TR is a relatively narrow layer between chromosphere and corona where the plasma temperature jumps. In the corona the magnetic field is commonly modelled as force-free, assuming the plasma pressure to be negligible, but in the low chromosphere and the photosphere kinetic forces cannot reasonably be ignored, with the ratio of thermal to magnetic pressure  $\text{plasma-}\beta \gg 1$ . The dynamic interface region (IR) spans the photosphere and lower corona. Typical mass and energy density in the IR are orders of magnitude larger than in the corona as a whole (McWhirter et al. 1975; Vernazza et al. 1981; Fontenla et al. 2006, 2007, 2009), so it is reasonable to expect IR dynamics to be critical for the coronal heating mechanism.

The extreme nine orders of magnitude gradient in plasma den-

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sity (six in pressure, three in temperature) over 2.5 Mm from the upper photosphere to the lower corona presents a significant challenge in modelling magnetic fields in the chromosphere (DeForest 2007). Typical magnetic flux-tube footpoint strength of about 100 mT (1000 G) are observed emerging from the photosphere (Zwaan 1978; Priest 1987, 2014; Aschwanden 2005; Erdélyi 2008, and references therein, the latter Ch.8.7, Ch.5, respectively). An isolated magnetic flux tube must, therefore, expand exponentially in radius as it rises to balance the plasma pressure. Magnetic structures remain steady over various time-scales (McGuire et al. 1977; Levine & Withbroe 1977; Malherbe et al. 1983) and this has been used to investigate the transport mechanisms along the field lines with a series of numerical simulations (Shelyag et al. 2008; Fedun et al. 2009; Shelyag et al. 2009; Fedun et al. 2011; Vigeesh et al. 2012; Khomenko & Collados 2012; Mumford et al. 2015; Mumford & Erdélyi 2015). These numerical studies were restricted to single flux tubes and did not breach the TR, so flux tube interaction and the effect on the corona cannot feasibly be explored. Khomenko et al. (2008); Khomenko & Collados (2012) constructed a 2D magnetic field with multiple flux tubes, each identical to its neighbour, but excluding the TR. Hasan et al. (2005); Hasan & van Ballegoijen (2008) constructed a 2D magnetic field which does extend into the low corona. Gent et al. (2014, hereafter Paper II) generalised the background configuration to 3D, multiple, non-identical flux tubes, extending into the lower corona. This was successfully applied to a 3D model of a flux-tube pair by Snow et al. (2018), who showed that chromospheric shocks at the intersections between the tubes are capable of driving supersonic jets.

However, all of these models apply only to open magnetic flux tubes of the same polarity. Their major omission is flux loops with footpoints of opposite polarity, which are common features of solar magnetic networks. Vesecky et al. (1979) considered an analytic construction of a single 3D magnetic flux loop as a static background, but for a thermodynamic model, not MHD. The primary contribution of the current work will be to add loops to the multiple flux tube network described in Paper II. An advantage of this result shall be that any arbitrary magnetogram of the photosphere, e.g. from the Helioseismic and Magnetic Imager for SDO (HMI) (Kosovichev & HMI Science Team 2007), can be constructed by matching the vertical field for each pixel to the model and constructing analytically a realistic 3D magnetic network extending into the corona. Using the corresponding velocity field from the same observational image or similar, forward modelling can then be applied to explore the energy transport mechanism. The analytical model is outlined explicitly in Section 2, and differences with Paper II. In Section 3 some applications for the model are described and some discussion of its uses and limitations.

## 2 MAGNETIC FLUX LOOP

### 2.1 Ambient magnetic field outside the flux tubes

In Gent et al. (2013, hereafter Paper I) we constructed analytically a 3D model of a single vertical magnetic flux tube embedded in a realistic solar atmosphere at magnetohydrostatic (MHS) equilibrium. This was extended to multiple magnetic flux tubes in Paper II.

The background atmosphere employed was derived from the combined modelling profiles of Vernazza et al. (1981, Table 12, VALIIC) and McWhirter et al. (1975, Table 3) for the chromosphere and lower solar corona, respectively (see Fig 1 Paper I). However, the models do not depend on the choice of atmosphere

and the derivation described could be applied to many alternative atmospheric models.

