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Early warning signals in plant disease outbreaks

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Abstract

Infectious disease outbreaks in plants threaten ecosystems, agricultural crops and food trade. Currently, several fungal diseases are affecting forests worldwide, posing a major risk to tree species, habitats and consequently ecosystem decay. Prediction and control of disease spread are difficult, mainly due to the complexity of the interaction between individual components involved. In this work, we introduce a lattice-based epidemic model coupled with a stochastic process that mimics, in a very simplified way, the interaction between the hosts and pathogen. We studied the disease spread by measuring the propagation velocity of the pathogen on the susceptible hosts. Our quantitative results indicate the occurrence of a critical transition between two stable phases: local confinement and an extended epiphytotic outbreak that depends on the density of the susceptible individuals. Quantitative predictions of epiphytotics are performed using the framework early-warning indicators for impending regime shifts, widely applied on dynamical systems. These signals forecast successfully the outcome of the critical shift between the two stable phases before the system enters the epiphytotic regime. Our study demonstrates that early-warning indicators could be useful for the prediction of forest disease epidemics through mathematical and computational models suited to more specific pathogen-host-environmental interactions. Our results may also be useful to identify a suitable planting density to slow down disease spread and in the future, design highly resilient forests.

Keywords:

Plant–pathogen interactions, Lattice model, Tree disease, Early-warning signals, Disease triangle, Plant pathology

1. Introduction

Invasive non-indigenous pathogens and vectors such as fungi, bacteria and insects pose a serious threat to trees and forest health worldwide. The re-

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9 cent and well-publicised outbreak of the ash dieback fungus (*Hymenoscyphus*
10 *pseudoalbidus*) and emerald ash borer (*Agrilus planipennis*) risks the survival
11 of the ash tree (*Fraxinus excelsior*) in the UK, one of the most abundant trees
12 in small woodlands and high forests across the country (Maskell et al., 2013;
13 Forest Research, 2016). At the same time, this fungus, threatens the ash tree
14 extinction across the European continent (Mitchell et al., 2014; Thomas, 2016;
15 Gross et al., 2013). The larch tree disease, caused by the fungus *Phytophthora*
16 *ramorum* (*P. ramorum*), continues to spread through conifer forests in both
17 Scotland and Wales, changing the landscape and forcing the Forestry Commis-
18 sion to fell thousands of hectares of trees to slow down the spread of the disease
19 (Forestry Commission, 2018a).

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28 Historically, these events cause catastrophic ecological, economic and social
29 impact, and motivate a detailed understanding of the mechanisms that underlie
30 the epidemics, from which strategies to manage and prevent future occurrences
31 can be developed systematically (Harwood et al., 2010). The propagation of
32 these infectious agents to the susceptible trees depends on a plethora of biologi-
33 cal, geographical, climatic and anthropological factors. In the literature, several
34 spatial models have been developed for forests diseases, that consider specific
35 factors aiding the dispersal of invasive pests, such as vectors (insects, humans)
36 or economical activities like the international plant trade and timber industry
37 (Macnadbay et al., 2004; Alfinito et al., 2016; Harwood et al., 2010). However,
38 these models, specifically designed to account for large geographical areas of
39 natural forests, are very complex and require a large amount of input data to
40 predict the disease spread.

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51 The forests in the United Kingdom and several parts of Europe have been
52 reshaped continually since the mid-Holocene due to anthropogenic factors (Ka-
53 plan et al., 2009). During the last centuries, the timber industry has left a
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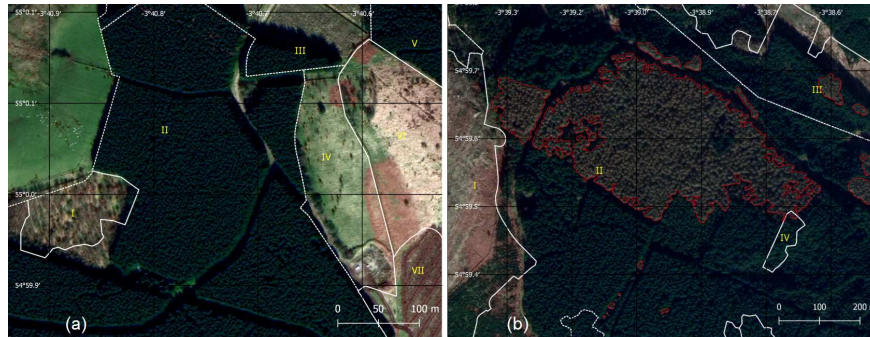


