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ASYMPTOTIC ROOT-LOCI OF LINEAR MULTIVARIABLE
SYSTEMS: A GEOMETRIC ANALYSIS

by

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Abstract

Recent results on the asymptotic behaviour of the root-loci of a linear time-invariant system $S(A,B,C)$ are formulated in geometric terms and equivalent results obtained in two cases of practical interest in terms of the matrix coefficients in the expansion of $(A-pBC)^l$, $l \geq 1$.

1. Introduction

A recent paper (Shaked and Kouvaritakis, 1976) presented a theoretical analysis of the asymptotic behaviour of the eigenvalues of the linear, time-invariant system $S(A,B,C)$

$$\begin{aligned} \dot{x} &= Ax(t) + Bu(t) \quad , \quad u(t) \in R^m \quad , \quad x(t) \in R^n \\ y(t) &= Cx(t) \quad , \quad y(t) \in R^m \end{aligned} \quad \dots(1)$$

when subject to unity negative feedback with scalar gain $p \geq 0$. The closed-loop system takes the form

$$\begin{aligned} \dot{x}(t) &= \{A - pBC\}x(t) + Br(t) \\ y(t) &= Cx(t) \end{aligned} \quad \dots(2)$$

Previous work (Shaked and Kouvaritakis, 1976) used determinantal manipulation techniques to obtain explicit formula for the asymptotic directions and pivots of the root-locus. This paper describes some solutions of this problem by geometric analysis of the closed-loop eigenvalue equation

$$\{s(p)I_n - A + pBC\}x(p) = 0 \quad , \quad \|x(p)\| = 1 \quad , \quad p \geq 0 \quad \dots(3)$$

and the identification of the asymptotic directions and pivots in terms of the structural properties of the matrix coefficients in the expansion of $(A - pBC)^l$, $l \geq 1$.

2. Asymptotic Behaviour of Closed-loop Eigenvectors

Let $\{p_j\}_{j \geq 1}$ be an unbounded sequence of positive real numbers and $\{s(p_j)\}_{j \geq 1}$, $\{x(p_j)\}_{j \geq 1}$ a corresponding sequence of closed-loop eigenvalues and eigenvectors respectively. By extraction of a suitable subsequence, it is possible to assume that

$$\lim_{j \rightarrow \infty} x(p_j) = x_\infty \quad , \quad \|x_\infty\| = 1 \quad \dots(4)$$

If $R(Q)$, $N(Q)$ denote the range and null space of a matrix Q , then

Theorem 1

(a) If the sequence $\{|s(p_j)|\}_{j \geq 1}$ is unbounded, then $x_\infty \in R(B)$.

- (b) If the sequence $\{s(p_j)\}_{j \geq 1}$ has a finite cluster point λ , then $x_\infty \in W_B$, where (Owens, 1975) W_B is the maximal subspace of $N(C)$ satisfying the relation $AW_B \subset W_B + R(B)$.

Proof

To prove (a), divide equation (3) by $s(p)$, from which

$$x_\infty = \lim_{j \rightarrow \infty} (s(p_j))^{-1} p_j B C x(p_j) \in R(B).$$

To prove (b), equation (3) implies that $(\lambda I_n - A)x_\infty = \lim_{j \rightarrow \infty} p_j B C x(p_j) \in R(B)$ ie $x_\infty \in W_B$.

Q.E.D.

3. Asymptotic Root-loci for Uniform-rank Multivariable Systems

To illustrate the general structure of the geometric relationships defining the asymptotic form of the system root-locus, consider the case of an open-loop system (equation (1)) satisfying the relations

$$\begin{aligned} CA^{j-1}B &= 0 & j < k \\ |CA^{k-1}B| &\neq 0 \end{aligned} \quad \dots(5)$$

Equivalently, if $G(s) = C(sI_n - A)^{-1}B$ is the open-loop system transfer function matrix, then

$$G_\infty^{(k)} \triangleq \lim_{s \rightarrow \infty} s^k G(s) = CA^{k-1}B \quad \dots(6)$$

exists, is nonsingular and $|G(s)| \neq 0$. On intuitive grounds, the above relations imply that each loop has a dynamic behaviour analogous to a classical rank k transfer function and, as such, $G(s)$ will be termed a uniform rank transfer function matrix and $S(A,B,C)$ a uniform rank system.

