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Quantum choice models: a flexible new approach for understanding moral decision-making

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1 ABSTRACT

2 Quantum probability, first developed in theoretical physics, has recently been successfully used in
3 cognitive psychology to model data from experiments that previously resisted effective modelling
4 by classical methods. This has led to the development of choice models based on quantum prob-
5 ability, which have greater flexibility than standard models due to the implementation of complex
6 numbers through, for example, complex phases or ‘quantum rotations’. This paper tests whether
7 these new models can also capture choice modification under *implicit* ‘changing perspectives’ in
8 choice contexts with salient moral attributes. We apply these models to two distinctly different
9 case-studies. In the first, respondents have to make choices between route alternatives with vari-
10 able ‘concrete’ and ‘moral’ attributes - [Chorus et al. \(2018\)](#)’s ‘taboo trade-off’ between time-cost
11 and deaths-injuries. The second study investigates how an individual weighs wages and commut-
12 ing times for themselves relative to the wages and commuting times for their partner. Under both
13 scenarios, we find that the flexibility provided by quantum choice models allows them to accu-
14 rately capture and formally explain choices across the differing contexts.

15

16 **Keywords:** Quantum probability; moral choice; travel behaviour

17 1. INTRODUCTION

18 Moral choice scenarios can be summarised as those where the choices or actions a decision-maker
19 takes could negatively impact other individuals. Thus, to the decision-maker, the choice alter-
20 natives may to some extent be categorised as ‘right’ or ‘wrong’, depending on how serious (and
21 possibly how likely) the consequences are. As a result, the associated choices can perhaps be more
22 complex as they do not involve straightforward trade-offs between rather concrete attributes of al-
23 ternatives. For example, a decision-maker may not choose the alternative that they would choose
24 based on more attractive concrete features as they believe it to be an overall morally contentious
25 option. Alternatively, a set of options may all have negative features, where different schools of
26 moral thought suggest different actions should be taken (for example, [Awad et al. \(2020\)](#) discuss
27 country-level variations in decision-making in ‘moral machine’ choice tasks).

28 While moral choice behaviour has received much attention in economics and psychology, it is
29 rarely considered in the choice modelling literature (see [Chorus 2015](#) for a detailed discussion).
30 This is despite the fact that many typical experiments conducted to understand or interpret an indi-
31 vidual’s preferences in moral choice scenarios use paradigms such as variations of the well-known
32 trolley problem (where a ‘runaway trolley’ has two possible paths, both of which will result in the
33 death of some individual(s), and the decision-maker must choose who to save), for which a precise
34 understanding of the trade-offs that are being made could be obtained using choice models. This
35 is perhaps due to the fact that an individual’s moral preferences are difficult to investigate outside
36 of the laboratory, with typical experimental methods for examining moral choice scenarios often
37 suffering from low external validity ([Bauman et al., 2014](#)). However, more recently, moral choice
38 behaviour has become more prominent in the travel behaviour modelling community through, for
39 example, the reinvention of the trolley problem as a self-driving car problem ([Awad et al., 2018](#)).
40 Thus far, there has not been much consideration given to the types of choice models used for the
41 modelling of such scenarios, despite the wide range of theoretical explanations for moral behaviour
42 that have been proposed ([Chorus, 2015](#)). However, some steps towards the development of choice
43 models specifically for moral choice contexts have been made ([Chorus et al., 2018](#)).

44 In this paper, we specifically look at models based on quantum probability theory. These have

45 not yet been applied to moral choice scenarios, despite the adoption of such methods ‘allowing
46 for a re-examination of the challenge of formalising psychological concepts of conflict, ambiguity,
47 and uncertainty’ (Wang et al., 2013). Quantum probability theory has recently made a significant
48 impact in cognitive psychology (Bruza et al., 2015). This impact is in part due to the underlying
49 logic of quantum probability theory which revealed a fundamental lack of distributivity of
50 propositions concerning non-compatible features of an observed system (Birkhoff and Von Neumann,
51 1936). This key difference between classical and quantum logic reveals that under quantum
52 theory, the law of probability following the distributivity of ‘and’ and ‘or’ of propositions –
53 $A \wedge (B \vee C) = (A \wedge B) \vee (A \wedge C)$ – may fail to hold (for a detailed example, see Hancock et al. 2020).
54 Another essential difference follows from the description of a system by using state vectors with
55 complex-valued components which entail the occurrence of interference effects when such states
56 are superposed, famously leading to the paradoxical state of Schrödinger’s cat being both dead and
57 alive at the same time in a historical thought experiment devised to point out the consequences
58 of the entanglement of the quantum system and its observer (Schrödinger, 1935). In effect, the
59 measurement of a property of a system occurs differently, namely by applying projection operators
60 on the state vector of a system which inherently ‘changes the system by making an observation’ -
61 as opposed to simply reading of the value of a pre-existent property of the system. Crucially, these
62 features mean that the adoption of quantum probability theory allows for a powerful and elegant
63 framework for modelling and understanding many ‘paradoxical’ findings which become ‘intuitive’
64 (Wang et al., 2013), such as probability judgement errors (Busemeyer et al., 2011), question ordering
65 effects (Trueblood and Busemeyer, 2011) and violations of the ‘sure thing principle’ (Pothos
66 and Busemeyer, 2009; Broekaert et al., 2020). A classic example of a probability judgement error
67 is given by Tversky and Kahneman (1983), who found that participants, after reading ‘Linda was
68 a philosophy major. She is bright and concerned with issues of discrimination and social justice’,
69 were more likely to agree with the statement ‘Linda is a feminist bank teller’ than the statement
70 ‘Linda is a bank teller’. This subjective assessment clearly contradicts logical set theory in which
71 the category “feminist bank teller” is a subset of the category “bank teller”, and hence on proba-
72 bilistic grounds of set membership, this should lead to a lower association of Linda with the former
73 category.

74 With, for example, ordering effects also frequently observed in choice modelling applications,
75 it is unsurprising that quantum models have also since made the transition into choice modelling
76 (Lipovetsky, 2018). Furthermore, quantum models can be used to accurately capture the ‘change of
77 decision context and mental state’ when moving between choices made under revealed preference
78 and stated preference settings (Yu and Jayakrishnan, 2018). Additionally, it has been demonstrated
79 that quantum probability theory can be implemented into choice models to accurately understand
80 route choice problems as well as best-worst choice behaviour in the context of alternative routes
81 (Hancock et al., 2020). Thus there appears to be ample scope for further developments of quantum
82 choice models, with our previous development of the notion of a ‘quantum rotation’ within a
83 choice model providing useful transitions across choice contexts. The aim of this paper is to build
84 on work presented in Hancock et al. (2020), which focussed solely on typical travel behaviour
85 data, by testing these models on more complex choice scenarios. We specifically test whether
86 these rotations and other quantum choice model features can equivalently be used to accurately
87 capture changes in choice context within moral choice scenarios.¹

¹A prior version of a formal model using rotations in choice scenarios with moral trade-off was developed by

88 We apply the models to two very different datasets. The first allows us to test whether quantum
89 choice models can be used to capture the impact of the presence of a ‘taboo trade-off’ (Chorus
90 et al., 2018) involving trade-offs between ‘moral’ and ‘concrete’ features.² The moral attributes of
91 the route alternatives appeal to the personal sense of *right* versus *wrong* grounded in the decision-
92 maker’s socio-cultural and philosophical or religious association - like the personal answerability
93 or blame for opting for a route alternative with a higher expected number of deaths or severely
94 injured travellers. The concrete attributes on the other hand call for a more pragmatic material
95 utility which a priori does not ponder rightness or wrongness of the choice - like for instance the
96 additional time on a route alternative. It goes without saying that these categories may well be per-
97 ceived as intertwined; a faster route alternative with implicit detrimental environmental effects can
98 appeal to the decision-maker’s ethical principles. Vice versa, a utilitarian based ethical approach
99 held by a decision-maker could result in equating moral attributes with pragmatic features of the
100 alternative.

101 The second dataset tests whether quantum choice models can be used to capture differences
102 between how an individual weighs wage and commuting times for themselves relative to consid-
103 ering the wages and commuting times for both their partner and themselves, developed by Swärdh
104 and Algers (2009), with descriptions also in Beck and Hess (2016). An aspect of morality is again
105 appealed to in this experimental paradigm. The consideration of the partner’s situation may appeal
106 to the decision-maker’s empathy or selfishness with respect to the partner, or, a particular balanced
107 choice may result from an evaluation of the pragmatic joint utility for the couple.

108 The remainder of this paper is organised as follows. Section 2 gives an introduction to quantum
109 probability, discusses how it has provided useful explanations for choices with a moral component
110 in cognitive psychology, and shows how we mathematically build our quantum choice models.
111 Section 3 shows the empirical application to our two moral choice datasets. We finish with some
112 conclusions and directions for future research.

113 2. THE QUANTUM PROBABILITY APPROACH

114 In this section, we first give a basic overview of the quantum probability approach; we refer the
115 reader to Khrennikov (2010); Busemeyer and Bruza (2012); Broekaert et al. (2016); Yearsley and
116 Busemeyer (2016); Yearsley (2017) for a more extensive coverage on the application of quantum
117 theory in decision-making. Next, we in turn look at how quantum probability can be used to capture
118 a change in perspective, and how it has been used to explain a number of ‘paradoxical’ phenomena
119 in cognitive psychology, some of which have moral components. Finally, we demonstrate how we
120 mathematically operationalise the quantum probability approach into the models utilised in this
121 paper.

122 2.1. Basic features of the approach

123 Under quantum models, each choice scenario is represented in a n -dimensional ‘Hilbert’ space,
124 which is spanned by a set of n orthonormal (possibly complex) vectors, with one vector for each
125 possible choice alternative. In essence, the cognitive process corresponding to the experimen-
126 tal paradigm is implemented by performing operations on specifically constructed vectors of the

Hancock (2019).

²The authors Chorus et al. (2018) have coined the types of attributes as ‘sacred’ and ‘secular’. We have opted to denominate the attributes by more culturally neutral terms in comparison to Chorus et al. (2018).

127 Hilbert space.³ This vector represents the decision-maker’s behavioural belief-action state at a
 128 given moment in the experimental paradigm, in particular for the present datasets, expressing their
 129 preferences.

130 A basic example of this is given in Fig. (1), where we adapt the Hilbert space to the paradigm
 131 corresponding to the first dataset (Chorus et al., 2018). A similar example is described in more
 132 detail in the introduction of Hancock et al. (2020), where an individual is choosing whether to
 133 commute to work by car or by train.

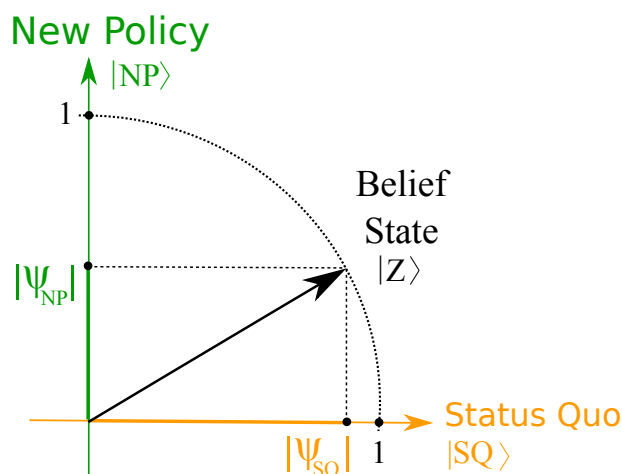


FIGURE 1 : A schematic representation of the belief state in the geometric quantum-like model for a binary choice between the ‘New Policy’ or the ‘Status Quo’. The belief state $|Z\rangle$ is a superposition of $|NP\rangle$ and $|SQ\rangle$, meaning that the decision-maker has a propensity to choose both the ‘New Policy’ or their ‘Status Quo’. The numerical probabilities of choosing each alternative are obtained from the complex-valued amplitudes of the projections on the respective axes by squaring the moduli $|\psi_{NP}|$ and $|\psi_{SQ}|$.

