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## **Value of Information Analytical Methods: Report 2 of the ISPOR Value of Information Analysis Emerging Good Practices Task Force**

### **Authors**

Claire Rothery, PhD\*

Senior Research Fellow, Centre for Health Economics, University of York, York, UK.

Mark Strong, PhD.

Professor of Public Health, School of Health and Related Research, University of Sheffield, Sheffield, UK.

Hendrik (Erik) Koffijberg, PhD.

Associate Professor of Health Economics, Department of Health Technology & Services Research, Technical Medical Centre, University of Twente, Enschede, The Netherlands.

Anirban Basu, PhD.

Professor & Director, The Comparative Health Outcomes, Policy, and Economics Institute, School of Pharmacy, University of Washington, Seattle, Washington, DC, USA.

Salah Ghabri, PhD.

Health Economist/Scientific Project Coordinator, French National Authority for Health, Paris, France.

Saskia Knies, PhD.

Senior Advisor Pharmacoeconomics, National Health Care Institute (Zorginstituut Nederland), Diemen, the Netherlands.

James F. Murray, PhD.

Research Fellow, Global Patient Outcomes and Real World Evidence, Eli Lilly and Company, Indianapolis, IN, USA.

Gillian D Sanders Schmidler, PhD.

Deputy Director, Academics and Professor of Population Health Sciences, Duke-Margolis Center for Health Policy, Duke Clinical Research Institute and Department of Population Health Sciences, Duke University, Durham, NC, USA.

Lotte Steuten, PhD.

Vice President, Head of Consulting, Office of Health Economics, London, UK.

Elisabeth Fenwick, PhD.

Senior Director, Pharmerit International, Oxford, UK.

**\*Corresponding author**

Claire Rothery, PhD.  
Centre for Health Economics  
Alcuin A Block  
University of York  
Heslington, York  
YO10 5DD, UK  
claire.rothery@york.ac.uk

**Precis:** This report provides practical guidance on the methods and reporting of VOI analysis for assessing the value of research to inform decisions in different contexts.

**Highlights:**

- Value of Information (VOI) analysis provides a framework for quantifying the value of acquiring additional information to reduce uncertainty in decision-making. Quantifying the expected improvement with new information requires an assessment of the scale and consequences of uncertainty in terms of pay-offs. Acquiring information, however, can be costly. Therefore, the value of new information is compared to the cost of acquiring the information to determine whether it is worthwhile.
- This report provides practical guidance on the methods and reporting of VOI analysis. The methods are presented in generic form to allow them to be adapted to any specific decision making context. This means that even in health care systems where economic considerations are not explicitly incorporated into decision making, the same methods can be applied.
- This report provides eight recommendations for good practice when planning, undertaking or reviewing VOI analyses. The primary audience for the report are methodologists and/or analysts who are responsible for undertaking VOI analysis to inform decision-making.

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# 1 **Abstract**

2 The allocation of health care resources among competing priorities requires an assessment  
3 of the expected costs and health effects of investing resources in the activities, and on the  
4 opportunity cost of the expenditure. To date, much effort has been devoted to assessing the  
5 expected costs and health effects, but there remains an important need to also reflect the con-  
6 sequences of uncertainty in resource allocation decisions and the value of further research to  
7 reduce uncertainty. Decision-making with uncertainty may turn out to be suboptimal, resulting  
8 in health loss. Consequently, there may be value in reducing uncertainty, through the collec-  
9 tion of new evidence, to better inform resource decisions. This value can be quantified using  
10 Value of Information (VOI) analysis. This report, from the ISPOR VOI Task Force, describes  
11 methods for computing four VOI measures: the Expected Value of Perfect Information (EVPI),  
12 Expected Value of Partial Perfect Information (EVPPI), Expected Value of Sample Information  
13 (EVSI) and Expected Net Benefit of Sampling (ENBS). Several methods exist for computing  
14 EVPPI and EVSI, and this report provides guidance on selecting the most appropriate method  
15 based on the features of the decision problem. The report provides a number of recommenda-  
16 tions for good practice when planning, undertaking or reviewing VOI analyses. The software  
17 needed to compute VOI is discussed, and areas for future research are highlighted.

18 **Keywords:** value of information, value of research, decision making, study design, EVPI,  
19 EVPPI, EVSI, ENBS.

20 **Running title:** Value of Information Analytical Methods.

### **Box 1: Background on the Task Force Process**

The proposal to initiate an ISPOR Value of Information Good Practices Task Force was evaluated by the ISPOR Health Science Policy Council and then recommended to the ISPOR Board of Directors for approval. The task force was comprised of international subject matter experts representing a diverse range of stakeholder perspectives (academia, research organizations, government, regulatory agencies and commercial entities). The task force met approximately every five weeks by teleconference and in person at ISPOR conferences. All task force members reviewed many drafts of the report and provided frequent feedback in both oral and written comments. To ensure that ISPOR Good Practices Task Force Reports are consensus reports, findings and recommendations are presented and discussed at ISPOR conferences. In addition, the first and final draft reports are circulated to the task force's review group for a formal review. All reviewer comments are considered. Comments are addressed as appropriate in subsequent versions of the report. Most are substantive and constructive at improving the report.

21

## **Introduction**

22

Health care resource allocation decisions are made with uncertainty. Decision-makers, tasked with selecting among competing alternative options, need to determine the pay-offs associated with each option before making a choice, but these pay-offs are based on imperfect knowledge. This inevitably means that decisions based on the available information may turn out to be suboptimal. Suboptimal decisions can lead to unintended effects such as adverse health consequences to individuals, when expected benefits of an activity are not realized, and to the population, when the resources committed to the activity are transferred away from other activities. Acquiring more information could reduce uncertainty and the associated consequences of suboptimal decision-making.

23

Value of Information (VOI) analysis provides a framework for quantifying the value of acquiring additional information to reduce uncertainty in decision-making. Quantifying the expected improvement with new information requires an assessment of uncertainty and the scale of the consequences of that uncertainty in terms of pay-offs. Acquiring information, however, can be costly. Therefore, the value of new information is compared to the cost of acquiring the information to determine whether it is worthwhile.

24

This report is the second report of the ISPOR Value of Information Analysis Emerging Good Practices Task Force. It provides details of the various methods used to assess the value of research, as well as practical guidance for selecting the appropriate method for the decision problem of interest. These methods are presented in generic form to allow them to be adapted to any specific decision making context. The primary audience for this report are

25

43 methodologists and/or analysts who are responsible for undertaking VOI analysis to inform  
44 decision-making. It compliments the first report of the ISPOR VOI Task Force [1], which in-  
45 troduced the concept of VOI analysis, outlined the role of VOI for supporting different types of  
46 research decisions, and provided an overview of the steps for conducting and reporting VOI  
47 analysis.

## 48 **Characterization of uncertainty**

49 The outcomes of VOI analysis are always conditional on the characterization of the decision  
50 problem and the specification of judgements about the relevant uncertainties. This means that  
51 the extent to which VOI analysis is sufficient to quantify the value of further research depends  
52 critically on how well the uncertainties have been characterized. With this in mind, this report  
53 first characterizes the sources of uncertainty.

54 The starting point for VOI analysis is typically a decision-analytic model that represents judge-  
55 ments about the relationship between *outputs* that are relevant for decision making (e.g., costs  
56 and health outcomes) and *input parameters* derived from clinical, epidemiological, registry,  
57 and/or economic studies. Uncertainty in decision-analytic models can be broadly character-  
58 ized as relating to either model input *parameters* or model *structure*; although this distinction  
59 is not always meaningful since model structural choices can be parametrized.

### 60 *Parameter uncertainty*

61 Decision-analytic models typically use information from a variety of sources, such as random-  
62 ized controlled trials (RCTs), observational studies, registries or expert opinion. Model input  
63 parameters usually correspond to unknown ‘population’ quantities, and finite-sized studies pro-  
64 vide imprecise estimates of these quantities. Uncertainty about the ‘true’ population parameter  
65 values is represented by probability distributions [2].