Observations (Ch.3.5 in Mariska 1993; Schrijver & Title 2003) indicate the atmosphere outside the flux tubes includes a non-zero magnetic field of order 1–10 mT in the corona. It is important to model this ambient field, so that realistic ratios can be obtained between the thermal and magnetic pressures, i.e. plasma- $\beta < 1$  outside the flux tube. Paper I and Paper II implemented explicit external fields to provide ambient magnetic pressure. In this article we model magnetic flux loops by combining vertical flux tubes of opposite polarity. For a flux tube of opposite polarity an ordered ambient field will negate the effective field in the flux tube. Therefore, a constant vertical ambient field is not suitable for use with flux loops. A realistic solution still requires a low plasma- $\beta$  in the corona. Further refining the model the ambient magnetic pressure felt by each individual flux tube is now induced by the superposition of its neighbouring flux tubes. Plasma- $\beta < 1$  above the photosphere will be obtained due to the expansion of strong flux tubes and loops near the local network. Therefore, we drop the ambient field denoted by  $b_{00}$  in Equation 22 of Paper II.

### 2.2 The MHD equations

A full outline of the governing ideal MHD equations, which we would use to describe the environment in the solar atmosphere is provided in Gent et al. (2014, Section 2.2). Our approach, following that of Shelyag et al. (2008), is to derive the system of equations governing the perturbed MHD variables by splitting the variables  $\rho$  (plasma density),  $e$  (energy density) and  $\mathbf{B}$  (magnetic field) into their background and perturbed components

$$\rho = \rho_b + \tilde{\rho}, \quad e = e_b + \tilde{e}, \quad \mathbf{B} = \mathbf{B}_b + \tilde{\mathbf{B}}, \quad (1)$$

where tilde denotes the perturbed portion and it is assumed  $\rho_b$ ,  $e_b$  and  $\mathbf{B}_b$  do not vary with time. When the time-independent momentum equation describing the background equilibrium is deduced, the modified form of the momentum equation governing the perturbed system is given by

$$\frac{\partial [(\rho_b + \tilde{\rho}) u_i]}{\partial t} + \frac{\partial}{\partial x_j} \left[ (\rho_b + \tilde{\rho}) u_i u_j - \frac{\tilde{B}_i \tilde{B}_j}{\mu_0} \right] + \frac{\partial}{\partial x_j} \tilde{p}_T - \frac{\partial}{\partial x_j} \left[ \frac{\tilde{B}_i B_{bj} + B_{bi} \tilde{B}_j}{\mu_0} \right] + F_{\text{bal}_i} = \tilde{\rho} g_i, \quad (2)$$

and the consequent energy equation is given by

$$\frac{\partial \tilde{e}}{\partial t} + \frac{\partial}{\partial x_j} \left[ (e_b + \tilde{e}) u_j - \frac{\tilde{B}_i \tilde{B}_j}{\mu_0} u_i \right] + \frac{\partial}{\partial x_j} \left[ \tilde{p}_T u_j - \frac{\tilde{B}_i B_{bj} + B_{bi} \tilde{B}_j}{\mu_0} u_i \right] + p_{bT} \frac{\partial u_j}{\partial x_j} - \frac{B_{bj} B_{bi}}{\mu_0} \frac{\partial u_i}{\partial x_j} + F_{\text{bal}_i} u_i = \tilde{\rho} g_i u_i, \quad (3)$$

in which  $\mathbf{u}$  and  $\mathbf{g}$  are the velocity and gravitational acceleration.  $F_{\text{bal}}$  represent net background equilibrium forces. The system is completed by the equations of continuity, induction and state, as detailed in Paper II.