134 The preference of an individual decision-maker is represented by a (normalised) belief state
 135 vector which is denoted $|Z\rangle$. The action of making a choice is represented by a projection from
 136 the belief state vector onto the vector representing the chosen alternative, i.e. $|NP\rangle$ for the ‘New
 137 Policy’ or $|SQ\rangle$ for the ‘Status Quo’, in Fig. (1).

138 The projection operations are represented by the dotted lines connecting the belief state (on the
 139 arc) to the axes orthogonally spanned by the two choice alternatives, resulting in the two respective
 140 component moduli $|\psi_{NP}|$ and $|\psi_{SQ}|$. To be used as probabilities, the outputs of these projection
 141 processes need to fulfil two properties; a) they need to all be between 0 and 1, and b) they need
 142 to sum to 1. With the quantum approach, this is achieved by using the *squared* ‘length’ of each
 143 projection as the probability for that alternative. Since the state vector is normalised - i.e. of unit
 144 ‘length’ (or modulus) - these two requirements are fulfilled. One can easily verify that with the
 145 two choices represented by a set of orthonormal vectors, the set of squared ‘length’ projections
 146 will sum to one according to Pythagoras’ Theorem (see Fig. 1).

³A Hilbert space is a regular real, or complex-valued, vector space with an inner product and a completeness property that assures converging limits will exist within the space itself.

147 **2.2. A change in choice perspective**

148 In quantum mechanics, two observables of a system are considered *incompatible* if a measurement
149 of one of them influences the outcome of the other. Conversely, two observables are compatible
150 if they do not influence each other.⁴ Thus in the context of our model, if two choices have no
151 relation to each other and their respective answers do not impact each other, they are compatible.
152 In such cases, the *same* belief state vector - albeit with *different* components dedicated to each of
153 the choice tasks - can invariably be used for the two tasks. However, if we had two tasks which
154 were related to each other by simple variation of some concrete attributes and hence require the
155 *same* components of the belief state vector - then the belief state needs to be updated as well.
156 For instance, in repeated choice tasks with only modified attributes of the alternatives, the belief
157 state of the decision-maker is updated in line with the cognitive process associated with each new
158 choice. Mathematically, the adaptation of the belief state to the different values of the attributes
159 is determined by immediate implementation⁵ in the vector components, Eq. (3), and effectively
160 corresponds to a rotation between the two state vectors (Hancock et al., 2020).

161 However, ‘incompatible’ choice tasks at a deeper level - when a pair of choices impact each
162 other on different components of the belief state - require different belief vectors for each of the
163 tasks. To give a more detailed example of such task ‘incompatibility’, consider a scenario where
164 the decision-maker has to choose their *favourite* and *least favourite* alternative from a set. The
165 sensitivities for what constitutes the best alternative may not be equivalent to what constitutes the
166 worst. This can be represented in quantum models through different vectors for an alternative being
167 the best compared to the same alternative being the worst. To capture the change of perspective
168 (considering the best, to considering the worst), a ‘quantum rotation’ is required, which maps
169 the belief state vector representing the choice of alternatives as being the best, to the belief state
170 vector representing the choice of alternatives as being the worst - and where the projection on
171 the respective axes remain with their interpretation of providing the amplitudes for the respective
172 alternatives. One can equivalently describe this rotation from a passive perspective in which the
173 belief state remains invariant but the basis is rotated in the opposite direction. Hancock et al. (2020)
174 have shown that such rotations (in Hilbert space) can capture the difference in the representation
175 (value) of an alternative when evaluated as best compared to when evaluated as worst. In this paper,
176 we use the same concept of a quantum rotation to capture changes of perspective in moral choice
177 scenarios. We also introduce a supplementary method based on inserting complex phases at the
178 level of attribute value functions in the belief state vectors to implement an alternative perspective
179 operation. We thus assume that choices under moral contexts involve more of a dilemma within
180 the deliberation process, with these model extensions capturing this additional process.

181 In a given choice context, we assume that an individual would evaluate the scenario differently
182 if they were first asked explicitly about the ‘ethical answerability’ of their choice. The presence of a
183 salient moral component may lead the decision-maker to a similar implicit intermediate assessment
184 and result in the decision-maker considering their choice from a different perspective. In the event
185 of such an intermediate assessment of the moral attributes - from an effective change of perspective

⁴In case of incompatibility, a Heisenberg uncertainty relation can be derived which states that the product of the standard deviations of both observables should always be larger or equal to half the expectation value of their commutator. Compatible observables will hence be represented by commuting operators, see e.g. Griffiths (1994) section 3.4.

⁵Note that at this point, in stated preference settings, we make the assumption that previous choices do not impact the current choice.

186 on the choice - the choice proportions for the alternatives will have changed depending on the
 187 acceptance or dismissal of the moral components (see Fig. 2).

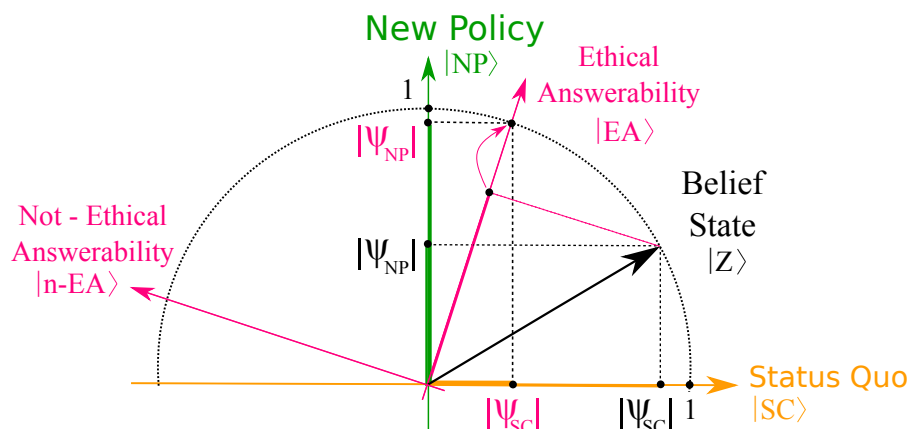


FIGURE 2 : Schematic representation of making explicit consecutive binary choices under quantum probability theory in the geometric quantum-like model; first the ‘Ethical Answerability’ or ‘Not - Ethical Answerability’ question, followed by ‘New Policy’ or ‘Status Quo’ question. In this particular illustration, the change of the belief state is shown following a *positive* outcome for the ‘Ethical Answerability’ question. While the initial belief state $|Z\rangle$ only had some latent tendency for responding ‘Ethical Answerability’, after the positive outcome, the updated belief state coincides with the ethical answerability belief state $|EA\rangle$ (the curved pink arrow shows the renormalisation of the belief state after the collapse of $|Z\rangle$ onto $|EA\rangle$). Note that in this particular case, the intermediate question results in an increase of the belief support for the choice ‘New Policy’ on a *positive* outcome for ‘Ethical Answerability’ since the amplitude norm $|\psi_{NP}|$, in pink, is larger in our case than the amplitude norm $|\psi_{NP}|$, in black, and the reverse is true for the ‘Status Quo’ scenario. In the present rotation-based model, we make the assumption that the salient moral attribute(s) of the alternatives can elicit an *implicit* questioning that does not entail a collapse of the belief state but leads to a rotation approaching either towards the $|EA\rangle$ or $|n-EA\rangle$ belief state. The rotation induced by implicit questioning thus causes a change of the belief support for both alternatives SQ and NP compared to the initial belief state $|Z\rangle$.

188 Hence in general, under a quantum model, when a decision-maker makes a choice - albeit im-
 189 plicit - this will update their belief state. If, for example, they implicitly decide that a particular
 190 alternative is ethically answerable, their state vector would converge more closely to the ‘Ethical
 191 Answerability’ vector itself. This results in a change in the ‘lengths’ of projection onto the vec-
 192 tors representing the choice of the New Policy or the Status Quo alternative. We follow [Chorus](#)
 193 [et al. \(2018\)](#) by defining a new policy as involving a ‘*taboo trade-off*’ if a decision-maker could
 194 choose to decrease tax or travel time (a concrete attribute) at the cost of increasing the number
 195 of injuries or deaths (a moral attribute). Thus, in this example, under choice tasks that feature
 196 taboo trade-offs, the decision-maker is more likely to choose the new policy if they first decide
 197 that it is ethically answerable, and is less likely to choose it otherwise. Both tendencies are present
 198 in the decision-maker’s belief state, hence the implemented rotation for the decision-maker’s im-
 199 plicit change of perspective results effectively from a weighted combination of the two possible
 200 positions. The result of this is that quantum models can capture a change in perspective through

201 a quantum rotation, which can be mathematically represented simply by estimating the impact a
202 change of basis (passive) - or change of the belief state (active) - has on the ‘lengths’ of projec-
203 tions (Sections 3.1.3, 3.2.3). Besides implementing the change of perspective through a quantum
204 rotation of the belief state vector, we also implement such a change of projection ‘lengths’ by the
205 insertion of a complex phase on the attribute values in the belief states, (Sections 3.1.4, 3.2.4). In
206 the latter case, the change of projection ‘length’ results from a constructive or destructive inter-
207 ference between the complex summands within each belief state component itself. This complex
208 phase method is similar to the more encompassing quantum rotation method in its effect of sum-
209 ming complex components but differs in that this interference occurs at the more basal level of
210 each attribute itself. Since specific complex phasing can augment the effect of moral attributes in
211 the moral choice scenarios, this approach implements a perspective operation by a more detailed
212 process than the encompassing effect of a quantum rotation.

213 **2.3. Quantum theory and formal modelling of moral choices in psychology**

214 Whilst choice models with a quantum logic framework have not yet been tested on moral choice
215 data, there have been a number of applications of quantum logic to experiments for paradigms with
216 a moral component (where, for example, decision-makers may make choices that impact a number
217 of other individuals) in cognitive psychology. In particular, quantum probability theory has been
218 used to explain ‘interference’ effects where an additional decision task impacts the probability of
219 a subsequent decision for an action. For example, [Busemeyer et al. \(2009\)](#) tested the impact of ad-
220 ditionally asking decision-makers to categorise a digitally modified face - according to pre-learned
221 ad-hoc criteria - as ‘good’ or ‘bad’, before choosing how to respond by either a ‘withdraw’ or
222 ‘attack’ action, and in which a bonus was provided for responding with the action ‘attack’ after
223 categorisation ‘bad’, or the action ‘withdraw’ after the category ‘good’, and a penalty otherwise.
224 Their study found that the quantum approach could be used to accurately capture the difference in
225 action responses with and without the categorisation task. Furthermore, in simulated jury decision-
226 making experiments, where participants read strong or weak defences and prosecutions, quantum
227 probability theory provided a better account of the ordering effects that were observed relative
228 to models based on classical probability ([Trueblood and Busemeyer, 2010](#)). Ordering effects ob-
229 served when participants state opinions about political figures can also be explained by quantum
230 models ([Pothos and Busemeyer, 2013](#)). In the context of a ‘taboo trade-off’, where an individual
231 can sacrifice ‘moral’ features in favour of ‘concrete’ features, a similar interference may take place
232 in that a decision-maker may not wish to appear ‘unethical’ or expose socially undesirable choices.
233 Similarly, an individual may consider their own welfare differently if they are also required to con-
234 sider the welfare of their partner.⁶ For this reason, we use quantum models to test for interference
235 effects in both of the choice datasets considered in this paper.

