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# Cold-formed steel beam-to-column bolted connections for seismic applications

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## Abstract

Cold-formed steel (CFS) portal frames are gaining increased popularity around the world. The structural performance of these frames is to a large extent controlled by the CFS beam-to-column connections, which in most practical applications transfer the loads through the beam web using a gusset plate, while the flanges are left unconnected. This can lead to premature local buckling failure of either the CFS beam web in the connection zone or the gusset plate, leading to poor seismic performance. This paper aims to develop two new connection configurations which engage the flanges in the connection behaviour. In conjunction, practical seismic design recommendations are presented, which allow a balance between the load carrying capacity of the connections and their seismic performance to be reached. Detailed Finite Element connection models, taking into account material nonlinearity and initial geometric imperfections, are developed and validated against experimental data. The validated FE models are then used to conduct a comprehensive parametric study to investigate the effects of key design parameters, including the beam thickness and the gusset plate shape and thickness, on the moment-rotation behaviour of the connections. Based on the results, suitable connections, which balance strength with seismic performance, are introduced. Their seismic performance is evaluated in terms of ductility, energy dissipation and damping coefficient, leading to some practical design recommendations commensurate with different seismic performance levels.

28 **Keywords:** Cold-formed steel (CFS); Moment-resisting connections; Flange-connected joints;  
29 Optimum design; Performance based design; Ductility

30

## 31 **1 Introduction**

32 The demand for cold-formed steel (CFS) systems has significantly increased over the past  
33 decade. Among them, CFS portal frames have become a popular structural system, mainly for  
34 single-storey industrial buildings. The seismic performance of CFS frames is to a large extent  
35 controlled by the beam-to-column connections, which are implemented in a fundamentally  
36 different way compared to the traditional frames composed of hot-rolled sections.  
37 Consequently, the use of CFS moment-resisting frames in seismic regions is still very limited  
38 due to the challenges associated with developing resilient moment-resisting CFS connections  
39 that can prevent premature local buckling failure of the thin-walled elements. As a result, strap-  
40 braced load-bearing stud walls [1–5] are currently the dominant lateral force-resisting system  
41 used in multi-storey CFS structures, while moment-resisting frame systems are generally  
42 reserved for low-rise CFS portal frames.

43 The behaviour and design of CFS Web-Connected (W-C) bolted connections have been  
44 previously investigated experimentally and numerically in several research studies. Chung and  
45 Lau [6] and Wong and Chung [7] carried out a series of experiments on CFS bolted beam-to-  
46 column connections, using various shapes of gusset plates. They demonstrated the practical  
47 feasibility of these connections, which achieved a moment resistance ranging between 42%  
48 and 84% of the bending moment capacity of the beam and exhibited a semi-rigid response.  
49 Similar observations were reported by Lim and Nethercot [8], who tested apex and eaves joints  
50 of CFS portal frames to study their behaviour under monotonic bending. The joints failed by  
51 cross-sectional instability of the beam, triggered by web buckling. The authors also identified  
52 an increased bolt group length and an increased number of bolts as the main factors which can

53 improve the rotational stiffness of the connections. Dubina et al. [9] tested eaves and apex joints  
54 of portal frames under monotonic and cyclic loading and observed bearing elongations of the  
55 bolt holes, as well as local buckling failure in the beam adjacent to the connection, which led  
56 to a low overall ductility. In the same study, full-scale testing of a pair of portal frames with  
57 bolted connections revealed that these systems lose their capacity rapidly once local buckling  
58 occurs in the connections. In another relevant study, Zhang et al. [10] carried out three full-  
59 scale tests of portal frames and concluded that the stiffness of the eaves and apex connections  
60 significantly depends on the bolt tightness and the bracket (i.e. gusset plate) dimensions. Blum  
61 and Rasmussen [11] also quantified the stiffness of portal frame connections based on the  
62 results of a series of experiments, while Bučmys et al. [12] used an approach based on the  
63 component method. In another study, Rinchen and Rasmussen [13] established simplified  
64 nonlinear moment-rotation relationships for eaves, apex and base connections. More recently,  
65 Sabbagh and Torabian [14] conducted a proof-of-concept study on a joist-stud framed design  
66 for semi-rigid floor-to-wall connections and proposed a method to estimate the rotational  
67 stiffness of such connections.

68 Several studies have demonstrated the capacity of W-C connections to be considerably  
69 affected by the bolt group length [8,15–19]. This effect was initially attributed by Lim et al. [8]  
70 to the presence of a bimoment in the connection, and different design approaches were  
71 presented using the Direct Strength Method (DSM) and the Direct Design Method (DDM) to  
72 account for this bimoment [15–17]. However, more recently, Mojtabaei et al. [18,19] have  
73 argued that the influence of the bolt group length in doubly symmetric beam sections can  
74 instead be attributed to a shear lag effect, and the researchers subsequently proposed design  
75 equations for the connection strength under various load combinations.

76 The cyclic behaviour of CFS beam-to-column W-C connections was studied  
77 experimentally and numerically by Sabbagh et al. [20,21]. It was reported that curved beam

78 flanges and welded-in vertical beam stiffeners delayed local buckling failure and improved the  
79 bending moment capacity and ductility by 35% and 75%, respectively. The connections were  
80 categorised as ‘Rigid’, based on their rotational stiffness determined according to Eurocode 3  
81 [22]. A similar experimental study was conducted by Serror et al. [23]. However, in this case,  
82 the column consisted of a hot-rolled profile. It was reported that the presence of stiffeners in  
83 the beam improved the connection characteristics, while additional flange bends averted  
84 premature buckling of the flanges but could not prevent buckling of the web.

85 Shahini et al. [24] numerically and experimentally investigated the effect of different bolt  
86 arrangements on cyclic connection behaviour, and demonstrated that a circular arrangement  
87 with slotted holes in the gusset plate can delay local buckling failure in the CFS beam and  
88 consequently improve the cyclic response. In a similar study, Ye [25] developed detailed Finite  
89 Element (FE) models of CFS moment-resisting connections while taking into account material  
90 nonlinearity and geometric imperfections and studied the effects of key design parameters,  
91 such as the cross-sectional shape of the beam and the bolt arrangement, on the cyclic  
92 performance. In a follow-up study by Ye et al. [26], the seismic characteristics of beam-to-  
93 column connections which mobilise a friction-slip fuse mechanism were assessed and  
94 compared with similar connections where bolt slippage is prevented. However, no  
95 experimental verification of the feasibility of prestressing CFS connections was provided as  
96 part of this study. Mojtabaei et al. [27] improved the seismic performance of bolted moment  
97 connections in terms of ductility and energy dissipation by using optimised CFS beams with  
98 enhanced non-linear post-buckling behaviour.

99 Currently, CFS moment-resisting connections are mostly implemented as W-C  
100 connections. This has the implication that, unlike in moment-resisting connections in hot-  
101 rolled steel structures, the beam and column flanges do not directly participate in transferring  
102 the applied loads. This considerably affects the stiffness, load bearing capacity and resilience

103 of these connections, especially under extreme loading events such as earthquakes and blast.  
104 Virtually no research exists which explores alternative CFS moment-resisting connection  
105 geometries, in particular with respect to the effects of connecting the flanges in various ways  
106 to obtain stiffer connections with higher moment capacities. More generally, there is still  
107 insufficient knowledge about the behaviour of CFS moment-resisting connections (especially  
108 in seismic areas) and this results in low confidence among designers and fabricators, hampering  
109 the further evolution and implementation of CFS structures. More research is needed regarding  
110 the structural performance parameters of CFS connections, particularly focusing on their  
111 deformability, ductility, and energy dissipation capacity.

112 The present work aims to address these important issues by developing and studying two  
113 new configurations of beam-to-column bolted connections: Flange-Connected (F-C) and Web-  
114 and-Flange-Connected (WF-C) joints, which benefit from the load transfer contribution of the  
115 flanges. The performance of the newly proposed connections is compared to that of the  
116 conventional Web-Connected (W-C) connections (see Table 4). To achieve this, detailed  
117 ABAQUS [28] FE models were employed, which were first validated against experimental  
118 results. A parametric study further investigated the effect of key design parameters, such as the  
119 beam thickness and the gusset plate shape and thickness, on the moment-rotation behaviour of  
120 each type of connection. The connections with the overall best performance, considering both  
121 capacity and rotational behaviour, were identified and compared in terms of ductility, energy  
122 dissipation and damping coefficient, leading to practical seismic design guidance linked to  
123 different seismic performance levels.

## 124 **2 Description of the ABAQUS numerical models**

125 Sabbagh et al. [20] previously carried out a comprehensive experimental programme on  
126 W-C connections, where the webs of back-to-back channel beam and column sections were  
127 bolted to a gusset plate. The web panel zone was stiffened to prevent local failure in the column,

128 in alignment with the commonly accepted strong-column/weak-beam philosophy in earthquake  
 129 engineering. More detailed information about these experiments can be found in [29]. In this  
 130 section, the results of two of these tests, pertaining to specimens A1 and B1, which were tested  
 131 under cyclic loading conditions, were selected to validate the numerical models. The models  
 132 were developed using the ABAQUS software [28] and accounted for material nonlinearity and  
 133 initial geometric imperfections. Various previous studies have demonstrated that the adopted  
 134 modelling approach, described below, can be used to simulate the nonlinear behaviour of CFS  
 135 systems in an effective and reliable way [17,21,26,30,31].

## 136 **2.1 Material properties**

137 The nonlinear stress-strain relationships of the CFS beam and the gusset plate materials  
 138 were incorporated in ABAQUS [28] utilizing a two-stage material model proposed by  
 139 Heidarali and Nethercot [32], fitted to the results of coupon tests reported by Sabbagh et al.  
 140 [29]. In a first stage, the stress-strain behaviour was defined up to the 0.2% proof stress ( $\sigma_{0.2}$ )  
 141 using Eq. (1), initially proposed by Ramberg and Osgood [33] and later modified by Hill [34].  
 142 A straight line with a slope  $E = \frac{E_0}{100}$  was used in the second stage, as expressed by Eq. (2). In  
 143 Eqs. (1) and (2),  $\varepsilon_{0.2}$  is the strain corresponding to the  $\sigma_{0.2}$  proof stress,  $E_0$  stands for the elastic  
 144 modulus (which was taken as 210 GPa), and  $n$  is a constant which was assumed equal to 10,  
 145 as recommended by Rasmussen [35].

$$\varepsilon = \frac{\sigma}{E_0} + 0.002 \left( \frac{\sigma}{\sigma_{0.2}} \right)^n, \quad \sigma \leq \sigma_{0.2} \quad (1)$$

$$\varepsilon = \varepsilon_{0.2} + \frac{\sigma - \sigma_{0.2}}{E}, \quad \sigma \geq \sigma_{0.2} \quad (2)$$

146 In a next step the engineering strains and stresses were converted to logarithmic plastic  
 147 strains and stresses, while the linear kinematic hardening rule available in ABAQUS was  
 148 adopted to simulate the hardening behaviour of the material. The (engineering) material

149 properties of the connection components are summarised in Table 1 for reference tests A1 and  
150 B1.

## 151 **2.2 Finite element type and mesh size**

152 The S4R general-purpose finite element available in ABAQUS was employed to model all  
153 connection components, since it has previously proven to be accurate in capturing the  
154 behaviour of CFS elements and connections [18,19,31,36,37]. This four-noded shell element  
155 has six degrees of freedom per node. It can account for nonlinear material properties and finite  
156 membrane strains, and features hourglass control and reduced integration. Following a mesh  
157 sensitivity analysis, a mesh size of 10×10 mm was selected to guarantee adequate numerical  
158 accuracy while keeping the computational time within acceptable limits.

## 159 **2.3 Bolt modelling**

160 The bolt behaviour was simulated by employing the Discrete Fastener feature of the  
161 ABAQUS software [28]. This modelling technique creates attachment lines between the  
162 fastening points located on the connecting surfaces, as shown in Fig. 1(a-b). An influence  
163 radius was assigned to each fastening point, with the implication that the displacements of the  
164 fastening points are coupled to the average displacements of the nodes within this radius. An  
165 influence radius equal to 8 mm was used in the FE models, corresponding to half the bolt  
166 diameter, as recommended in [18,31]. In this study, rigid bearing behaviour was assumed for  
167 the bolts connecting the column to the gusset plate, while combined friction and bearing  
168 behaviour was modelled for the beam to gusset plate bolts. This was motivated by the fact that  
169 bolt hole elongation is typically more critical in the beam due to its lower thickness compared  
170 to the column and the gusset plate. In the A1 and B1 tests, preloading forces of  $P_b=88$  kN and  
171  $P_b=70$  kN, respectively, were applied to the head of the bolt by using a torque wrench, which  
172 generated friction between the beam web and gusset plate. When friction is overcome, bearing



173 action of the bolts is mobilised, which was modelled using the equations proposed by Fisher  
174 [38]:

$$R_B = R_{ult} [1 - e^{-\mu \left( \frac{\delta_{br}}{25.4} \right)}]^\lambda \quad (3)$$

$$R_{ult} = 2.1dtF_u \quad (4)$$

175 where  $R_B$  is the bearing force,  $R_{ult}$  is the ultimate bearing strength,  $\delta_{br}$  is the bearing  
176 deformation (in mm),  $t$  is the plate thickness,  $d$  is the bolt diameter,  $F_u$  is the ultimate tensile  
177 strength of the plate material, and  $\mu$  and  $\lambda$  are constants equal to 5 and 0.55, respectively,  
178 according to the recommendations by Uang et al. [39]. The load-displacement behaviour of the  
179 bolts obtained from the above-mentioned equations is shown in Fig. 2 for tests A1 and B1. It  
180 should be noted that in experiments A1 and B1 [29], no bolt shear failure was observed.

## 181 **2.4 Boundary conditions and interactions**

182 The boundary conditions imposed onto the FE models of the W-C connections are shown  
183 in Fig. 3. All three translational degrees of freedom of the nodes at the bottom of the column  
184 were restrained ( $U_X=U_Y=U_Z=0$ ), while the horizontal displacements of the top nodes were also  
185 restrained ( $U_X=U_Y=0$ ). The out-of-plane deformations of the beam were prevented at the  
186 locations where the lateral bracing system was positioned in the experiments (see Fig. 3). The  
187 webs of the back-to-back channels were connected at three different locations using “Tie”  
188 constraints to simulate the bolts outside the connection zone. Additionally, tie constraints were  
189 used to connect the column stiffeners rigidly to the column web and flanges. The “Hard”  
190 contact feature was employed between the connecting faces of the beam webs and the gusset  
191 plate to avoid penetration of the surfaces into each other. All degrees of freedom of the beam  
192 end section, where the external load was applied, were coupled to a Reference Point (RP)  
193 located at mid-height of the webs.

