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Zuhal Ozdemir, Andrew Tyas, Russell Goodall, Harm Askes

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Highlights

- A numerical analysis framework has been developed that captures the experimentally observed dynamic response of micro-lattices
- The framework has been demonstrated to be accurate and robust across two lattice geometries and two loading rates, with responses monitored at both the impact face and the distal face of the sample
- The results suggest that simple MDoF models can be developed to capture the response of such geometries under fast loading regimes

1

Energy absorption in lattice structures in dynamics: Nonlinear FE simulations

Zuhal Ozdemir^a, Andrew Tyas^a, Russell Goodall^b, Harm Askes^a,

^aDepartment of Civil and Structural Engineering, The University of Sheffield ^bDepartment of Materials Science and Engineering, The University of Sheffield

1 Abstract

An experimental study of the stress-strain behaviour of titanium alloy 2 Ti6Al4V) lattice structures across a range of loading rates has been reported (3 in a previous paper (Ozdemir et al., 2016). The present work develops sim-4 ble numerical models of re-entrant and diamond lattice structures, for the 5 first time, to accurately reproduce quasi-static and Hopkinson Pressure Bar 6 (HPB) test results presented in the previous paper. Following the develop-7 ment of lattice models using implicit and explicit non-linear finite element 8 (FE) codes, the numerical models are first validated against the experimental 9 results and then utilised to explore further the phenomena associated with 10 impact, the failure modes and strain-rate sensitivity of these materials. We 11 have found that experimental results can be captured with good accuracy 12 by using relatively simple numerical models with beam elements. Numer-13 ical HPB simulations demonstrate that intrinsic strain rate dependence of 14 Ti6Al4V is not sufficient to explain the emergent rate dependence of the 15 re-entrant cube samples. There is also evidence that, whilst re-entrant cube 16 17 specimens made up of multiple layers of unit cells are load rate sensitive, the mechanical properties of individual lattice structure cell layers are relatively 18

^{*}Corresponding author

^{**}Tel. +44(0)114 222 5769; Fax: +44(0)124 222 5700

Email address: h.askes@sheffieldac.uk (Harm Askes)

¹⁹ insensitive to load rate. These results imply that a rate-independent load-

- $_{20}$ deflection model of the unit cell layers could be used in a simple multi degree
- ²¹ of freedom (MDoF) model to represent the impact behaviour of a multi-layer
- 22 specimen and capture the microscopic rate dependence. Keywords: lattice structures, impact and blast protection, finite element

method (FEM), emergent rate-dependence

23 1. Introduction

Over the previous few decades, research into the quasi-static and dy-24 namic behaviour and energy absorbing characteristics of cellular solids has 25 been assessed using costly experiments, because of the extreme complexities 26 associated with their collapse mechanisms. With the current advances in 27 numerical methods, we can predict the response of cellular solids even under 28 very highly nonlinear loading regimes with a reasonable accuracy. Thus, in 29 recent years, numerical methods have been widely used for the characteri-30 sation of mechanical behaviour and energy absorption properties of cellular 31 solids. 32

Numerical studies carried out on cellular solids are of both quasi-static and dynamic nature and have been performed on a wide range of materials including both stochastic (such as metallic foams) and periodic cellular solids (such as lattice structures, hallow rings). Aktay et al. (2008) studied the quasi-static crushing behaviour of honeycombs using detailed micromechanical models, homogenised modelling approach and a finite elementdiscrete particle model with semi-adaptive coupling (SAC) technique and compared the results of these models with experiments. The progressive

folding behaviour of square aluminium tubes subjected to quasi-static axial 41 crushing was numerically investigated using FEM by El-Hage et al. (2005). 42 Karagiozova et al. (2005) studied the dynamic response of circular and square 43 aluminium alloy tubes subjected to an axial explosive load using experimen-44 tal and numerical techniques. Particular attention was paid to the influence 45 of the impulse and material properties on the energy absorption capacity of 46 tubes. Compressive response of a multi-layered steel pyramidal lattice, which 47 was investigated by underwater explosive tests, was simulated using a fully 48 coupled Euler-Lagrange FE hydro code by (Wadley et al., 2008). Energy 49 absorption, wave filtering and wave variation characteristics of ring systems 50 after collapse were studied both experimentally and numerically by Wang 51 et al. (2010). In the majority of the numerical studies, cellular structures are 52 assumed to have perfect geometries. However, the extent of imperfections 53 can be more easily considered and controlled in a numerical model than a 54 physical test. The effects of cell shape and cell wall thickness imperfections 55 on the dynamic crushing behaviour of honeycomb structures were studied 56 using the FEM by Li et al. (2007). Ajdari et al. (2011) carried out a nu-57 merical study on 2D honeycomb structures in order to clarify the effect of 58 deformation rate, defects and irregularity on the behaviour of cellular struc-59 tures. However, validation of the numerical model was not presented in their 60 paper. 61

Although there are several disadvantages associated with experiments (for instance cost, time and collection of limited information during a fast dynamic phenomenon), experimental works conducted on a range of cellular materials have highlighted important issues associated with energy

absorption mechanisms of such materials when subjected to high loading 66 rates. For instance, Reid and Peng (1997) and Vural and Ravichandran 67 (2003) carried out Hopkinson Pressure Bar (HPB) and Split Hopkinson 68 Pressure Bar (SHPB) tests on wood samples, respectively. Reid and Peng 69 (1997) reported localised deformation mechanism and enhancement of crush-70 ing strength of wood under dynamic loading conditions. Vural and Ravichan-71 dran (2003) computed specific energy dissipation capacity of balsa wood and 72 they found that it was comparable with those of fiber-reinforced polymer 73 composites. Quasi-static and dynamic response of rectangular arrays of thin-74 walled metal cylindrical tubes were examined experimentally by Shim and 75 Stronge (1986) and Stronge and Shim (1987), respectively. It was observed 76 that the response of a tightly-packed array of ductile, thin-walled tubes un-77 der quasi-static and dynamic conditions is governed by the packing arrange-78 ment. Similarly, experiments carried out on diamond and re-entrant cube 79 lattices (Ozdemir et al., 2016) demonstrated that unit cell geometry controls 80 the force-deformation response of such structures. Goldsmith and Sackman 81 (1992) determined the energy dissipation characteristics of bare honeycombs 82 and sandwich plates with honeycomb cores using a ballistic pendulum. Al-83 ghamdi (2001) presented a review on mechanical properties of materials and 84 devices including tubes, sandwich plates and honeycomb cells for dissipating 85 kinetic energy. 86

