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1 **A bee or not a bee: an experimental test of acoustic mimicry by hoverflies**

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18
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1 **Lay summary**

2 Many plants and animals look, smell, or sound like something other than what they are in order to
3 deceive and manipulate. We show that a small number of harmless hoverflies make sounds that
4 computers cannot distinguish from the sounds of bumble bees, yet it seems that their bird predators
5 are able to do learn to do so in the field.

6 **A bee or not a bee: an experimental test of acoustic mimicry by hoverflies**

7

8 **Abstract**

9 The degree of similarity between Batesian mimics and their models varies widely and occurs across a
10 range of sensory modalities. We use three complementary experimental paradigms to investigate
11 acoustic mimicry in hoverflies (Diptera: Syrphidae) which mimic stinging Hymenoptera. First, we
12 analyse sounds made by 13 hoverfly species and 9 Hymenoptera species with and without simulated
13 predation (“alarm” and “flight” sounds, respectively). We demonstrate that the bumblebees *Bombus*
14 *terrestris*, *B. hortorum*, and *B. lucorum*, and the hoverfly *Cheilosia illustrata* exhibit alarm sounds
15 that are significantly different to their respective flight sounds, and indistinguishable between species.
16 We then demonstrate that the *B. terrestris* alarm sound reduces predation on artificial prey by wild
17 birds, but that the hoverfly mimic alarm sound does not. Finally, we trained chicks to avoid distasteful
18 food in the presence of different acoustic stimuli. Overall the chicks showed no difference in response
19 to bee and hoverfly stimuli, demonstrating no innate aversion to the *Bombus* alarm sound. We
20 therefore conclude that (i) similarity of acoustic signals exists among Hymenoptera and hoverflies, (ii)
21 acoustic aposematic signals (but not the almost identical mimetic signals) are effective at reducing
22 predation, and (iii) wild birds exhibit learned rather than innate aversion to certain acoustic stimuli.

23

24 **Introduction**

25 Aposematic insects advertise their defences to predators by presenting conspicuous warning displays
26 (Poulton, 1890) and these displays can involve one or more sensory modalities. The signal may act in
27 direct and indirect ways to influence the fitness of the signaller and the receiver. The signal may
28 benefit individual prey exhibiting the signal if the defence is strong and immediate, through predator
29 neophobia or startle displays. Benefits to prey may also be indirect, as aposematic signals serve to
30 educate predators by forming an association between a strong sensory stimulus and a negative
31 outcome (bad taste, sickness) such that the predator avoids similar prey individuals in the future
32 (Gittleman and Harvey, 1980; Harvey and Greenwood, 1978). These honest signals can also be
33 hijacked by mimics that reap the benefits of the predator's learned aversion to a given signal without
34 having to pay the cost of producing the defence to which it is linked. The result is that mimics
35 converge towards their models, while models diverge from their mimics (Nur, 1970). Such species are
36 known as Batesian mimics (Bates, 1862) and represent some of the most celebrated and intensively
37 studied examples of evolution with an array of adaptations that render them, in some cases, almost
38 indistinguishable from their model species. However, if there is such a clear benefit to close
39 resemblance to an aposematic species then the question remains: why are there no perfect mimics?
40 Indeed, while there are many examples of exceptional mimicry, there are far more species within the
41 same taxonomic groups that exhibit little to no evidence of mimicry. A range of hypotheses have been
42 put forward to explain why some species might exhibit closer mimetic similarity than others (for a
43 review, see Penney et al., 2012). These include the simultaneous mimicry of multiple models
44 (Edmunds, 2000), kin selection (Johnstone, 2002), observer failure to take into account the
45 evolutionarily-relevant predator's visual system (Cuthill and Bennett, 1993), and a relaxation of
46 selection under certain circumstances (Sheppard, 1959; Sherratt, 2002).

47

48 A further possibility is that mimics resemble the same models in different sensory modalities, and
49 recent analyses of the syrphid flies have suggested that there may be a role for behavioural mimicry
50 alongside morphological mimicry (Penney et al., 2014). Several studies have also demonstrated
51 classes of sound produced by hymenopteran models, involving a "hissing" noise that is distinct from

52 flight noises (Kirchner and Roeschard, 1999; Sarma et al., 2002). Numerous suggestions have been
53 made that syrphids mimic these acoustic signals. For example, some syrphid mimics have very similar
54 wingbeat frequencies to their hymenopteran models (Gaul, 1952) and toads show greater avoidance of
55 bees and syrphids with wings than of the same species with wings removed (Brower and Brower,
56 1965) . Under the assumption that these distinctive sounds represent an aposematic signal, and given
57 that syrphids are already well-known to mimic other aspects of hymenopteran biology, it is a surprise,
58 then, that a study that investigated acoustic mimicry in this group found equivocal evidence (Rashed
59 et al., 2009). This is particularly surprising given the range of indirect observations that suggest
60 acoustic mimicry occurs. Also, sounds are a common feature of aposematic displays (Masters, 1979)
61 and acoustic Batesian mimicry has been described in field and laboratory experiments on a wide range
62 of species from tiger moths to burrowing owls (Barber et al., 2009; Dowdy and Conner, 2016; Rowe
63 et al., 1986) although some examples are disputed (Kardong, 1980; Sibley, 1955).

64

65 Many previous studies have taken a detailed, narrow approach to studying acoustic mimicry. This has
66 involved removing acoustic cues (Brower and Brower, 1965), measuring wing beat frequencies (Gaul,
67 1952), or quantifying acoustic similarity (Rashed et al., 2009). What is needed is a comprehensive
68 analysis that describes variation in acoustic signals within an evolutionary context and then tests
69 empirically the potential benefits that such signals might confer to a mimic. To address this gap in the
70 literature, a series of experiments were designed to search for acoustic mimicry in the syrphids, assess
71 its impact on predator-prey interactions, and determine whether predator avoidance behaviours are
72 learned or innate.

