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Environmental Geotechnics

An Improved Quantification Method for Characterization of Clay Microstructure Using SEM

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52 applied to Hangzhou clay. Results show that anisotropy in clay microstructure should
53 be considered when choosing the observed surface. And there is no significant
54 difference in micro-parameters between liquid nitrogen frozen-vacuum drying and
55 critical point drying. A comparison among the *A-K* method, artificial method, and
56 theoretical methods that can determine threshold shows that the proposed *A-K* method
57 combines the advantages of all methods. The optimal magnification and number of
58 images can be determined by mathematical theory, which also improves reliability and
59 efficiency.

60

61 **Keywords:**

62 Fabric of soils; Geoenvironment; Porous-media characterisation; SEM

63

64 **List of notations**

65 A_p real area of the particle
66 A' circumcircle area of clay particle
67 A_1 pore area
68 A_0 area of total SEM image
69 D_v fractal dimension
70 F mean shape factor
71 F_i shape factor for each clay particle
72 G_s specific gravity

73	H_m	orientation probability entropy
74	k	number of equally divided areas in the whole particle direction range
75	L	actual perimeter of the clay particle
76	m	total number of clay particles in the SEM image
77	n_i	image porosity
78	n	the porosity of clay
79	$N(r)$	number of square boxes
80	$N(\mu, \sigma^2)$	normal distribution
81	P	perimeter of a circle that has the same area as the clay particle
82	$P_i(\alpha)$	percentage of soil particles whose directions α belong to a specific range
83	r	side length of a square box
84	R_0	roundness
85	S^2	variance of the sample $X = (X_1, \dots, X_n)$
86	$t_{n-1} \frac{\alpha}{2}$	upper quantile
87	n_{3-D}	3-D surface porosity
88	V_{pore}	volume of pore
89	\bar{X}	mean value of the sample $X = (X_1, \dots, X_n)$
90	α	confidence coefficient
91	α_p	orientation of soil particle
92	γ	unit weight
93	μ	unknown mean value of $N(\mu, \sigma^2)$

94 σ^2 unknown standard deviation of $N(\mu, \sigma^2)$

95 w water content

96 w_L liquid limit

97 w_P plastic limit

98

99 **1. Introduction**

100 Clay is a common material widely used in geoenvironmental engineering (Alba et
101 al., 2009; Dohrmann et al., 2013; Tournassat et al., 2015), ranging from landfill clay
102 liner to the barrier in the nuclear waste disposal (Chen et al., 2012; Estabragh et al.,
103 2018; Toprak et al., 2018) (Fig.1). In engineering practice, it's crucial to understand the
104 physical and mechanical properties of these clay barriers, such as the strength,
105 mechanical stability, and hydraulic conductivity. The macro-behaviour of clays
106 depends chiefly on their microstructure. For example, the shear strength of clay can be
107 improved by increasing inter-cluster cementation bonding and reducing the pore space
108 (Horpibulsuk et al. 2010). And microstructural changes in the clays may cause
109 settlement and bearing capacity problems (Oztoprak and Pisirici, 2011).

110

111 Therefore, it's significant to study the micro-mechanisms of clay behaviour by
112 effectively quantifying clay microstructure parameters such as image porosity, fractal
113 dimension, mean shape factor, et al. (Pusch and Weston, 2003; Bennett and Hulbert M,
114 2012).

115 The efforts to explore the clay microstructure began since Terzaghi (1925) first
116 proposed the concept of soil microstructure. And Scanning Electron Microscope (SEM)
117 is one of the most popular equipment for micro research (Bohor and Hughes, 1971;
118 Horpibulsuk et al., 2010; Liu et al., 2011; Liu et al., 2017). However, there are still
119 many problems in the quantification of clay microstructure, and the challenges remain
120 in obtaining ‘reliable’ quantified information of clay microstructure effectively and
121 easily (Liu et al., 2017; Di Remigio et al., 2018). Reliable quantification means that the
122 micro-parameters obtained from a limited number of images with a selected
123 magnification should represent the clay microstructure more credibly.

124

125 The main difficulties in the quantification process of clay microstructure by SEM are
126 shown in Fig.1 (Mazumder et al., 2018; Yang and Liu, 2019). The first issue is the clay
127 sample preparation, and the sample milling and drying methods are discussed in this
128 paper. There are many ways to mill and dry the samples for SEM experiments
129 (Kaczyński and Trzcíński 1997; Kjellsen et al., 2003; Janecek and Robert, 2016;
130 Bangaru et al., 2019). The optimal method for clay samples is still uncertain. Another
131 issue is the reliable representativeness of the results obtained from SEM images. The
132 reliable representativeness is mainly related to three aspects as follows: (1) the
133 magnification of SEM images; (2) the number of SEM images; (3) image processing.

134

135 In terms of the magnification, too low magnification will make it hard to distinguish
136 between pores and particles in the SEM image, while too high magnification makes it
137 difficult to recognise the micro-structural features since the whole image is occupied
138 only by a few particles or pores (Lin et al. 2018; Bangaru et al. 2019; Wu and Chu,
139 2020). As for the number, since SEM images can only show the features of clay in the
140 order of microns, a large number of SEM images are required to improve the
141 representativeness of the quantification results, but an increased number of SEM
142 images also costs longer time and higher fee. There are many tools and approaches for
143 image processing, such as MATLAB®, Image-Pro Plus software, and Pores / Particles
144 and Cracks Analysis System (PCAS), to extract micro-parameters from the SEM
145 images (Cox and Budhu, 2008; Prakongkep et al., 2010; Liu et al., 2011; Taillon et al.,
146 2018). The key for these image processing methods is the thresholding used to identify
147 the particles and the pores in the binary image. However, it's still a big challenge to
148 determine the optimal threshold value for SEM images of clay, and there is significant
149 scope for advancements and refinements of the used techniques (Taillon et al., 2018).

150

151 The aim of this paper is to develop an improved quantification method for the
152 characterization of clay microstructure using SEM. The method should be more reliable
153 and more efficient. The influences of different milling methods and drying methods on
154 the clay microstructure are quantitatively characterized by micro-parameters to achieve
155 these goals. Besides, the following three aspects are discussed: 1. the magnification of

156 SEM image. 2. the number of SEM images. 3. image processing. Subsequently, the clay
157 from Hangzhou, China, was studied as an example.

158

159 **2. Factors influencing quantification of clay microscopic characterization**

160 Influencing factors include SEM sample preparation and SEM-based quantitative
161 analysis. SEM sample preparation mainly involves milling and drying. The SEM-based
162 quantitative analysis mainly focuses on image processing, magnification, and number
163 of images.

164

165 **2.1 Milling directions**

166 The milling direction may affect the clay microstructure characterization since clay
167 is an anisotropic material at the macro scale. The clay sample considered in this study
168 for SEM analysis was a small cuboid whose length, width, and depth were about 5 mm,
169 5 mm, and 2 mm, respectively. This SEM sample is milled from a remoulded sample,
170 which is a cylindrical specimen with 39.1 mm diam and 80 mm height. The method to
171 mill is a big issue.

172

173 **2.2 Drying techniques**

174 The clay sample should be dry when testing in the vacuum environment of SEM.
175 But if the clay is dried, the pores between clay particles would become smaller (Burton
176 et al., 2015; Sun and Cui, 2018), then the distance between particles would become

177 smaller, which could change the interparticle forces such as van der Waals and capillary
178 interactions, and hence the arrangement of the particles. Therefore, the clay
179 microstructure would be modified, resulting in parameters corresponding to an entirely
180 different microstructure. The method to dry is also a big issue.

181

182 ***2.3 Magnification and quantity of SEM image***

183 Several decisions are needed to be made before imaging (Trzciński, 2004). Among
184 them, the optimal selection of magnification and the number of images were most vital.
185 The key to the problem was to improve efficiency and reliability so that with a limited
186 number of images, all representative features have been captured and at the selected
187 appropriate magnification. In this paper, the interval estimation method is introduced
188 to make an optimal selection.

189

190 ***2.4 Image processing***

191 The SEM image, for example, Fig.2a, is a grey photo of clay, whose relatively dark
192 region represented pore space, and the relatively lighter region referred to as clay
193 particle. The thresholding of the image is carried out to separate the two parts. The total
194 range of threshold values is from 0 to 255. If the threshold value is set 0 in the PCAS
195 program, the whole image is white, which means that all elements in the image are clay
196 particles (Fig. 2b). On the contrary, if the threshold value is set to be 255, the whole
197 image is black, i.e. all elements in the image are regarded as pores (Fig. 2c).

198 In the image processing for general images, there are two approaches to calculate the
199 threshold value, one is the artificial approach, the other is the theoretical approach. The
200 artificial approach compares the binarized images with the original SEM image by
201 naked eyes. This artificial method can obtain the threshold directly, but it is time-
202 consuming and error-prone. As for the theoretical approach, there are many methods,
203 such as the method of iterative global thresholding (Shaikh et al. 2011), Otsu's method
204 (Otsu, 1979), and the method of local properties based thresholding (Cheremkhin and
205 Kurbatova, 2019). The theoretical approach can compute the threshold using algorithms
206 such as iteration and variation of iteration (Bansal and Maini, 2013). However, many
207 existing theoretical methods are not suitable for SEM images of clay since the particles
208 and pores in the images are very small.

209

210 **To** combine the advantages of both the artificial approach and the theoretical approach,
211 and avoid their disadvantages, the *A-K* threshold determination method is proposed in
212 this paper. This new method also takes the natural porosity into account, and this
213 method can improve the efficiency and reliability of image processing. It should be
214 noted that the natural porosity is the fraction of the volume of pores over the total clay
215 volume, and the natural porosity can be measured in a conventional geotechnical
216 experiment.

217

218 **3. Methodology for quantitative analysis of microstructures in SEM**

219 The four main factors mentioned above should be considered to improve the clay
220 quantification method.

221

222 **3.1 The method of milling**

223 The key issue in milling operation is to obtain an undisturbed surface. To study the
224 influence of milling directions on the quantification result, samples from cross-section
225 and vertical-section of Hangzhou clay were compared. The cross-section is parallel to
226 the bottom base of the cylindrical remoulded clay sample, while the vertical-section is
227 perpendicular to the bottom base. The methods to obtain the cross-section surface and
228 vertical-section surface are shown in Fig. 3a and Fig. 3b, respectively. At first, the
229 remoulded clay sample was broken into a strip about 20 mm (length) × 5 mm (width)
230 × 5 mm (height) from the center. Then two parallel grooves of 0.5mm depth were
231 carved in the middle of this strip. The distance between the grooves was 2 mm. After
232 that, the sample was carefully broken by hand along the groove to get the undisturbed
233 surface for SEM observation (SEM sample).