Figure 1: Woodland patches located in the Mabie Forest near Dumfries and Galloway, UK. (a) Monocultures of coniferous forests outlined according to the interpreted forest type (IFT) accounted in the National Forest Inventory Scotland 2016 (white dotted lines): I, young trees; II and V conifer trees; III and VII, felled area; IV, bare area and VI, grassland. Trees were planted at intervals of 2-3 m. (b) Coniferous forests with patches of trees infected with *P. ramorum* (red outline). The IFTs showed are I, felled trees; II, conifer trees, III, young trees and IV, broadleaved trees. Maps are shown in latitude/longitude coordinates and were obtained with QGIS 2.18 'Las Palmas', using ©2018 Google Satellite datasets. To account for the interpreted forest types we used the National Forest Inventories from Scotland (2016) (Forestry Commission, 2018b). Image analysis was done with ImageJ (Schneider et al., 2012).

characteristic homogeneous pattern in the woodland patches: forests managed for timber are usually planted in lines or curved lines. These patterns allow an efficient management and an even access to sunlight and nutrients; with all trees in the plantations being even-aged monocultures of conifer or broadleaved forests (Forestry Commission, 2017), see figure 1(left). However, the homogeneity in the trees diminishes the resilience of the forests to several threats, including forest diseases (Rist and Moen, 2013). Examples of this can be observed in the current outbreak of *P. ramorum* spreading in the Mabie Forest in Scotland, see figure 1(right), which consists mainly of coniferous forests with trees planted at the same time between 2-3 m of each other.

Mathematical modelling provides a powerful approach to understand, predict and counter-act disease propagation (Bate et al., 2016; Macpherson et al., 2017) with the advantage of fine-tuning the model to take into account specific attributes found in the forests. In this work we have developed an individual-based model in which trees are represented explicitly alongside their susceptibil-

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ity to disease and infectious status, to account for disease spread in terms of the tree density, a basic forest measurement calculated in the field. Our model is similar in nature to the forest fires and percolation lattice models widely investigated in the literature in which transmission occurs upon direct contact (Bak et al., 1990; Beer and Enting, 1990; Grassberger, 1993) and there is only spatial stochasticity. However, to consider the effect of a simultaneous presence of both spatial and temporal stochasticity we introduced a probability of transmission for the trees to catch the disease, which is not considered in the former models.

Early-warning indicators for abrupt changes in the behaviour of complex systems, group a set of statistical properties measured on parameters that change in unique ways before the occurrence of a catastrophic shift, (also known in the literature as tipping point or critical transition), which occurs when a system switches abruptly between alternate equilibria (Scheffer et al., 2009; Scheffer, 2009). These indicators are generic and suitable for application across many system types, even when the underlying system dynamics are poorly understood (Carpenter and Brock; Scheffer et al., 2009; Morales et al., 2015).

In ecosystems, early-warning methods have been used to predict the occurrence of desertification processes (Corrado et al., 2014), animal extinction in deteriorating environments (Drake and Griffen, 2010), behaviour of aquatic ecosystems (Gsell et al., 2016), and have been applied on climate models for the simulation of dieback on the Amazon rainforest (Boulton et al., 2013). Most recently, their applicability as an effective model to monitor tree mortality has been highlighted in Rogers et al. through satellite data. Therefore, their usefulness to predict changes on degradation processes for biological systems has increased in the literature during the last decade (Carpenter and Brock; Scheffer et al., 2009; Dakos et al., 2012; Litzow and Hunsicker, 2016; Ratajczak et al.). The main purpose behind these indicators is their effectiveness to identify prop-

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9 73 erties in an ecological system that would change significantly as it approaches
10 74 a tipping point between different stable states. However, this idea has been ap-
11 75 plied only to a handful of ecological problems due to the unavailability of data
12 76 sets, (Gsell et al., 2016; Litzow and Hunsicker, 2016; Ratajczak et al.).

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15 77 Following this premise, our interest lies in analysing the dynamics of disease
16 78 outbreaks under the scope of classical early-warning techniques using the tree
17 79 density as a state variable. This suggests applying the universality class and
18 80 scaling exponents—which have been widely studied in the literature (Bunde and
19 81 Havlin, 1996; Stauffer and Aharony, 2003)—to the prediction and detection of
20 82 the transition from the progression of the disease to an epiphytotic outbreak.

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23 83 The structure of the paper is as follows. In §2, we propose a simplified model
24 84 of a forest, in terms of susceptible, infected or removed individuals (SIR model)
25 85 which exhibits a phase transition above a percolation threshold (Grassberger,
26 86 1993; Clar et al., 1996; Bunde and Havlin, 1996). In §3, we show the results of
27 87 the simulations in which, we quantify the propagation velocity of the infection.
28 88 Then, we obtain the phase diagram of the contained-to-outbreak phases of the
29 89 system and study the behaviour of relevant parameters. Finally, in §4 we discuss
30 90 the meaning and implications of our findings.

31 91 **2. Materials and Methods**

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34 92 We model a forest as a regular square lattice of dimensions $L \times L$ where
35 93 $L = 500$, see Fig. 2(a-b). The forest landscape is flat and there is only one type
36 94 of vegetation, with the initial occupation of trees following a Bernoulli trial
37 95 according to a binomial distribution with mean ρL^2 , in which each trial has two
38 96 possible outcomes a tree or an empty space. Forest patches with monocultures
39 97 of trees with the same age that fulfill these characteristics can be found in
40 98 several regions in Scotland, UK, see figure 2(c), in which the trees planted every

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9 2-3 m are infected with *P. ramorum*.

