

This is a repository copy of Asymptotic Root-Loci of Linear Multivariable Systems: Geometric Analysis.

White Rose Research Online URL for this paper: http://eprints.whiterose.ac.uk/75816/

Monograph:

Owens, D.H. (1976) Asymptotic Root-Loci of Linear Multivariable Systems: Geometric Analysis. Research Report. ACSE Report 40 . Deoartment of Control Engineering, University of Sheffield, Mappin Street, Sheffield

Reuse

Unless indicated otherwise, fulltext items are protected by copyright with all rights reserved. The copyright exception in section 29 of the Copyright, Designs and Patents Act 1988 allows the making of a single copy solely for the purpose of non-commercial research or private study within the limits of fair dealing. The publisher or other rights-holder may allow further reproduction and re-use of this version - refer to the White Rose Research Online record for this item. Where records identify the publisher as the copyright holder, users can verify any specific terms of use on the publisher's website.

Takedown

If you consider content in White Rose Research Online to be in breach of UK law, please notify us by emailing eprints@whiterose.ac.uk including the URL of the record and the reason for the withdrawal request.



eprints@whiterose.ac.uk https://eprints.whiterose.ac.uk/

ASYMPTOTIC ROOT-LOCI OF LINEAR MULTIVARIABLE

SYSTEMS: A GEOMETRIC ANALYSIS

1.1

D. H. Owens, B.Sc., A.R.C.S., Ph.D., AFIMA

Lecturer in the Department of Control Engineering University of Sheffield Mappin Street Sheffield S1 3JD

Research Report No.40

January 1976

Abstract

1

Recent results on the asymptotic behaviour of the root-loci of a linear time-invariant system S(A,B,C) are formulated in geometric terms and equivalent results obtained in two cases of practical interest in terms of the matrix coefficients in the expansion of $(A-pBC)^{\ell}$, $\ell \ge 1$.

1. Introduction

A recent paper (Shahed and Kouvaritakis, 1976) presented a theoretical analysis of the asymptotic behaviour of the eigenvalues of the linear, time-invariant system S(A,B,C)

$$\dot{x} = Ax(t) + Bu(t) , \quad u(t) \in \mathbb{R}^{m} , \quad x(t) \in \mathbb{R}^{n}$$

$$y(t) = Cx(t) , \quad y(t) \in \mathbb{R}^{m}$$
...(1)

when subject to unity negative feedback with scalar gain $p \ge 0$. The closed-loop system takes the form

$$\dot{x}(t) = {A-pBC}x(t)+Br(t)$$

y(t) = Cx(t) ...(2)

Previous work (Shaked and Kouvaritakis, 1976) used determinantal manipulation techniques to obtain explicit formula for the asymptotic directions and pivots of the root-locus. This paper describes some solutions of this problem by geometric analysis of the closed-loop eigenvalue equation

$$\{s(p)I_n - A + pBC\}x(p) = 0$$
, $||x(p)|| = 1$, $p \ge 0$...(3)

and the identification of the asymptotic directions and pivots in terms of the structural properties of the matrix coefficients in the expansion of $(A-pBC)^{\&}$, $l \ge 1$.

2. Asymptotic Behaviour of Closed-loop Eigenvectors

Let $\{p_j\}_{j\geq 1}$ be an unbounded sequence of positive real numbers and $\{s(p_j)\}_{j\geq 1}, \{x(p_j)\}_{j\geq 1}$ a corresponding sequence of closed-loop eigenvalues and eigenvectors respectively. By extraction of a suitable subsequence, it is possible to assume that

$$\lim_{j \to \infty} x(p_j) = x_{\infty} , \qquad ||x_{\infty}|| = 1 \qquad \dots (4)$$

If R(Q), N(Q) denote the range and null space of a matrix Q, then Theorem 1

(a) If the sequence $\{|s(p_i)|\}_{i \ge 1}$ is unbounded, then $x_{\infty} \in R(B)$.

(b) If the sequence $\{s(p_j)\}_{j \ge 1}$ has a finite cluster point λ , then $x_{\infty} \in W_{B}$, where (Owens, 1975) W_{B} is the maximal subspace of N(C) satisfying the relation $AW_{B} \subset W_{B}+R(B)$.

