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Dutra e Silva Junior, Elvio Carlos, Soares Indrusiak, Leandro, Finamore, W.A. et al. (2012)
A Programmable look-up table-based interpolator with nonuniform sampling scheme.
International Journal of Reconfigurable Computing. 647805. ISSN: 1687-7209

<https://doi.org/10.1155/2012/647805>

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Research Article

A Programmable Look-Up Table-Based Interpolator with Nonuniform Sampling Scheme

Élvio Carlos Dutra e Silva Júnior,¹ Leandro Soares Indrusiak,²
Weiler Alves Finamore,³ and Manfred Glesner⁴

¹ Department of Aerospace Science and Technology, Institute for Advanced Studies, 12228-001 São José dos Campos, SP, Brazil

² Department of Computer Science, University of York, York YO10 5GH, UK

³ Department of Electrical Energy, Federal University of Juiz de Fora, 36036-900 Juiz de Fora, MG, Brazil

⁴ Department of Microelectronic Systems, Darmstadt University of Technology, 64283 Darmstadt, Germany

Correspondence should be addressed to Élvio Carlos Dutra e Silva Júnior, elvio.dutra@gmail.com

Received 14 June 2012; Accepted 4 September 2012

Academic Editor: Scott Hauck

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Interpolation is a useful technique for storage of complex functions on limited memory space: some few sampling values are stored on a memory bank, and the function values in between are calculated by interpolation. This paper presents a programmable Look-Up Table-based interpolator, which uses a reconfigurable nonuniform sampling scheme: the sampled points are not uniformly spaced. Their distribution can also be reconfigured to minimize the approximation error on specific portions of the interpolated function's domain. Switching from one set of configuration parameters to another set, selected on the fly from a variety of precomputed parameters, and using different sampling schemes allow for the interpolation of a plethora of functions, achieving memory saving and minimum approximation error. As a study case, the proposed interpolator was used as the core of a programmable noise generator—output signals drawn from different Probability Density Functions were produced for testing FPGA implementations of chaotic encryption algorithms. As a result of the proposed method, the interpolation of a specific transformation function on a Gaussian noise generator reduced the memory usage to 2.71% when compared to the traditional uniform sampling scheme method, while keeping the approximation error below a threshold equal to 0.000030518.

1. Introduction

Nowadays, the world is facing a boom on the fusion between telecommunications and information technology. The merging of these two fields spreads over all kinds of information systems, requiring efforts for ensuring the integration among many kinds of organizations [1], from tactical to strategic operations, in different levels of information system interoperability [2]. The ISO/OSI seven-layer model arises as a lighthouse for seeking the interoperability on many different layers of networked solutions [3]. Many standards and protocols arise from this model, including cryptographic ones.

Encryption solutions can be implemented on both software and hardware. Software implementations are more related to the protection of the information itself, while

hardware ones can be also used to protect the communication channels [4]. In the case of tactical telecommunication systems, which require both channel and information security, the hardware implementation of such encryption algorithms arises as a better compromise. The need to test the behavior of such systems against different sources of noise and jamming becomes the motivation to implement, on FPGA (Field-Programmable Gate Array), a programmable noise generator.

A Look-Up Table- (LUT-) based interpolation system is the core of the programmable noise generator developed in this work. Using a LUT, complex and otherwise slow calculations can be sped up by storing precomputed values of the function, interpolating the desired values in between, achieving high-speed designs [5]. Look-Up Tables are very

common microelectronic blocks for many applications [5–19]. Ba et al. [9] proposed a linearly interpolated LUT predistorter used to mitigate the effects of nonlinear amplifiers. Monga and Bala [10] proposed an algorithm for minimizing the approximation error on multidimensional LUTs where both samples values and distributions are optimized.

Some authors used nonuniform sampling schemes as a solution for minimizing the LUT memory size: Seidner [11] reduced the memory usage on the implementation of a 10^Y conversion circuit with a LUT scaling sample scheme; Yan and Mämmelä [15] used a nonuniformly segmented interpolation LUT for simulating nonlinear radio frequency power amplifiers; Cavers [16] proposed a systematic way to describe and analyze arbitrary nonuniform LUT sampling schemes as a companding function, which was further improved by Hassani and Kamarei [17] with a LUT segmentation concept; Boumaiza et al. [18] proposed a new companding function for amplifier predistortion with built-in dependence on the nonlinearity of the power amplifier; Dutra et al. [19] used a nonuniform but fixed sampling scheme to minimize the memory size of a LUT-based interpolator designed to represent the Inverse Error Function (erf^{-1}).

All works previously mentioned used a *fixed*, uniform or not, sampling scheme to characterize a given function or class of functions. The main contribution of this work is to implement on FPGA a LUT-based interpolator system with a sampling scheme that is *not-fixed* (it can be programmed on the fly) and *not-uniformly* distributed (it uses not equally spaced sampling points).

The remaining of the paper is organized as follows: based on the definition of partitions, Section 2 will present the offline calculations performed to define the parameters that configure the proposed programmable LUT-based interpolator. Section 3 will describe the interpolator architecture, including the description of the subsystem that calculates the nonuniformly distributed addresses and the corresponding displacements. An application of the proposed interpolator will be presented on Section 4, where its flexibility will be discussed with the usage of a gamma of different functions $g(x)$, using different *not-fixed* and *not-uniformly* distributed sampling schemes. Section 5 will end this paper with a summary of the achieved results and a flavor of future works.

2. Configuration Parameters

To discuss the determination of the configuration tables for the LUT-based interpolator, discussed hitherto, we will consider a generic function $g(x)$ which will have notable values stored on the appropriate tables. To set an example, values that define a set of arbitrary intervals are stored in Table 1. The number of intervals is related to the number of resources used on the FPGA implementation. As a project decision, $P = 22$ partitions were used in order to minimize the final approximation error. Although we focus on a specific example, the underlined method is revealed in its generality.

To define the configuration tables for the LUT-based interpolator, we will consider a generic function $g(x)$

TABLE 1: Frequency assignment for sampling scheme α .

n	x_n	f_n
1	-1.0000000000000000	32768
2	-0.9977000000000000	16384
3	-0.9954000000000000	8192
4	-0.9903000000000000	4096
5	-0.9805000000000000	2048
6	-0.9590000000000000	1024
7	-0.9141000000000000	512
8	-0.8204000000000000	256
9	-0.6407000000000000	128
10	-0.3438000000000000	64
11	-0.1251000000000000	32
12	+0.0000000000000000	32
13	+0.1249000000000000	64
14	+0.3436000000000000	128
15	+0.6405000000000000	256
16	+0.8202000000000000	512
17	+0.9140000000000000	1024
18	+0.9589000000000000	2048
19	+0.9804000000000000	4096
20	+0.9901000000000000	8192
21	+0.9953000000000000	16384
22	+0.9976000000000000	32768
—	+0.99993896484375	—

which will have only notable values stored on appropriate tables. We start by considering the interval $[x_1, x_{P+1})$ to be the function $g(x)$ domain and a set of points $\{x_1, x_2, \dots, x_n, x_{n+1}, \dots, x_p, x_{p+1}\}$ which will induce the P partitions $\{[x_1, x_2), \dots, [x_n, x_{n+1}), \dots, [x_p, x_{p+1})\}$ on the domain $[x_1, x_{P+1})$. Samples are next drawn from each element of partition $[x_n, x_{n+1})$, where $n \in \{1, 2, \dots, P\}$, with a given frequency f_n —the set of $i_n = (x_{n+1} - x_n)f_n$ sampling points induces the subpartition $\{[x_{n_1}, x_{n_2}), [x_{n_2}, x_{n_3}), \dots, [x_{n_{i_n}}, x_{n_{i_n+1}})\}$ of the n th interval (notice that $x_{n_1} = x_n$ and $x_{n_{i_n+1}} = x_{n+1}$). For each function $g(x)$, the appropriate configuration table is stored—the values stored on the table contain, among other parameters discussed in this section, both the ordinate values given by the set $\{g(x_{n_1}), g(x_{n_2}), \dots, g(x_{n_{i_n+1}})\}$ and the corresponding derivate values $\{g'(x_{n_1}), g'(x_{n_2}), \dots, g'(x_{n_{i_n}})\}$ estimated by (1), where $m \in \{1, 2, \dots, i_n\}$. Both ordinate and derivate values are defined for $n \in \{1, 2, \dots, P\}$:

$$g'(x_{n_m}) = \frac{g(x_{n_{m+1}}) - g(x_{n_m})}{x_{n_{m+1}} - x_{n_m}}. \quad (1)$$

