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# Automatically Improving Constraint Models in Savile Row through Associative-Commutative Common Subexpression Elimination

Peter Nightingale, Özgür Akgün, Ian P. Gent, Christopher Jefferson, and Ian Miguel

School of Computer Science, University of St Andrews, St Andrews, Fife KY16 9SX, UK  
{pwn1, ozgur.akgun, ian.gent, caj21, ijm}@st-andrews.ac.uk

**Abstract.** When solving a problem using constraint programming, constraint modelling is widely acknowledged as an important and difficult task. Even a constraint modelling expert may explore many models and spend considerable time modelling a single problem. Therefore any automated assistance in the area of constraint modelling is valuable. Common sub-expression elimination (CSE) is a type of constraint reformulation that has proved to be useful on a range of problems. In this paper we demonstrate the value of an extension of CSE called *Associative-Commutative CSE* (AC-CSE). This technique exploits the properties of associativity and commutativity of binary operators, for example in sum constraints. We present a new algorithm, X-CSE, that is able to choose from a larger palette of common subexpressions than previous approaches. We demonstrate substantial gains in performance using X-CSE. For example on BIBD we observed speed increases of more than 20 times compared to a standard model and that using X-CSE outperforms a sophisticated model from the literature. For Killer Sudoku we found that X-CSE can render some apparently difficult instances almost trivial to solve, and we observe speed increases up to 350 times. For BIBD and Killer Sudoku the common subexpressions are not present in the initial model: an important part of our methodology is reformulations at the preprocessing stage, to create the common subexpressions for X-CSE to exploit. In summary we show that X-CSE, combined with preprocessing and other reformulations, is a powerful technique for automated modelling of problems containing associative and commutative constraints.

## 1 Introduction

When solving a problem using constraint programming, constraint modelling is widely acknowledged as both important and difficult [13]. A problem may have many models, and it is difficult to know which will be solved most efficiently by a given constraint solver. Even a constraint modelling expert may explore many models and spend considerable time modelling a single problem. Therefore, any automated assistance in constraint modelling is valuable.

We focus on the process we call *tailoring*: given a constraint model in a solver-independent language and a value for each of its parameters, translate it into a form suitable for efficient solving by a given constraint solver. Tailoring must be efficient: it is

performed separately for each problem instance, hence any computationally expensive reformulation must pay for itself by saving time during solving.

Common sub-expression elimination (CSE) is a type of constraint reformulation that has proved to be useful on a range of problems [16, 15]. Herein we investigate an extension of CSE, *Associative-Commutative* CSE (AC-CSE), which exploits the properties of associativity and commutativity of binary operators (e.g. + and  $\times$ ). Expressions containing these operators can be rearranged to reveal common subexpressions. As an example, take the following two constraints over four variables:

$$w + x + y + z = 6, \quad z + y + w = 5$$

Conventional constraint propagation will not reveal the fact that  $x = 1$ . AC-CSE could extract  $w + y + z$  and replace it with an auxiliary variable  $a$  to give the following three constraints. Performing constraint propagation on this set will assign  $x$  to 1.

$$x + a = 6, \quad a = 5, \quad a = w + y + z$$

An Associative-Commutative Common Subexpression (AC-CS) of a set of associative and commutative (AC) expressions (e.g. sums) is a set of at least two terms that all appear in each one of the AC expressions (sums). In the example above, the set of three terms  $\{w, y, z\}$  appears in both the original sum constraints, hence  $\{w, y, z\}$  is an AC-CS of the two sum constraints.

A simple normalisation step, such as sorting the terms in the AC expressions, followed by examining contiguous subsequences of terms within AC expressions, can reveal some but not all of the available AC-CSs. More is necessary to find AC-CSs in general. Consider the example above, with an alphabetical ordering of the terms  $w + x + y + z$  and  $w + y + z$ . The largest contiguous subsequence of both is  $y + z$ , so this approach would miss the maximal AC-CS  $w + y + z$ .

In this paper we introduce and describe in detail a new algorithm, X-CSE, to perform AC-CSE in constraint problems. We show that X-CSE is able to find common subexpressions (CSs) automatically in a variety of problems, and that using these subexpressions can greatly reduce search and improve solving time. A particular advantage of X-CSE is that it is able to find and exploit small CSs that occur in many constraints, as well as larger ones that occur in few constraints. This is made possible by finding CSs that contain auxiliary variables introduced at an earlier step of the algorithm. We can thus exploit the occurrence of many small CSs without losing the advantages of finding larger ones. We illustrate this with an example below in Sections 2.3 and 3.3. The reuse of auxiliary variables created by AC-CSE in subsequent common subexpressions is an important advantage of X-CSE.

In addition, we show that X-CSE can be particularly effective in combination with other automated modelling techniques. In this paper we give two examples. First, we show that automated reformulation of an all-different constraint can lead to sum constraints, which can be exploited by X-CSE. Second, we see that by applying Singleton Arc Consistency at the preprocessing stage, we reveal new common subexpressions that can be exploited by X-CSE. These combinations show in particular that X-CSE is a valuable addition to the armoury of automated constraint modelling techniques, both alone and in combination with other techniques.

We evaluate the new algorithm on four problem classes: BIBD, the SONET problem, Killer Sudoku and Molnar’s Problem. When applying X-CSE we demonstrate substantial gains in performance. On BIBD we observed speed increases of more than 20 times compared to a standard model. We found that X-CSE outperforms a sophisticated model from the literature with manually derived implied constraints [7]. On the SONET problem we observed speed increases of 5 times on some instances. For Killer Sudoku we found that applying X-CSE can render some apparently difficult instances almost trivial to solve, and we saw more than 300 times speed increases in some cases. Molnar’s Problem exhibits more modest gains peaking at 5 times faster for the most difficult instance.