Proof

To prove (a), divide equation (3) by s(p), from which $\begin{aligned} x_{\infty} &= \lim_{j \to \infty} (s(p_j))^{-1} p_j BCx(p_j) \in R(B). \\ &\text{To prove (b), equation (3) implies that } (\lambda I_n - A) x_{\infty} = \lim_{j \to \infty} p_j BCx(p_j) \in R(B) \\ &\text{ie } x_{\infty} \in W_B. \end{aligned}$ ie $x_{\infty} \in W_B.$ Q.E.D.

3. Asymptotic Root-loci for Uniform-rank Multivariable Systems

To illustrate the general structure of the geometric relationships defining the asymptotic form of the system root-locus, consider the case of an open-loop system (equation (1)) satisfying the relations

$$CA^{j-1}B = 0 \qquad j < k$$
$$|CA^{k-1}B| \neq 0 \qquad \dots (5)$$

Equivalently, if $G(s) = C(sI_n - A)^{-1}B$ is the open-loop system transfer function matrix, then

$$G_{\infty}^{(k)} \stackrel{\Delta}{=} \lim_{s \to \infty} s^{k} G(s) = CA^{k-1}B \qquad \dots (6)$$

exists, is nonsingular and $|G(s)| \neq 0$. On intuitive grounds, the above relations imply that each loop has a dynamic behaviour analogous to a classical rank k transfer function and, as such, G(s) will be termed a uniform rank transfer function matrix and S(A,B,C) a uniform rank system.

The following theorem defines the asymptotic form of the root-locus plot in terms of the expansion of the matrix $(A-pBC)^{L}$. For convenience, define

$$\Gamma_{o} = 0$$
, $\Gamma_{\ell} = \sum_{j=1}^{\ell} A^{j-1} BCA^{\ell-j}$, $\ell \ge 1$...(7)

and note from condition (5) that

$$(A-pBC)^{\ell} = A^{\ell} - p\Gamma_{\ell} , \qquad 1 \leq \ell \leq k \qquad \dots (8)$$

and, from equation (7), by induction,

$$\Gamma_{0} = 0 \qquad \dots (9)$$

$$\Gamma_{j+1} = A\Gamma_{j} + BCA^{j}$$
$$= \Gamma_{j}A + A^{j}BC , \qquad j \ge 0 \qquad \dots (10)$$

Theorem 2

With the above notation, and S(A,B,C) of uniform rank, the closed-loop system S(A-pBC,B,C) has km unbounded poles of the form, $1 \le j \le m$, $1 \le l \le k$

$$\mu_{j\ell}(p) = p^{k} \eta_{j\ell} + \alpha_{j} + \varepsilon_{j\ell}(p) \qquad \dots (11)$$

where $\eta_{jl}, \ 1 \leqslant l \leqslant k$ are the kth roots of λ_j where λ_j is a non-zero solution of

$$\{\lambda_{j}\mathbf{I}_{n} + BCA^{k-1}\}\mathbf{x}_{\infty} = 0$$
, $\|\mathbf{x}_{\infty}\| = 1$...(12)

Also,

$$\lim_{p \to \infty} \varepsilon_{j\ell}(p) = 0$$

and if,

$$N(\lambda_{j}I_{n} + BCA^{k-1}) \cap R(\lambda_{j}I_{n} + BCA^{k-1}) = \{0\}$$
, ...(13)

then, the pivot α_i is a solution of the relation

$$\{k\alpha_{j} \cap A\}_{\infty} \in \mathbb{R}(\lambda_{j} I_{n} + BCA^{k-1}) \qquad \dots (14)$$

The remaining n-km poles tend to the zeros of S(A,B,C).

