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Numerical Analysis of the Seepage-Deformation in Unsaturated 1 Soils 2 Enlong Liu^{1*}, Hai-Sui Yu², Gang Deng³, Jianhai Zhang¹, Siming He⁴ 3 ¹ State Key Laboratory of Hydraulics and Natural River Engineering, College of Water Resource and 4 Hydropower, Sichuan University, Chengdu, P.R. China 610065; 5 ²Nottingham Centre for Geomechanics, University of Nottingham, NG7 2RD, UK; 6 7 ³State Key Laboratory of Simulation and Regulation of Water Cycle in River Basin, China Institute of Water Resources and Hydropower Research, Beijing 100048, P.R. China; 8 ⁴ Institute of Mountain Hazards and Environment, CAS, Chengdu 610041, P.R. China. 9 10 *Corresponding author: Enlong Liu, Email: <u>liuenlong@scu.edu.cn</u> 11 Abstract: A coupled elastic-plastic finite element analysis based on simplified consolidation 12 theory for unsaturated soils is used to investigate the coupling processes of water infiltration and 13 deformation of unsaturated soil. By introducing a reduced suction and an elastic-plastic 14 constitutive equation for the soil skeleton, the simplified consolidation theory for unsaturated 15 soils is incorporated into an in-house finite element method code. Using the numerical method 16 proposed here, the generation of pore water pressure and development of deformation can be 17 simulated under evaporation or rainfall infiltration conditions. Through a parametric study and 18 comparison with the test results, the proposed method is found to describe well the 19 characteristics during water evaporation/infiltration into unsaturated soils. Finally, an 20 unsaturated soil slope with water infiltration is analyzed in detail to investigate the development 21 of the displacement and generation of pore water pressure. 22 Keywords: unsaturated soil, water infiltration, seepage-deformation coupled analysis, finite 23 element method. Introduction 24

There are currently many geotechnical engineering problems that are related to unsaturated soils, such as rainfall induced slope failure and expansive soils. For embankment and slope engineering, failures are usually induced by rainfall infiltration because water infiltration will result in an increase in saturation and a change in the distribution of pore-water pressure, which in turn leads to a change in the stress and deformation of a soil. The change of stress and deformation, contrarily, affects the seepage process by modifying the hydraulic properties of porosity and permeability of the soil. Based on these results, it is necessary to conduct a coupled analysis of water infiltration and deformation to study the failure mechanism of unsaturated soil engineering; such a coupled analysis is becoming more important [16].

33 Many experimental studies have been conducted to investigate the coupling interactions of flow through 34 unsaturated soils with rainfall infiltration. Columns composed of sandy materials have been tested to 35 investigate the leakage as a result of download drainage from an initially saturated state [23], and a new soil 36 column apparatus for laboratory infiltration study was developed that can measure all the variables (pore-37 water pressures, water contents, inflow rate and outflow rate) instantaneously and automatically in an 38 infiltration process by control of all the boundary conditions [36]. Because more layered soils are 39 encountered than uniform soils in geotechnical engineering, infiltration in layered soils has drawn much 40 attention and has been studied by many researchers [30, 33]. The laboratory test results of vertical 41 infiltration in two soil columns of finer over coarse soils subjected to simulated rainfalls under conditions 42 of no-ponding at the surface and a constant head at the bottom have been presented [37], and an 43 experimental device used to investigate the transient unsaturated-saturated hydraulic response of sand-44 geotextile layers under conditions of 1-D constant head surface infiltration have been discussed in detail 45 [4]. In addition to laboratory experiments, in-situ tests have been performed to observe the flow through 46 unsaturated soil masses. For example, studies were performed under natural and simulated rainfall on a 47 residual soil slope in Singapore [28] that was instrumented with pore water pressure, water content, and 48 rainfall measuring devices.

Rainfall infiltration into unsaturated soils has also been analyzed by analytical solutions for simple initial and boundary conditions. Ignoring the coupling effects of flow and deformation, Morel-Seytoux [25, 26] obtained an analytical solution by using Green and Ampt's infiltration equation as a basic equation, Basha [2, 3] derived multidimensional non-steady solutions for domains with prescribed surface flux boundary conditions and bottom boundary conditions by using Green's function, and Chen et al. [11] obtained a series solution that has the merit of easy calculation by using a Fourier integral transformation. To improve the understanding of the influence of hydraulic properties and rainfall conditions on rainfall infiltration 56 mechanism and hence on the pore-water pressure distributions in single- and two-layer unsaturated soil 57 systems, an analytical parametric study was performed [38]. Based on Fredlund's incremental-linear elastic 58 constitutive model for unsaturated soil, the analytical solution to a one-dimensional coupled water 59 infiltration and deformation problem by a Fourier integral transform was obtained; the results indicated that 60 the volume change due to a change in soil suction and the ratio of rainfall intensity to saturated 61 permeability has a significant effect on the distribution of the negative pore water pressure and 62 deformations along the soil profile [35]. By assuming that the vertical loading varies exponentially with 63 time, an analytical solution to one-dimensional consolidation in unsaturated soils with a finite thickness 64 under confinement in the lateral direction was also presented [29].

65 Recently, to address complicated initial and boundary conditions, numerical solutions have been used to 66 analyze the soil engineering related to unsaturated soils. Using the modified Mohr-Coulomb failure criterion [12], the process of infiltration into a slope due to rainfall and its effect on soil slope behavior 67 68 were examined using a two-dimensional finite element flow-deformation coupled analysis program. The 69 finite element analysis of transient water flow through unsaturated-saturated soils [10] was used to 70 investigate the effects of the hydraulic characteristics, the initial relative degree of saturation, the methods 71 used to consider boundary conditions, and the rainfall intensity and duration on the water pressure in the 72 slopes. The elasto-plastic finite element model [18] in conjunction with a novel analytical formulation for 73 the suction stress above the water table were used to analyze the unsaturated slope stability. A seepage-74 deformation coupled approach [15] including the effective pore-pressure and the effective stress concept 75 was used to analyze the deformation and the localization of strains on unsaturated soils due to seepage flow. 76 The net stress concept [1] was used to compute the deformations and the variation of the safety factor with 77 time of an unstable slope in a profile of weathered overconsolidated clay using an unsaturated coupled 78 hydromechanical model. Based on the theory of porous media [17], a multiphase coupled elasto-79 viscoplastic finite-element analysis formulation was used to describe the rainfall infiltration process into a 80 one-dimensional soil column, which demonstrates that the generation of pore water pressure and 81 volumetric strain is mainly controlled by material parameters that describe the soil-water characteristic 82 curve. Based on the existing hydro-mechanical model for non-expansive unsaturated soil, an elastoplastic 83 constitutive model was developed for predicting the hydraulic and mechanical behavior of unsaturated

