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A UNIFIED THEORY FOR CONTINUOUS IN TIME EVOLVING FINITE ELEMENT SPACE APPROXIMATIONS TO PARTIAL DIFFERENTIAL EQUATIONS IN EVOLVING DOMAINS

C. M. ELLIOTT¹ AND T. RANNER²

ABSTRACT. We develop a unified theory for continuous in time finite element discretisations of partial differential equations posed in evolving domains including the consideration of equations posed on evolving surfaces and bulk domains as well as coupled surface bulk systems. We use an abstract variational setting with time dependent function spaces and abstract time dependent finite element spaces. Optimal a priori bounds are shown under usual assumptions on perturbations of bilinear forms and approximation properties of the abstract finite element spaces. The abstract theory is applied to evolving finite elements in both flat and curved spaces. Evolving bulk and surface isoparametric finite element spaces defined on evolving triangulations are defined and developed. These spaces are used to define approximations to parabolic equations in general domains for which the abstract theory is shown to apply. Numerical experiments are described which confirm the rates of convergence.

Dedicated to the memory of John W. Barrett

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1. INTRODUCTION

In this paper, we develop a unified theory for finite element discretisations of partial differential equations posed in evolving domains including the consideration of equations posed on evolving surfaces and bulk domains as well as coupled surface bulk systems. The discretisation is based on evolving finite element spaces defined on evolving triangulations using isoparametric elements. Optimal order a priori error bounds are proven. This unification is achieved by using an abstract variational setting with time dependent abstract function spaces and time dependent abstract finite element spaces. Given a time dependent Hilbert triple

$$\mathcal{V}(t) \subset \mathcal{H}(t) \subset \mathcal{V}^*(t),$$

the abstract strong formulation is: Find $u(t) \in \mathcal{V}(t)$ such that

$$(1.1a) \quad \partial^\bullet u + \mathcal{L}(t)u + \omega(t)u = 0 \quad \text{in } \mathcal{V}^*(t)$$

$$(1.1b) \quad u(0) = u_0,$$

where $\mathcal{V}(t)$ is an appropriate time dependent Hilbert space with dual $\mathcal{V}^*(t)$, $\partial^\bullet u$ is an appropriate abstract material derivative arising from the evolution of the spaces, $\mathcal{L}(t)$ is an abstract elliptic operator satisfying suitable coercivity properties and $\omega(t)$ is a lower order term arising from evolution of the space. Similar to the case of time independent function spaces this equation may be written in variational form as

Problem 1.1. *Given $u_0 \in \mathcal{V}_0 := \mathcal{V}(0)$, find $u \in L^2_{\mathcal{V}}$ with $\partial^\bullet u \in L^2_{\mathcal{H}}$ such that for almost every $t \in [0, T]$,*

$$(1.2) \quad m(t; \partial^\bullet u, \varphi) + g(t; u, \varphi) + a(t; u, \varphi) = 0 \quad \text{for all } \varphi \in \mathcal{V}(t),$$

subject to the initial condition $u(0) = u_0$.

Here $L^2_{\mathcal{V}}$ and $L^2_{\mathcal{H}}$ are generalisations of the Bochner spaces $L^2(0, T; V)$ and $L^2(0, T; H)$, where $V \subset H \subset V^*$ is a time-independent Hilbert triple. The bilinear form $a(\cdot, \cdot)$ is associated with the elliptic operator \mathcal{L} and the bilinear forms m and g are associated with the $\mathcal{H}(t)$ -inner product and its time derivative (i.e. the operator ω). The above problem is also well posed for $u_0 \in \mathcal{H}(0)$ where we seek $\partial^\bullet u \in L^2_{\mathcal{V}^*}$. Here we seek error bounds for sufficiently smooth solutions.

We formulate and analyse an abstract finite element discretisation based on a Galerkin ansatz with perturbations of the bilinear forms. Under assumptions on the approximation of geometry and the approximation of function spaces by abstract finite element spaces

optimal order error bounds are proved. Then we construct realisations of this abstract setting in the context of partial differential equations on evolving domains. This is achieved by means of the construction of evolving finite element spaces on evolving triangulations of time dependent surfaces and bulk domains from first principals. We give a concrete realisation of these spaces based on evolving Lagrange isoparametric finite elements.

This approach is applied to three model problems: a linear parabolic problem in an evolving, bounded bulk domain in \mathbb{R}^{n+1} , a linear parabolic problem on an evolving compact n -dimensional surface embedded in \mathbb{R}^{n+1} and a linear parabolic problem coupling problems in an evolving, bounded bulk domain in \mathbb{R}^{n+1} to a problem on its boundary. In each case, we assume that the evolution of the problem domain is prescribed. The abstract approach is applicable to other situations including nonlinear equations, coupled equations and problems with dynamic boundary conditions.

1.1. Background. Partial differential equations posed on complex evolving domains arise in numerous settings such as surfactant transport on fluid interfaces, receptor ligand dynamics on cell surfaces and phase separation on dissolving alloy surfaces (Deckelnick, Elliott, Kornhuber and Sethian, 2015; Elliott, Ranner and Venkataraman, 2017; Barrett, Garcke and Nürnberg, 2015; Alphonse, Elliott and Terra, 2018; Torres-Sánchez, Millán and Arroyo, 2019; Zimmermann, Toshniwal, Landis, Hughes, Mandadapu and Sauer, 2019). Numerical approaches to solve these problems include surface finite elements, implicit surface formulations, diffuse interface approximations, trace finite elements, unfitted finite elements, finite volume schemes and mesh free methods. See the works of Dziuk (1988); Dziuk and Elliott (2007); Deckelnick, Dziuk, Elliott and Heine (2009); Dziuk and Elliott (2010); Deckelnick, Elliott and Ranner (2014); Deckelnick and Styles (2018); Olshanskii and Reusken (2017); Burman, Hansbo, Larson and Zahedi (2016); Lehrenfeld, Olshanskii and Xu (2018); Lehrenfeld and Olshanskii (2019); Giesselmann and Müller (2014); Deckelnick, Elliott, Miura and Styles (2019); Suchde and Kuhnert (2019) and the review of Dziuk and Elliott (2013a).

The problem of solving parabolic problems in evolving bulk domains has been studied for many years. In particular, we mention the ALE (arbitrary Lagrangian-Eulerian) approach first proposed by Hirt, Amsden and Cook (1974) in the context of finite difference methods and by Donea, Giuliani and Halleux (1982); Hughes, Liu and Zimmermann (1981) for finite element methods. Analysis of a similar problem considering both spatial and temporal discretisation is given by Badia and Codina (2006); Boffi and Gastaldi (2004); Formaggia and Nobile (1999, 2004); Gastaldi (2001); Nobile (2001); Gawlik and Lew (2015). The analysis by Bonito, Kyza and Nochetto (2013b,a) provides optimal order convergence for a discrete Galerkin in time approach.

The study of finite element methods for partial differential equations posed on surfaces started with the seminal work of Dziuk (1988). Evolving surface finite elements were introduced and analysed for an advection diffusion equation posed on evolving surfaces by Dziuk and Elliott (2007, 2012, 2013a). In these works optimal error bounds were proved for piecewise linear finite elements on triangulated surface evolved using the normal and advective velocity. In this work we consider a more general parabolic equation on surfaces and discretisations which cover the case of higher-order schemes (Heine, 2005; Demlow, 2009; Kovács, 2018) and arbitrary Lagrangian-Eulerian methods (Elliott and Styles, 2012; Elliott and Venkataraman, 2015). The discretisations presented in this paper can be combined with different time stepping schemes (Dziuk, Lubich and Mansour, 2011; Dziuk and Elliott, 2012; Lubich, Mansour and Venkataraman, 2013; Kovács and Guerra, 2018) to provide a fully discrete scheme. We also mention the analysis of Kovács, Li, Lubich and

Guerra (2017) who study a diffusion equation on the surface which drives the a priori unknown evolution of the surface.

Our abstract approach will be applied to equations posed on evolving bulk domains and coupled bulk surface systems. See the work of Elliott and Ranner (2013); Gross, Olshanskii and Reusken (2015); Burman et al. (2016) for approaches to stationary surface problems. Kovacs and Lubich (2017) extended the results for piecewise linear elements to a coupled bulk-surface system. The functional analytic setting will be the product of spaces over the bulk domain, $\Omega(t)$, and the surface, $\Gamma(t)$.

1.2. Some partial differential equations on evolving domains. Let $T > 0$. For $t \in [0, T]$ let $\Omega(t)$ denote an $(n+1)$ -dimensional bounded, connected, open subset (domain) in \mathbb{R}^{n+1} , for $n = 1, 2, 3$. We denote by $\Gamma(t)$ the boundary $\partial\Omega(t)$ assumed to be a sufficiently smooth compact n -dimensional orientable hypersurface with unit normal $\nu(t)$ pointing outward from $\Omega(t)$. We write $\Omega_0 = \Omega(0)$, $\Gamma_0 = \Gamma(0)$.

We assume that there exists a sufficiently smooth mapping (called the flow map) $\Phi_t(\cdot) : [0, T] \times \bar{\Omega}_0 \rightarrow \mathbb{R}^{n+1}$ satisfying

- (1) $\Phi_t(\cdot)$ is a diffeomorphism of $\bar{\Omega}_0$ onto $\bar{\Omega}(t)$ for each $t \in [0, T]$;
- (2) $\Phi_0(\cdot) = \text{Id}|_{\bar{\Omega}_0}$.

We will write $\Phi_{-t} : \bar{\Omega}(t) \rightarrow \bar{\Omega}_0$ for the inverse of Φ_t . We define the material velocity w by

$$w : \bar{\Omega}_T \left(:= \bigcup_{t \in (0, T)} \bar{\Omega}(t) \times \{t\} \right) \rightarrow \mathbb{R}^{n+1},$$

$$w(x, t) := \frac{\partial \Phi_t}{\partial t} ((\Phi_t(\cdot))^{-1}(x)), \quad x \in \bar{\Omega}(t), t \in (0, T)$$

which may be written as

$$(1.3) \quad \frac{\partial}{\partial t} \Phi_t(p) = w(\Phi_t(p), t), \quad t \in (0, T), \quad \Phi_0(p) = p.$$

We use the terminology that $\Omega(t)$ is an evolving bulk domain and $\Gamma(t)$ is an evolving surface domain. In order to define the evolution of the domains as sets we need only to specify the normal velocity $V\nu = (w \cdot \nu)|_{\Gamma(t)}$ of $\Gamma(t)$. The tangential components of $w = \frac{\partial \Phi_t}{\partial t}$ allows for an arbitrary parametrisation of the domain.

Illustrative examples of the boundary value problems we wish to consider are:

- (1) Find a time-dependent scalar field u such that on an evolving Cartesian bulk domain $\Omega(t)$

$$(1.4a) \quad u_t + \nabla \cdot (b_\Omega u) - \nabla \cdot (a_\Omega \nabla u) + c_\Omega u = 0 \quad \text{on } \Omega(t)$$

$$(1.4b) \quad (a_\Omega \nabla u - (b_\Omega - V\nu)u) \cdot \nu = 0 \quad \text{on } \Gamma(t)$$

$$(1.4c) \quad u(0) = u_0 \quad \text{on } \Omega_0 := \Omega(0),$$

where a_Ω is a smooth diffusion tensor, b_Ω a smooth vector field and c_Ω a smooth scalar field.

- (2) Seek a time-dependent scalar surface field u such that

$$(1.5a) \quad \partial^\circ u + \nabla_\Gamma \cdot (b_\Gamma u) - \nabla_\Gamma \cdot (a_\Gamma \nabla_\Gamma u) + c_\Gamma u = 0 \quad \text{on } \Gamma(t)$$

$$(1.5b) \quad u(0) = u_0 \quad \text{on } \Gamma_0 := \Gamma(0),$$

where a_Γ is a smooth diffusion tensor which maps the tangent space of Γ into itself and c_Γ is a smooth scalar field. Here b_Γ is a tangential vector field. We use

the notation $\partial^\circ \mathbf{u}$ for the normal time derivative (Cermelli, Fried and Gurtin, 2005; Dziuk and Elliott, 2013b), which denotes the time derivative of a function along a trajectory on $\Gamma(t)$ moving in the normal direction. This equation is supposed to hold pointwise on $\Gamma(t)$ on trajectories evolving from $\Gamma(0)$ with velocity $V\mathbf{v}$.

- (3) Find a time-dependent pair (\mathbf{u}, \mathbf{v}) with \mathbf{u} a scalar volumetric field and \mathbf{v} a scalar surface field such that

$$(1.6a) \quad \mathbf{u}_t + \nabla \cdot (b_\Omega \mathbf{u}) - \nabla \cdot (a_\Omega \nabla \mathbf{u}) + c_\Omega \mathbf{u} = 0 \quad \text{on } \Omega(t)$$

$$(1.6b) \quad (a_\Omega \nabla \mathbf{u} - (b_\Omega - V\mathbf{v})\mathbf{u}) \cdot \mathbf{v} + \alpha \mathbf{u} - \beta \mathbf{v} = 0 \quad \text{on } \Gamma(t)$$

$$(1.6c) \quad \partial^\circ \mathbf{v} + \nabla_\Gamma \cdot (b_\Gamma \mathbf{v}) - \nabla_\Gamma \cdot (a_\Gamma \mathbf{v}) + c_\Gamma \mathbf{v} + \beta \mathbf{v} - \alpha \mathbf{u} = 0 \quad \text{on } \Gamma(t)$$

$$(1.6d) \quad \mathbf{u}(\cdot, 0) = \mathbf{u}_0 \quad \text{on } \Omega_0 := \Omega(0)$$

$$(1.6e) \quad \mathbf{v}(\cdot, 0) = \mathbf{v}_0 \quad \text{on } \Gamma_0 := \Gamma(0),$$

where α and β are positive constants. Equation (1.6b) couples the equations posed on the domain $\Omega(t)$ and its boundary $\Gamma(t)$.

Remark 1.2. (a) We do not explain the models in the above equations other than to comment that examples may be derived as conservation laws for scalar quantities subject to diffusive and advective fluxes with linear reactions. Note that in these equations the only part of the material velocity w that appears is the normal velocity of $\Gamma(t)$.

- (b) Our formulation of these initial boundary value problems allows, by means of a tangential velocity field, for a reparametrisation of the evolving domains. In our definition of material velocity the velocity component tangential to $\Gamma(t)$ is used to define a parametrisation of the domains $\Omega(t)$ and $\Gamma(t)$. This is an *Arbitrary Lagrangian Eulerian (ALE)* approach. A consequence is that the differential operators and the function spaces in the abstract setting depend on this *ALE* velocity. In the discretisations the meshes we use are transported using this velocity.
- (c) Working with evolving triangulations on evolving domains has advantages when the domain is unknown and is to be found. For example the hypersurface $\Gamma(t)$ may be a free boundary or a surface evolving via a geometric evolution equation coupled to the parabolic equation on the bulk or surface domain, Pozzi and Stinner (2017); Kovács et al. (2017); Barrett, Deckelnick and Styles (2017); Pozzi and Stinner (2018). Evolving triangulated surfaces are often computed as approximations of geometric evolution flows, Deckelnick, Dziuk and Elliott (2005); Barrett, Garcke and Nürnberg (2019); Kovács, Li and Lubich (2019).
- (d) The analysis applies to the use of evolving finite element spaces in the case of domains which are time independent. This may be useful when devising schemes which evolve the mesh in time in order to adjust to the solution.

1.3. Contributions. The primary contributions of this work which generalises the evolving surface finite element continuous in time analysis of Dziuk and Elliott (2007, 2013a) are:-

- The analysis is carried out in a generalised abstract setting extending earlier work by allowing for arbitrary parametrisations and higher order approximations together with domains with boundaries.
- We construct evolving finite element spaces and derive approximation results for quasi-uniform evolving surface and bulk triangulations using isoparametric elements.

- We show that the resulting finite element methods satisfy the necessary geometric and interpolation estimates for the abstract theory to apply.
- We give a complete presentation of the theory for the numerical approximation of parabolic equations on evolving domains using evolving finite element spaces and give three examples of concrete realisations to initial boundary value problems involving time dependent domains in flat and curved space. In particular the approach to evolving bulk domains with boundary requires a more complex treatment than that of surfaces without boundary and the abstract theory is structured to allow this.
- The analysis provides error bounds for higher order isoparametric approximations of the case of evolving curved hypersurfaces, evolving bulk domains and evolving coupled surface- bulk systems.

1.4. Extensions.

- (a) All the theory presented in this paper will be applicable with the addition of sufficiently smooth right hand side functionals under natural appropriate assumptions.
- (b) Although we will apply our abstract formulation to settings where we approximate a known continuous domain, our intention is that this framework may also be applied to situations where the evolution of the domain is a priori unknown. One way to interpret this work would be to determine the minimum requirements of an evolving finite element method in order to have a sensible, well-posed method.
- (c) In this paper we do not consider the example of a parabolic PDE posed on an evolving n -dimensional curved sub-manifold $\Gamma(t)$ in \mathbb{R}^{n+1} with a moving boundary $\partial\Gamma(t)$ on which there is an appropriate boundary condition. On the other hand, it is possible to take the perspective in our first example on an evolving bulk domain that $\Omega(t) \subset \mathbb{R}^{n+2}$ is an evolving flat sub-manifold with moving boundary and work with the definitions from [Sec. 6](#) (see also [Ex. 6.7\(c\)](#)), though we choose not to follow this approach.

1.5. Outline. The article is set out in three parts. The first part comprises the abstract theory. In [Sec. 2](#), we introduce the abstract functional analytic setting in which we pose the continuous partial differential equations. An abstract analysis of evolving finite element methods is provided in [Sec. 3](#). The second part comprises the construction of and approximation theory for evolving finite element spaces. We introduce our basic theory for evolving bulk and evolving surface finite elements in [Sec. 4](#) and [Sec. 6](#). [Sec. 5](#) and [7](#) give technical details on relating the finite elements used in our computational methods to the structures in the underlying continuous problem. The third part comprises applications to three PDE settings. [Sec. 8](#) to [Sec. 10](#) apply these ideas to tackle three model problems. In [Sec. 11](#) results of numerical experiments are given confirming the proven error bounds. Finally, there is an appendix ([App. A](#)) with a technical result concerning a Faà di Bruno formula for parametric surfaces.

Part 1. Abstract theory

2. ABSTRACT FORMULATION

2.1. Evolving function spaces. We introduce an abstract functional analytic setting formulated by Alphonse, Elliott and Stinner (2015a) generalising the surface parabolic PDE setting of Vierling (2014). One of the key novelties of these works is to provide the basic theory for evolving Bochner-like spaces for evolving Hilbert spaces such as $H^1(\Gamma(t))$ in order make a definition similar to “ $L^2(0, T; H^1(\Gamma(t)))$ ”. Using this formulation, we can pose partial differential equations on evolving domains in a fully rigorous setting.

Remark 2.1. The work of Alphonse et al. (2015a) uses a Lagrangian formulation where the evolving domain is parametrised over the initial domain. This matches well with the arbitrary Lagrangian-Eulerian finite element methods we will consider. The setting may be applied to evolving parametrisations of fixed domains. A different functional analytic setting may be more appropriate for different discretisation approaches such as the trace finite element method (Olshanskii, Reusken and Xu, 2014; Olshanskii and Reusken, 2017) or the implicit surface approach (Dziuk and Elliott, 2010).

Definition 2.2 (Compatibility). For $t \in [0, T]$, let $\mathcal{X}(t)$ be a separable Hilbert space and denote by $\mathcal{X}_0 := \mathcal{X}(0)$. Let $\phi_t: \mathcal{X}_0 \rightarrow \mathcal{X}(t)$ be a family of invertible, linear homeomorphisms, with inverse $\phi_{-t}: \mathcal{X}(t) \rightarrow \mathcal{X}_0$, such that there exists $C_{\mathcal{X}} > 0$ such that for every $t \in [0, T]$

$$\begin{aligned} \|\phi_t \eta\|_{\mathcal{X}(t)} &\leq C_{\mathcal{X}} \|\eta\|_{\mathcal{X}_0} && \text{for all } \eta \in \mathcal{X}_0 \\ \|\phi_{-t} \eta\|_{\mathcal{X}_0} &\leq C_{\mathcal{X}}^{-1} \|\eta\|_{\mathcal{X}(t)} && \text{for all } \eta \in \mathcal{X}(t), \end{aligned}$$

and such that the map $t \mapsto \|\phi_t \eta\|_{\mathcal{X}(t)}$ is continuous for all $\eta \in \mathcal{X}_0$. Under these circumstances, we call the pair $(\mathcal{X}(t), \phi_t)_{t \in [0, T]}$ *compatible*. We call the map ϕ_t the *push-forward* operator and ϕ_{-t} the *pull-back* operator.

Remark 2.3. If $\mathcal{S}(t)$ is a closed subspace in $\mathcal{H}(t)$ for each $t \in [0, T]$ and ϕ_t maps $\mathcal{S}_0 := \mathcal{S}(0) \rightarrow \mathcal{S}(t)$, then $(\mathcal{S}(t), \phi_t|_{\mathcal{S}_0})_{t \in [0, T]}$ form a compatible pair.

Definition 2.4 (Evolving Hilbert triple). For each $t \in [0, T]$, let $\mathcal{V}(t)$ and $\mathcal{H}(t)$ be real, separable Hilbert spaces with $\mathcal{V}_0 := \mathcal{V}(0)$ and $\mathcal{H}_0 := \mathcal{H}(0)$ such that inclusion $\mathcal{V}(t) \subset \mathcal{H}(t)$ is continuous and dense. We will write $\|\cdot\|_{\mathcal{V}(t)}$ and $\|\cdot\|_{\mathcal{H}(t)}$ for the norms on $\mathcal{V}(t)$ and $\mathcal{H}(t)$, $(\cdot, \cdot)_{\mathcal{H}(t)}$ for the inner product on $\mathcal{H}(t)$ and $\langle \cdot, \cdot \rangle_{\mathcal{V}^*(t), \mathcal{V}(t)}$ for the pairing of $\mathcal{V}(t)$ with its dual. We assume there exists a family of linear homeomorphisms $\phi_t: \mathcal{H}_0 \rightarrow \mathcal{H}(t)$ such that $(\mathcal{H}(t), \phi_t)_{t \in [0, T]}$ and $(\mathcal{V}(t), \phi_t|_{\mathcal{V}_0})_{t \in [0, T]}$ are compatible. We will write ϕ_t for $\phi_t|_{\mathcal{V}_0}$. It follows that $\mathcal{H}(t) \subset \mathcal{V}^*(t)$ continuously and densely. Under these assumptions, we say that $(\mathcal{V}(t), \mathcal{H}(t), \mathcal{V}^*(t))_{t \in [0, T]}$ is an *evolving Hilbert triple*.

For a compatible pair, we can define an equivalent structure to Bochner spaces in an evolving context. For $(\mathcal{X}(t), \phi_t)_{t \in [0, T]}$ a compatible pair, we define $L_{\mathcal{X}}^2$ to be

$$(2.1) \quad L_{\mathcal{X}}^2 := \left\{ \eta: [0, T] \rightarrow \bigcup_{t \in [0, T]} \mathcal{X}(t) \times \{t\}, t \mapsto (\bar{\eta}(t), t) : \phi_{-(\cdot)} \bar{\eta}(\cdot) \in L^2(0, T; \mathcal{X}_0) \right\},$$

with norm

$$\|\eta\|_{L_{\mathcal{X}}^2} := \left(\int_0^T \|\bar{\eta}\|_{\mathcal{X}(t)}^2 dt \right)^{\frac{1}{2}}.$$

One can show that the space $L^2_{\mathcal{X}}$ is a separable Hilbert space (Alphonse et al., 2015a, Cor. 2.12), $L^2_{\mathcal{X}}$ is isomorphic to $L^2(0, T; \mathcal{X}_0)$ and

$$C_{\mathcal{X}}^{-1} \|\eta\|_{L^2_{\mathcal{X}}} \leq \|\phi_{-\cdot} \eta\|_{L^2(0, T; \mathcal{X}_0)} \leq C_{\mathcal{X}} \|\eta\|_{L^2_{\mathcal{X}}} \quad \text{for all } \eta \in L^2_{\mathcal{X}}.$$

For $k \geq 0$, we also define the space of smoothly evolving in time functions by

$$(2.2) \quad C_{\mathcal{X}}^k := \left\{ \eta \in L^2_{\mathcal{X}} : t \mapsto \phi_{-t} \eta(t) \in C^k([0, T], \mathcal{X}_0) \right\}$$

$$(2.3) \quad \mathcal{D}_{\mathcal{X}}(0, T) := \left\{ \eta \in L^2_{\mathcal{X}} : t \mapsto \phi_{-t} \eta(t) \in \mathcal{D}((0, T); \mathcal{X}_0) \right\},$$

where $\mathcal{D}((0, T), \mathcal{X}_0)$ is the space of \mathcal{X}_0 -valued infinitely differentiable functions compactly supported in the interval $(0, T)$.

For $\eta \in C_{\mathcal{X}}^1$, we can define a strong material derivative which we denote by $\partial^\bullet \eta \in C_{\mathcal{X}}^0$ by

$$(2.4) \quad \partial^\bullet \eta := \phi_t \left(\frac{d}{dt} (\phi_{-t} \eta) \right).$$

This is a temporal derivative which takes into account that fact that $\mathcal{X}(t)$ is changing as well as the function η .

Remark 2.5. If $(\mathcal{X}(t), \phi_t^{(1)})_{t \in [0, T]}$ and $(\mathcal{X}(t), \phi_t^{(2)})_{t \in [0, T]}$ are both compatible pairs, with $\phi_t^{(1)} \neq \phi_t^{(2)}$, then the spaces $L^2_{(\mathcal{X}, \phi^{(1)})}$ and $L^2_{(\mathcal{X}, \phi^{(2)})}$ induced using each push forward map are the same vector space with distinct but equivalent norms. On the other hand, in general, the spaces $C^k_{(\mathcal{X}, \phi^{(1)})}$ and $C^k_{(\mathcal{X}, \phi^{(2)})}$, when they are non-trivial, are different spaces for $k > 0$. In such cases where ambiguity will occur we will add the push-forward map to the subscript of $C^k_{(\cdot)}$ so no confusion will occur.

We can define a weak material derivative for which an integration by parts in time formula holds. This takes into account the evolution of the space $\mathcal{H}(t)$ and is often called a transport formula when applied to the derivative of the time dependent inner product. It generalises the notion of the Reynold's transport formula, Cermelli et al. (2005). In order to provide this definition, we require a further assumption on $\mathcal{H}(t)$.

Assumption 2.6. We shall assume the following for all $\eta_0, \zeta_0 \in \mathcal{H}_0$:

$$\begin{aligned} \theta(t, \eta_0) &:= \frac{d}{dt} \|\phi_t \eta_0\|_{\mathcal{H}(t)}^2 \text{ exists classically} \\ \eta_0 &\mapsto \theta(t, \eta_0) \text{ is continuous} \\ |\theta(t, \eta_0 + \zeta_0) - \theta(t, \eta_0 - \zeta_0)| &\leq c \|\eta_0\|_{\mathcal{H}_0} \|\zeta_0\|_{\mathcal{H}_0}, \end{aligned}$$

with the constant c independent of $t \in [0, T]$.

We define $\hat{g}(t; \cdot, \cdot): \mathcal{H}_0 \times \mathcal{H}_0 \rightarrow \mathbb{R}$ by

$$\hat{g}(t; \eta_0, \zeta_0) := \frac{1}{4} (\theta(t, \eta_0 + \zeta_0) - \theta(t, \eta_0 - \zeta_0)).$$

Then we have a bilinear form $g(t; \cdot, \cdot): \mathcal{H}(t) \times \mathcal{H}(t) \rightarrow \mathbb{R}$ by

$$(2.5) \quad g_0(t; \eta, \zeta) := \hat{g}(t; \phi_{-t} \eta, \phi_{-t} \zeta).$$

It can be shown that the map $t \mapsto g_0(t; \eta, \zeta)$ is measurable for $\eta, \zeta \in L^2_{\mathcal{H}}$ and we have the following bound independently of t :

$$(2.6) \quad |g_0(t; \eta, \zeta)| \leq c \|\eta\|_{\mathcal{H}(t)} \|\zeta\|_{\mathcal{H}(t)}.$$

We say a function $\eta \in L^2_{\mathcal{V}}$ has a weak material derivative $\partial^\bullet \eta \in L^2_{\mathcal{V}^*}$ if

$$\int_0^T \langle \partial^\bullet \eta, \zeta \rangle_{\mathcal{V}^*(t), \mathcal{V}(t)} dt = \int_0^T -(\eta, \partial^\bullet \zeta)_{\mathcal{H}(t)} + g_0(t; \eta, \zeta) dt$$

for all $\zeta \in \mathcal{D}_{\mathcal{V}}(0, T)$.

Remark 2.7. The weak and strong material derivatives coincide for $\eta \in C^1_{\mathcal{V}}$.

Lemma 2.8 (Abstract transport formula). *For all $\eta, \zeta \in L^2_{\mathcal{V}}$ with weak material derivatives $\partial^\bullet \eta, \partial^\bullet \zeta \in L^2_{\mathcal{V}^*}$ we have*

$$(2.7) \quad \frac{d}{dt} (\eta, \zeta)_{\mathcal{H}(t)} = \langle \partial^\bullet \eta, \zeta \rangle_{\mathcal{V}^*(t), \mathcal{V}(t)} + \langle \partial^\bullet \zeta, \eta \rangle_{\mathcal{V}^*(t), \mathcal{V}(t)} + g_0(t; \eta, \zeta).$$

Proof. See [Alphonse et al. \(2015a, Thm. 2.40\)](#). □

The natural solution space is the space $\mathcal{W}(\mathcal{V}, \mathcal{V}^*)$ given by

$$(2.8) \quad \mathcal{W}(\mathcal{V}, \mathcal{V}^*) := \{\eta \in L^2_{\mathcal{V}} : \partial^\bullet \eta \in L^2_{\mathcal{V}^*}\},$$

which we equip with the inner product

$$(\eta, \zeta)_{\mathcal{W}(\mathcal{V}, \mathcal{V}^*)} = \int_0^T (\eta, \zeta)_{\mathcal{V}(t)} dt + \int_0^T (\partial^\bullet \eta, \partial^\bullet \zeta)_{\mathcal{V}^*(t)} dt.$$

Assumption 2.9. Let $W(\mathcal{V}_0, \mathcal{V}_0^*)$ be the space given by

$$W(\mathcal{V}_0, \mathcal{V}_0^*) := \{\eta \in L^2(0, T; \mathcal{V}_0) : \eta_t \in L^2(0, T; \mathcal{V}_0^*)\},$$

equipped with the inner product

$$(\eta, \zeta)_{W(\mathcal{V}_0, \mathcal{V}_0^*)} = \int_0^T (\eta, \zeta)_{\mathcal{V}} dt + \int_0^T (\eta', \zeta')_{\mathcal{V}^*} dt.$$

We assume there is an *evolving space equivalence* between $\mathcal{W}(\mathcal{V}, \mathcal{V}^*)$ and $W(\mathcal{V}_0, \mathcal{V}_0^*)$ that is

$$\eta \in \mathcal{W}(\mathcal{V}, \mathcal{V}^*) \text{ if and only if } \phi_{-(\cdot)} \eta(\cdot) \in W(\mathcal{V}_0, \mathcal{V}_0^*)$$

and there exists $c_1, c_2 > 0$ such that

$$c_1 \|\phi_{-(\cdot)} \eta(\cdot)\|_{W(\mathcal{V}_0, \mathcal{V}_0^*)} \leq \|\eta\|_{\mathcal{W}(\mathcal{V}, \mathcal{V}^*)} \leq c_2 \|\phi_{-(\cdot)} \eta(\cdot)\|_{W(\mathcal{V}_0, \mathcal{V}_0^*)}.$$

2.2. Abstract formulation of the partial differential equation. Let $T > 0$. We assume we are in the setting that we have an evolving Hilbert triple $(\mathcal{V}(t), \mathcal{H}(t), \mathcal{V}^*(t))_{t \in [0, T]}$ and [Ass. 2.6](#) and [2.9](#) hold so that we have a weak material derivative, which we denote, $\partial^\bullet \eta$ for appropriate η , and a transport formula for the $\mathcal{H}(t)$ -inner product.

We assume that we have three time dependent bilinear forms m, g , and a

$$m(t; \cdot, \cdot): \mathcal{H}(t) \times \mathcal{H}(t) \rightarrow \mathbb{R}$$

$$g(t; \cdot, \cdot): \mathcal{H}(t) \times \mathcal{H}(t) \rightarrow \mathbb{R}$$

$$a(t; \cdot, \cdot): \mathcal{V}(t) \times \mathcal{V}(t) \rightarrow \mathbb{R}.$$

We consider problems of the following form:

Problem 2.10. *Given $u_0 \in \mathcal{H}_0$, find $u \in \mathcal{W}(\mathcal{V}, \mathcal{V}^*)$ such that for almost every $t \in [0, T]$,*

$$(2.9) \quad m(t; \partial^\bullet u, \zeta) + g(t; u, \zeta) + a(t; u, \zeta) = 0 \quad \text{for all } \zeta \in \mathcal{V}(t),$$

subject to the initial condition $u(0) = u_0$.

Remark 2.11. The abstract formulation of Alphonse et al. (2015a) allows for a weaker formulation with solutions in $\mathcal{W}(\mathcal{V}, \mathcal{V}^*)$ (2.8) and initial condition in \mathcal{H}_0 . However in order to obtain optimal order error bounds we require more smoothness for the solution. We leave the consideration of error analysis for solutions which are less regular in time to a future work.

In order to make sense of this formulation we restrict to the following assumptions on the bilinear forms holding for each $t \in [0, T]$.

Assumptions on m : First, we assume that $m(t; \cdot, \cdot)$ is symmetric:

$$(M1) \quad m(t; \eta, \zeta) = m(t; \zeta, \eta) \quad \text{for } \eta, \zeta \in \mathcal{H}(t).$$

We assume that there exists $c_1, c_2 > 0$ such that for all $t \in [0, T]$, we have

$$(M2) \quad c_1 \|\eta\|_{\mathcal{H}(t)} \leq (m(t; \eta, \eta))^{1/2} \leq c_2 \|\eta\|_{\mathcal{H}(t)} \quad \text{for all } \eta \in \mathcal{H}(t).$$

Assumptions on g : We assume the bilinear form $g(t; \cdot, \cdot)$ satisfies

$$(G1) \quad \frac{d}{dt} m(t; \eta, \zeta) = m(t; \partial^\bullet \eta, \zeta) + m(t; \eta, \partial^\bullet \zeta) + g(t; \eta, \zeta) \quad \text{for } \eta, \zeta \in C_{\mathcal{H}}^1,$$

and such that there exists $c_3 > 0$ such that for all $t \in [0, T]$

$$(G2) \quad |g(t; \eta, \zeta)| \leq c_3 \|\eta\|_{\mathcal{H}(t)} \|\zeta\|_{\mathcal{H}(t)} \quad \text{for } \eta, \zeta \in \mathcal{H}(t).$$

Assumptions on a : (a) We assume that the map

$$(A1) \quad t \mapsto a(t; \eta, \zeta) \quad \text{for } \eta, \zeta \in L_{\mathcal{V}}^2$$

is measurable and can be decomposed

$$(A2) \quad a(t; \eta, \zeta) = a_s(t; \eta, \zeta) + a_n(\eta, \zeta) \quad \text{for } \eta, \zeta \in L_{\mathcal{V}}^2,$$

where a_s and a_n are both measurable bilinear forms:

$$a_s(t; \cdot, \cdot): \mathcal{V}(t) \times \mathcal{V}(t) \rightarrow \mathbb{R}, \quad a_n(t; \cdot, \cdot): \mathcal{H}(t) \times \mathcal{V}(t) \rightarrow \mathbb{R}.$$

We assume that a_s is symmetric and allow $a_n \equiv 0$.

(b) We assume there exists $c_4, c_5, c_6, c_7 > 0$ such that

$$(A3) \quad a_s(t; \eta, \eta) \geq c_4 \|\eta\|_{\mathcal{V}(t)}^2 - c_5 \|\eta\|_{\mathcal{H}(t)}^2 \quad \text{for } \eta \in \mathcal{V}(t)$$

$$(A_s4) \quad |a_s(t; \eta, \zeta)| \leq c_6 \|\eta\|_{\mathcal{V}(t)} \|\zeta\|_{\mathcal{V}(t)} \quad \text{for } \eta, \zeta \in \mathcal{V}(t)$$

$$(A_n4) \quad |a_n(t; \eta, \zeta)| \leq c_7 \|\eta\|_{\mathcal{H}(t)} \|\zeta\|_{\mathcal{V}(t)} \quad \text{for } \eta \in \mathcal{H}(t), \zeta \in \mathcal{V}(t).$$

We note that together (A_s4) and (A_n4) imply

$$(A4) \quad |a(t; \eta, \zeta)| \leq (c_6 + c_7) \|\eta\|_{\mathcal{V}(t)} \|\zeta\|_{\mathcal{V}(t)} \quad \text{for } \eta, \zeta \in \mathcal{V}(t).$$

(c) We assume the existence of bilinear forms $b_s(t; \cdot, \cdot): \mathcal{V}(t) \times \mathcal{V}(t) \rightarrow \mathbb{R}$ and $b_n(t; \cdot, \cdot): \mathcal{H}(t) \times \mathcal{V}(t) \rightarrow \mathbb{R}$ such that

(B_s1)

$$\frac{d}{dt} a_s(t; \eta, \zeta) = a_s(t; \partial^\bullet \eta, \zeta) + a_s(t; \eta, \partial^\bullet \zeta) + b_s(t; \eta, \zeta) \quad \text{for all } \eta, \zeta \in C_{\mathcal{V}}^1$$

(B_n1)

$$\frac{d}{dt} a_n(t; \eta, \zeta) = a_n(t; \partial^\bullet \eta, \zeta) + a_n(\eta, \partial^\bullet \zeta) + b_n(t; \eta, \zeta) \quad \text{for all } \eta \in C_{\mathcal{H}}^1, \zeta \in C_{\mathcal{V}}^1,$$

and that there exists $c_8, c_9 > 0$ such that

$$\begin{aligned} (\text{B}_s2) \quad & |b_s(t; \eta, \zeta)| \leq c_8 \|\eta\|_{\mathcal{V}(t)} \|\zeta\|_{\mathcal{V}(t)} && \text{for all } \eta, \zeta \in \mathcal{V}(t) \\ (\text{B}_n2) \quad & |b_n(t; \eta, \zeta)| \leq c_9 \|\eta\|_{\mathcal{H}(t)} \|\zeta\|_{\mathcal{V}(t)} && \text{for all } \eta \in \mathcal{H}(t), \zeta \in \mathcal{V}(t). \end{aligned}$$

(d) We define $b(t; \cdot, \cdot): \mathcal{V}(t) \times \mathcal{V}(t) \rightarrow \mathbb{R}$ to be

$$(\text{B1}) \quad b(t; \eta, \zeta) := b_s(t; \eta, \zeta) + b_n(t; \eta, \zeta) \quad \text{for } \eta, \zeta \in \mathcal{V}(t)$$

and note that [\(B_s2\)](#) and [\(B_n2\)](#) together imply that

$$(\text{B2}) \quad |b(t; \eta, \zeta)| \leq (c_8 + c_9) \|\eta\|_{\mathcal{V}(t)} \|\zeta\|_{\mathcal{V}(t)} \quad \text{for all } \eta, \zeta \in \mathcal{V}(t).$$

Remark 2.12. We allow for the case that a is non-symmetric. This is similar to the choice of [Alphonse et al. \(2015a\)](#) but in contrast to much of the finite element literature (e.g. [Elliott and Venkataraman \(2015\)](#) use different bilinear forms for diffusion and advection terms in a parabolic operator).

Assumption 2.13. We assume there exists a basis $\{\eta_j^0\}_{j \in \mathbb{N}}$ of \mathcal{V}_0 and a sequence $\{u_{0N}\}_{N \in \mathbb{N}}$ with $u_{0N} \in \text{span}\{\eta_1^0, \dots, \eta_N^0\}$ for each N such that there exists $c_1, c_2 > 0$ (which do not depend on N or u_0) with

$$\begin{aligned} u_{0N} &\rightarrow u_0 && \text{in } \mathcal{V}_0 \\ \|u_{0N}\|_{\mathcal{H}_0} &\leq c_1 \|u_0\|_{\mathcal{H}_0} \\ \|u_{0N}\|_{\mathcal{V}_0} &\leq c_2 \|u_0\|_{\mathcal{V}_0}. \end{aligned}$$

Remark 2.14. In the case of \mathcal{V}_0 being compactly embedded in \mathcal{H}_0 , [Ass. 2.13](#) follows by Hilbert-Schmidt theory

Theorem 2.15. *Let Assumptions [\(M1\)](#), [\(M2\)](#), [\(G1\)](#), [\(G2\)](#), [\(A1\)](#), [\(A2\)](#), [\(A3\)](#), [\(A_s4\)](#), [\(B_s1\)](#), [\(B_n1\)](#), [\(B_s2\)](#), [\(B_n2\)](#) and [Ass. 2.13](#) hold. Then problem [\(2.9\)](#) has a unique solution which satisfies the stability bound*

$$(2.10) \quad \sup_{t \in [0, T]} \|u\|_{\mathcal{H}(t)}^2 + \int_0^T \|u\|_{\mathcal{V}(t)}^2 dt \leq c(T) \|u_0\|_{\mathcal{H}_0}^2$$

and if $u_0 \in \mathcal{V}_0$ then

$$(2.11) \quad \sup_{t \in [0, T]} \|u\|_{\mathcal{V}(t)}^2 + \int_0^T \|\partial^\bullet u\|_{\mathcal{H}(t)}^2 dt \leq c(T) \|u_0\|_{\mathcal{V}_0}^2.$$

Proof. Employing [Ass. 2.13](#) existence may be proved by a Galerkin argument similar to [Alphonse et al. \(2015a, Thm. 3.6 and 3.13\)](#). The a priori estimates can be shown for Galerkin approximations and then used in standard compactness arguments. We do not show the details here but indicate the arguments in deriving estimates in the continuous setting.

Testing [\(2.9\)](#) with u :

$$m(t; \partial^\bullet u, u) + g(t; u, u) + a(t; u, u) = 0.$$

[\(G1\)](#) gives after integrating in time

$$m(t; u, u) + \int_0^t a(t'; u, u) dt' = m(0, u_0, u_0) - \int_0^t g(t', u, u) dt'.$$

Applying (M2), (A3), (A_n4) and (G2):

$$\begin{aligned} c_1^2 \|\mathbf{u}\|_{\mathcal{H}(t)}^2 + \int_0^t (c_4 \|\mathbf{u}\|_{\mathcal{V}(t')}^2 - c_5 \|\mathbf{u}\|_{\mathcal{H}(t')}^2 - c_7 \|\mathbf{u}\|_{\mathcal{V}(t')} \|\mathbf{u}\|_{\mathcal{H}(t')}) dt' \\ \leq c_2^2 \|\mathbf{u}_0\|_{\mathcal{H}_0}^2 + c_3 \int_0^t \|\mathbf{u}\|_{\mathcal{H}(t')}^2 dt'. \end{aligned}$$

We infer that

$$c_1^2 \|\mathbf{u}\|_{\mathcal{H}(t)}^2 + \int_0^t \frac{c_4}{2} \|\mathbf{u}\|_{\mathcal{V}(t')}^2 dt \leq c_2^2 \|\mathbf{u}_0\|_{\mathcal{H}_0}^2 + (c_5 + \frac{c_7^2}{2c_4} + c_3) \int_0^t \|\mathbf{u}\|_{\mathcal{H}(t')}^2 dt'$$

and applying a Grönwall inequality we see the first stability bound.

The bound (2.11) uses the decomposition $a(t; \cdot, \cdot) = a_s(t; \cdot, \cdot) + a_n(t; \cdot, \cdot)$ (A2). We test (2.9) with $\partial^\bullet \mathbf{u}$

$$m(t; \partial^\bullet \mathbf{u}, \partial^\bullet \mathbf{u}) + g(t; \mathbf{u}, \partial^\bullet \mathbf{u}) + a(t; \mathbf{u}, \partial^\bullet \mathbf{u}) = 0.$$

(B_s1) and (B_n1) gives

$$a(\mathbf{u}, \partial^\bullet \mathbf{u}) = \frac{d}{dt} (\frac{1}{2} a_s(\mathbf{u}, \mathbf{u}) + a_n(\mathbf{u}, \mathbf{u})) - \frac{1}{2} b_s(\mathbf{u}, \mathbf{u}) - b_n(\mathbf{u}, \mathbf{u}) - a_n(\partial^\bullet \mathbf{u}, \mathbf{u}),$$

so we have

$$\begin{aligned} m(t; \partial^\bullet \mathbf{u}, \partial^\bullet \mathbf{u}) + \frac{d}{dt} (\frac{1}{2} a_s(t; \mathbf{u}, \mathbf{u}) + a_n(t; \mathbf{u}, \mathbf{u})) \\ = -g(t; \mathbf{u}, \partial^\bullet \mathbf{u}) + \frac{1}{2} b_s(t; \mathbf{u}, \mathbf{u}) + b_n(t; \mathbf{u}, \mathbf{u}) + a_n(t; \partial^\bullet \mathbf{u}, \mathbf{u}). \end{aligned}$$

Integrating forwards in time gives

$$\begin{aligned} \int_0^t m(t'; \partial^\bullet \mathbf{u}, \partial^\bullet \mathbf{u}) dt' + (\frac{1}{2} a_s(t; \mathbf{u}, \mathbf{u}) + a_n(t; \mathbf{u}, \mathbf{u})) \\ = (\frac{1}{2} a_s(0; \mathbf{u}_0, \mathbf{u}_0) + a_n(0; \mathbf{u}_0, \mathbf{u}_0)) \\ + \int_0^t (-g(t'; \mathbf{u}, \partial^\bullet \mathbf{u}) + \frac{1}{2} b_s(t'; \mathbf{u}, \mathbf{u}) + b_n(t'; \mathbf{u}, \mathbf{u}) + a_n(t'; \partial^\bullet \mathbf{u}, \mathbf{u})) dt'. \end{aligned}$$

Applying (A3), (A_n4), and a Young's inequality we observe:

$$\begin{aligned} & (\frac{1}{2} a_s(t; \mathbf{u}, \mathbf{u}) + a_n(t; \mathbf{u}, \mathbf{u})) \\ & \geq \frac{c_4}{2} \|\mathbf{u}\|_{\mathcal{V}(t)}^2 - c_5 \|\mathbf{u}\|_{\mathcal{H}(t)}^2 - c_7 \|\mathbf{u}\|_{\mathcal{V}(t)} \|\mathbf{u}\|_{\mathcal{H}(t)} \\ & \geq \frac{c_4}{2} \|\mathbf{u}\|_{\mathcal{V}(t)}^2 - c_5 \|\mathbf{u}\|_{\mathcal{H}(t)}^2 - (\frac{c_4}{4} \|\mathbf{u}\|_{\mathcal{V}(t)}^2 + \frac{c_7^2}{c_4} \|\mathbf{u}\|_{\mathcal{H}(t)}^2) \\ & = \frac{c_4}{4} \|\mathbf{u}\|_{\mathcal{V}(t)}^2 - (c_5 + \frac{c_7^2}{c_4}) \|\mathbf{u}\|_{\mathcal{H}(t)}^2; \end{aligned}$$

applying (A_s4) and (A_n4), we see

$$(\frac{1}{2} a_s(0; \mathbf{u}_0, \mathbf{u}_0) + a_n(0; \mathbf{u}_0, \mathbf{u}_0)) \leq (\frac{c_5}{2} + c_7) \|\mathbf{u}_0\|_{\mathcal{V}_0}^2.$$

From the previous two inequalities with (M2), (G2), (B₃2), (B_n2) and (A_n4), we infer

$$\begin{aligned}
& c_1 \int_0^t \|\partial^\bullet \mathbf{u}\|_{\mathcal{H}(t')}^2 dt' + \frac{c_4}{4} \|\mathbf{u}\|_{\mathcal{V}(t)}^2 - (c_5 + \frac{c_7^2}{c_4}) \|\mathbf{u}\|_{\mathcal{H}(t)}^2 \\
& \leq (\frac{c_5}{2} + c_7) \|\mathbf{u}_0\|_{\mathcal{V}_0}^2 \\
& \quad + \int_0^t (c_3 \|\mathbf{u}\|_{\mathcal{H}(t')} \|\partial^\bullet \mathbf{u}\|_{\mathcal{H}(t')} + \frac{c_8}{2} \|\mathbf{u}\|_{\mathcal{V}(t')}^2 + c_9 \|\mathbf{u}\|_{\mathcal{V}(t')}^2 + c_7 \|\partial^\bullet \mathbf{u}\|_{\mathcal{H}(t')} \|\mathbf{u}\|_{\mathcal{V}(t')}) dt' \\
& \leq (\frac{c_5}{2} + c_7) \|\mathbf{u}_0\|_{\mathcal{V}_0}^2 + \int_0^t ((\frac{4c_3^2}{c_1} + \frac{c_8}{2} + c_9 + \frac{4c_7^2}{c_1}) \|\mathbf{u}\|_{\mathcal{V}(t')}^2 + \frac{c_1}{2} \|\partial^\bullet \mathbf{u}\|_{\mathcal{H}(t')}^2) dt'.
\end{aligned}$$

Rearranging and applying a Grönwall inequality gives the desired result. \square

Remark 2.16. Note that \mathbf{u} also satisfies the variational form of (2.9)

$$(2.12) \quad \frac{d}{dt} m(t; \mathbf{u}, \zeta) + a(t; \mathbf{u}, \zeta) = m(t; \mathbf{u}, \partial^\bullet \zeta) \quad \text{for } \zeta \in L^2_{\mathcal{V}} \text{ with } \partial^\bullet \zeta \in L^2_{\mathcal{H}}.$$

3. ABSTRACT DISCRETISATION ANALYSIS

In this section we present an abstract discretisation and a numerical analysis. We assume that for each $h \in (0, h_0)$ there are Hilbert spaces $(\mathcal{H}_h(t), \|\cdot\|_{\mathcal{H}_h(t)})$ and $(\mathcal{V}_h(t), \|\cdot\|_{\mathcal{V}_h(t)})$ for all $t \in [0, T]$, for some value of h_0 fixed throughout this section. These spaces are used to help with the stability and error analysis. We assume that all constants are independent of $h \in (0, h_0)$ unless indicated. Throughout this section the integer k will denote a further discretisation parameter denoting the order of approximation. Our method will be based in a finite dimensional subspace $\mathcal{S}_h(t) \subset \mathcal{V}_h(t)$.

- We assume that the evolving Hilbert space $\mathcal{V}_h(t)$ is continuously embedded in $\mathcal{H}_h(t)$ uniformly for $h \in (0, h_0)$: For the two norms $\|\cdot\|_{\mathcal{H}_h(t)}$ and $\|\cdot\|_{\mathcal{V}_h(t)}$ there exists a constant $c_{10} > 0$ such that for all $h \in (0, h_0)$ and all $t \in (0, T)$, we have

$$(3.1) \quad \|\boldsymbol{\eta}_h\|_{\mathcal{H}_h(t)} \leq c_{10} \|\boldsymbol{\eta}_h\|_{\mathcal{V}_h(t)} \quad \text{for all } \boldsymbol{\eta}_h \in \mathcal{V}_h(t).$$

- We assume we have a push forward map $\phi_t^h: \mathcal{H}_{h,0} := \mathcal{H}_h(0) \rightarrow \mathcal{H}_h(t)$ such that $(\mathcal{H}_h(t), \phi_t^h)_{t \in [0, T]}$ and $(\mathcal{V}_h(t), \phi_t^h)_{t \in [0, T]}$ ($\mathcal{V}_{h,0} := \mathcal{V}_h(0)$) are compatible pairs (Def. 2.2) uniformly in h : That is there exists $c_{11}, c_{12} > 0$ such that, for all $h \in (0, h_0)$,

$$(3.2) \quad \begin{aligned} c_{11}^{-1} \|\boldsymbol{\eta}_h\|_{\mathcal{H}_{h,0}} &\leq \left\| \phi_t^h \boldsymbol{\eta}_h \right\|_{\mathcal{H}_h(t)} \leq c_{11} \|\boldsymbol{\eta}_h\|_{\mathcal{H}_{h,0}} & \text{for all } \boldsymbol{\eta}_h \in \mathcal{H}_{h,0} \\ c_{12}^{-1} \|\boldsymbol{\eta}_h\|_{\mathcal{V}_{h,0}} &\leq \left\| \phi_t^h \boldsymbol{\eta}_h \right\|_{\mathcal{V}_h(t)} \leq c_{12} \|\boldsymbol{\eta}_h\|_{\mathcal{V}_{h,0}} & \text{for all } \boldsymbol{\eta}_h \in \mathcal{V}_{h,0}. \end{aligned}$$

- This allows us to define the spaces $L^2_{\mathcal{H}_h}, L^2_{\mathcal{V}_h}$ and $C^1_{\mathcal{H}_h}, C^1_{\mathcal{V}_h}$ as in (2.1) and (2.2). For $\boldsymbol{\eta}_h \in C^1_{\mathcal{H}_h}$, we denote by $\partial_h^\bullet \boldsymbol{\eta}_h$ the (strong) material derivative (c.f. (2.4)) with respect to the push-forward map ϕ_t^h defined by

$$(3.3) \quad \partial_h^\bullet \boldsymbol{\eta}_h := \phi_t^h \left(\frac{d}{dt} \phi_{-t}^h \boldsymbol{\eta}_h \right).$$

3.1. Abstract discrete method. Let $T > 0$ and $h \in (0, h_0)$. Let $\{\mathcal{S}_h(t)\}_{t \in [0, T]}$ be an evolving, finite-dimensional space which is a subspace of $\mathcal{V}_h(t)$ at each $t \in [0, T]$ and satisfies $\phi_t^h(\mathcal{S}_{h,0}) = \mathcal{S}_h(t)$ (where $\mathcal{S}_{h,0} = \mathcal{S}_h(0)$). Since $\mathcal{S}_h(t)$ is a closed subspace of $\mathcal{V}_h(t)$ it is a Hilbert space and forms a compatible pair $(\mathcal{S}_h(t), \phi_t^h|_{\mathcal{S}_{h,0}})_{t \in [0, T]}$ (Rem. 2.3). In particular, we have well defined spaces $L_{\mathcal{S}_h}^2$ (2.1) and $C_{\mathcal{S}_h}^1$ (2.2) and the material derivative $\partial_h^\bullet \chi_h$ is well defined for $\chi_h \in C_{\mathcal{S}_h}^1$ ((2.4) and (3.3)).

Basis functions. Let the dimension of $\mathcal{S}_h(t)$ be N for all $t \in [0, T]$. We write $\{\chi_i(0)\}_{i=1}^N$ for a basis of $\mathcal{S}_{h,0}$ and push-forward to construct a time dependent basis $\{\chi_i(t)\}_{i=1}^N$ of $\mathcal{S}_h(t)$ by

$$(3.4) \quad \chi_i(t) = \phi_t^h(\chi_i(0)).$$

The following important transport properties of the basis functions hold.

Lemma 3.1. *The material derivative of a basis function is zero,*

$$\partial_h^\bullet \chi_j = 0 \quad \text{for } 1 \leq j \leq N.$$

Furthermore, any function $\chi_h \in C_{\mathcal{S}_h}^1$, which can be written as $\chi_h = \sum_{j=1}^N \gamma_j(t) \chi_j(t)$, satisfies

$$(3.5) \quad \partial_h^\bullet \chi_h(x, t) = \sum_{i=1}^N \dot{\gamma}_i(t) \chi_i(\cdot, t) \quad \text{for } x \in \Gamma_h(t).$$

Proof. By definition, it follows that

$$(3.6) \quad \partial_h^\bullet \chi_j = \phi_t \left(\frac{d}{dt} \phi_{-t} \chi_j(t) \right) = \phi_t \left(\frac{d}{dt} \chi_j(0) \right) = 0$$

so that for a decomposition

$$\chi_h(t) := \sum_{j=1}^N \gamma_j(t) \chi_j(t) \quad \text{for all } \chi_h \in \mathcal{S}_h(t),$$

we compute that

$$\partial_h^\bullet \chi_h = \sum_{j=1}^N \dot{\gamma}_j(t) \chi_j(t) \quad \text{for all } \chi_h \in C_{\mathcal{S}_h}^1. \quad \square$$

Discrete bilinear forms. Let m_h and a_h be two time dependent bilinear forms:

$$m_h(t; \cdot, \cdot): \mathcal{H}_h(t) \times \mathcal{H}_h(t) \rightarrow \mathbb{R}$$

$$a_h(t; \cdot, \cdot): \mathcal{V}_h(t) \times \mathcal{V}_h(t) \rightarrow \mathbb{R}.$$

We make assumptions similar to those in Sec. 2.2.

We assume that $m_h(t; \cdot, \cdot)$ is symmetric:

$$(M_h1) \quad m_h(t; \eta_h, \zeta_h) = m_h(t; \zeta_h, \eta_h) \quad \text{for } \eta_h, \zeta_h \in \mathcal{H}_h(t).$$

We assume that there exists $c_{13}, c_{14} > 0$ such that for all $t \in [0, T]$, we have

$$(M_h2) \quad c_{13} \|\eta_h\|_{\mathcal{H}_h(t)} \leq (m_h(t; \eta_h, \eta_h))^{\frac{1}{2}} \leq c_{14} \|\eta_h\|_{\mathcal{H}_h(t)} \quad \text{for } \eta_h \in \mathcal{H}_h(t).$$

We assume we have a transport formula for the bilinear form m_h : there exists a bilinear form $g_h(t; \cdot, \cdot): \mathcal{H}_h(t) \times \mathcal{H}_h(t) \rightarrow \mathbb{R}$ such that

$$(G_h1) \quad \frac{d}{dt} m_h(t; \eta_h, \zeta_h) = m_h(t; \partial_h^\bullet \eta_h, \zeta_h) + m_h(t; \eta_h, \partial_h^\bullet \zeta_h) + g_h(t; \eta_h, \zeta_h) \quad \text{for } \eta_h, \zeta_h \in C_{\mathcal{H}_h}^1.$$

We assume that there exists $c_{15} > 0$ such that for all $t \in [0, T]$

$$(G_h2) \quad |g_h(t; \eta_h, \zeta_h)| \leq c_{15} \|\eta_h\|_{\mathcal{H}_h(t)} \|\zeta_h\|_{\mathcal{H}_h(t)} \quad \text{for } \eta_h, \zeta_h \in \mathcal{H}_h(t).$$

We assume that the map

$$(A_h1) \quad t \mapsto a_h(t; \eta_h, \zeta_h) \quad \text{for } \eta_h, \zeta_h \in L^2_{\mathcal{V}_h},$$

is measurable, and there exists constants $c_{16}, c_{17}, c_{18} > 0$ such that for all $t \in [0, T]$, we have

$$(A_h2) \quad a_h(t; \eta_h, \eta_h) \geq c_{16} \|\eta_h\|_{\mathcal{V}_h(t)}^2 - c_{17} \|\eta_h\|_{\mathcal{H}_h(t)}^2 \quad \text{for } \eta_h \in \mathcal{V}_h(t)$$

$$(A_h3) \quad |a_h(t; \eta_h, \zeta_h)| \leq c_{18} \|\eta_h\|_{\mathcal{V}_h(t)} \|\zeta_h\|_{\mathcal{V}_h(t)} \quad \text{for } \eta_h, \zeta_h \in \mathcal{V}_h(t).$$

We assume a transport formula for the a_h bilinear form, that there exists a bilinear form $b_h(t; \cdot, \cdot): \mathcal{V}_h(t) \times \mathcal{V}_h(t) \rightarrow \mathbb{R}$ such that

$$(B_h1) \quad \frac{d}{dt} a_h(t; \eta_h, \zeta_h) = a_h(t; \partial_h^\bullet \eta_h, \zeta_h) + a_h(t; \eta_h, \partial_h^\bullet \zeta_h) + b_h(t; \eta_h, \zeta_h) \quad \text{for } \eta_h, \zeta_h \in C^1_{\mathcal{V}_h}$$

and that there exists $c_{19} > 0$ such that for all $t \in [0, T]$ we have

$$(B_h2) \quad |b_h(t; \eta_h, \zeta_h)| \leq c_{19} \|\eta_h\|_{\mathcal{V}_h(t)} \|\zeta_h\|_{\mathcal{V}_h(t)} \quad \text{for } \eta_h, \zeta_h \in \mathcal{V}_h(t).$$

Abstract discrete variational problem and well posedness. Motivated by the variational form (2.12), we consider semi-discrete problems of the following form:

Problem 3.2. Given $U_{h,0} \in \mathcal{S}_{h,0}$, find $U_h \in C^1_{\mathcal{S}_h}$ such that $U_h(0) = U_{h,0}$ and

$$(3.7) \quad \frac{d}{dt} m_h(t; U_h, \chi_h) + a_h(t; U_h, \chi_h) = m_h(t; U_h, \partial_h^\bullet \chi_h) \quad \text{for all } \chi_h \in C^1_{\mathcal{S}_h}.$$

We note that due to Assumption (G_h1), the discrete scheme (3.7) can be re-written as

$$(3.8) \quad m_h(t; \partial_h^\bullet U_h, \chi_h) + g_h(t; U_h, \chi_h) + a_h(t; U_h, \chi_h) = 0 \quad \text{for } \chi_h \in C^1_{\mathcal{S}_h}.$$

The solution U_h may be written as a decomposition into the time dependent basis functions $\{\chi_i\}_{i=1}^N$ of $\{\mathcal{S}_h(t)\}_{t \in [0, T]}$,

$$(3.9) \quad U_h(x, t) = \sum_{i=1}^N \alpha_i(t) \chi_i(x, t) \quad \text{for } x \in \Gamma_h(t),$$

where $\alpha(t) = (\alpha_1(t), \dots, \alpha_N(t)) \in \mathbb{R}^N$. Using this notation Prob. 3.2 is equivalent to finding a solution $\alpha \in C^1([0, T]; \mathbb{R}^N)$ of the (finite dimensional) system of ordinary differential equations:

$$(3.10) \quad \frac{d}{dt} (\mathcal{M}(t) \alpha(t)) + \mathcal{S}(t) \alpha(t) = 0,$$

where

$$\mathcal{M}(t)_{ij} = m_h(t; \chi_j, \chi_i) \quad \mathcal{S}(t)_{ij} = a_h(t; \chi_j, \chi_i) \quad \text{for } i, j = 1, \dots, N.$$

Here, we have used the fact that $\partial_h^\bullet \chi_i = 0$ for $1 \leq i \leq N$.

We first wish to show that there exists a solution to our discrete scheme satisfying a stability bound similar to (2.10) for the continuous case. Due to our abstract formulation the calculations follow in a similar way to Thm. 2.15.

Theorem 3.3 (Existence and stability of finite element method). *Let Assumptions (M_h1), (M_h2), (G_h1), (G_h2), (A_h1), (A_h2), (A_h3), (B_h1) and (B_h2) hold with constants independent of $h \in (0, h_0)$. Then (3.7) has a unique solution $U_h \in C_{S_h}^1$ with $\partial_h^\bullet U_h \in C_{S_h}^0$ and there exists a constant $C(T) > 0$ independent of $h \in (0, h_0)$ such that*

$$(3.11) \quad \sup_{t \in (0, T)} \|U_h\|_{\mathcal{H}_h(t)}^2 + \int_0^T \|U_h\|_{\mathcal{V}_h(t)}^2 dt \leq C(T) \|U_{h,0}\|_{\mathcal{H}_h(0)}^2.$$

Proof. We consider the problem in the matrix form (3.10). Since $\mathcal{M}(\cdot) \in C^1(0, T; \mathbb{R}^{N \times N})$ (G_h1) and is invertible (M_h2), this is equivalent to

$$(3.12) \quad \dot{\alpha}(t) + \mathcal{M}^{-1}(t)(\mathcal{M}'(t) + \mathcal{S}(t))\alpha(t) = 0.$$

This is a linear system of ordinary equations with C^0 coefficients (easily verified). Standard theory implies there exists a unique solution $\alpha \in C^1(0, T; \mathbb{R}^N)$, which can be translated as $U_h \in C_{S_h}^1$.

To show the energy bound, we start by testing (3.7) with $\chi_h = U_h$:

$$\frac{d}{dt} m_h(t; U_h, U_h) + a_h(t; U_h, U_h) - m_h(t; U_h, \partial_h^\bullet U_h) = 0.$$

The transport equality (G_h1) implies that

$$\frac{1}{2} \frac{d}{dt} m_h(t; U_h, U_h) + a_h(t; U_h, U_h) = -\frac{1}{2} g_h(t; U_h, U_h).$$

The desired stability bound follows using the same calculations as used in deriving (2.10). \square

3.2. Abstract lifted finite element spaces. The discrete space $\mathcal{S}_h(t)$ is not assumed to be contained in the continuous space $\mathcal{V}(t)$. This is an example of a ‘‘variational crime’’ (Strang and Fix, 2008). However it is convenient to prove error bounds in the spaces $\mathcal{H}(t)$ and $\mathcal{V}(t)$. To do this we use lifted discrete spaces using an embedding map $\lambda_h(\cdot, t): \mathcal{S}_h(t) \rightarrow \mathcal{S}_h^\ell(t) \subset \mathcal{V}(t)$. The error analysis will relate the solution of (2.9) u with a so-called lift $\lambda_h(U_h, t)$ of the discrete solution.

We require two further time dependent Hilbert spaces $\{\mathcal{Z}_0(t)\}_{t \in [0, T]}$ and $\{\mathcal{Z}(t)\}_{t \in [0, T]}$ which satisfy $\mathcal{Z}(t) \subset \mathcal{Z}_0(t) \subset \mathcal{V}(t)$ for each $t \in [0, T]$ with the inclusions uniformly continuous. Furthermore, we assume that $(\mathcal{Z}_0(t), \phi_t|_{\mathcal{Z}_0(0)})_{t \in [0, T]}$ and $(\mathcal{Z}(t), \phi_t|_{\mathcal{Z}(0)})_{t \in [0, T]}$ are both compatible pairs Def. 2.2 so that we may define the spaces $L_{\mathcal{Z}_0}^2, L_{\mathcal{Z}}^2$ (2.1) and $C_{\mathcal{Z}_0}^1, C_{\mathcal{Z}}^1$ (2.2). These spaces are abstractions of spaces of smoother functions.

The link between all the function spaces used in the section is shown in Fig. 3.1.

Lifting operator. Let $t \in [0, T]$. We assume there is a continuous, bijective, linear function $\lambda_h(\cdot, t): \mathcal{H}_h(t) \rightarrow \mathcal{H}(t)$ with inverse denoted by $\zeta_h(\cdot, t): \mathcal{H}(t) \rightarrow \mathcal{H}_h(t)$ such that $\lambda_h(\cdot, t)|_{\mathcal{V}_h(t)}$ is also a bijection onto $\mathcal{V}(t)$. We will denote $(\cdot)^\ell := \lambda_h(\cdot, t)$ and $(\cdot)^{-\ell} := \zeta_h(\cdot, t)$, i.e. $\eta_h^\ell(\cdot, t) := \lambda_h(\eta_h, t)(\cdot)$ for $\eta_h \in \mathcal{H}_h(t)$ and $\eta^{-\ell}(\cdot, t) := \zeta_h(\eta, t)(\cdot)$ for $\eta \in \mathcal{H}(t)$.

We assume that the lifting map is bounded and that there exists $c_{20}, c_{21} > 0$ such that for all $t \in [0, T]$

$$(L1) \quad c_{20} \left\| \eta_h^\ell \right\|_{\mathcal{H}(t)} \leq \|\eta_h\|_{\mathcal{H}_h(t)} \leq c_{21} \left\| \eta_h^\ell \right\|_{\mathcal{H}(t)} \quad \text{for all } \eta_h \in \mathcal{H}_h(t)$$

$$(L2) \quad c_{20} \left\| \eta_h^\ell \right\|_{\mathcal{V}(t)} \leq \|\eta_h\|_{\mathcal{V}_h(t)} \leq c_{21} \left\| \eta_h^\ell \right\|_{\mathcal{V}(t)} \quad \text{for all } \eta_h \in \mathcal{V}_h(t).$$

Remark 3.4. As a convention, variables denoted by ℓ correspond to lifted objects and $-\ell$ to inverse lifted objects. The construction of each depends on the parameter h .

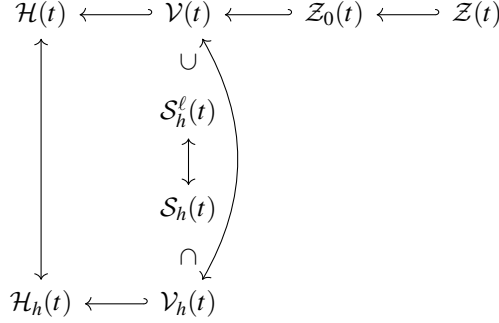


FIGURE 3.1. The relationships between different spaces used in this section. \subset denotes subspace inclusion, \hookrightarrow denotes continuous embedding, \leftrightarrow denotes that the lift is a bijection between these spaces.

Lifted push-forward and pull back maps. The lift of the discrete space push-forward map induces a new push-forward map on $\mathcal{H}(t)$. Let $\phi_t^\ell: \mathcal{H}(0) \rightarrow \mathcal{H}(t)$ be given by

$$(3.13) \quad \phi_t^\ell(\eta) := \lambda_h(\phi_t^h(\zeta_h(\eta, 0)), t) \quad \text{for } \eta \in \mathcal{H}(0),$$

with inverse $\phi_{-t}^\ell: \mathcal{H}(t) \rightarrow \mathcal{H}(0)$ given by

$$(3.14) \quad \phi_{-t}^\ell(\eta) := \lambda_h(\phi_{-t}^h(\zeta(\eta, t)), 0) \quad \text{for } \eta \in \mathcal{H}(t),$$

so that

$$\begin{aligned} \phi_t^\ell(\eta_h^\ell) &= (\phi_t^h(\eta_h))^\ell && \text{for } \eta_h \in \mathcal{H}_h(0) \\ \phi_{-t}^\ell(\eta_h^\ell) &= (\phi_{-t}^h(\eta_h))^\ell && \text{for } \eta_h \in \mathcal{H}_h(t). \end{aligned}$$

Note that $(\cdot)^\ell$ is a time dependent operator. Our assumptions imply that both pairs $\{\mathcal{H}(t), \phi_t^\ell\}_{t \in [0, T]}$ and $\{\mathcal{V}(t), \phi_t^\ell|_{\mathcal{V}_0}\}_{t \in [0, T]}$ are compatible uniformly in h (Def. 2.2). For example, applying that $(\mathcal{H}_h(t), \phi_t^h)_{t \in [0, T]}$ is compatible and (L1) gives

$$\left\| \phi_t^\ell \eta \right\|_{\mathcal{H}(t)} \leq c \left\| \phi_t^h(\eta^{-\ell}) \right\|_{\mathcal{H}_h(t)} \leq c \left\| \eta^{-\ell} \right\|_{\mathcal{H}_{h,0}} \leq c \|\eta\|_{\mathcal{H}_0} \quad \text{for } \eta \in \mathcal{H}_0.$$

We use the notation $C_{(\mathcal{H}, \phi^\ell)}^1$ and $C_{(\mathcal{V}, \phi^\ell)}^1$ for the spaces of smoothly evolving functions, each with respect to the pull back ϕ_{-t}^ℓ (c.f. (2.2)). We recall that the definition of $L_{\mathcal{H}}^2$ and $L_{\mathcal{V}}^2$ only does not depend on the choice of push-forward map up to norm equivalence (Rem. 2.5). We assume the following inclusions hold:

$$(L3) \quad C_{(\mathcal{H}, \phi)}^1 \cap C_{\mathcal{V}}^0 \subset C_{(\mathcal{H}, \phi^\ell)}^1, \quad \text{and} \quad C_{(\mathcal{V}, \phi)}^1 \cap C_{\mathcal{Z}_0}^0 \subset C_{(\mathcal{V}, \phi^\ell)}^1.$$

Lifted material derivative. We denote by $\partial_\ell^\bullet \eta$ the material derivative for the push-forward map ϕ_t^ℓ (2.4):

$$(3.15) \quad \partial_\ell^\bullet \eta := \phi_t^\ell \frac{d}{dt} (\phi_{-t}^\ell \eta) \quad \text{for all } \eta \in C_{(\mathcal{H}, \phi^\ell)}^1.$$

This is a different material derivative to the material derivative defined with respect to the push-forward map ϕ_t^h (3.3). However, as observed in Dziuk and Elliott (2013a), our construction implies that first taking material derivatives and then lifting is the same as first lifting and then taking material derivatives:

Lemma 3.5 (Commutation of material derivative and lifting). *The following hold:*

- For all $\eta_h \in C^1_{\mathcal{H}_h}$

$$(3.16) \quad \partial_\ell^\bullet(\eta_h^\ell) = (\partial_h^\bullet \eta_h)^\ell.$$

- $\eta_h \in C^1_{\mathcal{H}_h}$ if, and only if, $\eta_h^\ell \in C^1_{(\mathcal{H}, \phi^\ell)}$, and $\eta_h \in C^1_{\mathcal{V}_h}$ if, and only if, $\eta_h^\ell \in C^1_{(\mathcal{V}, \phi^\ell)}$.

