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- 7
- 8 Chloe Bellamy, Christopher Scott & John Altringham
- 9 School of Biology, University of Leeds
- 10 <u>bsccb@leeds.ac.uk</u> <u>c.d.scott@leeds.ac.uk</u> <u>j.d.altringham@leeds.ac.uk</u>
- 11 Corresponding author:
- 12 John Altringham j.d.altringham@leeds.ac.uk
- 13 School of Biology, Faculty of Biological Sciences, University of Leeds, Leeds, LS2 9JT
- 14 Tel. +44 (0)113 343 2832
- 15
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24 Summary

1. To manage anthropogenic environmental change for the benefit of biodiversity we must improve our
understanding of the complex relationships between organisms and their environment. We have
developed multiscale habitat suitability models (HSMs) for bats, a mobile group of mammals, for a
geographically varied region of the UK. We ask if the models have sufficient accuracy to contribute to
informed decision-making in habitat management and in minimizing the impact of climate change and
human infrastructural development.

- 31 2. We used acoustic surveys supplemented by catching to gather presence data for eight species from 32 30 sites across the south of the Lake District National Park in NW England. Species were identified by 33 manual and automated extraction and analysis of echolocation calls. Fine-resolution (50 and 100 m) 34 habitat maps were generated at twelve spatial scales by calculating the variables across squares of 35 increasing size, from 100–6000 m, around each focal 50 or 100 m square. Presence-only HSM software, 36 MaxEnt, was used to determine the predictive power of each habitat variable at each scale. Multiscale 37 models included data for each variable at the scale at which it had the strongest relationship with the 38 presence of each species.
- 39 3. The best multiscale models were selected using 5-fold cross-validation, with backwards, stepwise

40 variable removal, whilst minimising residual spatial autocorrelation and sampling bias. Further tests with

41 independent field data indicated good model transferability across the entire National Park.

42 4. Foraging bats were generally most strongly associated with variables measured at small spatial scales

43 and distance measures. However, each species responded differently across the range of scales, and

44 strong associations were also found at the largest scale of analysis (6000 m).

45 5. Synthesis and applications. The best models for determining habitat suitability had few variables,

46 making them easy to interpret and use in practical conservation planning. The approach is applicable to

47 any taxa for which reliable presence records are available, providing insight into the potential impacts of

48 land use and environmental change. Maps identify areas of conservation concern, such as hotspots for

- 49 diversity, rare or vulnerable species and potential or threatened network corridors, making them useful
- 50 for ecological impact assessment of proposed developments, and to conservation managers planning
- 51 habitat creation or improvement.

53 Key words

- 54 Bats, Habitat Suitability Model, MaxEnt, multiscale model, presence-only model, spatial scale, Species
- 55 Distribution Model

56 Introduction

57 To protect our natural heritage in the face of climate change and increasingly intensive land-use, conservation 58 management must operate on a landscape scale (e.g. Lindenmayer et al. 2008; Heller & Zavaleta 2009; Lawton 59 et al. 2010). In addition to retaining and managing existing protected areas, we must improve the ecological 60 connections between them and, where possible, improve the surrounding matrix of agricultural and urban 61 landscapes. This management, whether for a species, community or ecosystem, should be driven by an 62 understanding of how the target species interact with their abiotic and biotic environment, since it is by 63 changing this environment that management is achieved. To develop the best management solutions, we need 64 to be able to predict the consequences of performing a particular task in a particular place. This could be 65 deciding where to plant new woodland, or choosing the line of a new road to cause minimal ecological 66 disturbance. This requires tools that facilitate decision-making in complex environments at a landscape scale. 67 This paper uses bats to explore the usefulness of Habitat Suitability Modelling (HSM, or Species Distribution 68 Modelling, SDM), generated by the program MaxEnt, as such a tool.

