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1	Elastic and Inelastic Buckling of Steel Cellular Beams under Strong-Axis Bending
2 3	Komal Rajana <sup>1</sup> , Konstantinos Daniel Tsavdaridis <sup>2*</sup> and Efthymios Koltsakis <sup>3</sup>
4	<sup>1</sup> PhD Student, School of Mathematics, Computer Science and Engineering, Civil Engineering, City,
5	University of London, EC1V 0HB, London, UK
6	<sup>2</sup> Associate Professor of Structural Engineering, School of Civil Engineering, Faculty of Engineering and
7	Physical Sciences, University of Leeds, LS2 9JT, Leeds, UK
8	<sup>3</sup> Associate Professor, Department of Civil Engineering, Aristotle University of Thessaloniki, Greece
9 10 11 12	*Corresponding author, E-mail: <u>K.Tsavdaridis@leeds.ac.uk</u>
12	ABSTRACT
14 15 16 17 18 19 20 21 22	This paper presents an extensive parametric study of elastic and inelastic buckling of cellular beams subjected to strong axis bending in order to investigate the effect of a variety of geometric parameters, and further generate mass data to validate and train a neural network-based formula. Python was employed to automate mass finite element (FE) analyses and reliably examine the influence of the parameters. Overall, 102,060 FE analyses were performed. The effects of the initial geometric imperfection, material nonlinearity, manufacture-introduced residual stresses, web opening diameter, web-post width, web height, flange width, web and flange thickness, end web-post width, and span of the beams and their combinations were thoroughly examined. The results are also compared with the current state-of-the-art design guidelines used in the UK.
23 24 25 26	It was concluded that the critical elastic buckling load of perforated beams corresponds to the lateral movement of the compression flange while the most critical parameters are the web thickness and the geometry of the flange. However, from the inelastic analysis, the geometry and position of the web opening influence the collapse load capacity in a similar fashion to the geometry of the flange and thickness of the

*Keywords*: Cellular beams; Elastic and inelastic buckling; Strong-axis bending; FEA; Parametric studies;

web. It was also concluded that the effect of the initial conditions was insignificant.

30 Automated analyses; Python; Mass data

#### 31 1. Introduction

#### 32 1.1 Background

The use of steel beams is an attractive option within the steel construction industry due to its flexibility in terms of strength, size, and weight. The most notable benefits of perforated beams are the inclusion of services, thereby reducing the building's height, the need for internal columns, construction time and costs. The increased depth of cellular beams offers greater bending resistance in the strong-axis which provides an increased moment of inertia when compared to similar weight sections.

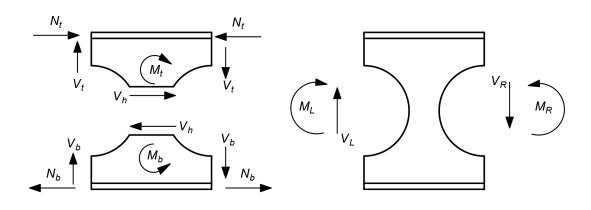
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Perforated beams with circular web openings referred to as cellular beams have been found to have additional merits relating to its flexibility and design when compared to other beams with varying opening shapes. The presence of web openings, however, presents several intricate behavioural patterns due to the combined shear and bending stresses concentrated at the openings. According to Ward (1990) the loadcarrying capacity of a cellular beam is significantly affected by the response of the web-post and the tee-

43 carrying capacity of a cellular beam is significantly affected by the response of the web-post and the tee-44 sections to local bending and vertical shear across the web opening. Consequently, over the years,

45 researchers have studied the stress distribution pattern and failure modes of these beams based on elastic

46 and inelastic behavioural patterns. Figure 1 displays a cellular perforated section in static equilibrium.



47

48

Figure 1: Forces in static equilibrium at the opening and the web-post

49 The aim of the current study is to highlight the effects of certain key parameters (e.g., material 50 nonlinearities, manufacture-introduced residual stresses, web opening diameters, web-post widths, heights 51 of web, widths of flange, flange thicknesses, web thicknesses, and lengths of beams) on the global structural 52 behaviour and ultimate load capacity through developing mass data. The global response was considered 53 as a combined interaction of the global lateral buckling mode and localised deformations at the openings. 54 The interaction of buckling modes in I-section beams (perforated and non-perforated) has been a subject of 55 extensive experimental and numerical investigations. For example, Bradford (1992, 1998) thoroughly 56 examined the lateral-distortional buckling of I-sections, Zirakian and Showtaki (2006) was one of the first 57 to study the distortional buckling of castellated beams, also Zirakian (2008) studied the elastic distortional 58 buckling of doubly symmetric I-shaped flexural members with slender webs, and Ellobody (2011, 2012, 59 2017) comprehensively investigated the interaction of buckling modes in castellated steel beams conducting 60 nonlinear analyses under combined buckling modes as well as studying the interaction of buckling modes 61 in steel plate girders. Ellobody (2012) concluded that the influence of the interactions of lateral-torsional 62 and web distortional buckling of cellular beams on the strength and inelastic behaviour is yet to be

63 understood. As such, this research sought to avoid the analysis of many complex localised failures

- associated with cellular beams by utilising a FE collapse analysis to compute the global buckling capacity
- as a Load Proportionality Factor (LPF) of the entire beam. Even though many researchers since 1957 (e.g.,

66 Altfillisch et al., 1957, Kolosowski J, 1964, etc.) investigated perforated beams; until the past decade where

- 67 scientists have studied various locatlised failures such as buckling (e.g., Ellobody, 2011) and vertical shear,
- 68 aka Vierendeel (e.g., Tsavdaridis and D'Mello, 2012; Tsavdaridis and Galiatsatos, 2015), very little has
- 69 been done with regards to the global response of such members.
- 70

71 With the power of todays' FE tools and CPU, this study provides an opportunity to fill this gap in the 72 literature, as extensive FE parametric analyses on the structural stability of thin-walled cellular beams can

73 attempt to clarify the influence of each parameter to the perforated beams' complex structural behaviours.

# 74 *1.2 Failure Modes*

75 Past numerical and experimental studies on perforated beams have shown that the failure modes are

dependent on the slenderness of the section, the geometry of the web opening (i.e., diameter and web-post)

and the type of load application (Chung et al., 2003). The bending and shear stresses concentrate in the

vicinity of the openings and trigger several types of failure modes including web-post buckling, lateraltorsional buckling (LTB) with web-distortion, Vierendeel mechanism and the rupture of the welded joints.