Proof. Indeed, applying the definitions (3.13) and (3.14), we see

$$\partial_\ell^\bullet(\eta_h^\ell) = \phi_t^\ell \frac{d}{dt}(\phi_{-t}^\ell(\eta_h^\ell)) = \left(\phi_t^h \left(\left(\frac{d}{dt}(\phi_{-t}^h \eta_h) \right)^{-\ell} \right) \right)^\ell = \left(\phi_t^h \left(\frac{d}{dt}(\phi_{-t}^h \eta_h) \right) \right)^\ell = (\partial_h^\bullet \eta_h)^\ell,$$

since the lift at time $t = 0$ and time derivative commute and $(\cdot)^\ell$ and $(\cdot)^{-\ell}$ are inverses. By similar reasoning, we have that

$$\partial_h^\bullet(\eta^{-\ell}) = \partial_\ell^\bullet \eta \quad \text{for all } \eta \in C^1_{(\mathcal{H}, \phi^\ell)}.$$

In particular, applying (L1) and (L2), we have the second statement. \square

Abstract lifted transport formulae. We assume that we have a transport formula for functions in $C^1_{(\mathcal{H}, \phi^\ell)}$ and $C^1_{(\mathcal{V}, \phi^\ell)}$ for the m and a bilinear forms. We assume that there exists bilinear forms $g_\ell(t; \cdot, \cdot): \mathcal{H}(t) \times \mathcal{H}(t) \rightarrow \mathbb{R}$ and $b_\ell(t; \cdot, \cdot): \mathcal{V}(t) \times \mathcal{V}(t) \rightarrow \mathbb{R}$ such that

$$(G_\ell 1) \quad \frac{d}{dt} m(t; \eta, \zeta) = m(t; \partial_\ell^\bullet \eta, \zeta) + m(t; \eta, \partial_\ell^\bullet \zeta) + g_\ell(t; \eta, \zeta) \quad \text{for } \eta, \zeta \in C^1_{(\mathcal{H}, \phi^\ell)}$$

$$(B_\ell 1) \quad \frac{d}{dt} a(t; \eta, \zeta) = a(t; \partial_\ell^\bullet \eta, \zeta) + a(t; \eta, \partial_\ell^\bullet \zeta) + b_\ell(t; \eta, \zeta) \quad \text{for } \eta, \zeta \in C^1_{(\mathcal{V}, \phi^\ell)}.$$

We assume that for these bilinear forms there exists $c_1, c_2 > 0$ such that for all $t \in [0, T]$ and all $h \in (0, h_0)$,

$$(G_\ell 2) \quad |g_\ell(t; \eta, \zeta)| \leq c_1 \|\eta\|_{\mathcal{H}(t)} \|\zeta\|_{\mathcal{H}(t)} \quad \text{for } \eta, \zeta \in \mathcal{H}(t)$$

$$(B_\ell 2) \quad |b_\ell(t; \eta, \zeta)| \leq c_2 \|\eta\|_{\mathcal{V}(t)} \|\zeta\|_{\mathcal{V}(t)} \quad \text{for } \eta, \zeta \in \mathcal{V}(t).$$

Lifted finite element space. Let $t \in [0, T]$. The lifting process allows us to introduce a new space $\mathcal{S}_h^\ell(t)$ by

$$(3.17) \quad \mathcal{S}_h^\ell(t) := \{\chi_h^\ell : \chi_h \in \mathcal{S}_h(t)\}.$$

This is a subspace of $\mathcal{V}(t)$ for each $t \in [0, T]$.

The lifted discrete space $\mathcal{S}_h^\ell(t)$ is a closed subspace of $\mathcal{V}(t)$ and $\phi_t^\ell(\mathcal{S}_{h,0}^\ell) = \mathcal{S}_h^\ell(t)$ so we may infer that $(\mathcal{S}_h^\ell(t), \phi_t^\ell|_{\mathcal{S}_{h,0}^\ell})_{t \in [0, T]}$ is a compatible pair (Rem. 2.3). Hence, the spaces $L^2_{\mathcal{S}_h^\ell}$ (2.1) and $C^1_{\mathcal{S}_h^\ell}$ (2.2) are well defined and we will write $\partial_\ell^\bullet \chi_h^\ell$ for the material derivative of $\chi_h^\ell \in C^1_{\mathcal{S}_h^\ell}$. From our assumptions, in general it does not hold that $\phi_t(\mathcal{S}_{h,0}^\ell) = \mathcal{S}_h^\ell(t)$.

Approximation property of $\mathcal{S}_h^\ell(t)$. For each $t \in [0, T]$, we assume that there exists a well defined interpolation operator $I_h: \mathcal{Z}_0(t) \rightarrow \mathcal{S}_h^\ell(t)$ such that there exists a constant $c > 0$ such that for all $t \in [0, T]$

$$(I1) \quad \|\eta - I_h \eta\|_{\mathcal{H}(t)} + h \|\eta - I_h \eta\|_{\mathcal{V}(t)} \leq ch^2 \|\eta\|_{\mathcal{Z}_0(t)} \quad \text{for } \eta \in \mathcal{Z}_0(t)$$

$$(I2) \quad \|\eta - I_h \eta\|_{\mathcal{H}(t)} + h \|\eta - I_h \eta\|_{\mathcal{V}(t)} \leq ch^{k+1} \|\eta\|_{\mathcal{Z}(t)} \quad \text{for } \eta \in \mathcal{Z}(t).$$

Assumptions on the geometric approximation. Finally, we assume we have the following relations between continuous and discrete bilinear forms. We assume that there exists constants $c > 0$ such that for all $t \in [0, T]$ the following holds for all $\eta_h, \zeta_h \in \mathcal{V}_h(t)$ with lifts $\eta_h^\ell, \zeta_h^\ell \in \mathcal{V}(t)$ we have

$$(P1) \quad \left| m(t; \eta_h^\ell, \zeta_h^\ell) - m_h(t; \eta_h, \zeta_h) \right| \leq ch^{k+1} \left\| \eta_h^\ell \right\|_{\mathcal{V}(t)} \left\| \zeta_h^\ell \right\|_{\mathcal{V}(t)}$$

$$(P2) \quad \left| g_\ell(t; \eta_h^\ell, \zeta_h^\ell) - g_h(t; \eta_h, \zeta_h) \right| \leq ch^{k+1} \left\| \eta_h^\ell \right\|_{\mathcal{V}(t)} \left\| \zeta_h^\ell \right\|_{\mathcal{V}(t)}$$

$$(P3) \quad \left| g_\ell(t; \eta_h^\ell, \zeta_h^\ell) - g(t; \eta_h, \zeta_h) \right| \leq ch^k \left\| \eta_h^\ell \right\|_{\mathcal{V}(t)} \left\| \zeta_h^\ell \right\|_{\mathcal{V}(t)}$$

$$(P4) \quad \left| a(t; \eta_h^\ell, \zeta_h^\ell) - a_h(t; \eta_h, \zeta_h) \right| \leq ch^k \left\| \eta_h^\ell \right\|_{\mathcal{V}(t)} \left\| \zeta_h^\ell \right\|_{\mathcal{V}(t)}$$

$$(P5) \quad \left| b_\ell(t; \eta_h^\ell, \zeta_h^\ell) - b_h(t; \eta_h, \zeta_h) \right| \leq ch^k \left\| \eta_h^\ell \right\|_{\mathcal{V}(t)} \left\| \zeta_h^\ell \right\|_{\mathcal{V}(t)}$$

$$(P6) \quad \left| b_\ell(t; \eta_h^\ell, \zeta_h^\ell) - b(t; \eta_h, \zeta_h) \right| \leq ch^k \left\| \eta_h^\ell \right\|_{\mathcal{V}(t)} \left\| \zeta_h^\ell \right\|_{\mathcal{V}(t)}.$$

For $\eta, \zeta \in \mathcal{Z}_0(t)$ with inverse lifts $\eta^{-\ell}, \zeta^{-\ell}$, we have

$$(P4') \quad \left| a(t; \eta, \zeta) - a_h(t; \eta^{-\ell}, \zeta^{-\ell}) \right| \leq ch^{k+1} \|\eta\|_{\mathcal{Z}_0(t)} \|\zeta\|_{\mathcal{Z}_0(t)}$$

$$(P5') \quad \left| b_\ell(t; \eta, \zeta) - b_h(t; \eta^{-\ell}, \zeta^{-\ell}) \right| \leq ch^{k+1} \|\eta\|_{\mathcal{Z}_0(t)} \|\zeta\|_{\mathcal{Z}_0(t)}.$$

For $\eta \in C_{\mathcal{Z}_0}^1$ and $\zeta \in \mathcal{Z}_0(t)$, with inverse lifts $\eta^{-\ell}$ and $\zeta^{-\ell}$, we have

$$(P7) \quad \left| a(t; \partial_\ell^\bullet \eta, \zeta) - a_h(t; \partial_h^\bullet \eta^{-\ell}, \zeta^{-\ell}) \right| \leq ch^{k+1} (\|\eta\|_{\mathcal{Z}_0(t)} + \|\partial^\bullet \eta\|_{\mathcal{Z}_0(t)}) \|\zeta\|_{\mathcal{Z}_0(t)}.$$

Finally, we assume

$$(P8) \quad \|\partial_\ell^\bullet \zeta - \partial^\bullet \zeta\|_{\mathcal{H}(t)} \leq ch^{k+1} \|\zeta\|_{\mathcal{V}(t)} \quad \text{for } \zeta \in C_{\mathcal{V}}^1$$

$$(P9) \quad \|\partial_\ell^\bullet \zeta - \partial^\bullet \zeta\|_{\mathcal{V}(t)} \leq ch^k \|\zeta\|_{\mathcal{Z}_0(t)} \quad \text{for } \zeta \in C_{\mathcal{Z}_0}^1.$$

3.3. Ritz projection. It is convenient to introduce a Ritz projection which is a standard approach in the finite element analysis of evolution equations (Thomée, 2006) also applied to problems on evolving surfaces (e.g. Dziuk and Elliott, 2013a). The Ritz projection is defined with respect to modified positive definite bilinear forms a^κ and a_h^κ .

A new bilinear form. We know from Assumptions (M2), (M_h2), (A3), (A_n4) and (A_h2), there exists $\kappa > 0$ such that there exists $c > 0$ such that for all $t \in [0, T]$ and all $h \in (0, h_0)$

$$(3.18) \quad a(t; \eta, \eta) + \kappa m(t; \eta, \eta) \geq c \|\eta\|_{\mathcal{V}(t)}^2 \quad \text{for } \eta \in \mathcal{V}(t)$$

$$(3.19) \quad a_h(t; \eta_h, \eta_h) + \kappa m_h(t; \eta_h, \eta_h) \geq c \|\eta_h\|_{\mathcal{V}_h(t)}^2 \quad \text{for } \eta_h \in \mathcal{V}_h(t).$$

We now take κ fixed in the sequel. Thus, we infer that the bilinear forms:

$$\begin{aligned} a^\kappa(t; \eta, \zeta) &:= a(t; \eta, \zeta) + \kappa m(t; \eta, \zeta) && \text{for } \eta, \zeta \in \mathcal{V}(t) \\ a_h^\kappa(t; \eta_h, \zeta_h) &:= a_h(t; \eta_h, \zeta_h) + \kappa m_h(t; \eta_h, \zeta_h) && \text{for } \eta_h, \zeta_h \in \mathcal{V}_h(t), \end{aligned}$$

are uniformly coercive for all $h \in (0, h_0)$.

The projection.

Definition 3.6. The Ritz projection is an operator $\Pi_h : \mathcal{V}(t) \rightarrow \mathcal{S}_h(t)$. For $z \in \mathcal{V}(t)$, $\Pi_h z$ is given as the unique solution of

$$(3.20) \quad a_h^\kappa(t; \Pi_h z, \chi_h) = a^\kappa(t; z, \chi_h^\ell) \quad \text{for all } \chi_h \in \mathcal{S}_h(t) \text{ with lift } \chi_h^\ell \in \mathcal{S}_h^\ell(t).$$

We denote by $\pi_{hz} = (\Pi_h z)^\ell \in \mathcal{S}_h^\ell(t)$.

We will further assume that there exists a constant $c_{22} > 0$ such that for all $t \in [0, T]$, for $\eta = z - \pi_{hz} \in \mathcal{V}(t)$ and all $\zeta \in \mathcal{Z}_0(t)$ we have

$$(B3) \quad |b(t; \eta, \zeta)| \leq c_{22} \left(\|\eta\|_{\mathcal{H}(t)} + h \|\eta\|_{\mathcal{V}(t)} + h^{k+1} \|z\|_{\mathcal{Z}(t)} \right) \|\zeta\|_{\mathcal{Z}_0(t)}.$$

Remark 3.7. In an application it may be possible to prove that a simpler version of (B3) is sufficient. For example in the case of surfaces without boundary for all $t \in [0, T]$, for $\eta \in \mathcal{V}(t)$ and all $\zeta \in \mathcal{Z}_0(t)$ we have

$$(B3') \quad |b(t; \eta, \zeta)| \leq c_{22} \|\eta\|_{\mathcal{H}(t)} \|\zeta\|_{\mathcal{Z}_0(t)}$$

holds.

A dual problem. We introduce the dual problem: Given $\xi \in \mathcal{H}(t)$, find $\mathcal{R}(\xi) \in \mathcal{V}(t)$ such that

$$(3.21) \quad a^\kappa(t; \eta, \mathcal{R}(\xi)) = m(t; \xi, \eta) \quad \text{for } \eta \in \mathcal{V}(t).$$

Assumptions on κ along with the previous assumptions from [Sec. 2.2](#) imply that (3.21) has a unique solution and we assume the regularity condition that there exists $c > 0$ such that

$$(R2) \quad \|\mathcal{R}(\xi)\|_{\mathcal{Z}_0(t)} \leq c \|\xi\|_{\mathcal{H}(t)},$$

where the constant is independent of ξ and time t .

Ritz error analysis.

Lemma 3.8. *For each $z \in \mathcal{V}(t)$, there exists a unique solution $\Pi_h z$ of (3.20). There exists a constant $c > 0$ such that for all $h \in (0, h_0)$ and all $t \in [0, T]$ we have*

$$(3.22) \quad \|\Pi_h z\|_{\mathcal{V}_h(t)} \leq c \|z\|_{\mathcal{V}(t)} \quad \text{for } z \in \mathcal{V}(t).$$

Furthermore, there exists a constant $c > 0$ such that for all $t \in [0, T]$ and $h \in (0, h_0)$,

$$(3.23) \quad \|z - \pi_{hz}\|_{\mathcal{H}(t)} + h \|z - \pi_{hz}\|_{\mathcal{V}(t)} \leq ch^{k+1} \|z\|_{\mathcal{Z}(t)} \quad \text{for all } z \in \mathcal{Z}(t).$$

Proof. Since a_h^κ is uniformly coercive (3.19) and bounded ((A_h3) and (M_h2)) and a^κ is bounded ((A4) and (M2)), standard Lax-Milgram theory gives that there exists a unique solution that satisfies the stability bound (3.22).

To show the error bound, we consider the functional $F_h : \mathcal{V}(t) \rightarrow \mathbb{R}$ given by

$$F_h(\eta) = a^\kappa(t; z - \pi_{hz}, \eta).$$

First, note that for $\eta = \chi_h^\ell \in \mathcal{S}_h^\ell(t)$, we can use the definition of $\Pi_h z$ (3.20) to see that

$$F_h(\chi_h^\ell) = a^\kappa(t; z - \pi_{hz}, \chi_h^\ell) = a_h^\kappa(t; \Pi_h z, \chi_h) - a^\kappa(t; \pi_{hz}, \chi_h^\ell).$$

Then the perturbation estimates (P1) and (P4) and the stability bound (3.22) imply that

$$(3.24) \quad \left| F_h(\chi_h^\ell) \right| \leq ch^k \|\Pi_h z\|_{\mathcal{V}_h(t)} \left\| \chi_h^\ell \right\|_{\mathcal{V}(t)} \leq ch^k \|z\|_{\mathcal{V}(t)} \left\| \chi_h^\ell \right\|_{\mathcal{V}(t)}.$$

Next, we consider $F_h(\eta)$ for $\eta \in \mathcal{Z}_0$. Then, again using (3.20) we have

$$\begin{aligned} F_h(\eta) &= a^\kappa(t; z - \pi_h z, \eta) \\ &= a^\kappa(t; z - \pi_h z, \eta - I_h \eta) + a^\kappa(t; z - \pi_h z, I_h \eta) \\ &= a^\kappa(t; z - \pi_h z, \eta - I_h \eta) + (a_h^\kappa(t; \Pi_h z, (I_h \eta)^{-\ell}) - a^\kappa(t; \pi_h z, I_h \eta)) =: I_1 + I_2. \end{aligned}$$

Using the boundedness of a^κ ((A4) and (M2)) and the interpolation bounds (I1), we have

$$|I_1| \leq c \|z - \pi_h z\|_{\mathcal{V}(t)} \|\eta - I_h \eta\|_{\mathcal{V}(t)} \leq ch \|z - \pi_h z\|_{\mathcal{V}(t)} \|\eta\|_{\mathcal{Z}_0(t)}.$$

We split I_2 so that together with the perturbation estimates (P1), (P4) and (P4') and the interpolation result we have

$$\begin{aligned} |I_2| &\leq \left| a_h^\kappa(t; \Pi_h z, (I_h \eta - \eta)^{-\ell}) - a^\kappa(t; \pi_h z, I_h \eta - \eta) \right| \\ &\quad + \left| a_h^\kappa(t; \Pi_h z - z^{-\ell}, (\eta)^{-\ell}) - a^\kappa(t; \pi_h z - z, \eta) \right| \\ &\quad + \left| a_h^\kappa(t; z^{-\ell}, (\eta)^{-\ell}) - a^\kappa(t; z, \eta) \right| \\ &\leq ch^{k+1} \|\Pi_h z\|_{\mathcal{V}_h(t)} \|\eta\|_{\mathcal{Z}_0(t)} + ch^k \|\pi_h z - z\|_{\mathcal{V}(t)} \|\eta\|_{\mathcal{V}(t)} \\ &\quad + ch^{k+1} \|z\|_{\mathcal{Z}_0(t)} \|\eta\|_{\mathcal{Z}_0(t)}. \end{aligned}$$

Then combining the above estimates with the stability bound (3.22), we see that

$$(3.25) \quad |F_h(\eta)| \leq c(h \|z - \pi_h z\|_{\mathcal{V}(t)} + h^{k+1} \|z\|_{\mathcal{Z}(t)}) \|\eta\|_{\mathcal{Z}_0(t)}.$$

To show the $\mathcal{V}(t)$ -norm error bound, we have

$$a^\kappa(t; z - \pi_h z, z - \pi_h z) = a^\kappa(t; z - \pi_h z, z - I_h z) + F_h(I_h z - \pi_h z).$$

Applying the boundedness ((A4) and (M2)) and coercivity (3.18) of a^κ , the interpolation bound (I2) and the first bound on F_h (3.24) gives

$$\begin{aligned} \|z - \pi_h z\|_{\mathcal{V}(t)}^2 &\leq ch^k \|z - \pi_h z\|_{\mathcal{V}(t)} \|z\|_{\mathcal{Z}(t)} + ch^k \|z\|_{\mathcal{V}(t)} \|I_h z - \pi_h z\|_{\mathcal{V}(t)} \\ &\leq ch^k \|z - \pi_h z\|_{\mathcal{V}(t)} \|z\|_{\mathcal{Z}(t)} + ch^k \|z\|_{\mathcal{V}(t)} \left(\|I_h z - z\|_{\mathcal{V}(t)} + \|z - \pi_h z\|_{\mathcal{V}(t)} \right). \end{aligned}$$

Using the interpolation bound (I2) and rearranging using a Young's inequality gives

$$(3.26) \quad \|z - \pi_h z\|_{\mathcal{V}(t)} \leq ch^k \|z\|_{\mathcal{Z}(t)}.$$

For the $\mathcal{H}(t)$ -norm bound, we consider the dual problem (3.21) with $\xi = z - \pi_h z \in \mathcal{H}(t)$. Then there exists a unique $\mathcal{R}(\xi) \in \mathcal{V}(t)$ such that

$$a^\kappa(t; \eta, \mathcal{R}(\xi)) = m(t; \xi, \eta) \quad \text{for all } \eta \in \mathcal{V}(t).$$

Furthermore, $\mathcal{R}(\xi) \in \mathcal{Z}_0(t)$ and satisfies (R2)

$$(3.27) \quad \|\mathcal{R}(\xi)\|_{\mathcal{Z}_0(t)} \leq c \|z - \pi_h z\|_{\mathcal{H}(t)}.$$

Then we have from (M2) that

$$\|z - \pi_h z\|_{\mathcal{H}(t)}^2 \leq c_2 m(t; z - \pi_h z, z - \pi_h z) = c_2 a^\kappa(t; z - \pi_h z, \mathcal{R}(\xi)) = c_2 F_h(\mathcal{R}(\xi)).$$

Then the second bound on F_h (3.25) together with the $\mathcal{V}(t)$ -norm bound (3.26) and the dual regularity estimate (3.27) imply that

$$\begin{aligned} \|z - \pi_h z\|_{\mathcal{H}(t)}^2 &\leq (ch \|z - \pi_h z\|_{\mathcal{V}(t)} + ch^{k+1} \|z\|_{\mathcal{Z}(t)}) \|\mathcal{R}(\xi)\|_{\mathcal{Z}_0(t)} \\ &\leq ch^{k+1} \|z\|_{\mathcal{Z}(t)} \|z - \pi_h z\|_{\mathcal{H}(t)}. \end{aligned}$$

Rearranging this inequality provides the $\mathcal{H}(t)$ -norm bound. \square

Time derivative of Ritz projection. Since in general the material derivative and Ritz projection do not commute, we must provide a further estimate for this material derivative of the error $z - \pi_h z$. First, we derive an equation for $\partial_h^\bullet \Pi_h z$.

Lemma 3.9. *Let $z \in C_V^1$, then, for each $t \in [0, T]$, we have the equation:*

$$(3.28) \quad a_h^K(t; \partial_h^\bullet \Pi_h z, \chi_h) = a^K(t; \partial_\ell^\bullet z, \chi_h^\ell) + b_\ell^K(t; z, \chi_h^\ell) - b_h^K(t; \Pi_h z, \chi_h)$$

for all $\chi_h \in \mathcal{S}_h(t)$.

Proof. First consider $\chi_h \in C_{\mathcal{S}_h}^1$ and take the time derivative of (3.20). We apply the discrete transport formulae (G_h1) and (B_h1) on the left hand side and the lifted transport formulae (B_ℓ1) and (G_ℓ1) on the right hand side and rearrange to see:

$$\begin{aligned} a_h^K(t; \partial_h^\bullet \Pi_h z, \chi_h) \\ = a^K(t; \partial_\ell^\bullet z, \chi_h^\ell) + a^K(t; z, \partial_\ell^\bullet \chi_h^\ell) - a_h^K(t; \Pi_h z, \partial_h^\bullet \chi_h) + b_\ell^K(t; z, \chi_h^\ell) - b_h^K(t; \Pi_h z, \chi_h). \end{aligned}$$

Using the fact that for $\chi_h \in C_{\mathcal{S}_h}^1$, we have $\partial_h^\bullet \chi_h \in \mathcal{S}_h(t)$ and $(\partial_h^\bullet \chi_h)^\ell = \partial_\ell^\bullet \chi_h^\ell$, we can apply (3.20) once more to see that

$$a_h^K(t; \partial_h^\bullet \Pi_h z, \chi_h) = a^K(t; \partial_\ell^\bullet z, \chi_h^\ell) + b_\ell^K(t; z, \chi_h^\ell) - b_h^K(t; \Pi_h z, \chi_h).$$

We can expand this result to arbitrary $\chi_h \in \mathcal{S}_h(t)$ by considering the function χ_h^* given by $s \mapsto \phi_s^h(\phi_{-t}^h \chi_h)$ which satisfies $\chi_h^* \in C_{\mathcal{S}_h}^1$ and $\chi_h^*|_{s=t} = \chi_h$. \square

Lemma 3.10. *For $z \in C_{\mathcal{Z}_0}^1$, we have that $\Pi_h z \in C_{\mathcal{S}_h}^1$ and there exists a constants $c > 0$ such that for all $t \in [0, T]$, $h \in (0, h_0)$*

$$(3.29) \quad \|\partial_h^\bullet \Pi_h z\|_{\mathcal{V}_h(t)} \leq c(\|z\|_{\mathcal{Z}_0(t)} + \|\partial^\bullet z\|_{\mathcal{V}(t)}) \quad \text{for all } z \in \mathcal{Z}_0(t).$$

Furthermore, if $z \in C_{\mathcal{Z}}^1$, then

$$(3.30) \quad \|\partial_\ell^\bullet(z - \pi_h z)\|_{\mathcal{H}(t)} + h \|\partial_\ell^\bullet(z - \pi_h z)\|_{\mathcal{V}(t)} \leq ch^{k+1}(\|z\|_{\mathcal{Z}(t)} + \|\partial^\bullet z\|_{\mathcal{Z}(t)}).$$

Proof. For the stability bound, we see that $\partial_h^\bullet \Pi_h z$ satisfies the discrete elliptic problem (3.28). This tells us that $\partial_h^\bullet \Pi_h z \in \mathcal{S}_h(t)$ and, combined with the boundedness of a^K ((A4) and (M2)), b_ℓ^K ((B_ℓ2) and (G_ℓ2)), and b_h^K ((B_h2) and (G_h2)) we see that

$$\|\partial_h^\bullet \Pi_h z\|_{\mathcal{V}_h(t)} \leq c(\|\partial_h^\bullet z\|_{\mathcal{V}(t)} + \|z\|_{\mathcal{V}(t)} + \|\Pi_h z\|_{\mathcal{V}_h(t)}).$$

Then applying the perturbation estimate (P9) and the stability of estimate (3.22), we see (3.29).

To show the error bound, we proceed in a similar fashion to Lem. 3.8, we introduce the functional $T_h: \mathcal{V}(t) \rightarrow \mathbb{R}$ given by

$$T_h(\eta) = a^K(t; \partial_\ell^\bullet(z - \pi_h z), \eta).$$

First, for $\eta = \chi_h^\ell \in \mathcal{S}_h^\ell(t)$, we can use (3.28) to see

$$\begin{aligned} T_h(\chi_h^\ell) &= a^K(t; \partial_\ell^\bullet(z - \pi_h z), \chi_h^\ell) \\ &= (a_h^K(t; \partial_h^\bullet \Pi_h z, \chi_h) - a^K(t; \partial_\ell^\bullet \pi_h z, \chi_h^\ell)) + (b_h^K(t; \Pi_h z, \chi_h) - b_\ell^K(t; \pi_h z, \chi_h^\ell)) \\ &\quad + b_\ell^K(t; \pi_h z - z, \chi_h^\ell). \end{aligned}$$

Then, using the perturbation estimates on a^K ((P1) and (P4)), with the fact that the two discrete material derivatives and lifting commute (3.16), and b^K ((P2) and (P5)), the boundedness of b_ℓ^K ((G ℓ 2) and (B ℓ 2)), the error bound (3.23) and the stability estimates (3.22) and (3.29) gives

$$(3.31) \quad \begin{aligned} |T_h(\mathcal{X}_h^\ell)| &\leq ch^k (\|\partial_h^\bullet \Pi_h z\|_{\mathcal{V}_h(t)} + \|\Pi_h z\|_{\mathcal{V}_h(t)} + \|z\|_{\mathcal{Z}(t)}) \|\mathcal{X}_h^\ell\|_{\mathcal{V}(t)} \\ &\leq ch^k (\|z\|_{\mathcal{Z}(t)} + \|\partial^\bullet z\|_{\mathcal{Z}(t)}) \|\mathcal{X}_h^\ell\|_{\mathcal{V}(t)}. \end{aligned}$$

Secondly, for $\eta \in \mathcal{Z}_0(t)$, we have using (3.28)

$$\begin{aligned} T_h(\eta) &= a^K(t; \partial_\ell^\bullet(z - \pi_h z), \eta - I_h \eta) + a^K(t; \partial_\ell^\bullet(z - \pi_h z), I_h \eta) \\ &= a^K(t; \partial_\ell^\bullet(z - \pi_h z), \eta - I_h \eta) \\ &\quad + (a_h^K(t; \partial_h^\bullet \Pi_h z, (I_h \eta)^{-\ell}) - a^K(t; \partial_\ell^\bullet \pi_h z, I_h \eta)) \\ &\quad + (b_h^K(t; \Pi_h z, (I_h \eta)^{-\ell}) - b_\ell^K(t; \pi_h z, I_h \eta)) \\ &\quad + b_\ell^K(t; \pi_h z - z, I_h \eta) \\ &=: I_1 + I_2 + I_3 + I_4. \end{aligned}$$

We split the four terms I_1, \dots, I_4 using the smooth functions z and η so that

$$\begin{aligned} I_1 &= a^K(t; \partial_\ell^\bullet(z - \pi_h z), \eta - I_h \eta) \\ I_2 &= (a_h^K(t; \partial_h^\bullet \Pi_h z, (I_h \eta - \eta)^{-\ell}) - a^K(t; \partial_\ell^\bullet \pi_h z, I_h \eta - \eta)) \\ &\quad + (a_h^K(t; \partial_h^\bullet (\Pi_h z - z^{-\ell}), (\eta)^{-\ell}) - a^K(t; \partial_\ell^\bullet (\pi_h z - z), \eta)) \\ &\quad + (a_h^K(t; \partial_h^\bullet (z^{-\ell}) - (\partial^\bullet z)^{-\ell}, (\eta)^{-\ell}) - a^K(t; \partial_\ell^\bullet z - \partial^\bullet z, \eta)) \\ &\quad + (a_h^K(t; (\partial^\bullet z)^{-\ell}, (\eta)^{-\ell}) - a^K(t; \partial^\bullet z, \eta)) \\ I_3 &= (b_h^K(t; \Pi_h z, (I_h \eta - \eta)^{-\ell}) - b_\ell^K(t; \pi_h z, I_h \eta - \eta)) \\ &\quad + (b_h^K(t; \Pi_h z - z^{-\ell}, (\eta)^{-\ell}) - b_\ell^K(t; \pi_h z - z, \eta)) \\ &\quad + (b_h^K(t; z^{-\ell}, (\eta)^{-\ell}) - b_\ell^K(t; z, \eta)) \\ I_4 &= b_\ell^K(t; \pi_h z - z, I_h \eta - \eta) + (b_\ell^K(t; \pi_h z - z, \eta) - b^K(t; \pi_h z - z, \eta)) \\ &\quad + b^K(t; \pi_h z - z, \eta). \end{aligned}$$

Using the boundedness of a^K ((A4) and (M2)) and the interpolation estimate (I1), we have

$$|I_1| \leq ch \|\partial_\ell^\bullet(z - \pi_h z)\|_{\mathcal{V}(t)} \|\eta\|_{\mathcal{Z}_0(t)}.$$

Using the perturbation errors for a^K (P1) to (P4') (with the fact that discrete material derivatives and lifting commute (3.16), the inclusions shown in (L3) and Lem. 3.5), as well as the estimate with material derivatives (P7), together with the interpolation bound (I1) and the error in material derivatives (P9), we have

$$\begin{aligned} |I_2| &\leq ch^{k+1} \|\partial_h^\bullet \Pi_h z\|_{\mathcal{V}_h(t)} \|\eta\|_{\mathcal{Z}_0(t)} + ch^k \|\partial_\ell^\bullet(z - \pi_h z)\|_{\mathcal{V}(t)} \|\eta\|_{\mathcal{V}(t)} \\ &\quad + ch^{2k} \|z\|_{\mathcal{Z}_0(t)} \|\eta\|_{\mathcal{V}(t)} + ch^{k+1} \|\partial^\bullet z\|_{\mathcal{Z}_0(t)} \|\eta\|_{\mathcal{Z}_0(t)} \\ &\leq ch^k \|\partial_\ell^\bullet(z - \pi_h z)\|_{\mathcal{V}(t)} \|\eta\|_{\mathcal{Z}_0(t)} \\ &\quad + ch^{k+1} (\|z\|_{\mathcal{Z}(t)} + \|\partial^\bullet z\|_{\mathcal{Z}(t)} + \|\partial_h^\bullet \Pi_h z\|_{\mathcal{V}_h(t)}) \|\eta\|_{\mathcal{Z}_0(t)}. \end{aligned}$$

Using the simple and improved perturbation estimate for b^κ (P2), (P5) and (P5'), the interpolation result (I1), and the Ritz $\mathcal{V}(t)$ -norm error bound (3.23), we have

$$\begin{aligned} |I_3| &\leq ch^{k+1} \|\Pi_h z\|_{\mathcal{V}_h(t)} \|\eta\|_{\mathcal{Z}_0(t)} + ch^{k+1} \|z\|_{\mathcal{Z}(t)} \|\eta\|_{\mathcal{V}(t)} + ch^{k+1} \|z\|_{\mathcal{Z}_0(t)} \|\eta\|_{\mathcal{Z}_0(t)} \\ &\leq ch^{k+1} (\|z\|_{\mathcal{Z}(t)} + \|\Pi_h z\|_{\mathcal{V}_h(t)}) \|\eta\|_{\mathcal{Z}_0(t)}. \end{aligned}$$

Using the boundedness of b_ℓ^κ ((B ℓ 2) and (G ℓ 2)), the perturbation estimates (P6) and (P3) on b^κ , the boundedness of b^κ ((B3) and (G2)) and the Ritz $\mathcal{V}(t)$ and $\mathcal{H}(t)$ -norm error bounds (3.23) we have

$$\begin{aligned} |I_4| &\leq ch^{k+1} \|z\|_{\mathcal{Z}(t)} \|\eta\|_{\mathcal{Z}_0(t)} + ch^{2k} \|z\|_{\mathcal{Z}(t)} \|\eta\|_{\mathcal{V}(t)} \\ &\quad + c(\|z - \pi_h z\|_{\mathcal{H}(t)} + h \|z - \pi_h z\|_{\mathcal{V}(t)} + h^{k+1} \|z\|_{\mathcal{Z}(t)}) \|\eta\|_{\mathcal{Z}_0(t)} \\ &\leq ch^{k+1} \|z\|_{\mathcal{Z}(t)} \|\eta\|_{\mathcal{Z}_0(t)}. \end{aligned}$$

Combining the previous four bounds with the stability estimates for $\Pi_h z$ (3.22) and $\partial_\ell^\bullet \Pi_h z$ (3.29) gives

$$(3.32) \quad |T_h(\eta)| \leq ch^{k+1} (\|z\|_{\mathcal{Z}(t)} + \|\partial^\bullet z\|_{\mathcal{Z}(t)}) \|\eta\|_{\mathcal{Z}_0(t)} + ch \|\partial_\ell^\bullet (z - \pi_h z)\|_{\mathcal{V}(t)} \|\eta\|_{\mathcal{Z}_0(t)}.$$

To show the $\mathcal{V}(t)$ -norm error bound, we start with

$$\begin{aligned} &a^\kappa(t; \partial_\ell^\bullet (z - \pi_h z), \partial_\ell^\bullet (z - \pi_h z)) \\ &= a^\kappa(t; \partial_\ell^\bullet (z - \pi_h z), \partial_\ell^\bullet z - \partial^\bullet z) + a^\kappa(t; \partial_\ell^\bullet (z - \pi_h z), \partial^\bullet z - I_h \partial^\bullet z) \\ &\quad + a^\kappa(t; \partial_\ell^\bullet (z - \pi_h z), I_h \partial^\bullet z - \partial_\ell^\bullet \pi_h z). \end{aligned}$$

Noting that the final term on the right hand side is $T_h(I_h \partial^\bullet z - \partial_\ell^\bullet \pi_h z)$, the bounds on a^κ ((A4) and (M2)), the perturbation estimate (P9), the interpolation estimate (I2) and the first bound on T_h (3.31) gives

$$\begin{aligned} &a^\kappa(t; \partial_\ell^\bullet (z - \pi_h z), \partial_\ell^\bullet (z - \pi_h z)) \\ &\leq \|\partial_\ell^\bullet (z - \pi_h z)\|_{\mathcal{V}(t)} ch^k \|z\|_{\mathcal{Z}_0(t)} + \|\partial_\ell^\bullet (z - \pi_h z)\|_{\mathcal{V}(t)} ch^k \|\partial^\bullet z\|_{\mathcal{Z}(t)} \\ &\quad + ch^k (\|z\|_{\mathcal{Z}(t)} + \|\partial^\bullet z\|_{\mathcal{Z}(t)}) \|I_h \partial^\bullet z - \partial_\ell^\bullet \pi_h z\|_{\mathcal{V}(t)} \\ &\leq \|\partial_\ell^\bullet (z - \pi_h z)\|_{\mathcal{V}(t)} ch^k \|z\|_{\mathcal{Z}_0(t)} + \|\partial_\ell^\bullet (z - \pi_h z)\|_{\mathcal{V}(t)} ch^k \|\partial^\bullet z\|_{\mathcal{Z}(t)} \\ &\quad + ch^k (\|z\|_{\mathcal{Z}(t)} + \|\partial^\bullet z\|_{\mathcal{Z}(t)}) (\|I_h \partial^\bullet z - \partial^\bullet z\|_{\mathcal{V}(t)} \|\partial^\bullet z - \partial_\ell^\bullet \pi_h z\|_{\mathcal{V}(t)}). \end{aligned}$$

Again, using the interpolation bound (I2) and the coercivity of a^κ (3.18) and rearranging using a Young's inequality gives

$$(3.33) \quad \|\partial_\ell^\bullet (z - \pi_h z)\|_{\mathcal{V}(t)} \leq ch^k (\|z\|_{\mathcal{Z}(t)} + \|\partial^\bullet z\|_{\mathcal{Z}(t)}).$$

To show the $\mathcal{H}(t)$ -norm bound, we consider the dual problem (3.21) with $\xi = e := \partial_\ell^\bullet (z - \pi_h z) \in \mathcal{H}(t)$. Then, there exists $\mathcal{R}(\xi) \in \mathcal{V}(t)$ such that

$$a^\kappa(t; \eta, \mathcal{R}(\xi)) = m(t; e, \eta) \quad \text{for all } \eta \in \mathcal{V}(t).$$

Furthermore, $\mathcal{R}(\xi) \in \mathcal{Z}_0(t)$ and satisfies the bound

$$(3.34) \quad \|\mathcal{R}(\xi)\|_{\mathcal{Z}_0(t)} \leq c \|e\|_{\mathcal{H}(t)}.$$

Then we have

$$\|\partial_\ell^\bullet (z - \pi_h z)\|_{\mathcal{H}(t)}^2 \leq c_2^2 m(t; e, e) = c_2^2 a^\kappa(t; \partial_\ell^\bullet (z - \pi_h z), \mathcal{R}(\xi)) = c_2^2 T_h(\mathcal{R}(\xi)).$$

The second bound on T_h (3.32), the $\mathcal{V}(t)$ -norm error bound (3.33) and the dual regularity result (3.34) give

$$\begin{aligned} \|e\|_{\mathcal{H}(t)}^2 &\leq ch^{k+1} (\|z\|_{\mathcal{Z}(t)} + \|\partial^\bullet z\|_{\mathcal{Z}(t)}) \|\mathcal{R}(\xi)\|_{\mathcal{Z}_0(t)} + ch \|e\|_{\mathcal{V}(t)} \|\mathcal{R}(\xi)\|_{\mathcal{Z}_0(t)} \\ &\leq ch^{k+1} (\|z\|_{\mathcal{Z}(t)} + \|\partial^\bullet z\|_{\mathcal{Z}(t)}) \|e\|_{\mathcal{H}(t)}. \end{aligned}$$

Rearranging this inequality gives the desired $\mathcal{H}(t)$ -norm bound. \square

3.4. Abstract error bound. To show the error bound we make the following assumption on the smoothness of the continuous problem. We assume that $u \in C_{\mathcal{V}}^1$, and that there exists a constant $C > 0$ such that u satisfies that regularity estimate

$$(R1) \quad \sup_{t \in [0, T]} \|u\|_{\mathcal{Z}(t)}^2 + \int_0^T \|\partial^\bullet u\|_{\mathcal{Z}(t)}^2 dt \leq C.$$

Theorem 3.11. *Let all the assumptions listed in Sec. 3.2 hold as well as (B3) and (R1). Denote by u the solution of (2.9) and by $U_h \in C_{S_h}^1$ the solution of (3.7) with lift $u_h \in C_{S_h}^1$. Then, there exists constant $c > 0$ such that for $h \in (0, h_0)$ we have the error estimate*

$$(3.35) \quad \sup_{t \in [0, T]} \|u - u_h\|_{\mathcal{H}(t)}^2 + h^2 \int_0^T \|u - u_h\|_{\mathcal{V}(t)}^2 dt \leq \|u_0 - u_{h,0}\|_{\mathcal{H}(0)}^2 + ch^{2k+2} \left(\sup_{t \in [0, T]} \|u\|_{\mathcal{Z}(t)}^2 + \int_0^T \|\partial^\bullet u\|_{\mathcal{Z}(t)}^2 dt \right).$$

To show the error bound, we start by rescaling both solutions. Let $\check{u} = e^{-\kappa t} u$ and $\check{U}_h = e^{-\kappa t} U_h$, which satisfy

$$(3.36) \quad m(t; \partial^\bullet \check{u}, \eta) + g(t; \check{u}, \eta) + a^\kappa(t; \check{u}, \eta) = 0 \quad \text{for all } \eta \in L_{\mathcal{V}}^2$$

$$(3.37) \quad \frac{d}{dt} m_h(t; \check{U}_h, \chi_h) + a_h^\kappa(t; \check{U}_h, \chi_h) - m_h(t; \check{U}_h, \partial_h^\bullet \chi_h) = 0 \quad \text{for all } \chi_h \in C_{S_h}^1.$$

Our assumptions imply

$$(3.38) \quad \sup_{t \in [0, T]} \|\check{u}\|_{\mathcal{Z}(t)}^2 + \int_0^T \|\partial^\bullet \check{u}\|_{\mathcal{Z}(t)}^2 dt \leq e^{-2\kappa t} \left(\sup_{t \in [0, T]} \|u\|_{\mathcal{Z}(t)}^2 + \int_0^T \|\partial^\bullet u\|_{\mathcal{Z}(t)}^2 dt + \kappa^2 \|u\|_{\mathcal{Z}(t)}^2 dt \right) < C.$$

We define $\check{u}_h := \check{U}_h^\ell$ to be the lift of \check{U}_h . We will decompose the error as:

$$(3.39) \quad \check{u}_h - \check{u} = (\check{u}_h - \pi_h \check{u}) + (\pi_h \check{u} - \check{u}) =: \theta + \rho.$$

We already have bounds on ρ from Lem. 3.8 and 3.10, thanks to assumption (R1), so it remains to show a bound for θ . We will denote by $\vartheta = \check{U}_h - \Pi_h \check{u}$, and by our assumptions, we know $\vartheta \in C_{S_h}^1$.

Lemma 3.12. *Let $\chi_h \in C_{S_h}^1$ and denote by $\chi_h^\ell \in C_{S_h}^1$. Then $\vartheta = \check{U}_h - \Pi_h \check{u}$ satisfies*

$$(3.40) \quad \frac{d}{dt} m_h(t; \vartheta, \chi_h) + a_h^\kappa(t; \vartheta, \chi_h) - m_h(t; \vartheta, \partial_h^\bullet \chi_h) = -E_1(\chi_h) - E_2(\chi_h),$$

where

$$\begin{aligned} E_1(\chi_h) &= m(t; \partial_\ell^\bullet \rho, \chi_h^\ell) + g_\ell(t; \rho, \chi_h^\ell) \\ E_2(\chi_h) &= (m_h(t; \partial_h^\bullet \Pi_h \check{u}, \chi_h) - m(t; \partial_\ell^\bullet \pi_h \check{u}, \chi_h^\ell)) + (g_h(t; \Pi_h \check{u}, \chi_h) - g_\ell(t; \pi_h \check{u}, \chi_h^\ell)) \\ &\quad + m(t; \check{u}, \partial^\bullet \chi_h^\ell - \partial_\ell^\bullet \chi_h^\ell). \end{aligned}$$

Proof. We transform (3.36) into variational form using (G1), then together with the definition of the Ritz projection (3.20), we see that

$$\begin{aligned} &\frac{d}{dt} m_h(t; \Pi_h \check{u}, \chi_h) + a_h^K(t; \Pi_h \check{u}, \chi_h) - m_h(t; \Pi_h \check{u}, \partial_h^\bullet \chi_h) \\ &= \frac{d}{dt} (m_h(t; \Pi_h \check{u}, \chi_h) - m(t; \check{u}, \chi_h^\ell)) - (m_h(t; \Pi_h \check{u}, \partial_h^\bullet \chi_h) - m(t; \check{u}, \partial^\bullet \chi_h^\ell)). \end{aligned}$$

We use the transport formulae (G_h1) for m_h and (G_ℓ1) for m to see

$$\begin{aligned} &\frac{d}{dt} m_h(t; \Pi_h \check{u}, \chi_h) + a_h^K(t; \Pi_h \check{u}, \chi_h) - m_h(t; \Pi_h \check{u}, \partial_h^\bullet \chi_h) \\ &= (m_h(t; \partial_h^\bullet \Pi_h \check{u}, \chi_h) - m(t; \partial_\ell^\bullet \check{u}, \chi_h^\ell)) + (g_h(t; \Pi_h \check{u}, \chi_h) - g_\ell(t; \check{u}, \chi_h^\ell)) \\ &\quad + m(t; \check{u}, \partial^\bullet \chi_h^\ell - \partial_\ell^\bullet \chi_h^\ell). \end{aligned}$$

Subtracting this equation from (3.37) and rearranging gives (3.40). \square

Lemma 3.13. For $\chi_h \in \mathcal{S}_h(t)$, the consistency terms E_1 and E_2 satisfy

$$(3.41) \quad |E_1(\chi_h)| + |E_2(\chi_h)| \leq ch^{k+1} (\|\check{u}\|_{\mathcal{Z}(t)} + \|\partial^\bullet \check{u}\|_{\mathcal{Z}(t)}) \|\chi_h\|_{\mathcal{V}_h(t)}.$$

Proof. For E_1 , we use (M2) and (2.6) together with the error bounds from (3.23) and (3.30) to see

$$\begin{aligned} |E_1(\chi_h)| &\leq c (\|\rho\|_{\mathcal{H}(t)} + \|\partial_\ell^\bullet \rho\|_{\mathcal{H}(t)}) \|\chi_h\|_{\mathcal{H}_h} \\ &\leq ch^{k+1} (\|\check{u}\|_{\mathcal{Z}(t)} + \|\partial^\bullet \check{u}\|_{\mathcal{Z}(t)}) \|\chi_h\|_{\mathcal{V}_h(t)}. \end{aligned}$$

For E_2 , we use the perturbation estimates (P1), (P2) and (P8) together with the stability bounds on the Ritz projection (3.22) and (3.29) to see

$$\begin{aligned} |E_2(\chi_h)| &\leq ch^{k+1} (\|\check{u}\|_{\mathcal{H}(t)} + \|\Pi_h \check{u}\|_{\mathcal{V}_h(t)} + \|\partial_h^\bullet \Pi_h \check{u}\|_{\mathcal{V}_h(t)}) \|\chi_h\|_{\mathcal{V}_h(t)} \\ &\leq ch^{k+1} (\|\check{u}\|_{\mathcal{Z}(t)} + \|\partial^\bullet \check{u}\|_{\mathcal{Z}(t)}) \|\chi_h\|_{\mathcal{V}_h(t)}. \end{aligned} \quad \square$$

Lemma 3.14. The following bound holds for $\vartheta = \check{U}_h - \Pi_h \check{u}$

$$(3.42) \quad \sup_{t \in [0, T]} \|\vartheta\|_{\mathcal{H}_h(t)}^2 + \int_0^T \|\vartheta\|_{\mathcal{V}_h(t)}^2 dt \leq \|\vartheta\|_{\mathcal{H}_h(0)}^2 + ch^{2k+2} \int_0^T (\|\check{u}\|_{\mathcal{Z}(t)}^2 + \|\partial^\bullet \check{u}\|_{\mathcal{Z}(t)}^2) dt.$$

Proof. We test (3.40) with $\chi_h = \vartheta$ to see

$$\frac{d}{dt} m_h(t; \vartheta, \vartheta) + a_h^K(t; \vartheta, \vartheta) - m_h(t; \vartheta, \partial_h^\bullet \vartheta) = -E_1(\vartheta) - E_2(\vartheta).$$

The transport formula for m_h (G_h1) tells us that

$$\frac{d}{dt} m_h(t; \vartheta, \vartheta) - m_h(t; \vartheta, \partial_h^\bullet \vartheta) = \frac{1}{2} \frac{d}{dt} m_h(t; \vartheta, \vartheta) + \frac{1}{2} g_h(t; \vartheta, \vartheta),$$

hence, applying the bound on E_1 and E_2 (3.41) we infer that

$$\frac{1}{2} \frac{d}{dt} m_h(t; \vartheta, \vartheta) + a_h^k(t; \vartheta, \vartheta) \leq -\frac{1}{2} g_h(t; \vartheta, \vartheta) + ch^{k+1} (\|\check{u}\|_{\mathcal{Z}(t)} + \|\partial^\bullet \check{u}\|_{\mathcal{Z}(t)}) \|\vartheta\|_{\mathcal{V}_h(t)}.$$

Applying the boundedness and coercivity estimates from m_h, a_h^k and g_h (M_h2), (3.19) and (G_h2) with a Young's inequality and integrating in time gives

$$\begin{aligned} \|\vartheta\|_{\mathcal{H}_h(t)}^2 + \int_0^t \|\vartheta\|_{\mathcal{V}_h(t')}^2 dt' \\ \leq \|\vartheta\|_{\mathcal{H}_h(0)}^2 + c \int_0^t \|\vartheta\|_{\mathcal{H}_h(t')}^2 dt' + ch^{2k+2} \int_0^t (\|\check{u}\|_{\mathcal{Z}(t')}^2 + \|\partial^\bullet \check{u}\|_{\mathcal{Z}(t')}^2) dt'. \end{aligned}$$

Finally, we use a Grönwall inequality to see the desired result. \square

Finally, we can show the result of Thm. 3.11.

Proof of Thm. 3.11. We apply the splitting (3.39), the bounds on ρ from Lem. 3.8, the bounds on θ from Lem. 3.14 and the estimate on \check{u} from (3.38) to see

$$\begin{aligned} \sup_{t \in (0, T)} \|u - u_h\|_{\mathcal{H}(t)}^2 + h^2 \int_0^T \|u - u_h\|_{\mathcal{V}(t)}^2 dt \\ \leq c \sup_{t \in (0, T)} (\|\theta\|_{\mathcal{H}(t)}^2 + \|\rho\|_{\mathcal{H}(t)}^2) + h^2 \int_0^T (\|\theta\|_{\mathcal{V}(t)}^2 + \|\rho\|_{\mathcal{V}(t)}^2) \\ \leq ch^{2k+2} \left(\sup_{t \in (0, T)} \|\check{u}\|_{\mathcal{Z}(t)}^2 + \int_0^T (\|\check{u}\|_{\mathcal{Z}(t)}^2 + \|\partial^\bullet \check{u}\|_{\mathcal{Z}(t)}^2) dt \right) + c \|u - u_{h,0}\|_{\mathcal{H}(0)}^2 \\ \leq ch^{2k+2} \left(\sup_{t \in (0, T)} \|u\|_{\mathcal{Z}(t)}^2 + \int_0^T \|\partial^\bullet u\|_{\mathcal{Z}(t)}^2 dt \right) + c \|u_0 - u_{h,0}\|_{\mathcal{H}(0)}^2. \end{aligned}$$

The final line follows since the L^2 norm is bounded by the L^∞ norm. \square

Part 2. Evolving finite element spaces

4. EVOLVING BULK FINITE ELEMENT SPACES

In this section, we will define families of evolving bulk finite element spaces $\{\mathcal{S}_h(t)\}_{t \in [0, T]}$ on families of evolving triangulated bulk domains $\{\Omega_h(t)\}_{t \in [0, T]}$ consisting of unions of elements. We have in mind $\Omega_h(t) \subset \mathbb{R}^{n+1}$ approximating an open bounded domain $\Omega(t) \subset \mathbb{R}^{n+1}$. We will use the word bulk in this section to emphasise the difference to the surface case considered in [Sec. 6](#) but more common terminology would simply remove this word.

Our work extends from standard bulk finite element theory ([Ciarlet, 1978](#)) and the work of [Ciarlet and Raviart \(1972\)](#) and [Bernardi \(1989\)](#) for Cartesian bulk domains with curved boundaries to the evolving case. Throughout this section we will denote global discrete quantities with a subscript $h \in (0, h_0)$, which is related to element size. We assume implicitly that these structures exist for each h in this range. See also [Rem. 4.11](#). For ease of exposition we begin with definitions without the time parameter, t .

4.1. Reference finite element.

Definition 4.1 (Reference finite element). The triple $(\hat{K}, \hat{P}, \hat{\Sigma})$ is a *reference finite element* if:

- (a) the *element domain* $\hat{K} \subset \mathbb{R}^m$ is the closure of an open domain with Lipschitz piecewise smooth boundary,
- (b) the set of *shape functions* \hat{P} is a finite dimensional space of functions over \hat{K} ,
- (c) the *nodal variables* or *degrees of freedom* $\hat{\Sigma} = \{\hat{\sigma}_1, \dots, \hat{\sigma}_d\}$ are a basis of \hat{P}' the dual space to \hat{P} ,

and $\hat{\Sigma}$ determines \hat{P} , that is if for $\hat{\chi} \in \hat{P}$ with $\hat{\sigma}(\hat{\chi}) = 0$ for all $\hat{\sigma} \in \hat{\Sigma}$, we have $\hat{\chi} = 0$.

As part of this definition, we are implicitly assuming that the nodal variables live in the dual to a larger function space than \hat{P} . We will see that this usually requires further smoothness or continuity of finite element functions. We give an example of a simplicial finite element, but this definition includes other examples such as isoparametric finite elements and brick finite elements.

Recall that a (non-degenerate) m -simplex K in \mathbb{R}^m , is the convex hull of $m + 1$ distinct points $\{a_i\}_{i=1}^{m+1} \subset \mathbb{R}^m$, called the *vertices* of the m -simplex, which are not contained in a common $(m - 1)$ -dimension hyperplane. More precisely, we have

$$K = \left\{ x = \sum_{i=1}^{m+1} \mu_i a_i : 0 \leq \mu_i \leq 1, 1 \leq i \leq m+1, \sum_{i=1}^{m+1} \mu_i = 1 \right\}.$$

For each $x \in K$, we call $\{\mu_i\}_{i=1}^{m+1}$ *barycentric coordinates*. For any integer l with $0 \leq l \leq m$, an l -facet of an m -simplex K is any l -simplex whose $(l + 1)$ vertices are also vertices of K . We call an $(m - 1)$ -facet a *boundary facet*. We will also use the term boundary facet for any boundary polytopes (union of simplicies) of a polytope K . For each $k \geq 0$, we shall denote by P_k the space of all polynomials of degree k in the variables x_1, \dots, x_m in \mathbb{R}^m . For any set $A \subset \mathbb{R}^m$, we let

$$P_k(A) = \{\chi|_A : \chi \in P_k\}.$$

Example 4.2 (Example of reference finite element). The standard piecewise linear finite element $(K, P_1(K), \Sigma^K)$ is obtained by choosing K to be a non-degenerate m -simplex in \mathbb{R}^m and $\Sigma^K = \{\chi \mapsto \chi(a_i) : 1 \leq i \leq m + 1\}$. We can also define higher order spaces $(K, P_k(K), \Sigma^K)$, for $k \geq 2$, by including extra evaluation points in Σ^K (see, for example, [Ciarlet \(1978, Section 2.2\)](#)). The key property of the extra evaluation points is that they

determine the particular function in $P_k(K)$. It is also true that the restriction of Σ^K to any facet determines the restriction of functions in $P_k(K)$ on that facet.

Given the reference element $(\hat{K}, \hat{P}, \hat{\Sigma})$ and a function $\hat{\eta} : \hat{K} \rightarrow \mathbb{R}$ for which the nodal variables $\sigma_i(\hat{\eta})$ can be computed (e.g. in the case of Lagrange element we require $\hat{\eta}$ to be continuous), we define the nodal interpolation of $\hat{\eta}$, written $\hat{I}\hat{\eta}$, as the unique function in \hat{P} which has the same nodal values as $\hat{\eta}$. Let $\{\hat{\chi}_i : 1 \leq i \leq d\} \subset P$ be the basis of P dual to Σ then we can characterise $\hat{I}\hat{\eta}$ as

$$\hat{I}\hat{\eta} := \sum_{i=1}^d \sigma_i(\hat{\eta}) \chi_i.$$

Lemma 4.3 (Bramble-Hilbert Lemma, Ciarlet 1978, Thm. 3.1.5). *Let the following inclusions hold for $m, k > 0$, and $p, q \in [1, \infty]$,*

$$\begin{aligned} W^{k+1,p}(\hat{K}) &\hookrightarrow C(\hat{K}) \\ W^{k+1,p}(\hat{K}) &\hookrightarrow W^{m,q}(\hat{K}) \\ P_k(\hat{K}) &\subset \hat{P} \subset W^{m,q}(\hat{K}). \end{aligned}$$

Under the above assumptions on the reference finite element we have that there exists a constant $C = C(\hat{K}, \hat{P}, \hat{\Sigma}) > 0$ such that for all functions $\hat{\eta} \in W^{k+1,p}(\hat{K})$,

$$(4.1) \quad |\hat{\eta} - \hat{I}\hat{\eta}|_{W^{m,q}(\hat{K})} \leq C |\hat{\eta}|_{W^{k+1,p}(\hat{K})}.$$

4.2. Bulk finite element. We start by defining a single bulk finite element in \mathbb{R}^{n+1} . Our definition of bulk finite element combines Def. 2.1 and 2.3 from (Bernardi, 1989).

Definition 4.4 (Bulk element reference map and bulk finite element). Let $(\hat{K}, \hat{P}, \hat{\Sigma})$ be a reference finite element (Def. 4.1) with $\hat{K} \subset \mathbb{R}^{n+1}$.

- (a) Let $F_K : \hat{K} \rightarrow \mathbb{R}^{n+1}$ satisfy
 - (1) (a) $F_K \in C^1(\hat{K}, \mathbb{R}^{n+1})$;
 - (b) $\text{rank } \nabla F_K = n + 1$;
 - (c) F_K is a bijection onto its image;
- (2) F_K can be decomposed into an affine part and smooth part

$$F_K(\hat{x}) = A_K \hat{x} + b_K + D_K(\hat{x})$$

such that A_K is an invertible $(n+1) \times (n+1)$ matrix, $b_K \in \mathbb{R}^{n+1}$, and $D_K \in C^1(\hat{K})$

$$(4.2) \quad C_K := \sup_{\hat{x} \in \hat{K}} \|\nabla D_K(\hat{x}) A_K^{-1}\| < 1,$$

where $\|\cdot\|$ denotes the two-norm of the matrix.

In this situation we call F_K a *bulk element reference map*.

- (b) Let F_K be a bulk element reference map and (K, P, Σ) be the triple given by

$$(4.3a) \quad K := F_K(\hat{K}) \quad (\text{the element domain})$$

$$(4.3b) \quad P := \{\hat{\chi} \circ F_K^{-1} : \hat{\chi} \in \hat{P}\} \quad (\text{the shape functions})$$

$$(4.3c) \quad \Sigma := \{\chi \mapsto \hat{\sigma}(\chi \circ F_K) : \hat{\sigma} \in \hat{\Sigma}\} \quad (\text{the nodal variables}).$$

Under the above assumptions, we call (K, P, Σ) a *bulk finite element*, $(\hat{K}, \hat{P}, \hat{\Sigma})$ the associated *reference finite element*.

With the bulk reference element map F_K we can compute integrals and derivatives over the reference element using the transformation identity:

$$\int_K \chi(x) dx = \int_{\hat{K}} \hat{\chi}(\hat{x}) |\det \nabla F_K(\hat{x})| d\hat{x}, \quad \nabla \chi(x) = \nabla F_K^{-t}(\hat{x}) \nabla \hat{\chi}(\hat{x}).$$

We denote by ν_K the outward pointing normal to K .

Definition 4.5 (Θ -bulk finite element, Def. 2.4 Bernardi 1989). Let $\Theta \in \mathbb{N}$ and F_K be the bulk element reference map for a bulk finite element (K, P, Σ) .

- (a) We say that F_K is a Θ -bulk finite element reference map if
- (i) the bulk element reference map $F_K \in C^{\Theta+1}(\hat{K}; \mathbb{R}^{n+1})$;
 - (ii) for $1 \leq m \leq \Theta + 1$, there exists constants $C_m(K) > 0$ such that

$$(4.4) \quad \sup_{\hat{x} \in \hat{K}} |\nabla^m F_K(\hat{x})| \|A_K\|^{-m} \leq C_m(K).$$

- (b) We say that (K, P, Σ) is a Θ -bulk finite element if F_K is a Θ -bulk finite element reference map and
- (i) the space P contains the functions $\hat{\chi} \circ F_K^{-1}$ for all $\hat{\chi} \in P_{\Theta}(\hat{K})$;
 - (ii) the space P is contained in $C^{\Theta+1}(K)$.

Remark 4.6. The properties of K allow us to define the Sobolev spaces $W^{m,p}(K)$ for $1 \leq m \leq \Theta + 1$, $1 \leq p \leq \infty$. Since $P \subset C^{\Theta+1}(K)$ and is finite dimensional, we clearly see that P is a closed subspace of $W^{m,p}(K)$ for $1 \leq m \leq \Theta + 1$, $1 \leq p \leq \infty$.

Example 4.7 (Bulk finite elements). We are thinking of two particular examples. The first is a standard Lagrange finite element and the second is an isoparametric finite element. Examples of each of these cases are shown in Fig. 4.1.

- (a) Let $(\hat{K}, \hat{P}, \hat{\Sigma})$ be a reference finite element. Consider the affine map $F_K: \hat{K} \rightarrow \mathbb{R}^{n+1}$ given by $F_K(\hat{x}) = A_K \hat{x} + b_K$. If A_K is non-singular, then this defines a bulk finite element (K, P, Σ) . In the standard way, the element domain K is defined by the location of its vertices. For a simplex reference element domain \hat{K} , we are thinking of line segments in \mathbb{R} , triangles in \mathbb{R}^2 and tetrahedra in \mathbb{R}^3 .
- (b) Let $(\hat{K}, \hat{P}, \hat{\Sigma})$ be a reference finite element. Let (K, P, Σ) be a bulk finite element which is the image of $(\hat{K}, \hat{P}, \hat{\Sigma})$ under a map F_K which satisfies $F_K \in (\hat{P})^{n+1}$. We call (K, P, Σ) an isoparametric bulk finite element. We note that the functions in P will not necessarily consist of polynomials over K even if \hat{P} consists of polynomials over \hat{K} , however this leads to a practical scheme where integrals are computed over reference elements. This example is the basis for the method in Sec. 8.

The definition of bulk finite element (Def. 4.4), in particular (4.2), is constructed to allow the following result:

Lemma 4.8 (Lem. 2.1, Bernardi 1989). Let $F_K: \hat{K} \rightarrow K$ be a bulk finite element reference map then F_K is a C^1 -diffeomorphism and satisfies

$$(4.5) \quad \sup_{\hat{x} \in \hat{K}} \|\nabla F_K(\hat{x})\| \leq (1 + C_K) \|A_K\|$$

$$(4.6) \quad \sup_{\hat{x} \in \hat{K}} \|(\nabla F_K(\hat{x}))^{-1}\| \leq (1 - C_K) \|A_K^{-1}\|,$$

and also for all $\hat{x} \in \hat{K}$

$$(4.7) \quad (1 - C_K)^{n+1} |\det(A_K)| \leq |\det(\nabla F_K(\hat{x}))| \leq (1 + C_K)^{n+1} |\det(A_K)|.$$

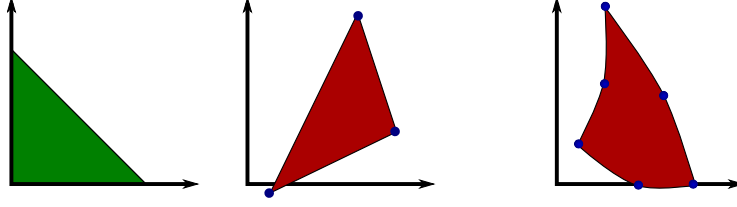


FIGURE 4.1. Examples of different bulk finite elements in the case $n = 2$. Left shows a reference finite element (in green), centre shows a standard finite element (Ex. 4.7(a)) and right shows an isoparametric bulk finite element (Ex. 6.7(b)) with quadratic F_K . The plot shows the element domains in red and the location of the nodes in blue.

To help us understand the geometry of the new element domains K , we introduce a new element domain \tilde{K} defined by the affine part of the parametrisation: $\tilde{K} := \{A_K \hat{x} + b_K : \hat{x} \in \hat{K}\}$.

Lemma 4.9. *Let K be an element domain (4.3a) parametrised by a bulk element reference map F_K over \hat{K} . Denote by*

$$(4.8a) \quad h_K := \text{diam}(\tilde{K})$$

$$(4.8b) \quad \rho_K := \sup\{\text{diam}(B) : B \text{ is a } n\text{-dimensional ball contained in } \tilde{K}\}.$$

We will also write \hat{h} and $\hat{\rho}$ for the diameter of \hat{K} and diameter of the maximum inscribed ball in \hat{K} . Then we have that

$$(4.9a) \quad \|A_K\| \leq \frac{h_K}{\hat{\rho}}$$

$$(4.9b) \quad \|A_K^{-1}\| \leq \frac{\hat{h}}{\rho_K}$$

$$(4.9c) \quad \sup_{\hat{x} \in \hat{K}} |\det(\nabla F_K(\hat{x}))| \leq \frac{1}{\text{meas } \hat{K}} \left(\frac{1+C_K}{1-C_K} \right)^{n+1} \text{meas}(K).$$

Proof. See (Ciarlet, 1978, Thm. 3.1.3). □

Remark 4.10. We note that the volume of an element $\text{meas}(K)$ can be estimated by h_K and ρ_K by

$$c_1 \rho_K^{n+1} \leq \text{meas} K \leq c_2 h_K^{n+1}.$$

Here the positive constants c_1, c_2 depend on the volume of the unit ball in \mathbb{R}^{n+1} and the constant C_K .

Remark 4.11. In the sequel, we will assume implicitly that results hold for h_K sufficiently small ($h_K < h_0$) for some particular value of h_0 . In general this is always possible by subdividing a particular element using a refinement procedure and applying the result to the subdivided, smaller elements.

The choice of mapping allows us to relate functions defined on K to functions on \hat{K} .

Lemma 4.12 (Lem. 2.3, Bernardi 1989). *Let $F_K: \hat{K} \rightarrow K$ be a Θ -bulk finite element reference map (Def. 4.5). Let $0 \leq m \leq \Theta + 1$ and $p \in [1, \infty]$, then $\chi \in W^{m,p}(K)$ implies $\hat{\chi} = \chi \circ F_K$ belongs to $W^{m,p}(\hat{K})$. We have for any $\chi \in W^{m,p}(K)$ that*

$$(4.10) \quad |\hat{\chi}|_{W^{m,p}(\hat{K})} \leq c |\det A_K|^{-\frac{1}{p}} \|A_K\|^m \sum_{r=0}^m |\chi|_{W^{r,p}(K)},$$

for a constant which depends on $C_K, C_2(K), \dots, C_m(K)$. We also have for any $\hat{\chi} \in W^{m,p}(\hat{K})$ that $\chi = \hat{\chi} \circ F_K^{-1} \in W^{m,p}(K)$ and

$$(4.11) \quad |\chi|_{W^{m,p}(K)} \leq c |\det A_K|^{\frac{1}{p}} \sum_{r=0}^m \|A_K^{-1}\|^r |\hat{\chi}|_{W^{r,p}(\hat{K})},$$

where the constant here depends on $C_K, C_2(K), \dots, C_m(K)$ and the product $\|A_K\| \|A_K^{-1}\|$.

Given a bulk finite element (K, P, Σ) (Def. 4.4), let $\{\chi_i : 1 \leq i \leq d\} \subset P$ be the basis dual to Σ . This is the set of *basis functions* of the finite element. If η is a function for which all $\sigma_i(\eta)$, $1 \leq i \leq d$ is well defined, then we define the *local interpolant* by

$$(4.12) \quad I_K \eta := \sum_{i=1}^d \sigma_i(\eta) \chi_i.$$

We can think of $I_K \eta$ as the unique shape function that has the same nodal values as η so that, in particular, $I_K \chi = \chi$ for $\chi \in P$.

Theorem 4.13 (Local interpolation estimate). *Let (K, P, Σ) be a Θ -bulk finite element (Def. 4.5) with reference element $(\hat{K}, \hat{P}, \hat{\Sigma})$ by F_K which satisfies the assumptions of Lem. 4.3 for some $0 < k, m \leq \Theta$, $p, q \in [1, \infty]$. Then there exists a constant $C = C(\hat{K}, \hat{P}, \hat{\Sigma})$ such that for all functions $\chi \in W^{k+1,p}(K)$*

$$(4.13) \quad |\chi - I_K \chi|_{W^{m,q}(K)} \leq C \text{meas}(K)^{1/q-1/p} \frac{h_K^{k+1}}{\rho_K^m} |\chi|_{W^{k+1,p}(K)}.$$

Proof. We re-scale (4.1) using Lem. 4.12 and the estimates from (4.9):

$$\begin{aligned} |\chi - I_K \chi|_{W^{m,q}(K)} &\leq c \left(\sup_{\hat{x} \in \hat{K}} |\det \nabla F_K(\hat{x})| \right)^{1/q} \sum_{r=0}^m \|A_K^{-1}\|^r |\hat{\chi} - I_{\hat{K}} \hat{\chi}|_{W^{r,q}(\hat{K})} \\ &\leq c \left(\sup_{\hat{x} \in \hat{K}} |\det \nabla F_K(\hat{x})| \right)^{1/q} \sum_{r=0}^m \|A_K^{-1}\|^r |\hat{\chi}|_{W^{k+1,p}(\hat{K})} \\ &\leq c \left(\sup_{\hat{x} \in \hat{K}} |\det \nabla F_K(\hat{x})| \right)^{1/q-1/p} \sum_{r=0}^m \|A_K^{-1}\|^r \|A_K\|^{k+1} |\chi|_{W^{k+1,p}(K)} \\ &\leq c \text{meas}(K)^{1/q-1/p} \frac{h_K^{k+1}}{\rho_K^m} \|\chi\|_{W^{k+1,p}(K)}. \end{aligned}$$

The last line holds if $\rho_K < 1$ (note that $\rho_K \geq h_K$ so this statement is true for h_K small enough). \square

4.3. Triangulated bulk domain and spaces. Next, we bring together a finite family of bulk finite elements in order to create a bulk finite element space.

Definition 4.14. (a) A *triangulated (bulk) domain* is a set Ω_h equipped with an *admissible subdivision* \mathcal{T}_h consisting of bulk finite element domains such that $\bigcup_{K \in \mathcal{T}_h} K = \Omega_h$, $\hat{K}_1 \cap \hat{K}_2 = \emptyset$ for $K_1, K_2 \in \mathcal{T}_h$ with $K_1 \neq K_2$.

(b) The maximum subdivision diameter h is defined by:

$$(4.14) \quad h := \max_{K \in \mathcal{T}_h} h_K.$$

- (c) Let Ω_h be a discrete bulk domain equipped with an admissible subdivision \mathcal{T}_h such that each set $K \in \mathcal{T}_h$ is an element domain for a bulk finite element $(K, \mathbf{P}^K, \Sigma^K)$ parametrised over the same polygonal reference finite element $(\hat{K}, \hat{\mathbf{P}}, \hat{\Sigma})$. We say that $E \subset K$ is a *facet* if E is the image of a boundary facet of \hat{K} .
- (d) We say that \mathcal{T}_h is a *conforming* subdivision of Ω_h if any facet of an element domain K is either a facet of another element domain $K' \in \mathcal{T}_h$, in which case we say K and K' are *adjacent*, or a portion of the boundary $\partial\Omega_h$.
- (e) For a conforming subdivision, we denote by \mathcal{F}_h the set of facets between adjacent elements and by $\partial\mathcal{T}_h$ the set of boundary facets. For an internal facet $F \in \mathcal{F}_h$ between adjacent elements $K, K' \in \mathcal{T}_h$, we make a choice of the two elements and denote by \mathbf{v}_F^+ the outward normal to K and by \mathbf{v}_F^- the outward normal to K' . The particular choice will not affect our calculations.

Remark 4.15. (a) We recall that our element domains (Def. 4.1(a)) are closed so that Ω_h is also a closed set.

- (b) When putting together bulk finite elements in order to form a discrete domain Ω_h , we will be generally thinking of the case that only elements with more than one vertex on the boundary are curved ($D_K \neq 0$). See Sec. 8 for more details. We allow for the more general case here.

