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Some results on the penalised nematic liquid crystals driven by multiplicative noise: weak solution and maximum principle

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Abstract

In this paper, we prove several mathematical results related to a system of highly nonlinear stochastic partial differential equations (PDEs). These stochastic equations describe the dynamics of penalised nematic liquid crystals under the influence of stochastic external forces. Firstly, we prove the existence of a global weak solution (in the sense of both stochastic analysis and PDEs). Secondly, we show the pathwise uniqueness of the solution in a 2D domain. In contrast to several works in the deterministic setting we replace the Ginzburg–Landau function $\mathbb{1}_{|\mathbf{n}|\leq 1}(|\mathbf{n}|^2 - 1)\mathbf{n}$ by an appropriate polynomial $f(\mathbf{n})$ and we give sufficient conditions on the polynomial f for these two results to hold. Our third result is a maximum principle type theorem. More precisely, if we consider $f(\mathbf{n}) = \mathbb{1}_{|d|\leq 1}(|\mathbf{n}|^2 - 1)\mathbf{n}$ and if the initial condition \mathbf{n}_0 satisfies $|\mathbf{n}_0| \leq 1$, then the solution \mathbf{n} also remains in the unit ball.

Keywords Nematic Liquid Crystal · Leslie–Ericksen System · Martingale Solution · Maximum Principle Theorem

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1 Introduction

Nematic liquid crystal is a state of matter that has properties which are between amorphous liquid and crystalline solid. Molecules of nematic liquid crystals are long and thin, and they tend to align along a common axis. This preferred axis indicates the orientations of the crystalline molecules; hence it is useful to characterize its orientation with a vector field \mathbf{n} which is called the **director**. Since its magnitude has no significance, we shall take \mathbf{n} as a unit vector. We refer to [10, 15] for a comprehensive treatment of the physics of liquid crystals. To model the dynamics of nematic liquid crystals most scientists use the continuum theory developed by Ericksen [17] and Leslie [28]. From this theory Lin and Liu [29] derived the most basic and simplest form of the dynamical system describing the motion of nematic liquid crystals filling a bounded region $\mathcal{O} \subset \mathbb{R}^d$, $d = 2, 3$. This system is given by

$$\mathbf{v}_t + (\mathbf{v} \cdot \nabla)\mathbf{v} - \mu \Delta \mathbf{v} + \nabla p = -\lambda \operatorname{div}(\nabla \mathbf{n} \odot \nabla \mathbf{n}), \text{ in } (0, T] \times \mathcal{O} \tag{1.1}$$

$$\operatorname{div} \mathbf{v} = 0, \text{ in } (0, T] \times \mathcal{O} \tag{1.2}$$

$$\mathbf{n}_t + (\mathbf{v} \cdot \nabla)\mathbf{n} = \gamma \left(\Delta \mathbf{n} + |\nabla \mathbf{n}|^2 \mathbf{n} \right), \text{ in } (0, T] \times \mathcal{O} \tag{1.3}$$

$$\mathbf{n}(0) = \mathbf{n}_0, \text{ and } \mathbf{v}(0) = \mathbf{v}_0 \text{ in } \mathcal{O} \tag{1.4}$$

$$|\mathbf{n}|^2 = 1, \text{ on } (0, T] \times \mathcal{O}. \tag{1.5}$$

Here $p : \mathbb{R}^d \rightarrow \mathbb{R}$ represents the pressure of the fluid, $\mathbf{v} : \mathbb{R}^d \rightarrow \mathbb{R}^d$ its velocity and $\mathbf{n} : \mathbb{R}^d \rightarrow \mathbb{R}^3$ the liquid crystal molecules director. By the symbol $\nabla \mathbf{n} \odot \nabla \mathbf{n}$ we mean a $d \times d$ -matrix with entries defined by

$$[\nabla \mathbf{n} \odot \nabla \mathbf{n}]_{i,j} = \sum_{k=1}^3 \frac{\partial \mathbf{n}^{(k)}}{\partial x_i} \frac{\partial \mathbf{n}^{(k)}}{\partial x_j}, \quad i, j = 1, \dots, d.$$

We assume that the boundary of \mathcal{O} is smooth and equip the system with the boundary conditions

$$\mathbf{v} = 0 \text{ and } \frac{\partial \mathbf{n}}{\partial \boldsymbol{\nu}} = 0 \text{ on } \partial \mathcal{O}, \tag{1.6}$$

and the initial conditions

$$\mathbf{v}(0) = \mathbf{v}_0 \text{ and } \mathbf{n}(0) = \mathbf{n}_0, \tag{1.7}$$

where \mathbf{v}_0 and \mathbf{n}_0 are given mappings defined on \mathcal{O} . Here, the vector field $\boldsymbol{\nu}$ is the unit outward normal to $\partial \mathcal{O}$, *i.e.*, at each point x of \mathcal{O} , $\boldsymbol{\nu}(x)$ is perpendicular to the tangent space $T_x \partial \mathcal{O}$, of length 1 and facing outside of \mathcal{O} .

Although the system (1.1)–(1.6) is the most basic and simplest form of equations from the Ericksen–Leslie continuum theory, it retains the most physical significance of the Nematic liquid crystals. Moreover, it offers several interesting mathematical problems. In fact, on one hand, two of the main mathematical difficulties related to

the system (1.1)–(1.6) are non-parabolicity of Eq. (1.3) and high nonlinearity of the term $\operatorname{div} \sigma^E = -\operatorname{div} (\nabla \mathbf{n} \odot \nabla \mathbf{n})$. The non-parabolicity follows from the fact that

$$\Delta \mathbf{n} + |\nabla \mathbf{n}|^2 \mathbf{n} = \mathbf{n} \times (\Delta \mathbf{n} \times \mathbf{n}), \tag{1.8}$$

so that the linear term $\Delta \mathbf{n}$ in (1.3) is only a tangential part of the full Laplacian. Here we have denoted the vector product by \times . The term $\operatorname{div} (\nabla \mathbf{n} \odot \nabla \mathbf{n})$ makes the problem (1.1)–(1.6) a fully nonlinear and constrained system of PDEs coupled via a quadratic gradient nonlinearity. On the other hand, a number of challenging questions about the solutions to Navier–Stokes equations (NSEs) and Geometric Heat equation (GHE) are still open.

In 1995, Lin and Liu [29] proposed an approximation of the system (1.1)–(1.6) to relax the constraint $|\mathbf{n}|^2 = 1$ and the gradient nonlinearity $|\nabla \mathbf{n}|^2 \mathbf{n}$. More precisely, they studied the following system of equations

$$\mathbf{v}_t + (\mathbf{v} \cdot \nabla) \mathbf{v} - \mu \Delta \mathbf{v} + \nabla p = -\lambda \operatorname{div}(\nabla \mathbf{n} \odot \nabla \mathbf{n}), \text{ in } (0, T] \times \mathcal{O} \tag{1.9}$$

$$\operatorname{div} \mathbf{v} = 0, \text{ in } [0, T] \times \mathcal{O} \tag{1.10}$$

$$\mathbf{n}(0) = \mathbf{n}_0 \text{ and } \mathbf{v}(0) = \mathbf{v}_0 \text{ in } \mathcal{O}, \tag{1.11}$$

$$\mathbf{n}_t + (\mathbf{v} \cdot \nabla) \mathbf{n} = \gamma \left(\Delta \mathbf{n} - \frac{1}{\varepsilon^2} (|\mathbf{n}|^2 - 1) \mathbf{n} \right) \text{ in } (0, T] \times \mathcal{O}, \tag{1.12}$$

where $\varepsilon > 0$ is an arbitrary constant.

Problem (1.9)–(1.12) with boundary conditions (1.6) is much simpler than (1.1)–(1.5) with (1.6), but it offers several difficult mathematical problems. Since the pioneering work [29] the systems (1.9)–(1.12) and (1.1)–(1.5) have been the subject of intensive mathematical studies. We refer, among others, to [13, 19, 21, 29, 31–33, 42] and references therein for the relevant results. We also note that more general Ericksen–Leslie systems have been recently studied, see, for instance, [9, 22, 23, 25, 30, 47, 48] and references therein.

In this paper, we are interested in the mathematical analysis of a stochastic version of problem (1.9)–(1.12). Basically, we will investigate a system of stochastic evolution equations which is obtained by introducing appropriate noise term in (1.1)–(1.5). In contrast to the unpublished manuscript [7] we replace the bounded Ginzburg–Landau function $1_{|\mathbf{n}| \leq 1} (|\mathbf{n}|^2 - 1) \mathbf{n}$ in the coupled system by an appropriate polynomial function $f(\mathbf{n})$. More precisely, we set $\mu = \lambda = \gamma = 1$ and we consider cylindrical Wiener processes W_1 on a separable Hilbert space K_1 and a standard real-valued Brownian motion W_2 . We assume that W_1 and W_2 are independent. We consider the problem

$$d\mathbf{v}(t) + [(\mathbf{v}(t) \cdot \nabla) \mathbf{v}(t) - \Delta \mathbf{v}(t) + \nabla p] dt = -\operatorname{div}(\nabla \mathbf{n}(t) \odot \nabla \mathbf{n}(t)) dt + S(\mathbf{v}(t)) dW_1(t), \tag{1.13}$$

$$\operatorname{div} \mathbf{v}(t) = 0, \tag{1.14}$$

$$d\mathbf{n}(t) + (\mathbf{v}(t) \cdot \nabla) \mathbf{n}(t) dt = [\Delta \mathbf{n}(t) - f(\mathbf{n})] dt + (\mathbf{n}(t) \times \mathbf{h}) \circ dW_2(t), \tag{1.15}$$

$$\mathbf{v} = 0 \text{ and } \frac{\partial \mathbf{n}}{\partial \nu} = 0 \text{ on } \partial \mathcal{O}, \tag{1.16}$$

$$\mathbf{v}(0) = \mathbf{v}_0 \text{ and } \mathbf{n}(0) = \mathbf{n}_0, \tag{1.17}$$

where $\mathbf{h} : \mathbb{R}^d \rightarrow \mathbb{R}^3$ is a given function, $(\mathbf{n}(t) \times \mathbf{h}) \circ dW_2(t)$ is understood in the Stratonovich sense and f is a polynomial function and the above system holds in $\mathcal{O}_T := (0, T] \times \mathcal{O}$. We will give more details about the polynomial f later on.

Our work is motivated by the importance of external perturbation on the dynamics of the director field \mathbf{n} . Indeed, an essential property of nematic liquid crystals is that its director field \mathbf{n} can be easily distorted. However, it can also be aligned to form a specific pattern under some external perturbations. This pattern formation occurs when a threshold value of the external perturbations is attained; this is the so-called Fréedericksz transition. Random external perturbations change a little bit the threshold value for the Fréedericksz transition. For example, it has been found that with the fluctuation of the magnetic field the relaxation time of an unstable state diminishes, *i.e.*, the time for a noisy system to leave an unstable state is much shorter than the unperturbed system. For these results, we refer, among others, to [24,40, 41] and references therein. In all of these works, the effect of the hydrodynamic flow has been neglected. However, it is pointed out in [15, Chapter 5] that the fluid flow disturbs the alignment and conversely a change in the alignment will induce a flow in the nematic liquid crystal. Hence, for a full understanding of the effect of fluctuating magnetic field on the behavior of the liquid crystals one needs to take into account the dynamics of \mathbf{n} and \mathbf{v} . To initiate this kind of investigation we propose a mathematical study of (1.13)–(1.15) which basically describes an approximation of the system governing the nematic liquid crystals under the influence of fluctuating external forces.

In the present paper, we prove some results that are the stochastic counterparts of some of those obtained by Lin and Liu in [29]. Our results can be described as follows. In Sect. 3 we establish the existence of global martingale solutions (weak in the PDEs sense). To prove this result, we first find a suitable finite dimensional Galerkin approximation of system (1.13)–(1.15), which can be solved locally in time. Our choice of the approximation yields the global existence of the approximating solutions $(\mathbf{v}_m, \mathbf{n}_m)$. For this purpose, we derive several significant global a priori estimates in higher order Sobolev spaces involving the following two energy functionals

$$\mathcal{E}_1(\mathbf{n}, t) := \|\mathbf{n}(t)\|^q + q \int_0^t \|\mathbf{n}(s)\|^{q-2} \|\nabla \mathbf{n}(s)\|^2 ds + q \int_0^t \|\mathbf{n}(s)\|^{q-2} \|\mathbf{n}(s)\|_{\mathbf{L}^{2N+2}}^{2N+2} ds$$

and

$$\begin{aligned} \mathcal{E}_2(\mathbf{v}, \mathbf{n}, t) := & \|\mathbf{v}(t)\|^2 + \tilde{\ell} \|\mathbf{n}(t)\|^2 + \|\nabla \mathbf{n}(t)\|^2 + \int_{\mathcal{O}} F(\mathbf{n}(t), x) dx \\ & + \left(\int_0^t \|\nabla \mathbf{v}(s)\|^2 + \|\Delta \mathbf{n}(s) - f(\mathbf{n}(s))\|^2 \right) ds. \end{aligned}$$

Here $F(\cdot)$ is the antiderivative of f such that $F(0) = 0$ and $\tilde{\ell} > 0$ is a certain constant. These global a priori estimates, the proofs of which are non-trivial and require long and tedious calculation, are very crucial for the proof of the tightness

of the family of distributions $\{(\mathbf{v}_m, \mathbf{n}_m) : m \in \mathbb{N}\}$, where $(\mathbf{v}_m, \mathbf{n}_m)$ is the solution of the Galerkin approximation in certain appropriate topological spaces such as $L^2(0, T; \mathbb{L}^2(\mathcal{O}) \times \mathbf{H}^1(\mathcal{O}))$. This tightness result along Prokhorov’s theorem and Skorokhod’s representation theorem will enable us to construct a new probability space on which we also find a new sequence of processes $(\bar{\mathbf{v}}_m, \bar{\mathbf{n}}_m, \bar{W}_1^m, \bar{W}_2^m)$ of solutions of the Galerkin equations. This new sequence is proved to converge to a system $(\mathbf{v}, \mathbf{n}, \bar{W}_1, \bar{W}_2)$ which along with the new probability space will form our weak martingale solution. To close the first part of our results we show that the weak martingale solution is pathwise unique in the 2-D case. We prove a maximum principle type theorem in Sect. 5. More precisely, if we consider $f(\mathbf{n}) = \mathbb{1}_{|\mathbf{n}| \leq 1} (|\mathbf{n}|^2 - 1)\mathbf{n}$ instead and if the initial condition \mathbf{n}_0 satisfies $|\mathbf{n}_0| \leq 1$, then the solution \mathbf{n} also remains in the unit ball. In contrast to the deterministic case, this result does not follow in a straightforward way from well-known results. Here the method of proofs are based on the blending of ideas from [11,16].

To the best of our knowledge, our work is the first mathematical work, which studies the existence and uniqueness of a weak martingale solution of system (1.13)–(1.15). Under the assumption that $f(\cdot)$ is a bounded function, the authors proved in the unpublished manuscript [7] that the system (1.13)–(1.15) has a maximal strong solution which is global for the 2D case. Therefore, the present article is a generalization of [7] in the sense that we allow $f(\cdot)$ to be an unbounded polynomial function.

The organization of the present article is as follows. In Sect. 2 we introduce the notations that are frequently used throughout this paper. In the same section, we also state and prove some useful lemmata. By using the scheme, we outlined above we show in Sect. 3 that (1.13)–(1.15) admits a weak martingale solution which is pathwise unique in the two-dimensional case. The existence results rely on the derivation of several crucial estimates for the approximating solutions. These uniform estimates are proved in Sect. 4. In Sect. 5 a maximum principle type theorem is proved when $f(\mathbf{n}) = \mathbb{1}_{|\mathbf{n}| \leq 1} (|\mathbf{n}|^2 - 1)\mathbf{n}$. In “Appendix” section we recall or prove several crucial estimates about the nonlinear terms of the system (1.13)–(1.15).

2 Functional spaces and preparatory lemma

2.1 Functional spaces and linear operators

Let $d \in \{2, 3\}$ and assume that $\mathcal{O} \subset \mathbb{R}^d$ is a bounded domain with boundary $\partial\mathcal{O}$ of class \mathcal{C}^∞ . For any $p \in [1, \infty)$ and $k \in \mathbb{N}$, $L^p(\mathcal{O})$ and $\mathbf{W}^{k,p}(\mathcal{O})$ are the well-known Lebesgue and Sobolev spaces, respectively, of \mathbb{R} -valued functions. The spaces of functions $\mathbf{v} : \mathbb{R}^d \rightarrow \mathbb{R}^d$ (resp. $\mathbf{n} : \mathbb{R}^d \rightarrow \mathbb{R}^3$) such that each component of \mathbf{v} (resp. \mathbf{n}) belongs to $L^p(\mathcal{O})$ or to $\mathbf{W}^{k,p}(\mathcal{O})$ are denoted by $\mathbb{L}^p(\mathcal{O})$ or by $\mathbb{W}^{k,p}(\mathcal{O})$ (resp. by $\mathbf{L}^p(\mathcal{O})$ or by $\mathbf{W}^{k,p}(\mathcal{O})$). For $p = 2$ the function space $\mathbb{W}^{k,2}(\mathcal{O})$ is denoted by \mathbb{H}^k and its norm is denoted by $\|\mathbf{u}\|_k$. The usual scalar product on \mathbb{L}^2 is denoted by $\langle u, v \rangle$ for $u, v \in \mathbb{L}^2$ and its associated norm is denoted by $\|u\|$, $u \in \mathbb{L}^2$. By \mathbb{H}_0^1 we mean the space of functions in \mathbb{H}^1 that vanish on the boundary on \mathcal{O} ; \mathbb{H}_0^1 is a Hilbert space when endowed with the scalar product induced by that of \mathbb{H}^1 . We understand that the same

remarks hold for the spaces and $\mathbf{W}^{k,p}, \mathbf{H}^1, \mathbf{L}^2$ and so on. We will also understand that the norm of \mathbf{H}^k (resp. \mathbf{L}^2) is also denoted by $\|\cdot\|_k$ (resp. $\|\cdot\|$).

We now introduce the following spaces

$$\begin{aligned} \mathcal{V} &= \left\{ \mathbf{u} \in C_c^\infty(\mathcal{O}, \mathbb{R}^d) \text{ such that } \operatorname{div} \mathbf{u} = 0 \right\} \\ \mathbf{V} &= \text{closure of } \mathcal{V} \text{ in } \mathbb{H}_0^1(\mathcal{O}) \\ \mathbf{H} &= \text{closure of } \mathcal{V} \text{ in } \mathbb{L}^2(\mathcal{O}). \end{aligned}$$

We endow \mathbf{H} with the scalar product and norm of \mathbb{L}^2 . As usual we equip the space \mathbf{V} with the the scalar product $\langle \nabla \mathbf{u}, \nabla \mathbf{v} \rangle$ which, owing to the Poincaré inequality, is equivalent to the $\mathbb{H}^1(\mathcal{O})$ -scalar product.

Let $\Pi : \mathbb{L}^2 \rightarrow \mathbf{H}$ be the Helmholtz-Leray projection from \mathbb{L}^2 onto \mathbf{H} . We denote by $\mathbf{A} = -\Pi \Delta$ the Stokes operator with domain $D(\mathbf{A}) = \mathbf{V} \cap \mathbb{H}^2$. It is well-known (see for e.g. [45, Chapter I, Section 2.6]) that there exists an orthonormal basis $(\varphi_i)_{i=1}^\infty$ of \mathbf{H} consisting of the eigenfunctions of the Stokes operator \mathbf{A} . For $\beta \in [0, \infty)$, we denote by \mathbf{V}_β the Hilbert space $D(\mathbf{A}^\beta)$ endowed with the graph inner product. The Hilbert space $\mathbf{V}_\beta = D(\mathbf{A}^\beta)$ for $\beta \in (-\infty, 0)$ can be defined by standard extrapolation methods. In particular, the space $D(\mathbf{A}^{-\beta})$ is the dual of \mathbf{V}_β for $\beta \geq 0$. Moreover, for every $\beta, \delta \in \mathbb{R}$ the mapping \mathbf{A}^δ is a linear isomorphism between \mathbf{V}_β and $\mathbf{V}_{\beta-\delta}$. It is also well-known that $\mathbf{V}_{\frac{1}{2}} = \mathbf{V}$, see [12, page 33].

The Neumann Laplacian acting on \mathbb{R}^3 -valued function will be denoted by \mathbf{A}_1 , that is,

$$\begin{aligned} D(\mathbf{A}_1) &:= \left\{ \mathbf{u} \in \mathbf{H}^2 : \frac{\partial \mathbf{u}}{\partial \mathbf{v}} = 0 \text{ on } \partial \mathcal{O} \right\}, \\ \mathbf{A}_1 \mathbf{u} &:= - \sum_{i=1}^d \frac{\partial^2 \mathbf{u}}{\partial x_i^2}, \quad \mathbf{u} \in D(\mathbf{A}_1). \end{aligned} \tag{2.1}$$

It can also be shown, see e.g. [20, Theorem 5.31], that $\hat{\mathbf{A}}_1 = I + \mathbf{A}_1$ is a definite positive and self-adjoint operator in the Hilbert space $\mathbf{L}^2 := \mathbf{L}^2(\mathcal{O})$ with compact resolvent. In particular, there exists an ONB $(\phi_k)_{k=1}^\infty$ of \mathbf{L}^2 and an increasing sequence $(\lambda_k)_{k=1}^\infty$ with $\lambda_1 = 0$ and $\lambda_k \nearrow \infty$ as $k \nearrow \infty$ (the eigenvalues of the Neumann Laplacian \mathbf{A}_1) such that $\mathbf{A}_1 \phi_k = \lambda_k \phi_k$ for any $j \in \mathbb{N}$.

For any $\alpha \in [0, \infty)$ we denote by $\mathbf{X}_\alpha = D(\hat{\mathbf{A}}_1^\alpha)$, the domain of the fractional power operator $\hat{\mathbf{A}}_1^\alpha$. We have the following characterization of the spaces \mathbf{X}_α ,

$$\mathbf{X}_\alpha = \left\{ \mathbf{u} = \sum_{k \in \mathbb{N}} u_k \phi_k : \sum_{k \in \mathbb{N}} (1 + \lambda_k)^{2\alpha} |u_k|^2 < \infty \right\}. \tag{2.2}$$

It can be shown that $\mathbf{X}_\alpha \subset \mathbf{H}^{2\alpha}$, for all $\alpha \geq 0$ and $\mathbf{X} := \mathbf{X}_{\frac{1}{2}} = \mathbf{H}^1$, see, for instance, [46, Sections 4.3.3 and 4.9.2].

For a fixed $\mathbf{h} \in \mathbf{L}^\infty$ we define a bounded linear operator G from \mathbf{L}^2 into itself by

$$G : \mathbf{L}^2 \ni \mathbf{n} \mapsto \mathbf{n} \times \mathbf{h} \in \mathbf{L}^2.$$

It is straightforward to check that there exists a constant $C > 0$ such that

$$\|G(\mathbf{n})\| \leq C \|\mathbf{h}\|_{\mathbf{L}^\infty} \|\mathbf{n}\|, \text{ for any } \mathbf{n} \in \mathbf{L}^2.$$

Given two Hilbert spaces K and H , we denote by $\mathcal{L}(K, H)$ and $\mathcal{T}_2(K, H)$ the space of bounded linear operators and the Hilbert space of all Hilbert–Schmidt operators from K to H , respectively. For $K = H$ we just write $\mathcal{L}(K)$ instead of $\mathcal{L}(K, K)$.

2.2 The nonlinear terms

Throughout this paper \mathbf{B}^* denotes the dual space of a Banach space \mathbf{B} . We also denote by $\langle \Psi, \mathbf{b} \rangle_{\mathbf{B}^*, \mathbf{B}}$ the value of $\Psi \in \mathbf{B}^*$ on $\mathbf{b} \in \mathbf{B}$.

We define a trilinear form $b(\cdot, \cdot, \cdot)$ by

$$b(\mathbf{u}, \mathbf{v}, \mathbf{w}) = \sum_{i,j=1}^d \int_{\mathcal{O}} \mathbf{u}^{(i)} \frac{\partial \mathbf{v}^{(j)}}{\partial x_i} \mathbf{w}^{(j)} dx, \quad \mathbf{u} \in \mathbb{L}^p, \mathbf{v} \in \mathbb{W}^{1,q}, \text{ and } \mathbf{w} \in \mathbb{L}^r,$$

with numbers $p, q, r \in [1, \infty]$ satisfying

$$\frac{1}{p} + \frac{1}{q} + \frac{1}{r} \leq 1.$$

Here $\partial_{x_i} = \frac{\partial}{\partial x_i}$ and $\phi^{(i)}$ is the i -th entry of any vector-valued ϕ . Note that in the above definition we can also take $\mathbf{v} \in \mathbb{W}^{1,q}$ and $\mathbf{w} \in \mathbb{L}^r$, but in this case we have to take the sum over j from $j = 1$ to $j = 3$.

The mapping b is the trilinear form used in the mathematical analysis of the Navier–Stokes equations, see for instance [45, Chapter II, Section 1.2]. It is well known, see [45, Chapter II, Section 1.2], that one can define a bilinear mapping B from $\mathbb{V} \times \mathbb{V}$ with values in \mathbb{V}^* such that

$$\langle B(\mathbf{u}, \mathbf{v}), \mathbf{w} \rangle_{\mathbb{V}^*, \mathbb{V}} = b(\mathbf{u}, \mathbf{v}, \mathbf{w}) \text{ for } \mathbf{w} \in \mathbb{V}, \text{ and } \mathbf{u}, \mathbf{v} \in \mathbb{H}^1. \tag{2.3}$$

In a similar way, we can also define a bilinear mapping \tilde{B} defined on $\mathbb{H}^1 \times \mathbb{H}^1$ with values in $(\mathbb{H}^1)^*$ such that

$$\langle \tilde{B}(\mathbf{u}, \mathbf{v}), \mathbf{w} \rangle_{(\mathbb{H}^1)^*, \mathbb{H}^1} = b(\mathbf{u}, \mathbf{v}, \mathbf{w}) \text{ for any } \mathbf{u} \in \mathbb{H}^1, \mathbf{v}, \mathbf{w} \in \mathbb{H}^1. \tag{2.4}$$

Well-known properties of B and \tilde{B} will be given in the ‘‘Appendix’’ section.

Let m be the trilinear form defined by

$$m(\mathbf{n}_1, \mathbf{n}_2, \mathbf{u}) = - \sum_{i,j=1}^d \sum_{k=1}^3 \int_{\mathcal{O}} \partial_{x_i} \mathbf{n}_1^{(k)} \partial_{x_j} \mathbf{n}_2^{(k)} \partial_{x_j} \mathbf{u}^{(i)} dx \tag{2.5}$$

for any $\mathbf{n}_1 \in \mathbf{W}^{1,p}$, $\mathbf{n}_2 \in \mathbf{W}^{1,q}$ and $\mathbf{u} \in \mathbb{W}^{1,r}$ with $r, p, q \in (1, \infty)$ satisfying

$$\frac{1}{p} + \frac{1}{q} + \frac{1}{r} \leq 1.$$

Since $d \leq 4$, the integral in (2.5) is well defined for $\mathbf{n}_1, \mathbf{n}_2 \in \mathbf{H}^2$ and $\mathbf{u} \in \mathbf{V}$. We have the following lemma.

Lemma 2.1 *Let $d \in [1, 4]$. Then, there exist a constant $C > 0$ such that*

$$|m(\mathbf{n}_1, \mathbf{n}_2, \mathbf{u})| \leq C \|\nabla \mathbf{n}_1\|^{1-\frac{d}{4}} \|\nabla^2 \mathbf{n}_1\|^{\frac{d}{4}} \|\nabla \mathbf{n}_2\|^{1-\frac{d}{4}} \|\nabla^2 \mathbf{n}_2\|^{\frac{d}{4}} \|\nabla \mathbf{u}\|, \tag{2.6}$$

for any $\mathbf{n}_1, \mathbf{n}_2 \in \mathbf{H}^2$ and $\mathbf{u} \in \mathbf{V}$.