The following theorem defines the asymptotic form of the root-locus plot in terms of the expansion of the matrix $(A - pBC)^\ell$. For convenience, define

$$\Gamma_0 = 0, \quad \Gamma_\ell = \sum_{j=1}^{\ell} A^{j-1} B C A^{\ell-j}, \quad \ell \geq 1 \quad \dots(7)$$

and note from condition (5) that

$$(A-pBC)^\ell = A^\ell - p\Gamma_\ell, \quad 1 \leq \ell \leq k \quad \dots(8)$$

and, from equation (7), by induction,

$$\Gamma_0 = 0 \quad \dots(9)$$

$$\begin{aligned} \Gamma_{j+1} &= A\Gamma_j + BCA^j \\ &= \Gamma_j A + A^j BC, \quad j \geq 0 \end{aligned} \quad \dots(10)$$

Theorem 2

With the above notation, and $S(A,B,C)$ of uniform rank, the closed-loop system $S(A-pBC, B, C)$ has km unbounded poles of the form, $1 \leq j \leq m$, $1 \leq \ell \leq k$

$$\mu_{j\ell}(p) = p^{\frac{1}{k}} \eta_{j\ell} + \alpha_j + \varepsilon_{j\ell}(p) \quad \dots(11)$$

where $\eta_{j\ell}$, $1 \leq \ell \leq k$ are the k th roots of λ_j where λ_j is a non-zero solution of

$$\{\lambda_j I_n + BCA^{k-1}\} x_\infty = 0, \quad \|x_\infty\| = 1 \quad \dots(12)$$

Also,

$$\lim_{p \rightarrow \infty} \varepsilon_{j\ell}(p) = 0$$

and if,

$$N(\lambda_j I_n + BCA^{k-1}) \cap R(\lambda_j I_n + BCA^{k-1}) = \{0\}, \quad \dots(13)$$

then, the pivot α_j is a solution of the relation

$$\{k\alpha_j I_n - A\} x_\infty \in R(\lambda_j I_n + BCA^{k-1}) \quad \dots(14)$$

The remaining $n-km$ poles tend to the zeros of $S(A,B,C)$.

Proof

Equation (3) implies that

$$\{(s(p))^\ell I_n - (A-pBC)^\ell\} x(p) = 0, \quad \ell \geq 1 \quad \dots(15)$$

or, by equation (8), for $1 \leq \ell \leq k$,

$$\left\{ \frac{(s(p))^\ell}{p} I_n - p^{-1} A^\ell + \Gamma_\ell \right\} x(p) = 0 \quad \dots(16)$$

In an analogous manner to section 2, suppose that the family $\{x(p)\}$ has a cluster point x_∞ ($\|x_\infty\| = 1$) then

$$\lim_{p \rightarrow \infty} \frac{s(p)^\ell}{p} x_\infty = \Gamma_\ell x_\infty, \quad 1 \leq \ell \leq k \quad \dots(17)$$

Considering only unbounded eigenvalues, then (Theorem 1) $x_\infty \in R(B)$ so that (equations (5), (7))

$$\lim_{p \rightarrow \infty} \frac{s(p)^\ell}{p} = 0, \quad \ell < k \quad \dots(18)$$

and,

$$\Gamma_k x_\infty = BCA^{k-1} x_\infty \neq 0 \quad \dots(19)$$

the (equation (17)) $\lambda_j \triangleq \lim_{p \rightarrow \infty} p^{-1} (s(p))^k$ exists, is non-zero and is a solution of the eigenvalue equation (12). Write $s(p) = p^{\frac{1}{k}} \eta_{j\ell} + \psi_{j\ell}(p)$ where $\eta_{j\ell}^k = \lambda_j$ and

$$\lim_{p \rightarrow \infty} p^{\frac{1}{k}} \psi_{j\ell}(p) = 0 \quad \dots(20)$$