## 194 2.5 Initial geometric imperfections

195 In the experiments, as well as in the FE model, the global buckling mode of the CFS beam  
196 was prevented due to the presence of the lateral bracing system. Hence, only a local or a  
197 distortional imperfection (whichever mode had the lower critical buckling load) was included  
198 in the FE models. Imperfection amplitudes of  $0.94t$  and  $0.34t$  (where  $t$  is the plate thickness)  
199 were used for the distortional and local imperfections, respectively, as recommended by  
200 Schafer and Peköz [40]. These are the 50% values of the cumulative distribution function of  
201 experimentally measured imperfections and represent ‘most probable’ values. Since these  
202 amplitudes are only applicable for  $t \leq 3$  mm, Walker’s [41] equation was instead used for plate  
203 thicknesses larger than 3 mm:

$$w_d = 0.3t \lambda \quad (5)$$

204 where  $w_d$  is the imperfection amplitude and  $\lambda$  represents the cross-sectional slenderness, which  
205 is calculated as:

$$\lambda = \sqrt{\frac{M_y}{M_{cr}}} \quad (6)$$

206 In the above equation,  $M_y$  is the yield moment of the cross-section and  $M_{cr}$  is the elastic  
207 local/distortional buckling moment, which was obtained using the CUFSM software [42]. To  
208 generate the overall shape of the geometric imperfections, an elastic eigenvalue buckling  
209 analysis was performed in ABAQUS. The shape of the critical buckling mode was then scaled  
210 by the appropriate imperfection amplitude.

211 It should be noted that previous research on CFS portal frame connections failing by local  
212 buckling [18] has demonstrated through sensitivity studies that the connection capacity is only  
213 affected to a very minor extent by imperfections. This is somewhat expected, since the local  
214 mode has a stable post-buckling range, and no interaction with other modes takes place in the

215 problem under consideration [43].

## 216 **2.6 Loading**

217 The FE models of the connections were loaded in a displacement controlled manner under  
218 both monotonic and cyclic conditions. While a maximum displacement of 200 mm was applied  
219 for monotonic loading, in the cyclic analyses the loading protocol presented in section S6.2 of  
220 the AISC 341-16 [44] provisions (as used in the corresponding experiments) was adopted. This  
221 protocol includes the following steps (Fig. 4):

222 (1) 6 cycles at  $\theta = 0.00375$  rad

223 (2) 6 cycles at  $\theta = 0.00500$  rad

224 (3) 6 cycles at  $\theta = 0.00750$  rad

225 (4) 4 cycles at  $\theta = 0.010$  rad

226 (5) 2 cycles at  $\theta = 0.015$  rad

227 (6) 2 cycles at  $\theta = 0.02$  rad

228 (7) 2 cycles at  $\theta = 0.03$  rad

229 (8) 2 cycles at  $\theta = 0.04$  rad

230 (9) Continue loading in increments of  $\theta = 0.01$  rad, applying two cycles of loading in each step.

## 231 **2.7 Numerical model validation**

232 ‘Static General’ analyses were carried out using the High-Performance Computing (HPC)  
233 facilities at the University of Sheffield.

234 Fig. 5 compares the moment-rotation relationships extracted from experiments A1 and B1  
235 with the corresponding FE predictions for both cyclic and monotonic loading conditions. The  
236 bending moments were made dimensionless relative to the plastic moment of the CFS beam  
237 ( $M_p$ ) and the rotation of the connection was determined as the ratio of the beam tip  
238 displacement to the length of the beam up to the gusset plate.

239 Fig. 5 indicates that the FE models were able to simulate the behaviour of both tested  
240 connections with good accuracy over the whole loading range. The initial stiffnesses of the  
241 tested connections were virtually identical to those obtained from the FE models, while the  
242 experimental and predicted flexural capacities compared as 54.3 kNm and 51.6 kNm for test  
243 A1, and 81.7 kNm and 82.4 kNm for test B1. A comparison between the FE cyclic and  
244 monotonic results also indicated that the initial stiffness and the connection capacities were  
245 coincident in both cases. However, the results of the monotonic analyses slightly  
246 underestimated the cyclic stiffness degradation rate. Failure of the connections under both  
247 monotonic and cyclic loading was predicted by the FE analyses to be initiated by local buckling  
248 of the beam web, followed by buckling of the compression flange, consistent with the  
249 experiment, as shown in Fig. 6. These observations confirm the adequacy of the adopted FE  
250 models in this study. It should be noted that these modelling techniques have also been verified  
251 against experiments reported by Lim and Nethercot [8] in two recent publications by the  
252 authors [18,19].

### 253 **3 Development of new connection configurations**

254 This section discusses the development of two new configurations of bolted CFS beam-to-  
255 column connections, which are capable of transferring the applied loads through either the  
256 flanges only (F-C connection) or both the flanges and the webs (WF-C connection). The  
257 behaviour and failure mechanism of these connections, alongside W-C connections of the type  
258 introduced in Section 2, were investigated under monotonic loading conditions while  
259 considering various beam thicknesses and gusset plate shapes and thicknesses. The obtained  
260 moment-rotation curves were compared in terms of their relevant performance criteria,  
261 including the bending moment capacity, the ultimate rotation and the rotational rigidity in  
262 relation to code-prescribed categories. As shown in the previous section, the monotonic loading  
263 results can be considered representative of both monotonic and cyclic loading when

264 considering these parameters. The connections displaying the best performance were identified  
265 for each connection configuration (W-C, F-C and WF-C) and were further investigated under  
266 cyclic loading.

### 267 **3.1 Connection configurations**

268 The proposed W-C connections are assembled by bolting a gusset plate in between the  
269 webs of the beam and the webs of the column. The choice of the gusset plate shape is a rather  
270 challenging issue encountered in practice since it may cause either architectural limitations or  
271 reductions in structural performance. Therefore, as shown in Table 2, three different gusset  
272 plate shapes were selected in this study, including a T-shaped plate with sharp corners (further  
273 referred to as the ‘T-shape’), a T-shaped plate with rounded corners (the ‘rounded T-shape’)  
274 and the rectangular plate with chamfered corners which was employed in the experiment (see  
275 Section 2), which is simply referred to as the ‘Chamfered shape’. The transition radius of the  
276 rounded T-shape was chosen as 350 mm in this study. In Table 4, 3D graphical representations  
277 of the different joint configurations are presented.

278 For the F-C connection configuration, either ‘unstiffened’ or ‘stiffened’ top and seat angles  
279 were used, bolted to the column and beam flanges, as shown in Table 2. The stiffened angles  
280 contained an infill plate to form a haunch. The WF-C connections, on the other hand, were  
281 conceived as a combination of the other two configurations, where both a T-shaped gusset plate  
282 and unstiffened top and seat angles were used. The bolt group length ( $l_b$ ) in the CFS beam was  
283 consistently taken equal to the beam depth ( $h$ ), and a fixed number of bolts was used in each  
284 type of connection, as illustrated in Table 2. However, the thicknesses of the CFS beam and  
285 the gusset plate were varied to investigate their effects and identify the slenderness limits where  
286 failure shifted from the gusset plate to the beam. The CFS beam was assigned thicknesses  $t_b =$   
287 1, 2, 4 and 6 mm, whereas the gusset plate thickness was taken as a multiple of the beam  
288 thickness (see Table 2). It is thereby noted that for the chosen beam dimensions  $t_b = 1, 2, 4$  and

289 6 mm correspond to Class 4, 3, 2 and 1 cross-sections according to EC3 [45], respectively. The  
290 critical local and distortional buckling stresses for each thickness are listed in Table 3.

291 The other design parameters were kept constant across all connection models, including the  
292 material properties, the locations of the lateral bracing, the lengths of the members, the cross-  
293 sectional dimensions and the thickness of the column and its stiffeners (Fig. 7). The 2000 mm  
294 long beam and 900 mm long column segments used in the FE models consisted of back-to-  
295 back lipped channel and plain channel sections, respectively, with the dimensions (along the  
296 centrelines) given in Fig. 7. The modelled beam segment can be considered representative of  
297 the part of a beam in a moment-resisting frame between the point of contraflexure and the  
298 column. The material properties listed in Table 1 were used for all FE models. Lateral bracing  
299 was provided along the length of the beam at 500 mm spacing.

## 300 **3.2 Evaluation of connections under monotonic loading**

### 301 **3.2.1 Performance criteria**

302 The rotational behaviour of the connections was quantified through various performance  
303 parameters related to their (i) rotational rigidity, and (ii) rotational capacity. The latter was  
304 assessed in two distinct ways, as detailed below.

305 To assess the rigidity of the connections, the provisions of EN 1993-1-8 [22] were followed,  
306 in which the moment-rotation relationship of a connection is derived by calculating the bending  
307 moment ( $M_j$ ) at the face of the column and by taking the corresponding rotation ( $\phi$ ) as the  
308 difference between rotations ( $\phi_1$ ) and ( $\phi_2$ ), shown in Fig. 8(a). The initial stiffness ( $S_{j,ini}$ ) is then  
309 defined as the secant slope of the moment-rotation curve (see Fig. 8b) at a value of  $2/3 \times M_{j,R}$ ,  
310 where ( $M_{j,R}$ ) is the moment resistance of the connection. Subsequently, the connection is  
311 categorised as either Rigid, Semi-Rigid or Pinned, by comparing the initial stiffness ( $S_{j,ini}$ ) with  
312 the limits shown in Fig. 8(c). A Rigid (R) connection has an initial stiffness greater or equal to

313  $k_b \times E \times I_b / L_b$ , where  $k_b=25$  for an unbraced system, ( $E$ ) is the elastic modulus, ( $I_b$ ) is the second  
314 moment of area of the beam and ( $L_b$ ) is the beam span, measured between the centre lines of  
315 the columns. The connection is classified as Pinned (P) if the initial stiffness is smaller or equal  
316 to  $0.5 \times E \times I_b / L_b$ . For intermediate values, the connection is Semi-Rigid (S-R).

317 A first performance parameter adopted to assess the rotational capacity of the connections  
318 consisted of the ultimate rotation, taken equal to the minimum of 0.06 rad and the rotation  
319 corresponding to a 20% drop in moment from the peak point in the moment-rotation curve.  
320 This is based on the recommendations given by the American Seismic codes: AISC 341-16  
321 [44] and FEMA-350 [46].

322 A second indicator of inelastic rotational capacity is provided by the American Seismic  
323 Provisions for Structural Steel Buildings (AISC 341-16), in which moment-resisting frames  
324 are classified into three categories: Ordinary Moment Frames (OMF), Intermediate Moment  
325 Frames (IMF) and Special Moment Frames (SMF). The connections of SMFs and IMFs should  
326 be able to accommodate minimum storey drift angles of 0.04 rad and 0.02 rad, respectively,  
327 while OMFs do not meet the 0.02 rad value. It should be noted that using OMFs in seismic  
328 regions is prohibited by most seismic design codes.

### 329 **3.2.2 Moment-rotation results and discussions**

#### 330 **3.2.2.1 W-C connections**

331 Fig. 9 shows the moment-rotation curves obtained for the W-C connections (see Table 2)  
332 with various beam thicknesses ( $t_b$ ), gusset plate thicknesses ( $t_g$ ) and gusset plate shapes (①:  
333 T-shape, ②: rounded T-shape and ③: chamfered shape) up to their ultimate rotations. Both  
334 the moment and the rotation in Fig. 9 were calculated based on the location of failure, which  
335 was idealised to coincide with the end of the gusset plate, i.e. at a distance of 1700 mm from  
336 the cantilever tip (Fig. 7). Failure occurred by either local buckling of the beam immediately

337 adjacent to the connection (followed by distortional buckling past the peak load), or local  
338 buckling of the gusset plate.

339 It is seen that the connections with the chamfered gusset plate (i.e. ③) reached higher  
340 moment capacities ( $M_{max}$ ) than their ‘rounded T-shape’ counterparts (i.e. ②) for gusset plate  
341 thicknesses  $t_g$  with  $t_b \leq t_g \leq 1.5t_b$ , while both configurations reached the same moment capacities  
342 for gusset plate thicknesses with  $2t_b \leq t_g \leq 3t_b$ . The latter is due to gusset plate failure no longer  
343 being critical. This makes the rounded T-shape a suitable alternative to the conventional  
344 chamfered gusset plates for those higher thicknesses. The T-shaped gusset plate connections  
345 exhibited the lowest moment capacity among the three selected gusset plate shapes, which can  
346 be attributed to the abrupt change in depth of the gusset plate at the column face, leading to  
347 stress concentrations and premature buckling at the corners, especially for lower plate  
348 thicknesses.

349 Table 5 lists the dominant failure modes for all connections, which consisted of either local  
350 buckling of the CFS beam (B) or local buckling of the gusset plate (GP). Fig. 10 shows  
351 examples of the typical failure modes of the connections with T-shaped, rounded T-shaped and  
352 chamfered gusset plates for  $t_b=4$  mm and  $t_g=1.5t_b$ , where the yielding areas are highlighted in  
353 grey. It is seen that significant plasticity developed in the beam for the connection with the  
354 chamfered gusset plate, while the connections with T-shaped and rounded T-shaped gusset  
355 plates mainly experienced plasticity in the gusset plate rather than the beam.

356 All connections with T-shaped gusset plates were classified as Semi-Rigid (S-R) according  
357 to EC3 [22] (Table 5). All rounded T-shaped connections also performed as Semi-Rigid joints,  
358 with the exception of those with the thickest gusset plates connecting Class 3 or 4 beams, which  
359 were classified as Rigid (R). With the chamfered connections, however, mostly Rigid (R)  
360 connections were obtained in Class 2, 3 and 4 beams, with the exception of those with the  
361 thinnest gusset plates ( $t_g = t_b$  for Class 2-4, and  $t_g = 1.5t_b$  for Class 2), which were Semi-Rigid.



362 The ultimate rotation and the corresponding classification according to AISC 341 [44] (see  
363 section 3.2.1) are also listed in Table 5. All studied connections with Class 1 beams were  
364 categorised as Special Moment Frame (SMF) connections. The same category was obtained  
365 for the connections with Class 2 beams, except for the case where  $t_b=t_g$ . On the contrary, none  
366 of the connections with Class 3 or 4 beams performed as SMFs, which indicated that they are  
367 not suitable for regions with high seismicity.