Given no vertical current  $J_z$  a stationary state, where magnetic force balances exactly pressure and gravitational forces, has an MHS equilibrium solution providing the magnetic field satisfies

$$\partial_y B_z \partial_z B_x = \partial_x B_z \partial_z B_y, \quad (4)$$

and, hence,  $F_{\text{bal}} = \mathbf{0}$ . A scalar solution for pressure can otherwise still be derived by inclusion of minimal horizontal balance

ing forces  $\mathbf{F}_{\text{bal}}$ , yielding forced magnetohydrostatic equilibrium (FME). These balancing forces are small compared to the other forces and may be considered to be a statistical steady superposition of small-scale high-cadence turbulence in the chromosphere, where the magnetic field is not force-free. Our approach is to specify the background magnetic field. We then solve the time-independent momentum equation

$$\nabla p_b + \nabla \frac{|\mathbf{B}_b|^2}{2\mu_0} - (\mathbf{B}_b \cdot \nabla) \frac{\mathbf{B}_b}{\mu_0} - \rho_b g \hat{\mathbf{R}} + \mathbf{F}_{\text{bal}} = \mathbf{0}, \quad (5)$$

to find the FME  $p_b$  and  $\rho_b$ , and identify the balancing forces  $\mathbf{F}_{\text{bal}}$ . Gravity depends only on solar radius  $\mathbf{R}$ ,

### 2.3 A single magnetic flux tube

In cylindrical coordinates, taking  $\hat{\mathbf{z}}$  to be along  $\mathbf{R}$ , the magnetic potential of a self-similar axisymmetric magnetic flux tube is

$${}^m A_{br} = {}^m S \phi {}^m G \frac{\partial {}^m f}{\partial r}, \quad {}^m A_{b\phi} = 0, \quad {}^m A_{bz} = {}^m S \phi {}^m G \frac{\partial {}^m f}{\partial z},$$

or in Cartesian coordinates we have

$$\begin{aligned} {}^m A_{bx} &= {}^m S \arctan\left(\frac{y - {}^m y}{x - {}^m x}\right) {}^m G \frac{\partial {}^m f}{\partial x}, \\ {}^m A_{by} &= {}^m S \arctan\left(\frac{y - {}^m y}{x - {}^m x}\right) {}^m G \frac{\partial {}^m f}{\partial y}, \\ {}^m A_{bz} &= {}^m S \arctan\left(\frac{y - {}^m y}{x - {}^m x}\right) {}^m G \frac{\partial {}^m f}{\partial z}, \end{aligned} \quad (6)$$

where  ${}^m A_b$  denotes the potential for the  $m^{\text{th}}$  flux tube, which has its axial vertical magnetic field  ${}^m S$  located at a footpoint  $({}^m x, {}^m y)$  on the photosphere. We scale  ${}^m f$  and  ${}^m G$  from Paper II to

$${}^m f = -\frac{{}^m r^2 B_{0z}^2}{2} \quad \text{and} \quad {}^m G = \exp\left(\frac{{}^m f}{f_0^2}\right), \quad (7)$$

with factor  $f_0^2$  governing the radial scale of the flux tube and the radial distance  ${}^m r$  from the axis at  $({}^m x, {}^m y)$  is

$${}^m r = \sqrt{(x - {}^m x)^2 + (y - {}^m y)^2}. \quad (8)$$

The reduction in the vertical field strength along the flux tube axis is specified by an appropriate monotonically decreasing function  $B_{0z}(z)$ , such as a sum of exponentials as applied in Paper II or a polynomial form as applied by Gary (2001) and employed in Section 3.1. The sign of real parameter  ${}^m S$  determines the polarity of the flux tube. The components of the magnetic field for the  $m^{\text{th}}$  flux tube  ${}^m \mathbf{B}_b$  are then defined as in Equation 22 of Paper II with  $b_{00} = 0$ . Now, however, by construction at  $({}^m x, {}^m y)$   ${}^m G = 1$  and  ${}^m r = {}^m f = 0$ . We also impose  $B_{0z}(z=0) = 1$ . Hence, at the flux tube axis the photospheric magnetic field is  ${}^m B_{bz} = {}^m S$ , which can be set directly or interpolated from HMI data or similar.