Definition 4.16 (Broken Sobolev spaces and norms). Let \mathcal{T}_h be a subdivision of Ω_h consisting of Θ -bulk finite elements. Then for $0 \leq m \leq \Theta + 1$, $p \in [1, \infty]$, we define the broken Sobolev space $W^{m,p}(\mathcal{T}_h)$ by

$$(4.15) \quad W^{m,p}(\mathcal{T}_h) := \{ \eta_h \in L^1(\Omega_h) : \eta_h|_K \in W^{m,p}(K) \text{ for all } K \in \mathcal{T}_h \},$$

with norm

$$(4.16) \quad \|\eta_h\|_{W^{m,p}(\mathcal{T}_h)} := \begin{cases} \left(\sum_{K \in \mathcal{T}_h} \|\eta_h\|_{W^{m,p}(K)}^p \right)^{1/p} & p < \infty \\ \max_{K \in \mathcal{T}_h} \|\eta_h\|_{W^{m,\infty}(K)} & p = \infty. \end{cases}$$

Remark 4.17. This space is often used in the context of discontinuous Galerkin finite element methods. See, for example, Arnold, Brezzi, Cockburn and Marini (2002).

Lemma 4.18. *The space $W^{m,p}(\mathcal{T}_h)$ is complete.*

Proof. Consider a Cauchy sequence $\{\eta_j\} \in W^{m,p}(\mathcal{T}_h)$. This implies

- η_j is Cauchy in $L^p(\Omega_h)$ so there exists ξ such that $\eta_j \rightarrow \xi$ in $L^p(\Omega_h)$.
- $\eta_j|_K$ is Cauchy for all K so there exists ξ_K such that $\eta_j|_K \rightarrow \xi_K$ in $W^{m,p}(K)$.

It is clear from the triangle inequality that $\xi|_K = \xi_K$:

$$\|\xi|_K - \xi_K\|_{W^{m,p}(K)} \leq \|\xi|_K - \eta_j|_K\|_{L^{m,p}(K)} + \|\eta_j|_K - \xi_K\|_{W^{m,p}(K)},$$

since the right hand-side converges to 0 as $j \rightarrow \infty$. Hence, we have shown that η_j converges to a function $\xi \in W^{m,p}(\mathcal{T}_h)$ in the $W^{m,p}(\mathcal{T}_h)$ norm. \square

Let Ω_h be a triangulated domain with conforming subdivision \mathcal{T}_h . For $K \in \mathcal{T}_h$, we denote the trace of a function $\eta \in W^{1,p}(K)$ by $T_K \eta \in L^p(\partial K)$ and recall that there exists a constant $c_{T_K} > 0$ such that

$$(4.17) \quad \|T_K \eta\|_{L^p(\partial K)} \leq c_{T_K} \|\eta\|_{W^{1,p}(K)} \quad \text{for all } \eta \in W^{1,p}(K).$$

We define the space $W_T^{1,p}(\mathcal{T}_h)$ by

$$(4.18) \quad W_T^{1,p}(\mathcal{T}_h) := \left\{ \eta_h \in L^p(\Gamma_h) : \eta_h|_K \in W^{1,p}(K) \text{ for all } K \in \mathcal{T}_h, \text{ and} \right. \\ \left. T_K(\eta_h|_K) = T_{K'}(\eta_h|_{K'}) \text{ a.e. in } K \cap K' \text{ for adjacent } K, K' \in \mathcal{T}_h \right\}.$$

We equip this space with the broken norm $\|\cdot\|_{W^{1,p}(\mathcal{T}_h)}$.

Lemma 4.19. *The space $W_T^{1,p}(\mathcal{T}_h)$ is a closed subspace of $W^{1,p}(\mathcal{T}_h)$ so is complete.*

Proof. Take a sequence $\{\eta_j\}$ which converges to $\eta_h \in W^{1,p}(\mathcal{T}_h)$. Then for any pair of adjacent elements $K, K' \in \mathcal{T}_h$ we have

$$\begin{aligned} \|\eta_h|_K - \eta_h|_{K'}\|_{L^p(K \cap K')} &\leq \|\eta_h - \eta_j\|_{L^p(\partial K)} + \|\eta_h - \eta_j\|_{L^p(\partial K')} \\ &\leq c_{T_K} \|\eta_h - \eta_j\|_{W^{1,p}(K)} + c_{T_{K'}} \|\eta_h - \eta_j\|_{W^{1,p}(K')} \leq (c_{T_K} + c_{T_{K'}}) \|\eta_h - \eta_j\|_{W^{1,p}(\mathcal{T}_h)}. \end{aligned}$$

Clearly the right hand side converges to 0 as $j \rightarrow \infty$ so we have the traces of η_h from adjacent elements coincide and $\eta_h \in W^{1,p}(\mathcal{T}_h)$. \square

We will use the notation for $H_T^1(\mathcal{T}_h) := W_T^{1,2}(\mathcal{T}_h)$ which is a Hilbert space when equipped with the obvious broken inner product.

Lemma 4.20. *Let \mathcal{T}_h be a conforming subdivision of Ω_h then $W_T^{1,p}(\mathcal{T}_h) = W^{1,p}(\Omega_h)$.*

Proof. First, let $\eta_h \in W_T^{1,p}(\mathcal{T}_h)$. Then we have that $\eta_h \in L^p(\Omega_h)$ and it is left to show that η_h has a weak derivative in $L^p(\Omega_h)$. We have a candidate ξ given element-wise by $\xi|_K = \nabla(\eta_h|_K)$. It is clear that $\xi \in L^p(\Omega_h)$ and for $\varphi \in C_c^1(\Omega_h)$ and $i = 1, \dots, n+1$, we have

$$\begin{aligned} \int_{\Omega_h} \eta_h \partial_i \varphi &= \sum_{K \in \mathcal{T}_h} \int_K \eta_h \partial_i \varphi \\ &= \sum_{K \in \mathcal{T}_h} \left(- \int_K \xi_i \varphi + \int_{\partial K} \eta_h \varphi \nu_i^K \right) \\ &= - \int_{\Omega_h} \xi_i \varphi + \sum_{K \in \mathcal{T}_h} \int_{\partial K} \eta_h \varphi \nu_i^K. \end{aligned}$$

We note that we can write

$$\sum_{K \in \mathcal{T}_h} \int_{\partial K} \eta_h \varphi \nu_i^K = \sum_{F \in \mathcal{F}_h} \int_F \eta_h \varphi (\nu_F^+ + \nu_F^-)_i + \sum_{F \in \partial \mathcal{T}_h} \int_F \eta_h \varphi \nu_F = 0,$$

where \mathcal{F}_h is the set of facets between adjacent elements in \mathcal{T}_h , since the traces of $\eta_h|_K$ and $\eta_h|_{K'}$ to $K \cap K'$ coincide for any adjacent pair K, K' . We note that the sum over edges is zero since the normals from adjacent elements are equal and opposite in a conforming triangulation and the integral over boundary facets is zero since $\varphi \in C_c^1(\Omega_h)$ is zero here. Thus, we see that ξ is the weak derivative of η_h .

Second, let $\eta_h \in W^{1,p}(\Omega_h)$ then it is clear that $\eta_h \in L^p(\Omega_h)$, $\eta_h|_K \in W^{1,p}(K)$ and by the trace theorem η_h has common trace between adjacent elements. \square

Remark 4.21. The proof is based on ideas from Ciarlet (1978, Thm. 2.1.1) which showed that appropriate finite element spaces defined in that work are contained in $H^1(\Omega_h)$ (in our notation).

Bulk finite element space. We restrict to Lagrangian finite elements over a polygonal reference finite element. More precisely, we assume that the degrees of freedom for each element (K, P, Σ) are given by

$$\Sigma = \{\chi \mapsto \chi(a) : a \in \mathcal{N}^K\},$$

where \mathcal{N}^K is a finite set of nodes in K . We call \mathcal{N}^K the set of *Lagrange nodes* of K .

The set of degrees of freedom of adjacent bulk finite elements will be related as follows. Let (K, P, Σ) and (K', P', Σ') be two bulk finite elements such that K and K' are adjacent with $\Sigma = \{\chi \mapsto \chi(a), a \in \mathcal{N}^K\}$ and $\Sigma' = \{\chi \mapsto \chi(a'), a' \in \mathcal{N}^{K'}\}$. Then, we have

$$(4.19) \quad \left(\bigcup_{a \in \mathcal{N}^K} a \right) \cap K' = \left(\bigcup_{a' \in \mathcal{N}^{K'}} a' \right) \cap K.$$

We denote the *global set of Lagrange nodes* by

$$(4.20) \quad \mathcal{N}_h = \bigcup_{K \in \mathcal{T}_h} \mathcal{N}^K.$$

For each $a \in \mathcal{N}_h$, let $\mathcal{T}(a) \subset \mathcal{T}_h$ be the local neighbourhood of elements for which $a \in \mathcal{N}^K$.

Definition 4.22 (Bulk finite element space). (a) Let Ω_h be a discrete bulk domain equipped with a conforming subdivision \mathcal{T}_h with each domain K equipped with a bulk finite element (K, P^K, Σ^K) (Def. 4.4) which satisfy (4.19). A *bulk finite element space* is a (generally proper) subset of the product space $\prod_{K \in \mathcal{T}_h} P^K$ given by

$$\mathcal{S}_h := \left\{ \chi_h = (\chi_K)_{K \in \mathcal{T}_h} \in \prod_{K \in \mathcal{T}_h} P^K : \right. \\ \left. \chi_K(a) = \chi_{K'}(a), \text{ for all } K, K' \in \mathcal{T}(a), \text{ for all } a \in \mathcal{N}_h \right\}.$$

(b) The bulk finite element space is determined by the *global degrees of freedom*

$$\Sigma_h = \{\chi_h \mapsto \chi_h(a) : a \in \mathcal{N}_h\}.$$

In this definition, an element $\chi_h \in \mathcal{S}_h$ is not, in general a “function” defined over $\bar{\Omega}_h$, since we do not necessarily have a good definition of χ_h over element boundaries: The “function” may be double-valued.

If it happens, however, that for each element $\chi_h \in \mathcal{S}_h$, the restrictions χ_K and $\chi_{K'}$ coincide along the common face of any adjacent elements K and K' , then the function χ_h can be identified with a function defined over the set $\bar{\Gamma}_h$. In this case, we call the elements $\chi_h \in \mathcal{S}_h$ *bulk finite element functions*. Examples of bulk finite element functions are shown in Fig. 4.2.

We enumerate the nodes so that $\mathcal{N}_h = \{a_i\}_{i=1}^N$ and take $\{\chi_i\}_{i=1}^N$ to be the basis of \mathcal{S}_h dual to Σ_h . Since, we have a finite basis of \mathcal{S}_h we note that we can identify any $\chi_h \in \mathcal{S}_h$ with a vector $\gamma \in \mathbb{R}^N$ so that

$$\chi_h(x) = \sum_{i=1}^N \gamma_i \chi_i(x) \quad \text{for } x \in \Omega_h.$$

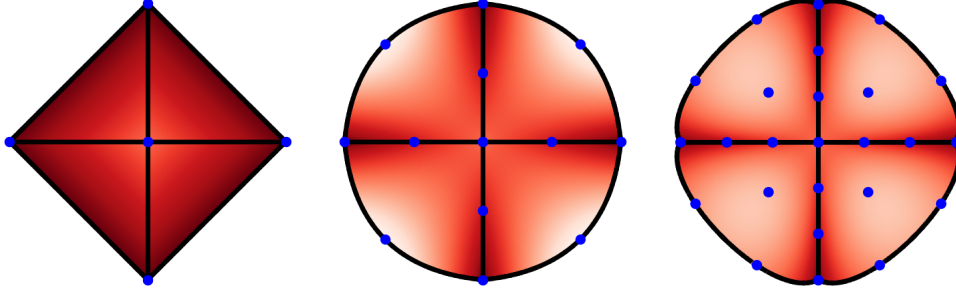


FIGURE 4.2. Examples of finite element functions. Left shows a piecewise linear function over a collection of standard finite elements (c.f. Ex. 4.7(a)), centre and right shows a piecewise quadratic and cubic function over a collection of isoparametric (quadratic, respectively cubic) finite elements (c.f. Ex. 4.7(b)). The functions shown are interpolations into the appropriate finite element spaces of the function $x \mapsto |x| \cos(4 \arctan(x_2/x_1))$. The distribution of Lagrange points is shown in blue

Lemma 4.23. *Let \mathcal{S}_h be a bulk finite element space consisting of bulk finite elements over a conforming subdivision \mathcal{T}_h of Ω_h . Assume further that for each $K \in \mathcal{T}_h$, the corresponding reference finite element is a Lagrange element of order $k \geq 1$ (Ex. 4.2). Then we can identify elements of \mathcal{S}_h as functions in $C(\Omega_h)$. Furthermore \mathcal{S}_h is a closed subspace in $H_T^1(\mathcal{T}_h)$.*

Proof. Consider two adjacent elements $K, K' \in \mathcal{T}_h$ and $\chi_h \in \mathcal{S}_h$. The functions $\chi_K \circ F_K$ and $\chi_{K'} \circ F_{K'}$ when restricted to the appropriate edges in \hat{K} are polynomials of degree k which agree at the Lagrange points on this edge from (6.20) and the definition of \mathcal{S}_h . The Lagrange points in the reference element determine polynomials of degree k so we have that $\chi_K = \chi_{K'}$ on $K \cap K'$. Since \mathcal{T}_h is a conforming subdivision we can define a global function $\chi_h: \bar{\Omega}_h \rightarrow \mathbb{R}$ such that $\chi_h|_K = \chi_K$ for each $K \in \mathcal{T}_h$ which is globally continuous. Indeed χ_h restricted to each element is continuous, as the composition of a polynomial (element of $\hat{P} = P_k(\hat{K})$) and a smooth surface finite element reference map F_K , and is single valued on the facets where any two elements meet.

In fact the restriction $\chi_h|_K$ to each element $K \in \mathcal{T}_h$ is a C^1 -function hence $\chi_h|_K \in H^1(K)$ so it is clear that $\mathcal{S}_h \subset H_T^1(\mathcal{T}_h)$. The space \mathcal{S}_h is closed since it is finite dimensional. \square

Remark 4.24. The proof is based on ideas from Ciarlet (1978, Thm. 2.2.3) which show that appropriate finite element spaces defined in that work are contained in $C^0(\bar{\Omega}_h) \cap H^1(\Omega_h)$ (in our notation).

The approximation property of the finite element space will be defined through an interpolation operator:

Definition 4.25 (Interpolation). If η is a function on Ω_h for which all $\sigma_i(\eta)$, $1 \leq i \leq N$, is well defined (in case of Lagrangian finite elements, $\eta \in C(\Omega_h)$ suffices), then we can define a *global interpolant* $I_h \eta$ by

$$I_h \eta := \sum_{i=1}^N \sigma_i(\eta) \chi_i.$$

Note that our construction implies that

$$(I_h \eta)|_K = I_K \eta|_K \text{ for all } K \in \mathcal{T}_h,$$

and $I_h \chi_h = \chi_h$ for all $\chi_h \in \mathcal{S}_h$.

In order to prove estimates on the global interpolant, we will first define three further properties of our subdivision \mathcal{T}_h .

Definition 4.26 (Regular and quasi-uniform subdivisions). For $h \in (0, h_0)$, let Ω_h be a triangulated bulk domain (Def. 4.14(a)) equipped with a conforming subdivision \mathcal{T}_h (Def. 4.14(d)).

- (a) [Def. 3.1, Bernardi 1989] The family is said to be non-degenerate or *regular* if there exists $\rho_{\text{reg}} > 0$ such that for all $K \in \mathcal{T}_h$ and all $h \in (0, h_0)$,

$$\rho_K \geq \rho_{\text{reg}} h_K,$$

and there exists a constant $C > 0$ such that

$$\sup_{h \in (0, h_0)} \max_{K \in \mathcal{T}_h} C_K \leq C < 1.$$

- (b) [Def. 3.2, Bernardi 1989] The family is said to be Θ -*regular* if it is regular, if for all $h \in (0, h_0)$ and all $K \in \mathcal{T}_h$, $F_K \in C^{\Theta+1}(K; \mathbb{R}^{n+1})$, and if, there exists a constant $C > 0$ such that

$$\sup_{h \in (0, h_0)} \max_{K \in \mathcal{T}_h} C_m(K) \leq C < +\infty \quad \text{for } 2 \leq m \leq \Theta + 1.$$

- (c) A regular family is said to be *quasi-uniform* if there exists $\rho > 0$ such that

$$\min\{\rho_K : K \in \mathcal{T}_h\} \geq \rho h \quad \text{for all } h \in (0, h_0).$$

Remark 4.27. We note that:

- for a regular subdivision there exists a constant $c > 0$ depending on the global quantities $\hat{\rho}$, \hat{h} and ρ_{reg}

$$\|A_K\| \leq ch_K \leq ch \quad \text{and} \quad \|A_K^{-1}\| \leq ch_K^{-1},$$

- for a quasi-uniform subdivision there exists a constant $c > 0$ depending on the global quantities $\hat{\rho}$, \hat{h} and ρ

$$\|A_K\| \leq ch \quad \text{and} \quad \|A_K^{-1}\| \leq ch^{-1}.$$

Theorem 4.28 (Global interpolation estimates, c.f. Cor. 4.1, Bernardi 1989). For $h \in (0, h_0)$, let Ω_h be a triangulated bulk domain (Def. 4.14(a)) equipped with a Θ -regular (Def. 4.26(b)), quasi-uniform (Def. 4.26(c)), conforming (Def. 4.14(d)) subdivision \mathcal{T}_h . Let each $K \in \mathcal{T}_h$ be equipped with a Θ -bulk finite element $(K, \mathcal{P}^K, \Sigma^K)$ (Def. 6.4) parametrised over a reference finite element $(\hat{K}, \hat{\mathcal{P}}, \hat{\Sigma})$ which satisfies the assumptions of Lem. 4.3 for some $0 < k, m \leq \Theta$, $p, q \in [1, \infty]$. Then there exists a constant $C = C(\hat{K}, \hat{\mathcal{P}}, \hat{\Sigma}, \rho)$ such that for all functions $\eta \in W^{k+1, p}(\mathcal{T}_h) \cap C^0(\Omega_h)$,

$$(4.21) \quad \|\eta - I_h \eta\|_{W^{m, q}(\mathcal{T}_h)} \leq Ch^{k+1-m} \|\eta\|_{W^{k+1, p}(\mathcal{T}_h)}.$$

Proof. The proof follows by piecing together Thm. 4.13 using the fact that \mathcal{T}_h is quasi-uniform. \square

Remark 4.29. The approximation property shown in (Bernardi, 1989, Cor. 4.1) is a result for an L^2 projection for a more general class of finite element spaces.

4.4. Evolving bulk finite elements. Let $t \in [0, T]$ denote time. We consider families of bulk finite elements, spaces and triangulated domains parametrised by t .

Definition 4.30 (Evolving bulk finite element). (a) Let $(K(t), P(t), \Sigma(t))_{t \in [0, T]}$ be a time dependent family of bulk finite elements (Def. 4.4) parametrised over a common reference element $(\hat{K}, \hat{P}, \hat{\Sigma})$. If the constant $C_K = \sup_t C_{K(t)}$ is uniformly bounded away from 1,

$$C_K := \max_{t \in [0, T]} \sup_{\hat{x} \in \hat{K}} \|\nabla D_K(\hat{x}, t) A_K^{-1}(t)\| < c < 1,$$

we say that $(K(t), P(t), \Sigma(t))_{t \in [0, T]}$ is an *evolving bulk finite element*.

(b) Let $\Phi_{(\cdot)}^K \in C^2([0, T], C^1(K_0))$ where $K_0 := K(0)$. We say that if $\Phi_t^K : K_0 := K(0) \rightarrow K(t)$ is such that

$$(4.22) \quad F_{K(t)}(\hat{x}) = \Phi_t^K(F_{K_0}(\hat{x})) \quad \text{for } \hat{x} \in \hat{K}$$

then Φ_t^K is the *flow* defining the evolution of the element domain and that $F_{K(t)}$ is the *evolving bulk element reference map*.

(c) The *element velocity* W_K of $K(t)$ is defined by

$$W_K(\Phi_t^K(x), t) = \frac{d}{dt} \Phi_t^K(x) \quad \text{for } x \in K_0, t \in [0, T].$$

(d) If each $(K(t), P(t), \Sigma(t))$ is a Θ -bulk finite element for each $t \in [0, T]$ and the constants $C_m(K(t))$ are uniformly bounded:

$$\sup_{t \in [0, T]} C_m(K(t)) \leq c < \infty \quad \text{for } 2 \leq m \leq \Theta + 1$$

then we say that $(K(t), P(t), \Sigma(t))_{t \in [0, T]}$ is an *evolving Θ -bulk finite element* and $F_{K(t)}$ is an *evolving Θ -bulk element reference map*.

(e) We say that an evolving bulk finite element is *temporally quasi-uniform*, if there exists $\rho_K > 0$ such that

$$\inf\{\rho_{K(t)} : t \in [0, T]\} \geq \rho_K \sup\{h_{K(t)} : t \in [0, T]\}.$$

(f) The family of *element push forward maps* denoted by $\phi_t^K(\chi) : K(t) \rightarrow \mathbb{R}$ for $\chi : K_0 \rightarrow \mathbb{R}$, indexed by $t \in [0, T]$, is defined to be the linear bijections defined by:

$$\phi_t^K(\chi)(x) = \chi(\Phi_{-t}^K(x)) \quad \text{for } x \in K(t).$$

Lemma 4.31. *Let $F_{K(t)} : \hat{K} \rightarrow K(t)$, for $t \in [0, T]$ be an evolving Θ -bulk finite element reference map (Def. 4.30(d)) for a temporally quasi-uniform element domain $K(t)$ (Def. 4.30(e)) and ϕ_t^K the family of element push forward maps (Def. 4.30(f)). Then there exists constants $c_1, c_2 > 0$, which depend only on the reference element $(\hat{K}, \hat{P}, \hat{\Sigma})$ and the constants C_K and ρ_K , such that for all $t \in [0, T]$, $\chi \in W^{m,p}(K_0)$ if and only if $\phi_t^K \chi \in W^{m,p}(K(t))$ and*

$$(4.23) \quad c_1 \|\chi\|_{W^{m,p}(K_0)} \leq \|\phi_t^K \chi\|_{W^{m,p}(K(t))} \leq c_2 \|\chi\|_{W^{m,p}(K_0)} \quad \text{for all } \chi \in W^{m,p}(K_0).$$

Proof. From Lem. 4.12 and (4.9), we have

$$\|\chi\|_{W^{m,p}(K_0)} \leq c \left(\frac{\text{meas}(K(t))}{\text{meas}(K_0)} \right)^{1/p} \|\phi_t^K \chi\|_{W^{m,p}(K(t))} \sum_{r=1}^m \left(\frac{h_{K(t)}}{\rho_{K_0}} \right)^r$$

and

$$|\phi_t^K \mathcal{X}|_{W^{m,p}(K(t))} \leq c \left(\frac{\text{meas}(K_0)}{\text{meas}(K(t))} \right)^{1/p} \|\mathcal{X}\|_{W^{m,p}(K_0)} \sum_{r=1}^m \left(\frac{h_{K_0}}{\rho_{K(t)}} \right)^r.$$

It can be easily seen that for a quasi-uniform evolving surface finite element that these constants only depend on allowed quantities. \square

This result implies that $(W^{m,p}(K(t)), \phi_t^K|_{W^{m,p}(K_0)})_{t \in [0,T]}$ is a compatible pair (Def. 2.2). Furthermore $(P(t), \phi_t^K|_{P(0)})_{t \in [0,T]}$, equipped with the $W^{m,p}(K(t))$ norm is also a compatible pair since $P(t)$ is a closed subspace of $W^{m,p}(K(t))$ (Rem. 2.3 and 4.6).

4.5. Evolving bulk triangulations and spaces. We now derive definitions of an evolving bulk finite element space which is part of a compatible pair (in the sense of Sec. 2, Def. 2.2). For each $h \in (0, h_0)$, we are given a family of discrete bulk domains $\{\Omega_h(t)\}_{t \in [0,T]}$ and each equipped with a bulk finite element space $\{\mathcal{S}_h(t)\}_{t \in [0,T]}$. Furthermore, we are interested in under what assumptions does the compatibility hold independently of the element diameter h .

Definition 4.32 (Evolving bulk domain). For $t \in [0, T]$, let $\Omega_h(t)$ be a family of triangulated bulk domains (Def. 4.14(a)) each equipped with a conforming subdivision $\mathcal{T}_h(t)$ (Def. 4.14(d)) such that each element domain $K(t) \in \mathcal{T}_h(t)$ is equipped with an element flow map $\Phi_{(\cdot)}^K \in C^2([0, T]; C^1(K_0))$ (Def. 4.30(b)).

- (a) We call $\{\mathcal{T}_h(t)\}_{t \in [0,T]}$ an *evolving conforming subdivision* if for each element $K(0) \in \mathcal{T}_h(0)$ and each facet $E(0)$ of $K(0)$ either $E(0)$ is a facet of another element $K'(0) \in \mathcal{T}_h(0)$, in which case $E(t)$ is a common facet between $K(t)$ and $K'(t)$ for all $t \in [0, T]$ or $E(0)$ is a portion of the boundary $\partial\Omega(0)$, in which case $E(t)$ is a portion of the boundary $\partial\Omega(t)$ for all $t \in [0, T]$.
- (b) An *evolving triangulated (bulk) domain* is defined to be a family of triangulated bulk domains $\{\Omega_h(t)\}_{t \in [0,T]}$ equipped with an evolving conforming subdivision. In this case, we define the mesh parameter h to be

$$(4.24) \quad h := \sup_{t \in [0,T]} \max_{K(t) \in \mathcal{T}_h(t)} h_{K(t)}.$$

- (c) We define a *global discrete flow* $\Phi_{(\cdot)}^h(\cdot): [0, T] \times \Omega_{h,0} \rightarrow \mathbb{R}^{n+1}$ element-wise by

$$\Phi_t^h|_{K_0} := \Phi_t^K \quad \text{for } K_0 \in \mathcal{T}_h(0).$$

Our assumptions imply that Φ_t^h is piecewise smooth and $\Phi_t^h: \Omega_{h,0} \rightarrow \Omega_h(t)$.

- (d) We define a *global discrete velocity* W_h given by

$$W_h|_{K(t)} = W_K.$$

- (e) The family of linear bijections induced by the flow Φ_t^h and called the *global push forward map* is denoted by $\phi_t^h(\eta_h): \Omega_h(t) \rightarrow \mathbb{R}$ for $\eta_h: \Omega_{h,0} \rightarrow \mathbb{R}$ and defined by

$$(\phi_t^h \eta_h)|_{K(t)} := \phi_t^K(\eta_h|_{K_0}) \quad \text{for all } K(t) \in \mathcal{T}_h(t).$$

In order to bring together a collection of elements, we again restrict to Lagrangian finite elements over a polygonal reference finite element. We note that our construction implies that for each element $K(t)$ each node $a(t) \in \mathcal{N}^{K(t)}$ is the trajectory of a point $a_0 \in \mathcal{N}^{K(0)}$ under the flow Φ_t^K - that is $a(t) = \Phi_t^K(a_0)$.

We make the following extra requirement on how adjacent elements will be related. For each $t \in [0, T]$, we denote by $\mathcal{N}_h(t)$ the global set of Lagrange nodes of $\Omega_h(t)$ (4.20) and

for any $a \in \mathcal{N}_h(t)$, $\mathcal{T}(a)$ is the set of elements $K(t)$ such that a is a node of $K(t)$. We make the restriction that the global flow is single-valued at each Lagrange point: for all $a_0 \in \mathcal{N}_h(0)$ we have

$$(4.25) \quad \Phi_t^K(a_0) = \Phi_t^{K'}(a_0) \quad \text{for all } K, K' \in \mathcal{T}(a_0).$$

Remark 4.33. We note that our construction does not imply that the global flow map is indeed a function: Its restrictions to a facet from adjacent elements may not coincide. The assumption (4.25) imposes that the global flow map should coincide at Lagrange points along element boundaries.

Definition 4.34 (Evolving bulk finite element space). (a) Let $\{\Omega_h(t)\}_{t \in [0, T]}$ be an evolving triangulated bulk domain (Def. 4.32(b)) equipped with an evolving conforming subdivision $\{\mathcal{T}_h(t)\}_{t \in [0, T]}$ (Def. 4.32(a)). For $t \in [0, T]$, let $\mathcal{S}_h(t)$ be a bulk finite element space (Def. 4.22(a)) over $\Omega_h(t)$. If each $K(t) \in \mathcal{T}_h(t)$ is equipped with an evolving bulk finite element $(K(t), P(t), \Sigma(t))_{t \in [0, T]}$ (Def. 4.30(a)) which together satisfy (4.25) then we say $\{\mathcal{S}_h(t)\}_{t \in [0, T]}$ is an *evolving bulk finite element space*. (b) For each $t \in [0, T]$, we will write $\Sigma_h(t)$ for the set of global nodal variables (Def. 4.22(b)). We will use the convention that

$$\Sigma_h(t) = \{\chi_h \mapsto \chi_h(a_i(t)) : 1 \leq i \leq N\},$$

where $a_i(t)$ is the trajectory of a Lagrange point under the global flow Φ_t^h . We will denote by $\{\chi_i(\cdot, t) : 1 \leq i \leq N\}$ the global basis of finite element functions such that $\chi_i(a_j(t), t) = \delta_{ij}$ for $t \in [0, T]$ and all $i, j = 1, \dots, N$. This implies that $\chi_i(\cdot, t) = \phi_t^h(\chi_i(\cdot, 0))$.

Definition 4.35 (Uniformly regular and uniformly quasi-uniform evolving subdivisions). For $h \in (0, h_0)$, let $\{\mathcal{T}_h(t)\}_{t \in [0, T]}$ be a family of evolving conforming subdivisions (Def. 4.32(a)).

(a) We say that the family is *uniformly regular* if there exists $\rho > 0$ such that for all $h \in (0, h_0)$ and all times $t \in [0, T]$, we have

$$\rho_{K(t)} \geq \rho h_{K(t)} \quad \text{for all } K(t) \in \mathcal{T}_h(t),$$

and there exists $C > 0$ such that

$$\sup_{h \in (0, h_0)} \sup_{t \in [0, T]} \max_{K(t) \in \mathcal{T}_h(t)} C_{K(t)} \leq C < 1.$$

(b) We say that the family is *uniformly Θ -regular* if it is uniformly regular, if for each time $t \in [0, T]$, the family $\{\mathcal{T}_h(t)\}_{h \in (0, h_0)}$ is Θ -regular and if there exists a constant such that

$$\sup_{h \in (0, h_0)} \sup_{t \in [0, T]} \max_{K(t) \in \mathcal{T}_h(t)} C_m(K(t)) \leq C \leq +\infty \quad \text{for } 2 \leq m \leq \Theta + 1.$$

(c) We say that the family is *uniformly quasi-uniform* if there exists $\rho > 0$ such that for all $h \in (0, h_0)$ and all times $t \in [0, T]$, we have

$$\min\{\rho_{K(t)} : K(t) \in \mathcal{T}_h(t)\} \geq \rho h.$$

Note that a uniformly quasi-uniform subdivision consists of element domains for temporally quasi-uniform evolving bulk finite elements.

Lemma 4.36. For $h \in (0, h_0)$, let $\{\mathcal{T}_h(t)\}_{t \in [0, T]}$ be a uniformly Θ -regular (Def. 4.35(b)), uniformly quasi-uniform (Def. 4.35(c)), evolving, conforming subdivision (Def. 4.32(a)) and let ϕ_t^h be the global push-forward map (Def. 4.32(e)). Let $0 \leq k \leq \Theta + 1$, $p \in [0, \infty]$.

Then, $\eta_h \in W^{m,p}(\mathcal{T}_h(0))$ if and only if $\phi_t^h \eta_h \in W^{m,p}(\mathcal{T}_h(t))$ for all $t \in [0, T]$. Furthermore, there exists $c_1, c_2 > 0$ independent of $h \in (0, h_0)$ and $t \in [0, T]$ such that for all $\eta_h^\ell \in \mathcal{S}_h(t)$

$$(4.26) \quad c_1 \|\eta_h\|_{W^{m,p}(\mathcal{T}_h(0))} \leq \left\| \phi_t^h \eta_h \right\|_{W^{m,p}(\mathcal{T}_h(t))} \leq c_2 \|\eta_h\|_{W^{m,p}(\mathcal{T}_h(0))}.$$

Proof. We simply sum the element-wise result from [Lem. 4.31](#). The constants are independent of h_K and ρ_K due to the uniform quasi-uniformity of $\{\mathcal{T}_h(t)\}$. \square

Remark 4.37. In particular, the pair $(W^{m,p}(\Omega_h(t)), \phi_t^h|_{W^{m,p}(\Omega_h(t))})_{t \in [0, T]}$ is compatible with respect to the broken Sobolev norm $\|\cdot\|_{W^{m,p}(\mathcal{T}_h(t))}$ ([Def. 4.16](#)). Furthermore, the pairs $(\mathcal{S}_h(t), \phi_t^h|_{\mathcal{S}_h(t)})_{t \in [0, T]}$, equipped with the $W^{m,p}(\mathcal{T}_h(t))$ norm, and $(W_T^{1,p}(\mathcal{T}_h(t)), \phi_t^h|_{W_T^{1,p}(\mathcal{T}_h(t))})_{t \in [0, T]}$ are also both compatible ([Rem. 2.3](#) and [Lem. 4.19](#) and [4.23](#)). Note that this result implies that the spaces $L_{\mathcal{S}_h}^2$ and $C_{\mathcal{S}_h}^1$ are well defined when equipped with the appropriate norms (c.f. [\(2.1\)](#) and [\(2.2\)](#)).

5. LIFTED BULK FINITE ELEMENT SPACES

This section sets out a procedure for relating functions on the discrete bulk domain Ω_h to the smooth domain Ω via the construction of $\mathcal{S}_h^\ell(t)$ from the space $\mathcal{S}_h(t)$ defined in the previous section. We start by defining a lifted bulk finite element $(K^\ell, P^\ell, \Sigma^\ell)$ in Ω using a mapping $\Lambda_K: K \rightarrow K^\ell \subset \Omega$. This process is called *lifting*. In the following we will provide the appropriate assumptions on Λ_K to allow us to relate structures on Ω_h to their lifted counterparts on Ω .

5.1. Lifted bulk finite element. Consider a single bulk finite element (K, P, Σ) ([Def. 4.4](#)), with element reference map $F_K: \hat{K} \rightarrow K$, where the element domain approximates a portion of a domain Ω with smooth boundary in \mathbb{R}^{n+1} . Let $\Lambda_K: K \rightarrow \Omega$ be a C^1 -map which is a diffeomorphism onto its image. We define $K^\ell := \Lambda_K(K) \subset \Omega$. For a function $\chi: K \rightarrow \mathbb{R}$, we call $\chi^\ell: K^\ell \rightarrow \mathbb{R}$ the *lift* of χ which is given by

$$\chi^\ell(\Lambda_K(x)) = \chi(x) \quad \text{for } x \in K.$$

We assume that we can decompose Λ_K into

$$\Lambda_K(x) = A_\Lambda x + b_\Lambda + \tilde{\Lambda}_K(x) \quad \text{for } x \in K,$$

where A_Λ is an invertible $(n+1) \times (n+1)$ matrix, $b_\Lambda \in \mathbb{R}^{n+1}$ and $\tilde{\Lambda}_K \in C^1(K, \mathbb{R}^{n+1})$. We will assume that $\tilde{\Lambda}_K$ does not affect the affine part of the parametrisation: $\tilde{\Lambda}_K(a) = 0$ for each vertex $a \in K$.

Definition 5.1 (Lifted bulk finite element). We call the triple $(K^\ell, P^\ell, \Sigma^\ell)$ defined by

$$\begin{aligned} K^\ell &:= \Lambda_K(K) \subset \Omega \\ P^\ell &:= \{\chi^\ell(\Lambda_K(\cdot)) := \chi(\cdot) : \chi \in P\} \\ \Sigma^\ell &:= \{\sigma^\ell := \chi^\ell \mapsto \sigma(\chi) : \sigma \in \Sigma\}, \end{aligned}$$

the *lift* of (K, P, Σ) and Λ_K the *lifting map*. If $(K^\ell, P^\ell, \Sigma^\ell)$ forms a bulk finite element over $(\hat{K}, \hat{P}, \hat{\Sigma})$ then we say that $(K^\ell, P^\ell, \Sigma^\ell)$ is the *lifted bulk finite element associated with* (K, P, Σ) . In this case, we call $F_{K^\ell}(\cdot) := \Lambda_K(F_K(\cdot))$ the lifted bulk finite element reference map.

The next two results show under what assumptions on Λ_K is $(K^\ell, P^\ell, \Sigma^\ell)$ a bulk finite element ([Def. 4.4](#)) or a Θ -bulk finite element ([Def. 4.5](#)).

Lemma 5.2. *If Λ_K satisfies that*

$$(5.1) \quad \sup_{x \in K} \left\| \nabla_K \tilde{\Lambda}(x) \right\| \leq \frac{\|A_\Lambda^{-1}\|^{-1} - C_K \|A_\Lambda\|}{1 + C_K},$$

then $(K^\ell, P^\ell, \Sigma^\ell)$ is a bulk finite element. Furthermore, for $p \in [1, \infty]$, we have that there exists $c_1, c_2 > 0$ such that

$$(5.2a) \quad c_1 \|\chi\|_{L^p(K)} \leq \left\| \chi^\ell \right\|_{L^p(K^\ell)} \leq c_2 \|\chi\|_{L^p(K)} \quad \text{for all } \chi \in L^p(K)$$

$$(5.2b) \quad c_1 \|\chi\|_{W^{1,p}(K)} \leq \left\| \chi^\ell \right\|_{W^{1,p}(K^\ell)} \leq c_2 \|\chi\|_{W^{1,p}(K)} \quad \text{for all } \chi \in W^{1,p}(K),$$

where the constants c_1, c_2 depend on $C_K, \|A_\Lambda^{-1}\|$ and the ratio h_K/ρ_K .

Proof. To show that $(K^\ell, P^\ell, \Sigma^\ell)$ is a bulk finite element (Def. 4.4), the conditions on the element reference map $F_{K^\ell}(\hat{x}) = \Lambda_K(F_K(\hat{x}))$ are clear and we are left to check the curvedness condition (4.2). Using the expansion of Λ_K , we see

$$A_{K^\ell} = A_\Lambda A_K, \quad A_{K^\ell}^{-1} = A_K^{-1} A_\Lambda^{-1}, \quad b_{K^\ell} = A_\Lambda b_K + b_\Lambda$$

and $D_{K^\ell}(\hat{x}) = A_\Lambda D_K(\hat{x}) + \tilde{\Lambda}_K(F_K(\hat{x})).$

So that

$$\nabla D_{K^\ell}(\hat{x}) A_{K^\ell}^{-1} = A_\Lambda \nabla D_K(\hat{x}) A_K^{-1} A_\Lambda^{-1} + \nabla_K \tilde{\Lambda}_K(F_K(\hat{x})) (\text{Id} + \nabla D_K(\hat{x}) A_K^{-1}) A_\Lambda^{-1}.$$

Applying the curvedness condition for K we see

$$\left\| \nabla D_{K^\ell}(\hat{x}) A_{K^\ell}^{-1} \right\| \leq C_K \|A_\Lambda\| \|A_\Lambda^{-1}\| + (1 + C_K) \left\| \nabla_K \tilde{\Lambda}_K(F_K(\hat{x})) \right\| \|A_\Lambda^{-1}\|.$$

The curvedness condition is shown by applying (5.1).

To show (5.2a) the result is clear for $p = \infty$. For $p < \infty$, we will apply Lem. 6.12. Then we see

$$c \left(\frac{\text{meas}(K)}{\text{meas}(K^\ell)} \right)^{1/p} \|\chi\|_{L^p(K)} \leq \left\| \chi^\ell \right\|_{L^p(K^\ell)} \leq c \left(\frac{\text{meas}(K^\ell)}{\text{meas}(K)} \right)^{1/p} \|\chi\|_{L^p(K)},$$

where c depends on C_K and the bound (5.1). For the $W^{1,p}$ bound (5.2b), we note that

$$\|A_K\| = \|A_\Lambda^{-1} A_\Lambda A_K\| \leq \|A_\Lambda^{-1}\| \|A_\Lambda A_K\| = \|A_\Lambda^{-1}\| \|A_{K^\ell}\|,$$

so that we infer

$$(5.3) \quad \|A_{K^\ell}\| \geq \frac{\|A_K\|}{\|A_\Lambda^{-1}\|}.$$

Then applying Lem. 4.12 once more we see

$$\begin{aligned} c \left(\frac{\text{meas}(K)}{\text{meas}(K^\ell)} \right)^{1/p} \frac{\|A_\Lambda^{-1}\|}{\|A_K\| \|A_K^{-1}\|} |\chi|_{W^{1,p}(K)} &\leq \left\| \chi^\ell \right\|_{W^{1,p}(K^\ell)} \\ &\leq c \left(\frac{\text{meas}(K^\ell)}{\text{meas}(K)} \right)^{1/p} \|A_\Lambda^{-1}\| \|A_K\| \|A_K^{-1}\| |\chi|_{W^{1,p}(K)}. \end{aligned}$$

The final result is given by applying (4.9a) and (4.9b). \square

Lemma 5.3. *If (K, P, Σ) is a Θ -bulk finite element and Λ_K satisfies $\Lambda_K \in C^{\Theta+1}(K; \mathbb{R}^n)$ and $\|\Lambda_K\|_{W^{\Theta+1, \infty}(K)} \leq c$, then $(K^\ell, P^\ell, \Sigma^\ell)$ is also a Θ -bulk finite element. Furthermore, for $0 \leq m \leq \Theta + 1$ and $p \in [1, \infty]$, we have that there exists $c_1, c_2 > 0$ such that*

$$c_1 \|\chi\|_{W^{m,p}(K)} \leq \|\chi^\ell\|_{W^{m,p}(K^\ell)} \leq c_2 \|\chi\|_{W^{m,p}(K)} \quad \text{for all } \chi \in W^{m,p}(K),$$

where the constants c_1, c_2 depend on $C_1(K), \dots, C_m(K)$, $\|A_\Lambda^{-1}\|$ and the ratio h_K/ρ_K .

Proof. To see that $(K^\ell, P^\ell, \Sigma^\ell)$ is a Θ -bulk finite element (Def. 4.5), the first three conditions are clear from the smoothness assumption on Λ_K . We must show (4.4) holds: for $2 \leq m \leq \Theta + 1$, there exists a constant $C_m(K^\ell)$ such that

$$\|\nabla^m F_{K^\ell}(\hat{x})\| \leq C_m(K^\ell) \|A_{K^\ell}\|^m.$$

Computing directly using (Bernardi, 1989, Eq. (2.9)), we have

$$\nabla^m F_{K^\ell}(\hat{x}) = \sum_{r=1}^m (\nabla^r \Lambda_K)(F_K(\hat{x})) \left(\sum_{i \in E(m,r)} c_i \prod_{q=1}^m (\nabla^q F_K(\hat{x}))^{i_q} \right)$$

where c_i are constants and

$$E(m, r) = \left\{ i \in \mathbb{N}^m; \sum_{q=1}^m i_q = r \text{ and } \sum_{q=1}^m q i_q = m \right\}.$$

But applying the fact that (K, P, Σ) is a Θ -bulk finite element, the definition of $E(m, r)$, Lem. 4.12 and the smoothness assumption on Λ_K , we see that

$$|\nabla^m F_{K^\ell}(\hat{x})| \leq c(C_1(K), \dots, C_m(K)) \sum_{r=1}^m |\Lambda_K|_{W^{r, \infty}(K)} \|A_K\|^m.$$

Finally, applying (5.3), we have that

$$\|\nabla^m F_{K^\ell}(\hat{x})\| \leq c \|\Lambda_K\|_{W^{m, \infty}(K)} \|A_{K^\ell}\|^m \|A_\Lambda^{-1}\|^m.$$

This shows that $(K^\ell, P^\ell, \Sigma^\ell)$ is a Θ -surface finite element.

To show the norm equivalence we again apply Lem. 4.12, recognising the geometric progression, to see

$$\begin{aligned} c \left(\frac{\text{meas}(K)}{\text{meas}(K^\ell)} \right) \frac{A_1^{m+1} - 1}{A_1 - 1} \|\chi\|_{W^{m,p}(K)} &\leq \|\chi^\ell\|_{W^{m,p}(K^\ell)} \\ &\leq c \left(\frac{\text{meas}(K^\ell)}{\text{meas}(K)} \right) \frac{A_2^{m+1} - 1}{A_2 - 1} \|\chi\|_{W^{m,p}(K)}, \end{aligned}$$

where

$$A_1 = \|A_K\| \|A_K^\dagger\| \|A_\Lambda\| \quad \text{and} \quad A_2 = \|A_K\| \|A_K^\dagger\| \|A_\Lambda^{-1}\|.$$

The final result is given by applying (5.4c), (4.9a) and (4.9b). \square

Remark 5.4. Considering the case that Λ_K fixes the vertices of K then we can write Λ_K as

$$\Lambda_K(x) = x + \tilde{\Lambda}(x) \quad \text{for } x \in K.$$

That is that $A_\Lambda = \text{Id}$ and $b_\Lambda = 0$. Then the assumptions of Lem. 5.2 can be replaced by

$$\sup_{x \in K} \|\nabla_K \tilde{\Lambda}(x)\| \leq \frac{1 - C_K}{1 + C_K},$$

and the assumptions of Lem. 5.3 can be replaced by the assumption that $\|\Lambda_K\|_{W^{\Theta, \infty}(K)}$ is bounded.

We can also use Λ_K to define an inverse lift. Given an element domain K , lifted element domain K^ℓ and lifting map Λ_K . We know that Λ_K is invertible onto its image, namely K^ℓ . So for $\eta: K^\ell \rightarrow \mathbb{R}$, we denote its inverse lift by $\eta^{-\ell}: K \rightarrow \mathbb{R}$ defined by

$$\eta^{-\ell}(x) := \eta(\Lambda_K(x)) \quad \text{for } x \in K.$$

Lemma 5.5. *If the assumptions of Lem. 5.2 and 5.3 hold then, for $0 \leq m \leq \Theta$ and $p \in [1, \infty]$, we have that there exists $c_1, c_2 > 0$ such that for all $\eta \in C(K^\ell) \cap W^{m,p}(K^\ell)$, we have*

$$c_1 \left\| \eta^{-\ell} \right\|_{W^{m,p}(K)} \leq \|\eta\|_{W^{m,p}(K^\ell)} \leq c_2 \left\| \eta^{-\ell} \right\|_{W^{m,p}(K)}.$$

Proof. The same proof can be applied to the case of the inverse lift as well as the lift. \square

We next relate the geometry of the base and lifted element domains.

Lemma 5.6. *Using the decomposition of Λ_K , we have*

$$(5.4a) \quad \left\| A_\Lambda^{-1} \right\|^{-1} h_K \leq h_{K^\ell} \leq \|A_\Lambda\| h_K$$

$$(5.4b) \quad \left\| A_\Lambda^{-1} \right\|^{-1} \rho_K \leq \rho_{K^\ell} \leq \|A_\Lambda\| \rho_K$$

(5.4c)

$$c_1 \left(\frac{\rho_K}{h_K} \right)^{n+1} \left\| A_\Lambda^{-1} \right\|^{-n+1} \text{meas}(K) \leq \text{meas}(K^\ell) \leq c_2 \left(\frac{h_K}{\rho_K} \right)^{n+1} \left\| A_\Lambda^{-1} \right\|^{-n+1} \text{meas}(K).$$

Proof. For (5.4a), we show the second inequality. The first follows by the same reasoning applied to the inverse of A_Λ . Since \tilde{K}^ℓ is compact, there exists $x^\ell, y^\ell \in \tilde{K}^\ell$ such that

$$h_{K^\ell} = \left| y^\ell - x^\ell \right|.$$

But since A_Λ is invertible, there exists $x, y \in \tilde{K}$ such that

$$A_\Lambda x + b_\Lambda = x^\ell \quad \text{and} \quad A_\Lambda y + b_\Lambda = y^\ell.$$

Then, we can compute that

$$h_{K^\ell} = \left| x^\ell - y^\ell \right| = \left| A_\Lambda(x - y) \right| \leq \|A_\Lambda\| |x - y| \leq \|A_\Lambda\| h_K.$$

Similarly, for (5.4b), we only show the first inequality. For each $\varepsilon > 0$, there exists B_ε a ball in \tilde{K} such that

$$\rho_K - \text{diam} B_\varepsilon \leq \varepsilon.$$

Denote by x_ε and r_ε the centre and radius of B_ε respectively. Consider the affine map $\Xi_\varepsilon: \mathbb{R}^{n+1} \rightarrow \mathbb{R}^{n+1}$ given by

$$\Xi_\varepsilon(x) = \frac{1}{\left\| A_\Lambda^{-1} \right\|} (x - x_\varepsilon) + b_\Lambda + A_\Lambda x_\varepsilon.$$

It is clear that Ξ_ε maps balls to balls and B_ε is mapped to a ball centred at $A_\Lambda x_\varepsilon + b_\Lambda$ with radius $r_\varepsilon / \left\| A_\Lambda^{-1} \right\|$. We claim $\Xi_\varepsilon(B_\varepsilon)$ is contained in \tilde{K}^ℓ . Indeed, take $x^\ell \in \Xi_\varepsilon(B_\varepsilon)$, then there exists $x \in B_\varepsilon$ such that $\Xi_\varepsilon(x) = x^\ell$. Denote by

$$x' = x_\varepsilon + \frac{1}{\left\| A_\Lambda^{-1} \right\|} A_\Lambda^{-1} (x - x_\varepsilon),$$

then

$$\left| x' - x_\varepsilon \right| = \frac{1}{\left\| A_\Lambda^{-1} \right\|} \left| A_\Lambda^{-1} (x - x_\varepsilon) \right| \leq |x - x_\varepsilon| \leq r_\varepsilon,$$

so $x' \in B_\varepsilon \subset \tilde{K}$ and

$$A_\Lambda x' + b_\Lambda = \frac{1}{\|A_\Lambda^{-1}\|} (x - x_\varepsilon) + A_\Lambda x_\varepsilon + b_\Lambda = x^\ell,$$

so that $x^\ell \in \tilde{K}^\ell = A_\Lambda \tilde{K} + b_K$.

Therefore, we have found a ball $\Xi_\varepsilon(B_\varepsilon) \subset \tilde{K}^\ell$ with radius $r_\varepsilon / (\|A_\Lambda^{-1}\|)$, thus we can infer that

$$\rho_{K^\ell} \geq \frac{1}{2} \|A_\Lambda^{-1}\|^{-1} \text{diam} B_\varepsilon \geq \|A_\Lambda^{-1}\|^{-1} (\rho_K - \varepsilon).$$

Since the proof holds for all $\varepsilon > 0$, we see the desired result.

Given (5.4a) and (5.4b), the final result (5.4c) follows directly from Rem. 4.10. \square

5.2. Lifted bulk triangulations and spaces. Let Ω be a smooth bulk domain and for $h \in (0, h_0)$ and let Ω_h be a triangulated bulk domain (Def. 4.14(a)) equipped with a conforming subdivision \mathcal{T}_h (Def. 4.14(d)) and a bulk finite element space \mathcal{S}_h (Def. 4.22(a)). Let each $K \in \mathcal{T}_h$ be associated with a lifted finite element K^ℓ with lifted map Λ_K .

Definition 5.7. (a) We denote by \mathcal{T}_h^ℓ the set of all lifted element domains

$$\mathcal{T}_h^\ell := \{K^\ell : K \in \mathcal{T}_h\}.$$

If the global map Λ_h is single valued and \mathcal{T}_h^ℓ forms a conforming subdivision of $\tilde{\Omega}$, we say that \mathcal{T}_h^ℓ is an *exact* subdivision of the domain Ω .

- (b) We define a *global lifting map* $\Lambda_h: \Omega_h \rightarrow \tilde{\Omega}$ by $\Lambda_h|_K = \Lambda_K$. We define the inverse lift $\Lambda_h^{-1}: \tilde{\Omega} \rightarrow \Omega_h$ in a similar element-wise fashion by $\Lambda_h^{-1}|_{K^\ell} = \Lambda_K^{-1}$.
- (c) We denote by $\lambda_h(\eta_h): \tilde{\Omega} \rightarrow \mathbb{R}$, for $\eta_h: \Omega_h \rightarrow \mathbb{R}$, the *global lift* given by

$$\lambda_h(\eta_h)(\Lambda_h(x)) = \eta_h(x) \text{ for } x \in \Omega_h,$$

and by $\zeta_h(\eta): \Omega_h \rightarrow \mathbb{R}$, for $\eta: \tilde{\Omega} \rightarrow \mathbb{R}$, the *global inverse lift* given by

$$\zeta_h(\eta)(x) = \eta(\Lambda_h(x)) \text{ for } x \in \Omega_h.$$

We will also use the notations $\eta_h^\ell = \lambda_h(\eta_h)$ and $\eta^{-\ell} = \zeta_h(\eta)$.

- (d) Let \mathcal{S}_h be a bulk finite element space. If for each bulk finite element (K, P, Σ) there is an associated lifted bulk finite element $(K^\ell, P^\ell, \Sigma^\ell)$, then, we define a *lifted bulk finite element space* (c.f. (3.17)) by

$$\mathcal{S}_h^\ell := \{\chi_h^\ell : \chi_h \in \mathcal{S}_h\}.$$

Proposition 5.8. *Assume additionally that the family of triangulations $\{\mathcal{T}_h\}_{h \in (0, h_0)}$ is regular (Def. 4.26(a)), Λ_K satisfies the assumptions of Lem. 5.2 and there exists $C_1, C_2 > 0$ such that*

$$(5.5) \quad \|A_\Lambda\| \leq C_1 \quad \text{and} \quad \|A_\Lambda^{-1}\| \leq C_2 \quad \text{for all } K \in \mathcal{T}_h \text{ for all } h \in (0, h_0),$$

for all $K \in \mathcal{T}_h$ for all $h \in (0, h_0)$. Then $\{\mathcal{T}_h^\ell\}_{h \in (0, h_0)}$ is regular and \mathcal{S}_h^ℓ is a bulk finite element space and there exists constants $c_1, c_2 > 0$, which are independent of $h \in (0, h_0)$ such that

$$(5.6) \quad \begin{aligned} c_1 \|\eta_h\|_{L^p(\mathcal{T}_h)} &\leq \|\eta_h^\ell\|_{L^p(\mathcal{T}_h^\ell)} \leq c_2 \|\eta_h\|_{L^p(\mathcal{T}_h)} && \text{for all } \eta_h \in L^p(\mathcal{T}_h) \\ c_1 \|\eta_h\|_{W^{1,p}(\mathcal{T}_h)} &\leq \|\eta_h^\ell\|_{W^{1,p}(\mathcal{T}_h^\ell)} \leq c_2 \|\eta_h\|_{W^{1,p}(\mathcal{T}_h)} && \text{for all } \eta_h \in W^{1,p}(\mathcal{T}_h). \end{aligned}$$

Furthermore, if Λ_K satisfies the assumptions of [Lem. 5.3](#) for all $K \in \mathcal{T}_h$ and all $h \in (0, h_0)$, then for $0 \leq m \leq \Theta$, there exists $c_1, c_2 > 0$ independent of $h \in (0, h_0)$ such that

$$(5.7) \quad c_1 \|\eta_h\|_{W^{m,p}(\mathcal{T}_h)} \leq \left\| \eta_h^\ell \right\|_{W^{m,p}(\mathcal{T}_h^\ell)} \leq c_2 \|\eta_h\|_{W^{m,p}(\mathcal{T}_h)} \quad \text{for all } \eta_h \in W^{m,p}(\mathcal{T}_h).$$

Proof. The regularity of the family of triangulations $\{\mathcal{T}_h\}_{h \in (0, h_0)}$ follows from [\(5.4a\)](#) and [\(5.4b\)](#) from assumption [\(5.5\)](#).

The results follow by combining the previous results for each element in \mathcal{T}_h . We achieve bounds independently of $h \in (0, h_0)$ since the regularity of the subdivisions implies that h_K/ρ_K is bounded independently of $h \in (0, h_0)$. \square

We next define interpolation estimate which interpolates smooth functions over the continuous surface into the lifted surface finite element space. We denote by I_h an interpolation operator $I_h: C(\bar{\Omega}) \rightarrow \mathcal{S}_h^\ell$ defined by

$$(5.8) \quad I_h \eta|_{K^\ell} := I_{K^\ell} \eta.$$

Theorem 5.9 (Global lifted interpolation theorem). *For $h \in (0, h_0)$, let $\{\mathcal{T}_h\}_{h \in (0, h_0)}$ be a Θ -regular ([Def. 4.26\(b\)](#)), quasi-uniform ([Def. 4.26\(c\)](#)) family of subdivisions of triangulated bulk domains Ω_h equipped with a bulk finite element space \mathcal{S}_h ([Def. 4.22\(a\)](#)) consisting of Θ -bulk finite elements ([Def. 4.5](#)) over a reference element which satisfies [Lem. 4.3](#) for some $0 < k, m \leq \Theta$, $p, q \in [1, \infty]$. Let each element $K \in \mathcal{T}_h$ be equipped with a lifting map $\Lambda_K \in C^{\Theta+1}(K)$ such that $\|\Lambda_K\|_{W^{\Theta+1, \infty}(K)} \leq C$ and [\(5.5\)](#) and [\(5.1\)](#) hold each uniformly for $h \in (0, h_0)$. Then $\{\mathcal{T}_h^\ell\}_{h \in (0, h_0)}$ is a Θ -regular, quasi-uniform family of subdivisions of Ω and \mathcal{S}_h^ℓ is a bulk finite element space consisting of Θ -bulk finite elements. Let $\eta \in C(\bar{\Omega})$ be a continuous function, then $I_h \eta \in \mathcal{S}_h^\ell$ is well defined. Furthermore, if the assumptions of [Thm. 4.13](#) hold for the reference element $(\hat{K}, \hat{P}, \hat{\Sigma})$, there exists a constant $C = C(\hat{K}, \hat{P}, \hat{\Sigma}, \rho)$ such that for all functions $\eta \in W^{k+1,p}(\mathcal{T}_h^\ell) \cap C(\bar{\Omega})$,*

$$(5.9) \quad \|\eta - I_h \eta\|_{W^{m,q}(\mathcal{T}_h^\ell)} \leq Ch^{k+1-m} \|\eta\|_{W^{k+1,p}(\mathcal{T}_h^\ell)}.$$

Proof. The result follows by combining previous lemmas in the appropriate way. We see the lifted triangulation is quasi-uniform by applying the results in [Lem. 5.6](#) and the assumption [\(5.5\)](#). The interpolation result then follows by applying [Thm. 4.28](#). \square

Corollary 5.10. *Let $\eta \in C(\bar{\Omega})$, then the interpolant of η into \mathcal{S}_h , denoted by $\tilde{I}_h \eta$, given by*

$$(5.10) \quad \tilde{I}_h \eta := (I_h \eta)^{-\ell}.$$

Furthermore, there exists a constant C such that for all functions $\eta \in W^{k+1,p}(\mathcal{T}_h^\ell) \cap C(\bar{\Omega})$, and all $h \in (0, h_0)$, we have

$$(5.11) \quad \left\| \eta^{-\ell} - \tilde{I}_h \eta \right\|_{W^{m,q}(\mathcal{T}_h)} \leq Ch^{k+1-m} \|\eta\|_{W^{k+1,p}(\mathcal{T}_h^\ell)}.$$

Proof. We apply the inverse lift result to the estimates in the theorem. \square

5.3. Evolving lifted bulk triangulations. For $t \in [0, T]$, let $\Omega(t)$ be a smoothly evolving bulk domain with flow map Φ_t defined for the closure $\bar{\Omega}(t)$: i.e. $\Phi_{(\cdot)} \in C^2([0, T], C^1(\bar{\Omega}(0)))$, $\Phi_t(\Omega(0)) = \Omega(t)$ and $\Phi_t(\partial\Omega(0)) = \partial\Omega(t)$. For $h \in (0, h_0)$, let $\Omega_h(t)$ be an evolving triangulated bulk domain ([Def. 4.32\(b\)](#)) with global discrete flow Φ_t^h ([Def. 4.32\(c\)](#)) and equipped with an evolving conforming subdivision $\mathcal{T}_h(t)$ ([Def. 4.32\(a\)](#)) and an evolving bulk finite element space $\mathcal{S}_h(t)$ ([Def. 4.34\(a\)](#)). We assume that we are given a global lifting map $\Lambda_h(\cdot, t)$ ([Def. 5.7\(b\)](#)) which gives an exact subdivision $\mathcal{T}_h^\ell(t)$ of $\Omega(t)$ ([Def. 5.7\(a\)](#)).

Definition 5.11 (Lifted discrete flow map, material velocity and pushed forward map).

- (a) The *lifted flow map* $\Phi_{(\cdot)}^\ell(\cdot): [0, T] \times \bar{\Omega}_0 \rightarrow \mathbb{R}^{n+1}$ of the smooth bulk domain is defined by

$$\Phi_t^\ell(\Lambda_h(x, t)) = \Lambda_h(\Phi_t^h(x), t) \quad \text{for } x \in \bar{\Omega}_0.$$

We note that $\Phi_t^\ell: \bar{\Omega}_0 \rightarrow \bar{\Omega}(t)$.

- (b) The *lifted discrete material velocity* w_h on $\{\bar{\Omega}(t)\}_{t \in [0, T]}$ is defined by

$$\frac{d}{dt} \Phi_t^\ell(\cdot) = w_h(\Phi_t^\ell(\cdot), t).$$

- (c) The family of *lifted push forward maps* denoted by $\phi_t^\ell(\eta): \Omega(t) \rightarrow \mathbb{R}$, for $\eta: \Omega_0 \rightarrow \mathbb{R}$, indexed by $t \in [0, T]$, are the linear bijections defined by

$$\phi_t^\ell(\eta)(x) = \eta(\Phi_{-t}^\ell(x)) \quad \text{for } x \in \bar{\Omega}(t).$$

Remark 5.12. Note that in general Φ_t^ℓ is different to Φ_t , but each describes a different parametrisation of the same evolving domain. Also w , the material velocity of $\bar{\Omega}(t)$, and w_h define the same domain $\bar{\Omega}(t)$ evolving from $\bar{\Omega}(0)$, so have the same normal components on the boundary $\partial\Omega(t)$.

Proposition 5.13. *For $h \in (0, h_0)$, let $\{\mathcal{S}_h(t)\}_{t \in [0, T]}$ be an evolving bulk finite element space over a Θ -regular (Def. 4.26(b)), uniformly quasi-uniform (Def. 4.35(c)), evolving conforming subdivision $\{\mathcal{T}_h(t)\}_{t \in [0, T]}$ consisting of Θ -evolving bulk finite elements (Def. 4.30(d)) and ϕ_t^h the global push-forward map (Def. 4.32(e)). For each $t \in [0, T]$ and each $h \in (0, h_0)$, let each element $K(t) \in \mathcal{T}_h(t)$ be equipped with a lifting map $\Lambda_K(\cdot, t) \in C^{\Theta+1}(K(t))$ such that $\|\Lambda_K(\cdot, t)\|_{W^{\Theta+1, \infty}(K)} \leq C$ and (5.5) and (5.1) hold each uniformly for $h \in (0, h_0)$ and $t \in [0, T]$. Then $\{\mathcal{S}_h^\ell(t)\}_{t \in [0, T]}$ is also an evolving bulk finite element space over a Θ -regular, uniformly quasi-uniform, evolving conforming subdivision $\{\mathcal{T}_h^\ell(t)\}_{t \in [0, T]}$ consisting of Θ -evolving bulk finite elements. Furthermore, for $0 \leq k \leq \Theta + 1$, $p \in [0, \infty]$, there exists $c_1, c_2 > 0$ independent of $h \in (0, h_0)$ and $t \in [0, T]$ such that*

(5.12)

$$c_1 \|\eta\|_{W^{k,p}(\mathcal{S}_h^\ell(0))} \leq \left\| \phi_t^\ell \eta \right\|_{W^{k,p}(\mathcal{S}_h^\ell(t))} \leq c_2 \|\eta\|_{W^{k,p}(\mathcal{S}_h^\ell(0))} \quad \text{for all } \eta \in W^{k,p}(\mathcal{S}_h^\ell(0)).$$

In particular, the pair $(W^{k,p}(\mathcal{S}_h^\ell(t)), \phi_t^\ell)_{t \in [0, T]}$ is compatible (Def. 2.2). Furthermore, $(\mathcal{S}_h(t), \phi_t^\ell|_{\mathcal{S}_h(0)})_{t \in [0, T]}$, equipped with the norm $\|\cdot\|_{W^{k,p}(\mathcal{S}_h^\ell(t))}$, and $(W^{1,p}(\Omega(t)), \phi_t^\ell|_{W^{1,p}(\Omega_0)})_{t \in [0, T]}$ are also compatible pairs (Rem. 2.3 and Lem. 4.19 and 4.23).

Proof. The properties of $\mathcal{S}_h^\ell(t)$ follow for the same reasoning as Prop. 5.8 since the constants are bounded uniformly in time. The bounds (5.12) and the compatibility of $(W^{k,p}(\mathcal{S}_h^\ell(t)), \phi_t^\ell)_{t \in [0, T]}$ follow since the assumptions imply that $(W^{k,p}(\mathcal{T}_h(t)), \phi_t^h)_{t \in [0, T]}$ are compatible and we can simply lift this result with uniform bounds. \square

6. EVOLVING SURFACE FINITE ELEMENT SPACES

In this section, we will give precise definitions concerning the evolving surface finite element spaces we use. The ideas follow in a similar manner to Sec. 4. The upshot will be a notion of a discrete surface $\Gamma_h(t)$ consisting of a union of elements and a finite element space $\mathcal{S}_h(t)$ defined on this discrete domain. Our extensions from standard bulk finite element theory, presented in Sec. 4, to surface finite elements build on the work of Nedelec (1976), Dziuk (1988) and Heine (2005) for surfaces. The subscript h parametrises the

constructions and will be related to the size of elements used in our computational domain. Implicitly it is assumed that these structures exist for all $h \in (0, h_0)$ for some fixed value of h_0 . See also [Rem. 6.11](#).

6.1. Surface finite elements. We next define a surface finite element which takes its inspiration from the notion of curved finite elements studied by [Ciarlet and Raviart \(1972\)](#) and [Bernardi \(1989\)](#). The key idea here is that a surface finite element is an n -dimensional parametrised surface with boundary embedded in \mathbb{R}^{n+1} . In the following for a matrix A , we use A^\dagger to denote the pseudo-inverse. For any matrix A of full column rank the pseudo-inverse is given by

$$A^\dagger = (A^t A)^{-1} A^t.$$

In this case A^\dagger is the left inverse of A : $A^\dagger A = \text{Id}$.

Definition 6.1 (Surface finite element and surface element reference map). Let $(\hat{K}, \hat{P}, \hat{\Sigma})$ be a reference finite element with $\hat{K} \subset \mathbb{R}^n$.

- (a) Let $F_K: \hat{K} \rightarrow \mathbb{R}^{n+1}$ satisfy
- (1) (a) $F_K \in C^1(\hat{K}, \mathbb{R}^{n+1})$;
 - (b) $\text{rank } \nabla F_K = n$;
 - (c) F_K is a bijection onto its image;
- (2) F_K can be decomposed into an affine part, and smooth part

$$F_K(\hat{x}) = A_K \hat{x} + b_K + D_K(\hat{x})$$

such that A_K has full column rank, $D_K \in C^1(\hat{K})$ and

$$(6.1) \quad C_K := \sup_{\hat{x} \in \hat{K}} \left\| \nabla D_K(\hat{x}) A_K^\dagger \right\| < 1,$$

where $\|\cdot\|$ denotes the two-norm in this context.

In this case, we call F_K a *surface element reference map*.

- (b) Let F_K be a surface element reference map and (K, P, Σ) be the triple given by

$$(6.2a) \quad K := F_K(\hat{K}) \quad (\text{the element domain})$$

$$(6.2b) \quad P := \{\hat{\chi} \circ F_K^{-1} : \hat{\chi} \in \hat{P}\} \quad (\text{the shape functions})$$

$$(6.2c) \quad \Sigma := \{\chi \mapsto \hat{\sigma}(\chi \circ F_K) : \hat{\sigma} \in \hat{\Sigma}\} \quad (\text{the nodal variables}).$$

Under the above assumptions, we call (K, P, Σ) a *surface finite element*, and $(\hat{K}, \hat{P}, \hat{\Sigma})$ the associated *reference finite element*.

Remark 6.2. (a) We note that our assumptions imply that both A_K and $\nabla F_K(\cdot)$ are full column rank.

- (b) The first three assumptions in the definition of surface finite element imply that K is a parametrised surface and the fourth (6.1) that K is not too curved. The final assumption allows the case that \hat{K} is a flat simplicial domain and K is curved.

Remark 6.3. (a) We denote by \mathbf{v}_K the unit normal vector field to K . It is the unique (up to sign) unit vector orthogonal to the \hat{x}_i partial derivatives of F_K for $i = 1, \dots, n$ and is given by

$$\mathbf{v}_K := \begin{cases} \left(\frac{\partial F_K}{\partial \hat{x}_1} \right)^\perp & \text{for } n = 1 \\ \left(\frac{\partial F_K}{\partial \hat{x}_1} \right)^\perp & \text{for } n > 1. \\ \left(\frac{\partial F_K}{\partial \hat{x}_1} \wedge \dots \wedge \frac{\partial F_K}{\partial \hat{x}_n} \right) & \\ \left(\left| \frac{\partial F_K}{\partial \hat{x}_1} \wedge \dots \wedge \frac{\partial F_K}{\partial \hat{x}_n} \right| \right) & \end{cases}$$

Here \wedge denotes the wedge product. The sign of the normal vector field is chosen by fixing a permutation of the barycentric coordinates $\hat{x}_1, \dots, \hat{x}_n$ of the reference element. By swapping any two elements, we reverse the sign of \mathbf{v}_K . For a simplex reference element, the orientation can be fixed by ordering the labels of vertices so that $a_i = F_K(\hat{a}_i)$ where $\{\hat{a}_i\}$ are the vertices of the reference element domain.

- (b) We also define the outward pointing unit *conormal* μ_K on the boundary of the element domain ∂K . This is the unique (up to sign) vector which is orthogonal to the boundary ∂K and the normal \mathbf{v}_K .
- (c) Our assumptions imply that $\nabla F_K(\hat{x})^\dagger$ (or A_K^\dagger) is a left inverse but not a right inverse of $\nabla F_K(\hat{x})$ (respectively, A_K). We can compute that

$$\nabla F_K(\hat{x}) \nabla F_K(\hat{x})^\dagger = \text{Id} - \mathbf{v}_K(F_K(\hat{x})) \otimes \mathbf{v}_K(F_K(\hat{x})) =: P_K(F_K(\hat{x})),$$

where P_K denotes projection onto the tangent plane to K . One way to interpret this result is to note that P_K is the identity operator when restricted to the tangent plane so that in some sense $\nabla F_K(\hat{x})^\dagger$ is a right inverse of $\nabla F_K(\hat{x})$ when we restrict to the tangent plane of K .

Definition 6.4 (Θ -surface finite element and Θ -surface element reference map). Let $\Theta \in \mathbb{N}$ and F_K a surface element reference map for a surface finite element (K, P, Σ) .

- (a) We say that F_K is a Θ -surface finite element reference map if
 - (i) the surface element reference map $F_K \in C^{\Theta+1}(\hat{K}; \mathbb{R}^{n+1})$ (i.e. K is a $C^{\Theta+1}$ -hypersurface);
 - (ii) for $1 \leq m \leq \Theta + 1$, there exists constants $C_m(K) > 0$ such that

$$(6.3) \quad \sup_{\hat{x} \in \hat{K}} |\nabla^m F_K(\hat{x})| \|A_K\|^{-m} \leq C_m(K).$$

- (b) We say that (K, P, Σ) is a Θ -surface finite element if F_K is a Θ -surface finite element reference map and
 - (i) the space P contains the functions $\hat{\chi} \circ F_K^{-1}$ for all $\hat{\chi} \in P_\Theta(\hat{K})$;
 - (ii) the space P is contained in $C^{\Theta+1}(K)$.

Remark 6.5. (a) The Θ -surface finite element is a generalisation of a curved finite element of order Θ given by [Bernardi \(1989\)](#). See also [Def. 4.5](#).

- (b) For a Θ -surface finite element (K, P, Σ) , we have that the Sobolev space $W^{m,p}(K)$ is well defined for $0 \leq m \leq \Theta + 1$ and $1 \leq p \leq \infty$ ([Hebey, 2000](#); [Dziuk and Elliott, 2013b](#)).
- (c) Since $P \subset C^{\Theta+1}(K)$ and P is finite dimensional, P is a closed subspace of $W^{m,p}(K)$ for $0 \leq m \leq \Theta + 1$ and $p \in [1, \infty]$.
- (d) We note that (K, P, Σ) is a 1-surface finite element if (K, P, Σ) is a surface finite element ([Def. 6.1](#)), the map $F_K \in C^2(\hat{K}, \mathbb{R}^{n+1})$ and P contains all affine functions on K . We see that the constant $C_1(K) = 1 + C_K$ (see [Lem. 6.8](#)).
- (e) Our applications ([Sec. 9](#) and [10](#)) will use $F_K \in P_\Theta(\hat{K})$ in the computational method but we allow the more general case here.