80

81 The excessive plastification of plastic hinges, or Vierendeel mechanism, commonly occurs in beams with

short spans, wide web-post, width flange, and shallow tee-sections. This type of failure was firstly reported

- 83 by Alfifillisch et al. in 1957 and later by Kolosowski, 1964, while it was comprehensively studied by Kerdal
- 84 and Nethercot (1984) to develop an in-depth understanding of the effects of the opening geometry. The past
- 85 decade, Tsavdaridis et al. presented a series of extensive research studies investigating the mobility and 86 position of plastic hinges when different shape and size of web openings are used and relate them with the
- 87 shear-moment interaction at the centreline of the particular opening. Experimental (Tsavdaridis 2010;
- 88 Tsavdaridis and D'Mello 2012) and FE (Tsavdaridis and D'Mello, 2009; Tsavdaridis and D'Mello, 2011)
- 89 studies have been conducted. Moreover, Kingman et al. (2015) proposed optimised architectures for web 90 openings to better control the position of the plastic hinges, increasing the capacity of the section.
- 91 Tsavdaridis and Galiatsatos (2015) have also studied the position of the plastic hinges and capacity gains
- 92 by the introduction web-welded stiffeners. Yu et al. (2010) and Tsavdaridis et al. (2013) also studied the
- 93 vertical shear capacity of such perforated sections when infilled by concrete. Later, Maraveas et al. (2017)
- 94 has examined the performance of such beams under fire conditions too. Overall, it was concluded that the
- 95 position of the plastic hinges drastically influences the beam's load-carrying capacity.
- 96

97 This study seeks to activate a lateral global buckling failure combined with a localised web-post 98 deformation by alternating various magnitude of geometrical imperfections to the first global and local 99 buckling modes. Therefore, the collapse failure (e.g., at maximum LPF) is in the form of a lateral 100 distortional buckling (LDB) which consists of a combined effect of lateral movement, unequal twisting of 101 the flange and localised web distortion of the cross-section.

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- 103
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#### 106 1.3 Design Guidelines

107 Akrami and Erfani (2016) compared the most prevalent design guidelines and concluded that the methods

108 proposed by Chung et al. (2003) and Tsavdaridis and D'Mello (2012) were the least restrictive as compared 109 to the other design methods (i.e., ASCE 23-97; SCI-P100; SCI-P355) and produced the lowest errors.

to the other design methods (i.e., ASCE 23-97; SCI-P100; SCI-P355) and produced the lowest errors.
 However, even though design methods have been presented, there are still several uncertainties that result

in conservative and complicated design approaches. Therefore, the complexity of perforated beams and the

- 112 numerous parameters which affect the performance indicate the need for further research most importantly
- 113 in the global response. In the design guidelines, some of the failure modes or a combination of failure modes
- 114 and parameters are excluded, thus they are restrictive approaches.
- 115

## 116 2. Parametric Matrix and Finite Element Modelling

117 The variables required for the elastic analysis is only based on the linear elastic stiffness, boundary 118 conditions, and geometry. The parametric study required the creation of 405 ABAQUS CAE base models.

119 The non-scripted parameters were the spacing of web opening (3 values), the diameter of web opening (3

values), the height of section (3 values), the width of the flange (3 values) and length of member (5 values).

122 The total number of combinations generated with Python for each analysis type is as follow:

• Elastic analysis =  $3^{6}$  (x 5 lengths) = 3,645 FE simulations

• Nonlinear analysis =  $3^9$  (x 5 lengths) = 98,415 FE simulations

125

126 The critical geometrical parameters are provided in Figure 2.

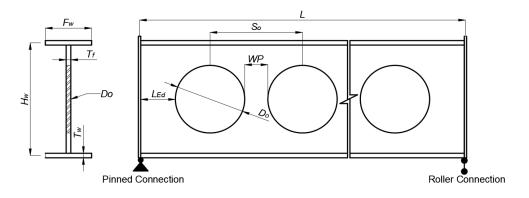






Figure 2: Important dimensional parameters of cellular beams

#### 129 2.1 Geometric Parameters of Cross-Section

130 The lengths of beams selected for this study were 4m, 5m, 6m, 7m, and 8m. It was decided not to examine 131 longer beams as the effect of the web opening is less critical to local failure mechanisms. According to 132 Chung et al. (2001) and Tsavdaridis (2010) the longer the beam is, the less is the effect of the web opening 133 position -a critical parameter for this study. When perforated sections with large web openings are 134 considered, the combination of the beam span and the web opening position could yield completely 135 different results. In particular, for long span beams (>7m) and web openings located close to the mid-span; 136 the global bending moment at the perforated section increases quickly while the shear force decreases 137 steadily. Therefore, the beams tend to fail in flexure due to a reduced moment capacity of the perforated

138 section. However, for short span beams a reduced load carrying capacity is obtained when the web openings 139 are located either close to the supports or close to the mid-span. Obviously, the reduction of the shear 140 capacity for large web openings close to the support is more severe. For conservative reasons, it is decided 141 to use spans up to 8m for this research programme as the fluctuation of the results using large web openings 142 leads to important conclusions. The fillet radius has been neglected in high impact research relating to 143 cellular beams (Ellobody E, 2012; Tsavdaridis and D'Mello, 2011, 2012; Wang, Ma and Wang, 2014) and 144 design guidelines (AISC, 2017), therefore, the influence is considered insignificant to alter the beam's 145 global response, and it is not considered as a parameter variable for this study. This assumption is also in 146 line with Sonck (2014) and Taras (2010) who have reported that this simplification by ignoring the fillet 147 radius effects is small on the buckling curve parameters. This approach is also conservative and covers the 148 case where fabricated sections are considered. The cross-section properties of the beams are summarised in 149 Table 1.

- 150
- 151

Table 1: Cross-sectional description of beams

Description	Variable (1) (mm)	Variable (2) (mm)	Variable (3) (mm)
Web height $(H_w)$	700	560	420
Web thickness $(T_w)$	15	12	9
Flange width $(F_w)$	270	216	162
Flange thickness $(T_f)$	25	20	15

152

#### 153 2.2 Web Opening Limits

The web opening diameter and spacing were limited to the recommended range in accordance with SCI-P100 ( $H_w/D_o=1.25$  to 1.7 and  $S_o/D_o=1.1$  to 1.49). Table 2 provides the geometrical parameters for the perforation. It is worth noting that the location of the first web opening in the parametric study was placed at the centre of the beam while the subsequent adjacent openings were offset from the central opening until no more web opening can fit in the beam's length. This approach resulted in 135 different distances from the end perforation to the support (centreline of end-plate) which was also considered as an independent variable ( $L_{Ed}$ ).