The configuration parameters of the LUT-based interpolator, including the content of the memories that store the ordinates and derivatives, are previously calculated and imported into the FPGA. These parameters are calculated according to a scheme of P *not-fixed* and *not-uniformly* distributed partitions, or sampling regions, as exemplified in Table 1. In this table, each partition n is defined by the interval $[x_n, x_{n+1})$ and a sampling frequency f_n . For example, in Table 1, the fourth partition ($n = 4$) is defined on the

interval $(x_4, x_5] = (-0.9903, -0.9805]$, with a sampling frequency $f_n = 4096$. Note also in Table 1 that $x_{P+1} = 0.99993896484375$.

The interval and sampling frequency of each partition should be chosen in order to allow the representation of $g(x)$ with a minimum approximation error. Therefore, higher sampling frequencies f_n should be expected on n intervals where $g(x)$ changes more abruptly, presenting higher curvature. Based on the data of Table 1, we calculate the configuration parameters of the LUT-based interpolator, as illustrated in Table 2 and explained ahead.

We start the construction of Table 2 by adjusting the partitions limits $\{x_1, x_2, \dots, x_n, x_{n+1}, \dots, x_P, x_{P+1}\}$ of Table 1 according to the sampling frequency of each partition. The Precise Inferior Limit (PIL) and the Corrected Superior Limit (CSL) of each partition n are calculated by (2) and (3) which use a constant binary decimal point position ($d = 14$), the function signal $Sg(a)$, which outputs the values -1 or $+1$ according to the signal negative or positive of a given argument a (notice that for a null argument, $Sg(0) = 0$), and the function round $R(b/c)$, which calculates the maximum multiple of the argument c , less or equal to them the argument b (note that the symbol $/$ used on the representation of the function round $R(b/c)$ has no relation to the division operation). Both PIL and CSL are necessary for adjusting the n partitions of Table 1 (an empiric project choice) to the corresponding frequencies:

$$PIL_1 = R\left(\frac{x_1}{Sg(x_1) \times 2^{1-\log_2(f_1)}}\right)$$

$$PIL_n = R\left(\frac{R(x_n/Sg(x_n) \times 2^{1-\log_2(f_{n-1})})}{Sg(x_n) \times 2^{1-\log_2(f_n)}}\right), \quad (2)$$

$$CSL_n = R\left(\frac{R(x_{n+1}/Sg(x_{n+1}) \times 2^{1-\log_2(f_n)})}{Sg(x_{n+1}) \times 2^{1-\log_2(f_{n+1})}}\right) - 2^{-d}. \quad (3)$$

Table 2 also brings three parameters used to select some input bits of the LUT, necessary to calculate the addresses and differences. They are the parameter B_n , calculated by (4) and used to select the B_n more significant bits (MSBs) of input x , required on the calculation of the nonuniform spaced addresses; the parameter D_n , calculated by (5) and used to slice the D_n less significant bits (LSBs) of input x , also required on the addresses calculation; and parameter S_n , calculated by (6) and used to slice the S_n less significant bits (LSBs) of input x , required to calculate the difference $(x - x_{n_m})$ between the LUT input and the corresponding stored sampling point. The usage of these parameters will be discussed in Section 3:

$$B_n = 1 - \log_2(f_n), \quad (4)$$

$$D_n = \log_2(f_n), \quad (5)$$

$$S_n = 15 - \log_2(f_n), \quad \text{for } f_n \neq 2^{15} \quad (6)$$

$$S_n = 7, \quad \text{for } f_n = 2^{15}.$$

Two other important configuration parameters present in Table 2 are the Displacement (Dsp_n) and the Address Logic ($Add \log_n$), calculated by (7) and (8). These two parameters are used in the calculation of nonuniform spaced addresses, as will be presented in more details in Section 3:

$$Dsp_n = \frac{f_n}{2}, \quad (7)$$

$$Add \log_n = SMN_n - IMN_n$$

$$SMN_n = 1 + EMN_{n-1}$$

$$SMN_1 = 0$$

$$EMN_n = SMN_n + QMR_n - 1$$

$$QMR_n = 0.5 \times f_n \times (CSL_n - PIL_n + 2^{-d}) \quad (8)$$

$$IMN_n = MNM_n + SMP_n$$

$$MNM_n = 0.5 \times f_n$$

$$SMP_n = 0.5 \times f_n \times PIL_n.$$

The quantities QMR, SMN, EMN, MNM, SMP, and IMN are intermediate variables necessary for the recursive calculation of the Address Logic in (8). They are related, respectively, to the following entities: the Quantity of Memories Required (QMR) on each partition n , the Starting Memory Number (SMN) and the Ending Memory Number (EMN) on each partition n , the Maximum Number of Memories (MNM) considering that the specific sampling frequency was applied to the entire domain $[x_1, x_{P+1}]$, the Starting Memory Position (SMP) considering that the specific sampling frequency was applied to the entire domain $[x_1, x_{P+1}]$, and the Initial Memory Number (IMN) used on the specific sampling frequency.

The last four configuration parameters are related to the calculation of the sampling points x_{n_m} used to define the ordinate $g(x_{n_m})$ and derivate $g'(x_{n_m})$ stored values. These parameters are the Sampling Points Start (SPS), Sampling Points Final (SPF), Memory Position Start (MPS), and the Memory Position Final (MPF), calculated by (9), (10), (11), and (12), respectively:

$$SPS_1 = PIL_1$$

$$SPS_n = \frac{2}{f_n} + SPF_{n-1}, \quad (9)$$

$$SPF_1 = CSL_1 + 2^{-d}$$

$$SPF_n = CSL_n + 2^{-d} - \frac{2}{f_n}, \quad (10)$$

$$MPS_1 = 1$$

$$MPS_n = 1 + MPF_{n-1}, \quad (11)$$

TABLE 2: Configuration parameters calculated for sampling scheme α .