Proof

Equation (3) implies that

$$\{(s(p))^{\ell}I_{n} - (A-pBC)^{\ell}\}x(p) = 0 , \ell \ge 1$$
 ...(15)

or, by equation (8), for $1 \le l \le k$,

$$\{\frac{(s(p))^{\ell}}{p}I_{n} - p^{-1}A^{\ell} + \Gamma_{\ell}\}_{X}(p) = 0 \qquad \dots (16)$$

In an analogous manner to section 2, suppose that the family $\{x(p)\}$ has a cluster point $x_{\infty}(||x_{\infty}|| = 1)$ then

$$\lim_{p \to \infty} \frac{s(p)^{\ell}}{p} x_{\infty} = \Gamma_{\ell} x_{\infty} , \qquad 1 \le \ell \le k \qquad \dots (17)$$

Considering only unbounded eigenvalues, then (Theorem 1) $x_{\infty} \in R(B)$ so that (equations (5),(7))

$$\lim_{p \to \infty} \frac{s(p)^{\ell}}{p} = 0 \qquad , \qquad \ell < k \qquad \dots (18)$$

and,

- an - 8

$$\Gamma_{k} x_{\infty} = BCA^{k-1} x_{\infty} \neq 0 \qquad \dots (19)$$

..e (equation (17)) $\lambda_j \stackrel{\Delta}{=} \lim_{p \to \infty} p^{-1}(s(p))^k$ exists, is non-zero and is a solution of the eigenvalue equation (12). Write $s(p) = p^k \eta_{j\ell} + \psi_{j\ell}(p)$ where $\eta_{j\ell}^k = \lambda_j$ and

$$\lim_{p \to \infty} p^{\frac{1}{k}} \psi_{jk}(p) = 0 \qquad \dots (20)$$

It follows that

$$\lim_{p \to \infty} p^{\frac{1}{k}} \left\{ \frac{s(p)^{k}}{p} - \lambda \right\} x(p) = -\lim_{p \to \infty} p^{\frac{1}{k}} \left\{ \lambda_{j} + \Gamma_{l} \right\} x(p) \qquad \dots (21)$$

Writing (equation (10)) $\Gamma_k = A\Gamma_{k-1} + BCA^{k-1}$ and noting (equation (16)) that

$$\lim_{p \to \infty} p^{\frac{1}{k}} A \Gamma_{k-1} x(p) = -\lambda_{j}^{\frac{k-1}{k}} A x_{\infty} \qquad \dots (22)$$

then

$$\{\lim_{p\to\infty}p^{\frac{1}{k}}\left\{\frac{s(p)^{k}}{p}-\lambda_{j}\right\}I_{n}-\lambda_{j}^{\frac{k-1}{k}}A\}x_{\infty} = \lim_{p\to\infty}p^{\frac{1}{k}}\left\{\lambda_{j}+BCA^{k-1}\right\}x(p) \qquad \dots (23)$$

Using equation (13) and noting that $x_{\infty} \in N(\lambda, I_{j} + BCA^{k-1})$, it follows that $\lim_{p \to \infty} p^{k} (\frac{s(p)^{k}}{p} - \lambda_{j})$ exists, so that (equation (20))

$$\lim_{p \to \infty} p^{\frac{1}{k}} \left(\frac{s(p)^{k}}{p} - \lambda_{j} \right) = \lim_{p \to \infty} k \lambda^{\frac{k-1}{k}} \mu_{j\ell}(p)$$
$$= k \lambda^{\frac{k-1}{k}} \alpha_{j\ell} \qquad \dots (24)$$

for some finite scalar $\alpha_{j\ell}$. It is easily seen that $\alpha_{j\ell}$ is independent of ℓ and writing $\alpha_{j\ell} = \alpha_{j}$, equation (23) implies that

$$(k\alpha_{j} \Gamma_{n} - A) x_{\infty} \in \mathbb{R}(\lambda_{j} \Gamma_{n} + BCA^{k-1}) \qquad \dots (25)$$

as required.

Finally, it can be shown (Owens, 1975) that S(A,B,C) has n-km zeros, each of which (Shaked and Kouvaritakis, 1976) attracts a pole at high gain. Q.E.D.