236 **2.4. Mathematical outline for basic quantum choice models**

237 Whilst the quantum approach provides a convenient structure for capturing phenomena in cognitive
238 psychology, its operationalisation into a choice model is less simple. The key component (as
239 discussed in detail by [Hancock et al. 2020](#)) is that a decision-maker has some ‘belief state’ $|Z\rangle$

⁶A recent theoretical model by [Yilmaz \(2019\)](#) proposes unitary transformations of the decision-maker’s belief state based on first-person perspectives on imagined belief states of third-person agents to produce an effective ethical choice outcome. In contrast, our model implements the decision-maker’s implicit intermediate belief state rotation to potentially consider their choice from their ethically concerned perspective, or not.

240 regarding their preferences over J alternatives presented in the experimental paradigm. When a
 241 decision-maker makes a choice, their state goes from ‘indefinite’ to ‘definite’, by projecting their
 242 belief state onto the vector representing the chosen alternative, where we further assume that the
 243 presented alternatives are mutually exclusive and exhaust all choice possibilities. This means that
 244 the choice probability, $Pr[Alt_j]$, for a specific alternative Alt_j , is given by the modulus square of
 245 the amplitude for that alternative appearing in the decision-maker’s belief state

$$Pr[Alt_j] = |\psi_j|^2, \quad (1)$$

246 where $|Z\rangle$ is a column vector, with $|Z\rangle = (\psi_1 \dots \psi_j \dots \psi_J)^T$. Since the belief state vector is nor-
 247 malised, the probabilities for the alternatives add up to 1:

$$\sum_{j=1}^J |\psi_j|^2 = 1. \quad (2)$$

248 Consequently, we must build quantum choice models by developing methods for defining a belief
 249 state vector based on functions of the attributes of the alternatives. For the applications in this
 250 paper, we consider an approach based on the ‘quantum amplitude model’, as developed in [Hancock
 251 et al. \(2020\)](#). The key feature of the quantum amplitude model (QA) is that the amplitudes of
 252 each alternative are explicitly implemented with the use of some value function. This allows us
 253 to directly estimate the probabilities with which each alternative is chosen. Whilst a number of
 254 different value functions can be used, we focus on the use of regret-like functions ([Chorus, 2010](#))
 255 for the applications in this paper. The amplitude for an alternative i for individual n in choice task
 256 t is thus defined as:

$$\psi_{nti} = \left(\delta_{QA,i} + \sum_{j \neq i} \sum_{k=1}^K \ln(1 + e^{\beta_k(x_{ntik} - x_{ntjk})}) \right) / \sqrt{\mathcal{N}_{nt}}, \quad (3)$$

257 where $j = 1, \dots, J$ is an index across alternatives, $k = 1, \dots, K$ is an index across attributes, $\delta_{QA,i}$
 258 are alternative specific constants, β_k are attribute-specific weights and \mathcal{N} is a normalisation factor.
 259 This factor, which ensures that the probabilities with which each alternative is chosen sum to one,
 260 is obtained from the sum of the squared moduli numerators:

$$\mathcal{N}_{nt} = \sum_i \left| \left(\delta_{QA,i} + \sum_{j \neq i} \sum_{k=1}^K \ln(1 + e^{\beta_k(x_{ntik} - x_{ntjk})}) \right) \right|^2. \quad (4)$$

261 Note that given the probabilities with which the different alternatives are chosen are based on
 262 squaring these amplitudes, the same probabilities will be generated if all amplitudes are multiplied
 263 by the same factor - as opposed to the *addition* of the same term. Thus the number of additive
 264 constants that are identifiable is equal to the number of alternatives. Additionally, the equations
 265 as presented here imply that the amplitudes are in real-valued space, with operations moving the
 266 amplitudes into complex space introduced in the following section. Our approach thus makes
 267 explicit use of complex-valued operations and hence enacts interference effects which cannot be
 268 obtained in the real-valued trigonometric approach of [Lipovetsky \(2018\)](#). Alternative methods for
 269 capturing moral features can still use the above implementations, with for example, the use of
 270 additional constants or separate β -coefficients depending on the choice context.

271 **2.5. Quantum model perspective operations for a change in choice context**

272 We consider two possible extensions (which we label ‘perspective operations’) to the basic quan-
 273 tum choice models described above, with each extension attempting to capture a ‘change of per-
 274 spective’ for the taboo or moral trade-off in a different way.

275 1. A ‘**quantum rotation**’ (models QAR-1 and QAR-2). We follow [Hancock et al. \(2020\)](#) in
 276 using Pauli matrices to implement a rotation operation on the belief state itself. For scenarios
 277 involving two alternatives, this rotation occurs in a 2-dimensional Hilbert space, with the
 278 rotation matrix generated by Pauli matrices;

$$\sigma_x = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \quad \sigma_y = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}, \quad \sigma_z = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}. \quad (5)$$

279 The rotation operator, R , itself - about axis $\mathbf{n} = (n_x, n_y, n_z)$ and over angle ϑ - is then given
 280 by;

$$R = e^{-i\vartheta \mathbf{n} \cdot \boldsymbol{\sigma}}, \quad (6)$$

281 where $\mathbf{n} \cdot \boldsymbol{\sigma}$ gives some combination of the Pauli factors, with the restriction that $|\mathbf{n}| = 1$.

282 For choice scenarios involving three alternatives, as in the second dataset, we apply two
 283 consecutive quantum rotations on different pairs of alternatives. Given the importance of
 284 ordering within quantum models, the choice of pairs and order in which the two rotations
 285 are made will impact the outcome.

286 To apply the rotation, we use the initial belief state, Ψ_0 , which is simply the vector with
 287 amplitudes for each alternative using Eq. (3) - i.e. model QA without additional features.
 288 We then obtain the belief state for the changed perspective, Ψ_f , by applying the rotation
 289 matrix:

$$\Psi_f = R\Psi_0. \quad (7)$$

290 The rotation thus appropriately adjusts the amplitudes for the different alternatives depending
 291 on the impact that the change of perspective has on the choice being made. A matrix R with
 292 zero off-diagonal elements (i.e. if we have $\mathbf{n} \cdot \boldsymbol{\sigma} = \sigma_z$) would result in no change in the
 293 probabilities with which each alternative is chosen. As a contrast, $\vartheta = \pi/2$ and $\mathbf{n} \cdot \boldsymbol{\sigma} = \sigma_y$
 294 results in the probabilities for a pair of alternatives perfectly swapping.

295 We consider two different options for constructing R :

296 (a) A rotation, R_1 , that uses a single estimated parameter. It is based on previous work
 297 where we used a Hamiltonian approach to quantum modelling (see [Hancock et al.](#)
 298 [2020](#)). We implement the rotation with a fixed constant ($\vartheta = \pi/2$) and modulate it
 299 with a single parameter (h) that also weights the Pauli matrices:

$$R_1 = e^{-i\frac{\pi}{2}\sqrt{1+h^2}\mathbf{n} \cdot \boldsymbol{\sigma}}, \quad (8)$$

300 with $\mathbf{n} = \left(0, \frac{h}{\sqrt{1+h^2}}, \frac{1}{\sqrt{1+h^2}}\right)$.

301 (b) A rotation, R_2 , that uses up to three estimated parameters. The angle ϑ is estimated
 302 directly and ω_1 and ω_2 are axis parameters used to weight the Pauli matrices, with
 303 $\mathbf{n} = (\sin(\omega_1), \cos(\omega_1) \cdot \cos(\omega_2), \cos(\omega_1) \cdot \sin(\omega_2))$.

304 2. The introduction of ‘**complex phases**’ (model QAP), such that the amplitudes for the choice
 305 alternatives contain real and imaginary parts. We implement these complex phases in the
 306 QA model by multiplying $\ln(1 + e^{\beta_k(x_{ntik} - x_{ntjk})})$ in Eqs. (3, 4), with $e^{i\varphi_k}$. Note that we could
 307 estimate a different φ_k for each attribute k , or alternatively have a simpler structure such that
 308 a single additional parameter is estimated ($\varphi_k = \varphi, \forall k$).

309 To apply a model with a rotation, we first estimate amplitudes for each alternative based on the
 310 basic QA model. Then, under choice scenarios in which there is a ‘change of perspective’, we apply
 311 either of two implementations of the quantum rotation (QAR-1 and QAR-2). The second feature
 312 of the complex phases is instead implemented directly into the basic QA model. It thus assumes
 313 that moral attributes are ‘treated differently’ to others. If these attributes are very different, then
 314 the estimates for their respective phases, φ_k , will be different, allowing interference interactions.

315 3. EMPIRICAL APPLICATION

316 In this section, we present the results of two case studies. In each case, we first detail the dataset
 317 that is used for testing our quantum choice models. We then apply our quantum model under
 318 basic settings before introducing quantum rotations for specific choice contexts or alternatively
 319 adding complex phases in the specification. We conclude by providing combined models with
 320 both rotations and complex phases.

321 3.1. Quantum modelling for taboo trade-offs

322 3.1.1. Description of data

323 The first dataset we use involves ‘taboo trade-offs’ and comes from [Chorus et al. \(2018\)](#) (and is
 324 thus henceforth labelled the ‘taboo trade-off dataset’). Decision-makers choose between the intro-
 325 duction of a new transport policy or keeping the status quo. To simplify the choice scenarios, each
 326 new policy simply offered an increase or decrease compared to the status quo for four attributes,
 327 with shifts by ± 300 EUR vehicle ownership tax, ± 20 minutes travel time for each car commuter
 328 per day, ± 100 serious injuries in traffic accidents and ± 5 deaths in traffic accidents. This results
 329 in a total of 16 possible new policies, which are offered in turn to each of 99 decision-makers,
 330 resulting in a dataset with a total of 1,584 choices. For consistency, we follow [Chorus et al. \(2018\)](#)
 331 by defining a choice as involving a ‘taboo trade-off’ if a decision-maker could choose a policy that
 332 involves decreasing tax or travel time (a concrete attribute) at the cost of increasing the number
 333 of injuries or deaths (a moral attribute). One could of course argue that a scenario that increases
 334 injuries and reduces time or cost is not a taboo trade-off if deaths are also reduced at the same
 335 time. We also follow [Chorus et al. \(2018\)](#) in including all 16 choice scenarios in our dataset to aid
 336 a direct comparison with their ‘Taboo Trade-off Aversion’ model (TTOA). Two of these scenarios
 337 include dominated alternatives (Scenarios 1 and 5 in Table 3). A summary of the observed share
 338 of choices under the different scenarios is given in Table 1.

339 For all attributes, we observe that the new policy is more likely to be chosen if there is a
 340 decrease in the attribute, as expected. Additionally, we observe that individuals are less likely to
 341 pick the new policy if it falls into the category of a taboo trade-off. The observed shares for each

TABLE 1 : Observed shares for choosing the new policy or the status quo depending on the attribute change

		Chosen alternative	
		New Policy	Status Quo
Tax	Decrease	50.88%	49.12%
	Increase	20.32%	79.68%
Time	Decrease	43.44%	56.56%
	Increase	27.78%	72.22%
Injuries	Decrease	53.28%	46.72%
	Increase	17.92%	82.08%
Deaths	Decrease	47.72%	52.28%
	Increase	23.48%	76.52%
Taboo	Yes	30.08%	69.92%
Trade-Off	No	42.72%	57.28%

342 specific choice scenario are given together with model results in Table 3. This dataset is suitable
 343 for quantum choice modelling as decision-makers may not process the different attributes or the
 344 different choice tasks in the same way. Thus, quantum rotations and complex phases may both
 345 provide a method for capturing these differences.

346 3.1.2. Basic models for the taboo trade-off dataset

347 For the first set of models tested, we do not include either quantum rotations or complex phases in
 348 the specifications, so as to test the basic structure of the quantum models.