#### 368 3.2.2.2 F-C connections

369 The F-C connections considered in this study employed either stiffened or unstiffened angle  
370 sections, instead of a gusset plate, to transfer shear and bending moments to the column (see  
371 Table 2). The thicknesses of the angle sections were taken as multiples of the beam thickness,  
372 and ranged between  $t_b$  and  $6t_b$  for the 1 mm and 2 mm thick beams, and between  $t_b$  and  $3t_b$  for  
373 the 4 mm and 6 mm thick beams (as to not exceed a maximum value of 18 mm). In the case of  
374 stiffened angles, the thickness of the stiffening plate was taken equal to the thickness of the  
375 angles. Fig. 11 presents the moment-rotation relationships, up to the ultimate rotation, for beam  
376 thicknesses of 1, 2, 4 and 6 mm, where ① and ② stand for connections with unstiffened and  
377 stiffened angles, respectively. It was observed that using stiffened angles increased both the  
378 flexural stiffness and the capacity of the connections by an average factor of 4, compared to  
379 the connections with unstiffened angles. This increase was especially evident for the  
380 connections with Class 3 and 4 beam sections (i.e. 1 mm and 2 mm thickness). Table 6 presents  
381 the failure modes of the studied F-C connections. The unstiffened angles failed due to yielding  
382 under combined bending and tension/compression, while the connections employing stiffened  
383 angles failed due to either local buckling of the stiffening plates and angle plastification  
384 (indicated with 'A' in Table 4), or local/distortional buckling of the beam (indicated with 'B').  
385 For small angle thicknesses the F-C connections with Class 2, 3 and 4 beam sections (i.e. 1, 2  
386 and 4 mm thickness) practically acted as pin connections, and are hence unsuited for seismic

387 use in unbraced moment-resisting frames. Conversely, the studied connections with Class 1  
388 beam sections (i.e.  $t_b=6$  mm) were determined to all be Semi-Rigid. Incorporating stiffened  
389 angles, as opposed to unstiffened angles, improved the rigidity of the connections from Pinned  
390 to Semi-Rigid in many cases, as shown in Table 6.

391 Due to the deformability of the unstiffened angles under combined tension/compression  
392 and bending, with a gap opening up between the beam and the column on the tension side, all  
393 connections with unstiffened angles reached an ultimate rotation of at least 0.06 rad without a  
394 significant drop in moment resistance and satisfied SMF requirements according to the AISC  
395 341 [44] classification. During these large rotations the beam remained unbuckled (see Fig.  
396 12(a)). On the other hand, stiffening the top and seat angles with infill plates dramatically  
397 reduced their deformations, and as a result, failure shifted to the beam element instead (see Fig.  
398 12(b)). In this case, the deformations and yielding on the compression side of the beam are  
399 mostly concentrated around the local buckle, with the top infill plate attracting little stress.

400 This has the potential to reduce the rotational capacity to below 0.06 rad and alter the  
401 connection behaviour from a SMF to an IMF for the larger plate thicknesses and Class 3 and 4  
402 beam sections. These results indicate that for seismic applications, using very thick stiffened  
403 angle sections to connect thin-walled beam sections may not be appropriate.

#### 404 3.2.2.3 *WF-C connections*

405 The WF-C connections consisted of a T-shaped gusset plate in combination with  
406 unstiffened top and seat angles, connecting both the web and the flanges of the beam (see Table  
407 2). The moment-rotation relationships of the studied WF-C connections, up to their ultimate  
408 rotations, are shown in Fig. 13 for different beam thicknesses (i.e.  $t_b=1, 2, 4$  and 6 mm) and  
409 gusset plate thicknesses ( $t_g=t_b, 1.5t_b, 2t_b,$  and  $3t_b$ ). The thickness of the angles was also taken  
410 equal to  $t_g$ . As expected, increasing the gusset plate and angle thicknesses generally increased

411 both the flexural capacity and the rotational stiffness of the WF-C connections. As illustrated  
412 in Fig. 14 (and listed in Table 7), the failure mode of the WF-C connections was identified to  
413 be local/distortional buckling of the CFS beam for the connections with the thickest gusset  
414 plate and angles (i.e.  $t_g=3t_b$ ), while in the other cases the failure mode was yielding of the gusset  
415 plate and/or the angles. This is reflected in the rotational capacities ( $\phi_{max}$ ) of the connections  
416 listed in Table 7: increasing the gusset plate and angle thickness up to  $t_g=2t_b$  enhanced the  
417 rotational capacity, while for higher plate and angle thicknesses the rotational capacity  
418 decreased due to distortional buckling of the CFS beam.

419 Based on the AISC [44] classification, all connections with Class 1 beam sections were  
420 categorised as SMFs. Connections using Class 2 and 3 beams also satisfied the SMF  
421 requirement when the gusset plate thickness  $t_g \leq 2t_b$ . On the contrary, WF-C connections with  
422 Class 4 beam sections always belonged to IMFs or OMFs, which indicates they are not suitable  
423 for regions with high seismicity. In terms of rotational rigidity, all connections needed to be  
424 classified as Semi-Rigid according to EC3 [22].

### 425 **3.3 Selection of most suitable connection configurations for seismic applications**

426 The results regarding the bending moment capacity, ultimate rotation, rotational rigidity  
427 and seismic classification of the connections obtained in the previous section were used to  
428 identify the connection configurations with the best overall performance for each connection  
429 type.

430 For comparative purposes, the flexural capacity of each connection was normalised with  
431 respect to the cross-sectional bending capacity of the beam  $M_{u,b}$ , obtained from the FE analysis  
432 of a beam segment subject to pure bending. This FE model is shown in Fig. 15. The beam  
433 remained laterally restrained at discrete locations (i.e. every 500 mm) to prevent global  
434 buckling. The length of the beam segment was taken as three times the distortional buckle half-

435 wave length, calculated using the CUFSM [42] software, as suggested by Shifferaw and  
436 Schafer [47]. The values of  $M_{u,b}$  obtained for the studied cross-sections with thicknesses of 1  
437 mm, 2 mm, 4 mm and 6 mm were calculated to be 10.6 kNm, 32.3 kNm, 79.3 kNm and 121.6  
438 kNm, respectively.

439 Fig. 16, Fig. 17 and Fig. 18 show the variation of  $M_{max}/M_{u,b}$  (where  $M_{max}$  is the connection  
440 capacity) for various gusset plate and beam thicknesses for the W-C, F-C and WF-C  
441 connections, respectively. These figures, along with the results presented in Tables 3, 4 and 5,  
442 were used to draw the following conclusions:

- 443 • Among the three gusset plate configurations considered for the W-C connections, the  
444 rounded T-shape and the chamfered shape are generally preferred over the plain T-shape,  
445 because of their higher flexural capacity, higher stiffness and more ductile behaviour (the  
446 latter evaluated based on the AISC 341 code). There was no significant difference between  
447 the performance of the connections with the rounded T-shape and the chamfered shape in  
448 terms of the rotational capacity, stiffness and strength for  $t_g \geq 2t_b$ . However, the rounded  
449 T-shape provides more flexibility for the installation of the floor system. Therefore, a  
450 rounded T-shaped gusset plate with a minimum thickness of  $t_g = 2t_b$  was taken forward as  
451 the preferred W-C option.
- 452 • With regard to the F-C connections, the connections with stiffened angles were  
453 demonstrated to be more suitable for seismic applications than those with unstiffened  
454 angles, due to their higher flexural capacities (see Fig. 17) and stiffnesses (see Table 6).  
455 For the connections with Class 3 and 4 beam sections, the most efficient thickness of the  
456 angles and stiffening plates was identified to be  $4t_b$ . F-C connections with this thickness act  
457 as Semi-Rigid and satisfy SMF requirements, while developing around 80% of the beam  
458 strength. For the F-C connections with Class 2 beam sections, a thickness of  $2t_b$  was  
459 preferred for the stiffened angles, as this satisfied SMF requirements while providing

460 virtually the same rotational capacity and rigidity as the connections with thicker angles.  
461 For the F-C connection with Class 1 beams, although using a plate thickness of  $3t_b$  resulted  
462 in a bending capacity which was about 10% higher than for a thickness of  $2t_b$ , it may not  
463 be practical to use, for instance, 18 mm angles. Therefore,  $t_g=2t_b$  was chosen for Class 1  
464 beam sections.

465 • For WF-C connections, a thickness  $t_g=2t_b$  was chosen for the gusset plate and the angles.  
466 These connections were able to develop more than 90% of the flexural capacity of the beam  
467 section, while maintaining a high rotational capacity and ductile behaviour according to the  
468 AISC 341 code (see Table 7).

469 Table 8 summarises the connections which were selected based on their performance with  
470 respect to the criteria in section 3.2.1. It should be noted that the dominant failure mode for the  
471 W-C and F-C connections was generally local/distortional buckling in the beam, whereas the  
472 WC-F connections exhibited yielding in the gusset plates. While it is possible to prevent  
473 yielding of the gusset plate in WF-C connections by increasing its thickness, this would reduce  
474 the ultimate rotation capacity and hence the ductility of this connection type.

#### 475 **4 Seismic evaluation of connections with balanced performance**

476 Fig. 19, Fig. 20 and Fig. 21 present the hysteretic moment-rotation relationships of the W-  
477 C, F-C and WF-C connections with ‘balanced’ seismic performance listed in Table 8, including  
478 beams of all four cross-sectional classes (i.e.  $t_b=1, 2, 4$  and  $6$  mm). The results were obtained  
479 by applying the cyclic loading protocol shown in Fig. 4 to the FE models. For comparative  
480 purposes, the cyclic moment-rotation backbone curve is also presented, which was obtained by  
481 plotting the locus of the peak moment points in the first cycle of each loading amplitude.

482 For the W-C connections with Class 3 and 4 beams, the hysteretic curves exhibited an  
483 abrupt strength degradation immediately after reaching the maximum bending moment. For

484 beams with a larger thickness (i.e. Class 1 and 2 sections), on the other hand, the connections  
485 experienced a more prolonged amount of plastic rotation before degradation commenced.

486 F-C connections with Class 2-4 beams comprised a softening branch in their hysteretic  
487 behaviour before reaching the ultimate rotation, which was again taken as the minimum of 0.06  
488 rad and the rotation at which a 20% drop from the peak moment was recorded (see Fig. 20(a),  
489 (b) and (c)). However, no strength degradation was observed in the hysteretic behaviour of the  
490 F-C connection with a Class 1 beam before the ultimate rotation, as shown in Fig. 20(d). This  
491 is attributed to the considerably lower slenderness of both the beam and the stiffened angle  
492 elements in this case, reducing their susceptibility to local buckling.

493 The moment-rotation curves of the WF-C connections indicated that, in general, the  
494 connection responses were characterised by plastic strain hardening without any strength  
495 degradation. This was due to the opening and closing behaviour of the angles, which acted as  
496 a seismic fuse and increased the rotational capacity of the connection, postponing connection  
497 failure to larger rotations. However, an exception can be seen for the connection with a Class  
498 4 beam. This is attributed to the high slenderness of both the beam and the gusset plate, leading  
499 to premature local buckling.

#### 500 **4.1 Ductility**

501 Ductility is an indicator of the ability to sustain plastic deformations without experiencing  
502 a significant drop in strength. The ductility of a structure ( $\mu_\phi$ ) is commonly expressed as the  
503 ratio  $\phi_u/\phi_y$ , where ( $\phi_u$ ) is the ultimate rotation and ( $\phi_y$ ) is the rotation at yield. In this study, the  
504 rotation at yield ( $\phi_y$ ) was calculated based on the equivalent energy elastic-plastic method  
505 (EEEP) recommended by ASTM E2126 [48]. An iterative procedure was carried out to define  
506 the equivalent bilinear elasto-plastic curve so that the net area enclosed between the equivalent  
507 curve and the backbone curve was zero (with the area below the backbone curve being taken

508 as negative). As shown in Fig. 22, the rotation at yield ( $\phi_y$ ) corresponds to the rotation where a  
509 secant line intersecting the backbone curve at 40% of the peak moment ( $M_{max}$ ) meets a  
510 horizontal line extending to the ultimate rotation. The ultimate rotation ( $\phi_u$ ) was previously  
511 defined in section 3.2.1.

512 Fig. 23 and Fig. 24 compare the ductility ( $\mu_\phi$ ) and the yield rotation ( $\phi_y$ ) of the connection  
513 configurations previously studied in Fig. 19 - Fig. 21. The results indicate that using Class 1  
514 and 2 beam sections generally led to similar ductility level across all connection configurations.  
515 However, ductility results varied significantly when Class 3 and 4 beam sections were used,  
516 with the F-C and WF-C connections providing significantly higher ductility (by up to 136%)  
517 than the W-C joints.

518 In general, the results presented in Fig. 24 indicate that the equivalent yield rotation depends  
519 more on the beam classification than on the connection type. While increasing the thickness of  
520 the beam section always led to a higher yield rotation of the connection (see Fig. 24), no such  
521 trend could be observed for the ductility.

## 522 4.2 Energy dissipation

523 In this study the area below the idealised EEEP curve up to the ultimate rotation (see  
524 Section 4.1) was used to calculate the energy dissipation capacity ( $E_d$ ) of the various  
525 connections conforming to Table 8, and the results are compared in Fig. 25. As expected, the  
526 connections with Class 1 and 2 beam sections dissipated significantly more energy than those  
527 with Class 3 or 4 beam sections.

528 All connection configurations with Class 1 beam sections performed similarly in terms of  
529 their energy dissipation capacity, as did those with Class 2 beams. On the other hand, F-C and  
530 WF-C connections with Class 3 and 4 beam sections provided energy dissipation capacities  
531 which were up to 181% and 196% higher, respectively, than those of the corresponding W-C

532 connections.

### 533 4.3 Damping coefficient

534 The equivalent viscous damping coefficient ( $\xi_{eq}$ ) is another indicator of the energy  
535 dissipation capacity of a system, quantifying the energy loss per cycle. As shown in Fig. 26,  $\xi_{eq}$   
536 is defined by relating the energy dissipated in the hysteresis loop ( $E_h$ ) of a particular cycle to  
537 the fictitious energy ( $E_{(OAB)}+E_{(OCD)}$ ) dissipated in viscous damping during the same cycle [49],  
538 and is calculated using the following equation [30,50]:

$$\xi_{eq} = \frac{1}{2\pi} \cdot \frac{E_h}{E_{(OAB)} + E_{(OCD)}} \quad (7)$$

539

540 The points A and C in Fig. 26 correspond to the maximum positive and negative bending  
541 moments, respectively. The above quantity was calculated for two different cycles,  
542 corresponding to the maximum bending moment ( $M_{max}$ ) and the bending moment at the  
543 ultimate rotation ( $M_u$ ).

544 In general, W-C connections were capable of more substantial damping at the ultimate  
545 rotation compared to the other connection configurations. This can be attributed to the fact that  
546 more material plasticity is developed in W-C connections compared to other types, which in  
547 turn increases the plumpness of the hysteresis loop and consequently the value of the damping  
548 coefficient.