A thorough understanding of the dynamic behaviour of cellular solids is crucial for maximising the performance of such materials particularly under high loading rates. The response of cellular solids may show quite distinctive differences under quasi-static and dynamic loads, because of rate sensitiv-

ity. The mechanisms of rate sensitivity of cellular materials consist of the 91 strain rate dependence of the parent material, the microinertia effects, the 92 compression and flow of air trapped in cells, the shock wave generation, 93 the effect of micro-structural geometry and the influence of intrinsic length 94 scale of the material. Several experimental and numerical studies have been 95 undertaken on cellular materials to highlight mechanisms causing rate sen-96 sitivity. Lee et al. (2006a) carried out a series of quasi-static compression, 97 Kolsky bar (SHPB) and gas gun experiments (HPB) on a type of open-98 cell aluminium alloy foam and stainless steel woven textile core materials. 99 While the peak stress of open-cell foams was deformation insensitive, the 100 rate-sensitivity of the peak stress was observed in the textile cores. Differ-101 ences in local strain fields were observed in both materials at intermediate 102 strain rates $(230 - 330 \,\mathrm{s}^{-1})$, when compared with quasi-static loading con-103 ditions. This was attributed to the microinertia effects for the case of foam 104 materials. At very high strain rates, the shock wave propagation was ob-105 served in both materials. In a following study, Lee et al. (2006b) undertook 106 similar physical tests on pyramidal truss cores made of 304 stainless steel 107 to investigate deformation modes of such materials. In addition, non-linear 108 FE simulations were performed to understand the roles of material strain 109 rate hardening and microinertia on the quasi-static and dynamic response 110 of sandwich panels with pyramidal truss cores. At intermediate strain rates, 111 microinertia effects caused differences in force-deformation response and de-112 formation mode of such materials when compared with quasi-static loading 113 conditions. At larger deformations, in addition to micro-inertia, the material 114 strain rate hardening contributed to changes in deformation mode and stress-115

strain response. Liu et al. (2009) studied the dynamic crushing behaviour 116 of 2D Voronoi honeycomb using FE method. Three different deformation 117 modes were observed at different loading ranges. These are: (1) quasi-static 118 homogeneous modes where crush bands are located randomly and the defor-119 mation is macroscopically uniform; (2) transition mode in which crush bands 120 are mainly concentrated at the impact end rather than the support end; and 121 (3) shock mode where crush bands sequentially propagate from impact end 122 to the distal end. The changes in deformation mechanisms and stress-strain 123 response of Voronoi honeycomb observed under high loading rates were at-124 tributed to inertia effects. Zhao and Gary (1998) performed quasi-static 125 and SHPB tests on aluminium honeycombs in the in-plane and out-of-plane 126 directions. While the in-plane crushing behaviour of the aluminium honey-127 comb was rate insensitive, significant differences between static and dynamic 128 out-of-plane crushing behaviour of the honeycombs were observed due to 129 structural effects. Barnes et al. (2014) used direct impact tests to evaluated 130 shock-like response of an open cell aluminium foam by developing shock-131 impact speed Hugoniot relations. As an extension of this work, Gaitanaros 132 and Kyriakides (2014) used FE analysis to replicate the experimentally ob-133 served dynamic crushing behaviour of the open cell aluminium foam by form-134 ing planar shocks. Zheng et al. (2014) examined the dynamic stress-strain 135 states in a closed-cell foam under direct impact conditions by creating FE 136 models of the foam using 3D Voronoi technique. Sun et al. (2016) obtained 137 a linear relation between shock speed and impact speed and established a 138 ¹³⁹ unique linear Hugoniot relation to characterise shock constitutive relation for a 2D virtual foam. 140

In this study, we aim to develop simple FE models of titanium alloy 141 (Ti6Al4V) lattice structures to reproduce quasi-static and Hopkinson Pres-142 sure Bar (HPB) test results reported in a previous study (Ozdemir et al., 143 2016) with a reasonable accuracy. In the literature, existing numerical and 144 experimental studies on lattice structures focus mainly on two geometries: 145 body-centred cubic (BCC) and a similar structure with vertical pillars (BCC-146 Z) (McKown et al., 2008; Mines et al., 2013; Smith et al., 2013). To the 147 best of our knowledge, this is the first research to numerically investigate 148 the dynamic response of re-entrant and diamond lattices. Imperfections of 149 the lattice structures have not been accounted for in the numerical mod-150 els and perfect models of re-entrant cube and diamond lattices have been 151 built. In addition, there are very limited studies in the literature, which 152 validate numerical results against experiments for the dynamic response of 153 cellular solids over all duration of impact event (Lee et al., 2006b) and exist-154 ing studies mainly focus on a maximum value of a response parameter (such 155 as maximum displacement). Following the development of numerical lattice 156 models using implicit and explicit non-linear finite element (FE) codes, in 157 this work, these models are validated against experimental results during all 158 time history of the impact event. Finally, the numerical models are utilised 159 to explore further the phenomena associated with impact, the failure modes 160 and strain-rate sensitivity of these materials. 161

The outline of the present paper can be summarised as follows: In Section 2, a nonlinear FE procedure for the analysis of quasi-static and impact response of diamond and re-entrant cube lattice structures is discussed briefly. Next, stress-strain response and associated failure modes of lattices, which were captured by quasi-static compression tests, are simulated using the nonlinear FEM in Section 3. The energy absorption characteristics of lattices under high deformation rates are examined numerically in Section 4 by taking into account the effect of unit-cell geometric configuration. Finally, the influence of strain rate sensitivity of Ti6Al4V and radial confinement on the impact response lattice samples is assessed in Sections 5 and 6, respectively.