It follows that

$$\lim_{p \rightarrow \infty} p^{\frac{1}{k}} \left\{ \frac{s(p)^k}{p} - \lambda_j \right\} x(p) = -\lim_{p \rightarrow \infty} p^{\frac{1}{k}} \{ \lambda_j + \Gamma_\ell \} x(p) \quad \dots(21)$$

Writing (equation (10)) $\Gamma_k = A\Gamma_{k-1} + BCA^{k-1}$ and noting (equation (16)) that

$$\lim_{p \rightarrow \infty} p^{\frac{1}{k}} A\Gamma_{k-1} x(p) = -\lambda_j^{\frac{k-1}{k}} Ax_\infty \quad \dots(22)$$

then

$$\left\{ \lim_{p \rightarrow \infty} p^{\frac{1}{k}} \left\{ \frac{s(p)^k}{p} - \lambda_j \right\} \Gamma_{k-1} \right\} Ax_\infty = \lim_{p \rightarrow \infty} p^{\frac{1}{k}} \{ \lambda_j + BCA^{k-1} \} x(p) \quad \dots(23)$$

Using equation (13) and noting that $x_\infty \in N(\lambda_j I_n + BCA^{k-1})$, it follows that $\lim_{p \rightarrow \infty} p^{\frac{1}{k}} \left(\frac{s(p)^k}{p} - \lambda_j \right)$ exists, so that (equation (20))

$$\begin{aligned} \lim_{p \rightarrow \infty} p^{\frac{1}{k}} \left(\frac{s(p)^k}{p} - \lambda_j \right) &= \lim_{p \rightarrow \infty} k \lambda^{\frac{k-1}{k}} \mu_{j\ell}(p) \\ &= k \lambda^{\frac{k-1}{k}} \alpha_{j\ell} \end{aligned} \quad \dots(24)$$

for some finite scalar $\alpha_{j\ell}$. It is easily seen that $\alpha_{j\ell}$ is independent of ℓ and writing $\alpha_{j\ell} = \alpha_j$, equation (23) implies that

$$(k\alpha_j I_n - A)x_\infty \in R(\lambda_j I_n + BCA^{k-1}) \quad \dots(25)$$

as required.

Finally, it can be shown (Owens, 1975) that $S(A,B,C)$ has $n-km$ zeros, each of which (Shaked and Kouvaritakis, 1976) attracts a pole at high gain. Q.E.D.

The above theorem provides explicit geometrical conditions for the construction of the asymptotes of the root locus plot. For purposes of calculation, write $x_\infty = Bz$, then (equation (12)) as $\text{rank } B = m$ (equation (5)), λ_j is the solution of the eigenvalue problem,

$$\begin{aligned} 0 &= \{\lambda_j I_m + CA^{k-1}B\}\alpha_j \\ &= \{\lambda_j I_m + G_\infty^{(k)}\}\alpha_j, \quad \alpha_j \neq 0 \end{aligned} \quad \dots(26)$$

