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# A pilot inference study for a beta-Bernoulli spatial scan statistic

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**Summary:** The Bernoulli spatial scan statistic is used to detect localised clusters in binary labelled point data, such as that used in spatial or spatio-temporal case/control studies. We test the inferential capability of a recently developed beta-Bernoulli spatial scan statistic, which adds a beta prior to the original statistic. This pilot study, which includes two test scenarios with 6,000 data sets each, suggests a marked increase in power for a given false alert rate. We suggest a more extensive study would be worthwhile to corroborate the findings. We also speculate on an explanation for the observed improvement.

**KEYWORDS:** cluster detection, case control study, spatial scan statistic, beta, Bernoulli

## 1. Introduction

Building upon the multiple scan window procedure of Openshaw et al. (1987), the spatial scan statistic (hereafter SSS) (Kulldorff 1997) is a widely used cluster detection tool in spatial epidemiology, and other fields such as criminology and forestry. Different SSS versions are applicable to different data types: the Bernoulli version is suitable for binary labelled point data, making it ideal for case/control studies.

The SSS has utility in GIS as it identifies statistically significant clusters in spatial, or spatio-temporal data, which may not be obvious to a human observer.

As part of an ongoing Bayesian study we have added a beta prior to create a beta-Bernoulli SSS (hereafter BBSSS). We have also found the BBSSS to have greater spatial accuracy, when tested head-to-head against the Bernoulli SSS on benchmark data. However, due to the differences in the Bayesian and frequentist approaches, we did not directly compare the inferential<sup>1</sup> capabilities of the two statistics.

This paper reports the initial findings of a separate study, using the beta-Binomial SSS in a frequentist manner which permits direct comparison between the two statistics using receiver operating characteristic (ROC) curves.

Section 2 outlines the scope of this research, Section 3 briefly outlines the BBSSS and gives details of our study. Section 4 presents results, Section 5 gives concluding thoughts.

## 2. Research background

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<sup>1</sup> The ability to distinguish whether a cluster is present, irrespective of how accurately cluster location is delineated.

Case/control studies have a useful role within spatial and spatio-temporal data analysis, a classic example being Diggle's (1990) spatial analysis of larynx cancer (cases) and lung cancer (controls). A more recent example is Diggle, Rowlingson and Su's (2005) analysis of emerging gastrointestinal symptom clusters, using historic incidents as controls, and recent incidents as cases.

Various statistical techniques are available for case/control studies, of which the above provide two novel examples. The Bernoulli SSS (Kulldorff 1997) can also be applied to case/control studies, and is freely available as SaTScan ([www.satscan.org](http://www.satscan.org)). However, the Bernoulli is under-researched, compared to other SSS versions (see bibliography in Kulldorff 2010). Developing a Bayesian SSS for areal data, Neill (2006) suggested adding a gamma prior, with parameters estimated from historical data. Investigating a Bayesian SSS for point data, we have added a beta prior to create the BBSSS, and found this to give improved spatial accuracy, using the new  $\Omega$  measure (Read et al. 2011). This paper extends our study of the BBSSS.

### 3. Methodology

Section 3.1 describes the BBSSS, Section 3.2 describes the tests used.

#### 3.1 A beta-Bernoulli spatial scan statistic

Study region  $R$  has  $N$  points, including  $C$  cases. Scan window set  $Z=\{Z_1...Z_k...Z_K\}$ , where  $Z_k (\subset R)$  has  $n$  points, including  $c$  cases. Each point  $p$  is an independent Bernoulli trial, where  $p$  is a case with probability  $q_{in}$  ( $p \in Z_k$ ) or  $q_{out}$  ( $p \notin Z_k$ ).