73

74 **Methods**

75 *Experiment 1: Comparison of acoustic signals*

76 *Specimen collection:* Recordings were made of 172 insects comprising 13 syrphid species, 9
77 Hymenoptera species, as well as 32 *Calliphora vomitoria* (Diptera: Calliphoridae) as a non-syrphid
78 comparison. Individuals were collected using aerial nets between 12/06/2014 and 16/06/2014 at three
79 locations in Leeds, UK (the University of Leeds West Campus, 53.807°N, -1.562°E; Meanwood Park,

80 53.840°N,-1.577°E; and Redcoat Lane, 53.808°N,-1.600°E) and stored in 30cm³ sample tubes for
81 transportation. Acoustic recordings were always taken within six hours of capture. Additionally
82 *Episyrphus balteatus* pupae were purchased from Koppert Biological Systems (Koppert, Berkel en
83 Rodenrijs, The Netherlands; product name Syrphidend) and *C. vomitoria* maggots were purchased
84 from P&S Taylor (Sunny Bank Bait Farm, Halifax, UK). These were reared at 25°C (±1.5°C) and
85 individuals were used within 24 hours of eclosion, Body mass was measured to ±0.01mg using a
86 Mettler Toledo Micro Balance (Mettler Toledo, Greifensee, Switzerland; model AX26DR).

87

88 *Acoustic recordings:* Insects were dorsally tethered by the mesothorax to a 10cm length of rigid
89 plastic coated wire (300µm diameter) using a non-toxic adhesive (Bostik). Reliable positioning of
90 insects in front of the microphone was achieved using a retort stand, boss and clamp leaving 5cm of
91 wire protruding on which the tethered insect was mounted. Recordings were taken using a Neumann
92 mono microphone (Neuman, Berlin, Germany; model KM184, cardioid pick up) (response 20Hz to 20
93 kHz) positioned 10cm behind the tethered insect with a König and Meyer Popkiller (Wertheim,
94 Germany; model 23956) exactly half way between the microphone and the insect to reduce the effects
95 of the mechanical impact of air striking the microphone. Acoustic signals were recorded using AVID
96 Pro-Tools11 digitising at 48 kHz and stored as waveform (.WAV) audio file format. All recordings
97 were taken in a soundproof room at a temperature of 24°C (±1.5°C). Two recordings were made of
98 each insect. First, insects were mounted in front of the microphone and allowed to attempt to fly. If
99 after one minute an individual did not fly, flight was provoked by introducing a solid surface to the
100 animal's feet for 5 seconds then removing it again. These acoustic signals are hereafter referred to as
101 "flight" sounds. Second, to simulate avian predation, insects were squeezed gently on the ventral side
102 of the abdomen with a pair of flexible-tipped entomological forceps. Attacks were aimed at the
103 insect's ventral side to avoid contact with the wings. Each insect was stimulated a minimum of three
104 times in order to ensure that an alarm response had been elicited if the insect were capable of
105 generating such a response (hereafter "alarm" sounds).

106

107 *Acoustic analysis:* The flight and alarm sounds produced by the insects were analysed using Avisoft-

108 SASLab Lite sound analysis software (Avisoft Bioacoustics, Glienicke, Germany). Fourier
109 transformation was used to generate averaged power spectra for segments of the recordings. The
110 target length of the analysed segments was 500ms but this varied due to variability in the length of the
111 sustained acoustic response (range 118-500ms). Seven variables were extracted from these spectra:
112 the frequency (P1) and power (P1dB) of the greatest amplitude, the frequency (P2) and power (P2dB)
113 of the second greatest amplitude, the difference between the amplitudes (Δ dB) and frequencies (Δ Hz)
114 of the two peaks, the bandwidth of the peak power output measured as the difference between the
115 high (BW1) and low frequencies (BW2) 6Db below the peak (Δ BW). BW1 was not used in the
116 analysis because most power spectra lacked this feature. Variables are illustrated in Figure S1, with
117 descriptions in Table S1. This cut-off point was chosen as 6Db represents a 50% decrease in power.
118 Any data in the power spectra at frequencies above 12kHz were omitted as this is the high frequency
119 limit generally attributed to avian hearing (Heffner and Heffner, 2007).

120

121 To evaluate the capacity of species to produce different flight and alarm sounds, sound files were
122 analysed using two different techniques. First, the `diffspec` function in the `Seewave` package (Sueur et
123 al., 2008) in R version 3.1.2 (R Core Team, 2014) was used to calculate the percentage difference
124 between sounds based on their probability mass functions. We would predict that larger species would
125 show greater capacity to produce warning sounds, as has been shown in morphological and
126 behavioural modalities in hoverflies (Penney et al., 2012; Penney et al., 2014). To test this, the mean
127 of the individual differences between flight and alarm sounds was tested against mean species mass
128 using Pearson correlations. We performed a statistical hypothesis test for a difference between alarm
129 and flight sounds within a species using a MANOVA. A set of seven out of nine acoustic
130 characteristics were used, as some species exhibited spectra that did not allow the calculation of the
131 remaining two parameters (P1dB and BW1). Data were extracted for each species individually and all
132 variables were scaled to unit variance and mean-centred, then principal components analysis was used
133 to extract orthogonal variables to avoid covariance in the raw data. A MANOVA was then performed
134 with the sound type (alarm or flight) as the predictor and the first two principal components (which
135 always explained >98% of the variance in the data) as the response.

136

137 To test for a difference between species, MANOVA was used as above but with all species together
138 and the species as the predictor. The first four principal components were included as the response
139 variable in the MANOVA, which explained 97.4% of the variance in the alarm sounds and 98.4% of
140 the variance in the flight sounds. Two further groups of tests were performed. First, linear
141 discriminant analysis (LDA) was conducted on the sounds using the `lda` function in the MASS
142 package (Venables and Ripley, 2002) in R to attempt to discriminate among the species and to
143 visualise the differences. Second, a pairwise comparison of species was carried out using the `contrast`
144 function in the `lsmeans` package (Lenth, 2015) while accounting for multiple tests (n=66 pairwise
145 comparisons) using the false discovery rate (FDR) in R.

