



This is a repository copy of *Hedlund metrics and the stable norm*.

White Rose Research Online URL for this paper:
<http://eprints.whiterose.ac.uk/89093/>

Version: Accepted Version

Article:

Jotz, M. (2009) Hedlund metrics and the stable norm. *Differential Geometry and its Applications*, 27 (4). pp. 543-550. ISSN 0926-2245

<https://doi.org/10.1016/j.difgeo.2009.01.012>

Reuse

Unless indicated otherwise, fulltext items are protected by copyright with all rights reserved. The copyright exception in section 29 of the Copyright, Designs and Patents Act 1988 allows the making of a single copy solely for the purpose of non-commercial research or private study within the limits of fair dealing. The publisher or other rights-holder may allow further reproduction and re-use of this version - refer to the White Rose Research Online record for this item. Where records identify the publisher as the copyright holder, users can verify any specific terms of use on the publisher's website.

Takedown

If you consider content in White Rose Research Online to be in breach of UK law, please notify us by emailing eprints@whiterose.ac.uk including the URL of the record and the reason for the withdrawal request.



eprints@whiterose.ac.uk
<https://eprints.whiterose.ac.uk/>

Hedlund Metrics and the Stable Norm

Madeleine Jotz

Section de Mathématiques, Ecole Polytechnique Fédérale de Lausanne, 1015 Lausanne, Switzerland.

Abstract

The real homology of a compact Riemannian manifold M is naturally endowed with the stable norm. The stable norm on $H_1(M, \mathbb{R})$ arises from the Riemannian length functional by homogenization. It is difficult and interesting to decide which norms on the finite-dimensional vector space $H_1(M, \mathbb{R})$ are stable norms of a Riemannian metric on M . If the dimension of M is at least three, I. Babenko and F. Balacheff proved in [1] that every polyhedral norm ball in $H_1(M, \mathbb{R})$, whose vertices are rational with respect to the lattice of integer classes in $H_1(M, \mathbb{R})$, is the stable norm ball of a Riemannian metric on M . This metric can even be chosen to be conformally equivalent to any given metric. In [1], the stable norm induced by the constructed metric is computed by comparing the metric with a polyhedral one. Here we present an alternative construction for the metric, which remains in the geometric framework of smooth Riemannian metrics.

Key words: Riemannian metrics, stable norm, polytopes.

2008 MSC: 53C22, 53C38, 58A10, 58F17, 53B21

1. Introduction

On every compact Riemannian manifold M the real homology vector spaces $H_m(M; \mathbb{R})$ are endowed with a natural norm $\|\cdot\|_s$, called *stable norm*. This concept appeared for the first time in Federer [4] and was named *stable norm* in Gromov [5]. The stable norm on $H_1(M; \mathbb{R})$ arises directly from the Riemannian metric on the manifold M . The following equality for an integral class $v \in H_1(M; \mathbb{R})$ (see [5])

$$\|v\|_s := \inf\{n^{-1}L(\gamma) \mid \gamma \text{ is a closed curve representing } nv, n \in \mathbb{N}\}$$

allows a description of this object that is geometrically very intuitive: the stable norm describes the geometry of the Abelian covering \tilde{M} of M from a point of view from which fundamental domains look arbitrarily small. Knowing the unit ball of this norm, one can decide on existence and properties of some of the minimal geodesics relative to the Riemannian Abelian covering of the manifold; these are curves in M whose lifts to the Riemannian Abelian covering minimize arc length between each two of their points.

Email addresses: madeleine.jotz@epfl.ch (Madeleine Jotz)

Preprint submitted to Elsevier

September 18, 2008

Bangert has presented in [3] a Riemannian metric on the 3-torus \mathbb{T}^3 , such that the unit ball of the induced stable norm on $H_1(\mathbb{T}^3; \mathbb{R}) \simeq \mathbb{R}^3$ is a symmetric octahedron. Furthermore, Babenko and Balacheff have shown in [1] that, given a compact Riemannian manifold (M, ρ) of dimension greater than 2, for every centrally symmetric and convex polytope in $H_1(M; \mathbb{R})$ with nonempty interior, such that the directions of its vertices are rational, there is a Riemannian metric on M that is conformal to ρ and induces the given polytope as unit ball of the stable norm. Here we propose an alternative Riemannian metric, satisfying the same conditions. Our construction is a generalization of the Hedlund metric in Bangert [3]. The idea, that can be already found in the original paper of Hedlund [6] and is also used in [1], is to construct a metric that is “small” in tubular neighborhoods of disjoint closed curves representing the vertices of the polytope, and much “bigger” everywhere else. The convexity properties of the polytope play a decisive role in our computation of the stable norm induced by the Hedlund metric.

Bangert and Hedlund use such metrics in order to illustrate their results on minimal geodesics. Here we focus only on the proof of the theorem of Babenko and Balacheff [1]. In fact, if we wanted to show results on minimal geodesics, we would need to specify the definition of the Hedlund metric we give here. A discussion of the minimal geodesics for such metrics (with additional assumptions) was made in Jotz [7].

Outline of the paper.: in the next section the construction of tubular neighborhoods of curves will be recalled. There a lemma on existence of representatives for cohomology classes with “good” properties on the tubular neighborhood will be stated. In the following section the construction of the Riemannian metric will be given and the formula for the corresponding stable norm will be computed.