## 2 Related Work

The context of our work is reformulation of constraint modelling languages such as OPL [19], MiniZinc [18] and ESSENCE’ [16]. These languages have a collection of global constraints, arithmetic and logical operators that act on finite-domain or real interval decision variables. In this paper we consider finite-domain decision variables.

Such languages are not directly accepted by constraint solvers but must be tailored into a form suitable for a constraint solver. During tailoring the model can be *reformulated* to improve the efficiency of the constraint solver. There are many ways of producing better constraint models, some requiring manual interaction [2], and others that are automated [8]. For example these tools can discover global constraints or automatically detect and remove symmetries [11]. These improvements often complement each other, for example Frisch, Jefferson, and Miguel [7] show how breaking symmetries can lead to effective implied constraints for BIBDs among other problems. In this paper we show how to automatically generate a superior model for the BIBD problem.

### 2.1 Flattening and CSE

Flattening is the process of taking a nested expression and reducing the degree of nesting by replacing a subexpression with a new variable. For example given the product  $X \times (Y + Z)$  and a target solver that does not allow sums inside products, the flattening process will add a new variable *aux*, replace the product with the new expression  $X \times aux$  and add a new constraint  $aux = Y + Z$ . We say that  $X \times (Y + Z)$  is *flattened* to  $X \times aux$  and that  $Y + Z$  is *extracted*.

Common sub-expression elimination (CSE) was first applied in the context of finite-domain constraint languages by Andrea Rendl [16, 15]. In its simplest form, CSE takes two or more syntactically identical sub-expressions that must be flattened, and flattens them all using the same auxiliary variable. This reduces both the number of constraints and auxiliary variables. Importantly, CSE can reduce the search space dramatically [16, 15] by linking different constraints together thus strengthening constraint propagation.

### 2.2 Normalisation and Active CSE

One way CSE has been fruitfully extended is by matching subexpressions that are not syntactically identical [16]. This is achieved in two ways. The first is *normali-*

sation, where prior to CSE the expression tree is converted to a normal form (primarily by ordering the arguments of commutative operators and evaluating any constant expressions). This converts some semantically equivalent expressions (such as  $C = B + A + 1 - 1$  and  $A + B = C$ ) to syntactically identical expressions. The second is *Active CSE*, where two expressions  $A$  and  $B$  may be matched if they are identical after some transformation (for example by applying one of De Morgan’s laws). For example, Active CSE can match  $A < B$  with  $A \geq B$  by a simple negation.

The algorithm introduced by Rendl [15] and used by Stuckey and Tack [18] performs CSE during flattening. The algorithm maintains a hash table keyed by the expressions that have been extracted so far, and containing the new auxiliary variable for each. When extracting an expression  $E$ , the algorithm looks up  $E$  in the hash table, and (if present) uses the auxiliary variable in the hash table rather than creating a new auxiliary. This algorithm has the advantage that is easily extended to active CSE. When looking up  $E$  in the hash table, active CSE also looks up each transformation of  $E$ . However it is not clear how this algorithm could be extended to AC-CSE. The common subexpressions extracted by AC-CSE would not normally be extracted by flattening.

### 2.3 Associative-Commutative CSE

Araya, Neveu and Trombettoni [1] exploited common subexpressions among  $+$  and  $\times$  expressions. Their work is in the context of numerical CSP solved by algorithms such as HC4, but the reformulation is equally applicable to finite-domain CSP. They proposed two algorithms named I-CSE and I-CSE-NC. Both algorithms apply a form of AC-CSE prior to flattening as a separate operation.

The first pass of both algorithms is to transform the abstract syntax tree (AST) into a directed acyclic graph where identical subexpressions are represented once. The second step is to intersect each pair of sums and pair of products to create a set of candidate AC-CSs. As we will see in Section 3.3 other AC-CSs (generated by the intersection of three or more sums) can also be useful, but I-CSE and I-CSE-NC will never generate them. Later passes extract the AC-CSs from the original expressions.

Araya et al. defined two AC-CSs  $f_1$  and  $f_2$  to be *in conflict* if  $f_1 \cap f_2 \neq \emptyset$ ,  $f_1 \not\subseteq f_2$  and  $f_2 \not\subseteq f_1$ . Two AC-CSs in conflict cannot both be extracted from the same expression. When a set of AC-CSs in conflict are subsets of the same original expression  $s$ , then I-CSE copies  $s$  a sufficient number of times to extract each of the AC-CSs from at least one copy. I-CSE-NC (for No Conflicts) does not copy  $s$ , it simply extracts a single maximal subset of the candidate AC-CSs from  $s$ . Consider the following example:

$$\begin{aligned} v + w + x + y = 0, \quad v + w + x + z = 0 \\ v + w + y + z = 0 \end{aligned}$$

In this example I-CSE(-NC) would generate three AC-CSs:  $v + w + x$ ,  $v + w + y$  and  $v + w + z$ . I-CSE would duplicate each of the original constraints resulting in six constraints and three further constraints to define the auxiliary variables.

I-CSE-NC can extract only one AC-CS. Suppose it extracts  $v + w + x$ , then at this point  $v + w + y$  and  $v + w + z$  cease to be AC-CSs:

$$aux + y = 0, \quad aux + z = 0, \quad v + w + y + z = 0$$

$$aux = v + w + x$$

I-CSE-NC can only extract CSEs from the original expressions, so fails to exploit the AC-CS  $v + w$ . Even on this small example I-CSE has increased the size of the model substantially. I-CSE-NC has not, but it has missed a potentially useful AC-CS and has not linked  $v + w + y + z$  to the other two sums.