Proof of Lemma 2.1 From (2.5) and Hölder’s inequality we derive that

$$|m(\mathbf{n}_1, \mathbf{n}_2, \mathbf{u})| \leq \int_{\mathcal{O}} |\nabla \mathbf{n}_1| |\nabla \mathbf{n}_2| |\nabla \mathbf{u}| dx.$$

The above integral is well-defined since $\nabla \mathbf{n}_i \in \mathbf{L}^{\frac{2d}{d-2}}$, $i = 1, 2$, $\nabla \mathbf{u} \in \mathbb{L}^2$ and $\frac{d-2}{d} + \frac{1}{2} \leq 1$ for $d \leq 4$. When $d = 2$ we replace $2d/(d - 2)$ by any $q \in [4, \infty)$. Note that for $d \leq 4$ we have $|\nabla \mathbf{n}_i| \in \mathbf{L}^4$, $i = 1, 2$. Hence

$$|m(\mathbf{n}_1, \mathbf{n}_2, \mathbf{u})| \leq C \|\nabla \mathbf{n}_1\|_{\mathbb{L}^4} \|\nabla \mathbf{n}_2\|_{\mathbb{L}^4} \|\nabla \mathbf{u}\|.$$

This last estimate and Gagliardo–Nirenberg’s inequality (6.1) lead us to

$$|m(\mathbf{n}_1, \mathbf{n}_2, \mathbf{u})| \leq C \|\nabla \mathbf{n}_1\|^{1-\frac{d}{4}} \|\nabla^2 \mathbf{n}_1\|^{\frac{d}{4}} \|\nabla \mathbf{n}_2\|^{1-\frac{d}{4}} \|\nabla^2 \mathbf{n}_2\|^{\frac{d}{4}} \|\nabla \mathbf{u}\|. \tag{2.7}$$

This concludes the proof of our claim. □

The above result tells us that the mapping $\mathbf{V} \ni \mathbf{u} \mapsto m(\mathbf{n}_1, \mathbf{n}_2, \mathbf{u})$ is an element of $\mathcal{L}(\mathbf{V}, \mathbb{R})$ whenever $\mathbf{n}_1, \mathbf{n}_2 \in \mathbf{H}^2$. Now, we state and prove the following proposition.

Proposition 2.2 *Let $d \in [1, 4]$. There exists a bilinear operator M defined on $\mathbf{H}^2 \times \mathbf{H}^2$ taking values in \mathbf{V}^* such that for any $\mathbf{n}_1, \mathbf{n}_2 \in \mathbf{H}^2$*

$$\langle M(\mathbf{n}_1, \mathbf{n}_2), \mathbf{u} \rangle_{\mathbf{V}^*, \mathbf{V}} = m(\mathbf{n}_1, \mathbf{n}_2, \mathbf{u}) \quad \mathbf{u} \in \mathbf{V}. \tag{2.8}$$

Furthermore, there exists a constant $C > 0$ such that

$$\|M(\mathbf{n}_1, \mathbf{n}_2)\|_{\mathbf{V}^*} \leq C \|\nabla \mathbf{n}_1\|^{1-\frac{d}{4}} \|\nabla^2 \mathbf{n}_1\|^{\frac{d}{4}} \|\nabla \mathbf{n}_2\|^{1-\frac{d}{4}} \|\nabla^2 \mathbf{n}_2\|^{\frac{d}{4}}, \tag{2.9}$$

for any $\mathbf{n}_1, \mathbf{n}_2 \in \mathbf{H}^2$. We also have the following identity

$$\langle \tilde{B}(\mathbf{v}, \mathbf{n}), A_1 \mathbf{n} \rangle = -\langle M(\mathbf{n}, \mathbf{n}), \mathbf{v} \rangle_{V^*, V}, \text{ for any } \mathbf{v} \in V, \mathbf{n} \in D(A_1). \quad (2.10)$$

Proof The first part and (2.9) follow from Lemma 2.1.

To prove (2.10) we first note that $\langle \tilde{B}(\mathbf{v}, \mathbf{n}_2), A_1 \mathbf{n}_1 \rangle = b(\mathbf{v}, \mathbf{n}_2, A_1 \mathbf{n}_1)$ is well-defined for any $\mathbf{v} \in V, \mathbf{n}_1, \mathbf{n}_2 \in D(A_1)$. Thus, taking into account that \mathbf{v} is divergence free and vanishes on the boundary we can perform an integration-by-parts and deduce that

$$\begin{aligned} \langle B(\mathbf{v}, \mathbf{n}), A_1 \mathbf{n} \rangle &= - \int_{\mathcal{O}} \mathbf{v}^{(i)} \frac{\partial \mathbf{n}^{(k)}}{\partial x_i} \frac{\partial^2 \mathbf{n}^{(k)}}{\partial x_l \partial x_l} dx \\ &= \int_{\mathcal{O}} \frac{\partial \mathbf{v}^{(i)}}{\partial x_l} \frac{\partial \mathbf{n}^{(k)}}{\partial x_i} \frac{\partial \mathbf{n}^{(k)}}{\partial x_l} dx - \int_{\mathcal{O}} \mathbf{v}^{(i)} \frac{\partial^2 \mathbf{n}^{(k)}}{\partial x_i \partial x_l} \frac{\partial \mathbf{n}^{(k)}}{\partial x_l} dx \\ &= - \int_{\mathcal{O}} \frac{\partial \mathbf{v}^{(i)}}{\partial x_l} \frac{\partial \mathbf{n}^{(k)}}{\partial x_i} \frac{\partial \mathbf{n}^{(k)}}{\partial x_l} dx - \frac{1}{2} \int_{\mathcal{O}} \mathbf{v}^{(i)} \frac{\partial |\nabla \mathbf{n}|^2}{\partial x_i} dx \\ &= \int_{\mathcal{O}} \frac{\partial \mathbf{v}^{(i)}}{\partial x_l} \frac{\partial \mathbf{n}^{(k)}}{\partial x_i} \frac{\partial \mathbf{n}^{(k)}}{\partial x_l} dx \\ &= -m(\mathbf{n}, \mathbf{n}, \mathbf{v}) = -\langle M(\mathbf{n}, \mathbf{n}), \mathbf{v} \rangle_{V^*, V}. \end{aligned}$$

In the above chain of equalities summation over repeated indexes is enforced. □

Remark 2.3 1. For any $\mathbf{f}, \mathbf{g} \in \mathbf{X}_1$ and $\mathbf{v} \in H$ we have

$$\langle M(\mathbf{f}, \mathbf{g}), \mathbf{v} \rangle_{V^*, V} = \langle \Pi[\text{div}(\nabla \mathbf{f} \odot \nabla \mathbf{g})], \mathbf{v} \rangle. \quad (2.11)$$

In fact, for any $\mathbf{f}, \mathbf{g} \in \mathbf{X}_1$ and $\mathbf{v} \in \mathcal{V}$

$$\begin{aligned} \langle M(\mathbf{f}, \mathbf{g}), \mathbf{v} \rangle_{V^*, V} &= -\langle \nabla \mathbf{f} \odot \nabla \mathbf{g}, \nabla \mathbf{v} \rangle \\ &= \langle \text{div}(\nabla \mathbf{f} \odot \nabla \mathbf{g}), \Pi \mathbf{v} \rangle \\ &= \langle \Pi[\text{div}(\nabla \mathbf{f} \odot \nabla \mathbf{g})], \mathbf{v} \rangle. \end{aligned}$$

Thanks to the density of \mathcal{V} in H we can easily show that the last line is still true for $\mathbf{v} \in H$, which completes the proof of (2.11).

2. In some places in this manuscript we use the following shorthand notation:

$$B(\mathbf{u}) := B(\mathbf{u}, \mathbf{u}) \text{ and } M(\mathbf{n}) := M(\mathbf{n}, \mathbf{n}),$$

for any \mathbf{u} and \mathbf{n} such that the above quantities are meaningful.

We now fix the standing assumptions on the function $f(\cdot)$.

Assumption 2.1 Let I_d be the set defined by

$$I_d = \begin{cases} \mathbb{N} := \{1, 2, 3, \dots\} & \text{if } d = 2, \\ \{1\}, & \text{if } d = 3. \end{cases} \quad (2.12)$$

Throughout this paper we fix $N \in I_d$ and a family of numbers $a_k, k = 0, \dots, N$, with $a_N > 0$. We define a function $\tilde{f} : [0, \infty) \rightarrow \mathbb{R}$ by

$$\tilde{f}(r) = \sum_{k=0}^N a_k r^k, \text{ for any } r \in \mathbb{R}_+.$$

We define a mapping $f : \mathbb{R}^3 \rightarrow \mathbb{R}^3$ by $f(\mathbf{n}) = \tilde{f}(|\mathbf{n}|^2)\mathbf{n}$ where \tilde{f} is as above.

We now assume that there exists $F : \mathbb{R}^3 \rightarrow \mathbb{R}$ a differentiable mapping such that for any $\mathbf{n} \in \mathbb{R}^3$ and $\mathbf{g} \in \mathbb{R}^3$

$$F'(\mathbf{n})[\mathbf{g}] = f(\mathbf{n}) \cdot \mathbf{g}.$$

Before proceeding further let us state few important remarks.

Remark 2.4 Let \tilde{F} be an antiderivative of \tilde{f} such that $\tilde{F}(0) = 0$. Then, as a consequence of our assumption we have

$$\tilde{F}(r) = a_{N+1}r^{N+1} + U(r),$$

where U is a polynomial function of at most degree N and $a_{N+1} > 0$.

Remark 2.5 For any $r \in [0, \infty)$ let $\tilde{f}(r) := r - 1$. If $1 \in I_d$ then the mappings f and F defined on \mathbb{R}^3 by $f(\mathbf{n}) := \tilde{f}(|\mathbf{n}|^2)\mathbf{n}$ and $F(\mathbf{n}) := \frac{1}{4}[\tilde{f}(|\mathbf{n}|^2)]^2$ for any $\mathbf{n} \in \mathbb{R}^3$ satisfy the above set of assumptions.

Remark 2.6 There exist two constants $\ell_1, \ell_2 > 0$ such that

$$|\tilde{f}(r)| \leq \ell_1 (1 + r^N), \quad r > 0, \tag{2.13}$$

$$|\tilde{f}'(r)| \leq \ell_2 (1 + r^{N_1}), \quad r > 0. \tag{2.14}$$

Remark 2.7 Let f be defined as in Assumption 2.1.

(i) Then, there exist two positive constants $c > 0$ and $\tilde{c} > 0$ such that

$$|f(\mathbf{n})| \leq c (1 + |\mathbf{n}|^{2N+1}) \text{ and } |f'(\mathbf{n})| \leq \tilde{c} (1 + |\mathbf{n}|^{2N}) \text{ for any } \mathbf{n} \in \mathbb{R}^3.$$

(ii) By performing elementary calculations we can check that there exists a constant $C > 0$ such that for any $\mathbf{n} \in \mathbf{H}^2$

$$\begin{aligned} \|A_1 \mathbf{n}\|^2 &= \|A_1 \mathbf{n} + f(\mathbf{n}) - f(\mathbf{n})\|^2 \leq 2\|A_1 \mathbf{n} + f(\mathbf{n})\|^2 + 2\|f(\mathbf{n})\|^2, \\ &\leq 2\|A_1 \mathbf{n} + f(\mathbf{n})\|^2 + C\|\mathbf{n}\|_{\mathbf{L}^{\tilde{q}}}^{\tilde{q}} + C, \end{aligned} \tag{2.15}$$

where $\tilde{q} = 4N + 2$.

(iii) Observe also that since the norm $\|\cdot\|_2$ is equivalent to $\|\cdot\| + \|A_1\cdot\|$ on $D(A_1)$, there exists a constant $C > 0$ such that

$$\|\mathbf{n}\|_2^2 \leq C(\|A_1\mathbf{n} + f(\mathbf{n})\|^2 + \|\mathbf{n}\|_{\mathbf{L}^{\tilde{q}}}^{\tilde{q}} + 1), \text{ for any } \mathbf{n} \in D(A_1). \quad (2.16)$$

(iv) Finally, since $\mathbf{H}^1 \subset \mathbf{L}^{4N+2}$ for any $N \in I_d$, we can use the previous observation to conclude that $\mathbf{n} \in \mathbf{H}^2 \subset \mathbf{L}^\infty$ whenever $\mathbf{n} \in \mathbf{H}^1$ and $A_1\mathbf{n} + f(\mathbf{n}) \in \mathbf{L}^2$.

2.3 The assumption on the coefficients of the noise

Let $(\Omega, \mathcal{F}, \mathbb{P})$ be a complete probability space equipped with a filtration $\mathbb{F} = \{\mathcal{F}_t : t \geq 0\}$ satisfying the usual conditions, *i.e.* the filtration is right-continuous and all null sets of \mathcal{F} are elements of \mathcal{F}_0 . Let $W_2 = (W_2(t))_{t \geq 0}$ be a standard \mathbb{R} -valued Wiener process on $(\Omega, \mathcal{F}, \mathbb{F}, \mathbb{P})$. Let us also assume that K_1 is a separable Hilbert space and $W_1 = (W_1(t))_{t \geq 0}$ is a K_1 -cylindrical Wiener process on $(\Omega, \mathcal{F}, \mathbb{F}, \mathbb{P})$. Throughout this paper we assume that W_2 and W_1 are independent. Thus we can assume that $W = (W_1(t), W_2(t))$ is a K -cylindrical Wiener process on $(\Omega, \mathcal{F}, \mathbb{F}, \mathbb{P})$, where

$$K = K_1 \times \mathbb{R}.$$

Remark 2.8 If K_2 is a Hilbert space such that the embedding $K_1 \subset K_2$ is Hilbert-Schmidt, then W_1 can be viewed as a K_2 -valued Wiener process. Moreover, there exists a trace class symmetric nonnegative operator $Q \in \mathcal{L}(K_2)$ such that W_1 has covariance Q . This K_2 -valued K_1 -cylindrical Wiener process is characterised by, for all $t \geq 0$,

$$\mathbb{E} e^{i \langle x^*, W(t) \rangle_{K_2^*, K_2}} = e^{-\frac{t}{2} \|x^*\|_{K_1}^2}, \quad x^* \in K_2^*,$$

where K_2^* is the dual space to K_2 such that identifying K_1^* with K_1 we have

$$K_2^* \hookrightarrow K_1^* = K_1 \hookrightarrow K_2.$$

Let \tilde{H} be a Hilbert space and $\mathcal{M}^2(\Omega \times [0, T]; \mathcal{T}_2(K, \tilde{H}))$ the space of all equivalence classes of \mathbb{F} -progressively measurable processes $\Psi : \Omega \times [0, T] \rightarrow \mathcal{T}_2(K, \tilde{H})$ satisfying

$$\mathbb{E} \int_0^T \|\Psi(s)\|_{\mathcal{T}_2(K, \tilde{H})}^2 ds < \infty.$$

From the theory of stochastic integration on infinite dimensional Hilbert space, see [35, Chapter 5, Section 26] and [14, Chapter 4], for any $\Psi \in \mathcal{M}^2(\Omega \times [0, T]; \mathcal{T}_2(K, \tilde{H}))$ the process M defined by

$$M(t) = \int_0^t \Psi(s) dW(s), \quad t \in [0, T],$$

is a \tilde{H} -valued martingale. Moreover, we have the following Itô isometry

$$\mathbb{E}'\left(\left\|\int_0^t \Psi(s)dW(s)\right\|_{\tilde{H}}^2\right) = \mathbb{E}'\left(\int_0^t \|\Psi(s)\|_{\mathcal{T}_2(K,\tilde{H})}^2 ds\right), \forall t \in [0, T], \quad (2.17)$$

and the Burkholder–Davis–Gundy inequality

$$\mathbb{E}'\left(\sup_{0 \leq s \leq t} \left\|\int_0^s \Psi(s)dW(s)\right\|_{\tilde{H}}^q\right) \leq C_q \mathbb{E}'\left(\int_0^t \|\Psi(s)\|_{\mathcal{T}_2(K,\tilde{H})}^2 ds\right)^{\frac{q}{2}},$$

$$\forall t \in [0, T], \forall q \in (1, \infty). \quad (2.18)$$

We also have the following relation between Stratonovich and Itô’s integrals, see [5],

$$G(\mathbf{n}) \circ dW_2 = \frac{1}{2} G^2(\mathbf{n}) dt + G(\mathbf{n}) dW_2,$$

where $G^2 = G \circ G$ is defined by

$$G^2(\mathbf{n}) = G \circ G(\mathbf{n}) = (\mathbf{n} \times \mathbf{h}) \times \mathbf{h}, \text{ for any } \mathbf{n} \in \mathbf{L}^2.$$

We now introduce the set of hypotheses that the function S must satisfy in this paper.

Assumption 2.2 We assume that $S : H \rightarrow \mathcal{T}_2(K_1, H)$ is a globally Lipschitz mapping. In particular, there exists $\ell_3 \geq 0$ such that

$$\|S(\mathbf{u})\|_{\mathcal{T}_2}^2 := \|\mathcal{S}(\mathbf{u})\|_{\mathcal{T}_2(K_1,H)}^2 \leq \ell_3(1 + \|\mathbf{u}\|^2), \text{ for any } \mathbf{u} \in H. \quad (2.19)$$

3 Existence and uniqueness of a weak martingale solution

In this section, we are going to establish the existence of a weak martingale solution to (1.13)–(1.17) which, using all the notations in the previous section, can be formally written in the following abstract form

$$d\mathbf{v}(t) + \left(A\mathbf{v}(t) + B(\mathbf{v}(t), \mathbf{v}(t)) + M(\mathbf{n}(t)) \right) dt = S(\mathbf{v}(t))dW_1(t), \quad (3.1)$$

$$d\mathbf{n}(t) + \left(A_1\mathbf{n}(t) + \tilde{B}(\mathbf{v}(t), \mathbf{n}(t)) + f(\mathbf{n}(t)) - \frac{1}{2}G^2(\mathbf{n}(t)) \right) dt = G(\mathbf{n}(t))dW_2(t), \quad (3.2)$$

$$\mathbf{v}(0) = \mathbf{v}_0 \text{ and } \mathbf{n}(0) = \mathbf{n}_0. \quad (3.3)$$

For this purpose, we use the Galerkin approximation to reduce the original system to a system of finite-dimensional ordinary stochastic differential equations (SDEs for short). We establish several crucial uniform a priori estimates which will be used to prove the tightness of the family of laws of the sequence of solutions of the system

of SDEs on appropriate topological spaces. However, before we proceed further, we define what we mean by weak martingale solution.

Definition 3.1 Let K_1 be as in Remark 2.8. By a weak martingale solution to (3.1)–(3.3) we mean a system consisting of a complete and filtered probability space

$$(\Omega', \mathcal{F}', \mathbb{F}', \mathbb{P}'),$$

with the filtration $\mathbb{F}' = (\mathcal{F}'_t)_{t \in [0, T]}$ satisfying the usual conditions, and \mathbb{F}' -adapted stochastic processes

$$(\mathbf{v}(t), \mathbf{n}(t), \bar{W}_1(t), \bar{W}_2(t))_{t \in [0, T]}$$

such that:

1. $(\bar{W}_1(t))_{t \in [0, T]}$ (resp. $(\bar{W}_2(t))_{t \in [0, T]}$) is a K_1 -cylindrical (resp. real-valued) Wiener process,
2. $(\mathbf{v}, \mathbf{n}) : [0, T] \times \Omega' \rightarrow \mathbf{V} \times \mathbf{H}^2$ and \mathbb{P}' -a.e.

$$(\mathbf{v}, \mathbf{n}) \in C([0, T]; \mathbf{V}_{-\beta}) \times C([0, T]; \mathbf{X}_\beta), \text{ for any } \beta \in \left(0, \frac{1}{2}\right), \tag{3.4}$$

$$\mathbb{E}' \sup_{0 \leq s \leq T} [\|\mathbf{v}(s)\| + \|\nabla \mathbf{n}(s)\|] + \mathbb{E}' \int_0^T \left(\|\nabla \mathbf{v}(s)\|^2 + \|A_1 \mathbf{n}(s)\|^2 \right) ds < \infty, \tag{3.5}$$

3. for each $(\Phi, \Psi) \in \mathbf{V} \times \mathbf{L}^2$ we have for all $t \in [0, T]$ \mathbb{P}' -a.s..

$$\begin{aligned} & \langle \mathbf{v}(t) - \mathbf{v}_0, \Phi \rangle + \int_0^t \left\langle A\mathbf{v}(s) + B(\mathbf{v}(s), \mathbf{v}(s)) + M(\mathbf{n}(s)), \Phi \right\rangle_{\mathbf{V}^*, \mathbf{V}} ds \\ & = \int_0^t \langle \Phi, S(\mathbf{v}(s)) d\bar{W}_1(s) \rangle, \end{aligned} \tag{3.6}$$

and

$$\begin{aligned} & \langle \mathbf{n}(t) - \mathbf{n}_0, \Psi \rangle + \int_0^t \left\langle A_1 \mathbf{n}(s) + \tilde{B}(\mathbf{v}(s), \mathbf{n}(s)) + f(\mathbf{n}(s)) - \frac{1}{2} G^2(\mathbf{n}(s)), \Psi \right\rangle ds \\ & = \int_0^t \langle G(\mathbf{n}(s)), \Psi \rangle d\bar{W}_2(s). \end{aligned} \tag{3.7}$$

Now we can state our first result in the following theorem.

Theorem 3.2 *If Assumptions 2.2 and 2.1 are satisfied, $\mathbf{h} \in \mathbf{W}^{1,3} \cap \mathbf{L}^\infty$, $\mathbf{v}_0 \in \mathbf{H}$, $\mathbf{n}_0 \in \mathbf{H}^1$, and $d = 2, 3$, then the system (3.1)–(3.3) has a weak martingale solution in the sense of Definition 3.1.*

Proof The proof will be carried out in Sects. 3.1–3.3. □

Before we state the uniqueness of the weak martingale solution we should make the following remark.

Remark 3.3 We should note that the existence of weak martingale solutions stated in Theorem 3.2 still holds if we assume that the mapping $S(\cdot)$ is only continuous and satisfies a linear growth condition of the form (2.19).

To close this subsection we assume that $d = 2$ and we state the following uniqueness result.

Theorem 3.4 *Let $d = 2$ and assume that $(\mathbf{v}_i, \mathbf{n}_i)$, $i = 1, 2$ are two solutions of (3.1) and (3.3) defined on the same stochastic system $(\Omega, \mathcal{F}, \mathbb{F}, \mathbb{P}, W_1, W_2)$ and with the same initial condition $(\mathbf{v}_0, \mathbf{n}_0) \in \mathbf{H} \times \mathbf{H}^1$, then for any $t \in (0, T]$ we have \mathbb{P} -a.s.*

$$(\mathbf{v}_1(t), \mathbf{n}_1(t)) = (\mathbf{v}_2(t), \mathbf{n}_2(t)).$$

Remark 3.5 Due to the continuity given in (3.4) the two solutions are indistinguishable. Therefore, uniqueness holds.

Proof The proof of this result will be carried out in Sect. 3.4. □

3.1 Galerkin approximation and a priori uniform estimates

As we mentioned earlier, the proof of the existence of weak martingale solution relies on the Galerkin and compactness methods. This subsection will be devoted to the construction of the approximating solutions and the proofs of crucial estimates satisfied by these solutions.

Recall that there exists an orthonormal basis $(\varphi_i)_{i=1}^\infty \subset C^\infty$ of \mathbf{H} consisting of the eigenvectors of the Stokes operator A . Recall also that there exists an orthonormal basis $(\phi_i)_{i=1}^\infty \subset C^\infty$ of \mathbf{L}^2 consisting of the eigenvectors of the Neumann Laplacian A_1 . For any $m \in \mathbb{N}$ let us define the following finite-dimensional spaces

$$\begin{aligned} \mathbf{H}_m &:= \text{linspan}\{\varphi_1, \dots, \varphi_m\}, \\ \mathbf{L}_m &:= \text{linspan}\{\phi_1, \dots, \phi_m\}. \end{aligned}$$

In this subsection, we introduce the finite-dimensional approximation of the system (3.1)–(3.3) and justify the existence of solution of such approximation. We also derive uniform estimates for the sequence of approximating solutions. To do so, denote by π_m (resp. $\hat{\pi}_m$) the projection from \mathbf{H} (resp. \mathbf{L}^2) onto \mathbf{H}_m (resp. \mathbf{L}_m). These operators are self-adjoint, and their operator norms are equal to 1. Remark 6.3, Lemma 6.2 enable us to define the following mappings

$$\begin{aligned} B_m &: \mathbf{H}_m \ni \mathbf{u} \mapsto \pi_m B(\mathbf{u}, \mathbf{u}) \in \mathbf{H}_m, \\ \tilde{B}_m &: \mathbf{H}_m \times \mathbf{L}_m \ni (\mathbf{u}, \mathbf{n}) \mapsto \hat{\pi}_m \tilde{B}(\mathbf{v}, \mathbf{n}) \in \mathbf{L}_m, \\ M_m &: \mathbf{L}_m \ni \mathbf{n} \mapsto \pi_m M(\mathbf{n}) \in \mathbf{H}_m, \end{aligned}$$

From the definition of \mathbf{L}_m and the regularity of elements of the basis $(\phi)_{i=1}^\infty$ we infer that for any $\mathbf{u} \in \mathbf{L}_m$ $|\mathbf{u}|^{2r} \mathbf{u} \in \mathbf{L}^2$ for any $r \in \{1, \dots, N\}$. Hence the mapping f_m defined by

$$f_m : \mathbf{L}_m \ni \mathbf{n} \mapsto \hat{\pi}_m f(\mathbf{n}) \in \mathbf{L}_m,$$

is well-defined. From the assumptions on S and \mathbf{h} the following mappings are well-defined,

$$\begin{aligned} S_m : \mathbf{H}_m \ni \mathbf{u} &\mapsto \pi_m \circ S(\bar{\mathbf{u}}) \in \mathcal{T}_2(\mathbf{K}_1, \mathbf{H}_m), \\ G_m : \mathbf{L}_m \ni \mathbf{n} &\mapsto \hat{\pi}_m G(\mathbf{n}) \in \mathbf{L}_m, \\ G_m^2 : \mathbf{L}_m \ni \mathbf{n} &\mapsto \hat{\pi}_m G^2(\mathbf{n}) \in \mathbf{L}_m. \end{aligned}$$

Lemma 3.6 For each m let Ψ_m and Φ_m be two mappings on $\mathbf{H}_m \times \mathbf{L}_m$ defined by

$$\Psi_m(\mathbf{u}, \mathbf{n}) = \begin{pmatrix} A\mathbf{u} + B_m(\mathbf{u}) + M_m(\mathbf{n}) \\ A_1\mathbf{n} + \tilde{B}_m(\mathbf{u}, \mathbf{n}) + f_m(\mathbf{n}) - \frac{1}{2}G_m^2(\mathbf{n}) \end{pmatrix}, \quad (\mathbf{u}, \mathbf{n}) \in \mathbf{H}_m \times \mathbf{L}_m,$$

and

$$\Phi_m(\mathbf{u}, \mathbf{n}) = \begin{pmatrix} S_m(\mathbf{u}) & 0 \\ 0 & G_m(\mathbf{n}) \end{pmatrix}, \quad (\mathbf{u}, \mathbf{n}) \in \mathbf{H}_m \times \mathbf{L}_m.$$

Then, the mappings Ψ_m and Φ_m are locally Lipschitz.

Proof The mapping S_m is globally Lipschitz as the composition of a continuous linear operator and a globally Lipschitz mapping. Since A, A_1, G_m and G_m^2 are linear, they are globally Lipschitz. Thus, Φ is also globally Lipschitz.

From the bilinearity of $B(\cdot, \cdot)$, the boundedness of π_m and Remark 6.3 we infer that there exists a constant $C > 0$, depending on m , such that for any $\mathbf{u}, \mathbf{v} \in \mathbf{H}_m$

$$\|B_m(\mathbf{u}, \mathbf{u}) - B_m(\mathbf{v}, \mathbf{v})\| \leq C[\|\mathbf{u} - \mathbf{v}\|_1 \|\mathbf{v}\|_2 + \|\mathbf{u}\|_1 \|\mathbf{u} - \mathbf{v}\|_2]. \tag{3.8}$$

Since the $\mathbb{L}^2, \mathbb{H}^1$ and \mathbb{H}^2 norms are equivalent on the finite dimensional space \mathbf{H}_m we infer that for any $m \in \mathbb{N}$ there exists a constant $C > 0$, depending on m , such that

$$\|B_m(\mathbf{u}, \mathbf{u}) - B_m(\mathbf{v}, \mathbf{v})\| \leq C[\|\mathbf{u} - \mathbf{v}\| \|\mathbf{v}\| + \|\mathbf{u}\| \|\mathbf{u} - \mathbf{v}\|], \tag{3.9}$$

from which we infer that for any number $R > 0$ there exists a constant $C_R > 0$, also depending on m , such that

$$\|B_m(\mathbf{u}, \mathbf{u}) - B_m(\mathbf{v}, \mathbf{v})\| \leq C_R \|\mathbf{u} - \mathbf{v}\|,$$

for any $\mathbf{u}, \mathbf{v} \in \mathbf{H}_m$ with $\|\mathbf{u}\|, \|\mathbf{v}\| \leq R$. That is, $B_m(\cdot) := B_m(\cdot, \cdot)$ is locally Lipschitz. Thanks to (6.11) one can also use the same idea to show that M_m is locally Lipschitz

with Lipschitz constant depending on m . Now, for any $r \in \{1, \dots, N\}$ there exists a constant $C > 0$ such that for any $\mathbf{n}_1, \mathbf{n}_2 \in \mathbf{L}_m$

$$\begin{aligned} \|\mathbf{n}_1\|^{2r} \|\mathbf{n}_1 - \mathbf{n}_2\|^{2r} &\leq C \|\mathbf{n}_1\|^{2r} \|\mathbf{n}_1 - \mathbf{n}_2\| \\ &+ C \|\mathbf{n}_1 - \mathbf{n}_2\| \|\mathbf{n}_2\| \left(\sum_{k=0}^{2r-1} \|\mathbf{n}_1\|^{2r-1-k} \|\mathbf{n}_2\|^k \right) \end{aligned}$$

from which we easily derive the local Lipschitz property of f_m .