Notations.: In the following M will denote a compact smooth manifold with $\dim M \geq 3$ and ρ a Riemannian metric on M . Let \bar{M} denote the Abelian covering of M . More precisely \bar{M} is the subcovering of the universal covering whose group of deck transformations is the set $H_1(M; \mathbb{Z})_{\mathbb{R}}$ of integer classes in $H_1(M; \mathbb{R})$. We denote by $p: \bar{M} \rightarrow M$ the covering map and by $\bar{\rho} := p^*\rho$ the pull-back metric. If $h: \pi_1(M) \rightarrow H_1(M; \mathbb{Z})$ denotes the Hurewicz homomorphism ([see 9]) and T the torsion subgroup of $H_1(M; \mathbb{Z})$, then the Abelian covering can be described as the quotient manifold of the action of the normal subgroup $h^{-1}(T) \subseteq \pi_1(M)$ of the fundamental group on the universal cover \tilde{M} of M . Hence the operation

$$\begin{aligned} \Phi: H_1(M; \mathbb{Z})_{\mathbb{R}} \times \bar{M} &\rightarrow \bar{M} \\ (v, m) &\mapsto \Phi(v, m) =: m + v \end{aligned}$$

of $H_1(M; \mathbb{Z})_{\mathbb{R}}$ on \bar{M} is abelian and torsionfree (that is why we choose to use this + notation).

The de Rham cohomology vector space $H_{\mathbf{dR}}^1(M)$ is isomorphic to the dual of $H_1(M; \mathbb{R})$ [8, de Rham theorem]. In the following, we will use this isomorphism without mentioning it.

Given a Riemannian metric g on M , we will write g^* for its dual metric. The space of 1-forms on M (respectively on \bar{M}) will be denoted by $\Omega^1(M)$ (respectively $\Omega^1(\bar{M})$). We will denote by $\|\cdot\|_x$ (or also simply $\|\cdot\|$) the norm on $T_x M$ induced by the considered metric on M (we will also use this notation for the norm on $T_{\bar{x}} \bar{M}$, $\bar{x} \in \bar{M}$ induced from the corresponding metric on \bar{M}). For a curve $\gamma: I \rightarrow M$, $L(\gamma)$ will be the length induced

from the given metric on M and for a curve $\bar{\gamma} : I \rightarrow \bar{M}$, $\bar{L}(\bar{\gamma})$ the length induced from the corresponding periodic metric on \bar{M} .

Given a polytope P , we will call the set $\{\sum_{i=1}^k \alpha_i v_i \mid \alpha_i \geq 0\}$ the *cone over the face S* of the polytope, where v_1, \dots, v_k are the vertices of P lying in this face (i.e. $S = \{\sum_{i=1}^k \alpha_i v_i \mid \alpha_i \geq 0 \text{ and } \sum_{i=1}^k \alpha_i = 1\}$).

An integer class v in $H_1(M; \mathbb{Z})_{\mathbb{R}}$ will be called *indivisible* if the equation $v = n \cdot v'$, $n \in \mathbb{Z}$ and $v' \in H_1(M; \mathbb{Z})_{\mathbb{R}}$ yields $n = \pm 1$.

Acknowledgment.: I would like to thank Prof. Victor Bangert who supervised my diploma thesis and gave me much advice for this paper. I am also very grateful that he gave me the possibility to stay at the University of Freiburg during a few months after my diploma.

I also thank the referees for many useful comments.

2. Tubular neighborhoods of curves, adapted one-forms

Tubular neighborhoods and semi-geodesic coordinates.. Let $\gamma : [0, 1] \rightarrow M$ be a regular simple closed curve. In the following, such a curve will be called *admissible*. We can write $\gamma : \mathbb{S}^1 \rightarrow M$ and assume the curve γ is parametrized proportionally to arc length.

For $\varrho > 0$ let $V_{\varrho}(\Gamma)$ denote the bundle of balls of radius ϱ in the normal bundle $\pi : N\Gamma \rightarrow \Gamma$ of the embedded submanifold $\Gamma := \gamma(\mathbb{S}^1)$ in M . Analogously, if $I \subseteq \mathbb{S}^1$ is an interval, then $V_{\varrho}(\gamma(I)) = V_{\varrho}(\Gamma) \cap \pi^{-1}(\gamma(I))$. We choose $\varrho > 0$ small enough such that the normal exponential map E restricted to $V_{\varrho}(\Gamma)$ is a diffeomorphism onto an open neighborhood $U_{\varrho}(\Gamma) \subseteq M$ of Γ (and similarly $U_{\varrho}(\gamma(I)) = E(V_{\varrho}(\gamma(I)))$). Such an open set $U_{\varrho}(\Gamma)$ is called the *tubular neighborhood* (of radius ϱ) of Γ .

Choose an orthogonal frame (E_1, \dots, E_m) on $U \subseteq M$ open, such that for all $x = \gamma(t)$ in $\Gamma \cap U$,

$$E_1|_x = \dot{\gamma}(t)$$

and, consequently, $(E_2|_x, \dots, E_m|_x)$ forms a basis for $N_x\Gamma$. Assume the open set U is such that $U_{\varrho}(\Gamma) \cap U = U_{\varrho}(\gamma(I))$ for an open interval $I \subseteq \mathbb{S}^1$. The diffeomorphism

$$\begin{aligned} \varphi : U_{\varrho}(\gamma(I)) &\rightarrow I \times B_{\varrho}^{m-1} \subseteq \mathbb{R}^m \\ x &\mapsto (s(x), \varphi_2(x), \dots, \varphi_m(x)), \end{aligned}$$

where $\varphi_j(x)$ and $s(x)$ are such that

$$E^{-1}(x) = \sum_{j=2}^m \varphi_j(x) \cdot E_j|_{\gamma(s(x))} \in \mathcal{V}_{\varrho},$$

will be called a *semigeodesic chart* for $U_{\varrho}(\Gamma)$. A particularity of this chart is that $\partial_1^{\varphi}|_x = \dot{\gamma}(t)$ and, for $j = 2, \dots, m$, $\partial_j^{\varphi}|_x = E_j|_x$ holds for all $x = \gamma(t) \in \Gamma \cap U$ (note that $\Gamma \cap U = \gamma(I)$).