I-CSE and I-CSE-NC are both compared to our algorithm in the experiments below. We implement the algorithms exactly as described in Section 4 of Araya et al. [1]. Both I-CSE and I-CSE-NC only extract AC-CSs from the original expressions, they do not extract AC-CSs from other AC-CSs.

### 3 The X-CSE Algorithm

The X-CSE algorithm is implemented in Savile Row 1.6 [12]. Savile Row reads the ESSENCE' language and transforms it in many passes to an output for a constraint solver. X-CSE simply becomes another pass. In this paper we consider the associative and commutative (AC) operators  $\setminus$  (or),  $/\setminus$  (and),  $+$ ,  $*$ . These are represented as a single AST node with  $n$  children in Savile Row 1.6. There are other AC operators in the language, notably  $\min$  and  $\max$ , and  $!=$  between boolean expressions (exclusive or). We leave these for future work.

Prior to running X-CSE the AST is normalised by sorting the children of all commutative operators. For any AC operator  $\diamond$ , the goal of X-CSE is to find common sets containing two or more expressions that are contained in more than one  $\diamond$  expression. The X-CSE algorithm uses a hash table *map* from *pairs* of expressions  $\{a, b\}$  to a list of the  $\diamond$  expressions that contain both  $a$  and  $b$ . Algorithm 2 (*populateMap*) takes a reference to an AST node and explores the tree, populating *map* for each  $\diamond$  expression.

Algorithm 1 (X-CSE) takes a reference to the AST representing all constraints, a reference to the global symbol table, and the AC operator  $\diamond$ . After initialising data structures it calls *populateMap* with the entire AST. Following that it enters the main loop on line 4. On line 5 one pair is selected from *map* according to a heuristic. If the pair occurs in more than one  $\diamond$  expression then there must exist an AC-CS including that pair. Lines 10-20 find an AC-CS and extract it from all the relevant expressions. The algorithm includes as many  $\diamond$  expressions as possible to maximise the effect of extracting the AC-CS. Line 10 intersects all  $\diamond$  expressions containing the pair. A new  $\diamond$  expression for the AC-CS is constructed, and an auxiliary variable is created. On line 14 a constraint is created to define the auxiliary variable. Each  $\diamond$  expression containing the AC-CS is replaced. At this point, lines 19 and 20 update *map* to include all the newly created expressions, allowing X-CSE to extract further AC-CSs from the new expressions. Some references to removed  $\diamond$  expressions will remain in *map*; these will be filtered out on line 8.

#### 3.1 Heuristics

X-CSE chooses the next pair to process by calling a heuristic on line 5. We experimented with eight heuristics. There are four basic heuristics: most occurrences (i.e. select the pair that leads to the longest list *ls* after line 8 of X-CSE), fewest occurrences,

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**Algorithm 1** X-CSE(AST, ST,  $\diamond$ )

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**Require:** AST: Abstract syntax tree representing the model

**Require:** ST: Symbol table containing decision variables

**Require:**  $\diamond$ : The associative and commutative operator

- 1:  $newcons \leftarrow$  empty list {Collect new constraints}
- 2:  $map \leftarrow$  empty hash table mapping pairs of expressions to lists
- 3: populateMap(AST,  $map$ ,  $\diamond$ )
- 4: **while**  $map$  not empty **do**
- 5:    $pairexp \leftarrow$  heuristic( $map$ )
- 6:    $ls \leftarrow map(pairexp)$  { $ls$  is a list of  $\diamond$  AST nodes}
- 7:   delete  $map(pairexp)$
- 8:    $ls \leftarrow$  filter(isAttached,  $ls$ ) {Remove  $\diamond$  AST nodes no longer contained in AST or  $newcons$ }
- 9:   **if** length( $ls$ ) > 1 **then**
- 10:      $commonset \leftarrow ls[1] \cap ls[2] \cap \dots \cap ls[length(ls)]$
- 11:      $e \leftarrow$  fold( $\diamond$ ,  $commonset$ )
- 12:      $bnds \leftarrow$  bounds( $e$ )
- 13:      $aux \leftarrow$  ST.newAuxVar( $bnds$ )
- 14:      $newc \leftarrow (e = aux)$  {New constraint defining  $aux$ }
- 15:      $newcons.append(newc)$
- 16:     **for all**  $a \in ls$  **do**
- 17:        $newe \leftarrow$  fold( $\diamond$ , ( $a \setminus commonset$ )  $\cup$  { $aux$ })
- 18:       Replace  $a$  with  $newe$  within AST or  $newcons$
- 19:       populateMap( $newe$ ,  $map$ ,  $\diamond$ )
- 20:     populateMap( $newc$ ,  $map$ ,  $\diamond$ )
- 21: AST  $\leftarrow$  AST  $\wedge$  fold( $\wedge$ ,  $newcons$ )

---

largest AC-CS and smallest AC-CS. In some cases there exists a pair such that its corresponding AC-CS can be extracted without preventing any other AC-CS. We call these *non-blocking pairs* and it may be helpful to process them first. We created four more heuristics that select non-blocking pairs first, then fall back to one of the four basic heuristics. We found no clear winner among the eight heuristics. We use the ‘most occurrences’ heuristic throughout the rest of this paper because it is cheap to compute and often performs well.

