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The eating capability: constituents and assessments

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Laura Laguna¹ and Jianshe Chen^{2,*}

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1. School of Food Science and Nutrition, University of Leeds, Leeds LS2 9JT, UK

9

2. School of Food Science and Biotechnology, Zhejiang Gongshang University,

10

Hangzhou, Zhejiang 310018, China

11

12 * Corresponding author

13 Tel: (00)86 571 28008904

14 Fax: (00)86 571 28008900

15 Email: jschen@zjgsu.edu.cn

16 **Abstract**

17 With the rapid growth of elderly populations, the food industry is under increasing
18 pressure to provide texture-modified food for safe consumption by these vulnerable
19 populations. The imminent technical challenges to the manufacturing of food for elderly
20 consumption are the lack of knowledge of the elderly's physiological capability to eat
21 and swallow and, particularly, the lack of technical guidance in matching texture
22 properties with the individual's capability of eating. This review proposes the term
23 "Eating Capability" to represent the individual's abilities for food consumption. This
24 term collectively includes the following four groups of quantifiable parameters: food
25 handling capability (e.g., hand gripping, finger gripping, and coordination), oral
26 manipulation capability (e.g., lips sealing, biting and mastication, tongue pressing, and
27 swallowing), oral sensing capability (e.g., tasting and texture discrimination), and
28 cognitive capability (e.g., information seeking and processing, opinion forming, and
29 decision making). According to this definition, various capacities related to eating
30 performance and, particularly, the implications of any impairment in such capability are
31 discussed in detail in this paper; we pay particular attention to vulnerable elderly
32 consumers. Another primary objective of the review is to introduce feasible techniques
33 and methods that are currently available for quantitative assessment of these parameters.
34 With the growing research activities in food for elderly, we hope that this review will
35 stimulate new thinking and help the food industry to establish novel techniques to
36 design and manufacture quality food for safe consumption by elderly people.

37 **Keywords:** eating capability, food oral processing, texture modification, mastication,
38 swallowing

39 **Highlights**

40 The frail population could not properly perform eating actions and are at risk of
41 malnutrition.

42 The assessment of the eating actions has namely “eating capability” and has been
43 explored in the following four domains: hand, oral, mental and sense capability.

44 A number of techniques and methodologies have been discussed for their use as
45 reliable assessments of the eating capability components.

46 **1. Introduction**

47 It is common knowledge that ageing will cause inevitable weakening of one's physical,
48 physiological, and mental capability. This weakening is also true for eating and oral
49 food consumption in many elderly people. An immediate effect of eating difficulty is
50 reduced food intake, an increased risk of malnutrition and, possibly, more infections
51 among elderly people (McLaren & Dickerson, 2000; Ono, Hori, Tamine, & Maeda,
52 2009), as well as a compromised quality of life. For these vulnerable consumers,
53 texture modified diets are required to ensure safe consumption.

54 To date, eating difficulties have mostly been studied from the perspective of personal
55 care, especially in nursing interventions with elderly (Westergren, Unosson, Ohlsson,
56 Lorefält, & Hallberg, 2002) and in the stroke population (Jacobsson, 2000). For
57 example, Westergren et al. (2002) studied eating difficulty among elderly living at
58 home and in the hospital by observing individuals' eating habits during a regular meal.
59 These researchers observed difficulties, such as in sitting, manipulating food on the
60 plate, transporting food to the mouth, opening and closing the mouth, and swallowing,
61 and found a close association of a high level of eating difficult with low energy intake
62 and malnutrition. In a separate study, Jacobsson (2000) drew similar conclusions after
63 studying the eating behaviour in people affected by stroke as well as in healthy elderly
64 people The author also video-recorded subjects consuming test-meals with different
65 consistencies (thin liquids, thick liquids, jelly drinks, banana and crisp bread) and

66 analysed their eating performance. The proper identification of difficulty in eating
67 actions helped both the carer and patient develop an appropriate rehabilitation strategy.

68 However, Jacobsson (2000) noted the lack of reliable instruments for eating
69 assessments. Assessments of an eating processing and the capability of food oral
70 consumption have thus far largely been experience-based and subjective. Assessments
71 were qualitative and easily influenced by the observer (Jacobsson, 2000). Outcomes
72 from such assessments were not often comparable between different studies. Therefore,
73 it is desirable to establish easily quantifiable parameters and methods for objectively
74 assessing these parameters. For this reason, the authors of this paper propose “Eating
75 Capability” as a collective term to represent an individual’s capability of oral food
76 consumption. Based on the fact that eating involves a series of food–body interactions,
77 the term eating capability should be a combination of one’s physical, physiological,
78 and mental-coordination capabilities in handling and consuming food. This paper will
79 explain the physical and physiological meaning of these capabilities and important
80 implications if one such skill is impaired. The main focus of discussion is on the
81 feasible methods for quantitative assessment of these capabilities. Our long-term aim is
82 to establish possible correlations between one’s eating capability and the textural
83 properties of food to ensure safe food consumption by vulnerable elderly consumers.

84 **2. Constituents of the Eating Capability**

85 During the eating process, one has to perform a sequence of coordinated actions.
86 Before food ingestion, the following actions must occur: manipulating food on the

87 plate with hands or cutlery, lifting up food for ingestion, jaw lowering for mouth
88 opening and more. After food is ingested in the oral cavity, the following are
89 performed either sequentially or simultaneously: jaw lifting and mouth closing, biting,
90 mastication, transporting, mixing, sensory detecting, saliva secretion, bolus formation,
91 swallowing, and more. All of these actions also involve opinion formation and
92 decision-making. To execute all of these actions, some specific capabilities (physical,
93 physiological and mental) are needed for execution and precision.

94 The associated capabilities needed for an eating process can probably be grouped into
95 the following four categories: the hand manipulation capability, oral manipulation
96 capability, sensation capability, cognition (mental) and coordination capability. All of
97 these capabilities can be collectively termed as the Eating Capability, as shown in
98 Figure 1. Each category of the eating capability can further be characterised by some
99 associated measureable parameters. The meanings and implications of capability
100 impairment will be discussed in detail in the following sections.

101 **2.1 Hand manipulation capability**

102 The hands are the most versatile parts of the human body, and they are essential tools
103 for all sorts of situations in our daily life. Any injuries, diseases, or distortions of the
104 hand can affect our quality of life (Olandersson et al., 2005). In relation to eating, the
105 hand manipulating capability is important both before and during the course of a meal
106 (food preparation and hand cutlery manipulation). This capability can be defined as the
107 ability of an individual to exert an appropriate force, in a coordinated manner, to

108 manipulate food from package opening until it reaches the mouth. In relation to
109 self-feeding, the following four types of actions require hand manipulation: food
110 package handling and opening; managing food on the plate (e.g., cutlery or butter
111 spreading); handling and lifting an object (e.g., a glass of water); and transporting food
112 from the plate to the mouth.

113 Regarding food preparation, many elderly consumers experience some difficulties in
114 opening certain types of packaging. Winder, Ridgway, Nelson, and Baldwin (2002)
115 also noted that difficulty in dealing with food packaging is the main barrier for elderly
116 consumers in food consumption, and it is often a cause of packaging-related accidents.
117 This phenomenon has been evidenced by a number of reported accidents in which
118 inappropriate tools were used in the opening process (Lewis, Menardi, Yoxall, &
119 Langley, 2007).