n	PIL_n	CSL_n	B_n	D_n	S_n	Dsp_n	Add log $_n$	SPS_n	MPS_n	SPF_n	MPF_n
1	-1.0000000000	-0.99774169921	-14	15	7	16384	0	-1.0000000000	1	-0.99768066406	39
2	-0.99768066406	-0.99542236328	-13	14	1	8192	19	-0.99755859375	40	-0.99536132812	58
3	-0.99536132812	-0.99029541015	-12	13	2	4096	38	-0.99511718750	59	-0.99023437500	79
4	-0.99023437500	-0.98052978515	-11	12	3	2048	58	-0.98974609375	80	-0.98046875000	99
5	-0.98046875000	-0.95904541015	-10	11	4	1024	78	-0.97949218750	100	-0.95898437500	121
6	-0.95898437500	-0.91412353515	-9	10	5	512	99	-0.95703125000	122	-0.91406250000	144
7	-0.91406250000	-0.82037353515	-8	9	6	256	121	-0.91015625000	145	-0.82031250000	168
8	-0.82031250000	-0.64068603515	-7	8	7	128	144	-0.81250000000	169	-0.64062500000	191
9	-0.64062500000	-0.34381103515	-6	7	8	64	167	-0.62500000000	192	-0.34375000000	210
10	-0.34375000000	-0.12506103515	-5	6	9	32	188	-0.31250000000	211	-0.12500000000	217
11	-0.12500000000	-0.00006103515	-4	5	10	16	202	-0.06250000000	218	+0.00000000000	219
12	+0.00000000000	+0.06243896484	-4	5	10	16	202	+0.06250000000	220	+0.06250000000	220
13	+0.06250000000	+0.31243896484	-5	6	9	32	185	+0.09375000000	221	+0.31250000000	228
14	+0.31250000000	+0.62493896484	-6	7	8	64	143	+0.32812500000	229	+0.62500000000	248
15	+0.62500000000	+0.81243896484	-7	8	7	128	39	+0.63281250000	249	+0.81250000000	272
16	+0.81250000000	+0.91009521484	-8	9	6	256	-193	+0.81640625000	273	+0.91015625000	297
17	+0.91015625000	+0.95697021484	-9	10	5	512	-682	+0.91210937500	298	+0.95703125000	321
18	+0.95703125000	+0.97943115234	-10	11	4	1024	-1684	+0.95800781250	322	+0.97949218750	344
19	+0.97949218750	+0.98968505859	-11	12	3	2048	-3711	+0.97998046875	345	+0.98974609375	365
20	+0.98974609375	+0.99505615234	-12	13	2	4096	-7786	+0.98999023437	366	+0.99511718750	387
21	+0.99511718750	+0.99749755859	-13	14	1	8192	-15958	+0.99523925781	388	+0.99755859375	407
22	+0.99755859375	+0.99987792968	-14	15	7	16384	-32322	+0.99761962890	408	+0.99987792968	445

TABLE 3: Synthesis information.

Property	Value
Device part type	XC3S2000
Package type	FG 676
Speed grade	-5
Number of external IOBs	304 out of 489
Number of slices	802 out of 30720
Number of SLICEMs	123 out of 10240
Number of BUFGMUXs	1 out of 8
Number of RAMB16s	32 out of 40
Average connection delay	2.281 ns
Maximum frequency	151.717 MHz
Minimum period	6.591 ns
Total power consumption	636 mW
Junction temperature	25°C

$$MPF_1 = MPS_1 + \frac{f_n \times (CSL_1 + 2^{-d} - PIL_1)}{2} \quad (12)$$

$$MPF_n = MPS_n + \frac{f_n \times (CSL_n + 2^{-d} - PIL_n)}{2} - 1.$$

Based on the characterization of the $P = 22$ partitions (exemplified in Table 1), the equations described in this section are used to calculate the configuration parameters

(exemplified in Table 2) used by the proposed nonuniform LUT-based interpolator. Section 3 is going to discuss the internal structure of this interpolator and how it uses the configuration parameters present in Table 2 to perform its tasks.

3. Interpolator Architecture

The LUT-based interpolator designed in this paper maps a 15-bit wide input x , with binary point position $d = 14$, belonging to the domain $[x_1, x_{P+1}] = [-1, +0.99993896484375]$, using a two's complement signed fixed-point arithmetic, into a desired output $g(x)$. The LUT-based interpolator can be used with different $g(x)$ functions, no matter how wide their domains are. For example, for a domain $[-|M|, +|N|]$, where $|N| > |M|$, we have to scale the input from the interval $[-|N|, +|N|]$ to $[-1, +1]$ and neglect the values on the interval $[-|N|, -|M|]$.

The proposed LUT-based interpolator uses the Taylor's approximation described in (13) for interpolating $g(x)$ according to the input x . The bigger the Taylor's approximation order, the smaller the approximation error, but there is a trade-off involved: one extra multiplier and one extra RAM block are required every time the approximation order is increased. Therefore, the increment of the Taylor's approximation order brings one advantage: the reduction of approximation error; and three disadvantages: larger memory space required to store one more derivate order,

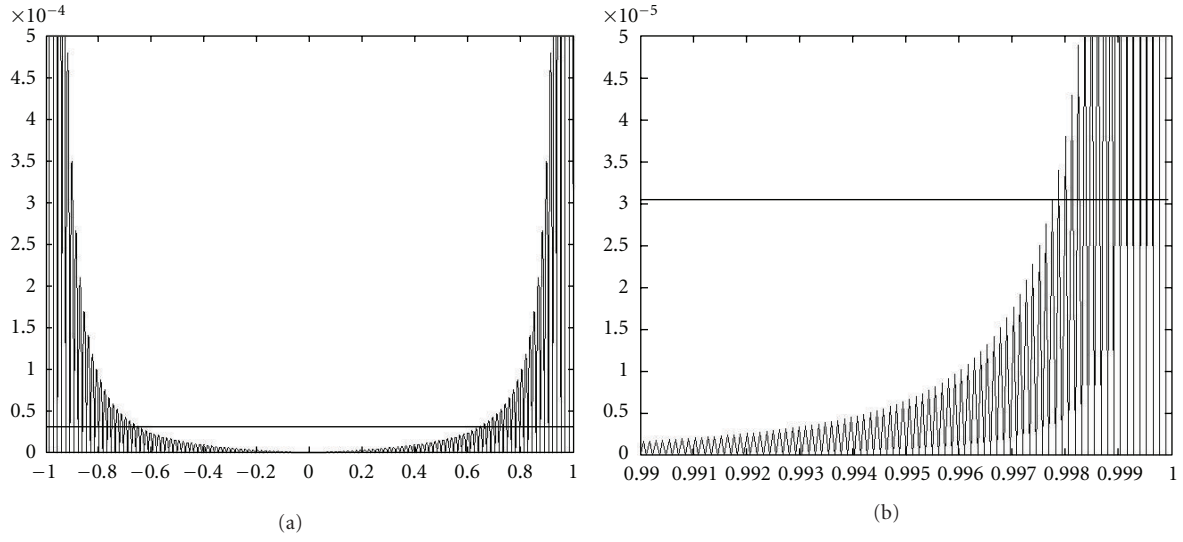


FIGURE 3: Absolute approximation error for two uniformly distributed sampling schemes ($f_n = 128$ for (a) and $f_n = 16384$ for (b)).

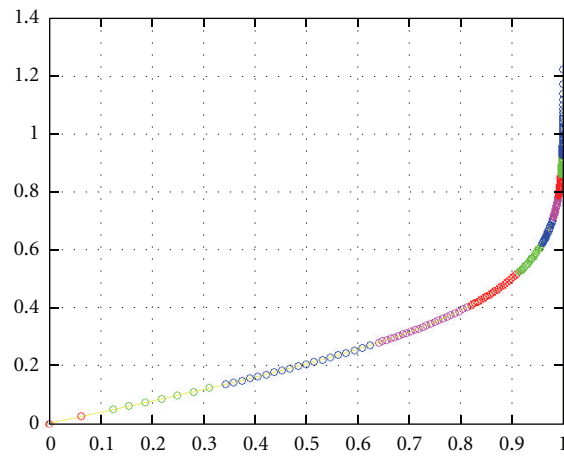


FIGURE 4: First quadrant of Gaussian transformation function (14) sampled according to the scheme α presented in Tables 1 and 2.