10 Following this, in our model, each site can exist in one of four states: sus-
11 ceptible (S), infected (I), removed (R) and empty (\emptyset). Susceptible individuals
12 correspond to a single or several trees distributed randomly which can become
13 infected. An infected site, represents a patch of vegetation that has acquired a
14 terminal disease, a removed site corresponds to the space left by the infected site
15 after the vegetation dies, and empty sites correspond to regions in the landscape
16 where no susceptible vegetation can grow, see figure 2(a-b). The location of the
17 forest patches is constant in time, such that vegetation sites (either S , I or R)
18 are randomly distributed with a density ρ .

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109 Once a site in the S category acquires an infection, its status is changed to
110 I and a numerical label η is attached to it. η increases with time at a constant
111 pace, ranging from $-T$ to 0. Whereupon at $\eta = 0$, the tree at the site dies and
112 is removed, i.e., its status is changed to R . Henceforth, T corresponds to the
113 infectious period, that is, the time in which an infected tree can transmit the
114 infection.

115 After a tree is infected, it has a probability β of transmitting the disease to
116 a neighbouring susceptible site during the infectious period. In epidemiological
117 terms, the probability β is denoted as the transmissibility of the pathogen,
118 and it is defined as the probability per unit time that an S site acquires the
119 infection from a neighbouring I site. Therefore, for a healthy tree with n infected
120 neighbours, the probability of remaining unaffected at each time step is given
121 by $1 - (1 - \beta)^n$. For simplicity, the neighbourhood is defined by the first four
122 nearest neighbours in the lattice, i.e., a von Neumann neighbourhood.

123 We consider the limit in which the disease spreads in a much smaller time-
124 scale than the growth of the susceptible species. Moreover, after a patch of
125 forest has died, there exists the possibility of invasion from another species of

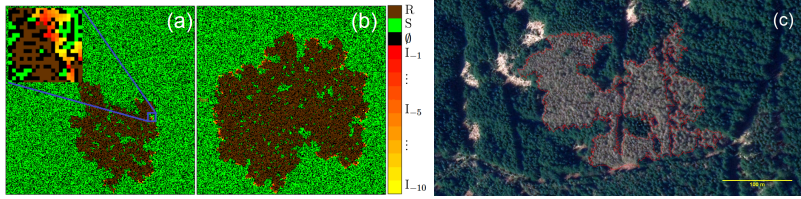


Figure 2: Typical final configurations of disease spread obtained for a system with $L = 500$, $\beta = 0.5$ and tree densities $\rho = 0.60$ (a) and 0.62 (b). Near the critical transition, slight changes in tree densities result in different spatial patterns of disease spread. *Inset*: Detail of the sites statuses with trees represented following the colour bar showed on the right: empty (\emptyset), susceptible (S), removed (R) and infected (I). The simulations were stopped after the disease dies out (a) or when it reached the edge of the system (b). (c) Patterns of disease spread (*P. ramorum*) on coniferous trees in the Mabie Forest near Dumfries, Scotland, UK. The total forest patch area is ~ 250 ha and the infected region ~ 2.5 ha. ©2018 Google Satellite datasets. Image analysis was done with ImageJ (Schneider et al., 2012).

126 plant, a phenomenon which has been observed in grass-woodland transitions
 127 (Abades et al.). As a consequence, it is unlikely that the woodland site regains
 128 susceptibility, and thus, we neglect any regenerative process in the simulations.

129 The parameters β and T regulate the evolution of the disease and both are
 130 relevant in the model; sampling from a suitable distribution for each parameter
 131 would allow to model levels of disease tolerance to the pathogen for each tree,
 132 since it has been identified that some plants exhibit little damage despite a high
 133 level presence of the pathogen (Gross et al., 2013).

134 For simplicity, in our simulations, we consider uniform values for β and T .
 135 This implies that we are free to set the time-scale by fixing a value for either
 136 variable. The time evolution of the landscape is carried out in discrete unitary
 137 time intervals. Therefore, by setting $T = 10$, a unitary time interval corresponds
 138 to $0.1T$. This leaves the average vegetation density, ρ , and the transmissibility
 139 of the pathogen, β , as the two free parameters.

140 3. Results

141 At the beginning of the simulation, the disease is introduced as a clump of
 142 infected trees at the centre of the domain of size 5×5 grid cells, with all trees

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9 143 infected inside this small area. This was found to be sufficient in order to avoid
10 144 extinction of the disease at initial stages. Under these conditions the transient
11 145 time, i.e., the time lapse that contains remnants of the initial conditions, was
12 146 found to be ~ 200 time steps. Since we are interested in the steady regime, we
13 147 discarded this transient from our final calculations. The simulations run until
14 148 the infected sites disappear or, in order to avoid boundary effects, when infected
15 149 sites reach any of the four sides. We carried out simulations over 10^4 ensemble
16 150 realisations, *i.e.* repetitions with different initial conditions with the same tree
17 151 density ρ .