Finally, thanks to (6.9) there exists a constant $C > 0$, which depends on $m \in \mathbb{N}$, such that

$$\|\tilde{B}_m(\mathbf{u}_1, \mathbf{n}_1) - \tilde{B}_m(\mathbf{u}_2, \mathbf{n}_2)\| \leq C [\|\mathbf{u}_1 - \mathbf{u}_2\| \|\mathbf{n}_2\| + \|\mathbf{u}_2\| \|\mathbf{n}_1 - \mathbf{n}_2\|],$$

where we have used the equivalence of all norms on the finite dimensional space $\mathbf{H}_m \times \mathbf{L}_m$ again. Now, it is clear that the mapping Ψ is locally Lipschitz. \square

Let $\mathbf{n}_{0m} = \hat{\pi}_m \mathbf{n}_0$ and $\mathbf{v}_{0m} = \pi_m \mathbf{v}_0$. The Galerkin approximation to (3.1)–(3.3) is

$$d\mathbf{v}_m(t) + [A\mathbf{v}_m(t) + B_m(\mathbf{v}_m(t)) + M_m(\mathbf{n}_m(t))]dt = S_m(\mathbf{v}_m(t))dW_1(t), \tag{3.10}$$

$$\begin{aligned} d\mathbf{n}_m(t) + [A_1\mathbf{n}_m(t) + \tilde{B}_m(\mathbf{v}_m(t), \mathbf{n}_m(t)) + f_m(\mathbf{n}_m(t))]dt \\ = \frac{1}{2}G_m^2(\mathbf{n}_m(t)) + G_m(\mathbf{n}_m(t))dW_2(t). \end{aligned} \tag{3.11}$$

The Eqs. (3.10)–(3.11) with initial condition $\mathbf{v}_m(0) = \mathbf{v}_{0m}$ and $\mathbf{n}_m(0) = \mathbf{n}_{0m}$ form a system of stochastic ordinary differential equations which can be rewritten as

$$d\mathbf{y}_m + \Psi_m(\mathbf{y}_m)dt = \Phi_m(\mathbf{y}_m)dW, \quad \mathbf{y}_m(0) = (\mathbf{v}_{0m}, \mathbf{n}_{0m}) \tag{3.12}$$

where $\mathbf{y}_m := (\mathbf{v}_m, \mathbf{n}_m)$, $W := (W_1, W_2)$. Due to Lemma 3.6 the mappings Ψ_m and Φ_m are locally Lipschitz. Hence, owing to [1,38, Theorem 38, p. 303] it has a unique local maximal solution $(\mathbf{v}_m, \mathbf{n}_m; T_m)$ where T_m is a stopping time.

Remark 3.7 In case we assume that $S(\cdot)$ is only continuous and satisfies (2.19), S_m is only continuous and locally bounded. However, with this assumption, we can still justify the existence, possibly non-unique, of a weak local martingale solution to (3.10)–(3.11) by using results in [26, Chapter IV, Section 2, pp 167–177].

We now derive uniform estimates for the approximating solutions. For this purpose, let $\tau_{R,m}$, $m, R \in \mathbb{N}$, be a stopping time defined by

$$\tau_{R,m} = \inf\{t \in [0, T]; \|\mathbf{n}_m(t)\|_1^2 + \|\mathbf{v}_m(t)\|^2 \geq R^2\} \wedge T. \tag{3.13}$$

Proposition 3.8 *If all the assumptions of Theorem 3.2 are satisfied, then for any $p \geq 2$ there exists a positive constant C_p such that we have for all $R > 0$ and $t \in (0, T]$*

$$\begin{aligned} & \sup_{m \in \mathbb{N}} \left(\mathbb{E} \sup_{s \in [0, t \wedge \tau_{R,m}]} \|\mathbf{n}_m(s)\|^p + p \int_0^{t \wedge \tau_{R,m}} \|\mathbf{n}_m(s)\|^{p-2} \|\nabla \mathbf{n}_m(s)\|^2 ds \right. \\ & \left. + p \int_0^{t \wedge \tau_{R,m}} \|\mathbf{n}_m(s)\|^{p-2} \|\mathbf{n}_m(s)\|_{\mathbf{L}^{2N+2}}^{2N+2} ds \right) \leq \mathbb{E} \mathfrak{G}_0(T, p), \end{aligned} \tag{3.14}$$

where

$$\mathfrak{G}_0(T, p) := \|\mathbf{n}_0\|^p (C_p + C_p e^{C_p T}). \tag{3.15}$$

Proof The proof will be given in Sect. 4. □

We also have the following estimates.

Proposition 3.9 *If all the assumptions of Theorem 3.2 are satisfied, then there exists $\tilde{\ell} > 0$ such that for all $p \in [1, \infty)$, for all $R > 0$ and $t \in (0, T]$*

$$\begin{aligned} & \sup_{m \in \mathbb{N}} \mathbb{E} \left[\sup_{0 \leq s \leq t \wedge \tau_{R,m}} \left(\|\mathbf{v}_m(s)\|^2 + \tilde{\ell} \|\mathbf{n}_m(s)\|^2 + \|\nabla \mathbf{n}_m(s)\|^2 + \int_{\mathcal{O}} F(\mathbf{n}_m(s, x)) dx \right)^p \right. \\ & \left. + \left(\int_0^{t \wedge \tau_{R,m}} \left(\|\nabla \mathbf{v}_m(s)\|^2 + \|\mathbf{A}_1 \mathbf{n}_m(s) + f(\mathbf{n}_m(s))\|^2 \right) ds \right)^p \right] \\ & \leq \mathfrak{G}_1(T, p), \quad t \in [0, T], m \in \mathbb{N}, \end{aligned} \tag{3.16}$$

and

$$\begin{aligned} & \sup_{m \in \mathbb{N}} \mathbb{E} \left[\int_0^{t \wedge \tau_{R,m}} \|\mathbf{A}_1 \mathbf{n}_m(s)\|^2 ds \right]^p \leq \mathfrak{G}_1(T, p \cdot (2N + 1)), \\ & t \in [0, T], m \in \mathbb{N}, \end{aligned} \tag{3.17}$$

where

$$\begin{aligned} \mathfrak{G}_1(T, p) := & \left[\left(\|\mathbf{v}_0\|^2 + \|\mathbf{n}_0\|^2 + \|\nabla \mathbf{n}_0\|^2 + \int_{\mathcal{O}} F(\mathbf{n}_0(x)) dx \right)^p + \kappa T + \kappa \mathfrak{G}_0(T, p) \right] \\ & \times \left[1 + \kappa T (T + 1) e^{\kappa(T+1)T} \right]. \end{aligned} \tag{3.18}$$

Here, $\kappa > 0$ is a constant which depends only on p and $\tilde{\ell}$, and \mathfrak{G}_0 is defined in (3.15).

Proof The proof of (3.16) will be given in Sect. 4. The estimate (3.17) easily follows from (3.16), (3.14) and item (ii) of Remark 2.7 (see also item (iii) of the same remark). □

In the next step we will take the limit $R \rightarrow \infty$ in the above estimates, but before proceeding further, we state and prove the following lemma.

Lemma 3.10 *Let $\tau_{R,m}$, $R, m \in \mathbb{N}$ be the stopping times defined in (3.13). Then we have for any $m \in \mathbb{N}$ \mathbb{P} -a.s.*

$$\lim_{R \rightarrow \infty} \tau_{R,m} = T.$$

Proof Since $(\mathbf{v}_m, \mathbf{n}_m) \cdot (\cdot \wedge \tau_{R,m}) : [0, T] \rightarrow \mathbf{H}_m \times \mathbf{L}_m$ is continuous we have

$$\begin{aligned} R^2 \mathbb{P}(\tau_{R,m} < t) &\leq \mathbb{E} \left[\mathbf{1}_{\tau_{R,m} < t} (\|\mathbf{v}_m(\tau_{R,m})\|^2 + \|\mathbf{n}_m(\tau_{R,m})\|_1^2) \right] \\ &\leq \mathbb{E} \left[\mathbf{1}_{\tau_{R,m} < t} (\|\mathbf{v}_m(\tau_{R,m})\|^2 + \|\mathbf{n}_m(\tau_{R,m})\|_1^2) \right] \\ &\quad + \mathbb{E} \left[\mathbf{1}_{\tau_{R,m} \geq t} (\|\mathbf{v}_m(\tau_{R,m})\|^2 + \|\mathbf{n}_m(\tau_{R,m})\|_1^2) \right] \\ &= \mathbb{E} \left[\|\mathbf{v}_m(\tau_{R,m})\|^2 + \|\mathbf{n}_m(\tau_{R,m})\|_1^2 \right], \end{aligned}$$

for any $m \in \mathbb{N}$ and $t \in [0, T]$. From the last line of the above chain of inequalities and Proposition 3.9 we infer that

$$\mathbb{P}(\tau_{R,m} < t) \leq \frac{1}{R^2} \mathfrak{G}_1(T, 2). \tag{3.19}$$

Hence

$$\lim_{R \rightarrow \infty} \mathbb{P}(\tau_{R,m} < t) = 0 \text{ for all } t \in [0, T] \text{ and } m \in \mathbb{N},$$

which implies that there exists a subsequence $\tau_{R_k,m}$ such that $\tau_{R_k,m} \rightarrow T$ a.s., which along with the fact that $(\tau_{R,m})_{R \in \mathbb{N}}$ is increasing, yields that $\tau_{R,m} \nearrow T$ a.s. for any $m \in \mathbb{N}$. This completes the proof of the lemma. \square

We now state the following corollary.

Corollary 3.11 *If all the assumptions of Theorem 3.2 are satisfied, then we have*

$$\begin{aligned} &\sup_{m \in \mathbb{N}} \left(\mathbb{E} \sup_{s \in [0, T]} \|\mathbf{n}_m(s)\|^p + p \int_0^T \|\mathbf{n}_m(s)\|^{p-2} \|\nabla \mathbf{n}_m(s)\|^2 ds \right. \\ &\quad \left. + p \int_0^T \|\mathbf{n}_m(s)\|^{p-2} \|\mathbf{n}_m(s)\|_{\mathbf{L}^{2N+2}}^{2N+2} ds \right) \leq \mathbb{E} \mathfrak{G}_0(T, p). \end{aligned} \tag{3.20}$$

Furthermore, there exists $\tilde{\ell} > 0$ such that for all $p \in [1, \infty)$

$$\begin{aligned} &\sup_{m \in \mathbb{N}} \mathbb{E} \left[\sup_{0 \leq s \leq T} \left(\|\mathbf{v}_m(s)\|^2 + \tilde{\ell} \|\mathbf{n}_m(s)\|^2 + \|\nabla \mathbf{n}_m(s)\|^2 + \int_{\mathcal{O}} F(\mathbf{n}_m(s, x)) dx \right)^p \right. \\ &\quad \left. + \left(\int_0^T (\|\nabla \mathbf{v}_m(s)\|^2 + \|\mathbf{A}_1 \mathbf{n}_m(s) + f(\mathbf{n}_m(s))\|^2) ds \right)^p \right] \\ &\leq \mathfrak{G}_1(T, p), \quad t \in [0, T], m \in \mathbb{N}, \end{aligned} \tag{3.21}$$

and

$$\sup_{m \in \mathbb{N}} \mathbb{E} \left[\int_0^T \|\mathbf{A}_1 \mathbf{n}_m(s)\|^2 ds \right]^p \leq \mathfrak{G}_1(T, p \cdot (2N + 1)), \quad t \in [0, T], m \in \mathbb{N}. \tag{3.22}$$

The quantities \mathfrak{G}_0 and \mathfrak{G}_1 are defined in (3.15) and (3.18), respectively.

Proof Thanks to Lemma 3.10 the inequalities (3.20), (3.21) and (3.22) can be established by using Fatou’s lemma and passing to the limit (as $R \rightarrow \infty$) in (3.14), (3.16) and (3.17). \square

In the next proposition, we prove two uniform estimates for \mathbf{v}_m and \mathbf{n}_m which are very crucial for our purpose.

Proposition 3.12 *In addition to the assumptions of Theorem 3.2, let $\alpha \in (0, \frac{1}{2})$ and $p \in [2, \infty)$ such that $1 - \frac{d}{4} \geq \alpha - \frac{1}{p}$. Then, there exist positive constants $\bar{\kappa}_5$ and $\bar{\kappa}_6$ such that we have*

$$\sup_{m \in \mathbb{N}} \mathbb{E} \|\mathbf{v}_m\|_{W^{\alpha,p}(0,T;V^*)}^2 \leq \bar{\kappa}_5, \tag{3.23}$$

and

$$\sup_{m \in \mathbb{N}} \mathbb{E} \|\mathbf{n}_m\|_{W^{\alpha,p}(0,T;L^2)}^2 \leq \bar{\kappa}_6. \tag{3.24}$$

Proof We rewrite the equation for \mathbf{v}_m as

$$\begin{aligned} \mathbf{v}_m(t) &= \mathbf{v}_{0m} - \int_0^t A\mathbf{v}_m(s)ds - \int_0^t B_m(\mathbf{v}_m(s), \mathbf{v}_m(s))ds - \int_0^t M_m(\mathbf{n}_m(s))ds \\ &\quad + \int_0^t S_m(\mathbf{v}_m(s))dW_1(s), \\ &= \mathbf{v}_{0m} + \sum_{i=1}^4 I_m^i(t). \end{aligned}$$

Since $A \in \mathcal{L}(V, V^*)$, we infer from (3.21) along with Corollary 3.11 that there exists a certain constant $C > 0$ such that

$$\begin{aligned} \sup_{m \in \mathbb{N}} \mathbb{E} \|I_m^1\|_{W^{1,2}(0,T;V^*)}^2 &= \sup_{m \in \mathbb{N}} \mathbb{E} \left\| \int_0^\cdot A\mathbf{v}_m(s)ds \right\|_{W^{1,2}(0,T;V^*)}^2 \\ &\leq C, \quad m \in \mathbb{N}. \end{aligned} \tag{3.25}$$

Applying [18, Lemma 2.1] and (2.19) in Assumption 2.2 we infer that there exists a constant $c > 0$ such that that for any $\alpha \in (0, \frac{1}{2})$ and $p \in [2, \infty)$

$$\begin{aligned} \sup_{m \in \mathbb{N}} \mathbb{E} \|I_m^4\|_{W^{\alpha,p}(0,T;H)}^p &= \sup_{m \in \mathbb{N}} \mathbb{E} \left\| \int_0^\cdot S_m(\mathbf{v}_m(s))dW_1(s) \right\|_{W^{\alpha,p}(0,T;H)}^p \\ &\leq c \mathbb{E} \int_0^T \|S_m(\mathbf{v}_m(t))\|_{\mathcal{T}_2(K_1;H)}^p dt, \\ &\leq c \ell_3^p \mathbb{E} \int_0^T (1 + \|\mathbf{v}_m(t)\|^p) ds. \end{aligned}$$

Now, invoking (3.21) and Corollary 3.11 we derive that there exists a constant $C > 0$ such that

$$\sup_{m \in \mathbb{N}} \mathbb{E} \|I_m^4\|_{W^{\alpha,p}(0,T;H)}^p \leq C. \tag{3.26}$$

Now, we treat the term $I_m^3(t)$. From (2.9) we infer that there exists a constant $C > 0$ such that for any $m \in \mathbb{N}$

$$\begin{aligned} \|M_m(\mathbf{n}_m)\|_{L^{\frac{4}{d}}(0,T;V^*)}^2 &\leq C \left(\int_0^T \|\nabla \mathbf{n}_m(t)\|^{\frac{2(4-d)}{d}} \|\nabla^2 \mathbf{n}_m(t)\|^2 dt \right)^{\frac{d}{2}} \\ &\leq C \sup_{t \in [0,T]} \|\nabla \mathbf{n}_m(t)\|^{4-d} \left(\int_0^T \|\nabla^2 \mathbf{n}_m(t)\|^2 dt \right)^{\frac{d}{2}}. \end{aligned}$$

Hence, there exists a constant $C > 0$ such that

$$\sup_{m \in \mathbb{N}} \mathbb{E} \|M_m(\mathbf{n}_m)\|_{L^{\frac{4}{d}}(0,T;V^*)}^2 \leq C \left[\mathbb{E} \left(\sup_{0 \leq t \leq T} \|\nabla \mathbf{n}_m(t)\|^{2(4-d)} \right) \mathbb{E} \left(\int_0^T \|\mathbf{n}_m(t)\|_2^2 dt \right)^d \right]^{\frac{1}{2}},$$

from which altogether with (3.21), (3.22) and Corollary 3.11 we infer that there exists a constant $C > 0$ such that

$$\sup_{m \in \mathbb{N}} \mathbb{E} \|I_m^3\|_{W^{1,\frac{4}{d}}(0,T;V^*)}^2 = \sup_{m \in \mathbb{N}} \mathbb{E} \left\| \int_0^t M_m(\mathbf{n}_m(s)) ds \right\|_{W^{1,\frac{4}{d}}(0,T;V^*)}^2 \leq C. \tag{3.27}$$

Using (6.8) and an argument similar to the proof of the estimate for I_m^3 we conclude that there exists a constant $C > 0$ such that

$$\begin{aligned} \sup_{m \in \mathbb{N}} \mathbb{E} \left\| \int_0^\cdot B_m(\mathbf{v}_m(s), \mathbf{v}_m(s)) ds \right\|_{W^{1,\frac{4}{d}}(0,T;V^*)}^2 \\ \leq C \left[\mathbb{E} \left(\sup_{0 \leq t \leq T} \|\mathbf{v}_m(t)\|^{2(4-d)} \right) \mathbb{E} \left(\int_0^T \|\mathbf{v}_m(t)\|_2^2 dt \right)^d \right]^{\frac{1}{2}}, \end{aligned}$$

from which along with (3.21) and Corollary 3.11 we conclude that there exists a constant $C > 0$ such that

$$\sup_{m \in \mathbb{N}} \mathbb{E} \|I_m^2\|_{W^{1,\frac{4}{d}}(0,T;V^*)}^2 = \sup_{m \in \mathbb{N}} \mathbb{E} \left\| \int_0^\cdot B_m(\mathbf{v}_m(s), \mathbf{v}_m(s)) ds \right\|_{W^{1,\frac{4}{d}}(0,T;V^*)}^2 < C. \tag{3.28}$$

By [44, Section 11, Corollary 19] we have the continuous imbedding

$$W^{1,\frac{4}{d}}(0,T;V^*) \subset W^{\alpha,p}(0,T;V^*), \tag{3.29}$$

for $\alpha \in (0, \frac{1}{2})$ and $p \in [2, \infty)$ such that $1 - \frac{d}{4} \geq \alpha - \frac{1}{p}$. Owing to Eqs. (3.25), (3.27), (3.26) and (3.28) and this continuous embedding we infer that (3.23) holds.

The second equations for the Galerkin approximation is written as

$$\begin{aligned} \mathbf{n}_m(t) &= \mathbf{n}_{0m} - \int_0^t A_1 \mathbf{n}_m(s) ds - \int_0^t \hat{\pi}_m[\tilde{B}_m(\mathbf{v}_m(s), \mathbf{n}_m(s))] ds - \int_0^t f_m(\mathbf{n}_m(s)) ds \\ &\quad + \frac{1}{2} \int_0^t G_m^2(\mathbf{n}_m(s)) ds + \int_0^t G_m(\mathbf{n}_m(s)) dW_2(s), \\ &=: \mathbf{n}_{0m} + \sum_{j=1}^5 J_m^j(t). \end{aligned}$$

From (3.22) and Corollary 3.11 we clearly see that

$$\sup_{m \in \mathbb{N}} \mathbb{E} \|J_m^1\|_{W^{1,2}(0,T;L^2)}^2 = \sup_{m \in \mathbb{N}} \mathbb{E} \left\| \int_0^\cdot A_1 \mathbf{n}_m(s) ds \right\|_{W^{1,2}(0,T;L^2)}^2 \leq C. \tag{3.30}$$

From (6.9) we infer that there exists a constant $c > 0$ such that

$$\|\hat{\pi}_m[\tilde{B}_m(\mathbf{v}_m(s), \mathbf{n}_m(s))]\| \leq c (\|\mathbf{v}_m(t)\| \|\nabla \mathbf{n}_m(t)\|)^{\frac{4-d}{4}} \left(\|\nabla \mathbf{v}_m(t)\| \|\nabla^2 \mathbf{n}_m(t)\| \right)^{\frac{d}{4}}.$$

Thus,

$$\begin{aligned} &\|\hat{\pi}_m[\tilde{B}_m(\mathbf{v}_m(s), \mathbf{n}_m(s))]\|_{L^{\frac{d}{4}}(0,T;L^2)}^2 \\ &\leq c \sup_{0 \leq t \leq T} (\|\mathbf{v}_m(t)\| \|\nabla \mathbf{n}_m(t)\|)^{\frac{4-d}{2}} \left[\int_0^T \|\nabla \mathbf{v}_m(t)\|^2 dt \right]^{\frac{d}{4}} \\ &\quad \times \left[\int_0^T (\|\mathbf{n}_m(t)\|^2 + \|\Delta \mathbf{n}_m(t)\|^2) dt \right]^{\frac{d}{4}}. \end{aligned}$$

Taking the mathematical expectation and using Hölder’s inequality lead to

$$\begin{aligned} &\sup_{m \in \mathbb{N}} \mathbb{E} \|\hat{\pi}_m[\tilde{B}_m(\mathbf{v}_m(s), \mathbf{n}_m(s))]\|_{L^{\frac{d}{4}}(0,T;L^2)}^2 \\ &\leq c \sup_{m \in \mathbb{N}} \left[\mathbb{E} \sup_{0 \leq t \leq T} \|\mathbf{v}_m(t)\|^{2(4-d)} \mathbb{E} \sup_{0 \leq t \leq T} \|\nabla \mathbf{n}_m(t)\|^{2(4-d)} \right]^{\frac{1}{4}} \\ &\quad \times \sup_{m \in \mathbb{N}} \left[\mathbb{E} \left(\int_0^T \|\nabla \mathbf{v}_m(t)\|^2 dt \right)^d \mathbb{E} \left(\int_0^T (\|\mathbf{n}_m(t)\|^2 + \|\Delta \mathbf{n}_m(t)\|^2) dt \right)^d \right]^{\frac{1}{4}}, \end{aligned}$$

which along with (3.21), (3.22) and Corollary 3.11 yield

$$\sup_{m \in \mathbb{N}} \mathbb{E} \|J_m^2\|_{W^{1, \frac{d}{4}}(0, T; \mathbf{L}^2)}^2 = \sup_{m \in \mathbb{N}} \mathbb{E} \left\| \int_0^\cdot \hat{\pi}_m[\tilde{B}_m(\mathbf{v}_m(s), \mathbf{n}_m(s))] ds \right\|_{W^{1, \frac{d}{4}}(0, T; \mathbf{L}^2)}^2 \leq C, \tag{3.31}$$

for some constant $C > 0$.

There exists a constant $c > 0$ such that for any $m \in \mathbb{N}$ and $t \in [0, T]$ we have

$$\begin{aligned} \|G_m^2(\mathbf{n}_m(t))\| &\leq \|\mathbf{h}\|_{\mathbf{L}^\infty} \|\mathbf{n}_m(t)\|_{\mathbf{L}^\infty} \|\mathbf{n}_m(t)\|, \\ &\leq c \|\mathbf{h}\|_{\mathbf{L}^\infty} \left(\|\mathbf{n}_m(t)\|^2 + \|\mathbf{n}_m(t)\| \|\nabla \mathbf{n}_m(t)\| + \|\mathbf{n}_m(t)\| \|\Delta \mathbf{n}_m(t)\| \right), \end{aligned}$$

which along with (3.21), (3.22) and Corollary 3.11 yields that there exists a constant $C > 0$ such that

$$\sup_{m \in \mathbb{N}} \mathbb{E} \|J_m^4\|_{W^{1,2}(0, T; \mathbf{L}^2)}^2 = \sup_{m \in \mathbb{N}} \mathbb{E} \left\| \frac{1}{2} \int_0^\cdot G_m^2(\mathbf{n}_m(s)) ds \right\|_{W^{1,2}(0, T; \mathbf{L}^2)}^2 \leq C. \tag{3.32}$$

For the polynomial nonlinearity f we have: for any $N \in I_d$ there exists a constant $C > 0$ such that

$$\begin{aligned} \sup_{m \in \mathbb{N}} \mathbb{E} \|J_m^3\|_{W^{1,2}(0, T; \mathbf{L}^2)}^2 &\leq C \mathbb{E} \left(\int_0^T \|f(\mathbf{n}_m(s))\|^2 ds \right)^2 \\ &\leq C \mathbb{E} \left(\int_0^T \|\mathbf{n}_m(s)\|_{\mathbf{L}^{4N+2}}^{4N+2} ds \right)^2 \leq CT \mathbb{E} \sup_{0 \leq s \leq T} \|\mathbf{n}_m(s)\|_{\mathbf{H}^1}^{8N+2} \\ &\leq C, \end{aligned} \tag{3.33}$$

where we have used the continuous embedding $\mathbf{H}^1 \subset \mathbf{L}^{4N+2}$ and the estimates (3.20) and (3.21).

For any $\mathbf{h} \in \mathbf{L}^\infty(\mathcal{O})$, using the embedding $\mathbf{H}^2 \hookrightarrow \mathbf{L}^\infty$ we have

$$\|\mathbf{h} \times \mathbf{n}_m(t)\|^p \leq \|\mathbf{h}\|_{\mathbf{L}^\infty}^p \|\mathbf{n}_m(t)\|^p, \tag{3.34}$$

from which along with [18, Lemma 2.1], (3.34), (3.21) and Corollary 3.11 we derive that there exists a constant $C > 0$ such that for any $\alpha \in (0, \frac{1}{2})$ and $p \in [2, \infty)$

$$\sup_{m \in \mathbb{N}} \mathbb{E} \|J_m^5\|_{W^{\alpha,p}(0, T; \mathbf{L}^2)}^p = \sup_{m \in \mathbb{N}} \mathbb{E} \left\| \int_0^\cdot G_m(\mathbf{n}_m(s)) dW_2 \right\|_{W^{\alpha,p}(0, T; \mathbf{L}^2)}^p \leq C. \tag{3.35}$$

Combining all these estimates complete the proof of our proposition. □

3.2 Tightness and compactness results

This subsection is devoted to the study of the tightness of the Galerkin solutions and derive several weak convergence results. The estimates from the previous subsection play an important role in this part of the paper.

Let $p \in [2, \infty)$ and $\alpha \in (0, \frac{1}{2})$ be as in Proposition 3.12. Let us consider the spaces

$$\begin{aligned} \mathfrak{X}_1 &= L^2(0, T; V) \cap W^{\alpha,p}(0, T; V^*), \\ \mathfrak{Y}_1 &= L^2(0, T; \mathbf{H}^2) \cap W^{\alpha,p}(0, T; \mathbf{L}^r). \end{aligned}$$

Recall that $V_\beta, \beta \in \mathbb{R}$, is the domain of the of the fractional power operator A^β . Similarly, \mathbf{X}_β is the domain of $(I + A_1)^\beta$. If $\gamma > \beta$, then the embedding $V_\gamma \subset V_\beta$ (resp. $\mathbf{X}_\gamma \subset \mathbf{X}_\beta$) is compact. We set

$$\begin{aligned} \mathfrak{X}_2 &= L^\infty(0, T; H) \cap W^{\alpha,p}(0, T; V^*), \\ \mathfrak{Y}_2 &= L^\infty(0, T; \mathbf{H}^1) \cap W^{\alpha,p}(0, T; \mathbf{L}^2), \end{aligned}$$

and for $\beta \in (0, \frac{1}{2})$

$$\begin{aligned} \mathfrak{S}_1 &= L^2(0, T; H) \cap C([0, T]; V_{-\beta}), \\ \mathfrak{S}_2 &= L^2(0, T; \mathbf{H}^1) \cap C([0, T]; \mathbf{X}_\beta). \end{aligned}$$

We shall prove the following important result.