69

70 Habitat Suitability Modelling is a statistical technique that predicts the distribution of a species over large areas 71 from environmental data and occurrence records. It has been usefully applied using few presence-only data 72 (e.g. Pearson et al. 2007), giving it considerable potential in practical conservation, since large 73 presence/absence datasets are frequently unavailable or unreliable. GIS-based HSM can produce large extent, 74 fine-resolution maps that encapsulate many of the interactions between species and environment. Maps can 75 be generated from small datasets, are easily interpreted by conservation practitioners, and can be updated 76 easily. However, HSMs can also have poor, and often over-estimated, predictive performance, due to residual 77 spatial autocorrelation in the data, sampling bias, and inadequate testing with independent data (Phillips et al. 78 2009; Veloz 2009; Merckx et al. 2011). Residual spatial autocorrelation (rSAC) can result from factors not 79 studied, such as a species' gregariousness, or when distribution is not adequately explained by the ecological 80 variables in the model. Use of spatially autocorrelated data violates the assumptions of many tests. We 81 explicitly test the effects of failing to account for these in models.

83 The interaction between an organism and its environment occurs on many scales (e.g. Wiens 1989). In the case 84 of bats, habitat choice on a small scale is typically driven by the constraints of echolocation and flight: 85 extremes include slow flying bats that feed by gleaning from the leaves and trunks of woodland trees and bats 86 adapted for aerial hawking during rapid, efficient flight in the open. The distribution of many of the 87 invertebrates that bats feed on is also likely to be determined by fine scale factors: insects with aquatic larvae 88 will be close to water, flying insects more often in the lee of woodland trees. On a larger scale, the presence or 89 absence of a species in a locality will be determined by such factors as woodland perimeter for edge habitat 90 specialists, the permeability of the typically 'disturbed' landscape between their multiple roosts and foraging 91 sites, and the distances between summer roosts and hibernacula. Our ecological understanding may therefore 92 need to encompass many scales. To date, most studies on foraging bat-habitat relationships have been at a 93 fixed spatial scale (e.g. Jaberg & Guisan 2001; Wickramasinghe et al. 2003; Rebelo & Jones 2010; Rainho & 94 Palmeirim 2011). These studies tell us which habitat factors are important determinants of bat-habitat 95 suitability, but only in relation to the scale considered. Multiscale models are now being used and a recent 96 paper by Razgour, Hanmer & Jones (2011) used such models to predict the distribution of a rare UK bat.

97

We have used field data collected specifically to develop multiscale HSMs for eight bat species in the Lake District National Park, NW England. Our aims were two-fold. (1) To investigate multiscale species-habitat relationships and provide accurate and easily interpretable habitat suitability maps for environmental impact assessment and conservation management. (2) To explicitly test the effects of sampling bias and rSAC on measures of model performance. The work thus serves as a template for HSMs for temperate bats in general, and since bats are increasingly recognised as good bioindicators (Jones *et al.* 2009) the maps have value beyond bat conservation.

105

106 Materials and methods

107 STUDY SITES AND SPECIES

The study was carried out in the Lake District National Park, NW England (subsequently referred to as "Park";
Fig. 1). It has wide post-glacial valleys filled with a rich mosaic of woodland, plantations, lakes, farmland and

110 open grassland, turning into moorland and rocky, mountainous terrain at higher elevations (up to 977 m a.s.l.).

111 Built areas vary from scattered farms linked by unlit tracks to small towns and well-lit, busy roads. Nine bat 112 species were recorded: Pipistrellus pipistrellus, P. pygmaeus, Plecotus auritus, Myotis daubentonii, M. 113 nattereri, M. brandtii, M. mystacinus and Nyctalus noctula and the locally rare N. leisleri. We used acoustic surveys to gather presence from thirty 1-km² sites across the southern part of the Park from May to August 114 115 inclusive in 2008 and 2009, walking two transects in each site each year (Fig.1 and Supplementary Appendix S1). Sites were chosen by aligning a 5 x 6 grid of 25 km² squares with the Ordnance Survey grid. At the centre 116 117 of each 25-km² square was the 1-km² study site, making the sites 5 km apart, centre to centre. Two sites were 118 repositioned to overcome access problems. Sites were highly varied in habitat composition, structure and 119 altitude. Within each site, 2–3 km transects encompassed this variation. Full transect methodology is given in 120 S1. Species were identified by manual and automated extraction and analysis of full-spectrum echolocation 121 calls (S1). We captured bats to obtain additional data from Plecotus auritus since their low intensity calls are 122 difficult to detect. Bats were captured as a component of other work at a single woodland site in over half of 123 the study squares, using mist nets and harp traps. To assess how robust models were to geographic transferral, 124 we collected independent data using the same methods in eight sites west and north of the training sites, 125 selected to encompass a range of habitat types (Fig. 1, S1).

