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COMPUTATION AND CHARACTERIZATION OF THE ZEROS OF LINEAR MULTIVARIABLE SYSTEMS

by

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Abstract

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A natural extension of the results of Kouvaritakis and MacFarlane on the calculation of multivariable zeros is described.

Kouvaritakis and MacFarlane^{1,2} have suggested a conceptually simple numerical technique for the calculation of the invariant zeros of the *l*-input/m-output linear, time-invariant left-invertible system S(A,B,C),

$$\dot{\mathbf{x}}(t) = A\mathbf{x}(t) + B\mathbf{u}(t) , \quad \mathbf{x}(t) \in \mathbb{R}^{n}$$

$$\mathbf{y}(t) = C\mathbf{x}(t) , \quad \mathbf{y}(t) \in \mathbb{R}^{m} , \quad \mathbf{u}(t) \in \mathbb{R}^{\ell}$$
(1)

when, in particular, $m \ge l$, rank B = l, rank C = m. The purpose of this note is to describe a natural extension of their results that can make possible a reduction in dimension of the defining relationships.

Let k^* be the uniquely defined integer ≥ 1 such that

$$CA^{i-1}B = 0$$
, $1 \le i \le k^* - 1$, $CA^{k^* - 1}B \ne 0$ (2)

Lemma 1

The subspaces

$$\mathbb{V}_{0} \stackrel{\Delta}{=} \{0\}$$
, $\mathbb{V}_{k} \stackrel{\Delta}{=} \mathbb{R}(B) \bigoplus \mathbb{A}\mathbb{R}(B) \bigoplus \cdots \bigoplus \mathbb{A}^{k-1}\mathbb{R}(B)$ $(k \ge 1)$ (3)

have dimension kl for k in the range $0 \le k \le k^*$. By suitable choice of subspace W, the state space has the direct sum decomposition

$$R^{n} = V_{k} \bigoplus v^{*} \bigoplus W$$
(4)

where v^* is the maximal {A,B}-invariant subspace in the kernel of C. Sufficient conditions for W = {0} are that m = ℓ and $|CA^{k^*-1}B| \neq 0$. Proof

Follows directly from theorem 5 in ref. 3.

This fundamental lemma leads to the following construction

Lemma 2

3 .

Let $1 \le k \le k^*$ and, for each complex scalar λ , define

$$S_{k}^{(\lambda)} \stackrel{\Delta}{=} \{x \in \bigcap_{i=1}^{k} \text{ ker } CA^{i-1} : (\lambda I_{n} - A) x \in V_{k}\}$$
(5)

Then

$$S_{k}(\lambda) = \omega_{1}(\lambda) \bigoplus \{ V_{k-1} \cap \{ \bigcap_{i=1}^{k} \ker CA^{i-1} \} \}$$
(6)

where
$$\omega_1(\lambda) = \{(\lambda I_n - A)^{-1} R(B)\} \cap \text{ker C.}$$

Proof

It is known³ that $\omega_1(\lambda) \subset \nu^*$ and, using equation (2), $\nu^* \subset \bigcap_{i=1}^k \ker CA^{i-1}$. By definition $(\lambda I_n - A)\omega_1(\lambda) \subset V_1 \subset V_k$ from which we obtain $\omega_1(\lambda) \subset S_k(\lambda)$. It is also easily verified that $(\lambda I_n - A)V_{k-1} \subset V_k$ and hence that

$$\omega_{1}^{(\lambda)} \bigoplus \{ \mathbb{V}_{k-1} \cap \{ \bigcap_{i=1}^{k} \ker CA^{i-1} \} \} \subset S_{k}^{(\lambda)}$$
(7)

(the sum being direct by lemma one). Now take $x \in S_k^{}(\lambda)$ and write

$$(\lambda I_n - A) x = B\alpha_1 + AB\alpha_2 + \dots + A^{k-1}B\alpha_k$$
 (8)

This expression can be written in the form

$$(\lambda I_n - A) (x + A^{k-2} B \alpha_k) = B \alpha_1 + A B \alpha_2 + \dots + A^{k-2} B (\alpha_{k-1} + \lambda \alpha_k)$$

and hence (by induction) in the form

$$(\lambda I_{n} - A) (x - b) \in R(B)$$

for some $b \in V_{k-1}$ ie x-b $\in \omega_1(\lambda)$. In particular, it is seen that $b \in S_k(\lambda) + \omega_1(\lambda) = S_k(\lambda)$ from which

$$b \in V_{k-1} \cap \{ \bigcap_{i=1}^{k} ker CA^{i-1} \}$$

and hence

$$x \in \omega_1(\lambda) \bigoplus \{ V_{k-1} \cap \{ \bigcap_{i=1}^k \text{ker } CA^{i-1} \} \}$$

which reverses the inclusion in equation (7). This proves the lemma. We obtain immediately the following geometric characterization of the invariant zeros of S(A,B,C).