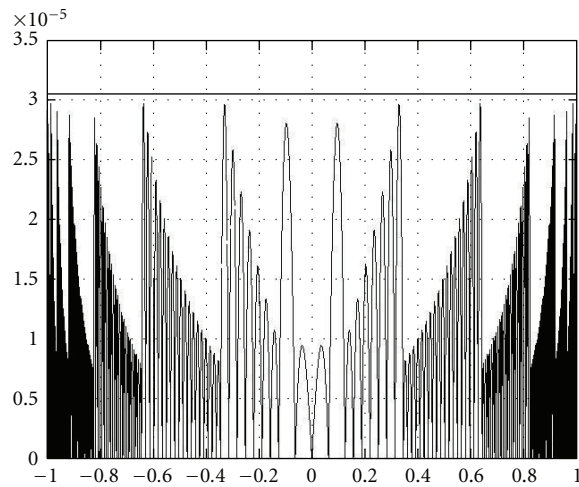


FIGURE 5: Absolute approximation error obtained with the nonuniform sampling scheme α presented in Tables 1 and 2.

TABLE 4: Frequency assignment for sampling schemes β and γ .

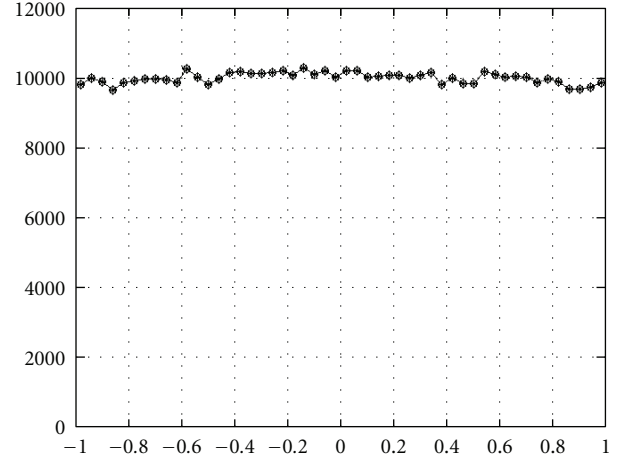
n	$x_n [\beta]$	$f_n [\beta]$	$x_n [\gamma]$	$f_n [\gamma]$
1	-1,000000	4096	-1,000000	1024
2	-0,997700	4096	-0,996000	1024
3	-0,995400	4096	-0,995400	4096
4	-0,990300	1024	-0,990000	1024
5	-0,980500	1024	-0,980500	1024
6	-0,959000	128	-0,959000	128
7	-0,914100	128	-0,914100	128
8	-0,820400	128	-0,700000	128
9	-0,640700	32	-0,500000	32
10	-0,343800	32	-0,343800	32
11	-0,125100	32	-0,125100	32
12	0,000000	32	0,000000	128
13	0,124900	32	0,200000	128
14	0,343600	256	0,400000	256
15	0,640500	256	0,700000	256
16	0,820200	1024	0,800000	1024
17	0,914000	1024	0,914000	1024
18	0,958900	8192	0,958900	8192
19	0,980400	8192	0,980400	8192
20	0,990100	512	0,990100	512
21	0,995300	512	0,995300	512
22	0,997600	16384	0,997600	16384
—	0,999938	—	0,999938	—

meaning that the input x belongs to the partition $[x_5, x_6) = [-0.95904541015625, -0.98052978515625)$.

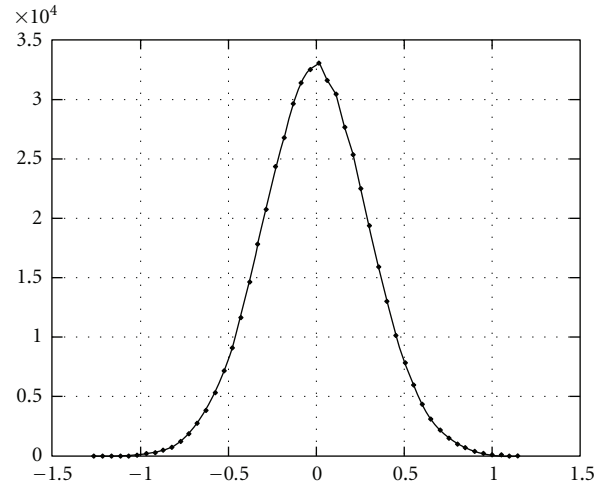
Based on the selector signal provided by subsystem *Sampled Region and Corrected Superior Limit*, the next two subsystems, *Displacement* and *AddLog*, output the values Dsp_n and Add_{log}_n calculated by (7) and (8). These both values are used to calculate the nonuniform RAM addresses via the two blocks named *Displacement_Adder* and *Add_Log_Adder*. Continuing on the example above, the provided selector signal equals to 5, implying $Dsp_n = 1024$ and $Add_{log}_n = 78$.

Keeping on the description of the Address branch of Figure 2, we have two subsystems that select a configurable number of bits from their inputs. The first one, named *Add_MSB*, slices a configurable number of the most significant bits of input x . This configurable number of selected bits is defined by the parameter B_n in (4). This output is added with the *Displacement* value Dsp_n , and a configurable number of its less significant bits, defined by the parameter D_n in (5), is selected by subsystem *Add_LSB*. Finally, the Address is calculated by adding this value with the parameter Add_{log}_n explained above and calculated by (8).

The output Difference is calculated by the configurable subsystem named *Dif_LSB*. It is configured by the parameters S_n in (6) and the sampling frequency f_n in Table 1. This subsystem slices a configurable number (defined by parameter S_n) of the less significant bits of the input x and forces the binary point to a fixed position $d = 14$. An exception must be done on the sampling regions where $f_n = 2^{15}$ because



(a)



(b)

FIGURE 6: Transformation of a uniformly distributed input signal (a) into a Gaussian noise (b) using the LUT-based interpolator programmed with the nonuniform sampling scheme α of Tables 1 and 2

no interpolation is necessary: all possible values x of these regions are mapped one to one to a corresponding $g(x_{m_n})$, and the differences are always made equal to zero.

The six subsystems discussed above are configured on the fly by the parameters enumerated in the example in Tables 1 and 2. These parameters are stored inside each subsystem by means of 28 memories (22 RAM blocks storing 2 positions each and 6 storing 22 positions). Their contents, as well as the contents of the 512 positions wide ordinate and derivative RAM blocks, can be changed on the fly, what enables this nonuniform LUT-based interpolator to represent different $g(x)$ functions, according to different sampling schemes, as it will be seen in Section 4. The reconfiguration time is defined by the depth of the longest RAM block, the ordinate or derivative RAM blocks: the interpolator requires 512 clock cycles for a full reconfiguration.