66 Probability distributions should be assigned to all uncertain parameters (including those with  
67 little or no information from which to estimate the parameter), otherwise the parameter value  
68 is assumed to be known with certainty. When a model has more than one input parameter,  
69 careful consideration should be given to any dependencies between parameter values. If  
70 parameters are dependent, then judgements about the values of those parameters should be  
71 represented via a joint, correlated probability distribution. Guidelines exist to aid the selection  
72 of distributions for parameters [3].

73 Statistical and methodological choices can also introduce uncertainty about parameter values  
74 when it is not clear which choice of method or statistical distribution is preferred. For exam-  
75 ple, choices made regarding methods used to synthesize data from multiple sources, type of  
76 survival distribution for extrapolation of study data, or weighting scheme used for pooling opin-

77 ions elicited from multiple experts [4, 5]. Uncertainty in parameter values can also arise due  
78 to missing data, poor quality data, and study estimates that are biased or confounded [6–9].  
79 When the most appropriate technique for data analysis or synthesis is unclear and choices  
80 or assumptions are required, the choice of technique should be parametrized and uncertainty  
81 about the choice included in the VOI analysis. Guidelines exist to aid characterization of un-  
82 certainty about methodological choice [10, 11].

### 83 ***Good practice recommendation 1***

84 **Uncertainty in parameter input values should be characterized using probability distri-**  
85 **butions, and any dependency between parameters represented by a joint, correlated**  
86 **probability distribution.**

#### 87 *Structural uncertainty*

88 A model's structure relies on scientific judgements or assumptions about the underlying de-  
89 cision problem. As the model structure, or functional form, is an approximation of real world  
90 processes and relationships, the choice of model structure gives rise to *structural uncertainty*  
91 as a result of uncertain model error [2, 12]. Quantifying structural uncertainty is difficult and is  
92 often ignored, which is equivalent to assuming that the model is perfect.

93 Where possible, structural uncertainty should be characterized. Several methods for handling  
94 structural uncertainty have been described in the literature. These include: 1) scenario analy-  
95 sis (reporting of alternative models based on different plausible structural assumptions [13]); 2)  
96 model structure parametrization (adding parameters to the model that define alternative struc-  
97 tural choices [14]); 3) model averaging (weighting the outcomes from a set of plausible models  
98 based on fit to observed data or expert opinion [15, 16]); or 4) model discrepancy analysis  
99 (the direct quantification of uncertainty about the difference between the model evaluated at  
100 its 'true' input values, and the true value of the output quantity, either by calibration to external  
101 data or through expert elicitation [12, 17]).

### 102 ***Good practice recommendation 2***

103 **Clearly describe any important model structural uncertainties. Where possible, struc-**  
104 **tural uncertainty should be quantified and included in the VOI analysis.**

#### 105 *Probabilistic analysis*

106 Once characterized, a complete assessment of uncertainty in all parameters, structural and  
107 analysis techniques is achieved through Monte Carlo probabilistic analysis (referred to as  
108 'Probabilistic Sensitivity Analysis' in the health economics literature). Probabilistic analysis  
109 is used to propagate the impact of uncertainty in model input parameters through to uncer-



110 tainty about model outputs. This involves repeatedly sampling values at random from each of  
111 the parameter input distributions and running the model, using the selected set of values, to  
112 provide a corresponding set of model outcomes of interest for each decision option being eval-  
113 uated. The results of many sampled simulations allows for estimation of the expected (mean)  
114 model outputs for each decision option and the uncertainty around these outputs [3].

### 115 ***Good practice recommendation 3***

116 **Use probabilistic analysis to provide an appropriate quantification of uncertainty in**  
117 **model outputs.**

## 118 **Value of Information analysis**

### 119 *Decision-making with uncertainty*

120 Decision-making with uncertainty involves choosing between alternative decision options based  
121 on imperfect information. In decision theory, a risk-neutral decision-maker would choose be-  
122 tween the alternative options based on the one that maximizes the expected pay-off [18].  
123 However, any decision made with uncertainty creates the potential for adverse consequences  
124 as the expected pay-off of the chosen option may not be realized in practice. Some decision-  
125 makers may be averse to this risk, preferring an option with a small guaranteed pay-off to an  
126 uncertain outcome with a larger expected pay-off [19, 20]. Careful selection of the attitude to  
127 risk that aligns with the decision-maker's perspective is required for VOI analysis [21].

128 In this report, VOI analysis is presented from the perspective of a risk-neutral decision-maker. It  
129 follows that a decision based on *expectation* is used to establish the decision option that offers  
130 maximum expected pay-off based on current knowledge. VOI analysis is used to address the  
131 question of whether further research is needed to reduce the uncertainty in the decision.

### 132 *Key concepts, definitions and notation*

133 VOI starts by assuming that a decision-maker is faced with a set of mutually exclusive decision  
134 options, indexed  $d$  in the decision space  $\mathcal{D}$ . Next, it is assumed that a decision model, denoted  
135  $\mathcal{U}(d, \theta)$ , predicts the utility for decision option  $d$  given  $p$  uncertain parameters  $\theta = \{\theta_1, \dots, \theta_p\}$ .  
136 The uncertainty about the 'true' unknown values of  $\theta$  is represented by the joint probability  
137 distribution,  $\pi(\theta)$ .

138 By specifying the model as a general utility function, the analysis can be tailored to any spe-  
139 cific decision-making context by choosing an appropriate utility metric. In Health Technology  
140 Assessment, where decision options represent alternative treatment interventions, the utility  
141 function is often defined as net health benefit or net monetary benefit.

142 The expected value of learning, with certainty, the ‘true’ values of all model parameters  $\theta$   
 143 (i.e., eliminating *all* parameter uncertainty) is referred to as the Expected Value of Perfect  
 144 Information (EVPI). The EVPI is equivalent to the expected costs of uncertainty associated  
 145 with making the decision based on the current evidence.

146 The expected value of acquiring new information about a *subset* of parameters of interest is  
 147 used to identify the parameters that are important in driving the decision uncertainty. The set  
 148 of parameters of interest is denoted by  $\theta_i$  and the remaining complementary set of parameters  
 149 by  $\theta_c$ , such that together  $\{\theta_i, \theta_c\} = \theta$ . The expected value of learning, with certainty, the  
 150 parameters of interest  $\theta_i$  is the Expected Value of Partial Perfect Information (EVPPI) for  $\theta_i$   
 151 (also known as the Expected Value of Perfect Parameter Information).

152 Perfect information about parameters is usually not achievable with a finite sample size, but it is  
 153 possible to conduct a study to provide some information about the parameters. The expected  
 154 value of a data collection exercise that will result in data  $\mathbf{X}$ , where  $\mathbf{X}$  will be informative for  $\theta_i$  is  
 155 referred to as the Expected Value of Sample Information (EVSI). The EVPPI for  $\theta_i$  is an upper  
 156 limit on the EVSI for any study that is informative about  $\theta_i$ .

#### 157 *Optimum decision option with current knowledge*

158 With current knowledge, the best that a risk-neutral decision-maker can do is to choose the  
 159 decision option that gives the highest expected utility. The utility associated with this option is:

$$\max_{d \in \mathcal{D}} \mathbb{E}_{\theta} \{ \mathcal{U}(d, \theta) \}, \quad (1)$$

160 where  $\mathbb{E}_{\theta}(\cdot)$  represents expectation (mean) taken with respect to  $\pi(\theta)$ .

