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1 **A bee or not a bee: an experimental test of acoustic mimicry by hoverflies**

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18  
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1 **Lay summary**

2 Many plants and animals look, smell, or sound like something other than what they are in order to  
3 deceive and manipulate. We show that a small number of harmless hoverflies make sounds that  
4 computers cannot distinguish from the sounds of bumble bees, yet it seems that their bird predators  
5 are able to do learn to do so in the field.

6                   **A bee or not a bee: an experimental test of acoustic mimicry by hoverflies**

7

8   **Abstract**

9   The degree of similarity between Batesian mimics and their models varies widely and occurs across a  
10 range of sensory modalities. We use three complementary experimental paradigms to investigate  
11 acoustic mimicry in hoverflies (Diptera: Syrphidae) which mimic stinging Hymenoptera. First, we  
12 analyse sounds made by 13 hoverfly species and 9 Hymenoptera species with and without simulated  
13 predation (“alarm” and “flight” sounds, respectively). We demonstrate that the bumblebees *Bombus*  
14 *terrestris*, *B. hortorum*, and *B. lucorum*, and the hoverfly *Cheilosia illustrata* exhibit alarm sounds  
15 that are significantly different to their respective flight sounds, and indistinguishable between species.  
16 We then demonstrate that the *B. terrestris* alarm sound reduces predation on artificial prey by wild  
17 birds, but that the hoverfly mimic alarm sound does not. Finally, we trained chicks to avoid distasteful  
18 food in the presence of different acoustic stimuli. Overall the chicks showed no difference in response  
19 to bee and hoverfly stimuli, demonstrating no innate aversion to the *Bombus* alarm sound. We  
20 therefore conclude that (i) similarity of acoustic signals exists among Hymenoptera and hoverflies, (ii)  
21 acoustic aposematic signals (but not the almost identical mimetic signals) are effective at reducing  
22 predation, and (iii) wild birds exhibit learned rather than innate aversion to certain acoustic stimuli.

23

24 **Introduction**

25 Aposematic insects advertise their defences to predators by presenting conspicuous warning displays  
26 (Poulton, 1890) and these displays can involve one or more sensory modalities. The signal may act in  
27 direct and indirect ways to influence the fitness of the signaller and the receiver. The signal may  
28 benefit individual prey exhibiting the signal if the defence is strong and immediate, through predator  
29 neophobia or startle displays. Benefits to prey may also be indirect, as aposematic signals serve to  
30 educate predators by forming an association between a strong sensory stimulus and a negative  
31 outcome (bad taste, sickness) such that the predator avoids similar prey individuals in the future  
32 (Gittleman and Harvey, 1980; Harvey and Greenwood, 1978). These honest signals can also be  
33 hijacked by mimics that reap the benefits of the predator's learned aversion to a given signal without  
34 having to pay the cost of producing the defence to which it is linked. The result is that mimics  
35 converge towards their models, while models diverge from their mimics (Nur, 1970). Such species are  
36 known as Batesian mimics (Bates, 1862) and represent some of the most celebrated and intensively  
37 studied examples of evolution with an array of adaptations that render them, in some cases, almost  
38 indistinguishable from their model species. However, if there is such a clear benefit to close  
39 resemblance to an aposematic species then the question remains: why are there no perfect mimics?  
40 Indeed, while there are many examples of exceptional mimicry, there are far more species within the  
41 same taxonomic groups that exhibit little to no evidence of mimicry. A range of hypotheses have been  
42 put forward to explain why some species might exhibit closer mimetic similarity than others (for a  
43 review, see Penney et al., 2012). These include the simultaneous mimicry of multiple models  
44 (Edmunds, 2000), kin selection (Johnstone, 2002), observer failure to take into account the  
45 evolutionarily-relevant predator's visual system (Cuthill and Bennett, 1993), and a relaxation of  
46 selection under certain circumstances (Sheppard, 1959; Sherratt, 2002).

47

48 A further possibility is that mimics resemble the same models in different sensory modalities, and  
49 recent analyses of the syrphid flies have suggested that there may be a role for behavioural mimicry  
50 alongside morphological mimicry (Penney et al., 2014). Several studies have also demonstrated  
51 classes of sound produced by hymenopteran models, involving a "hissing" noise that is distinct from

52 flight noises (Kirchner and Roeschard, 1999; Sarma et al., 2002). Numerous suggestions have been  
53 made that syrphids mimic these acoustic signals. For example, some syrphid mimics have very similar  
54 wingbeat frequencies to their hymenopteran models (Gaul, 1952) and toads show greater avoidance of  
55 bees and syrphids with wings than of the same species with wings removed (Brower and Brower,  
56 1965) . Under the assumption that these distinctive sounds represent an aposematic signal, and given  
57 that syrphids are already well-known to mimic other aspects of hymenopteran biology, it is a surprise,  
58 then, that a study that investigated acoustic mimicry in this group found equivocal evidence (Rashed  
59 et al., 2009). This is particularly surprising given the range of indirect observations that suggest  
60 acoustic mimicry occurs. Also, sounds are a common feature of aposematic displays (Masters, 1979)  
61 and acoustic Batesian mimicry has been described in field and laboratory experiments on a wide range  
62 of species from tiger moths to burrowing owls (Barber et al., 2009; Dowdy and Conner, 2016; Rowe  
63 et al., 1986) although some examples are disputed (Kardong, 1980; Sibley, 1955).

64

65 Many previous studies have taken a detailed, narrow approach to studying acoustic mimicry. This has  
66 involved removing acoustic cues (Brower and Brower, 1965), measuring wing beat frequencies (Gaul,  
67 1952), or quantifying acoustic similarity (Rashed et al., 2009). What is needed is a comprehensive  
68 analysis that describes variation in acoustic signals within an evolutionary context and then tests  
69 empirically the potential benefits that such signals might confer to a mimic. To address this gap in the  
70 literature, a series of experiments were designed to search for acoustic mimicry in the syrphids, assess  
71 its impact on predator-prey interactions, and determine whether predator avoidance behaviours are  
72 learned or innate.