126

127 ENVIRONMENTAL VARIABLES

GIS data from multiple sources were used to create gridded environmental variables (50 or 100 m resolution
rasters; Tables S1.1–1.3). Data were validated by comparing them with recent (2005) aerial photographs,
provided by Natural England. GIS manipulation was performed in ArcGIS 9.3 (www.esri.com). In brief, two nonscalar environmental variables were used in each model (distance to water and woodland edge) and all other
variables were measured at 12 scales (100–6000 m) by measuring cell statistics within different sized windows
centred on each raster cell using the focal statistics tool (details in S1).

135 MODELLING

136 Model fitting

137 MaxEnt is a program that predicts the geographical distribution of a species based on the environmental

138 conditions at locations where the species is known to occur, using the maximum entropy method (Phillips,

139 Anderson & Schapire 2006). All models were run in MaxEnt Version 3.3.3e

- (http://www.cs.princeton.edu/~schapire/maxent), using primarily default settings and one species record per
 cell (see S1). Models were evaluated using 5-fold cross validation: study site data were randomly partitioned
 into five roughly equal subsets, four being used to train a model and one to test the model. The process was
 repeated five times, using a different subset each time for testing, and the results averaged.
- 144

145 Sampling bias and spatial autocorrelation

146 Moran's correlograms were used to check for significant spatial autocorrelation of residuals (1 – predicted HSI

for each species record; de Marco, Diniz-Filho & Bini 2008) using Spatial Analysis in Macroecology (SAM;

Rangel, Diniz-Filho & Bini 2006). Significance of Moran's I was calculated using a randomisation test with 9,999

149 Monte Carlo permutations, correcting for multiple testing. If significant residual spatial autocorrelation (rSAC)

150 was detected we spatially constrained testing and training data: the first distance lags found to be positively

151 spatially autocorrelated were used to set a distance threshold and data pairs closer to each other than this

were placed in the same data partition (Parolo, Rossi & Ferrarini 2008). Models were also run using random 5-

153 fold cross validation for comparison.

154

To prevent MaxEnt from using background data from environmental conditions outside the range sampled, we included a mask, forcing MaxEnt to calibrate models with data from each field site and a surrounding 0.5-km buffer. To factor out any bias introduced by sampling habitats more or less often than they were available within these sites, a bias file was created by scoring cells every time they were sampled by either a transect or catching. When given the data, MaxEnt will correct for non-uniform sampling effort (Dudík, Schapire & Philips 2005).

161

Models were also run without measures to counteract sampling bias and rSAC, to explicitly determine the consequences. We hypothesised that this would result in falsely inflated measures of test performance. This was analysed using paired t-tests on Area Under Curve (AUC) scores, the most commonly used HSM performance parameter (Merckx *et al.* 2011; Parolo, Rossi & Ferrarini 2008) and assessing changes in individual variable performance with and without measures to control for sampling bias for selected species (details in S1). AUC measures the probability that a randomly chosen presence point will rank above a randomly chosen background point (AUC = 0.5 = random; the closer to 1.0 the better the discrimination).

Presence-only models vary in their maximum achievable AUC between species because of differences in the
likelihood that background samples will be drawn from suitable habitat (Phillips, Anderson & Shapire 2006).

171 Although this limits the ability to contrast model performance between species, scores can be used for

172 comparing the performance of model settings and parameters for a particular species. Other measures of

accuracy are available and are discussed in depth by Elith & Graham (2009).