161

Table 2: Spacing between web openings with respect to the opening diameter

( <b>H</b> <sub>w</sub> )	$(H_{u}/1.25, H_{u}/1.5)$ &	( <i>So</i> ) (mm)			WP (mm)		
$(\mathbf{m}\mathbf{m})$		1.1D <sub>0</sub>	1.29D <sub>0</sub>	1.49D <sub>0</sub>	D <sub>0</sub> /10	D <sub>0</sub> /3.45	D <sub>0</sub> /2.04
	560	616	722	834	56	162	274
700	467	514	602	696	48	135	229
-	412	453	531	613	41	119	202
	448	493	578	668	45	130	220
560	373	410	481	556	37	108	183
-	329	362	424	490	33	95	161
	336	370	433	501	37	97	165
420	280	308	361	417	28	81	137
-	247	272	319	368	25	72	121

162 2.3 Material Properties

- 163 The material behaviours used are elastic and elasto-plastic with isotropic strain hardening, which considered
- 164 a tangential modulus of  $(E_t)$  1000MPa, a Modulus of Elasticity of (E) 200GPa, and a Poisson's ratio of 0.3.
- 165 The Tangent modulus assumption utilised after a detailed study of the test data taken from Redwood and
- 166 McCutcheon (1968). The three combinations selected are presented in Table 3.
- 167
- 168

 Table 3: Material nonlinearities for the three selected strength class for steel

Yield stress (MPa)	Ultimate stress	Initial Strain (ɛ <sub>y</sub> )	Final Strain (ε <sub>t</sub> )
$f_y$	$(MPa) f_u$	$f_y/E$	$\varepsilon_y + (f_u - f_y)/E_t$
235	360	0.001175	0.156775
355	510	0.001775	0.126175
440	550	0.0022	0.1122

169

#### 170 2.4 Finite Element Properties

171 The geometry of the models was prepared using planar shell models having homogenous material 172 properties. The finite element mesh uses the quad-dominated, type S8R (e.g., stress-displacement shell with 173 eight nodes) doubly curved thick shell elements using reduced integration element which has six degrees 174 of freedom per node. Sonck (2014) reported this is ideal for modelling cellular beams as hour-glassing 175 would occur for the reduced order shell elements (e.g., S4R and S4R5). The consideration for the mesh was 176 taken from Hesham Martini (2011) and Sweedan, (2011) where 12 elements are across the flange width 177 and size for the web region was reduced by 20% (e.g., F<sub>W</sub>/12\*1.2). Support endplate uses 8 elements as this 178 is unimportant. This arrangement has been observed, to accurately predict the global response of cellular 179 beams tested in laboratory by Surtees and Liu (1995) and Tsavdaridis and D'Mello (2011) as detailed in 180 section 3.0 and was effectively implemented for computational application in Abambres et al. (2018).

### 181 2.5 Boundary and Loading Conditions

182 The models considered a simple supported connection where one end was pinned and the other was a roller.

183 This allowed an in-plane rotation but not a translation at one end while the other one permits the translation

184 of the beam beyond the in-plane rotation point. Twisting rotations at the ends were prevented by restraining

both the top and bottom flange tips against out-of-plane displacements. (Ellobody, 2012) A uniformly

distributed unit load was applied to the top flange which gives the critical buckling load and the collapse

187 load LPF as a multiplier of 1.0.

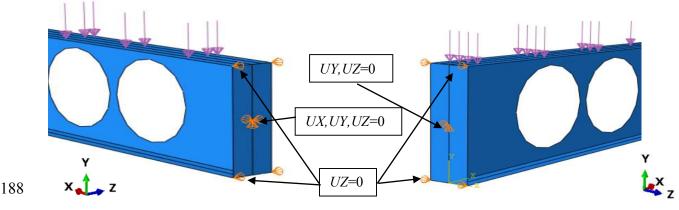


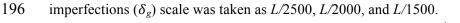


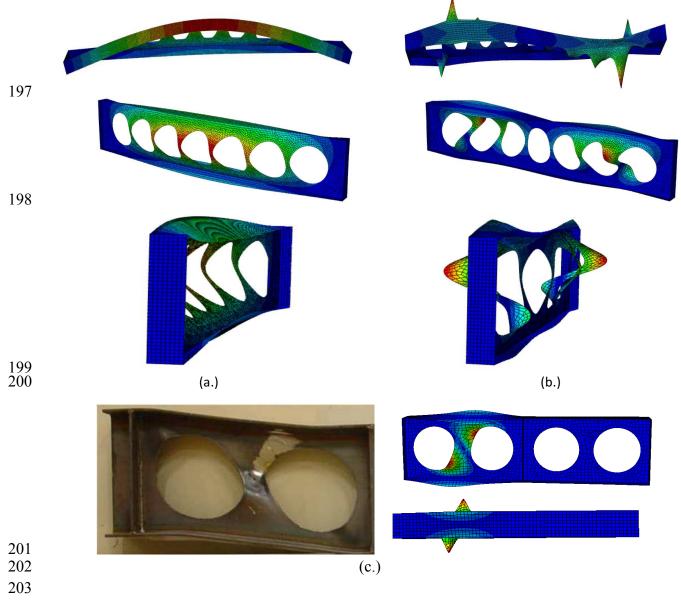
Figure 3: Boundary conditions in the finite element model

#### 191 2.6 Initial Geometric Imperfection

192 Imperfections allow the initiation of buckling failure; however, this imperfection must be of small 193 magnitude in order to avoid disruption of the beam's main responses. The global imperfection was applied 194 to the first Eigen buckling mode and the local imperfection to the second or third Eigen buckling mode. As the beam length increases, the first two modes produced global perturbation shapes. The global

195





204 Figure 4: Perturbed geometry: (a) the global, (b) local initial geometrical imperfection shapes (local 205 buckling near the supports), (c) Image of local imperfection (Tsavdaridis and D'Mello, 2011)

206 The local imperfection was based on Dawson and Walker (1972) method which is a function of the cross-207 section of the beam and the yield strength of steel. The following equations were utilised to calculate the

208 local imperfection for the web region as provided in Table 4. This imperfection shape only captured the 209 web distortion buckling mode. The calculations incorporated a yield strength ( $f_v$ ) of 355MPa.

210 
$$\delta_{LI} = \frac{\gamma T_w f_y}{\sigma_{cr.l}} = \frac{\gamma f_y (H_w)^2}{21.6E.T_w}$$
 (eq1)

211 
$$\sigma_{cr.l} = \frac{23.9\pi^2 E}{I2(I-0.3^2)} \left(\frac{T_w}{H_w}\right)^2 = 21.6E \left(\frac{T_w}{H_w}\right)^2$$
(eq2)

The third local geometrical imperfection was chosen based on the following parameters in order to considered a localised imperfection that is slightly higher than what is specified by Dawson and Walker (1972).

215 
$$\delta_{\text{LI}(3)} = \frac{\binom{F_W}{2}}{200} = \frac{C_{flange}}{200}$$
 (eq3)

216

#### 217

 Table 4: Local web imperfection applied to the web buckling deformed mode

Formulae	$T_w = 15$ mm $H_w = 700$ mm	$T_w = 12$ mm $H_w = 560$ mm	$T_w = 9$ mm $H_w = 420$ mm
$\delta_{LI(1)} = \frac{0.1T_w f_y}{\sigma_{cr.l}}$	0.268441358	0.214753086	0.161064815
$\delta_{LI(2)} = \frac{0.2T_w f_y}{\sigma_{cr.l}}$	0.536882716	0.429506173	0.32212963
$\delta_{LI(3)} = \frac{c_{flange}}{200}$	0.675	0.54	0.405

218

219

220 2.7 Residual Stresses

221 During the cutting and welding process, the use of heat can lead to uneven cooling along with the member 222 resulting in variable yield stress patterns and further differential plastic deformations (Sonck, 2014). The 223 process of welding can cause a thermal contraction as the beam cools which may result in residual tension 224 in the areas of the weld; as this takes longer to cool and compression in sections further away from the 225 welded region may occur (Sonck, 2014; Sehwail, 2013). The residual stress pattern shown in Figure 5 was 226 based on the findings reported by Snock (2014) for cellular beams where the web of the beam is subjected 227 to tensile stresses. The flange has both tension and compression stresses similar to those presented by 228 Tebedge (1973).