Using transformation formulae, we have for $\chi: K \rightarrow \mathbb{R}$

$$\int_K \chi \, d\sigma = \int_{\hat{K}} \hat{\chi}(\hat{x}) \sqrt{g(\hat{x})} \, d\hat{x}, \quad \nabla_K \chi(x) = \sum_{i,j=1}^n g^{ij}(\hat{x}) \frac{\partial \hat{\chi}(\hat{x})}{\partial \hat{x}_j} \frac{\partial F_K(\hat{x})}{\partial \hat{x}_i},$$

where $F_K(\hat{x}) = x$ and $\hat{\chi}(\hat{x}) = \chi(x)$, and

$$G(\hat{x}) = (\nabla F_K(\hat{x}))^t (\nabla F_K(\hat{x})), \quad g(\hat{x}) = \det G(\hat{x}),$$

and finally, (g^{ij}) are the components of the inverse G^{-1} . Note that the surface gradient on K can also be written as:

$$\nabla_K \chi(x) = \nabla \tilde{\chi}(x) - (\nabla \tilde{\chi}(x) \cdot \mathbf{v}_K(x)) \mathbf{v}_K(x) = (\text{Id} - \mathbf{v}_K(x) \otimes \mathbf{v}_K(x)) \nabla \tilde{\chi}(x),$$

where $\nabla \tilde{\chi}$ is the gradient of an arbitrary extension of χ away from K .

Remark 6.6. If the surface finite element map F_K is a C^2 function then we can define the extended Weingarten map $\mathbb{H}_K: K \rightarrow \mathbb{R}^{(n+1) \times (n+1)}$ by

$$(6.4) \quad (\mathbb{H}_K)_{ij} = (\nabla_K)_i (\mathbf{v}_K)_j \text{ for } i, j = 1, \dots, n+1.$$

Example 6.7 (Surface finite elements). We are thinking of three particular examples. The first is due to [Dziuk \(1988\)](#) and the second due to [Heine \(2005\)](#). Examples of each of these first two cases are shown in [Fig. 6.1](#).

- (a) Let $(\hat{K}, P_1(\hat{K}), \hat{\Sigma})$ be a reference Lagrangian finite element. Consider the affine map $F_K: \hat{K} \rightarrow \mathbb{R}^{n+1}$ given by $F_K(\hat{x}) = A_K \hat{x} + b_K$. If A_K is non-degenerate, then this defines a surface finite element (K, P, Σ) . The element domain K is determined by its vertices and P consists of affine functions over K . This is the surface finite element introduced by [Dziuk \(1988\)](#) which we will call an *affine finite element*. We think of a simplex for \hat{K} so that the domains K are either line segments embedded in \mathbb{R}^2 , triangles embedded in \mathbb{R}^3 , and tetrahedra embedded in \mathbb{R}^4 .
- (b) Let $(\hat{K}, \hat{P}, \hat{\Sigma})$ be a reference finite element. Let (K, P, Σ) be a surface finite element which the image of $(\hat{K}, \hat{P}, \hat{\Sigma})$ under a map F_K which satisfies $F_K \in (\hat{P})^{n+1}$. We call (K, P, Σ) an isoparametric (surface) finite element. This construction is a generalisation of an affine finite element and was introduced by [Heine \(2005\)](#). We note that the functions in P will not necessarily consist of polynomials over K even if \hat{P} consists of polynomials over \hat{K} , however this leads to a practical scheme where integrals are computed over reference elements. This example is the basis for the method in [Sec. 9](#).
- (c) Let $(\hat{K}, \hat{P}, \hat{\Sigma})$ be a reference finite element. Then $(\hat{K}, \hat{P}, \hat{\Sigma})$ can be thought of a surface finite element (K, P, Σ) by defining the parametrisation F_K by

$$F_K(\hat{x}) = (\hat{x}_1, \dots, \hat{x}_n, 0).$$

Note that $\hat{K} \subset \mathbb{R}^n$ but $K \subset \mathbb{R}^{n+1}$. In general, we could consider flat surface finite elements to be surface finite elements to have parametrisation F_K such that $(F_K)_{n+1} \equiv 0$.

Lemma 6.8. *Let $F_K: \hat{K} \rightarrow K$ be a surface finite element reference map then F_K is a C^1 -diffeomorphism and satisfies*

$$(6.5) \quad \sup_{\hat{x} \in \hat{K}} \|\nabla F_K(\hat{x})\| \leq (1 + C_K) \|A_K\|$$

$$(6.6) \quad \sup_{\hat{x} \in \hat{K}} \|(\nabla F_K(\hat{x}))^\dagger\| \leq (1 - C_K) \|A_K^\dagger\|,$$

and also for all $\hat{x} \in \hat{K}$

$$(6.7) \quad (1 - C_K)^{2n} \det(A_K^t A_K) \leq g(\hat{x})^2 \leq (1 + C_K)^{2n} \det(A_K^t A_K).$$

Proof. The proof of (6.5), (6.6) and (6.7) follows immediately from (6.1) by writing ∇F_K as

$$\nabla F_K(\hat{x}) = (\text{Id} + \nabla D_K(\hat{x}) A_K^\dagger) A_K.$$

For (6.7), we use the fact that the determinant is an n -linear continuous form. □

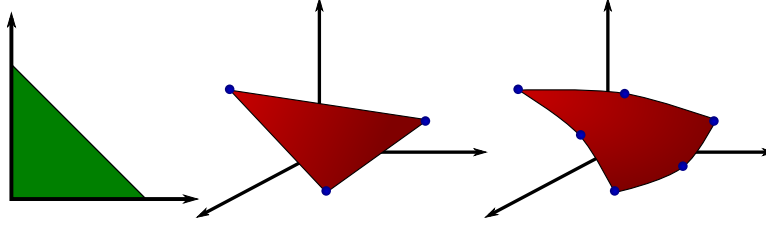


FIGURE 6.1. Examples of different surface finite elements in the case $n = 2$. Left shows a reference finite element (in green), centre shows an affine finite element (Ex. 6.7(a)) and right shows an isoparametric surface finite element (Ex. 6.7(b)) with a quadratic F_K . The plot shows the element domains in red and the location of nodes in blue.

To help us understand the geometry of the new elements, given an element domain K , we introduce a new affine element domain \tilde{K} defined by the affine part of the parametrisation: $\tilde{K} := \{A_K \hat{x} + b_K : \hat{x} \in \hat{K}\}$.

Lemma 6.9. *Let K be an element domain (6.2a) parametrised by a surface element reference map F_K over \hat{K} . Denote by*

$$(6.8a) \quad h_K := \text{diam}(\tilde{K})$$

$$(6.8b) \quad \rho_K := \sup\{\text{diam}(B) : B \text{ is a } n\text{-dimensional ball contained in } \tilde{K}\}.$$

We will also write \hat{h} and $\hat{\rho}$ for the diameter of \hat{K} and diameter of the maximum inscribed ball in \hat{K} . Then we have that

$$(6.9a) \quad \|A_K\| \leq \frac{h_K}{\hat{\rho}}$$

$$(6.9b) \quad \|A_K^\dagger\| \leq \frac{\hat{h}}{\rho_K}$$

$$(6.9c) \quad \sup_{\hat{x} \in \hat{K}} \sqrt{g(\hat{x})} \leq \frac{1}{\text{meas } \hat{K}} \left(\frac{1+C_K}{1-C_K} \right)^n \text{meas}(K).$$

Proof. To show (6.9a), we start by noticing that

$$\|A_K\| = \frac{1}{\hat{\rho}} \sup \{|A_K \xi| : \xi \in \mathbb{R}^n, |\xi| = \hat{\rho}\}.$$

From the definition of $\hat{\rho}$ we know that for all $\xi \in \mathbb{R}^n$, $|\xi| = \hat{\rho}$, there exists $\hat{y}, \hat{z} \in \hat{K}$ such that $\hat{y} - \hat{z} = \xi$. Then noting that $A_K \hat{y}, A_K \hat{z} \in \tilde{K}$, we have that

$$|A_K \xi| = |A_K(\hat{y} - \hat{z})| = |A_K \hat{y} - A_K \hat{z}| \leq h_K.$$

Since the choice of ξ was arbitrary, we have shown (6.9a).

For (6.9b), we proceed in a similar fashion with

$$\|A_K^\dagger\| = \frac{1}{\rho_K} \sup \left\{ |A_K^\dagger \xi| : \xi \in \mathbb{R}^{n+1}, |\xi| = \rho_K \right\}.$$

Let $\xi \in \mathbb{R}^{n+1}$. We note that A_K^\dagger has a non-trivial kernel so we decompose $\xi = \xi_1 + \xi_2$ where $A_K^\dagger \xi_2 = 0$ and ξ_1 is in the tangent plane to \tilde{K} . Then, we see that there exists $y, z \in \tilde{K}$

such that $y - z = \xi$, and noting that $A_K^\dagger(y - b_K), A_K^\dagger(z - b_K) \in \hat{K}$ (we see this using the definition of \tilde{K} and that A_K^\dagger is a left inverse of A_K), we see that

$$\left| A_K^\dagger \xi \right| = \left| A_K^\dagger(y - z) \right| = \left| A_K^\dagger(y - b_K) - A_K^\dagger(z - b_K) \right| \leq \hat{h}.$$

Again, since the choice of ξ was arbitrary, we have shown (6.9b).

To see (6.9c) we apply each of the previous two bounds with the result of Lem. 6.8 to see

$$\begin{aligned} \sup_{\hat{x} \in \hat{K}} \sqrt{g(\hat{x})} &\leq (1 + C_K)^n \sqrt{\det(A_K' A_K)} \\ &\leq \frac{1}{\text{meas } \hat{K}} (1 + C_K)^n \int_{\hat{K}} \sqrt{\det(A_K' A_K)} \, d\hat{x} \\ &\leq \frac{1}{\text{meas } \hat{K}} (1 + C_K)^n / (1 - C_K)^n \int_{\hat{K}} \sqrt{g(\hat{x})} \, d\hat{x} \\ &\leq \frac{1}{\text{meas } \hat{K}} \left(\frac{1 + C_K}{1 - C_K} \right)^n \text{meas}(K) \\ &\leq C(\hat{K}) \text{meas}(K). \quad \square \end{aligned}$$

Remark 6.10. We note that the volume of an element $\text{meas}(K)$ can be estimated by h_K and ρ_K by

$$c_1 \rho_K^n \leq \text{meas } K \leq c_2 h_K^n.$$

Here the positive constants c_1, c_2 depend on the volume of the unit ball in \mathbb{R}^n and the constant C_K .

Remark 6.11. In the sequel, we will assume implicitly that results hold for h_K sufficiently small ($h_K < h_0$) for some particular value of h_0 . In general this is always possible by subdividing a particular element using a refinement procedure and applying the result to the subdivided, smaller elements.

This scaling property allows us to characterise Sobolev spaces over a surface finite element K and calculate norms over \hat{K} (see Rem. 6.5(b)).

Lemma 6.12. *Let $F_K: \hat{K} \rightarrow K$ be a Θ -reference finite element map Def. 6.4(a). Let $0 \leq m \leq \Theta + 1$ and $p \in [1, \infty]$, then $\chi \in W^{m,p}(K)$ implies $\hat{\chi} = \chi \circ F_K$ belongs to $W^{m,p}(\hat{K})$. We have for any $\chi \in W^{m,p}(K)$ that*

$$(6.10) \quad |\hat{\chi}|_{W^{m,p}(\hat{K})} \leq c \left(\sup_{\hat{x} \in \hat{K}} \sqrt{g(\hat{x})} \right)^{-\frac{1}{p}} \|A_K\|^m \sum_{r=1}^m |\chi|_{W^{r,p}(K)},$$

for a constant which depends on $C_K, C_2(K), \dots, C_m(K)$. We also have for any $\hat{\chi} \in W^{m,p}(\hat{K})$ that $\chi = \hat{\chi} \circ F_K^{-1} \in W^{m,p}(K)$ and

$$(6.11) \quad |\chi|_{W^{m,p}(K)} \leq c \left(\sup_{\hat{x} \in \hat{K}} \sqrt{g(\hat{x})} \right)^{\frac{1}{p}} \sum_{r=1}^m \|A_K^\dagger\|^r |\hat{\chi}|_{W^{r,p}(\hat{K})},$$

where the constant here depends on $C_K, C_2(K), \dots, C_m(K)$ and the product $\|A_K\| \|A_K^\dagger\|$.

Proof. In this proof we use the results and notation for the Faá di Bruno result presented in App. A.

For (6.10) using (A.1), we see that

$$\frac{\partial^m}{\partial \hat{x}_{j_m} \dots \partial \hat{x}_{j_1}} \hat{\chi}(\hat{x}) = \sum_{r=1}^m \sum_{\lambda_1=1}^{n+1} \dots \sum_{\lambda_r=1}^{n+1} (\nabla_K)_{\lambda_r} \dots (\nabla_K)_{\lambda_1} \chi(x) \sum_{\mathbb{P}_{m,r}} \prod_{s=1}^r \frac{\partial^{|\sigma_s|}}{\partial \hat{x}_{j_{\sigma_s}}} (F_K(\hat{x}))_{\lambda_s}.$$

Then

$$\left| \frac{\partial^m}{\partial \hat{x}_{j_m} \dots \partial \hat{x}_{j_1}} \hat{\chi}(\hat{x}) \right| \leq \sum_{r=1}^m \sum_{\lambda_1=1}^{n+1} \dots \sum_{\lambda_r=1}^{n+1} |(\nabla_K)_{\lambda_r} \dots (\nabla_K)_{\lambda_1} \chi(x)| \sum_{\mathbb{P}_{m,r}} \prod_{s=1}^r \left| \frac{\partial^{|\sigma_s|}}{\partial \hat{x}_{j_{\sigma_s}}} (F_K(\hat{x}))_{\lambda_s} \right|.$$

We see that from assumption (6.3)

$$(6.12) \quad \sum_{\mathbb{P}_{m,r}} \prod_{s=1}^r \left| \frac{\partial^{|\sigma_s|}}{\partial \hat{x}_{j_{\sigma_s}}} (F_K(\hat{x}))_{\lambda_s} \right| \leq \sum_{\mathbb{P}_{m,r}} \prod_{s=1}^r c(c_{|\sigma_s|}(K)) \|A_K\|^{|\sigma_s|} \\ \leq c(C_1(K), \dots, C_m(K)) \sum_{\mathbb{P}_{m,r}} \|A_K\|^{\sum_{s=1}^r |\sigma_s|} \leq c(C_1(K), \dots, C_m(K)) \|A_K\|^m.$$

Then, we have that

$$\left| \frac{\partial^m}{\partial \hat{x}_{j_m} \dots \partial \hat{x}_{j_1}} \hat{\chi}(\hat{x}) \right| \leq c(C_1(K), \dots, C_m(K)) \|A_K\|^m \sum_{r=1}^m \sum_{\lambda_1=1}^{n+1} \dots \sum_{\lambda_r=1}^{n+1} |(\nabla_K)_{\lambda_r} \dots (\nabla_K)_{\lambda_1} \chi(x)|.$$

The inequality (6.10) then follows from integration and a Minkowski inequality.

For (6.11), from (A.4), we have

$$|(\nabla_K)_{i_m} \cdot (\nabla_K)_{i_1} \chi(x)| \\ \leq \left| \sum_{j_m, \dots, j_1=1}^n \frac{\partial^m}{\partial \hat{x}_{j_m} \dots \partial \hat{x}_{j_1}} \hat{\chi} \left(\prod_{s=1}^m (\nabla F_K(\hat{x}))_{j_s, i_s}^\dagger \right) \right| \\ + \left| \sum_{r=1}^{n-1} \sum_{\lambda_1, \dots, \lambda_r=1}^{n+1} (\nabla_\Gamma)_{\lambda_r} \dots (\nabla_\Gamma)_{\lambda_1} \chi(x) \sum_{j_m, \dots, j_1=1}^n \sum_{\mathbb{P}_{m,r}} \prod_{s=1}^r \frac{\partial^{|\sigma_s|}}{\partial \theta_{j_{\sigma_s}}} (F_K(\hat{x}))_{\lambda_s} \prod_{s=1}^m (\nabla F_K(\hat{x}))_{j_s, i_s}^\dagger \right| \\ =: A_1 + A_2.$$

We bound each of A_1 and A_2 in turn. We see that for A_1 , applying (6.6)

$$A_1 \leq (1 - C_K)^m \|A_K^\dagger\|^m \sum_{j_m=1}^n \dots \sum_{j_1=1}^n \left| \frac{\partial^m}{\partial x_{j_m} \dots \partial x_{j_1}} \hat{\chi}(\hat{x}) \right|.$$

For A_2 , applying (6.6) and (6.12):

$$A_2 \leq c(C_1(K), \dots, C_m(K)) (1 - C_K)^m \|A_K\|^m \|A_K^\dagger\|^m \sum_{r=1}^{m-1} \sum_{\lambda_1=1}^{n+1} \dots \sum_{\lambda_r=1}^{n+1} |(\nabla_K)_{\lambda_r} \dots (\nabla_K)_{\lambda_1} \chi(x)|.$$

Combining the above estimates and integrating over the domain, we see

$$|\chi|_{W^{m,p}(K)} \leq \left(\sup_{\hat{x} \in \hat{K}} \sqrt{g(\hat{x})} \right)^{1/p} (1 - C_K)^m \|A_K^\dagger\|^m |\hat{\chi}|_{W^{m,p}(\hat{K})} \\ + (c(C_1(K), \dots, C_m(K)) (1 - C_K)^m \|A_K\|^m \|A_K^\dagger\|^m) \sum_{r=1}^{m-1} |\chi|_{W^{m-1,p}(K)}.$$

Define $\beta_m = (c(C_1(K), \dots, C_m(K))(1 - C_K)^m \|A_K\|^m \|A_K^\dagger\|^m)$. Then, a simple induction argument shows that

$$|\chi|_{W^{m,p}(K)} \leq c \left(\sup_{\hat{x} \in \hat{K}} \sqrt{g(\hat{x})} \right)^{1/p} \sum_{r=1}^m c_{m,r} \|A_K^\dagger\|^r |\hat{\chi}|_{W^{r,p}(\hat{K})}$$

where $c_{m,r}$ satisfies

$$c_{m,m} = 1 \quad c_{m,r} = \sum_{s=r}^{m-1} \beta_m c_{s,r}. \quad \square$$

Given a surface finite element (K, P, Σ) (Def. 6.1), let $\{\chi_i : 1 \leq i \leq d\} \subset P$ be the basis dual to Σ . This is the set of *basis functions* of the finite element. If η is a function for which all $\sigma_i(\eta)$, $1 \leq i \leq d$ is well defined, then we define the *local interpolant* by

$$(6.13) \quad I_K \eta := \sum_{i=1}^m \sigma_i(\eta) \chi_i.$$

We can think of $I_K \eta$ as the unique shape function that has the same nodal values as η so that, in particular, $I_K \chi = \chi$ for $\chi \in P$.

Theorem 6.13 (Local interpolation estimate). *Let (K, P, Σ) be a Θ -surface finite element (Def. 6.4) with reference element $(\hat{K}, \hat{P}, \hat{\Sigma})$ which satisfies the assumptions of Lem. 4.3 for some $0 < k, m \leq \Theta$, $p, q \in [1, \infty]$. Then there exists a constant $C = C(\hat{K}, \hat{P}, \hat{\Sigma})$ such that for all functions $\chi \in W^{k+1,p}(K)$,*

$$(6.14) \quad |\chi - I_K \chi|_{W^{m,q}(K)} \leq C \text{meas}(K)^{1/q-1/p} \frac{h_K^{k+1}}{\rho_K^m} |\chi|_{W^{k+1,p}(K)}.$$

Proof. We re-scale (4.1) using Lem. 6.12 and the estimates from (6.9):

$$\begin{aligned} |\chi - I_K \chi|_{W^{m,q}(K)} &\leq c \left(\sup_{\hat{x} \in \hat{K}} \sqrt{g(\hat{x})} \right)^{1/q} \sum_{r=1}^m \|A_K^\dagger\|^r |\hat{\chi} - I_{\hat{K}} \hat{\chi}|_{W^{r,q}(\hat{K})} \\ &\leq c \left(\sup_{\hat{x} \in \hat{K}} \sqrt{g(\hat{x})} \right)^{1/q} \sum_{r=1}^m \|A_K^\dagger\|^r |\hat{\chi}|_{W^{k+1,p}(\hat{K})} \\ &\leq c \left(\sup_{\hat{x} \in \hat{K}} \sqrt{g(\hat{x})} \right)^{1/q-1/p} \sum_{r=1}^m \|A_K^\dagger\|^r \|A_K\|^{k+1} |\chi|_{W^{k+1,p}(K)} \\ &\leq c \text{meas}(K)^{1/q-1/p} \frac{h_K^{k+1}}{\rho_K^m} \|\chi\|_{W^{k+1,p}(K)}. \end{aligned}$$

The last line holds if $\rho_K < 1$ (note that $\rho_K \geq h_K$ so this statement is true for h_K small enough). \square

6.2. Triangulated hypersurface and surface finite element spaces. We will next bring together several surface finite elements in order to define Γ_h as a collection of finite element domains.

Definition 6.14. (a) A *triangulated hypersurface* is a set Γ_h equipped with an *admissible subdivision* \mathcal{T}_h consisting of surface finite element domains (6.2a) such that $\bigcup_{K \in \mathcal{T}_h} K = \Gamma_h$, $\hat{K}_1 \cap \hat{K}_2 = \emptyset$ for $K_1, K_2 \in \mathcal{T}_h$ with $K_1 \neq K_2$.

(b) The maximum subdivision diameter h is defined by:

$$(6.15) \quad h := \max_{K \in \mathcal{T}_h} h_K.$$

- (c) Let Γ_h be a discrete hypersurface equipped with an admissible subdivision \mathcal{T}_h such that each set $K \in \mathcal{T}_h$ is an element domain for a surface finite element $(K, \mathcal{P}^K, \Sigma^K)$ parametrised over the same polygonal reference finite element $(\hat{K}, \hat{\mathcal{P}}, \hat{\Sigma})$. We say that $E \subset K$ is a *facet* if E is the image of a boundary facet of \hat{K} .
- (d) We say that \mathcal{T}_h is a *conforming* subdivision of Γ_h if any facet of an element domain K is either a facet of another element domain $K' \in \mathcal{T}_h$, in which case we say K and K' are *adjacent*, or a portion of the boundary $\partial\Gamma_h$ (if such a boundary exists).
- (e) For a conforming subdivision \mathcal{T}_h of Γ_h , we denote by \mathcal{F}_h the set of facets between adjacent elements and $\partial\mathcal{T}_h$ any boundary facets. For a common facet $F \in \mathcal{F}_h$ between elements $K, K' \in \mathcal{T}_h$, we make a fixed choice that the conormal μ_K on F will be denoted μ_F^+ and the conormal $\mu_{K'}$ on F will be denoted μ_F^- . The choice of which element is on which side of the facet is not important in our considerations.

Remark 6.15. • In the above definition we do not impose any global assumptions on the connectivity or smoothness of Γ_h . Thus there may not be an underlying smooth surface.

- We orient a discrete hypersurface which is equipped with a conforming subdivision by choosing a particular sign to the element-wise definition of normal. We restrict that the induced orientation of the intersection of adjacent element domains are opposite. For example, for a simplex reference element, the vertices in facets between two elements should be ordered oppositely in each element.

For any triangulated hypersurface Γ_h , we may define spaces of Lebesgue integrable functions $L^p(\Gamma_h)$ with the usual norms $\|\cdot\|_{L^p(\Gamma_h)}$ for $p \in [1, \infty]$.

Definition 6.16 (Broken Sobolev spaces and norms). Let \mathcal{T}_h be a subdivision of Γ_h consisting of Θ -surface finite elements. Then for $0 \leq m \leq \Theta + 1$, $p \in [1, \infty]$, we define the broken Sobolev space $W^{m,p}(\mathcal{T}_h)$ by

$$(6.16) \quad W^{m,p}(\mathcal{T}_h) := \{ \eta_h \in L^1(\Gamma_h) : \eta_h|_K \in W^{m,p}(K) \text{ for all } K \in \mathcal{T}_h \},$$

with norm

$$(6.17) \quad \|\eta_h\|_{W^{m,p}(\mathcal{T}_h)} := \begin{cases} \left(\sum_{K \in \mathcal{T}_h} \|\eta_h\|_{W^{m,p}(K)}^p \right)^{1/p} & p < \infty \\ \max_{K \in \mathcal{T}_h} \|\eta_h\|_{W^{m,\infty}(K)} & p = \infty. \end{cases}$$

Lemma 6.17. *The space $W^{m,p}(\mathcal{T}_h)$ is complete.*

Proof. Consider a Cauchy sequence $\{\eta_j\} \in W^{m,p}(\mathcal{T}_h)$. This implies

- η_j is Cauchy in $L^p(\Gamma_h)$ so there exists ξ such that $\eta_j \rightarrow \xi$ in $L^p(\Gamma_h)$.
- $\eta_j|_K$ is Cauchy for all K so there exists ξ_K such that $\eta_j|_K \rightarrow \xi_K$ in $W^{m,p}(K)$.

It is clear from the triangle inequality that $\xi|_K = \xi_K$:

$$\|\xi|_K - \xi_K\|_{W^{m,p}(K)} \leq \|\xi|_K - \eta_j|_K\|_{L^{m,p}(K)} + \|\eta_j|_K - \xi_K\|_{W^{m,p}(K)},$$

since the right hand-side converges to 0 as $j \rightarrow \infty$. Hence, we have shown that η_j converges to a function $\xi \in W^{m,p}(\mathcal{T}_h)$ in the $W^{m,p}(\mathcal{T}_h)$ norm. \square

We also want more connectivity between elements. This is achieved in the following space. Let Γ_h be a triangulated hypersurface with conforming subdivision \mathcal{T}_h . For $K \in \mathcal{T}_h$, we denote the trace of a function $\chi \in W^{1,p}(K)$ by $T_K \chi \in L^p(\partial K)$ and recall that there exists a constant $c_{T_K} > 0$ such that

$$(6.18) \quad \|T_K \chi\|_{L^p(\partial K)} \leq c_{T_K} \|\chi\|_{W^{1,p}(K)} \quad \text{for all } \chi \in W^{1,p}(K).$$

We define the space $W_T^{1,p}(\mathcal{T}_h)$ by

$$(6.19) \quad W_T^{1,p}(\mathcal{T}_h) := \left\{ \eta_h \in L^p(\Gamma_h) : \eta_h|_K \in W^{1,p}(K) \text{ for all } K \in \mathcal{T}_h, \text{ and} \right. \\ \left. T_K(\eta_h|_K) = T_{K'}(\eta_h|_{K'}) \text{ a.e. in } K \cap K' \text{ for adjacent } K, K' \in \mathcal{T}_h \right\}.$$

We equip this space with the broken norm $\|\cdot\|_{W^{1,p}(\mathcal{T}_h)}$.

Lemma 6.18. *The space $W_T^{1,p}(\mathcal{T}_h)$ is a closed subspace of $W^{1,p}(\mathcal{T}_h)$ so is complete.*

Proof. Take a sequence $\{\eta_j\} \subset W_T^{1,p}(\mathcal{T}_h)$ which converges to $\eta_h \in W^{1,p}(\mathcal{T}_h)$. Then for any pair of adjacent elements $K, K' \in \mathcal{T}_h$ we have

$$\|\eta_h|_K - \eta_h|_{K'}\|_{L^p(K \cap K')} \leq \|\eta_h - \eta_j\|_{L^p(\partial K)} + \|\eta_h - \eta_j\|_{L^p(\partial K')} \\ \leq c_{T_K} \|\eta_h - \eta_j\|_{W^{1,p}(K)} + c_{T_{K'}} \|\eta_h - \eta_j\|_{W^{1,p}(K')} \leq (c_{T_K} + c_{T_{K'}}) \|\eta_h - \eta_j\|_{W^{1,p}(\mathcal{T}_h)}.$$

Clearly the right hand side converges to 0 as $j \rightarrow \infty$ so we have the traces of η_h from adjacent elements coincide and $\eta_h \in W_T^{1,p}(\mathcal{T}_h)$. \square

We will use the notation for $H_T^1(\mathcal{T}_h) := W_T^{1,2}(\mathcal{T}_h)$ which is a Hilbert space when equipped with the obvious broken inner product.

Surface finite element space. We now restrict to Lagrangian finite elements over a polygonal reference finite element. Here we assume that the degrees of freedom for each element (K, P, Σ) are given by

$$\Sigma = \{\chi \mapsto \chi(a) : a \in \mathcal{N}^K\},$$

where \mathcal{N}^K is a finite set of nodes in K . We call \mathcal{N}^K the set of *Lagrange nodes* of K . This restriction avoids difficulties in defining the edge of elements and how to effectively bring elements together to form a global finite element space. Extensions to other element types such as Hermite elements are left to future work.

Finally, the set of degrees of freedom of adjacent surface finite elements will be related as follows. Let (K, P, Σ) and (K', P', Σ') be two surface finite elements such that K and K' are adjacent with $\Sigma = \{\chi \mapsto \chi(a), a \in \mathcal{N}^K\}$ and $\Sigma' = \{\chi \mapsto \chi(a'), a' \in \mathcal{N}^{K'}\}$. Then, we have

$$(6.20) \quad \left(\bigcup_{a \in \mathcal{N}^K} a \right) \cap K' = \left(\bigcup_{a' \in \mathcal{N}^{K'}} a' \right) \cap K.$$

We denote the *global set of Lagrange nodes* by

$$(6.21) \quad \mathcal{N}_h = \bigcup_{K \in \mathcal{T}_h} \mathcal{N}^K.$$

For each $a \in \mathcal{N}_h$, let $\mathcal{T}(a) \subset \mathcal{T}_h$ be the local neighbourhood of elements for which $a \in \mathcal{N}^K$.

Definition 6.19 (Surface finite element space). (a) Let Γ_h be a discrete hypersurface equipped with a conforming subdivision \mathcal{T}_h with each domain K equipped with a surface finite element (K, P^K, Σ^K) (Def. 6.1) which satisfy (6.20). A *surface finite element space* is a (generally proper) subset of the product space $\prod_{K \in \mathcal{T}_h} P^K$ given by

$$\mathcal{S}_h := \left\{ \chi_h = (\chi_K)_{K \in \mathcal{T}_h} \in \prod_{K \in \mathcal{T}_h} P^K : \right. \\ \left. \chi_K(a) = \chi_{K'}(a), \text{ for all } K, K' \in \mathcal{T}(a), \text{ for all } a \in \mathcal{N}_h \right\}.$$

(b) The surface finite element space is determined by the *global degrees of freedom*

$$\Sigma_h = \{ \chi_h \mapsto \chi_h(a) : a \in \mathcal{N}_h \}.$$

In this definition, an element $\chi_h \in \mathcal{S}_h$ is not, in general a “function” defined over $\bar{\Gamma}_h$, since we do not necessarily have a good definition of χ_h over element boundaries: The “function” may be double-valued.

If it happens, however, that for each element $\chi_h \in \mathcal{S}_h$, the restrictions χ_K and $\chi_{K'}$ coincide along the common face of any adjacent elements K and K' , then the function χ_h can be identified with a function defined over the set $\bar{\Gamma}_h$. In this case, we call the elements $\chi_h \in \mathcal{S}_h$ *surface finite element functions*. Examples of surface finite element functions are shown in Fig. 6.2.

Lemma 6.20. *Let \mathcal{S}_h be a surface finite element space consisting of surface element elements over a conforming subdivision \mathcal{T}_h of Γ_h . Assume further that for each $K \in \mathcal{T}_h$, the corresponding reference finite element is a Lagrange element of order $k \geq 1$ (Ex. 4.2). Then we can identify elements of \mathcal{S}_h as functions in $C(\Gamma_h)$. Furthermore \mathcal{S}_h is a closed subspace in $H_T^1(\mathcal{T}_h)$.*

Proof. Consider two adjacent elements $K, K' \in \mathcal{T}_h$ and a element $\chi_h \in \mathcal{S}_h$. The functions $\chi_K \circ F_K$ and $\chi_{K'} \circ F_{K'}$ when restricted to the appropriate edges in \hat{K} are polynomials of degree k which agree at the Lagrange points on this edge from (6.20) and the definition of \mathcal{S}_h . The Lagrange points in the reference element determine polynomials of degree k so we have that $\chi_K = \chi_{K'}$ on $K \cap K'$. Since \mathcal{T}_h is a conforming subdivision we can define a global function $\chi_h: \bar{\Gamma}_h \rightarrow \mathbb{R}$ such that $\chi_h|_K = \chi_K$ for each $K \in \mathcal{T}_h$ which is globally continuous. Indeed χ_h restricted to each element is continuous, as the composition of a polynomial (element of $\hat{P} = P_k(\hat{K})$ for some k) and a smooth surface finite element reference map F_K , and is single valued on the facets where any two elements meet.

In fact the restriction $\chi_h|_K$ to each element $K \in \mathcal{T}_h$ is a C^1 -function hence $\chi_h|_K \in H^1(K)$ so it is clear that $\mathcal{S}_h \subset H_T^1(\mathcal{T}_h)$. The space \mathcal{S}_h is closed since it is finite dimensional. \square

We enumerate the nodes so that $\mathcal{N}_h = \{a_i\}_{i=1}^N$ and take $\{\chi_i\}_{i=1}^N$ to be the basis of \mathcal{S}_h dual to Σ_h . Since, we have a finite basis of \mathcal{S}_h we note that we can identify any $\chi_h \in \mathcal{S}_h$ with a vector $\gamma \in \mathbb{R}^N$ so that

$$\chi_h(x) = \sum_{i=1}^N \gamma_i \chi_i(x) \quad \text{for } x \in \Gamma_h.$$

Definition 6.21 (Interpolation). If η is a function on Γ_h for which all $\sigma_i(\eta)$, $1 \leq i \leq N$, is well defined (in case of Lagrangian finite elements, $\eta \in C(\Gamma_h)$ suffices), then we can

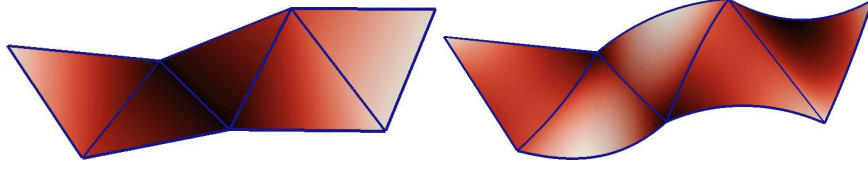


FIGURE 6.2. Examples of finite element functions. Left shows a piecewise linear function over a collection of affine finite elements (c.f. Ex. 6.7(a)) and right shows a piecewise quadratic function over a collection of isoparametric (quadratic) finite elements (c.f. Ex. 6.7(b)).

define a *global interpolant* $I_h \eta \in \mathcal{S}_h$ by

$$I_h \eta := \sum_{i=1}^N \sigma_i(\eta) \chi_i.$$

Note that our construction implies that

$$(I_h \eta)|_K = I_K \eta|_K \text{ for all } K \in \mathcal{T}_h,$$

and $I_h \chi_h = \chi_h$ for all $\chi_h \in \mathcal{S}_h$.

In order to prove estimates on the global interpolant, we will first define three further properties of our subdivision \mathcal{T}_h .

Definition 6.22 (Regular and quasi-uniform subdivisions). For $h \in (0, h_0)$, let Γ_h be a triangulated hypersurface (Def. 6.14(a)) equipped with a conforming subdivision \mathcal{T}_h (Def. 6.14(d)).

- (a) The family is said to be *non-degenerate* or *regular* if there exists $\rho_{\text{reg}} > 0$ such that for all $K \in \mathcal{T}_h$ and all $h \in (0, h_0)$,

$$\rho_K \geq \rho_{\text{reg}} h_K,$$

and there exists a constant $C > 0$ such that

$$\sup_{h \in (0, h_0)} \max_{K \in \mathcal{T}_h} C_K \leq C < 1.$$

- (b) The family is said to be Θ -*regular* if it is regular, if for all $h \in (0, h_0)$ and all $K \in \mathcal{T}_h$, $F_K \in C^{\Theta+1}(K; \mathbb{R}^{n+1})$, and if, there exists a constant $C > 0$ such that

$$\sup_{h \in (0, h_0)} \max_{K \in \mathcal{T}_h} C_m(K) \leq C < +\infty \quad \text{for } 2 \leq m \leq \Theta + 1.$$

This implies that F_K is a Θ -reference surface finite element map for each $K \in \mathcal{T}_h$.

- (c) A regular family is said to be *quasi-uniform* if there exists $\rho > 0$ such that

$$\min\{\rho_K : K \in \mathcal{T}_h\} \geq \rho h \quad \text{for all } h \in (0, h_0).$$

Remark 6.23. We note that:

- for a regular subdivision there exists a constant $c > 0$ depending on the global quantities $\hat{\rho}$, \hat{h} and ρ_{reg}

$$\|A_K\| \leq ch_K \leq ch \quad \text{and} \quad \|A_K^\dagger\| \leq ch_K^{-1},$$

- for a quasi-uniform subdivision there exists a constant $c > 0$ depending on the global quantities $\hat{\rho}$, \hat{h} and ρ

$$\|A_K\| \leq ch \quad \text{and} \quad \|A_K^\dagger\| \leq ch^{-1}.$$

Theorem 6.24 (Global interpolation estimates). *For $h \in (0, h_0)$, let Γ_h be a triangulated hypersurface (Def. 6.14(a)) equipped with a Θ -regular (Def. 6.22(b)), quasi-uniform (Def. 6.22(c)), conforming (Def. 6.14(d)) subdivision \mathcal{T}_h . Let each $K \in \mathcal{T}_h$ be equipped with a Θ -surface finite element (K, P^K, Σ^K) (Def. 6.4) parametrised over a reference finite element $(\hat{K}, \hat{P}, \hat{\Sigma})$ which satisfies the assumptions of Thm. 6.13 for some $0 < k, m \leq \Theta$, $p, q \in [1, \infty]$. Then there exists a constant $C = C(\hat{K}, \hat{P}, \hat{\Sigma}, \rho)$ such that for all functions $\eta \in W^{k+1,p}(\mathcal{T}_h) \cap C(\Gamma_h)$,*

$$(6.22) \quad \|\eta - I_h \eta\|_{W^{m,q}(\mathcal{T}_h)} \leq Ch^{k+1-m} \|\eta\|_{W^{k+1,p}(\mathcal{T}_h)}.$$

Proof. The proof follows by piecing together Thm. 6.13 using the fact that \mathcal{T}_h is quasi-uniform. \square

6.3. Evolving surface finite elements. Let $t \in [0, T]$. We consider families of surface finite elements, spaces and triangulated hypersurfaces parametrised by t .

Definition 6.25 (Evolving surface finite element). (a) Let $(K(t), P(t), \Sigma(t))_{t \in [0, T]}$ be a time dependent family of surface finite elements (Def. 6.1) parametrised over a common reference element $(\hat{K}, \hat{P}, \hat{\Sigma})$. If the constant $C_K = \sup_t C_{K(t)}$ is uniformly bounded away from 1,

$$C_K := \max_{t \in [0, T]} \sup_{\hat{x} \in \hat{K}} \left\| \nabla D_K(\hat{x}, t) A_K^\dagger(t) \right\| < c < 1,$$

we say that $(K(t), P(t), \Sigma(t))_{t \in [0, T]}$ is an *evolving surface finite element*.

(b) Let $\Phi_{(\cdot)}^K \in C^2([0, T], C^1(K_0))$ where $K_0 := K(0)$. We say that if $\Phi_t^K : K_0 := K(0) \rightarrow K(t)$ such that

$$(6.23) \quad F_{K(t)}(\hat{x}) = \Phi_t^K(F_{K_0}(\hat{x})) \quad \text{for } \hat{x} \in \hat{K}$$

then Φ_t^K is the *flow* defining the evolution of the element domain and that $F_{K(t)}$ is the *evolving surface element reference map*.

(c) The *element velocity* W_K of $K(t)$ is defined by

$$W_K(\Phi_t^K(x), t) = \frac{d}{dt} \Phi_t^K(x) \quad \text{for } x \in K_0, t \in [0, T].$$

(d) If each $(K(t), P(t), \Sigma(t))$ is a Θ -surface finite element for each $t \in [0, T]$ and the constants $C_m(K(t))$ are uniformly bounded:

$$\sup_{t \in [0, T]} C_m(K(t)) \leq c < \infty \quad \text{for } 2 \leq m \leq \Theta + 1$$

then we say that $(K(t), P(t), \Sigma(t))_{t \in [0, T]}$ is an *evolving Θ -surface finite element* and $F_{K(t)}$ is the *evolving Θ -surface element reference map*.

(e) We say that an evolving finite element domain is *temporally quasi-uniform*, if there exists $\rho_K > 0$ such that

$$\inf\{\rho_{K(t)} : t \in [0, T]\} \geq \rho_K \sup\{h_{K(t)} : t \in [0, T]\}.$$

(f) The family of *element push forward maps* ϕ_t^K , indexed by $t \in [0, T]$, is defined to be the linear invertible map given for $\chi : K_0 \rightarrow \mathbb{R}$ by $\phi_t^K(\chi) : K(t) \rightarrow \mathbb{R}$ where

$$\phi_t^K(\chi)(x) = \chi(\Phi_{-t}^K(x)) \quad \text{for } x \in K(t).$$

Lemma 6.26. *Let $F_{K(t)}: \hat{K} \rightarrow K(t)$, for $t \in [0, T]$, be an evolving Θ -surface finite element reference map (Def. 6.25(d)) for a temporally quasi-uniform element domain $K(t)$ (Def. 6.25(e)) and ϕ_t^K the family of element push forward maps (Def. 6.25(f)). Then there exists constant $c_1, c_2 > 0$ which depend only on the reference element domain \hat{K} , and the constant $C_K, C_1, \dots, C_\Theta$ and ρ_K , such that for $0 \leq m \leq \Theta$ and all $t \in [0, T]$, $\chi \in W^{m,p}(K_0)$ if, and only if, $\phi_t^K \chi \in W^{m,p}(K(t))$ and*

$$(6.24) \quad c_1 \|\chi\|_{W^{m,p}(K_0)} \leq \|\phi_t^K \chi\|_{W^{m,p}(K(t))} \leq c_2 \|\chi\|_{W^{m,p}(K_0)} \quad \text{for all } \chi \in W^{m,p}(K_0).$$

Proof. From Lem. 6.9 and 6.12, we have

$$\|\chi\|_{W^{m,p}(K_0)} \leq c \left(\frac{\text{meas}(K(t))}{\text{meas}(K_0)} \right)^{1/p} \|\phi_t^K \chi\|_{W^{m,p}(K(t))} \sum_{r=1}^m \left(\frac{h_{K(t)}}{\rho_{K_0}} \right)^r$$

and

$$\|\phi_t^K \chi\|_{W^{m,p}(K(t))} \leq c \left(\frac{\text{meas}(K_0)}{\text{meas}(K(t))} \right)^{1/p} \|\chi\|_{W^{m,p}(K_0)} \sum_{r=1}^m \left(\frac{h_{K_0}}{\rho_{K(t)}} \right)^r.$$

It can be easily seen that for a quasi-uniform evolving surface finite element that these constants only depend on allowed quantities. \square

This result implies that $(W^{m,p}(K(t)), \phi_t^K|_{W^{m,p}(K_0)})_{t \in [0, T]}$ is a compatible pair (Def. 2.2) and in particular $(P(t), \phi_t^K|_{P(0)})$ is a compatible pair when equipped with the $W^{m,p}(K(t))$ -norm (as $P(t)$ is a closed subspace of $W^{m,p}(K(t))$, Rem. 2.3 and Rem. 6.5(c)).

6.4. Evolving surface finite element spaces. We now formulate an evolving surface finite element space forming part of a compatible pair (in the sense of Sec. 2, Def. 2.2). For each $h \in (0, h_0)$, we are given a family of discrete hypersurfaces $\{\Gamma_h(t)\}_{t \in [0, T]}$ and each equipped with a surface finite element space $\{\mathcal{S}_h(t)\}_{t \in [0, T]}$. Furthermore, we are interested in under what assumptions does the compatibility hold independently of the mesh size h .

Definition 6.27 (Evolving triangulated hypersurface). For $t \in [0, T]$, let $\Gamma_h(t)$ be a family of triangulated hypersurfaces (Def. 6.14(a)) each equipped with a conforming subdivision $\mathcal{T}_h(t)$ (Def. 6.14(d)) such that each element domain $K(t) \in \mathcal{T}_h(t)$ is equipped with an element flow map $\Phi_{(\cdot)}^K \in C^2([0, T]; C^1(K_0))$ (Def. 6.25(b)).

- (a) We call $\{\mathcal{T}_h(t)\}_{t \in [0, t]}$ an *evolving conforming subdivision* if for each element $K(0) \in \mathcal{T}_h(0)$ and each facet $E(0)$ of $K(0)$ either $E(0)$ is a facet of another element $K'(0) \in \mathcal{T}_h(0)$, in which case $E(t)$ is a common facet between $K(t)$ and $K'(t)$ for all $t \in [0, T]$ or $E(0)$ is a portion of the boundary $\partial\Omega(0)$, in which case $E(t)$ is a portion of the boundary $\partial\Omega(t)$ for all $t \in [0, T]$.
- (b) An *evolving triangulated hypersurface* is defined to be a family of triangulated hypersurfaces $\{\Gamma_h(t)\}_{t \in [0, T]}$ equipped with an evolving conforming subdivision. In this case, we define the mesh parameter h to be

$$(6.25) \quad h := \sup_{t \in [0, T]} \max_{K(t) \in \mathcal{T}_h(t)} h_{K(t)}.$$

- (c) We define a *global discrete flow* $\Phi_{(\cdot)}^h(\cdot): [0, T] \times \Gamma_{h,0} \rightarrow \mathbb{R}^{n+1}$ element-wise by

$$\Phi_t^h|_{K_0} := \Phi_t^K \quad \text{for } K_0 \in \mathcal{T}_h(0).$$

Our assumptions imply that Φ_t^h is piecewise smooth and $\Phi_t^h: \Gamma_{h,0} \rightarrow \Gamma_h(t)$.

(d) We define a *global discrete velocity* W_h given by

$$W_h|_{K(t)} = W_K.$$

(e) The family of linear homeomorphisms induced by the flow Φ_t^h and called the *global push forward map* is denoted by $\phi_t^h(\eta_h): \Gamma_h(t) \rightarrow \mathbb{R}$ for $\eta_h: \Gamma_{h,0} \rightarrow \mathbb{R}$ and defined by

$$(\phi_t^h \eta_h)|_{K(t)} := \phi_t^K(\eta_h|_{K_0}) \quad \text{for all } K(t) \in \mathcal{T}_h(t).$$

Again, in order to bring together a collection of evolving surface finite elements we restrict to Lagrangian surface finite elements. For each $t \in [0, T]$, we denote by $\mathcal{N}_h(t)$ the global set of Lagrange nodes of $\Gamma_h(t)$ (6.21) and for any $a \in \mathcal{N}_h(t)$, $\mathcal{T}(a)$ is the set of elements $K(t)$ such that a is a node of $K(t)$. We make the further restriction that the global flow is single-valued at each Lagrange point: for all $a_0 \in \mathcal{N}_h(0)$ we have

$$(6.26) \quad \Phi_t^K(a_0) = \Phi_t^{K'}(a_0) \quad \text{for all } K, K' \in \mathcal{T}(a_0).$$

Definition 6.28 (Evolving surface finite element space). (a) Let $\{\Gamma_h(t)\}_{t \in [0, T]}$ be an evolving triangulated hypersurface (Def. 6.27(b)) equipped with an evolving conforming subdivision $\{\mathcal{T}_h(t)\}_{t \in [0, T]}$ (Def. 6.27(a)). For $t \in [0, T]$, let $\mathcal{S}_h(t)$ be a surface finite element space (Def. 6.19(a)) over $\Gamma_h(t)$. If each $K(t) \in \mathcal{T}_h(t)$ is equipped with an evolving surface finite element $(K(t), P(t), \Sigma(t))_{t \in [0, T]}$ (Def. 6.25(a)) then we say $\{\mathcal{S}_h(t)\}_{t \in [0, T]}$ is an *evolving surface finite element space*. (b) For each $t \in [0, T]$, we will write $\Sigma_h(t)$ for the set of global nodal variables (Def. 6.19(b)). We will use the convention that

$$\Sigma_h(t) = \{\chi_h \mapsto \chi_h(a_i(t)) : 1 \leq i \leq N\},$$

where $a_i(t)$ is the trajectory of a Lagrange point under the global flow Φ_t^h . We will denote by $\{\chi_i(\cdot, t) : 1 \leq i \leq N\}$ the global basis of finite element functions such that $\chi_i(a_j(t), t) = \delta_{ij}$ for $t \in [0, T]$ and all $i, j = 1, \dots, N$. This implies that $\chi_i(\cdot, t) = \phi_t^h(\chi_i(\cdot, 0))$. See also (3.4).

Definition 6.29 (Uniformly regular and uniformly quasi-uniform evolving subdivisions). For $h \in (0, h_0)$, let $\{\mathcal{T}_h(t)\}_{t \in [0, T]}$ be a family of evolving conforming subdivisions (Def. 6.27(a)).

(a) We say that the family is *uniformly regular* if there exists $\rho > 0$ such that for all $h \in (0, h_0)$ and all times $t \in [0, T]$, we have

$$\rho_{K(t)} \geq \rho h_{K(t)} \quad \text{for all } K(t) \in \mathcal{T}_h(t),$$

and there exists $C > 0$ such that

$$\sup_{h \in (0, h_0)} \sup_{t \in [0, T]} \max_{K(t) \in \mathcal{T}_h(t)} C_{K(t)} \leq C < 1.$$

(b) We say that the family is *uniformly Θ -regular* if it is uniformly regular, if for each time $t \in [0, T]$, the family $\{\mathcal{T}_h(t)\}_{h \in (0, h_0)}$ is Θ -regular and if there exists a constant such that

$$\sup_{h \in (0, h_0)} \sup_{t \in [0, T]} \max_{K(t) \in \mathcal{T}_h(t)} C_m(K(t)) \leq C \leq +\infty \quad \text{for } 2 \leq m \leq \Theta + 1.$$

This implies that $F_{K(t)}$ is an evolving Θ -reference finite element map for each $K(t) \in \mathcal{T}_h(t)$.

(c) We say that the family is *uniformly quasi-uniform* if there exists $\rho > 0$ such that for all $h \in (0, h_0)$ and all times $t \in [0, T]$, we have

$$\min\{\rho_{K(t)} : K(t) \in \mathcal{T}_h(t)\} \geq \rho h.$$

Note that a uniformly quasi-uniform subdivision consists of element domains for temporally quasi-uniform evolving surface finite element domains.

Lemma 6.30. *For $h \in (0, h_0)$, let $\{\mathcal{T}_h(t)\}_{t \in [0, T]}$ be a uniformly Θ -regular (Def. 6.29(b)), uniformly quasi-uniform (Def. 6.29(c)), evolving, conforming subdivision (Def. 6.27(a)) and let ϕ_t^h be the global push-forward map (Def. 6.27(e)). Let $0 \leq k \leq \Theta + 1$, $p \in [0, \infty]$. Then $\eta_h \in W^{m,p}(\mathcal{T}_h(0))$ if and only if $\phi_t^h \eta_h \in W^{m,p}(\mathcal{T}_h(t))$ for all $t \in [0, T]$. Furthermore, there exists $c_1, c_2 > 0$ independent of $h \in (0, h_0)$ and $t \in [0, T]$ such that for all $\eta_h \in W^{m,p}(\mathcal{T}_h(t))$*

$$(6.27) \quad c_1 \|\eta_h\|_{W^{m,p}(\mathcal{T}_h(0))} \leq \left\| \phi_t^h \eta_h \right\|_{W^{k,p}(\mathcal{T}_h(t))} \leq c_2 \|\eta_h\|_{W^{m,p}(\mathcal{T}_h(0))}.$$

Remark 6.31. This implies that $(W^{m,p}(\mathcal{T}_h(t)), \phi_t^h|_{W^{m,p}(\mathcal{T}_h(0))})_{t \in [0, T]}$ is a compatible pair. In particular the pairs $(\mathcal{S}_h(t), \phi_t^h)_{t \in [0, T]}$, equipped with the broken Sobolev norm $\|\cdot\|_{W^{m,p}(\mathcal{T}_h(t))}$ (Def. 6.16), and $(W_T^{1,p}(\mathcal{T}_h(t)), \phi_t^h)_{t \in [0, T]}$ are compatible since each is a closed subspace (Rem. 2.3 and Lem. 6.18 and 6.20).

Proof. We simply sum the element-wise result from Lem. 6.26. The constants are independent of h_K and ρ_K due to the uniform quasi-uniformity of $\{\mathcal{T}_h(t)\}$. \square

Note that this result implies that the spaces $L_{\mathcal{S}_h}^2$ and $C_{\mathcal{S}_h}^1$ are well defined when equipped with the appropriate norms (c.f. (2.1) and (2.2)).

7. LIFTED SURFACE FINITE ELEMENT SPACES

So far we have only defined surface finite elements without relation to approximation of a smooth hypersurface Γ and function spaces on Γ through the definition of a lifted finite element space $\mathcal{S}_h^\ell(t)$. In general, due to the curvature of the surface, the computational domain Γ_h will be an approximation to Γ . We will identify surface finite elements (K, P, Σ) on Γ_h with a corresponding curved surface finite elements $(K^\ell, P^\ell, \Sigma^\ell)$ on Γ using a mapping $\Lambda_K: K \rightarrow \Gamma$. We call this process *lifting*. This provides a convenient way to compare the smooth functions (solutions to PDEs) on Γ with the lift of discrete functions on Γ_h . We will also require an inverse lift that maps functions on the smooth domain to the computational domain.

In the following, we will answer the question what assumptions on Λ_K must be made so that $(K^\ell, P^\ell, \Sigma^\ell)$ is a Θ -surface finite element and how we can put several such *lifted* surface finite elements together in order to recover Γ and finite element spaces on Γ . We will also explore some interpolation results when these assumptions hold. Finally, we explore how we can lift the discrete push forward map.

7.1. Lifted surface finite element. We consider the situation of a surface finite element (K, P, Σ) (Def. 6.1), with element reference map $F_K: \hat{K} \rightarrow K$, where the element domain approximates a portion of Γ .

Let $\Lambda_K: K \rightarrow \Gamma$ be a C^1 -map which is a diffeomorphism onto its image. For a function $\chi: K \rightarrow \mathbb{R}$, we call χ^ℓ defined by $\chi^\ell(\Lambda_K(\cdot)) = \chi(\cdot)$ the *lift* of χ . We will assume that we can decompose Λ_K into

$$\Lambda_K(x) = A_\Lambda x + b_\Lambda + \tilde{\Lambda}_K(x) \quad \text{for } x \in K,$$

where A_Λ is an invertible $(n+1) \times (n+1)$ matrix, $b_\Lambda \in \mathbb{R}^{n+1}$ and $\tilde{\Lambda}_K \in C^1(K, \mathbb{R}^{n+1})$. We will assume that $\tilde{\Lambda}_K$ does affect the affine part of the parametrisations:

$$A_{K^\ell} \hat{x} + b_{K^\ell} = A_\Lambda (A_K \hat{x} + b_K) + b_\Lambda \quad \text{for all } \hat{x} \in \hat{K}.$$

Definition 7.1 (Lifted surface finite element). We call the triple $(K^\ell, P^\ell, \Sigma^\ell)$ defined by

$$\begin{aligned} K^\ell &:= \Lambda_K(K) \subset \Gamma \\ P^\ell &:= \{\chi^\ell(\Lambda_K(\cdot)) := \chi(\cdot) : \chi \in P\} \\ \Sigma^\ell &:= \{\sigma^\ell := \chi^\ell \mapsto \sigma(\chi) : \sigma \in \Sigma\}, \end{aligned}$$

the *lift* of (K, P, Σ) and Λ_K the *lifting map*. If $(K^\ell, P^\ell, \Sigma^\ell)$ forms a surface finite element over $(\hat{K}, \hat{P}, \hat{\Sigma})$ then we say that $(K^\ell, P^\ell, \Sigma^\ell)$ is the *lifted surface finite element associated with* (K, P, Σ) . In this case we call $F_{K^\ell}(\cdot) = \Lambda_K(F_K(\cdot))$ the *lifted surface finite element reference map*.

The next two results show under what assumptions on Λ_K is $(K^\ell, P^\ell, \Sigma^\ell)$ a surface finite element (Def. 6.1) or a Θ -surface finite element (Def. 6.4).

Lemma 7.2. *If Λ_K satisfies that*

$$(7.1) \quad \sup_{x \in K} \left\| \nabla_K \tilde{\Lambda}(x) \right\| \leq \frac{\|A_\Lambda^{-1}\|^{-1} - C_K \|A_\Lambda\|}{1 + C_K},$$

then $(K^\ell, P^\ell, \Sigma^\ell)$ is a surface finite element. Furthermore, for $p \in [1, \infty]$, we have that there exists $c_1, c_2 > 0$ such that

$$(7.2) \quad \begin{aligned} c_1 \|\chi\|_{L^p(K)} &\leq \left\| \chi^\ell \right\|_{L^p(K^\ell)} \leq c_2 \|\chi\|_{L^p(K)} && \text{for all } \chi \in L^p(K) \\ c_1 \|\chi\|_{W^{1,p}(K)} &\leq \left\| \chi^\ell \right\|_{W^{1,p}(K^\ell)} \leq c_2 \|\chi\|_{W^{1,p}(K)} && \text{for all } \chi \in W^{1,p}(K), \end{aligned}$$

where the constants c_1, c_2 depend on $C_K, \|A_\Lambda^{-1}\|$ and the ratio h_K/ρ_K .

Proof. To show that $(K^\ell, P^\ell, \Sigma^\ell)$ is a surface finite element (Def. 6.1), the conditions on the element reference map $F_{K^\ell}(\hat{x}) = \Lambda_K(F_K(\hat{x}))$ are clear and we are left to check the curvedness condition (6.1). Using the expansion of Λ_K , we see

$$\begin{aligned} A_{K^\ell} &= A_\Lambda A_K, \quad A_{K^\ell}^\dagger = A_K^\dagger A_\Lambda^{-1}, \quad b_{K^\ell} = A_\Lambda b_K + b_\Lambda \\ &\text{and} \quad D_{K^\ell}(\hat{x}) = A_\Lambda D_K(\hat{x}) + \tilde{\Lambda}_K(F_K(\hat{x})). \end{aligned}$$

So that

$$\nabla D_{K^\ell}(\hat{x}) A_{K^\ell}^\dagger = A_\Lambda \nabla D_K(\hat{x}) A_K^\dagger A_\Lambda^{-1} + \nabla_K \tilde{\Lambda}_K(F_K(\hat{x})) (\text{Id} + \nabla D_K(\hat{x}) A_K^\dagger) A_K A_K^\dagger A_\Lambda^{-1}.$$

Applying the curvedness condition for K and the fact that $A_K A_K^\dagger$ is a projection (Rem. 6.3(c)) applied to the flat element \tilde{K} we see

$$\left\| \nabla D_{K^\ell}(\hat{x}) A_{K^\ell}^\dagger \right\| \leq C_K \|A_\Lambda\| \|A_\Lambda^{-1}\| + (1 + C_K) \left\| \nabla_K \tilde{\Lambda}_K(F_K(\hat{x})) \right\| \|A_\Lambda^{-1}\|.$$

The curvedness condition is shown by applying (7.1).

To show (7.2) the result is clear for $p = \infty$. For $p < \infty$, we will apply Lem. 6.12. Then we see

$$c \left(\frac{\text{meas}(K)}{\text{meas}(K^\ell)} \right)^{1/p} \|\chi\|_{L^p(K)} \leq \left\| \chi^\ell \right\|_{L^p(K^\ell)} \leq c \left(\frac{\text{meas}(K^\ell)}{\text{meas}(K)} \right)^{1/p} \|\chi\|_{L^p(K)},$$

where c depends on C_K and the bound (7.1). For the higher order bound, we note that

$$\|A_K\| = \|A_\Lambda^{-1} A_\Lambda A_K\| \leq \|A_\Lambda^{-1}\| \|A_\Lambda A_K\| = \|A_{\Lambda^{-1}}\| \|A_{K^\ell}\|,$$

so that we infer

$$(7.3) \quad \|A_{K^\ell}\| \geq \frac{\|A_K\|}{\|A_{\Lambda^{-1}}\|}.$$

Then applying [Lem. 6.12](#) once more we see

$$\begin{aligned} c \left(\frac{\text{meas}(K)}{\text{meas}(K^\ell)} \right)^{1/p} \frac{\|A_\Lambda^{-1}\|}{\|A_K\| \|A_K^\dagger\|} |\chi|_{W^{1,p}(K)} &\leq \|\chi^\ell\|_{W^{1,p}(K^\ell)} \\ &\leq c \left(\frac{\text{meas}(K^\ell)}{\text{meas}(K)} \right)^{1/p} \|A_\Lambda^{-1}\| \|A_K\| \|A_K^\dagger\| |\chi|_{W^{1,p}(K)}. \end{aligned}$$

The final result is given by applying [\(7.4c\)](#), [\(6.9a\)](#) and [\(6.9b\)](#). \square

Lemma 7.3. *If (K, P, Σ) is a Θ -surface finite element and Λ_K satisfies $\Lambda_K \in C^{\Theta+1}(K; \mathbb{R}^{n+1})$ and $\|\Lambda_K\|_{W^{\Theta+1,\infty}(K)} \leq c$, then $(K^\ell, P^\ell, \Sigma^\ell)$ is also a Θ -surface finite element. Furthermore, for $0 \leq m \leq \Theta + 1$ and $p \in [1, \infty]$, we have that there exists $c_1, c_2 > 0$ such that*

$$c_1 \|\chi\|_{W^{m,p}(K)} \leq \|\chi^\ell\|_{W^{m,p}(K^\ell)} \leq c_2 \|\chi\|_{W^{m,p}(K)} \quad \text{for all } \chi \in W^{m,p}(K),$$

where the constants c_1, c_2 depend on $C_1(K), \dots, C_m(K)$, $\|A_\Lambda^{-1}\|$ and the ratio h_K/ρ_K .

Proof. To see that $(K^\ell, P^\ell, \Sigma^\ell)$ is a Θ -surface finite element ([Def. 6.4](#)), the first three conditions are clear from the smoothness assumption on Λ_K . We must show [\(6.3\)](#) holds: for $2 \leq m \leq \Theta + 1$, there exists a constant $C_m(K^\ell)$ such that

$$\|\nabla^m F_{K^\ell}(\hat{x})\| \leq C_m(K^\ell) \|A_{K^\ell}\|^m.$$

Computing directly using the Faà di Bruno formula [\(A.1\)](#), we have

$$\frac{\partial^{r'}}{\partial \hat{x}_{j_m} \dots \partial \hat{x}_{j_1}} F_{K^\ell}(\hat{x}) = \sum_{r=1}^m \sum_{\lambda_1, \dots, \lambda_r=1}^{n+1} (\nabla_K)_{\lambda_r} \dots (\nabla_K)_{\lambda_1} \Lambda_K(F_K(\hat{x})) \sum_{\mathbb{P}(m,r)} \prod_{s=1}^r \frac{\partial^{|\sigma_s|}}{\partial \hat{x}_{j_{\sigma_s}}} (F_K)_{\lambda_s}(\hat{x}).$$

But applying the fact that (K, P, Σ) is a Θ -surface finite element and the smoothness assumption on Λ_K , we see that

$$|\nabla^m F_{K^\ell}(\hat{x})| \leq c(C_1(K), \dots, C_m(K)) \sum_{r=1}^m |\Lambda_K|_{W^{r,\infty}(K)} \|A_K\|^m.$$

Finally, applying [\(7.3\)](#), we have that

$$\|\nabla^m F_{K^\ell}(\hat{x})\| \leq \|\Lambda_K\|_{W^{m,\infty}(K)} \|A_{K^\ell}\|^m \|A_\Lambda^{-1}\|^m.$$

This shows that $(K^\ell, P^\ell, \Sigma^\ell)$ is a Θ -surface finite element.

To show the norm equivalence we again apply [Lem. 6.12](#), recognising the geometric progression, to see

$$\begin{aligned} c \left(\frac{\text{meas}(K)}{\text{meas}(K^\ell)} \right) \frac{A_1^{m+1} - 1}{A_1 - 1} \|\chi\|_{W^{m,p}(K)} &\leq \|\chi^\ell\|_{W^{m,p}(K^\ell)} \\ &\leq c \left(\frac{\text{meas}(K^\ell)}{\text{meas}(K)} \right) \frac{A_2^{m+1} - 1}{A_2 - 1} \|\chi\|_{W^{m,p}(K)}, \end{aligned}$$

where

$$A_1 = \|A_K\| \|A_K^\dagger\| \|A_\Lambda\| \quad \text{and} \quad A_2 = \|A_K\| \|A_K^\dagger\| \|A_\Lambda^{-1}\|.$$

The final result is given by applying [\(7.4c\)](#), [\(6.9a\)](#) and [\(6.9b\)](#). \square

Remark 7.4. Considering the case that Λ_K fixes the vertices of K then we can write Λ_K as

$$\Lambda_K(x) = x + \tilde{\Lambda}(x) \quad \text{for } x \in K.$$

That is that $A_\Lambda = \text{Id}$ and $b_\Lambda = 0$. Then the assumptions of [Lem. 7.2](#) can be replaced by

$$\sup_{x \in K} \left\| \nabla_K \tilde{\Lambda}(x) \right\| \leq \frac{1 - C_K}{1 + C_K},$$

and the assumptions of [Lem. 7.3](#) can be replaced by the assumption that $\|\Lambda_K\|_{W^{0,\infty}(K)}$ is uniformly bounded.

We next relate the geometry of the base and lifted element domains.

Lemma 7.5. *Using the decomposition of Λ_K , we have*

$$(7.4a) \quad \|A_\Lambda^{-1}\|^{-1} h_K \leq h_{K^\ell} \leq \|A_\Lambda\| h_K$$

$$(7.4b) \quad \|A_\Lambda^{-1}\|^{-1} \rho_K \leq \rho_{K^\ell} \leq \|A_\Lambda\| \rho_K$$

$$(7.4c) \quad c_1 \left(\frac{\rho_K}{h_K} \right)^n \|A_\Lambda^{-1}\|^{-n} \text{meas}(K) \leq \text{meas}(K^\ell) \leq c_2 \left(\frac{h_K}{\rho_K} \right)^n \|A_\Lambda^{-1}\|^{-n} \text{meas}(K).$$

Proof. For [\(7.4a\)](#), we show the second inequality. The first follows by the same reasoning applied to the inverse of A_Λ . Since \tilde{K}^ℓ is compact, there exists $x^\ell, y^\ell \in \tilde{K}^\ell$ such that

$$h_{K^\ell} = |y^\ell - x^\ell|.$$

But since A_Λ is invertible, there exists $x, y \in \tilde{K}$ such that

$$A_\Lambda x + b_\Lambda = x^\ell \quad \text{and} \quad A_\Lambda y + b_\Lambda = y^\ell.$$

Then, we can compute that

$$h_{K^\ell} = |x^\ell - y^\ell| = |A_\Lambda(x - y)| \leq \|A_\Lambda\| |x - y| \leq \|A_\Lambda\| h_K.$$

Similarly, for [\(7.4b\)](#), we only show the first inequality. For each $\varepsilon > 0$, there exists B_ε a ball in \tilde{K} such that

$$\rho_K - \text{diam} B_\varepsilon \leq \varepsilon.$$

Denote by x_ε and r_ε the centre and radius of B_ε respectively. Consider the affine map $\Xi_\varepsilon: \mathbb{R}^{n+1} \rightarrow \mathbb{R}^{n+1}$ given by

$$\Xi_\varepsilon(x) = \frac{1}{\|A_\Lambda^{-1}\|} (x - x_\varepsilon) + b_\Lambda + A_\Lambda x_\varepsilon.$$

It is clear that Ξ_ε maps balls to balls and B_ε is mapped to a ball centred at $A_\Lambda x_\varepsilon + b_\Lambda$ with radius $r_\varepsilon / \|A_\Lambda^{-1}\|$. We claim $\Xi_\varepsilon(B_\varepsilon)$ is contained in \tilde{K}^ℓ . Indeed, take $x^\ell \in \Xi_\varepsilon(B_\varepsilon)$, then there exists $x \in B_\varepsilon$ such that $\Xi_\varepsilon(x) = x^\ell$. Denote by

$$x' = x_\varepsilon + \frac{1}{\|A_\Lambda^{-1}\|} A_\Lambda^{-1}(x - x_\varepsilon),$$

then

$$|x' - x_\varepsilon| = \frac{1}{\|A_\Lambda^{-1}\|} |A_\Lambda^{-1}(x - x_\varepsilon)| \leq |x - x_\varepsilon| \leq r_\varepsilon,$$

so $x' \in B_\varepsilon \subset \tilde{K}$ and

$$A_\Lambda x' + b_\Lambda = \frac{1}{\|A_\Lambda^{-1}\|} (x - x_\varepsilon) + A_\Lambda x_\varepsilon + b_\Lambda = x^\ell,$$

so that $x^\ell \in \tilde{K}^\ell = A_\Lambda \tilde{K} + b_K$.

Therefore, we have found a ball $\Xi_\varepsilon(B_\varepsilon) \subset \tilde{K}^\ell$ with radius $r_\varepsilon / (\|A_\Lambda^{-1}\|)$, thus we can infer that

$$\rho_{K^\ell} \geq \frac{1}{2} \|A_\Lambda^{-1}\|^{-1} \text{diam} B_\varepsilon \geq \|A_\Lambda^{-1}\|^{-1} (\rho_K - \varepsilon).$$

Since the proof holds for all $\varepsilon > 0$, we see the desired result.

Given (7.4a) and (7.4b), the final result (7.4c) follows directly from Rem. 6.10. \square

We can also use Λ_K to define an inverse lift. Given an element domain K , lifted element domain K^ℓ and lifting map Λ_K . We know that Λ_K is invertible onto its image, namely K^ℓ . So for $\eta: K^\ell \rightarrow \mathbb{R}$, we denote its inverse lift by $\eta^{-\ell}: K \rightarrow \mathbb{R}$ defined by

$$\eta^{-\ell}(x) := \eta(\Lambda_K(x)) \quad \text{for } x \in K.$$

Lemma 7.6. *If the assumptions of Lem. 7.2 and 7.3 hold then, for $0 \leq m \leq \Theta + 1$ and $p \in [1, \infty]$, we have that there exists $c_1, c_2 > 0$ such that for all $\eta \in W^{m,p}(K^\ell)$, we have*

$$c_1 \|\eta^{-\ell}\|_{W^{m,p}(K)} \leq \|\eta\|_{W^{m,p}(K^\ell)} \leq c_2 \|\eta^{-\ell}\|_{W^{m,p}(K)}.$$

Proof. The same proof can be applied to the case of the inverse lift as well as the usual lift. \square

7.2. Lifted surface finite element space. Let Γ be a smooth hypersurface and for $h \in (0, h_0)$ and let Γ_h be a triangulated hypersurface (Def. 6.14(a)) equipped with a conforming subdivision \mathcal{T}_h (Def. 6.14(d)) and a surface finite element space \mathcal{S}_h (Def. 6.19(a)). Let each $K \in \mathcal{T}_h$ be associated with a lifted finite element K^ℓ with lifted map Λ_K .

Definition 7.7. (a) We denote by \mathcal{T}_h^ℓ the set of all lifted element domains

$$\mathcal{T}_h^\ell := \bigcup_{K \in \mathcal{T}_h} K^\ell.$$

If the global map Λ_h is single valued and \mathcal{T}_h^ℓ forms a conforming subdivision of Γ , we say that \mathcal{T}_h^ℓ is an *exact* subdivision of the surface Γ . In this case we set \mathcal{F}_h^ℓ to be the set of facets between adjacent elements.

(b) We define a *global lifting map* $\Lambda_h: \Gamma_h \rightarrow \Gamma$ by $\Lambda_h|_K = \Lambda_K$. We define the inverse lift $\Lambda_h^{-1}: \Gamma \rightarrow \Gamma_h$ in a similar element-wise fashion by $\Lambda_h^{-1}|_{K^\ell} = \Lambda_K^{-1}$.

(c) We denote by λ_h the *global lift* given for $\eta_h: \Gamma_h \rightarrow \mathbb{R}$ by

$$\lambda_h(\eta_h)(\Lambda_h(x)) = \eta_h(x) \quad \text{for } x \in \Gamma_h,$$

and by ς_h the *global inverse lift* given for $\eta: \Gamma \rightarrow \mathbb{R}$ by

$$\varsigma_h(\eta)(x) = \eta(\Lambda_h(x)) \quad \text{for } x \in \Gamma_h.$$

We will also use the notation $\eta_h^\ell = \lambda_h(\eta_h)$ and $\eta^{-\ell} = \varsigma_h(\eta)$.