73

## 74 **Methods**

### 75 *Experiment 1: Comparison of acoustic signals*

76 *Specimen collection:* Recordings were made of 172 insects comprising 13 syrphid species, 9  
77 Hymenoptera species, as well as 32 *Calliphora vomitoria* (Diptera: Calliphoridae) as a non-syrphid  
78 comparison. Individuals were collected using aerial nets between 12/06/2014 and 16/06/2014 at three  
79 locations in Leeds, UK (the University of Leeds West Campus, 53.807°N, -1.562°E; Meanwood Park,

80 53.840°N,-1.577°E; and Redcoat Lane, 53.808°N,-1.600°E) and stored in 30cm<sup>3</sup> sample tubes for  
81 transportation. Acoustic recordings were always taken within six hours of capture. Additionally  
82 *Episyrphus balteatus* pupae were purchased from Koppert Biological Systems (Koppert, Berkel en  
83 Rodenrijs, The Netherlands; product name Syrphidend) and *C. vomitoria* maggots were purchased  
84 from P&S Taylor (Sunny Bank Bait Farm, Halifax, UK). These were reared at 25°C (±1.5°C) and  
85 individuals were used within 24 hours of eclosion, Body mass was measured to ±0.01mg using a  
86 Mettler Toledo Micro Balance (Mettler Toledo, Greifensee, Switzerland; model AX26DR).

87

88 *Acoustic recordings:* Insects were dorsally tethered by the mesothorax to a 10cm length of rigid  
89 plastic coated wire (300µm diameter) using a non-toxic adhesive (Bostik). Reliable positioning of  
90 insects in front of the microphone was achieved using a retort stand, boss and clamp leaving 5cm of  
91 wire protruding on which the tethered insect was mounted. Recordings were taken using a Neumann  
92 mono microphone (Neuman, Berlin, Germany; model KM184, cardioid pick up) (response 20Hz to 20  
93 kHz) positioned 10cm behind the tethered insect with a König and Meyer Popkiller (Wertheim,  
94 Germany; model 23956) exactly half way between the microphone and the insect to reduce the effects  
95 of the mechanical impact of air striking the microphone. Acoustic signals were recorded using AVID  
96 Pro-Tools11 digitising at 48 kHz and stored as waveform (.WAV) audio file format. All recordings  
97 were taken in a soundproof room at a temperature of 24°C (±1.5°C). Two recordings were made of  
98 each insect. First, insects were mounted in front of the microphone and allowed to attempt to fly. If  
99 after one minute an individual did not fly, flight was provoked by introducing a solid surface to the  
100 animal's feet for 5 seconds then removing it again. These acoustic signals are hereafter referred to as  
101 "flight" sounds. Second, to simulate avian predation, insects were squeezed gently on the ventral side  
102 of the abdomen with a pair of flexible-tipped entomological forceps. Attacks were aimed at the  
103 insect's ventral side to avoid contact with the wings. Each insect was stimulated a minimum of three  
104 times in order to ensure that an alarm response had been elicited if the insect were capable of  
105 generating such a response (hereafter "alarm" sounds).

106

107 *Acoustic analysis:* The flight and alarm sounds produced by the insects were analysed using Avisoft-

108 SASLab Lite sound analysis software (Avisoft Bioacoustics, Glienicke, Germany). Fourier  
109 transformation was used to generate averaged power spectra for segments of the recordings. The  
110 target length of the analysed segments was 500ms but this varied due to variability in the length of the  
111 sustained acoustic response (range 118-500ms). Seven variables were extracted from these spectra:  
112 the frequency (P1) and power (P1dB) of the greatest amplitude, the frequency (P2) and power (P2dB)  
113 of the second greatest amplitude, the difference between the amplitudes ( $\Delta$ dB) and frequencies ( $\Delta$ Hz)  
114 of the two peaks, the bandwidth of the peak power output measured as the difference between the  
115 high (BW1) and low frequencies (BW2) 6Db below the peak ( $\Delta$ BW). BW1 was not used in the  
116 analysis because most power spectra lacked this feature. Variables are illustrated in Figure S1, with  
117 descriptions in Table S1. This cut-off point was chosen as 6Db represents a 50% decrease in power.  
118 Any data in the power spectra at frequencies above 12kHz were omitted as this is the high frequency  
119 limit generally attributed to avian hearing (Heffner and Heffner, 2007).

120

121 To evaluate the capacity of species to produce different flight and alarm sounds, sound files were  
122 analysed using two different techniques. First, the *diffspec* function in the *Seewave* package (Sueur et  
123 al., 2008) in R version 3.1.2 (R Core Team, 2014) was used to calculate the percentage difference  
124 between sounds based on their probability mass functions. We would predict that larger species would  
125 show greater capacity to produce warning sounds, as has been shown in morphological and  
126 behavioural modalities in hoverflies (Penney et al., 2012; Penney et al., 2014). To test this, the mean  
127 of the individual differences between flight and alarm sounds was tested against mean species mass  
128 using Pearson correlations. We performed a statistical hypothesis test for a difference between alarm  
129 and flight sounds within a species using a MANOVA. A set of seven out of nine acoustic  
130 characteristics were used, as some species exhibited spectra that did not allow the calculation of the  
131 remaining two parameters (P1dB and BW1). Data were extracted for each species individually and all  
132 variables were scaled to unit variance and mean-centred, then principal components analysis was used  
133 to extract orthogonal variables to avoid covariance in the raw data. A MANOVA was then performed  
134 with the sound type (alarm or flight) as the predictor and the first two principal components (which  
135 always explained >98% of the variance in the data) as the response.

136

137 To test for a difference between species, MANOVA was used as above but with all species together  
138 and the species as the predictor. The first four principal components were included as the response  
139 variable in the MANOVA, which explained 97.4% of the variance in the alarm sounds and 98.4% of  
140 the variance in the flight sounds. Two further groups of tests were performed. First, linear  
141 discriminant analysis (LDA) was conducted on the sounds using the `lda` function in the MASS  
142 package (Venables and Ripley, 2002) in R to attempt to discriminate among the species and to  
143 visualise the differences. Second, a pairwise comparison of species was carried out using the `contrast`  
144 function in the `lsmeans` package (Lenth, 2015) while accounting for multiple tests (n=66 pairwise  
145 comparisons) using the false discovery rate (FDR) in R.