#### 161 *Expected Value of Perfect Information (EVPI)*

162 If all uncertainty about  $\theta$  could be eliminated with perfect information, the decision-maker would  
 163 know the values of all parameters  $\theta = \theta^*$  with certainty and, therefore, would choose the option  
 164 that maximizes the utility, conditional on knowing  $\theta^*$ . This has utility:

$$\max_{d \in \mathcal{D}} \mathcal{U}(d, \theta^*). \quad (2)$$

165 However, when a decision is made about whether to conduct further research,  $\theta^*$  is not known.  
 166 Therefore, the expected value of a decision when uncertainty is resolved with perfect informa-  
 167 tion is found by averaging the maximized utility over the joint distribution of  $\theta$ . This is the  
 168 expectation of (2), i.e.,

$$\mathbb{E}_{\theta} \{ \max_{d \in \mathcal{D}} \mathcal{U}(d, \theta) \}. \quad (3)$$

169 The EVPI is the difference between the expected value of a decision made with perfect infor-  
 170 mation and the expected value of a decision made with current knowledge, i.e., the difference

171 between (3) and (1),

$$\text{EVPI} = \mathbb{E}_{\theta} \left\{ \max_{d \in \mathcal{D}} \mathcal{U}(d, \theta) \right\} - \max_{d \in \mathcal{D}} \mathbb{E}_{\theta} \left\{ \mathcal{U}(d, \theta) \right\}. \quad (4)$$

172 *Expected Value of Partial Perfect Information (EVPPI)*

173 If all uncertainty about a *subset* of parameters,  $\theta_i$ , could be resolved with perfect information,  
 174 the decision-maker would know the ‘true’ values  $\theta_i = \theta_i^*$  with certainty when choosing be-  
 175 tween the alternative decision options. However, the values of the remaining (complementary)  
 176 parameters  $\theta_c$  remain uncertain. Therefore, the decision option is selected based on the one  
 177 that maximizes expected utility, conditional on the values  $\theta_i^*$ . This has utility:

$$\max_{d \in \mathcal{D}} \mathbb{E}_{\theta_c | \theta_i^*} \left\{ \mathcal{U}(d, \theta_i^*, \theta_c) \right\}, \quad (5)$$

178 where  $\mathbb{E}_{\theta_c | \theta_i^*}(\cdot)$  represents expectation taken with respect to  $\pi(\theta_c | \theta_i^*)$ . When the decision  
 179 about conducting further research to provide information about these parameters is made, the  
 180 values of  $\theta_i^*$  are unknown. Therefore, the expectation of (5) is computed:

$$\mathbb{E}_{\theta_i} \left[ \max_{d \in \mathcal{D}} \mathbb{E}_{\theta_c | \theta_i} \left\{ \mathcal{U}(d, \theta_i, \theta_c) \right\} \right]. \quad (6)$$

181 The EVPPI for  $\theta_i$  is the difference between (6) and (1):

$$\text{EVPPI}(\theta_i) = \mathbb{E}_{\theta_i} \left[ \max_{d \in \mathcal{D}} \mathbb{E}_{\theta_c | \theta_i} \left\{ \mathcal{U}(d, \theta_i, \theta_c) \right\} \right] - \max_{d \in \mathcal{D}} \mathbb{E}_{\theta} \left\{ \mathcal{U}(d, \theta) \right\}. \quad (7)$$

182 EVPI and EVPPI can be multiplied by the size of the beneficiary population to give *population*  
 183 EV(P)PI values. The population EV(P)PI provides an expected upper bound on the value  
 184 of further research that would eliminate uncertainty about all (or subsets of) parameters. A  
 185 population EV(P)PI that is less than the estimated costs of any research study is a sufficient  
 186 condition for establishing that research is not of value. A population EV(P)PI that is greater  
 187 than the estimated cost of the research study is a necessary, but not sufficient, condition for  
 188 establishing that research is potentially of value. In order to establish a sufficient condition for  
 189 further research, the *costs* of conducting the new study must also be considered.

190 *Expected Value of Sample Information (EVS)*

191 In the absence of perfect information, if data  $\mathbf{X}$  were to become available the decision-maker  
 192 would choose the option that maximizes the utility, conditional on knowing  $\mathbf{X}$ . This has utility:

$$\max_{d \in \mathcal{D}} \mathbb{E}_{\theta | \mathbf{X}} \left\{ \mathcal{U}(d, \theta) \right\}. \quad (8)$$

193 However, the data  $\mathbf{X}$  are not collected when the decision to conduct further research is made.  
 194 Therefore, the expected value of a decision taken with sample information is obtained by aver-  
 195 aging the maximized expected utility of (8):

$$\mathbb{E}_{\mathbf{X}} \left[ \max_{d \in \mathcal{D}} \mathbb{E}_{\theta | \mathbf{X}} \left\{ \mathcal{U}(d, \theta) \right\} \right]. \quad (9)$$

196 The EVSI for the data collection exercise that yields  $\mathbf{X}$  is the difference between (9) and (1):

$$\text{EVSI} = \mathbb{E}_{\mathbf{X}} \left[ \max_{d \in \mathcal{D}} \mathbb{E}_{\boldsymbol{\theta}|\mathbf{X}} \{ \mathcal{U}(d, \boldsymbol{\theta}) \} \right] - \max_{d \in \mathcal{D}} \mathbb{E}_{\boldsymbol{\theta}} \{ \mathcal{U}(d, \boldsymbol{\theta}) \}. \quad (10)$$

197 As with EVPI and EVPPI, EVSI can be multiplied by the size of the beneficiary population to  
 198 yield a population EVSI value.

### 199 *Expected Net Benefit of Sampling (ENBS)*

200 The difference between the population EVSI value and the cost of the data collection exercise  
 201 is the Expected Net Benefit of Sampling (ENBS). The ENBS is a measure of the net value  
 202 of any particular study. Under the assumption that the proposed study is relevant only to the  
 203 decision problem at hand and has no wider value, then  $\text{ENBS} \geq 0$  is a necessary condition  
 204 for conducting the study. The ENBS is powerful for guiding choices about study characteris-  
 205 tics such as sample size and length of follow up, with the optimal design being the one that  
 206 maximizes the ENBS [22, 23].

207 The costs of research not only include the costs of the study itself, but also the opportunity  
 208 costs to individuals while the research is underway, e.g., some participants will receive a non-  
 209 optimal intervention during the study [24].

## 210 **Estimation of VOI measures**

### 211 *EVPI Computation*

212 In the simplest case of a two-decision option problem in which the difference in utility be-  
 213 tween options is assumed to be normally distributed, an exact analytic expression for EVPI  
 214 exists [25, 26]. However, for most problems an analytic solution cannot easily be derived, and  
 215 sampling-based methods are required. For models that generate a non-linear relationship be-  
 216 tween inputs and outputs, such as those for which  $\mathbb{E}_{\boldsymbol{\theta}} \{ \mathcal{U}(d, \boldsymbol{\theta}) \} \neq \mathcal{U} \{ d, \mathbb{E}_{\boldsymbol{\theta}}(\boldsymbol{\theta}) \}$ , a *deterministic*  
 217 *analysis*, in which the model is evaluated at the mean values of its parameters, will gener-  
 218 ate an incorrect estimate of expected utility. Monte Carlo probabilistic analysis is used, which  
 219 approximates  $\mathbb{E}_{\boldsymbol{\theta}} \{ \mathcal{U}(d, \boldsymbol{\theta}) \}$  by:

$$\frac{1}{N} \sum_{n=1}^N \mathcal{U}(d, \boldsymbol{\theta}^{(n)}), \quad (11)$$

220 where  $\boldsymbol{\theta}^{(n)}$ ,  $n = 1, \dots, N$  are samples drawn from the joint distribution  $\pi(\boldsymbol{\theta})$ . Monte Carlo sim-  
 221 ulation is also used to approximate the first term in the EVPI expression,  $\mathbb{E}_{\boldsymbol{\theta}} \{ \max_{d \in \mathcal{D}} \mathcal{U}(d, \boldsymbol{\theta}) \}$   
 222 via

$$\frac{1}{N} \sum_{n=1}^N \max_{d \in \mathcal{D}} \mathcal{U}(d, \boldsymbol{\theta}^{(n)}). \quad (12)$$

223 Expression (12) can be computed using the single set of  $N$  samples from  $\pi(\boldsymbol{\theta})$  that are used  
 224 to approximate the baseline expected utility of (11). Therefore, the computation of EVPI is  
 225 a ‘single loop’ Monte Carlo scheme, and does not require additional sampling beyond that  
 226 required for a probabilistic analysis - note that ‘loop’ here calls into mind the for-loop program-  
 227 ming construct that is used to execute repeatedly a set of instructions. Algorithm 1 describes  
 228 the single-loop scheme for computing EVPI.