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**Algorithm 2** populateMap( $A$ ,  $map$ ,  $\diamond$ )

---

**Require:**  $A$ : Reference to an abstract syntax tree

**Require:**  $map$ : Hash table mapping pairs of expressions to lists

**Require:**  $\diamond$ : The associative and commutative operator

- 1: **if**  $A$  is expression of  $\diamond$  **then**
- 2:   **for all**  $\{e_1, e_2\} \subseteq A$  **do**
- 3:     Add  $A$  to list  $map[\{e_1, e_2\}]$
- 4: **for all**  $child \in A.Children()$  **do**
- 5:   populateMap( $child$ ,  $map$ ,  $\diamond$ )

---

### 3.2 Complexity Analysis

In this analysis we will use  $n$  for the number of  $\diamond$  expressions,  $k$  for the length of the longest  $\diamond$  expression,  $d$  as the depth of the deepest  $\diamond$  expression in the AST, and  $S$  as the number of nodes in the AST.

Central to the complexity analysis of X-CSE is the observation that at most  $k - 1$  AC-CSs may be extracted from one  $\diamond$  by X-CSE. Recall (from Section 2.3) that two AC-CSs in conflict cannot both be extracted from the same expression. A pair of AC-CSs may overlap only if one is a subset of the other. Consider an AC-CS  $f$  in an expression  $e$ . There can be no other AC-CSs involving  $f$  in  $e$  except possibly some  $f'$  where  $f \subsetneq f'$ . The smallest AC-CS is size two, and extracting this replaces a size two term with a size one term (i.e. the replacement auxiliary variable). If the original expression is size  $k$ , we thus find one AC-CS and now have a size  $k - 1$  expression. Iterating shows that at most  $k - 1$  AC-CSs may be extracted from one  $\diamond$  expression by X-CSE. This gives us a global limit of  $O(nk)$  AC-CS extractions.

To populate *map*, `populateMap` traverses the AST with  $S$  nodes, and for each  $\diamond$  expression  $e$  it inserts a reference to  $e$  in  $O(k^2)$  lists within *map*. Assuming hash table operations are  $O(1)$ , `populateMap` takes  $O(S + nk^2)$  time.<sup>1</sup>

X-CSE then enters a loop that continues until *map* is empty. Each iteration of the loop is as follows. We assume the heuristic takes  $O(1)$  time.<sup>2</sup> For the given pair, its list *ls* has at most  $n$  elements. Note that if the pair occurs more than once in an expression it might be entered into *ls* multiple times: to keep the list at size  $n$ , when inserting an expression  $e$  into *ls* we can check the last element of *ls*: if it is equal to  $e$ , we do not insert  $e$  for a second time. The list *ls* is filtered in  $O(nd)$  time. If the list has length two or greater, then we extract an AC-CS. For the following we assume that an AC expression is represented by a set data structure with  $O(1)$  lookup, insertion and removal.<sup>3</sup> Creating *commonset* on line 10 takes  $O(nk)$  time. Computing the bounds and creating the auxiliary variable and the new constraint can be done in  $O(k)$  time. The algorithm then replaces *commonset* in each *ls* expression in  $O(nk)$  time. Re-populating *map* (on lines 19 and 20) takes  $O(S + nk^2)$  because the updated AC expressions can contain the entire AST. Therefore the entire cost of extracting one AC-CS is  $O(S + nk^2 + nd)$ , and the total cost of X-CSE is  $O(nkS + n^2k^3 + n^2kd)$ .

While the complexity may seem high, the algorithm scales with the number of AC-CSs it is able to exploit, therefore it is relatively quick when there are few or no AC-CSs, and it takes more time when there is greater potential benefit.

### 3.3 Comparison with I-CSE(-NC)

X-CSE differs from the existing algorithms I-CSE(-NC) in that it can extract AC-CSs that are intersections of more than two expressions, and AC-CSs containing auxiliary

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<sup>1</sup> This is correct if all expressions to be hashed are size  $O(1)$  and computing the hash code is linear. If either assumption is invalid then an additional factor  $h$  is necessary, representing the time to hash an expression.

<sup>2</sup> As an example of an  $O(1)$  heuristic we could maintain a doubly linked list of keys in *map* and have the heuristic simply remove and return the first element of the list.

<sup>3</sup> Once again we are assuming expressions can be hashed in  $O(1)$  time.



variables (from earlier steps). Thus it has a larger palette of AC-CSs to choose from. In the example from Section 2.3, X-CSE would first extract  $v + w$  from all three sums as follows.

$$a = v + w, a + x + y = 0, a + x + z = 0, a + y + z = 0$$

Second, X-CSE would extract any one of  $a + x$ ,  $a + y$  or  $a + z$ , as follows. This second step is not possible in I-CSE(-NC).

$$a = v + w, b = a + x, b + y = 0, b + z = 0, a + y + z = 0$$

This result is clearly better than I-CSE-NC (Section 2.3) that extracted only  $v + w + x$  and thus did not connect the third constraint to the other two. I-CSE produced nine constraints on this example. It is possible that the more compact model produced by X-CSE is better. We investigate this further in Section 5.5.

## 4 Preprocessing and Reformulation

The number and quality of CSs found can be improved by using MINION to preprocess an initial version of the model then feeding it back into Savile Row for CSE. Our method is as follows. First Savile Row translates the instance to MINION (with or without X-CSE). Then MINION is called to filter domains with SACBounds (no search), which is a variant of SAC [3]. SACBounds applies the SAC test to prune the upper and lower bound of each variable to exhaustion. Savile Row re-starts the translation process with the filtered domains and translates the instance to MINION again (with or without X-CSE). Re-starting translation allows Savile Row to simplify the constraints following domain filtering. For example, on the BIBD problem below, some variables are assigned by SACBounds and this allows constant folding (e.g.  $\dots + a \times x + b \times y + \dots$  where SACBounds assigns  $a = 1$  and  $b = 0$  becomes  $\dots + x + \dots$ ).