174

175 From univariate to multivariate models

176 The predictive power of environmental variables was assessed using the MaxEnt jackknife measure of test 177 AUC. The scale at which an environmental variable had the highest test AUC in a univariate model was entered 178 into a species' multivariate model, to create 'full models' of all variables at their best performing scale. 179 Environmental variables with test AUC ≤0.5 were removed and those remaining were checked for 180 multicollinearity (r ≥ 0.70) using ENMTools (www.ENMTools.com; Warren, Glor & Turelli 2008; 2010). Collinear 181 variables were pruned by retaining those with higher test AUC scores. Models were further pruned to yield a 182 set of variables with the highest predictive power, using a jackknife, leave-one-out stepwise approach (Parolo, 183 Rossi & Ferrarini 2008). Environmental variables causing the smallest decrease (or largest increase) in test AUC 184 when removed were pruned in turn until only one environmental variable remained. The 'pruned model' with 185 the highest test AUC was used for further analysis. The contribution each remaining environmental variable 186 made to a species' pruned model was determined by randomly permuting the value of each environmental 187 variable in turn at the presence and background locations and re-testing the model. The resulting, normalised 188 drop in training AUC was compared between variables (Phillips 2011).

189

190 Model selection

191 The fit of full and pruned models were compared using Akaike Information Criteria corrected for small sample 192 sizes (AICc), in ENMTools (Warren & Seifert 2011). Models for each species were ranked by calculating the 193 difference (Δ AICc) between a model's AICc and the minimum AICc (minAICc). Models were considered 194 equivalent if Δ AICc was \leq 2 values of the minAICc model, or potential alternatives if \leq 10 of minAICc (Burnham 195 & Anderson 2002). AICc was calculated using all records unique to a single raster cell from study and test sites 196 separately. We could only assess fit when a species sample size was greater than the number of model 197 parameters (Burnham & Anderson 2002).

199	Model transferability: evaluation using independent data
200	Models were trained with all data and predictions were projected to the entire Park. Their performance was
201	assessed with new, independent field data from test sites. AUC was calculated in R (version 2.12.2, package
202	ROCR; Sing et al. 2009), comparing Habitat Suitability Index (HSI) values at presence sites (one species record
203	per cell) and at each cell within the eight test sites plus a 0.5-km buffer (background HSI values). Data were
204	bootstrapped 2,000 times to generate 95% confidence intervals. We created multivariate environmental
205	similarity surface (MESS) maps for the Park to highlight areas with habitat values outside the range
206	encountered within the study sites (Elith, Kearney & Phillips 2010; Rodda, Jarnevich & Reed 2011).
207	
208	Pruned models have been found to perform better on independent test data, suggesting that they may be less
209	prone to overfitting (Parolo, Rossi & Ferrarini 2008). One-tailed paired t-tests, comparing species' distributions
210	predicted by the full and pruned models within the study and test sites, examined whether model pruning
211	resulted in higher test AUC values, larger areas of suitable habitat, and lower and more statistically significant
212	extrinsic omission rates after accounting for the size of the suitable area (lower binomial test <i>P</i> -values). The
213	extrinsic omission rate is the proportion of all test points that fall outside the area predicted to be suitable for
214	the species.
215	
216	Plecotus auritus, a special case
217	Due to the low intensity of <i>P. auritus</i> echolocation calls we recorded only eight independent bat passes. This
218	species was therefore modelled using records from all 38 study and test sites, incidental records made during
219	other fieldwork and reliable county records. A target background approach was adopted rather than a bias file
220	(Phillips et al. 2009). We used 9,827 six-figure grid referenced mammal records held by the county records
221	office to extract background data (pseudoabsences) and a 100 x 100 m resolution. The principle is that these
222	records will have been collected using similar, and therefore similarly biased, methods to the bat records so
223	that differentiation between bat habitat and background is possible.
224	

225 Estimating species richness

Species' habitat suitability maps were combined in ArcGIS to generate richness maps. Each species' binary
presence-absence (suitable-unsuitable habitat) maps, generated by two threshold rules, were overlaid to
estimate the number of species predicted to be present at each cell. The Minimum Training Presence (MTP)
threshold uses the lowest predicted HSI value for a known species location in the training data, and therefore
always has a training omission rate of zero. The tenth percentile rule discards the lowest ten percent of
predicted habitat suitability indices at training locations, so that ten percent of training locations fall outside of
the suitable area. Alternative threshold rules are discussed in Liu *et al.* (2013).

233 Results

234

Presence data are summarised in Table S2.1. *Pipistrellus* records accounted for approximately 75% of all recordings. Since *N. leisleri* is rare in the study area we assumed all *Nyctalus* calls were *N. noctula*. Models built with random and spatially constrained data showed significant rSAC between data pairs at ≤3,000 m, i.e. those within a study site. Since all data from separate sites were separated by ≥4,000 m, data from within each site were placed in the same 20% partition of the data for 5-fold cross validation. *P. auritus* were modelled using random 5-fold cross validation because residuals were not found to be spatially autocorrelated.