120 The action of grasping and lifting food objects from the plate to the mouth is directed
121 by a complex interplay between multiple sensorimotor systems to signal, analyse and
122 process the mechanical interactions and constraints between the body and object
123 (Nowak & Hermsdörfer, 2003). To overcome problems in hand manipulation, a range
124 of adaptive eating utensils has been developed. Examples include a nose cup to avoid
125 bending the neck in case of dysphagia, cutleries for people with grasping difficulties,
126 plate guards to avoid spillage in people with low vision, and a weighted mug for those
127 with tremor problems. Although these tools are very helpful, they only address a part
128 of the eating difficulties. For example, patients with Parkinson's disease have

129 trembling hands and difficulty co-ordinating cutlery on the plate and transporting food
130 to the mouth (Andersson & Sidenvall, 2001); also, those individuals who suffer from
131 skeletal muscle weakness (due to the ageing or pathology) have reported problems in
132 the hand grip precision and force (Kurillo, Zupan, & Bajd, 2004).

133 **2.2 The oral processing capability**

134 The oral cavity is the first part of the digestive tract and is bounded anteriorly by the
135 upper and lower lips (vermillion surface, mucosal lip, and labial mucosa), laterally by
136 the cheeks, superiorly by the hard palate and inferiorly by the tongue and muscles
137 attached to the internal side of the mandible (Pereira, 2012). Food oral processing is
138 conducted in a highly coordinated manner (coordinated actions of orofacial muscles,
139 lips, cheeks, teeth, tongue, and palate) and is under close control by the central nervous
140 system, which generates efficient masticatory movements (Koshino, Hirai, Ishijima, &
141 Ikeda, 1997). The main functional purposes of the process are to transform
142 non-swallowable food into a swallow-able bolus and to transport it smoothly from the
143 oral cavity into the stomach. The process includes all oral actions from the first bite up
144 to following swallowing (details are shown in Figure 2).

145 **2.2.1 Actions in the oral cavity: biting, mastication and swallowing**

146 **2.2.1.1 Biting**

147 The first bite (of a solid or semi-solid food) is conducted by forcible occlusion of the
148 opposing edges of the upper and lower incisors (Okada, Honma, Nomura, & Yamada,

149 2007). Although that it is a single event, the first bite can give abundant sensory
150 feedback about the textural features of the food, including the hardness, springiness
151 and cohesiveness, among others (Chen, 2009). During the bite, the pressure exertion on
152 teeth causes slight stretching of the periodontal ligaments, sending information to the
153 central nervous system for texture interpretation. The periodontal ligaments are able to
154 detect very small forces (1 N or lower) (Lucas, Prinz, Agrawal, & Bruce, 2004).

155 How first bite is conducted by an individual depends on a number of factors, such as
156 the physical properties of the food and subjects' physiological conditions. The
157 maximum biting force one can exert is affected by several factors such as the dentition
158 status and the jaw-closing muscle strength (Tortopidis, Lyons, Baxendale, & Gilmour,
159 1998), face morphology (i.e. adults with normal facial morphology have higher biting
160 force than long-faced adults) (Proffit, Fields, & Nixon, 1983), gender (males can apply
161 generally larger force than females), ethnicity (e.g. Eskimos are able to apply higher
162 biting force than white American) (Bourne & Szczesniak, 2003) and age (aging will
163 have reduced biting strength) (van der Bilt, 2012). The maximum biting force ranging
164 between 60N (Fontijn-Tekamp et al., 2000) and 700 N (Ferrario, Sforza, Serrao,
165 Dellavia, & Tartaglia, 2004) have been reported.

166 **2.2.1.2 Mastication**

167 The purpose of mastication is to reduce food into smaller particles that are suitable for
168 swallowing, with the help of saliva and, in some cases, the liquid released from the
169 food, resulting in the formation of a cohesive mixture (the bolus) (Jalabert-Malbos,

170 Mishellany-Dutour, Woda, & Peyron, 2007). The mastication process is a succession
171 of chewing cycles (Woda, Foster, Mishellany, & Peyron, 2006). Each cycle consists of
172 one jaw-opening, followed by one jaw-closing, movement, which is the rhythm
173 generated by a brain stem central pattern generator (Woda et al., 2006).

174 The possible consequences of impaired mastication capability vary and depend on its
175 causes. If this impairment is caused by tooth loss, individuals will generally have
176 changed eating habits and often prefer easy-to-chew or over-cooked food. Large food
177 particles may be swallowed, increasing the risk of choking for these individuals. If
178 reduced masticatory capability is tongue-related, individuals will have great difficulty
179 moving food within the oral cavity. The oral preparation phase for bolus swallowing
180 will be compromised. If the problem is due to inadequate secretion of saliva, bolus
181 formation will be difficult and a much longer oral processing time will be needed.

182 **Mastication and dentition**

183 One's masticatory capability includes the ability to grind or pulverize a chewable food
184 (de Liz Pocztaruk et al., 2011; Hatch, Shinkai, Sakai, Rugh, & Paunovich, 2001).
185 Physiologically, individuals have a large variation in their mastication behaviour (e.g.,
186 number of cycles, muscular activity, duration, or lateral and vertical mandible
187 movement) and can be grouped according to their masticating characteristics. The most
188 obvious grouping is by gender, as has been reported by Woda et al. (Woda et al., 2006),
189 who assessed electromyography (EMG) activities of chewing muscles and observed
190 significantly higher masticatory frequency in males than in females.

191 Masticatory efficiency decreases for subjects who have missing teeth (Fontijn-Tekamp
192 et al., 2000; Miyaura, Morita, Matsuka, Yamashita, & Watanabe, 2000). The contact
193 area between the upper and lower teeth is important for oral food breakdown.
194 Replacing missing teeth with dentures can improve mastication, but it cannot always
195 fully recover the efficiency of natural teeth (N'Gom & Woda, 2002). People who have
196 lost post canine teeth, and replaced them with removable dentures (Fontijn-Tekamp et
197 al., 2000; Kapur & Soman, 2006; Pocztaruk, Frasca, Rivaldo, Fernandes, & Gavião,
198 2008), have a significantly reduced masticatory function. For this reason, elderly
199 people who usually suffer from more tooth loss often have partially depleted
200 mastication capability.

201 Generally speaking, subjects with incomplete dentition swallow relatively larger food
202 particles even if they try to compensate for tooth loss with an increased number of
203 chewing cycles and longer duration of mastication (Woda et al., 2006). Bates, Stafford,
204 and Harrison (1976) observed that dentures can be loose and moveable during eating.
205 In such a case, the tongue has to be used to stabilize and aid the retention of dentures.
206 This means that dentition not only has a decreased efficiency of oral food breakdown,
207 the tongue's capability in positioning food could also be compromised.

208 The dentition status will also influence an individual's food choice. Rana et al. (Ranta,
209 Tuominen, Paunio, & Seppänen, 1988) observed that when the dentition status is low
210 (i.e., wearing complete dentures), the intake of difficult-to-chew food items (e.g., roots,
211 vegetables, fruits and meat) becomes less pleasing for denture wearers. Furthermore,

212 subjects with a reduced masticatory efficiency will often require extra work in food
213 preparation. For example, some fruits and vegetables need to have their skins removed
214 and some foods need to be overcooked to facilitate their mastication deficiency (Walls
215 & Steele, 2004). Table 1 summarizes the main problems that denture wearers suffer
216 compared to those with natural teeth.

217 **Mastication and the role of saliva**

218 Saliva is a biological fluid that is naturally secreted from inside the human mouth and
219 required for eating and oral health (Pedersen, Bardow, Jensen, & Nauntofte, 2002).
220 Saliva plays an important role in bolus formation by mixing with food particles to form
221 a coherent and smooth bolus (Prinz & Lucas, 1997). The enzymes (i.e., α -amylase and
222 lipase) in saliva are very active ingredients (i.e., starch and lipids) that attack some
223 food components and cause immediate structural breakdown and viscosity decrease.
224 Furthermore, saliva also plays an important role in sensory perception by functioning
225 as a reservoir, which holds food ingredients for a continuous flavour release
226 (Doyennette et al., 2011).