229

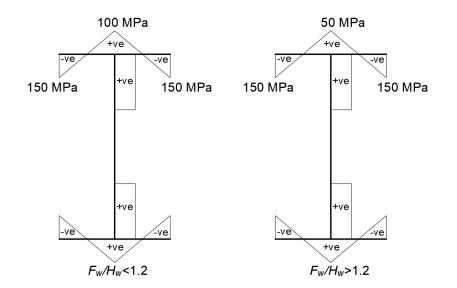


Figure 5: Residual stress pattern employed

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233 2.8 Inelastic Analysis (Static Riks Method)

The static Riks method has the ability to keep the beam in equilibrium at every load increment during unstable phases of the analysis. Therefore, the analyses do not terminate at maximum LPF and then go into a snap-through response as the beam's geometry changes which yields a lower LPF in the parametric study. Due to no stopping criterion at maximum LPF in ABAQUS, the arc-length increment was specified for each of the 405 models in the Python script to allow for the termination of the analyses before the onset of

- the snap-through response. This was done by monitoring 405\*3 = (1215) simulations.
- 240
- 241 2.9 Application of Geometric Imperfections and Residual Stresses

The initial geometric imperforation was introduced by using the perturbation in the geometry generated from the elastic buckling analysis by applying a scale factor (local and global imperfection). Following the introduction of the initial stresses, a general static step was required to allow the beam to regain its equilibrium before the load step. The static Riks step was then introduced to continue the analysis into the nonlinear response.

- 247
- 248 *2.10 LPF Output*

To establish LPF as a variable, it was required to request all displacement history output for a particular node in the model. The location of the node selected in the model is insignificant as LPF output variable is for the entire model response, therefore, in the Python script, a 'gather' and 'output' command was used to extract the LPF for a specific increment at maximum LPF.

253

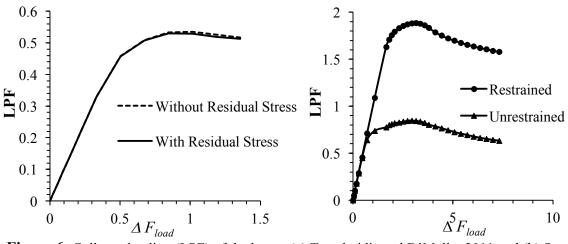
### 254 **3.** FE Validation Study

255 The FE models were validated employing two experimental models found in the literature (Tsavdaridis and

- 256 D'Mello, 2011; Surtees and Liu, 1995), including the response of a short beam to local web-post buckling
- failure and a longer beam to capture the global response with the combination of web distortional buckling.

258 Both validations were considered satisfactory with results within 3% of the load capacity recorded by the 259 experiment. In Figure 5.a, the collapse load ( $P_{CL}$ ) computed was 0.52 \* 572,009N (e.g., Eigen-mode 1, 260 elastic buckle load 572,009N) = 297kN and the experimental results is 288.7kN in Tsavdaridis and D'Mello 261 (2011) for a 1.7m length beam. For a longer restrained/braced beam, the experiment  $P_{CL}$  by Surtees and Liu 262 (1995) is 188.5kN and in Figure 5.b the LPF is 1.87 (e.g., 1.87\*100,000N is 187kN). Therefore, it is safe 263 to conclude that the Methodology adopted provides accurate results. For more information, please refer to 264 Tsavdaridis and D'Mello (2011).

265



266 Figure 6: Collapse loading (LPF) of the beam. (a) Tsavdaridis and D'Mello, 2011 and (b) Surtees and 267 268

Liu, 1995

#### 269 4. Results and Discussion

#### 270 4.1 FEA and SCI P355 Results

271 Figure 7 demonstrates that the SCI P355 analytical method produced conservative load-carrying capacities 272 as compared to that of the FEA models. It is also noticeable that the differences between the two 273 computational methods do not produce a similar percentage of variance (pattern) in the load-carrying 274 capacity for the 8 selected beams, while the inelastic results are compared very well with the SCI P355 275 calculation. For example, beam 'A11' and beam 'A25' has a percentage variance of 6% and 45%, 276 respectively. Beam 'A11' shows that the SCI P355 overestimated the capacity because the end distance from 277 the last opening to the edge of the beam was not incorporated in the SCI design calculations. On the 278 contrary, the narrow end distance which governed the analysis in FEA. In another case, beam 'A25', where 279 the end distance is larger, SCI P355 method resulted in a very conservative low load as compared to the 280 FEA, while the web-post buckling would always govern the design using the SCI P355 for beams with 281 slender web-posts (i.e., closely spaced web openings). Therefore, for slender WP, web buckling will always 282 govern the design in SCI P355. As for the FEAs, the end distance parameter governs the design for widely 283 spaced web openings. It is worth to note that SCI P355 does not consider  $L_{Ed}$  but recommends  $\geq 0.5D_o$ . 284

285 It should be noted, that the simple strut approach model adopted in SCI P355 underestimates the true 286 capacity of the web-post for slender wed-post (e.g.,  $D_0/3.45$  to  $D_0/10$ ) and a revision is necessary to improve

287 the accuracy. However, SCI P355 provides accurate results for widely spaced openings (e.g., web-post >

- 288  $D_0/3.45$ ) as the Vierendeel bending approach adopted is suitable to estimate the shear across the opening.
- 289

- 290
- 291

 Table 5 - Independent variable combination for SCI P355 design comparison

Ref #	<i>L</i> (mm)	$T_w$ (mm)	$T_f(\mathbf{mm})$	$F_{w}$ (mm)	$H_w$ (mm)	$D_o(\mathrm{mm})$	WP (mm)
A10					560	448	45 *
A11					560	448	130 **
A16					560	329	33 *
A17	4000	9	15	160	560	329	95 **
A19	4000	4000 9 15 162	102	420	336	34 *	
A20				420	336	97 **	
A25						420	247
A26					420	247	72**

293

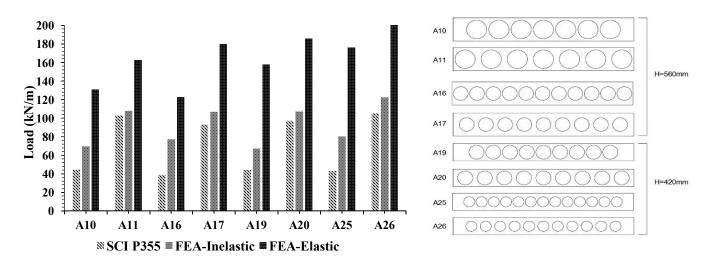
294 \* =  $0.1d_o$ 

295 **\*\*** =  $0.3 d_o$ 

296

Figure 7 includes the elastic buckling load ( $\gamma_{cr}$ ) is considerably high which concludes that the  $\gamma_{cr}$  should be used with caution as imperfection and initial stresses are always present. The  $\gamma_{cr}$  seems to be in the region of approximately 45% more than the nonlinear buckling load.