Theorem 3.13 *Let $p \in [2, \infty)$ and $\alpha \in (0, \frac{1}{2})$ be as in Proposition 3.12 and $\beta \in (0, \frac{1}{2})$ such that $p\beta > 1$. The family of laws $\{\mathcal{L}(\mathbf{v}_m, \mathbf{n}_m) : m \in \mathbb{N}\}$ is tight on the Polish space $\mathfrak{S}_1 \times \mathfrak{S}_2$.*

Proof We firstly prove that $\{\mathcal{L}(\mathbf{v}_m) : m \in \mathbb{N}\}$ is tight on $L^2(0, T; H)$. For this aim, we first observe that for a fixed number $R > 0$ we have

$$\begin{aligned} \mathbb{P}(\|\mathbf{v}_m\|_{\mathfrak{X}_1} > R) &\leq \mathbb{P}\left(\|\mathbf{v}_m\|_{L^2(0,T;V)} > \frac{R}{2}\right) + \mathbb{P}\left(\|\mathbf{v}_m\|_{W^{\alpha,p}(0,T;V^*)} > \frac{R}{2}\right), \\ &\leq \frac{4}{R^2} \mathbb{E}\left(\|\mathbf{v}_m\|_{L^2(0,T;V)}^2 + \|\mathbf{v}_m\|_{W^{\alpha,p}(0,T;V^*)}^2\right), \end{aligned}$$

from which along with (3.21), (3.23), and (3.24) we infer that

$$\sup_{m \in \mathbb{N}} \mathbb{P}(\|\mathbf{v}_m\|_{\mathfrak{X}_1} > R) \leq \frac{4C}{R^2}. \tag{3.36}$$

Since \mathfrak{X}_1 is compactly embedded into $L^2(0, T; H)$, we conclude that the laws of \mathbf{v}_m form a family of probability measures which is tight on $L^2(0, T; H)$. Secondly, the same argument is used to prove that the laws of \mathbf{n}_m are tight on $L^2(0, T; \mathbf{H}^1)$. Next,

we choose $\beta \in (0, \frac{1}{2})$ and $p \in [2, \infty)$ such that $p\beta > 1$ is satisfied. By [43, Corollary 5 of Section 8] the spaces \mathfrak{X}_2 and \mathfrak{Y}_2 are compactly imbedded in $C([0, T]; V_{-\beta})$ and $C([0, T]; \mathbf{X}_\beta)$, respectively. Hence the same argument as above provides us with the tightness of $\{\mathcal{L}(\mathbf{v}_m) : m \in \mathbb{N}\}$ and $\{\mathcal{L}(\mathbf{n}_m) : m \in \mathbb{N}\}$ on $C([0, T]; V_{-\beta})$ and $C([0, T]; \mathbf{X}_\beta)$. Now we can easily conclude the proof of the theorem. \square

Throughout the remaining part of this paper we assume that α , p and β are as in Theorem 3.13. We also use the notation from Remark 2.8.

Proposition 3.14 *Let $\mathfrak{S} = \mathfrak{S}_1 \times \mathfrak{S}_2 \times C([0, T]; \mathbf{K}_2) \times C([0, T]; \mathbb{R})$. There exist a Borel probability measure μ on \mathfrak{S} and a subsequence of $(\mathbf{v}_m, \mathbf{n}_m, W_1, W_2)$ such that their laws weakly converge to μ .*

Proof Thanks to the above lemma the laws of $\{(\mathbf{v}_m, \mathbf{n}_m, W_1, W_2) : m \in \mathbb{N}\}$ form a tight family on \mathfrak{S} . Since \mathfrak{S} is a Polish space, we get the result from the application of Prohorov’s theorem. \square

The following result relates the above convergence in law to almost sure convergence.

Proposition 3.15 *Let $\alpha, \beta \in (0, \frac{1}{2})$ be as in Theorem 3.13. Then, there exist a complete probability space $(\Omega', \mathcal{F}', \mathbb{P}')$ and a sequence of \mathfrak{S} -valued random variables, denoted by $\{(\bar{\mathbf{v}}_m, \bar{\mathbf{n}}_m, \bar{W}_1^m, \bar{W}_2^m) : m \in \mathbb{N}\}$, defined on $(\Omega', \mathcal{F}', \mathbb{P}')$ such that their laws are equal to the laws of $\{(\mathbf{v}_m, \mathbf{n}_m, W_1, W_2) : m \in \mathbb{N}\}$ on \mathfrak{S} . Also, there exists an \mathfrak{S} -random variable $(\mathbf{v}, \mathbf{n}, W_1, W_2)$ defined on $(\Omega', \mathcal{F}', \mathbb{P}')$ such that*

$$\mathcal{L}(\mathbf{v}, \mathbf{n}, \bar{W}_1, \bar{W}_2) = \mu \text{ on } \mathfrak{S}, \tag{3.37}$$

$$\bar{\mathbf{v}}_m \rightarrow \mathbf{v} \text{ for } m \rightarrow \infty \text{ in } L^2(0, T; \mathbf{H}) \text{ } \mathbb{P}'\text{-a.s.}, \tag{3.38}$$

$$\bar{\mathbf{v}}_m \rightarrow \mathbf{v} \text{ for } m \rightarrow \infty \text{ in } C([0, T]; V_{-\beta}) \text{ } \mathbb{P}'\text{-a.s.}, \tag{3.39}$$

$$\bar{\mathbf{n}}_m \rightarrow \mathbf{n} \text{ for } m \rightarrow \infty \text{ in } L^2(0, T; \mathbf{H}^1) \text{ } \mathbb{P}'\text{-a.s.}, \tag{3.40}$$

$$\bar{\mathbf{n}}_m \rightarrow \mathbf{n} \text{ for } m \rightarrow \infty \text{ in } C([0, T]; \mathbf{X}_\beta) \text{ } \mathbb{P}'\text{-a.s.}, \tag{3.41}$$

$$\bar{W}_1^m \rightarrow \bar{W}_1 \text{ for } m \rightarrow \infty \text{ in } C([0, T]; \mathbf{K}_2) \text{ } \mathbb{P}'\text{-a.s.}, \tag{3.42}$$

$$\bar{W}_2^m \rightarrow \bar{W}_2 \text{ for } m \rightarrow \infty \text{ in } C([0, T]; \mathbb{R}) \text{ } \mathbb{P}'\text{-a.s.} \tag{3.43}$$

Proof Proposition 3.15 is a consequence of Proposition 3.14 and Skorokhod’s Theorem. \square

Let $\mathfrak{X}_3 = L^\infty(0, T; \mathbf{H}) \cap L^2(0, T; \mathbf{V})$ and $\mathfrak{Y}_3 = L^\infty(0, T; \mathbf{H}^1) \cap L^2(0, T; \mathbf{H}^2)$.

Proposition 3.16 *If all the assumptions of Theorem 3.2 are verified, then for any $p \geq 2$ and $m \in \mathbb{N}$ the pair of processes $(\bar{\mathbf{v}}_m, \bar{\mathbf{n}}_m)$ satisfies the following estimates on the new probability space $(\Omega', \mathcal{F}', \mathbb{P}')$:*

$$\sup_{m \in \mathbb{N}} \left(\mathbb{E}' \left[\sup_{t \in [0, T]} \|\bar{\mathbf{n}}_m(t)\|^p + p \int_0^T \|\bar{\mathbf{n}}_m(s)\|^{p-2} \|\nabla \bar{\mathbf{n}}_m(s)\|^2 ds + p \int_0^t \|\bar{\mathbf{n}}_m(s)\|^{p-2} \|\bar{\mathbf{n}}_m(s)\|_{\mathbf{L}^{2N+2}}^{2N+2} ds \right] \right) \leq \mathfrak{G}_0(T, p), \tag{3.44}$$

$$\mathbb{E}' \left[\sup_{0 \leq s \leq T} \left(\|\bar{\mathbf{v}}_m(s)\|^2 + \tilde{\ell} \|\bar{\mathbf{n}}_m(s)\|^2 + \|\nabla \bar{\mathbf{n}}_m(s)\|^2 + \int_{\mathcal{O}} F(\bar{\mathbf{n}}_m(s, x)) dx \right)^p + \int_0^T \left(\|\nabla \bar{\mathbf{v}}_m(s)\|^2 + \|A_1 \bar{\mathbf{n}}_m(s) + f(\bar{\mathbf{n}}_m(s))\|^2 \right)^p \right] \leq \mathfrak{G}_1(T, p), \tag{3.45}$$

$$\mathbb{E}' \left[\int_0^T \|A_1 \bar{\mathbf{n}}_m(s)\|^2 ds \right]^p \leq \mathfrak{G}_1(T, p \cdot (2N + 1)), \tag{3.46}$$

where $\mathfrak{G}_0(T, p)$, $\tilde{\ell}$ and $\mathfrak{G}_1(T, p)$ are defined in Propositions 3.8 and 3.9, respectively. Furthermore, there exists a constant $C > 0$ such that

$$\sup_{m \in \mathbb{N}} \mathbb{E}' \left[\int_0^T \|B_m(\bar{\mathbf{v}}_m(t), \bar{\mathbf{v}}_m(t))\|_{\mathbf{V}^*}^{\frac{4}{r}} dt \right]^{\frac{d}{2}} \leq C, \tag{3.47}$$

$$\sup_{m \in \mathbb{N}} \mathbb{E}' \left[\int_0^T \|M_m(\bar{\mathbf{n}}_m(t))\|_{\mathbf{V}^*}^{\frac{4}{r}} dt \right]^{\frac{d}{2}} \leq C, \tag{3.48}$$

$$\sup_{m \in \mathbb{N}} \mathbb{E}' \left[\int_0^T \|\tilde{B}_m(\bar{\mathbf{v}}_m(t), \bar{\mathbf{n}}_m(t))\|_{\mathbf{L}^2}^{\frac{4}{r}} dt \right]^{\frac{d}{2}} \leq C, \tag{3.49}$$

$$\sup_{m \in \mathbb{N}} \mathbb{E}' \int_0^T \|f_m(\bar{\mathbf{n}}_m(t))\|_{\mathbf{L}^r}^r dt \leq C, \tag{3.50}$$

where $r = \frac{2N+2}{2N+1}$.

Proof Consider the function $\Phi(\mathbf{u}, \mathbf{e})$ on $\mathfrak{X}_3 \times \mathfrak{Y}_3 \subset \mathfrak{S}_1 \times \mathfrak{S}_2$ defined by

$$\Phi(\mathbf{u}, \mathbf{e}) = \sup_{0 \leq s \leq T} \left[\|\mathbf{u}(s)\|^{2p} + \|\nabla \mathbf{e}(s)\|^{2p} \right] + \tilde{\kappa}_0 \left[\int_0^T \left(\|\nabla \mathbf{u}(s)\|^2 + \|\Delta \mathbf{e}(s)\|^2 \right) ds \right]^p$$

Φ is on $\mathfrak{S}_1 \times \mathfrak{S}_2$ a continuous function, thus Borel measurable. Thanks to (3.37) for any $m \in \mathbb{N}$ the processes $(\mathbf{v}_m, \mathbf{n}_m)$ and $(\bar{\mathbf{v}}_m, \bar{\mathbf{n}}_m)$ are identical in law. Therefore, we derive that

$$\mathbb{E} \Phi(\mathbf{v}_m, \mathbf{n}_m) = \mathbb{E}' \Phi(\bar{\mathbf{v}}_m, \bar{\mathbf{n}}_m), \quad m \in \mathbb{N},$$

which altogether with the estimates (3.21), (3.22) and Corollary 3.11 yield (3.45). The estimates (3.47), (3.48) and (3.49) can be shown using similar idea to the proof of (3.28), (3.27), (3.31). The estimate (3.50) easily follows from the continuous embedding $\mathbf{L}^2 \subset \mathbf{L}^r$, $r = \frac{2n+2}{2N+1} \in (1, 2)$, and (3.33). \square

We prove several convergence results which are for the proof of our existence result.

Proposition 3.17 *Let $\beta \in (0, \frac{1}{2})$. We can extract a subsequence $\{(\bar{v}_{m_k}, \bar{n}_{m_k}) : k \in \mathbb{N}\}$ from $\{(\bar{v}_m, \bar{n}_m) : m \in \mathbb{N}\}$ such that*

$$\bar{v}_{m_k} \rightarrow \mathbf{v} \text{ strongly in } L^2(\Omega' \times [0, T]; \mathbf{H}), \tag{3.51}$$

$$\bar{v}_{m_k} \rightarrow \mathbf{v} \text{ strongly in } L^4(\Omega'; C([0, T]; \mathbf{V}_{-\beta})), \tag{3.52}$$

$$\bar{n}_{m_k} \rightarrow \mathbf{n} \text{ strongly in } L^2(\Omega' \times [0, T]; \mathbf{H}^1), \tag{3.53}$$

$$\bar{n}_{m_k} \rightarrow \mathbf{n} \text{ weakly in } L^2(\Omega' \times [0, T]; \mathbf{H}^2), \tag{3.54}$$

$$\bar{n}_{m_k} \rightarrow \mathbf{n} \text{ strongly in } L^4(\Omega'; C([0, T]; \mathbf{X}_\beta)) \tag{3.55}$$

$$\bar{n}_{m_k} \rightarrow \mathbf{n} \text{ strongly in } \mathfrak{S}_2 \text{ } \mathbb{P}'\text{-a.s.}, \tag{3.56}$$

$$\bar{n}_{m_k} \rightarrow \mathbf{n} \text{ for almost everywhere } (x, t) \text{ and } \mathbb{P}'\text{-a.s.} \tag{3.57}$$

Proof From (3.45) and Banach–Alaoglu’s theorem we infer that there exists a subsequence \bar{v}_{m_k} of \bar{v}_m satisfying

$$\bar{v}_{m_k} \rightarrow \mathbf{v} \text{ weakly in } L^{2p}(\Omega'; L^2(0, T; \mathbf{H})), \tag{3.58}$$

for any $p \in [2, \infty)$. Now let us consider the positive nondecreasing function $\varphi(x) = x^{2p}$, $p \in [2, \infty)$, defined on \mathbb{R}_+ . The function φ obviously satisfies

$$\lim_{x \rightarrow \infty} \frac{\varphi(x)}{x} = \infty. \tag{3.59}$$

Thanks to the estimate $\mathbb{E}' \sup_{t \in [0, T]} \|\bar{v}_{m_k}\|^{2p} \leq C$ (see (3.45)), we have

$$\sup_{k \geq 1} \mathbb{E}'(\varphi(\|\bar{v}_{m_k}\|_{L^2(0, T; \mathbf{H})})) < \infty, \tag{3.60}$$

which along with the uniform integrability criteria in [27, Chapter 3, Exercice 6] implies that the family $\{\|\bar{v}_{m_k}\|_{L^2(0, T; \mathbf{H})} : m \in \mathbb{N}\}$ is uniform integrable with respect to the probability measure. Thus, we can deduce from Vitali’s Convergence Theorem (see, for instance, [27, Chapter 3, Proposition 3.2]) and (3.38) that

$$\mathbb{E}' \|\bar{v}_{m_k}\|_{L^2(0, T; \mathbf{H})}^2 \rightarrow \mathbb{E}' \|\mathbf{v}\|_{L^2(0, T; \mathbf{H})}^2.$$

From this and (3.58) we derive that

$$\bar{v}_{m_k} \rightarrow \mathbf{v} \text{ strongly in } L^2(\Omega' \times [0, T]; \mathbf{H}). \tag{3.61}$$

Thanks to (3.40)–(3.43) in Proposition 3.15 and (3.45) we can use the same argument as above to show the convergence (3.52)–(3.55). By the tightness of the laws of $\{\bar{n}_m : m \in \mathbb{N}\}$ on \mathfrak{S}_2 we can extract a subsequence still denoted by $\{\bar{n}_{m_k} : k \in \mathbb{N}\}$ such that (3.56) and (3.57) hold. \square

The stochastic processes \mathbf{v} and \mathbf{n} satisfy the following properties.

Proposition 3.18 *We have*

$$\mathbb{E}' \sup_{t \in [0, T]} \|\mathbf{v}(t)\|^p < \infty, \tag{3.62}$$

$$\mathbb{E}' \sup_{t \in [0, T]} \|\mathbf{n}(t)\|_{\mathbf{H}^1}^p < \infty, \tag{3.63}$$

for any $p \in [2, \infty)$.

Proof One can argue exactly as in [6, Proof of (4.12), page 20], so we omit the details. □

Proposition 3.19 *Let $d \in \{2, 3\}$ and $T \geq 0$. There exist four processes $\mathfrak{B}_1, \mathfrak{M} \in L^2(\Omega'; L^{\frac{4}{d}}(0, T; \mathbf{V}^*))$, $\mathfrak{B}_2 \in L^2(\Omega'; L^{\frac{4}{d}}(0, T; \mathbf{L}^2))$ and $\mathfrak{f} \in \mathbf{L}^{\frac{2N+2}{2N+1}}(\Omega' \times [0, T] \times \mathcal{O})$ such that*

$$B_{m_k}(\bar{\mathbf{v}}_{m_k}, \bar{\mathbf{v}}_{m_k}) \rightarrow \mathfrak{B}_1, \text{ weakly in } L^2(\Omega'; L^{\frac{4}{d}}(0, T; \mathbf{V}^*)), \tag{3.64}$$

$$M_{m_k}(\bar{\mathbf{n}}_{m_k}) \rightarrow \mathfrak{M}, \text{ weakly in } L^2(\Omega'; L^{\frac{4}{d}}(0, T; \mathbf{V}^*)), \tag{3.65}$$

$$\tilde{B}_{m_k}(\bar{\mathbf{v}}_{m_k}, \bar{\mathbf{n}}_{m_k}) \rightarrow \mathfrak{B}_2, \text{ weakly in } L^2(\Omega'; L^{\frac{4}{d}}(0, T; \mathbf{L}^2)), \tag{3.66}$$

$$f_{m_k}(\bar{\mathbf{n}}_{m_k}) \rightarrow \mathfrak{f}, \text{ weakly in } L^{\frac{2N+2}{2N+1}}(\Omega' \times [0, T] \times \mathcal{O}; \mathbb{R}^3). \tag{3.67}$$

Proof Note that Proposition 3.16 remains valid with $\bar{\mathbf{n}}_m$ replaced by $\bar{\mathbf{n}}_{m_k}$. Thus, Proposition 3.19 follows from Eqs. (3.47)–(3.50) and application of Banach–Alaoglu’s theorem. □

3.3 Passage to the limit and the end of proof of Theorem 3.2

In this subsection we prove several convergences which will enable us to conclude that the limiting objects that we found in Proposition 3.15 are in fact a weak martingale solution to our problem.

Proposition 3.17 will be used to prove the following result.

Proposition 3.20 *For any process $\Psi \in L^2(\Omega'; L^{\frac{4}{4-d}}(0, T; \mathbf{V}))$, the following identity holds*

$$\begin{aligned} \lim_{k \rightarrow \infty} \mathbb{E}' \int_0^T \langle B_{m_k}(\bar{\mathbf{v}}_{m_k}(t), \bar{\mathbf{v}}_{m_k}(t)), \Psi(t) \rangle_{\mathbf{V}^*, \mathbf{V}} dt &= \mathbb{E}' \int_0^T \langle \mathfrak{B}_1(t), \Psi(t) \rangle_{\mathbf{V}^*, \mathbf{V}} dt, \\ &= \mathbb{E}' \int_0^T \langle B(\mathbf{v}(t), \mathbf{v}(t)), \Psi(t) \rangle_{\mathbf{V}^*, \mathbf{V}} dt. \end{aligned} \tag{3.68}$$

Proof Let

$$\mathbb{D} = \left\{ \Phi = \sum_{i=1}^k \mathbb{1}_{D_i} \mathbb{1}_{J_i} \psi_i : D_i \subset \Omega, J_i \subset [0, T] \text{ is measurable, } \psi_i \in \mathcal{V} \right\}.$$

Owing to [49, Proposition 21.23] and the density of \mathbb{D} in $L^2(\Omega, \mathbb{P}; L^{\frac{4}{4-d}}(0, T; \mathbf{V}))$ (see, for instance, [39, Theorem 3.2.6]), in order to show that the identity (3.68) holds it is enough to check that

$$\lim_{k \rightarrow \infty} \mathbb{E}' \int_0^T \mathbb{1}_J(t) \mathbb{1}_D \langle B_{m_k}(\bar{\mathbf{v}}_{m_k}(t), \bar{\mathbf{v}}_{m_k}(t)) - B(\mathbf{v}(t), \mathbf{v}(t)), \psi \rangle_{\mathbf{V}^*, \mathbf{V}} dt = 0,$$

for any $\Phi = \mathbb{1}_D \mathbb{1}_J \psi \in \mathbb{D}$. For this purpose we first note that

$$\begin{aligned} \langle B_{m_k}(\bar{\mathbf{v}}_{m_k}, \bar{\mathbf{v}}_{m_k}(t)) - B(\mathbf{v}, \mathbf{v}), \psi \rangle_{\mathbf{V}^*, \mathbf{V}} &= \langle \tilde{B}_{m_k}(\bar{\mathbf{v}}_{m_k} - \mathbf{v}, \bar{\mathbf{v}}_{m_k}), \psi \rangle_{\mathbf{V}^*, \mathbf{V}} \\ &\quad + \langle \tilde{B}_{m_k}(\mathbf{v}, \bar{\mathbf{v}}_{m_k} - \mathbf{v}), \psi \rangle_{\mathbf{V}^*, \mathbf{V}}, \\ &= I_1 + I_2. \end{aligned}$$

The mapping $\langle B_{m_k}(\mathbf{u}, \cdot), \psi \rangle_{\mathbf{V}^*, \mathbf{V}}$ from $L^2(\Omega'; L^2(0, T; \mathbf{V}))$ into $L^2(\Omega'; L^{\frac{4}{d}}(0, T; \mathbb{R}))$ is linear and continuous. Therefore if $\bar{\mathbf{v}}_{m_k}$ converges to \mathbf{v} weakly in $L^2(\Omega'; L^2(0, T; \mathbf{V}))$ then I_2 converges to 0 weakly in $L^2(\Omega'; L^{\frac{4}{d}}(0, T; \mathbb{R}))$. To deal with I_1 we recall that

$$\begin{aligned} &\left| \mathbb{E}' \int_0^T \mathbb{1}_J \mathbb{1}_D(\omega', t) \langle B_{m_k}(\bar{\mathbf{v}}_{m_k}(t) - \mathbf{v}(t), \bar{\mathbf{v}}_{m_k}(t)), \psi \rangle_{\mathbf{V}^*, \mathbf{V}} dt \right| \\ &\leq \|\psi\|_{\mathbb{L}^\infty} \left[\mathbb{E}' \int_0^T \|\nabla \bar{\mathbf{v}}_{m_k}(t)\|^2 dt \right]^{\frac{1}{2}} \\ &\quad \times \left[\mathbb{E}' \int_0^T \|\bar{\mathbf{v}}_{m_k}(t) - \mathbf{v}(t)\|^2 dt \right]^{\frac{1}{2}}. \end{aligned}$$

Thanks to (3.45) and the convergence (3.51) we see that the right-hand side of above inequality converges to 0 as m_k goes to infinity. Hence I_1 converges to 0 weakly in $L^2(\Omega'; L^{\frac{4}{d}}(0, T; \mathbb{R}))$. This ends the proof of our proposition. \square

In the next proposition we will prove that \mathfrak{M} coincides with $M(\mathbf{n})$.

Proposition 3.21 *Assume that $d < 4$. For any process $\Psi \in L^2(\Omega'; L^{\frac{4}{4-d}}(0, T; \mathbf{V}))$, the following identity holds*

$$\mathbb{E}' \int_0^T \langle \mathfrak{M}(t), \Psi(t) \rangle_{\mathbf{V}^*, \mathbf{V}} dt = \mathbb{E}' \int_0^T \langle M(\mathbf{n}(t)), \Psi(t) \rangle_{\mathbf{V}^*, \mathbf{V}} dt. \tag{3.69}$$

Proof Since π_m strongly converges to the identity operator Id in $L^2(\Omega'; L^{\frac{d}{4}}(0, T; \mathbf{V}^*))$, it is enough to show that (3.69) is true for $M(\bar{\mathbf{n}}_{m_k}(t))$ in place of $M(\mathbf{n}(t))$. By the relation (2.5) we have

$$\begin{aligned}
 & \langle M(\bar{\mathbf{n}}_{m_k}(t)) - M(\mathbf{n}(t)), \psi \rangle_{\mathcal{V}^*, \mathcal{V}} \\
 &= \sum_{i,j,k} \int_{\mathcal{O}} \partial_{x_j} \psi^i \partial_{x_i} \bar{\mathbf{n}}_{m_k}^{(k)}(t) \left(\partial_{x_j} \bar{\mathbf{n}}_{m_k}^{(k)}(t) - \partial_{x_i} \mathbf{n}^{(k)}(t) \right) dx \\
 &+ \sum_{i,j,k} \int_{\mathcal{O}} \partial_{x_j} \psi^i \partial_{x_j} \mathbf{n}^{(k)}(t) \left(\partial_{x_i} \bar{\mathbf{n}}_{m_k}^{(k)}(t) - \partial_{x_i} \mathbf{n}^{(k)}(t) \right) dx,
 \end{aligned} \tag{3.70}$$

for any $\psi \in \mathcal{V}$. From this inequality we infer that

$$\begin{aligned}
 & \left| \mathbb{E}' \int_0^T \mathbf{1}_J(\omega', t) \langle M(\bar{\mathbf{n}}_{m_k}(t)) - M(\mathbf{n}(t)), \psi \rangle_{\mathcal{V}^*, \mathcal{V}} dt \right| \\
 & \leq C \|\nabla \psi\| \left[\mathbb{E}' \int_0^T \|\nabla(\bar{\mathbf{n}}_{m_k}(t) - \mathbf{n}(t))\|^2 dt \right]^{\frac{1}{2}} \\
 & \quad \times \left(\left[\mathbb{E}' \sup_{0 \leq t \leq T} \|\nabla \bar{\mathbf{n}}_{m_k}(t)\|^2 \right]^{\frac{1}{2}} + \left[\mathbb{E}' \sup_{0 \leq t \leq T} \|\nabla \mathbf{n}(t)\|^2 \right]^{\frac{1}{2}} \right).
 \end{aligned} \tag{3.71}$$

Owing to the estimate (3.45) and the convergence (3.53) we infer that the left hand side of the last inequality converges to 0 as m_k goes to infinity. Now, arguing as in the proof of (3.68) we easily conclude the proof of the proposition. \square

Proposition 3.22 *Let $d \in \{2, 3\}$. Then,*

$$\mathfrak{B}_2 = \tilde{B}(\mathbf{v}, \mathbf{n}) \text{ in } L^2(\Omega'; L^{\frac{d}{4}}(0, T; \mathbf{L}^2)).$$

Proof The statement in the proposition is equivalent to say that $\{\tilde{B}_{m_k}(\bar{\mathbf{v}}_{m_k}(t), \bar{\mathbf{n}}_{m_k}(t)) : k \in \mathbb{N}\}$ converges to $\tilde{B}(\mathbf{v}(t), \mathbf{n}(t))$ weakly in $L^2(\Omega'; L^{\frac{d}{4}}(0, T; \mathbf{L}^2))$ as $k \rightarrow \infty$. To prove this we argue as above, but we consider the set

$$\mathbb{D} = \{\Phi = \mathbf{1}_J \mathbf{1}_D \mathbf{1}_K : J \subset \Omega', D \subset [0, T], K \subset \mathcal{O} \text{ is measurable}\}.$$

For any $\Phi \in \mathbb{D}$ we have

$$\begin{aligned}
 & \left| \mathbb{E}' \int_{[0,T] \times \mathcal{O}} \tilde{B}_{m_k}(\bar{\mathbf{v}}_{m_k}(t), \bar{\mathbf{n}}_{m_k}(t)) - \tilde{B}(\mathbf{v}(t), \mathbf{n}(t)) \Phi(\omega', t, x) dx dt \right| \\
 & \leq \left[\mathbb{E}' \int_0^T \|\bar{\mathbf{v}}_{m_k}(t) - \mathbf{v}(t)\|^2 dt \right]^{\frac{1}{2}} \left[\mathbb{E}' \int_0^T \|\nabla \bar{\mathbf{n}}_{m_k}(t)\|^2 dt \right]^{\frac{1}{2}} \\
 & \quad + \left[\mathbb{E}' \int_0^T \|\mathbf{v}(t)\|^2 dt \right]^{\frac{1}{2}} \left[\mathbb{E}' \int_0^T \|\nabla(\bar{\mathbf{v}}_{m_k}(t) - \mathbf{v}(t))\|^2 dt \right]^{\frac{1}{2}}
 \end{aligned} \tag{3.72}$$

Thanks to (3.45) and (3.53) we deduce that the left hand side of the last inequality converges to 0 as m_k goes to infinity. This proves our claim. \square

The following convergence is also important.