84 expansive soils [34]. To consider the spatial variability of the properties of the materials of the soil deposits, 85 a stochastic finite element model of unsaturated seepage through a flood defense embankment with 86 randomly heterogeneous material was presented [22]. The stochastic finite element model was also used to 87 simulate the contaminant transport through soils, focusing on the incorporation of the effects of soil 88 heterogeneity [27]. Recently, Borja et al. proposed a physical-based hydro-mechanical continuum model 89 and employed a finite element method to study the series of properties of unsaturated soils, which included 90 the following: (i) the stresses, pore pressures, and deformation within a slope were generated, and then the 91 factor of safety was determined with a limit-equilibrium solution [6]; (ii) the 3-D multi-physical aspects 92 triggering landslides were quantified by accounting for the loss of sediment strength due to increased 93 saturation as well as the frictional drag exerted by the moving fluid [7]; (iii) the effect of the spatially 94 varying degree of saturation on triggering a shear band in granular materials was investigated with new 95 variational formulations for porous solids and two critical state formulations [8]; and (iv) a mathematical 96 framework for a coupled solid-deformation/fluid-diffusion model in unsaturated porous material considering 97 geometric nonlinearity in the solid matrix was developed that relies on the continuum principle of 98 thermodynamics to identify an effective or constitutive stress for the solid matrix, along with a water-retention 99 law that highlights the interdependence of the degree of saturation, suction, and porosity of the material [32].

100 From the relevant works mentioned above, we know that the coupling processes of water infiltration and 101 deformation of unsaturated soils is an interesting topic that has not yet been fully studied. Solving the 102 problems of unsaturated soil engineering requires slightly simplifying the general consolidation theory for 103 unsaturated soil, which has so many unknowns [13, 20] and has been implemented using numerical 104 methods by only a few researchers. By introducing reduced suction and an elastic-plastic constitutive 105 equation for the soil skeleton, a coupled elastic-plastic finite element analysis based on simplified 106 consolidation theory for unsaturated soils [14, 31], compared with the general or standard consolidation 107 theory for unsaturated soils, is used here to investigate the coupled processes of water infiltration and 108 deformation of unsaturated soil. The generation of pore water pressure and deformation is simulated under 109 rainfall infiltration conditions and then compared with the experimental results, which enables the detailed 110 analysis of an unsaturated soil slope with water infiltration to investigate the development of displacement 111 and generation of pore water pressure.

4

112 Simplified consolidation theory for unsaturated soils

113 Effective stress

The formulation is based firmly within the context of Terzaghi's classical effective stress theory as modified for unsaturated soils by Bishop [5] in the form:

116 $\sigma' = \sigma - \mathbf{u}_{a} + \chi(\mathbf{u}_{a} - \mathbf{u}_{w}), \qquad (1)$

117 in which σ' and σ are the effective and total stress, respectively, u_a is the air pressure in the voids, and

118 u_w is the pore water pressure within the unsaturated soil matrix. The term $s = (u_a - u_w)$ is called the

119 matrix suction. We define the reduced suction \overline{s} by the following expression [31]:

120 $\overline{\mathbf{s}} = \chi(\mathbf{u}_{\mathrm{a}} - \mathbf{u}_{\mathrm{w}}). \tag{2}$

121 So we have $\chi = \overline{s} / s$, called the coefficient of reduced suction. As shown in Fig. 1, the reduced suction 122 can be determined by comparing the results of the compression curve of saturated soils with those of the 123 drying shrinkage curve of the unsaturated soils. Assuming p and s are the pressure sustained by saturated 124 soils and matrix suction induced in the unsaturated soils with the same void ratio, respectively, we have $\overline{s} = p$ by the equivalent strain theory, so the coefficient of reduced suction can be described by the 125 126 expression: $\chi = p/s$. Under the general stress state, the coefficient of reduced suction χ is a function of 127 the suction s. When the suction is smaller than the air entry value s_b , the coefficient of reduced suction is 128 equal to unity; when suction is smaller than the air entry value s_b , the coefficient of reduced suction varies 129 with the matrix suction in the manner proposed here as follows:

130 $\chi = \left(\frac{s}{s_{\rm b}}\right)^{-m_2},\tag{3}$

131 in which $s_b = (u_a - u_w)_b$ and m_2 is a materials constant.

132 **Pore air pressure**

133 To signify the air content (air mass) in the voids of a soil element within a unit volume, we define the ratio

134 of the pore air of a unit soil element, \mathbf{n}_{a} , as follows (see appendix I):

135
$$n_a = [1 - (1 - c_h)S_r]n,$$
 (4)

136 in which n is the porosity, c_h is the Henry coefficient of solubility and S_r is the degree of saturation of the

soil element. Based on Boyle's law, the density of air in the void ρ_a can be obtained:

138
$$\rho_{\rm a} = \rho_{\rm a0} (1 + u_{\rm a} / p_{\rm a}),$$
 (5)

139 in which, ρ_{a0} is the initial density of air in the void, u_a is the excess air pressure above the reference datum

140 p_a , which is the atmospheric pressure that is equal to 1.01×10^5 Pa, and $u_a + p_a$ is the absolute air

141 pressure. Under the conditions that the air in the voids cannot be discharged, we have (see Appendix II):

142
$$\mathbf{u}_{a} = \left(\frac{\mathbf{n}_{a0}}{\mathbf{n}_{a}} - 1\right) \mathbf{p}_{a}, \tag{6}$$

in which, $\mathbf{n}_{a0} = [1 - (1 - c_h)S_{r0}]\mathbf{n}_0$, S_{r0} is the initial degree of saturation, and \mathbf{n}_0 is the initial porosity.

144 If the pore air within the soil element can be discharged freely (that is, the excess pore air could be 145 completely discharged), the pore air pressure generated will finally dissipate and is equal to the 146 atmospheric pressure ($u_a = 0$). By Boyle's law, because the pore air pressure remains constant, the 147 density of the pore air will remain constant. Under these conditions, to dissipate the pore air pressure 148 completely, the change of the volume of the pore air within a unit soil element per unit time is Δn_a , so the 149 mass of the pore air discharged within a unit soil element per unit time is $\rho_a \Delta n_a$.

Under the conditions that the air in the voids is discharged partially, it is assumed that the mass of air discharged per unit time is Δq_a , so we define the discharge speed of pore air, ξ , which is the ratio of the mass of the pore air under discharged partially per unit time to that of the pore air discharged completely per unit time, as follows:

154
$$\xi = \frac{\Delta q_a}{\rho_a \Delta n_a}.$$
 (7)

155 So we can obtain the expression of the increment of pore-air pressure as follows (see Appendix III):

156
$$\Delta u_{a} = -\frac{p_{a} + u_{a}}{n_{a}} (1 - \xi) \Delta n_{a}.$$
(8)

157 If ξ is constant, by integrating equation (8), we obtain the expression of u_a as follows (see Appendix IV):

158
$$\mathbf{u}_{a} = [(\frac{\mathbf{n}_{a0}}{\mathbf{n}_{a}})^{(1-\xi)} - 1]\mathbf{p}_{a}.$$
(9)

159 When ξ is equal to 0, the equation (9) can be reduced to equation (6); when ξ is equal to 1, $u_a = 0$,

160 which corresponds to the conditions that the air is discharged completely.