549 By comparing the values of the damping coefficients in Fig. 27 and Fig. 28, it can be  
550 concluded that in the connections with Class 2, 3 and 4 beams the majority of the cyclic energy  
551 was dissipated after the connections reached their maximum bending moment. On the other  
552 hand, for the connections with Class 1 beams there was negligible difference between the  
553 values of  $\xi_{eq}$  at the peak moment and at the moment corresponding to the ultimate rotation, as  
554 plasticity was already significantly developed before the attainment of the maximum bending



555 moment. It should also be noted that the WF-C connections with Class 1 and 2 beams reached  
556 their maximum bending moment at the ultimate rotation ( $\phi_u=0.06$  rad), and thus the damping  
557 coefficients for both cycles were identical.

## 558 **5 Conclusions**

559 This study aimed to develop novel CFS beam-to-column bolted connections for seismic  
560 applications and evaluate their performance based on a number of established seismic  
561 performance criteria.

562 Detailed FE models of a range of CFS beam-to-column joints were developed, which were  
563 first validated against previous experimental data, and accounted for material nonlinearity and  
564 initial geometric imperfections. The structural performance of different configurations of Web-  
565 Connected (W-C), Flange-Connected (F-C) and Web-and-Flange-Connected (WF-C) joints  
566 was assessed while parametrically varying the thicknesses of key components and the shape of  
567 gusset plates. Based on the overall performance in terms of flexural capacity, ultimate rotation  
568 and rotational rigidity, the most suitable connection configurations for seismic applications  
569 were identified. Subsequently, these connections were evaluated under cyclic loading against  
570 key seismic performance parameters, including ductility, energy dissipation capacity and  
571 damping coefficient. Based on the results of this study, the following conclusions were drawn:

- 572 • Among the Web-Connected (W-C) joints, a rounded T-shaped gusset plate with a  
573 thickness larger than  $2t_b$  was identified as the preferred option across all beam classes. This  
574 connection delivers an advantageous combination of bending moment capacity, rotation  
575 capacity and stiffness, while the shape of the gusset plate creates a minimal obstruction when  
576 installing the floor system.
- 577 • Flange-Connected (F-C) joints employing stiffened top and seat angles exhibited a flexural  
578 capacity and rotational stiffness which were on average 4 times higher than those of their  
579 unstiffened counterparts. However, the results also indicated that using thick stiffened angle

580 sections alongside thin-walled beam sections led to a lower rotation capacity. The preferred  
581 angle and stiffener thicknesses were  $2t_b$  for Class 1 beams,  $3t_b$  for Class 2 beams, and  $4t_b$  for  
582 Class 3 and 4 beams.

583 • A study of Web-and-Flange-Connected (WF-C) joints, employing both unstiffened top and  
584 seat angles and a gusset plate, revealed that plate thicknesses larger than  $2t_b$  offered the best  
585 combination of flexural capacity, rotational stiffness and rotation capacity across all beam  
586 classes.

587 • Cyclic analyses of the recommended W-C, F-C and WF-C connections indicated that they  
588 were all suitable for practical seismic applications, as they provided an acceptable level of  
589 ductility while developing more than 80% of the flexural capacity of the connected beam.

590 • Very similar ductility levels were encountered for Class 1 and 2 beam sections across all  
591 connection configurations. However, for Class 3 and 4 beam sections WF-C and F-C  
592 connections exhibited up to 136% more ductility than W-C joints.

593 • In terms of dissipated energy, a similar performance was observed among all connections  
594 with Class 1 beams. This was also the case for Class 2 beams. However, for Class 3 and 4  
595 beams the WF-C and F-C connections significantly outperformed the W-C connections by  
596 up to two orders of magnitude. On the other hand, W-C connections displayed higher  
597 equivalent viscous damping coefficients at the ultimate rotation, reflecting the more  
598 extensive development of material plasticity in their components compared to the other  
599 types considered.

600

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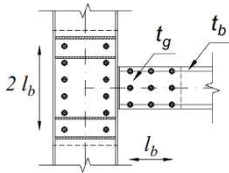
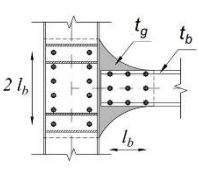
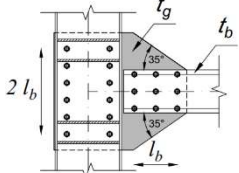
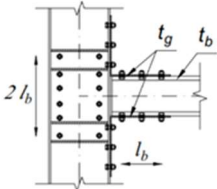
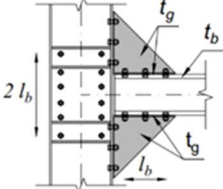
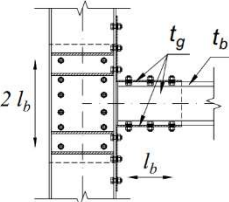
**Table 1** Material properties for tests A1 and B1

Test	Element	$\sigma_{0.2}$ (MPa)	$f_u$ (MPa)
A1	Beam	313	479
	Gusset Plate	353	516
B1	Beam	322	479
	Gusset Plate	308	474

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**Table 2** Connection configurations and selected design variables

Web-connected (W-C)			
$t_b=1$ mm $t_g = t_b, 1.5t_b, 2t_b, 3t_b$	$t_b=2$ mm $t_g = t_b, 1.5t_b, 2t_b, 3t_b$	$t_b=4$ mm $t_g = t_b, 1.5t_b, 2t_b, 3t_b$	$t_b=6$ mm $t_g = t_b, 1.5t_b, 2t_b, 3t_b$
T-shape 	Rounded T-shape 	Chamfered shape 	
Flange-connected (F-C)			
$t_b=1$ mm $t_g = t_b, 2t_b, 3t_b, 4t_b, 5t_b, 6t_b$	$t_b=2$ mm $t_g = t_b, 2t_b, 3t_b, 4t_b, 5t_b, 6t_b$	$t_b=4$ mm $t_g = t_b, 2t_b, 3t_b$	$t_b=6$ mm $t_g = t_b, 2t_b, 3t_b$
Unstiffened top and seat angles 		Stiffened top and seat angles 	
Web and flange-connected (WF-C)			
$t_b=1$ mm $t_g = t_b, 1.5t_b, 2t_b, 3t_b$	$t_b=2$ mm $t_g = t_b, 1.5t_b, 2t_b, 3t_b$	$t_b=4$ mm $t_g = t_b, 1.5t_b, 2t_b, 3t_b$	$t_b=6$ mm $t_g = t_b, 1.5t_b, 2t_b, 3t_b$
T-shaped gusset plate and unstiffened top and seat angles 			

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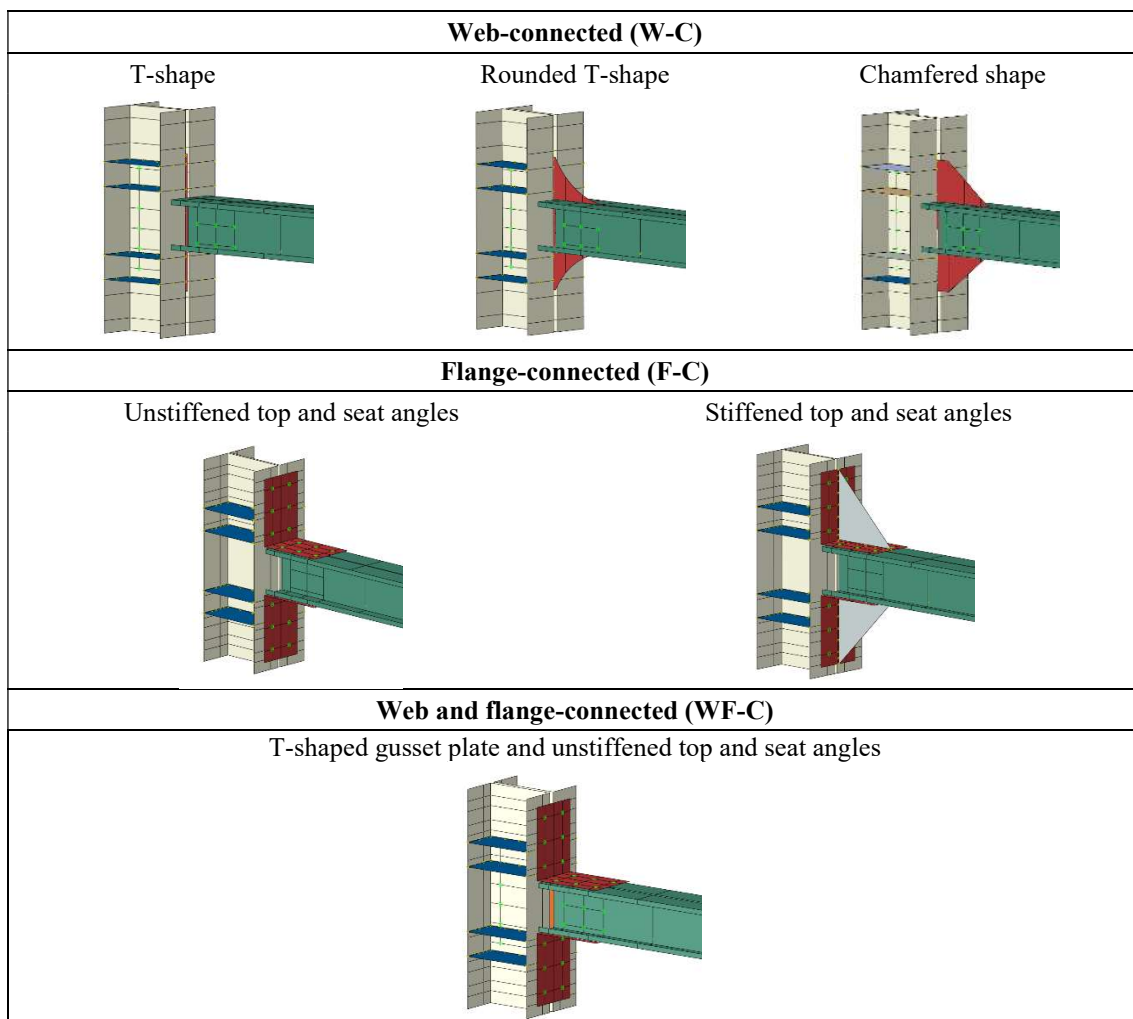
**Table 3** Critical elastic stresses for local and distortional buckling for each beam type

Beam	$\sigma_{,l}$ (MPa)	$\sigma_{,d}$ (MPa)
tb=1 mm	92.10	128.83
tb=2 mm	364.74	272.33
tb=4 mm	-	609.16
tb=6 mm	-	1013.56

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**Table 4.** 3D graphical representations of different connection types



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**Table 5** Ultimate rotation ( $\phi_{max}$ ), flexural rigidity per EC3 [22], rotational category per AISC provisions [44] and failure modes of W-C connections

Beam thickness $t_b$	Gusset plate thickness $t_g$	T-shape				Rounded T-shape				Chamfered shape			
		Failure mode	EC3 rotational rigidity	$\phi_{max}$ (rad)	AISC category	Failure mode	EC3 rotational rigidity	$\phi_{max}$ (rad)	AISC category	Failure mode	EC3 rotational rigidity	$\phi_{max}$ (rad)	AISC category
1 mm	$t_b$	GP	S-R	0.01	OMF	GP	S-R	0.006	OMF	GP	S-R	0.01	OMF
	$1.5t_b$	GP	S-R	0.011	OMF	GP	S-R	0.01	OMF	B	R	0.025	IMF
	$2t_b$	GP	S-R	0.013	OMF	B	S-R	0.024	IMF	B	R	0.035	IMF
	$3t_b$	GP	S-R	0.017	OMF	B	R	0.032	IMF	B	R	0.03	IMF
2 mm	$t_b$	GP	S-R	0.013	OMF	GP	S-R	0.012	OMF	GP	S-R	0.014	OMF
	$1.5t_b$	GP	S-R	0.016	OMF	GP	S-R	0.02	OMF	B	R	0.023	IMF
	$2t_b$	GP	S-R	0.021	IMF	B	S-R	0.023	IMF	B	R	0.022	IMF
	$3t_b$	GP	S-R	0.059	SMF	B	R	0.022	IMF	B	R	0.022	IMF
4 mm	$t_b$	GP	S-R	0.025	IMF	GP	S-R	0.027	IMF	GP	S-R	0.028	IMF
	$1.5t_b$	GP	S-R	0.05	SMF	GP	S-R	0.06	SMF	B	S-R	0.06	SMF
	$2t_b$	GP	S-R	0.06	SMF	B	S-R	0.06	SMF	B	R	0.06	SMF
	$3t_b$	GP	S-R	0.056	SMF	B	S-R	0.06	SMF	B	R	0.06	SMF
6 mm	$t_b$	GP	S-R	0.048	SMF	GP	S-R	0.06	SMF	GP	S-R	0.052	SMF
	$1.5t_b$	GP	S-R	0.06	SMF	GP	S-R	0.06	SMF	GP	S-R	0.06	SMF
	$2t_b$	GP	S-R	0.056	SMF	GP	S-R	0.06	SMF	B	S-R	0.06	SMF
	$3t_b$	GP	S-R	0.06	SMF	B	S-R	0.06	SMF	B	S-R	0.06	SMF

759 (GP): Gusset plate failure, (B): Beam failure

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761 **Table 6** Ultimate rotation ( $\phi_{max}$ ), flexural rigidity per EC3 [22], rotational category per AISC  
762 provisions [44] and failure modes of F-C connections

Beam thickness $t_b$	Gusset plate thickness $t_g$	Unstiffened top and seat angles				Stiffened top and seat angles			
		Failure mode	EC3 rotational rigidity	$\phi_{max}$ (rad)	AISC category	Failure mode	EC3 rotational rigidity	$\phi_{max}$ (rad)	AISC category
1 mm	$t_b$	A	P	0.06	SMF	A	P	0.06	SMF
	$2t_b$	A	P	0.06	SMF	A	P	0.06	SMF
	$3t_b$	A	P	0.06	SMF	B	S-R	0.06	SMF
	$4t_b$	A	P	0.06	SMF	B	S-R	0.06	SMF
	$5t_b$	A	S-R	0.06	SMF	B	S-R	0.038	IMF
	$6t_b$	A	S-R	0.06	SMF	B	S-R	0.025	IMF
2 mm	$t_b$	A	P	0.06	SMF	A	P	0.06	SMF
	$2t_b$	A	P	0.06	SMF	A	S-R	0.06	SMF
	$3t_b$	A	P	0.06	SMF	B	S-R	0.06	SMF
	$4t_b$	A	S-R	0.06	SMF	B	S-R	0.055	SMF
	$5t_b$	A	S-R	0.06	SMF	B	S-R	0.029	IMF
	$6t_b$	A	S-R	0.06	SMF	B	S-R	0.023	IMF
4 mm	$t_b$	A	P	0.06	SMF	A	P	0.06	SMF
	$2t_b$	A	P	0.06	SMF	A	S-R	0.06	SMF