Proposition 3.23 *Let r be as in Proposition 3.12, i.e., $r = \frac{2N+2}{2N+1} \in (1, 2)$, and $\beta \in (0, 1)$. Then,*

$$f = f(\mathbf{n}) \text{ in } L^r(\Omega' \times [0, T] \times \mathcal{O}; \mathbb{R}^3). \tag{3.73}$$

Proof To prove (3.73), first remark that by definition the embedding $\mathbf{X}_\beta \subset \mathbf{L}^r$ is continuous for any $\beta \in (0, \frac{1}{2})$. The convergence (3.57) implies that for any $k = 0, \dots, N$

$$|\bar{\mathbf{n}}_{m_k}|^{2k} \bar{\mathbf{n}}_{m_k} \rightarrow |\mathbf{n}|^{2k} \mathbf{n} \text{ for almost everywhere } (x, t) \text{ and } \mathbb{P}'\text{-a.s.} \tag{3.74}$$

Since $f(\bar{\mathbf{n}}_{m_k})$ is bounded in $L^r(\Omega' \times [0, T] \times \mathcal{O}; \mathbb{R}^3)$ we can infer from [34, Lemma 1.3, pp. 12] and the convergence (3.74) that

$$f(\bar{\mathbf{n}}_{m_k}) \rightarrow f(\mathbf{n}) \text{ weakly in } L^r(\Omega' \times [0, T] \times \mathcal{O}; \mathbb{R}^3),$$

which with the uniqueness of weak limit implies the sought result. □

To simplify notation let us define the processes $\mathcal{M}_{m_k}^1(t)$ and $\mathcal{M}_{m_k}^2(t)$, $t \in [0, T]$ by

$$\begin{aligned} \mathcal{M}_{m_k}^1(t) &= \bar{\mathbf{v}}_{m_k}(t) - \bar{\mathbf{v}}_{m_k}(0) \\ &\quad + \int_0^t \left(A\bar{\mathbf{v}}_{m_k}(s) + \tilde{B}_{m_k}(\bar{\mathbf{v}}_{m_k}(s), \bar{\mathbf{v}}_{m_k}(s)) - M_{m_k}(\bar{\mathbf{n}}_{m_k}(s)) \right) ds, \end{aligned}$$

and

$$\begin{aligned} \mathcal{M}_{m_k}^2(t) &= \bar{\mathbf{n}}_{m_k}(t) - \bar{\mathbf{n}}_{m_k}(0) + \int_0^t \left(A_1\bar{\mathbf{n}}_{m_k}(s) + \tilde{B}_{m_k}(\bar{\mathbf{v}}_{m_k}(s), \bar{\mathbf{n}}_{m_k}(s)) - f_{m_k}(\bar{\mathbf{n}}_{m_k}(s)) \right) ds \\ &\quad - \int_0^t G_{m_k}^2(\bar{\mathbf{n}}_{m_k}(s)) ds. \end{aligned}$$

Proposition 3.24 *Let $\mathcal{M}^1(t)$ and $\mathcal{M}^2(t)$, $t \in [0, T]$, be defined by*

$$\mathcal{M}^1(t) = \mathbf{v}(t) - \mathbf{v}_0 + \int_0^t \left(A\mathbf{v}(s) + B(\mathbf{v}(s), \mathbf{v}(s)) - M(\mathbf{n}(s)) \right) ds, \tag{3.75}$$

$$\mathcal{M}^2(t) = \mathbf{n}(t) - \mathbf{n}_0 + \int_0^t \left(A_1\mathbf{n}(s) + \tilde{B}(\mathbf{v}(s), \mathbf{n}(s)) - f(\mathbf{n}(s)) \right) - \int_0^t G^2(\mathbf{n}(s)) ds, \tag{3.76}$$

for any $t \in (0, T]$. Then, for any $t \in (0, T]$

$$\begin{aligned} \mathcal{M}_{m_k}^1(t) &\text{ converges weakly in } L^2(\Omega'; \mathbf{V}^*) \text{ to } \mathcal{M}^1(t), \\ \mathcal{M}_{m_k}^2(t) &\text{ converges weakly in } L^2(\Omega'; \mathbf{L}^2) \text{ to } \mathcal{M}^2(t), \end{aligned}$$

as $k \rightarrow \infty$.

Proof Let $t \in (0, T]$, we first prove that $\mathcal{M}_{m_k}^1(t) \rightarrow \mathcal{M}^1(t)$ weakly in $L^2(\Omega'; \mathbf{V}^*)$ as k goes to infinity. To this end we take an arbitrary $\xi \in L^2(\Omega'; \mathbf{V})$. We have

$$\begin{aligned} & \mathbb{E}' \left[\langle \mathcal{M}_{m_k}^1(t), \xi \rangle_{\mathbf{V}^*, \mathbf{V}} \right] \\ &= \mathbb{E}' \left[\langle \bar{\mathbf{v}}_{m_k}(t) - \bar{\mathbf{v}}_{m_k}(0), \xi \rangle - \int_0^t \langle \nabla \bar{\mathbf{v}}_{m_k}(s), \nabla \xi \rangle ds - \int_0^t \langle M_{m_k}(\bar{\mathbf{n}}_{m_k}(s)), \xi \rangle_{\mathbf{V}^*, \mathbf{V}} ds \right] \\ &+ \mathbb{E}' \left[\int_0^t \langle B_{m_k}(\bar{\mathbf{v}}_{m_k}(s), \bar{\mathbf{v}}_{m_k}(s)), \xi \rangle_{\mathbf{V}^*, \mathbf{V}} ds \right]. \end{aligned}$$

Thanks to the pointwise convergence in $C([0, T]; \mathbf{V}_{-\beta})$, thus in $C([0, T]; \mathbf{V}^*)$, and the convergences (3.64), (3.68), (3.65) and (3.69) we obtain

$$\begin{aligned} & \lim_{m \rightarrow \infty} \mathbb{E}' \left[\langle \mathcal{M}_{m_k}^1(t), \xi \rangle_{\mathbf{V}^*, \mathbf{V}} \right] \\ &= \mathbb{E}' \left[\langle \mathbf{v}(t) - \mathbf{v}_0, \xi \rangle - \int_0^t \langle \nabla \mathbf{v}(s), \nabla \xi \rangle ds - \int_0^t \langle M(\mathbf{n}(s)), \xi \rangle_{\mathbf{V}^*, \mathbf{V}} ds \right] \\ &+ \mathbb{E}' \left[\int_0^t \langle B(\mathbf{v}(s), \mathbf{v}(s)), \xi \rangle_{\mathbf{V}^*, \mathbf{V}} ds \right], \end{aligned}$$

which proves the sought convergence.

Second, we prove that for any $t \in (0, T]$ $\mathcal{M}_{m_k}^2(t) \rightarrow \mathcal{M}^2(t)$ weakly in $L^2(\Omega'; \mathbf{L}^2)$ as k tends to infinity. For this purpose, observe that $G_{m_k}^2(\cdot)$ is a linear mapping from $L^2(\Omega'; C([0, T]; \mathbf{L}^2))$ into itself and it satisfies

$$\mathbb{E}' \|G_{m_k}^2(\mathbf{n})\|_{C([0, T]; \mathbf{L}^2)}^p \leq c \|\mathbf{h}\|_{\mathbf{L}^\infty}^2 \mathbb{E}' \|\mathbf{n}\|_{C([0, T]; \mathbf{L}^2)}^p, \tag{3.77}$$

for any $p \in [2, \infty)$. So it is not difficult to show that

$$G_{m_k}(\bar{\mathbf{n}}_{m_k}) \rightarrow G(\mathbf{n}) \text{ strongly in } L^2(\Omega'; C([0, T]; \mathbf{L}^2)). \tag{3.78}$$

Thanks to this observation, the convergences (3.55), (3.73), (3.66) and Proposition 3.22 we can use the same argument as above to show that

$$\lim_{m \rightarrow \infty} \langle \mathcal{M}_{m_k}^2(t), \xi \rangle = \langle \mathcal{M}^2(t), \xi \rangle, \tag{3.79}$$

for any $t \in (0, T]$ and $\xi \in L^2(\Omega'; \mathbf{L}^2)$. This completes the proof of Proposition 3.24. \square

Let \mathcal{N} be the set of null sets of \mathcal{F}' and for any $t \geq 0$ and $k \in \mathbb{N}$, let

$$\begin{aligned} \hat{\mathcal{F}}_t^{m_k} &:= \sigma \left(\sigma \left((\bar{\mathbf{v}}_{m_k}(s), \bar{\mathbf{n}}_{m_k}(s), \bar{W}_1^{m_k}(s), \bar{W}_2^{m_k}(s)); s \leq t \right) \cup \mathcal{N} \right), \\ \mathcal{F}'_t &:= \sigma \left(\sigma \left((\mathbf{v}(s), \mathbf{n}(s), \bar{W}_1(s), \bar{W}_2(s)); s \leq t \right) \cup \mathcal{N} \right). \end{aligned} \tag{3.80}$$

Let us also define the stochastic processes $\mathfrak{M}_{m_k}^1$ and $\mathfrak{M}_{m_k}^2$ by

$$\begin{aligned} \mathfrak{M}_{m_k}^1(t) &= \int_0^t S_{m_k}(\bar{\mathbf{v}}_{m_k}(s)) d\bar{W}_1^{m_k}(s) \\ \mathfrak{M}_{m_k}^2(t) &= \int_0^t G_{m_k}(\bar{\mathbf{n}}_{m_k}(s)) d\bar{W}_2^{m_k}(s), \end{aligned}$$

for any $t \in [0, T]$.

From Proposition 3.24 we see that (\mathbf{v}, \mathbf{n}) is a solution to our problem if we can show that the processes \bar{W}_1 and \bar{W}_2 defined in Proposition 3.15 are Wiener processes and $\mathcal{M}^1, \mathcal{M}^2$ are stochastic integrals with respect to \bar{W}_1 and \bar{W}_2 with integrands $(S(\mathbf{v}(t)))_{t \in [0, T]}$ and $(G(\mathbf{n}(t)))_{t \in [0, T]}$, respectively. These will be the subjects of the following two propositions.

Proposition 3.25 *We have the following facts:*

1. *the stochastic process $(\bar{W}_1(t))_{t \in [0, T]}$ (resp. $(\bar{W}_2(t))_{t \in [0, T]}$) is a \mathbf{K}_1 -cylindrical \mathbf{K}_2 -valued Wiener process (resp. \mathbb{R} -valued standard Brownian motion) on $(\Omega', \mathcal{F}', \mathbb{P}')$.*
2. *For any s and t such that $0 \leq s < t \leq T$, the increments $\bar{W}_1(t) - \bar{W}_1(s)$ and $\bar{W}_2(t) - \bar{W}_2(s)$ are independent of the σ -algebra generated by $\mathbf{v}(r), \mathbf{n}(r), \bar{W}_1(r), \bar{W}_2(r), r \in [0, s]$.*
3. *Finally, \bar{W}_1 and \bar{W}_2 are mutually independent.*

Proof We will just establish the proposition for \bar{W}_1 , the same method applies to \bar{W}_2 . To this end we closely follow [6], but see also [36, Lemma 9.9] for an alternative proof.

Proof of item (1). By Proposition 3.15 the laws of $(\mathbf{v}_{m_k}, \mathbf{n}_{m_k}, W_1, W_2)$ are equal to those of the stochastic process $(\bar{\mathbf{v}}_{m_k}, \bar{\mathbf{n}}_{m_k}, \bar{W}_1^{m_k}, \bar{W}_2^{m_k})$ on \mathfrak{S} . Hence, it is easy to check that $\bar{W}_1^{m_k}$ (resp. $\bar{W}_2^{m_k}$) form a sequence of \mathbf{K}_1 -cylindrical \mathbf{K}_2 -valued Wiener process (resp. \mathbb{R} -valued Wiener process). Moreover, for $0 \leq s < t \leq T$ the increments $\bar{W}_1^{m_k}(t) - \bar{W}_1^{m_k}(s)$ (resp. $\bar{W}_2^{m_k}(t) - \bar{W}_2^{m_k}(s)$) are independent of the σ -algebra generated by the stochastic process $(\bar{\mathbf{v}}_{m_k}(r), \bar{\mathbf{n}}_{m_k}(r), \bar{W}_1^{m_k}(r), \bar{W}_2^{m_k}(r))$, for $r \in [0, s]$.

Now, we will check that \bar{W}_1 is a \mathbf{K}_1 -cylindrical \mathbf{K}_2 -valued Wiener process by showing that the characteristic function of its finite dimensional distributions is equal to the characteristic function of a Gaussian random variable. For this purpose let $k \in \mathbb{N}$ and $s_0 = 0 < s_1 < \dots < s_k \leq T$ be a partition of $[0, T]$. For each $\mathbf{u} \in \mathbf{K}_2^*$ we have

$$\mathbb{E}' \left[e^{i \sum_{j=1}^k \langle \mathbf{u}, \bar{W}_1^{m_k}(s_j) - \bar{W}_1^{m_k}(s_{j-1}) \rangle_{\mathbf{K}_2^*, \mathbf{K}_2}} \right] = e^{-\frac{1}{2} \sum_{j=1}^k (s_j - s_{j-1}) |\mathbf{u}|_{\mathbf{K}_1}^2},$$

where $i^2 = -1$. Thanks to (3.42) and the Lebesgue Dominated Convergence Theorem, we have

$$\begin{aligned} \lim_{m \rightarrow \infty} \mathbb{E}' \left[e^{i \sum_{j=1}^k \langle \mathbf{u}, \bar{W}_1^{m_k}(s_j) - \bar{W}_1^{m_k}(s_{j-1}) \rangle_{\mathbf{K}_2^*, \mathbf{K}_2}} \right] &= \mathbb{E}' \left[e^{i \sum_{j=1}^k \langle \mathbf{u}, \bar{W}_1(s_j) - \bar{W}_1(s_{j-1}) \rangle_{\mathbf{K}_2^*, \mathbf{K}_2}} \right] \\ &= e^{-\frac{1}{2} \sum_{j=1}^k (s_j - s_{j-1}) |\mathbf{u}|_{\mathbf{K}_1}^2} \end{aligned}$$

from which we infer that the finite dimensional distributions of \bar{W}_1 follow a Gaussian distribution. The same idea can be carried out to prove that the finite dimensional distributions of \bar{W}_2 are Gaussian.

Proof of item (2). Next, we prove that the increments $\bar{W}_1(t) - \bar{W}_1(s)$ and $\bar{W}_2(t) - \bar{W}_2(s)$, $0 \leq s < t \leq T$ are independent of the σ -algebra generated by $(\mathbf{v}(r), \mathbf{n}(r), \bar{W}_1(r), \bar{W}_2(r))$ for $r \in [0, s]$. To this end, let us consider $\{\phi_j : j = 1, \dots, k\} \subset C_b(\mathbb{V}_{-b} \times \mathbf{H}^1)$ and $\{\psi_j : j = 1, \dots, k\} \subset C_b(\mathbb{K}_2 \times \mathbb{R})$, where for any Banach space \mathbf{B} the space $C_b(\mathbf{B})$ is defined

$$C_b(\mathbf{B}) = \{\phi : \mathbf{B} \rightarrow \mathbb{R}, \phi \text{ is continuous and bounded}\}.$$

Also, let $0 \leq r_1 < \dots < r_k \leq s < t \leq T$, $\psi \in C_b(\mathbb{K}_2)$, and $\zeta \in C_b(\mathbb{R})$. For each $k \in \mathbb{N}$, there holds

$$\begin{aligned} & \mathbb{E}' \left[\left(\prod_{j=1}^k \phi_j(\bar{\mathbf{v}}_{m_k}(r_j), \bar{\mathbf{n}}_{m_k}(r_j)) \prod_{j=1}^k \psi_j(\bar{W}_1^{m_k}(r_j), \bar{W}_2^{m_k}(r_j)) \right) \right. \\ & \quad \left. \times \psi(\bar{W}_1^{m_k}(t) - \bar{W}_1^{m_k}(s)) \zeta(\bar{W}_2^{m_k}(t) - \bar{W}_2^{m_k}(s)) \right] \\ &= \mathbb{E}' \left[\prod_{j=1}^k \phi_j(\bar{\mathbf{v}}_{m_k}(r_j), \bar{\mathbf{n}}_{m_k}(r_j)) \prod_{j=1}^k \psi_j(\bar{W}_1^{m_k}(r_j), \bar{W}_2^{m_k}(r_j)) \right] \\ & \quad \times \mathbb{E}'(\zeta(\bar{W}_1^{m_k}(t) - \bar{W}_1^{m_k}(s))) \mathbb{E}'(\psi(\bar{W}_2^{m_k}(t) - \bar{W}_2^{m_k}(s))). \end{aligned}$$

Thanks to (3.39), (3.41), (3.42), (3.43) and the Lebesgue Dominated Convergence Theorem, the same identity is true with $(\mathbf{v}, \mathbf{n}, \bar{W}_1, \bar{W}_2)$ in place of $(\bar{\mathbf{v}}_{m_k}, \bar{\mathbf{n}}_{m_k}, \bar{W}_1^{m_k}, \bar{W}_2^{m_k})$. This completes the proof of the second item of the proposition.

Proof of item (3). By using the characteristic functions of the process $\bar{W}_1^{m_k}, \bar{W}_2^{m_k}, \bar{W}_1$ and \bar{W}_2 , item (3) can be easily proved as in the proof of item (1), so we omit the details. □

Proposition 3.26 *For each $t \in (0, T]$ we have*

$$\mathcal{M}^1(t) = \int_0^t S(\mathbf{v}(s)) d\bar{W}_1(s) \text{ in } L^2(\Omega', \mathbb{V}^*), \tag{3.81}$$

$$\mathcal{M}^2(t) = \int_0^t (\mathbf{n}(s) \times \mathbf{h}) d\bar{W}_2(s) \text{ in } L^2(\Omega, \mathbf{X}_\beta). \tag{3.82}$$

Proof The same argument given in [6] can be used without modification to establish (3.82), thus we only prove (3.81). The proof we give below can also be adapted to the proof of (3.82).

We will closely follow the idea in [4] to establish (3.81). For this purpose, let us fix $t \in (0, T]$ and for any $\varepsilon > 0$ let $\eta_\varepsilon : \mathbb{R} \rightarrow \mathbb{R}$ be a standard mollifier with support in $(0, t)$. For $R \in \{S, S_{m_k}\}$, $\mathbf{u} \in \{\bar{\mathbf{v}}_{m_k}, \mathbf{v}\}$ and $s \in (0, t]$ let us set

$$\begin{aligned}
 R^\varepsilon(\mathbf{u}(s)) &= (\eta_\varepsilon \star R(\mathbf{u}(\cdot)))(s) \\
 &= \int_{-\infty}^\infty \eta_\varepsilon(s-r)R(\mathbf{u}(r))dr.
 \end{aligned}$$

We recall that, since R is Lipschitz, R^ε is Lipschitz. We also have the following two important facts, see, for instance, [2, Section 1.3]:

(a) for any $p \in [1, \infty)$ there exists a constant $C > 0$ such that for any $\varepsilon > 0$ we have

$$\int_0^t \|R^\varepsilon(\mathbf{u}(s))\|_{\mathcal{T}_2(\mathbb{K}_1, \mathbb{H})}^p ds \leq C \int_0^t \|R(\mathbf{u}(s))\|_{\mathcal{T}_2(\mathbb{K}_1, \mathbb{H})}^p ds. \tag{3.83}$$

(b) For any $p \in [1, \infty)$, we have

$$\lim_{\varepsilon \rightarrow 0} \int_0^t \|R^\varepsilon(\mathbf{u}(s)) - R(\mathbf{u}(s))\|_{\mathcal{T}_2(\mathbb{K}_1, \mathbb{H})}^p ds = 0. \tag{3.84}$$

Now, let $\mathcal{M}_{m_k}^\varepsilon$ and \mathcal{M}^ε be respectively defined by

$$\begin{aligned}
 \mathcal{M}_{m_k}^\varepsilon(t) &= \int_0^t S_{m_k}^\varepsilon(\bar{\mathbf{v}}_{m_k}(s))d\bar{W}_1^{m_k}(s), \\
 \mathcal{M}^\varepsilon(t) &= \int_0^t S^\varepsilon(\mathbf{v}(s))d\bar{W}_1(s),
 \end{aligned}$$

for $t \in (0, T]$. From the Itô isometry, (3.83) and some elementary calculations we infer that there exists a constant $C > 0$ such that for any $\varepsilon > 0$ and $m_k \in \mathbb{N}$

$$\begin{aligned}
 \mathbb{E}' \|\mathcal{M}_{m_k}(t) - \mathcal{M}_{m_k}^\varepsilon(t)\|^2 &= \mathbb{E}' \int_0^t \|S(\bar{\mathbf{v}}_{m_k}(s)) - S_{m_k}^\varepsilon(\bar{\mathbf{v}}_{m_k}(s))\|_{\mathcal{T}_2(\mathbb{K}_1, \mathbb{H})}^2 ds, \\
 &\leq C\mathbb{E}' \int_0^t \|S(\bar{\mathbf{v}}_{m_k}(s)) - S(\mathbf{v}(s))\|_{\mathcal{T}_2(\mathbb{K}_1, \mathbb{H})}^2 ds \tag{3.85}
 \end{aligned}$$

$$+ C\mathbb{E}' \int_0^t \|S(\mathbf{v}(s)) - S^\varepsilon(\mathbf{v}(s))\|_{\mathcal{T}_2(\mathbb{K}_1, \mathbb{H})}^2 ds. \tag{3.86}$$

From Assumption 2.2 and (3.51) we derive that the first term in the right hand side of the last estimate converges to 0 as $m_k \rightarrow \infty$. Owing to (3.83) and (3.62) the sequence in the second term of (3.86) is uniformly integrable with respect to the probability measure \mathbb{P}' . Thus, from (3.84) and the Vitali Convergence Theorem we infer that

$$\lim_{\varepsilon \rightarrow 0} \mathbb{E}' \int_0^t \|S(\mathbf{v}(s)) - S^\varepsilon(\mathbf{v}(s))\|_{\mathcal{T}_2(\mathbb{K}_1, \mathbb{H})}^2 ds = 0.$$

Hence, for any $t \in (0, T]$

$$\lim_{\varepsilon \rightarrow 0} \lim_{k \rightarrow \infty} \mathbb{E}' \|\mathcal{M}_{m_k}(t) - \mathcal{M}_{m_k}^\varepsilon(t)\|^2 = 0. \tag{3.87}$$

In a similar way, we can prove that

$$\lim_{\varepsilon \rightarrow 0} \lim_{k \rightarrow \infty} \mathbb{E}' \left\| \mathcal{M}^2(t) - \mathcal{M}^\varepsilon(t) \right\|^2 = 0. \tag{3.88}$$

Next, we will prove that

$$\lim_{\varepsilon \rightarrow 0} \lim_{k \rightarrow \infty} \mathbb{E}' \left\| \mathcal{M}_{m_k}^\varepsilon(t) - \mathcal{M}^\varepsilon(t) \right\|^2 = 0. \tag{3.89}$$

To this end, we first observe that

$$\begin{aligned} \mathcal{M}_{m_k}^\varepsilon(t) - \mathcal{M}^\varepsilon(t) &= \int_0^t S_{m_k}^\varepsilon(\bar{\mathbf{v}}_{m_k}(s)) \bar{W}_1^{m_k}(s) - \int_0^t S_{m_k}^\varepsilon(\mathbf{v}(s)) d\bar{W}_1(s) \\ &\quad + \int_0^t S_{m_k}^\varepsilon(\mathbf{v}(s)) d\bar{W}_1(s) - \int_0^t S^\varepsilon(\mathbf{v}(s)) d\bar{W}_1(s) \\ &= I_{m_k,1}^\varepsilon(t) + I_{m_k,2}^\varepsilon(t). \end{aligned} \tag{3.90}$$

Second, by integration by parts we derive that

$$\begin{aligned} I_{m_k,1}^\varepsilon(t) &= \int_0^t [\eta'_\varepsilon \star S_{m_k}(\mathbf{v}(\cdot))](s) \bar{W}_1(s) ds - \int_0^t [\eta'_\varepsilon \star S_{m_k}(\bar{\mathbf{v}}_{m_k}(\cdot))](s) \bar{W}_1^{m_k}(s) ds \\ &= \int_0^t [\eta'_\varepsilon \star S_{m_k}(\bar{\mathbf{v}}_{m_k}(\cdot))](s) [\bar{W}_1^{m_k}(s) - \bar{W}_1(s)] ds \\ &\quad + \int_0^t [S_{m_k}^\varepsilon(\bar{\mathbf{v}}_{m_k}(s)) - S_{m_k}^\varepsilon(\mathbf{v}(s))] d\bar{W}_1(s) \\ &= J_{m_k,1}^\varepsilon(t) + J_{m_k,2}^\varepsilon(t). \end{aligned}$$

On one hand, by Proposition 3.25 the processes $\bar{W}_1^{m_k}$ and \bar{W}_1 are both K_1 -cylindrical K_2 -valued Wiener processes, thus, for any integer $p \geq 4$ there exists a constant $C > 0$ such that

$$\sup_{m_k \in \mathbb{N}} \mathbb{E}' \sup_{s \in [0, T]} \left(\|\bar{W}_1^{m_k}(s)\|_{K_2}^p + \|\bar{W}_1(s)\|_{K_2}^p \right) \leq CQT^{\frac{p}{2}}.$$

Hence, the sequence $\int_0^t \|\bar{W}_1^{m_k}(s) - \bar{W}_1(s)\|_{K_2}^2 ds$ is uniformly integrable with respect to the probability measure \mathbb{P}' , and from (3.42) and the Vitali Convergence Theorem we infer that

$$\lim_{m_k \rightarrow \infty} \mathbb{E}' \int_0^t \|\bar{W}_1^{m_k}(s) - \bar{W}_1(s)\|_{K_2}^2 ds = 0. \tag{3.91}$$

On the other hand, for any $\varepsilon > 0$ there exists a constant $C(\varepsilon)$ such that

$$\mathbb{E}' \int_0^t \left\| [\eta'_\varepsilon \star S_{m_k}(\bar{\mathbf{v}}_{m_k}(\cdot))](s) \right\|_{\mathcal{T}_2(K_1, H)}^2 ds \leq C(\varepsilon) T \mathbb{E}' \sup_{t \in [0, T]} \|S_{m_k}(\bar{\mathbf{v}}_{m_k}(t))\|_{\mathcal{T}_2(K_1, H)}^2,$$

from which along with Assumption 2.2 and (3.44) we infer that for any $\varepsilon > 0$ there exists a constant $C > 0$ such that for any $m_k \in \mathbb{N}$ we have

$$\mathbb{E}' \int_0^t \left\| \left[\eta'_\varepsilon \star S_{m_k}(\bar{\mathbf{v}}_{m_k}(\cdot)) \right] (s) \right\|_{\mathbb{T}_2(\mathbb{K}_1, \mathbb{H})}^2 ds \leq C(\varepsilon)T.$$

Thus, from these two observation along with (3.91) we derive that

$$\lim_{\varepsilon \rightarrow 0} \lim_{k \rightarrow \infty} \mathbb{E}' \left\| J_{m_k, 1}^\varepsilon(t) \right\|^2 = 0, t \in (0, T].$$

Using the same argument as in the proof of (3.87) and (3.88) we easily show that

$$\lim_{\varepsilon \rightarrow 0} \lim_{k \rightarrow \infty} \left(\mathbb{E}' \left\| J_{m_k, 2}^\varepsilon(t) \right\|^2 + \mathbb{E}' \left\| I_{m_k, 2}^\varepsilon(t) \right\|^2 \right) = 0.$$

Hence, we have just established that

$$\lim_{\varepsilon \rightarrow 0} \lim_{k \rightarrow \infty} \mathbb{E}' \left\| I_{m_k, 1}^\varepsilon(t) \right\|^2 + \left\| I_{m_k, 2}^\varepsilon(t) \right\|^2 = 0, t \in (0, T], \tag{3.92}$$

which along with (3.90) implies that

$$\lim_{\varepsilon \rightarrow 0} \lim_{k \rightarrow \infty} \mathbb{E}' \left\| \mathcal{M}_{m_k}^\varepsilon(t) - \mathcal{M}^\varepsilon(t) \right\|^2 = 0. \tag{3.93}$$

The identities (3.87), (3.88) and (3.93) imply that for any $t \in (0, T]$

$$\lim_{k \rightarrow \infty} \mathbb{E}' \left\| \mathcal{M}_{m_k}^1(t) - \mathcal{M}^1(t) \right\|^2 = 0. \tag{3.94}$$

To conclude the proof of the proposition we need to show that \mathbb{P}' -a.s.

$$\mathcal{M}_{m_k}^1(t) - \int_0^t S_{m_k}(\bar{\mathbf{v}}_{m_k}(s)) d\bar{W}_1^{m_k}(s) = 0, \tag{3.95}$$

for any $t \in (0, T]$. To this end, let \mathcal{M}_m^1 and $\mathcal{M}_m^\varepsilon$ be the analogue of $\mathcal{M}_{m_k}^1$ and $\mathcal{M}_{m_k}^\varepsilon$ with m_k and $\bar{\mathbf{v}}_{m_k}$ replaced by m and $\bar{\mathbf{v}}_m$, respectively. For any $\mathbf{u} \in L^2(0, T; \mathbb{V}^*)$ we set

$$\varphi(\mathbf{u}) = \frac{\int_0^T \|\mathbf{u}(s)\|_{\mathbb{V}^*}^2 ds}{1 + \int_0^T \|\mathbf{u}(s)\|_{\mathbb{V}^*}^2 ds}.$$

Since $(\bar{\mathbf{v}}_{m_k}, \bar{\mathbf{n}}_{m_k}, \bar{W}_1^{m_k})$ and $(\bar{\mathbf{v}}_m, \bar{\mathbf{n}}_m, W_1)$ have the same law and $\varphi(\cdot)$ is continuous as a mapping from $\mathfrak{S}_1 \times \mathfrak{S}_2 \times C([0, T]; \mathbb{K}_1)$ into \mathbb{R} , we infer that

$$\mathbb{E}\varphi\left(\mathcal{M}_m^1 - \mathcal{M}_m^\varepsilon\right) = \mathbb{E}'\varphi\left(\mathcal{M}_{m_k}^1 - \mathcal{M}_{m_k}^\varepsilon\right).$$

Note that arguing as above we can show that as $\varepsilon \rightarrow 0$ we have

$$\mathbb{E}\varphi\left(\mathcal{M}_m^1 - \mathfrak{M}_m^1\right) = \mathbb{E}'\varphi\left(\mathcal{M}_{m_k}^1 - \mathfrak{M}_{m_k}^1\right),$$

where

$$\mathfrak{M}_m^1(\cdot) = \int_0^\cdot S_m(\bar{\mathbf{v}}_m(s))dW_1(s).$$

Since $\bar{\mathbf{v}}_m$ and $\bar{\mathbf{n}}_m$ are the solution of the Galerkin approximation, we have \mathbb{P} -a.s. $\varphi(\mathcal{M}_m^1 - \mathfrak{M}_m^1) = 0$, from which we infer that

$$\mathbb{E}'\varphi\left(\mathcal{M}_{m_k}^1 - \mathcal{M}_{m_k}\right) = 0.$$

This last identity implies that \mathbb{P}' -a.s. $\mathcal{M}_{m_k}^1(t) - \mathcal{M}_{m_k}(t) = 0$ for almost all $t \in (0, T]$. Since the mappings $\mathcal{M}_{m_k}^1(\cdot) - \mathcal{M}_{m_k}(\cdot)$ are continuous in V^* and agree for almost everywhere $t \in (0, T]$, necessarily they agree for all $t \in (0, T]$. Thus, we have proved the identity (3.95) which along with (3.94) implies the desired equality (3.75). \square

Now we give the promised proof of the existence of a weak martingale solution.