A further step to promote the identification of AC-CSs is in reformulating a model to add implied constraints consisting of AC expressions. Savile Row creates implied sum constraints from all-different and global cardinality constraints. This is done by finding assignments to the all-different (GCC) with the smallest and largest sums ( $lb$  and  $ub$  resp.), then adding either  $\sum \geq lb$  and  $\sum \leq ub$  (when  $lb \neq ub$ ) or  $\sum = lb = ub$  where  $\sum$  is the sum of the variables in scope of the original constraint (except cardinality variables in GCC). For example, given  $\text{allDiff}(x, y, z)$  where all variables have domain  $\{1 \dots 4\}$ , we add constraints  $x + y + z \geq 1 + 2 + 3$  and  $x + y + z \leq 2 + 3 + 4$ .

## 5 Case Studies

In this section we study four problems where we found AC-common subexpressions. We use Savile Row 1.6 and the following optimisations are *always* applied: unification of equal variables, domain filtering with SACBounds (as described in the section above), and identical CSE (elimination of identical subtrees in the expression tree). In addition, X-CSE, I-CSE or I-CSE-NC may be applied (before any form of flattening or other CSE) as required for the experiment. Timings include both total time reported

by Savile Row (which includes the first preprocessing call to MINION) and total time reported by MINION 1.6.1 64-bit to search for a solution. MINION is given a time limit of 600s to solve the final model. Savile Row is executed in the Java 1.7.0\_55 JIT. Each reported timing is a mean of 5 runs. Experiments were performed on a 32-core AMD Opteron 6272 at 2.1 GHz. All model and parameter files are available at <http://pn.host.cs.st-andrews.ac.uk/cp-2013-ac-cse-experiments.tgz>.

## 5.1 Case study 1: BIBD

We use Puget’s model of the Balanced Incomplete Block Design (BIBD) problem, with *Lex*<sup>2</sup> symmetry breaking constraints [14]. BIBD is parameterised by  $(v, k, \lambda)$  and has  $r = \frac{\lambda(v-1)}{k-1}$  and  $b = \frac{\lambda v(v-1)}{k(k-1)}$ . The model has a  $v$  by  $b$  matrix  $m$  of boolean variables. Each of the  $v$  rows sums to  $r$  (row constraints), and each of the  $b$  columns sums to  $k$  (column constraints). The scalar product of each pair of rows has value  $\lambda$ :

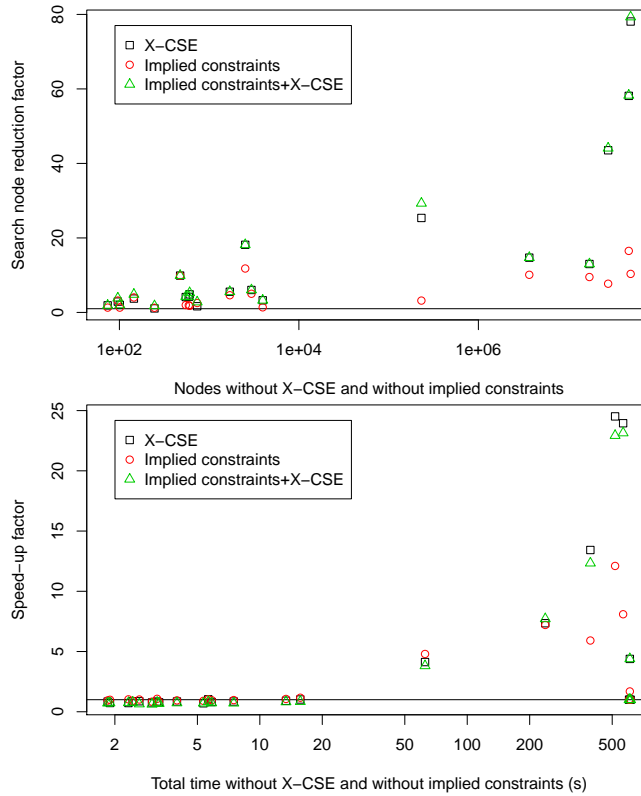
$$\forall i_1, i_2 \in \{1 \dots v\}. i_1 < i_2 \rightarrow \left( \sum_{j=1}^b m[i_1, j] * m[i_2, j] \right) = \lambda$$

This model initially has no common subexpressions (identical or AC). As described above the domains are filtered by applying SACBounds. This assigns some of the variables (the entire first two rows and first column, plus some other entries). When translating again with the domains filtered by SACBounds, the scalar product constraints are simplified causing AC-CSs to appear among scalar product constraints, and between scalar product and row sum constraints.

We evaluated X-CSE on the 24 instances in Figure 1 of Puget ([14]). MINION times out for 4 instances without X-CSE. For the remaining 20 instances, X-CSE always decreases the node count. Figure 1 plots the reduction factor for the 20 instances. Harder instances tend to show a greater reduction in node count. For the hardest instance solved within the time limit, the node count is reduced by 78 times.

Figure 1 plots speed-up of total time with X-CSE. For the easiest instances, the reduction in node count does not cause a measurable difference in MINION’s run time. The slow down in total time is caused by the up-front cost of X-CSE. On the harder instances, MINION search takes up most of the total time and X-CSE speeds up search substantially by reducing the number of search nodes. Figure 1 (lower) peaks with instance (10, 3, 6), which has a 58-fold reduction in nodes and speed up of 24.5 times. X-CSE typically increases the number of constraints and auxiliary variables, reducing the node rate of MINION. Finally, (10, 3, 8) times out without X-CSE, and takes 138.6 s with X-CSE. Hence it appears on the far right of Figure 1 with a speed up of 4.39.