	$3t_b$	A	S-R	0.06	SMF	B	S-R	0.06	SMF
6 mm	$t_b$	A	S-R	0.06	SMF	A	S-R	0.06	SMF
	$2t_b$	A	S-R	0.06	SMF	A	S-R	0.06	SMF
	$3t_b$	A	S-R	0.06	SMF	B	S-R	0.06	SMF

(A): Stiffening plate and angle failure, (B): Beam failure

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**Table 7** Maximum rotation ( $\phi_{max}$ ), flexural rigidity as per EC3 [22], rotational category as per AISC provisions [44] and failure modes for WF-C connections

Beam thickness $t_b$	Gusset plate thickness $t_g$	T-shape with unstiffened top and seat angles			
		Failure mode	EC3 rotational rigidity	$\phi_{max}$ (rad)	AISC category
1 mm	$t_b$	GP	S-R	0.031	IMF
	$1.5t_b$	GP	S-R	0.032	IMF
	$2t_b$	GP	S-R	0.033	IMF
	$3t_b$	B	S-R	0.013	OMF
2 mm	$t_b$	GP	S-R	0.048	SMF
	$1.5t_b$	GP	S-R	0.06	SMF
	$2t_b$	GP	S-R	0.06	SMF
	$3t_b$	B	S-R	0.0215	IMF
4 mm	$t_b$	GP	S-R	0.06	SMF
	$1.5t_b$	GP	S-R	0.06	SMF
	$2t_b$	GP	S-R	0.06	SMF
	$3t_b$	B	S-R	0.037	IMF
6 mm	$t_b$	GP	S-R	0.06	SMF
	$1.5t_b$	GP	S-R	0.06	SMF
	$2t_b$	GP	S-R	0.06	SMF
	$3t_b$	B	S-R	0.06	SMF

(GP): Gusset plate and/or angle failure, (B): Beam failure

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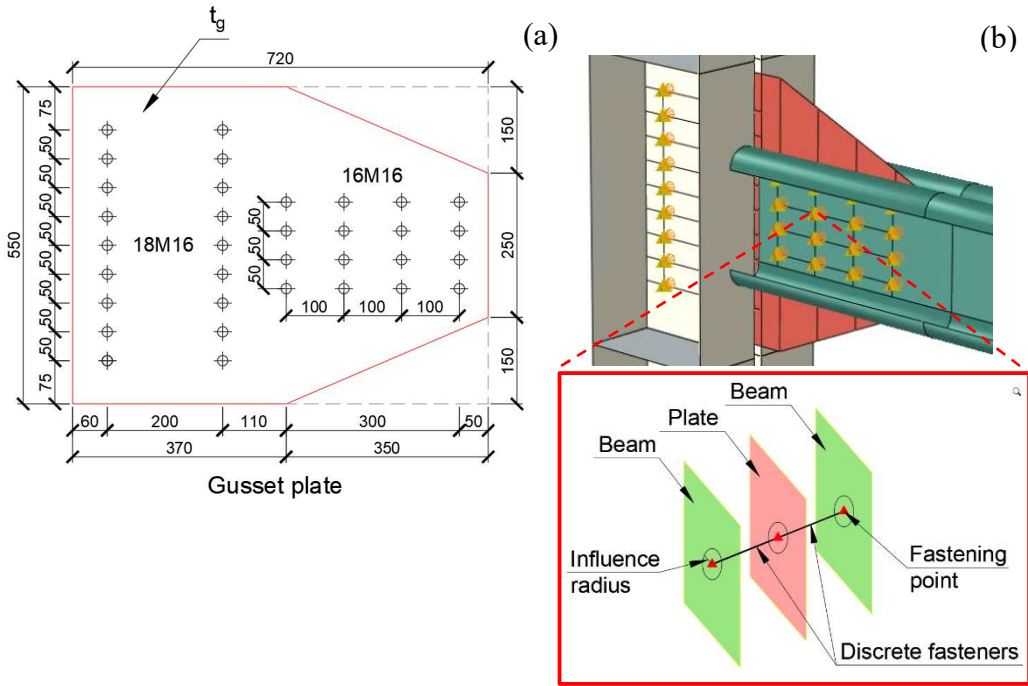
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**Table 8** Connections with balanced performance

Connection type	EC3 beam class	Gusset plate thickness $t_g$	Failure mode	Gusset plate shape
W-C	1, 2, 3 and 4	$2t_b$	B	Rounded T-shape
F-C	3 and 4	$4t_b$	B	Stiffened top and seat angles
	2	$3t_b$	B	
	1	$2t_b$	A	
WF-C	1, 2, 3 and 4	$2t_b$	GP	T-shape and unstiffened top and seat angles

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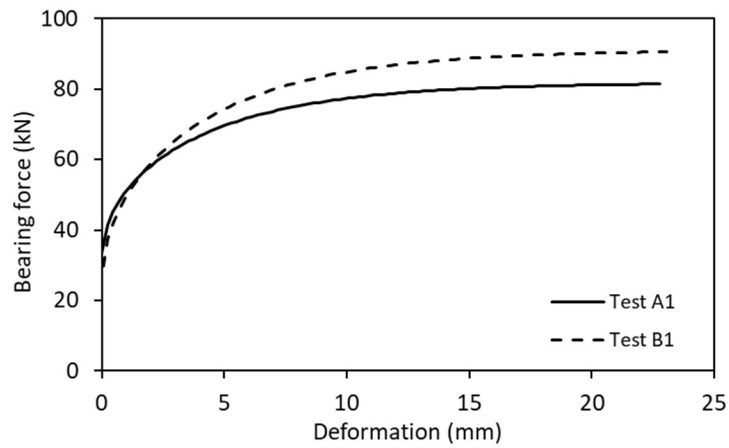
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**Fig. 1** FE modelling of the tested connections: a) bolt arrangement and b) discrete fasteners



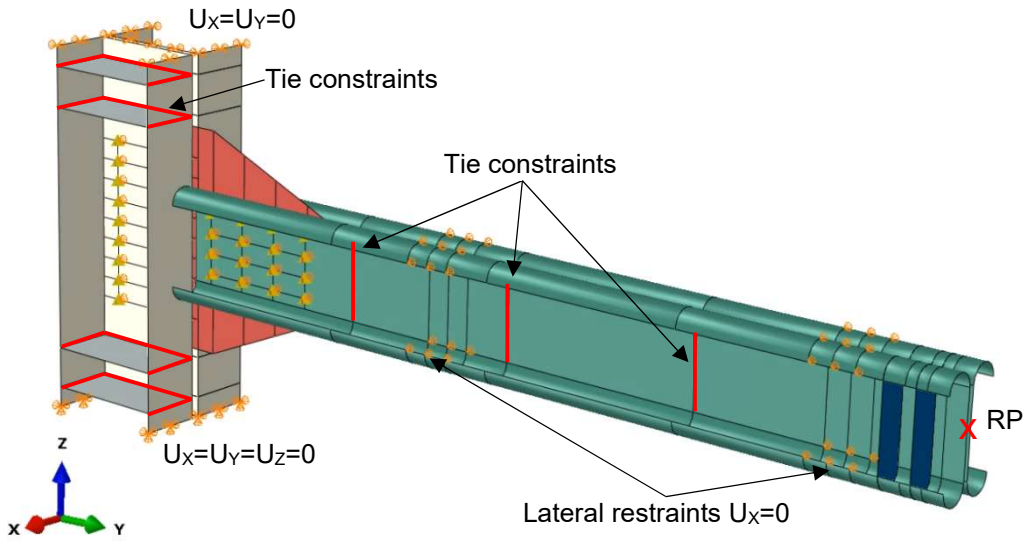
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**Fig. 2** Bearing behaviour of the beam to gusset plate bolts incorporated into the FE models of tests A1 and B1

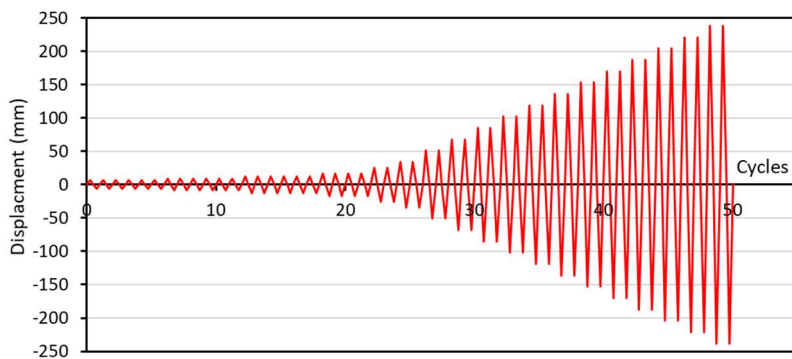


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**Fig. 3** Boundary conditions of the FE models

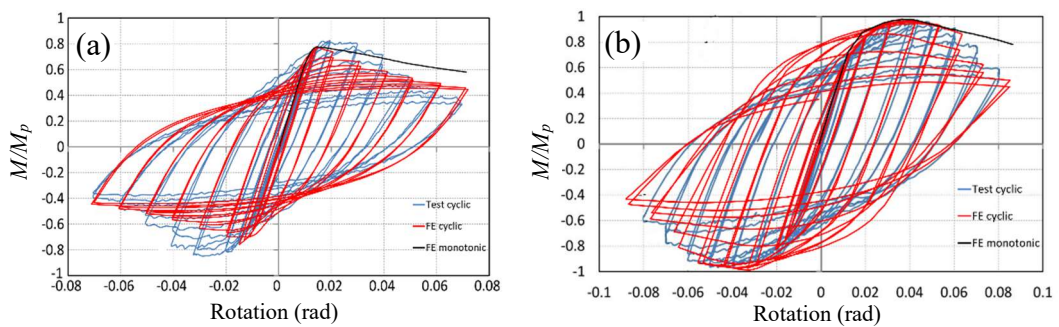


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**Fig. 4** Cyclic loading protocol adopted from AISC 341-16 [44]



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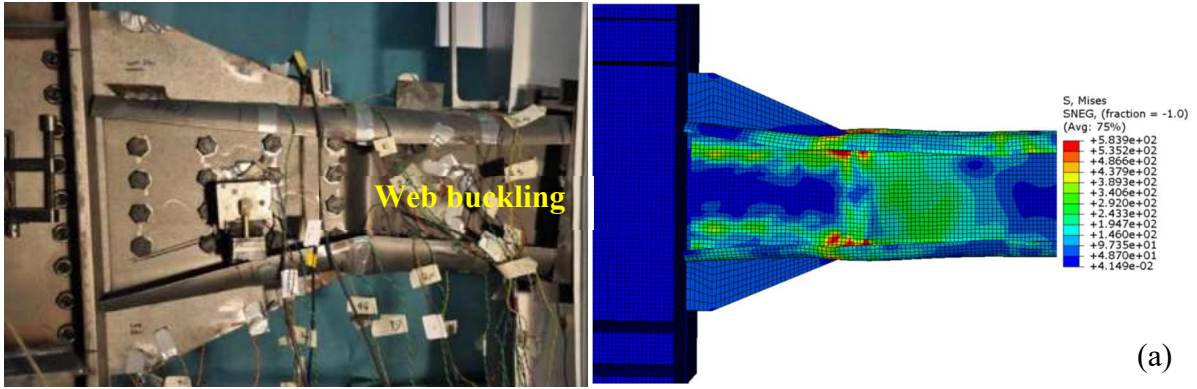
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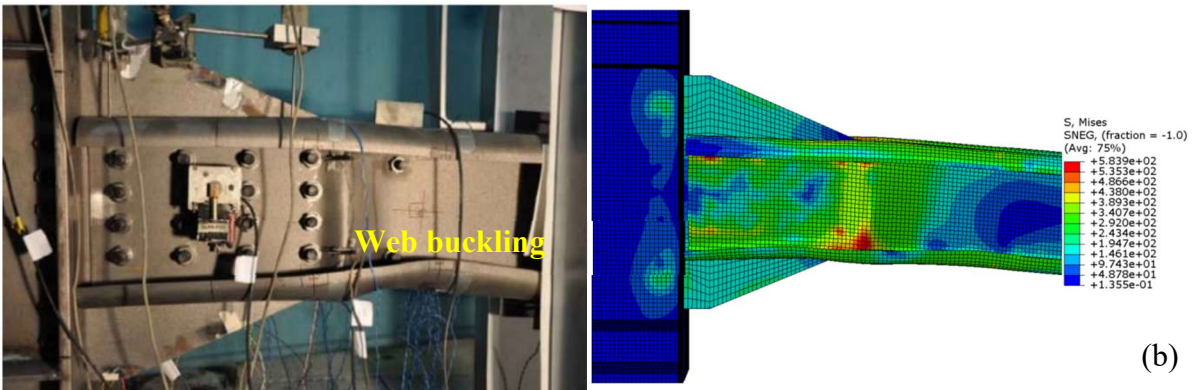
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**Fig. 5** Comparison between experimental moment-rotation behaviour [29] and FE analysis results for: (a) A1 and (b) B1 specimens

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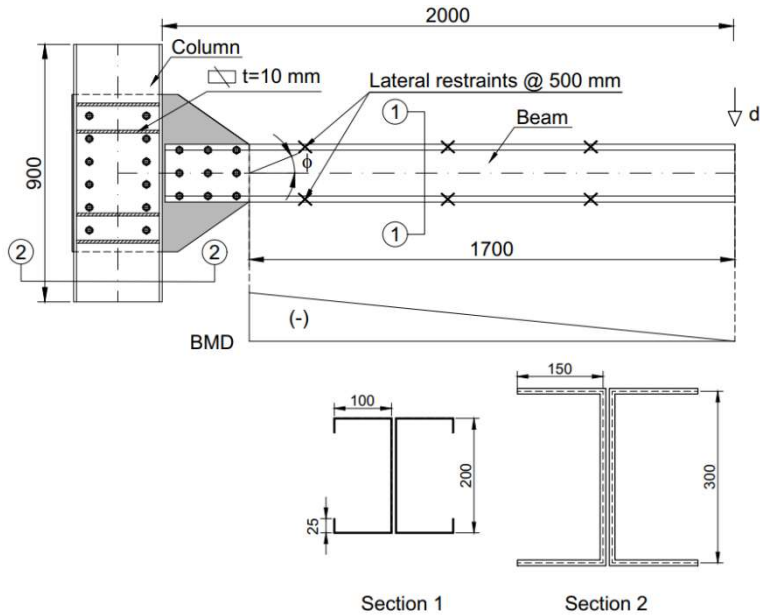


