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Recovering the initial distribution for strongly damped wave equation

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Abstract

We study for the first time the inverse backward problem for the strongly damped wave equation. First, we show that the problem is severely ill-posed in the sense of Hadamard. Then, under the *a priori* assumption on the exact solution belonging to a Gevrey space, we propose the Fourier truncation method for stabilising the ill-posed problem. A stability estimate of logarithmic type is established.

Keywords and phrases: Fourier regularization method; final value problem; strongly damped wave equation.

Mathematics subject Classification 2000: 35K05, 35K99, 47J06, 47H10

1. Introduction

The strongly damped wave equation (SDWE), see (1.1) below, occurs in a wide range of applications modelling the motion of viscoelastic materials [3, 7, 9, 10]. From both the theoretical and numerical point of view, the initial value problem for this equation has been extensively studied (e.g., [4, 5, 11]). However, to the best of our knowledge, the final value (backward) problem has not been solved yet (though it is worth mentioning that in [6], Lattes and Lions introduced the problem (1.1)-(1.2) but they did not regularize it). Our major objective is to provide a regularization method for solving the ill-posed nonlinear problem (1.1)-(1.2).

Let T be a positive number and Ω be an open, bounded and connected domain in \mathbb{R}^n , $n \geq 1$ with a smooth boundary $\partial\Omega$. We are interested in the following inverse backward problem: Find the initial data $u(x, 0)$ for $x \in \Omega$, where $u(x, t)$ satisfies the following semilinear SDWE:

$$u_{tt} - \alpha \mathcal{A}u_t - \mathcal{A}u = F(x, t, u(x, t)), \quad (x, t) \in \Omega \times (0, T), \quad (1.1)$$

subject to the conditions

$$\begin{cases} u = 0, & (x, t) \in \partial\Omega \times (0, T), \\ u(x, T) = g(x), & (x, t) \in \Omega \times (0, T), \\ u_t(x, T) = h(x), & (x, t) \in \Omega \times (0, T), \end{cases} \quad (1.2)$$

where $\alpha > 0$ is a given damping constant, $g(x)$ and $h(x)$ are given functions, and the source function F will be defined later. **Here, the operator $\mathcal{A} : D(\mathcal{A}) \subset L^2(\Omega) \rightarrow L^2(\Omega)$ is a linear, positive-definite, self-adjoint operator with compact inverse in $L^2(\Omega)$. For instance, $\mathcal{A} := \sum_{i,j=1}^d \frac{\partial}{\partial x_i} (l_{ij}(x) \frac{\partial}{\partial x_j})$, $x \in \Omega$ is a linear second-order elliptic operator with smooth coefficients $\{l_{ij}\}_{i,j=1}^d$ being symmetric and uniformly positive definite. Then, the Dirichlet eigenvalues $(\lambda_j)_{j \in \mathbb{N}^*}$ of $-\mathcal{A}$ satisfy, see Chapter 6.5 in [2], $0 < \lambda_1 \leq \lambda_2 \leq \lambda_3 \leq \dots \leq \lambda_j \leq \dots$ and $\lim_{j \rightarrow \infty} \lambda_j = \infty$.**

In practice, the data (g, h) is obtained by measurement contaminated with noise. Hence, instead of (g, h) , we have the observation data $(g^\epsilon, h^\epsilon) \in L^2(\Omega) \times L^2(\Omega)$ satisfying

$$\|g^\epsilon - g\|_{L^2(\Omega)} + \|h^\epsilon - h\|_{L^2(\Omega)} \leq \epsilon, \quad (1.3)$$

where the constant $\epsilon > 0$ represents a bound on the measurement error. We will show that the inverse backward problem (1.1)-(1.2) is ill-posed in the sense of Hadamard in Section 2. In order to stabilise the solution, in Section 3 we develop a regularization method based on the truncated Fourier method for which a stability estimate of logarithmic type is established.

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2. Ill-posedness of the inverse problem (1.1)-(1.2)

Assume that the problem (1.1)-(1.2) has a unique solution in the series form

$$u(x, t) = \sum_{j=1}^{\infty} u_j(t) \phi_j(x), \quad (2.4)$$

where ϕ_j denotes the eigenfunction corresponding to the eigenvalue λ_j and

$$\begin{cases} u_j''(t) + \alpha \lambda_j u_j'(t) + \lambda_j u_j(t) = F_j(u)(t), & t \in (0, T), \\ u_j(T) = g_j, \quad u_j'(T) = h_j, \end{cases} \quad (2.5)$$

where $F_j(u)(t) = \int_{\Omega} F(x, t, u(x, t)) \phi_j(x) dx$, $g_j = \int_{\Omega} g(x) \phi_j(x) dx$ and $h_j = \int_{\Omega} h(x) \phi_j(x) dx$.