### Algorithm 1

#### *Single loop Monte Carlo scheme for computing EVPI*

1. Sample a value from the distribution of the uncertain parameters.
2. Evaluate the utility function for each decision option using the parameter values generated in step 1. Store the values.
3. Repeat steps 1 to 2 for  $N$  samples (e.g., 10,000). This is the probabilistic analysis sample.
4. Calculate the expected (mean) utility value of the  $N$  samples for each decision option.
5. Choose the maximum of the expected utility values in step 4 and store. This is the expected utility with current knowledge.
6. Calculate the maximum utility of the decision options for each of the  $N$  samples generated in step 3.
7. Calculate the mean of the  $N$  maximum utilities generated in step 6. This is the expected utility when uncertainty is resolved with perfect information.
8. Calculate the EVPI as the difference between the expected utility when uncertainty is resolved with perfect information (step 7) and the expected utility with current knowledge (step 5).

229

### 230 *EVPI Computation*

231 An analytic solution for EVPI rarely exists and sampling-based methods are required. The  
 232 first term in the EVPI expression (7) contains a nested expectation, which means that the  
 233 Monte Carlo approach requires a nested ‘double-loop’ solution:

$$\mathbb{E}_{\boldsymbol{\theta}_i} \left[ \max_{d \in \mathcal{D}} \mathbb{E}_{\boldsymbol{\theta}_c | \boldsymbol{\theta}_i} \{ \mathcal{U}(d, \boldsymbol{\theta}_i, \boldsymbol{\theta}_c) \} \right] \simeq \frac{1}{K} \sum_{k=1}^K \left[ \max_{d \in \mathcal{D}} \frac{1}{J} \sum_{j=1}^J \{ \mathcal{U}(d, \boldsymbol{\theta}_i^{(k)}, \boldsymbol{\theta}_c^{(j,k)}) \} \right]. \quad (13)$$

234 For the parameters of interest,  $k = 1, \dots, K$  samples,  $\boldsymbol{\theta}_i^{(k)}$ , are drawn from the distribution  
 235  $\pi(\boldsymbol{\theta}_i)$  in the ‘outer loop’ of simulation. An ‘inner loop’ of simulation is then used to sample from  
 236 the complementary parameters, conditional on the value of  $\boldsymbol{\theta}_i^{(k)}$ . For the complementary pa-  
 237 rameters,  $j = 1, \dots, J$  samples,  $\boldsymbol{\theta}_c^{(j,k)}$ , are drawn from the conditional distribution  $\pi(\boldsymbol{\theta}_c | \boldsymbol{\theta}_i^{(k)})$ . If  
 238  $\boldsymbol{\theta}_i$  and  $\boldsymbol{\theta}_c$  are independent, then sampling from the conditional distribution  $\pi(\boldsymbol{\theta}_c | \boldsymbol{\theta}_i^{(k)})$  reduces to  
 239 sampling from the marginal distribution  $\pi(\boldsymbol{\theta}_c)$ . Algorithm 2 describes the double-loop scheme  
 240 for estimating EVPI.

## Algorithm 2

### ***Double-loop Monte Carlo scheme for computing EVPPI***

1. Sample a value from the distribution(s) of the target parameter(s) of interest.
2. Sample a value from the distributions of the remaining ('complementary') uncertain parameters, conditional on the value of the target parameter(s) sampled in step 1. If the target and complementary parameters are independent, the sample for this step can be drawn from the prior distribution of the complementary parameters.
3. Evaluate the utility function for each decision option using the parameter values generated in steps 1 and 2, and store the resulting utility values.
4. While holding the parameter value from step 1 constant, repeat steps 2 and 3 for  $J$  samples. This represents the inner loop of simulation.
5. Calculate the mean of the utility values across all  $J$  samples for each decision option and store.
6. Repeat steps 1 to 5 for  $K$  values from the distribution of the target parameter(s) (step 1) and store the outputs from step 5. This represents the outer loop of simulation.
7. Calculate the mean utility for each decision option across all  $K$  samples of the output loop stored in step 6.
8. Choose the maximum of the mean utilities calculated in step 7 and store. This is the expected utility with current knowledge about the target parameter(s) of interest.
9. Calculate the maximum utility of the decision options (i.e., the maximum of the inner loop means) for each of the  $K$  samples of the output stored in step 6.
10. Calculate the mean of the  $K$  maximum utility values generated in step 9. This yields the expected utility when uncertainty is resolved with perfect information about the target parameter(s) of interest.
11. Calculate the EVPPI as the difference between the expected utility when uncertainty is resolved with perfect information about the parameter(s) of interest (step 10) and the expected utility with current knowledge (step 8).

241

242 Note that the selection of the sample size of the inner loop ( $J$ ) is crucial as double-loop EVPPI  
243 computation can provide biased estimates when the sample size is small [27]. Nested double-  
244 loop sampling schemes can be computationally expensive. One of the key determinations  
245 for reducing the computational burden is whether the model is *linear* or *multilinear* in the  
246 complementary parameters  $\theta_c$ . A model is linear in complementary parameters,  $\theta_{c_1}$  and  $\theta_{c_2}$ , if  
247 it can be written as a sum of these parameters, e.g.,  $\mathcal{U}(\theta) = \theta_{c_1}\theta_{i_1}^2 + \theta_{c_2}\theta_{i_2}$ , where  $\theta_{i_1}$  and  $\theta_{i_2}$   
248 are parameters of interest. A model is multilinear in the complementary parameters if it can be  
249 written in sum-product form of the complementary parameters, e.g.,  $\mathcal{U}(\theta) = \theta_{c_1}\theta_{c_2}\theta_{i_1}^2 + \theta_{c_3}\theta_{i_1}\theta_{i_2}$ .  
250 If these conditions hold (and there is no correlation between the complementary parameters  
251 that are multiplied together), the double loop sampling scheme can be replaced by a single  
252 loop, where the mean values of the complementary parameters are used to avoid the need for  
253 the inner loop of simulation.

254 The general forms of model for which a single-loop approach is justified are described else-  
255 where [28]. Where applicable, single loop methods are to be preferred to reduce Monte Carlo  
256 error [27, 29, 30]. Algorithm 3 describes the single-loop Monte Carlo scheme for estimating  
257 EVPPI.

### **Algorithm 3**

#### ***Single-loop Monte Carlo scheme for computing EVPPI***

1. Sample a value from the distribution of the target parameter(s) of interest.
2. Evaluate the utility function for each decision option using the value for the target parameter(s) from step 1 and the mean values of the remaining uncertain parameters (or functions of them [28]). Store the values.
3. Repeat steps 1 and 2 for  $N$  samples.
4. Calculate the mean of the  $N$  utility values for each decision option.
5. Follow steps 5-8 of the algorithm for computing EVPI (algorithm 1).

258

259 EVPPI can also be computed using a *regression-based* method that uses a non-parametric,  
260 or other flexible regression, method to estimate the inner expectation of expression (6). The  
261 regression-based method only requires the single set of samples that is generated by the  
262 probabilistic analysis. Algorithm 4 describes the single-loop regression-based scheme for es-  
263 timating EVPPI.

### **Algorithm 4**

#### ***Single-loop regression-based scheme for computing EVPPI***

1. Generate the probabilistic analysis sample using steps 1-3 of the algorithm for computing EVPI (algorithm 1).
2. For each of the decision options, regress the estimates of utility on the parameter values of the target parameter(s) of interest.
3. Calculate the regression fitted values for each decision option.
4. Follow steps 5-8 of the algorithm for computing EVPI (algorithm 1).

264

265 A review of alternative methods for computing EVPPI is available elsewhere [31], while Figure  
266 1 of the supplementary appendix provides guidance on the choice of computation method  
267 based on model features.

#### ***Good practice recommendation 4***

269 **When using the nested double-loop method to compute EVPPI, choose inner and outer  
270 loop simulation sizes to ensure acceptable bias and precision.**

#### ***Good practice recommendation 5***

271

272 **When using the single-loop methods to compute EVPPI, check that the underlying as-**  
 273 **sumptions of the method hold.**

#### 274 *EVSI Computation*

275 EVSI can be computed analytically if the difference in utility between decision options is as-  
 276 sumed to be normally distributed, and the proposed data collection exercise is expected to  
 277 lead to a known reduction in the variance of the incremental utility [26, 32]. However, an an-  
 278 alytic solution cannot easily be derived for most problems and sampling-based methods are  
 279 usually required.