18 152 As a first step, we quantify the effect of ρ and β in the simulations. At low
19 153 ρ , the infection quickly dies out, since the distribution of hosts is sparse. On the
20 154 other side, for higher densities, the epidemic spreads out, infecting most of the
21 155 trees. Nonetheless, for certain densities, the system shows a critical transition
22 156 between a self-limited outbreak and a large-scale epiphytotic outbreak.

23 157 In Fig. 2(a-b), we show the final configuration ($t \sim 600$ time-steps) of the
24 158 landscape for densities below and above the critical transition. Near the criti-
25 159 cal transition, the pathogen spreads through the domain generating branching
26 160 structures, and patches of surviving trees may remain unaffected. To highlight
27 161 this result, the Fig. 3 shows the spatio-temporal behaviour of the total number
28 162 of infected hosts, at every time step, found along the direction $N(L_y)$ as a func-
29 163 tion of their position along the L_x direction, following the same parameters as
30 164 in Fig. 2. For the first case, $\rho = 0.58$ the disease dies out after approximately
31 165 600 time steps, but the fractal-like behaviour of disease spread can be observed
32 166 as ramifications of infected trees even at a density $\rho = 0.6$. For higher densities
33 167 $\rho = 0.8$, this filamentary-like behaviour is lost and we observe a filled pattern
34 168 of infected trees. We find that a transition in the severity of the disease occurs
35 169 in the density interval $[0.56, 0.64]$.

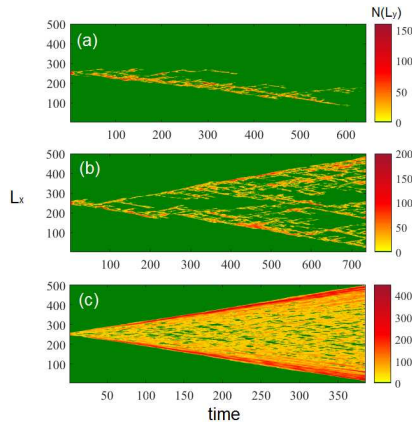


Figure 3: Spatio-temporal behaviour of the number of infected trees $N(L_y)$ along the height of the channel as a function of their location along width of the domain for the following tree densities ρ : (a) 0.58, (b) 0.60 and (c) 0.80. The colour bar shows the number of infected trees per line along L_y . The first two cases (a-b) correspond to values in the critical region $\rho \approx \rho_c$ and although the disease is spreading through the domain is not annihilating all susceptible hosts, since there are green sites interspersed with diseased trees. For $\rho = 0.8$ the number of infected individuals increases.

170 Near the critical transition, see figures 2(b) and 3(a-b), the disease does not
 171 annihilate all the trees, but rather spreads through the lattice as active clusters
 172 of diseased trees, interspersed with healthy individuals.

173 3.1. The Phase Diagram

174 The spreading of the disease has the effect of separating two domains, healthy
 175 susceptible trees, S , and dead trees, R by a transient interface of infected indi-
 176 viduals, I . In this model, the number of affected sites is on average, proportional
 177 to the landscape area where the infection has been present. By construction,
 178 this constant of proportionality is $1/\rho$, and thus, the proportion of affected
 179 woodland is

$$A = \frac{N}{\rho}, \quad (1)$$

180 where N is the sum of the I and R sites.

181 To quantify the observed dynamics in this system we calculated the spread

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9 182 dynamics of the disease through the lattice via the effective¹ velocity v of the
10 183 pathogen. On this basis of Eq. 1, a characteristic length-scale, $\mathcal{R} = N^{1/2}$,
11 184 measures of the radial extent of the disease. Thus, the rate of propagation of
12 185 the disease in the domain is measured through the velocity v , defined as the
13 186 change in \mathcal{R} , i.e.,

$$v(t) = N^{1/2}(t) - N^{1/2}(t-1). \quad (2)$$

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22 187 Therefore, Eq. 2 measures the spreading velocity in terms of the area of infected
23 188 trees in the domain. The time series of v is shown in Fig. 4(a-c); we will show
24 189 that the stochasticity observed in these time series gives valuable information
25 190 about the underlying dynamics when analysed in the framework of early warning
26 191 indicators for critical transitions.