For given fixed damping $\alpha > 0$, consider the decomposition

$$\mathbb{N}^* = \left(\mathbb{D}_1 = \left\{ j \in \mathbb{N}^* \mid \lambda_j > \frac{4}{\alpha^2} \right\} \right) \cup \left(\mathbb{D}_2 = \left\{ j \in \mathbb{N}^* \mid \lambda_j = \frac{4}{\alpha^2} \right\} \right) \cup \left(\mathbb{D}_3 = \left\{ j \in \mathbb{N}^* \mid \lambda_j < \frac{4}{\alpha^2} \right\} \right).$$

Then, the solution of (2.5) is given by:

(i) if $j \in \mathbb{D}_1$ then

$$u_j(t) = \frac{\lambda_j^+ e^{(T-t)\lambda_j^-} - \lambda_j^- e^{(T-t)\lambda_j^+}}{\sqrt{\Lambda_j}} g_j - \frac{e^{(T-t)\lambda_j^+} - e^{(T-t)\lambda_j^-}}{\sqrt{\Lambda_j}} h_j + \int_t^T \frac{e^{(s-t)\lambda_j^+} - e^{(s-t)\lambda_j^-}}{\sqrt{\Lambda_j}} F_j(u)(s) ds, \quad (2.6)$$

(ii) if $j \in \mathbb{D}_2$ then

$$u_j(t) = e^{\frac{2}{\alpha}(T-t)} \left[1 - \frac{2}{\alpha}(T-t) \right] g_j - e^{\frac{2}{\alpha}(T-t)} (T-t) h_j + \int_t^T (s-t) e^{\frac{2}{\alpha}(s-t)} F_j(u)(s) ds,$$

(iii) if $j \in \mathbb{D}_3$ then

$$\begin{aligned} u_j(t) &= \frac{2e^{\frac{\alpha \lambda_j}{2}(T-t)}}{\sqrt{-\Lambda_j}} \left[\frac{\sqrt{-\Lambda_j}}{2} \cos \left(\frac{\sqrt{-\Lambda_j}}{2} (T-t) \right) + \frac{\alpha \lambda_j}{2} \sin \left(\frac{\sqrt{-\Lambda_j}}{2} (T-t) \right) \right] g_j \\ &- \frac{2e^{\frac{\alpha \lambda_j}{2}(T-t)}}{\sqrt{-\Lambda_j}} \sin \left(\frac{\sqrt{-\Lambda_j}}{2} (T-t) \right) h_j + \int_t^T \frac{2e^{\frac{\alpha \lambda_j}{2}(s-t)}}{\sqrt{-\Lambda_j}} \sin \left(\frac{\sqrt{-\Lambda_j}}{2} (s-t) \right) F_j(u)(s) ds, \end{aligned}$$

where

$$\lambda_j^+ = \frac{\alpha \lambda_j + \sqrt{\alpha^2 \lambda_j^2 - 4\lambda_j}}{2}, \quad \lambda_j^- = \frac{\alpha \lambda_j - \sqrt{\alpha^2 \lambda_j^2 - 4\lambda_j}}{2}, \quad \Lambda_j = \alpha^2 \lambda_j^2 - 4\lambda_j. \quad (2.7)$$

Hence, the solution (2.4) can be represented as

$$u(x, t) = \sum_{j \in \mathbb{D}_1} u_j(t) \phi_j + \sum_{j \in \mathbb{D}_2} u_j(t) \phi_j + \sum_{j \in \mathbb{D}_3} u_j(t) \phi_j.$$

From above observations, we can show that the term $\sum_{j \in \mathbb{D}_2} u_j(t) \phi_j + \sum_{j \in \mathbb{D}_3} u_j(t) \phi_j$ containing sin and cos trigonometric functions is bounded and stable, and no regularization is need it for it. We only need to regularize the first term $\sum_{j \in \mathbb{D}_1} u_j(t) \phi_j$ which contains the exponential terms in (2.6). Alternatively, we can take $\mathbb{D}_1 = \mathbb{D}_2 = \emptyset$ by assuming that $\alpha^2 \lambda_1 > 4$, as will adopted in the remanding of the paper. Note that this also implies $\alpha^2 \lambda_j^2 - 4\lambda_j > 0$ for all $j \in \mathbb{N}^*$, and hence the roots in (2.7) are real and distinct.