The null (no clustering) hypothesis is  $H_0$ , where  $q_{in}=q_{out}$ . The composite alternate hypothesis is  $H_A$ , where  $H_A(Z_k)$  assumes  $Z_k$  is a cluster location, hence  $q_{in} > q_{out}$ . If  $D$  is the particular distribution of cases and controls amongst the points, and  $q_{in} \sim \text{beta}(\alpha_{in}, \beta_{in})$  and  $q_{out} \sim \text{beta}(\alpha_{out}, \beta_{out})$ , then:

$$P(D | H_A(Z_k)) = \frac{B(\alpha_{in} + c, \beta_{in} + n - c)B(\alpha_{out} + C - c, \beta_{out} + N - n - C + c)}{B(\alpha_{in}, \beta_{in})B(\alpha_{out}, \beta_{out})} \quad (1)$$

where  $B(*, *)$  is the beta function. The BBSSS is then the probability of the most likely  $Z_k$ :

$$BBSSS = \sup_{\forall Z_k} [P(D | H_A(Z_k))] \quad (2)$$

Although this was developed for a Bayesian approach, Type I error probability can be obtained using Monte Carlo simulation.

To use the BBSSS, one must find  $\{\alpha_{in}, \beta_{in}, \alpha_{out}, \beta_{out}\}$  specific to each  $Z_k$ . Historic point data is likely to be used as controls (e.g. Diggle et al. 2005), so historic fitting is inappropriate. Instead we take the odds ratio  $OR$ :

$$OR = \frac{q_{in}(1 - q_{out})}{q_{out}(1 - q_{in})} \quad (3)$$

as having the same expectation  $E(OR)$  and variance  $V(OR)$ , regardless of cluster size or location. Making a few assumptions, one can estimate  $\{\alpha_{in}, \beta_{in}, \alpha_{out}, \beta_{out}\}$  for any given  $\{E(OR), V(OR), N, C, n\}$  using a one dimensional search over  $\beta_{in}$  with a fairly tight lower bound, incurring little computational expense.

### 3.2 Benchmark testing

Our benchmark data sets resemble those in Read et al. (2010). 12,000 data sets were organised in four batches, see Table 1. CSR (complete spatial randomness) indicates an homogeneous distribution of controls; TRENT an inhomogeneous distribution proportional to the 2001 census population of Trent (Figure 1).  $H_0$  batches contain no clusters. Data sets in  $H_A$  batches contain one randomly located area of Gaussian-shaped multiplicative increased risk, MRR being the *maximum relative risk* at the cluster's centre.

**Table 1.** Description of four batches of data set used in study

Batch code	Data sets per batch	Cases per data set	Controls per data set	Injected clusters per dataset	Cluster strength (MRR)
CSR_ $H_0$	3000	200	800	None	-
CSR_ $H_A$	3000	200	800	One	10
TRENT_ $H_0$	3000	200	800	None	-
TRENT_ $H_A$	3000	200	800	One	10