302

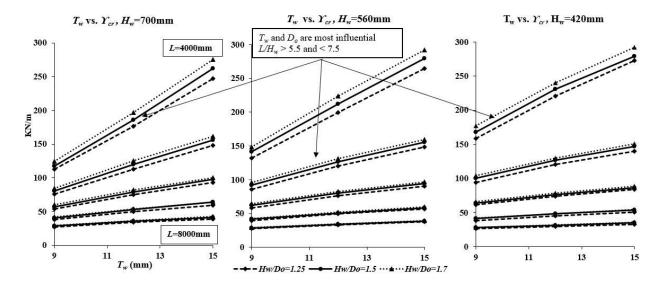
**Figure 7:** SCI P355, inelastic and elastic buckling load comparison, L = 4m

303

304 *4.2 Results of Elastic Analyses* 

This section contains an analysis of the relationships of the effects of the independent variables on the dependent out variable ( $\gamma_{cr}$ ). The graphs were analysed with respect to the  $T_w$  and  $D_o$  as a function of the  $H_w$ . Figure 8 demonstrates the effects of the length (*L*) and  $H_w$  with the constant parameters Do/WP = 10,  $F_w = 162$ mm and  $T_f = 15$ mm.

- 309 In Figure 8, the  $H_w$  is an insignificant parameter since the first buckling mode corresponded to a lateral 310 buckling and therefore the  $F_w$  is a critical parameter to restraint the lateral movement. The effects of  $D_o$
- 311 (e.g.,  $H_w/D_o = 1.25$  to 1.7) and the effects of  $T_w$  (e.g., 9mm to 15mm) are as follow:
- 312  $5.5 \ge L/H_w \le 7.5$ ,  $D_o$  effects are approximately 10.5% and  $T_w$  increases the  $\Upsilon_{cr}$  by about 98%.
- 313  $7.5 \ge L/H_w \le 10.5$ ,  $D_o$  effects are approximately 7.5% and  $T_w$  increases the  $\Upsilon_{cr}$  by about 62%.
- 314  $10.5 \ge L/H_w \le 13.5$ ,  $D_o$  effects are approximately 7.0% and  $T_w$  increases the  $\Upsilon_{cr}$  by about 45%.
- 315  $13.5 \ge L/H_w \le 19$ ,  $D_o$  effects are approximately 6.5% and  $T_w$  increases the  $\Upsilon_{cr}$  by about 30%.



**Figure 8:** Effects of  $H_w$  on the elastic load  $(\Upsilon_{cr})$  with respect to varying  $T_w$  and L: 4m to 8m

In Figure 9, the  $F_w$  was increased from 162mm to 270mm. The change in  $F_w$  positively impacted the  $\gamma_{cr}$  as lateral movement is restricted and the gradient of the plot increased greatly with the change in  $T_w$  (e.g., 15mm to 25mm). The following was concluded:

322 -  $5.5 \ge L/H_w \le 7.5$ ,  $D_o$  effects are approximately 14% and  $T_w$  increases the  $\Upsilon_{cr}$  by about 150%. 323 -  $7.5 \ge L/H_w \le 10.5$ ,  $D_o$  effects are approximately 11.5% and  $T_w$  increases the  $\Upsilon_{cr}$  by about 140%. 324 -  $10.5 \ge L/H_w \le 13.5$ ,  $D_o$  effects are approximately 8.5% and  $T_w$  increases the  $\Upsilon_{cr}$  by about 110%. 325 -  $13.5 \ge L/H_w \le 19$ ,  $D_o$  effects are approximately 5.5% and  $T_w$  increases the  $\Upsilon_{cr}$  by about 45%.

Comparing Figures 8 and 9 by increasing the  $F_w$  for critical members (e.g.,  $5.5 \ge L/H_w \le 7.5$ ) the load increased is in the region of 85% and for slightly less slender members (e.g.,  $7.5 \ge L/H_w \le 10.5$ ) the  $F_w$ effects has increases to 135%.

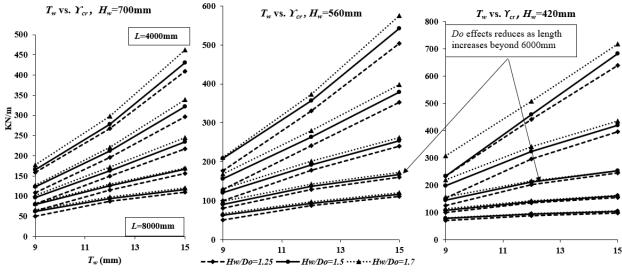




Figure 9: Effects of increasing the  $F_w$  from 162mm to 270mm from Figure 7

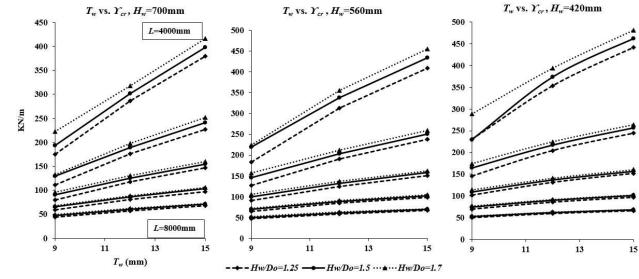
Figure 10 compared the effects of varying  $T_f$  from 15mm to 25mm. The following was concluded:

- 332  $5.5 \ge L/H_w \le 7.5$ ,  $D_o$  effects are approximately 10.5% and  $T_w$  increases the  $\Upsilon_{cr}$  by about 93%.
- $7.5 \ge L/H_w \le 10.5$ ,  $D_o$  effects are approximately 7.0% and  $T_w$  increases the  $\Upsilon_{cr}$  by about 72%.

-  $10.5 \ge L/H_w \le 13.5$ ,  $D_o$  effects are approximately 5.1% and  $T_w$  increases the  $\Upsilon_{cr}$  by about 49%.

-  $13.5 \ge L/H_w \le 19$ ,  $D_o$  effects are approximately 4.0% and  $T_w$  increases the  $\Upsilon_{cr}$  by about 35%.

Comparing Figures 8 and 10 by increasing the  $T_f$  for critical members (e.g.,  $5.5 \ge L/H_w \le 7.5$ ) the load increased is in the region of 53% and for slightly more flexible slender members (e.g.,  $7.5 \ge L/H_w \le 10.5$ ) the  $T_f$  effects has increases to 62.3%.