234

235 **3.2 The method of drying**

236 To study the influence of drying techniques on the quantification result, samples
237 dried by four popular methods, including liquid nitrogen frozen-vacuum drying, critical
238 point drying, air drying, and oven drying (Delage and Lefebvre G,1984; Dey et al.,

239 1989; Janecek and Robert, 2016; Lindroth et al., 1988). The steps are detailed in the
240 following lines:

241

242 In the liquid nitrogen frozen-vacuum drying method (Trzcinski, 2004), SEM
243 Sample was immersed in liquid nitrogen for 1 min before being placed in the vacuum
244 dryer for 20 h (equipment model: ALPHA1-4). As for the critical point drying method
245 (Lawrence, 1979), the sample was dehydrated in a graded ethanol series (5%, 15%,
246 50%, 75%, 100%) at an interval of 20 min each, and subsequently dried in a critical
247 point drying apparatus for 48 h (equipment model: Quorum-Emitech K850), which is
248 covered with liquid carbon dioxide. For the air drying method (Youn and Tonon, 2010),
249 the SEM sample was kept in the natural environment for 48 h. In the oven drying
250 method, the SEM sample was dried in the oven directly for 12 h at 105 °C (Korpa,
251 2006).

252

253 ***3.3 Image processing for clay microscopic quantification***

254 ***3.3.1 A-K threshold determining method***

255 A novel *A-K* method for determining threshold value has been developed. This
256 method combines the advantages of the theoretical approach and artificial approach and
257 thus can improve the efficiency and reliability of image processing. The method
258 consists of two steps: the first step is the prediction of the threshold range, and the
259 second step is the determination of an optimal threshold value. It should be noted that

260 the threshold range varies from the start-point to the end-point. For example, a threshold
 261 range is [20, 100], which means that 20 is the start-point, and 100 is the end-point.

262

263 (1) The prediction of the threshold range

264 This step is aimed at finding the start-point and the end-point within which the
 265 threshold value lies. For the convenience of description, the start-point is assumed to
 266 be the A -value, and the end-point is assumed to be the K -value. The A -value is
 267 confirmed on the principle that image porosity obtained from image processing is close
 268 to natural clay porosity, while K -value could be calculated by Otsu's method (Otsu,
 269 1979).

270

271 Since the SEM image reflected the macroscopic properties of the clay, the three-
 272 dimension surface porosity (3-D surface porosity) should be close to the natural clay
 273 porosity. Clay is assumed to be homogeneous, so as shown in Fig.4a, the A -value can
 274 be obtained from the following formula:

$$275 \quad n_{natural} = n_{3-D}, \quad n_{3-D} = \frac{V_{pore}}{V_{total}} = \frac{\int_0^a p dg}{\int_0^{255} p dg} \quad (1)$$

276 where, a is the A -value, $n_{natural}$ is the natural clay porosity, n_{3-D} is the 3-D
 277 surface porosity, V_{pore} is the volume of the pore, and V_{total} is the total volume of
 278 clay sample. p is the number of pixels, g is the grey value.

279

280 The natural porosity can be measured from the conventional geotechnical test methods,
281 while the 3-D surface porosity can be obtained from the grey histogram (Fig. 4b) based
282 on the 3-D surface clay model (Fig. 4d) of the original SEM image (Fig. 4e).

283

284 In fact, the grey histogram is a kind of statistical analysis of the 3-D surface model. The
285 grey histogram represents the number of pixels with a certain grey value in the SEM
286 image. Besides, in the grey histogram, if the threshold value is a , the grey range of $(0,$
287 $a)$ represents the pores, and the grey interval of $[a, 255]$ represents the particles (Fig.
288 5a).

289

290 The 3-D surface porosity of the SEM image is the ratio of the pore area to the total area.
291 The pore area can be calculated by integrating the interval of $(0, a)$ in the grey
292 histogram, while the total area of the grey histogram equalled the whole area of the
293 SEM image. In the example shown in Fig. 4, the SEM image (Fig.4e) of a clay sample
294 has a natural porosity of 0.311. If the threshold is 43 (the value of the threshold is
295 accurate to the single-digit), the 3-D surface porosity of the SEM image is 0.319, and
296 0.319 is the closest to the natural porosity 0.311. Therefore, the A -value is 43.
297 Subsequently, the K -value of the threshold range (Fig.4c) is calculated by Otsu's
298 method. For the SEM image in Fig.4e, the K -value is 76, and hence, for this example
299 considered here, the threshold range would be from 43 to 76.

300

301 (2) The determination of an optimal threshold value

302 The determination of the optimal threshold value within the threshold range
303 calculated above was carried out with the help of the PCAS program. The greyscale in
304 the PCAS program was adjusted within the predicted threshold range above. At the
305 same time, an artificial comparison with naked eyes was conducted to select the
306 greyscale that could best divide pore area and soil particle area.

307

308 In terms of the SEM image in Fig.4e, the artificial comparison was conducted in the
309 threshold range of [43, 76] by moving the grey bar of PCAS to show the different
310 binarized images of each threshold value. Typical comparative images for various
311 threshold values within the identified range are shown in Fig.5b. After comparing these
312 binarized images with the original SEM image, results showed that when the grey value
313 was 55, the image division had the optimal effect, since the binarized image matched
314 the original SEM image best. Therefore, the grey value of 55 was determined as the
315 threshold value for this SEM image.

316

317 3.3.2 Measurement of micro-parameters

318 Based on the threshold value calculated above, the SEM image was converted into
319 a binarized image, then the measurement of micro-parameters can be done with the help
320 of PCAS software (Liu et. al, 2011, 2013 and Tang et al, 2012). Finally, the image

321 porosity, mean shape factor, mean fractal dimension, roundness, and orientation
322 probability entropy can be obtained.

323

324 ***3.4 Interval estimation for clay microscopic quantification***

325 The method of interval estimation was proposed by Neyman (Neyman, 1937),
326 aiming at ensuring that the estimated interval had the highest accuracy with certain
327 reliability. In statistics, interval estimation is used to calculate an interval of possible
328 values of an unknown population parameter with sample data. The definition of interval
329 estimation is in the Appendix 1.

330

331 ***3.5 Micro-parameters for clay microscopic quantification***

332 Fig. 6a shows three clay particles in the microstructure. Their particle shapes, particle
333 directions, edge shapes, and edge complexity variations are quite different. These
334 features can be quantified by micro-parameters. In this paper, five statistical parameters,
335 i.e., image porosity n_i , mean shape factor F , mean fractal dimension D_v , roundness
336 R_0 , and orientation probability entropy H_m , are introduced to describe the fraction of
337 pore, particle shape, smoothness of particle edge, complexity variation of particle edge
338 and orientation distribution of clay particles, respectively. These micro-parameters are
339 defined in the Appendix 2.

340

341 **4. An example for characterization of clay microstructure**

342 **4.1 Materials**

343 To illustrate the improved quantification method described above, a clay from
344 Hangzhou, China, was employed as an example, which is a typical clay with low
345 permeability and high natural water content. Clay's physical properties are reported in
346 Table 1. The mineralogy and chemical composition of clay are provided in Table 2.

347

348 **4.2 Methods**

349 The methods mainly include four steps (i.e., Remolded sample preparation, sample
350 preparation for SEM imaging, SEM imaging, and SEM image processing). Their
351 detailed operations are presented in the Appendix 3.

352

353 **4.3 Test plan**

354 In this paper, four groups of tests were conducted. Each group has its unique test
355 objective, and each group contains several SEM samples. The first group is used to
356 compare different milling directions (Table 3). SEM samples from cross-section (1#,
357 3#, 5#, 7#) and vertical-section (2#, 4#, 6#, 8#) of 4 different remolded clay samples
358 (I#, II#, III#, IV#) were tested. These SEM samples were air-dried, and 10 SEM images
359 with magnification of 2000x were taken for each sample.

360

361 The second group aims at comparing different drying techniques. For this purpose, 4
362 SEM samples (9#, 10#, 11#, 12#) were prepared. All these SEM samples were made

363 from remolded clay sample V#, whose void ratio and water content were 0.45 and 20%
364 respectively. These SEM samples were dried in air (for 9# sample), hot-air oven (for
365 10# sample), critical point-device (for 11# sample), and liquid nitrogen frozen-vacuum
366 device (for 12# sample), respectively. The cross-sections of these SEM samples were
367 observed, and 10 SEM images with a magnification of 2000 times were taken for each
368 sample.

369

370 The third group is prepared to compare different SEM image magnifications. Only one
371 SEM sample (13#) was required here, which was obtained from clay sample VI#, whose
372 void ratio and water content were 0.51 and 21%, respectively. SEM sample 13# was
373 air-dried, and the cross-section was observed. For different magnifications, SEM
374 images with magnifications of 500×, 1000×, 1500×, 2000×, 3000×, 5000× were
375 obtained and analyzed.

376

377 The fourth group is used for comparing different quantities of SEM images. One SEM
378 sample, which was used in the third group (i.e., 13#), along with another SEM sample
379 (14#) was used for this purpose. Sample 14# is milled from the remolded clay sample
380 VII#, whose void ratio and water content were 0.66 and 30%, respectively. Both were
381 air-dried, and the cross-section was observed. 10 images with a magnification of 2000×
382 were taken for both SEM samples.

383

384 **4.4 Results of SEM imaging**

385 4.4.1 Effect of different milling directions on clay microscopic quantification

386 The micro-parameters from the SEM imaging for cross-section and vertical-
387 section samples are shown in Table 4, and the relative error in the micro-parameters
388 between the cross-section and the vertical-section of 4 remolded clay samples (I#, II#,
389 III#, IV#) are depicted in Fig. 6b.

390

391 The results show that the cross-section and vertical-section had similar image
392 porosity n_i , and the max relative error between the two values was 1.5%. The
393 probability entropy H_m of the two sections were also close, and the max difference
394 was observed to be 0.4%. These similar results were not surprising given that the clay
395 sample is homogeneous, and hence, the arrangement of clay particles is similar in each
396 direction. On the contrary, larger variations were observed in other micro-parameters.
397 The fractal dimension D_v of vertical-section was 3.6% bigger than cross-section, and
398 the mean shape factor F of the cross-section was up to 12.8% higher than that of
399 vertical-section. The max relative error in roundness between cross-section and
400 vertical-section was 5.5%. These relatively big differences are because the three
401 parameters are related to the particle shape. It's well known that most clay particles are
402 flat. Therefore, the difference between the shape projected on cross-section and that on
403 vertical-section is obvious.

404

405 4.4.2 Effect of different drying techniques on clay microstructure quantification

406 Volumetric shrinkage will occur when the clay is dried, and the degree of
407 shrinkage varies under different drying techniques. The quantitative comparison of
408 each method is shown in Table 5 and Fig. 7. Both the micro-parameters and the pore
409 sizes are compared. The pore sizes include pore area, pore length, and pore width.

410

411 The data show that there was no significant difference in micro-parameters and in pore
412 sizes between the two methods of liquid nitrogen frozen-vacuum drying and critical
413 point drying, owing to that the original clay structure was maintained by these two
414 methods. Compared with oven drying, the results of air drying were closer to the results
415 of the former two drying methods mentioned above. For example, among all the micro
416 parameters, the biggest difference between air drying and liquid nitrogen frozen
417 vacuum drying was 15% for image porosity n_i . While the biggest difference between
418 oven drying and liquid nitrogen frozen-vacuum drying was 51%, which is also shown
419 by the image porosity n_i . Meanwhile, among all the pore sizes, the biggest difference
420 between air drying and liquid nitrogen frozen was the maximum pore length, and the
421 value was 23%. The biggest difference between oven drying and liquid nitrogen frozen-
422 vacuum drying is the maximum pore length, while the value was 63%. These
423 differences were because oven drying had a larger shrinkage than others.