Condition (13) is equivalent to the requirement that $G_\infty^{(k)}$ has a complete set of eigenvectors. To calculate the pivot, suppose that u_1, \dots, u_ℓ are linearly independent eigenvectors of BCA^{k-1} spanning the eigenspace corresponding to the eigenvalue λ_j , and let v_1^+, \dots, v_ℓ^+ be the corresponding dual eigenvectors satisfying $v_j^+ u_\ell = \delta_{j,k}$, then, if M_j is the $\ell \times \ell$ matrix with elements

$$(M_j)_{rq} = k^{-1} v_r^+ A u_q, \quad 1 \leq r, q \leq \ell \quad \dots(27)$$

it follows that α_j is a solution of the eigenvalue equation

$$\{\alpha_j I_\ell - M\}\beta_j = 0, \quad \beta_j \neq 0 \quad \dots(28)$$

4. Asymptotic Root-loci for Non-uniform-rank Multivariable Systems

In more general situations (Shaked and Kouvaritakis, 1976) $S(A-pBC, B, C)$ will have unbounded poles of various orders as $p \rightarrow +\infty$. The main result of this section (Theorem 3) provides a geometric characterization of the asymptotes of the root-locus in certain situations of practical interest, using relations analogous to those of Theorem 2.

Write, $\ell \geq 1$

$$(A-pBC)^\ell = \sum_{j=0}^{\ell} (-1)^j p^j B_{j,\ell} \quad \dots (29)$$

from which, by induction,

$$B_{0,1} = A, \quad B_{1,1} = BC \quad \dots (30)$$

and, for $\ell \geq 1$,

$$\begin{aligned} B_{0,\ell+1} &= AB_{0,\ell} \\ B_{j,\ell+1} &= AB_{j,\ell} + BCB_{j-1,\ell}, \quad 1 \leq j \leq \ell \\ B_{\ell+1,\ell+1} &= BCB_{\ell,\ell} \end{aligned} \quad \dots (31)$$

so that (equations (9), (10), (30)), for $\ell \geq 1$,

$$B_{0,\ell} = A^\ell, \quad B_{1,\ell} = \Gamma_\ell, \quad B_{\ell,\ell} = (BC)^\ell \quad \dots (32)$$

In a similar manner to equation (5), let k be the uniquely defined integer such that

$$CA^{j-1}B = 0, \quad j < k, \quad CA^{k-1}B \neq 0 \quad \dots (33)$$

then (equation (8))

$$BC(A-pBC)^\ell = \begin{cases} BCA^\ell & , \quad 0 \leq \ell < k \\ BCA^{k-1}(A-pBC) & , \quad \ell = k \end{cases} \quad \dots (34)$$

so that, $k \leq \ell \leq 2k-1$,

$$BC(A-pBC)^\ell = BCA^{k-1} \{ A^{\ell+1-k} - p \Gamma_{\ell+1-k} \} \quad \dots (35)$$

Defining

$$V_0 \triangleq R(B) , \quad V_\ell \triangleq R(B) \cap \bigcap_{j=1}^{\ell} N(BCA^{j-1}) \equiv \bigcap_{j=1}^{\ell} N(\Gamma_j) \cap R(B) , \quad \ell \geq 1 \quad \dots (36)$$

then, if $|G(s)| \neq 0$, there exists an integer \hat{k} such that

$$V_\ell \neq \{0\} \quad (\ell < \hat{k}) , \quad V_\ell = \{0\} \quad (\ell \geq \hat{k}) \quad \dots (37)$$

for, if $x \in V_\ell$ for all $\ell \geq 1$, then $A^\ell x \in N(c)$ for all $\ell \geq 0$ ie (theorem 1)

$x \in W_B$ and the proposition is proved by noting (Owens, 1975) that $|G(s)| \neq 0$ implies that $W_B \cap R(B) = \{0\}$. It is easily shown that

$$k \leq \hat{k} \quad \dots (38)$$

Defining, $k-1 \leq \ell \leq 2k-1$,

$$W_\ell \triangleq R(BCA^{k-1} \Gamma_{\ell+1-k}) , \quad X_\ell \triangleq \bigcap_{j=k-1}^{\ell} N(BCA^{k-1} \Gamma_{j+1-k}) \quad \dots (39)$$