280 For sampling-based methods, EVSI relies on the generation of plausible datasets from a pro-  
 281 posed new study. The parameters  $\theta$  can usually be partitioned into two sets: a set,  $\theta_i$ , for  
 282 which judgements will be informed by the newly collected data,  $\mathbf{X}$ , and a complementary  
 283 set  $\theta_c$  such that  $\{\theta_i, \theta_c\} = \theta$ . Plausible datasets can be obtained by first sampling values  
 284  $\theta_i^{(k)}$ ,  $k = 1, \dots, K$  from the prior distribution of the model parameters  $\pi(\theta_i)$ . Then, conditional  
 285 on each value  $\theta_i^{(k)}$ , a sample from the ‘likelihood function’ (i.e., the probability distribution for  
 286 new data, conditional on the parameters)  $\mathbf{X}^{(k)} \sim \pi(\mathbf{X}|\theta_i^{(k)})$  is generated. The two sources of  
 287 information are then combined to form a posterior distribution for the model parameters given  
 288 the new sample data and the prior knowledge about the model parameters.

289 When defining the likelihood for data generation, consideration should be given to how the data  
 290 from the study would actually be analysed in the study in order to inform parameters  $\pi(\theta_i)$ . For  
 291 example, the likelihood that is expected to be used in the statistical analysis of the data would  
 292 be a naturally good candidate for the likelihood used to generate plausible datasets. The  
 293 analyst should also consider any mechanisms that may result in corrupted, biased or missing  
 294 (e.g. censored) data.

295 When the likelihood is chosen such that the updated posterior distribution is in the same family  
 296 as the prior (e.g., a beta prior updated by binomially distributed data results in a beta posterior)  
 297 the prior is called a conjugate prior for the likelihood function. Conjugacy has computational  
 298 advantages because it results in a known posterior distribution that is easy to sample from.  
 299 The likelihood function that results in conjugacy is often (but not always) the natural choice for  
 300 the data generating mechanism.

301 The first term in the EVSI expression contains a nested expectation, which means that the  
 302 basic Monte Carlo approach to EVSI requires a nested ‘double loop’ solution:

$$\mathbb{E}_{\mathbf{X}} \left[ \max_{d \in \mathcal{D}} \mathbb{E}_{\theta|\mathbf{X}} \{U(d, \theta)\} \right] \simeq \frac{1}{K} \sum_{k=1}^K \left[ \max_{d \in \mathcal{D}} \frac{1}{J} \sum_{j=1}^J \{U(d, \theta^{(j,k)})\} \right], \quad (14)$$

303 where parameters  $\theta^{(j,k)}$ ,  $j = 1, \dots, J$  are sampled from the posterior distribution  $\pi(\theta|\mathbf{X}^{(k)})$  in  
 304 an inner loop, conditional on samples  $\mathbf{X}^{(k)}$ ,  $k = 1, \dots, K$  in an outer loop.



305 Algorithm 5 describes the double loop Monte Carlo scheme for estimating EVSI.

### Algorithm 5

#### ***Double-loop Monte Carlo scheme for computing EVSI***

1. Define the proposed study design (sample size, length of follow-up etc). Determine the data generating distribution (the likelihood) under this design.
2. Sample a value from the prior distribution of the parameter(s) that will be informed by new data.
3. Sample a plausible dataset from the distribution defined in step 1, conditional on the value of the target parameter(s) sampled in step 2.
4. Update the prior distribution of the target parameter(s) with the plausible dataset from step 3 to form the posterior distribution for the target parameter(s). Sample a value from this posterior distribution, which may require Markov chain Monte Carlo sampling if the prior and likelihood are not conjugate.
5. Sample a value from the prior distribution of the remaining uncertain parameters.
6. Evaluate the utility function for each decision option using the parameter values from steps 4 and 5 and store the results.
7. Repeat steps 4 to 6  $J$  times. This represents the inner loop of simulation.
8. Calculate the mean of the utility values across all  $J$  samples for each decision option in step 7 and store.
9. Repeat steps 2 to 8 for  $K$  values from the prior distribution of the parameters. This represents the outer loop of simulation.
10. Calculate the mean utility values for each decision option across all  $K$  samples of the output stored in step 9.
11. Choose the maximum of the expected utility values in step 10 and store. This is the expected utility with current knowledge.
12. Calculate the maximum utility of the decision options (i.e. the maximum of the inner loop means) for each of the  $K$  samples of the output stored in step 9.
13. Calculate the mean of the  $K$  maximum utility values generated in step 12. This is the expected utility with new sample information about the target parameter(s) of interest.
14. Calculate the EVSI as the difference between the expected utility with new sample information (step 13) and the expected utility with current knowledge (step 11).
15. Repeat steps 1-14 to calculate EVSI for different study designs (e.g., studies with different sample sizes or lengths of follow-up).

306

307 As with EVPPI, one of the key determinations for reducing the computation of EVSI is whether  
308 the model is linear or multilinear in either  $\theta_i$  or  $\theta_c$  (or both). For EVSI, the computation can  
309 also be reduced if an analytic expression exists for the posterior mean  $\mathbb{E}_{\theta_i|\mathbf{X}}(\theta_i)$  given the new  
310 data. If these conditions hold, the double loop scheme can be replaced with a single loop in  
311 which the mean values for the posterior distribution for the parameter(s) of interest are used  
312 under certain conditions [33, 34]. Algorithm 6 describes the single loop Monte Carlo scheme

**Algorithm 6*****Single loop Monte Carlo scheme for computing EVSI***

1. Define the proposed study design (sample size, length of follow-up etc). Determine the data generating distribution (the likelihood) under this design.
2. Sample a value from the prior distribution of the parameter(s) that will be informed by new data.
3. Sample a plausible dataset from the distribution defined in step 1, conditional on the value of the parameter(s) sampled in step 2.
4. Update the prior distribution of the target parameter(s) of interest with the new data in step 3 to form the posterior distribution. Analytically compute the expectation (mean value) of this posterior distribution. This will be possible if the prior and likelihood distributions are conjugate.
5. Evaluate the utility function for each decision option using the posterior mean estimate of the target parameter(s) and the mean values of the remaining uncertain parameters. Store the values.
6. Repeat steps 2 to 5 for  $N$  samples from the prior distribution of the target parameter(s) of interest.
7. Calculate the mean utility values for each decision option across all  $N$  samples of the output stored in step 5.
8. Choose the maximum of the expected utility in step 7 and store. This is the expected utility with current knowledge about the target parameter(s) of interest.
9. Calculate the maximum utility of the decision options for each of the  $N$  samples of the output stored in step 5.
10. Calculate the mean of the  $N$  maximum utility values generated in step 9. This is the expected utility with new sample information about the target parameter(s) of interest.
11. Calculate the EVSI as the difference between the expected utility with new sample information (step 10) and the expected utility with current knowledge (step 8).
12. Repeat steps 1-11 to calculate EVSI for different study designs (e.g., studies with different sample sizes or lengths of follow-up).

314

315 Several other methods for computing EVSI exist. As with EVPPI, EVSI can be computed  
 316 directly from the probabilistic analysis sample using regression-based methods [30, 35]. A  
 317 non-parametric regression is used to estimate the inner expectation of the first term of the  
 318 EVSI expression (10), and the method becomes a single loop. The method relies on there  
 319 being a low dimensional summary statistic for the new data  $s(\mathbf{X})$ , a good choice being the  
 320 summary statistic that would be reported if the study was actually conducted. The method  
 321 makes the assumption that the relationship between  $s(\mathbf{X})$  and the conditional expectation  
 322  $\mathbf{E}_{\theta|s(\mathbf{X})}\{U(d, \theta)\}$  is smooth, which is likely to be a reasonable assumption in most models.