349 We test models without any parameters to control for the presence of a taboo trade-off, as well
 350 as models with an additional constant added to represent the presence of a taboo-trade off. We
 351 have a parameter to capture the relative importance of each attributes, and test the quantum model
 352 as specified by Eq. (3). We now look in turn at the amplitudes for the status quo (SQ) and new
 353 policy (NP) options, where we do not show an index for individuals, n , as all participants complete
 354 all 16 choice tasks and there is no variation in the attributes at the individual level:

$$\begin{aligned} \psi_{t,SQ} = & \left(\delta_{SQ} + \delta_{base} + \ln(1 + e^{-\beta_{TT} \cdot \Delta_{t,TT}}) + \ln(1 + e^{-\beta_{Tax} \cdot \Delta_{t,Tax}}) \right. \\ & \left. + \ln(1 + e^{-\beta_{DE} \cdot \Delta_{t,DE}}) + \ln(1 + e^{-\beta_{IN} \cdot \Delta_{t,IN}}) \right) / \mathcal{N}_t, \end{aligned} \quad (9)$$

355 and for the new policy:

$$\begin{aligned} \psi_{t,NP} = & \left(\delta_{Taboo} \cdot z_{t,taboo} + \delta_{base} + \ln(1 + e^{\beta_{TT} \cdot \Delta_{t,TT}}) + \ln(1 + e^{\beta_{Tax} \cdot \Delta_{t,Tax}}) \right. \\ & \left. + \ln(1 + e^{\beta_{DE} \cdot \Delta_{t,DE}}) + \ln(1 + e^{\beta_{IN} \cdot \Delta_{t,IN}}) \right) / \mathcal{N}_t, \end{aligned} \quad (10)$$

356 where t is an index across choice tasks, $t = 1..16$, $\Delta_{t,x} = 1$ if attribute x increases under the new pol-
 357 icy or $\Delta_{t,x} = -1$ if the attribute decreases under the new policy, and where the normalisation factor

358 \mathcal{N}_t satisfies Eq. (4). We include relative importance parameters for the four different attributes,
 359 β_{TT} for travel time, β_{Tax} for travel tax, β_{DE} for number of deaths and β_{IN} for number of injuries.
 360 As all of these attributes are unfavourable - less is better - we expect negative estimates for these
 361 coefficients. This leads to a decrease in the amplitude of the new policy if $\Delta_{t,x} = 1$ (i.e. there is
 362 an increase in the attribute), resulting in a smaller probability. We add a constant, δ_{base} , to both
 363 numerators and a constant, δ_{SQ} , that allows us to statistically test the underlying bias towards the
 364 status quo. As a contrast to random utility models, the additional constant here does not result in
 365 an overspecification, with an increased value for δ_{base} corresponding to less deterministic choices.
 366 Under the basic model that accounts for the presence of a taboo trade off, we additionally estimate
 367 a taboo trade-off constant where appropriate, δ_{Taboo} , which is multiplied by $z_{t,taboo}$, an indicator
 368 that takes a value of one for choice tasks where there is the presence of a taboo trade-off, and a
 369 value of zero otherwise. In our model that does not account for taboo trade-offs, we fix δ_{Taboo} to
 370 a value of zero. Additionally, as there are no attribute levels in this dataset, multiplying all param-
 371 eters by the same constant results in the same likelihood for the quantum amplitude model. We
 372 consequently fix the first β -coefficient to a value of -1 to avoid an overspecification. This will
 373 result in the QA model having the same number of free parameters as the logit model.

374 We compare our quantum models to logit models that are equivalent to those specified by
 375 [Chorus et al. \(2018\)](#). The utility for the two alternatives is defined as:

$$U_{t,SQ} = (\delta_{SQ} - \beta_{TT} \cdot \Delta_{t,TT} - \beta_{Tax} \cdot \Delta_{t,Tax} - \beta_{DE} \cdot \Delta_{t,DE} - \beta_{IN} \cdot \Delta_{t,IN}) + \varepsilon_{t,SQ}, \quad (11)$$

376 and:

$$U_{t,NP} = (\delta_{taboo} \cdot z_{t,taboo} + \beta_{TT} \cdot \Delta_{t,TT} + \beta_{Tax} \cdot \Delta_{t,Tax} + \beta_{DE} \cdot \Delta_{t,DE} + \beta_{IN} \cdot \Delta_{t,IN}) + \varepsilon_{t,NP}, \quad (12)$$

377 where ε is a type I extreme value error. The addition of δ_{taboo} to the utility for the new policy in the
 378 presence of a taboo trade-off gives us the ‘Taboo Trade-off Aversion’ model (TTOA) as specified
 379 by [Chorus et al. \(2018\)](#).

380 The results of our quantum and logit models are given in Table 2, where we first report basic
 381 logit and basic quantum models, before reporting models that include an additional constant for
 382 choices including a taboo trade-off (Logit-t and QA-t, respectively). For all of the model estimation
 383 in this paper, we use R packages maxLik ([Henningsen and Toomet, 2011](#)) and Apollo ([Hess and
 384 Palma, 2019](#)).

385 Without any parameter for a taboo trade-off, the quantum amplitude (QA) model is outper-
 386 formed by the logit model. Notably, the model appears to find very similar relative ratios for the
 387 different β -attribute coefficients as logit. The addition of a taboo parameter (which is significant
 388 in each model) results in a reduction in the estimates for injuries and deaths for both models. It
 389 improves the fit of the QA model slightly more than the logit model, but the logit model still has
 390 the best log-likelihood and adjusted ρ^2 value at this point.⁷ For the basic models, the best overall
 391 BIC value is obtained by a logit model without a taboo parameter.

392 3.1.3. Models with quantum rotations for the taboo trade-off dataset

393 We next turn to models with additional rotations implemented in the presence of a taboo trade-off,
 394 which attempt to capture the ‘change of perspective’, as described in Section 2.5. Thus, if the

⁷Note that ‘Logit-t’ is identical to the ‘Generic Taboo Trade-Off Aversion’ (TTOA) model as described by [Chorus et al. \(2018\)](#).

395 decision-maker can decrease travel time or tax at the cost of increasing the number of fatalities or
396 serious injuries, a rotation is applied.

TABLE 2 : Results of all models applied to the taboo trade-off dataset, together with all parameter estimates, where \circ and \star indicate attribute pairs which have the same phase.

Type		Basic models				Quantum rotations		Models with complex phases					Combined
Specification		Logit	QA	Logit-t	QA-t	QAR-1	QAR-2	QAPh-1	QAPh-2a	QAPh-2b	QAPh-2c	QAPh-3	QAC
Free parameters		5	5	6	6	6	7	6	7	7	7	9	9
Log-likelihood		-721.23	-725.40	-719.47	-722.61	-717.94	-717.77	-719.17	-712.94	-719.16	-718.83	-712.79	-712.35
BIC		1479.29	1487.63	1483.15	1489.43	1480.09	1487.12	1482.54	1477.45	1489.90	1489.24	1491.89	1491.02
B-S test p-value (vs. RRM-t)						0.0402	0.2655	0.2181	0.0008			0.0184	0.0111
Adj. ρ^2		0.3386	0.3348	0.3392	0.3364	0.3406	0.3399	0.3395	0.3443	0.3386	0.3389	0.3426	0.3430
Average probability of choosing NP	No taboo (before rotation)	41.57%	41.22%	42.71%	42.12%	41.86%	42.01%	42.06%	43.07%	42.08%	42.23%	43.04%	42.87%
	Taboo (after rotation)	-	-	-	-	30.69%	30.36%	-	-	-	-	-	30.16%
β_{Tax}	est.	-0.4888	-1.0000	-0.5232	-1.0000	-1.0000	-1.0000	-1.3989	-1.4536	-1.3963	-1.3679	-1.4293	-1.6455
	rob.t-rat.	-10.31	fixed	-10.05	fixed	fixed	fixed	-9.05	-6.88	-9.31	-9.45	-5.22	-5.70
β_{TT}	est.	-0.2598	-0.5271	-0.2834	-0.5675	-0.5225	-0.5304	-0.7442	-0.8368	-0.7476	-0.7792	-0.8517	-0.9638
	rob.t-rat.	-6.54	-5.08	-7.01	-5.83	-5.38	-5.40	-6.56	-5.23	-6.79	-6.59	-5.12	-4.53
β_{IN}	est.	-0.5548	-1.1239	-0.5052	-0.9660	-1.1731	-1.1201	-1.5786	-1.8668	-1.5764	-1.6693	-1.7748	-1.9672
	rob.t-rat.	-10.31	-7.26	-8.99	-6.75	-7.49	-6.84	-8.84	-9.21	-8.90	-7.05	-8.11	-7.74
β_{DE}	est.	-0.3957	-0.7870	-0.3444	-0.6627	-0.8458	-0.7988	-1.1301	-1.4356	-1.1364	-1.1128	-1.5081	-1.5517
	rob.t-rat.	-9.43	-6.95	-7.80	-6.32	-7.15	-6.15	-8.22	-7.93	-7.13	-8.24	-5.22	-6.61
δ_{SQ}	est.	-0.9269	-0.9208	-0.6293	-0.6244	-0.9704	-0.8747	-1.7840	-1.2720	-1.7945	-1.8456	-1.2543	-1.2672
	rob.t-rat.	-8.17	-6.95	-4.12	-4.35	-7.02	-5.10	-6.80	-9.52	-6.28	-6.53	-8.35	-7.90
δ_{base}	est.		-0.2995		-0.5226	-0.7632	-0.8383	0.0000	0.0000	0.0000	0.0000	0.0000	0.0000
	rob.t-rat.		-1.37		-2.65	-4.14	-4.38	fixed	fixed	fixed	fixed	fixed	fixed
δ_{taboo}	est.			-0.4409	-0.3506								
	rob.t-rat.			-2.30	-2.75								
h	est.					-0.2779							
	rob.t-rat.					-6.07							
ω	est.						-1.85						3.0729
	rob.t-rat. (vs $\pi/2$)						-94.29						28.79
ϑ	est.					1.5708	1.7257						2.0577
	rob.t-rat. (vs $\pi/2$)					fixed	0.91						0.43
φ_{Tax}	est.							-0.5644 $^\circ$	-0.9913 $^\circ$	-0.5797 $^\circ$	-0.7790 $^\circ$	-0.9584	-1.1296 $^\circ$
	rob.t-rat.							-6.23	-6.27	-3.23	-4.25	-4.77	-7.56
φ_{TT}	est.							-0.5644 $^\circ$	-0.9913 $^\circ$	-0.5540 \star	-0.4428 \star	-1.0188	-1.1296 $^\circ$
	rob.t-rat.							-6.23	-6.27	-3.60	-3.40	-4.21	-7.56
φ_{IN}	est.							-0.5644 $^\circ$	0.3904 \star	-0.5797 $^\circ$	-0.4428 \star	0.3367	0.4453 \star
	rob.t-rat.							-6.23	2.03	-3.23	-3.40	1.77	2.56
φ_{DE}	est.							-0.5644 $^\circ$	0.3904 \star	-0.5540 \star	-0.7790 $^\circ$	0.4794	0.4453 \star
	rob.t-rat.							-6.23	2.03	-3.60	-4.25	2.23	2.56
Rotation matrix	R[1,1]					-0.15-0.95i	-0.15+0.95i						-0.47-0.88i
	R[1,2]					0.27+0.00i	0.27+0.00i						-0.06+0.00i
	R[2,1]					-0.27+0.00i	-0.27+0.00i						0.06+0.00i
	R[2,2]					-0.15+0.95i	-0.15-0.95i						-0.47+0.88i

397 The models in this section are based on those in Section 3.1.2, with the amplitudes being
 398 estimated equivalently using Eqs. (9) and (10). However, instead of adding a constant to capture
 399 the presence of a taboo trade-off, an additional rotation is applied to the estimated amplitudes
 400 using Eq. (7). We test two different rotations, with each based on the Pauli matrices, as described
 401 in Section 2.5.