Equation (5) can be decomposed into hydrostatic (HS) and MHS parts, i.e.

$$\begin{aligned} \nabla(p_{bh} + {}^m p_{bm}) + \nabla \frac{|\mathbf{B}_b|^2}{2\mu_0} - (\mathbf{B}_b \cdot \nabla) \frac{\mathbf{B}_b}{\mu_0} \\ + {}^m \mathbf{F}_{\text{bal}} - (\rho_{bh} + {}^m \rho_{bm})g\hat{\mathbf{z}} = \mathbf{0}, \end{aligned} \quad (9)$$

in which  $p_{bh}$  and  $\rho_{bh}$  denote HS plasma pressure and density, and  ${}^m p_{bm}$  and  ${}^m \rho_{bm}$  denote MHS adjustments due to flux tube  ${}^m \mathbf{B}_b$ .  ${}^m \mathbf{F}_{\text{bal}}$  vanishes, with Equation (4) satisfied for the single flux tube. The HS equilibrium is constructed using the VAL IIIC (Vernazza et al. 1981) temperature and density profiles to calculate a pressure profile, using the ideal gas law. That is then differentiated vertically

to produce a stable density profile, assuming constant gravity. The advantage of this method is that it allows the pressure and density fields to be corrected, after the MHS corrections have been applied, to exclude negative values. What remains of Eq. (9) is

$$\nabla {}^m p_{bm} + \nabla \frac{|\mathbf{B}_b|^2}{2\mu_0} - (\mathbf{B}_b \cdot \nabla) \frac{\mathbf{B}_b}{\mu_0} - {}^m \rho_{bm} g \hat{\mathbf{z}} = \mathbf{0}. \quad (10)$$

The solution to Eq. (10) follows Paper I and Paper II, in the absence of terms defining an ambient magnetic field  $b_{00}$ , to yield

$${}^m p_{bm} = \frac{{}^m S^2}{2\mu_0} {}^m G^2 [f_0^2 B_{0z} B_{0z}' + 2 {}^m f B_{0z}'^2 - B_{0z}^4], \quad (11)$$

$${}^m \rho_{bm} = \frac{{}^m S^2 {}^m G^2}{\mu_0 g} \left[ \left( \frac{f_0^2}{2} + 2 {}^m f \right) B_{0z}' B_{0z}'' + \frac{B_{0z} B_{0z}'' f_0^2}{2} - 2 B_{0z}^3 B_{0z}' \right]. \quad (12)$$

### 2.4 Including a second or more flux tubes of mixed polarity

Let us now include a second flux tube, such that  ${}^n \mathbf{B}_b$  denotes one with the same construction as  ${}^m \mathbf{B}_b$  apart from the arbitrary axial coordinates  $({}^n x, {}^n y)$  and parameter  ${}^n S$ . Equation (10) becomes

$$\begin{aligned} \nabla ({}^m p_{bm} + {}^n p_{bm} + {}^{mn} p_{bm}) \\ - ([{}^m \mathbf{B}_b + {}^n \mathbf{B}_b] \cdot \nabla) \frac{{}^m \mathbf{B}_b + {}^n \mathbf{B}_b}{\mu_0} + \nabla \frac{|\mathbf{B}_b + {}^n \mathbf{B}_b|^2}{2\mu_0} \\ + {}^{mn} \mathbf{F}_{\text{bal}} - ({}^m \rho_{bm} + {}^n \rho_{bm} + {}^{mn} \rho_{bm})g\hat{\mathbf{z}} = \mathbf{0}, \end{aligned} \quad (13)$$

where superscript  ${}^n$  has equivalent meaning for the second flux tube as indicated for the first in Equation (9). The additional superscript  ${}^{mn}$  refers to the interaction between the flux tube pair. Subtracting Equation (10), and the equivalent for the second flux tube retains

$$\begin{aligned} \nabla {}^{mn} p_{bm} - (\mathbf{B}_b \cdot \nabla) \frac{{}^n \mathbf{B}_b}{\mu_0} - ({}^n \mathbf{B}_b \cdot \nabla) \frac{{}^m \mathbf{B}_b}{\mu_0} \\ + \nabla \frac{\mathbf{B}_b \cdot {}^n \mathbf{B}_b}{2\mu_0} + {}^{mn} \mathbf{F}_{\text{bal}} - {}^{mn} \rho_{bm} g \hat{\mathbf{z}} = \mathbf{0}. \end{aligned} \quad (14)$$