323 EVSI can also be approximated using importance sampling, with only a single set of prior  
324 parameter samples and the corresponding probabilistic analysis sample [36]. This requires  
325 repeated evaluation of the likelihood function, and the scheme is expected to be most use-  
326 ful when the utility function is computationally expensive compared to the likelihood function.  
327 More recently, a Gaussian approximation method, which has similarities to the regression-  
328 based scheme, and a moment matching method have been proposed [37, 38]. These meth-  
329 ods have the advantage that, once the EVSI has been computed for a single proposed study,  
330 the EVSI values for a range of different study sample sizes can be easily computed. Given  
331 the different methods available for computing EVSI, Figure 2 of the supplementary appendix  
332 provides guidance on the choice of EVSI computation method based on model features.

333 ***Good practice recommendation 6***

334 **Choose the data generating distribution for the EVSI computation to reflect how the**  
335 **data would be analysed if the proposed new study were conducted.**

336 ***Good practice recommendation 7***

337 **When simulating datasets, model the processes that are expected to result in censoring,**  
338 **missing data and measurement bias in order to mimic the true data generating process.**

339 **Reporting of results**

340 Information generated by research is used to inform decisions for the population of individuals  
341 who could potentially benefit from the information. This depends on the size of the beneficiary  
342 population whose decision choice will be informed by the additional research (e.g., the preva-  
343 lent cohort with the disease and/or the future incident cohort) and on the time horizon over  
344 which the information generated by research is useful. The VOI population estimate is deter-  
345 mined by multiplying the per-person VOI estimate by the size of the beneficiary population over  
346 the anticipated time horizon:

$$\text{Population VOI} = \text{VOI per-person} \times \sum_{t=0}^T \frac{I_t}{(1+d)^t}, \quad (15)$$

347 where  $I_t$  is the incidence in time period  $t$ ,  $T$  is the time horizon, and  $d$  is the discount rate for a  
348 single time period [39].

349 An estimate of the size of the beneficiary population is typically derived from epidemiological  
350 data. The benefits of future research are only realized when the study findings are reported  
351 [26]. However, some study participants who are enrolled in the optimal arm of a research  
352 study will also receive the benefits of the optimal intervention while the study is conducted  
353 [24]. The size of the beneficiary population also depends on the perspective of the study and

354 whether information might be generalizable to multiple jurisdictions [40]. Gradual uptake or  
355 implementation of research findings should also be considered when determining the size of  
356 the relevant population [41].

357 Estimating the time horizon,  $T$ , over which the additional evidence remains informative is more  
358 challenging. Information generated by research is not valuable indefinitely because future  
359 changes are expected to occur over time that impact on the value of information [39, 42]. The  
360 impact of these complex and uncertain processes is impossible to quantify with certainty, but  
361 some assessment is possible based on historical evidence and anticipated future changes,  
362 e.g., patent expiration, upcoming innovations, and other evaluative research underway. The  
363 value of research should also be discounted over this time horizon so that more weight is  
364 given to decisions that are informed by the research in the near term and less weight given to  
365 decisions informed in the more distant future.

366 VOI is expressed in units of utility, which is typically net health benefit or net monetary benefit  
367 when a cost-effectiveness model has been employed. Because both net health and mone-  
368 tary benefit depend on the valuation of health opportunity cost (as expressed by the cost-  
369 effectiveness threshold), VOI should be reported for explicit thresholds of interest, or presented  
370 in graphical form as a function of the cost-effectiveness threshold. Figure 3 of the supplemen-  
371 tary appendix illustrates the presentation of EV(P)PI.

372 Population EVSI should be reported in a similar way to EV(P)PI, but with the additional report-  
373 ing of information governing the research design, e.g., sample size, allocation of participants  
374 within the study, length of follow-up, endpoints included in the design. This includes the report-  
375 ing of the parameter prior distribution and likelihood function used to estimate EVSI. The costs  
376 of collecting the sample information should be clearly reported for the calculation of ENBS.  
377 This includes the fixed cost of the proposed research, the variable costs associated with the  
378 study design, and the expected opportunity costs while the research is underway [24]. Figure  
379 4 of the supplementary appendix illustrates the presentation of EVSI and ENBS.

### 380 ***Good practice recommendation 8***

381 **When reporting VOI results, clearly state all underlying assumptions.**

## 382 **Other modeling considerations**

### 383 *Minimal modeling*

384 Most commonly VOI analysis is applied when a decision-analytic model is available to charac-  
385 terize uncertainty and the need for further evaluative research. However, many organizations  
386 responsible for making research prioritization decisions lack the time and resources to under-

387 take formal decision modeling. In these circumstances, it may be necessary to adopt a minimal  
388 modeling approach, which allows for rapid estimation of the value of further research without  
389 the need for constructing a full disease and/or decision-analytic model [43, 44].

390 Minimal modeling may be used as a substitute for full modeling when a clinical study is avail-  
391 able that directly characterizes uncertainty in comprehensive measures of outcome that are  
392 sufficient to inform the decision maker's utility for all relevant decision options [43]. This is  
393 possible when:

- 394 • The clinical study captures all important differences in outcomes between the decision  
395 options being evaluated;
- 396 • The endpoints that are important for the decision occur during the study;
- 397 • No age-specific competing causes of death or other events occur after the study ends.

398 Clinical studies that report intermediate endpoints are also amenable to minimal modeling if  
399 intermediate outcomes can be mapped to comprehensive outcome measures using a simple  
400 model with a few parameters.

401 Minimal modeling offers a practical means for estimating the value of further research quickly,  
402 and offers a transparent and efficient method for setting research priorities [43, 44]. However, it  
403 has a number of notable limitations. First, minimal modeling may involve an over-simplification  
404 of complex clinical processes. The extent to which the approach adequately addresses the  
405 decision problem is important, and the analyst should make clear all the assumptions un-  
406 derpinning the analysis. Second, the EVPPI cannot be computed for quantities that are not  
407 parametrized within the model. Third, it is difficult to adapt a minimal model that is based on a  
408 specific study to address a different, but related decision problem [43].

#### 409 *VOI for endpoints other than cost-effectiveness*

410 Some decision-making bodies exclude economic considerations from their decision-making  
411 process and, instead, use a utility function based on health outcomes alone. VOI analysis may  
412 be applied directly to the results of standard meta-analysis (or a single study) on a specific  
413 outcome measure [45, 46]. This approach places the focus on an endpoint of interest, e.g.,  
414 distribution of values describing uncertainty about the relative effect of an intervention on mor-  
415 tality. The VOI is then estimated in terms of that endpoint, e.g., number of deaths avoided.  
416 However, it does lead to difficulty in interpreting VOI outcomes across diverse decision prob-  
417 lems.

418 Importantly, VOI analysis is relevant to different types of health care systems and decision-  
419 making contexts. It should not be regarded as restricted to situations where decision-analytic  
420 models or estimates of cost-effectiveness are available.

## 421 **Software resources**

422 Decision-analytic models are implemented in a range of software, including spreadsheets,  
423 modeling programs such as TreeAge (TreeAge Software, Inc., Williamstown, MA, USA) or  
424 SIMUL8 (SIMUL8 Corporation, Boston, MA, USA), statistical environments such as R or Stata  
425 (StataCorp LLC, TX, USA), or general purpose programming languages such as Python or  
426 C++. Whether or not the VOI analysis can be conducted using the same software as that  
427 used to implement the decision-analytic model will depend on the choice of VOI computation  
428 method.

429 Compared with spreadsheets (which are noted for their perceived transparency), programming  
430 languages provide faster execution times and vastly increased flexibility. The analyst must  
431 write code, but many programming languages have specialist libraries that can reduce this  
432 burden (e.g. the BCEA [47] and `heemod` [48] packages in R). Analysts can also use web tools  
433 such as the Sheffield Accelerated Value of Information (SAVI) app [49] and BCEAweb [47,50],  
434 an online version of the BCEA R package. The introduction of these software solutions have  
435 allowed VOI analysis to be computed quickly; however, the analyst should always ensure that  
436 the underlying assumptions of the methods hold when using and interpreting the results.

## 437 **Future research directions**

438 The following areas have been identified where future research in VOI is warranted:

439 *Optimising the value of research to reduce structural uncertainties.* Structural uncertainty is  
440 rarely quantified in model-based analysis. Not quantifying structural uncertainty implies that  
441 the model is a perfect representation of real world processes and relationships. VOI analysis  
442 for structural uncertainty has been explored previously in [12] and [14], but methods in this  
443 area are underdeveloped.