146

147 Experiment 2: Field study

148 Regardless of the interpretation of specific model-mimic relationships in these groups, it is then of
149 interest to know whether there is an anti-predator role for the acoustic signal when all else is held
150 equal. To quantify the evolutionary advantage of acoustic mimicry of bumblebees, a field study was
151 carried out using wild birds as predators. Fieldwork was conducted in Hertfordshire, England,
152 (51.855°N, -0.108°E) between 05/08/2014 and 18/08/2014. Pastry baits were made using 310g flour,
153 160g lard, 30ml water and 10ml Sainsbury's yellow food colouring (Easley and Hassall, 2014). Bait
154 size was adjusted to 20mm length and 5mm diameter, with cross-sectional uniformity ensured by
155 using a clay extruder with a 5mm aperture, in order to accommodate for the smaller birds in this
156 experiment (e.g. European robin (*Erithacus rubecula*) and great tit (*Parus major*)) being unable to
157 take baits compared to those in the previous study that include the Eurasian Magpie (*Pica pica*) and
158 Rock Pigeon (*Columba livia*). Baits were deployed on 50cmx50cm wooden boards that were painted
159 "Buckingham Green" with an exterior gloss (B&Q, Eastleigh, UK, product 5397007045949).

160

161 Four acoustic conditions were produced from the studio recordings: (i) post-attack *B. terrestris*, (ii)
162 post-attack *Cheilosia illustrata*, (iii) *C. vomitoria* flight, and (iv) silence. The acoustic stimuli were
163 sections of recordings between 657ms and 3537ms in length looped to generate a 6000ms waveform

164 (.wav) audio file using Avisoft-SASLab Lite (Avisoft Bioacoustics, Glienicke, Germany). Sound files
165 were played on a constant loop using Alba MP3 players (Alba, Milton Keynes, UK: model 189/9935)
166 and through Veho 360° capsule speakers (Veho, Southampton, UK: model VSS-001-360) positioned
167 directly below the bait boards held in a plastic container lidded with cling film which prevented water
168 damage but allowed unimpeded sound transmission. Suitable playback volume was determined by
169 collecting a sample of 10 bumblebees (5 *B. terrestris*, 5 *B. lucorum*) and measuring the maximum
170 volume produced by the insects during flight (mean 59.8Db \pm 8.6SE) and attack response
171 (56.4Db \pm 6.6SE) using a Tenma decibel meter (Tenma, China; model 72-947). Speaker volume was
172 set so that the volume of acoustic stimuli was within this range across each board, this was checked
173 using a Samsung Tablet (Samsung, Seoul, South Korea; model Tab2 10.1) running the Sound Meter
174 application version 1.5.9a (Sound Meter, 2014).

175

176 Twenty pastry baits were presented on each of four 50x50cm wooden bait boards, set out in a square
177 2m from one another with a 50cm perimeter marked around each board. This distance between boards
178 was chosen as it was calculated, using the inverse square law, that acoustic cues would be reduced to
179 $<1/32$ the power on neighbouring conditions. This was decided to be sufficiently quiet as to not
180 influence the birds feeding behaviours between conditions. Each board was randomly allocated one of
181 the four acoustic treatments. Thirty minutes before sunrise, 20 baits were placed on each board and
182 observations began 15 minutes before sunrise and continued for 4 hours separated into 8 x 30 minute
183 periods. The period of time between a bird entering the 0.5m perimeter of a board and first pecking a
184 bait was recorded. After each experimental run the remaining baits were removed and between each
185 trial the acoustic conditions were changed so that over a 4 day period each condition was supplied in
186 each location.

187

188 *Field study data analysis:* Cox proportional hazards models, implemented using the survival package
189 (Therneau, 2014) in R (R Core Team, 2014), were used to test for a difference in survival rates
190 between baits presented with different acoustic cues. Models included acoustic cue as a predictor and
191 were stratified by date to account for variability in weather conditions between days of the

192 experiment. Models were tested using `cox.zph()` to ensure that the data conformed to the assumptions
193 of proportional hazards. Generalised Rank-Order MANOVA was then used to investigate significant
194 difference between species (Thomas et al., 1999) and subsequent *post-hoc* Tukey's HSD analyses
195 were conducted to further investigate the significant differences between the treatment levels.

196

197 Experiment 3: Laboratory study

198 Since the wild bird trial suggested that avian predators could distinguish between the acoustically-
199 similar *B. terrestris* and *C. illustrata* alarm sounds, we conducted a third experiment using domestic
200 chicks as a model system to explore the capacity of birds to learn to differentiate between the two
201 stimuli. Day-old domestic chicken chicks (*Gallus gallus domesticus*, Ross 308 broiler strain, n=172)
202 were purchased from a commercial hatchery and housed in groups of <24 in holding pens of
203 dimensions 126cm x 84cm lined with sawdust. Holding pens were positioned so that chicks could get
204 no closer than 2m from the experimental enclosures because at this distance, as with the wild bird
205 experiment, experimental acoustics would be sufficiently quiet as to not influence birds while not
206 being experimented upon. . Chicks were housed under a brightness of 40 lux under a light cycle of
207 23L: 1D for the first two nights with the dark period increasing by one hour on subsequent nights.
208 Poultry shed temperature was 30°C for the first three days then reduced to 28°C. Water was always
209 available and chick crumb feed (from Target Feeds Ltd.) was also constantly available in feeding
210 trays except during experimental periods when food deprivation was imposed in accordance with
211 Home Office regulations and authorised by the University of Leeds ethics committee. Chick crumb
212 feed was used throughout the experiment to avoid introducing additional visual and taste stimuli that
213 could interfere with responses to acoustic signals. Studies of multi-modal mimicry or more realistic
214 experiments incorporating ecologically relevant combinations of stimuli should consider using pastry
215 model prey.