161 **Governing equations**

162 Ignoring the flow of dissolved air in the pore-water, the vapor in the pore-air and the influence of temperature, the consolidation equations for unsaturated soils have the following expressions [31]: 163 164 ① Equilibrium equations in incremental form $[L]{d\sigma} + {db} = 0,$ 165 (10)166 2 Continuous equations of pore-water 167 $\frac{\partial}{\partial t}(S_r n) = div \left[k_w grad \left(\frac{u_w}{\rho_w g} + z \right) \right],$ 168 169 (11)170 ③ Continuous equations of pore-air $\frac{\partial}{\partial t} \left[\rho_{a} (1 - S_{r}) n + \rho_{a} c_{h} S_{r} n \right] = div \left[\rho_{a} k_{a} grad \left(\frac{u_{a}}{g} \right) \right],$ 171 172 (12)④ The relationship of the effective stress-displacement 173 $\{d\sigma'\} = [D][L]^T \{dU\},\$ 174 175 (13)176 ⑤ The relationship of the saturation-matrix suction $S_r = f_r(s),$ 177 (14)178 (6) The coefficient of permeability of the pore-water $k_{w} = f_{w}(s),$ 179 (15) \bigcirc The coefficient of permeability of the pore-air 180 $\mathbf{k}_{a}=\mathbf{f}_{a}(\mathbf{s}),$ 181 (16) 182 in which,

183
$$[L] = \begin{bmatrix} \frac{\partial}{\partial x} & 0 & 0 & \frac{\partial}{\partial y} & 0 & \frac{\partial}{\partial z} \\ 0 & \frac{\partial}{\partial y} & 0 & \frac{\partial}{\partial x} & \frac{\partial}{\partial z} & 0 \\ 0 & 0 & \frac{\partial}{\partial z} & 0 & \frac{\partial}{\partial y} & \frac{\partial}{\partial x} \end{bmatrix}, \{d\sigma\} \text{ and } \{d\sigma'\} \text{ are the increments of the total stress and }$$

the effective stress, respectively, {db} is the increment of the body force, g is the gravitational acceleration,
[D] is the matrix of stress-strain and {dU} is the increment of displacement.

186 Simplified equations in 2-Dimensions

In this manuscript, we use equation (9) to describe the change of pore air pressure upon loading, so
equation (16) will not be used and the displacements and pore water pressure are solved simultaneously.

From equation (4), we have
$$\Delta n_a = \frac{\partial n_a}{\partial S_r} \frac{\partial S_r}{\partial s} (\Delta u_a - \Delta u_w) - \frac{\partial n_a}{\partial n} \Delta \varepsilon_v$$
 and $\Delta \varepsilon_v = -\Delta n$ for a soil element,

so the increment of total stress from equation (1) can be described as follows:

191
$$\Delta \sigma = \Delta \sigma' + A_1 \Delta u_w + A_2 \Delta \varepsilon_v, \qquad (17)$$

$$\partial \gamma \quad \partial n \quad \partial S \qquad \partial \gamma \qquad \partial n$$

192 in which
$$A_{r} = \frac{\chi + s \frac{\partial \chi}{\partial s} + P \frac{\partial n_{a}}{\partial S_{r}} \frac{\partial S_{r}}{\partial s}}{1 + P \frac{\partial n_{a}}{\partial S_{r}} \frac{\partial S_{r}}{\partial s}}, A_{2} = \frac{(\chi + s \frac{\partial \chi}{\partial s} - 1)P \frac{\partial n_{a}}{\partial n}}{1 + P \frac{\partial n_{a}}{\partial S_{r}} \frac{\partial S_{r}}{\partial s}}, P = (1 - \xi)(p_{a} + u_{a})/n_{a},$$

193 $\partial n_a / \partial S_r = -(1 - c_h)n$ and $\partial n_a / \partial n = 1 - (1 - c_h)S_r$. Substituting the above equations into equations

194 (10), we obtain:

$$(\mathbf{d}_{11} + \mathbf{A}_{2})\frac{\partial^{2}\Delta \mathbf{u}_{x}}{\partial x^{2}} + (\mathbf{d}_{14} + \mathbf{d}_{41})\frac{\partial^{2}\Delta \mathbf{u}_{x}}{\partial x \partial z} + \mathbf{d}_{44}\frac{\partial^{2}\Delta \mathbf{u}_{x}}{\partial z^{2}} + \mathbf{d}_{44}\frac{\partial^{2}\Delta \mathbf{u}_{x}}{\partial z^{2}} + \mathbf{d}_{44}\frac{\partial^{2}\Delta \mathbf{u}_{z}}{\partial z^{2}} + \mathbf{d}_{42}\frac{\partial^{2}\Delta \mathbf{u}_{z}}{\partial z^{2}} - \mathbf{A}_{1}\frac{\partial\Delta \mathbf{u}_{w}}{\partial x} = \Delta \mathbf{F}_{x},$$
(18a)

195

$$d_{41}\frac{\partial^{2}\Delta u_{x}}{\partial x^{2}} + (d_{21} + d_{44} + A_{2})\frac{\partial^{2}\Delta u_{x}}{\partial x \partial z} + d_{24}\frac{\partial^{2}\Delta u_{x}}{\partial z^{2}} + d_{44}\frac{\partial^{2}\Delta u_{z}}{\partial x^{2}} + (d_{24} + d_{42})\frac{\partial^{2}\Delta u_{z}}{\partial x \partial z} + (d_{22} + A_{2})\frac{\partial^{2}\Delta u_{z}}{\partial z^{2}} - A_{1}\frac{\partial\Delta u_{w}}{\partial z} = \Delta F_{z},$$
(18b)

197 in which Δu_x and Δu_z are the increments of the horizontal (or x) and vertical (or z) displacements,

respectively, d_{11} , d_{12} ... are the elements of the elastic-plastic matrix of stress-strain, ΔF_x and ΔF_z are the

199 increments of loads in the horizontal (or x) and vertical (or z) directions, respectively.

200 From equation (11), the continuous equation of pore-water can be formulated as follows,

$$\mu n \frac{\partial \mathbf{u}_{w}}{\partial t} = -\frac{\partial \mathbf{k}_{wx}}{\partial \mathbf{x}} \frac{\partial \mathbf{h}}{\partial \mathbf{x}} - \frac{\partial \mathbf{k}_{wz}}{\partial \mathbf{z}} \frac{\partial \mathbf{h}}{\partial \mathbf{z}} + \mathbf{S}_{r} \frac{\partial \boldsymbol{\varepsilon}_{v}}{\partial t}, \tag{19}$$

in which, $h = u_w / \rho_w g + z$, k_{wx} and k_{wz} are the coefficients of permeability in the horizontal and vertical directions, respectively, and $\mu = \partial S_r / \partial u_w$.