**Implied constraints for BIBD.** Frisch, Jefferson, and Miguel ([7]) derived a set of implied constraints for BIBD that drastically improve the performance of the model. First they observed that the first two rows and first column of the BIBD can be assigned by manually reasoning about the constraints. Second, for each of the remaining rows  $i$ , they reformulated the row sum constraint into four sum constraints. For example, for indices where row 1 is set to 0, row  $i$  sums to  $r - \lambda$ . These four constraints are derived

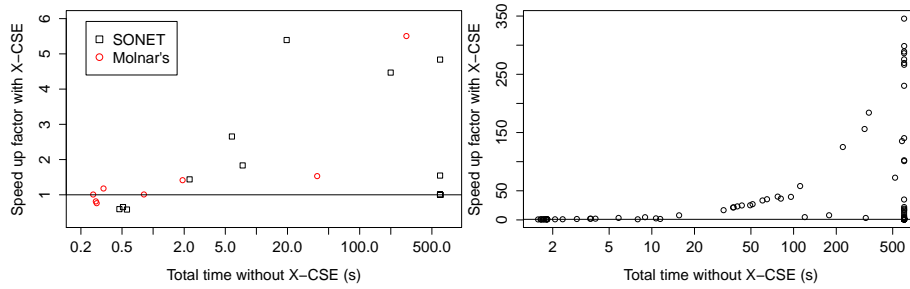


**Fig. 1.** (Top) BIBD search nodes of instances that do not time out. (Bottom) BIBD total time.

from the row constraint for row  $i$  and scalar product with either row 1 or 2 using an approach resembling manual AC-CSE.

The automated approach improves on Frisch et al. in two ways. First SACBounds is able to assign not just the first two rows and first column but also parts of other rows and columns. For example, on the instance  $(v = 22, k = 7, \lambda = 2)$  parts of the third and fourth rows and the first eight entries of the second column are assigned. Second, X-CSE is able to link multiple scalar product constraints and a row constraint, whereas the implied constraints are each derived from a single scalar product constraint and a row constraint.

The implied constraints alone do reduce node count (see Figure 1) but are not as effective as X-CSE. For the hardest instances the implied constraints speed up solving but by a smaller degree than X-CSE. Adding the implied constraints then applying X-CSE is slightly more effective than X-CSE alone in reducing node count. However this does not translate to more efficient search. Implied constraints plus X-CSE is slower than X-CSE alone on almost all instances. Remarkably, X-CSE is able to improve the sophisticated model on the hardest four solvable instances.



**Fig. 2.** (Left) Results for SONET and Molnar's Problem total time. (Right) Results for Killer Sudoku total time.

## 5.2 Case study 2: The SONET problem

The SONET problem [17] is a network design problem where each node is connected to a set of *rings* (fibre-optic connections). The simplified SONET problem (Section 3 of [17]) where each ring has unlimited capacity has the following parameters: the number of nodes  $n$ , the upper limit on the number of rings  $m$ , the maximum number of nodes per ring  $r$ , and a set of pairs that must be connected. For each of these pairs there must exist a ring connected to both nodes. The number of node-ring connections is minimised.

The problem is modelled as follows. We have a boolean matrix *rings* indexed by  $\{1 \dots m, 1 \dots n\}$ .  $rings[a, b]$  indicates whether ring  $a$  is connected to node  $b$ . For each ring  $a$  we have the sum constraint  $\sum_{b=1}^n rings[a, b] \leq r$ . The connectedness constraint between two nodes  $b_1$  and  $b_2$  is expressed as a disjunction (refined by Savile Row to a watched-or [9]) of sums:

$$\exists i \in \{1 \dots m\}. (rings[a_i, b_1] + rings[a_i, b_2] \geq 2)$$

The minimisation function is simply the sum of *rings*. Rings are indistinguishable so we use lexicographic ordering constraints to order the rows of *rings* in non-decreasing order. The static variable ordering we use is the reading order of *rings* and value order is 0 then 1. This model is very simple and does not include implied or dominance constraints [17]. The problem constraints are already flat and only the minimisation sum needs to be flattened, thus only one auxiliary variable is created by Savile Row without X-CSE. There are AC-CSs between the connectedness constraints, the ring sum constraints and the minimisation sum.

We generated 24 instances with  $n \in \{6 \dots 13\}$ ,  $r \in \{3, 4, 5\}$ , and  $m = 10$ . The demand graph when  $n = 13$  is Figure 1 of Smith [17]. For smaller  $n$  we take the subgraph with vertices  $\{n + 1 \dots 13\}$  and edges adjacent to these vertices removed.

Figure 2 plots the speed-up factor for X-CSE. As before the time limit is 600s. All instances with  $n \in \{10 \dots 13\}$  and also instance  $n = 9, r = 4$  timed out both with and without X-CSE. Instances  $n = 9, r = 5$  and  $n = 8, r = 3$  timed out without X-CSE, and appear on the far right of the plot with a speed-up of 4.84 and 1.55 respectively. X-CSE improves solving speed for all but the most trivial instances.

### 5.3 Case study 3: Killer Sudoku

We consider the Killer Sudoku problem. The standard Killer Sudoku has a  $9 \times 9$  grid where each row and column are all-different, and the nine non-overlapping  $3 \times 3$  sub-squares are also all-different. Each slot in the grid is initially empty and takes a digit  $1 \dots 9$ . Clues are sets of squares that sum to a given value (and are also all-different). We found that  $9 \times 9$  Killer Sudoku instances were very easy. We generalised the puzzle to  $16 \times 16$  with  $16 \ 4 \times 4$  subsquares, and each slot takes a number  $1 \dots 16$ . 100 instances were generated at random. Traditional Killer Sudoku puzzles have exactly one solution. The random  $16 \times 16$  instances may be unsatisfiable and may have multiple solutions. For brevity we do not describe how these instances are generated. All models and instances are available on the web at the URL given in Section 5 above.