¹⁷² 2. Nonlinear FE modelling

In this work, two unit cell geometries are chosen to carry out numerical 173 HPB impact simulations. The geometries are diamond (Figure 1(a)), where 174 the struts are arranged similar to the interatomic bonds in the atomic lattice 175 of diamond, and re-entrant cube (Figure 1(b)), a cube shape with all edges 176 and diagonal struts across the faces bent towards the centre; were it not for 177 the fact that the unit cells of the lattice are connected at the corners, this 178 last structure would resemble the auxetic structure of Lakes and Park (1998). 179 The repeating unit cell is kept as a 5 mm side length cube for both lattices. 180 Square strut cross-section was chosen for the diamond lattices with diagonal 181 length of 1.0 mm, whereas the strut diameter of the re-entrant cube is 0.48 182 mm. 183

For HPB impact tests, a steel bar projectile and a Nylon 66 impactor are used for low and high velocity loadings, respectively. The steel projectile has a diameter of 25 mm, a length of 250 mm and a mass of 963 g. The Nylon 66 projectiles have a diameter of 27 mm, a length of 31 mm and a mass of 188 19.3 g. Two testing configurations were considered for the HPB tests: In the first case, the specimen was placed on the impact face of the HPB and



Figure 1: Representative unit cells of (a) diamond and (b) re-entrant cube lattice structures.

the projectile was fired onto the specimen (Figure 2(a)). In the other case, the test specimens were fixed to the impact face of the projectile (Figure 2(b)). In these tests, 3D FE models of the impactor and HPB are built along with the full 3D models of lattices therefore, boundary conditions are taken care of by contact algorithms defined between the impactor and sample and between the HPB and sample. The HPB has a free boundary condition at its far end.

The multi-purpose nonlinear FE analysis program LS-DYNA is used to 197 simulate the response mechanisms of lattice samples. Due to the fact that 198 continuum elements are computationally expensive, 3D Timoshenko beam 199 elements with plasticity and large deformation capabilities are used for the 200 modelling of lattices. The main failure mechanisms of the lattices such as 201 202 plasticity, buckling, and brittle shear failure are considered in the numerical model. In order to take into account plasticity, a material model pertaining 203 to Von Mises yield condition with isotropic strain hardening is introduced in 204



Figure 2: Two testing configurations for the HPB tests: (a) the distal face test and (b) impact face test.

the FE model. A plastic strain-based failure criteria, where the element is 205 deleted when all the through thickness integration points reach the defined 206 failure strain, is used in the model. Buckling is considered by activating 207 geometric nonlinearity in the numerical simulations. In addition, struts are 208 discretised by several beam elements in order to capture the micro-buckling 209 of struts correctly. Tensile tests were performed on as-built round samples 210 with a cross-sectional area of 24 mm² by following ASTM E8M-13a guide-211 lines (E8M-13a (2013)) to determine mechanical properties of Ti6Al4V. In 212 the material model, Ti6Al4V alloy is assumed to have a Young's modulus of 213 114 GPa, Poisson's ratio of 0.3, mass density of 4.43×10^3 kg/m³ and yield 214 stress of 880 MPa. The values of these properties are also consistent with 215

the values obtained from the literature (Al-Bermani et al., 2010; Rafi et al., 216 2012). Numerical analysis results also indicated that the global response was 217 not very sensitive to these particular values. Effective plastic strain to fail-218 ure is set to be 0.3. Strain rate dependency of Ti6Al4V is ignored in the 219 numerical simulations, unless otherwise stated. For the numerical quasi-220 static simulations, rigid material is assumed for the steel test rig. For the 221 numerical HPB test simulations, a linear elastic material model with Young's 222 modulus of 210 GPa, Poisson's ratio 0.3, mass density 7.80×10^3 kg/m³ is as-223 sumed for the steel impactor. The Nylon 66 impactor is considered to exibit 224 elastic-perfect plastic behaviour with Young's modulus of 1.7 GPa, Poisson's 225 ratio of 0.4, mass density of $1.088 \times 10^3 \text{ kg/m}^3$, yield stress of 160 MPa and 226 tangent modulus of 1.00 MPa. All the input data for the material models 227 used in the quasi-static and impact tests are given in Table 1 along with the 228 LS-DYNA material number and name 220

In the FE simulations, the interaction forces between parts are trans-230 ferred with contact algorithms. The so-called one-way contact algorithm 231 (*CONTACT_AUTOMATIC_NODES_TO_SURFACE), in which only slave 232 nodes (lattice nodes) are checked for penetration of the master segments (test 233 rig), is used to model the interaction between lattices and test rig in the nu-234 merical quasi-static simulations. The friction forces between the test rig and 235 lattice sample are taken into account with static and dynamic friction coef-236 ficients of 0.1. For the numerical HPB test simulations, two separate one-way 237 contact types (*CONTACT_AUTOMATIC_NODES_TO_SURFACE) are used 238 to model the force transfer between the impactor and lattice sample and 239 the interaction between the lattice sample and HPB. Self-contact of the 240

lattices is modelled using a beam-to-beam contact algorithm (*CONTACT 241 _AUTOMATIC_GENERAL). Static and dynamic friction coefficients are de-242 fined as 0.30 for all contact cases. Following the development of the finite 243 element model of lattices, a mesh sensitivity analysis was carried out to en-244 sure that the results are not sensitive to the mesh size; it was found that five 24 beam elements per strut resulted in effective convergence of the results. The 246 finite element models of 5-layer auxetic and diamond samples consist of 24320 247 and 8320 beam elements respectively. The length of each beam element is 248 0.543 mm and 0.433 mm for auxetic and diamond lattices, respectively. The 240 rigid quasi-static test rig was modelled using 5408 four-node shell elements. 250 The experimental load-time signals from the impact loading events were 251 recorded by means of a single HPB, 25 mm diameter, 3.4 m length, with a 252 perimeter-mounted axial strain gauge station set 250 mm from the impact 253 face of the bar. The strain gauge station thus recorded a distorted ver-254 sion of the impact load, due to well-known dispersion effects. As discussed in 255 (Ozdemir et al., 2016), the impact load-time signals typically included signifi-256 cant energy at frequencies above that which can currently be accommodated 257 by standard frequency domain dispersion correction techniques (Tyas and 258 Watson 2001). Therefore, in order to compare like with like, the numerical 259 models of the impact events included explicit modelling of the full HPB in 260 addition to the impactor and lattice specimen. In the model, the load signal 261 dispersed as it travelled along the model of the HPB, before being recorded 262 on the bar perimeter at the location of the strain gauge in the experimental work, 250 mm from the impact face of the bar (Figure 3). In all subse-264 quent comparisons of the experimental and numerical stress-time histories in 265



this paper, the results are those measured at the gauge position. The HPB was modelled using 491904 and 724680 eight-node hexahedral elements in low and high velocity impact simulations, respectively. The steel and nylon impactors were represented with 39424 and 13200 eight-node hexahedral elements, respectively.