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30 192 From the time series for the velocity, we obtain the time average of the
31 193 velocity \bar{v} . Figure 4(d) shows several probability distribution functions, $F(\bar{v})$,
32 194 obtained from all realisations, for densities $\rho = 0.58$ (1), 0.59 (2), 0.595 (3), 0.6
33 195 (4) and 0.62 (5). For $\rho < \rho_c$, the distribution shows a maximum for $\bar{v} \sim 0.01$,
34 196 see curve for $\rho = 0.58$. As the tree density increases, and approaches the critical
35 197 value, $\rho = 0.595$ and $\rho = 0.6$, $F(\bar{v})$ shows clearly that the system can be found in
36 198 either two states, one for $\bar{v} \approx 0$, which corresponds to local disease confinement
37 199 and another for $\bar{v} \neq 0$, or epiphytotic outbreak. Figure 4(e) shows a zoom-in
38 200 around the local maxima for $\rho = 0.595$ and 0.6. As the density increases, e.g.,
39 201 $\rho = 0.62$, the probability distribution function shows a single maximum for

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¹We use the term “effective” to emphasize that strictly the velocity cannot be defined in this way close to the critical density since the spanning cluster of diseased trees becomes fractal. It can be rigorously shown that the velocity with which the disease front propagates is given in 2D as $v \sim \xi^{1-d_f/d_\ell} \sim (p - p_c)^{0.16}$, with ξ denoting the correlation length, d_f and d_ℓ the fractal and graph dimensions respectively, (Bunde and Havlin, 1996). However, Eq. 2 provides a convenient measure of the rate of spread of the infection, through the epidemic extent or area, which is usually monitored through observational data, (Cowger et al., 2005; Mundt et al., 2013).

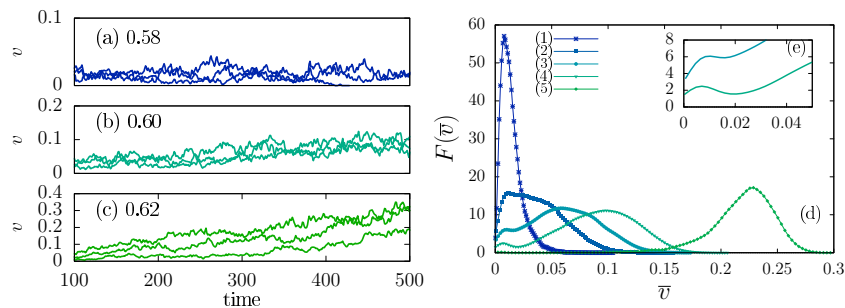


Figure 4: (a-c) Time series for the propagation velocity $v(t)$ for the following values of tree densities: (a) $\rho = 0.58$, (b) $\rho = 0.60$ and (c) $\rho = 0.62$. Three samples are showed for each density. The velocity increases as ρ is increased. (d) Probability distribution function $F(\bar{v})$ for the time averaged velocity \bar{v} obtained from 10^4 simulations, for densities ρ : (1) 0.58, (2) 0.59, (3) 0.595, (4) 0.6 and (5) 0.62. (e) Inset showing the For all cases $L = 500$ and $\beta = 0.5$.

202 $\bar{v} \approx 0.23$.

203 After taking the ensemble averages we obtain the mean propagation velocity
 204 $\langle \bar{v} \rangle$ as a function of the tree density ρ and various values of the transmission
 205 probability β . We identify from these results a critical density that separates
 206 the non-spreading to spreading phase of the disease. The existence of a critical
 207 density at ρ_c implies the existence of a spatially connected or spanning cluster
 208 of trees for disease spread. From these results, we conclude that this critical
 209 density ρ_c , is similar in nature to the critical percolation threshold observed in
 210 percolation theory (Stauffer and Aharony, 2003; Gandolfi, 2013; Saberi, 2015),
 211 since our computational model only involves a slight modification of the former.

212 In Fig. 5, we observe that the sole effect of the transmission probability
 213 $\beta = [0.1, 1]$ is a displacement of the critical point towards lower values of ρ .
 214 For low disease transmissibility, the density of trees has to be high to have
 215 a spanning cluster through the domain. As β increases, there is a chance of
 216 infecting more trees per infectious period (T) and consequently this cluster
 217 occurs at lower densities. Therefore, T, acting conjointly with β define the
 218 limiting value ρ_c . As β is increased, the critical transition should tend to the
 219 percolation threshold reported in the literature, $\rho_c \rightarrow 0.592746$ (Stauffer and

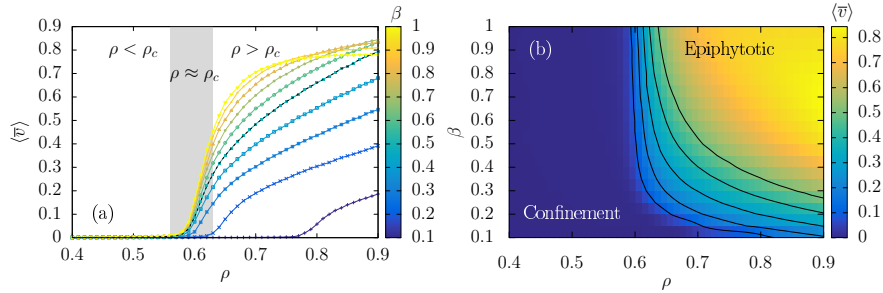


Figure 5: (a) Propagation velocity $\langle \bar{v} \rangle$ for the spread of a pathogen inside a grid with dimensions $L = 500$ as a function of tree density ρ and disease transmissibility β , following a Von Neumann neighbourhood. A shift between two stable states: infection confinement and an extended epiphytotic outbreak, occurs for $\rho \approx \rho_c$. A shaded region is shown for $\rho \sim \rho_c$, associated with the black dotted line highlighting the results for $\beta = 0.5$. (b) Phase space diagram for the pathogen dispersal on the grid, indicating region of disease containment and epiphytotics.