- 402 1. We first use a rotation matrix, R_1 , with one free parameter, h , for weighting the Pauli matrices
 403 $n_y = \frac{h}{\sqrt{1+h^2}}$, $n_z = \frac{1}{\sqrt{1+h^2}}$ and set the rotation angle $\vartheta = \frac{\pi}{2} \cdot \sqrt{1+h^2}$. Notice that an estimate
 404 of $h = 0$ would indicate no change in probability. Positive estimates indicate a shift towards
 405 alternative 1, whereas negative estimates indicate a shift towards alternative 2.
- 406 2. We next use a rotation matrix, R_2 , based on our second method using trigonometric functions
 407 to define the weights for $|\mathbf{n}|$. We find that fixing $n_x = 0$ results in no loss of model fit, leaving
 408 us with two free rotation parameters: one for the angle, ϑ , and another ω , where we set
 409 $n_y = \cos(\omega)$ and $n_z = \sin(\omega)$ (which guarantees $|\mathbf{n}| = 1$).

410 The results of models with quantum rotations are again given in Table 2. This table also reports
 411 p-values from Ben-Akiva and Swait tests (Ben-Akiva and Swait, 1986) for non-nested models,
 412 assessing whether the quantum models have a statistically better fit than the TTOA (Logit-t) model.
 413 This table further reports the average probability of choosing the new policy (NP) before and after
 414 the quantum rotation is applied to a choice scenario which contains a taboo trade-off (the observed
 415 choice proportions appear in Table 1).

416 For model QAR-1, which has the quantum rotation implemented, we see a significant improve-
 417 ment in log-likelihood from the addition of 1 parameter. This quantum model now has a better BIC
 418 (1,483.15) than the TTOA model (1,480.09) and is statistically better at the 5% level, with a p-value
 419 of 0.040 from the Ben-Akiva and Swait test. The addition of a second free parameter in the model
 420 (QAR-2) does not result in a significant improvement in the log-likelihood compared to the QAR-1
 421 model.

422 In line with the results of Chorus et al. (2018) and Table 1, we observe that across all models,
 423 the presence of a taboo trade-off results in the decision-maker being less likely to choose the
 424 New Policy alternative. As the number of model parameters increases, the average probabilities
 425 under the model become increasingly closer to matching the observed share of new policy choices
 426 (30.08% when there is a taboo trade-off, 42.72% when there is not, see Table 1). For QAR-2, we
 427 observe that the rotation, on average, reduces the probability of choosing the new policy. Under
 428 QAR-1, the opposite is true. Whilst this result may appear counterintuitive, we observe a greater
 429 estimate for β_{DE} (see Table 2) in QAR-1 in comparison to QA, demonstrating that the additional
 430 flexibility of including a rotation allows for more extreme estimates to help capture choices in
 431 general. We will return to the impact of quantum rotations on the probabilities of choosing the
 432 alternatives in more detail later (see Section 3.1.5).

433 3.1.4. Models with complex phases for the taboo trade-off dataset

434 An alternative mechanism for capturing different ‘processes’ with a quantum choice model is the
 435 implementation of complex phases, as described in Section 2.5. As with models implementing
 436 quantum rotations, we have a number of options for how many free parameters to use in the speci-
 437 fications for the quantum choice models. We consider the following three possibilities:

- 438 1. A single complex phase, φ , for all of the attributes, such that all $\ln(1 + e^{\beta_x \Delta_x})$ are replaced
 439 with $e^{-i\varphi} \cdot \ln(1 + e^{\beta_x \Delta_x})$ in Eqs. (9) and (10). This implementation of phases tests whether
 440 the introduction of complex phases improves the model performance in general.
- 441 2. Two complex phases, φ_1 and φ_2 , each respectively applied to two attributes. This gives us
 442 three distinct configurations. Our focus of interest is on the configuration with one phase
 443 applied to the two moral attributes and the other phase applied to the two concrete attributes.
 444 If this model is significantly better than the other configurations, it would suggest that the
 445 moral and concrete attributes are indeed ‘different’ and can be categorised as such.
- 446 3. Four complex phases with four free parameters, $\{\varphi_1, \varphi_2, \varphi_3, \varphi_4\}$, with a different phase for
 447 each attribute. This configuration allows us to test the performance of the introduction of
 448 relative complex phases overall.

449 The results of models with complex phases are given in Table 2. As with quantum rotations, we
 450 again observe that there is a significant improvement obtained by including complex phases. The
 451 first model offers a good improvement over the base QA model, but is not statistically better than
 452 the TTOA model. Further additional free parameters result in improvements in model fit. As these
 453 parameters are significantly different from zero (if $\varphi = 0$, then we have $e^{i0} = 1$, which corresponds
 454 to real-only amplitudes), we have evidence to reject models without complex phases in favour of
 455 models with complex phases. Note that the introduction of complex phases into the specification
 456 of the amplitudes (Eq. 3) means that we no longer have an overspecification by not fixing one
 457 of the β -coefficients. This is a direct result of having real-valued constants in the amplitudes.
 458 However, we still have five base parameters as the estimate for δ_{base} becomes insignificant, and is
 459 thus fixed to a value of zero. Crucially, the model results suggest that concrete and moral attributes
 460 are treated ‘differently’ in the cognitive choice process, as a substantial gain is found through the
 461 use of separate phases for the concrete and moral attributes, but not for other combinations of uses
 462 of two complex phases. Furthermore, we obtain insignificantly different estimates for the tax and
 463 time phases and the deaths and injuries phases when each parameter has a separate phase (model
 464 QAPh-3). This suggests that the concrete attributes are treated ‘equivalently’ in the cognitive
 465 choice process and similarly so for the moral attributes. In comparison to models with a quantum
 466 rotation, the models with complex phases record better BIC values, with the best adjusted ρ^2 value
 467 of 0.3443 for a model with complex phases compared to 0.3406 for a model with a rotation. This
 468 implies that the moral aspect in the choice tasks is better captured by a perspective operation that
 469 implements separate complex phases for moral and concrete attributes, as opposed to the inclusion
 470 of a rotation for particular choice tasks.

471 3.1.5. Combined model for the taboo trade-off dataset

472 For our final model, we test the use of a model that incorporates both a quantum rotation and
 473 complex phases simultaneously. Our final model for the taboo trade-off dataset is based on the
 474 best performing model thus far (QAPh-2a) combined with the use of a rotation based on Pauli
 475 matrices. It thus has two complex phase parameters (one for concrete attributes, and one for moral
 476 attributes), as well as two rotation parameters. This results in the model having an additional four
 477 parameters to capture the moral components in the choice tasks, on top of the five parameters of
 478 the basic QA model.

479 The results of the combined model (QAC) are shown in Table 2. For this model, we observe
480 significant estimates for the parameters for the complex phases, where these are not significantly
481 different from the estimates for these parameters under a model without additional rotation param-
482 eters (QAPh-2a). The combined model does not offer a significant improvement over the version
483 with complex phases, with the estimates for the rotation parameter ϑ not being significantly dif-
484 ferent from $\pi/2$, indicating that the rotation has minimal impact. This implies that for this dataset,
485 complex phases and additional rotations are approximately equivalent.

486 However, there is evidence that there is still an effect by including the rotation, through con-
487 sideration of the results in Table 3. This table gives the probability of supporting the new policy
488 under each of the different choice scenarios before and after the quantum rotation is applied. Cru-
489 cially, our final model has smaller mean absolute deviations from the true share of support than the
490 TTOA model (which is unsurprising given that this model has more free parameters and records
491 a statistically significant improvement in the model fit). This is only the case for the ‘taboo tasks’
492 after the implementation of the rotation, suggesting that the combined model still benefits from the
493 inclusion of the rotations. Note that a rotation is not like an additive constant, which would always
494 result in a bias towards one alternative. Instead, the combination of real and imaginary numbers
495 (the interference effect) results in a shift that may swing the probabilities in either direction, which
496 is hence unlikely to result in a direct bias towards one alternative. In this case, the rotation almost
497 always reduces the probability of choosing the new alternative. This is in line with our expecta-
498 tions: the presence of a taboo trade-off reduces the likelihood of choosing the new policy.

499 **3.2. Quantum modelling for moral trade-offs involving a couple’s respective commutes**

500 *3.2.1. Description of data*

501 The second dataset we test involves decision-makers completing two distinct sets of choice tasks
502 based on an individual’s willingness to accept longer commutes for better salaries (see [Beck and](#)
503 [Hess, 2016](#), for a detailed description of the survey). The first set of tasks involved trade-offs
504 between the individual’s current travel time and salary or an increased salary (of 500 or 1000 SEK
505 in net wage per month) at a cost of an increase in one-way travel time (of either 10 or 25 minutes).
506 The second set additionally included attributes for increased travel time and salaries for the partner
507 of the decision-maker (under the assumption that both the decision-maker and their partner both
508 commute to work), meaning that the decision-maker has to make choices about who to prioritise
509 (the dataset is thus henceforth referred to as the ‘couple commuter dataset’). All choice tasks
510 included a status quo alternative, a new location and an ‘I am indifferent’ option. A sample of
511 1,179 households (with both partners in each household, resulting in 2,358 individuals) completed
512 4 tasks for the first set involving only attributes affecting themselves, and 4 or 5 tasks for the
513 second set with attributes impacting both members of the household. This resulted in a total of
514 20,041 choice observations.

515 While the first set of choice tasks involves typical time-cost trade-offs that can potentially be
516 captured well with traditional choice models, the latter involves a more complex decision context
517 without any ‘crisp’ trade-off element in that there may not be a clear ethical protocol for how to
518 make the decision. This dataset thus provides another test for our quantum model features that
519 capture changes in choice context. The observed choice shares for the alternatives are given in
520 Table 4, where we see that a decision-maker is more likely to pick the status quo (SQ) over the
521 new location (NL) if the choice task also includes attributes concerning their partner.

522 At the outset, it should already be noted that the presence of an ‘indifference’ option in a SC

TABLE 3 : Observed and theoretical choice probabilities in the taboo trade-off dataset. The ‘taboo trade-off’ occurs if a decision-maker chooses to decrease tax or travel time at the cost of increasing the number of injuries or deaths. The impact of the quantum rotations is rendered explicit; ‘Before’ is the probability of choosing the new policy without applying a quantum rotation, ‘After’ is the probability following the application of the quantum rotation. TTOA gives theoretical probabilities from the ‘Generic Taboo Trade-Off Aversion’ model (Chorus et al., 2018).