the following theorem is proved below,

Theorem 3

With the above notation, $|G(s)| \neq 0$, and $k \leq 2k$, then, if

$$\begin{aligned} V_\ell \cap W_\ell &= \{0\} , & k-1 \leq \ell \leq \hat{k}-1 \\ \{\Gamma_{\ell+1} V_\ell\} \cap W_\ell &= \{0\} , & k-1 \leq \ell \leq \hat{k}-1 \end{aligned} \quad \dots (40)$$

the closed-loop system $S(A-pBC, B, C)$ possesses unbounded poles of the form,
 $k \leq \ell \leq \hat{k}$,

$$s(p) = p^{\frac{1}{\ell}} \eta + f(p) \quad \dots (41)$$

where, if λ is a non-zero solution of the relation

$$\{\lambda I_n + BCA^{\ell-1}\} x_\infty \in W_{\ell-1} \quad \dots (42)$$

$$0 \neq x_\infty \in V_{\frac{1}{\ell} \ell-1}$$

then η is an ℓ th root of λ , $p^{\frac{1}{\ell}}$ is the positive real ℓ th root of p and

$$\lim_{p \rightarrow \infty} p^{\frac{1}{\ell}} f(p) = 0 \quad \dots (43)$$

Moreover, if, for $k \leq \ell \leq \hat{k}$,

$$\{ \{\lambda I_n + BCA^{\ell-1}\} x_{\ell-1} + W_{\ell-1} \} \cap V_{\ell-1} \cap \{ \lambda I_n + BCA^{\ell-1} \}^{-1} W_{\ell-1} = \{0\} \quad \dots (44)$$

then $f(p)$ takes the form

$$f(p) = \alpha + \varepsilon(p) \quad \dots(45)$$

where $\lim_{p \rightarrow \infty} \varepsilon(p) = 0$, and the 'pivot' α is a constant, finite solution of the relation

$$\{\ell \alpha I_n - A\} x_\infty \in \{\lambda I_n + BCA^{\ell-1}\} x_{\ell-1} + W_{\ell-1} \quad \dots(46)$$

Proof

Equation (3) implies that

$$\{(s(p))^\ell I_n - (A - pBC)^\ell\} x(p) = 0, \quad \|x(p)\| = 1, \quad \ell \geq 1 \quad \dots(47)$$

Using equations (8), (29), (32), this takes the form

$$\{p^{-1}(s(p))^\ell - p^{-1}A^\ell + \Gamma_\ell\} x(p) = \begin{cases} 0 & ; \quad \ell \leq k \\ \sum_{j=2}^{\ell} (-1)^j p^{j-1} B_{j,\ell} x(p) & ; \quad \ell > k \end{cases} \quad \dots(48)$$

Taking the case of $\ell = k$, it follows that $p^{-1}s(p)$ is bounded ($p \rightarrow \infty$) from which $\lim_{p \rightarrow \infty} p^{-1}(s(p))^k$ exists for every closed-loop pole. If $\lim_{p \rightarrow \infty} p^{-1}(s(p))^k = \lambda \neq 0$, then, if $\lim_{p \rightarrow \infty} x(p) = x_\infty$ ($\|x_\infty\| = 1$), $\Gamma_j x_\infty = 0$, $j < k$, so that $x_\infty \in V_{k-1}$ and

$$\{\lambda I_n + BCA^{k-1}\} x_\infty = 0 \in W_{k-1} \quad \dots(49)$$

proving (42) in the case of $\ell = k$. Using induction, suppose that $\lim_{p \rightarrow \infty} p^{-1}(s(p))^r = 0$, $k \leq r < \ell$, and $x_\infty \in V_{\ell-1}$, so that (equation (40)),

$$\lim_{p \rightarrow \infty} \sum_{j=2}^r (-1)^j p^{j-1} B_{j,r} x(p) = 0, \quad k \leq r < \ell \quad \dots(50)$$