204 Constitutive equations for unsaturated soils

205 Soil-water characteristic curve

201

The soil-water characteristic curve is divided into two sections according to the values of the matrix suction s and the air entry suction S_b . When the value of matrix suction s is smaller than that of the air entry suction S_b , the soil can be assumed to be quasi-saturated and the degree of saturation of quasi-saturated soil is assumed to be S_{r1} (the value of S_{r1} approaches 1.0, such as 0.96), so the degree of saturation can be expressed as follows using Hilf formulation [19]:

211
$$\mathbf{S}_{r} = \mathbf{S}_{r1} \frac{\mathbf{p}_{a} + (\mathbf{u}_{w} + \mathbf{s}_{b})}{\mathbf{p}_{a} + (1 - \mathbf{c}_{b})\mathbf{S}_{r1}(\mathbf{u}_{w} + \mathbf{s}_{b})} \quad (s \le s_{b}),$$
(20a)

in which S_{r1} is the degree of saturation of soil masses when the matrix suction is equal to the value of air entry suction s_b . When the value of matrix suction s is greater than that of the air entry suction s_b , the

214 degree of saturation S_r is computed as follows [9]:

215
$$S_{r} = S_{ro} + (S_{r1} - S_{ro})(\frac{s}{s_{b}})^{-m_{i}} \qquad (s > s_{b}), \qquad (20b)$$

216 in which S_{r0} and m_1 are soil constants. During the process of drying shrinkage or absorbing water, the

217 parameters S_{r0} , S_{r1} and s_b may be different. By the derivation of equation (20b), we have:

218
$$\mu = (\mathbf{S}_{r_1} - \mathbf{S}_{r_0}) \frac{\mathbf{m}_1}{\mathbf{s}} (\frac{\mathbf{s}}{\mathbf{s}_b})^{-\mathbf{m}_1}.$$
 (21)

219 The effect of the degree of saturation on the permeability of unsaturated soils is assumed as follows:

220
$$k_{w} = k_{ws} \exp(-c_{k} \frac{s - s_{b}}{p_{c}}),$$
 (22)

221 where k_{ws} is the permeability for water under saturated conditions and c_k is constant. When $s \le s_b$,

$$222 k_w = k_{ws}.$$

223 Elastic-plastic model for soil skeleton

According to the principle of effective stress, i.e., equation (1), the stress in the following equations of this section refers to the effective stress. Ignoring the influence of temperature, the double hardening elasticplastic model for saturated soils [24] is used to describe the mechanical features of the soil skeleton of unsaturated soils.

228 Let
$$\sigma_{\rm m} = \frac{1}{3}\sigma_{\rm kk}$$
, $\sigma_{\rm s} = \sqrt{\frac{3}{2}}s_{\rm ij}s_{\rm ij}$, $s_{\rm ij} = \sigma_{\rm ij} - \sigma_{\rm kk}\delta_{\rm ij}$, $\varepsilon_{\rm s} = \sqrt{\frac{2}{3}}e_{\rm ij}e_{\rm ij}$, $e_{\rm ij} = \varepsilon_{\rm ij} - \frac{1}{3}\varepsilon_{\rm kk}\delta_{\rm ij}$. The yield

229 function of the model is expressed as follows:

230
$$F(\sigma, \varepsilon_{v}^{p}, \varepsilon_{s}^{p}) = \frac{\sigma_{m}}{1 - \left[\frac{\eta}{\alpha(\varepsilon_{v}^{p})}\right]^{m}} - p(\varepsilon_{v}^{p}), \qquad (23)$$

in which, $\eta = \sigma_s / \sigma_m$, and m is the parameter of yield function. When m = 1.2, the shape of the yield surface is close to an ellipse, as shown in Fig. 2. p and α are the two hardening parameters, which can be expressed as the functions of plastic volumetric strain ε_v^p and plastic shear strain ε_s^p , respectively, as follows,

235
$$p = p_0 \exp(\frac{\varepsilon_v^p}{c_c - c_e}), \qquad (24)$$

236 and
$$\alpha = \alpha_{\rm m} - (\alpha_{\rm m} - \alpha_0) \exp(\frac{\varepsilon_{\rm s}^{\rm p}}{c_{\rm a}}),$$
 (25)

237 in which,
$$\varepsilon_v^p = \varepsilon_{kk}^p$$
, $\varepsilon_s^p = \sqrt{\frac{2}{3}} e_{ij}^p e_{ij}^p$, $e_{ij}^p = \varepsilon_{ij}^p - \frac{1}{3} \varepsilon_{kk}^p \delta_{ij}$, c_c and c_e are the slopes of compressional

curve and rebound curve, respectively, and p_0 is the reference pressure with $\varepsilon_v^p = 0$. Equation (24) is in the same form as the hardening parameter of original Cam-clay model. In equation (25), 240 $\alpha_{\rm m} = (\sqrt[m]{1+m})\sin\phi$, ϕ is internal frictional angle, and α_0 and $c_{\rm a}$ are two other parameters that can be 241 determined by unloading triaxial compression test, in which the axial load is kept constant and the 242 confining pressure is reduced gradually.

Assuming that the flow rule is associated, the plastic strain increment can be determined by use of elastic-plastic theory as follows,

245
$$d\varepsilon_{ij}^{p} = d\lambda \frac{\partial F}{\partial \sigma_{ij}}$$
(26)

<u>~</u>

,

246 Or
$$d\varepsilon_v^p = d\lambda \frac{\partial F}{\partial \sigma_m}$$
,

247 (27a)

248
$$d\varepsilon_{s}^{p} = \frac{3}{2} d\lambda \frac{\partial F}{\partial \sigma_{s}}$$

249 (27b)

where $d\lambda$ is the plastic multiplier, which can be derived from the consistency conditions,

251
$$\frac{\partial F}{\partial \sigma_{ij}} d\sigma_{ij} + \frac{\partial F}{\partial \varepsilon_v^p} d\varepsilon_v^p + \frac{\partial F}{\partial \varepsilon_s^p} d\varepsilon_s^p = 0$$

252 (28)

253 Substituting for the plastic volumetric strain increment $d\mathcal{E}_v^p$ and the plastic shear strain increment

254 $d\varepsilon_s^p$ in equations (27-a) and (27-b), $d\lambda$ is obtained as follows,

255
$$d\lambda = \frac{\frac{\partial F}{\partial \sigma_{ij}} d\sigma_{ij}}{H}$$

256 (29)