**Figure 10:** Effects of varying the *T<sub>i</sub>*.15mm to 25mm from Figure 7

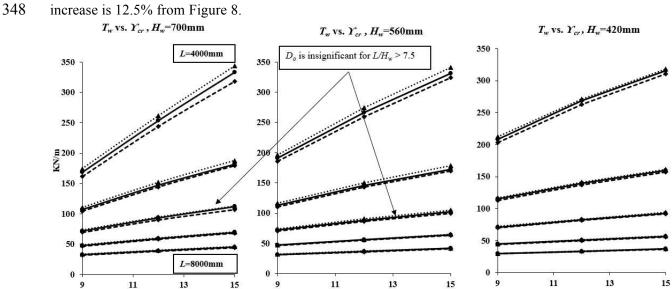
Figure 11 considers the effects of the web-post width from  $D_o/10$  to  $D_o/2.04$ . The change in the  $D_o$  parameter had little effect on the  $\gamma_{cr}$  for wider *WP*. The results are outlined as follow:

- 343  $5.5 \ge L/H_w \le 7.5$ ,  $D_o$  effects are approximately 6% and  $T_w$  increases the  $\Upsilon_{cr}$  by about 78%.
- $7.5 \ge L/H_w \le 10.5$ ,  $D_o$  effects are approximately 2.75% and  $T_w$  increases the  $\Upsilon_{cr}$  by about 37.5%.

Figure 11 shows that for  $L/H_w > 10.5$ , the other parameters (e.g., *Do*,  $H_w$ ,  $T_w$ ) had a minimum effect on the

346  $\Upsilon_{cr}$ . Based on Figures 8 and 11, increasing the  $WP = H_w/2.04$  for critical members (e.g.,  $5.5 \ge L/H_w \le 7.5$ )

the load increased is in the region of 20.5% and for slightly more flexible members  $7.5 \ge L/H_w \le 10.5$  the





**Figure 11:** Effects of varying Web-post width:  $D_o/10$  to  $D_o/2.4$  from Figure 7

Hw/Do=1.5 ····

·Hw/Do=1.7

#### 351 *4.3 Results of Inelastic Analyses*

 $T_w$  (mm)

Inelastic results were analysed similar to Figures 8 to 11, however, the inelastic data were only analysed for L=5m (e.g.,  $L/H_w=7.15$  to 12) as it was observed for flexible members (e.g.,  $L/H_w>12$ ) the effects of the other parameters become insignificantly. In addition, the effect of the length is already known from Chung et al. (2003) and Tsavdaridis (2010). The constant variables used for the inelastic analyses are  $F_y$ : 355MPa,  $T_f$ : 15mm,  $F_w$ : 162mm,  $\delta_a$ : 2.1mm,  $\delta_{LI}$ : 0.268441mm,  $D_o/WP$ :10,  $\varepsilon_y$ : 0.001775 and  $\varepsilon_f$ : 0.126175.

Hw/Do=1.25

357 In Figure 12, the three graphical responses demonstrate the effects of  $T_w$  is the most critical parameter as it

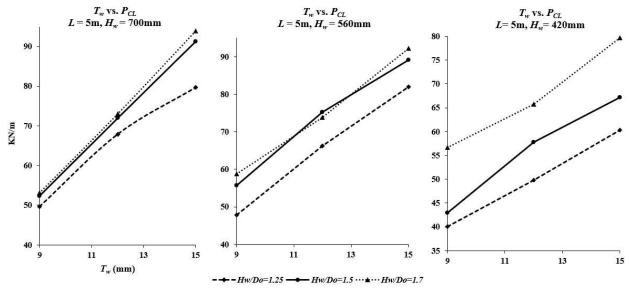
358 controls the web behaviour even when the opening diameter varies. The change in  $T_w$  from 9mm to 15mm

impacted the inelastic collapse load ( $P_{CL}$ ) as  $L/H_w$ : 7.15, the load increased by 71.9%,  $L/H_w$ : 8.9 (60%) and  $L/H_w$ : 11.9 (56.5%). The average increase per 1mm change in  $T_w$  is approximately 10.5% in  $P_{CL}$ . The effects

 $L/H_{W}$ . 11.9 (50.5%). The average increase per trinin change in  $T_{W}$  is approximately 10.5% in  $F_{CL}$ . The effects

of  $D_o$  (e.g.,  $H_w/Do$ : 1.25 to 1.7) are in the region of 20% which is fairly significant when compared to Figure 8.

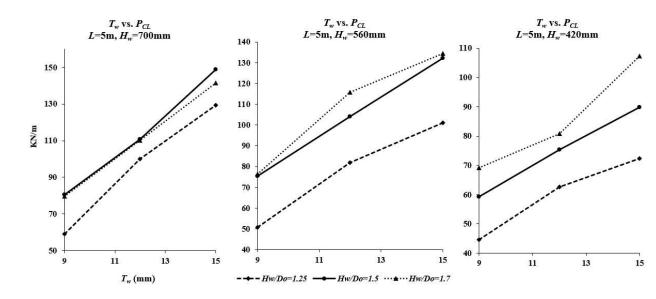
362363





**Figure 12:** Effects of the  $H_w$  on the inelastic load ( $P_{CL}$ ) with respect to varying  $T_w$ 

Figure 13 utilised the parameters as Figure 12 however, in this case, the  $F_w$  was increased from 162mm to 270mm. The change in the  $F_w$  significantly increase the load capacity since first buckling mode experienced a lateral buckling movement of the compression flange therefore with a wider  $F_w$ , the  $\delta_g$  scale in Figure 4 has a lesser impact on the  $P_{CL}$ . As such, the effects of  $T_w$  for  $L/H_w = 7.15$ , load increased by 87.1%,  $L/H_w =$ 8.9 (76.1%) and  $L/H_w = 11.9$  (51.5%). The average increase per 1.0 mm change in  $T_w$  is approximately 12% in  $P_{CL}$  which is similar to Figure 12. The effects of  $D_o$  (e.g.,  $H_w/D_o$ : 1.25 to 1.7) is in the region of 31.9% as such the effects of the  $D_o$  increase with the changing in  $F_w$ .



373374

**Figure 13:** Effects of the  $F_w$ : increased from 162mm (as in Figure 12) to 270mm

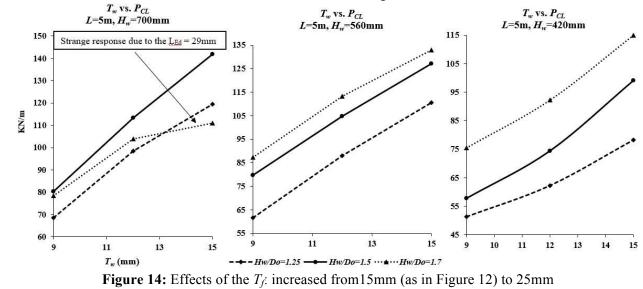
Figure 14 considered the effects of  $T_f$  from 15mm to 25mm. The effects seem to have a similar response to increasing the  $F_w$  (e.g., 162mm to 270mm). The change in  $T_w$  for  $L/H_w = 7.15$ , increased  $P_{CL}$  by 79.5%,

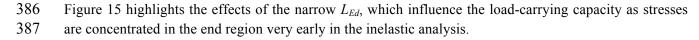
approximately 12% in  $P_{CL}$  which is similar to Figures 11 and 12. The effects of D<sub>o</sub> (e.g.,  $H_w/Do$ : 1.25 to 

- 1.7) is in the region of 33.6% (similar to Figure 12).