Using equation (31), (32), (35), equation (50) becomes

$$\begin{aligned} \lim_{p \rightarrow \infty} \{A \sum_{j=2}^{r-1} (-1)^j p^{j-1} B_{j,r-1} x(p) - BC \sum_{j=1}^{r-1} (-1)^j p^j B_{j,r-1} x(p)\} \\ = \lim_{p \rightarrow \infty} p BCA^{k-1} \Gamma_{r-k} x(p) = 0, \quad k \leq r < \ell \end{aligned} \quad \dots(51)$$

In a similar manner, it can be shown that

$$\lim_{p \rightarrow \infty} \{p^{-1}(s(p))^{\ell} I_n + \Gamma_{\ell}\} x(p) = \lim_{p \rightarrow \infty} p B C A^{k-1} \Gamma_{\ell-k} x(p) \in W_{\ell-1} \quad \dots (52)$$

Equation (40) implies that $p^{-1}(s(p))^{\ell}$ can only have a finite cluster point λ .

If $\lambda = 0$, then $\Gamma_{\ell} x_{\infty} \in W_{\ell-1}$ or (equation (40)) $x_{\infty} \in N(\Gamma_{\ell}) \cap V_{\ell-1} = V_{\ell}$ and

$\lim_{p \rightarrow \infty} p B C A^{k-1} \Gamma_{\ell-k} x(p) = 0$. Alternatively, if $\lambda \neq 0$, it is a solution of the relation

$$\{\lambda I_n + B C A^{\ell-1}\} x_{\infty} = B C A^{k-1} \Gamma_{\ell-k} z \in W_{\ell-1} \quad \dots (53)$$

for some vector $z \in R^n$, proving equation (42). Note that, if

$\lim_{p \rightarrow \infty} p^{-1}(s(p))^{\ell} = 0$, $1 \leq \ell \leq \hat{k}$, then, from the definition of \hat{k} , $x_{\infty} \notin R(B)$ ie (theorem 1) $s(p)$ has a finite limit.

Finally, if $p^{-1}(s(p))^{\ell} \rightarrow \lambda \neq 0$ ($p \rightarrow \infty$) and $\ell = k$, equation (40) follows directly from theorem 2. Alternatively, if $\ell > k$, rewrite equation (48) in the form,

$$\begin{aligned} & \frac{1}{p^{\ell}} \{p^{-1}(s(p))^{\ell-\lambda}\} x(p) \\ &= \frac{1}{p^{\ell}} \{-\{\lambda I_n + \Gamma_{\ell}\} + p^{-1} A^{\ell} + \sum_{j=2}^{\ell} (-1)^j p^{j-1} B_{j,\ell}\} x(p) \\ &= \frac{1}{p^{\ell}} \{-\{\lambda I_n + \Gamma_{\ell}\} + p^{-1} A^{\ell} + A \sum_{j=2}^{\ell-1} p^{j-1} (-1)^j B_{j,\ell-1} - B C \sum_{j=1}^{\ell-1} (-1)^j p^j B_{j,\ell-1}\} x(p) \end{aligned} \quad \dots (54)$$

From (48) replacing ℓ , by $\ell-1$,

$$\lim_{p \rightarrow \infty} p^{\frac{\ell-1}{\ell}} A \left\{ \sum_{j=2}^{\ell-1} p^{j-1} (-1)^j B_{j,\ell-1} - \Gamma_{\ell-1} \right\} x(p) = \eta^{\frac{\ell-1}{\ell}} A x_{\infty} \quad \dots (55)$$

so that, using equation (10), equation (54) takes the form

$$\begin{aligned} & \lim_{p \rightarrow \infty} \frac{1}{p^{\ell}} \{p^{-1}(s(p))^{\ell-\lambda}\} I_n - \eta^{\frac{\ell-1}{\ell}} A \} x_{\infty} \\ &= -\lim_{p \rightarrow \infty} p^{\frac{1}{\ell}} \{\lambda I_n + B C A^{\ell-1} + B C \sum_{j=1}^{\ell-1} (-1)^j p^j B_{j,\ell-1}\} x(p) \\ &= -\lim_{p \rightarrow \infty} p^{\frac{1}{\ell}} \{\lambda I_n + B C A^{\ell-1} - p B C A^{k-1} \Gamma_{\ell-k}\} x(p) \end{aligned} \quad \dots (56)$$