Figure 3: Schematic description of the 3D FE model of the HPB test setup

The average computation time for analysing low velocity impact tests of single and five-layer lattice samples was approximately 6 hours and 20 hours, respectively, on a quad core 64 bit PC with 2 GB memory. The finite element analysis of high velocity impact tests of single- and five-layer samples took around 40 minutes and 5 hours, respectively, on the same computer.

It is worth noting that stress measurements, whether experimental or numerical, may be influenced by edge (or size) effects in case of a low number cells in the height direction. Therefore, the findings of the experimental and numerical investigations regarding dynamic properties of lattices reported here are indicative only.

281 3. Nonlinear quasi-static behaviour of lattices

Single layer square samples of diamond and re-entrant cube lattices with 282 an edge length of 25 mm and a height of 5 mm were compressed at a crosshead 283 speed of 0.2 mm/min using a Hounsfield TX0038 universal test rig (Ozdemir 284 et al., 2016). For each sample type, three quasi-static tests were carried out. 285 The average stress-strain curves of the diamond and re-entrant cube samples 286 following quasi-static compression tests are shown in Figures 4(a) and (b), 287 respectively. As one can observe from these figures, the quasi-static stress-288 strain response of the re-entrant and diamond lattice structure show a typical 289 of Type II (stretch dominated) response as defined by Ashby (2006), where 290 a relatively constant initial stiffness is followed by post-peak softening, and 291 later by final densification of the material. 292

Relative density $\bar{\rho}$, elastic modulus *E*, yield stress $\sigma_{\rm v}$ and absorbed energy 293 (up to densification) of the single-layer samples obtained following the quasi-294 static tests are summarized in Table 2. Strain limits up to 30 % and 60 %295 are chosen to compute absorbed energy for the re-entrant cube and diamond 296 lattices, respectively. Stress-strain plots indicate that diamond lattices are 297 more efficient than re-entrant cube trusses for energy absorption under quasi-298 static conditions, although the relative density of the re-entrant cube samples 299 is higher than that of diamond lattices. 300

Numerical quasi-static stress-strain response of diamond and re-entrant cube lattices is also superimposed in Figures 4(a) and (b), respectively. An increase in initial stiffness of experimental stress-strain curves of re-entrant and diamond lattices at around of 80% and 180% is observed due to the initial crushing of diamond and re-entrant cube samples, respectively. Both

Lattice structure	N. of layers	$\bar{ ho}$	E	$\sigma_{ m y}$	Absorbed energy
		[-]	[MPa]	[MPa]	$[MJ/m^3]$
Diamond	1	0.137	132.2	11.8	2.32
Re-entrant cube	1	0.166	126.6	10.8	1.65

Table 2: Averaged material properties obtained following the quasi-static tests.

experimental and numerical stress-strain curves of diamond and re-entrant cube lattices show a clear peak load which coincides with the onset of fracture occurring in the struts near the nodes. After the peak load, post-yield softening behaviour is followed by a steep stress rise due to densification of the lattice layer.



Figure 4: The average experimental (black line) and numerical (grey line) stress-strain curves of single-layer (a) diamond and (b) re-entrant cube samples obtained following the quasi-static compression tests.

An implicit time integration technique is employed to obtain economic

solutions for the quasi-static response of lattice structures. However, the im-312 plicit FEM encountered numerical difficulties when solving non-linear prob-313 lem after the samples are compressed around 1 mm. Therefore, switching 314 from the quasi-static implicit scheme to the dynamic explicit scheme with 315 mass scaling is employed for both diamond and re-entrant cube lattice sam-316 ples. The time step size is kept large enough to ensure that that kinetic energy 317 is less than 5% of the peak internal energy. The numerical method predicts 318 a higher initial stiffness than experiments for both re-entrant cube and dia-319 mond samples. In the numerical simulations, the geometry of the struts is 320 assumed to be perfectly circular without any imperfection along their length. 321 On the other hand, lattice struts manufactured by the Electron Beam Melt-322 ing (EBM) technique include irregularities both in cross-section and along 323 the length of the strut (Ozdemir et al., 2016) which act as weakeners. There-324 fore, the numerical method predicts somewhat higher strength and stiffness 325 for the quasi-static response of diamond and re-entrant cube samples than 326 is observed experimentally. Since the diameter of the struts in the diamond 327 samples is larger than that of re-entrant cube samples, imperfections, which 328 are independent of strut size, arising from the resolution limitations of the 329 processing method, play a more important role in the quasi-static response 330 of the re-entrant cube samples. A remarkable consistency of experimental 331 and numerical deformed shapes of the re-entrant cube and diamond samples 332 is observed following the quasi-static compression tests (Figure 5). 333



Figure 5: Deformed shape of diamond sample during quasi-static (a) experiment and (b) numerical simulation. Deformed shape of re-entrant cube sample during quasi-static (c) experiment and (d) numerical simulation. The pre-test sample sizes were 25 x 25 x 5 mm.

334 4. Nonlinear impact response of lattices

The HPB tests carried out with bare impactor and on single and multilayer lattice samples are described in detail in (Ozdemir et al., 2016). In the present work, these test results are utilized to develop an effective modelling tool using the FEM for the prediction of the mechanical behaviour, progressive damage and failure modes of the lattices. The same material models
and material parameters defined in Section 3 are utilized in the numerical
impact models as validated with quasi-static tests.

342 4.1. Impact tests with bare impactor

Numerical simulations of low and high velocity impact tests were first carried out in the absence of the lattice specimen at the impact face of the HPB in order to verify the numerical models of the impactors. The steel and Nylon 66 impactors were fired at velocities of 7.6 m/s and 178 m/s during experiments, respectively, to transmit the same order of magnitude of impulse (around 6 Ns).