424

425 4.4.3 Determination of optimal image magnification

426 As shown in Fig.8, the clay sample was placed in the SEM to get the images with
427 different magnifications of 500×, 1000×, 1500×, 2000×, 3000×, 5000×. In these images,
428 if the magnification is too low, the clay particles and pores are hard to be recognised.
429 On the contrary, if the magnification is too high, then the whole image is occupied by
430 large particles, which brings difficulties in recognising the details of microstructural
431 features. Therefore, the optimal magnification should be between 500× and 5000× for
432 this sample. The optimal magnification can be selected from this range with the help of
433 interval estimation. The analysis of interval estimation, whose results are reported in
434 Fig.9, is based on the micro-parameters that are listed in Table 6.

435

436 In Fig.9, there are three lines and six dots in each figure. The first line and the third line
437 show the upper limit and lower limit of confidence interval (95% confidence level) for
438 each micro-parameter, respectively, while the line in the middle shows the mean value
439 of the micro-parameter. The dots are the micro-parameter value of different
440 magnifications. The calculation of confident interval and mean value are based on all
441 the SEM images considered in this experiment.

442

443 Based on these figures, there exists an optimal magnification for each parameter. For
444 example, in Fig.9a, the magnifications of the dots that are located in the area between
445 the upper line and the lower line are better than the magnifications of dots that are

446 outside this area, since parameter values of dots inside are in the confidence interval.
447 Furthermore, the magnification of the dot that is closer to the middle line is better than
448 that of another dot that is farther, because there is a greater probability that the mean
449 value can represent the real value of the micro-parameter.

450

451 Finally, the optimal magnification for the tested clay can be obtained, according to the
452 five commonly used micro-parameters used in this study. If one magnification is always
453 optimal in the five figures, then this magnification can be the best choice. Fig.9 shows
454 that the dots of 1500× and 2000× were inside the confidence interval in all cases, while
455 dots of other magnifications sometimes were out of the confidence interval. Therefore,
456 the magnification of 1500× and 2000× can be considered to be more reliable than others.
457 As for the best one, 1500× should be selected, since, in four of the five cases, the dot
458 of 1500× was closer to the mean line than the dot of 2000×, which means that most
459 micro-parameters were closer to the real value when the magnification is 1500×. Hence,
460 the optimal magnification of Hangzhou clay was considered to be 1500×.

461

462 4.4.4 Determination of optimal image quantity

463 According to the results above, SEM images with a magnification of 1500× were
464 used here to analyze the optimal quantity of images. In theory, when the quantity of
465 SEM images is larger, the mean value of micro-parameters would be closer to the true

466 value. But the time spent taking SEM photos would be more. The more efficient way
467 was to take fewer images to get the most accurate values of the micro- parameter.

468

469 10 SEM images had been taken for the SEM sample 13#. Five micro-parameters of
470 each image were calculated by the image processing method introduced above and are
471 listed in Table 7. Later, the interval estimation was done based on these data. For each
472 micro-parameter, interval estimation was carried out for the different quantities of
473 images, such as 2 images, 3 images, or 10 images. These results are presented in Fig.10.

474

475 For each parameter in Fig. 10(a-e), there are 9 bars with a short vertical line of different
476 lengths on the top. The height of each bar is the mean value of a certain image quantity,
477 for example, the first bar shows the mean value of 2 images. While the short vertical
478 line on the top of each bar represents the confidence interval, which means that there is
479 a 95% possibility that the true value of the micro-parameter is in this interval. The
480 length of these short vertical lines is useful because if the length is smaller, it will be
481 more credible that the mean value can be used to represent the true value of the micro-
482 parameter.

483

484 Fig. 10 shows that the length of confidence interval decreased as the number of images
485 increased when the number of images was less than 5. From 2 to 5 images, there is 78%,
486 83%, 78%, 81%, 78% decline for n , F , H_m , D_v , R_0 , respectively. But the declining

487 trend was less significant when the number of images was more than 5, except for the
488 mean shape factor F , which might be caused by accidental factors. And from 6 to 10
489 images, there is 23%, 37%, 38%, 36% decline for n , H_m , D_v , R_0 , respectively.

490

491 Further, the percentage difference between adjacent two confidence interval lengths is
492 defined as error ε . Assuming that when the error ε is less than 25%, the confidence
493 interval is considered acceptable, indicates that the corresponding number of images is
494 selected. The errors ε of each micro-parameters for SEM sample 13# are listed in
495 Table 8. Results show that, with the exception of the mean shape factor F , the error ε
496 is less than 25% when the quantity is equal to 5 or more. The error ε is abnormal in
497 the mean shape factor F , that is, when the quantity is 7, the ε increases to 49%.

498

499 **To** verify these observations, another SEM sample 14# was used. The void ratio and
500 water content of SEM sample 14# were 0.656 and 30%, respectively. The methodology
501 adopted was the same as in the case of SEM sample 13#. Micro-parameters of each
502 image are listed in Table 9, the results of interval estimation are shown in Fig.11, and
503 the error ε are listed in Table 10. The results show that when the number is equal to 5
504 or more, the error ε are always less than 25% for all the micro-parameters. Therefore,
505 5 images and more than 5 images meet the requirements, hence, the smallest number
506 of 5 can be chosen as the optimal number.

507

508 **5. Discussion**

509 To further demonstrate the reliability and efficiency of the proposed improved
510 quantification method, more details about the 3-D surface model are presented to prove
511 the reliability of the *A-K* method. Besides, comparison with other researches is
512 discussed.

513

514 ***5.1 Demonstration for reliability and limitation of the 3-D surface model***

515 The 3-D surface model in Fig. 4d is composed of an SEM image and the
516 corresponding grey value of each point in the SEM image. The dimension of grey can
517 reflect the spatial features of the structure surface on the 3rd dimension. This is because
518 the grey value of the SEM image can reflect the distance from the structure surface to
519 the imaging surface due to the imaging principle (as shown in Fig. 12). Fig. 12a shows
520 the imaging principle of secondary electron imaging mode in the SEM, and Fig. 12b
521 illustrates that the spatial features of the structure surface can be reflected by grey
522 values.

523

524 In Fig.12a, the high-energy incident electrons were emitted into the clay sample by the
525 electron gun in the SEM, then the secondary electrons in the clay particles can be
526 excited. These secondary electrons can be captured by the detectors in the SEM, and
527 finally, generate an SEM image with different brightness areas inside. Higher
528 brightness area means more electrons accumulation, and more electrons mean a shorter

529 distance from the structure surface to the imaging surface. Therefore, the bright areas
530 in the SEM image represent clay particles because the secondary electrons were
531 generated from clay particles. While the relative dark areas in the SEM image represent
532 pores since the pores cannot generate electrons. Since the degree of brightness in SEM
533 images can be described by the grey value, and the distance from the structure surface
534 to the imaging surface describes the spatial features of the structure surface. Therefore,
535 there is a relation between the grey value and the spatial features of the structure surface,
536 as shown in Fig. 12b.

537

538 However, the porosity calculated by the 3-D surface models in Fig. 4 only describes the
539 porosity of the structure surface, and it can't show the pores behind the clay particles
540 on the surface. For instance, the pores may look quite small in the 2D image simply
541 because its appearance is small but inside it may be very big, such as pore 1 in Fig. 12b.

542

543 **5.2 Comparison with other thresholds determination methods**

544 To verify the proposed *A-K* method is better than the typical theoretical methods.
545 An example is given to compare different thresholds determination methods in the
546 following. Fig. 13a is the original image, which is the same as Fig. 4e. The thresholds
547 for Fig. 13a obtained through the *A-K* method (Fig. 13b), the method of iterative global
548 thresholding (Fig. 13c), the Otsu's method (Fig. 13d), and the method of local
549 properties based thresholding (Fig. 13e) were 55, 106, 76, 52 respectively. The different

550 threshold values from these methods resulted in a great variation in the resultant binary
551 image after processing. The dark area in Fig. 13b and Fig. 13c was much more than the
552 image in Fig. 13a, while the dark area in Fig. 13d was a little lesser than Fig.13a.
553 Meanwhile, Fig. 13b is the most similar to Fig. 13a. Besides, the difference in the binary
554 image could also be characterized by image porosity n_i . As shown in Fig. 13f, n_i
555 varied from 0.44 to 0.86. The natural porosity of Fig. 13a is 0.311, and n_i of Fig. 13b
556 and Fig. 13e are much closer to the natural porosity than Fig. 13c and Fig. 13d.

557

558 ***5.3 Comparison with other quantification methods***

559 Few studies have investigated the quantification method for SEM experiments
560 systematically. Most of the available studies have raised the challenges in
561 microstructure characterization, but still, need to be further studied to find the solutions.
562 For example, the differences between these drying techniques are inconsistent with the
563 research of other studies (Korpa, 2006; Osipov, 1985), and the importance of milling
564 direction for credible quantification is also agreed most with Trzciński (2004). But in
565 their research, no comparison of influence on micro-parameters (image porosity, mean
566 shape factor, mean fractal dimension, roundness, and orientation probability entropy)
567 was presented. In terms of the image magnification, Zhou et al. (2021) compare the
568 magnification of 500×, 800×, 3000× and 20000×. The magnification of 800× is used
569 for further quantitative analysis, but no theoretical reason was given. As for the number
570 of images, Trzciński (2004) proposed that the accuracy of characterization can be

571 improved by a bigger number of the analysed sample parts because the data from one
572 part do not coincide with results from a different portion of the same SEM sample. But
573 no further discussion on the number of images was provided. The improved
574 quantification method in this paper presents solutions to these challenges.

575

576 **6. Conclusions**

577 This paper aims to propose a practical and economical method to improve the
578 reliability and efficiency in the quantification technique of clay microstructure using
579 SEM. **The following conclusions are drawn:**

580

581 (1) The *A-K* threshold determination method is proposed to determine the optimal
582 threshold, combining the advantages of the artificial approach and theoretical
583 approach. An example has been given to show that the binary image of the *A-K*
584 method is more fit for the original SEM image than images processed by other
585 typical threshold determining methods.

586

587 (2) There exists an optimal magnification and an optimal number of images that can
588 enhance the experimental efficiency. **The anisotropy in the clay microstructure**
589 **should be considered for choosing milling directions. The quantification results are**
590 **significantly affected by the drying techniques.**

591

592 (3) This study presents a novel method to deal with the challenge of extracting
593 quantified micro-parameters from SEM images with higher reliability and higher
594 efficiency. As a result, an improved microstructure quantification method for
595 Hangzhou clay can be suggested: liquid nitrogen frozen-vacuum drying, sample
596 milled from the same direction, 1500× magnification, and 5 SEM images.

597

598

599 **Data Availability Statement**

600 All data, models, or code generated or used during the study are available from the
601 corresponding author by request, including all raw data from the tests, all used test
602 results, and codes used for the image analysis.