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**Fig. 6** Comparison between the experimental [29] and predicted failure modes under cyclic loading for: (a) A1 and (b) B1 specimens

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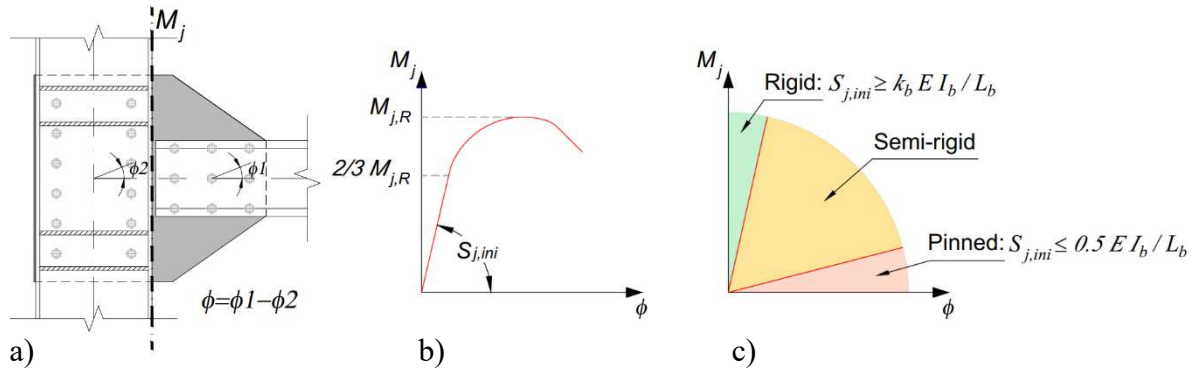


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**Fig. 7** Connection configuration

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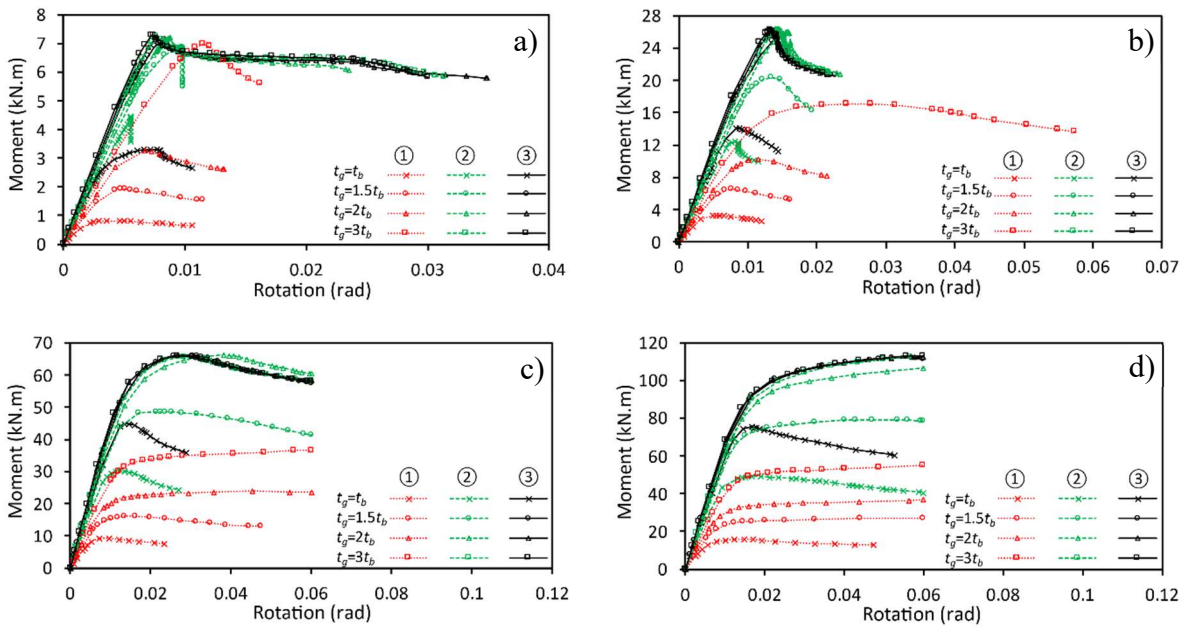
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**Fig. 8** Definition of a) moment-rotation relationship, b) initial stiffness ( $S_{j,ini}$ ), and c) boundaries for the rotational stiffness classification of connections



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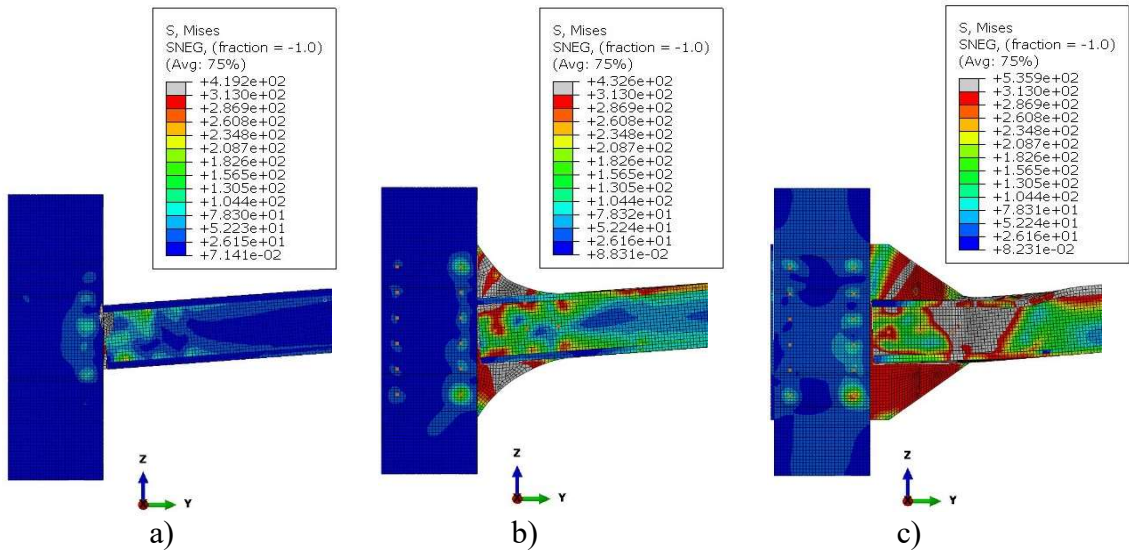
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**Fig. 9** Moment-rotation responses of W-C connections with various gusset plate thicknesses ( $t_g$ ) and shapes (①: T-shape, ②: rounded T-shape and ③: chamfered shape), and beam thicknesses ( $t_b$ ) of a) 1 mm, b) 2 mm, c) 4 mm and d) 6 mm





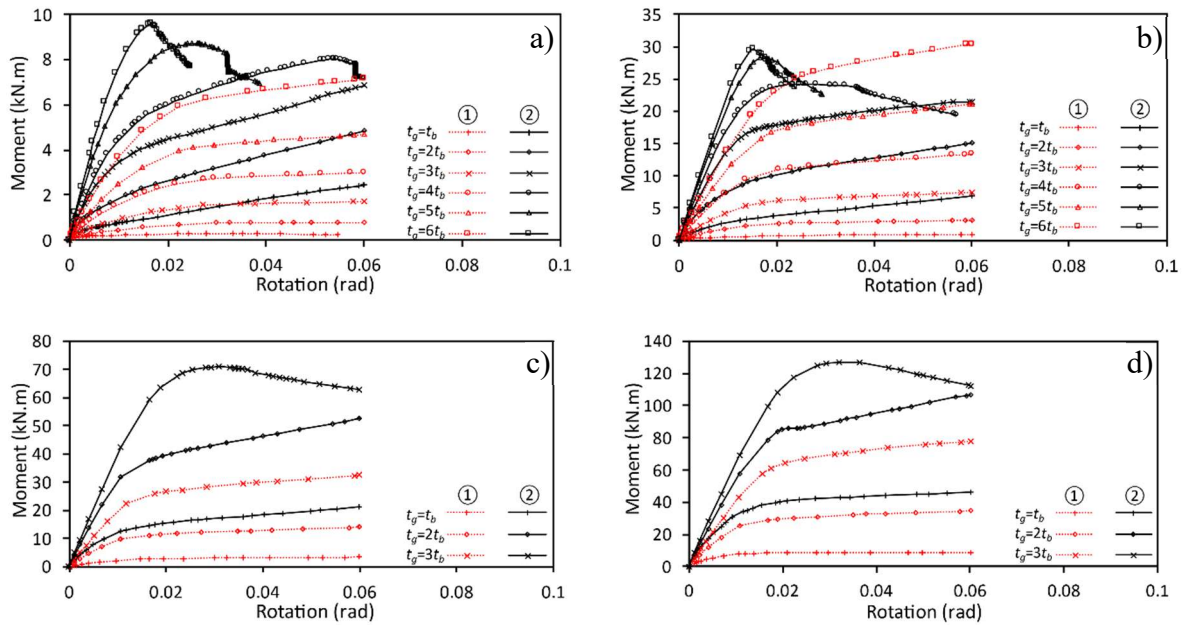
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**Fig. 10** Failure modes of W-C connections with: a) T shaped, b) rounded T-shaped and c) chamfered gusset plate, for  $t_b=4$  mm and  $t_g=1.5t_b$



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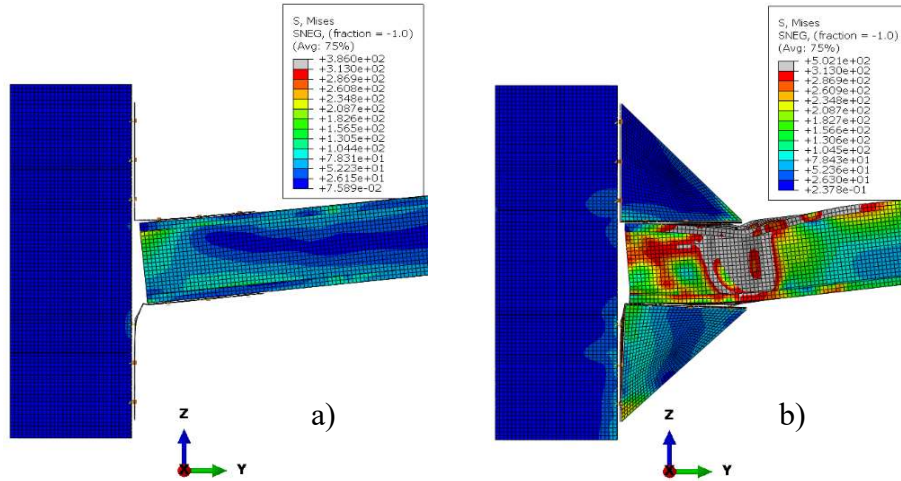
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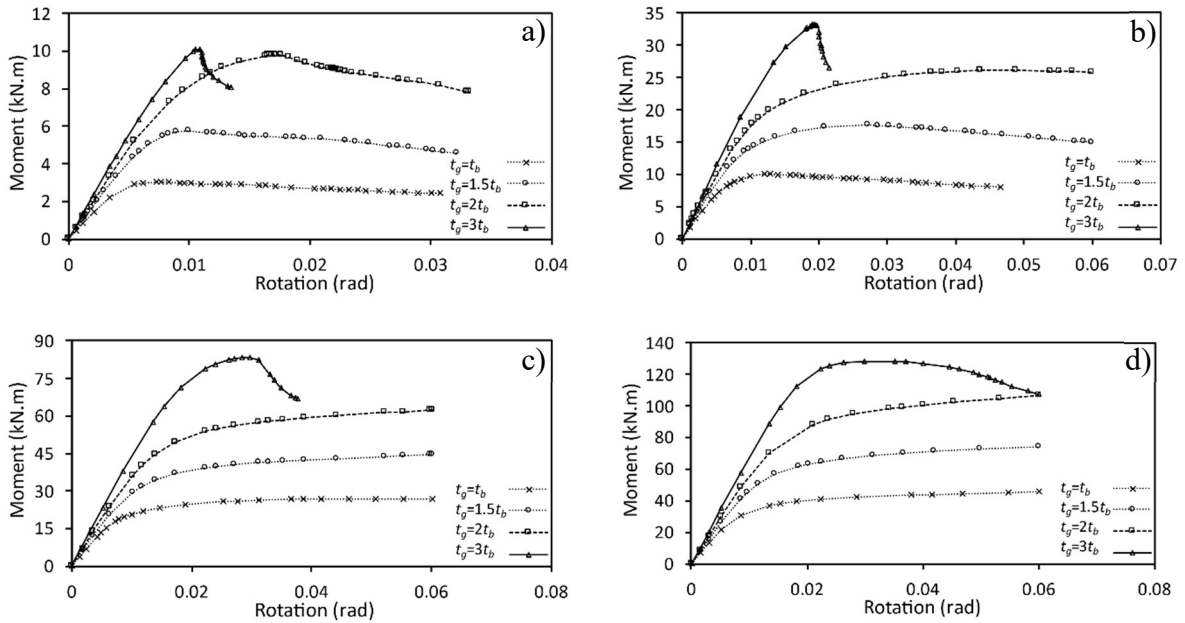
**Fig. 11** Moment-rotation responses of F-C connections with various gusset plate thicknesses ( $t_g$ ) and shapes (①: unstiffened angles and ②: stiffened angles), and beam thicknesses ( $t_b$ ) of a) 1 mm, b) 2 mm, c) 4 mm and d) 6 mm



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815 **Fig. 12** Failure modes of connections with a) unstiffened angles and b) stiffened angles, when  $t_b=2$   
 816 mm and  $t_g=3t_b$

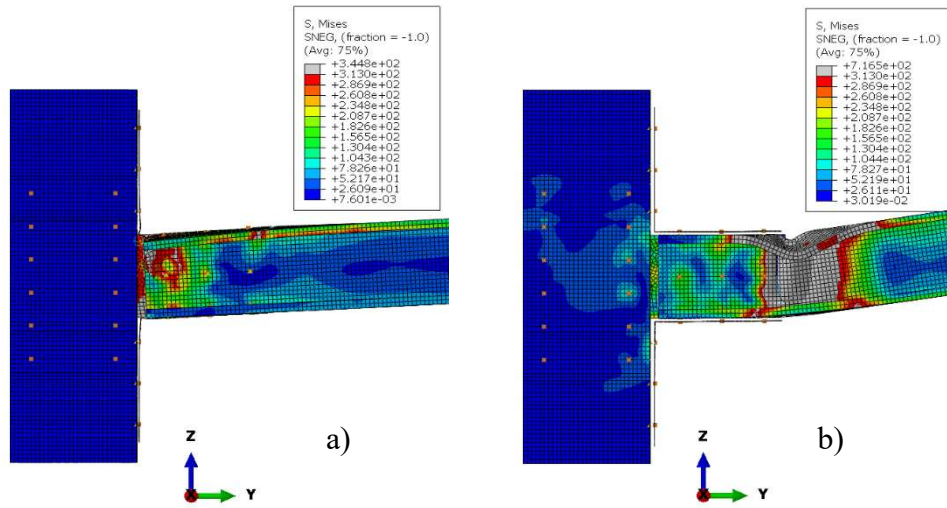
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819 **Fig. 13** Moment-rotation responses of WF-C connections with various gusset plate and angle  
 820 thicknesses ( $t_g$ ), and beam thicknesses ( $t_b$ ) of a) 1 mm, b) 2 mm, c) 4 mm and d) 6 mm