227 In addition to eating-related functions, saliva secretion ensures continuous rinsing of
228 the mouth and helps to clean the oral cavity against harmful pathogens. Lubrication
229 and protection of the oro-oesophageal mucosa is another important function of saliva
230 (Pedersen et al., 2002). The mucins present in saliva create a slippery effect so that a
231 food bolus can easily slide through the oesophagus (Pedersen et al., 2002). This finding

232 is perceived as critically important for safe swallowing (Engelen, Fontijn-Tekamp, &
233 Bilt, 2005).

234 Many health conditions could influence salivary secretion; in particular, many
235 medications cause diminished salivary secretion, a phenomenon that is clinically called
236 xerostomia (dryness in the mouth) (Walls & Steele, 2004). Subjects with xerostomia
237 will not only have problems with food chewing and swallowing, they will also have
238 problems with taste, speech, and tolerance of dentures (Narhi et al., 1992). The causes
239 of reduced saliva secretion can be either pathology-related or non-pathology-related.

240 Pedersen et al. (2002) reported cases of gland dysfunctions as a result of chronic
241 inflammatory autoimmune disease, endocrine diseases, neurological disorders, genetic
242 disorders, undernourishment, infections and other conditions, such as hypertension or
243 fibromyalgia, among others. Some medications/treatments (e.g., radiotherapy,
244 antidepressants or chemotherapy) can cause a significant loss of saliva secretion
245 (Pedersen et al., 2002). Some non-pathological statuses may also affect the saliva
246 secretion and composition. Budtz-Jørgensen et al. (Budtz-Jørgensen, Chung, & Rapin,
247 2001) reported that healthy elderly individuals often suffer salivary gland dysfunction
248 and xerostomia. The situation is worsened by the fact that many elderly may suffer
249 from other illnesses and be on regular medications.

250 **Mastication and the tongue**

251 The tongue is a mass of mobile muscle inside the oral cavity. Proper functioning of the
252 tongue is critically crucial for both eating and speaking. During oral food processing,
253 the tongue acts as a mechanical device for food manipulation and transportation (Heath,
254 2002) as well as the dominant source of energy to initiate bolus flow (Alsanei & Chen,
255 2014). Chemoreceptors and mechanoreceptors on the tongue surface act as the most
256 delicate sensation systems for detecting and discriminating the taste and textural
257 properties of food (Hiemae & Palmer, 1999). The tongue (Hiemae & Palmer, 1999)
258 also helps to move food distally through the oral cavity, from the anterior to the
259 pharynx (Pereira, 2012). Without a doubt, any dysfunction of the tongue (i.e., lack of
260 coordination or motor disorder) will provoke difficulties in eating and swallowing
261 (Ueda, Yamada, Toyosato, Nomura, & Saitho, 2004).

262 **2.2.1.3 Bolus swallowing**

263 Bolus swallowing is a transportation process that moves food from the oral cavity to
264 the stomach via the oral-pharyngeal-oesophagus tract. The entire process takes a few
265 seconds from the initiation to completion (Dodds, 1989). The swift switch between
266 breathing and swallowing is vital (Matsuo & Palmer, 2008). This is achieved by
267 physical closure of the airway from elevation of the soft palate (to seal off the nasal
268 cavity) and titling of the epiglottis (to seal off the larynx) as well as the neural
269 suppression of respiration in the brainstem (Nishino & Hiraga, 1991).

270 Dysphagia is the term that is often used to refer to those who have swallowing
271 disorders (Hori et al., 2009), and it affects to a range of populations, including the

272 elderly, dysphagia patients, cancer patients, and more. The exact effect of ageing on
273 oropharyngeal swallowing is not yet fully understood and requires collaboration
274 between oral physiologists, food scientists, and clinical researchers (Logemann, 2007).
275 The other collective group that is affected by swallowing disorders includes patients
276 who have a cerebrovascular accident or neurologic disorders. In addition to the above
277 causes, dysphagia symptoms can also be related to head and neck cancer (Langmore,
278 2003) (Gaziano, 2001) or Parkinson's disease (Palmer, Drennan, & Baba, 2000)
279 because of the general abnormalities in muscular movement (Troche, Sapienza, &
280 Rosenbek, 2008).

281 The major risks of inappropriate bolus swallowing are aspiration and choking. The
282 former is caused by accidental entering of food residues into the larynx pipe and will
283 cause a serious cough or even infection if oral bacteria also enter. The latter is caused
284 by the blocking of the airway by large food particles in the pharyngeal region and
285 could cause a fatal consequence (suffocation). Therefore, the capability of bolus
286 swallowing refers to two important aspects, the capability of muscle coordination for
287 swift switch between the breathing and swallowing actions and the strength of
288 swallowing muscle contraction to create a sufficiently high (oral) pressure to move the
289 bolus forward.

290 **2.3 Sensing capability**

291 Sensing capability is the ability of an individual to evaluate and perceive sensory
292 stimuli of food through the five human senses (sight, smell, taste, touch and hearing).

293 During eating, people enjoy and appreciate food via some specific sensory attributes,
294 including the appearance, odour/aroma/fragrance, consistency, texture and flavour
295 (aromatics, chemical feelings and taste) (Meilgaard, Carr, & Civille, 2006).

296 When the sensing capability for these sensory attributes is hampered by a physiological
297 factor (e.g., ageing), pathological state (e.g., stroke), or pathological treatment (e.g.,
298 chemotherapy cancer treatment), the losses and distortions of the sensing perception
299 can greatly compromise our enjoyment of eating as well as the appetite and overall
300 food intake. Some well recognized effects of sense impairment on the eating process
301 are summarized in Table 2.

302 **2.3.1 Vision**

303 Using the sense of vision, humans determine where an object is in 3-dimensional space
304 as well as its appearance (colour, shape, size, etc). In many cases, the first sensory
305 contact with food is through the eyes (Wadhera & Capaldi-Phillips, 2014). Therefore,
306 the capacity for sight is important to eating for two reasons, the sensory-motor (ability
307 required for reaching the food) and the sensory-satisfaction (visual pleasure of the
308 food).

309 With respect to the sensory motors abilities, Muurinen et al. (Muurinen et al., 2014)
310 showed that vision impairment affects the nutritional status due to the difficulties in
311 shopping, preparing and having meals. Crews and Campbell (Crews & Campbell, 2004)
312 found that old people with vision impairment reported more difficulty in preparing

313 meals than people with other sensory problems (19.2 % vs. 6.3 %). It was also found
314 that vision impairment was frequently associated with malnutrition (Muurinen et al.,
315 2014) or a low body mass index (BMI) (Steinman & Vasunilashorn, 2011).

316 It has to be said that before a food is consumed, its appearance provides expectations
317 about the other sensory attributes (taste, flavour, palatability, etc) influencing food
318 acceptance and consumption (Hurling & Shepherd, 2003). Previous authors have
319 indicated that vision affects the taste quality and hedonic rating of food items (van
320 Beilen et al., 2011; Verhagen & Engelen, 2006), affecting odour perception (Engen,
321 1972) and, consequently, appetite (or the motive that makes a person seek food) (De
322 Graaf, Blom, Smeets, Stafleu, & Hendriks, 2004).