(d) If for each surface finite element (K, P, Σ) there is an associated lifted surface finite element $(K^\ell, P^\ell, \Sigma^\ell)$, then, we define a *lifted surface finite element space* (c.f. (3.17)) by

$$\mathcal{S}_h^\ell := \left\{ \chi_h^\ell : \chi_h \in \mathcal{S}_h \right\}.$$

Proposition 7.8. *Assume additionally that the family of triangulations $\{\mathcal{T}_h\}_{h \in (0, h_0)}$ is regular (Def. 6.22(a)), Λ_K satisfies the assumptions of Lem. 7.2 and there exists $C_1, C_2 > 0$ such that*

$$(7.5) \quad \|A_\Lambda\| \leq C_1 \quad \text{and} \quad \|A_\Lambda^{-1}\| \leq C_2 \quad \text{for all } K \in \mathcal{T}_h \text{ for all } h \in (0, h_0),$$

for all $K \in T_h$ for all $h \in (0, h_0)$. Then $\{\mathcal{T}_h^\ell\}_{h \in (0, h_0)}$ is regular and \mathcal{S}_h^ℓ is a surface finite element space and there exists constants $c_1, c_2 > 0$, which are independent of $h \in (0, h_0)$ such that

$$(7.6) \quad \begin{aligned} c_1 \|\eta_h\|_{L^p(\mathcal{T}_h)} &\leq \left\| \eta_h^\ell \right\|_{L^p(\mathcal{T}_h^\ell)} \leq c_2 \|\eta_h\|_{L^p(\mathcal{T}_h)} && \text{for all } \eta_h \in L^p(\mathcal{T}_h) \\ c_1 \|\eta_h\|_{W^{1,p}(\mathcal{T}_h)} &\leq \left\| \eta_h^\ell \right\|_{W^{1,p}(\mathcal{T}_h^\ell)} \leq c_2 \|\eta_h\|_{W^{1,p}(\mathcal{T}_h)} && \text{for all } \eta_h \in W^{1,p}(\mathcal{T}_h). \end{aligned}$$

Furthermore, if Λ_K satisfies the assumptions of [Lem. 7.3](#) for all $K \in \mathcal{T}_h$ and all $h \in (0, h_0)$, then for $0 \leq m \leq \Theta$, there exists $c_1, c_2 > 0$ independent of $h \in (0, h_0)$ such that

$$(7.7) \quad c_1 \|\eta_h\|_{W^{m,p}(\mathcal{T}_h)} \leq \left\| \eta_h^\ell \right\|_{W^{m,p}(\mathcal{T}_h^\ell)} \leq c_2 \|\eta_h\|_{W^{m,p}(\mathcal{T}_h)} \quad \text{for all } \eta_h \in W^{m,p}(\mathcal{T}_h).$$

Proof. The regularity of the family of triangulations $\{\mathcal{T}_h\}_{h \in (0, h_0)}$ follows from [\(7.4a\)](#) and [\(7.4b\)](#) from assumption [\(7.5\)](#).

The results follow by combining the previous results for each element in \mathcal{T}_h . We achieve bounds independently of $h \in (0, h_0)$ since the regularity of the subdivisions implies that h_K/ρ_K is independent of $h \in (0, h_0)$. \square

Lemma 7.9. *Let \mathcal{T}_h^ℓ be an exact decomposition of Γ then $W_T^{1,p}(\mathcal{T}_h^\ell) = W^{1,p}(\Gamma)$.*

Proof. First, let $\eta \in W_T^{1,p}(\mathcal{T}_h)$. Then we have that $\eta \in L^p(\Gamma)$ and it is left to show that η has a weak derivative in $L^p(\Gamma)$ ([Dziuk and Elliott, 2013b](#), Def. 2.11). We have a candidate ξ given element-wise by $\xi|_{K^\ell} = \nabla_\Gamma(\eta)|_{K^\ell}$. It is clear that $\xi \in L^p(\Gamma)$ and for $\varphi \in C^1(\Gamma)$ with compact support and $i = 1, \dots, n+1$, we have

$$\begin{aligned} \int_\Gamma \eta D_i \varphi &= \sum_{K^\ell \in \mathcal{T}_h^\ell} \int_{K^\ell} \eta D_i \varphi \\ &= \sum_{K^\ell \in \mathcal{T}_h^\ell} \left(- \int_{K^\ell} \xi_i \varphi + \int_{K^\ell} \eta \varphi H v_i + \int_{\partial K^\ell} \eta \varphi \mu_i \right) \\ &= - \int_\Gamma \xi_i \varphi + \int_\Gamma \eta \varphi H v_i + \sum_{K^\ell \in \mathcal{T}_h^\ell} \int_{\partial K^\ell} \eta \varphi \mu_i. \end{aligned}$$

We note that we can write

$$\sum_{K^\ell \in \mathcal{T}_h^\ell} \int_{\partial K^\ell} \eta \varphi \mu_i = \sum_{F^\ell \in \mathcal{F}_h^\ell} \int_{F^\ell} \eta \varphi (\mu_{F^\ell}^+ + \mu_{F^\ell}^-)_i = 0,$$

where \mathcal{F}_h^ℓ is the set of facets between adjacent elements in \mathcal{T}_h^ℓ , since the traces of $\eta|_{K'}$ and $\eta|_{(K^\ell)'}$ to $K^\ell \cap (K^\ell)'$ coincide for any adjacent pair K, K' . We note that the sum over edges is zero since the conormals from adjacent elements are equal and opposite in the exact triangulation and we see that ξ is the weak derivative of η .

Second, let $\eta \in W^{1,p}(\Gamma)$ then it is clear that $\eta \in L^p(\Gamma)$, $\eta|_{K^\ell} \in W^{1,p}(K^\ell)$ and by the trace theorem η has common trace between adjacent elements. \square

We can also show a special interpolation estimate which interpolates smooth functions over the continuous surface into the lifted surface finite element space. We denote by I_h an interpolation operator $I_h: C(\Gamma) \rightarrow \mathcal{S}_h^\ell$ defined by

$$(7.8) \quad I_h \eta|_{K^\ell} := I_{K^\ell} \eta.$$

Theorem 7.10 (Global lifted interpolation theorem). *For $h \in (0, h_0)$, let $\{\mathcal{T}_h\}_{h \in (0, h_0)}$ be a Θ -regular (Def. 6.22(b)), quasi-uniform (Def. 6.22(c)) family of triangulations of Γ_h equipped with a surface finite element space \mathcal{S}_h (Def. 6.19(a)) consisting of Θ -surface finite elements (Def. 6.4) over a reference element which satisfies the assumptions of Lem. 4.3 for some $0 < k, m \leq \Theta$, $p, q \in [1, \infty]$. Let each element $K \in \mathcal{T}_h$ be equipped with a lifting map $\Lambda_K \in C^{\Theta+1}(K)$ such that $\|\Lambda_K\|_{W^{\Theta+1, \infty}(K)} \leq C$ and (7.5) and (7.1) hold each uniformly for $h \in (0, h_0)$, then $\{\mathcal{T}_h^\ell\}_{h \in (0, h_0)}$ is a Θ -regular, quasi-uniform family of triangulations of Γ and \mathcal{S}_h^ℓ is a surface finite element space consisting of Θ -surface finite elements. Let $\eta \in C(\Gamma)$ be a continuous function, then $I_h \eta \in \mathcal{S}_h^\ell$ is well defined. Furthermore, if the assumptions of Thm. 6.13 hold for the reference element $(\hat{K}, \hat{P}, \hat{\Sigma})$, there exists a constant $C = C(\hat{K}, \hat{P}, \hat{\Sigma}, \rho)$ such that for all functions $\eta \in W^{k+1, p}(\mathcal{T}_h^\ell) \cap C(\Gamma)$,*

$$(7.9) \quad \|\eta - I_h \eta\|_{W^{m, q}(\mathcal{T}_h^\ell)} \leq Ch^{k+1-m} \|\eta\|_{W^{k+1, p}(\mathcal{T}_h^\ell)}.$$

Proof. The result follows by combining previous lemmas in the appropriate way. We see the lifted triangulation is quasi-uniform by applying the results in Lem. 7.5 and the assumption (7.5). The interpolation result then follows by applying Thm. 6.24. \square

Thm. 7.10 will be used to show the abstract approximation properties (I1) and (I2).

Corollary 7.11. *Let $\eta \in C(\Gamma)$, then the interpolant of η into \mathcal{S}_h , denoted by $\tilde{I}_h \eta$, is given by*

$$(7.10) \quad \tilde{I}_h \eta := (I_h \eta)^{-\ell}.$$

Furthermore, there exists a constant C such that for all functions $\eta \in W^{k+1, p}(\mathcal{T}_h^\ell) \cap C(\Gamma)$, and all $h \in (0, h_0)$, we have

$$(7.11) \quad \left\| \eta^{-\ell} - \tilde{I}_h \eta \right\|_{W^{m, q}(\mathcal{T}_h)} \leq Ch^{k+1-m} \|\eta\|_{W^{k+1, p}(\mathcal{T}_h^\ell)}.$$

Proof. We apply the inverse lift result to the estimates in the theorem. \square

7.3. Evolving lifted finite element spaces. For $t \in [0, T]$, let $\Gamma(t)$ be a smoothly evolving hypersurface with flow map Φ_t : i.e. $\Phi_{(\cdot)} \in C^2([0, T], C^1(\Gamma(0)))$ and $\Phi_t(\Gamma(0)) = \Gamma(t)$. For $h \in (0, h_0)$, let $\Gamma_h(t)$ be an evolving triangulated hypersurface (Def. 6.27(b)) with global discrete flow Φ_t^h (Def. 6.27(c)) and equipped with an evolving conforming subdivision $\mathcal{T}_h(t)$ (Def. 6.27(a)) and an evolving surface finite element space $\mathcal{S}_h(t)$ (Def. 6.28(a)). We assume that we are given a global lifting map $\Lambda_h(\cdot, t)$ (Def. 7.7(b)) which gives an exact subdivision $\mathcal{T}_h^\ell(t)$ of $\Gamma(t)$ (Def. 7.7(a)).

Definition 7.12 (Lifted discrete flow map, material velocity and pushed forward map).

- (a) The *lifted flow map* $\Phi_{(\cdot)}^\ell(\cdot): [0, T] \times \Gamma_0 \rightarrow \mathbb{R}^{n+1}$ of the smooth hypersurface is defined by

$$\Phi_t^\ell(\Lambda_h(x, t)) = \Lambda_h(\Phi_t^h(x), t) \quad \text{for } x \in \Gamma_0.$$

We note that $\Phi_t^\ell: \Gamma_0 \rightarrow \Gamma(t)$.

- (b) The *lifted discrete material velocity* w_h on $\{\Gamma(t)\}_{t \in [0, T]}$ is defined by

$$\frac{d}{dt} \Phi_t^\ell(\cdot) = w_h(\Phi_t^\ell(\cdot), t).$$

- (c) The family of *lifted push forward maps* is denoted by $\phi_t^\ell(\eta): \Gamma(t) \rightarrow \mathbb{R}$ for $\eta: \Gamma_0 \rightarrow \mathbb{R}$ and is defined by

$$\phi_t^\ell(\eta)(x) = \eta(\Phi_{-t}^\ell(x)) \quad \text{for } x \in \Gamma(t).$$

See also (3.13).

Remark 7.13. Note that in general Φ_t^ℓ is different to Φ_t , but each describes a different parametrisation of the same evolving surface. Also w , the material velocity of $\Gamma(t)$, and w_h define the same surface $\Gamma(t)$ evolving from $\Gamma(0)$, so have the same normal components whilst the tangential components may not agree.

Proposition 7.14. *For $h \in (0, h_0)$, let $\{\mathcal{S}_h(t)\}_{t \in [0, T]}$ be an evolving surface finite element space over a Θ -regular (Def. 6.22(b)), uniformly quasi-uniform (Def. 6.29(c)), evolving conforming subdivision $\{\mathcal{T}_h(t)\}_{t \in [0, T]}$ consisting of Θ -evolving surface finite elements (Def. 6.25(d)) and ϕ_t^h the global push-forward map (Def. 6.27(e)). For each $t \in [0, T]$ and each $h \in (0, h_0)$, let each element $K \in \mathcal{T}_h$ be equipped with a lifting map $\Lambda_K(\cdot, t) \in C^{\Theta+1}(K(t))$ such that $\|\Lambda_K(\cdot, t)\|_{W^{\Theta+1, \infty}(K)} \leq C$ and (7.5) and (7.1) hold each uniformly for $h \in (0, h_0)$ and $t \in [0, T]$. Then $\{\mathcal{S}_h^\ell(t)\}_{t \in [0, T]}$ is also an evolving surface finite element space over a Θ -regular, uniformly quasi-uniform, evolving conforming subdivision $\{\mathcal{T}_h^\ell(t)\}_{t \in [0, T]}$ consisting of Θ -evolving surface finite elements. Furthermore, for $0 \leq m \leq \Theta + 1$, $p \in [0, \infty]$, there exists $c_1, c_2 > 0$ independent of $h \in (0, h_0)$ and $t \in [0, T]$ such that*

(7.12)

$$c_1 \|\eta\|_{W^{m,p}(\mathcal{S}_h^\ell(0))} \leq \left\| \phi_t^\ell \eta \right\|_{W^{m,p}(\mathcal{S}_h^\ell(t))} \leq c_2 \|\eta\|_{W^{m,p}(\mathcal{S}_h^\ell(0))} \quad \text{for all } \eta \in W^{m,p}(\mathcal{S}_h^\ell(0)).$$

In particular, the pair $(W^{m,p}(\mathcal{S}_h^\ell(t)), \phi_t^\ell|_{W^{m,p}(\mathcal{S}_h^\ell(0))})_{t \in [0, T]}$ is compatible (Def. 2.2). Furthermore the pairs $(\mathcal{S}_h^\ell(t), \phi_t^\ell|_{\mathcal{S}_{h,0}^\ell})_{t \in [0, T]}$, equipped with the norm $\|\cdot\|_{W^{m,p}(\mathcal{S}_h^\ell(t))}$, and $(W^{1,p}(\Gamma), \phi_t^\ell|_{W^{1,p}(\Gamma_0)})_{t \in [0, T]}$ are also compatible.

Proof. The initial properties of $\mathcal{S}_h(t)$ follow for the same reasoning as Prop. 7.8 since the constants are bounded uniformly in time. The bounds (7.12) and the compatibility of $(W^{m,p}(\mathcal{S}_h^\ell), \phi_t^\ell)_{t \in [0, T]}$ follow since the assumptions imply that $(W^{m,p}(\mathcal{S}_h^\ell), \phi_t^h)_{t \in [0, T]}$ are compatible and we can simply lift this result with uniform bounds. The compatibility of $(\mathcal{S}_h^\ell(t), \phi_t^\ell|_{\mathcal{S}_{h,0}^\ell})_{t \in [0, T]}$ and $(W^{1,p}(\Gamma(t)), \phi_t^\ell|_{W^{1,p}(\Gamma_0)})_{t \in [0, T]}$ follow since they are closed subspaces of $W^{1,p}(\mathcal{S}_h^\ell(t))$ (Lem. 6.18, 6.20 and 7.9) and Rem. 2.3. \square

Part 3. Application to parabolic equations on evolving domains

8. APPLICATION I: PARABOLIC EQUATION ON AN EVOLVING BULK DOMAIN

In this section, we will formulate and analyse a finite element method for a parabolic problem posed in an evolving bulk domain (1.4). We will begin with notation and definitions for the initial value problem. The numerical method is based on the general theory of Sec. 4 applied here with isoparametric bulk finite element spaces of order k . The analysis is based on the abstract theory presented in Sec. 2 and 3.

8.1. The domain and function spaces. We set $\mathcal{H}(t) = L^2(\Omega(t))$, $\mathcal{V}(t) = H^1(\Omega(t))$ and $\mathcal{V}^*(t) = (H^1(\Omega(t)))^*$. We will also make use of the spaces $\mathcal{Z}_0(t) = H^2(\Omega(t))$ and $\mathcal{Z}(t) = H^{k+1}(\Omega(t))$. We see that $Z(t) \subset \mathcal{Z}_0(t) \subset \mathcal{V}(t)$ for each $t \in [0, T]$ and the inclusions are uniformly continuous. We define the push-forward operator ϕ_t by

$$(8.1) \quad (\phi_t \eta)(\cdot, t) := \eta(\Phi_{-t}(\cdot)) \quad \text{for } \eta \in \mathcal{H}_0.$$

$(L^2(\Omega(t)), \phi_t)_{t \in [0, T]}$ and $(H^1(\Omega(t)), \phi_t)_{t \in [0, T]}$ are compatible pairs (Def. 2.2), the spaces $L^2_{\mathcal{H}}$, $L^2_{\mathcal{V}}$ and $L^2_{\mathcal{V}^*}$ are well defined (c.f. (2.1)) and we have a well defined strong material derivative, denoted ∂^\bullet (2.4). $(\mathcal{V}(t), \mathcal{H}(t), \mathcal{V}^*(t))_{t \in [0, T]}$ form an evolving Hilbert triple (Def. 2.4). We also have that $(\mathcal{Z}_0(t), \phi_t|_{\mathcal{Z}_0(t)})_{t \in [0, T]}$ and $(\mathcal{Z}(t), \phi_t|_{\mathcal{Z}(t)})_{t \in [0, T]}$ are compatible pairs. For details see Alphonse, Elliott and Stinner (2015b).

Remark 8.1. For the well posedness of the partial differential equation Prob. 8.3 we require that the boundary Γ is a C^2 -hypersurface and that the flow map $\Phi_{(\cdot)}(\cdot) \in C^2(0, T; C^2(\Omega_0))$. See Alphonse et al. (2015b) for more details. For the approximation properties we derive we require that Γ is a C^{k+2} -hypersurface and that $\Phi_{(\cdot)}(\cdot) \in C^{k+2}(0, T; C^{k+2}(\Omega_0))$ with $\Phi_t: \Omega_0 \rightarrow \Omega(t)$ and $\Phi_{-t}: \Omega(t) \rightarrow \Omega$ both of class C^{k+2} .

We introduce a signed distance function for the boundary surface $\Gamma(t) = \partial\Omega(t)$. The oriented signed distance function for $\Gamma(t)$ is given by

$$d(x, t) = \begin{cases} -\inf\{|x - y| : y \in \Gamma(t)\} & \text{for } x \in \bar{\Omega}(t) \\ \inf\{|x - y| : y \in \Gamma(t)\} & \text{otherwise.} \end{cases}$$

For each $t \in [0, T]$, we orient $\Gamma(t)$ by choosing the unit normal $\nu(x, t) = \nabla d(x, t)$ for $x \in \Gamma(t)$. Our assumptions on $\Gamma(t)$ imply that there exists a neighbourhood $\mathcal{N}(t)$ of $\Gamma(t)$ and normal projection operator $p(\cdot, t): \mathcal{N}(t) \rightarrow \Gamma(t)$ given as the unique solution of

$$(8.2) \quad x = p(x, t) + d(x, t)\nu(p(x, t), t).$$

See Gilbarg and Trudinger (1983, Lem. 14.16); Foote (1984) for more details.

The final result we show in this section will be useful in the error analysis of our methods.

Lemma 8.2 (Narrow band trace inequality). *For $t \in [0, T]$, let $B_\varepsilon(t) \subset \mathcal{N}(t)$ be the band given by*

$$B_\varepsilon(t) = \{x \in \Omega(t) : -\varepsilon < d(x, t) \leq 0\}.$$

Then there exists a constant c such that for all $t \in [0, T]$,

$$(8.3) \quad \|\eta\|_{L^2(B_\varepsilon(t))} \leq c\varepsilon^{1/2} \|\eta\|_{H^1(\Omega(t))} \quad \text{for all } \eta \in H^1(\Omega(t)).$$

Proof. The proof for stationary domains is given by Elliott and Ranner (2013, Lem. 4.10) which can be easily extended to the evolving case. \square

8.2. The initial value problem. We assume that $\mathcal{A}_\Omega \in C^1(\Omega_T; \mathbb{R}^{(n+1) \times (n+1)})$ is an $(n+1) \times (n+1)$ symmetric diffusion tensor, $\mathcal{B}_\Omega \in C^1(\Omega_T; \mathbb{R}^{n+1})$ a smooth vector field and $\mathcal{C}_\Omega \in C^1(\Omega_T)$ is a smooth scalar field. We assume that for each $t \in [0, T]$, $\mathcal{A}_\Omega(\cdot, t)$ is uniformly positive definite: There exists $a_0 > 0$ such that for all $\xi \in \mathbb{R}^{n+1}$

$$\mathcal{A}_\Omega(\cdot, t)\xi \cdot \xi \geq a_0 |\xi|^2 \quad \text{for all } \xi \in \mathbb{R}^{n+1}.$$

We consider the initial value problem

Problem 8.3. Find u such that

$$(8.4a) \quad \partial^\bullet u + \nabla \cdot (\mathcal{B}_\Omega u) - \nabla \cdot (\mathcal{A}_\Omega \nabla u) + \mathcal{C}_\Omega u + (\nabla \cdot w)u = 0 \quad \text{on } \Omega(t)$$

$$(8.4b) \quad (-\mathcal{B}_\Omega u + \mathcal{A}_\Omega \nabla u) \cdot \nu = 0 \quad \text{on } \Gamma(t)$$

$$(8.4c) \quad u(0) = u_0 \quad \text{on } \Omega_0.$$

Remark 8.4. The problem (1.4) is recovered by setting $\mathcal{A}_\Omega = a_\Omega$, $\mathcal{B}_\Omega = b_\Omega - w$ and $\mathcal{C}_\Omega = c_\Omega$.

Transport formulae. The following transport formulae hold on portions $\{\omega(t) \subseteq \Omega(t)\}_{t \in [0, T]}$ of the domain $\{\Omega(t)\}_{t \in [0, T]}$, which follow the flow $\omega(t) = \Phi_t(\omega(0))$ for $t \in [0, T]$, and have Lipschitz boundaries at each time. :-

- For $\eta, \zeta \in C^1_{\mathcal{H}}$ by

$$(8.5) \quad \frac{d}{dt} \int_{\omega(t)} \eta \zeta \, dx = \int_{\omega(t)} \partial^\bullet \eta \zeta + \partial^\bullet \eta \zeta \, dx + \int_{\omega(t)} \eta \zeta \nabla \cdot w \, dx.$$

- For $\eta, \zeta \in C^1_{\mathcal{V}}$, we have the identity

$$(8.6) \quad \begin{aligned} \frac{d}{dt} \int_{\omega(t)} \mathcal{A}_\Omega \nabla \eta \cdot \nabla \zeta \, dx &= \int_{\omega(t)} \mathcal{A}_\Omega \nabla \partial^\bullet \eta \cdot \nabla \zeta + \mathcal{A}_\Omega \nabla \eta \cdot \nabla \partial^\bullet \zeta \, dx \\ &\quad + \int_{\omega(t)} \mathcal{B}(w, \mathcal{A}_\Omega) \nabla \eta \cdot \nabla \zeta \, dx, \end{aligned}$$

where $\mathcal{B}(w, \mathcal{A}_\Omega)$ is given by

$$(8.7) \quad \mathcal{B}(w, \mathcal{A}_\Omega) = \partial^\bullet \mathcal{A}_\Omega + \nabla \cdot w \mathcal{A}_\Omega - 2D(w, \mathcal{A}_\Omega)$$

and $D(w, \mathcal{A}_\Omega)$ is the rate of deformation tensor

$$D(w, \mathcal{A}_\Omega)_{ij} = \frac{1}{2} \sum_{k=1}^{n+1} \{(\mathcal{A}_\Omega)_{ik} (\nabla)_k w_j + (\mathcal{A}_\Omega)_{jk} (\nabla)_k w_i\} \quad \text{for } i, j = 1, \dots, n+1.$$

- For $\eta \in C^1_{\mathcal{H}}$, $\zeta \in C^1_{\mathcal{V}}$, we have

$$(8.8) \quad \begin{aligned} \frac{d}{dt} \int_{\omega(t)} \mathcal{B}_\Omega \eta \cdot \nabla \zeta \, dx &= \int_{\omega(t)} \{\mathcal{B}_\Omega \partial^\bullet \eta \cdot \nabla \zeta + \mathcal{B}_\Omega \eta \cdot \nabla \partial^\bullet \zeta\} \, dx \\ &\quad + \int_{\omega(t)} \mathcal{B}_{\text{adv}}(w, \mathcal{B}_\Omega) \eta \cdot \nabla \zeta \, dx, \end{aligned}$$

where $\mathcal{B}_{\text{adv}}(w, \mathcal{B}_\Omega)$ is given by

$$\mathcal{B}_{\text{adv}}(w, \mathcal{B}_\Omega) = \partial^\bullet \mathcal{B}_\Omega + \mathcal{B}_\Omega \nabla \cdot w - \sum_{j=1}^{n+1} (\mathcal{B}_\Omega)_j (\nabla)_j w.$$

8.3. The bilinear forms and transport formulae. We define

$$\begin{aligned}
m(t; \eta, \zeta) &:= \int_{\Omega(t)} \eta \zeta \, dx & \eta, \zeta \in \mathcal{H}(t) \\
g(t; \eta, \zeta) &:= \int_{\Omega(t)} \eta \zeta \nabla \cdot w \, dx & \eta, \zeta \in \mathcal{H}(t) \\
a(t; \eta, \zeta) &:= a_s(t; \eta, \zeta) + a_n(t; \eta, \zeta) & \eta, \zeta \in \mathcal{V}(t) \\
a_s(t; \eta, \zeta) &:= \int_{\Omega(t)} \mathcal{A}_\Omega \nabla \eta \cdot \nabla \zeta + \mathcal{C}_\Omega \eta \zeta \, dx & \eta, \zeta \in \mathcal{V}(t) \\
a_n(t; \eta, \zeta) &:= \int_{\Omega(t)} \mathcal{B}_\Omega \eta \cdot \nabla \zeta \, dx & \eta \in \mathcal{H}(t), \zeta \in \mathcal{V}(t).
\end{aligned}$$

We can apply (8.5), (8.6) and (8.8) to see that we have the transport laws

$$(8.9) \quad \frac{d}{dt} m(t; \eta, \zeta) = m(t; \partial^\bullet \eta, \zeta) + m(t; \eta, \partial^\bullet \zeta) + g(t; \eta, \zeta) \quad \text{for all } \eta, \zeta \in C^1_{\mathcal{H}}$$

$$(8.10) \quad \frac{d}{dt} a_s(t; \eta, \zeta) = a_s(t; \partial^\bullet \eta, \zeta) + a_s(t; \eta, \partial^\bullet \zeta) + b_s(t; \eta, \zeta) \quad \text{for all } \eta, \zeta \in C^1_{\mathcal{V}}$$

$$(8.11) \quad \frac{d}{dt} a_n(t; \eta, \zeta) = a_n(t; \partial^\bullet \eta, \zeta) + a_n(t; \eta, \partial^\bullet \zeta) + b_n(t; \eta, \zeta) \quad \text{for all } \eta \in C^1_{\mathcal{H}}, \zeta \in C^1_{\mathcal{V}},$$

with the new forms

$$\begin{aligned}
b_s(t; \eta, \zeta) &= \int_{\Omega(t)} \mathcal{B}_\Omega(w, \mathcal{A}_\Omega) \nabla \eta \cdot \nabla \zeta + (\partial^\bullet \mathcal{C} + \mathcal{C}_\Omega \nabla \cdot w) \eta \zeta \, dx & \text{for } \eta, \zeta \in \mathcal{V}(t) \\
b_n(t; \eta, \zeta) &= \int_{\Omega(t)} \mathcal{B}_{\text{adv}}(w, \mathcal{B}_\Omega) \eta \cdot \nabla \zeta \, dx & \text{for } \eta \in \mathcal{H}(t), \zeta \in \mathcal{V}(t),
\end{aligned}$$

where

$$\begin{aligned}
\mathcal{B}_\Omega(w, \mathcal{A}_\Omega) &:= \partial^\bullet \mathcal{A}_\Omega + \nabla \cdot w \mathcal{A}_\Omega - 2D_h(w) \\
\mathcal{B}_{\text{adv}}(w, \mathcal{B}_\Omega) &:= \partial^\bullet \mathcal{B}_\Omega + \mathcal{B} \nabla \cdot w - \sum_{j=1}^{n+1} (\mathcal{B}_\Omega)_j \partial_{x_j} w,
\end{aligned}$$

and $D(w)$ is the rate of deformation tensor:

$$D(w)_{ij} = \frac{1}{2} \sum_{l=1}^{n+1} (\mathcal{A}_\Omega)_{il} \partial_{x_l} w_j + (\mathcal{A}_\Omega)_{jl} \partial_{x_l} w_i \quad \text{for } i, j = 1, \dots, n+1.$$

We define $b(t; \cdot, \cdot): \mathcal{V}(t) \times \mathcal{V}(t) \rightarrow \mathbb{R}$ to be

$$b(t; \eta, \zeta) := b_s(t; \eta, \zeta) + b_n(t; \eta, \zeta) \quad \text{for } \eta, \zeta \in \mathcal{V}(t).$$

The smoothness assumptions on the coefficients and the velocity imply that g , b_s and b_n are uniformly bounded. There exists a constant $c > 0$ such that

$$(8.12) \quad |g(t; \eta, \zeta)| \leq c \|\eta\|_{\mathcal{H}(t)} \|\zeta\|_{\mathcal{H}(t)} \quad \text{for all } \eta, \zeta \in \mathcal{H}(t)$$

$$(8.13) \quad |b_s(t; \eta, \zeta)| \leq c \|\eta\|_{\mathcal{V}(t)} \|\zeta\|_{\mathcal{V}(t)} \quad \text{for all } \eta, \zeta \in \mathcal{V}(t)$$

$$(8.14) \quad |b_n(t; \eta, \zeta)| \leq c \|\eta\|_{\mathcal{V}(t)} \|\zeta\|_{\mathcal{V}(t)} \quad \text{for all } \eta \in \mathcal{H}(t), \zeta \in \mathcal{V}(t).$$

8.4. Variational formulation. We consider the following variational formulation of (1.4):

Problem 8.5. Given $u_0 \in L^2(\Omega_0)$, find $u \in \mathcal{W}(\mathcal{V}, \mathcal{V}^*)$ such that for almost every $t \in (0, T)$ we have

$$(8.15) \quad \begin{aligned} m(t; \partial^\bullet u, \zeta) + g(t; u, \zeta) + a(t; u, \zeta) &= 0 \quad \text{for all } \zeta \in H^1(\Omega(t)) \\ u(0) &= u_0. \end{aligned}$$

Theorem 8.6. There exists a unique solution u to *Prob. 8.5* which satisfies the stability bound:

$$(8.16) \quad \sup_{t \in [0, T]} \|u\|_{L^2(\Omega(t))}^2 + \int_0^T \|u\|_{H^1(\Omega(t))}^2 dt \leq c(T) \|u_0\|_{L^2(\Omega_0)}^2$$

and if $u_0 \in H^1(\Omega_0)$

$$(8.17) \quad \sup_{t \in [0, T]} \|u\|_{H^1(\Omega(t))}^2 + \int_0^T \|\partial^\bullet u\|_{L^2(\Omega(t))}^2 dt \leq c(T) \|u_0\|_{H^1(\Omega_0)}^2.$$

Proof. We simply apply the abstract theory of [Thm. 2.15](#). For [Ass. 2.6](#) and [2.9](#) we refer to [Alphonse et al. \(2015b, Sec. 4 and Sec. 5\)](#). [Ass. 2.13](#) is a consequence of [Rem. 2.14](#). Also Assumptions [\(M1\)](#), [\(M2\)](#), [\(G1\)](#), [\(G2\)](#), [\(A1\)](#), [\(A2\)](#), [\(A3\)](#), [\(A_s4\)](#), [\(B_s1\)](#), [\(B_n1\)](#), [\(B_s2\)](#) and [\(B_n2\)](#) hold. It is clear that [\(M1\)](#) and [\(M2\)](#) hold since $m(t; \cdot, \cdot)$ is equal to the $\mathcal{H}(t)$ -inner product. Similarly assumptions [\(G1\)](#) and [\(G2\)](#) follow from the transport formula [\(8.9\)](#) and the boundedness of the velocity. We know that the map $t \mapsto a(t; \cdot, \cdot)$ is differentiable hence measurable which shows [\(A1\)](#). The coercivity [\(A3\)](#) and boundedness [\(A_s4\)](#) of a_s and the boundedness of [\(A_n4\)](#) follow from standard arguments. The existence of the bilinear forms b_s [\(B_s1\)](#) and b_n [\(B_n1\)](#) has been shown in [\(8.10\)](#) and [\(8.11\)](#) and the estimates [\(B_s2\)](#) and [\(B_n2\)](#) are shown in [\(8.13\)](#) and [\(8.14\)](#). \square

8.5. Discretisation of the domain and finite element spaces. The first stage in constructing our finite element method is to define an approximate computation domain $\{\Omega_h(t)\}$. Our construction satisfies that the boundary Lagrange points of $\Omega_h(t)$ lie on the boundary of $\Omega(t)$ and all Lagrange points evolve with the prescribed velocity w . We will consider $\Omega_h(t)$ as an interpolant of $\Omega(t)$. We recall k is the order of isoparametric bulk finite element spaces we wish to use. Throughout the remainder of this section we will denote global discrete quantities with a subscript $h \in (0, h_0)$, which is related to element size. We assume implicitly that these structures exist for each h in this range (see also [Rem. 4.11](#)).

We will use the simplicial, Lagrangian reference element $(\hat{K}, \hat{P}, \hat{\Sigma})$ over order k from [Ex. 4.2](#). We start by constructing a family of time dependent element reference maps [\(Def. 4.30\(b\)\)](#) which will define an evolving conforming subdivision $\{\mathcal{T}_h(t)\}$ [\(Def. 4.32\(a\)\)](#) of an evolving triangulated open domain $\{\Omega_h(t)\}$ [\(Def. 4.32\(b\)\)](#).

Let $\tilde{\Omega}_{h,0}$ be a polyhedral approximation of Ω_0 equipped with a quasi-uniform, conforming subdivision into simplicies $\tilde{\mathcal{T}}_{h,0}$ (see [Sec. 4.3](#) for details). We denote by $\tilde{\Gamma}_{h,0} = \partial\tilde{\Omega}_{h,0}$. We restrict that the vertices of $\tilde{\Gamma}_{h,0}$ lie on the surface Γ_0 . We assume that the normal projection operator [\(8.2\)](#), $p(\cdot, 0)$ is a homomorphism from $\tilde{\Gamma}_{h,0}$ onto Γ_0 . More precisely, for each $\tilde{K} \in \tilde{\mathcal{T}}_{h,0}$, there exists an affine map $\tilde{K} \rightarrow \mathbb{R}^{n+1}$ which satisfies the assumption of [Def. 4.4](#) so that we can define a bulk finite element $(\tilde{K}, \tilde{P}, \tilde{\Sigma})$ using [\(4.3\)](#). We assume the Lagrange points satisfy [\(4.19\)](#).

We extend p to construct a bijection $\Psi_h: \tilde{\Omega}_{h,0} \rightarrow \tilde{\Omega}_0$ which we will define element-wise. A similar construction is used by [Elliott and Ranner \(2013\)](#). We first decompose $\tilde{\mathcal{T}}_{h,0}$

into boundary elements, which have more than one vertex on the boundary, and interior elements. For an interior element $\tilde{K} \in \tilde{\mathcal{T}}_{h,0}$, we define

$$\Psi_h(\tilde{x}) = \tilde{x} \quad \text{for } \tilde{x} \in \tilde{K}.$$

Otherwise, let \tilde{K} be a boundary element and consider $\tilde{x} \in \tilde{K}$. Denote by $\{\tilde{a}_i\}_{i=1}^{n+2}$ the vertices of \tilde{K} ordered so that $\{\tilde{a}_i\}_{i=1}^L$ lie on Γ_0 (recall that $\Omega(t) \subset \mathbb{R}^{n+1}$). First, decompose \tilde{x} into barycentric coordinates:

$$\tilde{x} = \sum_{j=1}^{n+2} \mu_j(\tilde{x}) \tilde{a}_j.$$

We introduce the function $\mu^*(\tilde{x})$ and the singular set σ by

$$\mu^*(\tilde{x}) = \sum_{j=1}^L \mu_j(\tilde{x}), \quad \sigma = \{\tilde{x} \in \tilde{K} : \mu^*(\tilde{x}) = 0\}.$$

The scalar μ^* represents how far we are from $\tilde{\Gamma}_{h,0}$ with $\mu^* = 1$ on Γ_h . Note that we have $0 \leq \mu^* \leq 1$. The set σ is the set of points in \tilde{K} furthest from $\tilde{\Gamma}_{h,0}$. If $\tilde{x} \notin \sigma$, we denote the projection onto $\tilde{\Gamma}_{h,0} \cap \tilde{K}$ by $y(\tilde{x})$. We see that $y(\tilde{x})$ is given by

$$y(\tilde{x}) = \sum_{j=1}^L \frac{\mu_j(\tilde{x})}{\mu^*(\tilde{x})} \tilde{a}_j.$$

Then, we define $\Psi_h|_{\tilde{K}}$ by

$$\Psi_h|_{\tilde{K}}(\tilde{x}) = \begin{cases} \tilde{x} + (\mu^*(\tilde{x}))^{k+2} (p(y(\tilde{x}), 0) - y(\tilde{x})) & \text{if } \tilde{x} \notin \sigma \\ \tilde{x} & \text{otherwise.} \end{cases}$$

Remark 8.7. This mapping takes points on $\tilde{\Gamma}_{h,0}$ onto Γ_0 , since here $\mu^* = 1$ and $y(\tilde{x}) = \tilde{x}$ and we recover $\Psi_h(\tilde{x}) = p(\tilde{x}, 0)$. Points in σ remain unchanged by this mapping, since $\mu^* = 0$ here and furthermore the power $k+2$ on μ^* ensures that the mapping is C^{k+1} on the closed domain \tilde{K} .

We write \tilde{I} for interpolation over $(\tilde{K}, \tilde{P}, \tilde{\Sigma})$ (4.12) and define an initial element reference map $F_{K_0} : \hat{K} \rightarrow \mathbb{R}^{n+1}$ by

$$F_{K_0}(\hat{x}) = [\tilde{I}\Psi_h](F_{\tilde{K}}(\hat{x})) \quad \text{for } \hat{x} \in \hat{K}.$$

We call the union of all domains K constructed in this way $\mathcal{T}_{h,0}$, which is a conforming subdivision (Def. 4.14(d)), and call the union of element domains $\Omega_{h,0}$, which is a triangulated bulk domain (Def. 4.14(a)). Finally, we call $\{a_i\}_{i=1}^N$ the Lagrange nodes of $\Omega_{h,0}$ which satisfy (4.19) since Lagrange points on the boundaries of each element \tilde{K} are not moved by Ψ_h . An example of domains constructed using the above are shown in Fig. 8.1.

To complete the construction, for $K_0 \in \mathcal{T}_{h,0}$, we consider the discrete domain $K(t)$ given by the discrete flow $\Phi_t^K : K_0 \rightarrow K(t)$ defined by

$$\Phi_t^K|_{K_0} = I_{K_0}[\Phi_t(\Psi_h(\cdot))],$$

which is a bijection onto its image for h small enough. We denote its inverse by Φ_{-t}^K . Using (4.22) Φ_t^K defines an evolving reference element map and with (4.3) we have a bulk finite

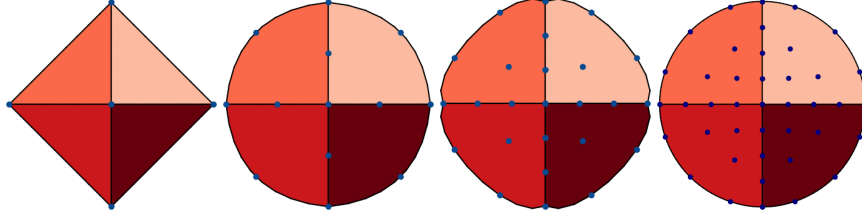


FIGURE 8.1. Examples of collections of isoparametric bulk finite elements. In each example we have four finite elements which approximate the unit disc in \mathbb{R}^2 . The element domains are shown in red and the Lagrange points in blue. From left to right we use $k = 1, 2, 3, 4$.

element $(K(t), P(t)^K, \Sigma(t)^K)$ (Def. 4.30(a)). We call the set of such domains at each time $\mathcal{T}_h(t)$ and we define $\Omega_h(t)$ by

$$\Omega_h(t) := \bigcup_{K(t) \in \mathcal{T}_h(t)} K(t),$$

and write a global discrete flow map $\Phi_t^h: \Omega_{h,0} \rightarrow \Omega_h(t)$ defined element-wise by $\Phi_t^h|_{K_0} := \Phi_t^K$ (Def. 4.32(c)). By h we denote the maximum mesh diameter over time (4.24):

$$h := \max_{t \in [0, T]} \max_{K(t) \in \mathcal{T}_h(t)} \text{diam}(\tilde{K}(t)).$$

We introduce the Hilbert spaces $\mathcal{H}_h(t) := L^2(\Omega_h(t))$ and $\mathcal{V}_h(t) := H_T^1(\mathcal{T}_h(t))$ (c.f. Lem. 4.20). Since Φ_t^h is a globally continuous function, it is clear that the Lagrange points in each element satisfy (4.25). We define a global discrete function space (Def. 4.34(a)) by

$$(8.18) \quad \mathcal{S}_h(t) := \left\{ \chi_h = (\chi_h)_{K(t) \in \mathcal{T}_h(t)} \in \prod_{K \in \mathcal{T}_h(t)} \{ \hat{\chi} \circ F_{K(t)}^{-1} : \hat{\chi} \in P_k(\hat{K}) \} : \right. \\ \left. \chi_K(a(t)) = \chi_{K'(t)} \text{ for all } K(t), K'(t) \in \mathcal{T}(a(t)), \text{ for all } a(t) \in \mathcal{N}_h(t) \right\}.$$

Using Lem. 4.23 we can identify elements in $\mathcal{S}_h(t)$ as continuous functions and $\mathcal{S}_h(t) \subset \mathcal{V}_h(t)$.

We will assume that this construction results in a uniformly quasi-uniform evolving subdivision $\{\mathcal{T}_h(t)\}_{t \in [0, T]}$ (Def. 4.35(c)) - that is that the velocity w is such that the simplices in $\mathcal{T}_h(t)$ do not become too distorted. In order to show the result of this construction satisfies the other assumptions we require we first state a result shown by Elliott and Ranner (2013):

Lemma 8.8 (Prop. 4.4, Elliott and Ranner 2013). *The mapping $\Psi_K = \Psi_h|_{\tilde{K}}$ is of class C^{k+1} when restricted to each element $\tilde{K} \in \tilde{\mathcal{T}}_{h,0}$ and the composed map $\Psi_K \circ F_{\tilde{K}}$ satisfies*

$$(8.19) \quad \left\| \nabla^m (\Psi_K \circ F_{\tilde{K}} - F_{\tilde{K}}) \right\|_{L^\infty(\tilde{K})} \leq ch^2 \quad \text{for } 0 \leq m \leq k+1.$$

Proposition 8.9. *The space $\{\mathcal{S}_h(t)\}_{t \in [0, T]}$ defined by the above construction is an evolving bulk finite element space consisting of k -surface finite elements over a uniformly k -regular evolving subdivision.*

Proof. Let $K(t)$ be a single element in $\mathcal{T}_h(t)$. We can write the element parametrisation $F_{K(t)}$ as

$$\begin{aligned} F_{K(t)}(\hat{x}) &= \Phi_t^K(F_{K_0}(\hat{x})) \\ &= \Phi_t^{\tilde{K}}(F_{\tilde{K}_0}(\hat{x})) + (\Phi_t^K(F_{K_0}(\hat{x})) - \Phi_t^{\tilde{K}}(F_{\tilde{K}_0}(\hat{x}))), \end{aligned}$$

where $\Phi_t^{\tilde{K}}$ is the flow map from $\tilde{K}_0 = F_{\tilde{K}_0}(\hat{x})$ defined as the piecewise linear interpolant of Φ_t^K . We note that $\hat{x} \mapsto \Phi_t^{\tilde{K}}(F_{\tilde{K}_0}(\hat{x}))$ is linear so we define the splitting

$$\begin{aligned} F_{K(t)}(\hat{x}) &= \underbrace{\Phi_t^{\tilde{K}}(F_{\tilde{K}_0}(\hat{x}))}_{=: A_{K(t)}\hat{x} + b_{K(t)}} + \underbrace{(\Phi_t^K(F_{K_0}(\hat{x})) - \Phi_t^{\tilde{K}}(F_{\tilde{K}_0}(\hat{x})))}_{=: \Phi_{K(t)}(\hat{x})}. \end{aligned}$$

Since $\Phi_t^K(F_{K_0}(\cdot))$ and $\Phi_t^{\tilde{K}}(F_{\tilde{K}_0}(\cdot))$ agree at the vertices of \hat{K} , we have that $\Phi_t^K(F_{\tilde{K}_0}(\cdot))$ is a linear interpolant of $\Phi_t^K(F_{K_0}(\cdot))$ over \hat{K} . Thus, we infer that

$$\begin{aligned} \left| \nabla_{\hat{x}} \left(\Phi_t^K(F_{K_0}(\hat{x})) - \Phi_t^{\tilde{K}}(F_{\tilde{K}_0}(\hat{x})) \right) \right| &= \left| \nabla_{\hat{x}} \left(\Phi_t^K(F_{K_0}(\hat{x})) - \hat{I}_1 \Phi_t^K(F_{K_0}(\hat{x})) \right) \right| \\ &\leq c \left\| \Phi_t^K(F_{K_0}(\cdot)) \right\|_{W^{2,\infty}(\hat{K})} \\ &\leq ch_K^2 \left\| \Phi_t^K \right\|_{W^{2,\infty}(K_0)}. \end{aligned}$$

Here, we have used the notation \hat{I}_1 for piecewise linear interpolation over \hat{K} and applied the Bramble-Hilbert Lemma (Lem. 4.3) and the rescaling (4.10).

Hence we have

$$C_{K(t)} = \sup_{\hat{x} \in \hat{K}} \left\| \nabla D_K(\hat{x}, t) A_K^\dagger \right\| \leq ch_K^2 \left\| \Phi_t^K \right\|_{W^{2,\infty}(K_0)} \left\| A_K^\dagger \right\| \leq c \frac{h_K^2}{\rho_K} \left\| \Phi_t^K \right\|_{W^{2,\infty}(K_0)}.$$

Since we have assumed that $\{\mathcal{T}_h(t)\}_{t \in [0, T]}$ is uniformly quasi-uniform we see that h_K^2/ρ_K is uniformly bounded, it remains to show that $\left\| \Phi_t^K \right\|_{W^{2,\infty}(K_0)}$ is uniformly bounded. However, this follows from the definition of Φ_t^K and the smoothness of Ψ_K (8.19) and the smooth flow map Φ_t . Therefore, for h_K sufficiently small, $C_{K(t)} < 1$.

To show the higher order bounds, we compute similarly that for $2 \leq m \leq k+1$

$$\begin{aligned} & \left| \nabla_{\hat{x}}^m F_K(\hat{x}) \right| \\ & \leq \left| \nabla_{\hat{x}}^m (A_{K(t)}\hat{x} + b_{K(t)}) \right| + \left| \nabla_{\hat{x}}^m \left(\Phi_t^K(F_{K_0}(\hat{x})) - \Phi_t^{\tilde{K}}(F_{\tilde{K}_0}(\hat{x})) \right) \right| \\ & = \left| \nabla_{\hat{x}}^m \left(\Phi_t^K(F_{K_0}(\hat{x})) - \hat{I}_1 \Phi_t^K(F_{K_0}(\hat{x})) \right) \right| \\ & \leq c \left\| \Phi_t^K(F_{K_0}(\cdot)) \right\|_{W^{m,\infty}(\hat{K})} \\ & \leq ch_K^m \left\| \Phi_t^K \right\|_{W^{m,\infty}(K_0)}. \end{aligned}$$

Hence, we see that

$$\sup_{\hat{x} \in \hat{K}} \left| \nabla^m F_K(\hat{x}) \right| \|A_K\|^{-m} \leq ch_K^m \|A_K\|^{-m} \left\| \Phi_t^K \right\|_{W^{m,\infty}(K_0)} \leq c \left(\frac{h_K}{\rho_K} \right)^m \left\| \Phi_t^K \right\|_{W^{m,\infty}(K_0)}.$$

In the final inequality, we use that $\|A_K\|^{-1} \leq \|A_K^{-1}\| \leq \rho_K^{-1}$. The bounds on $C_m(K(t))$ then follow since we have assumed that the mesh is uniformly quasi-uniform and that Φ_t^K is sufficiently smooth. \square

The element flow map Φ_t^K defines a velocity on each element W_K (Def. 4.30(c)) by

$$\frac{d}{dt}\Phi_t^K(\cdot) = W_K(\Phi_t^K(\cdot), t) \quad \text{for } t \in [0, T].$$

This can be combined into a global velocity W_h (4.32(d)). We note that the global velocity is determined purely by the velocity of the vertices $\{a_i(t)\}_{i=1}^N$:

$$(8.20) \quad W_h(x, t) = \sum_{i=1}^N w(a_i(t), t) \chi_i(x, t) \quad \text{for } x \in \Omega_h(t).$$

We also have a discrete push forward map ϕ_t^h (Def. 4.32(e)) for $\eta_h: \Omega_{h,0} \rightarrow \mathbb{R}$ given by

$$\phi_t^h(\eta_h)(x) = \eta_h(\Phi_{-t}^h(x)), \quad \text{for } x \in \Omega_h(t), t \in [0, T].$$

Since we have constructed a uniformly k -regular mesh, we infer that $(\mathcal{H}_h(t), \phi_t^h)_{t \in [0, T]}$ is a compatible pair (Lem. 4.36) so we may define the space $C_{\mathcal{H}_h}^1$ (2.2) and a discrete material derivative by (3.3):

$$\partial_h^\bullet \eta_h = \phi_t^h \left(\frac{d}{dt} (\phi_{-t}^h \eta_h) \right) \quad \text{for } \eta_h \in C_{\mathcal{H}_h}^1.$$

We note that the pairs $(\mathcal{V}_h(t), \phi_t^h|_{\mathcal{V}_h(t)})_{t \in [0, T]}$ and $(\mathcal{S}_h(t), \phi_t^h|_{\mathcal{S}_h(t)})_{t \in [0, T]}$ are also compatible (Lem. 4.36 and Rem. 4.37) so we may also define the spaces $C_{\mathcal{V}_h}^1$ and $C_{\mathcal{S}_h}^1$.

Lemma 8.10. *For $t \in [0, T]$ and for each $K(t) \in \mathcal{T}_h(t)$, let \mathcal{A}_Ω^K be a smooth, positive-definite, diffusion tensor on $K(t)$ and \mathcal{B}_Ω^K be a smooth vector field on $K(t)$ for each $K(t) \in \mathcal{T}_h(t)$ and $t \in [0, T]$. For $\eta_h \in C_{\mathcal{H}_h}^1$ we have the transport formula:*

$$(8.21) \quad \frac{d}{dt} \int_{\Omega_h(t)} \eta_h \, dx = \sum_{K(t) \in \mathcal{T}_h(t)} \int_{K(t)} \partial_h^\bullet \eta_h + \eta_h \nabla \cdot W_h \, dx.$$

Furthermore for $\eta_h, \zeta_h \in C_{\mathcal{V}_h}^1$ we have

$$(8.22) \quad \begin{aligned} & \frac{d}{dt} \sum_{K(t) \in \mathcal{T}_h(t)} \int_{K(t)} \mathcal{A}_\Omega^K \nabla \eta_h \cdot \nabla \zeta_h \, dx \\ &= \sum_{K(t) \in \mathcal{T}_h(t)} \int_{K(t)} \mathcal{A}_\Omega^K \nabla \partial_h^\bullet \eta_h \cdot \nabla \zeta_h + \mathcal{A}_\Omega^K \nabla \eta_h \cdot \nabla \partial_h^\bullet \zeta_h \, dx \\ & \quad + \sum_{K(t) \in \mathcal{T}_h(t)} \int_{K(t)} \mathcal{B}_K(W_K, \mathcal{A}_\Omega^K) \nabla \eta_h \cdot \nabla \eta_h \, dx, \end{aligned}$$

and for $\eta_h \in C_{\mathcal{V}_h}^1, \zeta_h \in C_{\mathcal{H}_h}^1$

$$(8.23) \quad \begin{aligned} & \frac{d}{dt} \sum_{K(t) \in \mathcal{T}_h(t)} \int_{K(t)} \mathcal{B}_\Omega^K \eta_h \cdot \nabla \zeta_h \, dx \\ &= \sum_{K(t) \in \mathcal{T}_h(t)} \int_{K(t)} \mathcal{B}_\Omega^K (\partial_h^\bullet \eta_h \cdot \nabla \zeta_h + \eta_h \cdot \nabla \partial_h^\bullet \zeta_h) \, dx \\ & \quad + \sum_{K(t) \in \mathcal{T}_h(t)} \int_{K(t)} \mathcal{B}_{\text{adv}, K}(W_K, \mathcal{B}_\Omega^K) \eta_h \cdot \nabla \zeta_h \, dx, \end{aligned}$$

where \mathcal{B}_K and $\mathcal{B}_{\text{adv},K}$ are given by

$$\begin{aligned}\mathcal{B}_K(W_K, \mathcal{A}_\Omega^K) &= \partial_K^\bullet \mathcal{A}_\Omega^K + \nabla \cdot W_K \mathcal{A}_\Omega^K - 2D_h(W_h) \\ \mathcal{B}_{\text{adv},K}(W_K, \mathcal{B}_\Omega^K) &= \partial_K^\bullet \mathcal{B}_\Omega^K + \mathcal{B}_\Omega^K \nabla \cdot W_K - \sum_{j=1}^{n+1} (\mathcal{B}_\Omega^K)_j (\nabla)_j W_K,\end{aligned}$$

and D_h is the rate of deformation tensor

$$D_h(W_h)_{ij} = \frac{1}{2} \sum_{k=1}^{n+1} (\mathcal{A}_\Omega^K)_{ik} (\nabla)_k (W_K)_j + (\mathcal{A}_\Omega^K)_{jk} (\nabla)_k (W_K)_i \quad \text{for } i, j = 1, \dots, n+1.$$

Proof. We note that the left hand side maybe decomposed into individual elements then apply (8.5), (8.6) and (8.8) on each element. \square

8.6. Construction of the lifted finite element space. We construct a bijection between the computation domain $\Omega_h(t)$ and the continuous problem domain $\Omega(t)$ which we will call the lifting operator. We do this using a similar construction to Ψ_h used to define $\Omega_h(t)$ at the start of Sec. 8.5. It will again be based on using an extension of the normal projection operator used as a lifting operator in Sec. 9.6.

Fix $t \in [0, T]$. We wish to construct a bijection $\Lambda_h(\cdot, t): \Omega_h(t) \rightarrow \bar{\Omega}(t)$ which we will define element-wise. We decompose $\mathcal{T}_h(t)$ into boundary elements, which have more than one vertex on the boundary, and interior elements. For an interior element $K(t) \in \mathcal{T}_h(t)$, we define

$$\Lambda_h(x, t) = x \quad \text{for } x \in K(t).$$

Otherwise, let $K(t)$ be a boundary element and consider $x \in K(t)$. Denote by $\{a_i(t)\}_{i=1}^{n+2}$ the vertices of $K(t)$ ordered so that $\{a_i(t)\}_{i=1}^L$ lie on $\Gamma(t)$. We recall that the element $K(t)$ is given by a parametrisation F_K over a reference element \hat{K} so that, fixing a point $x \in K$, we can define points \hat{x} and vertices $\{\hat{a}_i\}_{i=1}^{n+2}$ in \hat{K} by

$$x = F_K(\hat{x}, t) \quad \text{and} \quad a_i(t) = F_K(\hat{a}_i, t) \quad \text{for } 1 \leq i \leq n+2.$$

We decompose \hat{x} into barycentric coordinates on \hat{K} :

$$\hat{x} = \sum_{i=1}^{n+2} \hat{\mu}_i(\hat{x}) \hat{a}_i.$$

We introduce the function $\hat{\mu}^*(\hat{x})$ and the singular set $\hat{\sigma}$ by

$$\hat{\mu}^*(\hat{x}) = \sum_{i=1}^L \hat{\mu}_i(\hat{x}), \quad \hat{\sigma} = \{\hat{x} \in \hat{K} : \hat{\mu}^*(\hat{x}) = 0\}.$$

Again, we note that $0 \leq \hat{\mu}^* \leq 1$, $|D_{\hat{x}} \hat{\mu}^*| \leq 1$ and $D_{\hat{x}}^m \hat{\mu}^* = 0$ for $m \geq 2$. If $x \notin F_K(\hat{\sigma}, t)$, we denote the projection onto $\Gamma_h(t) \cap K(t)$ by $y(x, t)$ given by

$$(8.24) \quad y(\hat{x}, t) = F_K(\hat{y}(\hat{x}), t), \quad \hat{y}(\hat{x}) = \sum_{i=1}^L \frac{\hat{\mu}_i(\hat{x})}{\hat{\mu}^*(\hat{x})} \hat{a}_i.$$

We then define $\Lambda_h(\cdot, t)|_{K(t)}$ by

$$(8.25) \quad \Lambda_h(\cdot, t)|_{K(t)}(x) = \begin{cases} x + (\hat{\mu}^*(\hat{x}))^{k+2} (p(y(x, t), t) - y(x, t)) & \text{if } x \notin F_K(\hat{\sigma}, t) \\ x & \text{otherwise.} \end{cases}$$

The lifting map Λ_h induces a lifted subdivision $\{\mathcal{T}_h^\ell(t)\}_{t \in [0, T]}$ given as the set of all elements

$$K^\ell(t) := \Lambda_K(K(t), t) \quad \text{for all } K(t) \in \mathcal{T}_h(t).$$

Remark 8.11. The ideas behind this construction are similar to the construction of Ψ_h . See [Rem. 8.7](#) for more discussion and also [Lem. 8.12](#).

We next follow a sequence of calculations to show the properties of Λ_h . These estimates are based on previous work by [Bernardi \(1989\)](#) and [Elliott and Ranner \(2013\)](#). It is useful to recall the following Faá di Bruno formula ([Bernardi, 1989, Eq. 2.9](#)) for two smooth functions f, g

$$(8.26) \quad \nabla^m(f \circ g) = \sum_{r=1}^m \nabla^r f \left(\sum_{i \in E(m,r)} c_i \prod_{q=1}^m (\nabla^q g)^{i_q} \right),$$

where $\{c_i\}$ are constants and $E(m, r)$ is the set given by

$$E(m, r) = \left\{ i \in \mathbb{N}^m : \sum_{q=1}^m i_q = r \text{ and } \sum_{q=1}^m q i_q = m \right\}.$$

We wish to calculate derivatives of Λ_h of order m for $m \leq k+1$. A direct calculation shows that

$$\|D_{\hat{x}}^m \hat{y}\|_{L^\infty(\hat{K} \setminus \hat{\sigma})} \leq \frac{c}{(\hat{\mu}^*(\hat{x}))^m},$$

for a constant c independent of \hat{x} and $K(t)$. Then, we have that

$$(8.27) \quad \begin{aligned} \|\nabla_{\hat{x}}^m y(\cdot, t)\|_{L^\infty(\hat{K} \setminus \hat{\sigma})} &\leq c \sum_{r=1}^m \|\nabla_{\hat{x}}^r F_K(\cdot, t)\|_{L^\infty(\hat{K})} \left(\sum_{i \in E(m,r)} \prod_{q=1}^m \|\nabla_{\hat{x}}^q \hat{y}\|_{L^\infty(\hat{K} \setminus \hat{\sigma})}^{i_q} \right) \\ &\leq \sum_{r=1}^m \frac{h_K^r}{(\hat{\mu}^*(\hat{x}))^m} \leq c \frac{h_K}{(\hat{\mu}^*(\hat{x}))^m}, \end{aligned}$$

where in the second line, we have used that K is a k -surface finite element so

$$\|\nabla_{\hat{x}}^r F_K(\cdot, t)\|_{L^\infty(\hat{K})} \leq c \|A_K\|^r \leq c h_K^r.$$

Next, applying [\(8.26\)](#) and [\(8.27\)](#), we have

$$\|\nabla_{\hat{x}}^m (p(y(\cdot, t), t) - y(\cdot, t))\|_{L^\infty(\hat{K} \setminus \hat{\sigma})} \leq c \sum_{r=1}^m \|\nabla_y^r (p(\cdot, t) - \text{Id})\|_{L^\infty(K(t))} \frac{h_K^r}{(\hat{\mu}^*(\hat{x}))^m}.$$

Using a similar geometric construction to [Lem. 9.10](#), we have

$$\|\nabla^r (p(\cdot, t) - \text{Id})\|_{L^\infty(K(t))} = \|\nabla^r d\|_{L^\infty(K(t))} \leq c h_K^{k+1-r}.$$

Hence, we infer that

$$\|\nabla_{\hat{x}}^m (p(y(\cdot, t), t) - y(\cdot, t))\|_{L^\infty(\hat{K} \setminus \hat{\sigma})} \leq c \frac{h_K^{k+1}}{(\hat{\mu}^*(\hat{x}))^m}.$$

Finally, using the Leibniz formula and the properties of $\hat{\mu}^*$, we have

$$\begin{aligned} &\left| \nabla_{\hat{x}}^m ((\hat{\mu}^*(\hat{x}))^{k+2} (p(y(x, t), t) - y(x, t))) \right| \\ &\leq c \sum_{r=0}^m (\hat{\mu}^*(\hat{x}))^{k+2-r} \|\nabla_{\hat{x}}^{m-r} (p(y(\cdot, t) - y(\cdot))\|_{L^\infty(\hat{K} \setminus \hat{\sigma})} \\ &\leq c \sum_{r=0}^m (\hat{\mu}^*(\hat{x}))^{k+2-r} \frac{h_K^{k+1}}{(\hat{\mu}^*(\hat{x}))^{m-r}} \\ &\leq c h_K^{k+1} (\hat{\mu}^*(\hat{x}))^{k+2-m}. \end{aligned}$$

Lemma 8.12. *The lifting function $\Lambda_h(\cdot, t) : \Omega_h(t) \rightarrow \bar{\Omega}(t)$ is an element-wise C^{k+1} -diffeomorphism and satisfies*

$$(8.28) \quad \sup_{h \in (0, h_0)} \sup_{t \in [0, T]} \|\Lambda_h(\cdot, t)\|_{W^{k+1, \infty}(\mathcal{T}_h(t))} \leq C.$$

Proof. The first result is clear for all internal elements. Consider a time $t \in [0, T]$ and a single boundary element $K(t) \in \mathcal{T}_h(t)$. The smoothness away from $\sigma(t) = F_K(\hat{\sigma}, t)$ follows from the fact that Λ_h restricted to each element is the composition of smooth functions. The above calculations, combined with (4.11) and (4.9b), show that for $x = F_K(\hat{x}, t) \in K(t) \setminus \sigma(t)$,

$$(8.29) \quad |\nabla^m \Lambda_h|_{K(t)}(x, t) - \text{Id}| \leq \frac{c}{\rho_K^m} |\nabla^m \Lambda_h|_{K(t)}(F_K(\hat{x}, t), t) - \text{Id}| \leq c \frac{h_K^{k+1}}{\rho_K^m} |(\hat{\mu}^*(\hat{x}))^m|.$$

The mapping Λ_h is of class C^{k+1} on $K(t) \setminus \sigma(t)$ with derivatives of order less than or equal to $k+1$ tending to zero when x tends to a point in $\sigma(t)$. Hence, it can be extended to a C^{k+1} mapping on $K(t)$. \square

Lemma 8.13. *Furthermore, we have that the lifted triangulation $\{\mathcal{T}_h^\ell(t)\}_{t \in [0, T]}$ is a uniformly k -regular evolving subdivision (Def. 4.35(b)).*

Proof. We use the splitting

$$\Lambda_h(x, t) = x + \tilde{\Lambda}_h(x, t),$$

and write $\tilde{\Lambda}_K(\cdot, t) = \tilde{\Lambda}_h(\cdot, t)|_{K(t)} = (\Lambda_K(x, t) - x)$. We start by taking $m = 1$ in (8.29) to give

$$|\nabla \Lambda_h|_{K(t)}(x, t) - \text{Id}| \leq c \frac{h_K^{k+1}}{\rho_K} |(\hat{\mu}^*(\hat{x}))|.$$

Clearly the right hand side is less than $(1 - C_K)/(1 + C_K)$ for h_K small enough for a uniformly regular subdivision. This inequality can clearly be translated to the required estimate on Λ_h . \square

For $t \in [0, T]$ and a function $\eta_h : \bar{\Omega}_h(t) \rightarrow \mathbb{R}$, we define its lift $\eta_h^\ell : \bar{\Omega}(t) \rightarrow \mathbb{R}$ by

$$\eta_h^\ell(\Lambda_h(x, t)) = \eta_h(x) \quad \text{for } x \in \Omega_h(t).$$

We will also make use of an inverse lift for functions on $\bar{\Omega}(t)$. For $\eta : \bar{\Omega}(t) \rightarrow \mathbb{R}$, we define the inverse lift of η , denoted by $\eta^{-\ell} : \bar{\Omega}_h(t) \rightarrow \mathbb{R}$ by

$$\eta^{-\ell}(x) = \eta(\Lambda_h(x, t), t) \quad \text{for } x \in \Omega_h(t).$$

Lemma 8.14. *Let $\eta_h \in \mathcal{H}_h(t)$ and denote its lift by η_h^ℓ . Then there exists constants $c_1, c_2 > 0$ such that*

$$(8.30) \quad c_1 \left\| \eta_h^\ell \right\|_{\mathcal{H}(t)} \leq \|\eta_h\|_{\mathcal{H}_h(t)} \leq c_2 \left\| \eta_h^\ell \right\|_{\mathcal{H}(t)}$$

$$(8.31) \quad c_1 \left\| \eta_h^\ell \right\|_{\mathcal{V}(t)} \leq \|\eta_h\|_{\mathcal{V}_h(t)} \leq c_2 \left\| \eta_h^\ell \right\|_{\mathcal{V}(t)} \quad \text{if } \eta_h \in \mathcal{V}_h(t).$$

Proof. We apply Prop. 5.8 and Lem. 8.13. \square

For each $K(t) \in \mathcal{T}_h(t)$, we use Def. 5.1 to construct an associated lifted bulk finite element $(K^\ell(t), \mathcal{P}^\ell(t), \Sigma^\ell(t))$. We assume that the domains $\{\Omega_h(t)\}_{t \in [0, T]}$ are such that the set of lifted element domains $\mathcal{T}_h^\ell(t)$ defines an exact decomposition of $\Omega(t)$ (Def. 5.7(a))

for each $t \in [0, T]$. For $t \in [0, T]$, we define the space of lifted functions to be $\mathcal{S}_h^\ell(t)$ given by (c.f. (3.17))

$$\mathcal{S}_h^\ell(t) := \{\chi_h^\ell : \chi_h \in \mathcal{S}_h(t)\}.$$

Using the lift Λ_h and the discrete flow Φ_t^h , we can define the lifted flow map Φ_t^ℓ (Def. 5.11(a)), lifted discrete velocity w_h (Def. 5.11(b)) and lifted push forward maps ϕ_t^ℓ (Def. 5.11(c)). The results of Lem. 8.13 imply with Prop. 5.13 that $(\mathcal{H}(t), \phi_t^\ell)_{t \in [0, T]}$ and $(\mathcal{V}(t), \phi_t^\ell|_{\mathcal{V}_0})_{t \in [0, T]}$ and $(\mathcal{S}_h^\ell(t), \phi_t^\ell|_{\mathcal{S}_{h,0}^\ell})_{t \in [0, T]}$ form compatible pairs (Def. 2.2). We will use the notations $C_{(\mathcal{H}, \phi^\ell)}^1$ and $C_{(\mathcal{V}, \phi^\ell)}^1$ for the spaces of functions smoothly evolving in time (2.2) with respect to the push-forward map ϕ_t^ℓ in $\mathcal{H}(t)$ and $\mathcal{V}(t)$ respectively. We may define a lifted strong material derivative (3.15):

$$\partial_t^\bullet \eta = \phi_t^\ell \left(\frac{d}{dt} \left(\phi_{-t}^\ell \eta \right) \right) \quad \text{for } \eta \in C_{(\mathcal{H}, \phi^\ell)}^1.$$

Lemma 8.15. *The flow map Φ_t^ℓ induces a new transport formula on $\{\Omega(t)\}$. For $\eta \in C_{(\mathcal{H}, \phi^\ell)}^1$ we have*

$$(8.32) \quad \frac{d}{dt} \int_{\Omega(t)} \eta \, dx = \sum_{K^\ell(t) \in \mathcal{T}_h^\ell(t)} \int_{K^\ell(t)} \partial_t^\bullet \eta + \eta \nabla \cdot w_h \, dx.$$

Let \mathcal{A}_Ω be a smooth, positive-definite, diffusion tensor on $\Omega(t)$ and \mathcal{B}_Ω be a smooth vector field on $\Omega(t)$ for all $t \in [0, T]$. Furthermore, we have for $\eta, \zeta \in C_{(\mathcal{V}, \phi^\ell)}^1$

$$(8.33) \quad \begin{aligned} & \frac{d}{dt} \int_{\Omega(t)} \mathcal{A}_\Omega \nabla \eta \cdot \nabla \zeta \, dx \\ &= \sum_{K^\ell(t) \in \mathcal{T}_h^\ell(t)} \int_{K^\ell(t)} \mathcal{A}_\Omega (\nabla \partial_t^\bullet \eta \cdot \nabla \zeta + \nabla \eta \cdot \nabla \partial_t^\bullet \zeta) + \mathcal{B}_{K^\ell} (w_K, \mathcal{A}_\Omega) \nabla \eta \cdot \nabla \zeta \, dx \end{aligned}$$

and for $\eta \in C_{(\mathcal{V}, \phi^\ell)}^1, \zeta \in C_{(\mathcal{H}, \phi^\ell)}^1$ we have

$$(8.34) \quad \begin{aligned} & \frac{d}{dt} \int_{\Omega(t)} \mathcal{B}_\Omega \eta \cdot \nabla \zeta \, dx \\ &= \sum_{K^\ell(t) \in \mathcal{T}_h^\ell(t)} \int_{K^\ell(t)} \mathcal{B}_\Omega (\partial_t^\bullet \eta \cdot \nabla \zeta + \eta \cdot \nabla \partial_t^\bullet \zeta) + \mathcal{B}_{K^\ell, \text{adv}} (w_K, \mathcal{B}_\Omega) \eta \cdot \nabla \zeta \, d\sigma, \end{aligned}$$

where \mathcal{B}_{K^ℓ} and $\mathcal{B}_{K^\ell, \text{adv}}$ are defined as in Lem. 8.10.

Proof. We note that the left hand side may be decomposed into individual elements then apply (8.5), (8.6) and (8.8) on each element. \square

For the later analysis, we will also require bounds on the time derivative of Λ_h . We consider an element $K(t) \in \mathcal{T}_h(t)$ and the trajectory of a point $X(t)$ which follows the velocity field W_h . From the definition of W_h , we have that

$$X(t) = F_K(\hat{x}, t), \quad \hat{x} = \sum_{j=1}^{n+2} \hat{\mu}_j \hat{a}_i.$$

In particular, the barycentric coordinate representation of $X(t)$ does not depend on time. Therefore, writing $x = X(t)$ and using y from (8.24), we have

$$\partial_h^\bullet y(x, t) = \frac{d}{dt} y(X(t), t) = \frac{d}{dt} F_K(\hat{y}(\hat{x}), t) = \frac{\partial F_K}{\partial t}(\hat{y}(\hat{x}), t) = W_h(y(x, t), t).$$

Then we can compute that if $K(t)$ is a boundary element, recalling the definition of Λ_h (8.25), we have

$$\begin{aligned} \partial_h^\bullet \Lambda_h|_{K(t)}(x, t) &= \frac{d}{dt} \Lambda_h|_{K(t)}(X(t), t) \\ &= \begin{cases} W_h(x, t) + (\hat{\mu}^*(x))^{k+2} \left(\frac{\partial p}{\partial t}(y, t) + \nabla p(y, t) W_h(y(x, t), t) - W_h(y(x, t), t) \right) & \text{if } x \notin F_K(\hat{\mathbf{G}}, t) \\ 0 & \text{otherwise} \end{cases} \\ &= \begin{cases} W_h(x, t) + (\hat{\mu}^*(x))^{k+2} \left((W_h(y, t) - w(y, t)) \cdot \mathbf{v}(y, t) \mathbf{v}(y, t) - d(y, t) \mathbf{v}_t(y, t) \right) & \text{if } x \notin F_K(\hat{\mathbf{G}}, t) \\ 0 & \text{otherwise.} \end{cases} \end{aligned}$$

A similar calculation to those prior to [Lem. 8.12](#) show that for $m \leq k+1$

$$(8.35) \quad \|\partial_h^\bullet \Lambda_h(\cdot, t) - W_h(\cdot, t)\|_{W^{m, \infty}(K(t))} \leq ch_K^{k+1-m} (\hat{\mu}^*(\hat{x}))^{k+1-m} \leq ch_K^{k+1-m}.$$

This follows by using the smoothness of the surface $\Gamma(t)$ along with the fact that W_h is an interpolant of w ([Cor. 5.10](#)).

We conclude this section by showing some geometric estimates arising from the use of the lifting function Λ_h .

Lemma 8.16. *Under the above assumptions, we have the estimates that*

$$(8.36) \quad \sup_{t \in [0, T]} \|\nabla \Lambda_h(\cdot, t) - \text{Id}\|_{L^\infty(\Omega_h(t))} \leq ch^k$$

$$(8.37) \quad \sup_{t \in [0, T]} \|\partial_h^\bullet \nabla \Lambda_h(\cdot, t)\|_{L^\infty(\Omega_h(t))} \leq ch^k.$$

Additionally, writing $J_h(\cdot, t) = \sqrt{\det((\nabla \Lambda_h(\cdot, t))^t (\nabla \Lambda_h(\cdot, t)))}$, we have

$$(8.38) \quad \sup_{t \in [0, T]} \|J_h(\cdot, t) - 1\|_{L^\infty(\Omega_h(t))} \leq ch^k$$

$$(8.39) \quad \sup_{t \in [0, T]} \|\partial_h^\bullet J_h(\cdot, t)\|_{L^\infty(\Omega_h(t))} \leq ch^k.$$

Proof. We have already shown (8.36) as part of the proof of [Lem. 8.12](#). Inequality (8.38) then follows by a result of ([Ipsen and Rehman, 2008](#), Cor. 2.11).