The above theorem provides explicit geometrical conditions for the construction of the asymptotes of the root locus plot. For purposes of calculation, write $x_{\infty} = Bz$, then (equation (12)) as rank B = m (equation (5)), λ_i is the solution of the eigenvalue problem,

$$0 = \{\lambda_{j}I_{m} + CA^{k-1}B\}\alpha_{j}$$
$$= \{\lambda_{j}I_{m} + G_{\infty}^{(k)}\}\alpha_{j}, \qquad \alpha_{j} \neq 0 \qquad \dots (26)$$

Condition (13) is equivalent to the requirement that $G_{\infty}^{(k)}$ has a complete set of eigenvectors. To calculate the pivot, suppose that u_1, \ldots, u_k are linearly independent eigenvectors of BCA^{k-1} spanning the eigenspace corresponding to the eigenvalue λ_j , and let v_1^+, \ldots, v_k^+ be the corresponding dual eigenvectors satisfying $v_j^+ u_k = \delta_{j,k}$, then, if M_j is the kxl matrix with elements

$$(M_{.})_{j rq} = k^{-1} v_{r}^{+} Au_{q} , \qquad 1 < r, q < \ell \qquad \dots (27)$$

it follows that α_i is a solution of the eigenvalue equation

$$\{\alpha_{j}I_{\ell} - M\}\beta_{j} = 0 \qquad \beta_{j} \neq 0 \qquad \dots (28)$$

4. Asymptotic Root-loci for Non-uniform-rank Multivariable Systems

In more general situations (Shaked and Kouvaritakis, 1976) S(A-pBC,B,C)will have unbounded poles of various orders as $p \rightarrow +\infty$. The main result of this section (Theorem 3) provides a geometric characterization of the asymptotes of the root-locus in certain situations of practical interest, using relations analogous to those of Theorem 2.

Write, l≥1

$$(A-pBC)^{\ell} = \sum_{j=0}^{\ell} (-1)^{j} p^{j} B_{j,\ell} ... (29)$$

from which, by induction,

$$B_{01} = A$$
, $B_{11} = BC$... (30)

and, for $l \ge 1$,

$$B_{o,\ell+1} = AB_{o,\ell}$$

$$B_{j,\ell+1} = AB_{j,\ell} + BCB_{j-1,\ell} , \quad 1 \le j \le \ell$$

$$B_{\ell+1,\ell+1} = BCB_{\ell,\ell} . \quad \dots (31)$$

so that (equations (9), (10), (30)), for $l \ge 1$,

$$B_{o,l} = A^{l}$$
, $B_{1,l} = \Gamma_{l}$, $B_{l,l} = (BC)^{l}$... (32)

In a similar manner to equation (5), let k be the uniquely defined integer such that

$$CA^{j-1}B = 0$$
, $j < k$, $CA^{k-1}B \neq 0$...(33)

then (equation (8))

$$BC(A-pBC)^{\ell} = \begin{bmatrix} BCA^{\ell} & , & 0 \leq \ell < k \\ BCA^{k-1}(A-pBC) & , & \dot{\lambda} = k \end{bmatrix} \dots (34)$$

so that, $k \leq l \leq 2k-1$,

$$BC(A-pBC)^{\ell} = BCA^{k-1} \{ A^{\ell+1-k} - p\Gamma_{\ell+1-k} \} \qquad \dots (35)$$

Defining

$$V_{o} \stackrel{\Delta}{=} R(B)$$
, $V_{\ell} \stackrel{\Delta}{=} R(B) \cap \bigcap_{j=1}^{\ell} N(BCA^{j-1}) \equiv \bigcap_{j=1}^{\ell} N(\Gamma_{j}) \cap R(B)$, $\ell \ge 1$...(36)

then, if $|G(s)| \neq 0$, there exists an integer \hat{k} such that

$$V_{l} \neq \{0\}$$
 (lV_{l} = \{0\} (l>k) ...(37)

for, if $x \in V_{\ell}$ for all $\ell \ge 1$, then $A^{\ell}x \in N(c)$ for all $\ell \ge 0$ ie (theorem 1) $x \in W_{B}$ and the proposition is proved by noting (Owens, 1975) that $|G(s)| \ne 0$ implies that $W_{B} \land R(B) = \{0\}$. It is easily shown that

$$k \leq k$$
 ... (38)