323 **2.3.2 Smell**

324 The olfactory system is responsible for sensing and detecting the entire spectrum of
325 food aroma, through either sniffing or during mastication when volatile compounds
326 stimulate via the retro nasal system (Popper, 2003). The olfactory epithelium has been
327 shown to be sensitive to trauma, disease and aging. Olfactory receptors could also be
328 targets of several viral agents (Stroop 1995). Dysfunction on the olfactory system is
329 called hyposmia and a complete loss of the ability to smell is called anosmia
330 (Havermans, Hermanns, & Jansen, 2010).

331 Havermans et al. (2010) affirmed that the hedonic evaluation of the food rested on its
332 flavour (taste and smell). If one is unable to perceive food aromas, the flavour

333 diminishes. Duffy et al. (Duffy, Backstrand, & Ferris, 1995) studied how the olfactory
334 dysfunction affects daily living and observed that elderly individuals with olfactory
335 dysfunction had lower interest in food-related activities (e.g., cooking) and lower
336 preference for many nutritious food (e.g., sour/bitter taste as citrus fruits), but they had
337 a higher intake of sweets and fat. Surprisingly, many elderly were not aware of the loss
338 of olfactory capability (Popper, 2003), which was probably because the loss of this
339 capability is often gradual and occurs over a period of many years (Rolls, 1993).

340 Trigeminal sense is another important sensing mechanism that is linked to olfactory
341 receptors. Some chemical irritants (e.g., ammonia, chilli peppers, and menthol) can
342 stimulate the trigeminal nerve ends (Meilgaard et al., 2006). The trigeminal nerve
343 innervates the nasal passageways. It is linked to olfactory receptors, but it is separated
344 from the olfactory nerve. It has been reported that anosmics have an increased
345 threshold of trigeminal substances, which can hamper sensory enjoyment (Van Toller,
346 1999).

347 **2.3.3 Taste**

348 Taste is a gustatory function that is defined as a chemical stimulation to taste receptors
349 in the oral cavity. The following five primary tastes have been identified: sweet, sour,
350 salty, bitter and umami and, in food applications, the combination of these basic tastes
351 forms various complex tastes (Brondel, Jacquin, Meillon, & Pénicaud, 2013). Taste
352 alteration occurs often among elderly populations, but physicians frequently overlook
353 its negative implications to health. One well-known fact is that taste alteration can

354 aggravate the anorexic states and contribute to malnutrition (Brondel et al., 2013).
355 Compared with younger individuals, the elderly have greater difficulty detecting the
356 presence of sweet, sour, salty or bitter as well as umami (Schiffman & Graham, 2000).
357 For many elderly people, taste problems are also associated with cancer and cancer
358 treatment (Ravasco, 2005), diabetes, renal and liver conditions, arthritis, Alzheimer's
359 disease, cognitive impairment, and the use of certain medications (Boltong &
360 Campbell, 2013).

361 Both smell and taste are sensory features via chemosensory mechanisms. The two
362 sensory features are closely linked and are influenced by each other. In particular, a
363 change in the olfactory capability can significantly affect how a food tastes (Ravasco,
364 2005). Such cases are usually treated as chemosensory disorders, which are linked to
365 the decrease of food acceptability (Mattes et al., 1990). Hutton, Baracos, and Wismer
366 (2007) found that weight loss is a common finding among individuals who are
367 suffering from altered taste and smell perception.

368 Taste alteration can be classified into the following three different categories according
369 to Schiffman and Graham (Schiffman & Graham, 2000): totally absent (ageusia),
370 reduced capability (hypogeusia) and distorted capability (dysgeusia). This grading is
371 rather qualitative in assessing the individuals' sensing capability. A more quantitative
372 assessment can be made based on the threshold determination for either detecting or
373 discriminating some particular tastes.

374 **2.3.4 Touch**

375 The sense of touch can be divided into two different categories (Meilgaard et al., 2006),
376 somesthesia (tactile, skin feel) and kinesthesia (deep pressure). The former refers to the
377 touching senses felt through the surface nerves responsible for the sensation of
378 touching pressure, heat, cold, itching and tickling, while the latter is felt through nerve
379 fibres in the tendons, muscles and joints.

380 Both somesthesia sensing and kinesthesia sensing contribute to our texture sensation.
381 Once the food is inside the oral cavity, the texture will be perceived by numerous
382 mechanoreceptors as well as thermoreceptors located underneath oral surfaces. The
383 tongue, periodontal ligament and tissues lining of the oral cavity provide kinesthetic
384 information from the oral musculature (Essick & Trulsson, 2009). Previous studies
385 have reported that individuals wearing whole or partial removable dentures have a
386 lower enjoyment of the food texture, which is probably from the reduced tactile
387 information from the mouth (Popper, 2003).

388 A very recent study conducted in the authors' group revealed a huge variation in the
389 touching sensitivity among human populations (Laguna et al., 2015). A comparison
390 between the elderly population and young population showed a substantial difference,
391 wherein elderly people had a much higher threshold of tactile detection. The effects of
392 weakened touching sensitivity on an individual's health and well-being have not been
393 fully explored. However, some early evidence has shown that the consequences could
394 be serious. Smith et al. (Smith et al., 2006) reported that children with poorly
395 functioning tactile systems may have difficulty enjoying the texture of solid food.

396 **2.3.5. Proprioception**

397 Proprioception is defined as “the perception of body position and movements in three
398 dimensional space”. The overall proprioceptive performance of an individual is
399 determined by the quality of both the available proprioceptive information and an
400 individual’s proprioceptive ability (Han, Waddington, Adams, Anson, & Liu, 2015).

401 During eating, one needs to reach for food and bring it to the mouth. This “reach-to-eat”
402 action is guided by two different mechanisms, vision and proprioception (de Bruin,
403 Sacrey, Brown, Doan, & Whishaw, 2008). Visual impairment has led to great
404 difficulties for many elderly in food handling (section 2.3.1), and the loss of
405 proprioception sense is an added difficulty to the feeding action (Gordon, Ghilardi, &
406 Ghez, 1995).

407 **2.3.6 Hearing**

408 Hearing is another very important source of sensory perception. We do hear eating,
409 especially for crispy and crunchy food. Many authors have reported that the sound and
410 acoustic characteristics of a food product can influence the consumers’ appreciation
411 and enjoyment of the food (Luyten, Plijter, & Van Vliet, 2004). Hearing impairment
412 may negatively affect one’s eating experience and pleasure. However, people with
413 hearing impairment are still capable of appreciating crisp food. It is believed that
414 internal (skull) vibration could play an equally important role to that of external
415 acoustic transmission for sensing and appreciating crisp food (Van Der Bilt, de Liz
416 Pocztaruk, & Abbink, 2010).

417 **2.4 Mental and coordination capability**

418 The mental and coordination capability refers to the ability of an individual to make a
419 series of decisions in relation to feeding and being able (from a motor point of view) to
420 coordinate different tasks involved in an eating process. This requires appropriate
421 mental power and capability for information intake, information processing, opinion
422 forming, decision making, and action coordination. In relation to eating, one must be
423 able to make decisions, such as what to eat, how frequent, the quantity of intake, and
424 others. One should also be able to coordinate various actions linked to somatic
425 conditions or actions to perform the eating process.

426 **2.4.1. Mental capability for eating decisions**

427 Dovey (2010) explained that around the mealtime, there are many cognitive scripts.
428 The decision making on the type and quantity of food is based on a complex interplay
429 between biological, sensory, environment and learned influences. For healthy
430 individuals, the well-functioning appetite forms part of a feedback circuit that
431 influences the pattern of eating at the following three levels: first, the psychological;
432 second, the peripheral physiological and metabolic events; and finally, the
433 neurotransmitter and metabolic interactions in the brain. When the appetite system
434 does not operate harmoniously, numerous problems appear. The disruption of this
435 equilibrium could result in obesity or eating disorders, such as bingeing or vomiting.