From now on, we denote by $\langle \cdot, \cdot \rangle$ and $\| \cdot \|$ the inner product and norm in $L^2(\Omega)$, respectively. For $\varphi \in L^2(\Omega)$, defining

$$\mathcal{S}(t)\varphi = \sum_{j=1}^{\infty} \frac{\lambda_j^+ e^{t\lambda_j^-} - \lambda_j^- e^{t\lambda_j^+}}{\lambda_j^+ - \lambda_j^-} \langle \varphi, \phi_j \rangle \phi_j, \quad \mathcal{P}(t)\varphi = \sum_{j=1}^{\infty} \frac{e^{t\lambda_j^-} - e^{t\lambda_j^+}}{\lambda_j^+ - \lambda_j^-} \langle \varphi, \phi_j \rangle \phi_j, \quad (2.8)$$

we can recast (2.4) in the form

$$u(x, t) = \mathcal{S}(T-t)g(x) + \mathcal{P}(T-t)h(x) - \int_t^T \mathcal{P}(s-t)F(u(s))ds. \quad (2.9)$$

Next, we give an example which shows that the solution $u_m(x, t)$ (for any $m \in \mathbb{N}^*$) of problem (1.1)-(1.2) (if it exists) is not stable. Let $u_{T,m}$ and $v_{T,m}$ and F_0 be defined as follows:

$$u_m(x, T) = u_{T,m}(x) = 0, \quad \partial_t u_m(x, T) = v_{T,m}(x) = \frac{\phi_m(x)}{\sqrt{\lambda_m}} \quad \text{and} \quad F_0(w) = \sum_{j=1}^{\infty} \frac{e^{-\alpha T \lambda_j}}{2T^2} \langle w(x, t), \phi_j \rangle \phi_j, \quad \forall w \in L^2(\Omega). \quad (2.10)$$

Let u_m satisfy the integral equation

$$u_m(x, t) = \mathcal{P}(T-t)v_{T,m} - \int_t^T \mathcal{P}(s-t)F_0(u_m(s))ds. \quad (2.11)$$

First, we show that (2.11) has a unique solution $u_m \in C([0, T]; L^2(\Omega))$. Indeed, we consider the function

$$\mathcal{H}(w)(t) = \mathcal{P}(T-t)v_{T,m}(x) - \int_t^T \mathcal{P}(s-t)F_0(w(s))ds. \quad (2.12)$$

Then, for any $v_1, v_2 \in C([0, T]; L^2(\Omega))$, we have

$$\begin{aligned} \|\mathcal{H}(v_1)(t) - \mathcal{H}(v_2)(t)\| &\leq \int_t^T \|\mathcal{P}(s-t)(F_0(v_1(s)) - F_0(v_2(s)))\| ds \\ &= \int_t^T \sqrt{\sum_{j=1}^{\infty} \left[\frac{e^{(s-t)\lambda_j^-} - e^{(s-t)\lambda_j^+}}{\lambda_j^+ - \lambda_j^-} \right]^2 \langle F_0(v_1(s)) - F_0(v_2(s)), \phi_j \rangle^2} ds \\ &= \frac{1}{2} \int_t^T \sqrt{\sum_{j=1}^{\infty} \left[\frac{e^{(s-t)\lambda_j^-} - e^{(s-t)\lambda_j^+}}{\lambda_j^+ - \lambda_j^-} \right]^2 \frac{e^{-2\alpha T \lambda_j}}{T^4} \langle v_1(s) - v_2(s), \phi_j \rangle^2} ds. \end{aligned} \quad (2.13)$$

Using the the inequality $|e^{-a} - e^{-b}| \leq |a - b|$ for $a, b > 0$, we have

$$\left[\frac{e^{(s-t)\lambda_j^-} - e^{(s-t)\lambda_j^+}}{\lambda_j^+ - \lambda_j^-} \right]^2 \frac{e^{-2\alpha T \lambda_j}}{T^4} = e^{2(s-t)(\lambda_j^+ + \lambda_j^-)} \left[\frac{e^{-(s-t)\lambda_j^+} - e^{-(s-t)\lambda_j^-}}{\lambda_j^+ - \lambda_j^-} \right]^2 \frac{e^{-2\alpha T \lambda_j}}{T^4} \leq (s-t)^2 e^{2\alpha(s-t)\lambda_j} \frac{e^{-2\alpha T \lambda_j}}{T^4} \leq \frac{1}{T^2}. \quad (2.14)$$