Defining, $k-1 \leq l \leq 2k-1$,

$$W_{\ell} \stackrel{\Delta}{=} R(BCA^{k-1}\Gamma_{\ell+1-k})$$
, $X_{\ell} \stackrel{\Delta}{=} \bigcap_{j=k-1}^{\ell} N(BCA^{k-1}\Gamma_{j+1-k})$...(39)

the following theorem is proved below,

Theorem 3

2

. 4

With the above notation, $|G(s)| \neq 0$, and $\hat{k \leq 2k}$, then, if

$$\nabla_{\ell} \cap W_{\ell} = \{0\} , \qquad k-1 \leq \ell \leq k-1$$

$$\{\Gamma_{\ell+1} \nabla_{\ell}\} \cap W_{\ell} = \{0\} , \qquad k-1 \leq \ell \leq k-1 \qquad \dots (40)$$

the closed-loop system S(A-pBC,B,C) possesses unbounded poles of the form, $\hat{k \leqslant k \leqslant k},$

$$s(p) = p^{\frac{1}{\ell}} n + f(p)$$
 ...(41)

where, if λ is a non-zero solution of the relation

$$\{\lambda I_{n} + BCA^{\ell-1}\} x_{\infty} \in W_{\ell-1} \qquad \dots (42)$$

$$0 \neq x_{\infty} \in \underbrace{V}_{\ell-1}$$

then η is an ℓth root of λ , $p^{\overline{\ell}}$ is the positive real ℓth root of p and

$$\lim_{p \to \infty} p^{\frac{1}{\ell}} f(p) = 0 \qquad \dots (43)$$

Moreover, if, for k<l<k,

$$\{\{\lambda I_{n} + BCA^{\ell-1}\} X_{\ell-1} + W_{\ell-1}\} \land V_{\ell-1} \land \{\lambda I_{n} + BCA^{\ell-1}\}^{-1} W_{\ell-1} = \{0\} \qquad \dots (44)$$

- 7 -

then f(p) takes the form

$$f(p) = \alpha + \varepsilon(p) \tag{45}$$

where lim $\epsilon(p) = 0$, and the 'pivot' α is a constant, finite solution of the $p \rightarrow \infty$ relation

$$\{\ell \alpha I_n - A\}_{x_{\infty}} \in \{\lambda I_n + BCA^{\ell-1}\}_{\ell-1} + W_{\ell-1} \qquad \dots (46)$$

Proof

Equation (3) implies that

$$\{(s(p))^{\ell}I_{n} - (A-pBC)^{\ell}\}x(p) = 0$$
, $||x(p)|| = 1$, $\ell \ge 1$...(47)

Using equations (8),(29),(32), this takes the form

$$\{p^{-1}(s(p))^{\ell} - p^{-1}A^{\ell} + \Gamma_{\ell}\}_{X}(p) = \begin{bmatrix} 0 & ; & \ell \leq k \\ \sum_{j=2}^{\ell} (-1)^{j}p^{j-1}B_{j,\ell}x(p) & ; & \ell > k \end{bmatrix} \dots (48)$$

Taking the case of l = k, it follows that $p^{-1}s(p)$ is bounded $(p \rightarrow \infty)$ from which $\lim_{p \rightarrow \infty} p^{-1}(s(p))^k$ exists for every closed-loop pole. If $\lim_{p \rightarrow \infty} p^{-1}(s(p))^k = \lambda \neq 0$, then, if $\lim_{p \rightarrow \infty} x(p) = x_{\infty} (||x_{\infty}|| = 1), \Gamma_j x_{\infty} = 0, j < k$, so that $x_{\infty} \in V_{k-1}$ and $\{\lambda I_n + BCA^{k-1}\} x_{\infty} = 0 \in W_{k-1}$...(49)

proving (42) in the case of l = k. Using induction, suppose that $\lim_{p \to \infty} p^{-1}(s(p))^r = 0$, $k \le r < l \le k$, and $x_{\infty} \in V_{l-1}$, so that (equation (40)),

$$\lim_{p \to \infty} \sum_{j=2}^{r} (-1)^{j} p^{j-1} B_{j,r} x(p) = 0 , \quad k \le r \le \ell$$
 ... (50)