436 There are clear indications that eating disorders is a frequent problem for people with
437 intellectual disability (Hove, 2004). For example, Rimmer and Yamaki (Rimmer &
438 Yamaki, 2006) noted that obesity is a major health threat in persons with intellectual
439 disability and that impaired cognitive capability diminishes both one's capability of
440 sensory perception and the control of food intake. The prevalence of obesity in adults
441 with intellectual and developmental disabilities is approximately two to three times
442 greater than that in the general population (Rimmer, Braddock, & Marks, 1995;
443 Rimmer & Wang, 2005).

444 In children with intellectual developmental deficits (sub-average in cognitive status),
445 different eating and feeding problems have also been reported. The problems include
446 mealtime tantrums, bizarre food habits, multiple food dislikes, selectivity by food
447 textures, delay or difficulty in chewing, sucking, delay in self-feeding, pica (ingestion
448 of non-eatable substances), overeating or under-eating, and rumination (Linscheid
449 1983). Gal, Hardal-Nasser, and Engel-Yeger (2011) also linked eating problems with
450 the intellectual developmental deficit (IDD)level. The authors found problems of
451 malnutrition across all groups with different levels of IDD.

452 **2.4.2. Mental capability and the coordination capability of eating actions**

453 Eating is a complex sensorimotor process that involves integration between the
454 functioning muscles and nervous system. For example, mastication involves
455 coordinated activities of the teeth, jaw muscles, temporomandibular joints, tongue and
456 other structures, such as the lips, palate and salivary glands. Similarly, a swallowing

457 action requires a complex coordination between breathing and bolus pushing. It
458 remains a myth how humans develop such skills since birth. Wolf (1992) studied the
459 eating (sucking) behaviour of new born babies. They demonstrated that milk sucking
460 requires a good coordination of breathing, sucking and swallowing, and involves
461 functional interactions between the jaw, tongue, soft palate, pharynx, larynx and
462 oesophagus. Brown and Ross (2011) further added that sensation coordination is also
463 an essential part of milk sucking. Infants must sense and react to tactile, kinaesthetic,
464 proprioceptive, olfactory, auditory and visual inputs to coordinate sucking, swallowing
465 and breathing.

466 Summerset al. (2008) also studied the activities of daily living in children who are 5 to
467 9 years old with developmental coordination disorder (deficit in motor skills). Through
468 focus group discussion and interviewing the parents, they investigated the eating
469 behaviour of these children, among other daily activities, such as dressing or oral
470 hygiene. They found that these children had difficulty with cutlery manipulation and
471 were slow in eating. Additionally, these children were often described as messy eaters.

472 In a separate study on children eating, Hung et al. (2012) observed reach-grasp-eat
473 tasks by children with cognitive problem and noted difficulty in the coordination
474 between their body parts. The researchers studied their movements to grab a biscuit
475 (cookie) and transport it to the mouth and observed that inappropriate rotation of the
476 head and wrist resulted in difficulty with the eating process.

477 Difficulties in end-point locations have also been observed in adults after strokes.
478 Malnutrition in stroke patients (Paquereau, Allart, Romon, & Rousseaux, 2014) is
479 common and caused by eating problems, such as inadequate lip closure, mastication,
480 dysphagia, and loss of sitting balance (McLaren & Dickerson, 2000), as well as other
481 difficulties, such as manipulating food on the plate or transporting food to the mouth
482 (Jacobsson, Axelsson, Wenngren, & Norberg, 1996). In the elderly population, stroke
483 is one of the major causes of functional disabilities and multiple researchers have
484 reported on its effects on eating in these people (McLaren et al. 2000, Jacobsson et al.
485 2000)

486 **3. Assessments of the Eating Capability**

487 **3.1 Hand manipulation capability**

488 The ability to manipulate food by hand involves two dimensions, an adequate force to
489 perform the movement (i.e., to lift a glass) and a degree of coordination to execute the
490 movement. These two dimensions are related and affect each other. For example, to
491 open an “easy to open” package, one has to first have sufficient hand dexterity (or
492 coordination) to initiate the peel force and second have enough force to tear the plastic
493 apart.

494 The capability of an individual in applying hand holding/gripping can be precisely
495 measured by various techniques. A hand dynamometer has been reported to be easy to
496 use for such a purpose (Sasaki, Kasagi, Yamada, & Fujita, 2007) (Figure 3). However,

497 the maximal voluntary grip force only reflects partial information of hand movement
498 and does not give information about the dynamics of the force application. To obtain
499 additional knowledge on the sensory-motor control, Hermsdorfer et al. (2003)
500 developed a method for dynamic holding and transporting different spherical objects,
501 allowing for analysis of the impairments of manipulative gripping control in patients
502 with a chronic cerebral stroke. Additionally Kurillo et al. (2004) used the load curves,
503 adding different end-objects of different shapes (nippers, pinch, spherical, lateral and
504 cylindrical grip, see Figure 3), so that they could monitor the functionality of different
505 hand muscles. This last device is more versatile and capable of providing different
506 types of gripping forces that are used in daily activities. The values obtained from such
507 measurements can give an effective indication of the strength and coordination of the
508 hand (as well as finger) muscles and, therefore, the capability of food handling.

509 The core concern of the hand manipulation capability assessment is the prediction of
510 user's confidence and the food and food package design. Marks et al. (2012)
511 investigated food package designs for elderly use and found that the current package
512 design were not fit for purpose. They reported that 82 % elderly found jam jars
513 difficult to open, 78 % mentioned difficulty with peel-able meat/cheese packages, 69
514 % mentioned difficulty with bottles, 68 % mentioned difficulty with peel-able coffee
515 containers, and 62 % mentioned difficulty with peel-able cereal packs. By measuring
516 the maximum hand gripping capability of elderly women, Lewis et al. (2007)
517 suggested that, for safe use by elderly women, the maximum opening torque for a
518 bottle/jar design should be no larger than 2 Nm.

519 Considering that the hand manipulation capability consists of two very different
520 aspects (the maximum magnitude of the gripping force and coordination of muscle
521 activities), authors tend to propose assessing this capability assessed in the following
522 two steps. First, use a hand dynamometer for general strength measurement of hand
523 holding and gripping. Second, use the finger gripping force to assess fine coordination.
524 The finger gripping force requires fine control of many minor hand muscles. This
525 measurement can be performed with some of the methodologies proposed by Marks et
526 al. (2012) and Kurillo (2004) or using the same gripping sensor for biting force
527 measurements (see section 3.2.1.2).

528 **3.2 Oral capability**

529 **3.2.1 Capability of oral force creation**

530 The oral cavity is the core focus of an eating process. Food conversion and sensory
531 perception all happens in this place. Food is chewed, moved, mixed, and squeezed
532 inside the mouth via a combination of various oral actions, involving the lips, teeth,
533 tongue, and other orofacial muscles. The capability of performing each action will
534 affect one's overall capability of eating and oral food processing.

535 **3.2.1.1 Lip closing force**

536 Lip closing is a very important oral function that helps to keep food inside the mouth
537 and prevents oral fluid escape. Proper lip sealing is even more critical during
538 swallowing when an elevated pressure is created inside the oral cavity. The capability

539 of lip sealing can be measured by the magnitude of the closing force by the two lips, as
540 has been reported in clinical studies of patients after cleft lip surgery (Trotman, Barlow,
541 & Faraway, 2007) and orthognathic surgery (Umemori, Sugawara, Kawauchi, &
542 Mitani, 1996). In earlier works, a dynamometer with dial gauges, manometer system,
543 and load cell with strain gauges have been used as pressure sensors to measure the lip
544 force against a certain point on the surface of the teeth. Many other rather simpler but
545 reliable methods have also been reported and examples are listed in Table 3.