Equation (4) is not satisfied, so  ${}^{mn} \mathbf{F}_{\text{bal}}$  does not vanish.

$$\begin{aligned} \frac{\partial}{\partial x} {}^{mn} p_{bm} &= \frac{2 {}^n f^2}{f_0^2} B_{0z}'^2 {}^m S {}^n S B_{0z}^2 {}^m G {}^n G \frac{x - {}^n x}{\mu_0} \\ &+ \frac{2 {}^m f^2}{f_0^2} B_{0z}'^2 {}^m S {}^n S B_{0z}^2 {}^m G {}^n G \frac{x - {}^m x}{\mu_0} \\ &+ \frac{\partial}{\partial x} \left( \frac{{}^m S {}^n S f_0^2}{2\mu_0} {}^m G {}^n G [B_{0z}'^2 + B_{0z} B_{0z}'] \right), \end{aligned} \quad (15)$$

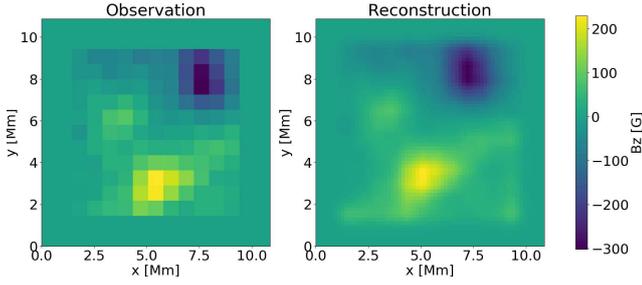
in which the first two lines cannot integrate with respect to  $x$ , while a similar residual expression is obtained from integrating the  $y$ -component of Equation (14). However, a scalar solution for the pressure and density is possible, if this contribution to the magnetic tension force is balanced by

$$\begin{aligned} {}^{mn} \mathbf{F}_{\text{bal}} &= -\frac{2}{f_0^2} B_{0z}'^2 {}^m S {}^n S B_{0z}^2 {}^m G {}^n G \\ &\left\{ {}^n f^2 \left[ \frac{x - {}^n x}{\mu_0} \hat{\mathbf{x}} + \frac{y - {}^n y}{\mu_0} \hat{\mathbf{y}} \right] + {}^m f^2 \left[ \frac{x - {}^m x}{\mu_0} \hat{\mathbf{x}} + \frac{y - {}^m y}{\mu_0} \hat{\mathbf{y}} \right] \right\}. \end{aligned} \quad (16)$$

If we generalise to a system of  $N$  flux tubes with  $\mathbf{B}_b = {}^1 \mathbf{B}_b + {}^2 \mathbf{B}_b + \dots + {}^N \mathbf{B}_b$ , then the pressure can be fully described by

$$p_b = p_{bh} + \sum_{m=1}^N {}^m p_{bm} + \sum_{m,n=1|n>m}^N {}^{mn} p_{bm}, \quad (17)$$

in which  $p_{bh}$  is derived from the interpolated observed profile, constrained to be monotonically decreasing with height, and  ${}^m p_{bm}$  is



**Figure 1.** Observed HMI magnetogram (left) model (right) of the photosphere. Filled pixels highlight the resolution.

defined by Equation (11). The pressure adjustment due to each pairwise flux tube interaction is given by

$${}^{mn}\rho_{bm} = \frac{{}^mS {}^nS f_0^2}{{}^2\mu_0} {}^mG {}^nG \left[ B_{0z}'^2 + B_{0z}B_{0z}'' \right] - \frac{{}^mB_{bz} {}^nB_{bz}}{\mu_0}. \quad (18)$$