603

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List of Table Captions761 **Table 1** Physical properties of Hangzhou clay.762 **Table 2** Mineralogy and chemical composition of Hangzhou clay.763 **Table 3** Testing program of the first group for comparing different milling directions.764 **Table 4** Micro-parameters of different milling directions.765 **Table 5** Micro-parameters of different drying techniques.766 **Table 6** Micro-parameters of images with different magnifications of 13# SEM sample.767 **Table 7** Micro-parameters of each image for 13# SEM sample.768 **Table 8** Error ε of each micro-parameter for 13# SEM sample.769 **Table 9** Micro-parameters of each image for 14# SEM sample.770 **Table 10** Error ε of each micro-parameter for 14# SEM sample.

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781 **Table 1** Physical properties of Hangzhou clay.

Water content, w (%)	Bulk density, ρ (g/cm ³)	Specific gravity, G_s	Porosity, n	Liquid limit, WL	Plastic limit, WP	Particle size distribution		
						0.075~2mm	0.002~0.075mm	<0.002mm
30%	2.01	2.505	0.522	38.0	21.4	25%	56%	19%

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785 **Table 2** Mineralogy and chemical composition of Hangzhou clay (Huang et al. 2017).

Mass percentage of main minerals (%)				Mass percentage of main elements (%)			
Quartz	Chlorite	Phlogopite	Anorthite	oxygen(O)	silicon(Si)	aluminum(Al)	others
41.8	34.5	4.4	19.3	46.65	29.85	11.47	12.03

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793 **Table 3** Testing program of the first group for comparing different milling directions.

No. of SEM sample	The No. of remolded		Void ratio	Water content	Milling direction
	clay sample that SEM	sample obtained from			
1#	Remolded sample I#		0.68	27%	Cross-section
2#	Remolded sample I#		0.68	27%	Vertical-section
3#	Remolded sample II#		0.67	26%	Cross-section
4#	Remolded sample II#		0.67	26%	Vertical-section
5#	Remolded sample III#		0.64	25%	Cross-section
6#	Remolded sample III#		0.64	25%	Vertical-section
7#	Remolded sample IV#		0.78	32%	Cross-section
8#	Remolded sample IV#		0.78	32%	Vertical-section

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803 **Table 4** Micro-parameters of different milling directions.

Clay sample No.	SEM sample No.	Milling method	Image porosity n_i	Mean shape factor F	Probability entropy H_m	Fractal dimension D_v	Roundn- ess R_0
I#	1#	Cross-section	0.411	0.293	0.989	1.441	0.421
I#	2#	Vertical-section	0.417	0.284	0.992	1.491	0.410
II#	3#	Cross-section	0.415	0.353	0.992	1.385	0.443
II#	4#	Vertical-section	0.410	0.310	0.993	1.386	0.420
III#	5#	Cross-section	0.374	0.337	0.995	1.439	0.433
III#	6#	Vertical-section	0.368	0.314	0.991	1.491	0.419
IV#	7#	Cross-section	0.428	0.276	0.991	1.529	0.395
IV#	8#	Vertical-section	0.421	0.277	0.994	1.552	0.411

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816 **Table 5** Micro-parameters of different drying techniques.

SEM sample No.	Drying techniques	Image porosity n_i	Mean shape factor F	Probability entropy H_m	Fractal dimension D_v	Roundness R_0
9#	Air drying	0.241	0.388	0.995	1.301	0.656
10#	Oven drying	0.138	0.447	0.992	1.201	0.816
11#	Critical point	0.277	0.397	0.986	1.295	0.618
12#	frozen-vacuum	0.284	0.378	0.987	1.324	0.623

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832 **Table 6** Micro-parameters of images with different magnifications of 13# SEM sample.

Magnification of image	Image porosity	Mean shape factor	Probability entropy	Fractal dimension	Roundness
500	0.368	0.333	0.982	1.431	0.396
1000	0.377	0.353	0.979	1.362	0.397
1500	0.337	0.393	0.985	1.301	0.416
2000	0.345	0.402	0.983	1.270	0.420
3000	0.299	0.430	0.986	1.242	0.430
5000	0.289	0.445	0.983	1.248	0.410

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846 **Table 7** Micro-parameters of 10 SEM images for 13# SEM sample.

Image No.	Image porosity	Mean shape factor	Probability entropy	Fractal dimension	Roundness
1	0.337	0.393	0.985	1.298	0.416
2	0.367	0.402	0.990	1.283	0.429
3	0.376	0.394	0.993	1.266	0.402
4	0.298	0.412	0.995	1.269	0.425
5	0.316	0.409	0.990	1.264	0.395
6	0.325	0.394	0.991	1.281	0.408
7	0.307	0.406	0.995	1.257	0.420
8	0.269	0.444	0.991	1.272	0.433
9	0.304	0.410	0.996	1.267	0.422
10	0.284	0.4278	0.991	1.278	0.426

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858 **Table 8** Error ϵ of each micro-parameter from 10 SEM images for 13# SEM sample.

Adjacent two quantity	Image porosity	Mean shape factor	Probability entropy	Fractal dimension	Roundness
2 and 3	0.730	0.789	0.533	0.582	0.596
3 and 4	0.093	0.099	0.318	0.410	0.436
4 and 5	0.270	0.253	0.322	0.236	0.054
5 and 6	0.231	0.179	0.244	0.236	0.234
6 and 7	0.133	0.169	0.116	0.049	0.170
7 and 8	0.073	0.490	0.163	0.162	0.024
8 and 9	0.122	0.138	0.034	0.125	0.129
9 and 10	0.063	0.041	0.114	0.114	0.096

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872 **Table 9** Micro-parameters of 10 SEM images for 14# SEM sample.

Image No.	Image porosity	Mean shape factor	Probability entropy	Fractal dimension	Roundness
1	0.362	0.392	0.990	1.281	0.415
2	0.434	0.394	0.994	1.288	0.411
3	0.360	0.392	0.992	1.263	0.422
4	0.446	0.375	0.986	1.283	0.404
5	0.326	0.405	0.989	1.287	0.447
6	0.364	0.396	0.992	1.271	0.397
7	0.440	0.378	0.995	1.304	0.411
8	0.368	0.378	0.996	1.291	0.409
9	0.362	0.395	0.992	1.273	0.414
10	0.291	0.407	0.996	1.261	0.411

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884 **Table 10** Error ϵ of each micro-parameter from 10 SEM images for 14# SEM sample.

Adjacent two quantity	Image porosity	Mean shape factor	Probability entropy	Fractal dimension	Roundness
2 and 3	0.755	0.787	0.804	0.260	0.463
3 and 4	0.302	0.770	0.139	0.458	0.139
4 and 5	0.116	0.057	0.311	0.277	0.436
5 and 6	0.230	0.230	0.208	0.171	0.102
6 and 7	0.098	0.052	0.034	0.140	0.190
7 and 8	0.150	0.088	0.063	0.138	0.153
8 and 9	0.123	0.120	0.140	0.101	0.140
9 and 10	0.077	0.020	0.051	0.016	0.120

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Appendix

Appendix 1

A.1.1 Definition of interval estimation

Let $F = \{f(x, \theta), \theta \in \Theta\}$ be a random distribution, where Θ is the parameter space for θ . $X = (X_1, \dots, X_n)$ is a random sample space from the distribution F . $g(\theta)$ is a real-valued function of θ . $\hat{g}_1(x)$ and $\hat{g}_2(x)$ are two statistics that are defined in the sample space X , and their values are in the Θ . Then the random interval $[\hat{g}_1(x), \hat{g}_2(x)]$ is an interval estimation of $g(\theta)$.

A.1.2 Confidence interval

$P_\theta(\hat{g}_1(x) \leq g(\theta) \leq \hat{g}_2(x))$ is the probability that the value of $g(\theta)$ is in the random interval $[\hat{g}_1(x), \hat{g}_2(x)]$. The random interval $[\hat{g}_1(x), \hat{g}_2(x)]$ is supposed to be an interval estimation of $g(\theta)$, if the value of α ($0 < \alpha < 1$) is given, and

$$P_\theta(\hat{g}_1(x) \leq g(\theta) \leq \hat{g}_2(x)) \geq 1 - \alpha, \quad g(\theta) \in \Theta \quad (2)$$

then $[\hat{g}_1(x), \hat{g}_2(x)]$ is the confidence interval of $g(\theta)$, and the confidence level of $g(\theta)$ is $1 - \alpha$. For example, if $\alpha = 0.05$, then $1 - \alpha = 0.95$, then the probability of $g(\theta) \in [\hat{g}_1(x), \hat{g}_2(x)]$ is 0.95, while the probability of $g(\theta) \notin [\hat{g}_1(x), \hat{g}_2(x)]$ is 0.05.

A.1.3 Interval estimation using t-distribution

Let's assume that the parametric distribution $F = \{f(x, \theta), \theta \in \Theta\}$ obeys normal distribution $N(\mu, \sigma^2)$, and $X = (X_1, \dots, X_n)$ is a sample drawn from $N(\mu, \sigma^2)$. μ and σ^2 are the unknown mean and unknown standard deviation of $N(\mu, \sigma^2)$, respectively. \bar{X} and S^2 are defined as the mean and variance of the sample $X = (X_1, \dots, X_n)$, respectively.

$$\bar{X} = \frac{1}{n} \sum_{i=1}^n X_i \quad (3)$$

$$S^2 = \frac{1}{n-1} \sum_{i=1}^n (X_i - \bar{X})^2 \quad (4)$$

If σ^2 is replaced by S^2 , then the statistic is known as t distribution:

$$t = \frac{\bar{x} - \mu}{s/\sqrt{n}} \quad (5)$$

Defining

$$T_{n-1} = \frac{\sqrt{n}(\bar{X} - \mu)}{S} \quad (6)$$

T follows the distribution of t_{n-1} , and the distribution of t is symmetrical about the origin point. For any $\alpha \in (0, 1)$, the upper quantile $t_{n-1} \frac{\alpha}{2}$ satisfies

$$P_{\mu}(|T| < \varepsilon) = 1 - \alpha \quad (7)$$

where,

$$\varepsilon = \frac{S}{\sqrt{n}} t_{n-1} \frac{\alpha}{2} \quad (8)$$

then the confidence space of μ with confidence coefficient α is

$$\left(\bar{X} - \frac{S}{\sqrt{n}} t_{n-1} \frac{\alpha}{2}, \bar{X} + \frac{S}{\sqrt{n}} t_{n-1} \frac{\alpha}{2} \right) \quad (9)$$

Appendix 2

A.2.1. Image porosity

In the SEM image, the whole area can be divided into two parts: clay particles and pores between them. The image porosity n_i can be calculated by:

$$n_i = \frac{A_1}{A_0} \quad (10)$$

where A_1 is the pore area; A_0 is the area of total SEM image. The value range of n is (0,1).