Using equation (31),(32),(35), equation (50) becomes

$$\lim_{p \to \infty} \{A \sum_{j=2}^{r-1} (-1)^{j} p^{j-1} B_{j,r-1} x(p) = BC \sum_{j=1}^{r-1} (-1)^{j} p^{j} B_{j,r-1} x(p) \}$$

=
$$\lim_{p \to \infty} p^{BCA^{k-1}} \Gamma_{r-k} x(p) = 0 , \quad k \le r \le l \quad \dots (51)$$

In a similar manner, it can be shown that

$$\lim_{p \to \infty} \{ p^{-1}(s(p))^{\ell} I_{n} + \Gamma_{\ell} \} x(p) = \lim_{p \to \infty} pBCA^{k-1} \Gamma_{\ell-k} x(p) \in W_{\ell-1} \qquad \dots (52)$$

Equation (40) implies that $p^{-1}(s(p))^{\ell}$ can only have a finite cluster point λ . If $\lambda = 0$, then $\Gamma_{\ell} x_{\infty} \in W_{\ell-1}$ or (equation (40)) $x_{\infty} \in N(\Gamma_{\ell}) \cap V_{\ell-1} = V_{\ell}$ and $\lim_{p \to \infty} p BCA^{k-1} \Gamma_{\ell-k} x(p) = 0$. Alternatively, if $\lambda \neq 0$, it is a solution of the relation

$$\{\lambda I_{n} + BCA^{\ell-1}\}_{x_{\infty}} = BCA^{k-1} \Gamma_{\ell-k} z \in W_{\ell-1} \qquad \dots (53)$$

for some vector $z \in \mathbb{R}^n$, proving equation (42). Note that, if $\lim_{p \to \infty} p^{-1}(s(p))^{\ell} = 0$, $1 \le \ell \le \hat{k}$, then, from the definition of \hat{k} , $x_{\infty} \notin \mathbb{R}(B)$ ie (theorem 1) s(p) has a finite limit.

Finally, if $p^{-1}(s(p))^{\ell} \rightarrow \lambda \neq 0$ ($p \rightarrow \infty$) and $\ell = k$, equation (40) follows directly from theorem 2. Alternatively, if $\ell > k$, rewrite equation (48) in the form,

$$p^{\frac{1}{k}} \{p^{-1}(s(p))^{k} - \lambda\}x(p)$$

$$= p^{\frac{1}{k}} \{-\{\lambda I_{n} + \Gamma_{k}\} + p^{-1}A^{k} + \sum_{j=2}^{k} (-1)^{j}p^{j-1}B_{j,k}\}x(p)$$

$$= p^{\frac{1}{k}} \{-\{\lambda I_{n} + \Gamma_{k}\} + p^{-1}A^{k} + A\sum_{j=2}^{k-1} p^{j-1}(-1)^{j}B_{j,k-1} - BC\sum_{j=1}^{k-1} (-1)^{j}p^{j}B_{j,k-1}\}x(p)$$
...(54)

From (48) replacing L, by L-1,

$$\lim_{p \to \infty} p^{\frac{1}{\ell}} A \left\{ \sum_{j=2}^{\ell-1} p^{j-1} (-1)^{j} B_{j,\ell-1} - \Gamma_{\ell-1} \right\} x(p) = \eta^{\frac{\ell-1}{\ell}} A x_{\infty} \qquad \dots (55)$$

so that, using equation (10), equation (54) takes the form

$$\lim_{p \to \infty} \{ p^{\frac{1}{\ell}} \{ p^{-1}(s(p))^{\ell} - \lambda \} I_n^{-\eta} \xrightarrow{\ell-1}{\ell} A \}_{\infty}$$

$$= -\lim_{p \to \infty} p^{\frac{1}{\ell}} \{ \lambda I_n^{+} B C A^{\ell-1}^{+} + B C \sum_{j=1}^{\ell-1} (-1)^{j} p^{j} B_{j,\ell-1}^{-1} \}_{\infty}^{+} (p)$$

$$= -\lim_{p \to \infty} p^{\frac{1}{\ell}} \{ \lambda I_n^{+} + B C A^{\ell-1}^{-} - p B C A^{k-1} \Gamma_{\ell-k}^{-} \}_{\infty}^{+} (p) \qquad \dots (56)$$