546 The pressure distribution between closed lips can also be determined using a device
547 developed by Umemori et al. (1996). This device consists of the following three parts:
548 sensor cartridge, light source and connector, and it is capable of displaying images of
549 lips pressure-distribution. A much simpler version was developed later, which consists
550 of a sensor, lip adaptor and digital display. Ueki et al. (2012) used Lip de Cum (R)
551 with a lip holder (Ducklings (R)) for lip strength measurements. The device contains
552 four strain gauges. The subject closes his or her upper and lower lips without teeth
553 touching the device and detected signals are converted into a load value (N). Trotman
554 et al. (2007) designed a device where a load-sensitive cantilever with an integrated lip
555 saddle is mounted to an interdental yoke. First, the upper lip strength was measured.
556 Then, the lower lip force was measured as the interdental yoke reached the lower
557 mandible. The main benefit of the technique is that it not only registers the maximum
558 force, it also registers the reaction time, rising time, peak force and target force (Table
559 3).

560 Different tools have been used to measure the maximum pressure and time to reach the
561 maximum (Ueki et al. 2012 and Trotman et al. 2007). A combination of both
562 parameters could possibly give useful information about the roles of the lips during the
563 entire eating process. Although lip closing has been recognized as an important factor
564 that interferes with food oral processing and swallowing, very limited research has
565 been reported in literature, particularly for cases of elderly people.

566 **3.2.1.2 Biting force**

567 The biting force is an important variable that determines the functional state of the
568 masticatory system (Van Der Bilt, Tekamp, Van Der Glas, & Abbink, 2008). However,
569 although many studies have been reported in literature in this regard, there is no
570 standard procedure. More confusing is the large variation of the biting forces recorded
571 in different studies. For example, Fontijn-Tekamp et al. (2000) registered a highest
572 force of 125 N, while Ferrario et al. (2004) registered a maximum force of 700 N. Such
573 a variation could be understandable considering that the biting force determination
574 depends on a number factors, including the location (Ferrario et al. 2004), number of
575 teeth (Gibbs, Anusavice, Young, Jones, & Esquivel-Upshaw, 2002), shape of the
576 device used and compliance of its material.

577 Regarding the device location, Fontijn-Tekamp et al. (2000) measured the biting forces
578 in pre-molars, canines and incisor in individuals with natural teeth, full dentures and
579 overdentures (or fix dentures). Subjects with natural teeth were able to perform the

580 highest biting force with the pre-molars (~110-125 N), followed by canines (~70-95 N),
581 and incisors (~60-70 N).

582 The number of teeth included is another important influencing factor. With more teeth
583 involved in the measurement, the assessment of the oral action could be more relevant
584 to the reality. However, in dental studies, it is common to assess a single tooth or
585 single position for the efficiency of oral tooth implants (Flanagan, Ilies, O'brien,
586 McManus, and Larrow (2012).

587 Tortopidis et al. (1998) used three different shapes of the stainless steel force
588 transducer to measure the biting force at different positions (Figure 4). These
589 transducers used a similar model described by Lyons (1990), where two stainless steel
590 beams with two strain gauges were attached to each side of the beam with flexible
591 epoxy resin and wire to form a Wheatstone bridge circuit. The three transducers were
592 designed in shape and pattern to fit the space between the second premolars and first
593 molars on both sides (Figure 4a), between the anterior teeth (Figure 4b), and between
594 the second premolar and first molars on one side (Figure 4c) (Tortopidis et al., 1998).
595 The highest force was registered by the bilateral posterior transducer (580 N), and the
596 lowest force was registered on the anterior transducer (286 N).

597 While different devices can be used for biting force measurements, devices that require
598 considerable levels of mouth openings (more than 15 mm) are not desirable (Fernandes,
599 Glantz, Svensson, & Bergmark, 2003). Recently, a flexi-sensor (with only 1 mm
600 thickness) was reported for biting force measurement (Fernandes et al., 2003; Flanagan

601 et al., 2012; Singhet al., 2011). This slim design has the great advantage of minimal
602 inconvenience to the subjects during the biting test.

603 **3.2.1.3 Tongue capability**

604 The available techniques for studying tongue capability can be divided into techniques
605 that measure the tongue-palate contact and techniques that study the tongue movement
606 during oral processing and swallowing.

607 The tongue palate-contact refers to tongue pressing, an indication of the contraction
608 strength of the tongue muscles. Devices for such measurements normally consist of the
609 following two parts: a sensor inserted between the tongue and palate and a register for
610 data recording. The Iowa Oral Performance Instrument (IOPI) (see Figure 5a) is a
611 commonly used technique for this purpose, using a mobile plastic bulb to detect the
612 strength of tongue pressing (Ono et al., 2009). The Handy Probe System is similar to
613 the IOPI device, except that it uses a balloon instead (Figure 5e). A major problem of
614 using the above devices is that they are inconvenient and uncomfortable due to the
615 presence of a sizeable sensor inside the oral cavity, especially during swallowing.
616 Potential measurement error can be caused by improper bulb placement inside the
617 mouth (Butler et al., 2011). The design of multiple sensing probes (Figure 5c) involves
618 where three (or even more) air filled bulbs that are arranged in a sequence (Tsuga et al.,
619 2003). When the tongue presses the hard palate, pressures at different locations can be
620 determined. A great advantage of this design is that it can measure pressure the profile

621 rather than the pressure at a single point. However, a disadvantage is its inevitable
622 interference with normal tongue movement.

623 A more sophisticated device for measuring the tongue pressure is the palatal plate with
624 multi-sensors. Palates for measuring the tongue pressure during swallowing and
625 mastication were created (see Figure 5b). Ono et al. (2009) combined palate design
626 with the electromyography technique for simultaneous measurement of the tongue
627 pressure and muscle activities. The approach was extremely useful in revealing the
628 effects of denture wearing on swallowing for elderly people (Ono et al., 2009).
629 However, real applications of palatal plates could be difficult because the prostheses
630 require advanced techniques and are expensive to manufacture. Furthermore, subjects
631 often find it very uncomfortable and usually need a period of time to obtain used to the
632 plate. A sensor sheet (Figure 5d) consists of five measuring points, which are attached
633 directly to the palatal mucosa with a sheet denture adhesive (Hori et al., 2009). The last
634 two multisensors not only measure the tongue pressing strength, they also evaluate the
635 tongue movement during mastication and swallowing initiation.

636 For a proper study of tongue movement during oral processing and swallowing,
637 non-invasive imaging techniques, such as ultrasound imaging and videofluorography,
638 have been reported in literature. Ultrasound has been used to study the coordination
639 between the swallowing movement of the tongue and hyoid bone motion by placing
640 pellets on two spots of the tongue as markers (Stone & Shawker, 1986); then, images
641 are recorded and studied, frame by frame, for tongue movements (Böckler & Klajman,
642 1991). Videofluorography can also record the jaw and tongue movement, as has been

643 demonstrated by Okada et al. (2007). Researchers gave subjects a stick of sushi rice
644 containing a small amount of barium powder. To measure jaw gape, radiopaque
645 markers were glued to the buccal surfaces of the upper and lower incisors and a
646 calibrator was attached between the nose tip and upper lip so that the actual dimensions
647 and movements of the organs in the videofluorography images can be calculated. In this
648 way, researchers were able to record the jaw and tongue movement during the process
649 of eating and swallowing. They found that most of the food was swallowed in the first
650 swallow, and residual food was aggregated by the tongue into a bolus and then
651 swallowed in the last swallow, a process often called oral clearance.