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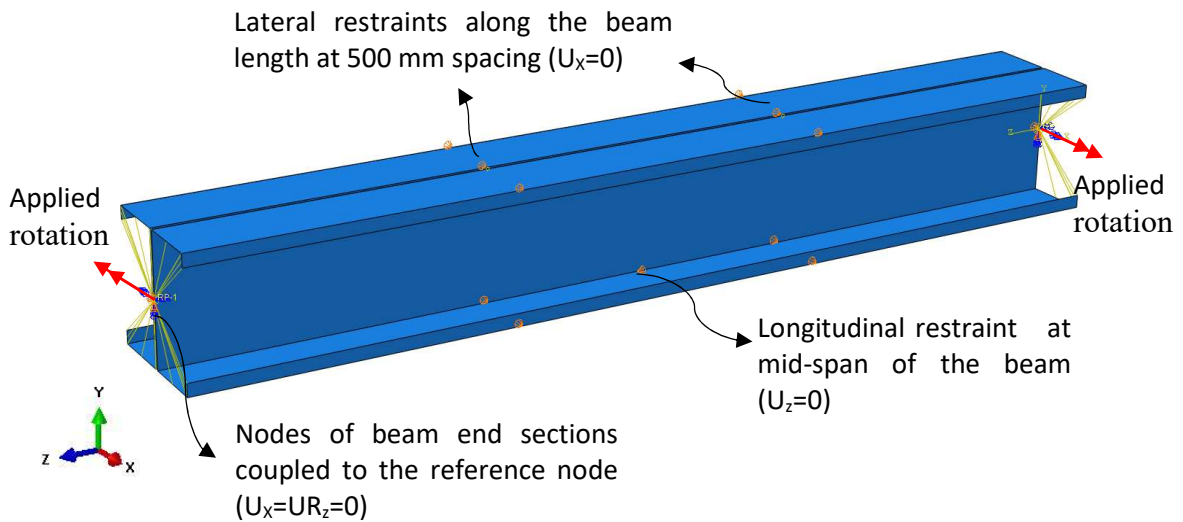
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**Fig. 14** Failure modes of WF-C connections for  $t_b=1$  mm and a)  $t_g=t_b$  and b)  $t_b=3t_b$

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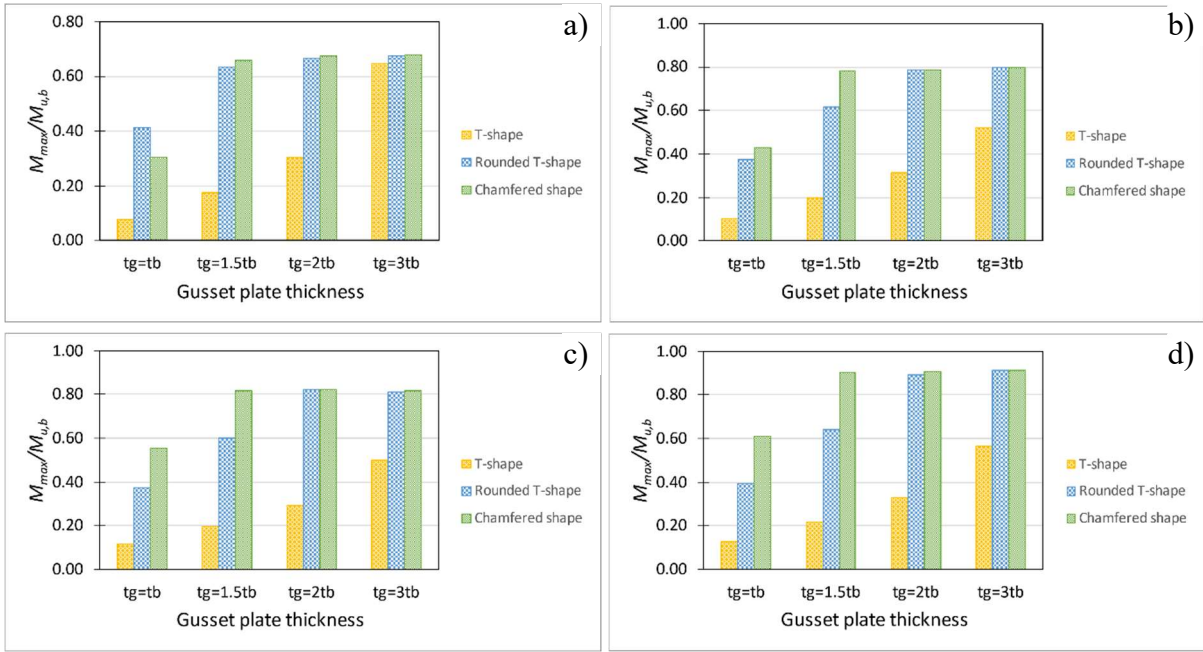
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**Fig. 15** FE model of CFS beam with back-to-back channel sections used to determine the cross-sectional flexural capacity ( $M_{u,b}$ )

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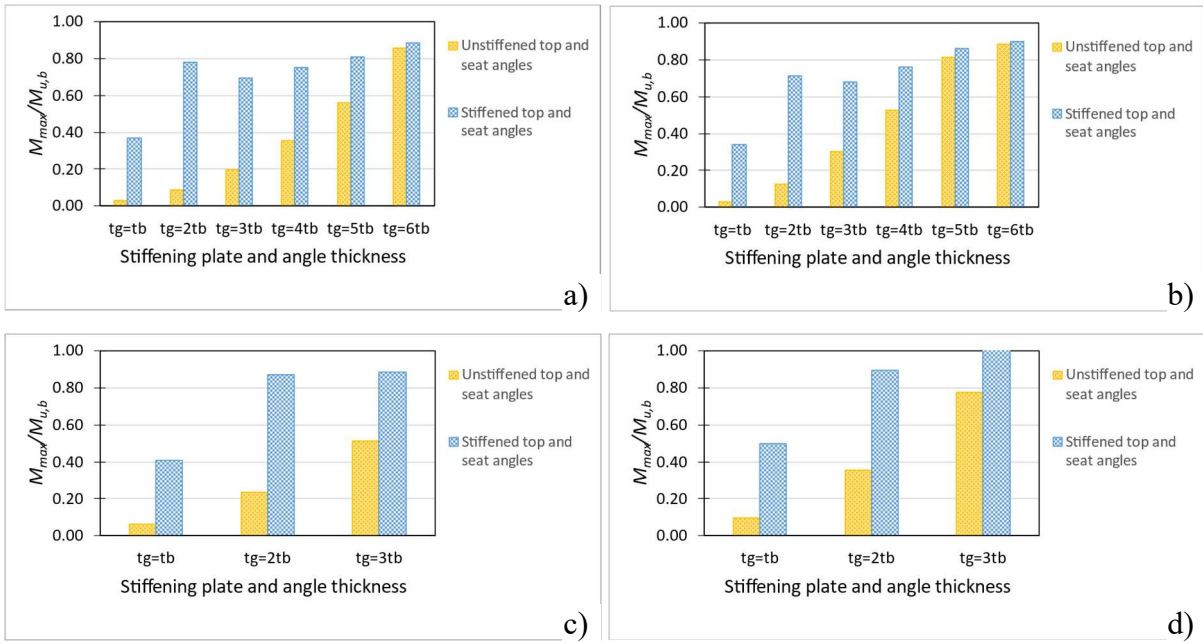


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**Fig. 16**  $M_{max}/M_{u,b}$  ratios for W-C connections with beam thicknesses  $t_b$  of a) 1 mm, b) 2 mm, c) 4 mm and d) 6 mm



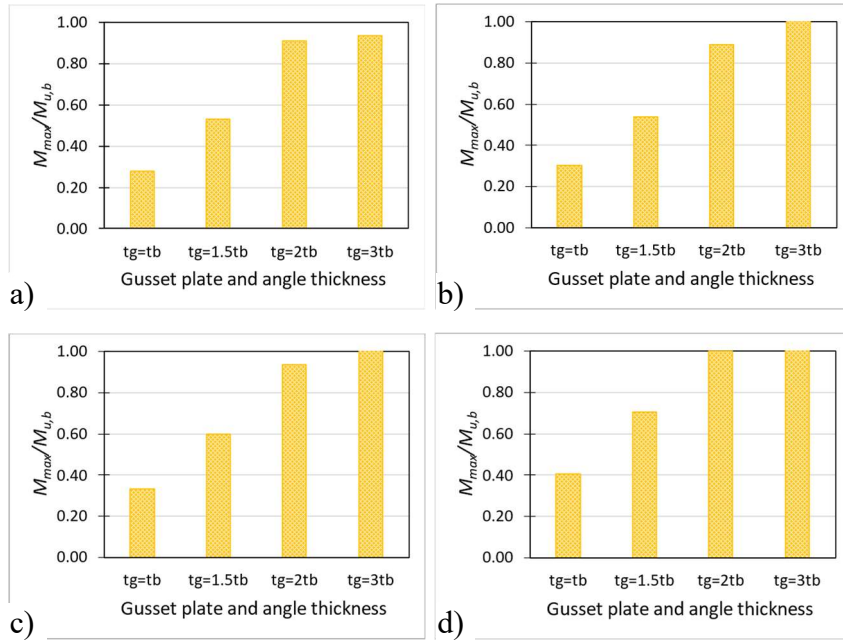
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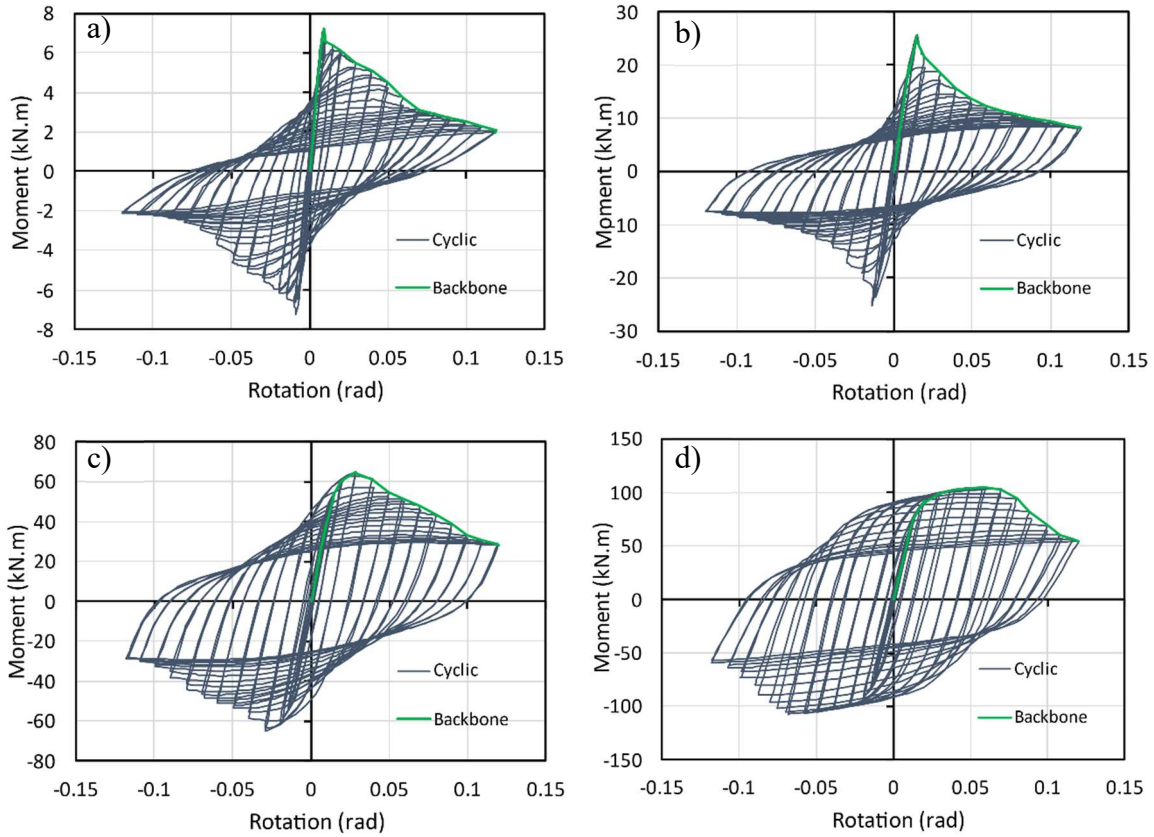
**Fig. 17**  $M_{max}/M_{u,b}$  ratios for F-C connections with beam thicknesses  $t_b$  of a) 1 mm, b) 2 mm, c) 4 mm and d) 6 mm