216

217 The experimental arena was a sawdust lined cage measuring 42cm x 84cm containing a Veho 360°
218 speaker (Veho, Southampton, UK: model VSS-001-360), an Alba MP3 player (Alba, Milton Keynes,
219 UK: model 189/9935) and a feeding tray holding approximately 500g of chick crumb. On the first day

220 post-hatch chick pairs were placed in the experimental arena and supplied with plain chick crumb
221 twice during the day to acclimatise them to the experimental set-up (Skelhorn et al., 2010). Chicks
222 remained in the arena until both chicks had pecked at the feed and were then allowed to remain in the
223 arena for a further minute so that an association between feeding in the arena and being handled, a
224 potentially stressful and negative experience, would not develop. Chicks were trained and tested in
225 pairs since the “buddy method” involving separating chicks using mesh cages but retaining visual and
226 auditory contact as described in Skelhorn et al. (2010) were found to be insufficient to prevent chicks
227 from becoming distressed. Hence the paired trials were used due to ethical considerations to reduce
228 the stress of the animals being separated from the rest of the group. Such stress is not only an animal
229 welfare issue in and of itself, but would also influence the behaviour of the animals such that
230 experimental data may not be reliable. Individual adult birds which are less stressed by solo foraging
231 tasks may give more precise individual-level behavioural data (i.e. independent of social factors), but
232 would not have been naïve at the start of the experiment.

233

234 On the second day post hatch chicks were divided randomly into four equal groups (n=43) and
235 allocated to one of four feeding regimes. One training regime, representing aposematic prey, was
236 provided with the acoustic stimulus of post-attack *B. terrestris* and provided chick crumb given a
237 bitter flavour using Bitrex solution (6ml 5% Bitrex solution per 500g of crumb (Mostler, 1935)). The
238 three other regimes were provided with unaltered chick crumb, representing undefended prey,
239 presented with either a synthesised tone of 120Hz, post-attack *C. illustrata* sound or silence. Acoustic
240 stimuli were supplied constantly while chicks were in the arena by the speaker at between 56.4 and
241 59.8Db, as established as an ecologically relevant level in the field study. Chicks were trained in this
242 regime for three days before each group was further split into four groups (n≥10 in each group), each
243 of which was tested once on one of the four treatments thus achieving a fully-factorial design of
244 training vs. testing. During both the training and the testing phase chicks were deprived of food for 30
245 minutes before entering the arena, latency to peck at the food by each chick in a pair was recorded and
246 chicks were allowed 30 seconds after pecking before being removed from the arena.

247

248 *Laboratory study data analysis:* Two-way ANOVAs were run using R to compare the latency to
249 attack the baits during the testing phase, with the training treatment, testing treatment, and the
250 interaction of training and testing as predictors. Using one-way ANOVAs, we further analysed the
251 overall response to the different cues across training and testing phases, the response of bee-trained
252 chicks to the four test treatments, and the response of chicks trained in each of the four cues to the bee
253 test treatment. Tukey's HSD tests were used to investigate the data further where there was a
254 statistically significant effect in the full model.

255

256 **Results**

257 *Experiment 1: Comparison of acoustic signals*

258 The Hymenoptera *Bombus terrestris* (MANOVA: $F_{2,35}= 54.340$, $p<0.001$, Pillai's trace=0.756), *B.*
259 *hortorum* (MANOVA: $F_{2,9}= 6.696$, $p=0.017$, Pillai's trace=0.598), and *B. lucorum* (MANOVA: $F_{2,17}=$
260 44.797 , $p<0.001$, Pillai's trace=0.841), and the Syrphidae *Cheilosia illustrata* (MANOVA:
261 $F_{2,8}=24.036$, $p<0.001$, Pillai's trace=0.857) were the only species to generate significantly different
262 flight and alarm sounds. A slow motion video showing the transition between flight and alarm sound
263 production can be seen in the Supplementary Information, and Figure S2 shows the difference
264 between acoustic waveforms from flight and alarm sounds in *B. terrestris*, *C. illustrata*, and the
265 syrphid *Episyrphus balteatus*. When the percentage dissimilarity of flight and alarm sounds was
266 analysed across the hoverflies (excluding singletons), there was a strong positive correlation with
267 body size (Pearson correlation: $R=0.741$, $p=0.014$, $n=10$; Figure 1), indicating that larger animals
268 produced alarm sounds that were more distinct from their flight sounds.

269

270 Linear discriminant analysis showed that the flight sounds of the species were clustered together with
271 no clear separation of Hymenoptera and hoverflies (Figure 2A) but that the five hymenopteran
272 *Bombus* sp., and the three syrphids *C. illustrata*, *Eristalis tenax*, and *Leucozona lucorum* showed
273 similar alarm sounds (Figure 2B; though note that *L. lucorum* is represented by a single individual). A
274 MANOVA on the full flight dataset confirmed that while there were differences between species in
275 flight sounds ($F_{88,536}=2.578$, $p<0.001$), there were no significant pair-wise differences after control for

276 multiple comparisons using false discovery rates ($p > 0.5$ in all cases; Figure 2A). A MANOVA on the
277 full alarm dataset confirmed that there were much stronger differences between species in alarm
278 sounds ($F_{88,540} = 3.998$, $p < 0.001$), and that *B. terrestris* produces an alarm sound that is significantly
279 different to those of all other species apart from the other *Bombus* species, *C. illustrata*, *E. tenax*, and
280 *L. lucorum* (as can be seen in Figure 2B).

281

282 Experiment 2: Field study

283 Baits presented with the post-attack sounds of *B. terrestris* experienced significantly lower attack
284 rates than those presented in all other conditions (Cox proportional hazards analyses: *C. illustrata*
285 alarm: $z = 2.804$, $p < 0.010$; *C. vomitoria* flight $z = 2.656$, $p < 0.010$; silence $z = 2.115$, $p < 0.050$, see Figure
286 3). These results demonstrate strong evidence for the evolutionary benefit of acoustic aposematism,
287 but do not seem to support a role for mimicry. However, it is unclear as to the characteristics of the
288 *Bombus* and *Cheilosia* signals that cause the birds to respond differently.