652 Although imaging techniques provide a good understanding of the tongue behaviour
653 during the entire eating process, they are only qualitative, and the time required to
654 complete the test and image analysis is superior to the tongue-palate contact tests.

655 Additionally, the videofluorography technique may have concerns of safety and
656 well-being for the subject due to radioactive exposure. For this reason, IOPI or a handy
657 probe could be a good choice for assessing the tongue strength. The sheet sensor
658 developed by Hori et al. (2009) allows for accurate measurement of the pressure at
659 different points without dramatically interfering with mastication and swallowing. The
660 great advantage of this technique compared with multiple sensing and palate sensors is
661 the super thin sensor sheet, which can be flexibly adapted to the hard palate without
662 causing too much inconvenience for the subject.

663 **3.2.1.4 Orofacial muscle strength**

664 Electromyography (EMG) is the most common method for monitoring activities and
665 the strength of various orofacial muscles, especially those responsible for chewing
666 (Yemm, 1977). EMG records live bioelectrical signals of the target orofacial muscle,
667 such as the mandible elevator muscles (masseter and temporales) and mandible
668 depressing muscles (digastrics). The former gives information about the closing phase
669 of a chewing cycle, while the latter gives information about the mouth-opening phase
670 of a chewing cycle. By analysing the EMG signals developed during the chewing cycle,
671 one could assess the activities of chewing muscles and influences of food texture
672 (Mioche, 2004). Many literature studies have been reported on this topic. Experimental
673 set up and data analysis of the EMG technique can be found in a detailed review by
674 Gonzalez and Chen (2012).

675 Orofacial muscle strength can also be reliably assessed in an indirect manner. For
676 example, Alsanei and Chen (2014) measured the buccal muscular strength by assessing
677 the maximum mouth volume. Subjects were asked to retain as much water in their
678 mouths as they could from a cup container. Then, by recording the amount of the water
679 inside the subject's mouth, the maximum oral capacity can be calculated and, therefore,
680 the strength of the orofacial muscles can be evaluated based on the assumption that
681 good stretch-ability and elasticity of orofacial muscles (in particular, the cheek muscles)
682 are essential for a maximum oral volume. In this work, it was shown that the maximum
683 oral volume generally decreases as a function of age for the elderly populations.
684 Furthermore, during the experiment, water dripping from the mouth corner was
685 observed for some elderly subjects, which is a sign of poor lips sealing. It was

686 concluded that all of these factors (a lower maximum volume capacity and lower
687 capability of lip sealing) were effective indicators of weakened orofacial muscles that
688 will affect one's capability of eating.

689 **3.2.2 Masticatory capability**

690 As was explained in section 2.2.1.2, the masticatory capability depends on many
691 variables, such as the number of teeth, oral muscular force, oral coordination
692 (open-jaw-swallow) and saliva secretion. Therefore, it makes sense that the
693 masticatory capability should be assessed by collective measurements of these
694 contributing parameters.

695 A convenient way to assess the masticatory capability is observing the efficiency of
696 chewing some particular food that is either edible (e.g., peanuts, almonds, cocoa,
697 carrots, jelly, hazelnuts, decaffeinated coffee beans, nuts, chewing gums or gelatin gels
698 (Ahmad, 2006; Gambareli, Serra, Pereira, & Gavião, 2007; Schneider & Senger, 2002))
699 or non-edible, such as silicone-based artificial materials Optosil^R, OptocalPlus^R and
700 CutterSil^R (Fontijn-Tekamp, Van Der Bilt, Abbink, & Bosman, 2004) and
701 leaking-proof polyvinyl acetate capsules (de Abreu et al., 2014). The great advantages
702 of silicone-based materials are that they are inert to water and saliva (they are not
703 soluble or enzymatically active), homogenous (size, shape and toughness), lack
704 seasonal variation, and can easily be stored (Fontijn-Tekamp et al., 2004). However,
705 one large limitation is that these gels are not digestible and, therefore, must not be
706 swallowed (Pocztaruk et al., 2008).

707 The methods for studying the degree of food fragmentation include sieving,
708 colorimetric determination, and image analysis, which are often used to determine the
709 particle size distribution. In all of these cases, the food is expectorated before
710 swallowing and is then studied for the particle size distribution. In the sieving method,
711 particles of a collected food bolus are carefully filtered through various mesh sizes.
712 Then, the contents of the food particles at each sieve size are weighed and calculated as
713 a percentage of the total weight. Van Der Bilt et al. (2008) compared the results
714 obtained from a single sieving and multiple sieving method in 176 dentate subjects.
715 They found that the single sieve method is less reliable than the multiple sieve method,
716 although it involves less work compared to multiple sieving. Although it is relatively
717 tedious and could involve some significant experimental error, the sieving method is
718 still commonly used (Ahmad 2006). An alternative to sieving is the particle imaging
719 method using an image analysis program (e.g., Image-Pro from MediaCybernetics), as
720 has been used in several studies (Chen, Khandelwal, Liu, & Funami, 2013; Mowlana,
721 Heath, Bilt, & Glas, 1994).

722 All assessment methods that require the mouth contents to be expectorated (i.e., spat
723 out) before swallowing have the same disadvantage. Saliva and particles can
724 accidentally be swallowed during chewing, which will cause inevitable experimental
725 error. Yamashita, Sugita, and Matsuo (2013) found that part of the oral bolus may pass
726 to the pharynx during mastication before a spontaneous swallow was initiated;
727 therefore, only a portion of the “real” food bolus was collected.

728 For subjects who were not able to comminute the test food, Van Der Bilt et al. (2010)
729 developed a gum kneading method. Instead of breaking up food, this method
730 determines the masticatory capability by mixing/kneading of two differently coloured
731 soft foods (e.g., chewing gums). The extent of colour mixing was measured as a
732 function of the chewing cycles, and the masticatory efficiency of an individual can
733 then be assessed. The authors (van der Bilt et al. 2010) concluded that the
734 mixing/kneading ability test was effective and feasibly applicable to determine the
735 masticatory function in subjects with a compromised masticatory performance (e.g.,
736 elderly subjects with denture). However, the method was not feasible for subjects with
737 good masticatory performance (young subjects with natural teeth) because the task is
738 too easy for them and it does not meaningfully distinguish among such subjects.

739 **3.2.3 Swallowing capability**

740 An objective assessment of the swallowing process is not an easy task. The clinical
741 diagnosis of a swallowing disorder commonly uses techniques, such as
742 videofluorography and fiberoptic endoscopy. The videofluorography technique has
743 been used to study feeding models of dysphagia in pathological patients since 1980
744 (Ono et al., 2009). In the videofluoroscopy examination, fluid food of a certain
745 consistency is mixed with barium and fed to the patient while the patient sits in the
746 upright position (Langmore, 2003; Palmer et al., 2000). Radiography images are
747 recorded when the subject swallows a barium marked bolus (Palmer et al., 2000). With
748 videofluorography recording, the subjects' swallowing anatomic structures and motion

749 of the food bolus can be observed and monitored (Palmer et al., 2000). By feeding
750 patients food of different consistencies, the examiners are able to determine how
751 capable the patient is of dealing with a bolus (Palmer et al., 2000). Ono et al. (2011)
752 cited that the inability to demonstrate kinematical tongue biomechanics is a main
753 limitation of videofluorography. Also the application of videofluorography to a healthy
754 individual is considered to be unethical because of the radiation exposure (though it is
755 well within the safe limit). Fiberoptic endoscopic evaluation of swallowing consists of
756 a flexible trans-nasal laryngoscope entering deep in the oropharyngeal region. It has
757 been used to evaluate the path of bolus entry and coordination during a normal meal
758 (Dua, Ren, Bardan, Xie, & Shaker, 1997). The advantage of the trans-nasal endoscopy
759 is that the results can be obtained in real time and with no oral invasion (and, therefore,
760 no influence on tongue movement). Although both techniques are very useful for
761 studying swallowing, the use of these techniques requires clinical qualification, making
762 them less accessible for food scientists.