To show the time derivative bounds, we note that for each $K(t) \in \mathcal{T}_h(t)$ we can write

$$\partial_K^\bullet \eta_h(x, t) = \partial_t \eta_h(x, t) + W_K(x, t) \cdot \nabla \eta_h(x, t) \quad \text{for } x \in \text{int } K(t).$$

Then we can compute, for $i = 1, \dots, n+1$

$$\begin{aligned} \partial_h^\bullet \partial_{x_i} \Lambda_h &= (\partial_{x_i} \Lambda_h)_t + \sum_{j=1}^{n+1} \partial_{x_j} \partial_{x_i} \Lambda_h (W_h)_j \\ &= \partial_{x_i} (\partial_t \Lambda_h) + \partial_{x_i} \left(\sum_{j=1}^{n+1} \partial_{x_j} \Lambda_h (W_h)_j \right) - \sum_{j=1}^{n+1} \partial_{x_j} \Lambda_h \partial_{x_i} (W_h)_j \\ &\quad - \sum_{j=1}^{n+1} \partial_{x_i} \partial_{x_j} \Lambda_h (W_h)_j + \sum_{j=1}^{n+1} \partial_{x_i} \partial_{x_j} \Lambda_h (W_h)_j. \end{aligned}$$

Hence we have that (up to a set of measure zero)

$$\partial_h^\bullet \nabla \Lambda_h = \nabla \partial_h^\bullet \Lambda_h - (\nabla W_h)(\nabla \Lambda_h).$$

Then applying (8.35), (8.36) together with Lem. 8.18, we have

$$\begin{aligned} \|\partial_h^\bullet \nabla \Lambda_h\|_{L^\infty(\Omega_h(t))} &\leq \|\nabla(\partial_h^\bullet \Lambda_h - W_h)\|_{L^\infty(\Omega_h(t))} + \|\nabla W_h(\text{Id} - \nabla \Lambda_h)\|_{L^\infty(\Omega_h(t))} \\ &\leq ch^k + \|\nabla W_h\|_{L^\infty(\Omega_h(t))} ch^k \leq ch^k. \end{aligned}$$

This shows (8.37).

For (8.39) we have, applying (8.36) and (8.37), that

$$\begin{aligned} &\left| \partial_h^\bullet \sqrt{\det(\nabla \Lambda_h(x, t)' \nabla \Lambda_h(x, t))} \right| \\ &= \left| \frac{1}{2} \sqrt{\det(\nabla \Lambda_h(x, t)' \nabla \Lambda_h(x, t))} \text{trace} \left((\nabla \Lambda_h(x, t)' \nabla \Lambda_h(x, t))^{-1} \partial_h^\bullet (\nabla \Lambda_h(x, t)' \nabla \Lambda_h(x, t)) \right) \right| \\ &\leq c \|\partial_h^\bullet \nabla \Lambda_h\| \leq ch^k. \quad \square \end{aligned}$$

8.7. The discrete problem and stability. The practical finite element method is based on the variational formulation (2.12) of Prob. 8.5. We introduce an element-wise smooth $(n+1) \times (n+1)$ -diffusion tensor \mathcal{A}_Ω^h , an element-wise smooth $(n+1)$ dimensional vector field \mathcal{B}_Ω^h and an element-wise smooth scalar field \mathcal{C}_Ω^h . We will use the notation $\mathcal{A}_\Omega^K := \mathcal{A}_\Omega^h|_{K(t)}$, $\mathcal{B}_\Omega^K := \mathcal{B}_\Omega^h|_{K(t)}$ and $\mathcal{C}_\Omega^K := \mathcal{C}_\Omega^h|_{K(t)}$, for all $K(t) \in \mathcal{T}_h(t)$, which we assume satisfy:

$$\sup_{h \in (0, h_0)} \sup_{t \in [0, T]} \sup_{K(t) \in \mathcal{T}_h(t)} \left(\|\mathcal{A}_\Omega^K\|_{L^\infty(K(t))} + \|\mathcal{B}_\Omega^K\|_{L^\infty(K(t))} + \|\mathcal{C}_\Omega^K\|_{L^\infty(K(t))} \right) \leq C.$$

We assume that \mathcal{A}_Ω^K is uniformly positive definite: There exists $\bar{a}_0 > 0$ such that for all $h \in (0, h_0)$, $t \in [0, T]$ and $K(t) \in \mathcal{T}_h(t)$

$$\mathcal{A}_\Omega^K(t, \cdot) \xi \cdot \xi \geq \bar{a}_0 |\xi|^2 \quad \text{for all } \xi \in \mathbb{R}^{n+1}.$$

Problem 8.17. Given $U_{h,0} \in \mathcal{S}_{h,0}$, find $U_h \in C^1_{\mathcal{S}_h}$ such that for every $t \in [0, T]$

$$(8.40) \quad \begin{aligned} \frac{d}{dt} m_h(t; U_h, \zeta_h) + a_h(t; U_h, \zeta_h) &= m_h(t; U_h, \partial_h^\bullet \zeta_h) \quad \text{for all } \zeta_h \in C^1_{\mathcal{S}_h} \\ U_h(\cdot) &= U_{h,0}, \end{aligned}$$

where we have

$$\begin{aligned} m_h(t; \eta_h, \zeta_h) &= \int_{\Omega_h(t)} \eta_h \zeta_h \, dx && \text{for } \eta_h, \zeta_h \in \mathcal{H}_h(t) \\ a_h(t; \eta_h, \zeta_h) &= \sum_{K(t) \in \mathcal{T}_h(t)} \int_{K(t)} \mathcal{A}_\Omega^K \nabla \eta_h \cdot \nabla \zeta_h + \mathcal{B}_\Omega^K \eta_h \cdot \nabla \zeta_h + \mathcal{C}_\Omega^K \eta_h \zeta_h \, dx && \text{for } \eta_h, \zeta_h \in \mathcal{V}_h(t). \end{aligned}$$

To show the properties of these bilinear forms we require one further lemma:

Lemma 8.18. The discrete velocity W_h of the discrete evolving domain $\{\Omega_h(t)\}$ is uniformly bounded in $W^{1,\infty}(\Omega_h(t))$. That is, there exists a constant $C > 0$ such that for all $h \in (0, h_0)$

$$(8.41) \quad \sup_{t \in [0, T]} \|W_h\|_{W^{1,\infty}(\mathcal{T}_h(t))} \leq C.$$

Proof. The bound follows using the characterisation (8.20) by using the interpolation bound shown in Cor. 5.10. \square

We have a transport formula for the domain $\{\Omega_h(t)\}$.

Lemma 8.19. *There exists bilinear forms $g_h(t; \cdot, \cdot): \mathcal{H}_h(t) \times \mathcal{H}_h(t) \rightarrow \mathbb{R}$, and $b_h(t; \cdot, \cdot): \mathcal{V}_h(t) \times \mathcal{V}_h(t) \rightarrow \mathbb{R}$ such that*

(8.42a)

$$\frac{d}{dt} m_h(t; \eta_h, \zeta_h) = m_h(t; \partial_h^\bullet \eta_h, \zeta_h) + m_h(t; \eta_h; \partial_h^\bullet \zeta_h) + g_h(t; \eta_h, \zeta_h) \quad \text{for } \eta_h, \zeta_h \in C_{\mathcal{H}_h}^1$$

(8.42b)

$$\frac{d}{dt} a_h(t; \eta_h, \zeta_h) = a_h(t; \partial_h^\bullet \eta_h, \zeta_h) + a_h(t; \eta_h; \partial_h^\bullet \zeta_h) + b_h(t; \eta_h, \zeta_h) \quad \text{for } \eta_h, \zeta_h \in C_{\mathcal{V}_h}^1,$$

where

$$g_h(t; \eta_h, \zeta_h) := \int_{\Omega_h(t)} \eta_h \zeta_h \nabla \cdot W_h \, dx,$$

and

$$\begin{aligned} b_h(t; \eta_h, \zeta_h) := & \sum_{K(t) \in \mathcal{T}_h(t)} \int_{K(t)} \mathcal{B}_h(W_h, \mathcal{A}_\Omega^K) \nabla \eta_h \cdot \nabla \zeta_h + \mathcal{B}_{\text{adv},h}(W_h, \mathcal{B}_\Omega^K) \eta_h \cdot \nabla \zeta_h \\ & + (\partial_h^\bullet \mathcal{C}_\Omega^K + \mathcal{C}_\Omega^K \nabla \cdot W_h) \eta_h \zeta_h \, dx. \end{aligned}$$

Furthermore, there exists a constants $c > 0$ such that for all $t \in [0, T]$ and all $h \in (0, h_0)$ we have

$$\begin{aligned} |g_h(t; \eta_h, \zeta_h)| &\leq c \|\eta_h\|_{\mathcal{H}_h(t)} \|\zeta_h\|_{\mathcal{H}_h(t)} && \text{for all } \eta_h, \zeta_h \in \mathcal{H}_h(t) \\ |b_h(t; \eta_h, \zeta_h)| &\leq c \|\eta_h\|_{\mathcal{V}_h(t)} \|\zeta_h\|_{\mathcal{V}_h(t)} && \text{for all } \eta_h, \zeta_h \in \mathcal{V}_h(t). \end{aligned}$$

Proof. The bilinear forms exist due to the more general [Lem. 8.10](#). The estimates follow from [Lem. 8.18](#). \square

Theorem 8.20. *There exists a unique solution of the finite element scheme (8.40). The solution U_h satisfies the stability bound:*

$$(8.43) \quad \sup_{t \in (0, T)} \|U_h\|_{\mathcal{H}_h(t)}^2 + \int_0^T \|U_h\|_{\mathcal{V}_h(t)}^2 \, dt \leq c \|U_{h,0}\|_{\mathcal{H}_h(t)}^2.$$

Proof. We apply the abstract result of [Thm. 3.3](#). It is left to check the required assumptions. The assumptions on m_h , [\(M_h1\)](#) and [\(M_h2\)](#), follow directly since m_h is equal to the $\mathcal{H}_h(t)$ inner-product. That $t \mapsto a_h(t; \cdot, \cdot)$ is measurable [\(A_h1\)](#) and the estimates on a_h , [\(A_h2\)](#) and [\(A_h3\)](#) follow in the same manner as [Thm. 8.6](#). The transport formulae and estimates for g_h and b_h , [\(G_h1\)](#), [\(G_h2\)](#) [\(B_h1\)](#) and [\(B_h2\)](#), are shown in [Lem. 8.19](#). \square

8.8. Error analysis. The space $\mathcal{S}_h^\ell(t)$ is equipped with the following approximation property.

Lemma 8.21. *For $\eta \in C(\Omega(t))$ there exists a Lagrangian interpolation operator $I_h \eta \in \mathcal{S}_h^\ell(t)$ that is well defined. Furthermore, the following bounds hold for constants independent of h and time:*

$$(8.44) \quad \|\eta - I_h \eta\|_{L^2(\Omega(t))} + h \|\nabla(\eta - I_h \eta)\|_{L^2(\Omega(t))} \leq ch^{k+1} \|\eta\|_{\mathcal{Z}(t)} \quad \text{for } \eta \in \mathcal{Z}(t)$$

$$(8.45) \quad \|\eta - I_h \eta\|_{L^2(\Omega(t))} + h \|\nabla(\eta - I_h \eta)\|_{L^2(\Omega(t))} \leq ch^2 \|\eta\|_{\mathcal{Z}_0(t)} \quad \text{for } \eta \in \mathcal{Z}_0(t).$$

Proof. We apply [Thm. 5.9](#). The second result applies the theorem in the obvious way. The first result applies the theorem with $k = 1$ noting that $P_1(\hat{K}) \subset P_k(\hat{K})$ and the inclusions for [Lem. 4.3](#) still hold. \square

We can also use the lift to define an evolving lifted triangulation. For each $t \in [0, T]$ and $h \in (0, h_0)$, we define

$$\mathcal{T}_h^\ell(t) := \{K^\ell(t) : K(t) \in \mathcal{T}_h(t)\}.$$

The edges of these curvilinear-simplicies evolve with a velocity w_h which can be characterised as follows. Let $X(t)$ be the trajectory of a point on $\Omega_h(t)$ according to the flow Φ_t^h . Then we have that

$$W_h(X(t), t) = \frac{d}{dt}X(t).$$

Now consider a point $Y(t) = \Lambda_h(X(t), t)$. The trajectory of $Y(t)$ defines the velocity field w_h by

$$(8.46) \quad w_h(Y(t), t) := \frac{d}{dt}Y(t) = (\partial_t \Lambda_h)(X(t), t) + (\nabla \Lambda_h)(X(t), t)W_h(X(t), t).$$

Equivalently this means the flow Φ_t^ℓ is given by

$$\Phi_{t^*}^\ell(y_0) = Y(t^*) \quad \text{such that} \quad \frac{d}{dt}Y(t) = w_h(Y(t), t), Y(0) = y_0.$$

Lemma 8.22. *The pairs $\{\mathcal{H}(t), \phi_t^\ell\}_{t \in [0, T]}$ and $\{\mathcal{V}(t), \phi_t^\ell\}_{t \in [0, T]}$ are compatible and we may define a material derivative $\partial_\ell^\bullet \eta$ for $\eta \in C^1_{(\mathcal{H}, \phi^\ell)}$ and transport formula: There exists a bilinear form $g_\ell(t; \cdot, \cdot) : \mathcal{H}(t) \times \mathcal{H}(t) \rightarrow \mathbb{R}$ given by*

$$g_\ell(t; \eta, \zeta) := \int_{\Omega(t)} \eta \zeta \nabla \cdot w_h \, dx,$$

such that

$$(8.47) \quad \frac{d}{dt}m(t; \eta, \zeta) = m(t; \partial_\ell^\bullet \eta, \zeta) + m(t; \eta, \partial_\ell^\bullet \zeta) + g_\ell(t; \eta, \zeta) \quad \text{for } \eta, \zeta \in C^1_{(\mathcal{H}, \phi^\ell)},$$

and there exists a constant $c > 0$ such that for all $t \in [0, T]$ and $h \in (0, h_0)$ we have

$$(8.48) \quad |g_\ell(t; \eta, \zeta)| \leq c \|\eta\|_{\mathcal{H}(t)} \|\zeta\|_{\mathcal{H}(t)} \quad \text{for all } \eta, \zeta \in \mathcal{H}(t).$$

Furthermore, we have a new transport formula for the a bilinear form. There exists a bilinear form $b_\ell(t; \cdot, \cdot) : \mathcal{V}(t) \times \mathcal{V}(t) \rightarrow \mathbb{R}$ given by

$$b_\ell(t; \eta, \zeta) := \int_{\Omega(t)} \mathcal{B}(w_h, \mathcal{A}_\Omega) \nabla \eta \cdot \nabla \zeta + \mathcal{B}_{\text{adv}}(w_h, \mathcal{B}_\Omega) \eta \cdot \nabla \zeta + (\partial_\ell^\bullet \mathcal{C}_\Omega + \mathcal{C}_\Omega \nabla \cdot w_h) \eta \zeta \, dx,$$

such that

$$(8.49) \quad \frac{d}{dt}a(t; \eta, \zeta) = a(t; \partial_\ell^\bullet \eta, \zeta) + a(t; \eta, \partial_\ell^\bullet \zeta) + b_\ell(t; \eta, \zeta) \quad \text{for } \eta, \zeta \in C^1_{(\mathcal{V}, \phi^\ell)},$$

and there exists a constant $c > 0$ such that for all $t \in [0, T]$ and $h \in (0, h_0)$ we have

$$(8.50) \quad |b_\ell(t; \eta, \zeta)| \leq c \|\eta\|_{\mathcal{V}(t)} \|\zeta\|_{\mathcal{V}(t)} \quad \text{for all } \eta, \zeta \in \mathcal{V}(t).$$

Proof. We simply apply [Lem. 8.15](#). \square

The bounds in [Lem. 8.16](#) allow to show some of the abstract error bounds required use the result of [Thm. 3.11](#).

Lemma 8.23. *We have the estimate:*

$$(8.51) \quad |w - w_h|_{L^\infty(\Omega(t))} + h |\nabla(w - w_h)|_{L^\infty(\Omega(t))} \leq ch^{k+1}.$$

If $\eta \in C_{\mathcal{H}}^1 \cap C_{\mathcal{V}}^0$ then $\eta \in C_{(\mathcal{H}, \phi^\ell)}^1$ and if $\eta \in C_{\mathcal{V}}^1 \cap C_{\mathcal{Z}_0}^0$ then $\eta \in C_{(\mathcal{V}, \phi^\ell)}^1$. Moreover

$$(8.52a) \quad \|\partial^\bullet \eta - \partial_\ell^\bullet \eta\|_{L^2(\Omega(t))} \leq ch^{k+1} \|\eta\|_{H^1(\Omega(t))} \quad \text{for } \eta \in C_{\mathcal{V}}^1$$

$$(8.52b) \quad \|\nabla(\partial^\bullet \eta - \partial_\ell^\bullet \eta)\|_{L^2(\Omega(t))} \leq ch^k \|\eta\|_{H^2(\Omega(t))} \quad \text{for } \eta \in C_{\mathcal{Z}_0}^1.$$

Proof. We write for $x \in \Omega_h(t)$ that

$$\begin{aligned} & w(\Lambda_h(x, t), t) - w_h(\Lambda_h(x, t)) \\ &= (w(\Lambda_h(x, t), t) - W_h(x, t)) + (W_h(x, t) - w_h(x, t)) \\ &= (w(\Lambda_h(x, t), t) - W_h(x, t)) + (W_h(x, t) - \partial_h^\bullet \Lambda_h(x, t)). \end{aligned}$$

This allows us to apply the interpolation theorem (Cor. 5.10) to the embedded velocity with the estimate (8.35) to achieve the estimate (8.51). The inclusions and bounds (8.52) follow from a simple calculation finding $\partial_\ell^\bullet \eta - \partial^\bullet \eta$ for appropriate η and (8.51). \square

For the remainder of this section, we will take $\mathcal{A}_\Omega^h = \mathcal{A}_\Omega^{-\ell}$, $\mathcal{B}_\Omega^h = \mathcal{B}_\Omega^{-\ell}$ and $\mathcal{C}_\Omega^h = \mathcal{C}_\Omega^{-\ell}$. and assume that \mathcal{A}_Ω is of class C^2 in space.

Lemma 8.24. *There exists a constant $c > 0$ such that for all $t \in [0, T]$ and all $h \in (0, h_0)$ the following holds for all $\eta_h, \zeta_h \in \mathcal{V}_h(t)$ with lifts $\eta_h^\ell, \zeta_h^\ell$:*

$$(8.53) \quad \left| m(t; \eta_h^\ell, \zeta_h^\ell) - m_h(t; \eta_h, \zeta_h) \right| \leq ch^{k+1} \left\| \eta_h^\ell \right\|_{\mathcal{V}(t)} \left\| \zeta_h^\ell \right\|_{\mathcal{V}(t)}$$

$$(8.54) \quad \left| g_\ell(t; \eta_h^\ell, \zeta_h^\ell) - g_h(t; \eta_h, \zeta_h) \right| \leq ch^{k+1} \left\| \eta_h^\ell \right\|_{\mathcal{V}(t)} \left\| \zeta_h^\ell \right\|_{\mathcal{V}(t)}$$

$$(8.55) \quad \left| a(t; \eta_h^\ell, \zeta_h^\ell) - a_h(t; \eta_h, \zeta_h) \right| \leq ch^k \left\| \eta_h^\ell \right\|_{\mathcal{V}(t)} \left\| \zeta_h^\ell \right\|_{\mathcal{V}(t)}$$

$$(8.56) \quad \left| b_\ell(t; \eta_h^\ell, \zeta_h^\ell) - b_h(t; \eta_h, \zeta_h) \right| \leq ch^k \left\| \eta_h^\ell \right\|_{\mathcal{V}(t)} \left\| \zeta_h^\ell \right\|_{\mathcal{V}(t)}$$

$$(8.57) \quad \left| g_\ell(t; \eta_h^\ell, \zeta_h^\ell) - g(t; \eta_h^\ell, \zeta_h^\ell) \right| \leq ch^k \left\| \eta_h^\ell \right\|_{\mathcal{V}(t)} \left\| \zeta_h^\ell \right\|_{\mathcal{V}(t)}$$

$$(8.58) \quad \left| b_\ell(t; \eta_h^\ell, \zeta_h^\ell) - b(t; \eta_h^\ell, \zeta_h^\ell) \right| \leq ch^k \left\| \eta_h^\ell \right\|_{\mathcal{V}(t)} \left\| \zeta_h^\ell \right\|_{\mathcal{V}(t)}.$$

For $\eta, \zeta \in \mathcal{Z}_0(t)$ with inverse lifts $\eta^{-\ell}, \zeta^{-\ell}$, we have

$$(8.59) \quad \left| a(t; \eta, \zeta) - a_h(t; \eta^{-\ell}, \zeta^{-\ell}) \right| \leq ch^{k+1} \|\eta\|_{\mathcal{Z}_0(t)} \|\zeta\|_{\mathcal{Z}_0(t)}$$

$$(8.60) \quad \left| b_\ell(t; \eta, \zeta) - b_h(t; \eta^{-\ell}, \zeta^{-\ell}) \right| \leq ch^{k+1} \|\eta\|_{\mathcal{Z}_0(t)} \|\zeta\|_{\mathcal{Z}_0(t)}$$

$$(8.61) \quad \left| a(t; \partial_\ell^\bullet \eta, \zeta) - a_h(t; \partial_h^\bullet \eta^{-\ell}, \zeta^{-\ell}) \right| \leq ch^{k+1} (\|\eta\|_{\mathcal{Z}_0(t)} + \|\partial^\bullet \eta\|_{\mathcal{Z}_0(t)}) \|\zeta\|_{\mathcal{Z}_0(t)}.$$

Proof. We use the notation $J_h = \sqrt{\det((\nabla \Lambda_h)^t (\nabla \Lambda_h))}$. We note that Λ_h is the identity on elements away from the boundary and hence $J_h = 1$ on these elements. We denote by $[J_h \neq 1]$ the union of boundary elements where $J_h \neq 1$ and note that we have

$$[J_h \neq 1]^\ell := \{\Lambda_h(x, t) : x \in [J_h \neq 1]\} \subset \{x \in \Omega : -h < d(x, t) \leq 0\}.$$

For (8.53), we have

$$\int_{\Omega(t)} \eta_h^\ell \zeta_h^\ell dx = \int_{\Omega_h(t)} \eta_h \zeta_h J_h dx.$$

Hence, we have, applying (8.38) and Lem. 8.14, that

$$\begin{aligned} \left| m(t; \eta_h^\ell, \zeta_h^\ell) - m_h(t; \eta_h, \zeta_h) \right| &= \left| \int_{\Omega_h(t)} \eta_h \zeta_h (J_h - 1) \right| dx \\ &\leq \int_{[J_h \neq 1]} |\eta_h| |\zeta_h| |J_h - 1| dx \leq ch^k \|\eta_h\|_{\mathcal{H}_h(t)} \|\zeta_h^\ell\|_{\mathcal{H}_h(t)}. \end{aligned}$$

Applying the narrow band trace inequality Lem. 8.2 this can be improved to

$$\begin{aligned} \left| m(t; \eta_h^\ell, \zeta_h^\ell) - m_h(t; \eta_h, \zeta_h) \right| &\leq \int_{[J_h \neq 1]} |\eta_h| |\zeta_h| |J_h - 1| dx \\ &\leq c \left| [J_h \neq 1]^\ell \right| h^k \|\eta_h^\ell\|_{L^2([J_h \neq 1]^\ell)} \|\zeta_h^\ell\|_{L^2([J_h \neq 1]^\ell)} \leq ch^{k+1} \|\eta_h\|_{\mathcal{V}_h(t)} \|\zeta_h^\ell\|_{\mathcal{V}_h(t)}. \end{aligned}$$

Similarly we have

$$\begin{aligned} &\int_{\Omega(t)} \mathcal{A}_\Omega \nabla \eta_h^\ell \cdot \nabla \zeta_h^\ell + \mathcal{B}_\Omega \eta_h^\ell \cdot \nabla \zeta_h^\ell + \mathcal{C}_\Omega \eta_h^\ell \zeta_h^\ell dx \\ &= \int_{[J_h \neq 1]} J_h (\nabla \Lambda_h) \mathcal{A}_\Omega^h (\nabla \Lambda_h)' \nabla \eta_h \cdot \nabla \zeta_h + J_h (\nabla \Lambda_h) \mathcal{B}_\Omega^h \eta_h \cdot \nabla \zeta_h \\ &\quad + J_h \mathcal{C}_\Omega^h \eta_h \zeta_h dx. \end{aligned}$$

Applying (8.36), (8.38) and Lem. 8.14 we can see (8.55). Again, by applying Lem. 8.2 we show the improved bound in (8.59).

We apply a similar process to the proof of (Ranner, 2013, Lemma 3.3.14) combined with the results of Lem. 8.16 and the narrow band trace inequality (Lem. 8.2) to show the estimates (8.54), (8.56) and (8.60).

Finally, (8.57) and (8.58) follow from the estimate (8.51). The bound (8.61) follows from (8.59), the fact that $(\partial_\ell^\bullet \eta)^{-\ell} = \partial_h^\bullet \eta^{-\ell}$ and the estimate (8.52). Indeed we can compute that

$$\begin{aligned} &\left| a(t; \partial_\ell^\bullet \eta, \zeta) - a_h(t; \partial_h^\bullet \eta^{-\ell}, \zeta^{-\ell}) \right| \\ &\leq \left| a(t; (\partial_\ell^\bullet \eta - \partial^\bullet \eta), \zeta) - a_h(t; (\partial_h^\bullet \eta^{-\ell} - (\partial^\bullet \eta)^{-\ell}), \zeta^{-\ell}) \right| \\ &\quad + \left| a(t; \partial^\bullet \eta, \zeta) - a_h(t; (\partial^\bullet \eta)^{-\ell}, \zeta^{-\ell}) \right| \\ &\leq ch^{2k} \|\eta\|_{\mathcal{Z}_0(t)} \|\zeta\|_{\mathcal{V}(t)} + ch^{k+1} \|\partial^\bullet \eta\|_{\mathcal{Z}_0(t)} \|\zeta\|_{\mathcal{Z}_0(t)}. \quad \square \end{aligned}$$

The remaining assumption to verify is the estimate (B3).

Lemma 8.25. *For any $t \in [0, T]$, let $z, \pi_h z$ be as in (3.20) and $\eta = z - \pi_h z$ then for all $\zeta \in \mathcal{Z}_0(t)$, we have*

$$(8.62) \quad |b(t; \eta, \zeta)| \leq c \left(\|\eta\|_{\mathcal{H}(t)} + h \|\eta\|_{\mathcal{V}(t)} + h^{k+1} \|z\|_{\mathcal{Z}(t)} \right) \|\zeta\|_{\mathcal{Z}_0(t)}.$$

Proof. The proof is based on a duality argument from Douglas and Dupont (1973). Fix $t \in [0, T]$. We use the Hilbert triple $((H^{1/2}(\Gamma(t)))', L^2(\Gamma(t)), H^{1/2}(\Gamma(t)))$ (at each time $t \in [0, T]$) and identify

$$(8.63) \quad (H^{1/2}(\Gamma(t)))' \langle \xi_\eta, \zeta \rangle_{H^{1/2}(\Gamma(t))} = (\eta, \zeta)_{L^2(\Gamma(t))} \text{ when } \eta \in L^2(\Gamma(t)), \zeta \in H^{1/2}(\Gamma(t)).$$

For any $\eta \in H^1(\Omega(t))$, let $\xi_\eta \in H^{1/2}(\Gamma(t))$ be the solution of the variational problem

$$(\xi_\eta, \zeta)_{H^{1/2}(\Gamma(t))} = (H^{1/2}(\Gamma(t)))' \langle \eta, \zeta \rangle_{H^{1/2}(\Gamma(t))} \quad \text{for all } \zeta \in H^{1/2}(\Gamma(t)).$$

By the trace theorem the trace of η lies in $L^2(\Gamma(t))$ so that interpreting the duality product on the right-hand side as an $L^2(\Gamma(t))$ inner-product (8.63), we see that

$$(8.64a) \quad \|\xi_\eta\|_{H^{1/2}(\Gamma(t))} = \|\eta\|_{(H^{1/2}(\Gamma(t)))'}$$

$$(8.64b) \quad \int_{\Gamma(t)} \xi_\eta \eta \, d\sigma = \|\eta\|_{(H^{1/2}(\Gamma(t)))'}^2.$$

This is a simple consequence of the trace theorem and the Riesz representation theorem.

As in Sec. 3.3, we introduce $\kappa > 0$ such that there exists a constant $c > 0$ such that

$$a^\kappa(t; \zeta, \zeta) := a(t; \zeta, \zeta) + \kappa m(t; \zeta, \zeta) \geq c \|\zeta\|_{\mathcal{V}(t)}^2 \quad \text{for all } \zeta \in \mathcal{V}(t).$$

We wish to estimate $\eta = z - \pi_h z$ in the $(H^{1/2}(\Gamma(t)))'$ -norm. We consider the dual problem: Given ξ_η , find $\mathcal{R}(\xi_\eta) \in H^1(\Omega(t))$ such that

$$(8.65) \quad a^\kappa(\zeta, \mathcal{R}(\xi_\eta)) = \int_{\Gamma(t)} \xi_\eta \zeta \, d\sigma \quad \text{for all } \zeta \in H^1(\Omega(t)).$$

The problem is a weak form of an elliptic problem with inhomogenous Neumann boundary data and has a unique solution which satisfies the regularity estimate (Ladyzhenskaya and Uraltseva, 1968; Gilbarg and Trudinger, 1983)

$$(8.66) \quad \|\mathcal{R}(\xi_\eta)\|_{H^2(\Omega(t))} \leq C \|\xi_\eta\|_{H^{1/2}(\Gamma(t))} = C \|\eta\|_{(H^{1/2}(\Gamma(t)))'},$$

for a constant independent of time t .

We see using (8.64b) and $\zeta = \eta$ in (8.65), that

$$(8.67) \quad \|\eta\|_{(H^{1/2}(\Gamma(t)))'} = \int_{\Gamma(t)} \xi_\eta \eta \, d\sigma = a^\kappa(\eta, \mathcal{R}(\xi_\eta)) = a^\kappa(\eta, \mathcal{R}(\xi_\eta) - I_h \mathcal{R}(\xi_\eta)) - a^\kappa(\eta, I_h \mathcal{R}(\xi_\eta)).$$

For the first term on the right hand side of (8.67), we apply the boundedness of a^κ and the interpolation estimate (8.45) to see

$$\begin{aligned} & |a^\kappa(\eta, \mathcal{R}(\xi_\eta) - I_h \mathcal{R}(\xi_\eta))| \\ & \leq c \|\eta\|_{H^1(\Omega(t))} \|\mathcal{R}(\xi_\eta) - I_h \mathcal{R}(\xi_\eta)\|_{H^1(\Omega(t))} \leq ch \|\eta\|_{H^1(\Omega(t))} \|\mathcal{R}(\xi_\eta)\|_{H^2(\Omega(t))}. \end{aligned}$$

For the second term on the right hand side, we apply the geometric estimates (8.55), (8.53) and (8.59) and the interpolation estimate (8.45) to see that

$$\begin{aligned} |a^\kappa(\eta, I_h \mathcal{R}(\xi_\eta))| &= \left| a^\kappa(\pi_h z, I_h \mathcal{R}(\xi_\eta)) - a_h^\kappa(\Pi_h z, \tilde{I}_h \mathcal{R}(\xi_\eta)) \right| \\ &\leq \left| a^\kappa(\pi_h z - z, I_h \mathcal{R}(\xi_\eta)) - a_h^\kappa(\Pi_h z - z^{-\ell}, \tilde{I}_h \mathcal{R}(\xi_\eta)) \right| \\ &\quad + \left| a^\kappa(z, I_h \mathcal{R}(\xi_\eta) - \mathcal{R}(\xi_\eta)) - a_h^\kappa(z^{-\ell}, \tilde{I}_h \mathcal{R}(\xi_\eta) - \mathcal{R}(\xi_\eta)^{-\ell}) \right| \\ &\quad + \left| a^\kappa(z, \mathcal{R}(\xi_\eta)) - a_h^\kappa(z^{-\ell}, \mathcal{R}(\xi_\eta)^{-\ell}) \right| \\ &\leq ch^{k+1} \|z\|_{\mathcal{Z}_0(t)} \|\mathcal{R}(\xi_\eta)\|_{\mathcal{Z}_0(t)}. \end{aligned}$$

Hence, combining the previous estimates and applying the dual regularity (8.66), we infer that

$$\begin{aligned} \|\eta\|_{(H^{1/2}(\Gamma(t)))'}^2 &\leq c \left(h \|\eta\|_{H^1(\Omega(t))} + h^{k+1} \|z\|_{\mathcal{Z}_0(t)} \right) \|\mathcal{R}(\xi_\eta)\|_{\mathcal{Z}_0(t)} \\ &\leq c \left(h \|\eta\|_{H^1(\Omega(t))} + h^{k+1} \|z\|_{\mathcal{Z}_0(t)} \right) \|\eta\|_{(H^{1/2}(\Gamma(t)))'}, \end{aligned}$$

and we have shown that

$$(8.68) \quad \|\eta\|_{(H^{1/2}(\Gamma(t)))'} \leq c \left(h \|\eta\|_{H^1(\Omega(t))} + h^{k+1} \|z\|_{\mathcal{Z}_0(t)} \right).$$

Returning to (B3), we now see that for $\eta = z - \pi_h z$ and $\varphi \in \mathcal{Z}_0(t)$ that

$$\begin{aligned} |b(t; \eta, \zeta)| &\leq \left| \int_{\Omega(t)} \mathcal{B}(w, \mathcal{A}_\Omega) \nabla \eta \cdot \nabla \zeta \, dx \right| + \left| \int_{\Omega(t)} \mathcal{B}_{\text{adv}}(w, \mathcal{B}_\Omega) \eta \cdot \nabla \zeta \, dx \right| \\ &\quad + \left| \int_{\Omega(t)} (\partial^\bullet \mathcal{C}_\Omega + \mathcal{C}_\Omega \nabla \cdot w) \eta \zeta \, dx \right| \\ &=: I_1 + I_2 + I_3. \end{aligned}$$

For I_1 , using the smoothness of \mathcal{A}_Ω and the divergence theorem, we have

$$\begin{aligned} I_1 &= \int_{\Omega(t)} \mathcal{B}(w, \mathcal{A}_\Omega) \nabla \eta \cdot \nabla \zeta \, dx \\ &= \sum_{i,j=1}^{n+1} \int_{\Omega(t)} \mathcal{B}(w, \mathcal{A}_\Omega)_{ij} \partial_{x_j} \eta \partial_{x_i} \zeta \, dx \\ &= \sum_{i,j=1}^{n+1} \int_{\Omega(t)} \partial_{x_j} (\mathcal{B}(w, \mathcal{A}_\Omega)_{ij} \eta \partial_{x_i} \zeta) \, dx - \sum_{i,j=1}^{n+1} \int_{\Omega(t)} \eta \sum_{i,j=1}^{n+1} \partial_{x_j} (\mathcal{B}(w, \mathcal{A}_\Omega)_{ij} \partial_i \zeta) \, dx \\ &= \sum_{i,j=1}^{n+1} \int_{\Gamma(t)} \eta \mathcal{B}(w, \mathcal{A}_\Omega)_{ij} \partial_{x_i} \zeta \nu_j \, d\sigma - \sum_{i,j=1}^{n+1} \int_{\Omega(t)} \eta \sum_{i,j=1}^{n+1} \partial_{x_j} (\mathcal{B}(w, \mathcal{A}_\Omega)_{ij} \partial_i \zeta) \, dx \\ &=: I_{11} + I_{12}. \end{aligned}$$

We interpret the first term, I_{11} , on the right hand side as the duality pairing between $H^{1/2}(\Gamma(t))$ and its dual (8.63) and apply (8.68) and the trace theorem to see

$$|I_{11}| \leq c \sum_{i=1}^{n+1} \|\eta\|_{(H^{1/2}(\Gamma(t)))'} \|\partial_{x_i} \zeta\|_{H^{1/2}(\Gamma(t))} \leq c \left(h \|\eta\|_{H^1(\Omega(t))} + h^{k+1} \|z\|_{\mathcal{Z}_0(t)} \right) \|\zeta\|_{\mathcal{Z}_0(t)}.$$

For I_{12} , we use the smoothness of \mathcal{A} and w to see

$$|I_{12}| \leq c \|\eta\|_{\mathcal{H}(t)} \|\zeta\|_{\mathcal{Z}_0(t)}.$$

Similarly for I_2 and I_3 we have

$$|I_2| + |I_3| \leq c \|\eta\|_{\mathcal{H}(t)} \|\zeta\|_{\mathcal{Z}_0(t)}. \quad \square$$

Finally, we have collected all the estimates we require to show the error bound.

Theorem 8.26. *Let $\mathcal{A}_\Omega \in C^2(\Omega_T)$, $\mathcal{A}_\Omega^h = \mathcal{A}_\Omega^{-\ell}$, $\mathcal{B}_\Omega^h = \mathcal{B}_\Omega^{-\ell}$ and $\mathcal{C}_\Omega^h = \mathcal{C}_\Omega^{-\ell}$ and let $\mathbf{u} \in L^2_{\mathcal{V}}$ be the solution of (8.15) which we assume satisfies*

$$(8.69) \quad \sup_{t \in (0, T)} \|\mathbf{u}\|_{\mathcal{Z}(t)}^2 + \int_0^T \|\partial^\bullet \mathbf{u}\|_{\mathcal{Z}(t)}^2 \, dt \leq C_u.$$

Let $U_h \in \mathcal{V}_h^1$ be the solution of the finite element scheme (8.40) and denote its lift by $u_h = U_h^\ell$. Then we have the following error estimate

$$(8.70) \quad \sup_{t \in (0, T)} \|\mathbf{u} - u_h\|_{\mathcal{H}(t)}^2 + h^2 \int_0^T \|\mathbf{u} - u_h\|_{\mathcal{V}(t)}^2 \, dt \leq c \|\mathbf{u} - u_{h,0}\|_{\mathcal{H}(t)}^2 + ch^{2k+2} C_u.$$

Proof. The proof is performed by applying the abstract result from [Thm. 3.11](#). We know the lift is stable from [Lem. 8.14](#). The existence and boundedness of g_ℓ and b_ℓ^k are dealt with in [Lem. 8.22](#). The interpolation properties (I1) and (I2) are shown in [Lem. 8.21](#). The geometric perturbation estimates (P1) to (P9) are shown in [Lem. 8.23](#) and [8.24](#) and (P7) follow from (P1) to (P4') and that fact that lifting and taking material derivatives commute ([Lem. 3.5](#)). We have shown (B3) in [Lem. 8.25](#). \square

9. APPLICATION II: PARABOLIC EQUATION ON AN EVOLVING SURFACE

In this section, we will formulate and analyse a finite element method for a parabolic equation posed on an evolving surface [\(1.5\)](#). We begin with some notation and a definition of the initial value problem. Our numerical approach will be to first discretise the domain and construct isoparametric surface finite element spaces based on the general theory in [Sec. 6](#) and [7](#). We will consider isoparametric finite elements of order k , which will be fixed throughout this section. We will analyse this method using both techniques from the general surface finite element constructions in [Sec. 6](#) and the abstract theory from [Sec. 3](#).

9.1. The domain and function spaces. Let $0 < T < \infty$ and $\Gamma_0 \subset \mathbb{R}^{n+1}$ be a compact sufficiently smooth hypersurface without boundary. Let $\{\Gamma(t)\}_{t \in [0, T]}$ be a family of evolving hypersurfaces such that there exists a sufficiently smooth mapping (called the *flow map*) $\Phi_{(\cdot)}(\cdot): [0, T] \times \Gamma_0 \rightarrow \mathbb{R}^{n+1}$ such that:

- (1) $\Phi_t(\cdot)$ is a diffeomorphism of Γ_0 onto $\Gamma(t)$ for each $t \in [0, T]$;
- (2) $\Phi_0(\cdot) = \text{Id}_{|\Gamma_0}$.

We call

$$w: S_T \left(:= \bigcup_{t \in (0, T)} \Gamma(t) \times \{t\} \right) \rightarrow \mathbb{R}^{n+1},$$

$$w(x, t) := \frac{\partial \Phi_t}{\partial t}((\Phi_t(\cdot))^{-1}(x)), \quad x \in \Gamma(t), t \in (0, T)$$

the material velocity field of $\Gamma(t)$ which also satisfies

$$(9.1) \quad \frac{\partial}{\partial t} \Phi_t(p) = w(\Phi_t(p), t), \quad t \in (0, T), \quad \Phi_0(p) = p.$$

We denote $\mathcal{H}(t) = L^2(\Gamma(t))$, $\mathcal{V}(t) = H^1(\Gamma(t))$ and $\mathcal{V}^*(t) = (H^1(\Gamma(t)))^*$. We will also make use of the spaces $\mathcal{Z}_0(t) = H^2(\Gamma(t))$ and $\mathcal{Z}(t) = H^{k+1}(\Gamma(t))$. We see that $\mathcal{Z}(t) \subset \mathcal{Z}_0(t) \subset \mathcal{V}(t)$ for each $t \in [0, T]$ and the inclusions are uniformly continuous. We define the push-forward operator ϕ_t by

$$(9.2) \quad (\phi_t \eta)(\cdot, t) := \eta(\Phi_{-t}(\cdot)) \quad \text{for } \eta \in \mathcal{H}_0.$$

$(L^2(\Gamma(t)), \phi_t)_{t \in [0, T]}$ and $(H^1(\Gamma(t)), \phi_t)_{t \in [0, T]}$ are compatible pairs ([Def. 2.2](#)), the spaces $L^2_{\mathcal{H}}$, $L^2_{\mathcal{V}}$ and $L^2_{\mathcal{V}^*}$ are well defined (c.f. [\(2.1\)](#)) and we have a well defined strong material derivative denoted by ∂^\bullet [\(2.4\)](#) (see [Vierling 2014, Lem. 3.2, 3.3](#)). $(\mathcal{V}(t), \mathcal{H}(t), \mathcal{V}^*(t))_{t \in [0, T]}$ form a Hilbert triple ([Def. 2.4](#)). We also have that $(\mathcal{Z}_0(t), \phi_t|_{\mathcal{Z}_0(t)})_{t \in [0, T]}$ and $(\mathcal{Z}(t), \phi_t|_{\mathcal{Z}(t)})_{t \in [0, T]}$ are compatible pairs. For details see [Alphonse et al. \(2015b\)](#).

Remark 9.1. For the well posedness of the partial differential equation [Prob. 9.2](#) we require that the boundary Γ is a C^2 -hypersurface and that the flow map $\Phi_{(\cdot)}(\cdot) \in C^2(0, T; C^2(\Omega_0))$.

See [Alphonse et al. \(2015b\)](#) for more details. For the approximation properties we derive we require that Γ is a C^{k+2} -hypersurface and that $\Phi_{(\cdot)}(\cdot) \in C^{k+2}(0, T; C^{k+2}(\Omega_0))$ with $\Phi_t: \Omega_0 \rightarrow \Omega(t)$ and $\Phi_{-t}: \Omega(t) \rightarrow \Omega$ both of class C^{k+2} .

We introduce a signed distance function for a closed surface $\Gamma(t)$. We assume that $\Gamma(t) = \partial\Omega(t)$ is the boundary of an open bounded domain. The oriented distance function for $\Gamma(t)$ is defined by

$$d(x, t) = \begin{cases} \inf\{|x - y| : y \in \Gamma(t)\} & \text{for } x \in \mathbb{R}^{n+1} \setminus \bar{\Omega}(t) \\ -\inf\{|x - y| : y \in \Gamma(t)\} & \text{for } x \in \Omega(t). \end{cases}$$

We can orient $\Gamma(t)$ by choosing the unit normal \mathbf{v} as

$$(9.3) \quad \mathbf{v}(x, t) = \nabla d(x, t) \quad \text{for } x \in \Gamma(t).$$

This allows us to define the (extended) Weingarten map by $\mathbb{H} := \{\mathbb{H}_{ij}\} = \{d_{x_i x_j}\}$ and the mean curvature by $H_\kappa := \text{trace } \mathbb{H}$. Note that, for example when $n = 2$, this definition of H_κ is the sum of the principal curvatures rather than the mean. For each time $t \in [0, T]$, there exists a narrow band $\mathcal{N}(t)$ such that the distance function $d(\cdot, t)$ is smooth and, for each $x \in \mathcal{N}(t)$ there exists a unique point $p(x, t) \in \Gamma(t)$ such that (see Lemma 14.16 of [Gilbarg and Trudinger \(1983\)](#) and [Foote \(1984\)](#))

$$(9.4) \quad x = p(x, t) + d(x, t)\mathbf{v}(p(x, t), t).$$

We call the operator $p(\cdot, t): \mathcal{N}(t) \rightarrow \Gamma(t)$ the normal projection operator and note that $p(\cdot, t)$ is also smooth. We use this projection to extend the unit normal and Weingarten map to be defined in $\mathcal{N}(t)$ by $\mathbf{v}(x, t) = \mathbf{v}(p(x, t), t)$ and $\mathbb{H}(x, t) = \mathbb{H}(p(x, t), t)$. See [Gilbarg and Trudinger \(1983, Lem. 14.16\)](#); [Foote \(1984\)](#) for more details.

9.2. The initial value problem. We assume that $\mathcal{A}_\Gamma \in C^1(S_T; \mathbb{R}^{(n+1) \times (n+1)})$ is a symmetric diffusion tensor which maps the tangent space of $\Gamma(t)$ at a point into itself, and there exists $a_0 > 0$ such that for all $t \in [0, T]$

$$\mathcal{A}_\Gamma(\cdot, t)\xi \cdot \xi \geq a_0 |\xi|^2 \quad \text{for all } \xi \in \mathbb{R}^{n+1}, \xi \cdot \mathbf{v}(\cdot, t) = 0.$$

$\mathcal{B}_\Gamma \in C^1(S_T; \mathbb{R}^{n+1})$ is a smooth tangential vector field and $\mathcal{C}_\Gamma \in C^1(S_T)$ is a smooth scalar field.

We consider the initial value problem

Problem 9.2. Find \mathbf{u} such that

$$(9.5a) \quad \partial^\bullet \mathbf{u} + \nabla_\Gamma \cdot (\mathcal{B}_\Gamma \mathbf{u}) - \nabla_\Gamma \cdot (\mathcal{A}_\Gamma \nabla_\Gamma \mathbf{u}) + \mathcal{C}_\Gamma \mathbf{u} + (\nabla_\Gamma \cdot \mathbf{w}) \mathbf{u} = 0 \quad \text{on } \Gamma(t)$$

$$(9.5b) \quad \mathbf{u}(0) = \mathbf{u}_0 \quad \text{on } \Gamma_0.$$

Remark 9.3. Writing $\mathbf{w} = w_\tau + w_\nu$ for a decomposition of \mathbf{w} into tangential and normal components, the problem (1.5) is recovered by setting $\mathcal{A}_\Gamma = a_\Gamma$, $\mathcal{B}_\Gamma = b_\Gamma - w_\tau$ and $\mathcal{C}_\Gamma = c_\Gamma - \nabla_\Gamma \cdot w_\nu$.

Transport formulae. The following transport formulae hold on $\omega(t) \equiv \Gamma(t)$ and on portions $\{\omega(t) \subset \Gamma(t)\}_{t \in [0, T]}$ of the domain $\{\Gamma(t)\}_{t \in [0, T]}$, which follow the flow $\omega(t) = \Phi_t(\omega(0))$ for $t \in [0, T]$, and have Lipschitz boundaries at each time :-

- For $\eta, \zeta \in C^1_{\mathcal{H}}$

$$(9.6) \quad \frac{d}{dt} \int_{\omega(t)} \eta \zeta \, d\sigma = \int_{\omega(t)} (\partial^\bullet \eta \zeta + \eta \partial^\bullet \zeta) \, d\sigma + g(t; \eta, \zeta),$$

where

$$g(t; \eta, \zeta) = \int_{\omega(t)} \eta \zeta \nabla_{\Gamma} \cdot w \, d\sigma.$$

More precisely, we can show that [Ass. 2.6](#) holds for $\mathcal{H}(t) = L^2(\Gamma(t))$ ([Alphonse et al., 2015b](#), Sec. 4.1).

- For $\eta, \zeta \in C_{\mathcal{V}}^1$, we have the identity

$$(9.7) \quad \begin{aligned} \frac{d}{dt} \int_{\omega(t)} \mathcal{A}_{\Gamma} \nabla_{\Gamma} \eta \cdot \nabla_{\Gamma} \zeta \, d\sigma &= \int_{\Gamma(t)} \mathcal{A}_{\Gamma} \nabla_{\Gamma} \partial^{\bullet} \eta \cdot \nabla_{\Gamma} \zeta + \mathcal{A}_{\Gamma} \nabla_{\Gamma} \eta \cdot \nabla_{\Gamma} \partial^{\bullet} \zeta \, d\sigma \\ &\quad + \int_{\Gamma(t)} \mathcal{B}(w, \mathcal{A}_{\Gamma}) \nabla_{\Gamma} \eta \cdot \nabla_{\Gamma} \zeta \, d\sigma, \end{aligned}$$

where $\mathcal{B}(w, \mathcal{A}_{\Gamma})$ is given by

$$(9.8) \quad \mathcal{B}(w, \mathcal{A}_{\Gamma}) = \partial^{\bullet} \mathcal{A}_{\Gamma} + \nabla_{\Gamma} \cdot w \mathcal{A}_{\Gamma} - 2D(w, \mathcal{A}_{\Gamma})$$

and $D(w, \mathcal{A}_{\Gamma})$ is the rate of deformation tensor

$$D(w, \mathcal{A}_{\Gamma})_{ij} = \frac{1}{2} \sum_{k=1}^{n+1} \{ (\mathcal{A}_{\Gamma})_{ik} (\nabla_{\Gamma})_k w_j + (\mathcal{A}_{\Gamma})_{jk} (\nabla_{\Gamma})_k w_i \} \quad \text{for } i, j = 1, \dots, n+1.$$

- For $\eta \in C_{\mathcal{H}}^1, \zeta \in C_{\mathcal{V}}^1$, we have

$$(9.9) \quad \begin{aligned} \frac{d}{dt} \int_{\omega(t)} \mathcal{B}_{\Gamma} \eta \cdot \nabla_{\Gamma} \zeta \, d\sigma &= \int_{\omega(t)} \{ \mathcal{B}_{\Gamma} \partial^{\bullet} \eta \cdot \nabla_{\Gamma} \zeta + \mathcal{B}_{\Gamma} \eta \cdot \nabla_{\Gamma} \partial^{\bullet} \zeta \} \, d\sigma \\ &\quad + \int_{\omega(t)} \mathcal{B}_{\text{adv}}(w, \mathcal{B}_{\Gamma}) \eta \cdot \nabla_{\Gamma} \zeta \, d\sigma, \end{aligned}$$

where $\mathcal{B}_{\text{adv}}(w, \mathcal{B}_{\Gamma})$ is given by

$$\mathcal{B}_{\text{adv}}(w, \mathcal{B}_{\Gamma}) = \partial^{\bullet} \mathcal{B}_{\Gamma} + \mathcal{B}_{\Gamma} \nabla_{\Gamma} \cdot w - \sum_{j=1}^{n+1} (\mathcal{B}_{\Gamma})_j (\nabla_{\Gamma})_j w.$$

Remark 9.4. The identity (9.9) is equivalent to ([Elliott and Venkataraman, 2015](#), Lem. A.1). The proof of (9.7) and (9.9) follows from applying (9.6) with the identity (in which \mathbf{v} is the unit normal to $\Gamma(t)$)

$$(9.10) \quad \partial^{\bullet} (\nabla_{\Gamma})_i \chi = (\nabla_{\Gamma})_i \partial^{\bullet} \chi - \sum_{j=1}^{n+1} (\nabla_{\Gamma})_i w_j (\nabla_{\Gamma})_j \chi + \left(\nabla_{\Gamma}(w \cdot \mathbf{v}) \cdot \nabla_{\Gamma} \chi - \sum_{j,l=1}^{n+1} w_j (\nabla_{\Gamma})_i \chi (\nabla_{\Gamma})_l \mathbf{v}_j \right) \mathbf{v}_i.$$

9.3. The bilinear forms and transport formulae. We define

$$\begin{aligned} m(t; \eta, \zeta) &:= \int_{\Gamma(t)} \eta \zeta \, d\sigma && \eta, \zeta \in \mathcal{H}(t) \\ g(t; \eta, \zeta) &:= \int_{\Gamma(t)} \eta \zeta \nabla_{\Gamma} \cdot w \, d\sigma && \eta, \zeta \in \mathcal{H}(t) \\ a(t; \eta, \zeta) &:= a_s(t; \eta, \zeta) + a_n(t; \eta, \zeta) && \eta, \zeta \in \mathcal{V}(t) \\ a_s(t; \eta, \zeta) &:= \int_{\Gamma(t)} \mathcal{A}_{\Gamma} \nabla_{\Gamma} \eta \cdot \nabla_{\Gamma} \zeta + \mathcal{C}_{\Gamma} \eta \zeta \, d\sigma && \eta, \zeta \in \mathcal{V}(t) \\ a_n(t; \eta, \zeta) &:= \int_{\Gamma(t)} \mathcal{B}_{\Gamma} \eta \cdot \nabla_{\Gamma} \zeta \, d\sigma && \eta \in \mathcal{H}(t), \zeta \in \mathcal{V}(t). \end{aligned}$$

We can apply (9.6) (9.7) and (9.9) to see that:

$$(9.11) \quad \frac{d}{dt} m(t; \eta, \zeta) = m(t; \partial^\bullet \eta, \zeta) + m(t; \eta, \partial^\bullet \zeta) + g(t; \eta, \zeta) \quad \text{for all } \eta, \zeta \in C_{\mathcal{H}}^1$$

$$(9.12) \quad \frac{d}{dt} a_s(t; \eta, \zeta) = a_s(t; \partial^\bullet \eta, \zeta) + a_s(t; \eta, \partial^\bullet \zeta) + b_s(t; \eta, \zeta) \quad \text{for all } \eta, \zeta \in C_{\mathcal{V}}^1$$

$$(9.13) \quad \frac{d}{dt} a_n(t; \eta, \zeta) = a_n(t; \partial^\bullet \eta, \zeta) + a_n(t; \eta, \partial^\bullet \zeta) + b_n(t; \eta, \zeta) \quad \text{for all } \eta \in C_{\mathcal{H}}^1, \zeta \in C_{\mathcal{V}}^1$$

with

$$b_s(t; \eta, \zeta) := \int_{\Gamma(t)} \mathcal{B}(w, \mathcal{A}_\Gamma) \nabla_\Gamma \eta \cdot \nabla_\Gamma \zeta + (\partial^\bullet \mathcal{C}_\Gamma + \mathcal{C}_\Gamma \nabla_\Gamma \cdot w) \eta \zeta \, d\sigma$$

$$b_n(t; \eta, \zeta) := \int_{\Gamma(t)} \mathcal{B}_{\text{adv}}(w, \mathcal{B}_\Gamma) \eta \cdot \nabla_\Gamma \zeta \, d\sigma.$$

We define $b(t; \cdot, \cdot): \mathcal{V}(t) \times \mathcal{V}(t) \rightarrow \mathbb{R}$ to be

$$b(t; \eta, \zeta) := b_s(t; \eta, \zeta) + b_n(t; \eta, \zeta) \quad \text{for } \eta, \zeta \in \mathcal{V}(t).$$

9.4. Variational formulation. The weak formulation of Prob. 9.2 becomes

Problem 9.5. Given $u_0 \in L^2(\Gamma_0)$, find u such that for almost every $t \in (0, T)$ we have

$$(9.14) \quad \begin{aligned} m(t; \partial^\bullet u, \zeta) + g(t; u, \zeta) + a(t; u, \zeta) &= 0 \quad \text{for all } \zeta \in H^1(\Gamma(t)) \\ u(0) &= u_0. \end{aligned}$$

We have the following well-posedness result.

Theorem 9.6. There exists a unique solution u to (9.14) which satisfies

$$(9.15) \quad \sup_{t \in [0, T]} \|u\|_{L^2(\Gamma(t))}^2 + \int_0^T \|u\|_{H^1(\Gamma(t))}^2 \, dt \leq c \|u_0\|_{L^2(\Gamma_0)}^2,$$

and if $u_0 \in H^1(\Gamma_0)$ then

$$(9.16) \quad \sup_{t \in [0, T]} \|u\|_{H^1(\Gamma(t))}^2 + \int_0^T \|\partial^\bullet u\|_{L^2(\Gamma(t))}^2 \, dt \leq c \|u_0\|_{H^1(\Gamma_0)}^2.$$

Proof. We simply check the assumptions required for Thm. 2.15. For Ass. 2.6 and 2.9 we refer to Alphonse et al. (2015b, Sec. 4 and Sec. 5). Ass. 2.13 is a consequence of Rem. 2.14. The assumptions (M1) and (M2) follow simply since $m(t; \cdot, \cdot)$ is the $\mathcal{H}(t) = L^2(\Gamma(t))$ -inner product. (G1) holds from (9.6) and (2.6) from the assumption that $\nabla_\Gamma \cdot w$ is uniformly bounded in space and time. The bilinear form $a(t; \cdot, \cdot)$ is differentiable in time, hence measurable (A1). The coercivity of a (A3) follows from a standard calculation since \mathcal{A}_Γ is positive definite and \mathcal{C}_Γ is bounded.. The smoothness of $\mathcal{A}_\Gamma, \mathcal{B}_\Gamma$ and \mathcal{C}_Γ imply that a_s and a_n are bounded (A_s4), (A_n4). The existence of the bilinear forms b_s (B_s1) and b_n (B_n1) follow from (9.12) and (9.13) and the bounds (B_s2) and (B_n2) from the smoothness of $\mathcal{A}_\Gamma, \mathcal{B}_\Gamma$ and \mathcal{C}_Γ . \square

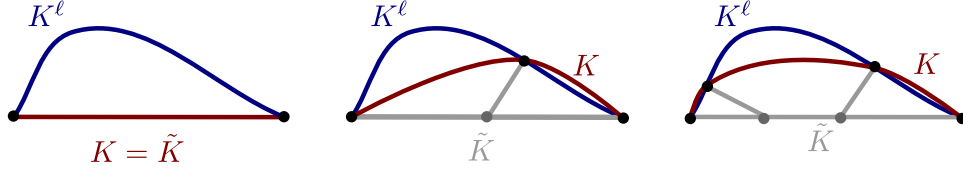


FIGURE 9.1. Examples of construction of an isoparametric surface finite element for $k = 1$ (left), $k = 2$ (centre), $k = 3$ (right). The Lagrange nodes \tilde{a}_i are shown in grey on \tilde{K} which are lifted to $K \subset \Gamma_{h,0}$ (red) to the Lagrange nodes \tilde{a}_i (black) which lie on the smooth surface $K^\ell \subset \Gamma_0$ (blue).

9.5. Discretisation of the domain and finite element spaces. The first stage in developing our finite element method is to define the approximate computational domain $\{\Gamma_h(t)\}$. We do this by constructing an isoparametric approximation of Γ_0 which is then pushed-forwards under an approximation to the flow Φ_t . The result will be that the Lagrange points of $\Gamma_h(t)$ lie on the surface $\Gamma(t)$ for all times and evolving according to the velocity w . In this sense, $\Gamma_h(t)$ can be considered as an interpolation of $\Gamma(t)$. Recall that p denotes the normal projection operator (9.4) and that k is the order of isoparametric finite elements we will use. Throughout the remainder of this section we will denote global discrete quantities with a subscript $h \in (0, h_0)$, which is related to element size. We assume implicitly that these structures exist for each h in this range (see also Rem. 6.11).

We will use the simplicial, Lagrange reference element $(\hat{K}, \hat{P}, \hat{\Sigma})$ from Ex. 4.2. We start by constructing a family of time dependent element reference maps (Def. 6.1) which defines an evolving conforming subdivision $\{\mathcal{T}_h(t)\}$ (Def. 6.27(a)) of an evolving triangulated hypersurface $\{\Gamma_h(t)\}$ (Def. 6.27(b)).

Let $\tilde{\Gamma}_{h,0}$ be a polyhedral approximation of Γ_0 equipped with a quasi-uniform, conforming subdivision $\tilde{\mathcal{T}}_{h,0}$ (Def. 6.14(d)). We restrict the vertices of $\tilde{\Gamma}_{h,0}$ to lie on the surface Γ_0 and denote by \tilde{h}_0 the maximum element domain diameter on $\tilde{\Gamma}_{h,0}$ (Def. 6.14(b)). We assume that \tilde{h}_0 is sufficiently small and $\tilde{\Gamma}_{h,0}$ is such that $p(\cdot, 0)$ is a smooth bijection from $\tilde{\Gamma}_{h,0}$ onto Γ_0 . More precisely, for each $\tilde{K} \in \tilde{\mathcal{T}}_{h,0}$, there exists an affine map $F_{\tilde{K}}: \hat{K} \rightarrow \mathbb{R}^{n+1}$ which satisfies the assumptions of Def. 6.1 so that we can define a surface finite element $(\tilde{K}, \tilde{P}, \tilde{\Sigma})$ using (6.2). Note that the vertices of \tilde{K} lie on Γ but the other Lagrange points may not. We assume the collection of all Lagrange points satisfy (6.20). We write \tilde{I} for the local interpolation operator over $(\tilde{K}, \tilde{P}, \tilde{\Sigma})$ (6.13) and define an initial element reference map $F_{K_0}: \hat{K} \rightarrow \mathbb{R}^{n+1}$ by

$$F_{K_0}(\hat{x}) = [\tilde{I}(p(\cdot, 0))](F_{\tilde{K}}(\hat{x})) \quad \text{for } \hat{x} \in \hat{K}.$$

An example of element domains (6.2a) defined by F_{K_0} is given for $k = 1, 2, 3$ in Fig. 9.1. We denote the union of all elements constructed in this way $\Gamma_{h,0}$ which is a triangulated hypersurface (Def. 6.14(a)) equipped with a conforming subdivision $\mathcal{T}_{h,0}$ (Def. 6.14(d)), the set of all element domains K .

To complete the construction of $F_{K(t)}: \hat{K} \rightarrow \mathbb{R}^{n+1}$, for $K_0 \in \mathcal{T}_{h,0}$, we consider the element flow map $\Phi_t^K: K_0 \rightarrow K(t)$ (Def. 6.25(b)) defined by

$$\Phi_t^K := I_{K_0}[\Phi_t(p(\cdot, 0))] \quad \text{for all } K_0 \in \mathcal{T}_{h,0},$$

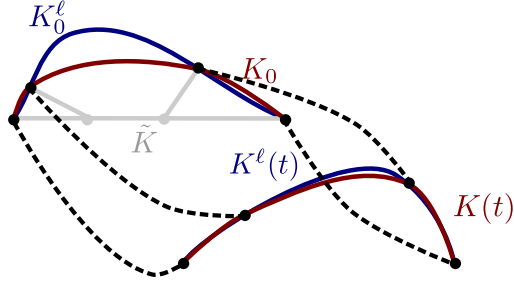


FIGURE 9.2. Examples of construction of an isoparametric evolving surface finite element for $k = 3$. The Lagrange nodes $a_i(t)$ follow the dashed black trajectories from the initial element $K_0 \subset \Gamma_{h,0}$ to a element $K(t) \subset \Gamma_h(t)$.

which is a bijection onto its image and we denote its inverse by Φ_{-t}^K . An example is shown in Fig. 9.2. Using (6.23), Φ_t^K defines an evolving reference element map:

$$F_{K(t)}(\hat{x}) = \Phi_t^K(F_{K_0}(\hat{x})) \quad \text{for } \hat{x} \in \hat{K}.$$

Using (6.2), this defines an evolving surface finite element $(K(t), P^K(t), \Sigma^K(t))_{t \in [0, T]}$ (Def. 6.25(a)).

We call the set of such elements $\mathcal{T}_h(t)$ and the union $\Gamma_h(t)$ and write a global discrete flow map $\Phi_t^h: \Gamma_{h,0} \rightarrow \Gamma_h(t)$ given element-wise by $\Phi_t^h|_{K_0} := \Phi_t^K$ (Def. 6.27(c)). By h we denote the maximum mesh diameter over time (6.25):

$$h := \max_{t \in [0, T]} \max_{K(t) \in \mathcal{T}_h(t)} \text{diam}(\tilde{K}(t)).$$

Our construction implies that (6.26) holds since each of the transformation from $\tilde{\Gamma}_{h,0}$ are continuous.

We will use two Hilbert spaces defined over $\Gamma_h(t)$. First we will denote by $\mathcal{H}_h(t) := L^2(\Gamma_h(t))$ and by $\mathcal{V}_h(t) := H_T^1(\mathcal{T}_h(t))$ (6.19). We equip each space with a norm:

$$(9.17) \quad \|\eta_h\|_{\mathcal{H}_h(t)} := \|\eta_h\|_{L^2(\Gamma_h(t))} = \left(\int_{\Gamma_h(t)} \eta_h^2 d\sigma_h \right)^{\frac{1}{2}}$$

$$(9.18) \quad \|\eta_h\|_{\mathcal{V}_h(t)} := \|\eta_h\|_{H^1(\mathcal{T}_h(t))} = \left(\sum_{K(t) \in \mathcal{T}_h(t)} \int_{K(t)} |\nabla_K \eta_h|^2 + \eta_h^2 d\sigma_h \right)^{\frac{1}{2}}.$$

We note that each element reference map $F_{K(t)}$ is an element of \hat{P} so that at each time t the triple $(K(t), P(t), \Sigma(t))$ is an isoparametric surface finite element. Furthermore, we can use the basis functions of \hat{P} to decompose $F_{K(t)}$:

$$F_{K(t)}(\hat{x}) = \sum_{i=1}^{N_K} F_{K(t)}(\hat{a}_i) \hat{\chi}_i(\hat{x}).$$

In particular, this implies that the evolving triangulated surface $\Gamma_h(t)$ only depends on the evolving of the Lagrange points $\{a_i(t)\}_{i=1}^N$ which we can infer satisfy

$$\dot{a}_i(t) = w(a_i(t), t).$$

We define a global evolving surface finite element space (Def. 6.28(a)) by

$$(9.19) \quad \mathcal{S}_h(t) := \left\{ \chi_h = (\chi_h)_{K(t) \in \mathcal{T}_h(t)} \in \prod_{K \in \mathcal{T}_h(t)} \{ \hat{\chi} \circ F_{K(t)}^{-1} : \hat{\chi} \in P_k(\hat{K}) \} : \right. \\ \left. \chi_K(a(t)) = \chi_{K'(t)} \text{ for all } K(t), K'(t) \in \mathcal{T}(a(t)), \text{ for all } a(t) \in \mathcal{N}_h(t). \right\}$$

Using Lem. 6.20 we can identify elements in $\mathcal{S}_h(t)$ as continuous functions and $\mathcal{S}_h(t) \subset \mathcal{V}_h(t)$.

Remark 9.7. This construction is a generalisation of the construction of Dziuk and Elliott (2007). Indeed, in the case that we wish to consider affine finite elements, it is worth noting that $\tilde{I}p(\tilde{x}, 0) = \tilde{x}$ for $\tilde{x} \in \tilde{K}$ and $K = \tilde{K}$. A different view of the same construction is given by Kovács (2018) and at each time our construction coincides with the work of Demlow (2009).

We will assume that the evolving subdivision $\{\mathcal{T}_h(t)\}_{t \in [0, T]}$ is uniformly quasi-uniform (Def. 6.29(c)). It is clear that our construction maintains the conformity of the initial base triangulation $\tilde{\mathcal{T}}_{h,0}$.

Proposition 9.8. *The evolving surface finite element space $\{\mathcal{S}_h(t)\}_{t \in [0, T]}$ defined by the above construction consists of evolving k -surface finite elements (Def. 6.25(d)) over a uniformly k -regular subdivision (Def. 6.29(b)).*

Proof. The proof follows in the same way as Prop. 8.9 and we do not give full details here. The only part to check is that the discrete flow map Φ_t^h is uniformly bounded in $W^{2,\infty}(\mathcal{T}_{h,0})$. However, this follows directly from the definition of Φ_t^K as an interpolation of $\Phi_t(p(\cdot, 0))$ which is a smooth function. \square

The element flow map Φ_t^K defines a velocity on each element W_K (Def. 6.25(c)) by

$$\frac{d}{dt} \Phi_t^K(\cdot) = W_K(\Phi_t^K(\cdot), t) \quad \text{for } t \in [0, T].$$

This can be combined into a global velocity W_h (Def. 6.27(d)). We note that the global velocity is determined purely by the velocity of the vertices $\{a_i(t)\}_{i=1}^N$:

$$(9.20) \quad W_h(x, t) = \sum_{i=1}^n w(a_i(t), t) \chi_i(x, t) \quad \text{for } x \in \Gamma_h(t).$$

We also have a discrete push forward map (Def. 6.27(e)) ϕ_t^h on $\mathcal{H}_h(t)$ by

$$\phi_t^h(\eta_h)(x) = \eta_h(\Phi_{-t}^h(x)) \quad \text{for } x \in \Gamma_h(t), t \in [0, T].$$

Since we have constructed a uniformly k -regular mesh, we infer that $(\mathcal{H}_h(t), \phi_t^h)_{t \in [0, T]}$ is a compatible pair (Lem. 6.30) and we may define the space $C_{\mathcal{H}_h}^1$ (2.2) and a discrete material derivative by (3.3):

$$\partial_h^\bullet \eta_h = \phi_t^h \left(\frac{d}{dt} (\phi_{-t}^h \eta_h) \right).$$

We also have that $(\mathcal{V}_h(t), \phi_t^h|_{\mathcal{V}_{h,0}})_{t \in [0, T]}$ and $(\mathcal{S}_h(t), \phi_t^h|_{\mathcal{S}_{h,0}})_{t \in [0, T]}$ are compatible pairs (Rem. 6.31) so we may define the spaces $C_{\mathcal{V}_h}^1$ and $C_{\mathcal{S}_h}^1$.

Lemma 9.9. *For $t \in [0, T]$ and for each $K(t) \in \mathcal{T}_h(t)$, let \mathcal{A}_Γ^K be a smooth, positive-definite, diffusion tensor on $K(t)$, which maps the tangent space of $K(t)$ to itself, and \mathcal{B}_Γ^K*

be a smooth tangential vector field on $K(t)$ for each $K(t) \in \mathcal{T}_h(t)$ and $t \in [0, T]$. Then for $\eta_h \in C^1_{\mathcal{H}_h}$:

$$(9.21) \quad \frac{d}{dt} \int_{\Gamma_h(t)} \eta_h \, d\sigma_h = \int_{\Gamma_h(t)} \partial_h^\bullet \eta_h + \eta_h \nabla_{\Gamma_h} \cdot W_h \, d\sigma_h.$$

For all $\eta_h, \zeta_h \in C^1_{\mathcal{V}_h}$, we have

$$(9.22) \quad \begin{aligned} \frac{d}{dt} \sum_{K(t) \in \mathcal{T}_h(t)} \int_{K(t)} \mathcal{A}_\Gamma^K \nabla_K \eta_h \cdot \nabla_K \zeta_h \, d\sigma_h \\ = \sum_{K(t) \in \mathcal{T}_h(t)} \int_{K(t)} \mathcal{A}_\Gamma^K \nabla_K \partial_h^\bullet \eta_h \cdot \nabla_K \zeta_h + \mathcal{A}_\Gamma^K \nabla_K \eta_h \cdot \nabla_K \partial_h^\bullet \zeta_h \, d\sigma_h \\ + \sum_{K(t) \in \mathcal{T}_h(t)} \int_{K(t)} \mathcal{B}_K(W_K, \mathcal{A}_\Gamma^K) \nabla_K \eta_h \cdot \nabla_K \eta_h \, d\sigma_h, \end{aligned}$$

and for all $\eta_h \in C^1_{\mathcal{V}_h}, \zeta_h \in C^1_{\mathcal{H}_h}$, we have

$$(9.23) \quad \begin{aligned} \frac{d}{dt} \sum_{K(t) \in \mathcal{T}_h(t)} \int_{K(t)} \mathcal{B}_\Gamma^K \eta_h \cdot \nabla_K \zeta_h \, d\sigma_h \\ = \sum_{K(t) \in \mathcal{T}_h(t)} \int_{K(t)} \mathcal{B}_\Gamma^K (\partial_h^\bullet \eta_h \cdot \nabla_K \zeta_h + \eta_h \cdot \nabla_K \partial_h^\bullet \zeta_h) \, d\sigma_h \\ + \sum_{K(t) \in \mathcal{T}_h(t)} \int_{K(t)} \mathcal{B}_{\text{adv},K}(W_K, \mathcal{B}_\Gamma^K) \eta_h \cdot \nabla_K \zeta_h \, d\sigma_h, \end{aligned}$$

where \mathcal{B}_K and $\mathcal{B}_{\text{adv},K}$ are given by

$$\begin{aligned} \mathcal{B}_K(W_K, \mathcal{A}_\Gamma^K) &= \partial_K^\bullet \mathcal{A}_\Gamma^K + \nabla_K \cdot W_K \mathcal{A}_\Gamma^K - 2D_h(W_h) \\ \mathcal{B}_{\text{adv},K}(W_K, \mathcal{B}_\Gamma^K) &= \partial_K^\bullet \mathcal{B}_\Gamma^K + \mathcal{B}_\Gamma^K \nabla_K \cdot W_K - \sum_{j=1}^{n+1} (\mathcal{B}_\Gamma^K)_j (\nabla_K)_j W_K, \end{aligned}$$

and D_h is the rate of deformation tensor

$$D(w)_{ij} = \frac{1}{2} \sum_{k=1}^{n+1} (\mathcal{A}_\Gamma^K)_{ik} (\nabla_K)_k (W_K)_j + (\mathcal{A}_\Gamma^K)_{jk} (\nabla_K)_k (W_K)_i \quad \text{for } i, j = 1, \dots, n+1.$$

Proof. We note that the left hand side may be decomposed into individual elements then apply (9.6), (9.7) and (9.9) on each element. \square

9.6. Construction of the lifted finite element space. Recalling the normal projection operator (9.4), we define the global lifting map $\Lambda_h(\cdot, t): \Gamma_h(t) \rightarrow \Gamma(t)$ (Def. 7.7(b)) by

$$\Lambda_h(x, t) := p(x, t) \quad \text{for } x \in \Gamma_h(t),$$

and denote the restriction to each element by $\Lambda_K(\cdot, t) := \Lambda_h(\cdot, t)|_{K(t)}$ for each $K(t) \in \mathcal{T}_h(t)$.