The experimental and numerical stress-time histories observed at the 349 gauge station positioned 250 mm from the impact face of the HPB along 350 with cumulative impulse-time histories are given in Figures 6 and 7. Al-351 though the numerical model predicts a higher peak stress than experiments 352 for both low-velocity and high-velocity impacts, durations of the experimen-353 tal and numerical main impact pulses are virtually the same. In experimental 354 work, it is inevitable that a less-than-perfect alignment will be achieved be-355 tween the impactor and the HPB. As a result, not all of the momentum of 356 the impactor is transferred to the HPB in the first cycle of the stress wave 357 through the length of the impactor. This results in an initial load plateau 358 which is lower than would be assumed from 1-D theory and a subsequent 359 low-magnitude coda to the main pulse which accounts for the majority of 360 the residual impulse. These features are clearly seen on the experimental 361

stress-time history shown in Figure 6(a). On the other hand, the numerical 362 model assumes that the impact surfaces of the impactor and the HPB are 363 perfectly parallel, and as a result the coda is not observed in the numerical 364 stress-time history. Impulse starts to increase when the impactor comes into 365 contact with the HPB and remains unchanged following the rebound of the 366 impactor (Figure 6(b)). Cumulative impulse-time histories suggest that re-367 bound velocity of the impactors in the numerical simulation is higher than 368 that observed in experiments. 369



Figure 6: Experimental (black line) and numerical (grey line) (a) stress and (b) cumulative impulse-time histories in the absence of lattice specimen generated by the steel impactor fired at a velocity of 7.6 m/s.

370 4.2. Impact response of single layer specimens

Examples of experimental and numerical impact stress, cumulative impulse and strain time histories as well as stress-strain curves developed on the distal and impact face of single-layer re-entrant cube specimens induced



Figure 7: Experimental (black line) and numerical (grey line) (a) stress and (b) cumulative impulse-time histories in the absence of lattice specimen generated by the Nylon 66 impactor fired at a velocity of 178 m/s.

by the steel impactor are shown in Figures 8 and 9, respectively. In these 374 tests, the average strain rate is around $3700 \,\mathrm{s}^{-1}$ and $3600 \,\mathrm{s}^{-1}$, respectively. 375 Figures 8(a) and 9(a) show examples of a good agreement between simulated 376 and measured stress-time histories. Strain developed in the samples was not 377 measured directly during the experiments. Therefore, the high speed video 378 footage was used to estimate the displacement vs time record of the impacted 379 face, from which the axial strain-time history was calculated. Subsequently, 380 a stress-strain curve was derived for each test. 381

Numerical distal and impact face stress, cumulative impulse and strain time histories as well as stress-strain curves induced by the Nylon 66 impactor fired at velocities of 200 m/s and 187 m/s are shown in Figures 10 and 11, respectively. The average strain rate is around $42400 \,\mathrm{s}^{-1}$ and $26000 \,\mathrm{s}^{-1}$, respectively, in these tests. Experimental stress and cumulative impulse-time

histories are also superimposed in Figures 10(a), 10(b), 11(a) and 11(b). The 387 resolution of the high speed video footage of high speed impact tests was not 388 sufficient to estimate the displacement time histories of samples under high 389 strain rates; strain vs time and stress vs strain curves for these samples could 390 not be predicted. As one can observe from Figures 10(a), 10(b), 11(a) and 391 11(b), the stress and cumulative impulse-time histories obtained from ex-392 perimental and numerical methods show a very good agreement for the first 303 $5.5 \cdot 10^{-5}$ s. After $5.5 \cdot 10^{-5}$ s, the numerical results deviate from the exper-394 imental results. Comparison of the experimental and numerical cumulative 395 impulse graphs given in Figures 10(b) and 11(b) shows that the numerical 396 method predicts a higher rebound velocity for the Nylon 66 impactor than 397 occurred in the experiment. This suggests that the difference between ex-398 perimental and numerical stress-time histories for the high velocity impact 399 tests (Figures 10(a) and 11(a)) is caused by the non-linear deformations of 400 the Nylon 66 impactor, since an elastic-perfectly plastic material model for 401 the impactor is used in the numerical simulations. Therefore, in reality, some 402 part of the energy remaining in the system is dissipated by the fracture of 403 the impactor, whereas, in the numerical models, this energy remains in the 404 impactor and it rebounds with a higher velocity. This shows that we have 405 captured the essentials in the stress-time lattice behaviour; late time differ-406 ences caused by the fracture of the experimental impactor are of secondary 407 importance and the lattice behaviour is modelled correctly. 408

The impact stress, cumulative impulse and strain time histories of two distal face impact tests (steel impactor at low speed, Nylon 66 impactor at high speed) differ significantly (Figures 12(a) - (c)). On the other hand, the

stress-strain curves of single-layer samples under low and high velocity loads 412 strongly suggest that there is little difference in the distal face stress vs overall 413 specimen strain at loading rates differing by an order of magnitude (Figure 414 12(d)). Therefore, we can conclude that distal face stress-strain response 415 of single-layer re-entrant cube samples exhibits rate insensitive behaviour. 416 Similar observations can be made for the impact stress, cumulative impulse 417 and strain time histories of two impact face impact tests under low and 418 high velocity loads (Figures 13(a) - (c)). However, the discrepancy between 419 numerical stress vs strain curves under low and high velocity loads increases 420 for impact face tests (Figure 13(d)). 421

422 4.3. Impact response of five-layer specimens

Impact tests on five-layer lattice samples of the same diameter as the impactor were conducted to establish the ability of the lattices to extend the duration of the impact load and to reduce peak response (Ozdemir et al., 2016).