The map s is defined globally on $U_{\varrho}(\Gamma)$ and we have the identity

$$ds|_{\gamma(t)}(\dot{\gamma}(t)) = \frac{d}{dt}s \circ \gamma(t) = \frac{d}{dt}t = 1 \tag{1}$$

for all t in \mathbb{S}^1 .

Let $\gamma_1, \dots, \gamma_N$ be disjoint admissible loops and choose $\varrho > 0$ so that the construction above is possible for all the curves $\gamma_1, \dots, \gamma_N$ simultaneously. Choose furthermore ε with $\varrho > \varepsilon > 0$ such that the tubular neighborhoods with radius ε of the curves are disjoint. Set $\Gamma_j = \gamma_j(\mathbb{S}^1)$, $\Gamma = \cup_{j=1}^N \Gamma_j$, and $U_\varepsilon(\Gamma) := \cup_{j=1}^N U_\varepsilon(\Gamma_j)$. Then there exists a bump-function ζ on M for the tubular neighborhoods, i.e., ζ is a smooth function such that the following holds:

$$\zeta(y) = \begin{cases} 1 & , y \in U_\varepsilon(\Gamma) \\ 0 & , y \in M \setminus U_\varrho(\Gamma). \end{cases} \quad (2)$$

“Good” one-forms.. Choose a connected fundamental domain F_0 for the action of $H_1(M; \mathbb{Z})_{\mathbb{R}}$ on \bar{M} . Denote by $\bar{\gamma}_j$ the lift of γ_j to \bar{M} such that $\bar{\gamma}_j(0) \in F_0$ (note that γ_j is here considered as a smooth 1-periodic curve $\gamma_j : \mathbb{R} \rightarrow M$). Write $\bar{\Gamma}_i = \bar{\gamma}_i(\mathbb{R})$ and $U_\varrho(\bar{\Gamma}_i)$ the corresponding lift to \bar{M} of $U_\varrho(\Gamma_i)$. Hence $U_\varrho(\bar{\Gamma}_i)$ is the tubular neighborhood of radius ϱ of $\bar{\Gamma}_i$. Thus the notion of a semigeodesic chart for $U_\varrho(\bar{\Gamma}_i)$ makes also sense here, and $\bar{s}_i : U_\varrho(\bar{\Gamma}_i) \rightarrow \mathbb{R}$ exists with $\bar{s}_i(\bar{\gamma}_i(t)) = t$ for all $t \in \mathbb{R}$. Since the covering map $p : \bar{M} \rightarrow M$ is a local isometry,

$$\bar{x} \in \exp_{\bar{M}}(N_{\bar{\gamma}_i(t)}\bar{\Gamma}_i) \Leftrightarrow p(\bar{x}) \in \exp_M(N_{p\circ\bar{\gamma}_i(t)}\Gamma_i)$$

holds for all $\bar{x} \in U_\varrho(\bar{\Gamma}_i)$ and

$$(p^* ds_i)|_{U_\varrho(\bar{\Gamma}_i)} = d\bar{s}_i. \quad (3)$$

Define $L_i = \bar{\Gamma}_i + H_1(M; \mathbb{Z})_{\mathbb{R}}$ and $U_\varrho(L_i) = U_\varrho(\bar{\Gamma}_i) + H_1(M; \mathbb{Z})_{\mathbb{R}}$, as well as $L = \cup_{j=1}^N L_j$ and $U_\varrho(L) = \cup_{j=1}^N U_\varrho(L_j)$. Choose ε with $0 < \varepsilon < \varrho$ and define $U_\varepsilon(\bar{\Gamma}_i)$, $U_\varepsilon(L_i)$ and $U_\varepsilon(L)$ as above. The connected components of L will be called *lines* in the following.

In the following, a regular simple closed curve will be called an *admissible* curve.

Proposition 2.1 *Let v_1, \dots, v_N be indivisible integer classes in $H_1(M; \mathbb{Z})_{\mathbb{R}}$, that span $H_1(M; \mathbb{R})$ as a real vector space. Let $\gamma_1, \dots, \gamma_N$ be disjoint admissible representatives of those classes, and $U_\varepsilon(\Gamma_1), \dots, U_\varepsilon(\Gamma_N)$ disjoint tubular neighborhoods of these curves. Furthermore let $\lambda \in H_{dR}^1(M)$ be an arbitrary cohomology class. Then there exists a one-form ω representing λ such that:*

$$\omega|_x = \lambda(v_i) ds_i|_x \text{ for } x \in U_\varepsilon(\Gamma_i), \quad i = 1, \dots, N.$$

PROOF: For $j = 1, \dots, N$, the function \bar{s}_j is defined on $U_\varrho(\bar{\Gamma}_j)$. Set $\bar{s}_j = 0$ on $U_\varrho(\bar{\Gamma}_i)$ for $i \neq j$ and define:

$$s_\lambda : U_\varrho(L) \rightarrow \mathbb{R} \\ x = x_0 + v_0 \mapsto \sum_{i=1}^N \lambda(v_i) \bar{s}_i(x_0) + \lambda(v_0).$$