For $\eta_h: \Gamma_h(t) \rightarrow \mathbb{R}$, we denote its lift by $\eta_h^\ell(x)$ given by

$$\eta_h^\ell(\Lambda_h(x, t)) = \eta_h(x) \quad \text{for } x \in \Gamma_h(t)$$

and for $\eta: \Gamma(t) \rightarrow \mathbb{R}$, we denote its inverse lift by $\eta^{-\ell}(x)$ given by

$$\eta^{-\ell}(x) = \eta_h(\Lambda_h(x, t)) \quad \text{for } x \in \Gamma_h(t).$$

For each $t \in [0, T]$ and each $K(t) \in \mathcal{T}_h(t)$, we use Def. 7.1 to construct an associated lifted surface finite element $(K^\ell(t), P^\ell(t), \Sigma^\ell(t))$. We assume the domains $\{\Gamma_h(t)\}_{t \in [0, T]}$

are such that the set of lifted element domains $\mathcal{T}_h^\ell(t)$ defines an exact decomposition of $\Gamma(t)$ (Def. 7.7(a)) at each $t \in [0, T]$.

We use the lift to define the space of lifted finite element functions $\mathcal{S}_h^\ell(t)$ (Def. 7.7(d)) by

$$\mathcal{S}_h^\ell(t) := \{\chi_h^\ell : \chi_h \in \mathcal{S}_h(t)\}.$$

We continue by showing some basic geometric estimates. These geometric estimates have been given by (Kovács, 2018, Lemma 5.2).

Lemma 9.10. *Under the above smoothness assumptions, we have*

$$(9.24) \quad \sup_{t \in [0, T]} \max_{K(t) \in \mathcal{T}_h(t)} \|d\|_{L^\infty(K(t))} \leq ch^{k+1}.$$

$$(9.25) \quad \sup_{t \in [0, T]} \max_{K(t) \in \mathcal{T}_h(t)} \|\mathbf{v} - \mathbf{v}_K\|_{L^\infty(K(t))} \leq ch^k$$

$$(9.26) \quad \sup_{t \in [0, T]} \max_{K(t) \in \mathcal{T}_h(t)} \|\mathbb{H} - \mathbb{H}_K\|_{L^\infty(K(t))} \leq ch^{k-1},$$

where $\mathbb{H}_K := \nabla_K \mathbf{v}_K$. Writing δ_h for the quotient between discrete and continuous surface measures so that $d\sigma = \delta_h d\sigma_h$, we have

$$(9.27) \quad \sup_{t \in [0, T]} \max_{K(t) \in \mathcal{T}_h(t)} \|1 - \delta_h\|_{L^\infty(K(t))} \leq ch^{k+1}.$$

Lemma 9.11. *Let $\{\mathcal{T}_h^\ell(t)\}_{t \in [0, T]}$ be the evolving subdivision defined by the lifting map Λ_h and assume that $\{\mathcal{T}_h(t)\}_{t \in [0, T]}$ is a uniformly k -regular, uniformly quasi-uniform, evolving conforming subdivision. Then $\{\mathcal{T}_h^\ell(t)\}_{t \in [0, T]}$ is also a uniformly k -regular, uniformly quasi-uniform, evolving conforming exact subdivision of $\Gamma(t)$.*

Proof. We use the decomposition that

$$\Lambda_h(\cdot, t) = x + (p(x, t) - x) =: x + \tilde{\Lambda}_h(x, t),$$

and write $\tilde{\Lambda}_K(\cdot, t)$ for $\tilde{\Lambda}_h(\cdot, t)|_{K(t)}$. From Rem. 7.4 and Prop. 7.14, we have to show

$$(9.28) \quad \sup_{x \in K} \left\| \nabla_{K(t)} \tilde{\Lambda}_K(x) \right\| \leq \frac{1 - C_K}{1 + C_K} \quad \text{for all } K \in \mathcal{T}_h(t), \text{ all } t \in [0, T], \text{ and all } h \in (0, h_0),$$

and

$$(9.29) \quad \sup_{h \in (0, h_0)} \sup_{t \in [0, T]} \|\Lambda_h(\cdot, t)\|_{W^{k+1, \infty}(\Gamma_h(t))} \leq C.$$

The second estimate follows from the smoothness of p (9.4) (which follows from the smoothness of $\Gamma(t)$ (Foote, 1984)). Next we compute directly that

$$\partial_{x_j}(p(x, t))_i = \delta_{ij} - \mathbf{v}_i(x, t) \mathbf{v}_j(x, t) - d(x, t) \mathbb{H}(x, t)_{ij}$$

so that using the notations $P_{ij} = \delta_{ij} - \mathbf{v}_i \mathbf{v}_j$ and $(P_h)_{ij} = \delta_{ij} - (\mathbf{v}_h)_i (\mathbf{v}_h)_j$ for $j = 1, \dots, n+1$, we have

$$\begin{aligned} \nabla_{K(t)} \tilde{\Lambda}_K(x, t) &= P_h(x, t)(P(x, t) - d(x, t) \mathbb{H}(x, t)) - P_h(x, t) \\ &= P_h(x, t)(P(x, t) - P_h(x, t)) - d(x, t) P_h(x, t) \mathbb{H}(x, t). \end{aligned}$$

Applying (9.24) and (9.25), we see that

$$\left\| \nabla_{K(t)} \tilde{\Lambda}_K(x, t) \right\| \leq \|P(x, t) - P_h(x, t)\| + ch^{k+1} \|\mathbb{H}(x, t)\| \leq ch^k.$$

Clearly the right hand side of this equation is less than $(1 - C_K)/(1 + C_K)$ for h sufficiently small. \square

Lemma 9.12. *Let $\eta_h \in \mathcal{H}_h(t)$ and denote its lift by η_h^ℓ . Then there exists constants $c_1, c_2 > 0$ such that*

$$(9.30) \quad c_1 \left\| \eta_h^\ell \right\|_{\mathcal{H}(t)} \leq \|\eta_h\|_{\mathcal{H}_h(t)} \leq c_2 \left\| \eta_h^\ell \right\|_{\mathcal{H}(t)}.$$

Furthermore, if $\eta_h \in \mathcal{V}_h(t)$, there exists constants $c_3, c_4 > 0$ such that

$$(9.31) \quad c_3 \left\| \eta_h^\ell \right\|_{\mathcal{V}(t)} \leq \|\eta_h\|_{\mathcal{V}_h(t)} \leq c_4 \left\| \eta_h^\ell \right\|_{\mathcal{V}(t)}.$$

Proof. We apply [Prop. 7.8](#) using [Lem. 9.11](#). \square

Using the lift Λ_h and the discrete flow Φ_t^h , we can define the lifted flow map Φ_t^ℓ ([Def. 7.12\(a\)](#)), lifted discrete velocity w_h ([Def. 7.12\(b\)](#)) and lifted push forward maps ϕ_t^ℓ ([Def. 7.12\(c\)](#) and [\(3.13\)](#)). [Lem. 9.11](#) implies, with [Prop. 7.14](#), that $(\mathcal{H}(t), \phi_t^\ell)_{t \in [0, T]}$, $(\mathcal{V}(t), \phi_t^\ell|_{\mathcal{V}_0})_{t \in [0, T]}$ and $(\mathcal{S}_h^\ell(t), \phi_t^\ell|_{\mathcal{S}_h(0)})_{t \in [0, T]}$ are compatible pairs uniformly for $h \in (0, h_0)$. We will use the notations $C_{(\mathcal{H}, \phi^\ell)}^1$ and $C_{(\mathcal{V}, \phi^\ell)}^1$ for the spaces of functions smoothly evolving in time [\(2.2\)](#) with respect to the push-forward map ϕ_t^ℓ in $\mathcal{H}(t)$ and $\mathcal{V}(t)$ respectively. We may also define a lifted material derivative for functions $\eta \in C_{(\mathcal{H}, \phi^\ell)}^1$ using [\(3.15\)](#) by

$$(9.32) \quad \partial_\ell^\bullet \eta = \phi_t^\ell \left(\frac{d}{dt} \left(\phi_{-t}^\ell \eta \right) \right).$$

Lemma 9.13. *The push forward map ϕ_t^ℓ induces a new transport formula on $\{\Gamma(t)\}$. For $\eta \in C_{(\mathcal{H}, \phi^\ell)}^1$ we have*

$$(9.33) \quad \frac{d}{dt} \int_{\Gamma(t)} \eta \, d\sigma = \sum_{K^\ell(t) \in \mathcal{T}_h^\ell(t)} \int_{K^\ell(t)} \partial_\ell^\bullet \eta + \eta \nabla_\Gamma \cdot w_h \, d\sigma.$$

Let \mathcal{A}_Γ be a smooth, positive-definite, diffusion tensor on $\Gamma(t)$, which maps the tangent space of $\Gamma(t)$ to itself, and \mathcal{B}_Γ be a smooth tangential vector field on $\Gamma(t)$ for all $t \in [0, T]$. Furthermore, we have for $\eta, \zeta \in C_{(\mathcal{V}, \phi^\ell)}^1$

$$(9.34) \quad \begin{aligned} & \frac{d}{dt} \int_{\Gamma(t)} \mathcal{A}_\Gamma \nabla_\Gamma \eta \cdot \nabla_\Gamma \zeta \, d\sigma \\ &= \sum_{K^\ell(t) \in \mathcal{T}_h^\ell(t)} \int_{K^\ell(t)} \mathcal{A}_\Gamma (\nabla_\Gamma \partial_\ell^\bullet \eta \cdot \nabla_\Gamma \zeta + \nabla_\Gamma \eta \cdot \nabla_\Gamma \partial_\ell^\bullet \zeta) + \mathcal{B}_{K^\ell} (w_K, \mathcal{A}_\Gamma) \nabla_\Gamma \eta \cdot \nabla_\Gamma \zeta \, d\sigma, \end{aligned}$$

and for $\eta \in C_{(\mathcal{V}, \phi^\ell)}^1, \zeta \in C_{(\mathcal{H}, \phi^\ell)}^1$ we have

$$(9.35) \quad \begin{aligned} & \frac{d}{dt} \int_{\Gamma(t)} \mathcal{B}_\Gamma \eta \cdot \nabla_\Gamma \zeta \, d\sigma \\ &= \sum_{K^\ell(t) \in \mathcal{T}_h^\ell(t)} \int_{K^\ell(t)} \mathcal{B}_\Gamma (\partial_\ell^\bullet \eta \cdot \nabla_\Gamma \zeta + \eta \cdot \nabla_\Gamma \partial_\ell^\bullet \zeta) + \mathcal{B}_{K^\ell, \text{adv}} (w_K, \mathcal{B}_\Gamma) \eta \cdot \nabla_\Gamma \zeta \, d\sigma, \end{aligned}$$

where \mathcal{B}_{K^ℓ} and $\mathcal{B}_{K^\ell, \text{adv}}$ are defined as in [Lem. 9.9](#).

Proof. We note that the left hand side may be decomposed into individual elements then apply [\(9.6\)](#), [\(9.7\)](#) and [\(9.9\)](#) on each element. \square

Lemma 9.14.

$$(9.36) \quad \sup_{t \in [0, T]} \|\partial_h^\bullet d\|_{L^\infty(\Gamma_h(t))} \leq ch^{k+1}$$

$$(9.37) \quad \sup_{t \in [0, T]} \|\partial_h^\bullet P v_h\|_{L^\infty(\Gamma_h(t))} \leq ch^k$$

$$(9.38) \quad \sup_{t \in [0, T]} \|\partial_h^\bullet \delta_h\|_{L^\infty(\Gamma_h(t))} \leq ch^{k+1}.$$

Proof. See (Kovács, 2018, Lem. 5.2). \square

We can characterise the lifted discrete material derivatives (9.32) using the difference between smooth, w , and lifted, w_h , velocities. The result also shows the abstract inclusions (L3).

Lemma 9.15. *If $\eta \in C_{\mathcal{H}}^1 \cap C_{\mathcal{V}}^0$, then $\eta \in C_{(\mathcal{H}, \phi^\ell)}^1$ and conversely if $\eta \in C_{(\mathcal{H}, \phi^\ell)}^1 \cap C_{(\mathcal{V}, \phi^\ell)}^0$ then $\eta \in C_{\mathcal{H}}^1$. In either case, we have the identity*

$$(9.39) \quad \partial^\bullet \eta - \partial_h^\bullet \eta = \nabla_\Gamma \eta \cdot (w - w_h).$$

Furthermore, if $\eta \in C_{\mathcal{V}}^1 \cap C_{\mathcal{Z}_0}^0$ then $\eta \in C_{(\mathcal{V}, \phi^\ell)}^1$.

Proof. We use a chart $X(\cdot, t): U \rightarrow V \subset \Gamma(t)$ and write $\eta(X(\theta, t), t) = F(\theta, t)$. Note that $X_t(\theta, t) = w(X(\theta, t), t)$. Then

$$\partial^\bullet \eta(x, t) - \partial_t^\bullet \eta(x, t) = \frac{\partial}{\partial t} \left(\eta(\Phi_t(x_0), t) - \eta(\Phi_t^\ell(y_0), t) \right) \Big|_{x_0 = \Phi_{-t}(x), y_0 = \Phi_{-t}^\ell(x)}.$$

Using the notation $X(\theta(t), t) = \Phi_t(x_0)$ and $X(\theta^\ell(t), t) = \Phi_t^\ell(y_0)$, we have

$$\begin{aligned} & \partial^\bullet \eta(x, t) - \partial_t^\bullet \eta(x, t) \\ &= \frac{\partial F}{\partial t}(\theta(t), t) - \frac{\partial F}{\partial t}(\theta^\ell(t), t) + \sum_{i=1}^n \left(\frac{\partial F}{\partial \theta_i}(\theta(t), t) \frac{\partial \theta_i}{\partial t}(t) - \frac{\partial F}{\partial \theta_i}(\theta^\ell(t), t) \frac{\partial \theta_i^\ell}{\partial t}(t) \right). \end{aligned}$$

Using the substitutions $X(\theta(t), t) = \Phi_t(x_0)$, $X(\theta^\ell(t), t) = \Phi_t^\ell(y_0)$, $x_0 = \Phi_{-t}(x)$, and $y_0 = \Phi_{-t}^\ell(x)$, we see

$$\frac{\partial F}{\partial t}(\theta(t), t) - \frac{\partial F}{\partial t}(\theta^\ell(t), t) = 0.$$

Next, we take a time derivative of $X(\theta(t), t) = \Phi_t(x_0)$ to see that

$$\sum_{i=1}^n \frac{\partial X}{\partial \theta_i}(\theta(t)) \frac{\partial \theta_i}{\partial t}(t) = 0.$$

By multiplying by $\partial X / \partial \theta_j$, summing over i and multiplying G^{-1} we see that $\partial \theta / \partial t = 0$.

Next, we take a time derivative of $X(\theta^\ell(t), t) = \Phi_t^\ell(x_0)$, to see that

$$w(X(\theta^\ell(t), t)) + \sum_{i=1}^n \frac{\partial X}{\partial \theta_i}(\theta^\ell(t)) \frac{\partial \theta_i^\ell}{\partial t}(t) = w_h(\Phi_t^\ell(y_0), t).$$

Multiplying by $\partial X / \partial \theta_j(\theta^\ell(t))$ we see that

$$\sum_{i=1}^n g_{ij}(\theta^\ell(t)) \frac{\partial \theta_i^\ell}{\partial t}(t) = \frac{\partial X}{\partial \theta_j}(\theta^\ell(t)) \left(w_h(\Phi_t^\ell(y_0), t) - w(\theta^\ell(t), t) \right),$$

from which we infer that

$$\frac{\partial \theta_i^\ell}{\partial t}(t) = \sum_{j=1}^n g^{ij}(\theta^\ell(t)) \frac{\partial X}{\partial \theta_j}(\theta^\ell(t)) \left(w_h(\Phi_i^\ell(y_0), t) - w(\theta^\ell(t), t) \right).$$

Combining the previous expressions we see that

$$\partial^\bullet \eta(x, t) - \partial_t^\bullet \eta(x, t) = \sum_{i,j=1}^n g^{ij}(\theta^\ell(t)) \frac{\partial X}{\partial \theta_j}(\theta^\ell(t)) \frac{\partial F}{\partial \theta_i}(\theta^\ell(t), t) \left(w_h(\Phi_i^\ell(y_0), t) - w(\theta^\ell(t), t) \right).$$

Using the substitutions as above and the parametric definition of tangential gradient gives the result.

The second result can be shown by applying the tangential gradient to the basic result. \square

9.7. The discrete problem and stability. For each $t \in [0, T]$, and $h \in (0, h_0)$, we assume that $\mathcal{A}_\Gamma^h(t)$ is an element-wise smooth $(n+1) \times (n+1)$ symmetric diffusion tensor defined element-wise with $\mathcal{A}_\Gamma^h(t)|_{K(t)} = \mathcal{A}_\Gamma^K(t)$ for each $K(t) \in \mathcal{T}_h(t)$. We assume that $\mathcal{A}_\Gamma^K(t)$ maps the tangent space of $K(t)$ at a point into itself and is uniformly positive definite on the tangent space: There exists $\bar{a}_0 > 0$ such that for all $h \in (0, h_0)$, $t \in [0, T]$, and $K(t) \in \mathcal{T}_h(t)$

$$\mathcal{A}_\Gamma^K(t)(\cdot) \xi \cdot \xi \geq \bar{a}_0 |\xi|^2 \quad \text{for all } \xi \in \mathbb{R}^{n+1}, \xi \cdot \nu_K(\cdot, t) = 0.$$

We assume we are also given a element-wise smooth tangential vector field $\mathcal{B}_\Gamma^h(t)$ (with $\mathcal{B}_\Gamma^h(t)|_K = \mathcal{B}_\Gamma^K(t)$) and element-wise smooth scalar field $\mathcal{C}_\Gamma^h(t)$ (with $\mathcal{C}_\Gamma^h(t)|_{K(t)} = \mathcal{C}_\Gamma^K(t)$). We assume that

$$(9.40) \quad \sup_{t \in [0, T]} \max_{K(t) \in \mathcal{T}_h(t)} \left(\|\mathcal{A}_\Gamma^K\|_{C^1(K(t))} + \|\mathcal{B}_\Gamma^K\|_{C^1(K(t))} + \|\mathcal{C}_\Gamma^K\|_{C^1(K(t))} \right) < C.$$

Example 9.16. Here we are thinking of the case that $\mathcal{A}_\Gamma^h = \mathcal{A}_\Gamma^{-\ell}$, $\mathcal{B}_\Gamma^h = \mathcal{B}_\Gamma^{-\ell}$ and $\mathcal{C}_\Gamma^h = \mathcal{C}_\Gamma^{-\ell}$.

We consider the following semi-discrete problem (c.f. [Prob. 3.2](#)):

Problem 9.17. Given $U_{h,0} \in \mathcal{S}_h(0)$, find $U_h \in C_{\mathcal{S}_h}^1$ with $U_h(0) = U_{h,0}$ and such that for every $t \in (0, T)$,

$$(9.41) \quad \frac{d}{dt} m_h(t; U_h, \zeta_h) + a_h(t; U_h, \zeta_h) = m_h(t; U_h, \partial_h^\bullet \zeta_h) \quad \text{for all } \zeta_h \in C_{\mathcal{S}_h}^1,$$

where

$$\begin{aligned} m_h(t; \eta_h, \zeta_h) &:= \int_{\Gamma_h(t)} \eta_h \zeta_h \, d\sigma_h && \text{for } \eta_h, \zeta_h \in \mathcal{H}_h(t) \\ a_h(t; \eta_h, \zeta_h) &:= \sum_{K(t) \in \mathcal{T}_h(t)} \int_{K(t)} \mathcal{A}_\Gamma^K \nabla_K \eta_h \cdot \nabla_K \zeta_h \\ &\quad + \eta_h \nabla_K \zeta_h \cdot \mathcal{B}_\Gamma^K + \mathcal{C}_\Gamma^K \eta_h \zeta_h \, d\sigma_h && \text{for } \eta_h, \zeta_h \in \mathcal{V}_h(t). \end{aligned}$$

We note that the assumption that $\{\mathcal{T}_h(t)\}_{t \in [0, T]}$ is uniformly quasi-uniform regular implies that $\{\mathcal{S}_h(t), \Phi_t^h\}_{t \in [0, T]}$ is a compatible pair when equipped with the $\mathcal{V}_h(t)$ or $\mathcal{H}_h(t)$ -norms ([Lem. 6.30](#)).

To show the properties of these bilinear forms we require one further lemma:

Lemma 9.18. *The discrete velocity W_h of the discrete evolving surface $\{\Gamma_h(t)\}$ (9.20) is uniformly bounded in $W^{1,\infty}(\Gamma_h(t))$. That is, there exists a constant $C > 0$ such that for all $h \in (0, h_0)$*

$$(9.42) \quad \|\nabla_{\Gamma_h} W_h\|_{L^\infty(\Gamma_h(t))} \leq c \|W\|_{W^{1,\infty}(\Gamma(t))}.$$

Proof. The result follows from the interpolation bound (Cor. 7.11) and the stability of the lift (Prop. 7.8). \square

We have transport formulae on the surface $\{\Gamma_h(t)\}$.

Lemma 9.19. *There exists a bilinear forms $g_h(t; \cdot, \cdot): \mathcal{H}_h(t) \times \mathcal{H}_h(t) \rightarrow \mathbb{R}$ and $b_h(t; \cdot, \cdot): \mathcal{V}_h(t) \times \mathcal{V}_h(t) \rightarrow \mathbb{R}$ such that*

$$(9.43) \quad \frac{d}{dt} m_h(t; \eta_h, \zeta_h) = m_h(t; \partial_h^\bullet \eta_h, \zeta_h) + m_h(t; \eta_h, \partial_h^\bullet \zeta_h) + g_h(t; \eta_h, \zeta_h) \quad \text{for } \eta_h, \zeta_h \in C^1_{\mathcal{H}_h}$$

$$(9.44) \quad \frac{d}{dt} a_h(t; \eta_h, \zeta_h) = a_h(t; \partial_h^\bullet \eta_h, \zeta_h) + a_h(t; \eta_h, \partial_h^\bullet \zeta_h) + b_h(t; \eta_h, \zeta_h) \quad \text{for } \eta_h, \zeta_h \in C^1_{\mathcal{V}_h},$$

where

$$(9.45) \quad g_h(t; \eta_h, \zeta_h) = \sum_{K(t) \in \mathcal{T}_h(t)} \int_{K(t)} \eta_h \zeta_h \nabla_K \cdot W_h \, d\sigma_h$$

and

$$(9.46) \quad \begin{aligned} b_h(t; \eta_h, \zeta_h) = \sum_{K(t) \in \mathcal{T}_h(t)} \int_{K(t)} & \left(\mathcal{B}_K(W_K, \mathcal{A}_\Gamma^K) \nabla_K \eta_h \cdot \nabla_K \zeta_h \right. \\ & + \mathcal{B}_{\text{adv},K}(W_K, \mathcal{B}_\Gamma^K) \eta_h \cdot \nabla_K \zeta_h \\ & \left. + (\partial_K^\bullet \mathcal{C}_\Gamma^K + \mathcal{C}_\Gamma^K \nabla_K W_K) \eta_h \zeta_h \right) d\sigma_h. \end{aligned}$$

Furthermore, there exist a constant $c > 0$ such that for all $t \in [0, T]$ and all $h \in (0, h_0)$ we have

$$(9.47) \quad |g_h(t; \eta_h, \zeta_h)| \leq c \|\eta_h\|_{\mathcal{H}_h(t)} \|\zeta_h\|_{\mathcal{H}_h(t)} \quad \text{for all } \eta_h, \zeta_h \in \mathcal{H}_h(t)$$

$$(9.48) \quad |b_h(t; \eta_h, \zeta_h)| \leq c \|\eta_h\|_{\mathcal{V}_h(t)} \|\zeta_h\|_{\mathcal{V}_h(t)} \quad \text{for all } \eta_h, \zeta_h \in \mathcal{V}_h(t).$$

Proof. The transport theorem (9.21) directly gives (9.45) and additionally (9.22) and (9.23) give (9.46). To see the boundedness properties, we directly apply Lem. 9.18. \square

Theorem 9.20. *There exists a unique solution of the finite element scheme (9.41). The solution satisfies the stability bound:*

$$(9.49) \quad \sup_{t \in (0, T)} \|U_h\|_{\mathcal{H}_h(t)}^2 + \int_0^T \|U_h\|_{\mathcal{V}_h(t)}^2 \, dt \leq c \|U_{h,0}\|_{\mathcal{H}_h(t)}^2.$$

Proof. The result is shown in the abstract setting in Thm. 3.3 so we are left to check the assumptions. The assumptions (M_h1) and (M_h2) follow since m_h is simply the $\mathcal{H}_h(t) = L^2(\Gamma_h(t))$ inner product. For (G_h1), we use (9.21) and the product rule $\partial_h^\bullet (v_h)^2 = 2v_h \partial_h^\bullet v_h$. The bound (G_h2) is shown in (9.47). The map $t \mapsto a_h(t; \cdot, \cdot)$ is differentiable and hence measurable (A_h1). The bounds (A_h2) and (A_h3) follow from standard calculations and our assumptions on $\mathcal{A}_\Gamma^h, \mathcal{B}_\Gamma^h, \mathcal{C}_\Gamma^h$. Finally we have shown (B_h1) and (B_h2) in (9.46) and (9.48). \square

9.8. Error analysis. The space $\mathcal{S}_h^\ell(t)$ is equipped with the following approximation property:

Lemma 9.21. *The interpolation operator $I_h: \mathcal{Z}_0(t) \rightarrow \mathcal{S}_h^\ell(t)$ is well defined and satisfies*

$$(9.50) \quad \|z - I_h z\|_{\mathcal{H}(t)} + h \|z - I_h z\|_{\mathcal{V}(t)} \leq ch^2 \|z\|_{\mathcal{Z}_0(t)} \quad \text{for } z \in \mathcal{Z}_0(t)$$

$$(9.51) \quad \|z - I_h z\|_{\mathcal{H}(t)} + h \|z - I_h z\|_{\mathcal{V}(t)} \leq ch^{k+1} \|z\|_{\mathcal{Z}(t)} \quad \text{for } z \in \mathcal{Z}(t).$$

Proof. We simply apply [Thm. 7.10](#). The second result applies the theorem in the obvious way. The first result applies the theorem with $k = 1$ noting that $P_1(\hat{K}) \subset P_k(\hat{K})$ and the inclusions for [Lem. 4.3](#) still hold. \square

We can further relate the lifted material velocity with the discrete material velocity. Let $x = X(t) \in \Gamma_h(t)$ evolve with velocity $W_h(X(t), t)$ and $Y(t) = \Lambda_h(X(t), t)$. Then

$$(9.52) \quad w_h(p(x, t), t) = \frac{d}{dt} Y(t) = \frac{d}{dt} p(X(t), t) = \nabla p(X(t), t) W_h(X(t), t) + p_t(X(t), t).$$

Then from the above calculation of $\partial_{x_j} p$ we have

$$(9.53) \quad w_h(p(x, t)) = (P(x, t) - d(x, t)) \mathbb{H}(x, t) W_h(x, t) - d_t(x, t) v(x, t) - d(x, t) v_t(x, t).$$

Lemma 9.22. *We have the estimate:*

$$(9.54) \quad \|w - w_h\|_{L^\infty(\Gamma(t))} + h \|\nabla_\Gamma(w - w_h)\|_{L^\infty(\Gamma(t))} \leq ch^{k+1}.$$

Proof. See ([Kovács, 2018](#), Lem 5.4). \square

The lifting operator also defines transport formulae:

Lemma 9.23. *There exists bilinear forms $g_\ell: \mathcal{H}(t) \times \mathcal{H}(t) \rightarrow \mathbb{R}$ and $b_\ell: \mathcal{V}(t) \times \mathcal{V}(t)$ given by*

$$(9.55) \quad g_\ell(t; \eta, \zeta) = \int_{\Gamma(t)} \eta \zeta \nabla_\Gamma \cdot w_h \, d\sigma \quad \text{for all } \eta, \zeta \in \mathcal{H}(t)$$

$$(9.56) \quad b_\ell(t; \eta, \zeta) = \sum_{K^\ell(t) \in \mathcal{T}_h^\ell(t)} \int_{K^\ell(t)} \left(\mathcal{B}(w_h, \mathcal{A}_\Gamma) \nabla_\Gamma \eta \cdot \nabla_\Gamma \zeta \right. \\ \left. + \mathcal{B}_{\text{adv}}(w_h, \mathcal{B}_\Gamma) \eta \cdot \nabla_\Gamma \zeta \right. \\ \left. + (\partial_\ell^\bullet \mathcal{C}_\Gamma + \mathcal{C}_\Gamma \nabla_\Gamma \cdot w_h) \eta \zeta \right) d\sigma \quad \text{for all } \eta, \zeta \in \mathcal{V}(t).$$

These bilinear forms satisfy the following transport formulae on $\Gamma(t)$:

$$(9.57) \quad \frac{d}{dt} m(t; \eta, \zeta) = m(t; \partial_\ell^\bullet \eta, \zeta) + m(t; \eta, \partial_\ell^\bullet \zeta) + g_\ell(t; \eta, \zeta) \quad \text{for } \eta, \zeta \in C^1_{(\mathcal{H}, \phi^\ell)}$$

$$(9.58) \quad \frac{d}{dt} a(t; \eta, \zeta) = a(t; \partial_\ell^\bullet \eta, \zeta) + a(t; \eta, \partial_\ell^\bullet \zeta) + b_\ell(t; \eta, \zeta) \quad \text{for } \eta, \zeta \in C^1_{(\mathcal{V}, \phi^\ell)}.$$

Furthermore, the two new bilinear forms are uniformly bounded in the sense that there exists a constant $c > 0$ such that for all $t \in [0, T]$ and all $h \in (0, h_0)$,

$$(9.59) \quad |g_\ell(t; \eta, \zeta)| \leq c \|\eta\|_{\mathcal{H}(t)} \|\zeta\|_{\mathcal{H}(t)} \quad \text{for all } \eta, \zeta \in \mathcal{H}(t)$$

$$(9.60) \quad |b_\ell(t; \eta, \zeta)| \leq c \|\eta\|_{\mathcal{V}(t)} \|\zeta\|_{\mathcal{V}(t)} \quad \text{for all } \eta, \zeta \in \mathcal{V}(t).$$

Proof. The transport formulae are direct translations of [Lem. 9.13](#). The bounds follow from the fact that $\|w_h\|_{W^{1,\infty}(\Gamma_h(t))}$ is bounded uniformly from [Lem. 9.22](#). \square

For the remainder of this section, we will additionally assume that \mathcal{A}_Γ is uniformly C^2 smooth in space. We set $\mathcal{A}_\Gamma^h = \mathcal{A}_\Gamma^{-\ell}$, $\mathcal{B}_\Gamma^h = \mathcal{B}_\Gamma^{-\ell}$, $\mathcal{C}_\Gamma^h = \mathcal{C}_\Gamma^{-\ell}$.

Lemma 9.24. *There exists a constant $c > 0$ such that for all $t \in [0, T]$ and all $\eta_h, \zeta_h \in \mathcal{V}_h(t)$ with lifts $\eta_h^\ell, \zeta_h^\ell \in \mathcal{V}(t)$ we have*

$$(9.61a) \quad \left| m(t; \eta_h^\ell, \zeta_h^\ell) - m_h(t; \eta_h, \zeta_h) \right| \leq ch^{k+1} \left\| \eta_h^\ell \right\|_{\mathcal{V}(t)} \left\| \zeta_h^\ell \right\|_{\mathcal{V}(t)}$$

$$(9.61b) \quad \left| a(t; \eta_h^\ell, \zeta_h^\ell) - a_h(t; \eta_h, \zeta_h) \right| \leq ch^{k+1} \left\| \eta_h^\ell \right\|_{\mathcal{V}(t)} \left\| \zeta_h^\ell \right\|_{\mathcal{V}(t)}$$

$$(9.61c) \quad \left| g_\ell(t; \eta_h^\ell, \zeta_h^\ell) - g_h(t; \eta_h, \zeta_h) \right| \leq ch^{k+1} \left\| \eta_h^\ell \right\|_{\mathcal{V}(t)} \left\| \zeta_h^\ell \right\|_{\mathcal{V}(t)}$$

$$(9.61d) \quad \left| b_\ell(t; \eta_h^\ell, \zeta_h^\ell) - b_h(t; \eta_h, \zeta_h) \right| \leq ch^{k+1} \left\| \eta_h^\ell \right\|_{\mathcal{V}(t)} \left\| \zeta_h^\ell \right\|_{\mathcal{V}(t)}$$

$$(9.61e) \quad \left| g_\ell(t; \eta_h^\ell, \zeta_h^\ell) - g(t; \eta_h^\ell, \zeta_h^\ell) \right| \leq ch^k \left\| \eta_h^\ell \right\|_{\mathcal{V}(t)} \left\| \zeta_h^\ell \right\|_{\mathcal{V}(t)}$$

$$(9.61f) \quad \left| b_\ell(t; \eta_h^\ell, \zeta_h^\ell) - b(t; \eta_h^\ell, \zeta_h^\ell) \right| \leq ch^k \left\| \eta_h^\ell \right\|_{\mathcal{V}(t)} \left\| \zeta_h^\ell \right\|_{\mathcal{V}(t)}.$$

Proof. The results (9.61a) to (9.61d) easily follow using ideas from (Kovács, 2018, Lem 5.6) and Lem. 8.24. (9.61e) and (9.61f) follow directly from Lem. 9.22. \square

Lemma 9.25.

$$(9.62) \quad \left\| \partial^\bullet \eta - \partial_\ell^\bullet \eta \right\|_{L^2(\Gamma(t))} \leq ch^{k+1} \left\| \eta \right\|_{H^1(\Gamma(t))} \quad \text{for } \eta \in H^1(\Gamma(t))$$

$$(9.63) \quad \left\| \nabla_\Gamma(\partial^\bullet \eta - \partial_\ell^\bullet \eta) \right\|_{L^2(\Gamma(t))} \leq ch^k \left\| \eta \right\|_{H^2(\Gamma(t))} \quad \text{for } \eta \in H^2(\Gamma(t)).$$

Furthermore for all $\eta \in C^1_{\mathcal{Z}_0}$ and $\zeta \in \mathcal{Z}_0(t)$, we have

$$(9.64) \quad \left| a(t; \partial_\ell^\bullet \eta, \zeta) - a_h(t; \partial_h^\bullet \eta^{-\ell}, \zeta^{-\ell}) \right| \leq ch^{k+1} (\left\| \eta \right\|_{\mathcal{Z}_0(t)} + \left\| \partial^\bullet \eta \right\|_{\mathcal{Z}_0(t)}) \left\| \zeta \right\|_{\mathcal{Z}_0(t)}.$$

Proof. We recall (9.39):

$$\partial^\bullet \eta - \partial_\ell^\bullet \eta = (w - w_h) \cdot \nabla_\Gamma \eta.$$

We combine this calculation with (9.54) to see (9.62).

We may apply the tangential gradient to the above equation and use (9.54) again to obtain

$$\left\| \nabla_\Gamma(\partial^\bullet \eta - \partial_\ell^\bullet \eta) \right\|_{L^2(\Gamma(t))} \leq ch^k \left\| \eta \right\|_{H^1(\Gamma(t))} + ch^{k+1} \left\| \eta \right\|_{H^2(\Gamma(t))}.$$

(9.64) follows from (9.61b) and (9.63). \square

Theorem 9.26. *Let $\mathbf{u} \in L^2_{\mathcal{V}}$ be the solution of (9.14) which we assume satisfies the further regularity requirement*

$$(9.65) \quad \sup_{t \in (0, T)} \left\| \mathbf{u} \right\|_{\mathcal{Z}(t)}^2 + \int_0^T \left\| \partial^\bullet \mathbf{u} \right\|_{\mathcal{Z}(t)}^2 dt \leq C_u.$$

Let $U_h \in C^1_{\mathcal{S}_h}$ be the solution of (9.41) and denote its lift by $u_h = U_h^\ell$. Then we have the following error estimate

$$(9.66) \quad \sup_{t \in (0, T)} \left\| \mathbf{u} - u_h \right\|_{\mathcal{H}(t)}^2 + h^2 \int_0^T \left\| \mathbf{u} - u_h \right\|_{\mathcal{V}(t)}^2 dt \leq c \left\| \mathbf{u} - u_{h,0} \right\|_{\mathcal{H}(t)}^2 + ch^{2k+2} C_u.$$

Proof. We simply check the assumptions of [Thm. 3.11](#). We know the lift is stable from [Lem. 9.12](#). The existence and boundedness of g_ℓ and b_ℓ^k are dealt with in [Lem. 9.23](#). The interpolation properties (I1) and (I2) are shown in [Lem. 9.21](#). The geometric perturbation estimates (P1) to (P9) are shown in the sequence of [Lem. 9.22](#), [9.24](#) and [9.25](#). Finally, to show (B3) we follow a calculation given in the proof of ([Dziuk and Elliott, 2013a](#), [Thm. 6.2](#)). In this setting the simpler version (B3') holds; see [Rem. 3.7](#). Observe that for any $\eta \in \mathcal{V}(t)$, $\zeta \in \mathcal{Z}_0(t)$, that

$$\begin{aligned} b(t; \eta, \zeta) &= \int_{\Gamma(t)} \mathcal{B}(w, \mathcal{A}_\Gamma) \nabla_\Gamma \eta \cdot \nabla_\Gamma \zeta \, d\sigma + \int_{\Gamma(t)} \mathcal{B}_{\text{adv}}(w, \mathcal{B}_\Gamma) \eta \cdot \nabla \zeta \, d\sigma \\ &\quad + \int_{\Gamma(t)} (\partial^\bullet \mathcal{C}_\Gamma + \mathcal{C}_\Gamma \nabla_\Gamma \cdot w) \eta \zeta \, d\sigma =: I_1 + I_2 + I_3. \end{aligned}$$

For I_1 , using the additional smoothness assumptions on \mathcal{A}_Γ , we can apply integration by parts to see that

$$\begin{aligned} I_1 &= \int_{\Gamma(t)} \mathcal{B}(w, \mathcal{A}_\Gamma) \nabla_\Gamma \eta \cdot \nabla_\Gamma \zeta \, d\sigma \\ &= \sum_{i,j=1}^{n+1} \int_{\Gamma(t)} \mathcal{B}(w, \mathcal{A}_\Gamma)_{ij} (\nabla_\Gamma)_j \eta (\nabla_\Gamma)_i \zeta \, d\sigma \\ &= \sum_{i,j=1}^{n+1} \int_{\Gamma(t)} (\nabla_\Gamma)_j (\mathcal{B}(w, \mathcal{A}_\Gamma)_{ij} \eta (\nabla_\Gamma)_i \zeta) \, d\sigma - \int_{\Gamma(t)} \eta \sum_{i,j=1}^{n+1} (\nabla_\Gamma)_j (\mathcal{B}(w, \mathcal{A}_\Gamma)_{ij} (\nabla_\Gamma)_i \zeta) \, d\sigma \\ &= \int_{\Gamma(t)} \sum_{i,j=1}^{n+1} H v_j \mathcal{B}(w, \mathcal{A}_\Gamma)_{ij} \eta (\nabla_\Gamma)_i \zeta \, d\sigma - \int_{\Gamma(t)} \eta \sum_{i,j=1}^{n+1} (\nabla_\Gamma)_j (\mathcal{B}(w, \mathcal{A}_\Gamma)_{ij} (\nabla_\Gamma)_i \zeta) \, d\sigma. \end{aligned}$$

The bounds for I_2 and I_3 are obvious. This implies that

$$(9.67) \quad |b(t; \eta, \zeta)| \leq |I_1| + |I_2| + |I_3| \leq c \|\eta\|_{\mathcal{H}(t)} \|\zeta\|_{\mathcal{Z}_0(t)}. \quad \square$$

10. APPLICATION III: A COUPLED BULK-SURFACE PARABOLIC SYSTEM

In this section we will consider a finite element method for the coupled bulk-surface problem (1.6). The method is based on combining the isoparametric approaches from the problem in a bulk domain ([Sec. 8](#)) and the problem on a surface ([Sec. 9](#)). The discretisation will be posed in the product of a bulk isoparametric finite element space of order k and a surface isoparametric finite element space of order k . We take our notation from the previous sections ([Sec. 8](#) and [9](#)).

10.1. The domain and function spaces. We set $\mathcal{H}(t) = L^2(\Omega(t)) \times L^2(\Gamma(t))$, $\mathcal{V}(t) = H^1(\Omega(t)) \times H^1(\Gamma(t))$ and $\mathcal{V}^*(t) = (H^1(\Omega(t)))^* \times (H^1(\Gamma(t)))^*$. We will also make use of the spaces $\mathcal{Z}_0(t) = H^2(\Omega(t)) \times H^2(\Gamma(t))$ and $\mathcal{Z}(t) = H^{k+1}(\Omega(t)) \times H^{k+1}(\Gamma(t))$. We see that $Z(t) \subset \mathcal{Z}_0(t) \subset \mathcal{V}(t)$ for each $t \in [0, T]$ and the inclusions are uniformly continuous. We define the push forward operator ϕ_t by

$$(10.1) \quad (\phi_t(\underline{\eta}))(x, y) := (\eta(\Phi_{-t}(x)), \xi(\Phi_{-t}(y))) \quad \text{for } \underline{\eta} = (\eta, \xi) \in \mathcal{H}_0, x \in \Omega(t), y \in \Gamma(t).$$

$(\mathcal{H}(t), \phi_t)_{t \in [0, T]}$ and $(\mathcal{V}(t), \phi_t)_{t \in [0, T]}$ are compatible pairs ([Def. 2.2](#)) and the spaces $L_{\mathcal{H}}^2, L_{\mathcal{V}}^2$ and $L_{\mathcal{V}^*}^2$ (c.f. (2.1)) and $C_{\mathcal{H}}^1, C_{\mathcal{V}}^1$ and $C_{\mathcal{V}^*}^1$ (c.f. (2.2)) are well defined. For $\underline{\eta} = (\eta, \xi) \in C_{\mathcal{H}}^1$, we define the strong material derivative, denoted $\partial^\bullet \underline{\eta}$, using (2.4). The product material derivative coincides with the product of surface and bulk material derivatives:

$$\partial^\bullet \underline{\eta} = (\partial^\bullet \eta, \partial^\bullet \xi) \quad \text{for } \underline{\eta} = (\eta, \xi) \in C_{\mathcal{H}}^1.$$

$(\mathcal{V}(t), \mathcal{H}(t), \mathcal{V}^*(t))_{t \in [0, T]}$ form an evolving Hilbert triple (Def. 2.4). We also have that $(\mathcal{Z}_0(t), \phi_t|_{\mathcal{Z}_0(t)})_{t \in [0, T]}$ and $(\mathcal{Z}(t), \phi_t|_{\mathcal{Z}_0(t)})_{t \in [0, T]}$ are compatible pairs. For further information on this functional analytic setting see Alphonse et al. (2015b, Sec. 5.3).

Remark 10.1. For the well posedness of the partial differential equation Prob. 10.2 we require that the boundary Γ is a C^2 -hypersurface and that the flow map $\Phi_{(\cdot)}(\cdot) \in C^2(0, T; C^2(\Omega_0))$. See Alphonse et al. (2015b) for more details. For the approximation properties we derive we require that Γ is a C^{k+2} -hypersurface and that $\Phi_{(\cdot)}(\cdot) \in C^{k+2}(0, T; C^{k+2}(\Omega_0))$ with $\Phi_t: \Omega_0 \rightarrow \Omega(t)$ and $\Phi_{-t}: \Omega(t) \rightarrow \Omega$ both of class C^{k+2} .

We introduce a signed distance function for the boundary surface $\Gamma(t) = \partial\Omega(t)$. The oriented signed distance function for $\Gamma(t)$ is given by

$$d(x, t) = \begin{cases} -\inf\{|x - y| : y \in \Gamma(t)\} & \text{for } x \in \bar{\Omega}(t) \\ \inf\{|x - y| : y \in \Gamma(t)\} & \text{otherwise.} \end{cases}$$

For each $t \in [0, T]$, we orient $\Gamma(t)$ by choosing the unit normal $\nu(x, t) = \nabla d(x, t)$ for $x \in \Gamma(t)$. Our assumptions on $\Gamma(t)$ imply that there exists a neighbourhood $\mathcal{N}(t)$ of $\Gamma(t)$ and normal projection operator $p(\cdot, t): \mathcal{N}(t) \rightarrow \Gamma(t)$ given as the unique solution of

$$(10.2) \quad x = p(x, t) + d(x, t)\nu(p(x, t), t).$$

See Gilbarg and Trudinger (1983, Lem. 14.16); Foote (1984) for more details.

10.2. The initial value problem. Given $\mathcal{A}_\Omega, \mathcal{B}_\Omega, \mathcal{C}_\Omega$ as in Sec. 8.2 and $\mathcal{A}_\Gamma, \mathcal{B}_\Gamma, \mathcal{C}_\Gamma$ as in Sec. 9.2, we consider the initial value problem

Problem 10.2. Find u and v such that

$$(10.3a) \quad \partial^\bullet u + \nabla \cdot (\mathcal{B}_\Omega u) - \nabla \cdot (\mathcal{A}_\Omega \nabla u) + \mathcal{C}_\Omega u + (\nabla \cdot w)u = 0 \quad \text{on } \Omega(t)$$

$$(10.3b) \quad \partial^\bullet v + \nabla \cdot (\mathcal{B}_\Gamma v) - \nabla \cdot (\mathcal{A}_\Gamma \nabla_\Gamma v) + \mathcal{C}_\Gamma v + (\nabla_\Gamma \cdot w)v = 0 \quad \text{on } \Gamma(t)$$

$$(10.3c) \quad (-\mathcal{B}_\Omega u + \mathcal{A}_\Omega \nabla_\Gamma u) \cdot \nu + (\alpha u - \beta v) = 0 \quad \text{on } \Gamma(t)$$

$$(10.3d) \quad u(0) = u_0 \text{ on } \Omega_0, \quad v(0) = v_0 \text{ on } \Gamma_0.$$

Remark 10.3. The problem (1.6) is recovered by setting $\mathcal{A}_\Omega = a_\Omega, \mathcal{B}_\Omega = b_\Omega - w$ and $\mathcal{C}_\Omega = c_\Omega$ and $\mathcal{A}_\Gamma = a_\Gamma, \mathcal{B}_\Gamma = b_\Gamma - w_\tau$ and $\mathcal{C}_\Gamma = c_\Gamma - \nabla_\Gamma \cdot w_\nu$, where $w = w_\tau + w_\nu$ is a decomposition of w into tangential and normal components on $\Gamma(t)$.

10.3. The bilinear forms and transport formulae. We set

$$m(t; (\eta, \xi), (\zeta, \rho)) = \alpha \int_{\Omega(t)} \eta \zeta \, dx + \beta \int_{\Gamma(t)} \xi \rho \, d\sigma \quad (\eta, \xi), (\zeta, \rho) \in \mathcal{H}(t)$$

$$g(t; (\eta, \xi), (\zeta, \rho)) = \alpha \int_{\Omega(t)} \eta \zeta \nabla \cdot w \, dx + \beta \int_{\Gamma(t)} \xi \rho \nabla_\Gamma \cdot w \, d\sigma \quad (\eta, \xi), (\zeta, \rho) \in \mathcal{H}(t)$$

$$\begin{aligned} a_s(t; (\eta, \xi), (\zeta, \rho)) &= \alpha \int_{\Omega(t)} \mathcal{A}_\Omega \nabla \eta \cdot \nabla \zeta + \mathcal{C}_\Omega \eta \zeta \, dx \\ &\quad + \beta \int_{\Gamma(t)} \mathcal{A}_\Gamma \nabla_\Gamma \xi \cdot \nabla \rho + \mathcal{C}_\Gamma \xi \rho \, d\sigma \\ &\quad + \int_{\Gamma(t)} (\alpha \eta - \beta \xi)(\alpha \zeta - \beta \rho) \, d\sigma. \end{aligned} \quad (\eta, \xi), (\zeta, \rho) \in \mathcal{V}(t)$$

$$\begin{aligned} a_n(t; (\eta, \xi), (\zeta, \rho)) &= \alpha \int_{\Omega(t)} \mathcal{B}_\Omega \eta \cdot \nabla \zeta \, dx + \beta \int_{\Gamma(t)} \mathcal{B}_\Gamma \xi \cdot \nabla_\Gamma \rho \, d\sigma \quad (\eta, \xi) \in H(t), \\ &\quad (\zeta, \rho) \in \mathcal{V}(t). \end{aligned}$$

We can combine the transport formula for the bulk and surface only cases (8.9) and (9.11) for m , (8.10) and (9.12) for a_s and (8.11) and (9.13) to derive transport laws for these coupled bilinear forms. First, for $\underline{\eta}, \underline{\zeta} \in C_{\mathcal{H}}^1$ we have

$$(10.4) \quad \frac{d}{dt} m(t; \underline{\eta}, \underline{\zeta}) = m(t; \partial^\bullet \underline{\eta}, \underline{\zeta}) + m(t; \underline{\eta}, \partial^\bullet \underline{\zeta}) + g(t; \underline{\eta}, \underline{\zeta}),$$

for $\underline{\eta}, \underline{\zeta} \in C_{\mathcal{V}}^1$, we have

$$(10.5) \quad \frac{d}{dt} a_s(t; \underline{\eta}, \underline{\zeta}) = a_s(t; \partial^\bullet \underline{\eta}, \underline{\zeta}) + a_s(t; \underline{\eta}, \partial^\bullet \underline{\zeta}) + b_s(t; \underline{\eta}, \underline{\zeta}),$$

and for $\underline{\eta} \in C_{\mathcal{H}}^1, \underline{\zeta} \in C_{\mathcal{V}}^1$, we have

$$(10.6) \quad \frac{d}{dt} a_n(t; \underline{\eta}, \underline{\zeta}) = a_n(t; \partial^\bullet \underline{\eta}, \underline{\zeta}) + a_n(t; \underline{\eta}, \partial^\bullet \underline{\zeta}) + b_n(t; \underline{\eta}, \underline{\zeta}),$$

where $b_s(t; \cdot, \cdot): \mathcal{V}(t) \times \mathcal{V}(t) \rightarrow \mathbb{R}$ is given for $(\eta, \xi), (\zeta, \rho) \in \mathcal{V}(t)$ by

$$\begin{aligned} b_s(t; (\eta, \xi), (\zeta, \rho)) &= \alpha \int_{\Omega(t)} \mathcal{B}(w, \mathcal{A}_\Omega) \nabla \eta \cdot \nabla \zeta + (\partial^\bullet \mathcal{C}_\Omega + \mathcal{C}_\Omega \nabla \cdot w) \eta \zeta \, dx \\ &\quad + \beta \int_{\Gamma(t)} \mathcal{B}(w, \mathcal{A}_\Gamma) \nabla_\Gamma \xi \cdot \nabla_\Gamma \rho + (\partial^\bullet \mathcal{C}_\Gamma + \mathcal{C}_\Gamma \nabla_\Gamma \cdot w) \xi \rho \, d\sigma \\ &\quad + \int_{\Gamma(t)} (\alpha \eta - \beta \xi)(\alpha \zeta - \beta \rho) \nabla_\Gamma \cdot w \, d\sigma, \end{aligned}$$

and $b_n(t; \cdot, \cdot): \mathcal{H}(t) \times \mathcal{V}(t) \rightarrow \mathbb{R}$ is given for $(\eta, \xi) \in \mathcal{H}(t), (\zeta, \rho) \in \mathcal{V}(t)$ by

$$\begin{aligned} b_n(t; (\eta, \xi), (\zeta, \rho)) &= \alpha \int_{\Omega(t)} \mathcal{B}_{\text{adv}}(w, \mathcal{B}_\Omega) \eta \cdot \nabla \zeta \, dx + \beta \int_{\Gamma(t)} \mathcal{B}_{\text{adv}}(w, \mathcal{B}_\Gamma) \xi \cdot \nabla_\Gamma \rho \, d\sigma. \end{aligned}$$

We define $b(t; \cdot, \cdot): \mathcal{V}(t) \times \mathcal{V}(t) \rightarrow \mathbb{R}$ to be

$$b(t; \underline{\eta}, \underline{\zeta}) := b_s(t; \underline{\eta}, \underline{\zeta}) + b_n(t; \underline{\eta}, \underline{\zeta}) \quad \text{for } \underline{\eta}, \underline{\zeta} \in \mathcal{V}(t).$$

We also have the estimates that there exists a constant $c > 0$ such that for all $t \in (0, T)$ we have

$$(10.7) \quad |g(t; \underline{\eta}, \underline{\zeta})| \leq c \|\underline{\eta}\|_{\mathcal{H}(t)} \|\underline{\zeta}\|_{\mathcal{H}(t)} \quad \text{for all } \underline{\eta}, \underline{\zeta} \in \mathcal{H}(t)$$

$$(10.8) \quad |b_s(t; \underline{\eta}, \underline{\zeta})| \leq c \|\underline{\eta}\|_{\mathcal{V}(t)} \|\underline{\zeta}\|_{\mathcal{V}(t)} \quad \text{for all } \underline{\eta}, \underline{\zeta} \in \mathcal{V}(t)$$

$$(10.9) \quad |b_n(t; \underline{\eta}, \underline{\zeta})| \leq c \|\underline{\eta}\|_{\mathcal{H}(t)} \|\underline{\zeta}\|_{\mathcal{V}(t)} \quad \text{for all } \underline{\eta} \in \mathcal{H}(t), \underline{\zeta} \in \mathcal{V}(t).$$

10.4. Variational formulation. We consider a weak form of (1.6).

Problem 10.4. Given $(u_0, v_0) \in \mathcal{H}_0$, find $(u, v) \in \mathcal{W}(\mathcal{V}, \mathcal{V}^*)$ such that for almost every $t \in [0, T]$ we have

$$(10.10) \quad \begin{aligned} m(t; \partial^\bullet(u, v), \underline{\zeta}) + g(t; (u, v), \underline{\zeta}) + a(t; (u, v), \underline{\zeta}) &= 0 \quad \text{for all } \underline{\zeta} \in H^1(\Omega(t)) \times H^1(\Gamma(t)) \\ u(0) &= u_0, \quad v(0) = v_0. \end{aligned}$$

Theorem 10.5. *There exists a unique solution pair (\mathbf{u}, \mathbf{v}) which satisfies the stability bound:*

$$(10.11) \quad \sup_{t \in [0, T]} \|(\mathbf{u}, \mathbf{v})\|_{(L^2(\Omega(t)) \times L^2(\Gamma(t)))}^2 + \int_0^T \|(\mathbf{u}, \mathbf{v})\|_{(H^1(\Omega(t)) \times H^1(\Gamma(t)))}^2 dt \\ \leq c \|(\mathbf{u}_0, \mathbf{v}_0)\|_{(L^2(\Omega_0) \times L^2(\Gamma_0))}^2$$

and if $(\mathbf{u}, \mathbf{v}) \in H^1(\Omega_0) \times H^1(\Gamma_0)$ then

$$(10.12) \quad \sup_{t \in [0, T]} \|(\mathbf{u}, \mathbf{v})\|_{(H^1(\Omega(t)) \times H^1(\Gamma(t)))}^2 + \int_0^T \|\partial^\bullet(\mathbf{u}, \mathbf{v})\|_{(L^2(\Omega(t)) \times L^2(\Gamma(t)))}^2 dt \\ \leq c \|(\mathbf{u}_0, \mathbf{v}_0)\|_{(H^1(\Omega_0) \times H^1(\Gamma_0))}^2.$$

Proof. We again apply the abstract theory of [Thm. 2.15](#) and check the assumptions. [Ass. 2.9](#) and [2.13](#) are shown in [Alphonse et al. \(2015b, Sec 5.3\)](#). It is clear that [\(M1\)](#) and [\(M2\)](#) hold since $m(t; \cdot, \cdot)$ is equal to the $\mathcal{H}(t)$ -inner product. The assumptions [\(G1\)](#) and [\(G2\)](#) are shown in [\(10.4\)](#) and [\(10.7\)](#). We know that the map $t \mapsto a(t; \cdot, \cdot)$ is differentiable hence measurable which shows [\(A1\)](#). The coercivity [\(A3\)](#) and boundedness [\(A_s4\)](#) of a_s and boundedness of a_n [\(A_n4\)](#) follow from standard arguments since the extra cross term is clearly positive (see also [Elliott and Ranner \(2013, Thm. 3.2\)](#)). The existence of the bilinear forms b_s [\(B_s1\)](#) and b_n [\(B_n1\)](#) has been shown in [\(10.5\)](#) and [\(10.6\)](#) and the estimates [\(B_s2\)](#) and [\(B_n2\)](#) are shown in [\(10.8\)](#) and [\(10.9\)](#). \square

10.5. Discretisation of the domain and finite element spaces. In order to define our computational method we use the construction of the isoparametric domain of order k used in [Sec. 8.5](#). This defines an evolving triangulated bulk domain $\{\Omega_h(t)\}_{t \in [0, T]}$ ([Def. 4.32\(b\)](#)) equipped with an evolving conforming subdivision $\{\mathcal{T}_h(t)\}_{t \in [0, T]}$ ([Def. 4.32\(a\)](#)). We will assume that $\{\mathcal{T}_h(t)\}_{t \in [0, T]}$ is a uniformly quasi-uniform subdivision ([Def. 4.35\(a\)](#)). We will make the same assumptions on the domain as in [Sec. 8.5](#) which allow us to show [Prop. 8.9](#). Namely, we conclude that we can define an evolving bulk finite element space $\{\mathcal{S}_h^\Omega(t)\}$ ([\(8.18\)](#) and [Def. 4.34\(a\)](#)) consisting of Lagrange finite elements of order k ([Ex. 4.7\(b\)](#)) over a uniformly k -regular evolving subdivision ([Def. 4.35\(b\)](#)). By h we denote the maximum mesh diameter over time ([4.24](#)):

$$h := \max_{t \in [0, T]} \max_{K(t) \in \mathcal{T}_h(t)} \text{diam}(\tilde{K}(t)).$$

Throughout the remainder of this section we will denote global discrete quantities with a subscript $h \in (0, h_0)$. We assume implicitly that these structures exist for each h in this range (see also [Rem. 4.11](#) and [6.11](#)).

For $t \in [0, T]$, we write $\Gamma_h(t) = \partial\Omega_h(t)$ and $\mathcal{T}_h^\Gamma(t)$ for the boundary faces of $\mathcal{T}_h(t)$:

$$\mathcal{T}_h^\Gamma(t) := \{K(t) \cap \Gamma_h(t) : K(t) \in \mathcal{T}_h(t)\}.$$

We note that $\{\mathcal{T}_h^\Gamma(t)\}_{t \in [0, T]}$ is also an evolving conforming subdivision ([Def. 6.27\(a\)](#)) which we assume is uniformly quasi-uniform ([Def. 6.29\(c\)](#)). In fact, this is the construction we have previously used for an evolving surface in [Sec. 9](#) so that we may make the same conclusions as [Prop. 9.8](#). That is that we can define an evolving surface finite element space $\{\mathcal{S}_h^\Gamma(t)\}$ ([\(9.19\)](#) and [Def. 6.28\(a\)](#)) consisting of Lagrange finite elements of order k ([Ex. 6.7\(b\)](#)) over a uniformly k -regular, evolving subdivision $\{\mathcal{T}_h^\Gamma(t)\}_{t \in [0, T]}$ ([Def. 6.29\(b\)](#)).

Our analysis will make use of the product Hilbert spaces $\mathcal{H}_h(t) := L^2(\Omega_h(t)) \times L^2(\Gamma_h(t))$ and $\mathcal{V}_h(t) := H_T^1(\mathcal{T}_h(t)) \times H_T^1(\mathcal{T}_h^\Gamma(t))$ and the product finite element space $\mathcal{S}_h(t) := \mathcal{S}_h^\Omega(t) \times$

$\mathcal{S}_h^\Gamma(t)$. Using [Lem. 4.23](#) and [6.20](#) we can identify elements of $\mathcal{S}_h(t)$ as a product of continuous functions on $\Omega(t)$ and $\Gamma(t)$ and that $\mathcal{S}_h(t) \subset \mathcal{V}_h(t)$. We equip $\mathcal{S}_h(t)$ with the norms:

$$\begin{aligned} \|(\mathcal{X}_h, \varrho_h)\|_{\mathcal{V}_h(t)} &:= \left(\|\mathcal{X}_h\|_{H^1(\mathcal{S}_h(t))}^2 + \|\varrho_h\|_{H^1(\mathcal{S}_h^\Gamma(t))}^2 \right)^{1/2} \\ \|(\mathcal{X}_h, \varrho_h)\|_{\mathcal{H}_h(t)} &:= \left(\|\mathcal{X}_h\|_{L^2(\Omega_h(t))}^2 + \|\varrho_h\|_{L^2(\Gamma_h(t))}^2 \right)^{1/2}. \end{aligned}$$

The previous constructions define a global flow map $\Phi_t^h: \Omega_{h,0} \rightarrow \Omega_h(t)$ ([Def. 4.32\(c\)](#)) and discrete velocity W_h ([Def. 4.32\(d\)](#)), with well defined surface restrictions $\Phi_t^h|_{\Gamma_{h,0}}$ ([Def. 6.27\(c\)](#)) and $W_h|_{\Gamma_h(t)}$ ([Def. 6.27\(d\)](#)). For each $t \in [0, T]$, we define the discrete push forward map $\phi_t^h: \mathcal{H}_h(0) \rightarrow \mathcal{H}_h(t)$ by

$$(\phi_t(\eta_h, \xi_h))(x, y) := (\eta_h(\Phi_{-t}^h(x)), \xi_h(\Phi_{-t}^h(y))) \quad \text{for } (\eta_h, \xi_h) \in \mathcal{H}_h(0), x \in \Omega_h(t), y \in \Gamma_h(t).$$

Since we have shown that $\{\mathcal{S}_h\}_{t \in [0, T]}$ and $\{\mathcal{S}_h^\Gamma(t)\}_{t \in [0, T]}$ are both uniformly k -regular and uniformly quasi-uniform, the spaces $(\mathcal{H}_h(t), \phi_t^h|_{\mathcal{H}_{h,0}})_{t \in [0, T]}$, $(\mathcal{V}_h(t), \phi_t^h|_{\mathcal{V}_{h,0}})_{t \in [0, T]}$ and $(\mathcal{S}_h(t), \phi_t^h|_{\mathcal{S}_{h,0}})_{t \in [0, T]}$ form a compatible pair ([Def. 2.2](#)). Further, we can define the spaces $L^2_{\mathcal{H}_h}$ ([2.1](#)) and $C^1_{\mathcal{H}_h}$ ([2.2](#)) and we can define a material derivative for functions $\underline{\eta}_h = (\eta_h, \xi_h) \in C^1_{\mathcal{H}_h}$ which can be identified as ([3.3](#)):

$$\partial_h^* \underline{\eta}_h = (\partial_h^* \eta_h, \partial_h^* \xi_h).$$

10.6. Construction of lifted finite element space. We have already constructed a bijection between the computational domain $\Omega_h(t)$ and the continuous domain $\bar{\Omega}(t)$. In [Sec. 8.6](#), for each $t \in [0, T]$, we constructed element-wise a bijection $\Lambda_h(\cdot, t): \Omega_h(t) \rightarrow \bar{\Omega}(t)$. Furthermore, we note that the restriction of the lifting operator to $\Gamma_h(t)$, $\Lambda_h(\cdot, t)|_{\Gamma_h(t)}$, is simply the normal projection operator which is the lifting operator used in [Sec. 9.6](#).

For each bulk finite element $K(t) \in \mathcal{T}_h(t)$, we can use [Def. 5.1](#) to construct an associated lifted bulk finite element $(K^\ell(t), P^\ell(t), \Sigma^\ell(t))$. We will denote the set of lifted bulk finite elements by $\mathcal{T}_h^\ell(t)$. For each surface finite element $E(t) \in \mathcal{S}_h^\Gamma(t)$, we can use [Def. 7.1](#) to construct an associated lifted surface finite element $(E^\ell(t), P_E^\ell(t), \Sigma_E^\ell(t))$. We will denote the set of lifted surface finite elements by $\mathcal{S}_h^{\Gamma, \ell}(t)$.

For $t \in [0, T]$ and a function pair $\underline{\eta}_h = (\eta_h, \xi_h): \Omega_h(t) \times \Gamma_h(t) \rightarrow \mathbb{R}^2$, we define the lift $\underline{\eta}_h^\ell = (\eta_h, \xi_h)^\ell: \Omega(t) \times \Gamma(t) \rightarrow \mathbb{R}^2$ by

$$\underline{\eta}_h^\ell(\Lambda_h(x, t), p(y, t)) := (\eta_h(x), \xi_h(y)) \quad \text{for } x \in \Omega_h(t), y \in \Gamma_h(t).$$

We will often write $\underline{\eta}_h^\ell = (\eta_h, \xi_h)^\ell = (\eta_h^\ell, \xi_h^\ell)$ to signify that the lifting process is simply a combination the previous lifts for the surface and bulk components.

We will also make use of an inverse lift for functions on $\Omega(t) \times \Gamma(t)$. For $\underline{\eta} = (\eta, \xi): \Omega_h \times \Gamma(t) \rightarrow \mathbb{R}^2$, we define the inverse lift of $\underline{\eta}$, denoted by $\underline{\eta}^{-\ell} = (\eta, \xi)^{-\ell}: \Omega_h(t) \times \Gamma_h(t) \rightarrow \mathbb{R}^2$ by

$$\underline{\eta}^{-\ell}(x, y) = (\eta(\Lambda_h(x, t)), \xi_h(p(x, t))) \quad \text{for } x \in \Omega_h(t), y \in \Gamma_h(t).$$

Lemma 10.6. *Let $\underline{\eta}_h \in \mathcal{H}_h(t)$ and denote their lift by $\underline{\eta}_h^\ell$. Then there exists constants $c_1, c_2 > 0$ such that*

$$(10.13) \quad c_1 \left\| \underline{\eta}_h^\ell \right\|_{\mathcal{H}(t)} \leq \left\| \underline{\eta}_h \right\|_{\mathcal{H}_h(t)} \leq c_2 \left\| \underline{\eta}_h^\ell \right\|_{\mathcal{H}(t)}$$

$$(10.14) \quad c_1 \left\| \underline{\eta}_h^\ell \right\|_{\mathcal{V}(t)} \leq \left\| \underline{\eta}_h \right\|_{\mathcal{V}_h(t)} \leq c_2 \left\| \underline{\eta}_h^\ell \right\|_{\mathcal{V}(t)}.$$

Proof. We simply combine the results of [Lem. 8.14](#) and [Lem. 9.12](#). \square

We use the lifts to define a product space of lifted finite element functions $\mathcal{S}_h^\ell(t)$ ([Def. 5.7\(d\)](#) and [7.7\(d\)](#)) by

$$\mathcal{S}_h^\ell(t) := \{\underline{\chi}_h^\ell : \underline{\chi}_h \in \mathcal{S}_h\}.$$

Using the lift Λ_h and the discrete flow Φ_t^h , we can defined a lifted flow map $\Phi_t^\ell : \bar{\Omega}(0) \rightarrow \bar{\Omega}(t)$ ([Def. 5.11\(a\)](#)) and lifted discrete velocity w_h ([Def. 5.11\(b\)](#)), with well defined restrictions $\Phi_t^\ell|_{\Gamma(0)}$ ([Def. 7.12\(a\)](#)) and $w_h|_{\Gamma(t)}$ ([Def. 7.12\(b\)](#)). This allows us to define a lifted push forward map ([\(3.13\)](#) and [Def. 7.12\(c\)](#) and [5.11\(c\)](#)):

$$\phi_t^\ell((\eta, \xi))(x, y) := (\eta(\Phi_{-t}^\ell(x)), \xi(\Phi_{-t}^\ell(y))) \quad \text{for } (\eta, \xi) \in \mathcal{H}_0, x \in \bar{\Omega}(t), y \in \Gamma(t).$$

Using the previous constructions, applying [Lem. 8.13](#) and [9.11](#), we see that $(\mathcal{H}(t), \phi_t^\ell)_{t \in [0, T]}$, $(\mathcal{V}(t), \phi_t^\ell|_{\mathcal{V}(t)})_{t \in [0, T]}$ and $(\mathcal{S}_h^\ell(t), \phi_t^\ell|_{\mathcal{S}_h^\ell(t)})_{t \in [0, T]}$ are compatible pairs uniformly for $h \in (0, h_0)$. We will use the notations $C^1_{(\mathcal{H}, \phi^\ell)}$ and $C^1_{(\mathcal{V}, \phi^\ell)}$ for the spaces of functions smoothly evolving in time [\(2.2\)](#) with respect to the push-forward map ϕ_t^ℓ in $\mathcal{H}(t)$ and $\mathcal{V}(t)$ respectively. This implies we have a well defined strong material derivative [\(3.15\)](#):

$$\partial_t^\bullet \underline{\eta} = \phi_t^\ell \left(\frac{d}{dt} \left(\phi_{-t}^\ell \underline{\eta} \right) \right) \quad \text{for } \underline{\eta} \in C^1_{(\mathcal{H}, \phi^\ell)}.$$

10.7. The discrete problem and stability. The finite element method is based on the variation form [\(2.12\)](#) of [Prob. 10.4](#). We assume we have $\mathcal{A}_\Omega^K, \mathcal{B}_\Omega^K$ and \mathcal{C}_Ω^K for $K \in \mathcal{T}_h(t)$ as in [Sec. 8.7](#) and $\mathcal{A}_\Gamma^E, \mathcal{B}_\Gamma^E$ and \mathcal{C}_Γ^E for $E \in \mathcal{T}_h^\Gamma(t)$ as in [Sec. 9.7](#).