257 in which the Hardening modulus H can be expressed as

258
$$\mathbf{H} = -\frac{3}{2} \frac{\partial \mathbf{F}}{\partial \varepsilon_{s}^{p}} \frac{\partial \mathbf{F}}{\partial \sigma_{s}} - \frac{\partial \mathbf{F}}{\partial \varepsilon_{v}^{p}} \frac{\partial \mathbf{F}}{\partial \sigma_{m}} = -\frac{3}{2} \frac{\partial \mathbf{F}}{\partial \alpha} \frac{\partial \alpha}{\partial \varepsilon_{s}^{p}} \frac{\partial \mathbf{F}}{\partial \sigma_{s}} - \frac{\partial \mathbf{F}}{\partial p} \frac{\partial p}{\partial \varepsilon_{v}^{p}} \frac{\partial \mathbf{F}}{\partial \sigma_{m}}.$$

259 (30)

260 Formulations of the finite-element equations

Analytical solutions to a one-dimensional seepage-deformation coupled problem in unsaturated soil could be derived by considering a homogeneous elastic material. Analytical solutions are simple and easy to implement but cannot account for the complex initial and boundary conditions, the soil heterogeneities [8, 32], the nonlinear stress-strain and the hydraulic relations involved in practical geotechnical problems, whereas the numerical solutions are more practical due to their flexibility. In the following, the formulations of finite element equations for the theory proposed here are presented.

Isoparametric elements are implemented with eight-node interpolating functions for the displacements (u_x , u_z) and four node interpolating functions for the pore water pressures (u_w), which can be expressed as follows,

270
$$\mathbf{u}_{x} = \sum_{i=1}^{8} N_{i} \mathbf{u}_{xi}, \mathbf{u}_{z} = \sum_{i=1}^{8} N_{i} \mathbf{u}_{zi}, \mathbf{u}_{w} = \sum_{i=1}^{4} \overline{N}_{i} \mathbf{u}_{wi}, \qquad (31)$$

in which \mathbf{u}_{xi} , \mathbf{u}_{zi} and \mathbf{u}_{wi} are the nodal variables at nodal point I and N_i and \overline{N}_i are interpolating functions for the displacements and pore-water pressure, respectively. Weak forms of equations (18a), (18b) and (19) are discretized in space and solved by the finite element method [21]. The time domain is divided into a number of elements or steps, and then the integration is performed for each step to obtain the changes of the parameters \mathbf{u}_{xi} , \mathbf{u}_{zi} and \mathbf{u}_{wi} . The step-by-step integrations may then be summed to determine the total change of the parameters. The backward differentiation method is used for the time discretization of the equations (18a), (18b) and (19) as follows:

278
$$\int_{t_{k}}^{t_{k}+\Delta t_{k}} \mathbf{G} dt = \Delta t_{k} \Big[(1-\beta) \mathbf{G}_{t_{k}} + \beta \cdot \mathbf{G}_{t_{k}+\Delta t_{k}} \Big] = \Delta t_{k} \Big[\mathbf{G}_{t_{k}} + \beta \Delta \mathbf{G} \Big]$$
(32)

where Δt_k is the time increment, G_{t_k} and $G_{t_k+\Delta t_k}$ are the corresponding function values at steps t_k and $t_k+\Delta t_k$, respectively, and ΔG is the incremental function value and β is an integral parameter. When $\beta > 0.5$, the difference format is unconditionally stable, and thus, $\beta=2/3$ is used here.

282 Therefore, the finite element equations for node i $(i = 1, 2, ..., N_t)$ can be formulated as follows,

283
$$\sum_{j=1}^{N_{t}} [k_{ij}^{11} \Delta u_{xj} + k_{ij}^{12} \Delta u_{zj} + k_{ij}^{13} \Delta h_{j}] = \Delta F_{xi}, \qquad (33a)$$

284
$$\sum_{j=1}^{N_{t}} [k_{ij}^{21} \Delta u_{xj} + k_{ij}^{22} \Delta u_{zj} + k_{ij}^{23} \Delta h_{j}] = \Delta F_{zi}, \qquad (33b)$$

285 and

286
$$\sum_{j=1}^{N_{t}} [k_{ij}^{31} \Delta u_{xj} + k_{ij}^{32} \Delta u_{zj} + k_{ij}^{33} (h_{j0} + \beta \Delta h_{j}) + s_{ij} \Delta h_{j}] = \Delta Q_{i}, \quad (33c)$$

in which N_t is the total number of nodal points; ΔF_{xi} , ΔF_{zi} and ΔQ_i are the load increments and flux increment at node i, respectively; h_{i0} and Δh_i are the initial value of the water head and the increment of the water head at node i in a computational time step Δt_k ; $h_i=z_i + u_{wi}/\gamma_w$, in which, z_i is the location of the water head at node i; and γ_w is the weight of water. The elements of the coefficient matrix in the finite element equations (33) are given in the Appendix V.

292 Numerical simulations

293 Simulation of the experimental results

294 The proposed benchmark is based on an experiment performed by Liakopolos [23] on a column of Del 295 Monte sand and instrumented to measure the moisture tension at several points along the column during its 296 desaturation due to gravitational effects. Before the start of the experiment, water was continuously added 297 from the top and allowed to drain freely at the bottom through a filter until the uniform flow conditions 298 were established. At the start of the experiment, the water supply ceased, and the tensiometer readings were 299 recorded, as well as the outflow and outflow rate at the bottom. The test diagram is shown in Fig. 3(a). The 300 initial conditions are as follows: for t=0, s=0 for all the nodes, which corresponds to a steady flow of water 301 through the sand column. Furthermore, a state of mechanical equilibrium is assumed for t=0. All the 302 displacements are related to these initial displacements, which correspond to the equilibrium state. The 303 boundary conditions are as follows.

- For the lateral surface: there is no flow horizontally, and $q_w=0$ and $u_x=0$. For the top surface: t>0 and $u_a=p_a$. For the bottom surface: t>0, free water outflow, $u_a=p_a$, s=0 for t>0, $u_x=u_z=0$.
- 306 The computed parameters used here are as follows: $\rho=2.0 \text{ g/cm}^3$, $k_0=0.6$, v=0.3077, $n_0=0.2975$, $k_{ws}=0.03$
- 307 cm/s, $c_k=1.0$, $c_c=0.006$, $c_e=0.0001$, $S_{r_0}=0.1$, $S_{r_1}=0.96$, $m_1=m_2=0.1$, $s_b=25$ kPa, $\alpha_m=1.0$, $\alpha_0=0.75$, $c_a=0.05$ and
- $\zeta = 0.6$. Fig. 3(b) presents the simulated results and the tested results of the development of the pore water

309 pressure at different depths. Compared with the test results and the simulated results proposed previously,

the new method proposed here can model the drying shrinkage process of unsaturated soils.

311 Parametric study

312 (a) Effects of discharge speed of pore air ξ

The mesh, shown in Figure 4(a), is used to simulate seepage-deformation processes under infiltration conditions in only the vertical direction (z direction) with different discharge speeds of the pore air ξ . The soil mass is 100 cm in length and 10 cm in width, with infiltration through the upper surface. The initial suction distribution is shown in Fig. 4(b). The boundary conditions are as follows.