146

#### 147 Experiment 2: Field study

148 Regardless of the interpretation of specific model-mimic relationships in these groups, it is then of  
149 interest to know whether there is an anti-predator role for the acoustic signal when all else is held  
150 equal. To quantify the evolutionary advantage of acoustic mimicry of bumblebees, a field study was  
151 carried out using wild birds as predators. Fieldwork was conducted in Hertfordshire, England,  
152 (51.855°N, -0.108°E) between 05/08/2014 and 18/08/2014. Pastry baits were made using 310g flour,  
153 160g lard, 30ml water and 10ml Sainsbury's yellow food colouring (Easley and Hassall, 2014). Bait  
154 size was adjusted to 20mm length and 5mm diameter, with cross-sectional uniformity ensured by  
155 using a clay extruder with a 5mm aperture, in order to accommodate for the smaller birds in this  
156 experiment (e.g. European robin (*Erithacus rubecula*) and great tit (*Parus major*)) being unable to  
157 take baits compared to those in the previous study that include the Eurasian Magpie (*Pica pica*) and  
158 Rock Pigeon (*Columba livia*). Baits were deployed on 50cmx50cm wooden boards that were painted  
159 "Buckingham Green" with an exterior gloss (B&Q, Eastleigh, UK, product 5397007045949).

160

161 Four acoustic conditions were produced from the studio recordings: (i) post-attack *B. terrestris*, (ii)  
162 post-attack *Cheilosia illustrata*, (iii) *C. vomitoria* flight, and (iv) silence. The acoustic stimuli were  
163 sections of recordings between 657ms and 3537ms in length looped to generate a 6000ms waveform

164 (.wav) audio file using Avisoft-SASLab Lite (Avisoft Bioacoustics, Glienicke, Germany). Sound files  
165 were played on a constant loop using Alba MP3 players (Alba, Milton Keynes, UK: model 189/9935)  
166 and through Veho 360° capsule speakers (Veho, Southampton, UK: model VSS-001-360) positioned  
167 directly below the bait boards held in a plastic container lidded with cling film which prevented water  
168 damage but allowed unimpeded sound transmission. Suitable playback volume was determined by  
169 collecting a sample of 10 bumblebees (5 *B. terrestris*, 5 *B. lucorum*) and measuring the maximum  
170 volume produced by the insects during flight (mean 59.8Db  $\pm$ 8.6SE) and attack response  
171 (56.4Db $\pm$ 6.6SE) using a Tenma decibel meter (Tenma, China; model 72-947). Speaker volume was  
172 set so that the volume of acoustic stimuli was within this range across each board, this was checked  
173 using a Samsung Tablet (Samsung, Seoul, South Korea; model Tab2 10.1) running the Sound Meter  
174 application version 1.5.9a (Sound Meter, 2014).

175

176 Twenty pastry baits were presented on each of four 50x50cm wooden bait boards, set out in a square  
177 2m from one another with a 50cm perimeter marked around each board. This distance between boards  
178 was chosen as it was calculated, using the inverse square law, that acoustic cues would be reduced to  
179  $<1/32$  the power on neighbouring conditions. This was decided to be sufficiently quiet as to not  
180 influence the birds feeding behaviours between conditions. Each board was randomly allocated one of  
181 the four acoustic treatments. Thirty minutes before sunrise, 20 baits were placed on each board and  
182 observations began 15 minutes before sunrise and continued for 4 hours separated into 8 x 30 minute  
183 periods. The period of time between a bird entering the 0.5m perimeter of a board and first pecking a  
184 bait was recorded. After each experimental run the remaining baits were removed and between each  
185 trial the acoustic conditions were changed so that over a 4 day period each condition was supplied in  
186 each location.

187

188 *Field study data analysis:* Cox proportional hazards models, implemented using the survival package  
189 (Therneau, 2014) in R (R Core Team, 2014), were used to test for a difference in survival rates  
190 between baits presented with different acoustic cues. Models included acoustic cue as a predictor and  
191 were stratified by date to account for variability in weather conditions between days of the

192 experiment. Models were tested using `cox.zph()` to ensure that the data conformed to the assumptions  
193 of proportional hazards. Generalised Rank-Order MANOVA was then used to investigate significant  
194 difference between species (Thomas et al., 1999) and subsequent *post-hoc* Tukey's HSD analyses  
195 were conducted to further investigate the significant differences between the treatment levels.

196

### 197 Experiment 3: Laboratory study

198 Since the wild bird trial suggested that avian predators could distinguish between the acoustically-  
199 similar *B. terrestris* and *C. illustrata* alarm sounds, we conducted a third experiment using domestic  
200 chicks as a model system to explore the capacity of birds to learn to differentiate between the two  
201 stimuli. Day-old domestic chicken chicks (*Gallus gallus domesticus*, Ross 308 broiler strain, n=172)  
202 were purchased from a commercial hatchery and housed in groups of <24 in holding pens of  
203 dimensions 126cm x 84cm lined with sawdust. Holding pens were positioned so that chicks could get  
204 no closer than 2m from the experimental enclosures because at this distance, as with the wild bird  
205 experiment, experimental acoustics would be sufficiently quiet as to not influence birds while not  
206 being experimented upon. . Chicks were housed under a brightness of 40 lux under a light cycle of  
207 23L: 1D for the first two nights with the dark period increasing by one hour on subsequent nights.  
208 Poultry shed temperature was 30°C for the first three days then reduced to 28°C. Water was always  
209 available and chick crumb feed (from Target Feeds Ltd.) was also constantly available in feeding  
210 trays except during experimental periods when food deprivation was imposed in accordance with  
211 Home Office regulations and authorised by the University of Leeds ethics committee. Chick crumb  
212 feed was used throughout the experiment to avoid introducing additional visual and taste stimuli that  
213 could interfere with responses to acoustic signals. Studies of multi-modal mimicry or more realistic  
214 experiments incorporating ecologically relevant combinations of stimuli should consider using pastry  
215 model prey.