Proof of Theorem 3.2 Endowing the complete probability space $(\Omega', \mathcal{F}', \mathbb{P}')$ with the filtration $\mathbb{F}' = (\mathcal{F}'_t)_{t \geq 0}$ which satisfies the usual condition, and combining Propositions 3.24, 3.25 and 3.26 we have just constructed a complete filtered probability space and stochastic processes $\mathbf{v}(t), \mathbf{n}(t), \bar{W}_1(t), \bar{W}_2(t)$ which satisfy all the items of Definition 3.1. \square

3.4 Proof of the pathwise uniqueness of the weak solution in the 2-D case

This subsection is devoted to the proof of the uniqueness stated in Theorem 3.4. Before proceeding to the actual proof of this pathwise uniqueness, we state and prove the following lemma.

Lemma 3.27 *For any $\alpha_8 > 0$ and $\alpha_9 > 0$ there exist $C(\alpha_8) > 0, C_1(\alpha_9) > 0$ and $C_2(\alpha_9) > 0$ such that*

$$|\langle f(\mathbf{n}_1) - f(\mathbf{n}_2), \mathbf{n}_1 - \mathbf{n}_2 \rangle| \leq \alpha_8 \|\nabla \mathbf{n}_1 - \nabla \mathbf{n}_2\|^2 + C(\alpha_8) \|\mathbf{n}_1 - \mathbf{n}_2\|^2 \varphi(\mathbf{n}_1, \mathbf{n}_2), \tag{3.96}$$

$$\begin{aligned} |\langle f(\mathbf{n}_1) - f(\mathbf{n}_2), A_1 \mathbf{n}_1 - A_1 \mathbf{n}_2 \rangle| &\leq \alpha_9 \|A_1 \mathbf{n}_1 - A_1 \mathbf{n}_2\|^2 \\ &+ C_1(\alpha_9) \|\nabla \mathbf{n}_1 - \nabla \mathbf{n}_2\|^2 \varphi(\mathbf{n}_1, \mathbf{n}_2) \\ &+ C_2(\alpha_9) \|\mathbf{n}_1 - \mathbf{n}_2\|^2 \varphi(\mathbf{n}_1, \mathbf{n}_2), \end{aligned} \tag{3.97}$$

where

$$\varphi(\mathbf{n}_1, \mathbf{n}_2) := C \left(1 + \|\mathbf{n}_1\|_{\mathbf{L}^{4N+2}}^{2N} + \|\mathbf{n}_2\|_{\mathbf{L}^{4N+2}}^{2N} \right)^2.$$

Proof of Lemma 3.27 It is enough to prove the estimate (3.96) for the special case $f(\mathbf{n}) := a_N |\mathbf{n}|^{2N} \mathbf{n}$. For this purpose we recall that

$$|\mathbf{n}_1|^{2N} \mathbf{n}_1 - |\mathbf{n}_2|^{2N} \mathbf{n}_2 = |\mathbf{n}_1|^{2N} (\mathbf{n}_1 - \mathbf{n}_2) + \mathbf{n}_2 (|\mathbf{n}_1| - |\mathbf{n}_2|) \left(\sum_{k=0}^{2N-1} |\mathbf{n}_1|^{2N-k-1} |\mathbf{n}_2|^k \right),$$

from which we easily deduce that

$$|\langle f(\mathbf{n}_1) - f(\mathbf{n}_2), \mathbf{n}_1 - \mathbf{n}_2 \rangle| \leq C \int_{\mathcal{O}} \left(1 + |\mathbf{n}_1|^{2N} + |\mathbf{n}_2|^{2N} \right) |\mathbf{n}_1 - \mathbf{n}_2|^2 dx,$$

for any $\mathbf{n}_1, \mathbf{n}_2 \in \mathbb{L}^{2N+2}(\mathcal{O})$. Now, invoking the Hölder, Gagliardo–Nirenberg and Young inequalities we infer that

$$\begin{aligned} |\langle f(\mathbf{n}_1) - f(\mathbf{n}_2), \mathbf{n}_1 - \mathbf{n}_2 \rangle| &\leq C \|\mathbf{n}_1 - \mathbf{n}_2\|_{\mathbb{L}^4}^2 \left(1 + \|\mathbf{n}_1\|_{\mathbb{L}^{4N+2}}^{2N} + \|\mathbf{n}_2\|_{\mathbb{L}^{4N+2}}^{2N} \right) \\ &\leq C \|\mathbf{n}_1 - \mathbf{n}_2\| \|\nabla(\mathbf{n}_1 - \mathbf{n}_2)\| \left(1 + \|\mathbf{n}_1\|_{\mathbb{L}^{4N+2}}^{2N} + \|\mathbf{n}_2\|_{\mathbb{L}^{4N+2}}^{2N} \right) \\ &\leq \alpha_8 \|\nabla(\mathbf{n}_1 - \mathbf{n}_2)\|^2 + C(\alpha_8) \|\mathbf{n}_1 - \mathbf{n}_2\|^2 \left(1 + \|\mathbf{n}_1\|_{\mathbb{L}^{4N+2}}^{2N} + \|\mathbf{n}_2\|_{\mathbb{L}^{4N+2}}^{2N} \right)^2. \end{aligned}$$

The last line of the above chain of inequalities implies (3.96).

Using the fact that $\mathbf{H}^1 \subset \mathbb{L}^{4N+2}$ for any $N \in \mathbb{N}$ and the same argument as in the proof of (3.96) we derive that

$$\begin{aligned} &|\langle f(\mathbf{n}_1) - f(\mathbf{n}_2), A_1 \mathbf{n}_1 - A_1 \mathbf{n}_2 \rangle| \\ &\leq C \int_{\mathcal{O}} \left(1 + |\mathbf{n}_1|^{2N} + |\mathbf{n}_2|^{2N} \right) |\mathbf{n}_1 - \mathbf{n}_2| |A_1(\mathbf{n}_1 - \mathbf{n}_2)| dx \\ &\leq C \|\mathbf{n}_1 - \mathbf{n}_2\|_{\mathbb{L}^{4N+2}} \|A_1[\mathbf{n}_1 - \mathbf{n}_2]\| \left(1 + \|\mathbf{n}_1\|_{\mathbb{L}^{4N+2}}^{2N} + \|\mathbf{n}_2\|_{\mathbb{L}^{4N+2}}^{2N} \right) \\ &\leq C \|\mathbf{n}_1 - \mathbf{n}_2\|_{\mathbf{H}^1} \|A_1[\mathbf{n}_1 - \mathbf{n}_2]\| \left(1 + \|\mathbf{n}_1\|_{\mathbb{L}^{4N+2}}^{2N} + \|\mathbf{n}_2\|_{\mathbb{L}^{4N+2}}^{2N} \right) \\ &\leq \alpha_9 \|A_1[\mathbf{n}_1 - \mathbf{n}_2]\|^2 + C(\alpha_9) \|\mathbf{n}_1 - \mathbf{n}_2\|_{\mathbf{H}^1}^2 \left(1 + \|\mathbf{n}_1\|_{\mathbb{L}^{4N+2}}^{2N} + \|\mathbf{n}_2\|_{\mathbb{L}^{4N+2}}^{2N} \right)^2. \end{aligned}$$

From the last line we easily deduce the proof of (3.97). □

Now, we give the promised proof of the uniqueness of our solution.

Proof of Theorem 3.4 Let $\mathbf{v} = \mathbf{v}_1 - \mathbf{v}_2$ and $\mathbf{n} = \mathbf{n}_1 - \mathbf{n}_2$. These processes satisfy $(\mathbf{v}(0), \mathbf{n}(0)) = (0, 0)$ and the stochastic equations

$$\begin{aligned} d\mathbf{v}(t) &+ \left(A\mathbf{v}(t) + B(\mathbf{v}(t), \mathbf{v}_1(t)) + B(\mathbf{v}_2(t), \mathbf{v}(t)) \right) dt \\ &= - \left(M(\mathbf{n}(t), \mathbf{n}_1(t)) + M(\mathbf{n}_2, \mathbf{n}) \right) dt \\ &\quad + [S(\mathbf{v}_1(t)) - S_2(\mathbf{v}_2(t))] dW_1(t), \end{aligned}$$

and

$$d\mathbf{n}(t) + \left(\mathbf{A}_1 \mathbf{n}(t) + \tilde{\mathbf{B}}(\mathbf{v}(t), \mathbf{n}_1(t)) + \tilde{\mathbf{B}}(\mathbf{v}_2(t), \mathbf{n}(t)) \right) dt = -[f(\mathbf{n}_2(t)) - f(\mathbf{n}_1(t))] dt + \frac{1}{2} G^2(\mathbf{n}(t)) dt + G(\mathbf{n}(t)) dW_2(t).$$

Firstly, from Young’s inequality and (6.8) we infer that for any $\alpha_1 > 0$ there exists a constant $C(\alpha_1) > 0$ such that

$$|\langle \tilde{\mathbf{B}}(\mathbf{v}, \mathbf{v}_1), \mathbf{v} \rangle_{V^*, V}| \leq \alpha_1 \|\nabla \mathbf{v}\|^2 + C(\alpha_1) \|\mathbf{v}_1\|^2 \|\nabla \mathbf{v}_1\|^2 \|\mathbf{v}\|^2.$$

Secondly, Young’s inequality and (2.9) yield that for any $\alpha_2 > 0, \alpha_3 > 0, \alpha_4 > 0$ and $\alpha_7 > 0$ there exist constants $C(\alpha_2, \alpha_3) > 0$ and $C(\alpha_7, \alpha_4) > 0$ such that

$$\begin{aligned} |\langle M(\mathbf{n}_2, \mathbf{n}), \mathbf{v} \rangle_{V^*, V}| &\leq \|\nabla \mathbf{v}\| \|\nabla \mathbf{n}_2\|^{\frac{1}{2}} (\|\mathbf{n}_2\| + \|\mathbf{A}_1 \mathbf{n}_2\|)^{\frac{1}{2}} \|\nabla \mathbf{n}\|^{\frac{1}{2}} (\|\mathbf{n}\| + \|\mathbf{A}_1 \mathbf{n}\|)^{\frac{1}{2}} \\ &\leq \alpha_2 \|\nabla \mathbf{v}\|^2 + \alpha_3 (\|\mathbf{A}_1 \mathbf{n}\|^2 + \|\mathbf{n}\|^2) + C(\alpha_2, \alpha_3) \|\nabla \mathbf{n}_2\|^2 (\|\mathbf{A}_1 \mathbf{n}_2\|^2 + \|\mathbf{n}_2\|^2) \|\nabla \mathbf{n}\|^2, \\ |\langle M(\mathbf{n}, \mathbf{n}_1), \mathbf{v} \rangle_{V^*, V}| &\leq \alpha_7 \|\nabla \mathbf{v}\|^2 + \alpha_4 (\|\mathbf{A}_1 \mathbf{n}\|^2 + \|\mathbf{n}\|^2) \\ &+ C(\alpha_7, \alpha_4) \|\nabla \mathbf{n}_1\|^2 (\|\mathbf{A}_1 \mathbf{n}_1\|^2 + \|\mathbf{n}_1\|^2) \|\nabla \mathbf{n}\|^2. \end{aligned} \tag{3.98}$$

Thirdly, from Young’s inequality and (6.9) we derive that for any $\alpha_5 > 0$ there exists a constant $C(\alpha_5) > 0$ such that

$$\begin{aligned} |\langle \tilde{\mathbf{B}}(\mathbf{v}_2, \mathbf{n}), \mathbf{A}_1 \mathbf{n} \rangle| &\leq (\|\mathbf{n}\| + \|\mathbf{A}_1 \mathbf{n}\|)^{\frac{3}{2}} \|\mathbf{v}_2\|^{\frac{1}{2}} \|\nabla \mathbf{v}_2\|^{\frac{1}{2}} \|\nabla \mathbf{n}\|^{\frac{1}{2}} \\ &\alpha_5 (\|\mathbf{A}_1 \mathbf{n}\|^2 + \|\mathbf{n}\|^2) + C(\alpha_5) \|\mathbf{v}_2\|^2 \|\nabla \mathbf{v}_2\|^2 \|\nabla \mathbf{n}\|^2. \end{aligned} \tag{3.99}$$

From Hölder’s inequality, Gagliardo–Nirenberg’s inequality (6.1) and the Sobolev embedding $\mathbf{H}^2 \subset \mathbf{L}^\infty$ we infer that for any $\alpha_6 > 0$ there exists $C(\alpha_6) > 0$ such that

$$\begin{aligned} |\langle \tilde{\mathbf{B}}(\mathbf{v}, \mathbf{n}_1), \mathbf{n} \rangle| &\leq \|\mathbf{v}\| \|\nabla \mathbf{n}_1\| \|\mathbf{n}\|_{\mathbf{L}^\infty}, \\ &\leq \alpha_6 (\|\mathbf{n}\|^2 + \|\mathbf{A}_1 \mathbf{n}\|^2) + C(\alpha_6) \|\mathbf{v}\|^2 \|\nabla \mathbf{n}_1\|^2. \end{aligned}$$

From the proof of Proposition 3.9 we see that there exists a constant $C > 0$ which depends only on $\|\mathbf{h}\|_{\mathbb{W}^{1,3}}$ and $\|\mathbf{h}\|_{\mathbf{L}^\infty}$ such that

$$\begin{aligned} \|\nabla G(\mathbf{n})\|^2 &\leq C (\|\nabla \mathbf{n}\|^2 + \|\mathbf{n}\|^2), \\ \|\nabla G^2(\mathbf{n})\|^2 &\leq C (\|\nabla \mathbf{n}\|^2 + \|\mathbf{n}\|^2), \\ |\langle \nabla G^2(\mathbf{n}), \nabla \mathbf{n} \rangle| &\leq C (\|\nabla \mathbf{n}\|^2 + \|\mathbf{n}\|^2). \end{aligned}$$

Owing to the Lipschitz property of S we have

$$\|S(\mathbf{v}_1) - S(\mathbf{v}_2)\|_{\mathcal{T}_2(\mathbb{K}_1, \mathbb{H})}^2 \leq C \|\mathbf{v}\|^2. \tag{3.100}$$

Now, let $\varphi(\mathbf{n}_1, \mathbf{n}_2)$ be as in Lemma 3.27 and

$$\Psi(t) = e^{-\int_0^t (\psi_1(s) + \psi_2(s) + \psi_3(s)) ds}, \text{ for any } t > 0,$$

where

$$\begin{aligned} \psi_1(s) &:= C(\alpha_1) \|\mathbf{v}_1(s)\|^2 \|\nabla \mathbf{v}_1(s)\|^2 + C(\alpha_6) \|\nabla \mathbf{n}_1(s)\|^2, \\ \psi_3(s) &:= [C(\alpha_8) + C_2(\alpha_9)] \varphi(\mathbf{n}_1(s), \mathbf{n}_2(s)), \end{aligned}$$

and

$$\begin{aligned} \psi_2(s) &:= C(\alpha_2, \alpha_3) \|\nabla \mathbf{n}_2(s)\|^2 (\|\mathbf{n}_2(s)\|^2 + \|\mathbf{A}_1 \mathbf{n}_2(s)\|^2) \\ &\quad + C(\alpha_7, \alpha_4) \|\nabla \mathbf{n}_1(s)\|^2 (\|\mathbf{n}_1(s)\|^2 + \|\mathbf{A}_1 \mathbf{n}_1(s)\|^2) \\ &\quad + C(\alpha_5) \|\mathbf{v}_2(s)\|^2 \|\nabla \mathbf{v}_2(s)\|^2 + C_1(\alpha_9) \varphi(\mathbf{n}_1(s), \mathbf{n}_2(s)). \end{aligned}$$

Now applying Itô's formula to $\|\mathbf{n}(t)\|^2$ and $\Psi(t)\|\mathbf{n}(t)\|^2$ yield

$$\begin{aligned} d \left[\Psi(t) \|\mathbf{n}(t)\|^2 \right] &= -2\Psi(t) \|\nabla \mathbf{n}(t)\|^2 dt - 2\Psi(t) \langle \tilde{B}(\mathbf{v}(t), \mathbf{n}_1(t)), \mathbf{n}(t) \rangle \\ &\quad - 2 \langle f(\mathbf{n}_2(t)) - f(\mathbf{n}_1(t)), \mathbf{n}(t) \rangle dt + \Psi'(t) \|\mathbf{n}(t)\|^2. \end{aligned}$$

Using the same argument we can show that $\Psi(t)\|\nabla \mathbf{n}(t)\|^2$ and $\Psi(t)\|\mathbf{v}(t)\|^2$ satisfy

$$\begin{aligned} d \left[\Psi(t) \|\nabla \mathbf{n}(t)\|^2 \right] &= \Psi(t) \left(-\|\mathbf{A}_1 \mathbf{n}(t)\|^2 + \langle \tilde{B}(\mathbf{v}(t), \mathbf{n}_1(t)) + \tilde{B}(\mathbf{v}_2(t), \mathbf{n}(t)), \mathbf{A}_1 \mathbf{n}(t) \rangle \right) dt \\ &\quad + \Psi(t) \left(2 \langle f(\mathbf{n}_2(t)) - f(\mathbf{n}_1(t)), \mathbf{A}_1 \mathbf{n}(t) \rangle + \langle \nabla G^2(\mathbf{n}(t)), \nabla \mathbf{n}(t) \rangle \right) dt \\ &\quad + \|\mathbf{G}(\mathbf{n}(t))\|^2 dt + \Psi'(t) \|\nabla \mathbf{n}(t)\|^2 dt + 2\Psi(t) \langle \nabla G(\mathbf{n}(t)), \nabla \mathbf{n}(t) \rangle dW_2(t), \end{aligned}$$

and

$$\begin{aligned} d[\Psi(t)\|\mathbf{v}(t)\|^2] &= -2\Psi(t) \left(\|\nabla \mathbf{v}(t)\|^2 + \langle \mathbf{B}(\mathbf{v}(t), \mathbf{v}_1(t)) + \mathbf{M}(\mathbf{n}(t), \mathbf{n}_1(t)), \mathbf{v}(t) \rangle_{\mathbf{V}^*, \mathbf{V}} \right) dt \\ &\quad - 2\Psi(t) \langle \mathbf{M}(\mathbf{n}_2(t), \mathbf{n}(t)), \mathbf{v}(t) \rangle_{\mathbf{V}^*, \mathbf{V}} dt + \Psi(t) \|S(\mathbf{v}_1(t)) - S(\mathbf{v}_2(t))\|_{\mathcal{T}_2}^2 dt \\ &\quad + \Psi'(t) \|\mathbf{v}(t)\|^2 dt \\ &\quad + 2\Psi(t) \langle \mathbf{v}(t), [S(\mathbf{v}_1(t)) - S(\mathbf{v}_2(t))] dW_1(t) \rangle. \end{aligned}$$

Summing up these last three equalities side by side and using the inequalities (3.97)–(3.100) imply

$$\begin{aligned}
 & d \left[\Psi(t) \left(\|\mathbf{v}(t)\|^2 + \|\mathbf{n}(t)\|^2 + \|\nabla \mathbf{n}(t)\|^2 \right) \right] \\
 & \quad + 2\Psi(t) \left[\|\nabla \mathbf{v}(t)\|^2 + \|\nabla \mathbf{n}(t)\|^2 + \|\mathbf{A}_1 \mathbf{n}(t)\|^2 \right] dt \\
 & \leq 2\Psi(t) \left(C \left[\|\mathbf{v}(t)\|^2 + \|\mathbf{n}(t)\|^2 + \|\nabla \mathbf{n}(t)\|^2 \right] dt + \langle \nabla G(\mathbf{n}(t)), \nabla \mathbf{n}(t) \rangle dW_2(t) \right) \\
 & \quad + 2\Psi(t) \left(\langle \mathbf{v}(t), [S(\mathbf{v}_1(t)) - S(\mathbf{v}_2(t))] \rangle dW_1(t) + \left[\alpha_9 + \sum_{j=3}^6 \alpha_j \right] \|\mathbf{A}_1 \mathbf{n}(t)\|^2 \right) \\
 & \quad + \Psi(t) \left[\psi_2(t) \|\nabla \mathbf{n}(t)\|^2 + \psi_1(t) \|\mathbf{v}(t)\|^2 + \psi_3(t) \|\mathbf{n}(t)\|^2 \right] dt \\
 & \quad + \Psi'(t) \left(\|\mathbf{v}(t)\|^2 + \|\mathbf{n}(t)\|^2 + \|\nabla \mathbf{n}(t)\|^2 \right) dt \\
 & \quad + (\alpha_1 + \alpha_2 + \alpha_7) \|\nabla \mathbf{v}(t)\|^2 + \alpha_8 \|\nabla \mathbf{n}(t)\|^2 dt.
 \end{aligned}$$

Notice that by the choice of Ψ we have

$$\begin{aligned}
 & \Psi(t) \left[\psi_2(t) \|\nabla \mathbf{n}(t)\|^2 + \psi_1(t) \|\mathbf{v}(t)\|^2 + \psi_3(t) \|\mathbf{n}(t)\|^2 \right] \\
 & \quad + \Psi'(t) \left(\|\mathbf{v}(t)\|^2 + \|\mathbf{n}(t)\|^2 + \|\nabla \mathbf{n}(t)\|^2 \right) \leq 0.
 \end{aligned}$$

Hence by choosing $\alpha_j = \alpha_9 = \frac{1}{10}, j = 3, \dots, 6, \alpha_i = \alpha_7 = \frac{1}{6}, i = 2, 3$ and $\alpha_8 = \frac{1}{2}$ we see that

$$\begin{aligned}
 & d[\Psi(t) \left(\|\mathbf{v}(t)\|^2 + \|\mathbf{n}(t)\|^2 + \|\nabla \mathbf{n}(t)\|^2 \right)] + \Psi(t) \left[\|\nabla \mathbf{v}(t)\|^2 + \|\mathbf{A}_1 \mathbf{n}(t)\|^2 + \|\nabla \mathbf{n}(t)\|^2 \right] dt \\
 & \leq 2\Psi(t) \left(C \left[\|\mathbf{v}(t)\|^2 + \|\mathbf{n}(t)\|^2 + \|\nabla \mathbf{n}(t)\|^2 \right] dt + \langle \nabla G(\mathbf{n}(t)), \nabla \mathbf{n}(t) \rangle dW_2(t) \right. \\
 & \quad \left. + \langle \mathbf{v}(t), [S(\mathbf{v}_1(t)) - S(\mathbf{v}_2(t))] \rangle dW_1(t) \right).
 \end{aligned}$$

Next, integrating and taking the mathematical expectation yield

$$\begin{aligned}
 & \mathbb{E} \left[\Psi(t) \left(\|\mathbf{v}(t)\|^2 + \|\mathbf{n}(t)\|^2 + \|\nabla \mathbf{n}(t)\|^2 \right) \right] \\
 & \quad + \mathbb{E} \int_0^t \Psi(s) \left[\|\nabla \mathbf{v}(s)\|^2 + \|\mathbf{A}_1 \mathbf{n}(s)\|^2 + 2\|\nabla \mathbf{n}(s)\|^2 \right] ds \\
 & \leq C \int_0^t \mathbb{E} \left[\Psi(s) \left(\|\mathbf{v}(s)\|^2 + \|\mathbf{n}(s)\|^2 + \|\nabla \mathbf{n}(s)\|^2 \right) \right] ds,
 \end{aligned}$$

from which along with Gronwall's inequality we infer that for any $t \in [0, T]$

$$\mathbb{E} \left(\Psi(t) \|\mathbf{v}(t)\|^2 + \|\mathbf{n}(t)\|^2 + \|\nabla \mathbf{n}(t)\|^2 \right) = 0.$$

□

4 Uniform estimates for the approximate solutions

This section is devoted to the crucial uniform estimates stated in Propositions 3.8 and 3.9.

Proof of Proposition 3.8 Let us note that for the sake of simplicity we write τ_m instead of $\tau_{R,m}$. Let $\Psi(\cdot)$ be the mapping defined by $\Psi(\mathbf{n}) = \frac{1}{2}\|\mathbf{n}\|^p$ for any $\mathbf{n} \in \mathbf{L}^2$. This mapping is twice Fréchet differentiable with first and second derivatives defined by

$$\begin{aligned} \Psi'(\mathbf{n})[\mathbf{g}] &= p\|\mathbf{n}\|^{p-2}\langle \mathbf{n}, \mathbf{g} \rangle, \\ \Psi''[\mathbf{g}, \mathbf{k}] &= p(p-2)\|\mathbf{n}\|^{p-4}\langle \mathbf{n}, \mathbf{k} \rangle \langle \mathbf{n}, \mathbf{g} \rangle + p\|\mathbf{n}\|^{p-2}\langle \mathbf{g}, \mathbf{k} \rangle. \end{aligned}$$

By straightforward calculations one can check that if $\mathbf{g} \in \mathbf{L}^2$ and $\mathbf{g} \perp_{\mathbb{R}^3} \mathbf{n}$ then $\Psi'(\mathbf{n})[\mathbf{g}] = 0$ and $\Psi''(\mathbf{n})[\mathbf{g}, \mathbf{g}] = p\|\mathbf{n}\|^{p-2}\|\mathbf{g}\|^2$.