289

290 Experiment 3: Laboratory study

291 Our laboratory study tested three predictions. First, that chicks trained on distasteful food with *B.*
292 *terrestris* sound would show greater latency to peck at both *C. illustrata* and *B. terrestris* food in the
293 test phase, indicating a generalisation of the acoustic cue. The results showed that chicks trained on
294 the *B. terrestris* food treatment exhibited no difference in latency to attack any of the four food
295 treatments in the test phase (ANOVA: $F_{3,40} = 0.766$, $p = 0.520$; Figure 4A). Second, that chicks trained
296 on palatable (i.e. not *B. terrestris*) foods would show lower latency to attack when tested on *B.*
297 *terrestris* food, indicating that they had learned that the sounds were associated with palatable food.
298 Here, we found that chicks' latency to attack the *B. terrestris* food treatment during the testing phase
299 was not significantly influenced by their food treatment during the training phase (ANOVA:
300 $F_{3,43} = 0.319$, $p = 0.812$; Figure 4B). Finally, that chicks respond to acoustic cues without discrimination,
301 in which case we would expect a greater latency to peck at foods presented with acoustic stimuli vs.
302 silence, irrespective of trials, testing, and training. We found a significant difference in latency to
303 attack across all encounters (training and testing) between acoustic stimuli (ANOVA: $F_{3,667} = 5.578$,

304 p=0.001; Figure 4C), and that this involved significantly shorter latency to attack the silent food
305 compared to *C. illustrata* (p=0.002) or *B. terrestris* food (p=0.014), and borderline significance in the
306 shorter latency to attack the tone food compared to *C. illustrata* food (p=0.051). These results suggest
307 that while training did not appear to have an effect on predator interactions there may be a general
308 heightened latency to attack when food is presented with an acoustic cue (as has been suggested
309 previously; Rowe and Guilford, 1999), with some suggestion that it is insect sounds specifically rather
310 than sound *per se* that delay predation.

311

312 **Discussion**

313 This study presents three complementary experiments: (i) a comparative analysis of the presence of
314 acoustic mimicry demonstrating the mimetic links between several *Bombus* species (a Müllerian
315 complex) and a subset of Syrphidae. Specifically, the similarity of alarm sounds indicate that *Bombus*
316 species represent a group of Müllerian acoustic mimics, and that *C. illustrata*, *E. tenax*, and possibly
317 *L. lucorum* are Batesian acoustic mimics of the *Bombus* group; (ii) a field based predation experiment
318 under ecologically-relevant conditions that demonstrates a benefit to the aposematic signal using
319 naturally-foraging birds but not for the acoustically-similar mimetic signal produced by a hoverfly;
320 and (iii) a tightly-controlled laboratory study using a model avian visual system to demonstrate that
321 there is a general aversion to sound (and insect sounds in particular) but no innate avoidance of the
322 *Bombus* alarm sound. This allows us to conclude that some hoverflies produce sounds that are
323 indistinguishable from those of Hymenoptera based on acoustic analysis, that there is no innate
324 avoidance to Hymenoptera sounds in particular, and that aposematic sounds enhance survival (but
325 mimicry of those sounds by syrphids may not). The findings complement previous work on
326 morphological and behavioural mimicry in this system (Penney et al., 2012; Penney et al., 2014).

327

328 As bumblebees use pheromones to warn conspecifics of predators (Goodale and Nieh, 2012) and are
329 unable to detect airborne sounds (Hunt and Richard, 2013) it is reasonable to assume that the observed
330 acoustic change from flight to alarm sound has evolved as an aposematic alarm signal. While our
331 findings from Experiment 1 are consistent with an explanation of Müllerian mimicry for the shared

332 alarm sounds of the *Bombus* sp., this pattern could also be explained simply through shared
333 evolutionary history. Despite experimental work demonstrating the benefits of Batesian mimicry of
334 *Bombus* sp. (e.g. Brower et al., 1960), experimental work demonstrating generalised avoidance of
335 *Bombus* congeners is lacking. All other Hymenoptera examined here immediately began biting and
336 stabbing their abdomen at the simulated predator suggesting that in these species conditioning the
337 predator not to attack similar individuals in the future is preferable to the survival of individual
338 workers. Considering the significantly smaller size of *Bombus* colonies compared to other social
339 hymenopterans (*Bombus* <100, *Apis* <100 000 and *Vespidae* <1000; data from (Bourke, 1999)) and
340 the greater energetic investment needed to produce larger workers it is considerably more costly to
341 lose an individual worker and therefore preferable to facilitate escape. Therefore there is greater
342 selective pressure for *Bombus* species to develop additional modes of signalling to their predators and
343 facilitate escape. Moreover, bumble bees are more robust, accumulating terminal levels of damage
344 more slowly than other insects when attacked (Krebs and Avery, 1985) allowing them more time to
345 escape during an attack. These factors could allow for the evolution of an aposematic alarm signal that
346 could encourage the predator to release the individual, and which could be exploited by mimics. As
347 far as we know there have been no experimental studies prior to our own that have attempted to move
348 beyond conjecture with respect to the alarm sounds. There are a number of studies that have proposed
349 a role for the sounds as acoustic aposematic signals, such as Kirchner and Roeschard (1999) who
350 described a “hissing” of bees in response to nest invasion, air currents, and the presence of mice
351 (which showed aversion to the sound). Those hissing responses were never associated with escape
352 behaviour. In addition, our own high speed video work (see Supplementary Information for a link to
353 the video online) demonstrates that the alarm sound in *Bombus terrestris* is associated with a change
354 in wing stroke amplitude which does not seem biomechanically appropriate for an escape behaviour.
355 We suggest that it has more in common with wing whirring (as used during behavioural
356 thermoregulation), with the wings decoupled from the flight muscles, to produce an acoustic
357 aposematic signal.