Write $x(p) = x_1(p) + x_2(p)$, $x_1(p) \in X_{\ell-1}$, $x_2(p) \in X_{\ell-1}^{\perp}$, then the relations (equations (51)-(53))

$$\begin{aligned} \lim_{p \rightarrow \infty} p \text{BCA}^{k-1} \Gamma_{r-k} x(p) &= 0, & k \leq r < \ell \\ \lim_{p \rightarrow \infty} p \text{BCA}^{k-1} \Gamma_{\ell-k} x(p) &= \text{BCA}^{k-1} \Gamma_{\ell-k} z \quad (\text{finite}) \end{aligned} \quad \dots (57)$$

imply that $\lim_{p \rightarrow \infty} p^{\frac{1}{\ell}} x_2(p) = 0$ ie

$$\begin{aligned} \lim_{p \rightarrow \infty} \{ p^{\frac{1}{\ell}} \{ p^{-1} (s(p))^{\ell-\lambda} \} I_n^{-\eta} \frac{\ell-1}{\ell} A \} x_{\infty} \\ = - \lim_{p \rightarrow \infty} p^{\frac{1}{\ell}} \{ \{ \lambda I_n + \text{BCA}^{\ell-1} \} x_1(p) - p \text{BCA}^{k-1} \Gamma_{\ell-k} x(p) \} \end{aligned} \quad \dots (58)$$

Condition (44) implies that $\lim_{p \rightarrow \infty} p^{\frac{1}{\ell}} \{ (s(p))^{\ell-1-\lambda} \}$ exists or (equation (41), (43))

$$\lim_{p \rightarrow \infty} p^{\frac{1}{\ell}} \{ p^{-1} (p^{\frac{1}{\ell}} \eta + f(p))^{\ell-\lambda} \} = \lim_{p \rightarrow \infty} \ell \eta^{\frac{\ell-1}{\ell}} f(p) \triangleq \ell \eta^{\frac{\ell-1}{\ell}} \alpha \quad \dots (59)$$

for one finite constant α . Substituting into (58) yields the relation

$$\{ \ell \alpha I_n - A \} x_{\infty} \in \{ \lambda I_n + \text{BCA}^{\ell-1} \} x_{\ell-1} + W_{\ell-1} \quad \dots (60)$$

which prove the result.

Q.E.D.

It is easily shown that theorem 3 reduces to theorem 2 if $S(A, B, C)$ is of uniform rank.

5. Illustrative Example

Consider the non-uniform-rank system defined by the matrices

$$A = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix} \quad B = \begin{bmatrix} 0 & 0 \\ 1 & 0 \\ 0 & 1 \end{bmatrix} \quad C = \begin{bmatrix} 1 & 0 & -1 \\ 1 & 0 & 1 \end{bmatrix}$$

from which, $|G(s)| \neq 0$, $k = 1$

$$\Gamma_0 = 0, \quad \Gamma_1 = BC = \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & -1 \\ 1 & 0 & 1 \end{bmatrix}, \quad (BC)^2 = \begin{bmatrix} 0 & 0 & 0 \\ -1 & 0 & -1 \\ 1 & 0 & 1 \end{bmatrix}$$

$$BCA = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & -1 \\ 0 & 1 & 1 \end{bmatrix}, \quad \Gamma_2 = \begin{bmatrix} 1 & 0 & -1 \\ 2 & 1 & -1 \\ 1 & 1 & 2 \end{bmatrix} \quad \dots(62)$$

so that

$$V_0 = \text{span}\left\{ \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right\}, \quad V_1 = \text{span}\left\{ \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \right\}, \quad V_2 = \{0\} \quad \dots(63)$$

ie $\hat{k} = 2 = 2k$. Also,

$$W_0 = \{0\}, \quad W_1 = \text{span}\left\{ \begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix} \right\}, \quad X_0 = \mathbb{R}^3, \quad X_1 = \text{span}\left\{ \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} \right\} \dots(64)$$

so that $W_0 \cap V_0 = W_1 \cap V_1 = \{0\}$, $\Gamma_1 V_0 \cap W_0 = \{0\}$, $\Gamma_2 V_1 \cap W_1 = \{0\}$.