From (2.13) and (2.14) we deduce that

$$\|\mathcal{H}(v_1)(t) - \mathcal{H}(v_2)(t)\| \leq \frac{1}{2} \int_t^T \frac{1}{T} \|v_1(s) - v_2(s)\| ds \leq \frac{1}{2} \|v_1 - v_2\|_{C([0, T]; L^2(\Omega))}, \quad \forall t \in [0, T]. \quad (2.15)$$

This implies that

$$\|\mathcal{H}(v_1) - \mathcal{H}(v_2)\|_{C([0, T]; L^2(\Omega))} \leq \frac{1}{2} \|v_1 - v_2\|_{C([0, T]; L^2(\Omega))}. \quad (2.16)$$

Hence, \mathcal{H} is a contraction. Using the Banach fixed-point theorem, we conclude that $\mathcal{H}(w) = w$ has a unique solution $u_m \in C([0, T]; L^2(\Omega))$.

It is easy to see that (here, noting that $F_0(0) = 0$)

$$\left\| \int_t^T \mathcal{P}(s-t)F_0(u_m(s))ds \right\| = \|\mathcal{H}(u_m)(t) - \mathcal{H}(0)(t)\| \leq \frac{1}{2} \|u_m\|_{C([0, T]; L^2(\Omega))}. \quad (2.17)$$

Hence,

$$\|u_m(t)\| \geq \left\| \mathcal{P}(T-t)v_{T,m} \right\| - \left\| \int_t^T \mathcal{P}(s-t)F_0(u_m(s))ds \right\| \geq \left\| \mathcal{P}(T-t)v_{T,m} \right\| - \frac{1}{2} \|u_m\|_{C([0, T]; L^2(\Omega))}. \quad (2.18)$$

This leads to

$$\|u_m\|_{C([0, T]; L^2(\Omega))} \geq \frac{2}{3} \sup_{0 \leq t \leq T} \left\| \mathcal{P}(T-t)v_{T,m} \right\|. \quad (2.19)$$

We continue to estimate the right hand side of this inequality. We have

$$\left\| \mathcal{P}(T-t)v_{T,m} \right\|^2 = \left[\frac{e^{(T-t)\lambda_m^-} - e^{(T-t)\lambda_m^+}}{\lambda_m^+ - \lambda_m^-} \right]^2 \frac{1}{\lambda_m} = \frac{e^{2(T-t)\lambda_m^+} \left(1 - e^{-(T-t)\sqrt{\alpha^2 \lambda_m^2 - 4\lambda_m}} \right)^2}{\lambda_m (\lambda_m^+ - \lambda_m^-)^2} \geq \frac{e^{2(T-t)\lambda_m^+} \left(1 - e^{-(T-t)\sqrt{\alpha^2 \lambda_1^2 - 4\lambda_1}} \right)^2}{\lambda_m (\alpha^2 \lambda_m^2 - 4\lambda_m)}.$$

Since the function $\Phi(t) = e^{(T-t)\lambda_m^+} \left(1 - e^{-(T-t)\sqrt{\alpha^2\lambda_1^2 - 4\lambda_1}}\right)$ is a decreasing function, we deduce that

$$\sup_{0 \leq t \leq T} \|\mathcal{P}(T-t)v_{T,m}\| \geq \sup_{0 \leq t \leq T} \frac{e^{(T-t)\lambda_m^+} \left(1 - e^{-(T-t)\sqrt{\alpha^2\lambda_1^2 - 4\lambda_1}}\right)}{\sqrt{\lambda_m(\alpha^2\lambda_m^2 - 4\lambda_m)}} = \frac{e^{T\lambda_m^+} \left(1 - e^{-T\sqrt{\alpha^2\lambda_1^2 - 4\lambda_1}}\right)}{\sqrt{\lambda_m(\alpha^2\lambda_m^2 - 4\lambda_m)}} \geq \frac{e^{\alpha T\lambda_m/2} \left(1 - e^{-T\sqrt{\alpha^2\lambda_1^2 - 4\lambda_1}}\right)}{\sqrt{\lambda_m(\alpha^2\lambda_m^2 - 4\lambda_m)}}. \quad (2.20)$$

Combining (2.19) and (2.20) yields

$$\|u_m\|_{C([0,T];L^2(\Omega))} \geq \frac{2}{3} \frac{e^{\alpha T\lambda_m/2} \left(1 - e^{-T\sqrt{\alpha^2\lambda_1^2 - 4\lambda_1}}\right)}{\sqrt{\lambda_m(\alpha^2\lambda_m^2 - 4\lambda_m)}}. \quad (2.21)$$