The corresponding expression for the plasma density is

$$\rho_b = \rho_{bh} + \sum_{m=1}^N {}^m\rho_{bm} + \sum_{m,n=1|n>m}^N {}^{mn}\rho_{bm}, \quad (19)$$

in which  $\rho_{bh}$  is the product of  $g^{-1}$  and the  $z$ -derivative of  $p_{bh}$ , and  ${}^m\rho_{bm}$  is defined by Equation (12). The density adjustments due to each pairwise flux tube interaction are given by

$$\begin{aligned} {}^{mn}\rho_{bm} = & 2 \frac{{}^mS {}^nS}{{}^2\mu_0 g} {}^mG {}^nG B_{0z}' B_{0z}'' \left[ \left( \frac{{}^mf + {}^nf}{f_0^2} - 2 \right) B_{0z}'^2 \right. \\ & - \frac{{}^mf + {}^nf}{2} \left( \frac{B_{0z}'^2}{B_{0z}^2} + \frac{B_{0z}''}{B_{0z}} \right) + \frac{f_0^2}{4} \left( 3 \frac{B_{0z}''}{B_{0z}} + \frac{B_{0z}'''}{B_{0z}'} \right) \\ & + \{ (x - {}^mx)(x - {}^nx) + (y - {}^my)(y - {}^ny) \} \\ & \left. \left\{ \left( 1 - \frac{{}^mf + {}^nf}{f_0^2} \right) B_{0z}'^2 + B_{0z}B_{0z}'' - 2 \frac{B_{0z}^4}{f_0^2} \right\} \right]. \end{aligned} \quad (20)$$

The net balancing force in Equation (5) is then fully specified as

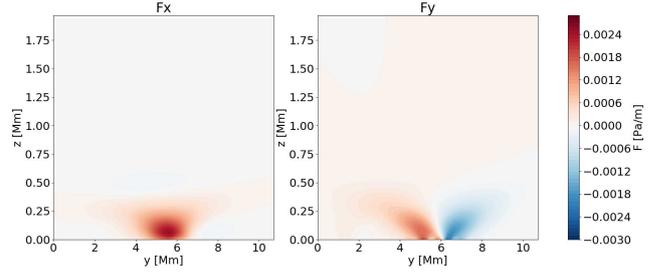
$$\mathbf{F}_{bal} = \sum_{m,n=1|n>m}^N {}^{mn}\mathbf{F}_{bal}. \quad (21)$$

### 3 APPLICATION OF THE MODEL

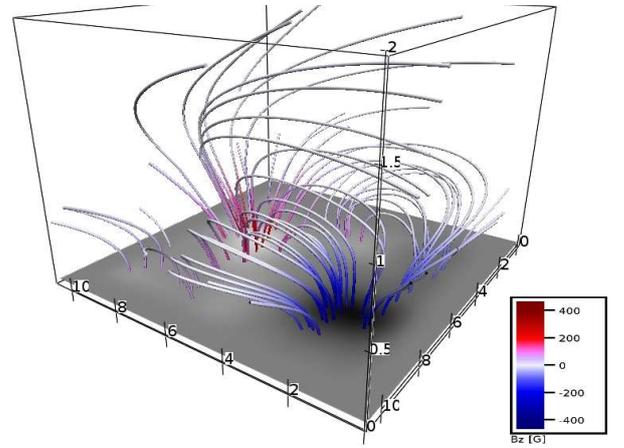
#### 3.1 Fitting arbitrary flux tubes

A stable atmosphere can be generated for any distribution of photospheric magnetic field by using the observed magnetic field in each pixel to construct a series of interacting flux tubes. To demonstrate this, the atmosphere is constructed using a subsection of the HMI magnetogram observed on 2014.07.06\_00\_00\_45. A relatively small region ( $16 \times 16$  pixels) is chosen that features a few isolated magnetic regions of opposite polarity.

In a numerical grid of horizontal dimension  $64 \times 64$  magnetic flux tubes with  $f_0 \simeq 750$  km are fitted for each pixel in the observing box. Figure 1 shows the observed HMI magnetogram (left) and the reconstructed photospheric magnetic field (right). A region around the observation is set to zero to allow numerical boundaries to be well defined when the atmosphere is used for simulations. Shown in Figure 1, there is strong agreement between the observation and the reconstruction both in terms of locations and magnitude of magnetic field.