Theorem 1

Let $1 \le k \le k^*$. Then the complex number λ is an invariant zero of S(A,B,C) if, and only if,

$$\dim S_{k}(\lambda) > \dim V_{k-1} \cap \{ \bigcap_{i=1}^{k} \ker CA^{i-1} \}$$
(9)

Proof

Follows directly from lemma 2 noting³ that λ is a zero if, and only if, $\omega_1(\lambda) \neq \{0\}$.

This geometric formulation can be converted into algebraic relations paralleling those of Kouvaritakis and MacFarlane by the following constructions. Define the matrices

$${}^{B}_{k} \stackrel{\Delta}{=} [B, AB, \dots, A^{k-1}B] , C_{k} \stackrel{\Delta}{=} \begin{pmatrix} C \\ CA \\ \vdots \\ CA^{k-1} \end{pmatrix}$$
(10)

when, taking $1 \le k \le k^*$, lemma one indicates that we can define full rank matrices N_k , M_k of dimension $(n-kl) \times n$ and $n \times (n-rank C_k)$ respectively satisfying the relations

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$$N_{k}B_{k} = 0$$
 , $C_{k}M_{k} = 0$ (11)

Lemma 3

rank $B_k = k\ell \leq rank C_k$, $1 \leq k \leq k^*$, equality holding if $m = \ell$.

Proof

rank $B_k = k\ell$, $1 \le k \le k^*$, follows directly from lemma one. If $m = \ell$ then a dual argument on the system $S(A^T, C^T, B^T)$ yields rank $C_k = km$ as required. Finally, taking $m > \ell$ and choosing an ℓxm matrix K such that the square system S(A, B, KC) is invertible, we see that

$$kl = rank \begin{pmatrix} KC \\ KCA \\ \vdots \\ KCA^{k-1} \end{pmatrix} \leq rank C_{k}, \quad 1 \leq k \leq k^{*}$$

as required.

Defining, for notational convenience, $N_o = I_n$, we now prove the following main result of this paper.

Theorem 2

The complex number λ is an invariant zero of S(A,B,C) if, and only if,

$$\operatorname{rank} N_{k} (\lambda I_{n} - A) M_{k} < \operatorname{rank} N_{k-1} M_{k}$$
(12)

for any 1<k<k*.

Proof

The proof is obtained by evaluation of the expressions occurring in equation (9). Firstly, we see from the definitions and lemma three that

$$\dim S_{k}(\lambda) = \dim \{x \in \bigcap_{i=1}^{k} \ker CA^{i-1} : N_{k}(\lambda I-A)x = 0 \}$$
$$= \dim \ker N_{k}(\lambda I_{n}-A)M_{k}$$
$$= \operatorname{rank} M_{k} - \operatorname{rank} N_{k}(\lambda I_{n}-A)M_{k}$$
(13)

Secondly, we can, without loss of generality, assume that $M_k = [X_k, Y_k]$ where the columns of X_k are a basis for $V_{k-1} \cap \{ \bigcap_{i=1}^k \ker CA^{i-1} \}$ and ker $Y_k = \{0\}$. It follows directly that rank $N_{k-1}M_k = \operatorname{rank} N_{k-1}Y_k$. Consider now the relation $N_{k-1}Y_k\beta = 0$. We see immediately that $Y_k\beta \in V_{k-1} \cap \{ \bigcap_{i=1}^k \ker CA^{i-1} \}$ ie $Y_k\beta = 0$ (from the definition of X_k and Y_k) and hence $\beta = 0$. It follows that

$$\operatorname{rank} N_{k-1}M_{k} = \operatorname{rank} M_{k} - \operatorname{dim} V_{k-1} \cap \{ \bigcap_{i=1}^{k} \operatorname{ker} CA^{i-1} \}$$
(14)

The theorem follows by combining equations (9), (13) and (14).

The results of Kouvaritakis and MacFarlane¹⁻³ are obtained by setting k = 1 when equation (12) reduces to

$$\operatorname{rank} N_{1}(\lambda I_{n} - A) M_{1} < \operatorname{rank} M_{1} = n - m$$
(15)

or, in the important case of m = l when (Lemma 3) the matrices are square, we recover the well-known relation¹

$$|\lambda N_{1}M_{1} - N_{1}AM_{1}| = 0$$
 (16)

For those systems with $k^*>1$, the choice of k>1 represents a reduction in dimension of the relationships defining the zeros.