358

359 The putative acoustic mimics, *C. illustrata* and *E. tenax*, are two of the three largest mimics in this

360 study (Figure 1). This finding, along with the observation that there is a significant positive
361 correlation between size and the capacity to generate alarm sounds, is consistent with the relaxed
362 selection hypothesis that suggests that larger species that are more profitable prey and suffer higher
363 predation rates should develop greater levels of mimetic fidelity than smaller, less rewarding species
364 (Penney et al., 2012; Sherratt, 2002). Furthermore, we can confirm that this behaviour is not a feature
365 of all large syrphids as *Volucella pellucens* was the second largest species but lacked obvious acoustic
366 mimetic qualities. While flight and alarm sounds of *V. pellucens* were different according to their
367 probability mass functions (Figure 1), there was no significant difference between the two
368 (MANOVA: $F_{2,10}=0.146$, $p=0.864$) and LDA grouped *V. pellucens* with the larger group of non-
369 mimetic species (Figure 2B). It is possible that this species has evolved other means of predator
370 avoidance, and observations by the authors of the fly's considerable speed and agility during flight
371 have recently been supported by laboratory comparisons which show that *V. pellucens* is among the
372 fastest syrphid fliers and can generate considerable aerodynamic force (Belyaev et al., 2014). Our
373 results imply that, as has been suggested for behavioural mimicry (Penney et al., 2014), acoustic
374 mimicry may be restricted to large, high-fidelity mimics. The results therefore provide the novel
375 suggestion that mimics may resemble different models in different mimetic modalities, although
376 previous work has interpreted a similar pattern as a lack of acoustic mimicry (Rashed et al., 2009).
377 However, it is interesting to note that *C. illustrata* is considered to be a morphological mimic of
378 *Bombus pratorum*, while *E. tenax* is considered to be a morphological mimic of the honeybee, *A.*
379 *mellifera* (Howarth and Edmunds, 2000). *L. lucorum* is easily confused with *C. illustrata* (Ball and
380 Morris, 2013), but is not considered to be mimetic and lacks the colour patterns of *B. pratorum*.
381 Indeed, we argue for a re-evaluation of Rashed et al.'s work, the results of which are broadly
382 consistent with those of the present study, which also demonstrated similarity between *Bombus* alarm
383 sounds and those of some hoverflies. We propose that where morphological and acoustic mimicry
384 appear to rely upon different models this constitutes a "multi-model" mimicry system (Edmunds,
385 2000).
386
387 The fact that just two of the species investigated exhibit acoustic mimicry, and that Rashed et al.

388 (2009) were unable to find the phenomenon despite investigating a similar number of hoverflies of
389 arguably higher mimetic fidelity, such as *Spilomyia sayi*, demonstrates that this behaviour is not a
390 feature of all visually mimetic species. Our findings are consistent with a previous systematic survey
391 of behavioural mimicry in hoverflies, which revealed mimetic behaviours in only six species
392 (belonging to only two genera, *Temnostoma* and *Spilomyia*) out of 57 species that were assayed
393 (Penney et al., 2014). Our identification of two species which do appear to exhibit acoustic mimicry
394 from a relatively small sample, and which are found in two different tribes within the subfamily
395 Eristalinae, opens the possibility that acoustic mimicry may be more common than behavioural
396 mimicry in the Syrphidae, of which there are over 6000 identified species worldwide (Rotheray and
397 Gilbert, 2011).

398

399 Of particular interest in this study is the apparent lack of effect of the *Cheilosia illustrata* alarm sound
400 when presented to wild birds in the field, despite its acoustic similarity to that of *Bombus terrestris*.
401 There are two explanations for this pattern, which are not mutually exclusive. The first is that the
402 birds are able to discriminate between the sounds based on an aspect of the acoustic signal that was
403 not measured during the acoustic analysis. The second explanation is that the benefits of the acoustic
404 signal are dependent upon some other aspect of the mimic phenotype that is not represented in the
405 pastry prey. For instance, higher morphological mimicry is associated with behavioural mimicry,
406 suggesting that the benefits of morphological and behavioural mimicry may be contingent on one
407 another (Penney et al., 2014). This notion of the interdependence of the multiple sensory modalities
408 through which mimicry manifests poses a problem for experimental researchers, as it is a complex
409 task to remove one modality without affecting others. Previous work with invertebrate sensory
410 modalities has reduced the sensory perception of the signal receiver (Bretman et al., 2011) or removed
411 the capacity of a signaller to produce certain signals (Olofsson et al., 2012). However, such
412 manipulations would have serious ethical implications and low ecological relevance in this study.

413

414 While a substantial body of work now exists on the ecology and evolution of mimicry, combining
415 comparative, lab and field studies, there has been far less study of the mechanisms by which mimetic

416 traits are produced and the lability of the genes underlying those traits. The video in the
417 supplementary information suggests that the alarm sound in *Bombus* is produced by decoupling the
418 wings from the flight muscles to produce low amplitude, high frequency movements, similar to the
419 thermoregulatory behaviour known as “wing-whirring” (May, 1979). Interestingly a previous study of
420 thermoregulation also suggested that hoverflies make a high pitched noise during warm-up (Morgan
421 and Heinrich, 1987), and so it is possible that thermoregulation and acoustic mimicry are linked in
422 some way. That sound production identified in *Bombus* accompanies reduced wing movement
423 suggests these acoustics satisfy an alternative function to movement during an attack, supporting the
424 suggestion of an aposematic signal which *Syrphidae* were able to mimic due to a shared physiology.
425 What is needed to test this hypothesis is a survey of the internal anatomy during sound production
426 using a technique such as high speed cineradiography to compare the musculature of models and
427 mimics (Betz et al., 2008).