For the lateral surface: there is no flow horizontally, and $q_w=0$ and $u_x=0$. For the top surface: drained freely (water and air). For the bottom surface: s=0 (water level located at the bottom surface) for t>0 and $u_x=u_x=0$.

The soil mass is infiltrated by rainfall with rate of 0.576 mm/hours, and the computed parameters employed are as follows: $\rho=2.0$ g/cm³, k_o=0.6, v=0.3077, n_o=0.432, k_{ws}=0.000088 cm/s, c_k=1.0, c_c=0.06, c_e=0.01, S_{ro}=0.2, S_{r1}=0.998, m₁= m₂=0.1, s_b=25kPa, $\alpha_m=1.0$, $\alpha_o=0.75$ and $c_a=0.05$. The discharge speeds of

323 pore air ξ are assumed to be 0.2, 0.4, 0.6, 0.8 and 1.0, respectively.

Fig. 4 (c)-(e) show the variation of suction during rainfall infiltration with different discharge speed of pore air ξ . It is obvious that the discharge speed of pore air has a greater influence on the development of suction in the unsaturated soils. In the process of infiltration, the magnitude of the suction with smaller ξ is greater than that of the suction with larger ξ because the pore air pressure will decrease with the increasing value of ξ . With rainfall infiltration, the magnitude of the suction becomes smaller for the same value of ξ .

330 (b) Effects of the evaporation intensity I

The effects of evaporation intensity I on the seepage-deformation coupling processes of unsaturated soils are investigated using the computational mesh and boundary conditions shown in Fig. 5 (a) with different values of evaporation intensity I. Before the start of the evaporation, the soils are fully saturated.

The initial conditions are as follows: for t=0, s=0 for all the nodes, which corresponds to a steady flow of

335 water through the soil column. Furthermore, a state of mechanical equilibrium is assumed for t=0. All the 336 displacements are related to these initial displacements, which correspond to the equilibrium state. The 337 boundary conditions are as follows: For the lateral surface: there is no flow horizontally, and $q_w=0$ and 338 $u_x=0$. For the top surface: evaporation, t>0, $u_a=p_a$ and a drained boundary (water and air). For the bottom 339 surface: $u_a = p_a$ s=0 for t>0, and $u_x = u_z = 0$. The computed parameters used here are as follows: $\rho = 2.0$ g/cm³, 340 341 s_b=25kPa, α_m =1.0, α_o =0.75 and c_{α} =0.05, ξ =0.6. The evaporation intensity I = 0.012 cm/hrs, 0.024 cm/hrs 342 and 0.036 cm/hrs are used here to study the influence of evaporation intensity on the features of the soil 343 column.

344 Fig. 5 (b)-(d) present the distributions of the pore water pressure during the process of evaporation with 345 different values of evaporation intensity, which demonstrates that the magnitude of the evaporation 346 intensity has great influence on the development of pore water pressure in the unsaturated soils. During the 347 process of evaporation, the magnitude of the pore water pressure (compressive is positive) increases 348 gradually with the same depth at the same time. With the increase of the evaporation intensity, the 349 magnitude of the pore water pressure also increases gradually at the same time with the same depth of the 350 soil column. When the magnitude of the evaporation intensity is greater on the upper surface of the soil 351 column, there is greater pore water pressure with a negative value, thus resulting in equilibrium of the 352 unsaturated soil masses.

353 (c) Effects of the saturated permeability k_{ws}

354 For the computational mesh and boundary conditions shown in Fig. 5(a), the effects of the permeability of 355 unsaturated soils kws on the seepage-deformation coupling processes of unsaturated soils are investigated with different values of k_{ws} . The initial and boundary conditions are the same as those of section (b) 356 discussed above. The computed parameters used here are as follows: $\rho = 2.0 \text{ g/cm}^3$, k_o=0.6, v=0.3077, 357 358 $n_0 = 0.2975$, I = 0.012 cm/hrs, $c_k = 1.0$, $c_c = 0.006$, $c_e = 0.0001$, $S_{r_0} = 0.1$, $S_{r_1} = 0.96$, $m_1 = m_2 = 0.1$, $s_b = 25$ kPa, $a_m = 1.0$, $a_m = 1.0$ 359 $\alpha_0=0.75$, $c_{\alpha}=0.05$, and $\zeta=0.6$. The saturated permeability k_{ws}=0.03 cm/s, 0.003 cm/s and 0.0008 cm/s are 360 used here to investigate the influence of the saturated permeability on the features of the soil column. 361 Figs. 6 (a)-(c) present the distributions of the pore water pressure during the process of evaporation with

362 different values of saturated permeability, which also demonstrates that the magnitude of the saturated

permeability affects the development of pore water pressure in the unsaturated soils greatly. With the decrease of the saturated permeability, the magnitude of the pore water pressure increases gradually at the same time with the same depth of the soil column. In addition, the magnitude of pore water pressure increases gradually with the same depth at the same time for the same saturated permeability. The greater the saturated permeability is, the quicker the dissipation of pore water. Thus, we obtained the computational results presented here.

369 Simulation of the unsaturated soil slope with rainfall infiltration

The seepage-deformation processes under evaporation and rainfall infiltration conditions are simulated for an unsaturated soil slope that is 20 m in depth and 54 m in width. The computational mesh and boundary conditions are shown in Figure 7(a).

373 For the lateral surfaces, there are undrained and constrained boundaries $(u_x = u_z = 0)$; for the bottom 374 surface, a constrained boundary, the pore water pressure is zero all the time with the surface of the water 375 table; for the upper surfaces composed of three planes, they drain freely, and evaporation/infiltration occurs 376 on these surfaces. When t=0, the soil slope is saturated and is in equilibrium with the weight stress state. 377 During the first 1100 days, the evaporation rate of the soil slope is 0.3 mm per day, and during the 378 subsequent 300 days, the infiltration rate of rainfall is 0.5 mm per day. The computed parameters are as 379 follows: $\rho = 2.0 \text{ g/cm}^3$, $k_0 = 0.6$, v = 0.3077, $e_0 = 0.7$, $k_{ws} = 0.000001 \text{ cm/s}$, $c_k = 0.2$, $c_c = 0.0332$, $c_c = 0.0064$, $S_{ro} = 0.2$, 380 $S_{r1}=0.96$, $m_1=m_2=0.1$, $s_b=20$ kPa, $\alpha_m=1.0$, $\alpha_o=0.75$, $\zeta=0.6$ and $c_{\alpha}=0.05$.