Write $x(p) = x_1(p) + x_2(p)$, $x_1(p) \in X_{l-1}$, $x_2(p) \in X_{l-1}$, then the relations (equations (51)-(53))

$$\lim_{p \to \infty} p BCA^{k-1} \Gamma_{r-k} x(p) = 0 , \qquad k \leq r < \ell$$

$$\lim_{p \to \infty} p BCA^{k-1} \Gamma_{\ell-k} x(p) = BCA^{k-1} \Gamma_{\ell-k} z \qquad (finite) \qquad \dots (57)$$

imply that $\lim_{p \to \infty} p^{\frac{1}{\ell}} x_2(p) = 0 \text{ ie}$ $\lim_{p \to \infty} \{p^{\frac{1}{\ell}} \{p^{-1}(s(p))^{\ell} - \lambda\} I_n - \eta^{\frac{\ell-1}{\ell}} A\} x_{\infty}$ $= -\lim_{p \to \infty} p^{\frac{1}{\ell}} \{\{\lambda I_n + BCA^{\ell-1}\} x_1(p) - pBCA^{k-1} \Gamma_{\ell-k} x(p)\} \qquad \dots (58)$

Condition (44) implies that $\lim_{p \to \infty} p^{\frac{1}{\ell}} \{(s(p)) p^{-1} - \lambda\} \text{ exists or (equation (41), (43))} \}$

$$\lim_{p \to \infty} p^{\frac{1}{\ell}} \{p^{-1}(p^{\frac{1}{\ell}} \eta + f(p))^{\ell} - \lambda\} = \lim_{p \to \infty} \ell \eta^{\frac{\ell-1}{\ell}} f(p) \stackrel{\Delta}{=} \ell \eta^{\frac{\ell-1}{\ell}} \alpha \qquad \dots (59)$$

for one finite constant α . Substituting into (58) yields the relation

$$\{\ell \alpha \mathbf{I}_{n} - \mathbf{A}\} \mathbf{x}_{\infty} \in \{\lambda \mathbf{I}_{n} + \mathbf{B} \mathbf{C} \mathbf{A}^{\ell-1}\} \mathbf{X}_{\ell-1} + \mathbf{W}_{\ell-1} \qquad \dots (60)$$

which prove the result.

Q.E.D.

It is easily shown that theorem 3 reduces to theorem 2 if S(A,B,C) is of uniform rank.

5. <u>Illustrative Example</u>

Consider the non-uniform-rank system defined by the matrices

$$A = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix} \qquad B = \begin{bmatrix} 0 & 0 \\ 1 & 0 \\ 0 & 1 \end{bmatrix} \qquad C = \begin{bmatrix} 1 & 0 & -1 \\ 1 & 0 & 1 \end{bmatrix}$$

from which, $|G(s)| \neq 0$, k = 1

$$\Gamma_{0} = 0 , \quad \Gamma_{1} = BC = \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & -1 \\ 1 & 0 & 1 \end{bmatrix} , \quad CBC^{2} = \begin{bmatrix} 0 & 0 & 0 \\ -1 & 0 & -1 \\ 1 & 0 & 1 \end{bmatrix}$$
$$BCA = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & -1 \\ 0 & 1 & 1 \end{bmatrix} , \quad \Gamma_{2} = \begin{bmatrix} 1 & 0 & -1 \\ 2 & 1 & -1 \\ 1 & 1 & 2 \end{bmatrix}(62)$$

so that

$$V_{0} = \text{span} \left\{ \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right\}, V_{1} = \text{span} \left\{ \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \right\}, V_{2} = \{0\} \dots (63)$$

ie $\hat{k} = 2 = 2k$. Also,

$$W_{o} = \{0\}$$
, $W_{1} = \operatorname{span}\left\{ \begin{bmatrix} 0\\-1\\1 \end{bmatrix} \right\}$, $X_{o} = R^{3}$, $X_{1} = \operatorname{span}\left\{ \begin{bmatrix} 0\\1\\0 \end{bmatrix}, \begin{bmatrix} -1\\0\\1 \end{bmatrix} \right\}$...(64)

so that $W_0 \cap V_0 = W_1 \cap V_1 = \{0\}, \Gamma_1 V_0 \cap W_0 = \{0\}, \Gamma_2 V_1 \cap W_1 = \{0\}.$