216

217 The experimental arena was a sawdust lined cage measuring 42cm x 84cm containing a Veho 360°  
218 speaker (Veho, Southampton, UK: model VSS-001-360), an Alba MP3 player (Alba, Milton Keynes,  
219 UK: model 189/9935) and a feeding tray holding approximately 500g of chick crumb. On the first day

220 post-hatch chick pairs were placed in the experimental arena and supplied with plain chick crumb  
221 twice during the day to acclimatise them to the experimental set-up (Skelhorn et al., 2010). Chicks  
222 remained in the arena until both chicks had pecked at the feed and were then allowed to remain in the  
223 arena for a further minute so that an association between feeding in the arena and being handled, a  
224 potentially stressful and negative experience, would not develop. Chicks were trained and tested in  
225 pairs since the “buddy method” involving separating chicks using mesh cages but retaining visual and  
226 auditory contact as described in Skelhorn et al. (2010) were found to be insufficient to prevent chicks  
227 from becoming distressed. Hence the paired trials were used due to ethical considerations to reduce  
228 the stress of the animals being separated from the rest of the group. Such stress is not only an animal  
229 welfare issue in and of itself, but would also influence the behaviour of the animals such that  
230 experimental data may not be reliable. Individual adult birds which are less stressed by solo foraging  
231 tasks may give more precise individual-level behavioural data (i.e. independent of social factors), but  
232 would not have been naïve at the start of the experiment.

233

234 On the second day post hatch chicks were divided randomly into four equal groups (n=43) and  
235 allocated to one of four feeding regimes. One training regime, representing aposematic prey, was  
236 provided with the acoustic stimulus of post-attack *B. terrestris* and provided chick crumb given a  
237 bitter flavour using Bitrex solution (6ml 5% Bitrex solution per 500g of crumb (Mostler, 1935) ). The  
238 three other regimes were provided with unaltered chick crumb, representing undefended prey,  
239 presented with either a synthesised tone of 120Hz, post-attack *C. illustrata* sound or silence. Acoustic  
240 stimuli were supplied constantly while chicks were in the arena by the speaker at between 56.4 and  
241 59.8Db, as established as an ecologically relevant level in the field study. Chicks were trained in this  
242 regime for three days before each group was further split into four groups (n≥10 in each group), each  
243 of which was tested once on one of the four treatments thus achieving a fully-factorial design of  
244 training vs. testing. During both the training and the testing phase chicks were deprived of food for 30  
245 minutes before entering the arena, latency to peck at the food by each chick in a pair was recorded and  
246 chicks were allowed 30 seconds after pecking before being removed from the arena.

247

248 *Laboratory study data analysis:* Two-way ANOVAs were run using R to compare the latency to  
249 attack the baits during the testing phase, with the training treatment, testing treatment, and the  
250 interaction of training and testing as predictors. Using one-way ANOVAs, we further analysed the  
251 overall response to the different cues across training and testing phases, the response of bee-trained  
252 chicks to the four test treatments, and the response of chicks trained in each of the four cues to the bee  
253 test treatment. Tukey's HSD tests were used to investigate the data further where there was a  
254 statistically significant effect in the full model.

255

## 256 **Results**

### 257 *Experiment 1: Comparison of acoustic signals*

258 The Hymenoptera *Bombus terrestris* (MANOVA:  $F_{2,35}= 54.340$ ,  $p<0.001$ , Pillai's trace=0.756), *B.*  
259 *hortorum* (MANOVA:  $F_{2,9}= 6.696$ ,  $p=0.017$ , Pillai's trace=0.598), and *B. lucorum* (MANOVA:  $F_{2,17}=$   
260  $44.797$ ,  $p<0.001$ , Pillai's trace=0.841), and the Syrphidae *Cheilosia illustrata* (MANOVA:  
261  $F_{2,8}=24.036$ ,  $p<0.001$ , Pillai's trace=0.857) were the only species to generate significantly different  
262 flight and alarm sounds. A slow motion video showing the transition between flight and alarm sound  
263 production can be seen in the Supplementary Information, and Figure S2 shows the difference  
264 between acoustic waveforms from flight and alarm sounds in *B. terrestris*, *C. illustrata*, and the  
265 syrphid *Episyrphus balteatus*. When the percentage dissimilarity of flight and alarm sounds was  
266 analysed across the hoverflies (excluding singletons), there was a strong positive correlation with  
267 body size (Pearson correlation:  $R=0.741$ ,  $p=0.014$ ,  $n=10$ ; Figure 1), indicating that larger animals  
268 produced alarm sounds that were more distinct from their flight sounds.

269

270 Linear discriminant analysis showed that the flight sounds of the species were clustered together with  
271 no clear separation of Hymenoptera and hoverflies (Figure 2A) but that the five hymenopteran  
272 *Bombus* sp., and the three syrphids *C. illustrata*, *Eristalis tenax*, and *Leucozona lucorum* showed  
273 similar alarm sounds (Figure 2B; though note that *L. lucorum* is represented by a single individual). A  
274 MANOVA on the full flight dataset confirmed that while there were differences between species in  
275 flight sounds ( $F_{88,536}=2.578$ ,  $p<0.001$ ), there were no significant pair-wise differences after control for

276 multiple comparisons using false discovery rates ( $p > 0.5$  in all cases; Figure 2A). A MANOVA on the  
277 full alarm dataset confirmed that there were much stronger differences between species in alarm  
278 sounds ( $F_{88,540} = 3.998$ ,  $p < 0.001$ ), and that *B. terrestris* produces an alarm sound that is significantly  
279 different to those of all other species apart from the other *Bombus* species, *C. illustrata*, *E. tenax*, and  
280 *L. lucorum* (as can be seen in Figure 2B).

281

### 282 Experiment 2: Field study

283 Baits presented with the post-attack sounds of *B. terrestris* experienced significantly lower attack  
284 rates than those presented in all other conditions (Cox proportional hazards analyses: *C. illustrata*  
285 alarm:  $z = 2.804$ ,  $p < 0.010$ ; *C. vomitoria* flight  $z = 2.656$ ,  $p < 0.010$ ; silence  $z = 2.115$ ,  $p < 0.050$ , see Figure  
286 3). These results demonstrate strong evidence for the evolutionary benefit of acoustic aposematism,  
287 but do not seem to support a role for mimicry. However, it is unclear as to the characteristics of the  
288 *Bombus* and *Cheilosia* signals that cause the birds to respond differently.