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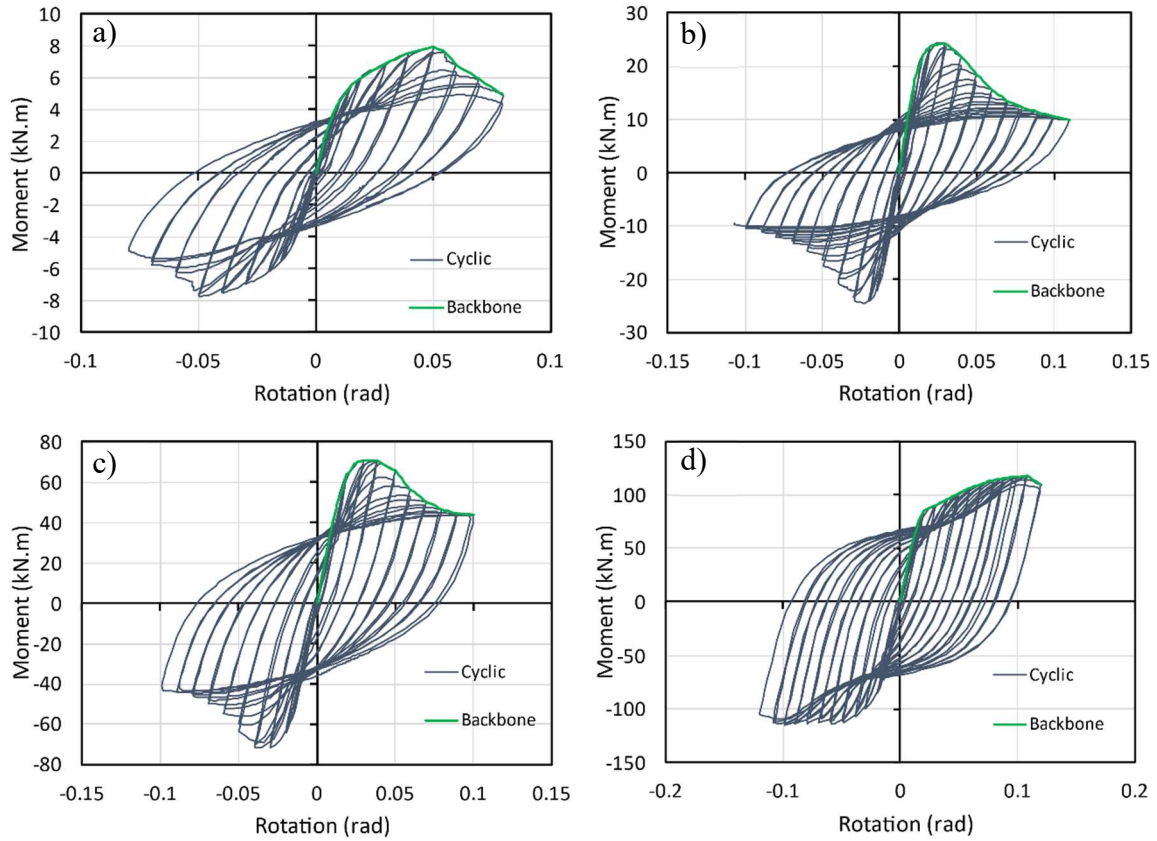
839 **Fig. 18**  $M_{max}/M_{ub}$  ratios for WF-C connections with beam thicknesses  $t_b$  of a) 1 mm, b) 2 mm, c) 4 mm  
 840 and d) 6 mm

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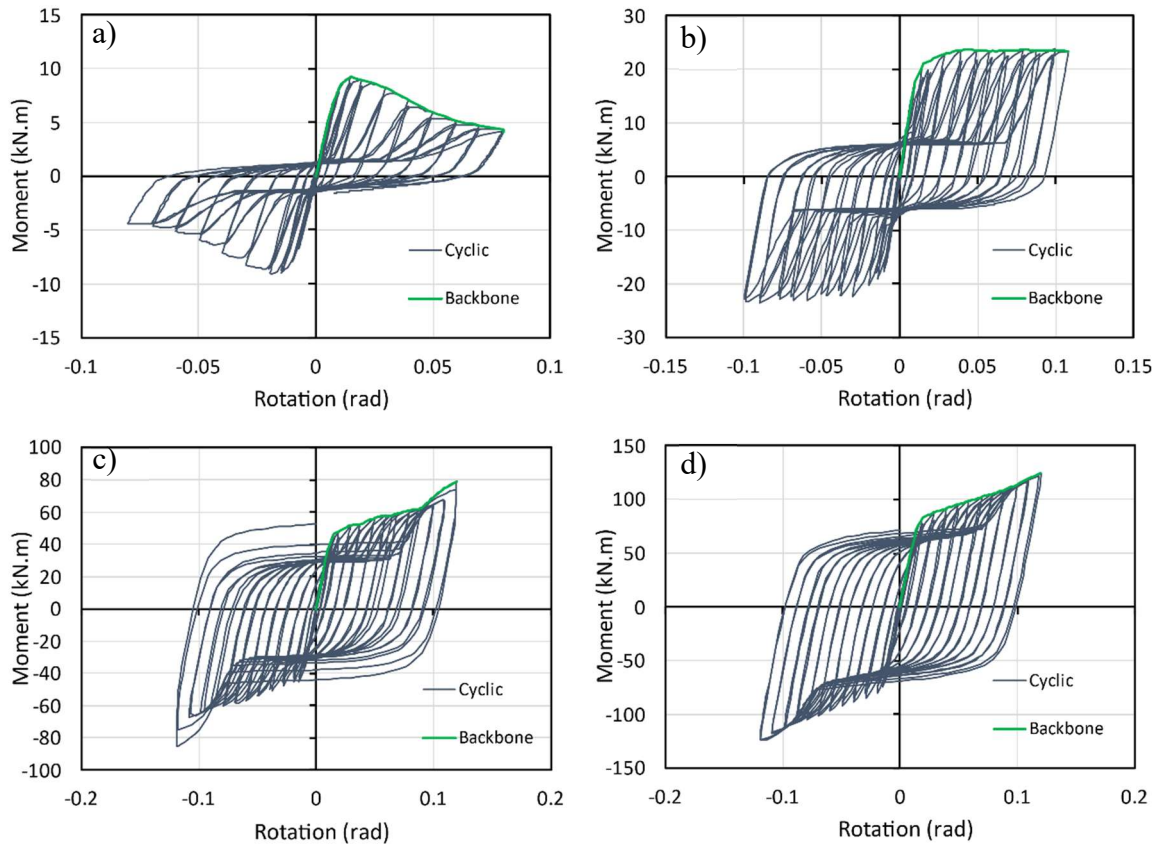
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843 **Fig. 19** Hysteretic moment-rotation curves for balanced W-C connections with gusset plate thickness  
 844  $t_g=2t_b$  and beam thickness ( $t_b$ ) of a) 1 mm, b) 2 mm, c) 4 mm and d) 6 mm  
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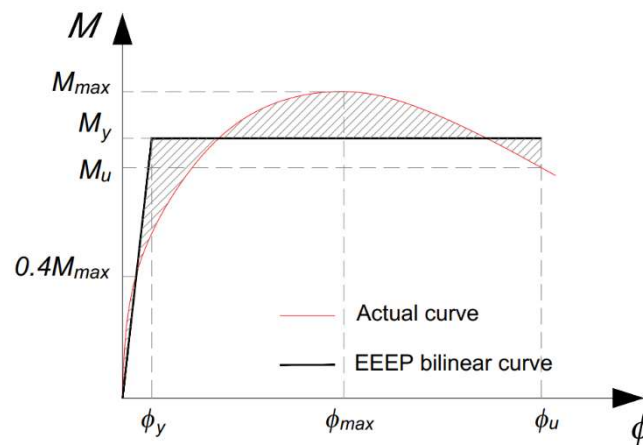
**Fig. 20** Hysteretic moment-rotation curves for balanced F-C connections with beam and gusset plate thicknesses of a)  $t_b=1$  mm,  $t_g=4t_b$ , b)  $t_b=2$  mm,  $t_g=4t_b$ , c)  $t_b=4$  mm,  $t_g=3t_b$  and d)  $t_b=6$  mm,  $t_g=2t_b$



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**Fig. 21** Hysteretic moment-rotation curves for balanced WF-C connections with gusset plate thickness  $t_g=2t_b$  and beam thickness ( $t_b$ ) of a) 1 mm, b) 2 mm, c) 4 mm and d) 6 mm

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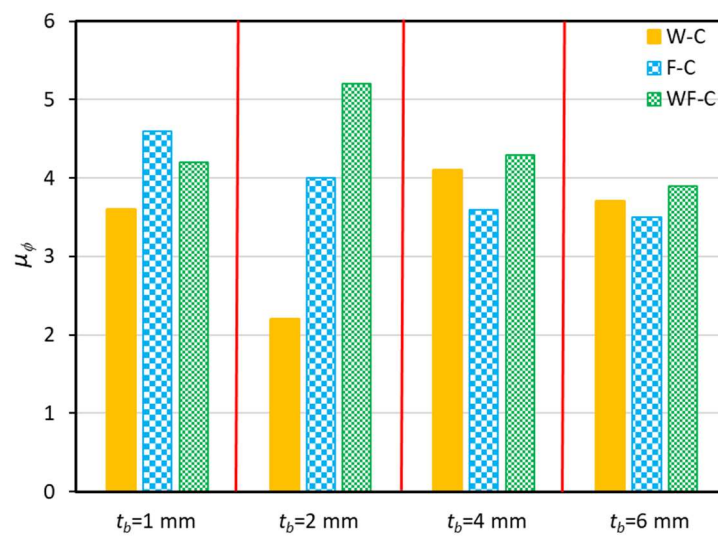


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**Fig. 22** Equivalent (EEEE) analysis model per ASTM E2126

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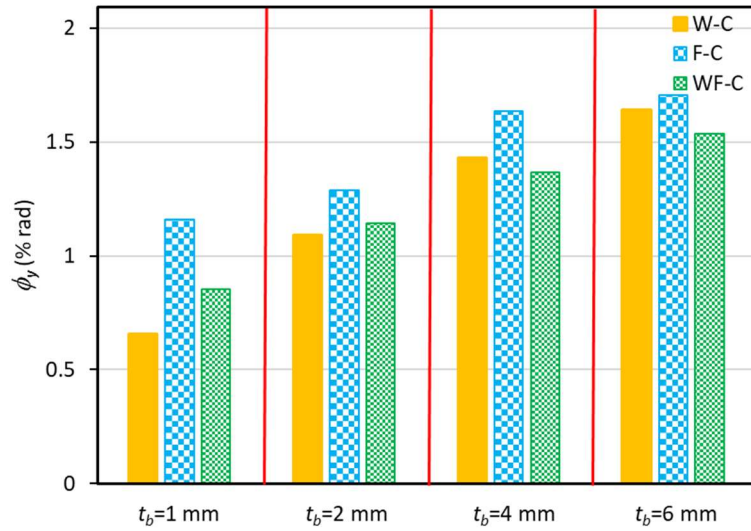


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**Fig. 23** Ductility ( $\mu_\phi$ ) of different connection configurations with balanced performance

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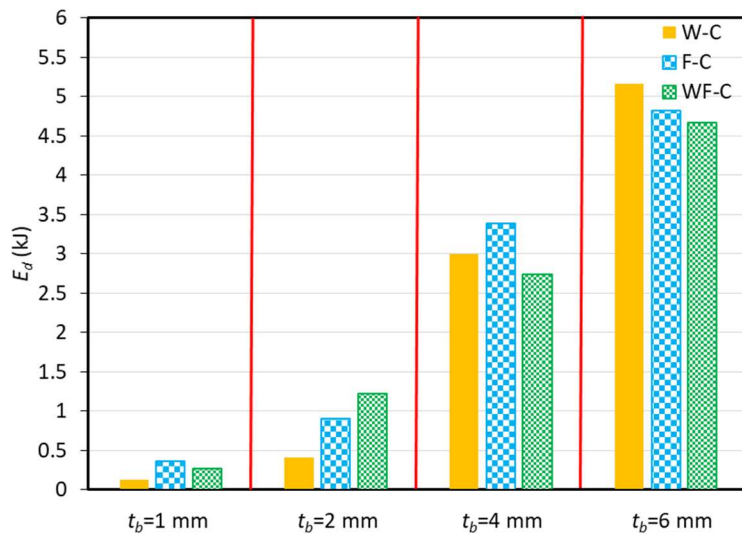


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**Fig. 24** Yield rotation ( $\phi_y$ ) of different connection configurations with balanced performance

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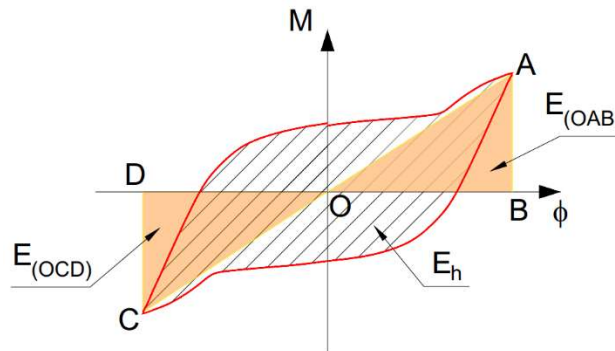


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**Fig. 25** Energy dissipation ( $E_d$ ) of connections with balanced performance

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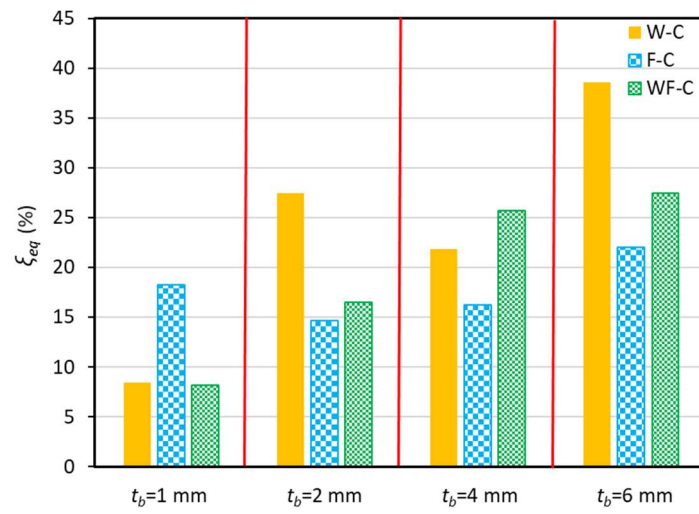
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**Fig. 26** Definition of equivalent viscous damping coefficient ( $\xi_{eq}$ )



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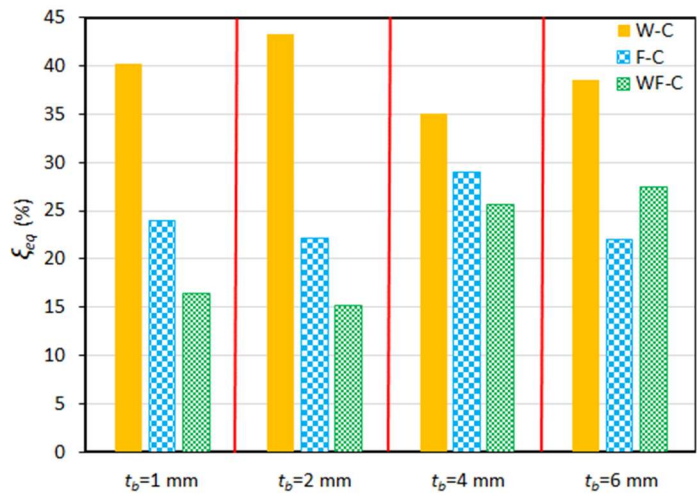
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**Fig. 27** Equivalent viscous damping coefficient ( $\xi_{eq}$ ) at  $M_{max}$  for connections with balanced performance



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**Fig. 28** Equivalent viscous damping coefficient ( $\xi_{eq}$ ) at  $M_u$  for connections with balanced performance