As $m \rightarrow +\infty$, we see that

$$\begin{aligned} \lim_{m \rightarrow +\infty} (\|u_{T,m}\| + \|v_{T,m}\|) &= \lim_{m \rightarrow +\infty} \frac{1}{\sqrt{\lambda_m}} = 0, \\ \lim_{m \rightarrow +\infty} \|u_m\|_{C([0,T];L^2(\Omega))} &\geq \lim_{m \rightarrow +\infty} \frac{2}{3} \frac{e^{\alpha T\lambda_m/2} \left(1 - e^{-T\sqrt{\alpha^2\lambda_1^2 - 4\lambda_1}}\right)}{\sqrt{\lambda_m(\alpha^2\lambda_m^2 - 4\lambda_m)}} = +\infty. \end{aligned} \quad (2.22)$$

This shows that problem (1.1)-(1.2) is ill-posed in the sense of Hadamard in the L^2 -norm.

3. Fourier's truncation method

For $\varphi \in L^2(\Omega)$, let us define the truncated version of (2.8) as

$$\mathcal{S}_N(t)\varphi = \sum_{j=1}^N \frac{\lambda_j^+ e^{t\lambda_j^-} - \lambda_j^- e^{t\lambda_j^+}}{\lambda_j^+ - \lambda_j^-} \langle \varphi, \phi_j \rangle \phi_j, \quad \mathcal{P}_N(t)\varphi = \sum_{j=1}^N \frac{e^{t\lambda_j^-} - e^{t\lambda_j^+}}{\lambda_j^+ - \lambda_j^-} \langle \varphi, \phi_j \rangle \phi_j. \quad (3.23)$$

Let us define the regularized solution by Fourier's truncation method as follows:

$$u^{N,\epsilon}(x,t) = \mathcal{S}_N(T-t)g^\epsilon(x) + \mathcal{P}_N(T-t)h^\epsilon(x) - \int_t^T \mathcal{P}_N(s-t)F(u^{N,\epsilon})(x,s)ds, \quad (3.24)$$

where N is a parameter regularization to be prescribed.

Lemma 3.1. *The following estimates hold:*

$$\|\mathcal{S}_N(t)\|_{\mathcal{L}(L^2(\Omega))} \leq \sqrt{\frac{2\alpha^2 + 8T^2}{\alpha^2}} e^{\alpha t\lambda_N}, \quad \|\mathcal{P}_N(t)\|_{\mathcal{L}(L^2(\Omega))} \leq T e^{\alpha t\lambda_N}, \quad \forall t \in [0, T]. \quad (3.25)$$

Proof. Let $\varphi \in L^2(\Omega)$. From (3.23) we have

$$\|\mathcal{S}_N(t)\varphi\|^2 = \sum_{j=1}^N \left[\frac{\lambda_j^+ e^{t\lambda_j^-} - \lambda_j^- e^{t\lambda_j^+}}{\lambda_j^+ - \lambda_j^-} \right]^2 \langle \varphi, \phi_j \rangle^2 = \sum_{j=1}^N e^{2t(\lambda_j^+ + \lambda_j^-)} \left[\frac{\lambda_j^+ e^{-t\lambda_j^+} - \lambda_j^- e^{-t\lambda_j^-}}{\lambda_j^+ - \lambda_j^-} \right]^2 \langle \varphi, \phi_j \rangle^2. \quad (3.26)$$

Using the inequality $(a+b)^2 \leq 2a^2 + 2b^2$ for $a, b \in \mathbb{R}$ and the inequality $|e^{-a} - e^{-b}| \leq |a-b|$ for $a, b > 0$, we obtain

$$\begin{aligned} \left[\frac{\lambda_j^+ e^{-t\lambda_j^+} - \lambda_j^- e^{-t\lambda_j^-}}{\lambda_j^+ - \lambda_j^-} \right]^2 &= \left(e^{-t\lambda_j^+} + \lambda_j^- \frac{e^{-t\lambda_j^+} - e^{-t\lambda_j^-}}{\lambda_j^+ - \lambda_j^-} \right)^2 \leq 2e^{-2t\lambda_j^+} + 2|\lambda_j^-|^2 t^2 \\ &\leq 2 + \left(\frac{2t\lambda_j}{\alpha\lambda_j + \sqrt{\alpha^2\lambda_j^2 - 4\lambda_j}} \right)^2 \leq \frac{2\alpha^2 + 8T^2}{\alpha^2}. \end{aligned} \quad (3.27)$$