289

### 290 Experiment 3: Laboratory study

291 Our laboratory study tested three predictions. First, that chicks trained on distasteful food with *B.*  
292 *terrestris* sound would show greater latency to peck at both *C. illustrata* and *B. terrestris* food in the  
293 test phase, indicating a generalisation of the acoustic cue. The results showed that chicks trained on  
294 the *B. terrestris* food treatment exhibited no difference in latency to attack any of the four food  
295 treatments in the test phase (ANOVA:  $F_{3,40} = 0.766$ ,  $p = 0.520$ ; Figure 4A). Second, that chicks trained  
296 on palatable (i.e. not *B. terrestris*) foods would show lower latency to attack when tested on *B.*  
297 *terrestris* food, indicating that they had learned that the sounds were associated with palatable food.  
298 Here, we found that chicks' latency to attack the *B. terrestris* food treatment during the testing phase  
299 was not significantly influenced by their food treatment during the training phase (ANOVA:  
300  $F_{3,43} = 0.319$ ,  $p = 0.812$ ; Figure 4B). Finally, that chicks respond to acoustic cues without discrimination,  
301 in which case we would expect a greater latency to peck at foods presented with acoustic stimuli vs.  
302 silence, irrespective of trials, testing, and training. We found a significant difference in latency to  
303 attack across all encounters (training and testing) between acoustic stimuli (ANOVA:  $F_{3,667} = 5.578$ ,

304 p=0.001; Figure 4C), and that this involved significantly shorter latency to attack the silent food  
305 compared to *C. illustrata* (p=0.002) or *B. terrestris* food (p=0.014), and borderline significance in the  
306 shorter latency to attack the tone food compared to *C. illustrata* food (p=0.051). These results suggest  
307 that while training did not appear to have an effect on predator interactions there may be a general  
308 heightened latency to attack when food is presented with an acoustic cue (as has been suggested  
309 previously; Rowe and Guilford, 1999), with some suggestion that it is insect sounds specifically rather  
310 than sound *per se* that delay predation.

311

## 312 **Discussion**

313 This study presents three complementary experiments: (i) a comparative analysis of the presence of  
314 acoustic mimicry demonstrating the mimetic links between several *Bombus* species (a Müllerian  
315 complex) and a subset of Syrphidae. Specifically, the similarity of alarm sounds indicate that *Bombus*  
316 species represent a group of Müllerian acoustic mimics, and that *C. illustrata*, *E. tenax*, and possibly  
317 *L. lucorum* are Batesian acoustic mimics of the *Bombus* group; (ii) a field based predation experiment  
318 under ecologically-relevant conditions that demonstrates a benefit to the aposematic signal using  
319 naturally-foraging birds but not for the acoustically-similar mimetic signal produced by a hoverfly;  
320 and (iii) a tightly-controlled laboratory study using a model avian visual system to demonstrate that  
321 there is a general aversion to sound (and insect sounds in particular) but no innate avoidance of the  
322 *Bombus* alarm sound. This allows us to conclude that some hoverflies produce sounds that are  
323 indistinguishable from those of Hymenoptera based on acoustic analysis, that there is no innate  
324 avoidance to Hymenoptera sounds in particular, and that aposematic sounds enhance survival (but  
325 mimicry of those sounds by syrphids may not). The findings complement previous work on  
326 morphological and behavioural mimicry in this system (Penney et al., 2012; Penney et al., 2014).

327

328 As bumblebees use pheromones to warn conspecifics of predators (Goodale and Nieh, 2012) and are  
329 unable to detect airborne sounds (Hunt and Richard, 2013) it is reasonable to assume that the observed  
330 acoustic change from flight to alarm sound has evolved as an aposematic alarm signal. While our  
331 findings from Experiment 1 are consistent with an explanation of Müllerian mimicry for the shared

332 alarm sounds of the *Bombus* sp., this pattern could also be explained simply through shared  
333 evolutionary history. Despite experimental work demonstrating the benefits of Batesian mimicry of  
334 *Bombus* sp. (e.g. Brower et al., 1960), experimental work demonstrating generalised avoidance of  
335 *Bombus* congeners is lacking. All other Hymenoptera examined here immediately began biting and  
336 stabbing their abdomen at the simulated predator suggesting that in these species conditioning the  
337 predator not to attack similar individuals in the future is preferable to the survival of individual  
338 workers. Considering the significantly smaller size of *Bombus* colonies compared to other social  
339 hymenopterans (*Bombus* <100, *Apis* <100 000 and *Vespidae* <1000; data from (Bourke, 1999)) and  
340 the greater energetic investment needed to produce larger workers it is considerably more costly to  
341 lose an individual worker and therefore preferable to facilitate escape. Therefore there is greater  
342 selective pressure for *Bombus* species to develop additional modes of signalling to their predators and  
343 facilitate escape. Moreover, bumble bees are more robust, accumulating terminal levels of damage  
344 more slowly than other insects when attacked (Krebs and Avery, 1985) allowing them more time to  
345 escape during an attack. These factors could allow for the evolution of an aposematic alarm signal that  
346 could encourage the predator to release the individual, and which could be exploited by mimics. As  
347 far as we know there have been no experimental studies prior to our own that have attempted to move  
348 beyond conjecture with respect to the alarm sounds. There are a number of studies that have proposed  
349 a role for the sounds as acoustic aposematic signals, such as Kirchner and Roeschard (1999) who  
350 described a “hissing” of bees in response to nest invasion, air currents, and the presence of mice  
351 (which showed aversion to the sound). Those hissing responses were never associated with escape  
352 behaviour. In addition, our own high speed video work (see Supplementary Information for a link to  
353 the video online) demonstrates that the alarm sound in *Bombus terrestris* is associated with a change  
354 in wing stroke amplitude which does not seem biomechanically appropriate for an escape behaviour.  
355 We suggest that it has more in common with wing whirring (as used during behavioural  
356 thermoregulation), with the wings decoupled from the flight muscles, to produce an acoustic  
357 aposematic signal.