To calculate the first order asymptote, solve the equation

$$\{\lambda I_3 + \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & -1 \\ 1 & 0 & 1 \end{bmatrix}\} x_\infty \in W_0, \quad x_\infty \in V_0 \quad \dots(65)$$

ie $\lambda = -1$ and $x_\infty = \{0, -1, 1\}^T \in R(B)$. The corresponding pivot is the solution of the relation

$$\{\alpha I_3 - \begin{bmatrix} 0 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix}\} \begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix} = \begin{bmatrix} -1 & 0 & 0 \\ 1 & -1 & -1 \\ 1 & 0 & 0 \end{bmatrix} z, \quad z \in \mathbb{R}^3 \quad \dots(66)$$

ie $\alpha = 0$, and the asymptote takes the form $-p$; and passes through the origin of the complex plane. Considering now the second order type asymptote,

$$\{\lambda I_3 + \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & -1 \\ 0 & 1 & 1 \end{bmatrix}\} x_\infty \in W_1, \quad x_\infty \in V_1 \quad \dots(67)$$

ie $\lambda = -2$ and $x_\infty = \{0, 1, 0\}^T$. The corresponding pivot is the solution of the relation

$$\begin{aligned} \{2\alpha I_3 - \begin{bmatrix} 0 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix}\} \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} &= \begin{bmatrix} -2 & 0 & 0 \\ 0 & -1 & -1 \\ 0 & 1 & -1 \end{bmatrix} \begin{bmatrix} 0 & -1 \\ 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} z_1 \\ z_2 \end{bmatrix} + z_3 \begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix} \\ &= \begin{bmatrix} 0 & 2 & 0 \\ -1 & -1 & -1 \\ 1 & -1 & 1 \end{bmatrix} \begin{bmatrix} z_1 \\ z_2 \\ z_3 \end{bmatrix} \quad \dots(68) \end{aligned}$$

ie $\alpha = 1$ and the second order asymptote takes the form $\pm p^{\frac{1}{2}} \sqrt{-2} + 1$.

6. Conclusions

The geometric characterization of the asymptotes of multivariable root-loci of a linear system has been discussed for two cases of practical interest. The work augments the analysis of Shaked and Kouvaritakis (1976) and illustrates the fact that (i) two integer parameters k, \hat{k} , derived from geometric considerations, play a fundamental role in the description of the root-locus, and (ii) both the asymptotic directions and pivots are described by inclusion relationships in the state space of the form

$$\{\xi I_n + F\}x \in Q, \quad z \in P \quad \dots(69)$$

where F is a $n \times n$ matrix and P, Q are well-defined subspaces of the state space. A glance at theorems 2,3 will indicate that the matrices $A, BCA^{j-1}, \Gamma_j, k \leq j \leq \hat{k}$ play a fundamental role in the root-locus theory. Writing,

$$\Gamma_j = [B, AB, \dots, A^{j-1}B] \begin{bmatrix} CA^{j-1} \\ CA^{j-2} \\ \vdots \\ CA \\ C \end{bmatrix} \quad \dots (70)$$

it is seen that the controllability and observability matrices play an important role in determining the structure of the root-locus. Further work could relate the structure of the root-loci to parameters defining controllability and observability, provide valuable insight into difficulties occurring in pole allocation and suggest new algorithms for the calculation of the system asymptotes.

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