Doing so, each element $U_\varrho(L_j)$ is written $x = x_0 + v_0$ with $x_0 \in U_\varrho(\bar{\Gamma}_j) \cap F_0$ and $v_0 \in H_1(M; \mathbb{Z})_{\mathbb{R}}$. For $x \in U_\varrho(\bar{\Gamma}_j) \cap F_0$ holds: $s_\lambda(x) = \lambda(v_j) \bar{s}_j(x)$. Thus, with the definition of s_λ , for $v = z \cdot v_j$ with $z \in \mathbb{Z}$:

$$s_\lambda(x + v) = \lambda(v_j) \bar{s}_j(x) + \lambda(v) = \lambda(v_j) \cdot (\bar{s}_j(x) + z) \stackrel{(3)}{=} \lambda(v_j) \cdot \bar{s}_j(x + v).$$

This leads to $s_\lambda|_{U_\varrho(\bar{\Gamma}_j)} = \lambda(v_j)\bar{s}_j$, and analogously: $s_\lambda|_{U_\varrho(\bar{\Gamma}_j)+v} = \lambda(v_j)\bar{s}_j \circ \Phi(-v, \cdot) + \lambda(v)$. Thus, s_λ is a smooth function.

Choose an arbitrary representative ω' for λ . Since ω' is closed, the 1-form $\tilde{p}^*\omega' \in \Omega^1(\tilde{M})$ is also closed, where $\tilde{p} : \tilde{M} \rightarrow M$ is the universal covering of M . Since each closed 1-form on \tilde{M} is exact, there exists $\tilde{f} \in C^\infty(\tilde{M})$ such that $\tilde{p}^*\omega' = d\tilde{f}$. One can show easily that \tilde{f} is invariant under the action of $h^{-1}(T)$ on \tilde{M} and descends to $\bar{f} \in C^\infty(\bar{M})$, i.e., $\tilde{f} = \bar{f} \circ q$ where $q : \tilde{M} \rightarrow \tilde{M}/h^{-1}(T) = \bar{M}$ is the projection. We have $p \circ q = \tilde{p}$ and $q^*d\bar{f} = d\tilde{f} = \tilde{p}^*\omega' = q^*(p^*\omega')$ and hence $d\bar{f} = p^*\omega'$. Let $\bar{g} := s_\lambda - \bar{f}|_{U_\varrho(L)} : U_\varrho(L) \rightarrow \mathbb{R}$. A computation shows that for all $x \in U_\varrho(L)$ and $v \in H_1(M; \mathbb{Z})_{\mathbb{R}}$, we have $\bar{g}(x+v) = \bar{g}(x)$ and the existence of $g : U_\varrho(\Gamma) \rightarrow \mathbb{R}$ with $\bar{g} = g \circ p$ follows.

The map g is smooth and we have on $U_\varrho(L)$:

$$p^*dg = d\bar{g} = \sum_{i=1}^N \lambda(v_i)d\bar{s}_i - d\bar{f} = p^* \left(\sum_{i=1}^N \lambda(v_i)ds_i - \omega' \right).$$

Since p is a surjective local diffeomorphism, the equality $dg = \sum_{i=1}^N \lambda(v_i)ds_i - \omega'$ follows.

Define now the smooth 1-form

$$\omega := gd\zeta + (1 - \zeta)\omega' + \zeta \sum_{i=1}^N \lambda(v_i)ds_i$$

with ζ as in (2). Using the fact that ω' is closed on $U_\varrho(\Gamma)$ and the properties of ζ , one can easily verify that ω is smooth and closed. Furthermore, for $x \in U_\varepsilon(\Gamma_j)$:

$$\omega|_x = g(x)d\zeta|_x + (1 - \zeta(x))\omega'|_x + \zeta(x) \cdot \sum_{i=1}^N \lambda(v_i)ds_i|_x = \lambda(v_j)ds_j|_x,$$

as claimed. We get

$$[\omega](v_j) = \int_{\gamma_j} \omega = \lambda(v_j) \int_0^1 ds_j|_{\gamma_j(t)}(\dot{\gamma}_j(t)) dt \stackrel{(1)}{=} \lambda(v_j)$$

for $j = 1, \dots, N$. With $\text{span}\{v_1, \dots, v_N\} = H_1(M; \mathbb{R})$, this yields that ω is a representative for λ . \square

In the following, such a representative ω will be called a *good representative* of λ with respect to the family $\{v_1, \dots, v_N\}$.

3. Hedlund metrics

Let P be a centrally symmetric and convex polytope in $H_1(M; \mathbb{R})$ with nonempty interior, such that the directions of its vertices are rational. Such a polytope will be called *admissible*. We call $\tilde{V}_P = \{\tilde{v}_1, \dots, \tilde{v}_N, -\tilde{v}_1, \dots, -\tilde{v}_N\}$ the set of vertices of P .

Let v_1, \dots, v_N be indivisible integer classes such that $v_i = \varepsilon_i \tilde{v}_i$ with $\varepsilon_i > 0$, $i = 1, \dots, N$. Define $V_P := \{v_1, \dots, v_N, -v_1, \dots, -v_N\}$ and let J_i be the subset of V_P consisting of the indivisible integer classes corresponding to the vertices belonging to the i -th face S_i of P . In order to simplify the notation, we assume without loss of generality

that $J_1 = \{v_1, \dots, v_k\}$ for an integer $k \leq N$. The norm $|\cdot|$ on $H_1(M; \mathbb{R})$, whose unit ball is P , is given as follows (for vectors lying in the cone over the face S_1):

$$v = \sum_{j=1}^k \alpha_j \tilde{v}_j \text{ with } \sum_{j=1}^k \alpha_j = 1 \text{ and all } \alpha_j \geq 0 \Rightarrow |v| = 1 \quad (4)$$

or generally

$$v = \sum_{j=1}^k \alpha_j \tilde{v}_j \text{ with all } \alpha_j \geq 0 \Rightarrow |v| = \sum_{j=1}^k \alpha_j$$

and likewise for every other face of P .