428

429 The findings described here represent the first empirical evidence linking the acoustic similarity of
430 Hymenoptera and Syrphidae acoustic signals to survival benefits in the field. However, further work
431 involving a larger array of acoustic signals is required to test these field patterns comprehensively. If
432 the survival benefits of acoustic mimicry in Syrphidae were to be confirmed, it would constitute the
433 third mode of mimicry in the Syrphidae alongside visual (Penney et al., 2012) and behavioural
434 (Penney et al., 2014), and all three modes suggest a role for body size in the evolution of mimetic
435 traits. Larger hoverflies generate sounds when attacked that are indistinguishable from those produced
436 by bumblebees immediately after attack while smaller and non-mimetic syrphid species are less able
437 to exhibit this behaviour as predicted by the relaxed selection hypothesis. A subsequent field
438 experiment demonstrated that avian predators preferentially avoided prey presented with post-attack
439 *B. terrestris* acoustic stimulus, confirming the presence of a selective pressure for the evolution of
440 acoustic aposematism and, potentially, for the evolution of mimicry in this predator-prey complex. An
441 experiment using naive predators demonstrated that the predator’s aversion is not intrinsic but is
442 developed over an extensive learning period and at considerable expense to the aposematically
443 signalling population. It is therefore suggested that further investigations into the interaction between

444 acoustic and visual mimicry using a multi-modal experimental design would yield interesting results
445 (Skelhorn et al., 2015). The discovery of a novel mode of mimicry in such a highly studied system
446 suggests that such acoustic mimetic complexes are likely to be present across the natural world,
447 particularly with acoustically dominant predators.

448

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456

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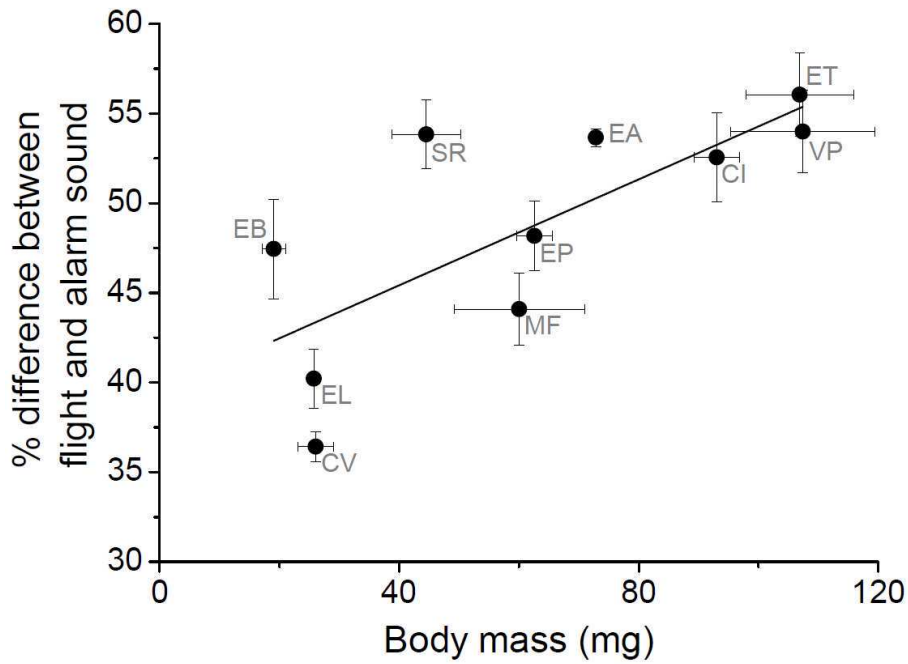
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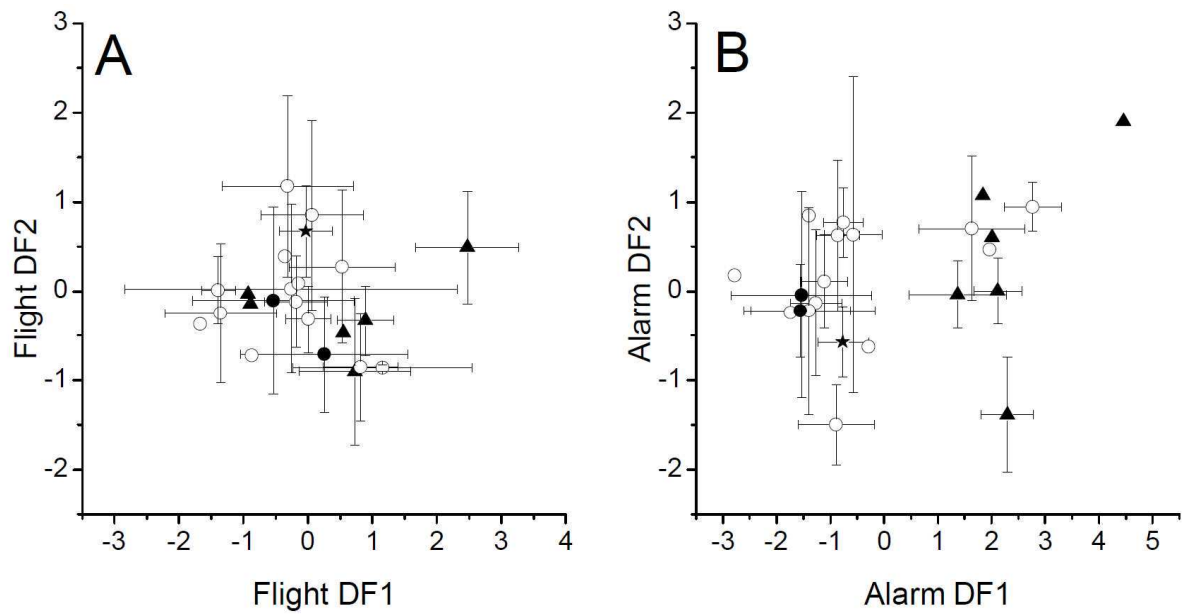
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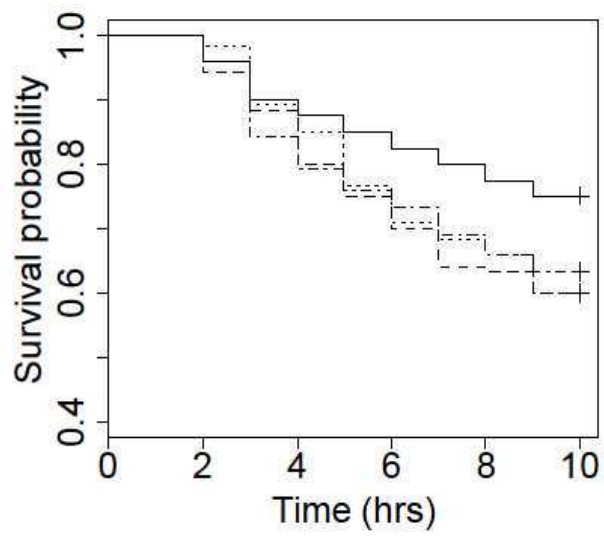
558