Figs. 7 (b) and (c) present the distribution of the pore water pressure at the end of the evaporation and rainfall infiltration, respectively. At the end of evaporation, the pore water with a negative value is highest near the upper surfaces of the soil slope, and it reduces gradually with the water infiltration into the unsaturated soil slope. Figs. 7 (d) and (e) present the distributions of the displacement at the end of evaporation and rainfall infiltration, respectively. From the simulation of the evaporation and rainfall infiltration for an unsaturated soil slope, the method proposed here can model the seepage-deformation process of unsaturated soils qualitatively.

388 Conclusions

389 A new FEM code was developed on the basis of a simplified consolidation theory for unsaturated soils that 390 can be used to analyze the seepage-deformation of unsaturated soil slope under evaporation/rainfall 391 infiltration conditions. The numerical examples demonstrate that the reduced suction and constant 392 discharge speed of the pore air can be introduced to simplify the consolidation equations for unsaturated 393 soils, thereby making it easy to program the consolidation theory into the numerical analysis code of the 394 elastic-plastic finite element method. Through a parameter study and comparison with the tested results, the 395 results of this study demonstrated that the proposed method can describe well the features in the process of 396 water evaporation/infiltration into unsaturated soils.

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476 Appendix I

- 477 From the simplified phase diagrams (see Fig. A1) for an unsaturated soil, we have
- 478 $V_v = V_a + V_w$, and $V = V_a + V_w + V_s = 1$,
- 479 $S_r = V_w / V_v, n = V_v / V,$

so we obtain $V_a = V_v - V_w$. However, for the unsaturated soils, some air is embedded in the water, which can be formulated by the simplified method as $V'_a = c_h V_w$, so the total air content of a unit volume of unsaturated soil element can be obtained:

483
$$V_a + V'_a = V_v - V_w + c_h V_w = nV[1 - S_r + c_h S_r] = [1 - S_r + c_h S_r] n.$$

484 We define $n_a = [1-S_r+c_hS_r]n = [1-(1-c_h)S_r]n$, where n is the ratio of the pore air of a unit soil element, which 485 signifies the air content in the voids of a soil element within unit volume.

- 486 Appendix II
- For a unit volume soil element, the pore air pressure u_a will be generated upon loading. Under the conditions that the air
 in the voids cannot be discharged, from Boyle's law, we have

489
$$(p_a + u_a)(V_a + c_h V_w) = (p_a + u_{a0})(V_{a0} + c_h V_{w0}),$$
 (II-1)

in which, p_a is the atmospheric pressure, u_a is the pore air pressure, V_{a0} is the initial content of pore air of a unit volume soil element (the corresponding pore air pressure $u_{a0} = 0$), and V_a is the content of pore air of a unit volume soil element. For a unit volume soil element (see Fig. A1), we have $V_w = nS_r$ and $V_a = n(1-S_r)$. Combining equation (4), $n_a = [1-(1-c_h)S_r]n$, and equation (II-1), we have

494
$$(p_a + u_a)n_a = (p_a + u_{a0})n_{a0},$$
 (II-2)

495 in which, \mathbf{n}_{a0} is the initial ratio of pore air of a unit soil element, $\mathbf{n}_{a0} = [1 - (1 - c_h)S_{r0}]\mathbf{n}_0$, S_{r0} is initial

- 496 degree of saturation and \mathbf{n}_0 is initial porosity.
- 497 Because the initial air pressure is equal to the atmospheric pressure ($u_{a0} = 0$), from equation (II-2), we have:

$$u_a = (\frac{n_{a0}}{n_a} - 1) p_a.$$
 (II-3) or (6)

499 Appendix III

500 In the following, we ignore the flow of the dissolved air in the pore-water, the vapor in the pore-air and the 501 influence of temperature. For a unit volume soil element, the mass of pore air discharged per unit time has the 502 following equation (mass conservation equation):

503
$$\frac{\partial}{\partial t} \left[\rho_{a} (1 - S_{r}) n + \rho_{a} c_{h} S_{r} n \right] = \frac{\partial}{\partial t} \left[\rho_{a} n_{a} \right] = \frac{dq_{a}}{dt}$$

504 (III-1)

505 in which \mathbf{q}_{a} is the mass of pore air discharged within a unit soil element. From equation (III-1), we can deduce the

(III-

 $\Delta \rho_{\rm a} \cdot \mathbf{n}_{\rm a} + \rho_{\rm a} \cdot \Delta \mathbf{n}_{\rm a} = \Delta \mathbf{q}_{\rm a}.$

506 following equation in incremental form:

508 2)

509 Differentiating equation (5), $\rho_a = \rho_{a0} (1 + u_a / p_a)$, we have

510
$$\Delta \rho_{a} = \rho_{a0} \cdot \Delta u_{a} / p_{a}. \qquad (III-3)$$

511 From equation (7), we have

512
$$\Delta \mathbf{q}_{\mathrm{a}} = \boldsymbol{\xi} \cdot \boldsymbol{\rho}_{\mathrm{a}} \cdot \Delta \mathbf{n}_{\mathrm{a}}, \qquad (\text{III-4})$$

513 Substituting equations (III-3) and (III-4) into equation (III-2), we obtain

514
$$\mathbf{n}_{\mathbf{a}} \cdot \boldsymbol{\rho}_{\mathbf{a}0} \cdot \Delta \mathbf{u}_{\mathbf{a}} / \mathbf{p}_{\mathbf{a}} + \boldsymbol{\rho}_{\mathbf{a}} \cdot \Delta \mathbf{n}_{\mathbf{a}} = \boldsymbol{\xi} \cdot \boldsymbol{\rho}_{\mathbf{a}} \cdot \Delta \mathbf{n}_{\mathbf{a}}, \qquad (\text{III-5})$$

515 Substituting equation (5), $\rho_a = \rho_{a0} (1 + u_a / p_a)$, into equation (III-5), we have

516
$$\Delta u_{a} = -\frac{p_{a} + u_{a}}{n_{a}} (1 - \xi) \Delta n_{a}. \qquad \text{(III-6) or (8)}$$

517 Appendix IV

518 The equation (8) can be expressed as:

519
$$\frac{\mathrm{d}\mathbf{u}_{\mathrm{a}}}{\mathbf{p}_{\mathrm{a}} + \mathbf{u}_{\mathrm{a}}} = -\frac{1 - \xi}{\mathbf{n}_{\mathrm{a}}} \mathrm{d}\mathbf{n}_{\mathrm{a}}, \qquad (\mathrm{IV-1})$$

520 Integrating the above equation, we obtain the following:

521
$$\ln(p_a + u_a) = -(1 - \xi) \ln(n_a) + \text{const.},$$
 (IV-2)

522 Substituting the initial conditions n_{a0} and u_{a0} into equation (IV-2), we have

523
$$\operatorname{const.} = \ln[(p_a + u_{a0})n_{a0}^{(1-\xi)}],$$
 (IV-3)

524 Combining equations (IV-2) and (IV-3), we have

525
$$u_{a} = [(\frac{n_{a0}}{n_{a}})^{(1-\xi)} - 1] p_{a}.$$
 (IV-4)