It follows from (3.26) and (3.27) that

$$\|\mathcal{S}_N(t)\varphi\|^2 \leq \frac{2\alpha^2 + 8T^2}{\alpha^2} \sum_{j=1}^N e^{2t(\lambda_j^+ + \lambda_j^-)} \langle \varphi, \phi_j \rangle^2 \leq \frac{2\alpha^2 + 8T^2}{\alpha^2} \sum_{j=1}^N e^{2\alpha t\lambda_j} \langle \varphi, \phi_j \rangle^2 \leq \frac{2\alpha^2 + 8T^2}{\alpha^2} e^{2\alpha t\lambda_N} \|\varphi\|^2. \quad (3.28)$$

This completes the proof of the first part of (3.25). Also, using $|e^{-a} - e^{-b}| \leq |a-b|$ for $a, b > 0$, we obtain

$$\|\mathcal{P}_N(t)\varphi\|^2 = \sum_{j=1}^N \left[\frac{e^{t\lambda_j^-} - e^{t\lambda_j^+}}{\lambda_j^+ - \lambda_j^-} \right]^2 \langle \varphi, \phi_j \rangle^2 = \sum_{j=1}^N e^{2t(\lambda_j^+ + \lambda_j^-)} \left[\frac{e^{-t\lambda_j^+} - e^{-t\lambda_j^-}}{\lambda_j^+ - \lambda_j^-} \right]^2 \langle \varphi, \phi_j \rangle^2 \leq T^2 \sum_{j=1}^N e^{2t(\lambda_j^+ + \lambda_j^-)} \langle \varphi, \phi_j \rangle^2, \quad (3.29)$$

which completes the proof of the second part of (3.25). \square

At this stage, **in order to obtain the convergence rate (3.31) given in the following theorem**, we introduce the abstract Gevrey class of functions of order $\gamma > 0$ and index $\sigma > 0$, e.g., [1], defined by

$$\mathbb{G}_{\gamma,\sigma} = \left\{ v \in L^2(\Omega) : \sum_{j=1}^{\infty} \lambda_j^{2\gamma} e^{2\sigma\lambda_j} \left| \langle v, \phi_j(x) \rangle \right|^2 < \infty \right\},$$

which is a Hilbert space equipped with the inner product

$$\langle v_1, v_2 \rangle_{\mathbb{G}_{\gamma,\sigma}} := \left\langle (-\Delta)^\gamma e^{\sigma\sqrt{-\Delta}} v_1, (-\Delta)^\gamma e^{\sigma\sqrt{-\Delta}} v_2 \right\rangle, \quad \forall v_1, v_2 \in \mathbb{G}_{\gamma,\sigma},$$

and the corresponding norm $\|v\|_{\mathbb{G}_{\gamma,\sigma}} = \sqrt{\sum_{j=1}^{\infty} \lambda_j^{2\gamma} e^{2\sigma\lambda_j} \left| \langle v, \phi_j(x) \rangle \right|^2} < \infty$.

We also assume that F is globally Lipschitz, i.e. there exists a constant $K > 0$ such that

$$\|F(x, t, u) - F(x, t, v)\| \leq K\|u - v\|, \quad \forall u, v \in L^2(\Omega), \quad \forall (x, t) \in \Omega \times (0, T). \quad (3.30)$$

Theorem 3.1. *The nonlinear integral equation (3.24) has a unique solution $u^{N,\epsilon} \in C([0, T]; L^2(\Omega))$. Assuming further that $u \in L^\infty(0, T; \mathbb{G}_{\gamma,\sigma T})$ for some $\gamma > 0$, then we have the following estimate:*

$$\|u^{N,\epsilon}(\cdot, t) - u(\cdot, t)\| \leq e^{-\alpha t \lambda_N} e^{KT^2} \left(\left(\sqrt{\frac{2\alpha^2 + 8T^2}{\alpha^2}} + T \right) e^{\alpha T \lambda_N} \epsilon + \lambda_N^{-\gamma} \|u\|_{L^\infty(0, T; \mathbb{G}_{\gamma,\sigma T})} \right), \quad \forall t \in [0, T]. \quad (3.31)$$

Remark 3.1. *If we choose $N = N(\epsilon)$ such that $\lambda_N \leq \frac{\delta}{\alpha T} \ln\left(\frac{1}{\epsilon}\right)$ for some $\delta \in (0, 1)$, then the error $\|u^{N,\epsilon}(\cdot, t) - u(\cdot, t)\|$ is of logarithmic order $\left[\ln\left(\frac{1}{\epsilon}\right)\right]^{-\gamma}$. Also, if $F(x, t, u) = F(x, t)$ does not depend on u then we do not need to employ the Gevrey space but only require that $u \in L^\infty(0, T; L^2(\Omega))$. To remove the assumption on u belonging to $L^\infty(0, T; \mathbb{G}_{\gamma,\sigma T})$, we can employ a new regularization method described in [8] for the Cauchy problem for semilinear elliptic equations, but its extension to the present damped semilinear wave equation (1.1) is deferred to a future work.*

Proof. Part 1. The existence and uniqueness solution of the nonlinear integral equation (3.24).