241

242 UNIVARIATE SPECIES-HABITAT ASSOCIATIONS

243 Figure 2 shows the strength of association (test AUC as an estimate of predictive power) from univariate 244 models, across the scales, between each species. Only the most important environmental variables are shown, 245 those retained in the final, multivariate pruned models. Further results are shown in Appendix S2, Fig. S2.1, in 246 the online Supporting Information. Representative MaxEnt response curves in Fig. 3 show the relationship 247 between the probability of a species presence and the values of the more important environmental variables. 248 Generally, habitat features measured at 100–500 m scales were the most important predictors of foraging 249 habitat suitability (Fig.2, Fig.S2.1), but there was considerable variation between species and variables. Most 250 species had strong, positive associations with cover of inland water (Fig. 2), and were negatively associated 251 with slope (Fig. 3c) and distance to woodland edge and water (Fig. 3 a, b). Deciduous woodland cover was also 252 a strong, positive predictor (Fig. 3d). Bats responded in more complex ways to other variables, such as cover of 253 roads and buildings (Fig. 3e, f).

255 Pipistrellus species showed similar associations across scales, but variable predictive power was usually higher 256 for P. pygmaeus. Power tended to decrease with increasing scale, although slope maintained a strong negative 257 association across scales. P. pygmaeus had an association with most environmental variables at small spatial 258 scales, but was most likely to be found within short distances of woodland edge and water in areas with high, 259 small scale, deciduous woodland cover and medium woodland edge densities. It was positively related to 260 water cover at all scales < 6,000 m, but this relationship was strongest at 1,000–1,500 m. P. pipistrellus showed 261 the same relationships with woodland edge distance and density. Small-scale road, building, and water cover 262 were the only other useful (positive) habitat predictors for this species.

263

The cover of water (positive) and average slope (negative) were important predictors for all *Myotis* species at small scales. The distance to water (negative), and the cover of roads (negative) and ancient woodland (positive) were also useful predictors for *M. nattereri*. Altitude (negative), distance to water and woodland edge (negative) and deciduous woodland cover (positive), had a strong association with *M. daubentonii* presence, and *M. brandtii/mystacinus* were strongly associated with areas close to woodland edge with medium densities of this edge habitat within small extents (≤ 500 m).

270

Nyctalus noctula presence was best predicted by altitude (negative at all scales, but strongest ≥ 1,000 m) and
 road cover (positive, small scales). Deciduous woodland cover (positive) and structural variables (all negative:
 richness, woodland edge density and maximum woodland patch) were most important at small scales (200–
 1,000 m).

275

P. auritus presence was strongly and negatively associated with slope at all scales. Variable importance
typically increased from 100 m to 400–500 m with little variation at larger scales. However, the positive effect
of building cover decreased with increasing scale, and the negative effect of water and positive effect of mixed
woodland became more important predictors at large scales. The positive relationships between *P. auritus* and
ancient woodland cover, deciduous woodland cover and maximum woodland patch size were strongest at
small scales.

282

283 MULTIVARIATE MODELS

284 Only the final pruned models are discussed here. A comparison of the performance of full and pruned models 285 can be found in S2. Removing poor performing variables and subsequent pruning significantly increased 286 model performance in study sites (test AUC increase = 0.20 ± 0.13 (mean \pm s.d.); test gain = 0.90 ± 0.53 ; Fig. 4; 287 Table S2.2). This process also increased the area predicted to be suitable for each species by a mean of 7.8% 288 (MTP) and 12.7% (tenth percentile), suggesting pruning reduced overfitting (Tables S2.2, S2.3). Extrinsic 289 omission rates fell from 9–36% to 0.002–8% (MTP) and from 29–73% to 8–22% (tenth percentile). Binomial 290 test P-values also decreased significantly between full and pruned models, with fewer test points falling 291 outside the suitable area than predicted by chance alone.