Aharony, 2003). However, since we are working on a finite-size domain, we expect that the critical transition is broadened relative to the result above for infinite-sized domains; in Fig. 5(a) we highlight this as a shaded region that divides density values according to a region where the critical shift occurs in our simulations (the black dotted line highlights the result for $\beta = 0.5$).

3.2. Catastrophic shifts in forest disease

A fundamental emergent property observed in systems near criticality is their capacity to extend over scales comparable to the size of the whole system at long times. Near the critical threshold, short-range interactions lead to the emergence of long-range correlations and the behaviour of the system changes abruptly between two alternative stable states, in this case, local containment and epiphytotics. The occurrence of this shift depends only on the local structure, in our case the density of susceptible hosts. Near the critical transition this system exhibits scale invariance, self-similarity and fractal properties. From the non-stationarity of the time series showed in Fig. 4(a-c) we can analyse the underlying dynamics through metric-based indicators proposed in the literature for the identification of early-warning signals: variance, skewness, kurtosis and

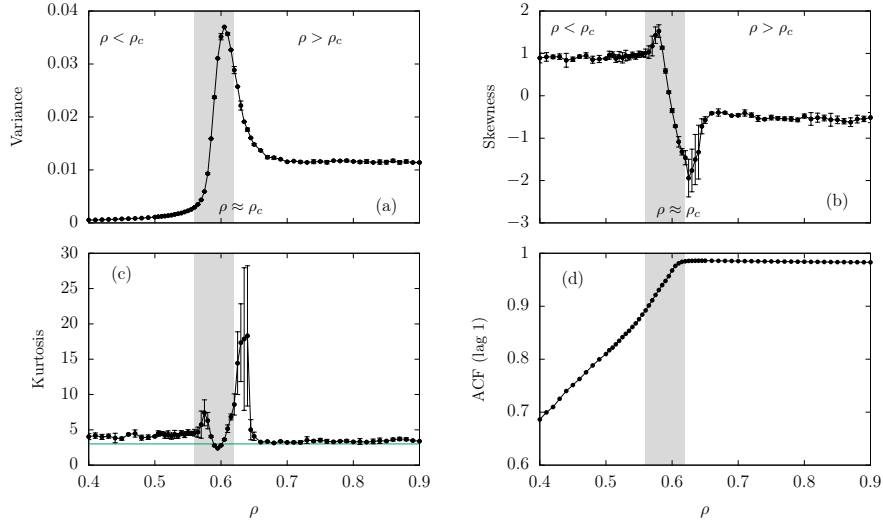


Figure 6: Ensemble behaviour for the metric-based indicators measured for the propagation velocity v of disease spread in the domain ($L = 500$, $\beta = 0.5$). Temporal variance (a), kurtosis (b), skewness (c) and autocorrelation function at lag $\tau = 1$, as a function of the tree density ρ . Three regimes are shown, with the shaded area corresponding to $\rho \approx \rho_c$.

autocorrelation function at lag 1 (Carpenter and Brock; Dakos et al., 2012; Morales et al., 2015).

Our goal is to predict the occurrence of a transition between disease containment and epiphytotics using the theory of catastrophic shifts, which in principle could be useful for the prediction of densities at which disease will spread in forests.

We quantify the stochastic variability of $v(t)$ from time series obtained for an ensemble of systems evolving for fixed $\beta = 0.5$ on a domain of size $L = 500$. Our interest was to study the variability in the spreading velocity as the density of trees crosses the critical region. From the probability distribution functions for $\langle \bar{v} \rangle$, we obtained the ensemble behaviour of the following statistical measures: variance (a), kurtosis (b), skewness (c) and autocorrelation function at lag 1 (d), see Fig. 6.

The variance, in Fig. 6(a), shows a rise around the critical point, the increase

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9 251 of this quantity is maximal, and its behaviour is different before the transition
10 252 occurs, for $\rho < \rho_c$ and after it has happened, $\rho > \rho_c$. The square-root of the
11 253 variance, the standard deviation, is maximal at the critical transition, which
12 254 for this finite-size system is $\rho^{\max} = 0.61$. Therefore, this quantity is useful as
13 255 an indicator for the prediction of a shift between the disease confinement and
14 256 epidemics.