Note that by the self-adjointness of $\hat{\pi}_m$ we have

$$\langle \hat{\pi}_m X_m, \mathbf{n}_m \rangle = \langle X_m, \mathbf{n}_m \rangle,$$

where $X_m \in \{G(\mathbf{n}_m), G^2(\mathbf{n}_m), \tilde{B}(\mathbf{v}_m, \mathbf{n}_m), f(\mathbf{n}_m)\}$. Thanks to Assumption 2.1 we also have

$$\hat{\pi}_m f(\mathbf{n}) = f(\mathbf{n}), \text{ for any } \mathbf{n} \in \mathbf{L}_m.$$

Since \mathbf{v}_m is a divergence free function it follows from lemma 6.1 that

$$\langle \hat{\pi}_m \tilde{B}(\mathbf{v}_m, \mathbf{n}_m), \mathbf{n}_m(t) \rangle = \langle \tilde{B}(\mathbf{v}_m, \mathbf{n}_m), \mathbf{n}_m \rangle = 0.$$

Now, applying Itô's formula to $\Psi(\mathbf{n}_m(t \wedge \tau_m))$ yields

$$\begin{aligned} \Psi(\mathbf{n}_m(t \wedge \tau_m)) &= \Psi(\mathbf{n}_m(0)) - \int_0^{t \wedge \tau_m} \Psi'(\mathbf{n}_m(s))[A\mathbf{n}_m(s)] \\ &\quad + \tilde{B}(\mathbf{v}_m(s), \mathbf{n}_m(s) + f(\mathbf{n}_m(s))] \\ &\quad + \frac{1}{2} \int_0^{t \wedge \tau_m} \left(\Psi'(\mathbf{n}_m(s))[G^2(\mathbf{n}_m(s))] + \Psi''(\mathbf{n}_m(s))[G(\mathbf{n}_m(s), G(\mathbf{n}_m(s)))] \right) ds \\ &\quad + \int_0^{t \wedge \tau_m} \Psi'(\mathbf{n}_m(s))[G(\mathbf{n}_m(s))] dW_2(s). \end{aligned}$$

The stochastic integral vanishes because $\mathbf{n}_m \times \mathbf{h} \perp \mathbf{n}_m$ in \mathbb{R}^3 and

$$\begin{aligned} \langle G(\mathbf{n}_m), \mathbf{n}_m \rangle &= \langle (\mathbf{n}_m \times \mathbf{h}), \mathbf{n}_m \rangle, \\ &= \langle \mathbf{n}_m \times \mathbf{h}, \mathbf{n}_m \rangle, \\ &= 0. \end{aligned}$$

Since \mathbf{v}_m is a divergence free function it follows from (6.10) that

$$\langle \tilde{B}(\mathbf{v}_m, \mathbf{n}_m), \mathbf{n}_m \rangle = 0.$$

From the identity

$$\langle (b \times a) \times a, b \rangle_{\mathbb{R}^3, \mathbb{R}^3} = -\|a \times b\|_{\mathbb{R}^3}^2,$$

we infer that

$$\begin{aligned} &\Psi'(\mathbf{n}_m)[G^2(\mathbf{n}_m)] + \Psi''(\mathbf{n}_m)[G(\mathbf{n}_m), G(\mathbf{n}_m)] \\ &= 2p\|\mathbf{n}_m\|^{2(p-1)} \left[\langle G^2(\mathbf{n}_m), \mathbf{n}_m \rangle + \|G(\mathbf{n}_m)\|^2 \right] \\ &= 0. \end{aligned}$$

Consequently,

$$\begin{aligned} \|\mathbf{n}_m(t \wedge \tau_m)\|^p &= \|\mathbf{n}_m(0)\|^p - p \int_0^{t \wedge \tau_m} \|\mathbf{n}_m(s)\|^{p-2} \|\nabla \mathbf{n}_m(s)\|^2 ds \\ &\quad - p \int_0^{t \wedge \tau_m} \|\mathbf{n}_m(s)\|^{p-2} \langle f(\mathbf{n}_m(s)), \mathbf{n}_m(s) \rangle ds. \end{aligned} \tag{4.1}$$

Now, by Assumption 2.1 that there exists a polynomial $\tilde{F}(r) = \sum_{l=1}^{N+1} b_l r^l$ with $\tilde{F}(0) = 0$ and $b_{N+1} > 0$ such that

$$\langle f(\mathbf{n}_m), \mathbf{n}_m \rangle = \int_{\mathcal{O}} \tilde{F}(|\mathbf{n}_m(x)|^2) dx.$$

In fact, it follows from Assumption 2.1 that

$$\begin{aligned} \langle \tilde{f}(|\mathbf{n}_m|^2) \mathbf{n}_m, \mathbf{n}_m \rangle &= \int_{\mathcal{O}} \tilde{f}(|\mathbf{n}_m(x)|^2) |\mathbf{n}_m(x)|^2 dx \\ &= \int_{\mathcal{O}} \sum_{k=0}^N a_k \left(|\mathbf{n}_m(x)|^2\right)^{k+1} dx \\ &= \int_{\mathcal{O}} \sum_{l=1}^{N+1} a_{l-1} \left(|\mathbf{n}_m(x)|^2\right)^l dx. \end{aligned}$$

Thanks to this observation we can use [8, Lemma 8.7] to infer that there exists $c > 0$ such that

$$\frac{a_{N+1}}{2} \int_{\mathcal{O}} |\mathbf{n}_m(x)|^{2N+2} dx - c \int_{\mathcal{O}} |\mathbf{n}_m(x)|^2 dx \leq \langle f(\mathbf{n}_m), \mathbf{n}_m \rangle.$$

From this estimate and (4.1) we deduce that there exists a constant $C > 0$ independent of $m \in \mathbb{N}$ such that

$$\begin{aligned} & \| \mathbf{n}_m(t \wedge \tau_m) \|^p + p \int_0^{t \wedge \tau_m} \| \mathbf{n}_m(s) \|^{p-2} \| \nabla \mathbf{n}_m(s) \|^2 ds \\ & + p \int_0^{t \wedge \tau_m} \| \mathbf{n}_m(s) \|^{p-2} \| \mathbf{n}_m(s) \|_{\mathbf{L}^{2N+2}}^{2N+2} ds \tag{4.2} \\ & \leq C \int_0^{t \wedge \tau_m} \| \mathbf{n}_m(s) \|^p ds + \| \mathbf{n}_m(0) \|^p, \end{aligned}$$

from which along with the fact that $\| \mathbf{n}_m(0) \| = \| \tilde{\pi}_m \mathbf{n}_0 \| \leq \| \mathbf{n}_0 \|$ and an application of the Gronwall lemma we complete the proof of our proposition. \square

Proof of Proposition 3.9 Let us note that for the sake of simplicity we write τ_m instead of $\tau_{R,m}$. By the self-adjointness of π_m we have

$$\langle \hat{\pi}_m Y_m, \mathbf{v}_m \rangle = \langle Y_m, \mathbf{v}_m \rangle,$$

where $Y_m \in \{B(\mathbf{v}_m, \mathbf{v}_m), M(\mathbf{n}_m, \mathbf{n}_m)\}$. A similar remark holds for those operators involving $\hat{\pi}_m$ (see the proof of Proposition 3.8).

Application of Itô’s formula to $\Phi(\mathbf{v}_m(t \wedge \tau_m)) = \frac{1}{2} \| \mathbf{v}_m(t \wedge \tau_m) \|^2, t \in [0, T)$, yields

$$\begin{aligned} & \frac{1}{2} \| \mathbf{v}_m(t \wedge \tau_m) \|^2 - \| \pi_m \mathbf{v}_0 \|^2 = - \int_0^{t \wedge \tau_m} \left\langle A \mathbf{v}_m(s) + B(\mathbf{v}_m(s)) + M(\mathbf{n}_m(s)), \mathbf{v}_m \right\rangle ds \\ & + \frac{1}{2} \int_0^{t \wedge \tau_m} \| S(\mathbf{v}_m) \|_{\mathcal{I}_2(\mathbb{K}_1, \mathbb{H})}^2 ds + \int_0^{t \wedge \tau_m} \langle \mathbf{v}_m(s), S(\mathbf{v}_m(s)) dW_1(s) \rangle. \tag{4.3} \end{aligned}$$

We now introduce the mapping Ψ defined by

$$\Psi(\mathbf{n}) = \frac{1}{2} \| \nabla \mathbf{n} \|^2 + \frac{1}{2} \int_{\mathcal{O}} F(|\mathbf{n}(x)|^2) dx, \mathbf{n} \in \mathbf{H}^1.$$

Thanks to Assumption 2.1 one can apply [8, Lemma 8.10] to infer that the mapping $\Psi(\cdot)$ is twice Fréchet differentiable and its first and second derivatives of Ψ are given by

$$\begin{aligned} \Psi'(\mathbf{n})\mathbf{g} &= \langle \nabla \mathbf{n}, \nabla \mathbf{g} \rangle + \langle f(\mathbf{n}), \mathbf{g} \rangle, \\ \Psi''(\mathbf{n})(\mathbf{g}, \mathbf{g}) &= \langle \nabla \mathbf{g}, \nabla \mathbf{g} \rangle + \int_{\mathcal{O}} \tilde{f}(\mathbf{n}) |\mathbf{g}|^2 dx + \int_{\mathcal{O}} [\tilde{f}'(\mathbf{n})][\mathbf{n} \cdot \mathbf{g}]^2 dx, \end{aligned}$$

for all $\mathbf{n}, \mathbf{g} \in \mathbf{H}^1$. Observe that if $\mathbf{g} \perp \mathbf{n}$ in \mathbb{R}^3 , then

$$\Psi''(\mathbf{n})(\mathbf{g}, \mathbf{g}) = \langle \nabla \mathbf{g}, \nabla \mathbf{g} \rangle + \int_{\mathcal{O}} \tilde{f}(\mathbf{n}) |\mathbf{g}|^2 dx.$$

Note also that

$$\Psi'(\mathbf{n})\mathbf{g} = \langle -A_1 \mathbf{n}, \mathbf{g} \rangle + \langle f(\mathbf{n}), \mathbf{g} \rangle,$$

for all $\mathbf{n} \in \mathbf{H}^2$ and $\mathbf{g} \in \mathbf{H}^1$. Before proceeding further we should also recall that it was proved in [8, Lemma 8.9] that there exists $\tilde{\ell} > 0$ such that

$$\|\nabla \mathbf{n}\|^2 + \|\mathbf{n}\|^2 \leq 2\Psi(\mathbf{n}) + \tilde{\ell}\|\mathbf{n}\|^2, \tag{4.4}$$

for any $\mathbf{n} \in \mathbf{H}^1$.

Now, by Itô's formula we have

$$\begin{aligned} & \Psi(\mathbf{n}_m(t \wedge \tau_m)) - \Psi(\hat{\pi}_m \mathbf{n}_0) \\ &= \int_0^{t \wedge \tau_m} \left(-\|A_1 \mathbf{n}_m(s) + f(\mathbf{n}_m(s))\|^2 + \frac{1}{2} \int_{\mathcal{O}} \tilde{f}(\mathbf{n}_m(s)) |G(\mathbf{n}_m(s))|^2 \right) ds \\ &+ \int_0^{t \wedge \tau_m} \left\langle \left(\frac{1}{2} G^2(\mathbf{n}_m(s)) - \tilde{B}(\mathbf{v}_m(s), \mathbf{n}_m(s)) \right), f(\mathbf{n}_m(s)) + A_1 \mathbf{n}_m(s) \right\rangle ds \\ &+ \frac{1}{2} \|\nabla G(\mathbf{n}_m(s))\|^2 + \langle G(\mathbf{n}_m(s)), f(\mathbf{n}_m(s)) + A_1 \mathbf{n}_m(s) \rangle dW_2(s), \end{aligned}$$

which is equivalent to

$$\begin{aligned} & \Psi(\mathbf{n}_m(t \wedge \tau_m)) - \Psi(\hat{\pi}_m \mathbf{n}_0) \\ &= \int_0^{t \wedge \tau_m} \left(-\|A_1 \mathbf{n}_m(s) + f(\mathbf{n}_m(s))\|^2 + \int_{\mathcal{O}} \tilde{f}(\mathbf{n}_m(s)) |G(\mathbf{n}_m(s))|^2 dx \right) ds \\ &+ \int_0^{t \wedge \tau_m} \left(\left\langle \frac{1}{2} G^2(\mathbf{n}_m(s)), f(\mathbf{n}_m(s)) + A_1 \mathbf{n}_m(s) \right\rangle - \langle \tilde{B}(\mathbf{v}_m(s), \mathbf{n}_m(s)), A_1 \mathbf{n}_m(s) \rangle \right) ds \\ &+ \frac{1}{2} \int_0^{t \wedge \tau_m} \|\nabla G(\mathbf{n}_m(s))\|^2 ds + \int_0^{t \wedge \tau_m} \langle G(\mathbf{n}_m(s)), f(\mathbf{n}_m(s)) + A_1 \mathbf{n}_m(s) \rangle dW_2(s). \end{aligned}$$

Here we used the fact that

$$\begin{aligned} \langle \mathbf{v}_m \cdot \nabla \mathbf{n}_m, f(\mathbf{n}_m) \rangle &= \sum_{i,j} \int_{\mathcal{O}} \mathbf{v}_m^{(i)}(x) \frac{\partial \mathbf{n}_m^{(j)}(x)}{\partial x_i} \tilde{f}(|\mathbf{n}_m(x)|^2) \mathbf{n}_m^{(j)}(x) dx \\ &= \frac{1}{2} \sum_{i=1}^d \int_{\mathcal{O}} \mathbf{v}_m^{(i)}(x) \frac{\partial \tilde{F}(|\mathbf{n}_m(x)|^2)}{\partial x_i} dx \\ &= \langle \mathbf{v}_m, \nabla \tilde{F}(|\mathbf{n}_m|^2) \rangle \\ &= 0, \text{ because } \operatorname{div} \mathbf{v}_m = 0. \end{aligned}$$

Now, let us observe that

$$\frac{1}{2} \left| \int_{\mathcal{O}} \tilde{f}(|\mathbf{n}_m(x)|^2) |G(\mathbf{n}_m(x))|^2 dx \right| \leq \frac{1}{2} \|\mathbf{h}\|_{\mathbb{L}^\infty}^2 \int_{\mathcal{O}} |\tilde{f}(|\mathbf{n}_m(x)|^2)| |\mathbf{n}_m(x)|^2 dx.$$

Next, by setting $\tilde{f}(r) = \sum_{k=0}^N b_k r^k$ with $b_k = |a_k|$, $k = 0, \dots, N$, we derive that there exists a polynomial \tilde{Q} of degree N such that

$$\tilde{f}(r)r = a_N r^{N+1} + \tilde{Q}(r).$$

From this last identity and the former estimate we derive that

$$\begin{aligned} & \frac{1}{2} \left| \int_{\mathcal{O}} \tilde{f}(|\mathbf{n}_m|^2) |G(\mathbf{n}_m)|^2 dx \right| \\ & \leq \frac{1}{2} \|\mathbf{h}\|_{\mathbb{L}^\infty}^2 \left[a_N \int_{\mathcal{O}} |\mathbf{n}_m(x)|^{2N+2} dx + \left| \int_{\mathcal{O}} \tilde{Q}(|\mathbf{n}_m(x)|^2) dx \right| \right], \end{aligned}$$

from which along with [8, Lemma 8.7] we deduce that there exists a constant $C > 0$ which depends only on $\|\mathbf{h}\|_{\mathbb{L}^\infty}$ such that

$$\frac{1}{2} \left| \int_{\mathcal{O}} \tilde{f}(|\mathbf{n}_m|^2) |G(\mathbf{n}_m)|^2 dx \right| \leq C \left(\int_{\mathcal{O}} F(|\mathbf{n}_m(x)|^2) dx + \|\mathbf{n}_m\|^2 \right).$$

Thus,

$$\frac{1}{2} \left| \int_{\mathcal{O}} \tilde{f}(|\mathbf{n}_m|^2) |G(\mathbf{n}_m)|^2 dx \right| \leq C \left(\Psi(\mathbf{n}_m) + \|\mathbf{n}_m\|^2 \right),$$

and

$$\begin{aligned} \Psi(\mathbf{n}_m(t \wedge \tau_m)) + \Psi(\hat{\tau}_m \mathbf{n}_0) & \leq \int_0^{t \wedge \tau_m} \left(-\|A_1 \mathbf{n}_m(s) + f(\mathbf{n}_m(s))\|^2 \right. \\ & \quad \left. + C \left[\Psi(\mathbf{n}_m(s)) + \|\mathbf{n}_m(s)\|^2 \right] \right) ds \\ & \quad + \int_0^{t \wedge \tau_m} \left(\left\langle \frac{1}{2} G^2(\mathbf{n}_m(s)), f(\mathbf{n}_m(s)) + A_1 \mathbf{n}_m(s) \right\rangle \right. \\ & \quad \left. - \langle \tilde{B}(\mathbf{v}_m(s), \mathbf{n}_m(s)), A_1 \mathbf{n}_m(s) \rangle \right) ds \\ & \quad + \frac{1}{2} \int_0^{t \wedge \tau_m} \|\nabla G(\mathbf{n}_m(s))\|^2 ds + \langle G(\mathbf{n}_m(s)), f(\mathbf{n}_m(s)) + A_1 \mathbf{n}_m(s) \rangle dW_2(s). \end{aligned} \tag{4.5}$$

Thanks to (2.10) we derive that

$$-\langle \tilde{B}(\mathbf{v}_m, \mathbf{n}_m), A_1 \mathbf{n}_m \rangle - \langle M(\mathbf{n}_m), \mathbf{v}_m \rangle = 0.$$

From Lemma 6.1 we also derive that

$$\langle B(\mathbf{v}_m, \mathbf{v}_m), \mathbf{v}_m \rangle = 0.$$

Thus, adding up inequality (4.3) and inequality (4.5) and using the last two identities we see that

$$\left[\Psi(\mathbf{n}_m) + \frac{1}{2} \|\mathbf{v}_m\|^2 \right] (t \wedge \tau_m) - \left[\Psi(\hat{\tau}_m \mathbf{n}_0) + \|\tau_m \mathbf{v}_0\|_{\mathbb{L}^2} \right]$$

$$\begin{aligned}
 & + \int_0^{t \wedge \tau_m} \left[\|\nabla \mathbf{v}_m(s)\|^2 - (\Psi(\mathbf{n}_m(s)) + \|\mathbf{n}_m(s)\|^2) \right] ds \\
 & \leq \frac{1}{2} \int_0^{t \wedge \tau_m} \left(-\|A_1 \mathbf{n}_m(s) + f(\mathbf{n}_m(s))\|^2 + \|S(\mathbf{v}_m(s))\|_{\mathcal{H}_2}^2 \right. \\
 & \quad \left. + \|G^2(\mathbf{n}_m(s))\|^2 + \|\nabla G(\mathbf{n}_m(s))\|^2 \right) ds \\
 & + \int_0^{t \wedge \tau_m} \langle \mathbf{v}_m(s), S(\mathbf{v}_m(s)) dW_1(s) \rangle + \langle G(\mathbf{n}_m(s)), f(\mathbf{n}_m(s)) + A_1 \mathbf{n}_m(s) \rangle dW_2(s).
 \end{aligned} \tag{4.6}$$

Since $G(\mathbf{n}_m) = \mathbf{n}_m \times \mathbf{h}$, we have

$$\begin{aligned}
 \|\nabla G(\mathbf{n}_m)\|^2 & \leq \|G(\mathbf{n}_m)\|_{\mathbf{H}^1}^2, \\
 & \leq \|\nabla(\mathbf{n}_m \times \mathbf{h})\|^2 + \|\mathbf{n}_m \times \mathbf{h}\|^2 \\
 & \leq 2[\|\nabla \mathbf{n}_m \times \mathbf{h}\|^2 + \|\mathbf{n}_m \times \nabla \mathbf{h}\|^2] + \|\mathbf{n}_m \times \mathbf{h}\|^2 \\
 & \leq C \|\mathbf{h}\|_{\mathbf{L}^\infty}^2 (\|\nabla \mathbf{n}_m\|^2 + \|\mathbf{n}_m\|^2) + \|\mathbf{n}_m \times \nabla \mathbf{h}\|^2.
 \end{aligned} \tag{4.7}$$

From Hölder’s inequality and the Sobolev embedding $\mathbf{H}^1 \subset \mathbf{L}^6$ (true for $d = 2, 3!$) we obtain

$$\begin{aligned}
 \|\mathbf{n}_m \times \nabla \mathbf{h}\|^2 & \leq \|\mathbf{n}_m\|_{\mathbf{L}^6}^2 \|\nabla \mathbf{h}\|_{\mathbf{L}^3}^2, \\
 & \leq c \left(\|\nabla \mathbf{n}_m\|^2 + \|\mathbf{n}_m\|^2 \right) \|\nabla \mathbf{h}\|_{\mathbf{L}^3}^2.
 \end{aligned}$$

By plugging this last inequality into (4.7), we infer the existence of a constant $C > 0$ which depend only on $\|\mathbf{h}\|_{\mathbf{W}^{1,3}}$ such that

$$\|\nabla G(\mathbf{n}_m)\|^2 \leq C(\|\nabla \mathbf{n}_m\|^2 + \|\mathbf{n}_m\|^2).$$

In a similar way one can prove that there exists $C > 0$ which depends only on $\|\mathbf{h}\|_{\mathbf{L}^\infty}$ such that

$$\|G^2(\mathbf{n}_m)\|^2 \leq C \|\mathbf{n}_m\|^2 \leq C \left(\|\nabla \mathbf{n}_m\|^2 + \|\mathbf{n}_m\|^2 \right).$$

From the last two estimates, (4.4) and the linear growth assumption (2.2) we derive that there exists a constant $C > 0$ such that

$$\begin{aligned}
 & \frac{1}{2} \left(\|S(\mathbf{v}_m)\|_{\mathcal{H}_2(K_1, H)}^2 + \|G^2(\mathbf{v}_m)\|^2 + \|\nabla G(\mathbf{n}_m)\|^2 \right) \\
 & \leq C \|\mathbf{v}_m\|^2 + 2C\Psi(\mathbf{n}_m) + \tilde{\ell}C \|\mathbf{n}_m\|^2.
 \end{aligned} \tag{4.8}$$

From this inequality and (4.6) we derive that there exists $C > 0$ such that

$$\mathbb{E} \sup_{s \in [0, t \wedge \tau_m]} \left[\Psi(\mathbf{n}_m(s)) + \frac{1}{2} \|\mathbf{v}_m(s)\|^2 \right]$$

$$\begin{aligned}
 & + \mathbb{E} \int_0^{t \wedge \tau_m} \left(\|\nabla \mathbf{v}_m(s)\|^2 + \frac{1}{2} \|\mathbf{A}_1 \mathbf{n}_m(s) + f(\mathbf{n}_m(s))\|^2 \right) ds \\
 & \leq C \mathbb{E} \int_0^{t \wedge \tau_m} \left[\|\mathbf{v}_m(s)\|^2 + \Psi(\mathbf{n}_m(s)) + \tilde{\ell} \|\mathbf{n}_m(s)\|^2 \right] ds \tag{4.9} \\
 & + \mathbb{E} \sup_{s \in [0, t \wedge \tau_m]} \left| \int_0^{s \wedge \tau_m} \langle \mathbf{v}_m(r), S(\mathbf{v}_m(r)) dW_1(r) \rangle \right| \\
 & + \mathbb{E} \sup_{s \in [0, t \wedge \tau_m]} \left| \int_0^{s \wedge \tau_m} \langle G(\mathbf{n}_m(r)), f(\mathbf{n}_m(r)) + \mathbf{A}_1 \mathbf{n}_m(r) \rangle dW_2(r) \right| \\
 & + \mathbb{E} \left(\frac{1}{2} \|\mathbf{v}_0\|^2 + \Psi(\mathbf{n}_m(0)) \right).
 \end{aligned}$$

Thanks to the Burkholder–Davis–Gundy, Cauchy–Schwarz and Cauchy inequalities we infer that

$$\begin{aligned}
 & \mathbb{E} \sup_{s \in [0, t \wedge \tau_m]} \left| \int_0^{s \wedge \tau_m} \langle G(\mathbf{n}_m(r)), f(\mathbf{n}_m(r)) + \mathbf{A}_1 \mathbf{n}_m(r) \rangle dW_2(r) \right| \\
 & \leq C \mathbb{E} \left(\int_0^{t \wedge \tau_m} [\langle G(\mathbf{n}_m(s)), \mathbf{A}_1 \mathbf{n}_m(s) + f(\mathbf{n}_m(s)) \rangle]^2 ds \right)^{\frac{1}{2}} \\
 & \leq C \mathbb{E} \left[\sup_{s \in [0, t \wedge \tau_m]} \|G(\mathbf{n}_m(s))\| \left(\int_0^{t \wedge \tau_m} \|\mathbf{A}_1 \mathbf{n}_m(s) + f(\mathbf{n}_m(s))\|^2 ds \right)^{\frac{1}{2}} \right] \\
 & \leq C \mathbb{E} \sup_{s \in [0, t \wedge \tau_m]} \|G(\mathbf{n}_m(s))\|^2 + \frac{1}{4} \mathbb{E} \int_0^{t \wedge \tau_m} \|\mathbf{A}_1 \mathbf{n}_m(s) + f(\mathbf{n}_m(s))\|^2 ds \\
 & \leq C \|\mathbf{h}\|_{\mathbf{L}^\infty}^2 \mathbb{E} \sup_{s \in [0, t \wedge \tau_m]} \|\mathbf{n}_m(s)\|^2 + \frac{1}{4} \mathbb{E} \int_0^{t \wedge \tau_m} \|\mathbf{A}_1 \mathbf{n}_m(s) + f(\mathbf{n}_m(s))\|^2 ds. \tag{4.10}
 \end{aligned}$$

By making use of a similar argument and (2.2) one can prove that

$$\begin{aligned}
 & \mathbb{E} \sup_{s \in [0, t \wedge \tau_m]} \left| \int_0^{s \wedge \tau_m} \langle \mathbf{v}_m(r), S(\mathbf{v}_m(r)) dW_1(r) \rangle \right| \leq \frac{1}{4} \mathbb{E} \sup_{s \in [0, t \wedge \tau_m]} \|\mathbf{v}_m(s)\|^2 \\
 & + C \mathbb{E} \int_0^{t \wedge \tau_m} \|\mathbf{v}_m(s)\|^2 ds. \tag{4.11}
 \end{aligned}$$

Note that from (4.4) we easily derive that $\|\mathbf{v}_m\|^2 + \|\mathbf{n}_m\|_{\mathbf{H}^1}^2 \leq \|\mathbf{v}_m\|^2 + 2\Psi(\mathbf{n}_m) + \tilde{\ell}\|\mathbf{n}_m\|^2$. Hence, using (4.10) and (4.11) in (4.9) we infer that

$$\begin{aligned} & \mathbb{E} \sup_{s \in [0, t \wedge \tau_m]} \left[\Psi(\mathbf{n}_m(s)) + \frac{1}{2} \|(\mathbf{v}_m(s))\|^2 \right] \\ & + \mathbb{E} \int_0^{t \wedge \tau_m} \left(\|\nabla \mathbf{v}_m(s)\|^2 + \frac{1}{2} \|\mathbf{A}_1 \mathbf{n}_m(s) + f(\mathbf{n}_m(s))\|^2 \right) ds \\ & \leq C \mathbb{E} \int_0^{t \wedge \tau_m} \left(\|\mathbf{v}_m(s)\|^2 + \Psi(\mathbf{n}_m(s)) \right) ds + C \varphi(t \wedge \tau_m), \end{aligned}$$

where $\varphi(\cdot)$ is the non-decreasing function defined by

$$\varphi(t) = \mathbb{E} \left(\|\mathbf{v}_0\|^2 + \Psi(\mathbf{n}_m(0)) \right) + \mathbb{E} \sup_{s \in [0, t]} \|\mathbf{n}_m(s)\|^2 + \mathbb{E} \int_0^t \|\mathbf{n}_m(s)\|^2 ds.$$

Now, it follows from Gronwall’s lemma that

$$\begin{aligned} & \mathbb{E} \sup_{s \in [0, t \wedge \tau_m]} \left[\Psi(\mathbf{n}_m(s)) + \frac{1}{2} \|(\mathbf{v}_m(s))\|^2 \right] \\ & + \mathbb{E} \int_0^{t \wedge \tau_m} \left(\|\nabla \mathbf{v}_m(s)\|^2 + \frac{1}{2} \|\mathbf{A}_1 \mathbf{n}_m(s) + f(\mathbf{n}_m(s))\|^2 \right) ds \\ & \leq \varphi(t \wedge \tau_m) \left(1 + T e^{CT} \right), \end{aligned}$$

which altogether with Proposition 3.8 completes the proof of Proposition 3.9 for the case $p = 1$.