292

293 rSAC and sampling bias

294 The final models we present minimise the effects of rSAC and sampling bias. Failing to control for rSAC in full 295 models (random cross-validation) significantly decreased training AUC (0.017 ± 0.02) and inflated test AUC 296 (0.198 ± 0.10) relative to models with spatially constrained testing and training data (Table S2.4 & S2.5). A 297 similar, significant increase in test AUC scores (0.104 ± 0.05) was found when the spatially constrained models 298 were run without the bias file. Training AUC also increased slightly, but not significantly. The selection of 299 random background data for P. auritus, rather than accounting for bias using the target background approach, 300 resulted in higher model training and test AUC (Table S2.4). Only small changes in the predictive power of all 301 variables in the full P. pipistrellus model were found on removal of the bias file, whereas use of a random 302 background increased test AUC for all variables in the P. auritus model, except coniferous woodland (Table 303 S2.6).

304

305 Environmental variables in the pruned models

The pruned models with the highest test AUC retained only 2–4 primarily small scale variables and at least one distance variable (Fig. S2.2). *Pipistrellus* pruned models contained only 2–3 variables (Fig. 2), with distance to woodland edge contributing 74% to *P. pygmaeus* and 64% to *P. pipistrellus* pruned models. The importance of water to *P. pygmaeus* was evident in the contributions made by large scale water cover and distance to water. The *P. pipistrellus* model included a positive effect of small scale (100 m) road cover. However, only roads close to woodland (<100 m) increased habitat suitability and roads >500 m from woodland decreased suitability. 312 Myotis pruned models contained similar environmental variables: all included distance to water or woodland 313 edge, and small scale (100-500 m) variables describing slope, water cover, and woodland composition or 314 structure (Fig. 2). Distance to woodland edge contributed 73% to the M. brandtii/mystacinus model, and 315 woodland edge density was the next most important variable (Fig. S2.2). Distance to water made the highest 316 contribution to the *M. daubentonii* model and high deciduous woodland cover (200 m) was also important. 317 Water cover was an important positive predictor of *M. nattereri* presence at the 100 m scale. However, the 318 distance to water response curve suggests that the species forages close to, but not over water, preferring flat 319 areas of ancient woodland (Fig. S2.2). The last variable to be pruned from the N. noctula model was average 320 altitude measured at 4,000 m. Favoured habitat is land <250 m a.s.l. with small woodland patches (500 m), ~1 km km⁻² of woodland edge (400 m), and high road cover (200 m)(Fig. S2.2). The variable response curves for *P*. 321 322 auritus indicate a preference for areas with high mixed woodland and low water cover (5,000 m), close to 323 buildings on landscapes with gentle slopes (1,000 m) (Fig. S2.2).

324

325 MODEL TRANSFERABILITY

Pruned models performed well within new field sites (test AUC: 0.70–0.84). The pruned models gave the highest test AUC scores, except for *N. noctula* and *M. brandtii/mystacinus*, when full models had slightly higher test AUCs (Table S2.7). Low MTP thresholds produced larger areas of suitability and lower extrinsic omission rates for independent data than the tenth percentile rule (Table S2.7). Error rates were lower than expected by chance for 11 out of the 12 full and pruned species models using the tenth percentile rule, indicating good model performance. Pruning significantly increased the area predicted to be suitable for a species and decreased extrinsic omission rates (Fig. S2.3; Table S2.8).

333

334 MODEL SELECTION

AICc results indicate that *Pipistrellus* pruned models fitted better to independent test data compared to full
models (Table S2.9). Although we were not able to perform this test on other species' independent data
because their sample size outweighed the number of model parameters, we were able to show that all
species' pruned models fit best to their training data (Table S2.9). This illustrates the positive effect of pruning
on model transferability.