Since P is convex, for each face S_i of P exists an element λ_i of $H_{dR}^1(M) \simeq H^1(M, \mathbb{R})$ such that

$$\lambda_i(\tilde{v}_j) \begin{cases} = 1, & v_j = \varepsilon_j \tilde{v}_j \in J_i \\ < 1, & v_j = \varepsilon_j \tilde{v}_j \notin J_i \end{cases}$$

(i.e. $\lambda_i \equiv 1$ on the plane defined by the face S_i and λ_i is smaller on the rest of the polytope). Now, since P is symmetric, $-\lambda_i$ is the 1-form corresponding to $-S_i$ and we get in fact:

$$-1 < \lambda_i(\tilde{v}_j) < 1 \text{ for } \pm v_j \notin J_i. \quad (5)$$

We get an alternative definition for the norm:

$$v \in \bigoplus_{j=1}^k \mathbb{R}_{\geq 0} \cdot v_j \Rightarrow |v| = \lambda_1(v), \quad (6)$$

and likewise for every other face of P .

The metrics defined below will be called *Hedlund metrics* since such a metric first appears in Hedlund's paper [6] in the case $M = \mathbb{T}^3$:

Definition 3.1 *Let P admissible polytope with vertices $\{\tilde{v}_1, \dots, \tilde{v}_N, -\tilde{v}_1, \dots, -\tilde{v}_N\}$. Let $v_1, \dots, v_N \in H_1(M, \mathbb{Z})_{\mathbb{R}}$ be the indivisible integer classes such that $\varepsilon_i \tilde{v}_i = v_i$ for some $\varepsilon_i > 0$, $i = 1, \dots, N$. Choose disjoint admissible curves $\gamma_1, \dots, \gamma_N$ representing the classes v_1, \dots, v_N . For each face S_i of P , let η_i be a good representative of λ_i with respect to the family $\{v_1, \dots, v_N\}$. A Hedlund metric associated to P on (M, ρ) is a Riemannian metric g that is conformal to ρ and such that its dual metric g^* satisfies:*

$$(H1) \ g_{\gamma_i(t)}^*(ds_i|_{\gamma_i(t)}, ds_i|_{\gamma_i(t)}) = \max_{x \in U_\varepsilon(\Gamma_i)} g_x^*(ds_i|_x, ds_i|_x) = \frac{1}{\varepsilon_i^2} \text{ for all } t \in [0, 1]$$

$$\text{and } g_x^*(ds_i|_x, ds_i|_x) < \frac{1}{\varepsilon_i^2} \text{ for } x \in U_\varepsilon(\Gamma_i) \setminus \Gamma_i \text{ and all } i \in \{1, \dots, N\}.$$

$$(H2) \ g_x^*(\eta_i|_x, \eta_i|_x) \leq 1 \text{ for all } i = 1, \dots, N \text{ and } x \notin U_\varepsilon(\Gamma).$$

Remark that for orientable compact surfaces of positive genus, it is not possible to choose disjoint loops representing the vertices of the polytope. In fact, it is shown in Bangert [3] that in the case of the 2-torus, the stable norm induced by a Riemannian metric on \mathbb{T}^2 has always a strictly convex unit ball. Yet, Massart shows in [10] that this is not true

in general: the stable norm induced by a smooth Finsler metric on a closed, orientable surface has neither to be strictly convex, nor smooth. For a *non-orientable* surface, the analogon to Theorem 3.5 can be found in Balacheff and Massart [2]: they show that if M is a closed non-orientable surface equipped with a Riemannian metric, then there exists in every conformal class a metric on M whose stable norm has a polyhedron as its unit ball.

Existence and properties of such a metric.

Proposition 3.2 *On every compact Riemannian manifold (M, ρ) with $\dim M \geq 3$ and for every admissible P in $H_1(M, \mathbb{R})$ there exists a Hedlund metric associated to P on (M, ρ) .*

PROOF: Given the admissible polytope P , choose disjoint admissible curves $\gamma_1, \dots, \gamma_N$ representing the indivisible integer classes v_1, \dots, v_N corresponding to its vertices $\tilde{v}_1, \dots, \tilde{v}_N$. Let $\varepsilon_1, \dots, \varepsilon_N$ be the coefficients as in Definition 3.1. For each face S_i of P , $i = 1, \dots, l$, let η_i be a good representative for λ_i . Set

$$\Omega := \max_{\substack{j=1, \dots, l \\ x \in M \setminus U_\varepsilon(\Gamma)}} \rho_x^*(\eta_j|_x, \eta_j|_x)$$

and

$$\Omega_i := \max \left\{ \max_{\substack{j=1, \dots, l \\ x \in U_\varepsilon(\Gamma_i)}} \frac{\rho_x^*(\eta_j|_x, \eta_j|_x)}{\rho_x^*(ds_i|_x, ds_i|_x)}, \varepsilon_i^2 \right\}$$

for $i = 1, \dots, N$. Define:

$$h_i : U_\varepsilon(\Gamma_i) \rightarrow (0, \infty) \\ x \mapsto \frac{1}{\varepsilon_i^2 \rho_x^*(ds_i|_x, ds_i|_x)} \cdot \exp(-C_i \cdot \ell(x)^2)$$

where

$$C_i := \ln \left(\frac{\Omega_i}{\varepsilon_i^2} \right) \cdot \frac{1}{\varepsilon_i^2} > 0$$

and $\ell(x)$ is the distance from x to its “projection” $\gamma_i(s_i(x)) \in \Gamma_i$. Define the smooth function $F : M \rightarrow (0, \infty)$ by

$$F(x) = \zeta(x) \cdot \sum_{i=1}^b h_i(x) + (1 - \zeta(x)) \cdot \frac{1}{\Omega},$$

where ζ is a smooth bump function as in (2). It is then easy to verify that the metric g defined by

$$g_x^* = F(x) \rho_x^* \quad \text{for all } x \in M$$

is a Hedlund metric associated to P . □

Proposition 3.3 *It results immediately from Definition 3.1 and from the properties of an admissible polytope that*

$$\|\eta_i\|^* := \max_{x \in \bar{M}} \|\eta_i|_x\|_x^* = 1 \quad (7)$$

for each face S_i of P .

PROOF: Here again, we assume that $i = 1$. The arguments are the same for every other face of P . Outside of $U_\varepsilon(\Gamma)$, Definition 3.1 yields $\|\eta_1|_x\|_x^* \leq 1$. With

$$\|\eta_1|_x\|_x^* = \begin{cases} \varepsilon_j \|ds_j|_x\|_x^* = 1 & , x \in \Gamma_j \\ & \text{and } j = 1, \dots, k \\ \varepsilon_j \|ds_j|_x\|_x^* < 1 & , x \in U_\varepsilon(\Gamma_j) \setminus \Gamma_j \\ & \text{and } j = 1, \dots, k \\ |\lambda_1(v_j)| \cdot \|ds_j|_x\|_x^* = \varepsilon_j |\lambda_1(\tilde{v}_j)| \cdot \frac{1}{\varepsilon_j} < 1 & , x \in U_\varepsilon(\Gamma_j) \\ & \text{and } j > k, \end{cases} \quad (5)$$

this proves the statement. \square

For the proof of the following lemma, we need to compute the lengths of the chosen admissible curve $\gamma_1, \dots, \gamma_N$ relative to the new metric. Choose $x = \gamma_i(t) \in \Gamma_i$ and a semi-geodesic chart φ around x . Recall the construction of such a chart; the matrix representing ρ relative to the orthogonal basis $(\dot{\gamma}_i(t), \partial_2^\varphi|_x, \dots, \partial_m^\varphi|_x)$ of $T_x M$ is diagonal. Hence, because g is conformal to ρ , the matrix representing g relative to this basis is diagonal, too. Since the covectors $(ds_i|_x, d\varphi_2|_x, \dots, d\varphi_m|_x)$ form a dual basis of $T_x^* M$, we obtain

$$g_x(\dot{\gamma}_i(t), \dot{\gamma}_i(t)) = \frac{1}{g_x^*(ds_i|_x, ds_i|_x)},$$

using the fact that the matrix representing g_x in the basis $(\dot{\gamma}_i(t), \partial_2^\varphi|_x, \dots, \partial_m^\varphi|_x)$ is inverse to the matrix representing g_x^* in the dual basis. But because of (H 1) in Definition 3.1, we have $g_x^*(ds_i|_x, ds_i|_x) = \frac{1}{\varepsilon_i^2}$. Hence, this leads to:

$$L(\gamma_i) = \int_0^1 \varepsilon_i dt = \varepsilon_i. \quad (8)$$

It is possible to show that γ_i is even the shortest curve representing v_i : Assume, without loss of generality, that $v_i \in J_1$ and choose an arbitrary curve $c : [0, 1] \rightarrow M$ representing v_i . We have $\lambda_1(v_i) = \varepsilon_i$ and hence

$$\begin{aligned} \varepsilon_i &= \int_c \eta_1 = \int_0^1 \eta_1|_{c(t)}(\dot{c}(t)) dt \leq \int_0^1 \|\eta_1|_{c(t)}\|^* \|\dot{c}(t)\| dt \\ &\stackrel{(7)}{\leq} \int_0^1 1 \cdot \|\dot{c}(t)\| dt = L(c). \end{aligned}$$

Lemma 3.4 *There is a constant $C = C(M, P)$ such that for each face S_i of P , every $w \in \bigoplus_{v \in J_i} \mathbb{N} \cdot v$ and every $x \in \bar{M}$, the distance from x to $x + w$ is bounded above by $\lambda_i(w) + C$.*

PROOF: Recall the definitions of $\gamma_i, \Gamma_i, \bar{\gamma}_i, \bar{\Gamma}_i, i = 1, \dots, N, L$ and F_0 . Define

$$D := \max_{1 \leq i, j \leq N} \min_{\substack{x \in \Gamma_i \\ y \in \Gamma_j}} d(x, y),$$

$$\text{diam}(M) := \max_{x, y \in M} d(x, y)$$

and choose a real positive number e such that $e > \max_{i=1, \dots, N} \varepsilon_i$. Let

$$C := 2 \cdot \text{diam}(M) + \kappa \cdot (D + e) \quad (9)$$

where d is the distance on M induced from the Hedlund metric g and $\kappa = \kappa(P)$ is the maximal number of vertices lying on a common face of P .