427 4.3.1. Diamond lattices

Examples of experimental and numerical distal face stress and cumulative impulse-time histories developed on the five-layer diamond lattices during low and high velocity impact tests are shown in Figures 14 and 15. In the case of the lower velocity impact, there is excellent correlation between the experimental and numerical results. The stress-time correlation is less good for the higher velocity impact, with the early time experimental stress being 10-15% higher than that predicted by the model, and the final peak associated



Figure 8: Experimental (black line) and numerical (grey line) distal face (a) stress, (b) cumulative impulse and (c) strain time histories, and (d) stress-strain curve of the single layer re-entrant cube lattice specimen induced by the steel impactor fired at a velocity of 18.8 m/s.

with full densification of the sample and final transfer of the residual momentum from the impactor being higher in the numerical model. However,
the experimental and numerical final cumulative impulse results show good
correspondence in both cases. This indicates that local fluctuations in the



Figure 9: Experimental (black line) and numerical (grey line) impact face (a) stress, (b) cumulative impulse and (c) strain time histories, and (d) stress-strain curve of the single layer re-entrant cube lattice specimen induced by the steel impactor fired at a velocity of 17.7 m/s.

439 stress-time histories average themselves out.

Figure 16 shows numerical and experimental impact face stress vs time and cumulative impulse vs time plots of five-layer diamond lattice induced by the Nylon 66 projectile. The discrepancies between experimental and



Figure 10: Experimental (black line) and numerical (grey line) distal face (a) stress, (b) cumulative impulse and (c) strain time histories, and (d) stress-strain curve of the single layer re-entrant cube lattice specimen induced by the Nylon 66 impactor fired at a velocity of 200 m/s.

⁴⁴³ numerical stress time histories can also be observed for impact face high
⁴⁴⁴ velocity loads. However, the experimental and numerical cumulative impulse
⁴⁴⁵ time histories show a good correlation for both cases.



Figure 11: Experimental (black line) and numerical (grey line) impact face (a) stress, (b) cumulative impulse and (c) strain time histories, and (d) stress-strain curve of the single layer re-entrant cube lattice specimen induced by the Nylon 66 impactor fired at a velocity of 187 m/s.

446 4.3.2. Re-entrant cube lattices

Figures 17 -20 show numerical and experimental distal and impact face stress vs time and cumulative impulse vs time plots of five-layer re-entrant cube lattices induced by the steel and Nylon 66 projectiles. Numerical simu-



Figure 12: Numerical distal face (a) stress, (b) cumulative impulse and (c) strain time histories, and (d) stress-strain curves of the single layer re-entrant cube lattice specimens induced by the steel (black line) and Nylon 66 (grey line) impactors fired at velocities of 18.8 and 200 m/s, respectively.

lations can reasonably well predict the response of lattices under low velocity
impact loads, while high frequency oscillations are observed both in the numerical plateau and the densification regime during high velocity impact
tests, especially on the distal face.



Figure 13: Numerical impact face (a) stress, (b) cumulative impulse and (c) strain time histories, and (d) stress-strain curves of the single layer re-entrant cube lattice specimens induced by the steel (black line) and Nylon 66 (grey line) impactors fired at velocities of 18.8 and 200 m/s, respectively.

As noted previously, the numerical model assumes perfectly co-axial and normal impact. This will inevitably lead to a faster rise time of the load, and hence, more significant high frequency content in the load-time signal. This may be the source of the high frequency oscillations in the early stages



Figure 14: Experimental (black line) and numerical (grey line) distal face (a) stress and (b) cumulative impulse-time histories of the five-layer diamond lattice specimen induced by the steel impactor fired at a velocity of 19.4 m/s.



Figure 15: Experimental (black line) and numerical (grey line) distal face (a) stress and (b) cumulative impulse-time histories of the five-layer diamond lattice specimen induced by the Nylon 66 impactor fired at a velocity of 140 m/s.



Figure 16: Experimental (black line) and numerical (grey line) impact face (a) stress and (b) cumulative impulse-time histories of the five-layer diamond lattice specimen induced by the Nylon 66 impactor fired at a velocity of 165 m/s.



Figure 17: Experimental (black line) and numerical (grey line) distal face (a) stress and (b) cumulative impulse-time histories of the five-layer re-entrant cube lattice specimen induced by the steel impactor fired at a velocity of 16.8 m/s.



Figure 18: Experimental (black line) and numerical (grey line) impact face (a) stress and (b) cumulative impulse-time histories of the five-layer re-entrant cube lattice specimen induced by the steel impactor fired at a velocity of 20.3 m/s.



Figure 19: Experimental (black line) and numerical (grey line) distal face (a) stress and(b) cumulative impulse-time histories of the five-layer re-entrant cube lattice specimeninduced by the Nylon 66 impactor fired at a velocity of 134 m/s.



Figure 20: Experimental (black line) and numerical (grey line) impact face (a) stress and (b) cumulative impulse-time histories of the five-layer re-entrant cube lattice specimen induced by the Nylon 66 impactor fired at a velocity of 136 m/s.

of the numerical signal in Figure 19(a). To assess the correlation between 458 the experimental and numerical loads without this high frequency content, 459 filtering was applied to the signals. An example of filtered experimental and 460 numerical results using a low-pass filter with a cut-off frequency of 60000 461 Hz is shown in Figure 21, which is the filtered counterpart of Figure 19. 462 The consistency of numerical and experimental results is improved by the 463 elimination of very high frequency oscillations in the stress-time history. High 464 frequency oscillations, which still exist in the numerical stress-time history 465 after filtering, may be associated with the uncertainties in the material model 466 of the Nylon 66 impactor. 467

In general, during impact tests, the specimen stress-time curve comprises a reasonably constant plateau load during cell collapse, followed by a much greater magnitude stress spike towards the end of the pulse (densification).

For low velocity impact tests, plateau load recorded during distal face and impact face tests have very similar values. However, for higher velocity impact tests, the impact face plateau stress is remarkably higher than distal face plateau stress. Similar observation was made by Liu et al. (2009) who reported the dynamic crushing behaviour of 2D Voronoi honeycombs at support and impact ends.