For $w \in C([0, T]; L^2(\Omega))$, we define

$$\mathcal{G}(w)(x, t) = \mathcal{S}_N(T-t)g^\epsilon(x) + \mathcal{P}_N(T-t)h^\epsilon(x) - \int_t^T \mathcal{P}_N(s-t)F(w(x, s))ds. \quad (3.32)$$

We shall prove by induction that

$$\left\| \mathcal{G}^m(w_1) - \mathcal{G}^m(w_2) \right\|_{C([0, T]; L^2(\Omega))} \leq \frac{(KT e^{\alpha T \lambda_N} (T-t))^m}{m!} \|w_1 - w_2\|_{C([0, T]; L^2(\Omega))}, \quad \forall w_1, w_2 \in C([0, T]; L^2(\Omega)). \quad (3.33)$$

For $m = 1$, we have

$$\begin{aligned} \|\mathcal{G}(w_1) - \mathcal{G}(w_2)\| &= \left\| \int_t^T \mathcal{P}_N(s-t) (F(w_1(s)) - F(w_2(s))) ds \right\| \\ &\leq \int_t^T T e^{\alpha(s-t)\lambda_N} \|F(w_1(s)) - F(w_2(s))\| ds \leq KT e^{\alpha T \lambda_N} (T-t) \|w_1 - w_2\|_{C([0, T]; L^2(\Omega))}. \end{aligned} \quad (3.34)$$

Assume that (3.33) holds for $m = p$. We show that (3.33) holds for $m = p + 1$. Indeed, we have

$$\begin{aligned} \|\mathcal{G}^{p+1}(w_1) - \mathcal{G}^{p+1}(w_2)\| &= \left\| \int_t^T \mathcal{P}_N(s-t) (F(\mathcal{G}^p(w_1)(s)) - F(\mathcal{G}^p(w_2)(s))) ds \right\| \\ &\leq \int_t^T T e^{\alpha(s-t)\lambda_N} \|F(\mathcal{G}^p(w_1)(s)) - F(\mathcal{G}^p(w_2)(s))\| ds \leq KT e^{\alpha T \lambda_N} \int_t^T \|\mathcal{G}^p(w_1(s)) - \mathcal{G}^p(w_2(s))\| ds \\ &\leq KT e^{\alpha T \lambda_N} \int_t^T \frac{(KT e^{\alpha T \lambda_N} (T-s))^p}{p!} \|w_1 - w_2\|_{C([0, T]; L^2(\Omega))} ds \leq \frac{(KT e^{\alpha T \lambda_N} (T-t))^{p+1}}{(p+1)!} \|w_1 - w_2\|_{C([0, T]; L^2(\Omega))}. \end{aligned} \quad (3.35)$$

Therefore, by the induction principle, we have that (3.33) holds. Since $\lim_{m \rightarrow +\infty} \frac{(KT e^{\alpha T \lambda_N})^m}{m!} = 0$ there exists a positive integer m_0 such that \mathcal{G}^{m_0} is a contraction. It follows that the equation $\mathcal{G}^{m_0} w = w$ has a unique solution $u^{N,\epsilon} \in C([0, T]; L^2(\Omega))$. We claim that $\mathcal{G}(u^{N,\epsilon}) = u^{N,\epsilon}$. Indeed, since $\mathcal{G}^{m_0}(u^{N,\epsilon}) = u^{N,\epsilon}$, we know that $\mathcal{G}(\mathcal{G}^{m_0}(u^{N,\epsilon})) = \mathcal{G}(u^{N,\epsilon})$. This is equivalent to $\mathcal{G}^{m_0}(\mathcal{G}(u^{N,\epsilon})) = \mathcal{G}(u^{N,\epsilon})$. Hence, $\mathcal{G}(u^{N,\epsilon})$ is a fixed point of \mathcal{G}^{m_0} . Moreover, as noted above, $u^{N,\epsilon}$ is a fixed point of \mathcal{G}^{m_0} .