A.2.2 Mean shape factor

The shape factor F_i of a single particle describes the particle shape. F_i defines the degree to which the particle is similar to a circle, and can be calculated by the following method (Sezer et al., 2008; Liu, et al., 2011):

$$F_i = \frac{P}{L} \quad (11)$$

where P is the perimeter of a circle that has the same area as the clay particle; L is the actual perimeter of the clay particle. The mean shape factor F is the mean value of all the soil particles' shape factors in the SEM image. F can be calculated by:

$$F = \frac{\sum_{i=1}^n F_i}{m} \quad (12)$$

where m is the total number of clay particles in the SEM image. The value range of F is (0, 1). If the particle shape is close to a circle, then F is close to 1.

A.2.3 Fractal dimension

Fractal dimension D_v reflects the complexity of clay particles' edges. D_v can be calculated by the following equation (Dathe et al., 2001):

$$D_v = \lim_{r \rightarrow 0} \frac{\ln N(r)}{\ln r} \quad (13)$$

where r is the side length of a square box; $N(r)$ is the number of square boxes. And the calculation of the mean fractal dimension is similar to that of the mean shape factor.

A.2.4 Roundness

Roundness R_0 describes the smoothness or roughness of the perimeter along the particle edge. R_0 can be calculated by the following equation (Cox and Budhu, 2008).

$$R_0 = \frac{A_p}{A'} \quad (14)$$

where A_p is the real area of the particle; A' is the circumcircle area of clay particle, $A' = Q^2/(4\pi)$, where Q is the perimeter of particle circumcircle. And the calculation of the mean roundness is similar to that of the mean shape factor.

A.2.5 Orientation probability entropy

The concept of probabilistic entropy is introduced into the microstructure analysis of clay to define the orientation probability entropy H_m , which is used to represent the orderliness of clay particle arrangement. The definition of H_m is as follows (Liu, et al., 2011):

$$H_m = -\sum_{i=1}^k P_i(\alpha_p) \log_k P_i(\alpha_p) \quad (15)$$

where α_p is the direction of a soil particle. α_p can be computed directly in PCAS software, and α_p varies between $[0^\circ-180^\circ]$; k is the number of equally divided areas in the whole particle direction range $[0^\circ, 180^\circ]$, and k can be selected by the user. In this paper, k is set to be 18 (a random number). Thus, each division corresponds to 10° . $P_i(\alpha_p)$ is the percentage of soil particles whose directions α_p belong to a specific range, for example, when $i = 1$, $P_1(\alpha_p)$ means the percentage of soil particles whose directions α_p belongs to the direction range of $[0^\circ, 10^\circ]$.

The value interval of H_m is $[0,1]$. When $H_m = 0$, all the soil particles are parallel to each other. When $H_m = 1$, all the soil particles are in random directions. With the increase in the value of H_m , the directions of soil particles are more random.

Appendix 3

A.3.1 Remolded sample preparation

The undisturbed clay was sliced into small blocks, and then these clay blocks were oven-dried for 8 h at 105 °C, pulverized to pass a 2 mm sieve. After that, the clay powder was mixed with water to form remolded clay, then kept in natural condition for 24 h. The water contents of remolded clay are listed in section 4.3. Later, the remolded clay was transferred to a miniature mould apparatus, which is a split cylindrical mould with 39.1 mm diameter and 80 mm height. The remolded clay was compacted in 3 layers. Each layer was tamped and compacted with the compaction rod. The height and number of blows needed depend on the desired void ratio. According to the wanted void ratio for each remolded clay sample, the weight of the individual clay layers was calculated. Then, the remolded clay sample was slid out from the cylinder. All the experimental operations above meet the requirements of GB/T 50123-1999. The remolded sample is a cylindrical specimen with 39.1 mm diam and 80 mm height.

A.3.2 Sample preparation for SEM imaging

The remolded clay sample above needed to be milled, dried and gold coated before SEM observation. The methods to obtain the cross-section surface and vertical-section surface are shown in section 3.1. For the drying method, the SEM samples were dried with drying methods as described in section 3.2. Then before SEM imaging of the

samples, to make clay conductive, the surface of the SEM sample was coated with an additional thin layer of about 20 nm of gold by SBC-12 ion sputterer from KYKY Technology Co., LTD.

A.3.3 SEM imaging

The Scanning Electron Microscope (SEM) of FEG650 type produced by FEI company in the Netherlands was used for SEM observation. The goal was to obtain high-quality images. The accelerating voltage was 5 kV, the working distance was 10 mm, and the secondary electron imaging mode was operated. All the tests were conducted by the same experimenter, which can reduce subjectivity. For example, all the images can keep similar brightness and contrast. Finally, SEM images with suitable magnification and quantity were obtained.

A.3.4 SEM image processing

After SEM imaging, the images should be processed to calculate the micro-parameters. At first, the threshold value for each image is determined by *A-K* method, which is introduced in section 3.2. Then the threshold value can be used in the program of Pores (Particle) and Cracks Analysis System (PCAS). Subsequently, the micro-parameters of image porosity n_i , probability entropy H_m , fractal dimension D_v , mean shape factor F , roundness R_0 can all be obtained from PCAS software.

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Figure 9. Quantitative analysis for optimal magnification.

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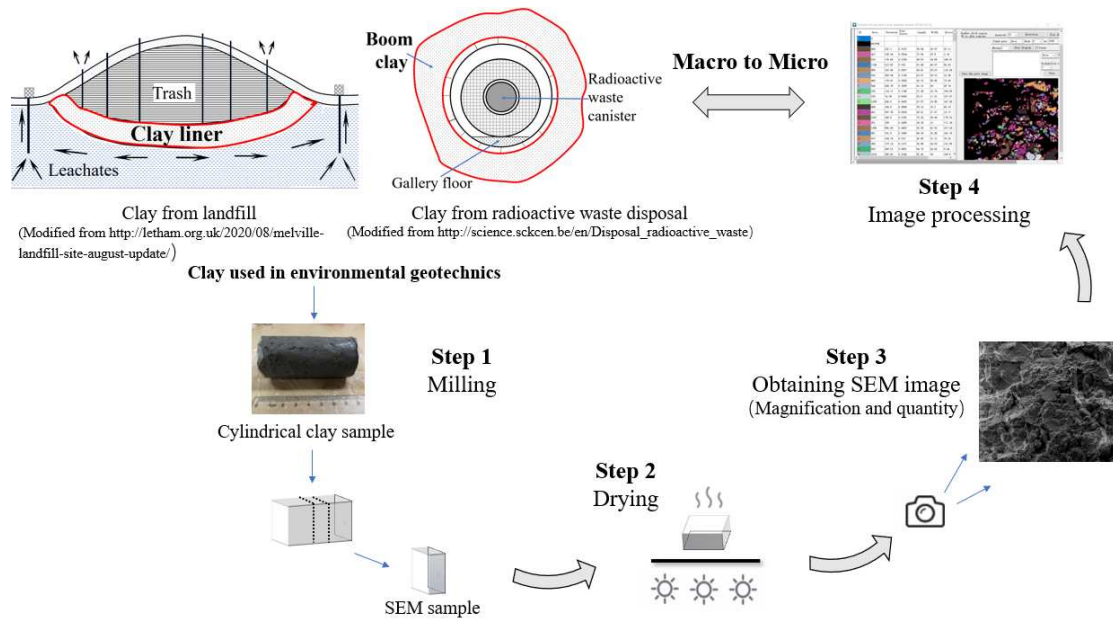


Figure 1 Main difficulties in the quantification procedure for characterization of clay microstructure using SEM.

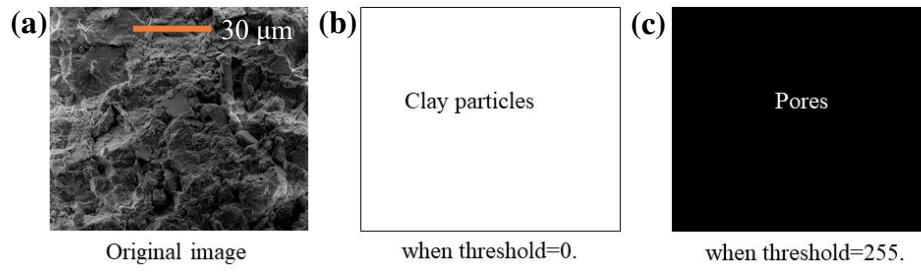


Figure 2 The range of threshold value in SEM image. (a) Original image. (b) The binary image when threshold value is 0. (c) The binary image when threshold value is 255.

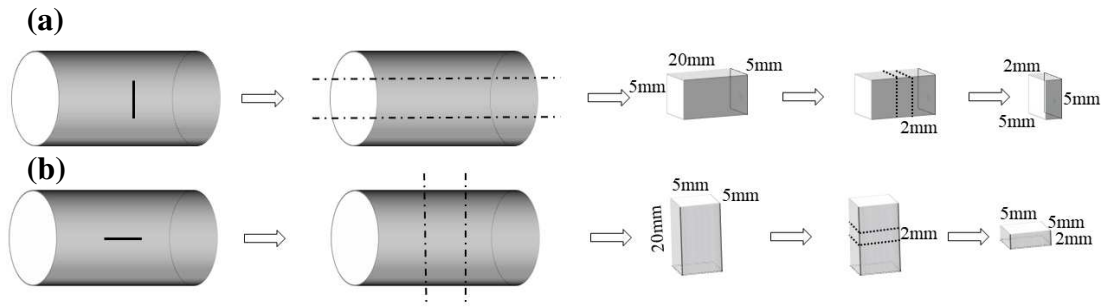


Figure 3 Milling methods. (a) The milling method of cross-section. (b) The milling method of vertical-section.

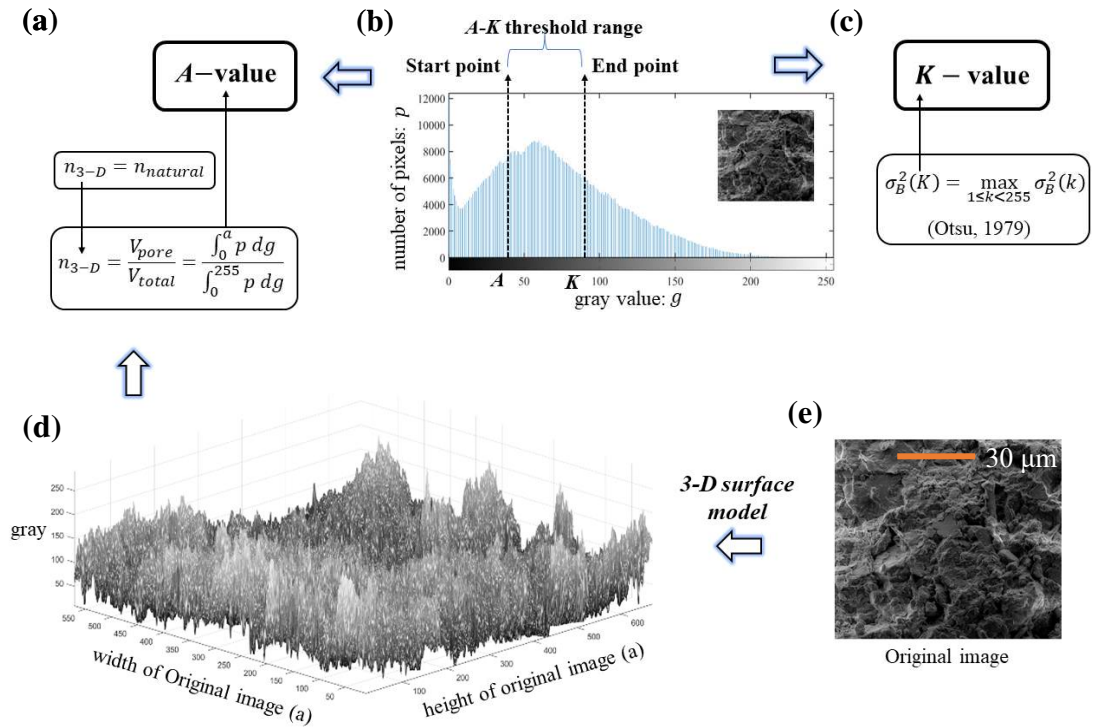


Figure 4 The A-K threshold determining method in image processing. (a-c) The prediction of threshold range. (d-e) The 3-D surface model.