444 *Optimising study design.* The set of potential study designs for a given research problem may  
445 be large. The design space may contain a range of sample sizes, allocations across treatment  
446 arms, follow-up duration, stopping rules, etc. [22]. Calculating EVSI for every combination of  
447 designs is likely to be computationally demanding [51], and methods are needed to increase  
448 computational efficiency. A related challenge is EVSI computation for trials with *adaptive* de-  
449 signs, in which aspects of the trial design itself are conditional on the data simulated in the  
450 EVSI calculation. The sequence in which different types of research studies should be con-  
451 ducted also represents an area that has received little attention to date [52].

452 *Computation of EVSI in complex modeling settings.* When evidence from a new research  
453 study informs functions of model parameters, more complex situations are created, which  
454 increase the computational burden. Complex modeling situations arise from dynamic trans-

455 mission modeling. EVSI computation also relies on the ability to generate plausible datasets  
456 from a distribution that reflects the data generating process. This can be difficult if the process  
457 is complex (e.g., when there is bias, censoring, missingness, data corruption or measurement  
458 error).

459 *Identifying the appropriate time horizon for VOI.* The ‘correct’ time horizon for research de-  
460 cisions (expression 15) is unknown since it is a proxy for uncertain future changes [39, 42].  
461 Identifying the appropriate time horizon for research decisions and incorporating uncertainty  
462 in the time horizon is an area that has received little attention to date.

## 463 **Conclusions**

464 This, second, report of the ISPOR VOI Task Force provides good practice guidance in the  
465 form of detailed algorithms for estimating EVPI, EVPPI and EVSI. It also provides information  
466 about efficient approaches and software available to support the implementation of VOI. Box 2  
467 provides a summary of the good practice recommendations, for conducting and reviewing VOI  
468 analyses, presented throughout this report.

### **Box 2: ISPOR Value of Information Analysis Task Force Report’s Good Practice Recommendations for Conducting and Reporting a VOI analysis**

1. Uncertainty in parameter input values should be characterized using probability distributions, and any dependency between parameters represented by a joint, correlated probability distribution.
2. Clearly describe any important model structural uncertainties. Where possible, structural uncertainty should be quantified and included in the VOI analysis.
3. Use probabilistic analysis to provide an appropriate quantification of uncertainty in model outputs.
4. When using the nested double-loop method to compute EVPPI, choose inner and outer loop simulation sizes to ensure acceptable bias and precision.
5. When using the single-loop methods to compute EVPPI, check that the underlying assumptions of the method hold.
6. Choose the data generating distribution for the EVSI computation to reflect how the data would be analysed if the proposed new study were conducted.
7. When simulating datasets, model the processes that are expected to result in censoring, missing data and measurement bias in order to mimic the true data generating process.
8. When reporting VOI results, clearly state all underlying assumptions.

469

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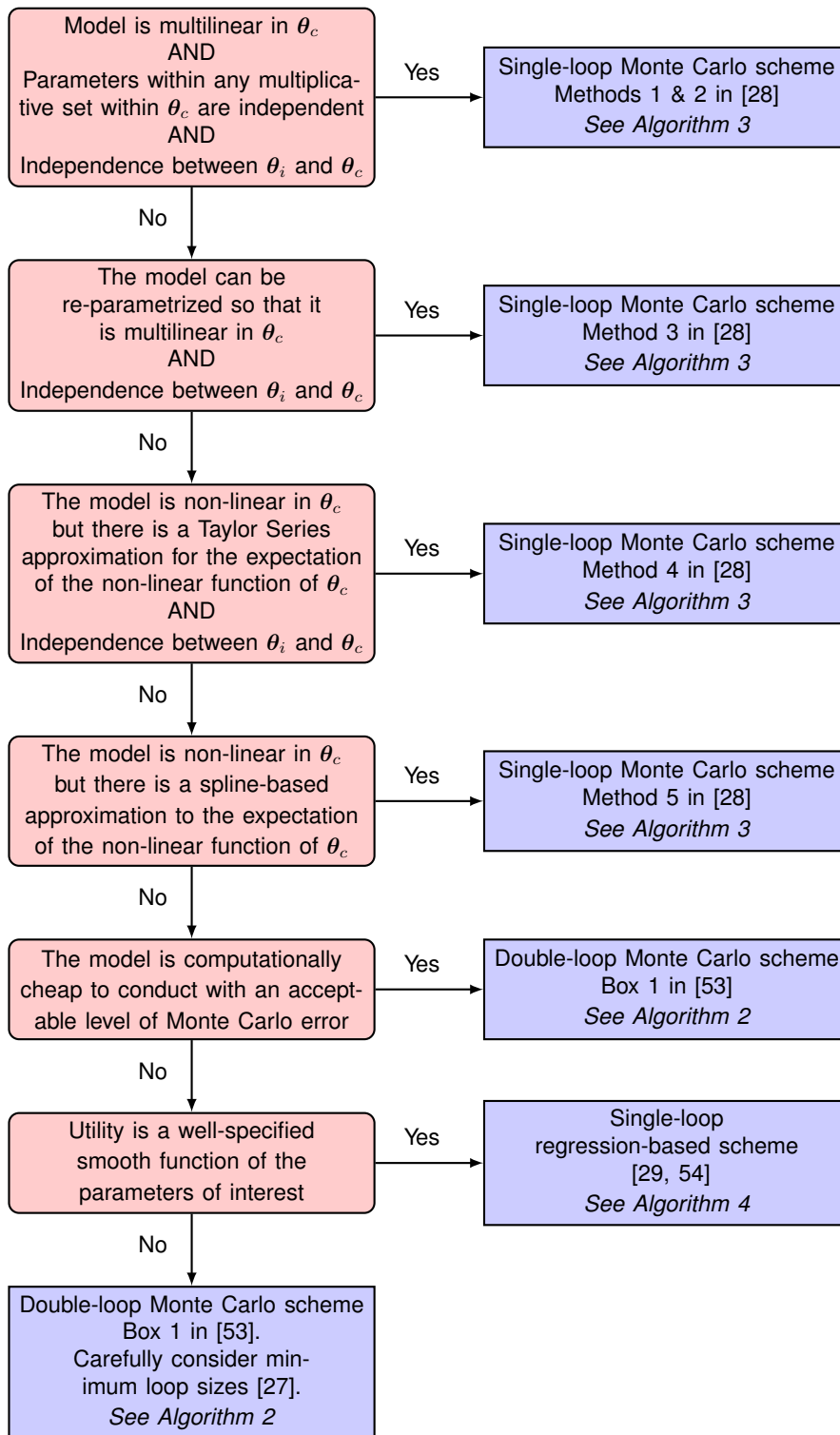


Figure 1: Process for choosing a method for computing the Expected Value of Partial Perfect Information based on model features. Algorithm numbers refer to algorithms in this report.