X-CSE alone does nothing because the sums in the clues are the only AC expressions and they do not overlap. However the sums overlap with all-different constraints. Each all-different constraint on a row, column or subsquare represents a permutation of  $\{1 \dots 16\}$  which sum to 136. Savile Row automatically adds these implied sum constraints as described in Section 4. X-CSE is able to find common subexpressions among rows, columns, sub-squares and clues.

Figure 2 plots the speed-up quotient for Killer Sudoku. Without X-CSE, 54 instances timed out. With X-CSE, 28 instances timed out. As the instances become more difficult the trend is towards greater speed-up by X-CSE. The plot peaks at 345 times faster. On this instance, without X-CSE Savile Row took 2.26 s and MINION timed out after exploring 2,774,028 nodes. With X-CSE, Savile Row took 1.62 s and MINION took 0.13 s to explore 2 nodes.

### 5.4 Case study 4: Molnar's Problem

Molnar's problem [6] (CSPLib problem 035 [5]) is to find a square matrix  $M$  of integers. The model has two parameters: the size  $k$  (i.e.  $M$  has size  $k \times k$ ) and the maximum absolute value of integers in  $M$ , named  $d$ . The initial domain of each element of  $M$  is  $\{-d \dots -2\} \cup \{0\} \cup \{2 \dots d\}$ . The first constraint is that the determinant of  $M$  is 1 or  $-1$  (following the model of Frisch et al. [6]). For the second constraint we construct another matrix  $S$  where each entry of  $S$  is the square of the corresponding entry of  $M$ . The determinant of  $S$  must also be 1 or  $-1$ .

We used the Leibniz formula for determinants, and expressed  $a^2$  as  $a \times a$  to allow more AC-CSs of products. When  $k = 3$  we have the following two matrices and two constraints. In addition we break symmetry on  $M$  by lexicographically ordering rows and columns.

$$M = \begin{bmatrix} a & b & c \\ d & e & f \\ g & h & i \end{bmatrix}, S = \begin{bmatrix} a^2 & b^2 & c^2 \\ d^2 & e^2 & f^2 \\ g^2 & h^2 & i^2 \end{bmatrix}$$

$$|M| = aei - afh + bfg - bdi + cdh - ceg \in \{-1, 1\}$$

$$|S| = aaeii - aaffhh + bbfogg - bbddii + ccddhh - cceegg \in \{-1, 1\}$$

There are multiple AC-CSs of products, for example  $aa$  and  $aei$ . Some connect the two sums, and others connect terms within one sum. X-CSE is able to extract a

particular AC-CS from the same product more than once on this problem. Consider  $aei$ : extracting it once creates a new constraint  $aei = x$  and modifies the expression  $aei$  to  $x$ , and the expression  $aaeeii$  to  $x \times aei$ . Now X-CSE extracts  $aei$  a second time from the new constraint and one of the modified expressions, creating a second auxiliary variable (that will later be unified with  $x$ ).

Figure 2 plots the speed-up quotient for Molnar’s Problem on the eight instances where  $k \in \{2, 3\}$  and  $d \in \{2 \dots 5\}$ . X-CSE appears to be more useful for the more difficult instances. None of the instances time out. The peak speed-up quotient is 5.5.

### 5.5 I-CSE and I-CSE-NC

In this section we use all four problem classes to compare X-CSE to I-CSE and I-CSE-NC. Figure 3 plots the speed-up factor for I-CSE and I-CSE-NC compared to X-CSE. It is clear from the lower plot that I-CSE-NC performs much more poorly than X-CSE (since almost all points are below  $y = 1$ ). By comparing the two plots in Figure 3 it is clear that I-CSE outperforms I-CSE-NC on Killer Sudoku, I-CSE-NC is preferable for SONET, and that the two algorithms are very similar for BIBD (without implied constraints) and Molnar’s Problem.

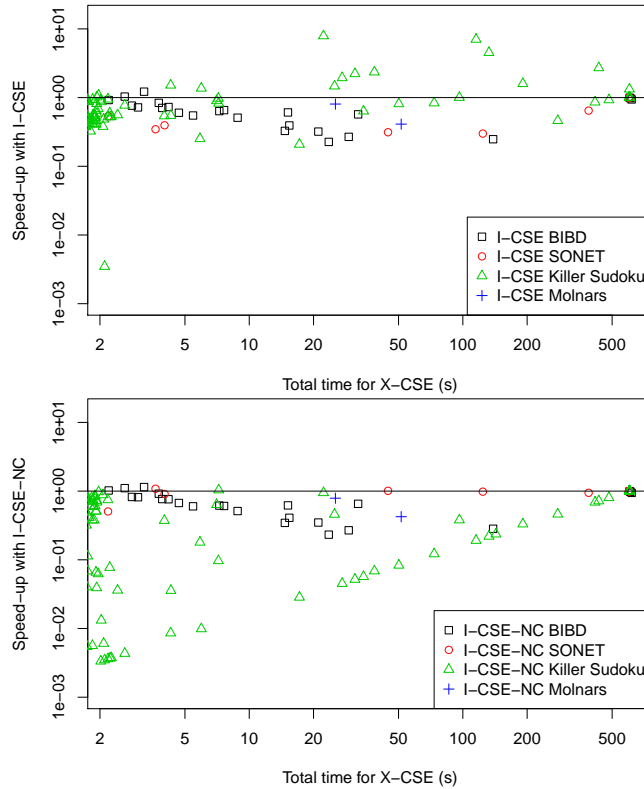
X-CSE performs substantially better than I-CSE on BIBD and SONET, and slightly better on Molnar’s Problem. For BIBD, both timed out on 3 instances and each solved 21. X-CSE explored fewer search nodes on 16 of the 21 instances, and was much faster overall. The mean time for X-CSE (on the set of 21 instances) was 16.7 s compared to 52.1 s for I-CSE.