Problem 10.7. Given $(U_{h,0}, V_{h,0}) \in \mathcal{S}_{h,0}$, find $(U_h, V_h) \in C^1_{\mathcal{S}_h}$ such that for all $t \in [0, T]$

$$(10.15) \quad \begin{aligned} \frac{d}{dt} m_h(t; (U_h, V_h), \underline{\chi}_h) + a_h(t; (U_h, V_h), \underline{\chi}_h) &= m_h(t; (U_h, V_h), \partial_t^\bullet \underline{\chi}_h) \\ &\text{for all } \underline{\chi}_h \in C^1_{\mathcal{S}_h} \end{aligned}$$

$$U_h(0) = U_{h,0}, V_h(0) = V_{h,0},$$

where for $(\eta_h, \xi_h), (\zeta_h, \rho_h) \in \mathcal{H}_h(t)$, we define

$$m_h(t; (\eta_h, \xi_h), (\zeta_h, \rho_h)) = \alpha \int_{\Omega_h(t)} \eta_h \zeta_h \, dx + \beta \int_{\Gamma_h(t)} \xi_h \rho_h \, d\sigma_h,$$

and, for $(\eta_h, \xi_h), (\zeta_h, \rho_h) \in \mathcal{V}_h(t)$, we define

$$\begin{aligned} a_h(t; (\eta_h, \xi_h), (\zeta_h, \rho_h)) &= \alpha \sum_{K(t) \in \mathcal{T}_h(t)} \int_{K(t)} \mathcal{A}_\Omega^K \nabla \eta_h \cdot \nabla \zeta_h + \mathcal{B}_\Omega^K \eta_h \cdot \nabla \zeta_h + \mathcal{C}_\Omega^K \eta \zeta \, dx \\ &\quad + \beta \sum_{E(t) \in \mathcal{T}_h^\Gamma(t)} \int_{E(t)} \mathcal{A}_\Gamma^E \nabla_E \xi_h \cdot \nabla \rho_h + \mathcal{B}_\Gamma^E \xi_h \cdot \nabla_E \rho_h + \mathcal{C}_\Gamma^E \xi_h \rho_h \, d\sigma_h \\ &\quad + \int_{\Gamma_h} (\alpha \eta_h - \beta \xi_h)(\alpha \zeta_h - \beta \rho_h) \, d\sigma_h. \end{aligned}$$

We also have discrete transport formula from the bulk and surface cases:

Lemma 10.8. There exists bilinear forms $g_h(t; \cdot, \cdot) : \mathcal{H}_h(t) \times \mathcal{H}_h(t) \rightarrow \mathbb{R}$ and $b_h(t; \cdot, \cdot) : \mathcal{V}_h(t) \times \mathcal{V}_h(t) \rightarrow \mathbb{R}$ such that for all $\underline{\eta}_h = (\eta_h, \xi_h), \underline{\zeta}_h = (\zeta_h, \rho_h) \in C^1_{\mathcal{H}_h}$ we have

$$\frac{d}{dt} m_h(t; \underline{\eta}_h, \underline{\zeta}_h) = m_h(t; \partial_t^\bullet \underline{\eta}_h, \underline{\zeta}_h) + m_h(t; \underline{\eta}_h, \partial_t^\bullet \underline{\zeta}_h) + g_h(t; \underline{\eta}_h, \underline{\zeta}_h),$$

and for all $\underline{\eta}_h, \underline{\zeta}_h \in \mathcal{C}_{\mathcal{V}_h}^1$ we have

$$\frac{d}{dt} a_h(t; \underline{\eta}_h, \underline{\zeta}_h) = a_h(t; \partial_t^\bullet \underline{\eta}_h, \underline{\zeta}_h) + a_h(t; \underline{\eta}_h, \partial_t^\bullet \underline{\zeta}_h) + b_h(t; \underline{\eta}_h, \underline{\zeta}_h),$$

where

$$g_h(t; (\underline{\eta}_h, \underline{\xi}_h), (\underline{\zeta}_h, \underline{\rho}_h)) = \alpha \int_{\Omega_h(t)} \underline{\eta}_h \underline{\zeta}_h \nabla \cdot W_h \, dx + \beta \int_{\Gamma_h(t)} \underline{\xi}_h \underline{\rho}_h \nabla_{\Gamma_h} \cdot W_h \, d\sigma_h,$$

and

$$\begin{aligned} & b_h(t; (\underline{\eta}_h, \underline{\xi}_h), (\underline{\zeta}_h, \underline{\rho}_h)) \\ &= \sum_{K(t) \in \mathcal{T}_h(t)} \int_{K(t)} \mathcal{B}_h(W_h, \mathcal{A}_\Omega^K) \nabla \underline{\eta}_h \cdot \nabla \underline{\zeta}_h + \mathcal{B}_{\text{adv},h}(W_h, \mathcal{B}_\Omega^K) \underline{\eta}_h \cdot \nabla \underline{\zeta}_h \\ & \quad + (\partial_h^\bullet \mathcal{C}_\Omega^K + \mathcal{C}_\Omega^K \nabla \cdot W_h) \underline{\eta}_h \underline{\zeta}_h \, dx \\ &+ \sum_{E(t) \in \mathcal{T}_h^\Gamma(t)} \int_{E(t)} \mathcal{B}_h(W_h, \mathcal{A}_\Gamma^K) \nabla_E \underline{\xi}_h \cdot \nabla_E \underline{\rho}_h + \mathcal{B}_{\text{adv},h}(W_h, \mathcal{B}_\Gamma^K) \underline{\xi}_h \cdot \nabla_E \underline{\rho}_h \\ & \quad + (\partial_h^\bullet \mathcal{C}_\Gamma^K + \mathcal{C}_\Gamma^K \nabla_E \cdot W_h) \underline{\xi}_h \underline{\rho}_h \, d\sigma_h. \end{aligned}$$

Further, there exists a constant $c > 0$ such that, for all $t \in [0, T]$,

$$(10.16a) \quad \left| g_h(t; \underline{\eta}_h, \underline{\zeta}_h) \right| \leq c \left\| \underline{\eta}_h \right\|_{\mathcal{H}_h(t)} \left\| \underline{\zeta}_h \right\|_{\mathcal{H}_h(t)} \quad \text{for all } \underline{\eta}_h, \underline{\zeta}_h \in \mathcal{H}_h(t)$$

$$(10.16b) \quad \left| b_h(t; \underline{\eta}_h, \underline{\zeta}_h) \right| \leq c \left\| \underline{\eta}_h \right\|_{\mathcal{V}_h(t)} \left\| \underline{\zeta}_h \right\|_{\mathcal{V}_h(t)} \quad \text{for all } \underline{\eta}_h, \underline{\zeta}_h \in \mathcal{V}_h(t).$$

Proof. We simply combine [Lem. 8.19](#) and [9.19](#). \square

Theorem 10.9. *There exists a unique solution pair (U_h, V_h) of the finite element scheme ([Prob. 10.7](#)) which satisfies the stability bound*

$$(10.17) \quad \sup_{t \in (0, T)} \|(U_h, V_h)\|_{\mathcal{H}_h(t)}^2 + \int_0^t \|(U_h, V_h)\|_{\mathcal{V}_h(t)}^2 \, dt \leq c \|(U_{h,0}, V_{h,0})\|_{\mathcal{H}_h(t)}^2.$$

Proof. We apply the abstract result of [Thm. 3.3](#) and check the assumptions. The assumptions on m_h , [\(M_h1\)](#) and [\(M_h2\)](#), follow directly since m_h is equal to the $\mathcal{H}_h(t)$ inner-product. The estimates on a_h , [\(A_h2\)](#) and [\(A_h3\)](#) follow in the same manner as [Thm. 10.5](#). The transport formulae and estimates for g_h and b_h , [\(G_h1\)](#), [\(G_h2\)](#) [\(B_h1\)](#) and [\(B_h2\)](#), are shown in [Lem. 10.8](#). \square

10.8. Error analysis. We assume in this section that $\mathcal{A}_\Omega^h = \mathcal{A}_\Omega^{-\ell}$, $\mathcal{B}_\Omega^h = \mathcal{B}_\Omega^{-\ell}$, $\mathcal{C}_\Omega^h = \mathcal{C}_\Omega^{-\ell}$, $\mathcal{A}_\Gamma^h = \mathcal{A}_\Gamma^{-\ell}$, $\mathcal{B}_\Gamma^h = \mathcal{B}_\Gamma^{-\ell}$, $\mathcal{C}_\Gamma^h = \mathcal{C}_\Gamma^{-\ell}$. The space of lifted finite element functions $\mathcal{S}_h^\ell(t)$ is equipped with the follow approximation property:

Lemma 10.10 (Approximation property). *For $\underline{\eta} = (\underline{\eta}, \underline{\xi}) \in C(\Omega(t)) \times C(\Gamma(t))$ the Lagrangian interpolation operator $I_h \underline{\eta}$ is well defined. Furthermore, the following bounds hold for a constant $c > 0$ for all $h \in (0, h_0)$ and $t \in [0, T]$:*

$$(10.18) \quad \left\| \underline{\eta} - I_h \underline{\eta} \right\|_{\mathcal{H}(t)} + h \left\| \underline{\eta} - I_h \underline{\eta} \right\|_{\mathcal{V}(t)} \leq ch^{k+1} \left\| \underline{\eta} \right\|_{\mathcal{Z}(t)} \quad \text{for } \underline{\eta} \in \mathcal{Z}(t)$$

$$(10.19) \quad \left\| \underline{\eta} - I_h \underline{\eta} \right\|_{\mathcal{H}(t)} + h \left\| \underline{\eta} - I_h \underline{\eta} \right\|_{\mathcal{V}(t)} \leq ch^2 \left\| \underline{\eta} \right\|_{\mathcal{Z}_0(t)} \quad \text{for } \underline{\eta} \in \mathcal{Z}_0(t).$$

Proof. We define the interpolation operator to be $I_h(\underline{\eta}, \underline{\xi}) = (I_h \underline{\eta}, I_h \underline{\xi})$ for $(\underline{\eta}, \underline{\xi}) \in C(\Omega(t)) \times C(\Gamma(t))$. The proof follows by combining the result of [Lem. 9.21](#) and [Lem. 8.21](#). \square

Lemma 10.11. *There exists a bilinear forms $g_\ell(t; \cdot, \cdot) : \mathcal{H}(t) \times \mathcal{H}(t) \rightarrow \mathbb{R}$ and $b_\ell(t; \cdot, \cdot) : \mathcal{V}(t) \times \mathcal{V}(t) \rightarrow \mathbb{R}$ given by*

$$\begin{aligned} g_\ell(t; (\eta, \xi), (\zeta, \rho)) &:= \alpha \int_{\Omega(t)} \eta \zeta \nabla \cdot w_h \, dx + \beta \int_{\Gamma(t)} \xi \rho \nabla_\Gamma \cdot w_h \, d\sigma \\ \tilde{b}_h(t; (\eta, \xi), (\zeta, \rho)) &:= \alpha \int_{\Omega(t)} \mathcal{B}(w_h, \mathcal{A}_\Omega) \nabla \eta \cdot \nabla \zeta + \mathcal{B}_{\text{adv}}(w_h, \mathcal{B}_\Omega) \eta \cdot \nabla \zeta \\ &\quad + (\partial_\ell^\bullet \mathcal{C}_\Omega + \mathcal{C}_\Omega \nabla \cdot w_h) \eta \zeta \, dx \\ &\quad + \beta \int_{\Gamma(t)} \mathcal{B}(w_h, \mathcal{A}_\Gamma) \nabla_\Gamma \xi \cdot \nabla_\Gamma \rho + \mathcal{B}_{\text{adv}}(w_h, \mathcal{B}_\Gamma) \xi \cdot \nabla_\Gamma \rho \\ &\quad + (\partial_\ell^\bullet c_\Gamma + c_\Gamma \nabla_\Gamma \cdot w_h) \xi \rho \, d\sigma \\ &\quad + \int_{\Gamma(t)} (\alpha \eta - \beta \xi) (\alpha \zeta - \beta \rho) \nabla_\Gamma \cdot w_h \, d\sigma, \end{aligned}$$

such that

$$(10.20) \quad \frac{d}{dt} m(t; \underline{\eta}, \underline{\zeta}) = m(t; \partial_\ell^\bullet \underline{\eta}, \underline{\zeta}) + m(t; \underline{\eta}, \partial_\ell^\bullet \underline{\zeta}) + g_\ell(t; \underline{\eta}, \underline{\zeta})$$

for $\underline{\eta}, \underline{\zeta} \in C^1_{(\mathcal{H}, \phi^\ell)}$

$$(10.21) \quad \frac{d}{dt} a(t; \underline{\eta}, \underline{\zeta}) = a(t; \partial_\ell^\bullet \underline{\eta}, \underline{\zeta}) + a(t; \underline{\eta}, \partial_\ell^\bullet \underline{\zeta}) + b_\ell(t; \underline{\eta}, \underline{\zeta})$$

for $\underline{\eta}, \underline{\zeta} \in C^1_{(\mathcal{V}, \phi^\ell)}$.

Furthermore, there exists a constant $c > 0$ such that for all $t \in [0, T]$ and all $h \in (0, h_0)$ we have

$$(10.22) \quad \left| g_\ell(t; \underline{\eta}, \underline{\zeta}) \right| \leq c \|\underline{\eta}\|_{\mathcal{H}(t)} \|\underline{\zeta}\|_{\mathcal{H}(t)} \quad \text{for all } \underline{\eta}, \underline{\zeta} \in \mathcal{H}(t)$$

$$(10.23) \quad \left| b_\ell(t; \underline{\eta}, \underline{\zeta}) \right| \leq c \|\underline{\eta}\|_{\mathcal{V}(t)} \|\underline{\zeta}\|_{\mathcal{V}(t)} \quad \text{for all } \underline{\eta}, \underline{\zeta} \in \mathcal{V}(t).$$

Proof. We combine the results of [Lem. 8.22](#) and [9.23](#). \square

The geometric perturbation results now follow directly by combining the appropriate results from [Sec. 8.8](#) and [9.8](#).

Lemma 10.12. *We have the estimates*

$$(10.24) \quad |w - w_h|_{L^\infty(\Omega(t))} + h |\nabla(w - w_h)|_{L^\infty(\Omega(t))} \leq ch^{k+1}$$

$$(10.25) \quad |w - w_h|_{L^\infty(\Gamma(t))} + h |\nabla_\Gamma(w - w_h)|_{L^\infty(\Gamma(t))} \leq ch^{k+1}.$$

In particular, this implies

$$(10.26a) \quad \|\partial_\ell^\bullet \underline{\eta} - \partial_\ell^\bullet \underline{\eta}\|_{\mathcal{H}(t)} \leq ch^{k+1} \|\underline{\eta}\|_{\mathcal{V}(t)} \quad \text{for } \underline{\eta} \in C^1_{\mathcal{V}}$$

$$(10.26b) \quad \|\partial_\ell^\bullet \underline{\eta} - \partial_\ell^\bullet \underline{\eta}\|_{\mathcal{V}(t)} \leq ch^k \|\underline{\eta}\|_{\mathcal{Z}_0(t)} \quad \text{for } \underline{\eta} \in C^1_{\mathcal{Z}_0}.$$

Proof. We combine the results of [Lem. 8.23](#), [9.22](#) and [9.25](#). \square

Lemma 10.13. *There exists a constant $c > 0$ such that for all $t \in [0, T]$ and all $h \in (0, h_0)$ the following holds for all $\underline{\eta}_h, \underline{\zeta}_h \in \mathcal{V}_h(t)$ with lifts $\underline{\eta}_h^\ell, \underline{\zeta}_h^\ell \in \mathcal{V}(t)$:*

$$(10.27) \quad \left| m(t; \underline{\eta}_h^\ell, \underline{\zeta}_h^\ell) - m_h(t; \underline{\eta}_h, \underline{\zeta}_h) \right| \leq ch^{k+1} \left\| \underline{\eta}_h^\ell \right\|_{\mathcal{V}(t)} \left\| \underline{\zeta}_h^\ell \right\|_{\mathcal{V}(t)}$$

$$(10.28) \quad \left| g_\ell(t; \underline{\eta}_h^\ell, \underline{\zeta}_h^\ell) - g_h(t; \underline{\eta}_h, \underline{\zeta}_h) \right| \leq ch^{k+1} \left\| \underline{\eta}_h^\ell \right\|_{\mathcal{V}(t)} \left\| \underline{\zeta}_h^\ell \right\|_{\mathcal{V}(t)}$$

$$(10.29) \quad \left| a(t; \underline{\eta}_h^\ell, \underline{\zeta}_h^\ell) - a_h(t; \underline{\eta}_h, \underline{\zeta}_h) \right| \leq ch^k \left\| \underline{\eta}_h^\ell \right\|_{\mathcal{V}(t)} \left\| \underline{\zeta}_h^\ell \right\|_{\mathcal{V}(t)}$$

$$(10.30) \quad \left| b_\ell(t; \underline{\eta}_h^\ell, \underline{\zeta}_h^\ell) - b_h(t; \underline{\eta}_h, \underline{\zeta}_h) \right| \leq ch^k \left\| \underline{\eta}_h^\ell \right\|_{\mathcal{V}(t)} \left\| \underline{\zeta}_h^\ell \right\|_{\mathcal{V}(t)}$$

$$(10.31) \quad \left| g_\ell(t; \underline{\eta}_h^\ell, \underline{\zeta}_h^\ell) - g(t; \underline{\eta}_h^\ell, \underline{\zeta}_h^\ell) \right| \leq ch^k \left\| \underline{\eta}_h^\ell \right\|_{\mathcal{V}(t)} \left\| \underline{\zeta}_h^\ell \right\|_{\mathcal{V}(t)}$$

$$(10.32) \quad \left| b_\ell(t; \underline{\eta}_h^\ell, \underline{\zeta}_h^\ell) - b(t; \underline{\eta}_h^\ell, \underline{\zeta}_h^\ell) \right| \leq ch^k \left\| \underline{\eta}_h^\ell \right\|_{\mathcal{V}(t)} \left\| \underline{\zeta}_h^\ell \right\|_{\mathcal{V}(t)}.$$

For $\underline{\eta}, \underline{\zeta} \in \mathcal{Z}_0(t)$ with inverse lifts $\underline{\eta}^{-\ell}, \underline{\zeta}^{-\ell}$, we have

$$(10.33) \quad \left| a(t; \underline{\eta}, \underline{\zeta}) - a_h(t; \underline{\eta}^{-\ell}, \underline{\zeta}^{-\ell}) \right| \leq ch^{k+1} \left\| \underline{\eta} \right\|_{\mathcal{Z}_0(t)} \left\| \underline{\zeta} \right\|_{\mathcal{Z}_0(t)}$$

$$(10.34) \quad \left| b_\ell(t; \underline{\eta}, \underline{\zeta}) - b_h(t; \underline{\eta}^{-\ell}, \underline{\zeta}^{-\ell}) \right| \leq ch^{k+1} \left\| \underline{\eta} \right\|_{\mathcal{Z}_0(t)} \left\| \underline{\zeta} \right\|_{\mathcal{Z}_0(t)}$$

$$(10.35) \quad \left| a(t; \partial_\ell^\bullet \underline{\eta}, \underline{\zeta}) - a_h(t; \partial_h^\bullet \underline{\eta}^{-\ell}, \underline{\zeta}^{-\ell}) \right| \leq ch^{k+1} (\left\| \underline{\eta} \right\|_{\mathcal{Z}_0(t)} + \left\| \partial^\bullet \underline{\eta} \right\|_{\mathcal{Z}_0(t)}) \left\| \underline{\zeta} \right\|_{\mathcal{Z}_0(t)}$$

Proof. We combine the results of [Lem. 8.24](#) and [9.24](#). \square

We require one final result in order to show the error bound.

Lemma 10.14. *For any $t \in [0, T]$, let $\underline{z}, \pi_h \underline{z}$ be as in [\(3.20\)](#) and $\underline{\eta} = (\eta, \xi) = \underline{z} - \pi_h \underline{z} \in \mathcal{V}(t)$, then for all $\underline{\zeta} = (\zeta, \rho) \in \mathcal{Z}_0(t)$, we have*

$$(10.36) \quad \left| b(\underline{\eta}, \underline{\zeta}) \right| \leq c \left(\left\| \underline{\eta} \right\|_{\mathcal{H}(t)} + h \left\| \underline{\eta} \right\|_{\mathcal{V}(t)} + h^{k+1} \left\| \underline{z} \right\|_{\mathcal{Z}_0(t)} \right) \left\| \underline{\zeta} \right\|_{\mathcal{Z}_0(t)}.$$

Proof. The proof follows a similar path to [Lem. 8.25](#). We start by fixing $t \in [0, T]$. We recall that for any $\eta \in H^1(\Omega(t))$, there exists $\xi_\eta \in H^{1/2}(\Gamma(t))$ such that

$${}_{(H^{1/2}(\Gamma(t)))'} \langle \xi_\eta, \zeta \rangle_{H^{1/2}(\Gamma(t))} = (\eta, \zeta)_{L^2(\Gamma(t))},$$

and ξ_η satisfies

$$(10.37a) \quad \left\| \xi_\eta \right\|_{H^{1/2}(\Gamma(t))} = \left\| \eta \right\|_{(H^{1/2}(\Gamma(t)))'}$$

$$(10.37b) \quad \int_{\Gamma(t)} \xi_\eta \eta \, d\sigma = \left\| \eta \right\|_{(H^{1/2}(\Gamma(t)))'}.$$

As in [Sec. 3.3](#), we introduce $\kappa > 0$ such that there exists a constant $c > 0$ such that

$$a^\kappa(t; \underline{\zeta}, \underline{\zeta}) := a(t; \underline{\zeta}, \underline{\zeta}) + \kappa m(t; \underline{\zeta}, \underline{\zeta}) \geq \left\| \underline{\zeta} \right\|_{\mathcal{V}(t)}^2 \quad \text{for all } \underline{\zeta} \in \mathcal{V}(t).$$

We wish to estimate the trace of η , the bulk component of $\underline{z} - \pi_h \underline{z}$, in the $(H^{1/2}(\Gamma(t)))'$ -norm. We consider the dual problem: Given ξ_η , find $\underline{\mathcal{R}}(\xi_\eta) = (\mathcal{R}_\Omega(\xi_\eta), \mathcal{R}_\Gamma(\xi_\eta)) \in \mathcal{V}(t)$ such that

$$(10.38) \quad a^\kappa(\underline{\zeta}, \underline{\mathcal{R}}(\xi_\eta)) = \int_{\Gamma(t)} \xi_\eta \zeta \, d\sigma \quad \text{for all } \underline{\zeta} = (\zeta, \rho) \in \mathcal{V}(t).$$

This problem is the weak form of coupled bulk surface elliptic problems and has a unique weak solution in $\mathcal{V}(t)$ (see Elliott and Ranner 2013, Thm. 3.2) which satisfies the estimate

$$\|\underline{\mathcal{R}}(\xi_\eta)\|_{\mathcal{V}(t)} \leq C \|\xi_\eta\|_{H^{1/2}(\Gamma(t))} = C \|\eta\|_{(H^{1/2}(\Gamma(t)))'}$$

The problem with $\rho = 0$ is a weak form of the problem:

$$(10.39) \quad -\nabla \cdot (\mathcal{A}_\Omega \nabla \mathcal{R}_\Omega(\xi_\eta)) + \mathcal{B}_\Omega \cdot \nabla \mathcal{R}_\Omega(\xi_\eta) + (\mathcal{C}_\Omega + \kappa) \mathcal{R}_\Omega(\xi_\eta) = 0$$

$$(10.40) \quad \mathcal{A}_\Omega \nabla \mathcal{R}_\Omega(\xi_\eta) + \alpha \mathcal{R}_\Omega(\xi_\eta) = \xi_\eta + \alpha \mathcal{R}_\Gamma(\xi_\eta).$$

This is a Robin problem which satisfies the regularity estimate (Ladyzhenskaya and Uraltseva, 1968; Gilbarg and Trudinger, 1983)

$$\|\mathcal{R}_\Omega(\xi_\eta)\|_{H^2(\Omega(t))} \leq c \|\xi_\eta\|_{H^{1/2}(\Gamma(t))} + c \|\mathcal{R}_\Gamma(\xi_\eta)\|_{H^{1/2}(\Gamma)} \leq c \|\eta\|_{(H^{1/2}(\Gamma(t)))'}$$

The problem with $\zeta = 0$ is a weak form of a surface elliptic problem with right hand side $\beta \mathcal{R}_\Omega(\xi_\eta)$ which satisfies the regularity estimate (Aubin, 1982).

$$\|\mathcal{R}_\Gamma(\xi_\eta)\|_{H^2(\Gamma(t))} \leq c \|\mathcal{R}_\Omega(\xi_\eta)\|_{L^2(\Gamma(t))} \leq c \|\eta\|_{(H^{1/2}(\Gamma(t)))'}$$

Combining the two regularity estimates we see that

$$(10.41) \quad \|\underline{\mathcal{R}}(\xi_\eta)\|_{\mathcal{Z}_0(t)} \leq c \|\eta\|_{(H^{1/2}(\Gamma(t)))'}$$

We note that the constant here is independent of time $t \in [0, T]$.

We see using (10.37b) and $\underline{\zeta} = \underline{\eta} = (\eta, \xi)$ in (10.38) that

$$(10.42) \quad \|\eta\|_{(H^{1/2}(\Gamma(t)))'} = \int_{\Gamma(t)} \xi_\eta \eta \, d\sigma = a^\kappa(\underline{\eta}, \underline{\mathcal{R}}(\xi_\eta)) = a^\kappa(\underline{\eta}, \underline{\mathcal{R}}(\xi_\eta) - I_h \underline{\mathcal{R}}(\xi_\eta)) + a^\kappa(\underline{\eta}, I_h \underline{\mathcal{R}}(\xi_\eta)).$$

For the first term on the right hand side of (10.42), we apply the boundedness of a^κ and the interpolation estimate (10.19) to see

$$|a^\kappa(\underline{\eta}, \underline{\mathcal{R}}(\xi_\eta) - I_h \underline{\mathcal{R}}(\xi_\eta))| \leq c \|\underline{\eta}\|_{\mathcal{V}(t)} \|\underline{\mathcal{R}}(\xi_\eta) - I_h \underline{\mathcal{R}}(\xi_\eta)\|_{\mathcal{V}(t)} \leq ch \|\underline{\eta}\|_{\mathcal{V}(t)} \|\underline{\mathcal{R}}(\xi_\eta)\|_{\mathcal{Z}_0(t)}.$$

For the second term on the right hand side of (10.42), we apply the geometric estimates (10.29), (10.27) and (10.33) and the interpolation estimate (10.19) to see that

$$\begin{aligned} |a^\kappa(\underline{\eta}, I_h \underline{\mathcal{R}}(\xi_\eta))| &= \left| a^\kappa(\pi_{h\bar{z}}, I_h \underline{\mathcal{R}}(\xi_\eta)) - a_h^\kappa(\Pi_{h\bar{z}}, \tilde{I}_h \underline{\mathcal{R}}(\xi_\eta)) \right| \\ &\leq \left| a^\kappa(\pi_{h\bar{z}} - \bar{z}, I_h \underline{\mathcal{R}}(\xi_\eta)) - a_h^\kappa(\Pi_{h\bar{z}} - \bar{z}^{-\ell}, \tilde{I}_h \underline{\mathcal{R}}(\xi_\eta)) \right| \\ &\quad + \left| a^\kappa(\bar{z}, I_h \underline{\mathcal{R}}(\xi_\eta) - \underline{\mathcal{R}}(\xi_\eta)) - a_h^\kappa(\bar{z}^{-\ell}, \tilde{I}_h \underline{\mathcal{R}}(\xi_\eta) - \underline{\mathcal{R}}(\xi_\eta)^{-\ell}) \right| \\ &\quad + \left| a^\kappa(\bar{z}, \underline{\mathcal{R}}(\xi_\eta)) - a_h^\kappa(\bar{z}^{-\ell}, \underline{\mathcal{R}}(\xi_\eta)^{-\ell}) \right| \\ &\leq ch^{k+1} \|\bar{z}\|_{\mathcal{Z}_0(t)} \|\underline{\mathcal{R}}(\xi_\eta)\|_{\mathcal{Z}_0(t)}. \end{aligned}$$

Hence, combining the previous estimates and applying the dual regularity (10.41), we infer that

$$\begin{aligned} \|\eta\|_{(H^{1/2}(\Gamma(t)))'}^2 &\leq c \left(h \|\underline{\eta}\|_{\mathcal{V}(t)} + h^{k+1} \|\bar{z}\|_{\mathcal{Z}_0(t)} \right) \|\underline{\mathcal{R}}(\xi_\eta)\|_{\mathcal{Z}_0(t)} \\ &\leq c \left(h \|\underline{\eta}\|_{\mathcal{V}(t)} + h^{k+1} \|\bar{z}\|_{\mathcal{Z}_0(t)} \right) \|\eta\|_{(H^{1/2}(\Gamma(t)))'}, \end{aligned}$$

and we have shown that

$$(10.43) \quad \|\eta\|_{(H^{1/2}(\Gamma(t)))'} \leq c \left(h \|\underline{\eta}\|_{\mathcal{V}(t)} + h^{k+1} \|\bar{z}\|_{\mathcal{Z}_0(t)} \right).$$

Returning to (10.36), we now see that for $(\eta, \xi) = z - \pi_h z$ and $(\zeta, \rho) \in \mathcal{Z}_0(t)$ that

$$\begin{aligned}
|b(t; (\eta, \xi), (\zeta, \rho))| &\leq \alpha \left| \int_{\Omega(t)} \mathcal{B}(w, \mathcal{A}_\Omega) \nabla \eta \cdot \nabla \zeta \, dx \right| + \alpha \left| \int_{\Omega(t)} \mathcal{B}_{\text{adv}}(w, \mathcal{B}_\Omega) \eta \cdot \nabla \zeta \, dx \right| \\
&\quad + \alpha \left| \int_{\Omega(t)} (\partial^\bullet \mathcal{C}_\Omega + \mathcal{C}_\Omega \nabla \cdot w) \eta \zeta \, dx \right| + \beta \left| \int_{\Gamma(t)} \mathcal{B}(w, \mathcal{A}_\Gamma) \nabla_\Gamma \xi \cdot \nabla_\Gamma \rho \, d\sigma \right| \\
&\quad + \beta \left| \int_{\Gamma(t)} \mathcal{B}_{\text{adv}}(w, \mathcal{B}_\Gamma) \xi \cdot \nabla_\Gamma \rho \, d\sigma \right| + \beta \left| \int_{\Gamma(t)} (\partial^\bullet \mathcal{C}_\Gamma + \mathcal{C}_\Gamma \nabla_\Gamma \cdot w) \xi \rho \, d\sigma \right| \\
&\quad + \left| \int_{\Gamma(t)} (\alpha \eta - \beta \xi)(\alpha \zeta - \beta \rho) \nabla_\Gamma \cdot w \, d\sigma \right| \\
&=: \alpha I_1 + \alpha I_2 + \alpha I_3 + \beta I_4 + \beta I_5 + \beta I_6 + I_7.
\end{aligned}$$

The estimates for I_2, I_3, I_5, I_6 and I_7 are clear

$$\alpha I_2 + \alpha I_3 + \beta I_5 + \beta I_6 + I_7 \leq c \|(\eta, \xi)\|_{\mathcal{H}(t)} \|(\zeta, \rho)\|_{\mathcal{Z}_0(t)}.$$

For I_1 , we apply similar reasoning to Lem. 8.25 with our estimate for η (10.43) and for I_4 , we apply similar reasoning to (9.67). Combining these estimates shows the desired bound. \square

Theorem 10.15. *Let $(u, v) \in L^2_V$ be the solution of (10.10) which we assume satisfies the regularity bound*

$$(10.44) \quad \sup_{t \in (0, T)} \|(u, v)\|_{\mathcal{Z}(t)}^2 + \int_0^T \|\partial^\bullet(u, v)\|_{\mathcal{Z}(t)}^2 \, dt \leq C_{u,v}.$$

Let $(U_h, V_h) \in C_{S_h}^1$, be the solution of the finite element scheme (10.15) and write $(u_h, v_h) = (U_h, V_h)^\ell$. Then we have the following error estimate

$$\begin{aligned}
(10.45) \quad \sup_{t \in (0, T)} \|(u, v) - (u_h, v_h)\|_{\mathcal{H}(t)}^2 + h^2 \int_0^T \|(u, v) - (u_h, v_h)\|_{\mathcal{V}(t)}^2 \, dt \\
\leq c \|(u_0, v_0) - (u_{h,0}, v_{h,0})\|_{\mathcal{H}(t)}^2 + ch^{2k+2} C_{u,v}.
\end{aligned}$$

Proof. We apply abstract Thm. 3.11 and check the assumptions. We know the lift is stable from Lem. 10.6. The existence and boundedness of g_ℓ and b_ℓ^K are dealt with in Lem. 10.11. The interpolation properties (I1) and (I2) are shown in Lem. 10.10. The geometric perturbation estimates (P1) to (P9) are shown in Lem. 10.12 and 10.13. Finally, (B3) is shown in Lem. 10.14. \square

11. NUMERICAL RESULTS

11.1. Implementation. The finite element methods were implemented using DUNE. In our numerical examples, we integrate the coefficients $\mathcal{A}_\Omega^h, \mathcal{B}_\Omega^h, \mathcal{C}_\Omega^h, \mathcal{A}_\Gamma^h, \mathcal{B}_\Gamma^h$ and c_Γ^h using a sufficiently accurate quadrature which does not affect the order of convergence of the schemes. We discretise in time using an implicit Euler time stepping scheme. The time step τ is scaled so that the optimal error scales are recovered. At each time step we solve the full system using the generalised minimal residual method,

The code produced to run these computations is available at

<https://github.com/tranner/dune-evolving-domains>

Let $T = 1$, and $t \in [0, T]$. For $t \geq 0$, we define $\Omega(t)$ via a parametrisation $G: \Omega_0 \times \mathbb{R}_+ \rightarrow \mathbb{R}^3$, for $\Omega_0 = B(0, 1) \subset \mathbb{R}^3$ the unit ball in three-dimensions. The parametrisation $G: \bar{\Omega} \times \mathbb{R}_+ \rightarrow \mathbb{R}^3$ is given by

$$G(x, t) = \left(a(t)^{1/2} x_1, x_2, x_3 \right), \quad a(t) = 1 + \frac{1}{4} \sin(t),$$

with velocity field w given by

$$w(x, t) = \left(\frac{\cos(t)x_1}{8(1 + 1/4 \sin(t))}, 0, 0 \right) \quad \text{for } x \in \bar{\Omega}(t).$$

The geometry is the same for each problem, which corresponds to an ellipsoidal domain growing along a single axis, but we solve in and on different parts of the domain.

For each test problem, for each iteration we complete an appropriate number of bisectional refinements (projecting boundary nodes on to the exact surface using the normal projection operator (9.4)) from a macro triangulation in order to approximately half the mesh size h and scale the time step τ to recover the optimal order of convergence – i.e. $\tau_j = \tau_0 2^{-(k+1)j}$. We show the error in an L^2 -norm at the final time. The experimental order of convergence (eoc) at level j is computed by

$$(\text{eoc})_j = \log(E_j/E_{j-1})/\log(h_j/h_{j-1}).$$

Errors in an H^1 -norm demonstrate an order of convergence less and are not listed here.

11.2. Problem on a bulk domain (1.4). We set the parameters in the equation as $\mathcal{A} = (1 + x_1^2)\text{Id}$, $\mathcal{B} = (1, 2, 0)$, $\mathcal{C} = \cos(x_1 x_2)$ and compute additional right hand sides in (1.4a) and (1.4b) and take appropriate initial data so that the solution is given by

$$u(x, t) = \sin(t) \cos(\pi x_1) \cos(\pi x_2) \quad \text{for } x \in \Omega(t).$$

We compute with $k = 1, 2$. The results are shown in Tab. 11.1 and 11.2.

h	τ	$L^2(\Omega(T))$ error	(eoc)
1.10017	1.00000	$7.54412 \cdot 10^{-2}$	—
$8.82662 \cdot 10^{-1}$	$2.50000 \cdot 10^{-1}$	$1.72380 \cdot 10^{-1}$	-3.75139
$5.23405 \cdot 10^{-1}$	$6.25000 \cdot 10^{-2}$	$1.07326 \cdot 10^{-1}$	0.90670
$2.79882 \cdot 10^{-1}$	$1.56250 \cdot 10^{-2}$	$3.17823 \cdot 10^{-2}$	1.94407
$1.44128 \cdot 10^{-1}$	$3.90625 \cdot 10^{-3}$	$8.34529 \cdot 10^{-3}$	2.01489

TABLE 11.1. $k = 1$

h	τ	$L^2(\Omega(T))$ error	(eoc)
1.10017	1.00000	$4.46630 \cdot 10^{-2}$	—
$8.82662 \cdot 10^{-1}$	$1.25000 \cdot 10^{-1}$	$4.44526 \cdot 10^{-2}$	0.02144
$5.23405 \cdot 10^{-1}$	$1.56250 \cdot 10^{-2}$	$7.59648 \cdot 10^{-3}$	3.38076
$2.79882 \cdot 10^{-1}$	$1.95312 \cdot 10^{-3}$	$1.05698 \cdot 10^{-3}$	3.15065
$1.44128 \cdot 10^{-1}$	$2.44141 \cdot 10^{-4}$	$1.38589 \cdot 10^{-4}$	3.06126

TABLE 11.2. $k = 2$

11.3. Problem on a closed surface (1.5). We set the parameters in the equation as $\mathcal{A} = (1 + x_1^2)\text{Id}$, $\mathcal{B} = (1, 2, 0) - (1, 2, 0) \cdot \mathbf{v}\mathbf{v}$, $\mathcal{C} = \sin(x_1x_2)$ and compute an additional right hand side in (1.5a) and take appropriate initial data so that the solution is given by

$$\mathbf{u}(x, t) = \sin(t)x_2x_3 \quad \text{for } x \in \Gamma(t).$$

We compute with $k = 2, 3$. The results are shown in Tab. 11.3 and 11.4.

h	τ	$L^2(\Gamma(T))$ error	(eoc)
$8.31246 \cdot 10^{-1}$	1.00000	$9.83996 \cdot 10^{-2}$	—
$4.40053 \cdot 10^{-1}$	$1.25000 \cdot 10^{-1}$	$1.47435 \cdot 10^{-2}$	2.98450
$2.22895 \cdot 10^{-1}$	$1.56250 \cdot 10^{-2}$	$1.99237 \cdot 10^{-3}$	2.94251
$1.11969 \cdot 10^{-1}$	$1.95312 \cdot 10^{-3}$	$2.50039 \cdot 10^{-4}$	3.01456
$5.60891 \cdot 10^{-2}$	$2.44141 \cdot 10^{-4}$	$3.12365 \cdot 10^{-5}$	3.00895

TABLE 11.3. $k = 2$

h	τ	$L^2(\Gamma(T))$ error	(eoc)
$8.31246 \cdot 10^{-1}$	1.00000	$9.88086 \cdot 10^{-2}$	—
$4.40053 \cdot 10^{-1}$	$6.25000 \cdot 10^{-2}$	$7.60635 \cdot 10^{-3}$	4.03157
$2.22895 \cdot 10^{-1}$	$3.90625 \cdot 10^{-3}$	$4.92316 \cdot 10^{-4}$	4.02476
$1.11969 \cdot 10^{-1}$	$2.44141 \cdot 10^{-4}$	$3.08257 \cdot 10^{-5}$	4.02448
$5.60891 \cdot 10^{-2}$	$1.52588 \cdot 10^{-5}$	$1.89574 \cdot 10^{-6}$	4.03416

TABLE 11.4. $k = 3$

11.4. Problem on a coupled bulk-surface domain (1.6). We set the parameters in the equation as $\mathcal{A}_X = \text{Id}$, $\mathcal{B}_X = (0, 0, 0)$, $\mathcal{C}_X = 0$, for $X = \Omega$ and Γ , and $\alpha = \beta = 1$, and compute additional right hand sides in (1.6a), (1.6b) and (1.6c) and take appropriate initial data so that the solution is given by

$$\mathbf{u}(x, t) = \sin(t)x_1x_2 \quad \text{for } x \in \Omega(t)$$

$$\mathbf{v}(x, t) = \sin(t)x_2x_3 \quad \text{for } x \in \Gamma(t).$$

We compute with $k = 1, 2$. The results are shown in Tab. 11.5 and 11.6.

h	τ	$L^2(\Omega(T))$ error	(eoc)	$L^2(\Gamma(T))$ error	(eoc)
1.10017	1.00000	$1.40014 \cdot 10^{-2}$	—	$7.41054 \cdot 10^{-2}$	—
$8.82662 \cdot 10^{-1}$	$2.50000 \cdot 10^{-1}$	$2.61297 \cdot 10^{-2}$	-2.83240	$4.53161 \cdot 10^{-2}$	2.23275
$5.23405 \cdot 10^{-1}$	$6.25000 \cdot 10^{-2}$	$9.52446 \cdot 10^{-3}$	1.93118	$1.58725 \cdot 10^{-2}$	2.00746
$2.79882 \cdot 10^{-1}$	$1.56250 \cdot 10^{-2}$	$2.61552 \cdot 10^{-3}$	2.06458	$4.25452 \cdot 10^{-3}$	2.10325
$1.44128 \cdot 10^{-1}$	$3.90625 \cdot 10^{-3}$	$6.72781 \cdot 10^{-4}$	2.04591	$1.08139 \cdot 10^{-3}$	2.06389

TABLE 11.5. $k = 1$

h	τ	$L^2(\Omega(T))$ error	(eoc)	$L^2(\Gamma(T))$ error	(eoc)
1.10017	1.00000	$2.44058 \cdot 10^{-2}$	—	$1.22069 \cdot 10^{-1}$	—
$8.82662 \cdot 10^{-1}$	$1.25000 \cdot 10^{-1}$	$2.92797 \cdot 10^{-3}$	9.62654	$9.65135 \cdot 10^{-3}$	11.51950
$5.23405 \cdot 10^{-1}$	$1.56250 \cdot 10^{-2}$	$4.02385 \cdot 10^{-4}$	3.79775	$1.47977 \cdot 10^{-3}$	3.58832
$2.79882 \cdot 10^{-1}$	$1.95312 \cdot 10^{-3}$	$5.08882 \cdot 10^{-5}$	3.30323	$1.87863 \cdot 10^{-4}$	3.29708
$1.44128 \cdot 10^{-1}$	$2.44141 \cdot 10^{-4}$	$6.36219 \cdot 10^{-6}$	3.13299	$2.34864 \cdot 10^{-5}$	3.13304

TABLE 11.6. $k = 2$

APPENDIX A. A FAÁ DI BRUNO FORMULA FOR PARAMETRIC SURFACES

A partition of the set $\{1, \dots, m\}$ is a collection of non-empty subsets $(\sigma_1, \dots, \sigma_r)$ such that $\sigma_s \cap \sigma_{s'} = \emptyset$ if $s' \neq s$ and $\bigcup_{s=1}^r \sigma_s = \{1, \dots, m\}$. We call r the order of the partition and denote by $|\sigma_s|$ the number of elements in σ_s . We say that two sets $\sigma = \{\sigma(1), \dots, \sigma(|\sigma|)\}$ and $\sigma' = \{\sigma'(1), \dots, \sigma'(|\sigma'|)\}$ are ordered and write $\sigma \prec \sigma'$ if $\min_{1 \leq l \leq |\sigma|} \sigma(l) < \min_{1 \leq l \leq |\sigma'|} \sigma'(l)$.

We denote by $\mathbb{P}_{m,r}$ the set of ordered non-empty partitions of $\{1, \dots, m\}$ of order r :

$$\mathbb{P}_{m,r} := \left\{ (\sigma_1, \dots, \sigma_r) : |\sigma_s| > 0 \text{ for } 1 \leq s \leq r, \sigma_s \cap \sigma_{s'} = \emptyset \text{ for } 1 \leq s \neq s' \leq r, \right. \\ \left. \bigcup_{s=1}^r \sigma_s = \{1, \dots, m\}, \text{ and } \sigma_s \prec \sigma_{s'} \text{ if } 1 \leq s < s' \leq r \right\}.$$

We note that we have $\mathbb{P}_{m,1} = \{\{\{1, 2, \dots, m\}\}\}$ and $\mathbb{P}_{m,m} = \{\{\{1\}, \{2\}, \dots, \{m\}\}\}$. That is that $\mathbb{P}_{m,1}$ and $\mathbb{P}_{m,m}$ each contain one partition.

For a subset $\sigma \subset \{1, \dots, m\}$, given $j_1, \dots, j_m \in \{1, \dots, n\}$, we write for smooth $\eta: \mathbb{R}^n \rightarrow \mathbb{R}$

$$\frac{\partial^{|\sigma|}}{\partial x_{j_\sigma}} \eta := \frac{\partial}{\partial x_{j_{\sigma(|\sigma|)}}} \cdots \frac{\partial}{\partial x_{j_{\sigma(1)}}} \eta.$$

Note that it is possible to have repeated indexes j_r which are not distinguished in this formula.

Theorem A.1. *Let $\Gamma \subset \mathbb{R}^{n+1}$ be a C^m surface with parametrisation $X: \Theta \rightarrow \Gamma$ over $\Theta \subset \mathbb{R}^n$. We denote the components of X by $X(\theta) = (X_1(\theta), \dots, X_{n+1}(\theta))$ for $\theta \in \Theta$ and the components of ∇_Γ by $((\nabla_\Gamma)_1, \dots, (\nabla_\Gamma)_{n+1})$. Let $f: \Gamma \rightarrow \mathbb{R}$ be in $C^m(\Gamma)$ and write $F: \Theta \rightarrow \mathbb{R}$ for the function defined by $F(\theta) = f(X(\theta))$ for $\theta \in \Theta$. Then $F \in C^m(\Theta)$ and*

$$(A.1) \quad \frac{\partial^m}{\partial \theta_{j_m} \cdots \partial \theta_{j_1}} F(\theta) = \sum_{r=1}^m \sum_{\lambda_1, \dots, \lambda_r=1}^{n+1} (\nabla_\Gamma)_{\lambda_r} \cdots (\nabla_\Gamma)_{\lambda_1} f(X(\theta)) \sum_{\mathbb{P}_{m,r}} \prod_{s=1}^r \frac{\partial^{|\sigma_s|}}{\partial \theta_{j_{\sigma_s}}} X_{\lambda_s}(\theta).$$

Before we show the result we will include some examples to show how this result can be interpreted and related to previous results.

Example A.2. (1) Consider the case $n = 1$ and Γ is a flat hypersurface. In this case $j_1 = \dots = j_m = 1$. Then the (A.1) translates to

$$\frac{d^m}{d\theta^m} F(\theta) = \sum_{r=1}^m \sum_{\lambda_1, \dots, \lambda_r=1}^2 (\nabla_\Gamma)_{\lambda_r} \cdots (\nabla_\Gamma)_{\lambda_1} f(X(\theta)) \sum_{\mathbb{P}_{m,r}} \prod_{s=1}^r \frac{d^{|\sigma_s|}}{d\theta^{|\sigma_s|}} X_{\lambda_s}(\theta).$$

We note that $(\nabla_\Gamma)_\lambda f = \partial f / \partial x$ if $\lambda = 1$ and 0 otherwise and that $X(\theta)_2 = 0$. Finally we note that the terms involving $X(\theta)$ can be reordered as

$$\sum_{\mathbb{P}_{m,r}} \prod_{s=1}^r \frac{d^{|\sigma_s|}}{d\theta^{|\sigma_s|}} (X(\theta))_{\lambda_s} = \sum_{E(m,r)} \prod_{q=1}^m c_i \left(\frac{d^q}{d\theta^q} X(\theta) \right)^{i_q},$$

where $E(m, r)$ is given by

$$E(m, r) = \{i \in \mathbb{N}_0^m : \sum_{q=1}^m i_q = r \text{ and } \sum_{q=1}^m qi_q = m\}.$$

The set $E(m, r)$ rather than being a set of partitions maps each partitions $(\sigma_1, \dots, \sigma_r)$ to a vector $i \in \mathbb{N}_0^m$ such that i_q is the number of sets in the partition such that $|\sigma_s| = q$ for $q = 1, \dots, m$. We can make the simplification in this case since, here, the order of derivatives is not important, whereas we wish to track this in (A.1).

Furthermore, the mapping from partitions to vectors i is not one-to-one (in particular because i does not care about ordering) which results in the constant c_i which counts how many partitions map to the same i .

We recover the result of (Bernardi, 1989, Eq. 2.9) in the scalar case:

$$\frac{d^m}{d\theta^m} F(\theta) = \sum_{r=1}^m \frac{\partial^r f}{\partial x^r}(X(\theta)) \sum_{E(m,r)} \prod_{q=1}^m c_i \left(\frac{d^q}{d\theta^q} X(\theta) \right)^{i_q}.$$

(2) We return to the general case, but to low numbers of derivatives. It is clear that

$$\frac{\partial}{\partial \theta_{j_1}} F(\theta) = \sum_{\lambda_1=1}^{n+1} (\nabla_{\Gamma})_{\lambda_1} f(X(\theta)) \frac{\partial}{\partial \theta_{j_1}} X_{\lambda_1}(\theta).$$

To start to understand the inductive procedure we will apply in the proof of [Thm. A.1](#), we construct a second derivative. We apply the product rule to see

$$\begin{aligned} & \frac{\partial^2}{\partial \theta_{j_2} \partial \theta_{j_1}} F(\theta) \\ &= \frac{\partial}{\partial \theta_{j_2}} \sum_{\lambda_1=1}^{n+1} (\nabla_{\Gamma})_{\lambda_1} f(X(\theta)) \frac{\partial}{\partial \theta_{j_1}} X_{\lambda_1}(\theta) \\ &= \sum_{\lambda_1=1}^{n+1} \left(\frac{\partial}{\partial \theta_{j_2}} (\nabla_{\Gamma})_{\lambda_1} f(X(\theta)) \right) \frac{\partial}{\partial \theta_{j_1}} X_{\lambda_1}(\theta) \\ & \quad + (\nabla_{\Gamma})_{\lambda_1} f(X(\theta)) \left(\frac{\partial}{\partial \theta_{j_2}} \frac{\partial}{\partial \theta_{j_1}} X_{\lambda_1}(\theta) \right) \\ &= \sum_{\lambda_1=1}^{n+1} \sum_{\lambda_2=1}^{n+1} (\nabla_{\Gamma})_{\lambda_2} (\nabla_{\Gamma})_{\lambda_1} f(X(\theta)) \frac{\partial}{\partial \theta_{j_2}} X_{\lambda_2}(\theta) \frac{\partial}{\partial \theta_{j_1}} X_{\lambda_1}(\theta) \\ & \quad + \sum_{\lambda_1=1}^{n+1} (\nabla_{\Gamma})_{\lambda_1} f(X(\theta)) \frac{\partial^2}{\partial \theta_{j_2} \partial \theta_{j_1}} X_{\lambda_1}(\theta). \end{aligned}$$

We see that the extra derivative either applies to the terms from the lower order derivative involving X or else apply to the terms involving f , in which case an extra first derivative of X is included. The result is a sum of these two terms.

To understand further how the terms involving X arise, we compute a third order derivative. Applying the same procedure as above we see

$$\begin{aligned}
& \frac{\partial^3}{\partial \theta_{j_3} \partial \theta_{j_2} \partial \theta_{j_1}} F(\theta) \\
&= \frac{\partial}{\partial \theta_{j_3}} \left(\sum_{\lambda_1=1}^{n+1} \sum_{\lambda_2=1}^{n+1} (\nabla_{\Gamma})_{\lambda_2} (\nabla_{\Gamma})_{\lambda_1} f(X(\theta)) \frac{\partial}{\partial \theta_{j_2}} X_{\lambda_2}(\theta) \frac{\partial}{\partial \theta_{j_1}} X_{\lambda_1}(\theta) \right. \\
&\quad \left. + \sum_{\lambda_1=1}^{n+1} (\nabla_{\Gamma})_{\lambda_1} f(X(\theta)) \frac{\partial^2}{\partial \theta_{j_2} \partial \theta_{j_1}} X_{\lambda_1}(\theta) \right) \\
&= \sum_{\lambda_1=1}^{n+1} \sum_{\lambda_2=1}^{n+1} \left(\frac{\partial}{\partial \theta_{j_3}} (\nabla_{\Gamma})_{\lambda_2} (\nabla_{\Gamma})_{\lambda_1} f(X(\theta)) \right) \frac{\partial}{\partial \theta_{j_2}} X_{\lambda_2}(\theta) \frac{\partial}{\partial \theta_{j_1}} X_{\lambda_1}(\theta) \\
&\quad + \sum_{\lambda_1=1}^{n+1} \sum_{\lambda_2=1}^{n+1} (\nabla_{\Gamma})_{\lambda_2} (\nabla_{\Gamma})_{\lambda_1} f(X(\theta)) \frac{\partial}{\partial \theta_{j_3}} \left(\frac{\partial}{\partial \theta_{j_2}} X_{\lambda_2}(\theta) \frac{\partial}{\partial \theta_{j_1}} X_{\lambda_1}(\theta) \right) \\
&\quad + \sum_{\lambda_1=1}^{n+1} \left(\frac{\partial}{\partial \theta_{j_3}} (\nabla_{\Gamma})_{\lambda_1} f(X(\theta)) \right) \frac{\partial^2}{\partial \theta_{j_2} \partial \theta_{j_1}} X_{\lambda_1}(\theta) \\
&\quad + \sum_{\lambda_1=1}^{n+1} (\nabla_{\Gamma})_{\lambda_1} f(X(\theta)) \frac{\partial}{\partial \theta_{j_3}} \frac{\partial^2}{\partial \theta_{j_2} \partial \theta_{j_1}} X_{\lambda_1}(\theta).
\end{aligned}$$

Again, we see that the θ_{j_3} derivative can either be applied to the terms involving f or the terms involving X and the result is a sum of these terms. Computing further we see

$$\begin{aligned}
& \frac{\partial^3}{\partial \theta_{j_3} \partial \theta_{j_2} \partial \theta_{j_1}} F(\theta) \\
&= \sum_{\lambda_1=1}^{n+1} \sum_{\lambda_2=1}^{n+1} \sum_{\lambda_3=1}^{n+1} (\nabla_{\Gamma})_{\lambda_3} (\nabla_{\Gamma})_{\lambda_2} (\nabla_{\Gamma})_{\lambda_1} f(X(\theta)) \frac{\partial}{\partial \theta_{j_3}} X_{\lambda_3}(\theta) \frac{\partial}{\partial \theta_{j_2}} X_{\lambda_2}(\theta) \frac{\partial}{\partial \theta_{j_1}} X_{\lambda_1}(\theta) \\
&\quad + \sum_{\lambda_1=1}^{n+1} \sum_{\lambda_2=1}^{n+1} (\nabla_{\Gamma})_{\lambda_2} (\nabla_{\Gamma})_{\lambda_1} f(X(\theta)) \\
&\quad \cdot \left(\frac{\partial^2}{\partial \theta_{j_3} \partial \theta_{j_2}} X_{\lambda_2}(\theta) \frac{\partial}{\partial \theta_{j_1}} X_{\lambda_1}(\theta) + \frac{\partial}{\partial \theta_{j_2}} X_{\lambda_2}(\theta) \frac{\partial^2}{\partial \theta_{j_3} \partial \theta_{j_1}} X_{\lambda_1}(\theta) \right. \\
&\quad \left. + \frac{\partial}{\partial \theta_{j_3}} X_{\lambda_2}(\theta) \frac{\partial^2}{\partial \theta_{j_2} \partial \theta_{j_1}} X_{\lambda_1}(\theta) \right) \\
&\quad + \sum_{\lambda_1=1}^{n+1} (\nabla_{\Gamma})_{\lambda_1} f(X(\theta)) \frac{\partial^3}{\partial \theta_{j_3} \partial \theta_{j_2} \partial \theta_{j_1}} X_{\lambda_1}(\theta).
\end{aligned}$$

We end up with terms involving one, two and three derivatives of f times sums of products of one, two and three terms involving derivatives of X respectively. We notice that the derivatives on X are not all arbitrary combinations of j 's and λ 's. The θ_{j_1} derivative always is against X_{λ_1} , the θ_{j_2} derivative is always against X_{λ_1} or X_{λ_2} and the θ_{j_3} derivative is against X_{λ_1} , X_{λ_2} or X_{λ_3} . Moreover, we see that the minimum index against X_{λ_s} is increasing in s . This property is written more formally in the definition of $\mathbb{P}_{m,r}$. Making this association rigorous is the route we take to proving the theorem.

We will show the result through the following two lemmas.

Lemma A.3. *The derivatives of F can be written as*

$$(A.2) \quad \frac{\partial^m}{\partial \theta_{j_m} \cdots \partial \theta_{j_1}} F(\theta) = \sum_{r=1}^m \sum_{\lambda_1, \dots, \lambda_r=1}^{n+1} (\nabla_{\Gamma})_{\lambda_r} \cdots (\nabla_{\Gamma})_{\lambda_1} f(X(\theta)) \alpha(j_1, \dots, j_m; \lambda_1, \dots, \lambda_r)(\theta)$$

where α satisfies the recurrence relationships

$$(A.3a) \quad \alpha(j; \lambda)(\theta) = \frac{\partial}{\partial \theta_j} X_{\lambda}(\theta)$$

$$(A.3b) \quad \alpha(j_1, \dots, j_{m+1}; \lambda)(\theta) = \frac{\partial}{\partial \theta_{j_{m+1}}} \alpha(j_1, \dots, j_m; \lambda)(\theta)$$

$$(A.3c) \quad \begin{aligned} \alpha(j_1, \dots, j_{m+1}; \lambda_1, \dots, \lambda_r)(\theta) &= \frac{\partial}{\partial \theta_{j_{m+1}}} \alpha(j_1, \dots, j_m; \lambda_1, \dots, \lambda_r)(\theta) \\ &+ \left(\frac{\partial}{\partial \theta_{j_{m+1}}} X_{\lambda_r}(\theta) \right) \alpha(j_1, \dots, j_m, \lambda_1, \dots, \lambda_{r-1})(\theta) \quad \text{for } 2 \leq r \leq m \end{aligned}$$

$$(A.3d) \quad \alpha(j_1, \dots, j_{m+1}; \lambda_1, \dots, \lambda_{m+1})(\theta) = \left(\frac{\partial}{\partial \theta_{j_{m+1}}} X_{\lambda_{m+1}}(\theta) \right) \alpha(j_1, \dots, j_m, \lambda_1, \dots, \lambda_m)(\theta).$$

Proof. For the base case (A.3a), we see that

$$\frac{\partial}{\partial \theta_j} F(\theta) = \sum_{\lambda=1}^{n+1} (\nabla_{\Gamma})_{\lambda} f(X(\theta)) \frac{\partial}{\partial \theta_j} X_{\lambda}(\theta) = \sum_{\lambda=1}^{n+1} (\nabla_{\Gamma})_{\lambda} f(X(\theta)) \alpha(j; \lambda)(\theta).$$

Then, given (A.2) holds up to m derivatives, we see that

$$\begin{aligned}
& \frac{\partial}{\partial \theta_j} \frac{\partial^m}{\partial \theta_{j_m} \cdots \partial \theta_{j_1}} F(\theta) \\
&= \frac{\partial}{\partial \theta_j} \sum_{r=1}^m \sum_{\lambda_1=1}^{n+1} \cdots \sum_{\lambda_r=1}^{n+1} (\nabla_{\Gamma})_{\lambda_r} \cdots (\nabla_{\Gamma})_{\lambda_1} f(X(\theta)) \alpha(j_1, \dots, j_m; \lambda_1, \dots, \lambda_r)(\theta) \\
&= \sum_{r=1}^m \sum_{\lambda_1=1}^{n+1} \cdots \sum_{\lambda_r=1}^{n+1} \left\{ \left(\frac{\partial}{\partial \theta_j} (\nabla_{\Gamma})_{\lambda_r} \cdots (\nabla_{\Gamma})_{\lambda_1} f(X(\theta)) \right) \alpha(j_1, \dots, j_m; \lambda_1, \dots, \lambda_r)(\theta) \right. \\
&\quad \left. + (\nabla_{\Gamma})_{\lambda_r} \cdots (\nabla_{\Gamma})_{\lambda_1} f(X(\theta)) \frac{\partial}{\partial \theta_j} \alpha(j_1, \dots, j_m; \lambda_1, \dots, \lambda_r)(\theta) \right\} \\
&= \sum_{r=1}^m \sum_{\lambda_1=1}^{n+1} \cdots \sum_{\lambda_r=1}^{n+1} \left\{ \sum_{\lambda_{r+1}=1}^{n+1} (\nabla_{\Gamma})_{\lambda_{r+1}} (\nabla_{\Gamma})_{\lambda_r} \cdots (\nabla_{\Gamma})_{\lambda_1} f(X(\theta)) \left(\frac{\partial}{\partial \theta_j} X_{\lambda_{r+1}}(\theta) \right) \alpha(j_1, \dots, j_m; \lambda_1, \dots, \lambda_r)(\theta) \right. \\
&\quad \left. + (\nabla_{\Gamma})_{\lambda_r} \cdots (\nabla_{\Gamma})_{\lambda_1} f(X(\theta)) \frac{\partial}{\partial \theta_j} \alpha(j_1, \dots, j_m; \lambda_1, \dots, \lambda_r)(\theta) \right\} \\
&= \sum_{r=2}^{m+1} \sum_{\lambda_1=1}^{n+1} \cdots \sum_{\lambda_r=1}^{n+1} (\nabla_{\Gamma})_{\lambda_r} \cdots (\nabla_{\Gamma})_{\lambda_1} f(X(\theta)) \left(\frac{\partial}{\partial \theta_j} X_{\lambda_r}(\theta) \right) \alpha(j_1, \dots, j_m; \lambda_1, \dots, \lambda_{r-1})(\theta) \\
&\quad + \sum_{r=1}^m \sum_{\lambda_1=1}^{n+1} \cdots \sum_{\lambda_r=1}^{n+1} (\nabla_{\Gamma})_{\lambda_r} \cdots (\nabla_{\Gamma})_{\lambda_1} f(X(\theta)) \frac{\partial}{\partial \theta_j} \alpha(j_1, \dots, j_m; \lambda_1, \dots, \lambda_r)(\theta) \\
&= \sum_{\lambda_1=1}^{n+1} (\nabla_{\Gamma})_{\lambda_1} f(X(\theta)) \frac{\partial}{\partial \theta_j} \alpha(j_1, \dots, j_m; \lambda_1)(\theta) \\
&\quad + \sum_{r=2}^m \sum_{\lambda_1=1}^{n+1} \cdots \sum_{\lambda_r=1}^{n+1} (\nabla_{\Gamma})_{\lambda_r} \cdots (\nabla_{\Gamma})_{\lambda_1} f(X(\theta)) \left\{ \left(\frac{\partial}{\partial \theta_j} X_{\lambda_r}(\theta) \right) \alpha(j_1, \dots, j_m; \lambda_1, \dots, \lambda_{r-1})(\theta) \right. \\
&\quad \left. + \frac{\partial}{\partial \theta_j} \alpha(j_1, \dots, j_m; \lambda_1, \dots, \lambda_r)(\theta) \right\} \\
&\quad + \sum_{\lambda_1=1}^{n+1} \cdots \sum_{\lambda_{m+1}=1}^{n+1} (\nabla_{\Gamma})_{\lambda_{m+1}} \cdots (\nabla_{\Gamma})_{\lambda_1} f(X(\theta)) \left(\frac{\partial}{\partial \theta_j} X_{\lambda_{m+1}}(\theta) \right) \alpha(j_1, \dots, j_m; \lambda_1, \dots, \lambda_m)(\theta).
\end{aligned}$$

Reading off coefficients gives the result. \square

Lemma A.4. *It holds that*

$$\alpha(j_1, \dots, j_m; \lambda_1, \dots, \lambda_r) = \sum_{\mathbb{P}_{m,r}} \prod_{s=1}^r \frac{\partial^{|\sigma_s|}}{\partial \theta_{j_{\sigma_s}}} X_{\lambda_s}(\theta).$$

Proof. For the base case, $m = 1$, we see that $\alpha(j; \lambda)(\theta) = \partial / \partial \theta_j X_{\lambda}(\theta)$ and clearly the set of ordered partitions is $\mathbb{P}_{1,1} = \{(1)\}$.

Suppose the identity holds for derivatives up to order m .

First, we consider $r = 1$, then

$$\alpha(j_1, \dots, j_{m+1}; \lambda)(\theta) = \frac{\partial}{\partial \theta_{j_{m+1}}} \alpha(j_1, \dots, j_m; \lambda)(\theta) = \cdots = \frac{\partial^{m+1}}{\partial \theta_{j_{m+1}} \cdots \partial \theta_{j_1}} X_{\lambda}(\theta).$$

We also have that there is only one partition of $1, \dots, m+1$ into 1 subset: $\mathbb{P}_{m+1,1} = \{(1, \dots, m+1)\}$.

Next, we consider $r = m + 1$, then

$$\begin{aligned}\alpha(j_1, \dots, j_{m+1}; \lambda_1, \dots, \lambda_{m+1})(\theta) &= \left(\frac{\partial}{\partial \theta_{j_{m+1}}} X_{\lambda_{m+1}}(\theta) \right) \alpha(j_1, \dots, j_m; \lambda_1, \dots, \lambda_m)(\theta) \\ &= \dots = \prod_{s=1}^{m+1} \frac{\partial}{\partial \theta_{j_s}} X_{\lambda_s}(\theta).\end{aligned}$$

We also have that there is only partition of $1, \dots, m+1$ into $m+1$ ordered sets: $\mathbb{P}_{m+1, m+1} = \{((1), (2), \dots, (m+1))\}$ so this case is complete.

Next, we consider $2 \leq r \leq m-1$. We see

$$\begin{aligned}\alpha(j_1, \dots, j_{m+1}; \lambda_1, \dots, \lambda_r)(\theta) &= \frac{\partial}{\partial \theta_{j_{m+1}}} \alpha(j_1, \dots, j_m; \lambda_1, \dots, \lambda_r)(\theta) + \left(\frac{\partial}{\partial \theta_{j_{m+1}}} X_{\lambda_r}(\theta) \right) \alpha(j_1, \dots, j_m, \lambda_1, \dots, \lambda_{r-1})(\theta) \\ &= \sum_{\mathbb{P}_{m,r}} \sum_{\alpha=1}^r \prod_{s=1}^r \frac{\partial^{|\tilde{\sigma}_s, \alpha|}}{\partial \theta_{j_{\tilde{\sigma}_s, \alpha}}} X_{\lambda_s}(\theta) + \sum_{\mathbb{P}_{m,r-1}} \left(\frac{\partial}{\partial \theta_{j_{m+1}}} X_{\lambda_r}(\theta) \right) \prod_{s=1}^r \frac{\partial^{|\sigma_s|}}{\partial \theta_{j_{\sigma_s}}} X_{\lambda_s}(\theta) \\ &= \sum_Q \prod_{s=1}^r \frac{\partial^{|\sigma_s|}}{\partial \theta_{j_{\sigma_s}}} X_{\lambda_s}(\theta),\end{aligned}$$

where $\tilde{\sigma}_s, \alpha = \sigma_s \cup \{m+1\}$ if $s = \alpha$ and σ_s otherwise and Q is given by

$$\begin{aligned}Q &:= \bigcup_{\alpha=1}^r \{(\tilde{\sigma}_{1,\alpha}, \dots, \tilde{\sigma}_{r,\alpha}) : (\sigma_1, \dots, \sigma_r) \in \mathbb{P}_{m,r}\} \\ &\quad \cup \{(\sigma_1, \dots, \sigma_{r-1}, (m+1)) : (\sigma_1, \dots, \sigma_{r-1}) \in \mathbb{P}_{m,r-1}\} \\ &=: \bigcup_{\alpha=1}^r Q_\alpha \cup Q_0.\end{aligned}$$

The proof will be complete if we show $Q = \mathbb{P}_{m+1,r}$.

First, let $(\sigma_1, \dots, \sigma_r) \in Q$. It is clear that $(\sigma_1, \dots, \sigma_r)$ is a partition. There are two cases to check the ordering $(\sigma_1, \dots, \sigma_r) \in Q_0$ (i) or Q_α for $\alpha = 1, \dots, r$ (ii). For case (i), we have that $\sigma_r = \{m+1\}$ and $(\sigma_1, \dots, \sigma_{r-1}) \in \mathbb{P}_{m,r-1}$. The first assertion shows that $\sigma_s < \sigma_r$ for $1 \leq s \leq r-1$ and the second shows that $\sigma_s < \sigma_{s'}$ for $1 \leq s < s' \leq r-1$. So we see that $(\sigma_1, \dots, \sigma_r) \in \mathbb{P}_{m,r}$. For case (ii), we have that $m+1 \in \sigma_\alpha$ and $(\sigma_1, \dots, \sigma_r) = (\tilde{\sigma}'_{1,\alpha}, \dots, \tilde{\sigma}'_{r,\alpha})$ for some $(\sigma'_1, \dots, \sigma'_r) \in \mathbb{P}_{m,r}$. Since $(\sigma'_1, \dots, \sigma'_r)$ is an ordered partition, we see that $\sigma'_\alpha = \sigma_\alpha \setminus \{m+1\}$ is non empty and the smallest index in σ'_α is the same as the smallest index in σ_α so that the ordering property is preserved.

Second, let $(\sigma_1, \dots, \sigma_r) \in \mathbb{P}_{m+1,r}$. Let $1 \leq s \leq r$ be such that $m+1 \in \sigma_s$. First, suppose that removing $m+1$ from σ_s results in a non-empty set. Then $(\sigma_1, \dots, \sigma_s \setminus \{m+1\}, \dots, \sigma_r)$ is a partition in $\mathbb{P}_{m,r}$. In this case, $(\sigma_1, \dots, \sigma_r) \in Q_s$. Otherwise suppose $\sigma_s \setminus \{m+1\}$ is empty. Then, by the ordering of partitions in $\mathbb{P}_{m,r}$, we must have that $s = r$ and $(\sigma_1, \dots, \sigma_{r-1})$ is an ordered partition of $(1, \dots, m)$. In this case $(\sigma_1, \dots, \sigma_r) \in Q_0$.

Thus we have shown the desired form of α . \square

Proof of Thm. A.1. Simply combine the two previous lemmas. \square

We could also apply a similar result using an inverse parametrisation X^{-1} and recover coefficients involving derivatives of X^{-1} . In the applications we consider, higher derivatives of X^{-1} are hard to estimate. As an alternative we give the following result which is based on rearranging terms in (A.1).

Corollary A.5. *Under the same assumptions as [Thm. A.1](#) we have:*

$$(A.4) \quad \begin{aligned} & (\nabla_\Gamma)_{i_m} \cdots (\nabla_\Gamma)_{i_1} f(X(\theta)) \\ &= \sum_{j_m, \dots, j_1=1}^n \frac{\partial^m}{\partial \theta_{j_m} \cdots \partial \theta_{j_1}} F(\theta) \left(\prod_{s=1}^m (\nabla X(\theta))_{j_s, i_s}^\dagger \right) \\ & \quad - \sum_{r=1}^{m-1} \sum_{\lambda_1, \dots, \lambda_r=1}^{n+1} (\nabla_\Gamma)_{\lambda_r} \cdots (\nabla_\Gamma)_{\lambda_1} f(X(\theta)) \sum_{j_m, \dots, j_1=1}^n \sum_{\mathbb{P}_{m,r}} \prod_{s=1}^r \frac{\partial^{|\sigma_s|}}{\partial \theta_{j_{\sigma_s}}} X_{\lambda_s}(\theta) \prod_{s=1}^m (\nabla X)_{j_s, i_s}^\dagger \end{aligned}$$

where $P_{ij} = P_{ij}(x) = \delta_{ij} - v_i(x)v_j(x)$ is projection onto the tangent space of Γ at x .

Proof. We start by noting that we have two equivalent ways of computing surface derivatives: either using the projection onto the tangent space of Γ or using the parametrisation of Γ . We apply each of these formulae to the function $x \mapsto x_i$ and take the $(\nabla_\Gamma)_j$ derivative at $x = X(\theta)$ to see

$$(A.5) \quad P_{ij}(x) = \delta_{ij} - v_i(x)v_j(x) = (\nabla_\Gamma)_j(x_i) = \sum_{\lambda=1}^n \left(\frac{\partial}{\partial \theta_\lambda} X_i(\theta) \right) (\nabla X(\theta))_{\lambda, j}^\dagger.$$

In particular, we see that

$$(A.6) \quad \sum_{j_m=1}^n \cdots \sum_{j_1=1}^n \left(\prod_{s=1}^m \frac{\partial}{\partial \theta_{j_s}} X_{\lambda_s}(\theta) \right) \left(\prod_{s=1}^m (\nabla X(\theta))_{j_s, i_s}^\dagger \right) = \prod_{s=1}^m P_{\lambda_s, i_s}(x).$$

The next step of the proof is to split the right hand side of [\(A.1\)](#) into terms involving m th order derivatives of X and the rest. We multiply by $\prod_{s=1}^m (\nabla X)_{j_s, i_s}^\dagger$ and sum of each j_s in turn to see that

$$\begin{aligned} & \sum_{j_m, \dots, j_1=1}^n \frac{\partial^m}{\partial \theta_{j_m} \cdots \partial \theta_{j_1}} F(\theta) \prod_{s=1}^m (\nabla X)_{j_s, i_s}^\dagger \\ &= \sum_{\lambda_1, \dots, \lambda_m=1}^{n+1} (\nabla_\Gamma)_{\lambda_m} \cdots (\nabla_\Gamma)_{\lambda_1} f(X(\theta)) \sum_{j_m, \dots, j_1=1}^n \prod_{s=1}^m \frac{\partial}{\partial \theta_{j_s}} X_{\lambda_s}(\theta) \prod_{s=1}^m (\nabla X)_{j_s, i_s}^\dagger \\ & \quad + \sum_{r=1}^{m-1} \sum_{\lambda_1, \dots, \lambda_r=1}^{n+1} (\nabla_\Gamma)_{\lambda_r} \cdots (\nabla_\Gamma)_{\lambda_1} f(X(\theta)) \sum_{j_m, \dots, j_1=1}^n \sum_{\mathbb{P}_{m,r}} \prod_{s=1}^r \frac{\partial^{|\sigma_s|}}{\partial \theta_{j_{\sigma_s}}} X_{\lambda_s}(\theta) \prod_{s=1}^m (\nabla X)_{j_s, i_s}^\dagger. \end{aligned}$$

For the first term on the right hand side we apply [\(A.6\)](#) and that the tangential gradient is already in the tangent space to see

$$\begin{aligned} & \sum_{\lambda_1, \dots, \lambda_m=1}^{n+1} (\nabla_\Gamma)_{\lambda_m} \cdots (\nabla_\Gamma)_{\lambda_1} f(X(\theta)) \sum_{j_m, \dots, j_1=1}^n \prod_{s=1}^m \frac{\partial}{\partial \theta_{j_s}} X_{\lambda_s}(\theta) \prod_{s=1}^m (\nabla X)_{j_s, i_s}^\dagger \\ &= \sum_{\lambda_1, \dots, \lambda_m=1}^{n+1} (\nabla_\Gamma)_{\lambda_m} \cdots (\nabla_\Gamma)_{\lambda_1} f(X(\theta)) \prod_{s=1}^m P_{\lambda_s, i_s}(x) \\ &= (\nabla_\Gamma)_{i_m} \cdots (\nabla_\Gamma)_{i_1} f(X(\theta)). \end{aligned}$$

The result then follows by simply rearranging the terms. \square

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