Without loss of generality, we assume that $w \in \bigoplus_{v \in J_1} \mathbb{N} \cdot v$, i.e. we can write $w = \sum_{i=1}^k n_i v_i$ with $n_1, \dots, n_k \in \mathbb{N}$. We give a path from x to $x + w$ that has length bounded above by $\lambda_1(w) + C = \sum_{i=1}^k \varepsilon_i n_i + C$. Assume that $x \in F_0$ (otherwise, if $x \in F_0 + u$ with $u \in H_1(M; \mathbb{Z})_{\mathbb{R}}$, we can replace the path with startpoint $x - u$ as constructed below with its image under Φ_u). We join x with $x + w$ by a path that runs *as much as possible* in L with “changes of lines” that are *as short as possible*:

Choose $i_1 \in \{j \mid 1 \leq j \leq k, n_j \neq 0\}$ such that the point x_1 in $L \cap F_0$ with minimal distance from x lies in $\bar{\Gamma}_{i_1}$. Let τ_1 be the corresponding geodesic segment from x to x_1 with minimal length. This length $\bar{L}(\gamma_1)$ is smaller than $\text{diam}(M)$. Let c_1 be the segment of $\bar{\gamma}_{i_1}$ connecting x_1 and $x_1 + n_{i_1} v_{i_1}$. This segment has length equal to

$$\bar{L}(c_1) = n_{i_1} \cdot L(\gamma_{i_1}) \stackrel{(8)}{=} n_{i_1} \cdot \varepsilon_{i_1}.$$

Now choose $i_2 \in \{j \mid 1 \leq j \leq k, n_j \neq 0\} \setminus i_1$ and $x_2 \in \bar{\Gamma}_{i_2} + n_{i_1} v_{i_1}$ such that x_2 is the point of $(L \setminus \bar{\Gamma}_{i_1}) \cap (F_0 + n_{i_1} v_{i_1})$ having minimal distance from $\bar{\Gamma}_{i_1} \cap (F_0 + n_{i_1} v_{i_1})$. Let x'_1 be the point in $\bar{\Gamma}_{i_1} \cap (F_0 + n_{i_1} v_{i_1})$ at this minimal distance from x_2 . Let c'_1 be the section of $\bar{\gamma}_{i_1}$ connecting x_1 and x'_1 ; the length of c'_1 lies in $[n_{i_1} \cdot \varepsilon_{i_1} - e, n_{i_1} \cdot \varepsilon_{i_1} + e]$. Let τ_2 be the minimal geodesic segment joining x'_1 and x_2 , it has length smaller than D . Now continue in this way; choose $i_3 \in \{j \mid 1 \leq j \leq k, n_j \neq 0\} \setminus \{i_1, i_2\}$ and $x_3 \in \bar{\Gamma}_{i_3} + n_{i_1} v_{i_1} + n_{i_2} v_{i_2}$ such that x_3 is the point of $(L \setminus (\bar{\Gamma}_{i_1} \cup \bar{\Gamma}_{i_2})) \cap (F_0 + n_{i_1} v_{i_1} + n_{i_2} v_{i_2})$ having minimal distance from $\bar{\Gamma}_{i_2} \cap (F_0 + n_{i_1} v_{i_1} + n_{i_2} v_{i_2})$. Let x'_2 be the point in $\bar{\Gamma}_{i_2} \cap (F_0 + n_{i_1} v_{i_1} + n_{i_2} v_{i_2})$ at this minimal distance from x_3 . The curve c'_2 joining x_2 and x'_2 on $\bar{\Gamma}_{i_2} + n_{i_1} v_{i_1}$ has length smaller than $n_{i_2} \cdot \varepsilon_{i_2} + e$.

If $n_j \neq 0$ for $j = 1, \dots, k$, our path will be the composition

$$\gamma := \tau_1 * c'_1 * \tau_2 * c'_2 * \dots * c'_k * \tau_{i_{k+1}}$$

where $\tau_{i_{k+1}}$ is the path joining the last point in $L \cap (F_0 + \sum_{i=1}^k n_i v_i)$ with minimal distance from $x + w$ to $x + w$ and has length smaller than $\text{diam}(M)$. Summing all the lengths of those segments we get

$$\begin{aligned} \bar{L}(\gamma) &\leq \text{diam}(M) + n_{i_1} \cdot \varepsilon_{i_1} + e + D + n_{i_2} \cdot \varepsilon_{i_2} + e + D \\ &\quad + \dots + n_{i_k} \cdot \varepsilon_{i_k} + e + \text{diam}(M) \\ &= \lambda_1(w) + k \cdot e + k \cdot D + 2 \cdot \text{diam}(M) \leq \lambda_1(w) + C. \end{aligned}$$

Finally, if $n_j = 0$ for some $j \in \{1, \dots, k\}$, we need to make fewer changes of lines, and the inequality can be shown the same way. \square

The stable norm and the main theorem.. In the introduction of this paper, we gave the definition of the stable norm induced from a Riemannian metric g on M . Here we give a way to compute the stable norm of a vector lying in $H_1(M; \mathbb{Z})_{\mathbb{R}}$: Define

$$\begin{aligned} f : H_1(M; \mathbb{Z})_{\mathbb{R}} &\rightarrow \mathbb{R}_{\geq 0} \\ v &\mapsto \inf\{L(\gamma) \mid \gamma \text{ closed curve representing } v\} \end{aligned}$$