358

359 The putative acoustic mimics, *C. illustrata* and *E. tenax*, are two of the three largest mimics in this

360 study (Figure 1). This finding, along with the observation that there is a significant positive  
361 correlation between size and the capacity to generate alarm sounds, is consistent with the relaxed  
362 selection hypothesis that suggests that larger species that are more profitable prey and suffer higher  
363 predation rates should develop greater levels of mimetic fidelity than smaller, less rewarding species  
364 (Penney et al., 2012; Sherratt, 2002). Furthermore, we can confirm that this behaviour is not a feature  
365 of all large syrphids as *Volucella pellucens* was the second largest species but lacked obvious acoustic  
366 mimetic qualities. While flight and alarm sounds of *V. pellucens* were different according to their  
367 probability mass functions (Figure 1), there was no significant difference between the two  
368 (MANOVA:  $F_{2,10}=0.146$ ,  $p=0.864$ ) and LDA grouped *V. pellucens* with the larger group of non-  
369 mimetic species (Figure 2B). It is possible that this species has evolved other means of predator  
370 avoidance, and observations by the authors of the fly's considerable speed and agility during flight  
371 have recently been supported by laboratory comparisons which show that *V. pellucens* is among the  
372 fastest syrphid fliers and can generate considerable aerodynamic force (Belyaev et al., 2014). Our  
373 results imply that, as has been suggested for behavioural mimicry (Penney et al., 2014), acoustic  
374 mimicry may be restricted to large, high-fidelity mimics. The results therefore provide the novel  
375 suggestion that mimics may resemble different models in different mimetic modalities, although  
376 previous work has interpreted a similar pattern as a lack of acoustic mimicry (Rashed et al., 2009).  
377 However, it is interesting to note that *C. illustrata* is considered to be a morphological mimic of  
378 *Bombus pratorum*, while *E. tenax* is considered to be a morphological mimic of the honeybee, *A.*  
379 *mellifera* (Howarth and Edmunds, 2000). *L. lucorum* is easily confused with *C. illustrata* (Ball and  
380 Morris, 2013), but is not considered to be mimetic and lacks the colour patterns of *B. pratorum*.  
381 Indeed, we argue for a re-evaluation of Rashed et al.'s work, the results of which are broadly  
382 consistent with those of the present study, which also demonstrated similarity between *Bombus* alarm  
383 sounds and those of some hoverflies. We propose that where morphological and acoustic mimicry  
384 appear to rely upon different models this constitutes a "multi-model" mimicry system (Edmunds,  
385 2000).

386

387 The fact that just two of the species investigated exhibit acoustic mimicry, and that Rashed et al.

388 (2009) were unable to find the phenomenon despite investigating a similar number of hoverflies of  
389 arguably higher mimetic fidelity, such as *Spilomyia sayi*, demonstrates that this behaviour is not a  
390 feature of all visually mimetic species. Our findings are consistent with a previous systematic survey  
391 of behavioural mimicry in hoverflies, which revealed mimetic behaviours in only six species  
392 (belonging to only two genera, *Temnostoma* and *Spilomyia*) out of 57 species that were assayed  
393 (Penney et al., 2014). Our identification of two species which do appear to exhibit acoustic mimicry  
394 from a relatively small sample, and which are found in two different tribes within the subfamily  
395 Eristalinae, opens the possibility that acoustic mimicry may be more common than behavioural  
396 mimicry in the Syrphidae, of which there are over 6000 identified species worldwide (Rotheray and  
397 Gilbert, 2011).

398

399 Of particular interest in this study is the apparent lack of effect of the *Cheilosia illustrata* alarm sound  
400 when presented to wild birds in the field, despite its acoustic similarity to that of *Bombus terrestris*.  
401 There are two explanations for this pattern, which are not mutually exclusive. The first is that the  
402 birds are able to discriminate between the sounds based on an aspect of the acoustic signal that was  
403 not measured during the acoustic analysis. The second explanation is that the benefits of the acoustic  
404 signal are dependent upon some other aspect of the mimic phenotype that is not represented in the  
405 pastry prey. For instance, higher morphological mimicry is associated with behavioural mimicry,  
406 suggesting that the benefits of morphological and behavioural mimicry may be contingent on one  
407 another (Penney et al., 2014). This notion of the interdependence of the multiple sensory modalities  
408 through which mimicry manifests poses a problem for experimental researchers, as it is a complex  
409 task to remove one modality without affecting others. Previous work with invertebrate sensory  
410 modalities has reduced the sensory perception of the signal receiver (Bretman et al., 2011) or removed  
411 the capacity of a signaller to produce certain signals (Olofsson et al., 2012). However, such  
412 manipulations would have serious ethical implications and low ecological relevance in this study.

413

414 While a substantial body of work now exists on the ecology and evolution of mimicry, combining  
415 comparative, lab and field studies, there has been far less study of the mechanisms by which mimetic

416 traits are produced and the lability of the genes underlying those traits. The video in the  
417 supplementary information suggests that the alarm sound in *Bombus* is produced by decoupling the  
418 wings from the flight muscles to produce low amplitude, high frequency movements, similar to the  
419 thermoregulatory behaviour known as “wing-whirring” (May, 1979). Interestingly a previous study of  
420 thermoregulation also suggested that hoverflies make a high pitched noise during warm-up (Morgan  
421 and Heinrich, 1987), and so it is possible that thermoregulation and acoustic mimicry are linked in  
422 some way. That sound production identified in *Bombus* accompanies reduced wing movement  
423 suggests these acoustics satisfy an alternative function to movement during an attack, supporting the  
424 suggestion of an aposematic signal which *Syrphidae* were able to mimic due to a shared physiology.  
425 What is needed to test this hypothesis is a survey of the internal anatomy during sound production  
426 using a technique such as high speed cineradiography to compare the musculature of models and  
427 mimics (Betz et al., 2008).