Part 2. Denote

$$U^N(x, t) = \mathcal{S}_N(T-t)g(x) + \mathcal{P}_N(T-t)h(x) - \int_t^T \mathcal{P}_N(s-t)F(u^N(x, s))ds. \quad (3.36)$$

Step 1. Firstly, we estimate $\|u^{N,\epsilon}(\cdot, t) - U^N(\cdot, t)\|$. Using Lemma 3.1, we have

$$\begin{aligned} \|u^{N,\epsilon}(\cdot, t) - U^N(\cdot, t)\| &\leq \left\| \mathcal{S}_N(T-t)(g - g^\epsilon) \right\| + \left\| \mathcal{P}_N(T-t)(h - h^\epsilon) \right\| + \left\| \int_t^T \mathcal{P}_N(s-t)(F(u^{N,\epsilon}(\cdot, s)) - F(U^N(\cdot, s)))ds \right\| \\ &\leq \sqrt{\frac{2\alpha^2 + 8T^2}{\alpha^2}} e^{\alpha(T-t)\lambda_N} \|g - g^\epsilon\| + T e^{\alpha(T-t)\lambda_N} \|h - h^\epsilon\| + T \int_t^T e^{\alpha(s-t)\lambda_N} \|F(u^{N,\epsilon}(\cdot, s)) - F(U^N(\cdot, s))\| ds \end{aligned} \quad (3.37)$$

It follows from (1.3) and (3.30) that

$$\|u^{N,\epsilon}(\cdot, t) - U^N(\cdot, t)\| \leq \left(\sqrt{\frac{2\alpha^2 + 8T^2}{\alpha^2}} + T \right) e^{\alpha(T-t)\lambda_N} \epsilon + KT \int_t^T e^{\alpha(s-t)\lambda_N} \|u^{N,\epsilon}(\cdot, s) - U^N(\cdot, s)\| ds. \quad (3.38)$$

Multiplying both sides by $e^{\alpha t \lambda_N}$ and applying Gronwall's inequality, we derive that

$$e^{\alpha t \lambda_N} \|u^{N,\epsilon}(\cdot, t) - U^N(\cdot, t)\| \leq \left(\sqrt{\frac{2\alpha^2 + 8T^2}{\alpha^2}} + T \right) e^{\alpha T \lambda_N} \epsilon e^{K(T-t)T}.$$

Hence,

$$\|u^{N,\epsilon}(\cdot, t) - U^N(\cdot, t)\| \leq e^{KT(T-t)} \left(\sqrt{\frac{2\alpha^2 + 8T^2}{\alpha^2}} + T \right) e^{\alpha(T-t)\lambda_N} \epsilon. \quad (3.39)$$

Step 2. Secondly, we estimate $\|u(\cdot, t) - U^N(\cdot, t)\|$. First, it is easy to see that

$$\sum_{j=1}^N u_j(t)\phi_j(x) = \mathcal{S}_N(T-t)g(x) + \mathcal{P}_N(T-t)h(x) - \int_t^T \mathcal{P}_N(s-t)F(u(x, s))ds.$$

Using Lemma 3.1, we obtain

$$\begin{aligned} \|u(\cdot, t) - U^N(\cdot, t)\| &\leq \left\| u(\cdot, t) - \sum_{j=1}^N u_j(t)\phi_j(\cdot) \right\| + \left\| \sum_{j=1}^N u_j(t)\phi_j(\cdot) - U^N(\cdot, t) \right\| \\ &\leq \sqrt{\sum_{j=N+1}^{\infty} \lambda_N^{-2\gamma} e^{-2\alpha t \lambda_N} \lambda_j^{2\gamma} e^{2\alpha t \lambda_j} |u_j(t)|^2} + \int_t^T \mathcal{P}_N(s-t) \|F(u(\cdot, s)) - F(U^N(\cdot, s))\| ds \\ &\leq \lambda_N^{-\gamma} e^{-\alpha t \lambda_N} \|u\|_{L^\infty(0, T; \mathbb{G}_{\gamma, \alpha T})} + KT \int_t^T e^{\alpha(s-t)\lambda_N} \|u(\cdot, s) - U^N(\cdot, s)\| ds. \end{aligned} \quad (3.40)$$

Multiplying both sides by $e^{\alpha t \lambda_N}$ and applying Gronwall's inequality, we derive that

$$\|u(\cdot, t) - U^N(\cdot, t)\| \leq e^{KT(T-t)} \|u\|_{L^\infty(0, T; \mathbb{G}_{\gamma, \alpha T})} \lambda_N^{-\gamma} e^{-\alpha t \lambda_N}. \quad (3.41)$$

Combining (3.39) and (3.41) we deduce (3.31). \square

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