Scenario	Attributes				Taboo Trade-Off?	Share of support for New Policy			
	Tax	Time	Injuries	Deaths		Observed	TTOA (Logit-t)	QAC	
							before	after	
1	-	-	-	-	No	98.0%	93.6%	97.5%	
2	-	-	-	+	Yes	68.7%	70.4%	67.6%	65.3%
3	-	-	+	+	Yes	29.3%	23.9%	32.6%	27.3%
4	-	+	+	+	Yes	11.1%	9.2%	16.1%	12.2%
5	+	+	+	+	No	2.0%	1.9%	2.7%	
6	+	-	-	-	No	62.6%	64.3%	63.3%	
7	+	+	-	-	No	44.4%	36.7%	42.7%	
8	+	+	+	-	No	4.0%	7.1%	3.5%	
9	-	+	-	+	Yes	42.4%	43.3%	40.6%	41.9%
10	+	-	+	-	Yes	15.2%	13.3%	12.2%	13.8%
11	-	-	+	-	Yes	46.5%	55.5%	56.4%	53.0%
12	-	+	-	-	No	80.8%	82.5%	81.4%	
13	-	+	+	-	Yes	30.3%	28.7%	29.5%	29.2%
14	+	-	-	+	Yes	22.2%	22.6%	21.0%	24.2%
15	+	-	+	+	Yes	5.1%	3.7%	7.3%	4.6%
16	+	+	-	+	No	7.1%	12.8%	9.1%	
Mean absolute deviation from true share of support (%; all choice tasks)						3.03	2.19	1.57	
Mean absolute deviation from true share of support (%; taboo tasks only)						2.68	3.15	2.05	

523 survey calls for special attention in model specification. Indeed, as discussed by Hess et al. (2014),
524 the inclusion of an ‘indifference’ option means that non context-dependent models are likely not
525 suitable. To understand this point, note that making both the status quo and the alternative option
526 worse or better by the same amount, be this through changes in time, salary, or both, should not
527 affect the degree to which a decision-maker is indifferent between them. However, in structures
528 based on random utility maximisation (RUM), changes to time or salary for the non-indifference
529 options would change their utilities and hence their probabilities relative to the indifference option,
530 whose utility is unchanged. Hess et al. (2014) shows that on the contrary, as a result of regret
531 models using a value function that is reliant on pairwise comparisons of alternatives, the same
532 change in all non-indifference alternatives does not impact the probability of choosing the indif-
533 ference option. Within a quantum choice model framework, there are numerous possibilities for
534 capturing indifference. For the work on this dataset, we implement the simplest solution. This
535 is to assume that the indifference choice is a separate component of the belief state, using a 3-
536 dimensional Hilbert space. The indifferent alternative thus appears in the model equivalently to
537 any of the other alternatives, except that it does not depend directly on the attributes of the other

TABLE 4 : Observed shares of alternatives under each choice scenario in the couple commuter dataset.

Scenario	Attribute changes				Observed		
	Travel time (TT, mins). Salary (SEK/month)				SQ	NL	Indifferent
	Own TT	Own Salary	Partner TT	Partner Salary			
1	+10	+500	0	0	70.3%	24.5%	5.2%
2	+25	+500	0	0	70.0%	23.9%	6.1%
3	+10	+1000	0	0	71.1%	24.1%	4.9%
4	+25	+1000	0	0	69.5%	25.3%	5.2%
5	+10	+500	+10	+500	74.4%	20.6%	5.0%
6	+10	+500	+25	+500	73.6%	21.2%	5.2%
7	+10	+500	+10	+1000	73.8%	20.3%	5.9%
8	+10	+500	+25	+1000	76.0%	19.2%	4.7%
9	+25	+500	+10	+500	74.4%	21.3%	4.3%
10	+25	+500	+10	+1000	73.4%	20.4%	6.2%
11	+10	+1000	+10	+500	74.8%	20.6%	4.6%
12	+10	+1000	+25	+500	74.0%	20.9%	5.1%
13	+25	+1000	+10	+500	72.4%	22.5%	5.1%

538 alternatives, c.f. Eq. (3). It does however depend on the attributes indirectly, by the normalisation
539 of the components (see Eq. 4). However, by implementing the RRM value functions, our quantum
540 model inherits the property that choice probabilities will be invariant to uniform increases or de-
541 creases of the attribute values. If, for example, we observe an increase of Δ_x across attribute x for
542 all alternatives, then there is no change in the amplitudes: $e^{\beta_k((x_{ntik}+\Delta_x)-(x_{ntjk}+\Delta_x))} = e^{\beta_k(x_{ntik}-x_{ntjk})}$.
543 This means that for the choice scenarios detailed in Table 4, the absolute values for a decision-
544 maker's travel time and salary do not have an impact: it is only the relative differences between the
545 status quo and new location that impact the choice probabilities, both in RRM and our quantum
546 amplitude model. This discussion explains the use of RRM as the base model against which we
547 compare our quantum model.

548 3.2.2. Basic models for the couple commuter dataset

549 For this dataset, there are two distinct choice sets: the first only includes factors impacting the
550 decision-maker alone (CT1) while the second additionally includes impacts on the partner (CT2).

551 For the QA model on the CT1 data, the amplitudes for the status quo (SQ), new location (NL)
552 and indifference (Ind) alternatives are then:

$$\Psi_{nt,SQ} = \frac{\delta_{base} + \delta_{SQ} + \ln(1 + e^{-\beta_{OTT} \cdot \Delta_{O_{nt,TT}}}) + \ln(1 + e^{-\beta_{OSal} \cdot \Delta_{O_{nt,Sal}}})}{\mathcal{N}_{nt}}, \quad (13)$$

553

$$\Psi_{nt,NL} = \frac{\delta_{base} + \ln(1 + e^{\beta_{OTT} \cdot \Delta_{O_{nt,TT}}}) + \ln(1 + e^{\beta_{OSal} \cdot \Delta_{O_{nt,Sal}}})}{\mathcal{N}_{nt}}, \quad (14)$$

554 and

$$\Psi_{nt,Ind} = \frac{\delta_{Ind} + \delta_{base}}{\mathcal{N}_{nt}}. \quad (15)$$

555 We again estimate a constant that is added to the amplitude for all alternatives, δ_{base} , and \mathcal{N}_{nt} is
 556 a normalisation factor calculated using the numerators from each amplitude, Eqs. (13, 14, 15),
 557 in line with Eq. (4). For the remaining terms, we have that $\Delta_{O_{nt,TT}}$ is the change in the decision-
 558 maker's travel time, $\Delta_{O_{nt,Sal}}$ is the change in their salary and the β -coefficients estimate the relative
 559 importance of these attributes ('O' for 'own'). The amplitude for the new location alternative re-
 560 places $-\beta$ with β and obviously drops δ_{SQ} , where we do not show δ_{NL} , which is normalised to
 561 zero, while the constant δ_{Ind} is included for the indifference alternative.

562 For the random regret minimisation models, the random regret functions for the CT1 data are
 563 given by:

$$564 \quad RR_{nt,SQ} = \delta_{SQ} + \ln(1 + e^{\beta_{OTT} \cdot \Delta_{O_{nt,TT}}}) + \ln(1 + e^{\beta_{OSal} \cdot \Delta_{O_{nt,Sal}}}) + \varepsilon_{nt,SQ}, \quad (16)$$

$$RR_{nt,NL} = \delta_{NL} + \ln(1 + e^{-\beta_{OTT} \cdot \Delta_{O_{nt,TT}}}) + \ln(1 + e^{-\beta_{OSal} \cdot \Delta_{O_{nt,Sal}}}) + \varepsilon_{nt,NL}, \quad (17)$$

565 and

$$RR_{nt,Ind} = \delta_{Ind} + \varepsilon_{nt,Ind}. \quad (18)$$

566 Note that the direct comparison of the equations for amplitudes and regret allows for a clear math-
 567 ematical interpretation of the difference between the models. Whereas the quantum models ad-
 568 ditionally have a normalisation factor such that the probabilities can be calculated directly from
 569 these amplitudes, using Eq. (2), the regret model implements uncertainty in which alternative is
 570 chosen through use of type I extreme value distributed error terms, ε . A further difference arises
 571 in that Δ_x and $-\Delta_x$ are interchanged when moving between amplitudes and regret. This is simply
 572 to ensure the correct sign for the directionality of the attributes in the respective models, with the
 573 negative of the regret used to calculate probabilities.

574 For CT2, additional terms are added for the attributes impacting the partner. An additional
 575 layer of flexibility is possible (and explored below), by allowing the parameters for own time and
 576 salary to be different in CT1 and CT2, i.e. not just allowing for differences between the evaluation
 577 of the impact on the respondent themselves (vs on the partner), but allowing that impact to be
 578 different when the impact on the partner is also considered.

579 The results of the basic quantum choice models together with the equivalent RRM models are
 580 given in Table 5. The first models (RRM-1 and QA-1) keep the parameters for the importance of
 581 a decision-maker's own salary and travel time constant between CT1 and CT2, labelling them as
 582 β_{OSal} and β_{OTT} . The second set (RRM-2 and QA-2) have separate parameters for CT1 and CT2 for
 583 the importance of own salary and cost, as well as separate constants for CT1 and CT2.

584 Regardless of whether RRM and QA are compared with or without the use of separate param-
 585 eters, the results indicate a substantial advantage for the quantum models. Additionally, both QA
 586 and RRM find clear evidence that the use of separate CT1 and CT2 parameters lead to further
 587 gains in fit, demonstrating that there is an inconsistency in how a decision-maker considers factors
 588 impacting themselves in the absence (CT1) or presence (CT2) of factors impacting their partner.
 589 These differences are clearly visible in the second set of models, where we see a reduction in both
 590 the own salary and own time parameters when going from CT1 to CT2, where this is an indication
 591 of differences in noise (lower parameters mean a less deterministic choice process), but also dif-
 592 ferences in relative valuations as the reduction is larger for the salary coefficient than for the time
 593 coefficient. The models imposing homogeneity between CT1 and CT2 are biased as a result and
 594 show that individuals give higher importance to their own salary and their own travel time, while
 595 the second set of models shows that this is only the case for salary.

TABLE 5 : Results of all basic models and models with quantum rotations for the couple commuter dataset, together with all parameter estimates.

Type		Basic Models				Models with a quantum rotation							
Specification		RRM-1	QA-1	RRM-2	QA-2	QAR-2a	QAR-2b	QAR-2c	QAR-2d	QAR-2e	QAR-2f		
Free parameters		6	7	10	12	11	11	11	11	11	11		
Log-likelihood		-12,784.21	-12,624.13	-12,426.71	-12,289.38	-12,430.74	-12,463.49	-12,283.33	-12,426.12	-12,461.48	-12,436.75		
Adj. ρ^2		0.41908	0.42631	0.43514	0.44129	0.43491	0.43342	0.44161	0.43512	0.43351	0.43464		
BIC		25,612.62	25,299.83	24,927.10	24,667.17	24,942.52	25,008.01	24,647.70	24,933.28	25,004.00	24,954.55		
Average probability of chosen alternative (by type of alternative and by experiment)													
CT1	Status Quo	77.66%	75.61%	76.97%	77.73%	77.84%	77.74%	77.63%	77.90%	77.70%	78.07%		
	New Location	44.47%	40.97%	42.39%	43.10%	44.04%	44.00%	43.04%	44.24%	44.22%	43.97%		
	Indifferent	1.91%	9.28%	5.01%	6.22%	6.76%	6.76%	6.24%	6.60%	6.67%	6.70%		
CT2	Status Quo	76.62%	78.70%	77.86%	78.19%	77.44%	77.75%	78.23%	77.62%	77.93%	77.07%		
	New Location	29.38%	29.41%	33.47%	33.54%	28.78%	27.73%	34.08%	28.40%	27.57%	28.72%		
	Indifferent	8.04%	3.54%	5.00%	5.37%	5.22%	5.29%	5.25%	5.35%	5.26%	5.35%		
Overall		64.38%	64.18%	64.84%	65.35%	64.69%	64.66%	65.39%	64.76%	64.72%	64.61%		
Parameter Estimates													
Choice Set		both	both	CT1	CT2	CT1	CT2	both	both	both	both	both	both
β_{OTT}	est.	-0.1434	-3.0200	-0.1609	-0.1290	-0.0747	-0.0315	-0.1875	-0.1554	-0.0692	-0.1617	-0.1445	-0.1960
	rob.t-rat.	-39.89	-16.95	-37.19	-30.43	-7.16	-13.04	-8.80	-10.91	-9.96	-10.33	-11.63	-6.79
$\beta_{O_{Sal}}$	est.	2.1004	26.3856	2.4834	1.4860	0.9225	0.3381	1.8225	1.6141	0.8541	1.6326	1.5364	1.8534
	rob.t-rat.	35.69	17.99	31.93	15.80	9.18	6.95	11.38	13.77	11.80	13.55	14.72	9.05
$\beta_{P_{TT}}$	est.	-0.0956	-1.5624		-0.1315		-0.0332	-0.1580	-0.1370	-0.0754	-0.1381	-0.1234	-0.1773
	rob.t-rat.	-35.77	-26.04		-28.78		-14.74	-13.88	-17.37	-15.31	-15.74	-17.57	-10.46
$\beta_{P_{Sal}}$	est.	1.3103	15.1615		0.8569		0.2052	1.7746	1.5900	0.5142	1.6317	1.6599	1.5995
	rob.t-rat.	21.77	35.19		5.40		3.74	8.42	8.79	4.67	10.41	9.56	7.37
δ_{SQ}	est.	-0.3498	-8.7204	-0.5274	0.8100	0.0056	-0.2434	-0.4447	-0.2817	0.0055	-0.3365	-0.2380	-0.5032
	rob.t-rat.	-5.43	-8.03	-6.88	4.33	0.15	-7.28	-4.03	-3.78	0.20	-4.02	-3.60	-3.44
δ_{IND}	est.	5.1402	10.2110	4.2313	6.1702	1.1199	2.4040	1.1086	1.1086	1.1221	1.0972	1.1075	1.1066
	rob.t-rat.	64.77	12.01	50.96	52.16	45.65	352.05	35.11	40.10	55.29	39.97	42.23	33.92
δ_{base}	est.		1.2753			-0.8342	-2.2278	-0.5590	-0.6243	-0.8522	-0.6151	-0.6524	-0.5510
	rob.t-rat.		2.06			-16.93	-221.78	-11.29	-15.27	-23.14	-14.55	-17.10	-9.56
First Rotation								1-2	1-2	1-3	1-3	2-3	2-3
Second Rotation								1-3	2-3	1-2	2-3	1-3	1-2
ω_{1-2}	est.							1.3914	1.0363	0.8699		1.3074	
	rob.t-rat. (vs $\pi/2$)							-3.34	-0.79	-15.70		-2.05	
ϑ_{1-2}	est.							2.8047	3.0650	1.9568		0.2188	
	rob.t-rat. (vs $\pi/2$)							44.56	23.58	9.33		-26.57	
ω_{1-3}	est.							0.3423		1.6702	2.7346		1.3994
	rob.t-rat. (vs $\pi/2$)							13.75		7.19	2.86		-9.03
ϑ_{1-3}	est.							0.5017		1.6371	2.8437		0.8244
	rob.t-rat. (vs $\pi/2$)							-22.57		0.74	28.91		-5.16
ω_{2-3}	est.								1.2713		1.2225	0.5071	1.6737
	rob.t-rat. (vs $\pi/2$)								-16.68		-16.78	-20.56	2.03
ϑ_{2-3}	est.								1.4465		1.5556	2.8602	1.2224
	rob.t-rat. (vs $\pi/2$)								-2.13		-0.46	108.97	-0.75