TABLE 5: Configuration parameters calculated for sampling scheme β .

n	PIL_n	CSL_n	B_n	D_n	S_n	Dsp_n	Add log $_n$	SPS_n	MPS_n	SPF_n	MPF_n
1	-1.0000000000	-0.99761962890	-11	12	3	2048	0	-1.0000000000	1	-0.99755859375	6
2	-0.99755859375	-0.99517822265	-11	12	3	2048	0	-0.99707037250	7	-0.99511718750	11
3	-0.99511718750	-0.99029541015	-11	12	3	2048	0	-0.99462890625	12	-0.99023437500	21
4	-0.99023437500	-0.98052978515	-9	10	5	512	15	-0.98828125000	22	-0.98046875000	26
5	-0.98046875000	-0.95318603515	-9	10	5	512	15	-0.97851562500	27	-0.95312500000	40
6	-0.95312500000	-0.90631103515	-6	7	8	64	36	-0.93750000000	41	-0.90625000000	43
7	-0.90625000000	-0.81256103515	-6	7	8	64	36	-0.89062500000	44	-0.81250000000	49
8	-0.81250000000	-0.62506103515	-6	7	8	64	36	-0.79687500000	50	-0.62500000000	61
9	-0.62500000000	-0.31256103515	-4	5	10	16	54	-0.56250000000	62	-0.31250000000	66
10	-0.31250000000	-0.12506103515	-4	5	10	16	54	-0.25000000000	67	-0.12500000000	69
11	-0.12500000000	-0.00006103515	-4	5	10	16	54	-0.06250000000	70	+0.00000000000	71
12	+0.00000000000	+0.06243896484	-4	5	10	16	54	+0.06250000000	72	+0.06250000000	72
13	+0.06250000000	+0.31243896484	-4	5	10	16	54	+0.12500000000	73	+0.31250000000	76
14	+0.31250000000	+0.63275146484	-7	8	7	128	-93	+0.32031250000	77	+0.63281250000	117
15	+0.63281250000	+0.81243896484	-7	8	7	128	-93	+0.64062500000	118	+0.81250000000	140
16	+0.81250000000	+0.91204833984	-9	10	5	512	-193	+0.81445312500	141	+0.91210937500	191
17	+0.91210937500	+0.95697021484	-9	10	5	512	-789	+0.91406250000	192	+0.95703125000	214
18	+0.95703125000	+0.98016357421	-12	13	2	4096	-789	+0.95727539062	215	+0.98022460937	309
19	+0.98022460937	+0.98822021484	-12	13	2	4096	-7803	+0.98046875000	310	+0.98828125000	342
20	+0.98828125000	+0.99212646484	-8	9	6	256	-168	+0.99218750000	343	+0.99218750000	343
21	+0.99218750000	+0.99603271484	-8	9	6	256	-168	+0.99609375000	344	+0.99609375000	344
22	+0.99609375000	+0.99981689453	-13	14	1	8192	-16009	+0.99621582031	345	+0.99975585937	374

TABLE 6: Configuration parameters calculated for sampling scheme γ .

n	PIL_n	CSL_n	B_n	D_n	S_n	Dsp_n	Add log $_n$	SPS_n	MPS_n	SPF_n	MPF_n
1	-1.0000000000	-0.99420166615	-9	10	5	512	0	-1.00000000000	1	-0.99414062500	4
2	-0.99414062500	-0.99420166615	-9	10	5	512	0	-0.99218750000	5	-0.99414062500	4
3	-0.99414062500	-0.98834228515	-11	12	3	2048	-9	-0.99365234375	5	-0.98828125000	16
4	-0.98828125000	-0.98052978515	-9	10	5	512	9	-0.98632812500	17	-0.98046875000	20
5	-0.98046875000	-0.95318603515	-9	10	5	512	9	-0.97851562500	21	-0.95312500000	34
6	-0.95312500000	-0.90631103515	-6	7	8	64	30	-0.93750000000	35	-0.90625000000	37
7	-0.90625000000	-0.68756103515	-6	7	8	64	30	-0.89062500000	38	-0.68750000000	51
8	-0.68750000000	-0.50006103515	-6	7	8	64	30	-0.67187500000	52	-0.50000000000	63
9	-0.50000000000	-0.31256103515	-4	5	10	16	54	-0.43750000000	64	-0.31250000000	66
10	-0.31250000000	-0.12506103515	-4	5	10	16	54	-0.25000000000	67	-0.12500000000	69
11	-0.12500000000	-0.00006103515	-4	5	10	16	54	-0.06250000000	70	+0.00000000000	71
12	+0.00000000000	+0.18743896484	-6	7	8	64	6	+0.01562500000	72	+0.18750000000	83
13	+0.18750000000	+0.39056396484	-6	7	8	64	6	+0.20312500000	84	+0.39062500000	96
14	+0.39062500000	+0.69525146484	-7	8	7	128	-83	+0.39843750000	97	+0.69531250000	135
15	+0.69531250000	+0.79681396484	-7	8	7	128	-83	+0.70312500000	136	+0.79687500000	148
16	+0.79687500000	+0.91204833984	-9	10	5	512	-773	+0.79882812500	149	+0.91210937500	207
17	+0.91210937500	+0.95697021484	-9	10	5	512	-773	+0.91406250000	208	+0.95703125000	230
18	+0.95703125000	+0.98016357421	-12	13	2	4096	-7787	+0.95727539062	231	+0.98022460937	325
19	+0.98022460937	+0.98822021484	-12	13	2	4096	-7787	+0.98046875000	326	+0.98828125000	358
20	+0.98828125000	+0.99212646484	-8	9	6	256	-152	+0.99218750000	359	+0.99218750000	359
21	+0.99218750000	+0.99603271484	-8	9	6	256	-152	+0.99609375000	360	+0.99609375000	360
22	+0.99609375000	+0.99981689453	-13	14	1	8192	-15993	+0.99621582031	361	+0.99975585937	390

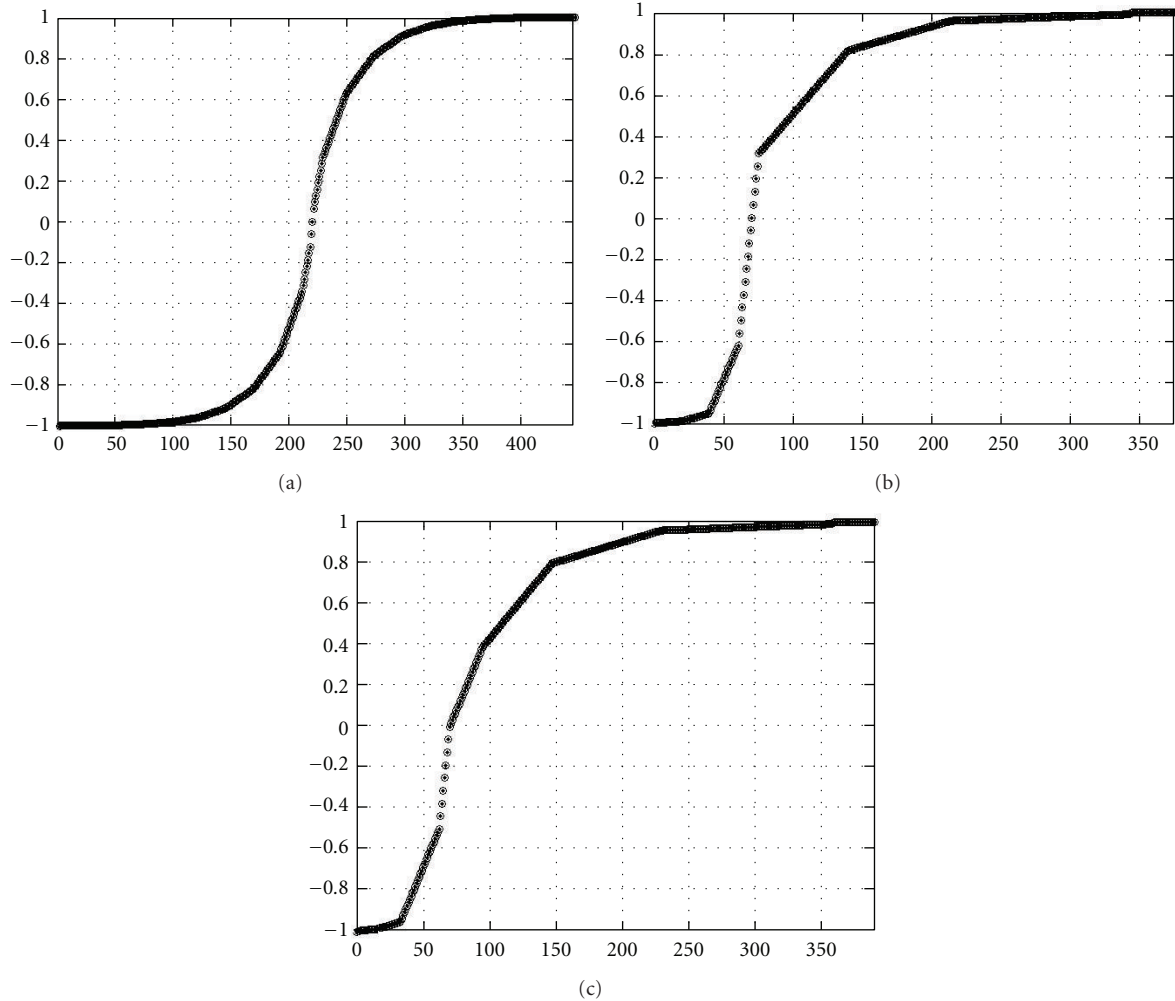


FIGURE 7: The abscissa values x_{n_m} obtained with the sampling schemes α (a), β (b), and γ (c).