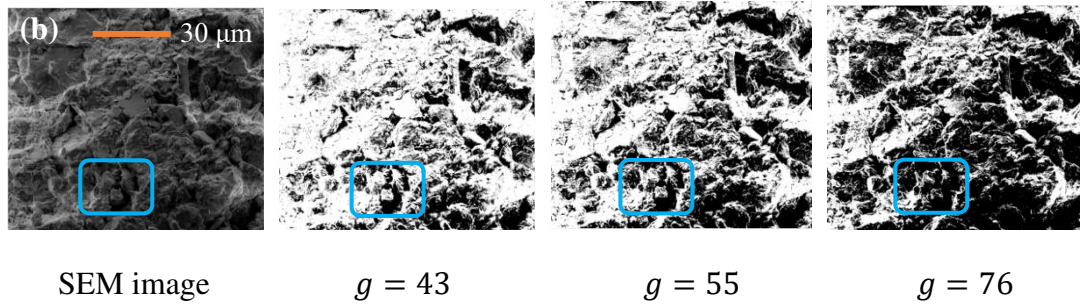
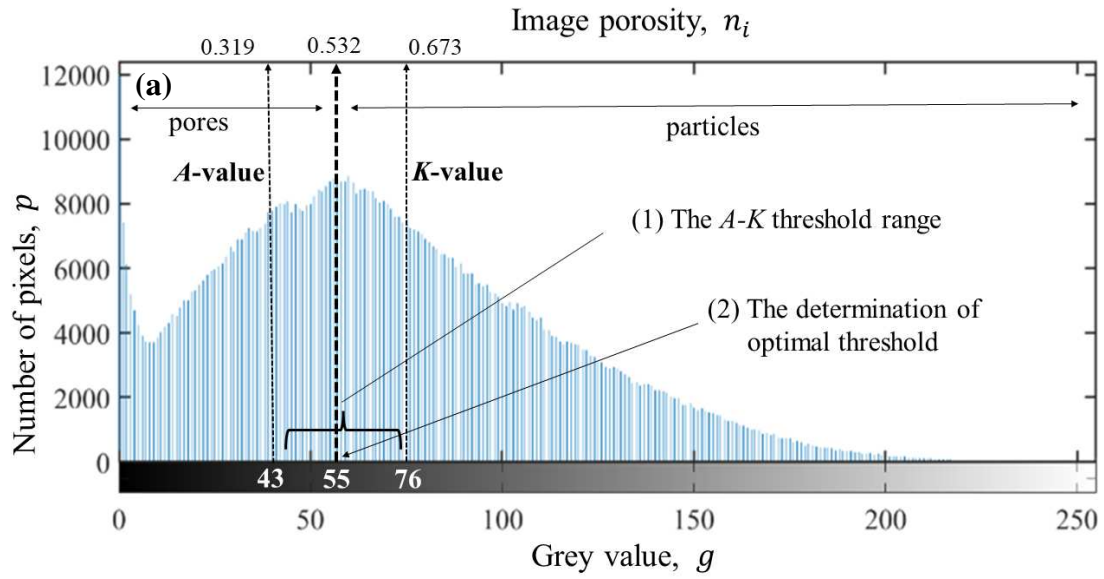


Figure 5 The determination of optimal threshold value in A-K method. (a) The A-K threshold range for original SEM image. (b) The optimal threshold value was determined by artificial comparison of binary images with threshold in the A-K range of [43, 76].

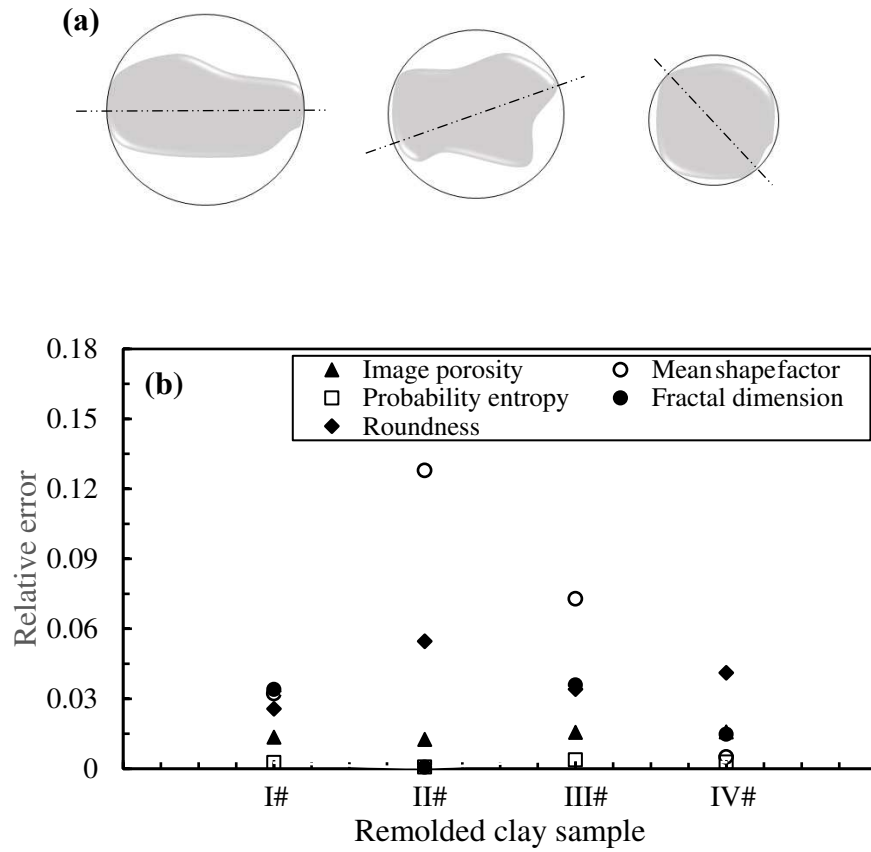


Figure 6 Clay particles and quantitative analysis of different milling directions. (a) Three clay particles with different features. (b) The relative error in the micro-parameters between the cross-section and the vertical-section of 4 remolded clay samples.

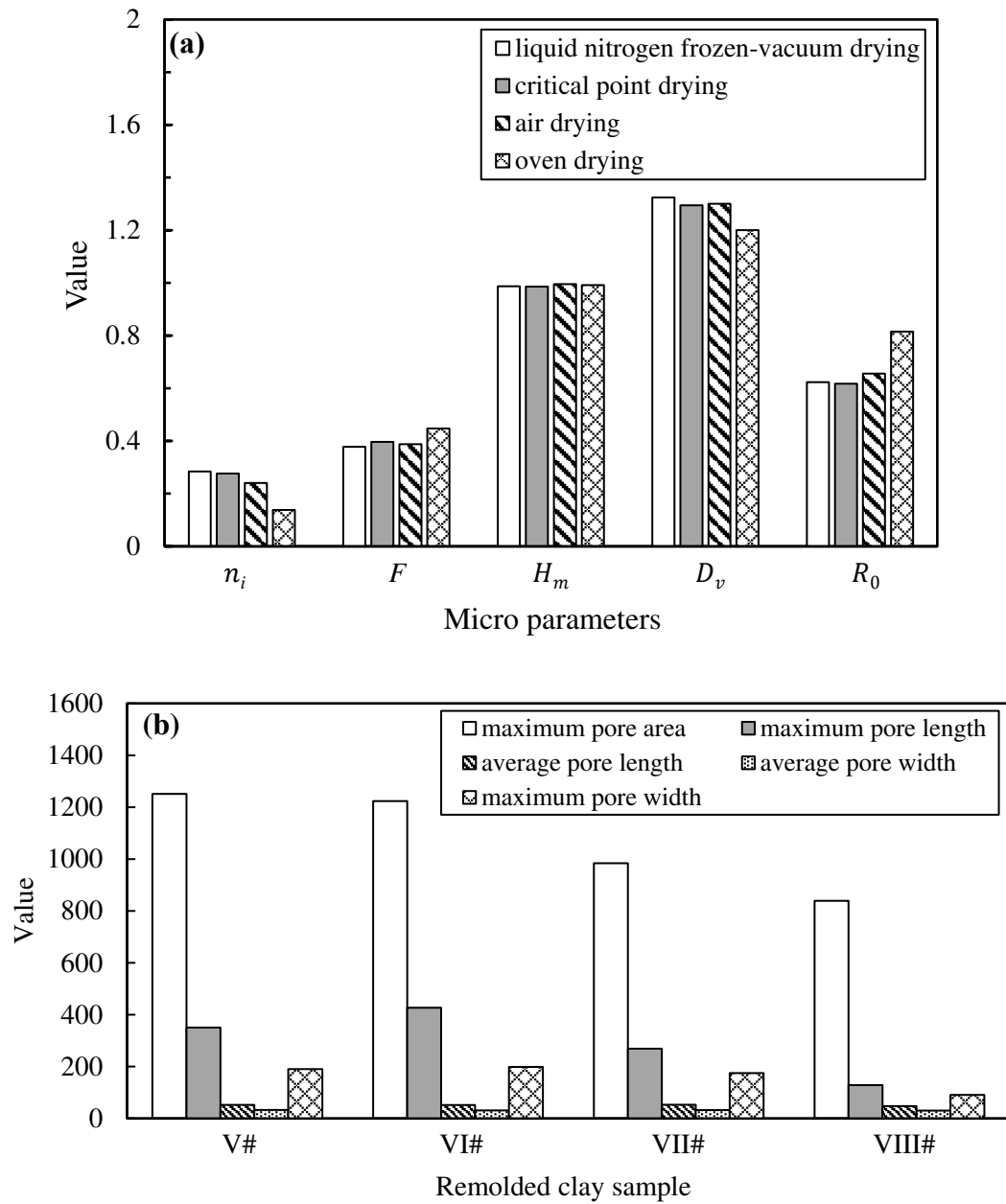


Figure 7 Quantitative analysis of different drying techniques. (a) Comparison of micro parameters for different drying techniques. (b) Comparison of pore sizes for different drying techniques