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19 257 The skewness, defined as the third moment of the distribution, quantifies
20 258 the asymmetry of fluctuations in the time series. It is a useful measure for
21 259 the prediction of the catastrophic shift since its value changes before and after
22 260 the transition, depending on whether the system settles down to an alternative
23 261 state in which the disease propagation is larger or smaller than in the current
24 262 state, (Guttal and Jayaprakash; Dakos et al., 2012; Kéfi et al., 2014). Our
25 263 results clearly show both an increase and further decrease in the skewness, see
26 264 Fig. 6(b). For $\rho < \rho_c$ the skewness is positive and rises up as we approach the
27 265 critical region. For $\rho \sim \rho_c$, it decreases abruptly and changes sign, becoming
28 266 negative, i. e., the probability distribution is left-skewed. For higher density of
29 267 trees, we drive the system away from the critical region, the skewness changes
30 268 again, and becomes less negative until it settles near zero (≈ -0.5). Notably,
31 269 the rise in skewness observed at $\rho \sim 0.57$, associated with an increase in the
32 270 nonlinearities of the time series, predicts the outcome of the tipping point.
33 271 Moreover, this parameter identifies the tree densities for which the system is
34 272 found in either disease confinement (Skewness ≈ 1) and epiphytotics (Skewness
35 273 ~ 0).

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49 274 Strong perturbations can drive the state of a system to reach extreme val-
50 275 ues close to a transition. Therefore, the probability distribution function of the
51 276 propagation velocity may show a rise in the kurtosis before the transition is
52 277 reached. Figure 6(c) shows the plot of this quantity obtained in our simula-

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 9 278 tions. The distribution shows two peaks: a local maximum that corresponds to
 10 279 kurtosis values of 7.4 for $\rho \approx 0.57$, and a global maximum with kurtosis of 18.3
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 12 280 for $\rho \approx 0.64$. This indicates that, as the system approaches and exits the crit-
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 14 281 ical region, the distribution becomes more strongly peaked, than the reference
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 16 282 normal distribution, which has a kurtosis of 3 (blue continuous line), and thus,
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 18 283 is leptokurtic. This is consistent with an increased presence of rare values in
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 20 284 the propagation velocity. Interestingly, for values closer to the critical point, i.
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 22 285 e., $\rho = 0.59$, the kurtosis is 2.4, which is equivalent to a flattened or platykurtic
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 24 286 distribution. We conclude that the kurtosis is a good indicator to detect the
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 26 287 outcome of the transition.

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 27 288 The temporal autocorrelation function (ACF) measures the spectral prop-
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 29 289 erties and changes in the correlation structure, “memory”, of the time series
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 31 290 (Dakos et al., 2012). In a general way, the τ^{th} order ACF is defined accordingly
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 33 291 as,

$$ACF(\tau) = \frac{\sum_{t=\tau+1}^n (v_t - \bar{v})(v_{t-\tau} - \bar{v})}{\sum_{t=1}^n (v_t - \bar{v})^2}. \quad (3)$$

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 38 292 Following equation 3, we measured the temporal autocorrelation function at
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 40 293 lag 1 ($\tau = 1$) in our simulations. Several dynamical systems have shown a
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 42 294 slow recovery from small perturbations as they approach the critical transition,
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 44 295 phenomenon termed in the literature as “critical slowing down”. These systems
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 46 296 show an increase in the short-term memory of time series which can be detected
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 48 297 through an increase of the autocorrelation function at lag 1.

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 49 298 Figure 6(d) show the values for the temporal autocorrelation function at lag
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 51 299 1 measured for the time series of the velocity as a function of the tree density ρ .
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 53 300 For $\rho < \rho_c$, this quantity increases linearly as we increase the tree density and
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 55 301 reaches a maximum threshold inside the critical region for $\rho \geq 0.6$. This is an
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 57 302 indication that the system has become increasingly similar between consecutive

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9 303 observations. Since, for $\rho < \rho_c$ there is a fast increase on the ACF, this is useful
10 304 for the prediction of the outcome of the critical shift in the system.
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14 305 **4. Discussion**

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16 306 The most important question during risk assessment for a forest disease is
17 307 how pathogens will spread on the landscape, both to predict the occurrence of
18 308 an epiphytotic outbreak and to assist in designing interventions to counter the
19 309 onset and progression of the disease. In a real-life scenario, the dispersal of these
20 310 diseases is complex, mainly due to the multiple geographical and environmental
21 311 factors affecting the disease spread.
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27 312 Lattice-based epidemic models have been used previously in the literature to
28 313 study temporal and spatial fluctuations on the prevalence of epidemic diseases in
29 314 terms of the minimum tree density for an epidemic to occur (Rhodes and Ander-
30 315 son, 1996, 1997). The sessility of trees makes lattice modelling of plant diseases
31 316 more attainable through computational simulations. Works on disease propa-
32 317 gation using this framework coupled with historical, geographical and weather
33 318 information have been used to predict the spread of pathogens through forests
34 319 on a large scale (Xu et al.; Meentemeyer et al., 2010; Potter et al., 2011; Cobb
35 320 et al., 2012). These models certainly capture some of the features of previous
36 321 epiphytotics, and coupling them to the framework of early-warning indicators
37 322 for detecting critical transitions could be useful for designing strategies against
38 323 disease spread.
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48 324 The following characteristics need to be fulfilled for an epidemic to occur:
49 325 (i) a critical number of susceptible hosts, (ii) an aggressive phenotype of the
50 326 pathogen with a high transmissibility rate and (iii) suitable environmental con-
51 327 ditions for the pathogen survival. In this paper, we chose to study the effect of
52 328 the two first factors using a generic stochastic model of epidemic spread on a
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9 329 lattice with a von Neumann neighbourhood. Our model does not incorporate
10 330 a sophisticated computational description of the system; however it is useful,
11 331 as a first approximation, for the application of the framework of early warning
12 332 signals, used widely on complex systems, to reach a new understanding in plant
13 333 disease epidemics. This could aide in the identification of an optimal planting
14 334 tree density for the future design of forests, for example, the re-design of the
15 335 coniferous forests in Scotland, to diminish the impact of disease spread.