341 HABITAT SUITABILITY MAPS

342 Pruned, multiscale models were used to create habitat suitability maps for all seven species or species groups. 343 The maps (Fig. 5) show that the lowland networks of inland water and woodland were most suitable for most 344 species. This pattern was emphasised by the species richness maps (Fig. 6). The lower MTP threshold 345 generated more generous predictions of species richness across the Park compared to the tenth percentile 346 threshold. Less than 0.1% of the Park held environmental conditions outside the range recorded in the training 347 sites. 348 349 Discussion 350 351 We built useful habitat suitability models for eight species of UK bat from data collected on acoustic transects. 352 The best results were obtained from multiscale models from which poor predictor variables had been removed 353 and backward stepwise deletion had identified the most useful subsets of variables. Steps taken to minimise 354 sampling bias and residual spatial autocorrelation led to significant improvements. Final models for the study 355 area, when tested using independent field data, had test AUCs in the range 0.70-0.84, making them useful 356 predictors of bat distributions. The small number of variables in the final models makes them easier to 357 interpret by practitioners when using them to inform planning or practical management decisions. A 358 discussion of the more technical aspects of the modelling process will be found in Appendix S2 and this 359 discussion will focus on the ecological and practical aspects of the study. 360 361 SPECIES-HABITAT RELATIONSHIPS AND THE IMPORTANCE OF SCALE. 362 Presence was best predicted by a set of variables that varied significantly between species. However, water 363 and ancient and deciduous woodland variables were generally the most important positive predictors of 364 habitat suitability in univariate tests and the pruned models of most species included these variables. It is 365 striking how similar the responses are among species for many variables. For example the probability of

- 366 occurrence decreased with distance to water in all species in a very similar way (Fig.3a), yet the community
- 367 includes a fast open-air forager (*N. noctula*), a trawler (*M. daubentonii*) woodland gleaners (e.g. *M. nattereri*)
- 368 and a generalist (*P. pipistrellus*). Several ecologically different species also show a similar relationship with

deciduous woodland cover (Fig. 3d). This indicates that many habitat management interventions have thepotential to benefit broad communities, not just individual species.

371

372 Woodland structure (distance to woodland, woodland edge density, patch size) was particularly important at 373 small spatial scales. In common with most small insectivorous bats, the species studied typically forage within 374 1–3 km of their roost, rarely more than 6 km, and once established at a foraging site, many occupy 'beats' of 375 less than 100 m (e.g. Senior, Butlin & Altringham 2005). The strongest relationships with environmental 376 variables were typically observed at smaller spatial scales (100–500 m), coinciding with foraging beat and small 377 home range distances (see e.g. Graf et al. (2005) who drew similar conclusions for capercaillie). Small-scale 378 bat-habitat relationships will therefore reflect the decisions made by bats from local roosts on where to feed 379 within their home range. Relationships at larger scales are more likely to reflect the 'carrying capacity' of a 380 locality: how many colonies, of what size, an area can support. However, with the ability to fly, bats can exploit 381 patchily distributed resources, so small areas of suitable habitat may still be important (and should be 382 conserved), particularly in marginal habitat (Gorresen & Willig 2004; Meyer & Kalko 2008). Because different 383 processes may be operating at different scales, it is not surprising that the relative importance of variables 384 often changed with scale. For example, in the N. noctula model, area of road cover and urban development 385 becomes less important, and altitude more important, with increasing scale. Deciduous woodland cover and 386 woodland edge density show more a complex, but similar pattern.

387

388 Road and urban cover was a useful predictor at small scales: positive for N. noctula and Pipistrellus, negative 389 for Myotis and P. auritus. As road cover increased above 5–10% it became a negative predictor for most 390 species at large scales, highlighting the complex relationships bats have with roads. Bat activity and diversity 391 are reduced by major roads, probably through a barrier effect (Berthinussen & Altringham 2012). However, 392 the hedges and woodland lining many of the predominantly minor roads in the study area are utilised by open-393 air foragers such as N. noctula and Pipistrellus. Woodland bats, such as many Myotis and Plecotus species, are 394 likely to avoid all but the most minor roads, since roads are associated with high levels of noise, light and open 395 space (Stone, Jones & Harris 2009; Siemers & Schaub 2011). Dense road cover, however small the roads may 396 be, is associated with urban development, habitat loss and disturbance, so it is not surprising that all species 397 avoid such areas. All species had a negative relationship with altitude, which is not surprising since higher

altitudes at the latitude of the study are associated with lower temperature, higher wind speed and higher
rainfall. However, the only pruned model to retain altitude was that of *N. noctula*, in which it was an important
negative predictor. Because *N. noctula* is a large bat that feeds in the open, it may be particularly prone to
these climatic effects. It should not be forgotten that the two scale-independent variables, distance to
woodland and water, were important components of most species' models.