428

429 The findings described here represent the first empirical evidence linking the acoustic similarity of  
430 Hymenoptera and *Syrphidae* acoustic signals to survival benefits in the field. However, further work  
431 involving a larger array of acoustic signals is required to test these field patterns comprehensively. If  
432 the survival benefits of acoustic mimicry in *Syrphidae* were to be confirmed, it would constitute the  
433 third mode of mimicry in the *Syrphidae* alongside visual (Penney et al., 2012) and behavioural  
434 (Penney et al., 2014), and all three modes suggest a role for body size in the evolution of mimetic  
435 traits. Larger hoverflies generate sounds when attacked that are indistinguishable from those produced  
436 by bumblebees immediately after attack while smaller and non-mimetic syrphid species are less able  
437 to exhibit this behaviour as predicted by the relaxed selection hypothesis. A subsequent field  
438 experiment demonstrated that avian predators preferentially avoided prey presented with post-attack  
439 *B. terrestris* acoustic stimulus, confirming the presence of a selective pressure for the evolution of  
440 acoustic aposematism and, potentially, for the evolution of mimicry in this predator-prey complex. An  
441 experiment using naive predators demonstrated that the predator’s aversion is not intrinsic but is  
442 developed over an extensive learning period and at considerable expense to the aposematically  
443 signalling population. It is therefore suggested that further investigations into the interaction between

444 acoustic and visual mimicry using a multi-modal experimental design would yield interesting results  
445 (Skelhorn et al., 2015). The discovery of a novel mode of mimicry in such a highly studied system  
446 suggests that such acoustic mimetic complexes are likely to be present across the natural world,  
447 particularly with acoustically dominant predators.

448

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456

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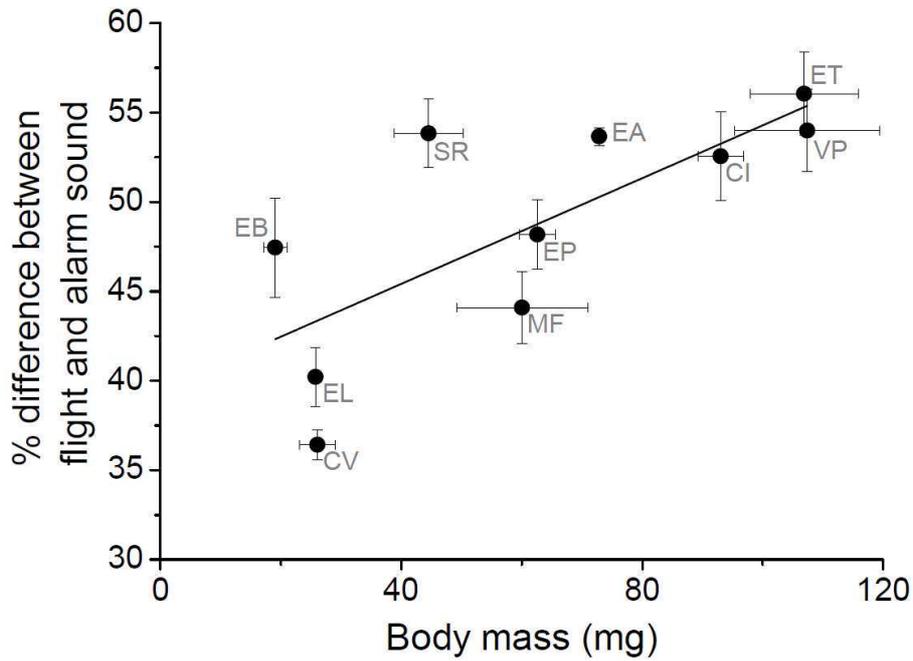
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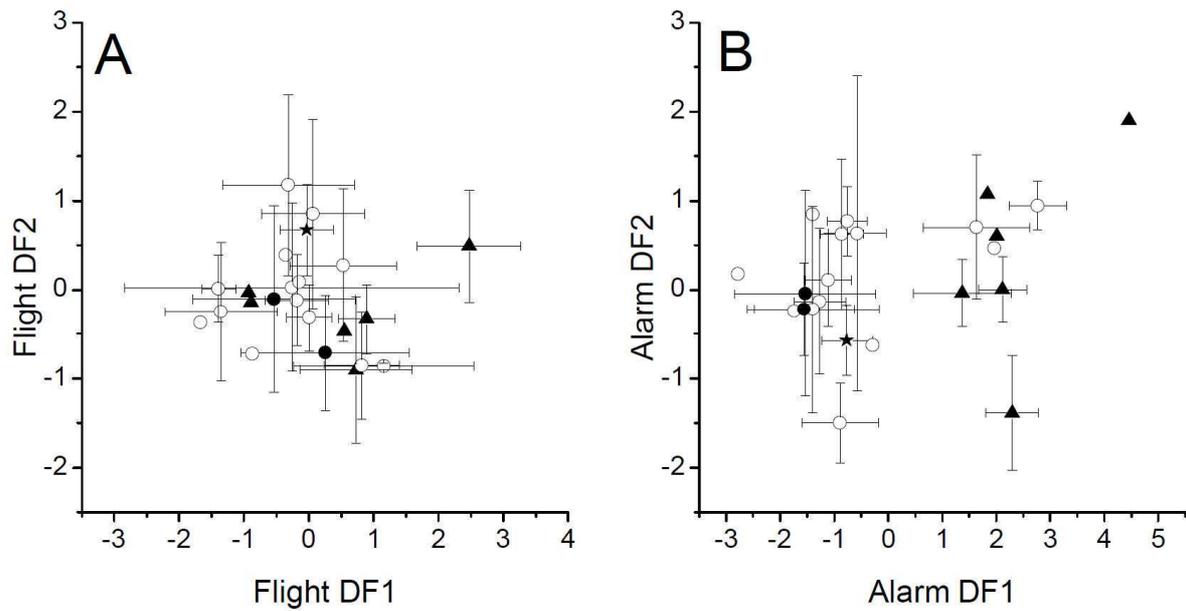
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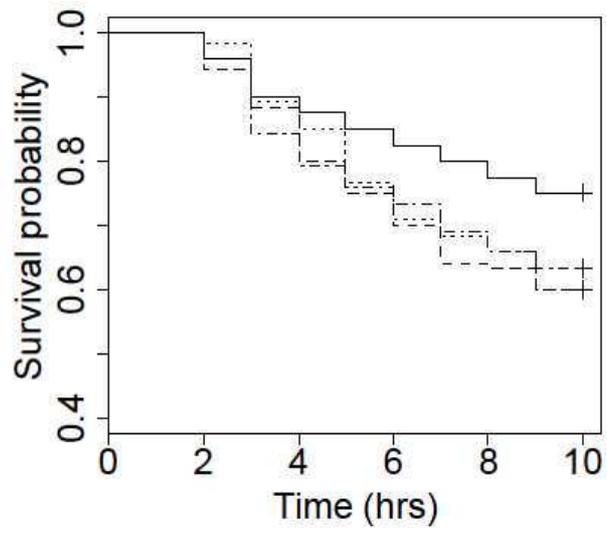
558