The first graph in Figure 14 ( $H_w$ =700mm) shows a strange response when  $H_w/D_o$ =1.7. This is because the

- end distance  $(L_{Ed})$  was only 29mm. The  $L_{Ed}$  could not be analysed by these basic graphs as each beam had
- a different end distance resulted from the aforementioned design limitations.





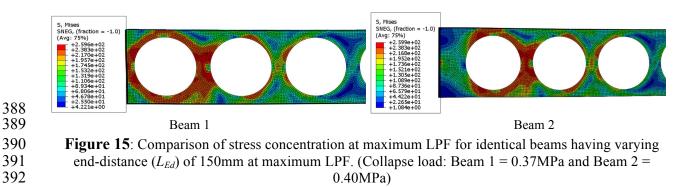
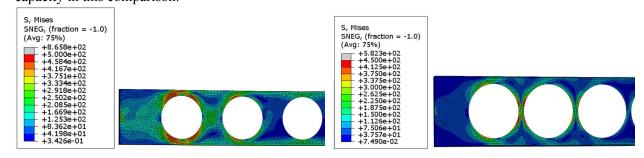


Figure 16 highlights the von-mises stresses concentration for varying the wed-post width (e.g., from  $D_o/10$ to  $D_0/2.04$ ) for a similar span and section height. The end distance ( $L_{Ed}$ ) does not influence the load carrying capacity in this comparison.

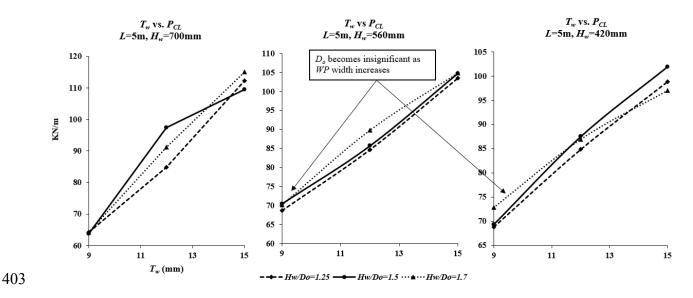


**Figure 16**: Comparison of stress concentration at maximum LPF for similar beams with varying web-post width. (e.g.,  $D_o/10$  to  $D_o/2.04$ )

399

400 Figure 17 depicts the effects of the WP (e.g.,  $D_o/10$  to Do/2.04). The change in T<sub>w</sub> for  $L/H_w = 7.15$ , load

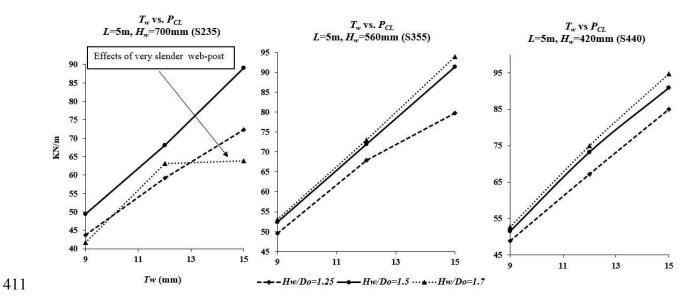
- 401 increased by 77.3%,  $L/H_w = 8.9$  (49.3%) and  $L/H_w = 11.9$  (33.2%). The effects of increasing the WP to
- 402  $D_o/2.04$  resulted in a  $P_{CL}$  increase of approximately 17.5% when compared to Figure 12.





**Figure 17**: Effects of the Web-post width from  $D_o/10$  (as in Figure 12) to  $D_o/2$ 

Figure 18 displays the effects of varying steel strength class from *S235* to *S440* and the variation results in a significant effect on sections that utilised a larger  $D_o$  as the effects were in the region of 17%. However, for a mid-range opening diameter ( $H_w/D_o=1.5$ ), the effect was approximately 5%. The first graph in Figure 18 (*S235* and  $H_w/D_o=1.7$ ), demonstrates that the beam collapses at a lower load although the  $D_o$  is smaller compared to the other plots. This particular beam experienced WP buckling (*WP*=41mm, refer to Table 2) and stresses at the end *WP* ( $L_{Ed}=29$ mm) very early in the analysis.



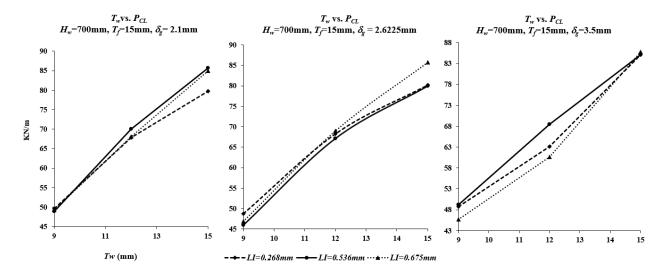
**Figure 18:** Effects on the steel strength class from *S235* (as in Figure 12) to *S440* 

413 Figure 19 represents the effects of the initial geometrical imperfection. The graphs depict the localised and

414 global imperfection response on the  $P_{CL}$  with varying  $T_w$ . The effects of the initial imperfection in most 415 cases were less than 5%. Localised web imperfections, however, seemed to have a slightly higher impact

416 d 1 d d 1 l 1 l 1 d d

416 on the beam response than the global imperfections.





412

**Figure 19:** Effects of the variation of the geometrical imperfection ( $\delta_g$  and  $\delta_{LI}$ )

#### 419 5. Global Stepwise Regression (GSR)

Global stepwise regression (GSR) analysis has the potential of producing statistical models to develop a relationship from a dataset of independent variables to dependent output variables. The process of GSR is iterative by selecting the best independent variables to represent the regression model (Campbell, 2013). Therefore, the combination of independent variables that best correlate to the dependent output variable is identified sequentially by simplifying either adding, deleting or depending on the method to identify which variable has the greatest impact.