21 336 Simulations for different tree densities and pathogen transmission indicate a
22 337 system that shows two stable states: disease confinement and an extended epi-
23 338 phytotic outbreak. We chose to focus our investigations on densities that may
24 339 result in the system be found in either state. All the indicators measured fore-
25 340 cast the occurrence of the critical transition. We observe a rise in the variance,
26 341 skewness and the autocorrelation function at lag 1 as the system approaches
27 342 $\rho \sim \rho_c$. The skewness also shows a steep change from a positive to a negative
28 343 value in this region, consistent with the system traversing the critical region and
29 344 reaching a new stable state. Similarly, the kurtosis, changes from leptokurtic
30 345 to platykurtic and leptokurtic again in the critical region and immediately af-
31 346 terwards. Consequently, we conclude that all these measures are applicable to
32 347 predict a transition to epiphytotics.

42 348 Although our current scenario of applicability is a regular domain, far away
43 349 from the heterogeneous and complex landscapes found in tropical forests, we
44 350 hypothesize that their applicability to plant diseases could be fruitful in pre-
45 351 dicting the outcome of major disease outbreaks (Liang et al., 2017). In real
46 352 datasets, one of the first challenges would be to define a set of parameters and
47 353 coarse-grain the system description to an appropriate scale (spatial resolution of
48 354 the ecological data) to apply these indicators to predict a range of future states
49 355 of disease propagation.

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356 Currently, remote sensing technologies, such as satellites and aerial photog-
357 raphy are used widely to obtain forest measurements on changes of vegetation
358 index, droughts, fire damage and extent of disease propagation. This informa-
359 tion is periodically updated, which implies the availability of spatial datasets
360 taken at time intervals which could be useful to detect the approach to a tipping
361 point before it is crossed.

362 In a recent publication (Rogers et al.), several indicators such as the vari-
363 ance, standard deviation, kurtosis and skewness were measured on vegetation
364 indexes (NDVI) time series to detect threshold changes in which the loss of re-
365 siliance led to state shifts. Their results suggest that that early warning signals
366 of tree mortality are evident up to 24 years and therefore provide a foundation
367 for their potential application on long-term remote sensing data to effectively
368 monitor vegetation patterns and forecast changes in environmental conditions.
369 Moreover, a study on the quantification of forest fragmentation through aerial
370 images and numerical simulations using a lattice model have suggested that the
371 present state of the tropical forests is close to a critical point of percolation
372 (Taubert et al., 2018). Taken together these two studies indicate that the ap-
373 plication of the early warning indicators through a lattice model could serve to
374 model and quantify the fragmentation of forests.

375 Particularly, the UK has an advantageous position on GIS forest datasets
376 such as the National Forestry Inventory (NFI) (Forest Research, 2016), Light
377 Detection And Ranging (LiDAR) (Forest Research, 2004) and the National Tree
378 Map[®] (NTM)(Bluesky International Ltd, 2017), which give accurate informa-
379 tion about the woodland patches, 3D forest structure and location and canopy
380 extent of individual trees over 3 m in height, respectively. Moreover, the cur-
381 rently running SAPPHIRE project (Forest Research, 2018), a collaboration be-
382 tween Forest Research and Rezatec will provide precision maps of tree species

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383 and pinpoint trees that exhibit features of stress and disease. Combining all
384 these together, the applicability of early-warning indicators on a complex adap-
385 tive system, such as forests, could prove fruitful for devising their stability and
386 resilience to external conditions (such as disease propagation) before a regime
387 shift occurs.

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393 **Data accesibility**

394 This papers does not use data.

395 **Author Contributions**

396 SOF, NGP, RE, and AWB conceived the ideas and designed methodol-
397 ogy; SOF implemented the computational model and led the writing of the
398 manuscript. SOF and GG analysed the data. NGP and AWB acquired the
399 funding. All authors contributed critically to the drafts and gave final approval
400 for publication. The authors declare no conflicts of interest.

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