526 Appendix V

527 The elements of the coefficient matrix in the finite element equation (33) are as follows,

528
$$k_{ij}^{11} = \int [(d_{11} + A_2) \frac{\partial N_i}{\partial x} \frac{\partial N_j}{\partial x} + d_{44} \frac{\partial N_i}{\partial z} \frac{\partial N_j}{\partial z} + d_{14} (\frac{\partial N_i}{\partial x} \frac{\partial N_j}{\partial z} + \frac{\partial N_j}{\partial x} \frac{\partial N_i}{\partial z})] dxdz, \quad (V-1)$$

529
$$k_{ij}^{12} = \int [(d_{12} + A_2) \frac{\partial N_i}{\partial x} \frac{\partial N_j}{\partial z} + d_{14} \frac{\partial N_i}{\partial x} \frac{\partial N_j}{\partial x} + d_{24} \frac{\partial N_i}{\partial z} \frac{\partial N_j}{\partial z} + d_{44} \frac{\partial N_j}{\partial x} \frac{\partial N_i}{\partial z}] dxdz, \quad (V-2)$$

530
$$k_{ij}^{21} = \int [(d_{12} + A_2) \frac{\partial N_i}{\partial z} \frac{\partial N_j}{\partial x} + d_{14} \frac{\partial N_i}{\partial x} \frac{\partial N_j}{\partial x} + d_{24} \frac{\partial N_i}{\partial z} \frac{\partial N_j}{\partial z} + d_{44} \frac{\partial N_i}{\partial x} \frac{\partial N_j}{\partial z})] dxdz, \quad (V-3)$$

531
$$k_{ij}^{22} = \int [(d_{22} + A_2) \frac{\partial N_i}{\partial z} \frac{\partial N_j}{\partial z} + d_{44} \frac{\partial N_i}{\partial x} \frac{\partial N_j}{\partial x} + d_{24} (\frac{\partial N_i}{\partial z} \frac{\partial N_j}{\partial x} + \frac{\partial N_j}{\partial z} \frac{\partial N_i}{\partial x})] dxdz, \quad (V-4)$$

532
$$k_{ij}^{33} = -\int \left[k_x \frac{\partial N_i}{\partial x} \frac{\partial N_j}{\partial x} + k_z \frac{\partial N_i}{\partial z} \frac{\partial N_j}{\partial z}\right] dxdz,$$
 (V-5)

533
$$k_{ij}^{13} = -\rho_w g \int A_j \frac{\partial \overline{N}_i}{\partial r} \overline{N}_j ddz$$
, (V-6)

534
$$k_{ij}^{23} = -\rho_w g \int A_1 \frac{\partial \overline{N}_i}{\partial z} \overline{N}_j dx dz$$
, (V-7)

535
$$k_{ij}^{31} = -\rho_w g \int S_r \frac{\partial \overline{N}_j}{\partial x} \overline{N}_i dx dz$$
, (V-8)

536
$$k_{ij}^{32} = -\rho_w g \int S_r \frac{\partial \overline{N}_j}{\partial z} \overline{N}_i dx dz,$$
 (V-9)

537
$$\mathbf{s}_{ij} = -\rho_{w}g \int \mathbf{c}_{s} \mathbf{N}_{i} \mathbf{N}_{j} d\mathbf{x} d\mathbf{z}, \qquad (V-10)$$

538 where $c_s = \mu n / S_r$.

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563	List of figures
564	Fig. 1. Determination of the reduced suction.
565	Fig. 2 Double hardening yield surfaces.
566	Fig. 3 Tested and simulated results. (a) The Liakopoulos test problem. (b) Tested and simulated results.
567	Fig. 4 Effects of the discharge speed of pore air, ξ . (a) Computational mesh and boundary conditions. (b)
568	The initial suction distribution at t=0.0 hours. (c) The suction distribution at t=100 hours of
569	infiltration. (d) The suction distribution at t=205 hours of infiltration. (e) The suction distribution at
570	t=310 hours of infiltration.
571	Fig. 5 Effects of the evaporation intensity I . (a) Computational mesh and boundary conditions. (b) The
572	distribution of pore water pressure with evaporation intensity I=0.012 cm/hours. (c) The distribution of

- 573 pore water pressure with evaporation intensity I=0.024 cm/hours. (d) The distribution of pore water 574 pressure with an evaporation intensity I=0.036 cm/hours.
- 575 Fig. 6 Effects of saturated permeability k_{ws} . (a) The distribution of pore water pressure with $k_{ws}=0.03$ cm/s.
- 576 (b) The distribution of pore water pressure with $k_{ws}=0.003$ cm/s. (c) The distribution of pore water 577 pressure with $k_{ws}=0.0008$ cm/s.
- 578 Fig. 7 Simulation of unsaturated soil slope with rainfall infiltration. (a) Computational mesh and boundary
- 579 conditions. (b) Pore water pressure distribution at the end of evaporation (kPa). (c) Pore water pressure
- 580 distribution at the end of infiltration (kPa). (d) Displacement distribution at the end of evaporation. (e)
- 581 Displacement distribution at the end of rainfall infiltration.
- 582 Fig. A1 Simplified three phase diagram.
- 583
- 584
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586



Fig.1 Determination of the reduced suction



Fig.2 (a) p=const.



Fig.2 (b) α =const.

Fig.2 Double hardening yield surfaces



Fig.3 (a)The Liakopoulos test problem



Fig.3 (b) Comparisons with laboratory test results of the Liakopoulos test problem (Liakopolos 1965)



Fig.4(a). Computational mesh and boundary conditions



Fig.4(b). The initial suction distribution at t=0.0hours



Fig.4(c). The suction distribution at t=100hours of infiltration



Fig.4(d). The suction distribution at t=205hours of infiltration



Fig.4(e). The suction distribution at t=310hours of infiltration



Fig.5(a). Computational mesh and boundary conditions



Fig.5(b). The distribution of pore water pressure with evaporation intensity I=0.012cm/hours



Fig.5(c). The distribution of pore water pressure with evaporation intensity I=0.024cm/hours



Fig.5(d). The distribution of pore water pressure with evaporation intensity I=0.036cm/hours



Fig.6(a). The distribution of pore water pressure with $k_{ws} {=} 0.03 \text{cm/s}$



Fig.6(b). The distribution of pore water pressure with k_{ws} =0.003cm/s



Fig.6(c). The distribution of pore water pressure with k_{ws} =0.0008cm/s



Constrained boundary ux=uz=0

Fig.7(a). Computational mesh and boundary conditions



Fig.7 (b) Pore water pressure distribution at the end of evaporation (kPa) $\,$



Fig.7 (c) Pore water pressure distribution at the end of infiltration (kPa) $\,$



Fig.7 (d) Displacement distribution at the end of evaporation



Fig.7 (e) Displacement distribution at the end of rainfall infiltration



Fig.A1 Simplified three phase diagram