For SONET, X-CSE always explores more (or an equal number of) search nodes than I-CSE but total time is lower with X-CSE for all instances taking longer than 1 s. X-CSE was able to solve all instances that I-CSE could within the timeout, and one additional one. Of the 9 that both solved, X-CSE had a mean time of 20.3 s compared to I-CSE’s mean of 65.1 s. X-CSE and I-CSE-NC are able to solve the same set of 10 SONET instances. X-CSE had a mean time of 57.1 s while I-CSE-NC had a mean time of 59.7 s.

For Killer Sudoku, the picture is less clear. 70 instances are solved by both I-CSE and X-CSE. I-CSE solves one additional instance in 454 s, and X-CSE solves two additional instances in 2.1 s and 278 s. On the 70 instances solved by both, I-CSE took a mean time of 28.6 s, and X-CSE took a mean time of 35.2 s. I-CSE searches fewer nodes on 16 of these 70 instances and is more than 1.5 times faster than X-CSE on 10 instances. In short, neither X-CSE nor I-CSE is clearly better than the other on Killer Sudoku. The successes of I-CSE show that it can be worthwhile to extract conflicting AC-CSs.

### 5.6 Other Problems

In this section we investigate the benefit and overhead of X-CSE on a larger set of problems. 47 example ESSENCE’ models were included with Savile Row 1.5 [12]. Four of these are used as case studies above. In this section we use the other 43 problems, almost all of which were written before X-CSE was conceived. Of these 43 problems, 16 have no AC-CSs and 27 have them.

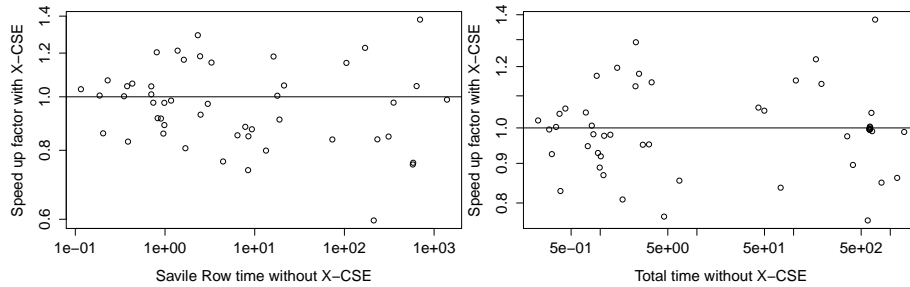


**Fig. 3.** Comparison of X-CSE with I-CSE (top) and I-CSE-NC (bottom).

Figure 4 (left) plots the time taken by Savile Row (including running MINION to enforce SACBounds). In some cases applying X-CSE speeds up Savile Row overall. Figure 4 (right) plots total time. Only two problems searched fewer nodes with X-CSE: Plotting (2% reduction) and waterBucket (21% reduction) and for both these problems the search time saved is outweighed by additional time required in Savile Row. For those problems that are sped up overall, there are two reasons: in some cases (e.g. quasiGroup5Idempotent, pegSolitaireState) X-CSE speeds up MINION without reducing the node count; and in other cases X-CSE speeds up Savile Row and not MINION. In summary, X-CSE provides a modest benefit on some of these problems and is a small overhead on others.

## 6 Future Work

X-CSE is able to extract sets of *identical* terms shared among a set of AC-expressions. It is unable to match non-identical terms that are equivalent after a simple transformation. On the other hand, Active CSE [16] (described in Section 2.2) can match non-identical



**Fig. 4.** Savile Row time only (left), and total time (right) on a set of 43 problems.

expressions that are identical after a simple transformation, but usually cannot extract AC-CSs. Suppose we had expressions  $x - y$  and  $y - x$ . They could in principle be extracted by Active CSE, with one replaced by an auxiliary variable  $aux$  and the other replaced by  $-aux$ . However, if we have  $x - y + z$  and  $y - x + z$ , the  $z$  term hides the common subexpression and neither X-CSE nor Active CSE can detect it. Exactly this situation arises in a potable water management problem (Choi and Lee [4]). Choi and Lee extracted the common subexpressions manually and proved that constraint propagation is strengthened by doing so.

Our proposed future work is to integrate X-CSE and Active CSE to create a single algorithm that is able to reveal AC-CSs by performing transformations. One (very simple) example of a transformation is multiplying by  $-1$  to reveal the common subexpression in  $x - y + z$  and  $y - x + z$ . A second example is negation (followed by De Morgan’s law) to reveal that  $\neg A \vee \neg C$  may be extracted from  $A \wedge C$  and  $\neg A \vee \neg B \vee \neg C$ .

## 7 Conclusions

We have introduced and described a new algorithm, X-CSE, to perform Associative-Commutative Common Subexpression Elimination (AC-CSE) as an automated modelling step for finite domain constraint satisfaction problems. X-CSE is able to find common subexpressions which reduce search in four sample problems: BIBD, SONET, Killer Sudoku and Molnar’s Problem. Of particular importance, X-CSE can interact with other automated modelling techniques, thereby magnifying the power of those techniques and X-CSE. We suggest that X-CSE is preferable to an earlier algorithm for AC-CSE, namely I-CSE, because it is able to exploit frequently occurring short common subexpressions. In our experiments X-CSE outperformed I-CSE in most cases. We conclude that X-CSE is a valuable addition to the armoury of automated constraint modelling techniques, both alone and in combination with other techniques.

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