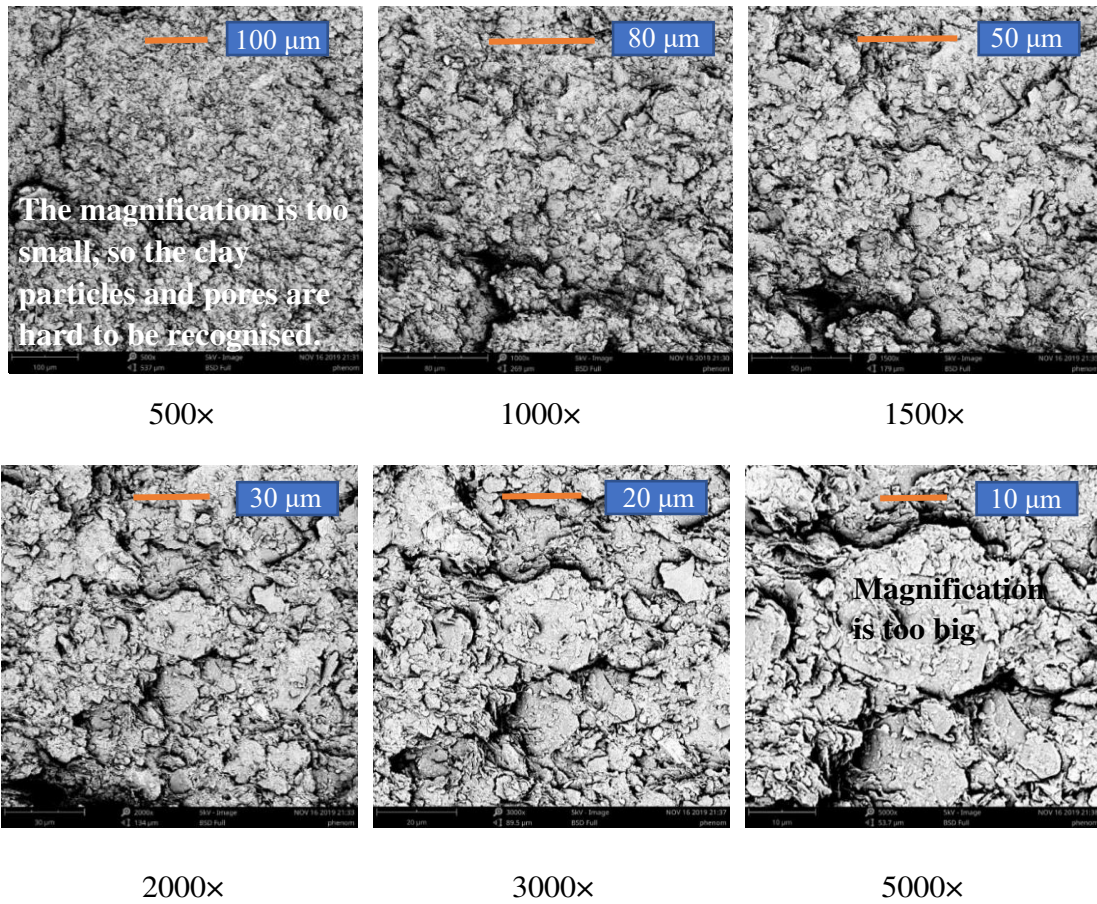


Figure 8 The comparison of magnifications between 500× and 5000× for this sample.

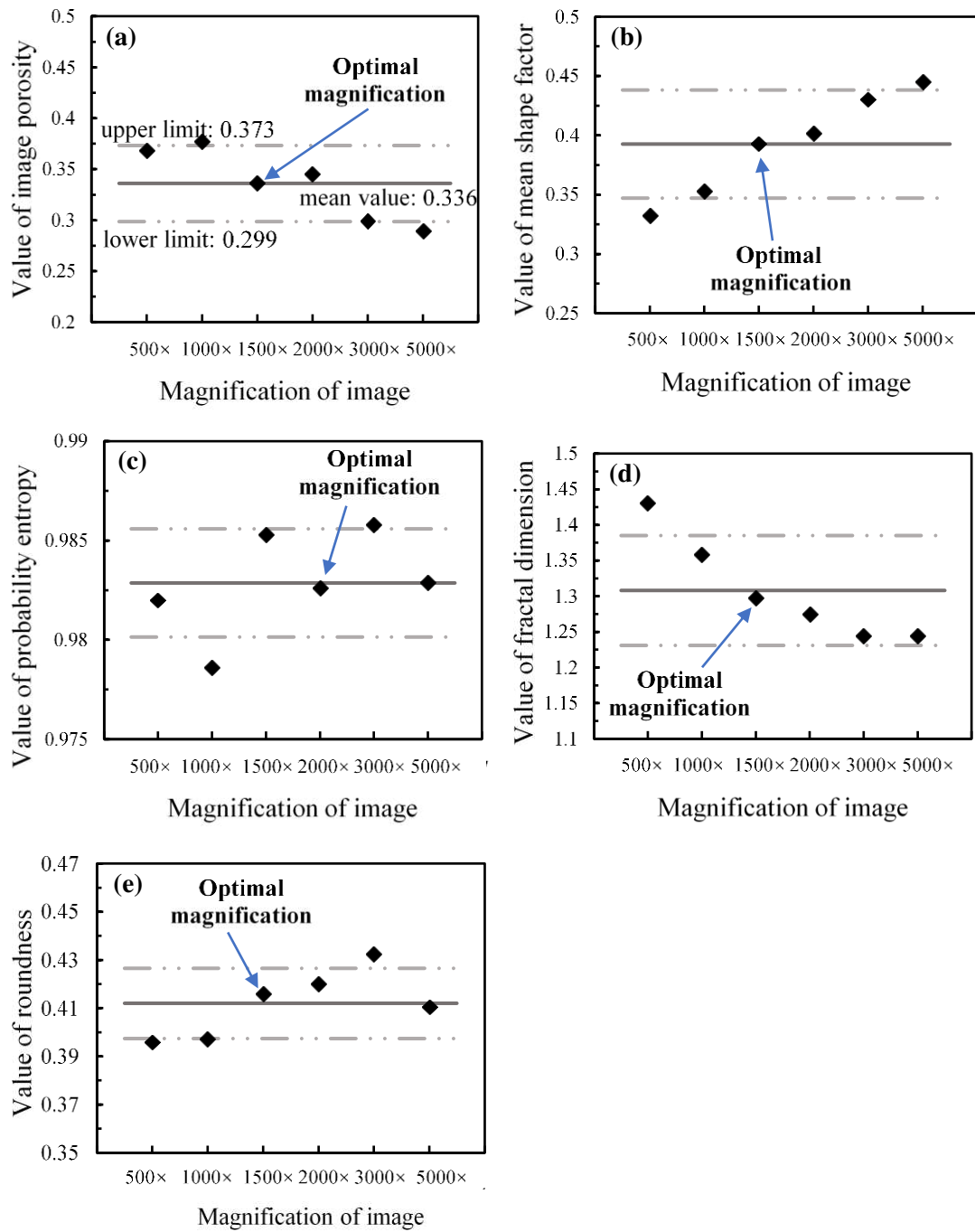


Figure 9 Quantitative analysis for optimal magnification. (a) Image porosity. (b) Mean shape factor. (c) Probability entropy. (d) Fractal dimension. (e) Roundness.

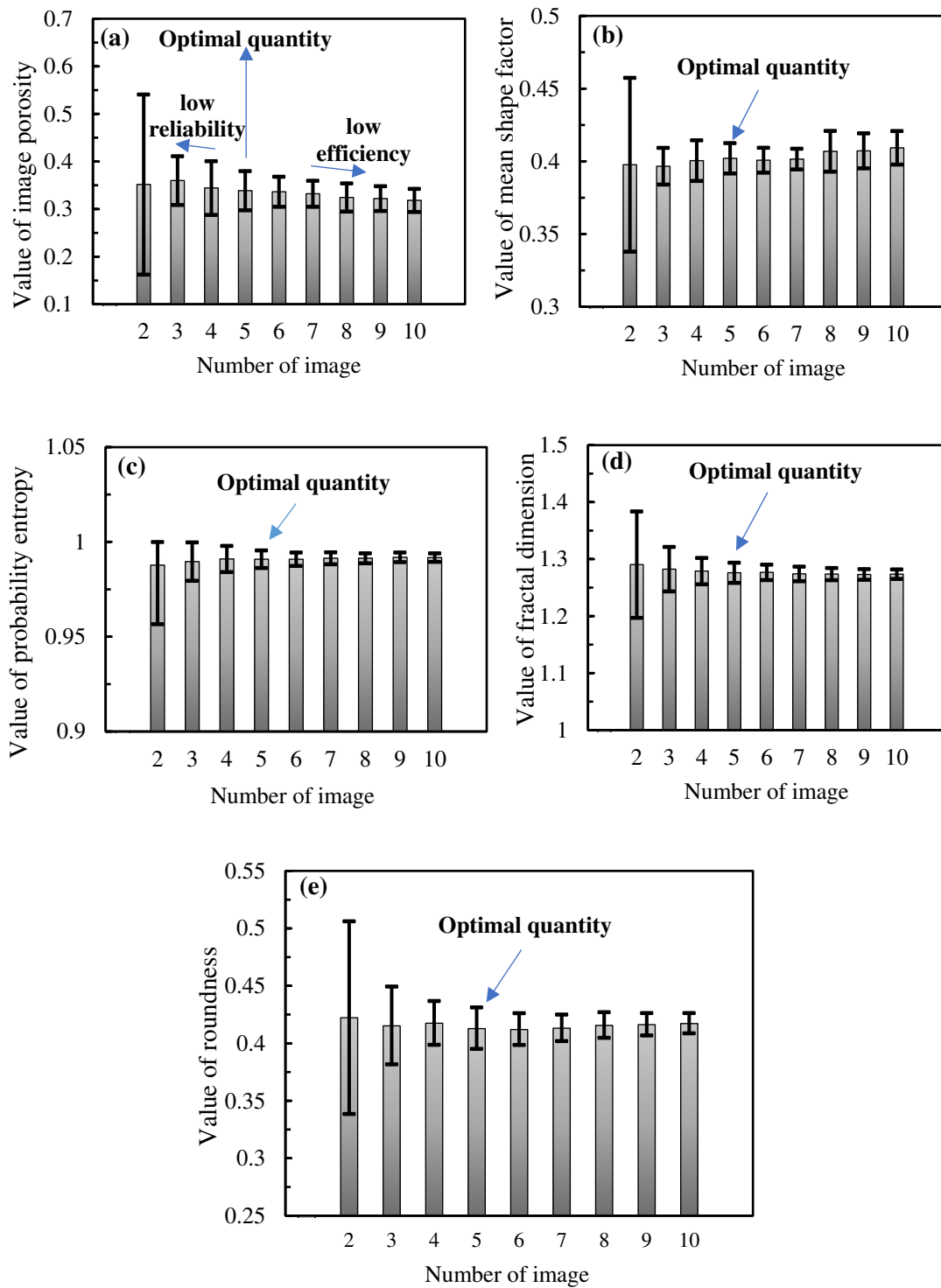


Figure 10 Analysis of optimal image quantity for SEM sample 13#. The height of each bar is the mean value of a certain image quantity, while the short vertical line on top represents the corresponding confident interval. (a) Statistic analysis of image porosity. (b) Mean shape factor. (c) Probability entropy. (d) Fractal dimension. (e) Roundness.