Both experiments and the FEM exhibit similar failure modes of re-entrant 477 cube lattices for low and high velocity HPB tests. In the lower velocity (steel 478 impactor) tests, the order of failure of the individual cell layers is random. 479 This implies a slowly applied impact load is equilibrated along the entire 480 length of the specimen and the order of cell layer collapse is governed by 481 the strength discrepancies between layers due to the imperfect geometry of 482 the struts along the length. Similar behaviour has been noted in the initial 483 crushing of hexagonally-packed rectangular arrays of thin-walled metal tubes 484 under quasi-static loads, which was localized in a narrow band (Shim and 485 Stronge, 1986). The random location of this band was attributed to the lo-486 cal imperfections or weaknesses in the array. The higher velocity (Nylon 66 487 impactor) tests show that the failure of cell layers occurs sequentially from 488 impact face to distal face as the deformation is localised. This indicates that 489 equilibrium of load throughout the length of the specimen is not established 490 at these higher velocities. This response is very similar to dynamic crush-491 ing behaviour of square-packed array in which propagates from the impact 492 surface into the undeformed array. In hexagonally-packed arrays, dynamic 493 crushing propagates from both the impact and distal ends (Stronge and Shim, 494 1987). 495

We have clear evidence of our layered system behaving as previous researchers have noted for other layered systems - layers failing in order of weakness at low impact velocities, layers failing in order of distance from impact face at high velocities as the deformation is localised (see for instance Figures 20 and 21 in (Ozdemir et al., 2016)).

Considering the difference in impact velocity from test to test, the impact and distal face stress-time histories from both the low-velocity and high-velocity impact tests demonstrate that diamond lattices appear to be marginally more efficient in temporally spreading the intensity of impact and reducing peak load than re-entrant cube lattices, even though re-entrant cube trusses have a higher relative density than diamond lattices.



Figure 21: Experimental (black line) and numerical (grey line) filtered distal face (a) stress and (b) cumulative impulse-time histories of the five-layer re-entrant cube lattice specimen induced by the Nylon 66 impactor fired at a velocity of 134 m/s.

507 5. Influence of intrinsic strain rate sensitivity of Ti6Al4V

In the previous numerical analyses, the intrinsic strain rate dependence of Ti6Al4V is ignored in the constitutive model. The Johnson-Cook material model captures strain hardening and strain rate sensitivity of a material by expressing stress as a function of strain and strain rate:

$$\sigma = (A + B\varepsilon^n) \left(1 + C\ln\left(\frac{\dot{\varepsilon}}{\dot{\varepsilon_o}}\right)\right) \tag{1}$$

where σ is the stress, ε is the plastic strain, ε_o is a reference strain rate equal to $1 \ s^{-1}$, $\dot{\varepsilon}$ is the effective plastic strain rate, A is the yield stress, the combination of B and n governs the hardening behaviour of the material, and C represents the strain rate sensitivity of the material. In this formulation temperature effects are ignored.

The influence of intrinsic rate dependency of Ti6Al4V on the impact re-517 sponse of single and multi-layer re-entrant cube lattice samples is assessed 518 by using different C values in the numerical simulations. A realistic value 519 of strain rate sensitivity parameter C for Ti6AL4V is reported to be on av-520 erage 0.022 (Shao et al. (2010) and US-DOT-FAA (2000)). In addition to 521 this realistic value, an extremely (and unrealistically) high value of C = 0.1522 is also assumed and simulation results are compared with those of strain 523 rate insensitive material model. Plots in Figure 22 show a comparison for 524 distal face stress-time histories of the single and multi-layer re-entrant cube 525 lattice specimens developed during low and high velocity impact tests. As 526 can be seen from this figure, the realistic value of intrinsic strain rate sen-527 sitivity of the Ti6Al4V only very slightly affects the response of the single 528

and multi-layer re-entrant cube lattice samples. Even with such an unreal-529 istically high value of C = 0.1, it is not possible to emulate the response 530 of five-layer samples with a one-layer sample. This suggests that the rate-531 dependent behaviour that emerges at the macro-scopic level is *not* due to 532 the rate-dependence of the Ti6Al4V alloy, but rather due to the interaction 533 of stiffness and inertia at the unit cell level which can thus be adjusted and 534 optimised according to user-defined performance requirements. The hypoth-535 esis regarding the source of rate-sensitivity of lattices needs further detailed 536 investigations on numerical models of lattices in a future work. Liu et al. 537 (2009) drawn similar conclusions in relation to the strain-rate sensitivity of 538 2D Voronoi honeycomb stating that the strain-rate sensitivity of cell wall 539 material has minor effect on the dynamic response of such materials; rate 540 effect is mainly caused by inertia. have also reached similar conclusions in 541 their numerical study 542



Figure 22: Distal face stress-time histories of (a) the single layer re-entrant cube lattice specimen induced by the steel impactor fired at a velocity of 18.8 m/s, (b) the single layer re-entrant cube lattice specimen induced by the Nylon 66 impactor fired at a velocity of 200 m/s, (c) the five-layer re-entrant cube lattice specimen induced by the steel impactor fired at a velocity of 16.8 m/s, and (d) the five-layer re-entrant cube lattice specimen induced by the Nylon 66 impactor fired at a velocity of 136 m/s for strain rate insensitive material model (thick black line), Johnson-Cook material model with C=0.02 (grey line) and C=0.1 (thin black line).

543 6. Effect of confinement

In the previous analyses, the impact behaviour of the lattice samples are 544 numerically simulated under uniaxial loading conditions without radial con-545 straint. Next, specimens are constrained against radial expansion by placing 546 them inside a frictionless circular steel tube with a clearance fit, therefore, 547 uniaxial straining of the samples is achieved. All other test parameters are 548 the same as in Section 4. It is clear from Figure 23 that lateral confinement 549 slightly affects the compressive response of re-entrant cube lattices for both 550 low and high velocity impact tests. This is also consistent with the Poisson 551 ratio of the re-entrant cube lattices which is near zero or negative (Almgren 552 (1985)). The failure of the re-entrant lattice occurs in a systematic, layer-by-553 layer fashion, so confinement does not substantially affect the compressive 554 stress of such lattices. However, a lattice specimen with a different mode of 555 collapse should be assessed to quantify the influence of the confinement on 556 the response of the structure. 557

Similar conclusions have been reached for different foam types under quasi-static conditions. Radford et al. (2005) evaluated the effect of lateral confinement on Alporas foam and only a small effect on the compression response was observed. This was attributed to the fact that the Alporas foam has a plastic Poisson ratio close to zero. Tan et al. (2005) radially confined Hydro/Cymat3 foam specimens and proposed that the radial confinement had little effect in the pre-densification regime.