596 *3.2.3. Models with quantum rotations for the couple commuter dataset.*

597 This dataset also provides opportunities for the use of additional features from quantum choice
 598 models to test for an inconsistency or ‘change of perspective’ incurred through changing from
 599 thinking about just yourself compared to yourself and your partner. We test the change of per-
 600 spective to the choice task with attributes impacting the partner through two consecutive quantum
 601 rotations over the alternatives (status quo, new location and indifferent). For our models imple-
 602 menting quantum rotations, we use Eqs. (13, 14, 15) to define the amplitudes for the alternatives
 603 within the first set of choice tasks. For the amplitudes under the second set of choice tasks, we ini-
 604 tially use these equations to estimate the amplitudes before then applying quantum rotations. Thus,
 605 for these models, we estimate a single set of coefficients that apply to choices made in both choice
 606 sets. We then require a product of two rotation matrices for adjusting the amplitudes appropriately
 607 when additionally considering travel time and salary changes for the partner. The new amplitudes
 608 after the rotation are then given by:

$$\Psi_f = R_B R_A \Psi_0, \quad (19)$$

609 where R_A and R_B are both estimated using Eq. (6) and rotation matrices based on R_2 with the
 610 use of axis and angle parameters. We again find that fixing $n_x = 0$ results in no loss of model fit,
 611 leaving us with four free parameters, ω_A , ω_B , ϑ_A and ϑ_B , where we again set $n_y = \cos(\omega)$ and
 612 $n_z = \sin(\omega)$. Given that we implement two consecutive rotations on pairs of alternatives, there are
 613 six combinations of pairwise rotations. The results of these six models are given in Table 5. In
 614 all six cases, we see an improvement in fit over the basic model (QA-1). The third option (QAR-
 615 2c) which first rotates between the status quo and the indifference option (alternatives 1 and 3),
 616 before rotating between the status quo and the new option (alternatives 1 and 2), offers the most
 617 substantial improvement in fit. It also outperforms the second basic model (QA-2), suggesting that
 618 the rotations can better account for the differences between tasks completed in the different choice
 619 sets than is the case for using separate parameters.

620 *3.2.4. Models with complex phases for the couple commuter dataset*

621 We next turn to the incorporation of complex phases, where we again test a number of possible
 622 specifications, given that there are six different attributes and many possibilities for how many
 623 phases to implement. We consider the following possibilities for how to introduce complex phases.

- 624 1. A model with a single complex phase, φ , that is applied to all of the attributes.
- 625 2. A model with two complex phases, φ_1 and φ_2 , with the first applied to attributes impacting
626 the decision-maker and the second applied to attributes impacting the partner.
- 627 3. A model with two complex phases, with the first applied to travel time attributes and the
628 second applied to salaries.
- 629 4. A model with two complex phases, with the first applied to attributes in the first set of choice
630 tasks, and the second applied to attributes in the second set of choice tasks.
- 631 5. A model with six complex phases with six free parameters, $\{\varphi_1, \dots, \varphi_6\}$, with a different
632 phase for each attribute in each set of choice tasks.

TABLE 6 : Results of all models with complex phases and the combined models for the couple commuter dataset, together with all parameter estimates, where \circ and \star indicate attribute pairs which have the same phase.

Type		Models with complex phases					Combined	
Specification		QAPh-1	QAPh-2	QAPh-3	QAPh-4	QAPh-5	QAC-1	QAC-2
Free parameters		8	9	9	9	13	17	15
Log-likelihood		-12,536.66	-12,366.51	-12,536.65	-12,487.07	-12,319.10	-12,249.70	-12,250.21
Adj. ρ^2		0.43024	0.43792	0.43019	0.43244	0.43989	0.44286	0.44293
BIC		25,132.26	24,799.33	25,139.60	25,040.45	24,733.98	24,624.65	24,610.94
Average probability of chosen alternative (by type of alternative and by experiment)								
CT1	Status Quo	75.57%	76.99%	75.57%	76.21%	77.79%	78.15%	78.18%
	New Location	39.84%	42.51%	39.84%	39.36%	42.96%	43.92%	43.84%
	Indifferent	8.77%	6.83%	8.76%	8.34%	6.65%	6.13%	6.15%
CT2	Status Quo	79.57%	78.57%	79.58%	78.99%	78.32%	78.21%	78.22%
	New Location	33.13%	31.82%	33.13%	33.51%	32.81%	34.15%	34.13%
	Indifferent	4.01%	5.40%	4.01%	4.37%	5.40%	5.26%	5.27%
Overall		64.79%	65.02%	64.79%	64.76%	65.34%	65.65%	65.66%
Parameter Estimates								
β_{OTT}	est.	-3.1325	-0.1441	-3.1557	-3.3643	-0.0709	-0.0385	-0.0383
	rob.t-rat.	-12.99	-28.52	-8.63	-14.15	-18.58	-9.75	-9.96
β_{OSal}	est.	17.9584	1.4095	18.0740	26.0038	0.8198	0.6026	0.5430
	rob.t-rat.	13.83	22.79	8.92	14.09	17.04	7.28	11.10
β_{PTT}	est.	-2.0343	-0.0992	-2.0487	-2.6486	-0.0908	-0.0513	-0.0543
	rob.t-rat.	-14.07	-18.67	-8.96	-14.95	-10.33	-7.12	-9.03
β_{PSal}	est.	9.0215	0.6876	9.0752	10.1627	0.5504	0.2528	0.2530
	rob.t-rat.	1.20	7.43	8.38	18.89	6.44	5.07	5.00
δ_{SQ}	est.	-41.2320	-0.5687	-41.4785	-33.3201	-0.0046	0.0992	0.0784
	rob.t-rat.	-12.40	-6.16	-8.57	-11.00	-0.15	4.85	5.04
δ_{IND}	est.	6.6360	1.2861	6.7424	8.9254	0.7372	1.0810	1.0512
	rob.t-rat.	10.09	36.59	7.70	10.35	15.23	81.06	32.53
δ_{base}	est.	1.1958	-0.8424	1.1482	0.7655	-0.9828	-1.2130	-1.1817
	rob.t-rat.	2.59	-25.32	2.75	17.27	-27.24	-99.16	-55.73
ω_{1-2}	est.						0.7219	0.3527
	rob.t-rat. (vs $\pi/2$)						-7.57	-9.96
ϑ_{1-2}	est.						2.3048	2.5050
	rob.t-rat. (vs $\pi/2$)						5.86	18.47
ω_{1-3}	est.						1.6817	1.7523
	rob.t-rat. (vs $\pi/2$)						3.55	3.94
ϑ_{1-3}	est.						2.3981	2.7212
	rob.t-rat. (vs $\pi/2$)						3.49	9.95
φ_{OTT_1}	est.	0.3958 $^\circ$	0.5282 $^\circ$	0.3960 $^\circ$	0.7655 $^\circ$	0.1119	0.1653	0.0619 $^\circ$
	rob.t-rat.	17.62	31.39	17.60	17.27	2.12	2.55	1.76
φ_{OTT_2}	est.	0.3958 $^\circ$	0.5282 $^\circ$	0.3958 $^\circ$	-3.04E-06 *	-1.0690	0.2035	0.0619 $^\circ$
	rob.t-rat.	17.62	31.39	17.60	-4.13	-15.75	1.41	1.76
φ_{PTT}	est.	0.3958 $^\circ$	-1.2984 *	0.3958 $^\circ$	-3.04E-06 *	1.2073	0.3628	0.2338
	rob.t-rat.	17.62	-29.61	17.60	-4.13	25.92	2.69	3.78
φ_{OSal_1}	est.	0.3958 $^\circ$	0.5282 $^\circ$	0.1602 *	0.7655 $^\circ$	0.2671	0.1045	0.1502 *
	rob.t-rat.	17.62	31.39	0.41	17.27	11.21	4.69	6.75
φ_{OSal_2}	est.	0.3958 $^\circ$	0.5282 $^\circ$	0.1602 *	-3.04E-06 *	0.7928	0.5541	0.1502 *
	rob.t-rat.	17.62	31.39	0.41	-4.13	12.23	3.77	6.75
φ_{PSal}	est.	0.3958 $^\circ$	-1.2984 *	0.1602 *	-3.04E-06 *	-1.0220	-0.5316	-0.7645
	rob.t-rat.	17.62	-29.61	0.41	-4.13	-27.09	-2.99	-3.29

633 The results of these different possibilities are given in Table 6. The incorporation of a larger
 634 number of complex phases opens up the potential for large gains in fit, but the actual specification

635 of the phases is important. For example, a significant gain is found by moving from a single phase
 636 to two phases for each combination except for the model with different phases for travel time as
 637 opposed to salaries (QAPh-3). The most substantial of these gains is found by QAPh-2, which has
 638 separate phases for attributes impacting the decision-maker and attributes impacting their partner.
 639 The best performing model overall is a model with a different phase for each of the different at-
 640 tributes, suggesting that, as with the first dataset, the attributes are considered differently. However,
 641 this model does not perform as well as a basic quantum amplitude model with separate parame-
 642 ters for the different choice sets (see Table 5). Consequently, as opposed to the results of the first
 643 dataset, it is the addition of quantum rotations rather than complex phases that better captures the
 644 implicit change in choice context.