The presented design was implemented using the softwares Integrated Software Environment (ISE) and System Generator (SysGen) from Xilinx, on a Spartan-3 development kit from Avnet with a XC3S2000-5 FG676 Spartan 3 FPGA. The synthesis details of this realization can be seen on Table 3.

4. Programmable Noise Generator

As a study case, the proposed nonuniform LUT-based interpolator was used as a programmable noise generator able to output noise with different Probability Density Functions (PDFs). A controlled level of approximation error is achieved by using the proposed programmable nonuniform sampling scheme.

A given transformation function $g(x)$ is responsible for changing the PDF of a source uniformly distributed noise into a noise with a different and configurable PDF. The configuration parameters presented as an example in Tables 1 and 2 were constructed having in mind the minimization of the approximation error of a Gaussian noise generator.

It uses a specific $g_1(x)$ transformation function [20], represented in (14), for transforming a uniform distributed noise into a Gaussian one:

$$g_1(x) = \sqrt{2}\sigma_y \operatorname{erf}^{-1}(x). \quad (14)$$

The transformation function $g_1(x)$ has two poles located at the abscissas $x = -1$ and $x = +1$, which are characterized by high values of curvature and derivatives. Both the uniformly distributed input signal and the domain of $g_1(x)$ are represented by the interval $[x_1, x_{p+1}) = [-1, +0.99993896484375)$. The ordinate of this function ideally goes from $-\infty$ to $+\infty$, what is expected since the output is an unlimited normally distributed signal.

One advantage of implementing a nonuniform sampling scheme for the interpolation of $g_1(x)$ is the lower RAM space necessary for storing both the $g_1(x_{n_m})$ ordinates and $g_1'(x_{n_m})$ derivatives, allied to a lower approximation error. As a counterexample, if we use a uniform sampling scheme instead of the proposed nonuniform one, we would face high approximation error around the poles of (14), even using high frequency samplings, as seen in Figure 3. These

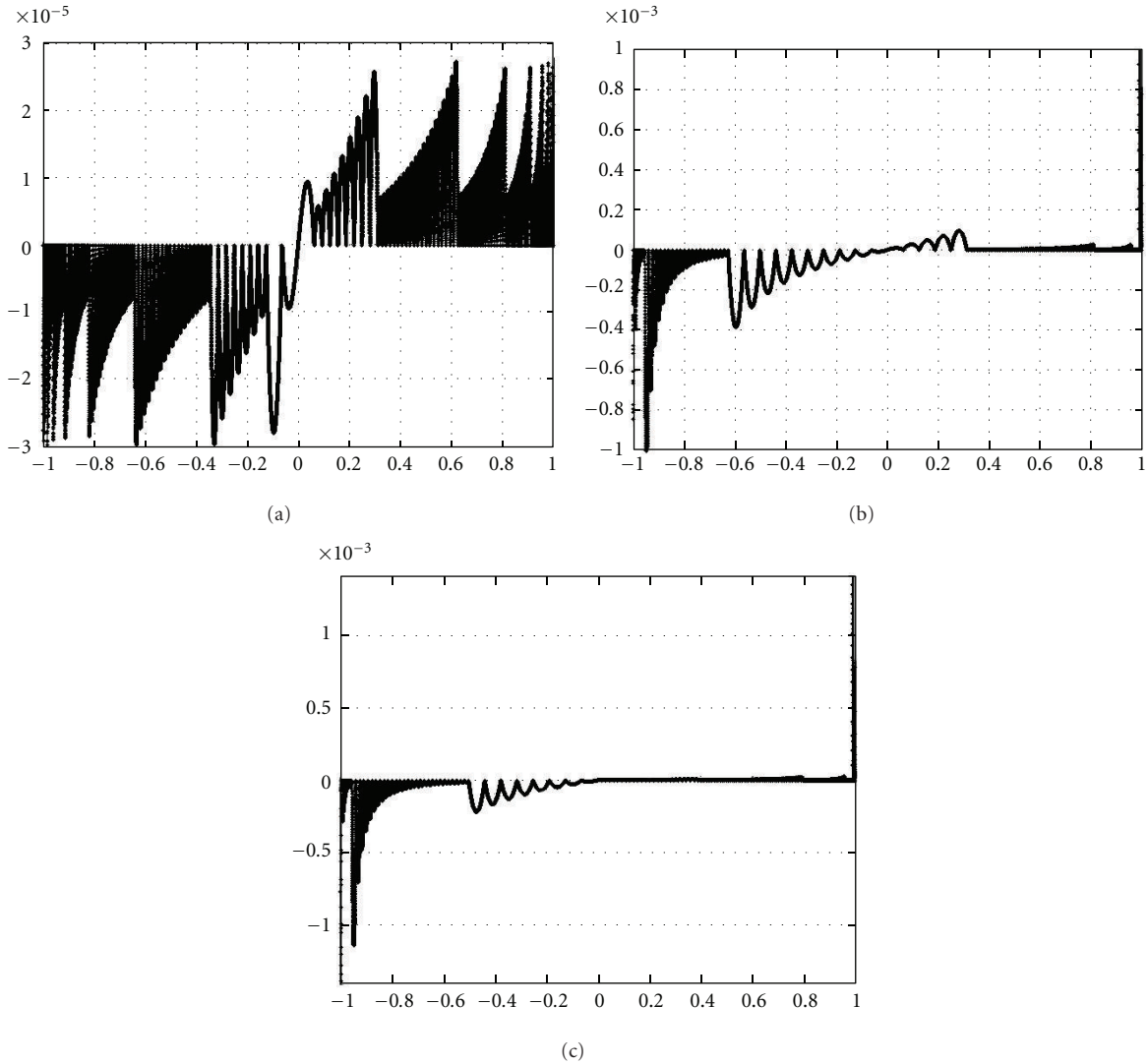


FIGURE 8: Approximation error obtained for the Displaced Error Function (15) using the sampling schemes α (a), β (b), and γ (c).

graphs show the absolute approximation error verified when two different uniform sampling schemes were applied to the whole $[x_1, x_{p+1})$ domain: the upper graph shows the error for $f_n = 128$, what requires the storage of $i_n = 256$ positions of $g_1(x_{n_m})$ ordinates plus $i_n = 256$ for $g'_1(x_{n_m})$ derivatives; and the lower graph (observe the zoom on x axis) shows the error for the case where $f_n = 16384$, that results in $i_n = 32768 + 32768 = 65536$ positions for both RAM blocks. The horizontal line in Figure 3 represents a boundary approximation error limit equal to 3.0518×10^{-5} : the input values are 15 bits long, and any error lower than that boundary does not decrease the quality of the interpolation.