559 Figure 1: Larger-bodied hoverflies (Diptera: Syrphidae) exhibit a greater variation between their
 560 routine flight sound and their alarm calls, which resemble those of Hymenoptera. This finding follows
 561 the expectation of the relaxed selection hypothesis, whereby larger prey species are under greater
 562 selective pressure to evolve anti-predator defences. Abbreviations are: *Apis mellifera* (AM), *Bombus*
 563 *terrestris* (BT), *Calliphora vomitoria* (CV), *Cheilosia illustrata* (CI), *Episyrphus balteatus* (EB),
 564 *Eristalis arbustorum* (EA), *Eristalis pertinax* (EP), *Eristalis tenax* (ET), *Eupeodes luniger* (EL),
 565 *Myathropa flora* (MF), *Syrphus ribesii* (SR), and *Volucella pellucens* (VP).



567

568 Figure 2: Linear discriminant analysis showed that while (A) flight sounds were very similar across
 569 hoverflies and their Hymenopteran models, (B) there were two discrete groups of species that produce
 570 different types of alarm call. This latter group includes all six *Bombus* species and the mimics
 571 *Eristalis tenax*, *Cheilosia illustrata*, and *Leucozona lucorum*. Points are species means (open circles =
 572 hoverflies, filled circles = Vespidae, triangles = *Bombus* sp., star = *Apis mellifera*) and error bars are
 573 95% confidence intervals.

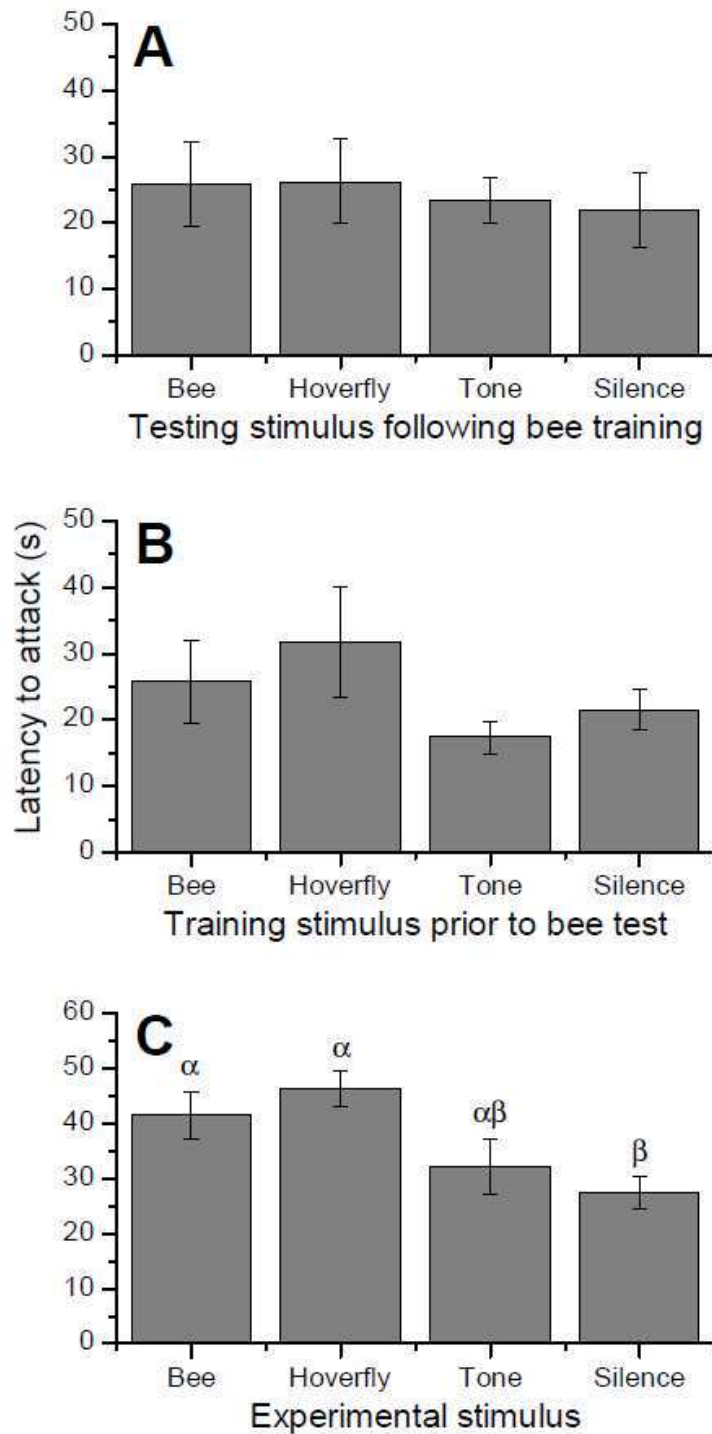


574

575 Figure 3: Survival of identical baits presented to wild birds with four acoustic stimuli: post-attack

576 *Bombus terrestris* (solid line), post-attack *Cheilosia illustrata* (dotted line), *Calliphora vomitaria*

577 flight (dashed line), and silence (dot-dash line).



578

579 Figure 4: Results of experimental training of domestic chicks to recognise acoustic cues: (A) latency
 580 to attack between four types of food following training on distasteful food presented with a *Bombus*
 581 *terrestris* alarm sound, (B) latency to attack distasteful food presented with a *B. terrestris* alarm sound
 582 following training on four types of food, and (C) overall latency to attack different food types across
 583 all training and testing phases in the experiment. Bars are means and error bars represent 1SE.