Figure 23: Numerical unconfined (grey line) and confined (black line) distal face stress-time histories of five-layer re-entrant cube lattice specimens induced by (a) the steel impactor fired at a velocity of 16.8 m/s and (b) the Nylon 66 impactor fired at a velocity of 134 m/s.

565 7. Discussion

Numerical simulations carried out in this work demonstrate that the FEM 566 is an efficient analysis tool for the prediction of the mechanical behaviour, 567 progressive damage and failure modes of lattice materials. Considering dis-568 advantages associated with continuum elements, 3D Timoshenko beam ele-569 ments with appropriate contact properties were preferred for the modelling 570 of lattice materials. Comparison of experimental and numerical results reveal 571 that quasi-static and impact response of lattices with 3D Timoshenko beam 572 elements is represented with high accuracy including individual collapse of 573 cell layers and densification. This led to a drastic reduction in the total 574 number of elements and degrees of freedom and, in turn, CPU time. On the 575 other hand, practical design tools are vital for early stage of design due to 576 the computational expense of the numerical methods. It is highly beneficial 577

to have a simplified model of lattice structures for generic assessment/design
purposes in addition to a numerical tool.

A short review on the quasi-static deformation mechanisms of stretch 580 dominated and bending dominated structures may help to explore the rate 581 sensitivity mechanism of lattices for future works. Most foams show a bend-582 ing dominated behaviour, whereas lattice structures demonstrate a stretch 583 dominated behaviour. Stiffnesses and initial collapse strengths of stretch 584 dominated structures are higher than those of bending dominated structures 585 of the same relative density, since the deformation mechanisms of stretch 586 dominated structures are characterized by hard response modes like tension 587 and compression rather than soft failure modes like bending. In stretch dom-588 inated response, initial yield of the material is followed by a post-yield soft-589 ening stiffness caused by plastic buckling or brittle collapse of struts, whereas 590 bending dominated structures continue to collapse at a nearly constant stress. 591 Because of this, the energy absorption capacity of stretch dominated struc-592 tures is less than that of bending dominated structures, although they are 593 Under dynamic loading, the collapse mode of cellular lighter Ashby (2006). 594 solids may change from a quasi-static failure mode to new mode involving 595 additional stretching which can dissipate more energy. This phenomenon is 596 called as micro-inertia which can cause an increase in the strength of cellu-597 lar solids under dynamic loading conditions in addition to inertia and shock 598 wave propagation effects Deshpande and Fleck (2000). Bending dominated 599 structures are slightly affected by micro-inertia, strain-rate and inertia effects 600 under dynamic conditions Calladine and English (1984). 601

602

Impact tests on single-layer re-entrant cube samples explained in Section

4.2 strongly suggest that the distal face stress-strain curves of single-layer re-603 entrant cube samples exhibit little difference at loading rates even differing by 604 an order of magnitude (Figure 12(d)), while five-layer samples under low and 605 high velocity impact loads exhibit load rate sensitive behaviour (Figure 24) 606 These results imply that a rate-independent load-deflection model of the unit 607 cell re-entrant cube layers could be used in a simple multi degree of freedom 608 (MDoF) model of a multi-layer specimen to represent its impact behaviour. 609 A simple 1-D MDoF spring-mass model can therefore be developed, using 610 lumped masses representing the inertia of each unit cell layer. The stiffness 611 of each layer can be represented with a rate-independent stress-strain curve 612 based on the data in Figure 12(d). 613



Figure 24: Numerical impact face stress-time histories of the five-layer re-entrant cube lattice specimen induced by the steel (black line) and Nylon 66 (grey line) impactors fired at velocities of 20.3 and 136 m/s, respectively

Regular periodic morphologies of lattice structures allow us to use such simple spring mass systems for representing their impact response. Therefore, we can specifically design 1-D layered systems for lattices to optimise

load spreading ability. However, the heterogeneous nature of foamed metals
complicates the development of such simplified models for representing dynamic behaviour of metallic foams under high-strain rates. But, there will be
certain restrictions in adopting an MDoF model: a physical justification for
spring geometry can only follow from cell dimensions, and such a restrictive
choice of parameters may limit the MDoF model's capability to provide the
spatial resolution required for dynamic response capture.

A MDoF spring-mass model for multi-layer re-entrant cube samples is also 624 consistent with the form of failure of such lattices. However, the efficiency of 625 a similar MDoF system of another lattice type with a different mode of col-626 lapse should be elaborated carefully. In a future work, simplified design tools 627 for lattices for impact threats will be studied in more detail. The relative ac-628 curacy by which multi-layer lattice structures can be modelled with a simple 629 MDOF model raises the question to what extent the dynamic behaviour of 630 lattice structures can be homogenised, and whether a homogenised model is 631 able to capture the essential characteristics of localisation. 632

633 8. Conclusions

This work focuses, for the first time, on the development of simple FE models of diamond and re-entrant cube lattices for the characterisation of dynamic response of such materials. The FE models of lattices are built using 3D Timoshenko beam elements. The results of the previous extensive experimental study (Ozdemir et al., 2016) are utilized to collect more data on the quasi-static and impact behaviour of titanium alloy (Ti6Al4V) lattices. Numerical analysis results show that 3D Timoshenko beam elements with appropriate contact properties are able to represent quasi-static and impact
response of lattices with enough accuracy including individual collapse of cell
layers and densification. Therefore, the FEM can be used an efficient tool for
the prediction of the mechanical behaviour, progressive damage and failure
modes of the lattice structures. Numerical impact analysis also reveals that
intrinsic strain rate dependence of the Ti6Al4V cannot cause any emergent
rate dependence of the response of the re-entrant cube lattices.

There is also some evidence that, whilst re-entrant cube specimens made 648 up over multiple layers of unit cells are load rate sensitive, the mechanical 649 properties of individual lattice cell layers are relatively insensitive to load 650 rate. These results imply that a rate-independent load-deflection model of 651 the unit cell layers could be used in a simple MDoF model of a multi-layer 652 specimen to represent its impact behaviour. In a future contribution, we will 653 focus on development of a simplified design tool of the lattices for impact 654 threats. In addition, a more realistic material model will be used for Nylon 655 66 impactor and imperfections of lattices will be included in the numerical 656 models in a future numerical modelling work. 657

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