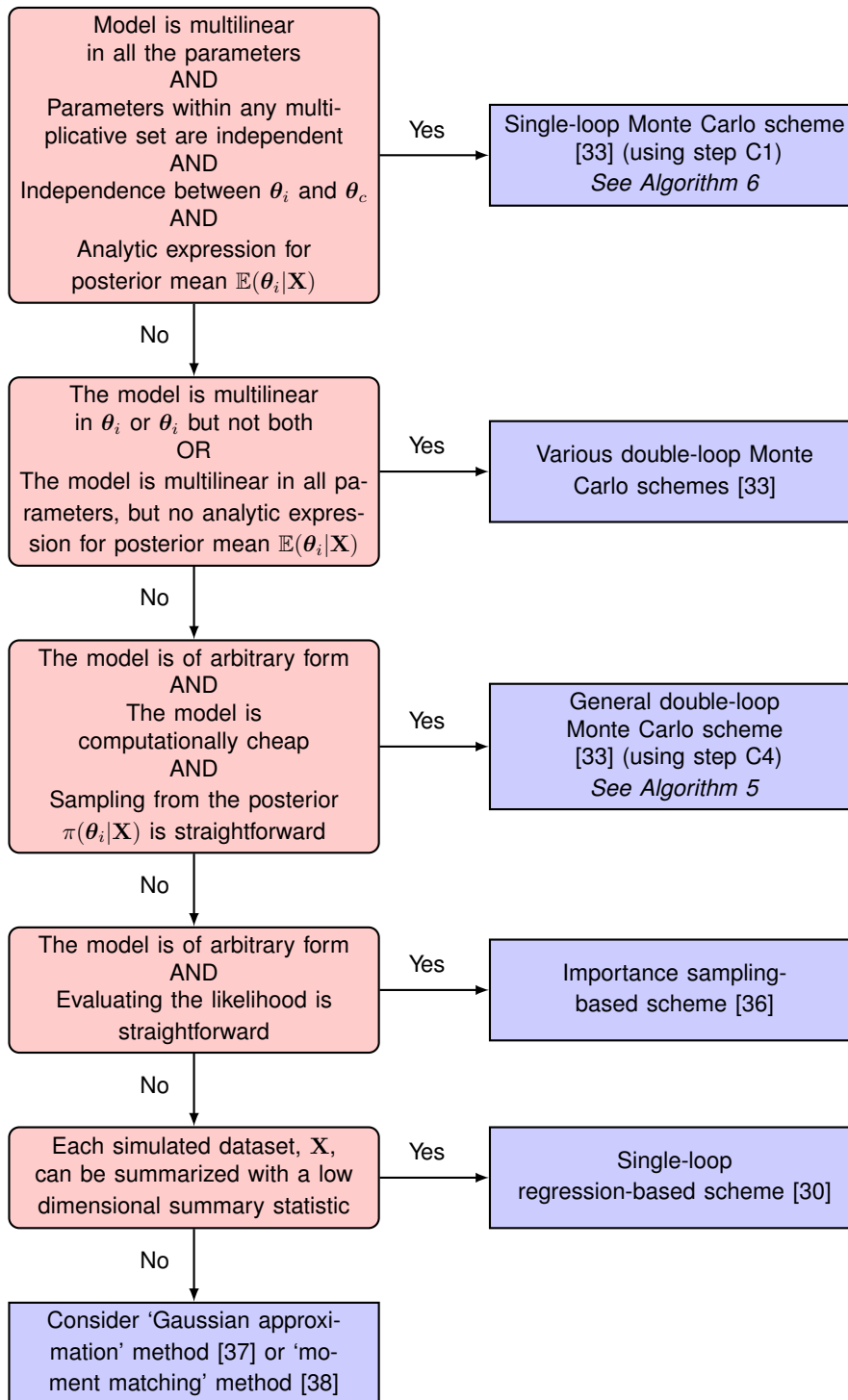


Figure 2: Process for choosing a method for computing the Expected Value of Sample Information based on model features. Algorithm numbers refer to algorithms in this report.

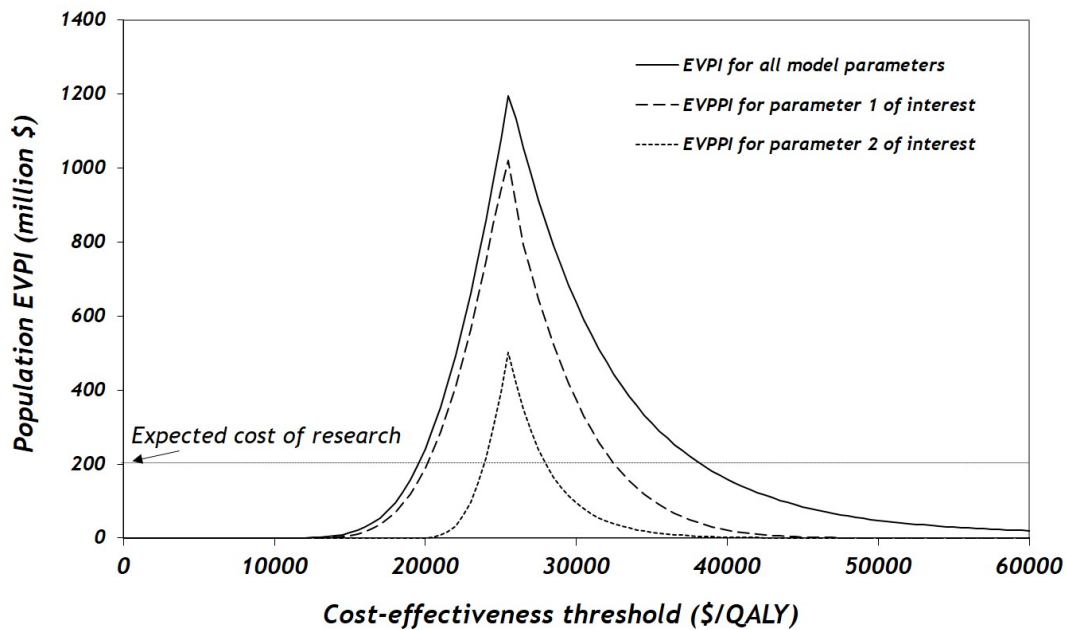


Figure 3: An illustration of population Expected Value of Perfect Information (EVPI) for all model parameters and Expected Value of Partial Perfect Information (EVPPPI) for two specific parameters of interest, over a range of cost-effectiveness thresholds. The higher the EV(P)PI, the larger the opportunity cost of a suboptimal decision. The EV(P)PI falls as one decision option appears increasingly optimal, i.e., as the probability of error falls. Additional research should only be considered if the EV(P)PI exceeds the expected cost of the research. In this example, the EVPI exceeds the cost of research between the cost-effectiveness thresholds of \$19,000 and \$38,000 per quality-adjusted life year (QALY).

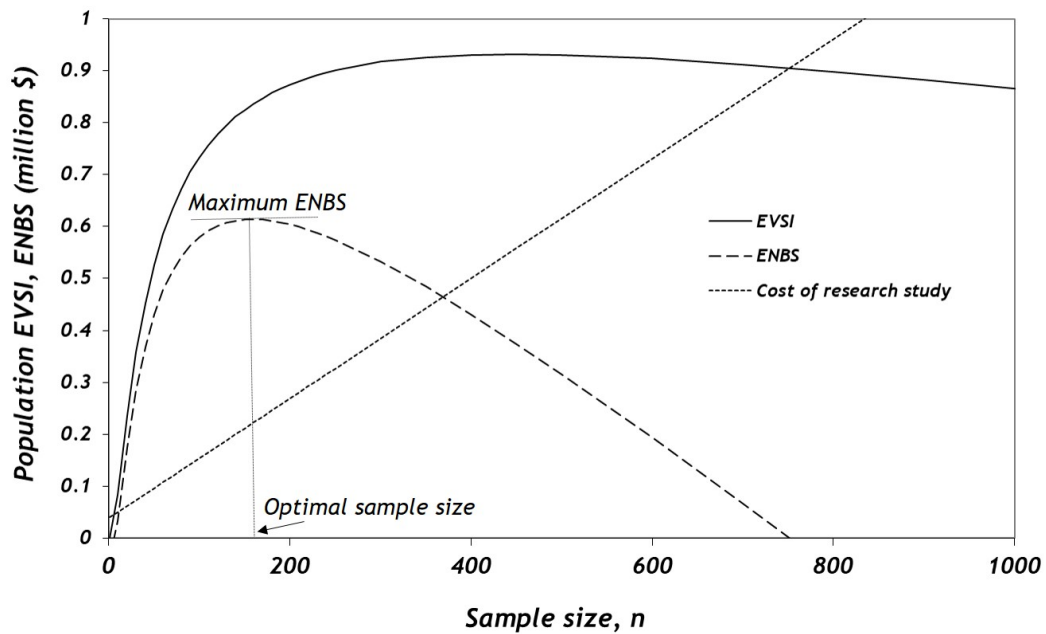


Figure 4: An illustration of population Expected Value of Sample Information (EVSI) and Expected Net Benefit of Sampling (ENBS) for a range of sample sizes of research study. The EVSI increases with the sample size but at a declining rate. In this example, the marginal costs of sampling are constant, as shown by the line indicating the cost of research study. The ENBS reaches a maximum at an optimal sample size of 170.