403

404 SPECIES RICHNESS PATTERNS

405 Richness maps based on presence should be interpreted with the occupancy thresholds in mind. The MTP 406 threshold is low for all species, suggesting large portions of the study area were suitable habitat. The tenth 407 percentile threshold is probably more useful at identifying critical foraging habitat. Generating species richness 408 maps by overlaying species HSM maps may overestimate richness since factors that limit species distributions, 409 such as competition and dispersal, are not accounted for (Graham & Hijmans 2006), but these effects are not 410 likely to be significant for bats (e.g. Bloch, Stevens & Willig 2011), and indeed more intensive survey work may 411 increase species richness (e.g. MacSwiney, Clarke & Racey 2007). Species richness is, as expected, high in the 412 lower elevation valleys that hold most of the woodland and water. The south-east quadrant of the study area 413 is strikingly rich compared to other areas, reflecting the generally lower elevations and the abundance of 414 woodland patches of varying size. This is despite the higher (although still low) human population density with 415 its associated development.

416 417

418 Conclusions, recommendations and applications

419 We have shown that useful bat HSMs can be built across a large and diverse area based on relatively limited 420 data collected on acoustic transects. Multiscale HSMs perform better than single scale models and will 421 therefore have greater practical value. Model building should account for sampling bias and spatial 422 autocorrelation. The most important variables for most species relate to distance to and coverage of woodland 423 and water. Our study provides a methodology for future bat population monitoring and the updating and 424 refining of the maps. The methodology also provides a template for mapping projects for a wide range of 425 localities and taxa. How can the maps and models be used? In scientific terms, the models improve our 426 understanding of how bats use large and complex habitats and help us to predict the consequences of climate 427 change and more direct anthropogenic alteration of the landscape. Conservation practitioners can make use of 428 the maps in several ways. Cost path analysis can identify the least disruptive routes for new or upgraded roads, 429 or locations for new developments that minimise impact. The maps can also be used to make more informed 430 judgements about the most effective mitigation methods and locations by modelling proposed changes in the 431 landscape. HSMs can be used in opportunity mapping for planning both large- and small-scale habitat 432 management for maximum effectiveness by identifying, for example, critical locations for corridors and 433 networks, hotspots for diversity and the location of rare or vulnerable species. The maps can also help in the identification of unknown populations of rarer species (e.g. Razgour, Hanmer & Jones 2011), or in the 434 435 identification of sites for reintroduction.

- 436
- 437

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447

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537

538 Fig. 1. (a) Lake District National Park, showing 5 km buffer, major lakes, relief, and study and test sites. (b)

539 Typical transect, showing route and bat records. An Ordnance Survey/EDINA supplied service © Crown

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and JISC, boundary material © Crown Copyright and the Post Office.



- Fig. 2. The strength of association (as test AUC) between each species' presence and individual environmental variables at different spatial scales. The average predictive power of
- 544 the distance variables is shown as a dashed line: these were independent of scale. Environmental variables with a predictive power < 0.5 are no better than random. Only variables
- 545 retained in pruned models are shown (see S2 for others). NB. The scale range is not linear for improved clarity at small scales.



- 547 Fig. 3. Representative MaxEnt response curves showing the probability of a species' presence at a
- 548 location for a range of parameters. (d) shows response curves at a species' best performing small scale
- 549 (100–500 m). These graphs are based on univariate models to prevent interacting or collinear variables
- 550 from affecting the relationships modelled. Variables found to have poor predictive power at a particular
- scale (AUC \leq 0.5) are not shown.



553 Fig. 4. Effect of model pruning on test AUC scores after removal of collinear variables and poor predictors







556 Fig 5. Habitat suitability maps made using each species' pruned set of variables. Novel conditions are areas

557 containing variables outside of the range on which a model was trained. HSI = Habitat Suitability Index.



- 559 Fig.6. Species richness maps using occupancy thresholds MTP (a) and tenth percentile (b).
- 560
- 561 Supporting Information
- 562 Additional Supporting Information may be found in the online version of this article:
- 563 Appendix S1: Methods.
- 564 **Appendix S2:** Results and technical discussion