559 Figure 1: Larger-bodied hoverflies (Diptera: Syrphidae) exhibit a greater variation between their  
 560 routine flight sound and their alarm calls, which resemble those of Hymenoptera. This finding follows  
 561 the expectation of the relaxed selection hypothesis, whereby larger prey species are under greater  
 562 selective pressure to evolve anti-predator defences. Abbreviations are: *Apis mellifera* (AM), *Bombus*  
 563 *terrestris* (BT), *Calliphora vomitoria* (CV), *Cheilosia illustrata* (CI), *Episyrphus balteatus* (EB),  
 564 *Eristalis arbustorum* (EA), *Eristalis pertinax* (EP), *Eristalis tenax* (ET), *Eupeodes luniger* (EL),  
 565 *Myathropa flora* (MF), *Syrphus ribesii* (SR), and *Volucella pellucens* (VP).



567

568 Figure 2: Linear discriminant analysis showed that while (A) flight sounds were very similar across  
 569 hoverflies and their Hymenopteran models, (B) there were two discrete groups of species that produce  
 570 different types of alarm call. This latter group includes all six *Bombus* species and the mimics  
 571 *Eristalis tenax*, *Cheilosia illustrata*, and *Leucozona lucorum*. Points are species means (open circles =  
 572 hoverflies, filled circles = Vespidae, triangles = *Bombus* sp., star = *Apis mellifera*) and error bars are  
 573 95% confidence intervals.

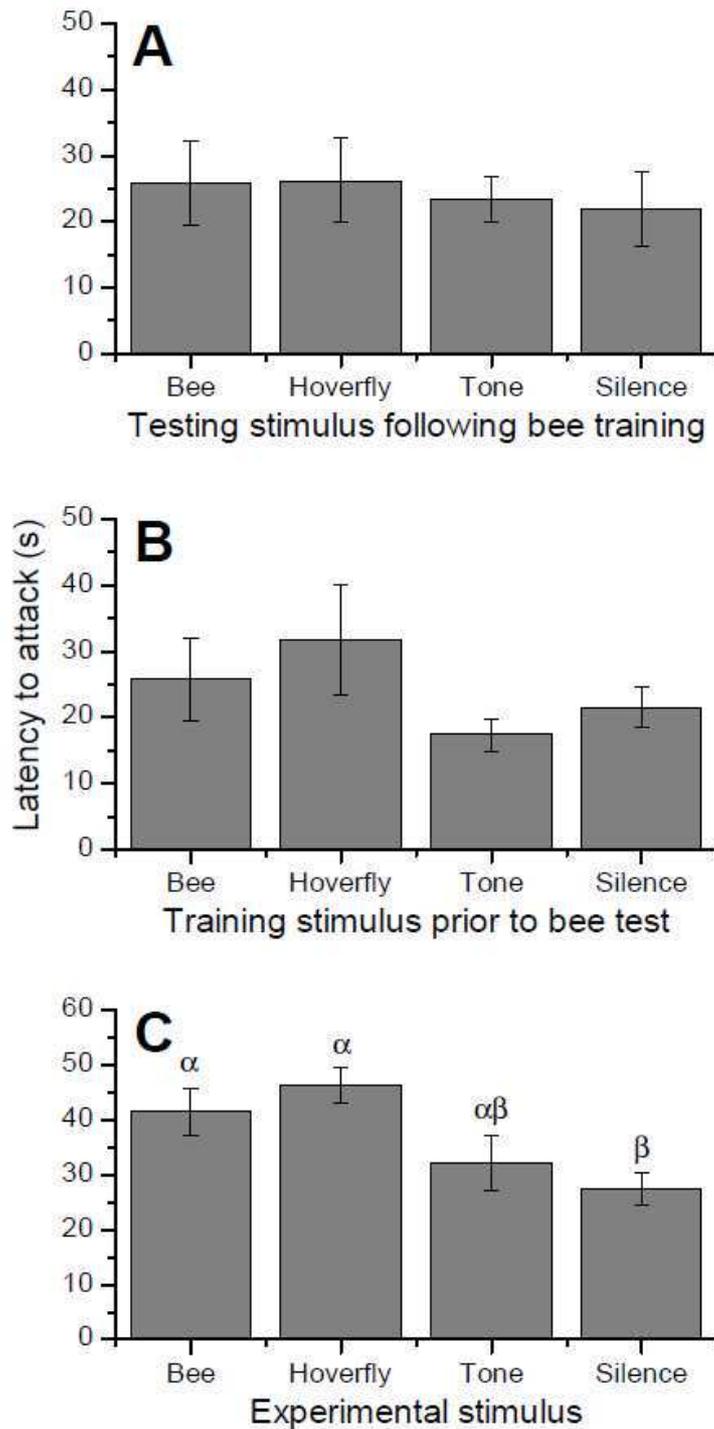


574

575 Figure 3: Survival of identical baits presented to wild birds with four acoustic stimuli: post-attack

576 *Bombus terrestris* (solid line), post-attack *Cheilosia illustrata* (dotted line), *Calliphora vomitaria*

577 flight (dashed line), and silence (dot-dash line).



578

579 Figure 4: Results of experimental training of domestic chicks to recognise acoustic cues: (A) latency  
 580 to attack between four types of food following training on distasteful food presented with a *Bombus*  
 581 *terrestris* alarm sound, (B) latency to attack distasteful food presented with a *B. terrestris* alarm sound  
 582 following training on four types of food, and (C) overall latency to attack different food types across  
 583 all training and testing phases in the experiment. Bars are means and error bars represent 1SE.