To calculate the first order asymptote, solve the equation

$$\{\lambda I_{3} + \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & -1 \\ 1 & 0 & 1 \end{bmatrix} \} x_{\infty} \in \mathbb{W}_{0} , x_{\infty} \in \mathbb{V}_{0}$$
 ...(65)

ie $\lambda = -1$ and $x_{\infty} = \{0, -1, 1\}^T \in R(B)$. The corresponding pivot is the solution of the relation

$$\{\alpha I_{3} - \begin{bmatrix} 0 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix}\} \begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix} = \begin{bmatrix} -1 & 0 & 0 \\ 1 & -1 & -1 \\ 1 & 0 & 0 \end{bmatrix} z , z \in \mathbb{R}^{3} \dots (66)$$

ie $\alpha = 0$, and the asymptote takes the form -p; and passes through the origin of the complex plane. Considering now the second order type asymptote,

- 11 -

$$\{\lambda I_{3} + \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & -1 \\ 0 & 1 & 1 \end{bmatrix} \} \quad x_{\infty} \in W_{1} \quad , \quad x_{\infty} \in V_{1} \qquad \dots (67)$$

ie $\lambda = -2$ and $x_{\infty} = \{0, 1, 0\}^{T}$. The corresponding pivot is the solution of the relation

$$\{2\alpha I_{3} = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix} \} \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} -2 & 0 & 0 \\ 0 & -1 & -1 \\ 0 & 1 & -1 \end{bmatrix} \begin{bmatrix} 0 & -1 \\ 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} z_{1} \\ z_{2} \end{bmatrix} + z_{3} \begin{bmatrix} 0 \\ -1 \\ 1 \end{bmatrix}$$

$$= \begin{bmatrix} 0 & 2 & 0 \\ -1 & -1 & -1 \\ 1 & -1 & 1 \end{bmatrix} \begin{bmatrix} z_1 \\ z_2 \\ z_3 \end{bmatrix} \dots (68)$$

ie α = 1 and the second order asymptote takes the form $\pm p^{\frac{1}{2}}/-2 + 1$.

6. Conclusions

The geometric characterization of the asymptotes of multivariable root-loci of a linear system has been discussed for two cases of practical interest. The work augments the analysis of Shaked and Kouvaritakis (1976) and illustrates the fact that (i) two integer parameters k,k, derived from geometric considerations, play a fundamental role in the description of the root-locus, and (ii) both the asymptotic directions and pivots are described by inclusion relationships in the state space of the form

$$\{\xi I_n + F\} x \in Q$$
, $z \in P$...(69)

where F is a nxn matrix and P,Q are well-defined subspaces of the state space. A glance at theorems 2,3 will indicate that the matrices A, BCA^{j-1} , Γ_j , $k \leq j \leq \hat{k}$ play a fundamental role in the root-locus theory. Writing,

$$\Gamma_{j} = [B, AB, \dots, A^{j-1}B] \begin{bmatrix} CA^{j-1} \\ CA^{j-2} \\ \vdots \\ CA \\ C \end{bmatrix} \dots (70)$$

it is seen that the controllability and observability matrices play an important role in determining the structure of the root-locus. Further work could relate the structure of the root-loci to parameters defining controllability and observability, provide valuable insight into difficulties occurring in pole allocation and suggest new algorithms for the calculation of the system asymptotes.

References

Shahed, U., Kouvaritakis, B., 1976, Int. Jrnl. Control, Vol.23, No.1, Jan., pp.297-340.

Owens, D.H., 1975, October, Research Report No.35, Department of Control Engineering, University of Sheffield, UK.

- 13 -