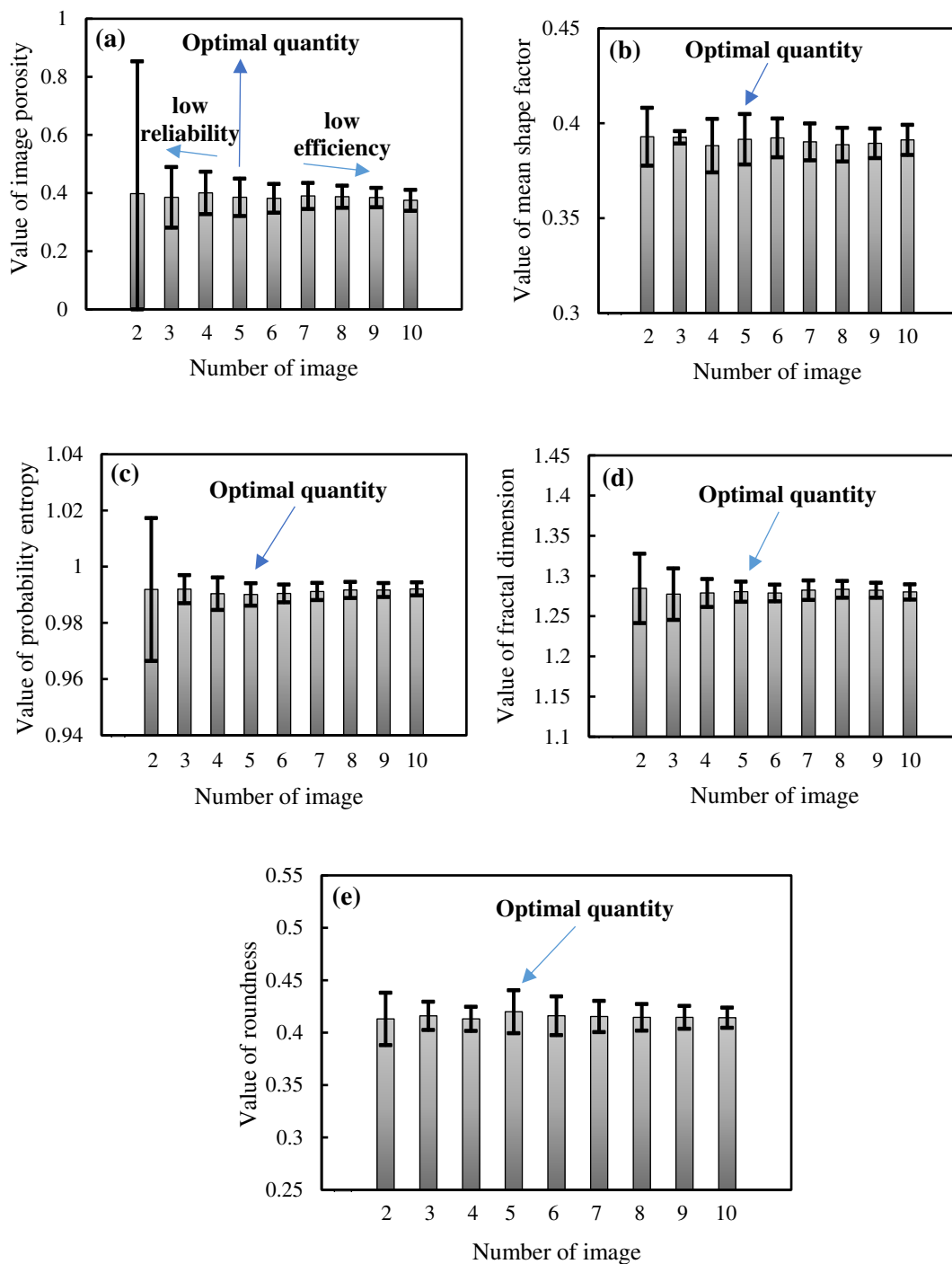


Figure 11 Analysis of optimal image quantity for SEM sample 14#. The height of each bar is the mean value of a certain image quantity, while the short vertical line on the top represents the corresponding confident interval. (a) Statistic analysis of image porosity. (b) Mean shape factor. (c) Probability entropy. (d) Fractal dimension. (e) Roundness.

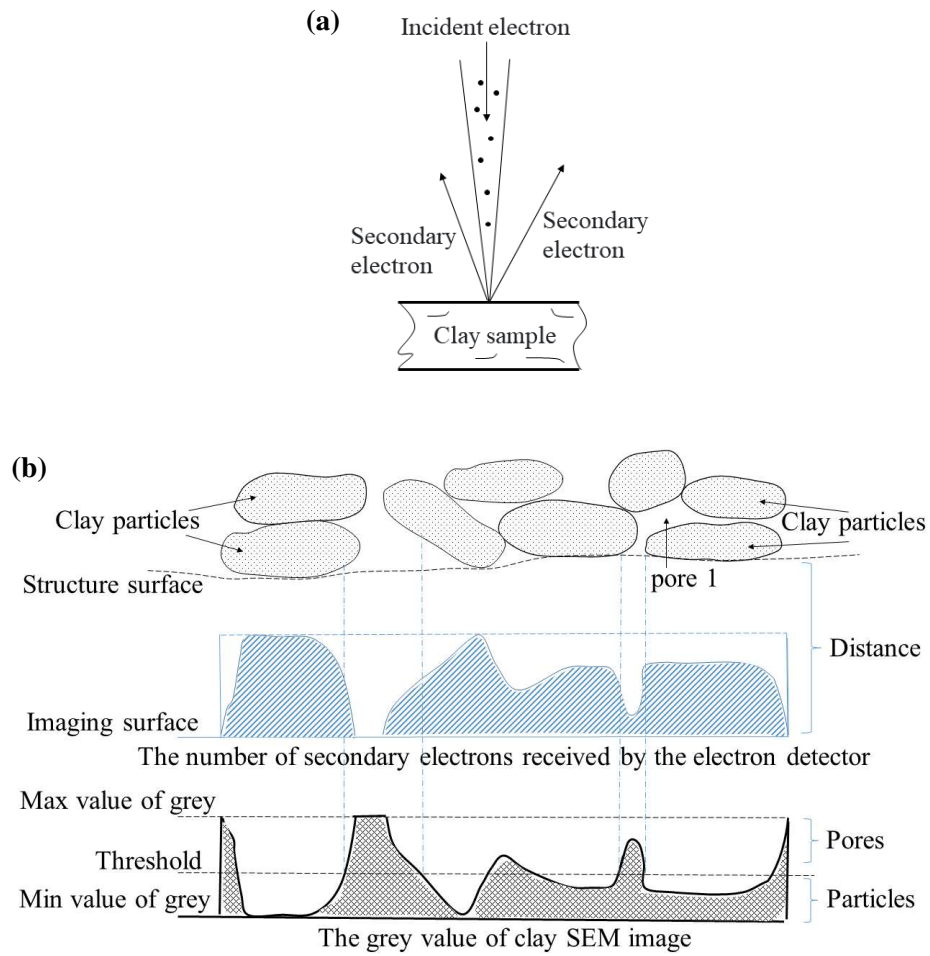


Figure 12 Discussion on 3-D surface model. (a) The imaging principle of SEM. (b)

The spatial features of the structure surface of the clay particles can be reflected by the grey value.

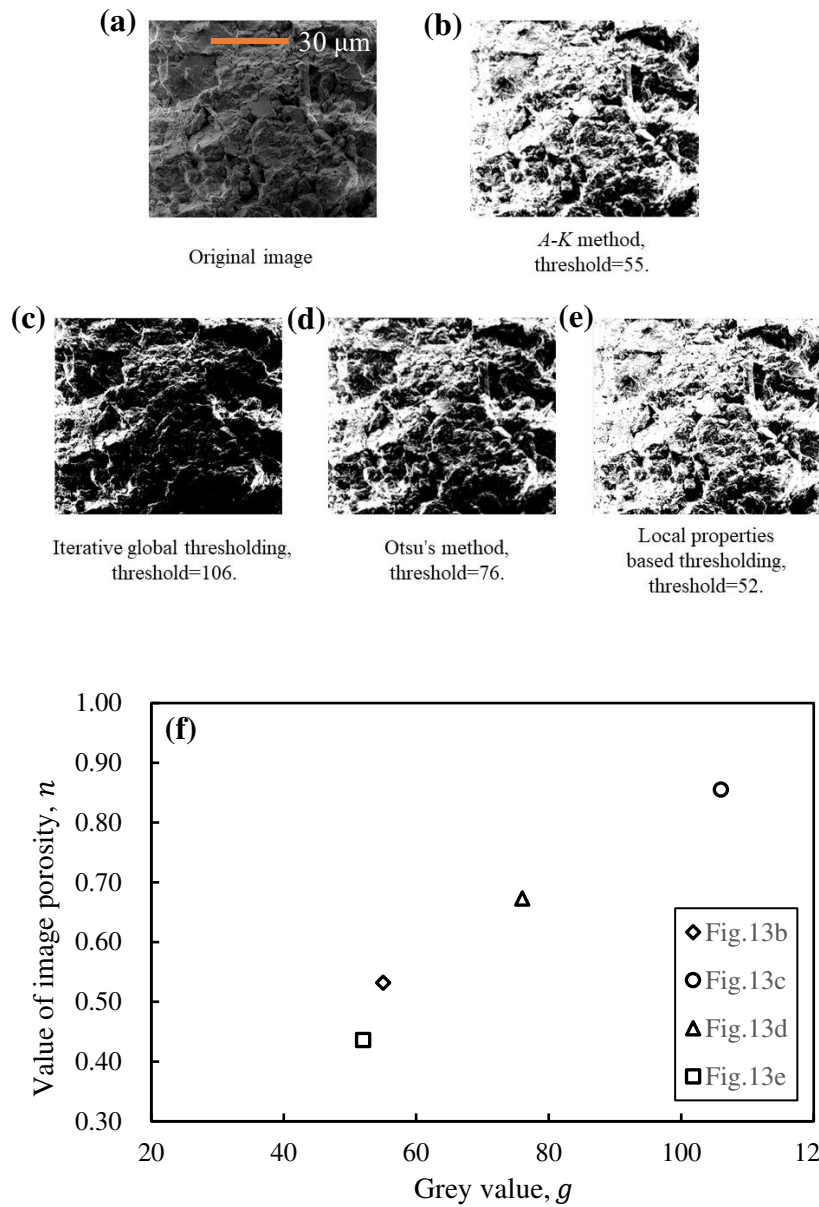


Figure 13 Quantitative comparison of different threshold value determining methods in image processing. (a) Original image. (b-e) The binary image after threshold segmentation with different methods. (f) Threshold and corresponding image porosity.