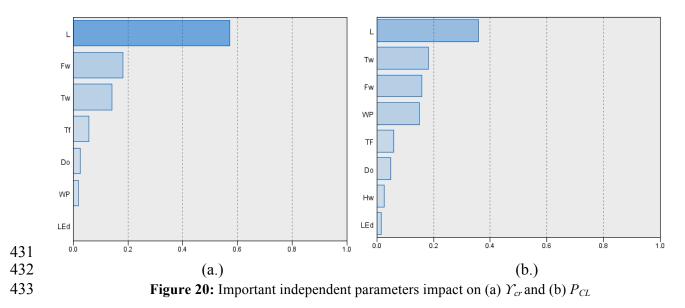
426

427 Figure 20 highlights the global impact of each parameter on the  $\gamma_{cr}$  and  $P_{CL}$ . In Figure 20a, the influences

428 are L: 57.32%,  $F_w$ : 18.1%,  $T_w$ : 14.25%,  $T_f$ : 5.64%,  $D_o$ : 2.58% and  $L_{Ed}$ : 0.06%. In Figure 20b, the influences

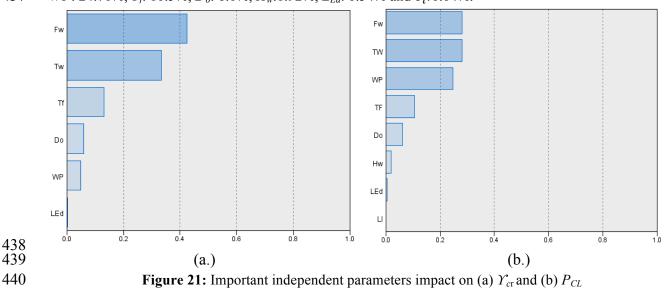
429 are L: 35.92%,  $T_w$ : 18.29%,  $F_w$ : 15.86%, WP: 14.93%,  $T_f$ : 5.96%,  $D_o$ : 4.98%,  $H_w$ : 2.59% and  $L_{Ed}$ : 1.47%.

430



434 Figure 21 considers a fixed length of beam to study the influences of each individual parameters globally.

435 The effects of the parameters in Figure 21a for  $\Upsilon_{cr}$  shows that  $F_w$ : 42.38%,  $T_w$ : 33.37,  $T_f$ : 13.21,  $D_o$ : 5.98%, 436 WP: 4.86% and  $L_{Ed}$ : 0.19%. Similarly, in Figure 21.b shows the effects of  $P_{CL}$  are  $F_w$ : 28.18%,  $T_w$ : 28.01%, 437 WP: 24.71%,  $T_f$ : 10.5%,  $D_o$ : 6.1%,  $H_w$ :1.92%,  $L_{Ed}$ : 0.54% and  $\delta_1$ :0.04%.





442 To summarise, when  $D_o$  changes from  $H_w/1.25$  to  $H_w/1.7$  the  $\Upsilon_{cr}$  increased by approximately 10.5% for 443 critical members (5.5  $\ge$  L/H<sub>w</sub>  $\le$  7.5). Similarly, increasing the WP width from D<sub>o</sub>/10 to D<sub>o</sub>/2.04 resulted in 444 an increase in the  $\gamma_{cr}$  by approximately 20.5% and the effect of the  $D_o$  becomes trivial. In collapse analysis, 445 when  $D_{\rho}$  changes from  $H_{W}/1.25$  to  $H_{W}/1.7$  resulted in an increase in the  $P_{CL}$  by approximately 20%. Also, 446 changing the web-post width from  $D_o/10$  to  $D_o/2.04$  resulted in an increase in the  $P_{CL}$  by approximately 447 17.5% for slender sections (e.g.,  $L/H_w = 7.15$  to 9.0). The influence of the load-carrying capacity due to the 448 initial conditions was observed to be lower than 5% for any geometrical imperfection. The influence of the 449 steel yield strength (from S235 to S440) was approximately 17% but only for the larger diameter 450  $(D_o = H_w/1.25)$  of web openings or when  $WP = D_o/10$ . For any other cases, the influence of the steel yield 451 strength was insignificant.

452

453 In addition, the GSR study demonstrated that  $\Upsilon_{\rm cr}$  is insensitive ( $\approx 5\%$ ) to a varying perforation geometry 454 but sensitive to the flange ( $F_w$  and  $T_f$ ) and  $T_w$  geometry. However, for the collapse analysis, WP influences 455 the  $P_{CL}$  greatly at 24.7%. This analysis concludes that the consideration of alternative web opening shapes 456 is possible, without compromising the capacity of the steel perforated beams and similar performances are 457 anticipated overall. Consequently, the work of various researchers on perforated beams with non-standard 458 web opening configurations should be considered for the Eurocode 3 compliance without the need for 459 drastic updates. Similarly, the coherent mass data results generated in this paper can be used to derive 460 sophisticated closed-form solutions. For example, the data has been already used to develop an artificial 461 neural network-based formula (Abambres et al., 2018).

462

## 463 7. Conclusions

From this comprehensive FE investigation, it was concluded that the most critical parameter for both global elastic and inelastic analyses of cellular beams is the web thickness. Since the beams were not laterally restraint, the first buckling mode is a result of the lateral movement of the compression flange, and consequently, both the  $T_f$  and  $F_w$  had significant impact on the beam response.

468

469 A comparison study was also established between the SCI P355 analytical method and the mass FE data,

- 470 which demonstrated the level of conservatism of the former. It is also noticeable that the elastic and inelastic
- FE results are not fluctuating together, with the inelastic analyses comparing very well with the SCI P355
- 472 calculation which suggests that cellular beams are vastly behaving inelastically, thus design approaches
- 473 using elastic design should be abandoned.
- 474

### 475 Notation

- 476 The following symbols are used in this paper:
- 477 *D*<sub>o</sub>: Perforation diameter
- 478 *E*: Modulus of Elasticity
- 479  $E_t$ : Tangential Modulus
- 480  $\varepsilon_{y}$ : Initial strain of steel
- 481  $\varepsilon_{f}$ : Final yield strain of steel
- 482  $f_{\mu}$ : Ultimate Stress
- 483  $f_y$ : Yield stress of steel
- 484  $F_w$ : Width of flange
- 485  $\delta_G$ : Global geometric imperfection
- 486 *H*: Total depth of the member
- 487  $H_w$ : Height of web (centre of web to web)
- 488 *L*: Length of beams
- 489  $L_{Ed}$ : End web-post distance (end perforation to support)
- 490  $\delta_{LI}$ : Local geometric imperfection
- 491  $M_R = M_L$ : local moment at the perforation
- 492  $M_h$ : Local moment at the web-post
- 493  $\sigma_R$ : Residual stresses

- 494  $P_{CL}$ : Inelastic collaspe load
- 495  $S_o$ : Center to center of openings.
- 496  $T_f$ : Flange thickness
- 497  $T_w$ : Web thickness
- 498  $\gamma$ : Material proof stresses of 0.1% and 0.2% in imperfection
- 499  $\Upsilon_{cr}$ : elastic bucle load (N/mm)
- 500  $V_L = V_R$ : Local shear force at the perforation
- 501  $V_t = V_b$ : Local shear force at the top and botoom tee-section.
- 502  $V_h$ : Local hpzontal shear force at the web-post
- 503 WP: Width of Web post
- 504 UX, UZ, UY: movement in different plane in model space (Figure 3) UZ: perpendicular to web, UX: along
- 505 beam and *UY*: perendicular to flange.
- 506  $\Delta F_{load}$ : incremental load
- 507

# 508 Data Availability

- 509 Both datasets are available at <u>https://osf.io/5jxut/</u>
- 510 For Python scripting contact with corresponding author of the paper at <u>k.tsavdaridis@leeds.ac.uk</u>
- 511

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