and $f_n : n^{-1}H_1(M; \mathbb{Z})_{\mathbb{R}} \rightarrow \mathbb{R}_{\geq 0}$, $f_n(v) = n^{-1}f(nv)$. In Bangert [3] it is shown that f_n converges uniformly on compact sets to the stable norm $\|\cdot\|_s$. Especially, we have: if $(v_n)_{n \in \mathbb{N}}$ is a sequence in $H_1(M; \mathbb{Z})_{\mathbb{R}}$ with $\lim_{n \rightarrow \infty} \frac{v_n}{n} = v \in H_1(M; \mathbb{R})$ (relative to the standard topology on the vector space $H_1(M; \mathbb{R}) \simeq \mathbb{R}^b$), then we have for the norm of v :

$$\|v\|_s = \lim_{n \rightarrow \infty} \frac{f(v_n)}{n}.$$

If \bar{d} is the distance on \bar{M} induced from p^*g , we have for $v \in H_1(M; \mathbb{Z})_{\mathbb{R}}$:

$$f(v) = \inf_{x \in \bar{M}} \bar{d}(x, x+v) = \min_{x \in F_0} \bar{d}(x, x+v)$$

because p^*g is a periodic metric and the closure of F_0 is a compact set. With $\lim_{n \rightarrow \infty} \frac{nv}{n} = v$, this yields:

$$\begin{aligned} \|v\|_s &= \lim_{n \rightarrow \infty} \frac{f(nv)}{n} \\ &= \lim_{n \rightarrow \infty} \frac{\min_{x \in F_0} \bar{d}(x, x+nv)}{n}. \end{aligned}$$

Theorem 3.5 *The polytope P is the unit ball of the stable norm on $H_1(M; \mathbb{R})$ induced by an arbitrary Hedlund metric associated to P on M .*

Note that by Definition 3.1, the Hedlund metric is chosen in the conformal class of the given Riemannian metric ρ on M .

PROOF: Let g be a Hedlund-metric associated to P . We show that for each $w \in \bigoplus_{j=1}^k \mathbb{N} \cdot v_j$, the stable norm of w is given by $\|w\|_s = \lambda_1(w)$. The proof of this works analogously for every other face of P . Consequently, this holds for all vectors in $H_1(M; \mathbb{R})$ that can be written as linear combinations of the vectors v_1, \dots, v_N with rational coefficients, and then, by continuity, this holds for all vectors in $H_1(M; \mathbb{R})$. Let x be an arbitrary point in F_0 and let $n \in \mathbb{N}$. Let $\gamma : [0, 1] \rightarrow \bar{M}$ be an arbitrary path from x to $x+nw$. We have

$$\begin{aligned} \lambda_1(nw) &= \int_{\gamma} \eta_1 = \int_0^1 \eta_1|_{\gamma(t)}(\dot{\gamma}(t)) dt \leq \int_0^1 \|\eta_1|_{\gamma(t)}\|^* \|\dot{\gamma}(t)\| dt \\ &\stackrel{(\gamma)}{\leq} \int_0^1 1 \cdot \|\dot{\gamma}(t)\| dt = \bar{L}(\gamma) \end{aligned}$$

With this and Lemma 3.4 we get

$$\lambda_1(n \cdot w) \leq \bar{d}(x, x+nw) \leq \lambda_1(n \cdot w) + C.$$

Thus

$$\lambda_1(n \cdot w) \leq \min_{x \in F_0} \bar{d}(x, x + nw) \leq \lambda_1(n \cdot w) + C,$$

and

$$\lambda_1(w) \leq \frac{\min_{x \in F_0} \bar{d}(x, x + nw)}{n} \leq \lambda_1(w) + \frac{C}{n}.$$

Letting n go to infinity, this yields $\|w\|_s = \lambda_1(w)$, as claimed. \square

References

- [1] I. Babenko and F. Balacheff. Sur la forme de la boule unit e de la norme stable unidimensionnelle. *Manuscripta Math.*, 119(3):347–358, 2006. ISSN 0025-2611.
- [2] F. Balacheff and D. Massart. Stable norms of non-orientable surfaces. *Ann. Inst. Fourier*, 58(4):1337–1369, 2008.
- [3] V. Bangert. Minimal geodesics. *Ergodic Theory Dynam. Systems*, 10(2):263–286, 1990. ISSN 0143-3857.
- [4] H. Federer. Real flat chains, cochains and variational problems. *Indiana Univ. Math. J.*, 24:351–407, 1974/75. ISSN 0022-2518.
- [5] M. Gromov. *Metric structures for Riemannian and non-Riemannian spaces. Transl. from the French by Sean Michael Bates. With appendices by M. Katz, P. Pansu, and S. Semmes. Edited by J. LaFontaine and P. Pansu. 3rd printing.* Modern Birkh user Classics. Basel: Birkh user. xx, 585 p. , 2007.
- [6] G. A. Hedlund. Geodesics on a two-dimensional Riemannian manifold with periodic coefficients. *Ann. of Math. (2)*, 33(4):719–739, 1932. ISSN 0003-486X.
- [7] M. Jotz. *Hedlund-Metriken und die stabile Norm.* Diplomarbeit, Albert-Ludwigs-Universit at Freiburg. Available at the author’s web page, 2007.
- [8] J. M. Lee. *Introduction to smooth manifolds.* Graduate Texts in Mathematics. 218. New York, NY: Springer. xvii, 628 p. , 2002.
- [9] J. M. Lee. *Introduction to topological manifolds*, volume 202 of *Graduate Texts in Mathematics.* Springer-Verlag, New York, 2000. ISBN 0-387-98759-2; 0-387-95026-5.
- [10] D. Massart. Stable norms of surfaces: local structure of the unit ball of rational directions. *Geom. Funct. Anal.*, 7(6):996–1010, 1997. ISSN 1016-443X.