763 Koshino et al. (1997) reported on the use of ultrasound diagnostic equipment for
764 studying bolus movement, the onset and offset of bolus flow, the bolus moving speed,
765 and others. One great advantage of ultrasound measurements is that they are
766 non-invasive. The attachment of ultrasound probes around the neck does not cause any
767 noticeable impediment in bolus movement or in the actions of the tongue and other
768 swallowing muscles. However, this technique is non quantitative and frame-by-frame
769 image analysis is time consuming.

770 To the authors' knowledge, apart from the aforementioned techniques, no other
771 technique is readily available for assessing the swallowing capability. As a
772 compromise, the authors have used the tongue muscle strength as an indication of the
773 swallowing capability based on the fact that tongue pressing generates the first pushing
774 force for bolus flow. However, it must be noted that the tongue muscle strength
775 measurement only provides information about the oral propulsive capability. This
776 measurement cannot give any information about possible abnormalities that occur in
777 the pharyngeal or oesophageal areas.

778 **3.3 Sensing capability**

779 To quantitatively assess an individual's sensing capabilities, threshold detection has
780 been found to be the most practically feasible option. One's sensing capability can be
781 assessed by the following three very different thresholds (Meilgaard et al., 2006): the
782 absolute or detection threshold, recognition or identification threshold, and difference
783 threshold. The absolute or detection threshold is the lowest intensity of a physical
784 stimulus that is perceivable by the human senses of smell, taste, and tactile feeling. The
785 recognition or identification threshold is the level at which a stimulus is not only
786 detectable but also be recognised. The difference threshold represents the smallest
787 change in stimulation that a person can detect.

788 Although these senses have a very different nature, the determination of their threshold
789 shares the same approach as follows: an incrementing battery of intensities with a
790 forced response of perception. For example, the absolute threshold in hearing refers to

791 the smallest level of a tone that can be detected by normal hearing when there is no
792 other interfering sound. For vision, the absolute threshold refers to the lowest level of
793 light that a participant can detect.

794 In relation to food, the sensory thresholds to taste and odour are widely used. Various
795 validated methods have been proposed by some authentic organizations, such as the
796 American Society for Testing and Materials (ASTM) and International Organization
797 for Standardization (ISO).

798 Tactile sensitivity is one of the most important physiological functions used for food
799 texture sensation and perception. Unfortunately, tactile sensitivity has not been well
800 studied in relation to eating and texture perception even though clinical studies have
801 assessed patients with neuropathic illness and dental studies have evaluated oral tactile
802 sensitivity (Hämmerle et al., 1995). Semmes-Weinstein monofilaments (SWMs) are
803 probably the most commonly used technique for tactile sensitivity assessment (Selim
804 et al., 2010). The technique has recently been successfully used in the authors' lab to
805 assess reduced tactile sensitivity in elderly versus young people. Elderly people have
806 significantly decreased tactile sensibility compared to young subjects (Laguna et al.,
807 2015). Although it is logical to speculate that a decreased tactile sensitivity could mean
808 a decreased capability of texture discrimination, experimental evidence to prove such a
809 correlation is still lacking.

810 **3.4. Mental and coordination capability measurements**

811 The evaluation of the mental and coordination capabilities in relation to eating
812 performance has been investigated from some very different perspectives.
813 Psychologists assess the mental and coordination capability by identifying the eating
814 behaviour problem, mostly through semi structured interviews (Cooper & Fairburn,
815 1987). The intelligence quotient was also used to assess and identify possible
816 populations that are at risk for obesity (Emerson, 2005). Neuroscientists (Coluccini,
817 Maini, Martelloni, Sgandurra, & Cioni, 2007) studied the grasp task in children with
818 motor disorders using infrared cameras to record and analyse their body movement.
819 Parameters, such as the total task duration and duration of each movement component
820 (e.g., transport, reaching, grasp and release), have also been evaluated. Similarly, Hung
821 et al. (2012) used an infrared technique to study the movements involved in grasping a
822 biscuit and transport to the mouth. Apart from hand movement, the positions of the
823 head, shoulder, elbow and bilateral wrist were also analysed. They reported that
824 inappropriate rotation in the head and wrist caused eating difficulty in hemiplegic
825 children.

826 Scientists from other medical areas, such as paediatrics and carers, used observational
827 methodology to study the effect of disability on eating. Summers, Larkin, and Dewey
828 (2008) conducted a study using parents as observers of children with developmental
829 coordination disorders. Through focus group studies and interviews, they investigated
830 the main problems children have in performing daily activities. A positive point of this
831 study design is that the same environment was maintained throughout the study, and
832 task-interactions occurred in most natural manner, which was close to real

833 circumstances. However, the study is subjective overall, and few parents were
834 interviewed. In their discussion, Summer et al. (2008) affirmed that a longitudinal,
835 prospective study is needed; a standardized measure of their daily living performance
836 in the context of the family is also needed.

837 Although scientists have been working hard to seek ideal methodologies or techniques
838 for the quantitative assessment of mental and coordination capabilities in relation to
839 eating and food consumption, no major, comprehensive method or technique has been
840 reported. According to these authors, a key problem is the identification of
841 measurement parameters that are closely related to eating and food oral consumption.
842 Unfortunately, consensus about relevant parameters has yet to be reached. We hope
843 that this review will stimulate more thinking on studying eating capability and inspire
844 new ideas on the feasible assessment techniques for studies in this increasingly
845 important area.

846 **4. Summary**

847 Many elderly people and dysphagia patients suffer from loss in their quality of life and
848 malnutrition due to their diminished capability for eating. These vulnerable consumers
849 (among others) have all sorts of problems in food handling, oral manipulation, sensing
850 and perception as well as swallowing. The causes of these problems are either
851 physiological or pathological. One of the top priorities for the food industry and carer
852 industry is to provide food for that is safe for these consumers to eat.

853 This review proposes the concept of eating capability, aiming for the quantitative
854 assessment of both the eating and food consumption capability of vulnerable
855 consumers. The term consists of the following four main constituents: food handling,
856 food oral manipulation, sensation, and cognition. The physical and physiological
857 meanings of these parameters have been discussed based on abundant literature
858 findings for all four aspects.

859 In this work, we demonstrated that it is scientifically viable to use some measurable
860 parameters to represent and quantify the eating capability of an individual. To
861 accomplish this, a number of techniques and methodologies have been discussed for
862 their use as reliable assessments of the various components of the eating capability.
863 Whenever possible, the advantages and limitations of such techniques have also been
864 highlighted. We hope that this preliminary work will provide a knowledge base for
865 assessing the eating capability of vulnerable consumers and useful guidance for the
866 assessment techniques and methods. Looking forward, additional studies are needed to
867 address the following topics: (1) establishing ideal technical solutions for the reliable,
868 quantitative assessment of specific components of the eating capability; (2) the
869 possibility of integrating four different components to form a single function of eating
870 capability; and, more importantly, (3) the establishment of technical guidance in
871 matching one's capability of eating and the textural properties of food. Considering
872 those topics, the aim of this review was to provide an introduction to the topic rather
873 than an exhaustive summary of what has been achieved.

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