For the case $p \geq 4N + 2$ we first observe that from (4.6) and (4.8) we easily see that

$$\begin{aligned} & \Psi(\mathbf{n}_m(t \wedge \tau_m)) + \tilde{\ell} \|\mathbf{n}_m(t \wedge \tau_m)\|^2 + \|\mathbf{v}_m(t \wedge \tau_m)\|^2 \\ & + \int_0^{t \wedge \tau_m} \left(2\|\nabla \mathbf{v}_m(s)\|^2 + \|\mathbf{A}_1 \mathbf{n}_m(s) + f(\mathbf{n}_m(s))\|^2 \right) ds \\ & \leq \Psi(\mathbf{n}_0) + \|\mathbf{v}_0\|^2 + \tilde{\ell} [\|\mathbf{n}_0\|^2 + \|\mathbf{n}_m(t \wedge \tau_m)\|^2] \\ & + C \int_0^{t \wedge \tau_m} \left(2\Psi(\mathbf{n}_m(s)) + \ell \|\mathbf{n}_m(s)\|^2 + \|\mathbf{v}_m(s)\|^2 \right) ds \\ & \left| \int_0^{t \wedge \tau_m} \langle \mathbf{v}_m(s), S(\mathbf{v}_m(s)) dW_1(s) \rangle \right| \\ & + \left| \int_0^{t \wedge \tau_m} \langle G(\mathbf{n}_m(s)), f(\mathbf{n}_m(s)) + \mathbf{A}_1 \mathbf{n}_m(s) \rangle dW_2(s) \right|. \end{aligned}$$

Second, rising both sides of this estimate to the power p and taking the supremum over $s \in [0, t \wedge \tau_m]$ and the mathematical expectation imply that there exists a constant $C > 0$ depending only in p such that

$$\mathbb{E} \sup_{s \in [0, t \wedge \tau_m]} [\psi(s)]^p - \mathbb{E}[\psi(0)]^p$$

$$\begin{aligned}
 & + \mathbb{E} \left[\int_0^{t \wedge \tau_m} \left(2 \|\nabla \mathbf{v}_m(s)\|^2 + \|A_1 \mathbf{n}_m(s) + f(\mathbf{n}_m(s))\|^2 \right) ds \right]^p \\
 \leq & C \mathbb{E} \sup_{t \in [0, T]} \|\mathbf{n}_m(t)\|^{2p} + CT \mathbb{E} \int_0^{t \wedge \tau_m} [\psi(s)]^p ds \tag{4.12} \\
 & + C \mathbb{E} \sup_{s \in [0, t \wedge \tau_m]} \left| \int_0^{s \wedge \tau_m} \langle \mathbf{v}_m(r), S(\mathbf{v}_m(r)) dW_1 \rangle \right|^p \\
 & + C \mathbb{E} \sup_{s \in [0, t \wedge \tau_m]} \left| \int_0^{s \wedge \tau_m} \langle G(\mathbf{n}_m(r)), f(\mathbf{n}_m(r)) + A_1 \mathbf{n}_m(r) \rangle dW_2 \right|^p,
 \end{aligned}$$

where, for the sake of simplicity, we have put

$$\psi(t) = \Psi(\mathbf{n}_m(t)) + \ell \|\mathbf{n}_m(t)\|^2 + \|\mathbf{v}_m(t)\|^2.$$

Now by making use of the Burkholder–Davis–Gundy, Cauchy–Schwarz, Cauchy inequalities and the linear growth assumption (2.2) we derive that

$$\begin{aligned}
 \mathbb{E} \sup_{s \in [0, t \wedge \tau_m]} \left| \int_0^{s \wedge \tau_m} \langle \mathbf{v}_m(r), S(\mathbf{v}_m(r)) dW_1 \rangle \right|^p & \leq C \mathbb{E} \left(\int_0^{t \wedge \tau_m} \|\mathbf{v}_m(s)\|^2 \|S(\mathbf{v}_m(s))\|_{\mathcal{L}_2}^2 ds \right)^{\frac{p}{2}} \\
 & \leq C \mathbb{E} \left[\sup_{s \in [0, t \wedge \tau_m]} [\psi(s)]^{\frac{p}{2}} \left(\int_0^{t \wedge \tau_m} (1 + \|\mathbf{v}_m(s)\|^2) ds \right)^{\frac{p}{2}} \right] \\
 & \leq \frac{1}{4} \mathbb{E} \sup_{s \in [0, t \wedge \tau_m]} [\psi(s)]^p + CT + C \mathbb{E} \int_0^{t \wedge \tau_m} [\psi(s)]^p ds. \tag{4.13}
 \end{aligned}$$

By using a similar argument we obtain

$$\begin{aligned}
 \mathbb{E} \sup_{s \in [0, t \wedge \tau_m]} \left| \int_0^{s \wedge \tau_m} \langle G(\mathbf{n}_m(r)), f(\mathbf{n}_m(r)) + A_1 \mathbf{n}_m(r) \rangle dW_2 \right|^p \\
 \leq C \mathbb{E} \left(\int_0^{t \wedge \tau_m} \|G(\mathbf{n}_m(s))\|^2 \|A_1 \mathbf{n}_m(s) + f(\mathbf{n}_m(s))\|^2 ds \right)^{\frac{p}{2}} \\
 \leq C \mathbb{E} \sup_{s \in [0, t \wedge \tau_m]} \|\mathbf{n}_m(s) \times \mathbf{h}\|^p + \frac{1}{2} \mathbb{E} \left(\int_0^{t \wedge \tau_m} \|A_1 \mathbf{n}_m(s) + f(\mathbf{n}_m(s))\|^2 ds \right)^p.
 \end{aligned}$$

From the last line we easily derive that

$$\begin{aligned}
 \mathbb{E} \sup_{s \in [0, t \wedge \tau_m]} \left| \int_0^{s \wedge \tau_m} \langle G(\mathbf{n}_m(r)), f(\mathbf{n}_m(r)) + A_1 \mathbf{n}_m(r) \rangle dW_2 \right|^p - C \mathbb{E} \sup_{s \in [0, t \wedge \tau_m]} \|\mathbf{n}_m(s)\|^{2p} \\
 \leq \frac{1}{2} \mathbb{E} \left(\int_0^{t \wedge \tau_m} \left(2 \|\nabla \mathbf{v}_m(s)\|^2 + \|A_1 \mathbf{n}_m(s) + f(\mathbf{n}_m(s))\|^2 \right) ds \right)^p. \tag{4.14}
 \end{aligned}$$

Plugging (4.13) and (4.14) in (4.12) yields that

$$\begin{aligned} & \mathbb{E} \sup_{s \in [0, t \wedge \tau_m]} [\psi(s)]^p + \mathbb{E} \left[\int_0^{t \wedge \tau_m} 2 \|\nabla \mathbf{v}_m(s)\|^2 + \|\mathbf{A}_1 \mathbf{n}_m(s) + f(\mathbf{n}_m(s))\|^2 ds \right] \\ & \leq 2\mathbb{E}[\psi(0)]^p + CT + C\mathbb{E} \sup_{s \in [0, t \wedge \tau_m]} \|\mathbf{n}_m(s)\|^{2p} + C(t \wedge \tau_m + 1)\mathbb{E} \int_0^{t \wedge \tau_m} [\psi(s)]^p ds, \end{aligned}$$

from which altogether with the Gronwall lemma implies that

$$\begin{aligned} & \mathbb{E} \sup_{s \in [0, t \wedge \tau_m]} [\psi(s)]^p + \mathbb{E} \left[\int_0^{t \wedge \tau_m} 2 \|\nabla \mathbf{v}_m(s)\|^2 + \|\mathbf{A}_1 \mathbf{n}_m(s) + f(\mathbf{n}_m(s))\|^2 ds \right] \\ & \leq \left[2\mathbb{E}[\psi(0)]^p + CT + C\mathbb{E} \sup_{s \in [0, t \wedge \tau_m]} \|\mathbf{n}_m(s)\|^{2p} \right] \left(1 + CT(T + 1)e^{C(T+1)T} \right). \end{aligned}$$

This along with (3.20) complete the proof of the proposition. □

5 Maximum principle type theorem

In this section we replace in the system (3.1)–(3.3) the general polynomial $f(\mathbf{n})$ by the bounded Ginzburg–Landau function $\mathbb{1}_{|\mathbf{n}| \leq 1} (|\mathbf{n}|^2 - 1)\mathbf{n}$. All our previous result remains true and the analysis are even easier. In the case $f(\mathbf{n}) = \mathbb{1}_{|\mathbf{n}| \leq 1} (|\mathbf{n}|^2 - 1)\mathbf{n}$, we will show that if the initial value \mathbf{n}_0 is in the unit ball, then so are the values of the vector director \mathbf{n} . That is, we must show that $|\mathbf{n}(t)|^2 \leq 1$ almost all $(\omega, t, x) \in \Omega \times [0, T] \times \mathcal{O}$. In fact we have the following theorem.

Theorem 5.1 *Assume that $d \leq 3$ and that a process $(\mathbf{v}, \mathbf{n}) = (\mathbf{v}(t), \mathbf{n}(t))_{t \in [0, T]}$, is a solution to problem (3.1)–(3.3) with initial condition $(\mathbf{v}_0, \mathbf{n}_0)$ such that $|\mathbf{n}_0|^2 \leq 1$ for almost all $(\omega, x) \in \Omega \times \mathcal{O}$. Then $|\mathbf{n}(t)|^2 \leq 1$ for almost all $(\omega, t, x) \in \Omega \times [0, T] \times \mathcal{O}$.*

Proof We follow the idea in [11, Lemma 2.1] and [16, Proof of Theorem 4, Page 513]. Let $\varphi : \mathbb{R} \rightarrow [0, 1]$ be an increasing function of class C^∞ such that

$$\begin{aligned} \varphi(s) &= 0 \text{ iff } s \in (-\infty, 1], \\ \varphi(s) &= 1 \text{ iff } s \in [2, +\infty). \end{aligned}$$

Let $\{\tilde{\varphi}_m : m \in \mathbb{N}\}$ and $\{\tilde{\phi}_m : m \in \mathbb{N}\}$ be two sequences of function \mathbb{R} defined by

$$\tilde{\varphi}_m(a) = \varphi(ma), \quad a \in \mathbb{R}, \tag{5.1}$$

$$\tilde{\phi}_m(a) = a^2 \varphi(ma), \quad a \in \mathbb{R}. \tag{5.2}$$

We also set

$$\varphi_m(\mathbf{u}) = \tilde{\varphi}_m(|\mathbf{u}|^2 - 1), \quad \mathbf{u} \in \mathbb{R}^3, \tag{5.3}$$

$$\phi_m(\mathbf{u}) = \tilde{\phi}_m(|\mathbf{u}|^2 - 1), \quad \mathbf{u} \in \mathbb{R}^3. \tag{5.4}$$

For each $m \in \mathbb{N}$ let $\Psi_m : \mathbf{H}^2 \rightarrow \mathbb{R}$ be a function defined by

$$\begin{aligned} \Psi_m(\mathbf{u}) &= \|\phi_m \circ \mathbf{u}\|_{\mathbf{L}^1}, \\ &= \int_{\mathcal{O}} \left(|\mathbf{u}(x)|^2 - 1 \right)^2 [\phi_m(\mathbf{u}(x))] dx, \quad \mathbf{u} \in \mathbf{H}^2. \end{aligned} \tag{5.5}$$

The mapping Ψ_m is twice (Fréchet) differentiable and its first and second derivatives satisfy

$$\begin{aligned} \Psi'_m(\mathbf{u})(\mathbf{k}) &= 4 \int_{\mathcal{O}} \left(|\mathbf{u}(x)|^2 - 1 \right) \phi_m(\mathbf{u}(x)) [\mathbf{u}(x) \cdot \mathbf{k}(x)] dx \\ &\quad + 2m \int_{\mathcal{O}} \left(|\mathbf{u}(x)|^2 - 1 \right)^2 \phi'_m \left(m \left(|\mathbf{u}(x)|^2 - 1 \right) \right) (\mathbf{u}(x) \cdot \mathbf{k}(x)) dx, \tag{5.6} \\ &\text{for } \mathbf{u} \in \mathbf{H}^2, \mathbf{k} \in \mathbf{L}^2, \end{aligned}$$

and,

$$\begin{aligned} \Psi''_m(\mathbf{u})(\mathbf{k}, \mathbf{f}) &= 4m^2 \int_{\mathcal{O}} \left[\left(|\mathbf{u}(x)|^2 - 1 \right)^2 \phi''_m \left(m \left(|\mathbf{u}(x)|^2 - 1 \right) \right) (\mathbf{u}(x) \cdot \mathbf{k}(x)) (\mathbf{u}(x) \cdot \mathbf{f}(x)) \right] dx \\ &\quad + 16m \int_{\mathcal{O}} \left[\left(|\mathbf{u}(x)|^2 - 1 \right) \phi'_m \left(m \left(|\mathbf{u}(x)|^2 - 1 \right) \right) (\mathbf{u}(x) \cdot \mathbf{k}(x)) (\mathbf{u}(x) \cdot \mathbf{f}(x)) \right] dx \\ &\quad + 8 \int_{\mathcal{O}} \left[\phi_m(\mathbf{u}(x)) (\mathbf{u}(x) \cdot \mathbf{k}(x)) (\mathbf{u}(x) \cdot \mathbf{f}(x)) \right] dx \\ &\quad + 2m \int_{\mathcal{O}} \left[\left(|\mathbf{u}(x)|^2 - 1 \right)^2 \phi'_m \left(m \left(|\mathbf{u}(x)|^2 - 1 \right) \right) (\mathbf{k}(x) \cdot \mathbf{f}(x)) \right] dx \\ &\quad + 4 \int_{\mathcal{O}} \left[\phi_m(\mathbf{u}(x)) \left(|\mathbf{u}(x)|^2 - 1 \right) (\mathbf{k}(x) \cdot \mathbf{f}(x)) \right] dx, \end{aligned}$$

for $\mathbf{u} \in \mathbf{H}^2$ and $\mathbf{k}, \mathbf{f} \in \mathbf{L}^2$. In particular, if $\mathbf{u} \in \mathbf{H}^2$ and $\mathbf{k}, \mathbf{f} \in \mathbf{L}^2$ are such that

$$\mathbf{k}(x) \perp \mathbf{u}(x) \text{ and } \mathbf{f}(x) \perp \mathbf{u}(x) \text{ for all } x \in \mathcal{O},$$

then

$$\Psi'_m(\mathbf{u})(\mathbf{k}) = 0, \tag{5.7}$$

and

$$\begin{aligned} \Psi''_m(\mathbf{u})(\mathbf{k}, \mathbf{f}) &= 4 \int_{\mathcal{O}} \left[\left(|\mathbf{u}(x)|^2 - 1 \right) \phi_m(\mathbf{u}(x)) (\mathbf{k}(x) \cdot \mathbf{f}(x)) \right] dx \\ &\quad + 2m \int_{\mathcal{O}} \left[\left(|\mathbf{u}(x)|^2 - 1 \right)^2 \phi'_m \left(m \left(|\mathbf{u}(x)|^2 - 1 \right) \right) (\mathbf{k}(x) \cdot \mathbf{f}(x)) \right] dx. \end{aligned} \tag{5.8}$$

It follows from Itô’s formula (see [37, Theorem I.3.3.2, Page 147]) that

$$d[\Psi_m(\mathbf{n})] = \Psi_m(\mathbf{n}) \left(-A_1 \mathbf{n} - \tilde{B}(\mathbf{v}, \mathbf{n}) - \frac{1}{\varepsilon^2} f(\mathbf{n}) + \frac{1}{2} G^2(\mathbf{n}) \right) dt + \frac{1}{2} \Psi_m''(\mathbf{n})(G(\mathbf{n}), G(\mathbf{n})) dt.$$

The stochastic integral vanishes because $G(\mathbf{n}) \perp_{\mathbb{R}^3} \mathbf{n}$. Since $G^2(\mathbf{n}) = (\mathbf{n} \times \mathbf{h}) \times \mathbf{h}$ and $G(\mathbf{n}) = \mathbf{n} \times \mathbf{h}$, we infer from (5.6) and the identity

$$-|a \times b|_{\mathbb{R}^3}^2 = a \cdot ((a \times b) \times b), a, b \in \mathbb{R}^3,$$

that

$$\Psi'(\mathbf{n})(G^2(\mathbf{n})) = -2m \int_{\mathcal{O}} (|\mathbf{n}(x)|^2 - 1) \varphi'(m(|\mathbf{n}(x)|^2 - 1)) |G(\mathbf{n}(x))|^2 dx - 4 \int_{\mathcal{O}} (|\mathbf{n}(x)|^2 - 1) \varphi_m(\mathbf{n}(x)) |G(\mathbf{n}(x))|^2 dx,$$

which along with the fact that $G(\mathbf{n}(x)) \perp \mathbf{n}(x)$ for any $x \in \mathcal{O}$ and (5.8) we infer that

$$\frac{1}{2} \Psi_m''(G(\mathbf{n}), G(\mathbf{n})) + \frac{1}{2} \Psi_m'(G^2(\mathbf{n})) = 0.$$

Hence

$$d[\Psi_m(\mathbf{n})] = \Psi_m(\mathbf{n}) \left(-A_1 \mathbf{n} - \tilde{B}(\mathbf{v}, \mathbf{n}) - \frac{1}{\varepsilon^2} f(\mathbf{n}) \right) dt. \tag{5.9}$$

Now, observe that from the assumptions on φ and the definition of $\tilde{\phi}_m, m \in \mathbb{N}$ we can show that for any $a \in \mathbb{R}$,

$$\tilde{\phi}_m(a) \rightarrow (a_+)^2 \text{ and } m\varphi'(ma) \rightarrow 0 \text{ as } m \rightarrow \infty, \tag{5.10}$$

where $a_+ := \max(a, 0)$. Observe also that there exists a constant $C > 0$ such that for all $m \in \mathbb{N}$ and $a \in \mathbb{R}$

$$|\tilde{\phi}_m(a)| \leq Ca^2 \text{ and } |m\varphi'(ma)| \leq C|a|. \tag{5.11}$$

We now easily infer from (5.10), (5.11) and the Lebesgue Dominated Convergence Theorem that for $\mathbf{u} \in \mathbf{H}^2, \mathbf{k} \in \mathbf{L}^2$

$$\lim_{m \rightarrow \infty} \Psi_m(\mathbf{u}) = \left\| \left(|\mathbf{u}|^2 - 1 \right)_- \right\|^2, \lim_{m \rightarrow \infty} \Psi'_m(\mathbf{u})(\mathbf{k}) = 4 \int_{\mathcal{O}} \left[\left(|\mathbf{u}(x)|^2 - 1 \right)_- (\mathbf{u}(x) \cdot \mathbf{k}(x)) \right] dx.$$

Hence, setting $y(t) = \|(|\mathbf{n}(t)|^2 - 1)_+\|^2$ we obtain from letting $\ell \rightarrow \infty$ in (5.9) that for almost all $(\omega, t) \in \Omega \times [0, T]$

$$y(t) - y(0) + 4 \int_0^t \left(\int_{\mathcal{O}} \left[A_1 \mathbf{n} + (\mathbf{v} \cdot \nabla) \mathbf{n} + \frac{1}{\varepsilon^2} f(\mathbf{n}) \right] \cdot \left[\mathbf{n} (|\mathbf{n}|^2 - 1)_+ \right] dx \right) ds = 0.$$

Let us set $\xi = (|\mathbf{n}|^2 - 1)_+$, it follows from [3, Exercise 7.1.5, p 283] that $\xi \in H^1$ if $\mathbf{n} \in \mathbf{H}^1$. Thus, since $\frac{\partial \mathbf{n}}{\partial \nu} = 0$ we derive from integration-by-parts that

$$4 \int_0^t \left(\int_{\mathcal{O}} A_1 \mathbf{n} \cdot \mathbf{n} (|\mathbf{n}|^2 - 1)_+ dx \right) ds = \int_0^t \left(\int_{\mathcal{O}} \left(2 \nabla(|\mathbf{n}|^2) \cdot \nabla \xi + 4 \xi |\nabla \mathbf{n}|^2 \right) dx \right) ds.$$

Since $\xi \geq 0$ and $|\nabla \mathbf{n}|^2 \geq 0$ a.e. $(t, x) \in \mathcal{O} \times [0, T]$ we easily derive from the above identity that

$$4 \int_0^t \left(\int_{\mathcal{O}} A_1 \mathbf{n} \cdot \mathbf{n} (|\mathbf{n}|^2 - 1)_+ dx \right) ds \geq 2 \int_0^t \left(\int_{\mathcal{O}} \nabla(|\mathbf{n}|^2 - 1) \cdot \nabla \xi dx \right) ds.$$

Thanks to [3, Exercise 7.1.5, p 283] we have

$$\int_0^t \left(\int_{\mathcal{O}} \nabla(|\mathbf{n}|^2 - 1) \cdot \nabla \xi dx \right) ds = \int_0^t \int_{\mathcal{O}} |\nabla(|\mathbf{n}|^2 - 1)|^2 \mathbb{1}_{\{|\mathbf{n}|^2 > 1\}} dx ds,$$

which implies

$$4 \int_0^t \left(\int_{\mathcal{O}} A_1 \mathbf{n} \cdot \mathbf{n} (|\mathbf{n}|^2 - 1)_+ dx \right) ds \geq \int_0^t \int_{\mathcal{O}} |\nabla(|\mathbf{n}|^2 - 1)|^2 \mathbb{1}_{\{|\mathbf{n}|^2 > 1\}} dx ds.$$

We also have

$$\begin{aligned} & 4 \int_0^t \left(\int_{\mathcal{O}} [(\mathbf{v} \cdot \nabla) \mathbf{n}] \cdot [\mathbf{n} (|\mathbf{n}|^2 - 1)_+] dx \right) ds \\ &= 2 \int_0^t \left(\int_{\mathcal{O}} [(\mathbf{v} \cdot \nabla)(|\mathbf{n}|^2)] [(|\mathbf{n}|^2 - 1)_+] dx \right) ds \\ &= \int_0^t \left(\int_{\mathcal{O}} (\mathbf{v} \cdot \nabla) \xi dx \right) ds \\ &= 0. \end{aligned}$$

Since $f(\mathbf{n}) = 0$ for $|\mathbf{n}|^2 > 1$ and $\xi f(\mathbf{n}) = 0$ for $|\mathbf{n}|^2 \leq 1$ we have

$$4 \int_0^t \left(\int_{\mathcal{O}} \xi f(\mathbf{n}) \cdot \mathbf{n} dx \right) ds = 0.$$

Therefore we see that $y(t)$ satisfies the estimate

$$y(t) + 2 \int_0^t \int_{\{|\mathbf{n}|^2 > 1\}} |\nabla(|\mathbf{n}|^2 - 1)_+|^2 ds \leq y(0),$$

for almost all $(\omega, t) \in \Omega \times [0, T]$. Since the second term in the left hand side of the above inequality is positive and $y(0) = \|(|\mathbf{n}_0|^2 - 1)_+\|^2$ and by assumption $|\mathbf{n}_0|^2 \leq 1$ for almost all $(\omega, t, x) \in \Omega \times [0, T] \times \mathcal{O}$ we derive that

$$y(t) = 0,$$

for almost all $(\omega, t) \in \Omega \times [0, T]$, $T \geq 0$. Hence we have $|\mathbf{n}|^2 \leq 1$ a.e. $(\omega, t, x) \in \Omega \times [0, T] \times \mathcal{O}$, $T \geq 0$. □

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6. Appendix: Some important estimates

In this section we recall or establish some crucial estimates needed for the proof of our mains results.

First, let $d \in [1, 4]$ and put $a = \frac{d}{4}$. Then the following estimates, valid for all $\mathbf{u} \in \mathbb{W}^{1,4}$, are special cases of Gagliardo–Nirenberg’s inequalities:

$$\|\mathbf{u}\|_{\mathbb{L}^4} \leq \|\mathbf{u}\|^{1-a} \|\nabla \mathbf{u}\|^a, \tag{6.1}$$

$$\|\mathbf{u}\|_{\mathbb{L}^\infty} \leq \|\mathbf{u}\|_{\mathbb{L}^4}^{1-a} \|\nabla \mathbf{u}\|_{\mathbb{L}^4}^a. \tag{6.2}$$

The inequality (6.1) can be written in the spirit of the continuous embedding

$$\mathbb{H}^1 \subset \mathbb{L}^4. \tag{6.3}$$

It follows from (6.2) and (6.3) that for $\mathbf{u} \in \mathbb{H}^2$

$$\|\mathbf{u}\|_{\mathbb{L}^\infty} \leq \|\mathbf{u}\|_1^{1-a} \|\mathbf{u}\|_2^a. \tag{6.4}$$

All these facts hold as well for the corresponding spaces \mathbf{L}^r , $r = 4, \infty$, and \mathbf{H}^ℓ , $\ell = 1, 2$. Next we give some properties of the bilinear form B and \tilde{B} defined in Sect. 2 (see Eqs. (2.3) and (2.4) on page 6, respectively).

Lemma 6.1 *The bilinear mapping $B(\cdot, \cdot)$ mappings continuously $\mathbf{V} \times \mathbb{H}^1$ into \mathbf{V}^* and*

$$\langle B(\mathbf{u}, \mathbf{v}), \mathbf{w} \rangle_{\mathbf{V}^*, \mathbf{V}} = b(\mathbf{u}, \mathbf{v}, \mathbf{w}), \text{ for any } \mathbf{u} \in \mathbf{V}, \mathbf{v} \in \mathbb{H}^1, \mathbf{w} \in \mathbf{V}, \tag{6.5}$$

$$\langle B(\mathbf{u}, \mathbf{v}), \mathbf{w} \rangle_{\mathbf{V}^*, \mathbf{V}} = -b(\mathbf{u}, \mathbf{w}, \mathbf{v}) \text{ for any } \mathbf{u} \in \mathbf{V}, \mathbf{v} \in \mathbb{H}^1, \mathbf{w} \in \mathbf{V}, \tag{6.6}$$

$$\langle B(\mathbf{u}, \mathbf{v}), \mathbf{v} \rangle_{\mathbf{V}^*, \mathbf{V}} = 0 \text{ for any } \mathbf{u} \in \mathbf{V}, \mathbf{v} \in \mathbf{V}, \tag{6.7}$$

$$\|B(\mathbf{u}, \mathbf{v})\|_{\mathbf{V}^*} \leq C_0 \|\mathbf{u}\|^{1-\frac{d}{4}} \|\nabla \mathbf{u}\|_{\frac{d}{4}} \|\mathbf{v}\|^{1-\frac{d}{4}} \|\nabla \mathbf{v}\|_{\frac{d}{4}}, \text{ for all } \mathbf{u} \in \mathbf{V}, \mathbf{v} \in \mathbb{H}^1. \tag{6.8}$$

Proof This lemma is well-known and we refer to [45, Chapter II, Section 1.2] for its proof. \square

With an abuse of notation, we again denote by $\tilde{B}(\cdot, \cdot)$ the restriction of $\tilde{B}(\cdot, \cdot)$ to $\mathbf{V} \times \mathbf{H}^2$.

Lemma 6.2 *The bilinear operator \tilde{B} mappings continuously $\mathbf{V} \times \mathbf{H}^2$ into \mathbf{L}^2 and there exists $C_1 > 0$ such that*

$$\|\tilde{B}(\mathbf{v}, \mathbf{n})\| \leq C_1 \|\mathbf{v}\|^{1-\frac{d}{4}} \|\nabla \mathbf{v}\|_{\frac{d}{4}} \|\nabla \mathbf{n}\|^{1-\frac{d}{4}} \|\nabla^2 \mathbf{n}\|_{\frac{d}{4}}, \text{ for any } \mathbf{v} \in \mathbf{V}, \mathbf{n} \in \mathbf{H}^2. \tag{6.9}$$

Moreover, we have

$$\langle \tilde{B}(\mathbf{v}, \mathbf{n}), \mathbf{n} \rangle = 0, \text{ for any } \mathbf{v} \in \mathbf{V}, \mathbf{n} \in \mathbf{H}^2. \tag{6.10}$$

Proof We can argue as in the proof of (6.8) (see also [45, Chapter II, Section 1.2]) to establish the estimate (6.9). The identity (6.10) easily follows by integration-by-parts and by taking into account that $\text{div } \mathbf{v} = 0$ and \mathbf{v} is zero on the boundary. \square

Remark 6.3 Using the same arguments as in the proof of Lemma 6.2 we can also prove that $B(\cdot, \cdot)$ mappings continuously $\mathbf{V} \times D(A)$ into \mathbf{H} . Furthermore, B satisfies (6.9) with $(\mathbf{v}, \mathbf{n}) \in \mathbf{V} \times \mathbf{H}^2$ replaced by $(\mathbf{u}, \mathbf{v}) \in \mathbf{V} \times D(A)$.

We finally close this appendix with the following lemma.

Lemma 6.4 *There exist some positive constants c_1 and c_2 such that for any $\mathbf{n}_i \in \mathbf{H}^3$, $i = 1, 2$ we have, with $a = \frac{d}{4}$,*

$$\begin{aligned} \|M(\mathbf{n}_1) - M(\mathbf{n}_2)\| \leq c_2 & \left(\|\mathbf{n}_1 - \mathbf{n}_2\|_2 \|\mathbf{n}_1\|_2^{1-a} \|\mathbf{n}_1\|_3^a \right. \\ & \left. + \|\mathbf{n}_1 - \mathbf{n}_2\|_2^{1-a} \|\mathbf{n}_1 - \mathbf{n}_2\|_3^a \|\mathbf{n}_2\|_2 \right). \end{aligned} \tag{6.11}$$

Note that we used the shorthand notation $M(\mathbf{n}) := M(\mathbf{n}, \mathbf{n})$.

Proof From elementary calculi we infer the existence of a constant $C > 0$ such that

$$\|M(\mathbf{f}, \mathbf{g})\| \leq C \|D^2\mathbf{f}\| \|\nabla\mathbf{g}\|_{\mathbf{L}^\infty} + C \|\nabla\mathbf{f}\|_{\mathbf{L}^4} \|D^2\mathbf{g}\|_{\mathbf{L}^4}.$$

Owing to the embedding (6.3) it is not difficult to check that

$$\|M(\mathbf{f}, \mathbf{g})\| \leq C \|\mathbf{f}\|_2 \left(\|\nabla\mathbf{g}\|_{\mathbf{L}^\infty} + \|D^2\mathbf{g}\|_{\mathbf{L}^4} \right).$$

Owing to (6.1) and (6.4) and the embedding (6.3) we obtain that

$$\|M(\mathbf{f}, \mathbf{g})\| \leq C \|\mathbf{f}\|_2 \|\mathbf{g}\|_2^{1-a} \|\mathbf{g}\|_3^a, \quad a = \frac{d}{4}. \tag{6.12}$$

Now, note that

$$M(\mathbf{n}_1) - M(\mathbf{n}_2) = M(\mathbf{n}_1 - \mathbf{n}_2, \mathbf{n}_1) + M(\mathbf{n}_2, \mathbf{n}_1 - \mathbf{n}_2).$$

From this last identity and (6.12) we easily deduce the inequality (6.11). This ends the proof of Lemma 6.4. □

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