If a uniform sampling scheme is used, the only solution to keep the absolute approximation error below this boundary for all abscissas x would be to use $f_n = 32768$, what makes the approximation error equal to zero for all possible abscissas x . This happens because, in this extreme case, there

is not a really interpolation, but a one-to-one mapping of all possible input values x . But such linear sampling scheme requires a RAM block with a high depth equal to $i_n = 65536$ positions for storing $g_1(x_{n_m})$, hard to implement on an FPGA due to the number of bits necessary to represent each stored value.

The solution is to use the proposed nonuniform sampling scheme which stores less $g_1(x_{n_m})$ ordinates and $g'_1(x_{n_m})$ derivatives for input values around $x = 0$, and more samples near the poles $x = +1$ and $x = -1$, where the approximation error is bigger, saving significant amount of memory space (the proposed LUT-based interpolator reserves only 512 positions for each ordinate and derivative RAM blocks). This approach is graphically presented in Figure 4, where you can see the 1st quadrant of $g_1(x)$ —the 3rd quadrant is not displayed since it is symmetric in relation to the origin $(0, 0)$. The absolute approximation error obtained with this

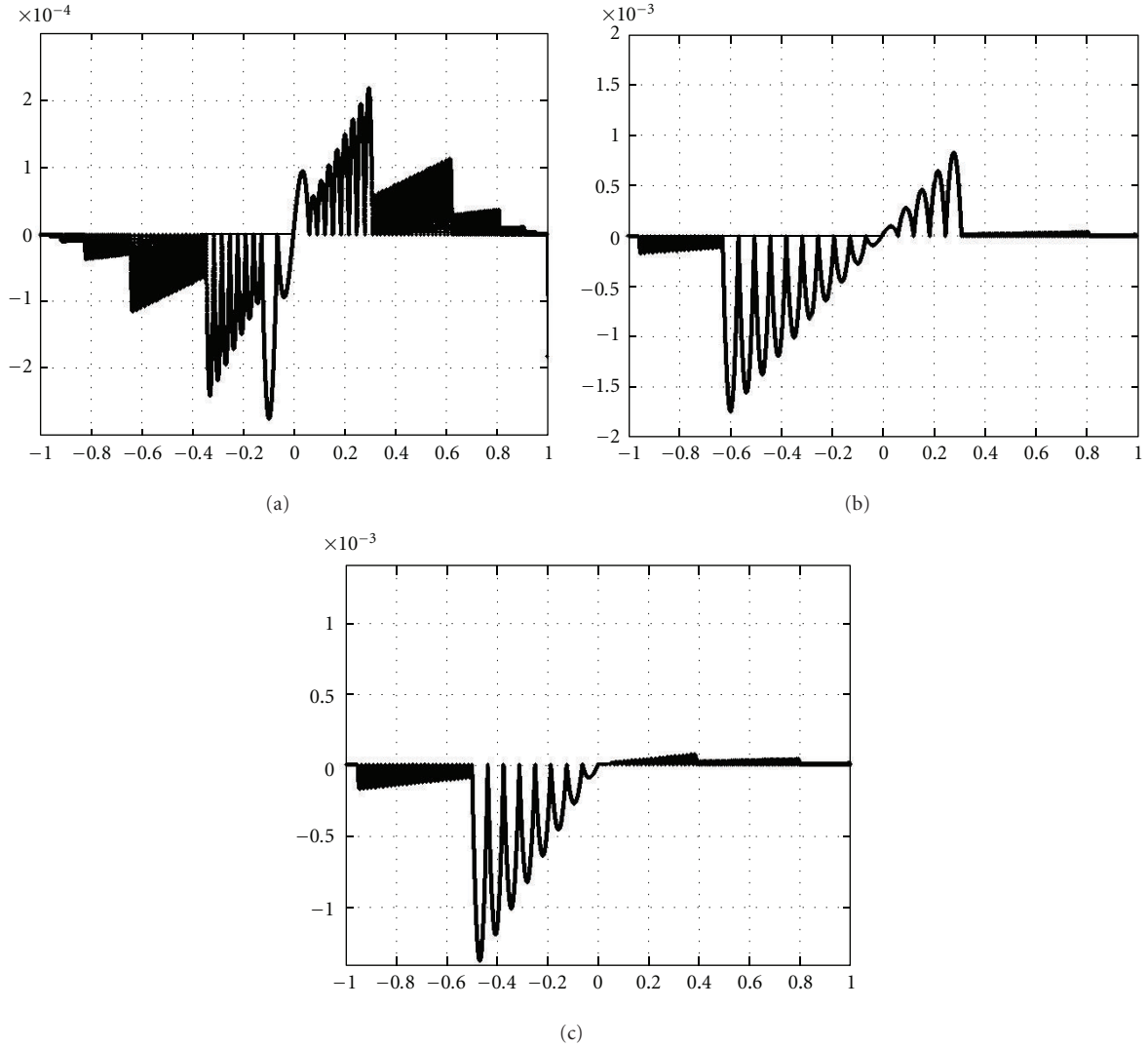


FIGURE 9: Approximation error obtained for the Cubic Function (18) using the sampling schemes α (a), β (b), and γ (c).

nonuniform approach remains under the boundary limit (3.0518×10^{-5}) even near the poles of $g_1(x)$, as seen in Figure 5.

When the proposed programmable nonuniform LUT-based interpolator is configured to represent (14), according to the sampling scheme of Tables 1 and 2, it works as a Gaussian noise generator: by applying to its input a signal with a uniform PDF (Figure 6(a)), it outputs a signal with Gaussian PDF (Figure 6(b)).

Tables 1 and 2 are just one example of configuration data for the proposed programmable LUT-based interpolator. In this work, 3 different sampling schemes (α , β , and γ) were formulated. The sampling scheme α was the one demonstrated in Tables 1 and 2. The abscissas x_{n_m} of sampling schemes α , β , and γ are plotted in Figure 7. As can be seen in these figures, there are $\sum_{n=1}^P i_n = 445$ sampling points on scheme α , $\sum_{n=1}^P i_n = 374$ on scheme β , and $\sum_{n=1}^P i_n = 390$ on scheme γ . As expected, the amount of sampling points is always smaller than the depth (equal to

512) of the two RAM blocks that store the corresponding ordinates $g(x_{n_m})$ and derivatives $g'(x_{n_m})$. Observe that the inclination on these graphs is inversely proportional to the sampling frequency f_n of each partition n : the higher the frequency f_n , the bigger the number of abscissas x_{n_m} , and the smaller the inclination in Figure 7.

To show the flexibility of the proposed design, the three sampling schemes (α , β , and γ) discussed above were applied to eight different $g(x)$ transformation functions, represented by (14) to (21), which gave us a total of 24 different examples for configuring the proposed LUT-based interpolator. These equations were selected as mathematical examples, and they are not related to the generation of noise with a natural response:

$$g_2(x) = 3 + \sqrt{2}\sigma_y \operatorname{erf}^{-1}(x), \quad (15)$$

$$g_3(x) = -\frac{1}{x^2 - 1}, \quad (16)$$

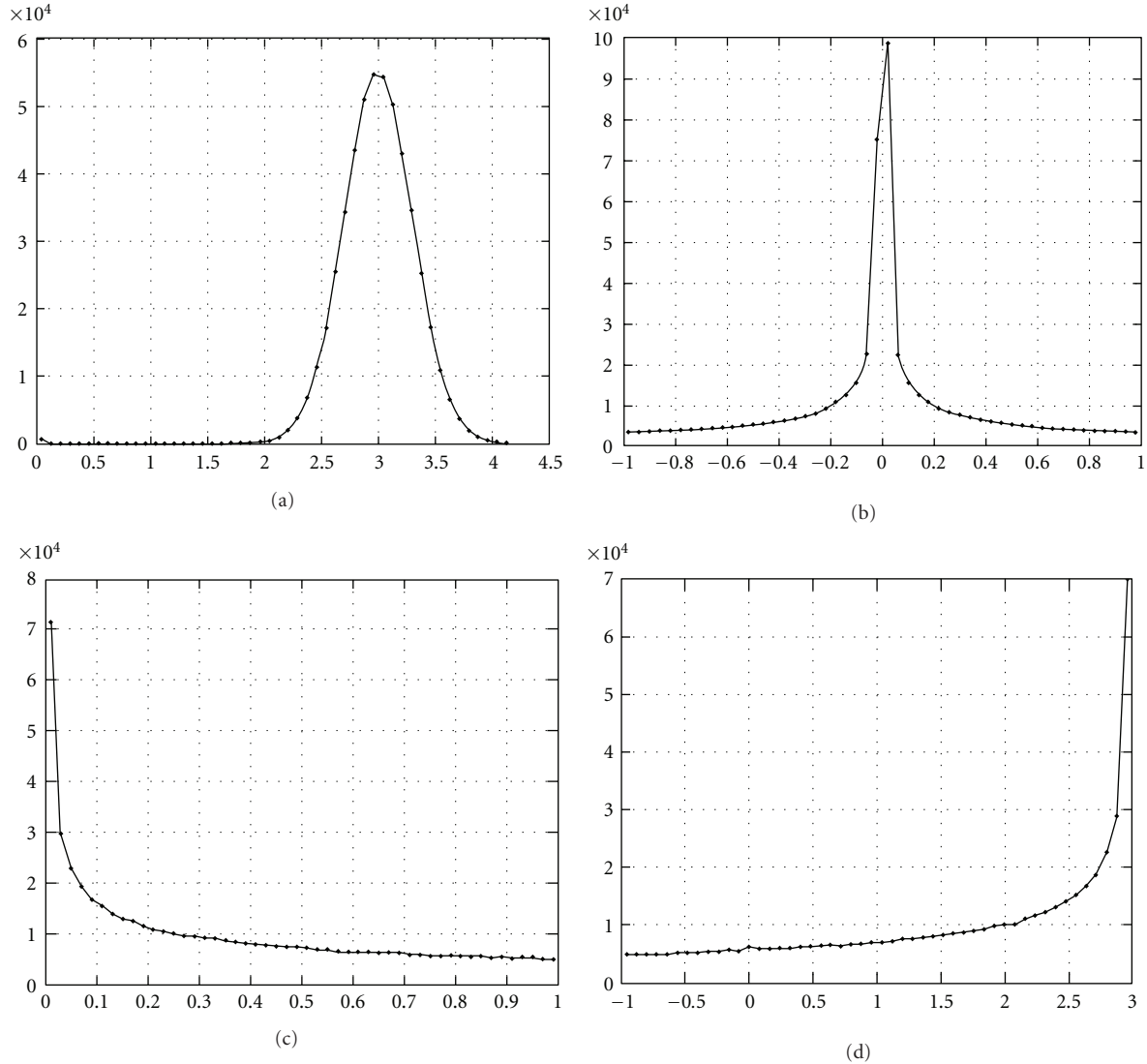


FIGURE 10: Probability density function (PDF) of the output signal obtained with the sampling scheme α and the following functions ((a) to (d)): Displaced Error Function (15), Cubic Function (18), first (19) and second Quadratic Function (20).

$$g_4(x) = e^x, \quad (17)$$

$$g_5(x) = x^3, \quad (18)$$

$$g_6(x) = x^2, \quad (19)$$

$$g_7(x) = -x^2 - 2x - 2, \quad (20)$$

$$g_8(x) = x^2 - 6x - 25. \quad (21)$$

Each sampling scheme was designed to minimize the approximation error for x abscissa values belonging to the sampling region with higher f_n values. As a matter of fact, high frequencies should be used for regions where $g(x)$ presents a strong nonlinear behavior and low frequencies for regions with a linear behavior. For example, the sampling scheme α was specifically designed for the Gaussian transformation function (14). It applies high frequencies ($f_n = 16384$) near the poles $x = +1$ and $x = -1$ and

low frequencies ($f_n = 32$) near the origin $x = 0$. The approximation error for the three sampling schemes α , β , and γ can be seen in Figure 8, in a case of using the displaced Gaussian transformation function (15), and in Figure 9, for the Cubic Function (18) case.

The frequency assignment of the $P = 22$ partitions for sampling schemes β and γ is presented in Table 4. The corresponding configuration parameters for these sampling schemes are calculated via (2) to (12) and are presented in Tables 5 and 6. Observe that the sampling limits x_n for sampling scheme β are the same as sampling scheme α , only the frequencies f_n are distributed differently. But in the sampling scheme γ , both sampling limits x_n and the frequencies f_n are distributed differently from sampling schemes α and β , what shows the flexibility for reconfiguring the designed programmable noise generator.

As seen in Table 1, the scheme α distributes the $P = 22$ sampling frequencies f_n symmetrically to the origin, with the

lower frequencies near the origin, as can be graphically seen in Figures 8 and 9 (upper graphs): the semiarcs with bigger diameters (related to $f_n = 32$) are located around the origin, in the interval $-0.125 < x < 0.125$. As seen in Table 4, the schemes β and γ distribute the lower sampling frequencies ($f_n = 32$) on the intervals $-0.64 < x < 0.34$ and $-0.5 < x < 0.0$, respectively, as can be graphically seen in Figures 8 and 9((b) and (c) graphs, resp.).

The designed programmable noise generator can generate different noise signals by properly filling the ordinate $g(x_{n_m})$ and the derivative $g'(x_{n_m})$ RAM blocks (Figure 1) and configuring its internal parameters on the *Difference Address* subsystem (Figure 2). For example, Figure 10 shows the Probability Density Functions (PDFs) of four different signals produced by the programmable noise generator when: (1) its input is fed with a uniform distributed noise, (2) it is configured with the sampling scheme α , and (3) it was configured to interpolate four different functions: the Displaced Error Function (15), the Cubic Function (18), the first (19), and the second (20) Quadratic Function.

5. Conclusion

A programmable Look-Up Table-based interpolator with nonuniform sampling scheme was implemented using a *Avnet* development kit containing an XC3S2000-5 FG676 Xilinx Spartan-3 FPGA. This LUT-based interpolator can be programmed on the fly by loading the proper configuration parameters presented in Section 2, including the $g(x_{n_m})$ ordinate and $g'(x_{n_m})$ derivative, inside RAM blocks. The complete reconfiguration takes 512 clocks cycles. When these parameters are changed, they can interpolate different $g(x)$ functions, sampled according to different nonuniform sampling schemes. The ability of changing the sampling scheme allows the minimization of both the approximation error and memory space: for instance, the sampling schema α (Table 1) applied to (14) was able to keep the approximation error below a threshold of 3.0518×10^{-5} while reducing the memory usage to 2.71% for a Gaussian noise generator application.

As a study case, the LUT-based interpolator was used as the core of a programmable noise generator able to output signals with different Probability Density Functions (PDFs). The flexibility of this design was proved by interpolating 8 different $g(x)$ functions, according to 3 different nonuniform sampling schemes (α , β , and γ) described in Tables 1 and 4, each one defining $P = 22$ partitions each characterized by a chosen sampling frequency f_n .

As future work, we recommend the implementation of a programmable nonuniform LUT-based interpolator with a domain not fixed to $[x_1, x_{P+1}] = [-1, +1]$ and where the number P of sampling regions can be changed on the fly.

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