645 3.2.5. Combined model for the couple commuter dataset

646 For our combined model, we again utilise a model with both quantum rotations and complex phases
 647 to capture the change of perspective when commute attributes concerning the partner are also
 648 present. Given the good performance of QAPh-5, which has six phases, and of QAR-2c, we opt
 649 to combine these models for our final model. This means that it has 7 parameters in common with
 650 the basic model (QA-1), 6 complex phases (with one for each attribute) and 4 rotation parameters,
 651 as before for the models with quantum rotations. Note that we implement rotations based on the
 652 best performing rotation model, thus first rotating between the status quo and the indifference
 653 option (axis parameter ω_{13} , angle ϑ_{13}) before rotating between the status quo and the new location
 654 alternative (axis parameter ω_{12} , angle ϑ_{12}).

655 Table 6 gives the results of our combined model. This time, in contrast with the results for the
 656 taboo trade-off dataset, we see that the model (QAC-1) combining quantum rotations and complex
 657 phases does offer a significant improvement over a model offering only one of these additional
 658 features to capture the change of perspective. We also see that the model with six phases has
 659 rather different estimates for the phases for the same attributes across the different choice sets,
 660 suggesting that these attributes cannot be treated equivalently (Fig. 3). For the combined models,
 661 we find significant estimates for both the phase and rotation parameters. However, we note that
 662 there is not a significant difference between the phase parameters across choice sets ($\varphi_{O_{Sal_1}}$ and
 663 $\varphi_{O_{Sal_2}}$) and (φ_{OTT_1} and φ_{OTT_2}). It thus appears that the quantum rotation, which is used for the
 664 ‘change of perspective’ from the first choice task to the second choice task, already captures the
 665 difference between choice sets. We consequently include a second combined model (QAC-2) with
 666 just four complex phases. This final model does not result in a significant loss of model fit, as
 667 expected, and achieves the best adjusted ρ^2 and BIC.

668 This effect is particularly clear through closer consideration of the estimates for the complex
 669 phase parameters, φ . These are displayed graphically in Fig. (3). For the model with complex
 670 phases only (QAPh-5), we observe very different estimates across attributes, choice task set and
 671 whether an attribute affects the decision-maker or the partner. This illustrates why the QAPh-5
 672 model can outperform the models with only two complex phases, with the flexibility of inter-
 673 actions across all attributes clearly helping to improve performance. The addition of quantum
 674 rotations, (moving from QAPh-5 to QAC-1) results in phases regressing closer to smaller values
 675 (modulo 2π). This results in a weaker interference interaction across the attributes, with the real
 676 parts growing in magnitude whilst the imaginary parts shrink. The only exception is the phase to
 677 attribute OTT-2 which appears to vary strongly. However, the phase to OTT-2 in QAC-1 is not
 678 reliable (t-value = 1.41), hence its value shift from QAPh-5 to QAC-1 should not necessarily be

679 understood as a significant adaptation but rather a shift to a spurious local optimisation value in
 680 QAC-1. Notably, the estimates for OTT-1 and OTT-2 are similar in QAC-1, and the use of only
 681 one phase for the decision-maker’s travel times (and one phase for salary) gives us the result in
 682 QAC-2, which records an insignificant loss of model fit.

683 Table 6 also compares the average probability for the chosen alternative under each of these
 684 models. The combined models do better than other models for choices where the decision-maker
 685 opts to change to the new location, with the combination of quantum rotations and complex phases
 686 evidently helping capture these choices. The coefficients associated with attributes (β) change
 687 substantially across the different models, with the ratios of parameters also changing. A decision-
 688 maker’s own salary ranges from being approximately equivalently as important as their partner’s
 689 salary, to more than double the importance in the combined model. The converse is true for travel
 690 times, with the combined model indicating a partner’s travel time is of greater importance than that
 691 of the decision-maker. The opposite is true in the basic model.

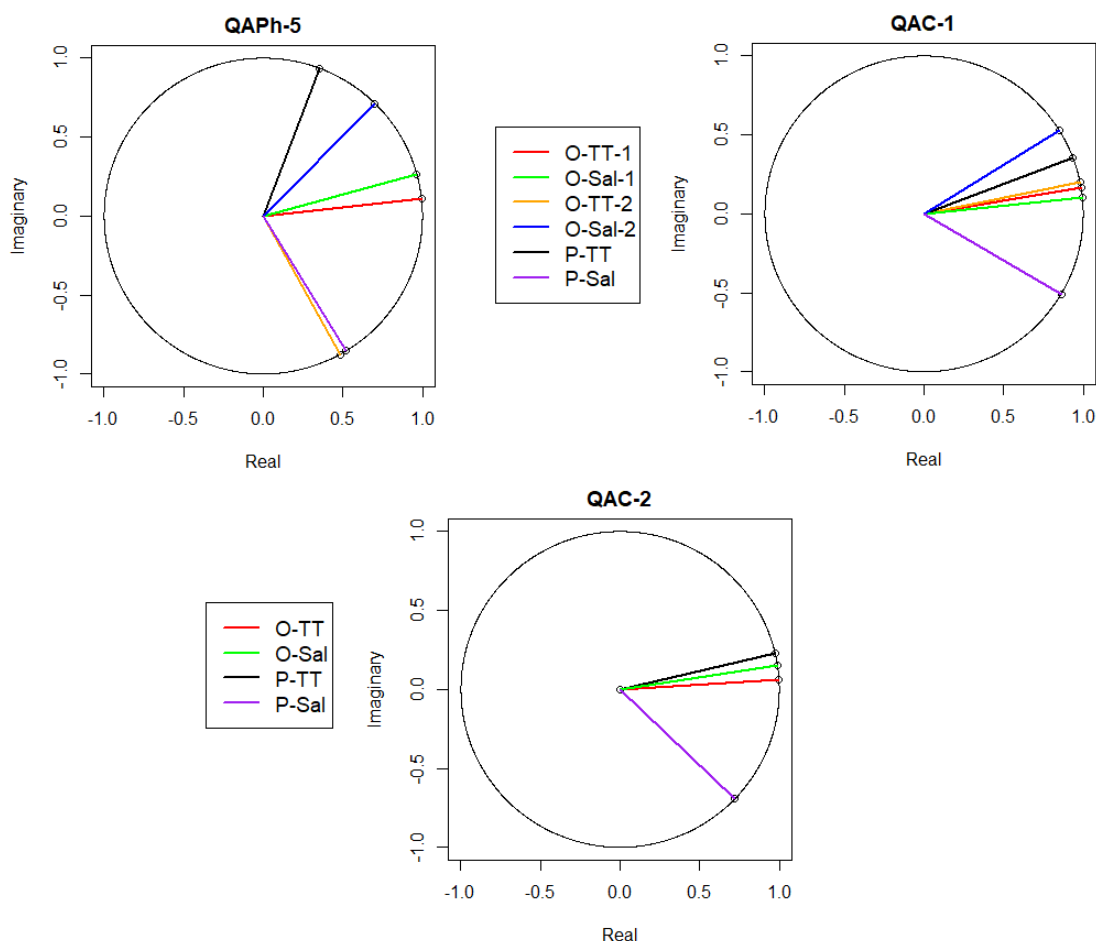


FIGURE 3 : Illustration of the estimated complex phase coefficients for the travel time (TT), salary increase (Sal) of the decision-maker (O) and partner (P) in the quantum models QAPh-5 (only complex phases), QAC-1 (rotations and 6 phases) and QAC-2 (rotations and 4 phases). Model QAC-2 keeps the same phases for the choice set CT1 (self) and CT2 (self and partner).

692 4. CONCLUSIONS

693 The growing interest in moral decision-making in choice modelling calls for the development of
694 appropriate model specifications. The present paper has focussed on quantum probability and
695 demonstrated that quantum rotations, as well as complex phases, accurately capture an implicit
696 change in decision context when a more salient moral element enters the dimension of choice.

697 For our first choice paradigm with a ‘Taboo trade-off’, we find that models containing a per-
698 spective operation implemented by both rotations and complex phases do not significantly improve
699 upon models with just one of these features. This however is not the case for the second choice
700 paradigm with a moral component due to choices impacting the partner, in which our combined
701 model with a perspective operation that has both features outperforms simpler specifications. Fur-
702 ther work is thus required to establish the relative strengths and merits of these different features
703 for the decision-maker’s implicit perspective change, with it being possible that the first choice sce-
704 nario is too simple (in having only two alternatives) to merit further model features. Importantly,
705 quantum models have the potential to offer better performance than more conventional approaches
706 in both datasets, as shown by our empirical results.

707 Overall, whilst the results for the quantum choice models in this paper are promising, it is not
708 clear that they are distinctly *better* than those of [Hancock et al. \(2020\)](#). This implies that we cannot
709 necessarily attribute the success of the quantum rotations and complex phases to the fact that there
710 are moral components in the choices modelled. This is particularly clear from the result that our
711 quantum model already has better model fit than the random regret model for the second dataset
712 tested in this paper *before* the moral component was captured through the additional quantum
713 model features. Further tests of quantum probability theory based models could shed light on
714 whether they are models that are particularly suited to moral decision-making with salient attribute
715 scenarios, or whether they are suitable for decision-making in general.

716 Further models should consider different sorts of moral choice data and scenarios. For exam-
717 ple, quantum models may be well suited for modelling choices made in ‘moral machine’ choice
718 tasks. The application of these models to choice scenarios where multiple individuals disagree,
719 communicate and reassess on what is their ‘most ethical’ choice would be particularly interesting.
720 On such socially sensitive matters moreover, results may also differ significantly for *revealed* pref-
721 erence datasets due to continuing concerns about external validity of *stated* moral choices ([Bauman
722 et al., 2014](#)).

723 Closer to our present study, given that quantum models explicitly assume that a decision-maker
724 is uncertain about their choice, an ‘indifferent’ (or equivalently a ‘neither’) alternative may be bet-
725 ter modelled not as a separate alternative, but based on the superposition principle. The indifferent
726 belief state would be expressed through a superposition of the belief states for each of the two
727 choices. Such a superposition could contain a relative complex phase, which could depend on
728 specific attributes of the alternatives. Such an approach would then resort to an interference effect
729 between the belief states supporting the respective choices. The representation space would be
730 smaller again - a 2-dimensional Hilbert space, and its choice probabilities renormalised to include
731 the third - indifference - option. Other extensions to explore scenarios with an indifference option
732 could make the indifference-component of the belief state explicitly dependent on the attributes of
733 the choices (as a contrast to Eq. 15). Such a function could, for example, express an additional
734 effect at play in the balance of the two other choices; the indifference between two very favourable
735 alternatives may be less prominent than the indifference between two pale alternatives - due to a
736 lack of interest. A further theoretical development of the quantum model could incorporate the im-

737 pact of previous choices through a carry-over parameter that modifies the amplitude of the present
738 quantum perspective operation. Finally, another next step could be to test the decision-maker for
739 explicit ethical answerability of the choice alternatives first. For example, in the taboo trade-off
740 paradigm, a decision-maker's explicit change of perspective could then be further analysed from
741 the tensorial belief state (Status Quo, New Policy) \otimes (Ethical, Not-Ethical), and compared to a test
742 where only an *implicit* change of perspective is assumed.

743 Whilst we include a discussion on various parameter ratios, one clear weakness of the new
744 quantum choice models developed here is that, by not being grounded in microeconomic theory,
745 they cannot be used to compute context independent welfare measures. This is a common limi-
746 tation of all models that include departures from a random utility framework. With our previous
747 work (Hancock et al., 2020) demonstrating that quantum choice models can produce forecasts and
748 elasticities, further research is needed to establish how the outputs can be used in an appraisal
749 context.

750 Overall, however, our results indicate that choice models with a quantum probability frame-
751 work have vast potential, both within moral choice scenarios and more generally.

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