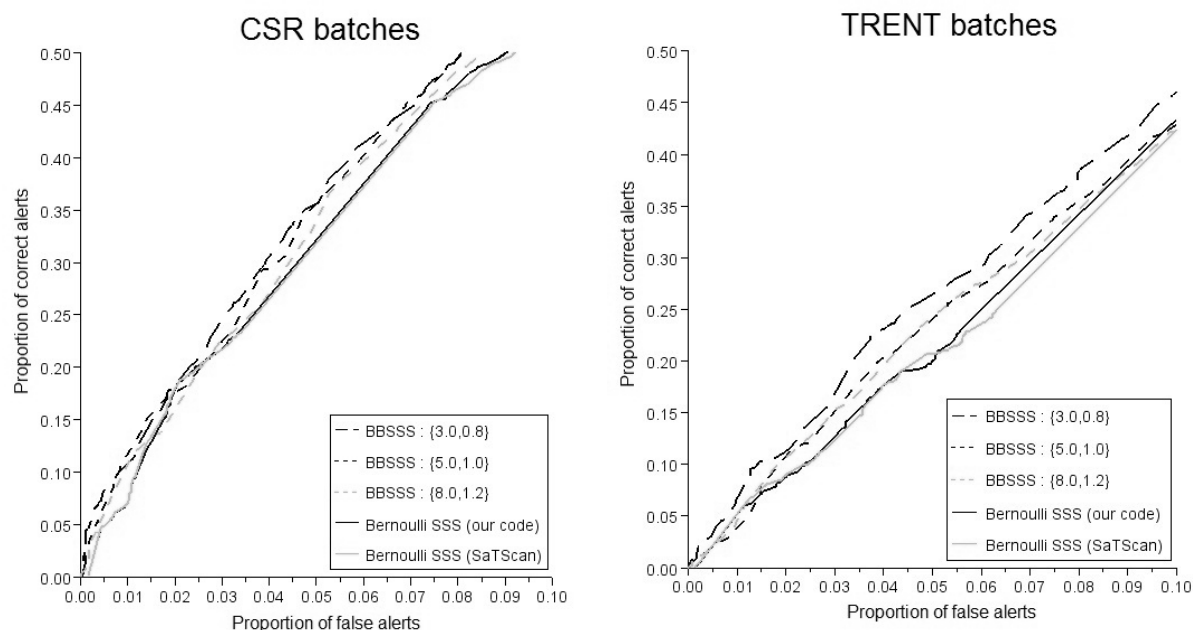


**Figure 1.** Trent region of UK

Our C++ versions of the BBSSS and Bernoulli SSS were run on each dataset, together with the Bernoulli SSS in SaTScan (v7.0) as a quality check. Three  $\{E(OR), V(OR)\}$  pairings were used:  $\{3.0, 0.8\}$ ,  $\{5.0, 1.0\}$ ,  $\{8.0, 1.2\}$ .

### 4. Results

By calculating the proportion of  $H_0$  and  $H_A$  datasets in which a given value of the statistic triggers an alert, one can plot standard ROC curves for each test. As these tests are only useful for low false alert rates, we present only the left-most 10% of the curve (Figure 2). Separate curves for each pairing  $\{E(OR), V(OR)\}$  demonstrate the variation in performance when different parameters are selected.



**Figure 2.** ROC curves (within useful false alert range) for CSR and TRENT batches

Although there is some random noise in these curves, the same pattern is apparent for both CSR and TRENT: for a given false alert rate, the BBSSS appears to have substantially higher power than the Bernoulli SSS, even compared to the bona-fide SaTScan implementation.

## 5. Conclusion

The findings in Section 4 suggest the addition of a beta prior increases the power of the Bernoulli SSS. However, a more comprehensive set of benchmark tests, using different cluster strength/size, and multiple clusters, would add more weight to these findings; as would an examination of a wider range of values for  $E(OR)$  and  $V(OR)$ . It may also be worth examining other versions of the SSS, to see if they benefit from a prior. This paper therefore represents a pilot study, which we hope to develop into a more authoritative set of benchmark tests.

Assuming these findings are correct, they raise an important question: why should adding a prior increase the detection capability of the SSS? A possible explanation is that the Bernoulli SSS maximises the likelihood of  $H_A(Z_k)$  by assuming  $q_{in}=c/n$ , which may promote small artefacts where  $c \approx n$ , despite unrealistically high  $q_{in}$ . In contrast, with sensible choices for  $E(OR)$  and  $V(OR)$ , the BBSSS constrains  $q_{in}$  within a realistic range, giving less weight to such artefacts. We stress this is entirely conjecture, and welcome all comments and suggestions on the matter.

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## 7. Biographies

**Dr. Simon Read** is a recent PhD graduate from the Information School at the University of Sheffield. He is interested in spatial data analysis, and is author of several refereed papers on the spatial scan statistic. Simon is the principal researcher and programmer on this project.

**Dr. Peter Bath** is a Reader in Health Informatics in the Information School at the University of Sheffield. He is Director of the Centre for Health Information Management Research (CHIMR). His main research interests and publications are in data mining and analyzing health data, e-Health and information behaviours in health.

**Peter Willett** is Professor of Information Science in the Information School at the University of Sheffield, where he has published very extensively on information retrieval, chemoinformatics and bibliometrics. Current interests include ligand-based virtual screening and the citation-based analysis of academic research performance.

**Dr. Ravi Maheswaran** is a Reader in Epidemiology and Public Health in the School of Health and Related Research at the University of Sheffield. His main research interests and publications are in geographical and environmental epidemiology, geographical variation in health and health care and methodology for spatial studies.