The rank conditions in equation (12) can be simplified when m = l and $|CA^{k^*-1}B| \neq 0$. In this case, applying lemma three rank $M_k = \operatorname{rank} N_k = n-km$, $1 \leq k \leq k^*$. Noting that (using equation (2) and lemma one)

$$V_{k-1} \cap \{ \bigcap_{i=1}^{k} \ker CA^{i-1} \} = V_{\min\{(k-1), (k^*-k)\}}$$
 (17)

and that dim $V_k = km$, $1 \le k \le k^*$, then a combination of equations (9) and (13) indicates that λ is a zero of S(A,B,C) if, and only if,

rank
$$N_k (\lambda I_n - A)M_k < n-km-min\{(k-1), (k^*-k)\}m$$
 (18)

In particular, if $k = k^*$ this reduces to the $(n-k^*m)x(n-k^*m)$ determinental relationship

$$z_{0}^{(\lambda)} \stackrel{\Delta}{=} \left| \lambda N_{*} M_{*} - N_{*} A M_{*} \right| = 0$$
(19)
k k k k

As $|CA^{k^*-1}B| \neq 0$, then it is easily verified that N $*^{M}$ is nonsingular and hence that, if N * is replaced by $\overline{N} * = (N *^{M})^{-1}N *^{K}$ in equation (19), then the invariant zeros are the <u>eigenvalues</u> of $\overline{N} *^{AM} *$. This result is a direct generalization of the result $\frac{1}{k}$ that the invariant zeros are the eigenvalues of N $^{AM}_{1}$ if $|CB| \neq 0$ and we choose N such that N $^{M}_{1} = I_{n-m}$. Finally, note that equation (19) will also give the correct <u>algebraic</u> multiplicity of each zero. To prove this, note that the above discussion indicates that $z_{(\lambda)}$ has degree equal to $n-k^*m$. The decomposition of lemma one makes possible the consideration of arbitrarily small perturbations δ to A such that $\delta v \stackrel{*}{\subset} v^*$ and $\delta [V_*] = \{0\}$. It is easily verified that the number of zeros including multiplicities (ie³ dim $v^* = n-k^*m$) is unaffected by any such perturbation, that the invariant zeros vary continuously with δ and that both N * and M * are unchanged. The invariant $k = k^*$

$$z_{\delta}(\lambda) \stackrel{\Delta}{=} |\lambda N_{*}M_{*} - N_{*}(A+\delta)M_{*}|$$

$$\equiv |N_{*}M_{*}| \cdot |\lambda I_{*} - \overline{N}_{*}(A+\delta)M_{*}|$$

$$= 0$$

Note that the degree of the polynomial $n-k^m$ is independent of δ and that the $n-k^m$ zeros are distinct for 'almost all' choices of δ . A simple continuity argument now proves that $z_0(s)$ provides the correct algebraic multiplicity.

(20)

To illustrate the results, consider the system defined by

	<pre>6</pre>	1	υ	-1	0	0	0	0
	0	0	1	0	0	0	0	0
	1	2	1	0	3	-1	0	1
A =	0	0	0	0	1	0	0	0
	1	0	0	1	0	1	0	0
	3	0	0	0	0	0	1	0
	1	-2	1	0	1	2	1	-1
	(-2	0	0	1	0	0	0	-4

The system has one zero at the point $\lambda = -4$ and $k^* = 3$.

Consider now the application of equation (12) to the calculation of the zero. Take initially k = 2, then $C_1 = C$,

		1	0	0	0	0	0	0	0)	
C ₂ =	0	0	0	1	0	0	0	0		
	0	1	0	-1	0	0	0	0		
		lo	0	0.	0	1	0	0	0)	
		0	0	1	0	0	0	0	0]	
_в т	-	0	0	0	0	0	0	1	0	
B ₂ ^T =	0	1	1	0	0	0	1	0		
	lo	0	0	0	0	1	1	0		

yielding

N ₁ -		(1	0	0	0	0	0	0	0)
		1 0 0 0 0	1	0	0	0	0	0	0
	=	0	0	0	1	0	0	0	0 0 0 0
		0	0 0	0	0	1	0	0	0
		0	0	0	0	0	1	0	0
		lo	0	0	0	0	0	0	1]
^N 2		1	0	0	0	0	0	0	0 0 0 1
	=	0	0	0 0	1	0	0	0	0
2		0	0	0	0	1	0	0	0
		lo	0	0	0	0	0	0	1]
M2 ^T		0	0	1	0	0	0	0	0
	н	0	0	0	0	0	1	0	0
		0	0	0	0	0	0	1	0
		lo	0	0	0	0	0	0	0 0 1

(23)

(22)

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Substituting into equation (12) indicates that λ is a zero if, and only if,

ie $\lambda = -4$ is the only zero. Considering now the case of $k = k^* = 3$ we obtain

	0	0	0	1	0	0	0	0]
N ₃ =	lo	0	0	0	0	0	0	1]

 $M_3^{\rm T} = \begin{pmatrix} 0 & 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 \end{pmatrix}$ (25)

Substituting into equation (12) indicates that λ is a zero if, and only if,

 $\operatorname{rank} \begin{pmatrix} 0 & 0 \\ 0 & \lambda+4 \end{pmatrix} < \operatorname{rank} \begin{pmatrix} 0 & 0 \\ 0 & 0 \\ 0 & 0 \\ 0 & 1 \end{pmatrix}$ (26) SHEFFIELD UNIV.

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again verifying that $\lambda = -4$ is the only zero of the system.

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