**Figure 2.** 2D slice at  $x = 8.15$  Mm of model balancing forces.

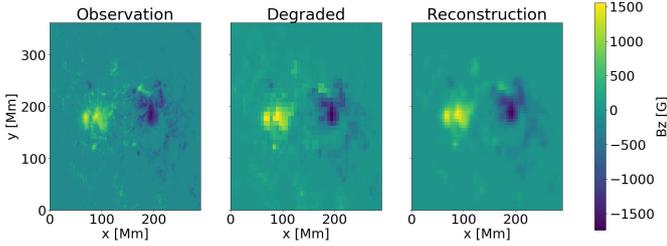


**Figure 3.** 3D plot of chromospheric loop reconstruction.

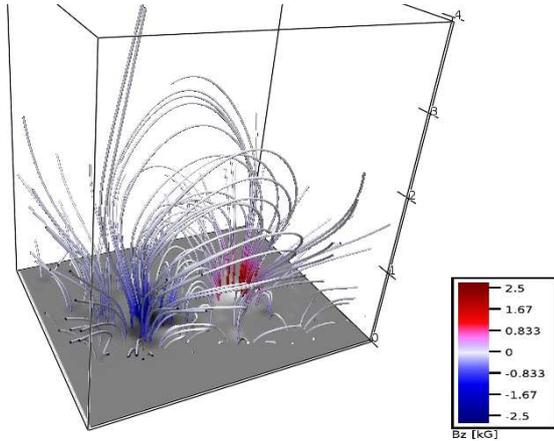
The density and pressure modifications, required to stabilise the magnetic field, are generated using the methods outlined in Section 2. The additional forcing terms  $\mathbf{F}_{bal}$  applied to account for the magnetic tension effects between neighbouring flux tubes are plotted in Figure 2. The forcing terms are significant only in the lower atmosphere and are zero in most of the domain. For context, the magnitude of the forcing terms is maximally around 2% of the horizontal pressure gradient. These forcing terms represent a small adjustment to the system.

The end result is a 3D FME that models the photospheric magnetic field, shown in Figure 3, using VAPOR (Clyne & Rast 2005; Clyne et al. 2007). Due to the modest footpoint magnetic field of around 30 mT, the loop is mainly confined to the chromosphere, so we model the region to a height of 2 Mm above the photosphere. Simulations of a well-observed region, in preparation, aim to illustrate the model's effectiveness for such complex networks.

Above active regions, the magnetic field can easily extend through the transition region and into the solar corona. To test the construction of such atmospheres we apply the same methodology to an active region with vertical magnetic field strength of  $B_z \approx \pm 2500$  G. This region is much larger than the previous test and hence fitting a flux tube to each observational pixel is computationally expensive. To circumvent this, we degrade the observation to a lower spatial resolution (see Figure 4 and fit flux tubes to the strongest sources only, yielding the network plotted in Figure 5.



**Figure 4.** HMI magnetogram (left), spatially degraded HMI (centre) and model photosphere (right).



**Figure 5.** 3D plot of magnetic fieldlines above an active region, including the lower corona.

#### 4 RESULTS SUMMARY

In this article we describe and demonstrate a new method for reconstructing a stationary state solar atmosphere, with realistic magnetic configuration. The model parameters have been streamlined and generalised, making them easy to apply for arbitrary photospheric magnetic field sources. Calculating the magnetic fields and resulting atmosphere is computationally efficient, available in parallel python from PYSAC (<https://github.com/fredgent/pysac>).

The free parameters in radial scaling and scale height, and the generalised inclusion of any ambient atmosphere models, makes the method versatile for a number of scientific problems. The physical veracity of the parameters can, however, be constrained by comparison with observations of the magnetic field and kinetics at various heights. The stability of the solution can also be confirmed by numerical simulation for each configuration. This was carried out for the flux-tube pair solution used in Snow et al. (2018), by treating the solution as the MHD perturbations, and the system remained stationary to within machine accuracy.

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